

# 5.5V to 28V Input, 2ch Synchronous Buck DC/DC Controller

# **BD95602MUV**

### **General Description**

BD95602MUV is a dual buck regulator controller with adjustable output voltage from1.0V to 5.5V and an input voltage range of 5.5 to 28V. High efficiency is achieved with an external synchronous Nch-MOSFET. H³Reg<sup>TM</sup>, Rohm's advanced proprietary control method that uses constant on-time control to provide ultra high transient responses to load changes is used. SLLM(Simple Light Load Mode) technology is added to improve efficiency with light loads giving high efficiency over a wide load range. In addition to the dual buck regulator controllers, here are 2 LDO regulators included that are fixed output voltage of 3.3V and 5.0V. Other functions included are soft start, variable frequency, short circuit protection with timer latch, over voltage, and power good outputs. This buck regulator is optimal for high-current applications.

### **Features**

- Adjustable Simple Light Load Mode (SLLM), Quiet light Load Mode (QLLM), Forced continuous Mode.
- Multifunctional Protection Circuit
  - -Settable Over Current Protection (OCP)
  - -Thermal Shut down (TSD)
  - -Under Voltage Lock Out (UVLO)
  - -Over Voltage Protection (OVP)
  - -Short Circuit Protection with Timer-Latch (SCP)
- 150kHz to 500kHz Switching frequency.
- Adjustable Soft Start.
- Power Good.
- Dual Linear Regulator (5V/3.3V (total 50mA)).
- Output Discharge.
- Reference voltage Circuit (0.7V).

### **Applications**

 FPGA, POL Power Supply, Mobile PC, Desktop PC, LCD-TV, Digital Components, etc.

# **Key Specifications**

Input Voltage Range: 5.5V to 28V
 Output Voltage Range: 1.0V to 5.5V
 Switching Frequency: 150k to 500MHz(Typ)
 Operating Temperature Range: -20°C to +85°C

Package VQFN032V5050 W(Typ) x D(Typ) x H(Max) 5.00mm x 5.00mm x 1.00mm



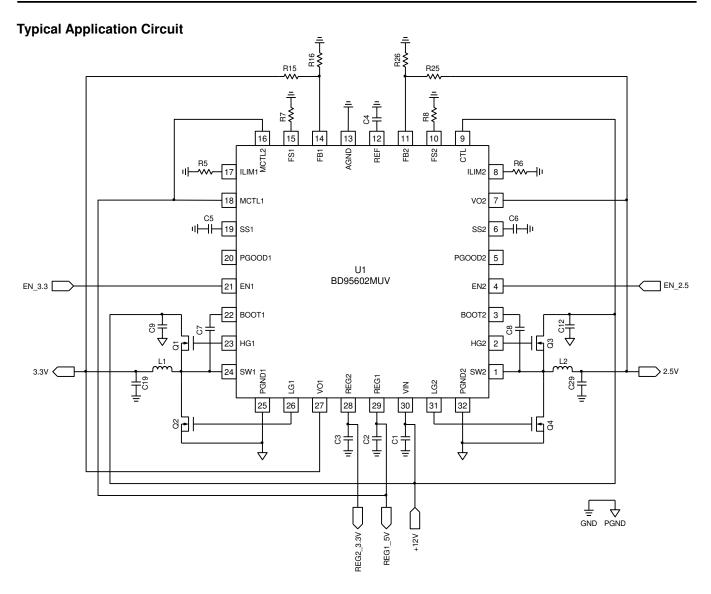


Figure 1. Application Circuit

# **Pin Configuration**

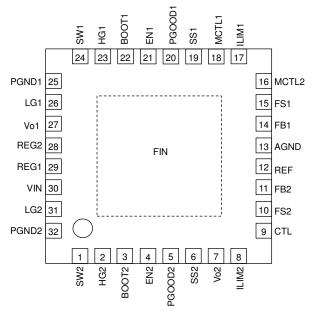


Figure 2. Pin Configuration

Pin Descriptions

SS1	Description	ns								
24 HG2 HG2 HG1 High-side FET gate drive pin. This is the power supply pin for High-side FET driver. The maximum voltage range to ground is to 35V, to SW pin is to 7V. In switching operations, the voltage swings from (VIN-REG1) to REG1 by BOOT pin operation.  4 ENZ ENC Conversely, the status switches off when EN pin voltage goes lower than 0.8V. This pin is pulled down to ASRD with ITMΩ resistor.  5 PGOOD2 If FB pin voltage is 11 seat 22 V3, the status of the switching regulator becomes active. Conversely, the status switches off when EN pin voltage goes lower than 0.8V. This pin is pulled down to ASRD with ITMΩ resistor.  5 PGOOD2 If FB pin voltage is 11 seat 22 V3, the status of the switching regulator becomes active. This is the setting pin for soft start. The rising time is determined by the capacitor connected between SS and ground, and the fixed current inside IC after it is the status of low in standby 19 SS1 under the output voltage it ISS voltage catch up the REF pin to become the SS terminal voltage.  7 VO2 77 VO2 YO1 This is the output discharge pin, and output voltage feedback pin for frequency setting.  8 LIM2 This is the coil current limit setting pin. Set the resistor which is connected in between ground than 0.8V. The switching regulator doesn't become active when the status of CTL pin voltage is at least 2.8V, the status sof the linear regulator REG1 and REG2 output becomes active. Conversely, the status with the set of CTL pin is low, in the status of EN pin is high.  This pin is pulled up to VIN with 1MΩ resistor.  FFS2 FFS2 FFS2 FFS4 FFS4 FFS4 FFS5 FFS5 FFS6 FFS6 FFS6 FFS6 FFS6 FFS6	Pin No.	Pin Name	Function							
Age			Ground pin for High-side FET. The maximum voltage range of this pin is 30V.							
ground is to 35V, to SW pin is to 7V. In switching operations, the voltage swings from (VIN-REG1) to REG1 by BOOT pin operation.			High-side FET gate	e drive pin.						
21			ground is to 35V, to	SW pin is to	7V. In switch	ning operations, the voltage swi				
PGOOD1   The output format is open drain, so please connect pull-up resistance.			Conversely, the sta	atus switches c	off when EN	pin voltage goes lower than 0.8				
6   SS2   SS1   between SS and ground, and the fixed current inside IC after it is the status of low in standby mode. It controls the output voltage till SS voltage catch up the REF pin to become the SS terminal voltage.										
Voice   Vo			between SS and g mode. It controls the	This is the setting pin for soft start. The rising time is determined by the capacitor connected between SS and ground, and the fixed current inside IC after it is the status of low in standby mode. It controls the output voltage till SS voltage catch up the REF pin to become the SS						
This is the coil current limit setting pin. Set the resistor which is connected in between ground when CTL pin voltage is at least 2.3V, the status of the linear regulator ReG1 and REG2 output becomes active. Conversely, the status of the linear regulator ReG1 and REG2 output becomes active. Conversely, the status of the linear regulator ReG1 and REG2 output becomes active when CTL pin voltage goes lower than 0.8V. The switching regulator doesn't become active when the status of CTL pin is low, it is status of EN pin is high.  10 FS2 Frequency input. A resistor to ground will set the switching frequency. Frequencies from 150kHz to 500kHz are possible.  11 FB2 This is the output voltage feedback pin.  12 REF This is the output voltage setting pin.  13 The IC controls reference voltage and FB terminal voltage are almost same.  14 This is the output voltage setting pin.  15 The IC control reference voltage and FB terminal voltage are almost same.  16 Ground input for control circuit.  18 MCTL2  19 MCTL1  10 MCTL2  11 MCTL2  11 MCTL2  12 MCTL1  13 MCTL2  14 MCTL1  15 Input  16 MCTL2  17 MCTL1  18 MCTL2  18 MCTL1  19 MCTL1  10 MCTL2  10 MCTL1  10 MCTL2  11 MCTL2  12 Control Mode  11 MCTL2  12 Low Low SLLM  13 Low High QLLM  14 High Low Continuous PWM Mode  15 PGND2  16 LG1  17 This is the ground pin for Low-side FET drive.  17 Inis is the coutput pin for 3.3V/50mA linear regulator (5V/3.3V (total 50mA)).  18 Please connect 10µF capacitor which characteristic is more than X5R near the pin.  18 PLG2  19 PRGD1  10 MIN December 10µF capacitor which characteristic is more than X5R near the pin.			This is the output of	discharge pin, a	and output v	oltage feedback pin for frequer	ncy setting.			
9         CTL         coutput becomes active. Conversely, the status switches off when CTL pin voltage goes lower than 0.8V. The switching regulator doesn't become active when the status of CTL pin is low, it the status of EN pin is high.			This is the coil curr	ent limit settin	g pin. Set the	e resistor which is connected in	n between ground.			
15 FS1 Frequencies from 150kHz to 500kHz are possible.  11 FB2 This is the output voltage feedback pin. The IC controls reference voltage and FB terminal voltage are almost same.  12 REF This is the output voltage setting pin. The IC controls reference voltage and FB terminal voltage are almost same.  13 AGND Ground input for control circuit.  14 This is the operation mode setting pin. If terminal voltage reaches less than 0.8V, it will be Lovel. If terminal voltage reaches sets than 0.8V, it will be High Level. This pin is pulled down to AGND with 300kΩ resistor.  16 MCTL1 MCTL2 Low Low SLLM Low High QLLM High Low Continuous PWM Mode High Low Continuous PWM Mode High High Continuous PWM Mode High High Continuous PWM Mode Low-side FET gate drive pin. It is operated in switching between REG1 to PGND. ON resistance of output stage when High, it is 2Ω and when Low, it is 0.5Ω drive Low-side FET gate with the high pace.  18 REG2 This is the output pin for 3.3V/50mA linear regulator (5V/3.3V (total 50mA)). Please connect 10μF capacitor which characteristic is more than X5R near the pin.  29 REG1 This is the output pin for 5V/50mA linear regulator. Monitor input voltage and determin necessary on-time. As a result, this terminal voltage changes, and then the IC operation become unstable. Please connect 10μF capacitor which characteristic is more than X5R near the pin.	9	CTL	output becomes ac than 0.8V. The swi the status of EN pi	output becomes active. Conversely, the status switches off when CTL pin voltage goes lower than 0.8V. The switching regulator doesn't become active when the status of CTL pin is low, if the status of EN pin is high.						
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Level. If terminal voltage reaches more than 2.3V, it will be High Level. This pin is pulled down to AGND with 300kΩ resistor.    Input	13	AGND	Ground input for co	ontrol circuit.						
MCTL1   MCTL2     Low   Low   SLLM     Low   High   QLLM     High   Low   Continuous PWM Mode     High   High   Continuous PWM Mode     High   High   Continuous PWM Mode     High   High   Continuous PWM Mode     1			Level. If terminal voltage	reaches more resistor.		will be High Level. This pin is p				
Low   Low   SLLM				MCTL1	MCTL2	Control Mode				
High Low Continuous PWM Mode    High   High   Continuous PWM Mode	10	MOTE		Low	Low	SLLM	]			
High High Continuous PWM Mode  25 PGND1 PGND2 This is the ground pin for Low-side FET drive.  26 LG1 CON resistance of output stage when High, it is operated in switching between REG1 to PGND. ON resistance of output stage when High, it is 2Ω and when Low, it is 0.5Ω drive Low-side FET gate with the high pace.  28 REG2 This is the output pin for 3.3V/50mA linear regulator (5V/3.3V (total 50mA)). Please connect 10μF capacitor which characteristic is more than X5R near the pin.  29 REG1 This is the output pin for 5V/50mA linear regulator (5V/3.3V (total 50mA)). Please connect 10μF capacitor which characteristic is more than X5R near the pin.  30 VIN Supply pin of H³Reg™ control circuit and linear regulator. Monitor input voltage and determin necessary on-time. As a result, this terminal voltage changes, and then the IC operation become unstable. Please connect 10μF capacitor which characteristic is more than X5R near the pin.				Low	High	QLLM				
25 PGND1 PGND2 This is the ground pin for Low-side FET drive.  26 31 LG1 CON resistance of output stage when High, it is 2Ω and when Low, it is 0.5Ω drive Low-side FET gate with the high pace.  28 REG2 This is the output pin for 3.3V/50mA linear regulator (5V/3.3V (total 50mA)). Please connect 10μF capacitor which characteristic is more than X5R near the pin.  29 REG1 This is the output pin for 5V/50mA linear regulator (5V/3.3V (total 50mA)). Please connect 10μF capacitor which characteristic is more than X5R near the pin.  30 VIN Supply pin of H³Reg™ control circuit and linear regulator. Monitor input voltage and determin necessary on-time. As a result, this terminal voltage changes, and then the IC operation become unstable. Please connect 10μF capacitor which characteristic is more than X5R near				High	Low	Continuous PWM Mode				
26 31 LG1 LG2 This is the Low-side FET gate drive pin. It is operated in switching between REG1 to PGND. ON resistance of output stage when High, it is 2Ω and when Low, it is 0.5Ω drive Low-side FET gate with the high pace.  28 REG2 This is the output pin for 3.3V/50mA linear regulator (5V/3.3V (total 50mA)). Please connect 10μF capacitor which characteristic is more than X5R near the pin.  This is the output pin for 5V/50mA linear regulator (5V/3.3V (total 50mA)). Please connect 10μF capacitor which characteristic is more than X5R near the pin.  Supply pin of H³Reg™ control circuit and linear regulator. Monitor input voltage and determin necessary on-time. As a result, this terminal voltage changes, and then the IC operation become unstable. Please connect 10μF capacitor which characteristic is more than X5R near				High	High	Continuous PWM Mode				
ON resistance of output stage when High, it is 2Ω and when Low, it is 0.5Ω drive Low-side FET gate with the high pace.  REG2  REG2  This is the output pin for 3.3V/50mA linear regulator (5V/3.3V (total 50mA)). Please connect 10μF capacitor which characteristic is more than X5R near the pin.  This is the output pin for 5V/50mA linear regulator (5V/3.3V (total 50mA)). Please connect 10μF capacitor which characteristic is more than X5R near the pin.  Supply pin of H³Reg™ control circuit and linear regulator. Monitor input voltage and determin necessary on-time. As a result, this terminal voltage changes, and then the IC operation become unstable. Please connect 10μF capacitor which characteristic is more than X5R near			This is the ground pin for Low-side FET drive.							
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one cessary on-time. As a result, this terminal voltage changes, and then the IC operation become unstable. Please connect 10μF capacitor which characteristic is more than X5R near	29	REG1	Please connect 10	This is the output pin for 5V/50mA linear regulator (5V/3.3V (total 50mA)).						
	30	VIN	necessary on-time become unstable. the pin.	Supply pin of H³Reg <sup>™</sup> control circuit and linear regulator. Monitor input voltage and determine necessary on-time. As a result, this terminal voltage changes, and then the IC operation become unstable. Please connect 10µF capacitor which characteristic is more than X5R near						
FIN FIN This is the thermal PAD. Please connect to the ground.	FIN	FIN	This is the thermal	PAD. Please	connect to th	ne ground.				

**Output condition table** 

Input			Output				
CTL	EN1	EN2	REG1(5V)	REG2(3.3V)	DC/DC1	DC/DC2	
Low	Low	Low	OFF	OFF	OFF	OFF	
Low	Low	High	OFF	OFF	OFF	OFF	
Low	High	Low	OFF	OFF	OFF	OFF	
Low	High	High	OFF	OFF	OFF	OFF	
High	Low	Low	ON	ON	OFF	OFF	
High	Low	High	ON	ON	OFF	ON	
High	High	Low	ON	ON	ON	OFF	
High	High	High	ON	ON	ON	ON	

<sup>\*</sup> CTL pin is connected to VIN pin with  $1M\Omega$  resistor(pull up) internal IC. \* EN pin is connected to AGND pin with  $1M\Omega$  resistor(pull down) internal IC.

# **Block Diagram**

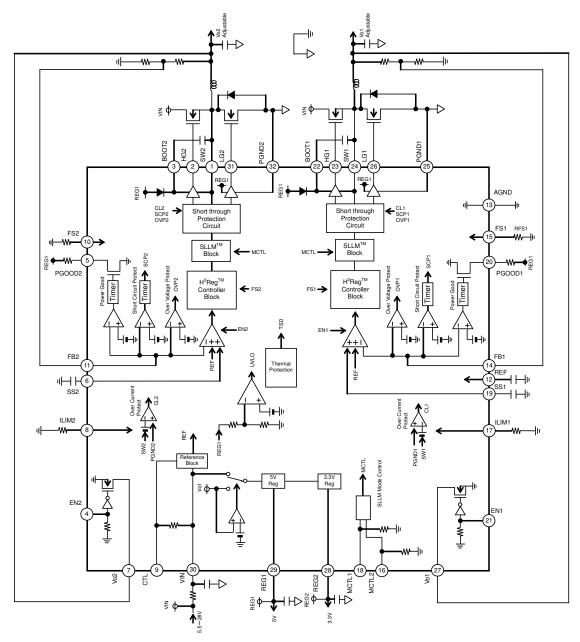


Figure 3. Block Diagram

Absolute Maximum Ratings(Ta = 25°C)

Parameter	Symbol	Rating	Unit	Conditions
	V <sub>IN</sub> , CTL, SW1, SW2	30	V	Note 1
	EN1, EN2, PGOOD1, PGOOD2 Vo1, Vo2, MCTL1, MCTL2	6	V	Note 1, Note 2
	FS1, FS2, FB1, FB2, I <sub>LIM1</sub> , I <sub>LIM2</sub> , SS1, SS2, LG1, LG2, REF,REG2	REG1+0.3	V	Note 1
Terminal Voltage	BOOT1, BOOT2	35	V	Note 1, Note 2
-	BOOT1-SW1, BOOT2-SW2, HG1-SW1, HG2-SW2	7	٧	Note 1, Note 2
	HG1	BOOT1+0.3	V	Note 1, Note 2
	HG2	BOOT2+0.3	V	Note 1, Note 2
	PGND1, PGND2	AGND±0.3	V	Note 1, Note 2
Power Dissipation1	Pd1	0.38	W	Note 3
Power Dissipation2	Pd2	0.88	W	Note 4
Power Dissipation3	Pd3	3.26	W	Note 5
Power Dissipation4	Pd4	4.56	W	Note 6
Operating Temperature Range	Topr	-20 to +85	°C	
Storage Temperature Range	Tstg	-55 to +150	°C	
Junction Temperature	Tjmax	+150	°C	

<sup>(</sup>Note 1) Not to exceed Pd.

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Recommended Operating Conditions (Ta=25°C)

Parameter	Symbol	Min	Тур	Max	Unit	Conditions
	V <sub>IN</sub>	5.5	-	28	٧	
	CTL	-0.3	-	28	V	
	EN1, EN2, MCTL1, MCTL2	-0.3	-	5.5	V	
Terminal Voltage	BOOT1, BOOT2	4.5	-	33	V	
	SW1, SW2	-0.3	-	28	V	
	BOOT1-SW1, BOOT2-SW2, HG1-SW1, HG2-SW2	-0.3	-	5.5	V	
	Vo1, Vo2, PGOOD1, PGOOD2	-0.3	-	5.5	V	_
Minimum ON Time	Tonmin	-	-	150	nsec	

This product should not be used in a radioactive environment.

<sup>(</sup>Note 2) Instantaneous surge voltage, back electromotive force and voltage under less than 10% duty cycle.

<sup>(</sup>Note 3) Derating in done 3.0 mW/°C for operating above Ta ≥ 25°C (when don't mounted on a heat radiation board).

<sup>(</sup>Note 4) Derating in done 7.0 mW/°C for operating above Ta ≥ 25°C (Mount on 1-layer 74.2mm x 74.2mm x 1.6mm board). Surface heat dissipation copper foil:20.2mm².

<sup>(</sup>Note 5) Derating in done 26.1 mW/°C for operating above Ta ≥ 25°C (Mount on 4-layer 74.2mm x 74.2mm x 1.6mm board Two sides heat dissipation copperfoil:20.2mm². 2 or 3-layer: heat dissipation copper foil: 5505mm²).

<sup>(</sup>Note 6) Derating in done 36.5 mW/°C for operating above Ta  $\geq$  25°C (Mount on 4-layer 74.2mm x 74.2mm x 1.6mm board) All layers heat dissipation copper foil:5505mm².

Electrical Characteristics (Unless otherwise noted, Ta=25°CVIN=12V, CTL=OPEN, EN1=EN2=5V, FS1=FS2=51kΩ)

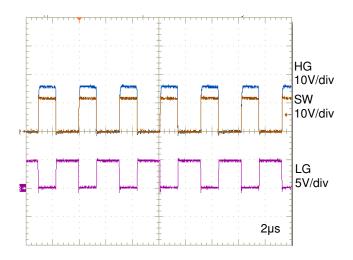
Parameter	Symbol	Min	Тур	Max	Unit	Conditions
VIN Standby Current	Іѕтв	70	150	250	μA	EN1= EN2= 0V, CTL= 5V
VIN Bias Current	I <sub>IN</sub>	60	130	230	μA	Vo1= 5V
VIN Shut Down Mode Current	Ishd	6	12	18	μA	CTL= 0V
CTL Low Voltage	V <sub>CTLL</sub>	-0.3	-	0.8	V	
CTL High Voltage	V <sub>CTLH</sub>	2.3	-	28	V	
CTL Bias Current	Iсть	-18	-12	-6	μA	CTL= 0V
EN Low Voltage	V <sub>ENL</sub>	-0.3	-	0.8	V	
EN High Voltage	V <sub>ENH</sub>	2.3	-	5.5	V	
EN Bias Current	I <sub>EN</sub>	-	3	6	μA	EN= 3V
5V Linear Regulator -VIN			<u>I</u>	<u>I</u>		
REG1 Output Voltage	V <sub>REG1</sub>	4.90	5.00	5.10	V	IREG1=1mA
Maximum Current	I <sub>REG1</sub>	50	-	-	mA	IREG2= 0mA, (Note 7)
Line Regulation	R <sub>EG.I1</sub>	-	90	180	mV	VIN= 5.5 to 28V
Load Regulation	R <sub>EG,L1</sub>	-	30	50	mV	IREG1= 0 to 30mA
3.3V Linear Regulator	li .	1	I.	I	i	1
REG2 Output Voltage	V <sub>REG2</sub>	3.27	3.30	3.33	V	IREG2= 1mA
Maximum Current	I <sub>REG2</sub>	50	-	-	mA	IREG1= 0mA, (Note 7)
Line Regulation	R <sub>EG.12</sub>	-	-	20	mV	VIN= 5.5 to 28V
Load Regulation	R <sub>EG.L2</sub>	-	-	30	mV	IREG2= 0 to 30mA
5V Linear Regulator -Vo1		1	1	1		1
Input Threshold Voltage	REG1th	4.1	4.4	4.7	V	Vo1: Sweep up
Input Delay Time	T <sub>REG1</sub>	1.5	3	6	ms	
Switch Resistance	R <sub>REG1</sub>	-	1.0	3.0	Ω	
Under Voltage Lock Out Block		1	I.	I.		1
REG1 Threshold Voltage	REG1_UVLO	3.9	4.2	4.5	V	REG1: Sweep up
Hysteresis Voltage	dV_uvlo	50	100	200	mV	REG1: Sweep down
Output Voltage Sense Block						·
Feedback Voltage1	V <sub>FB1</sub>	0.693	0.700	0.707	V	
FB1 Bias Current	I <sub>FB1</sub>	-	0	1	μA	FB1= REF
Output Discharge Resistance1	RDISOUT1	50	100	200	Ω	
Feedback Voltage2	V <sub>FB2</sub>	0.693	0.700	0.707	V	
FB2 Bias Current	I <sub>FB2</sub>	-	0	1	μA	FB2= REF
Output Discharge Resistance2	R <sub>DISOUT2</sub>	50	100	200	Ω	
H <sup>3</sup> REG <sup>™</sup> Control Block	l .	1	1	I.		1
On Time1	ton1	0.760	0.910	1.060	μs	Vo1= 5V,FS1= 51kΩ
On Time2	ton2	0.470	0.620	0.770	μs	Vo2= 3.3V ,FS2= 51kΩ
Maximum On Time 1	tonmax1	2.5	5	10	μs	Vo1= 5V
Maximum On Time 2	t <sub>ONMAX</sub> 2	1.65	3.3	6.6	μs	Vo2= 3.3V
Minimum Off Time	toffmin	-	0.2	0.4	μs	
FET Driver Block		1	I	I	<u> </u>	1
HG High Side ON Resistance	HGhon	-	3.0	6.0	Ω	
HG Low Side ON Resistance	HGLON	-	2.0	4.0	Ω	
LG High Side ON Resistance	LGHON	-	2.0	4.0	Ω	
LG Low Side ON Resistance	LGLON	_	0.5	1.0	Ω	

(Note 7)  $I_{REG1}+I_{REG2} \le 50mA$ .

Electrical Characteristics (Unless otherwise noted, Ta=25°CVIN=12V, CTL=OPEN, EN1=EN2=5V, FS1=FS2=51kΩ)

Over Voltage Protection Block						
OVP Threshold Voltage	Vovp	0.77 (+10%)	0.84 (+20%)	0.91 (+30%)	V	
OVP Hysteresis	dV_ovp	50	150	300	mV	
Output Short Protection Block	·					
SCP Threshold Voltage	Vscp	0.42 (-40%)	0.49 (-30%)	0.56 (-20%)	V	
Delay Time	TSCP	0.4	0.75	1.5	ms	
Over Current Protection Block	·					
Offset Voltage	dVsmax	80	100	120	mV	ILIM= 100kΩ
Power Good Block	·					
Power Good Low Threshold	VPGTHL	0.525 (-25%)	0.595 (-15%)	0.665 (-5%)	V	
Power Good Low Voltage	VPGL	-	0.1	0.2	V	IPGOOD= 1mA
Delay Time	TPGOOD	0.4	0.75	1.5	ms	
Power Good Leakage Current	ILEAKPG	-2	0	2	μΑ	VPGOOD= 5V
Soft Start Block	·					
Charge Current	Iss	1.5	2.3	3.1	μΑ	
Standby Voltage	Vss_stb	-	-	50	mV	
Mode Control Block		•				
MCTL Low Voltage	VMCTL_L	-0.3	-	0.3	٧	
MCTL High Voltage	VMCTL_H	2.3	-	REG1 +0.3	V	
MCTL Bias Current	IMCTL	8	16	24	μΑ	MCTL= 5V

# Typical Performance Curves (Reference data)



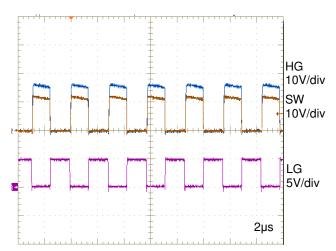
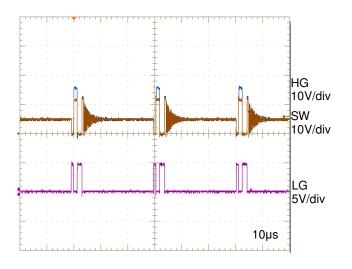


Figure 4. Switching Waveform (Vo= 5V, Io= 0A, PWM)

Figure 5. Switching Waveform (Vo= 5V, Io= 8A, PWM)



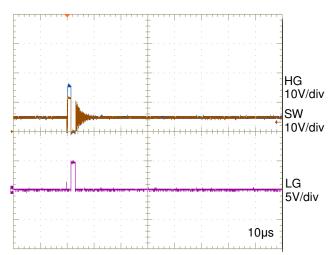
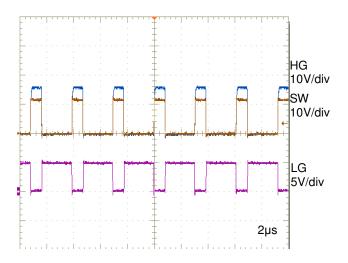


Figure 6. Switching Waveform (Vo= 5V, Io= 0A, QLLM)

Figure 7. Switching Waveform (Vo= 5V, Io= 0A, SLLM)



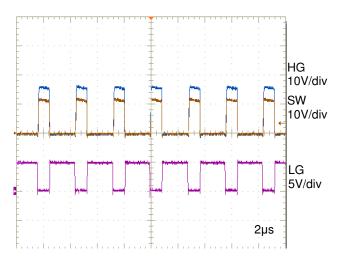
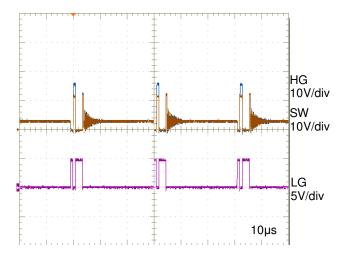


Figure 8. Switching Waveform (Vo= 3.3V, Io= 0A, PWM)

Figure 9. Switching Waveform (Vo= 3.3V, Io= 8A, PWM)



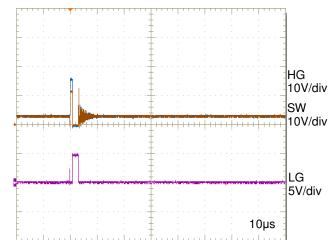
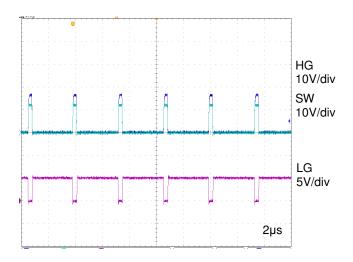


Figure 10. Switching Waveform (Vo= 3.3V, Io= 0A, QLLM)

Figure 11. Switching Waveform (Vo= 3.3V, Io= 0A, SLLM)



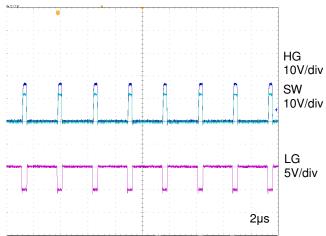
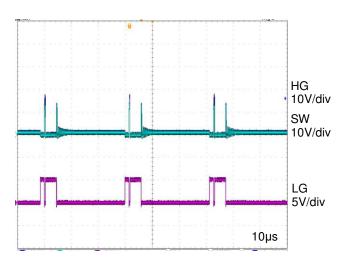


Figure 12. Switching Waveform (Vo= 1V, Io= 0A, PWM)

Figure 13. Switching Waveform (Vo= 1V, Io= 8A, PWM)



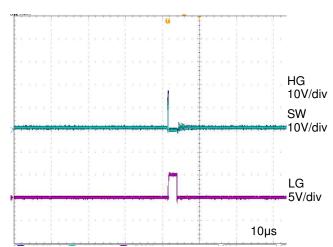


Figure 14. Switching Waveform (Vo= 1V, Io= 0A, QLLM)

Figure 15. Switching Waveform (Vo= 1V, Io= 0A, SLLM)

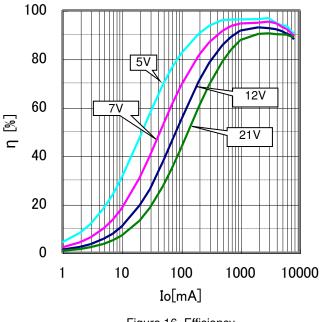


Figure 16. Efficiency (Vo= 5V, PWM)

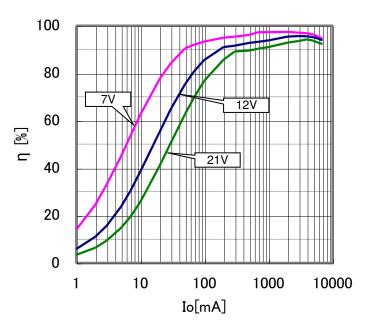


Figure 17. Efficiency (Vo= 5V, QLLM)

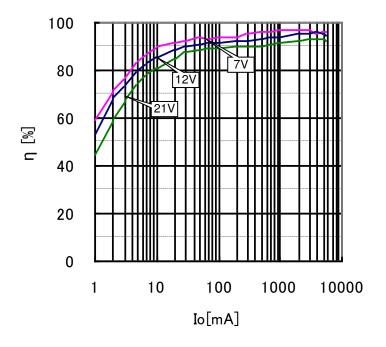


Figure 18. Efficiency (Vo= 5V, SLLM)

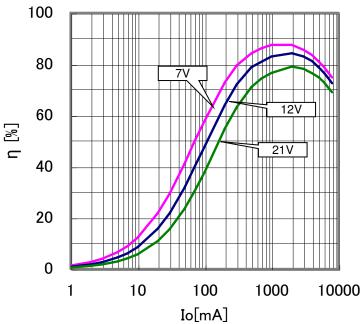
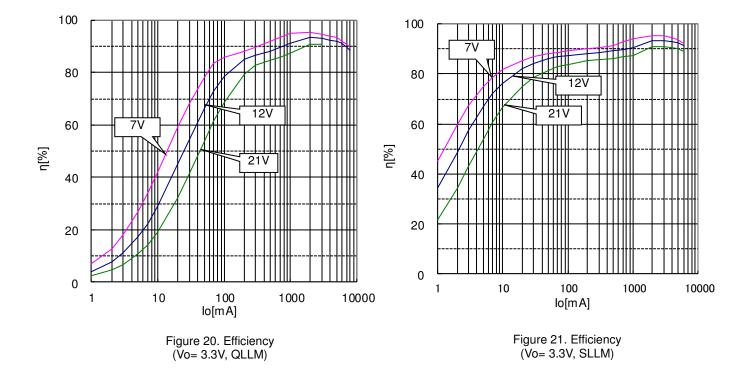


Figure 19. Efficiency (Vo= 3.3V, PWM)



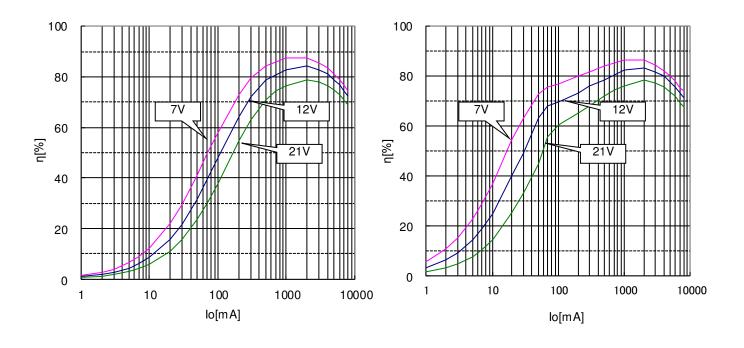
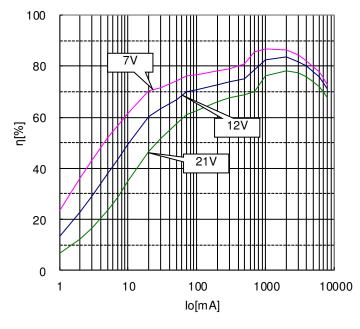


Figure 22. Efficiency

(Vo= 1V, PWM)

Figure 23. Efficiency

(Vo= 1V, QLLM)



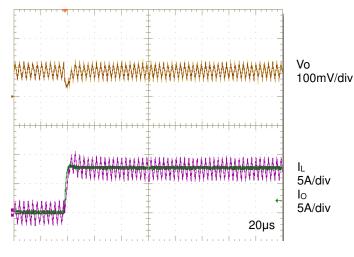
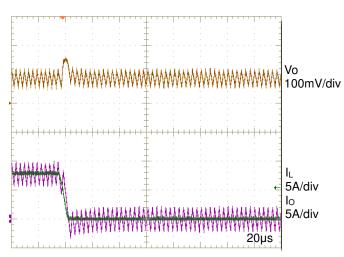


Figure 24. Efficiency (Vo= 1V, SLLM)

Figure 25. Transient Response (Vo= 5V, PWM, Io= 0A→8A)



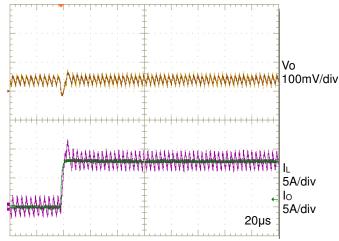


Figure 26. Transient Response (Vo= 5V, PWM, Io= 8A→0A)

Figure 27. Transient Response (Vo= 3.3V, PWM, Io= 0A→8A)

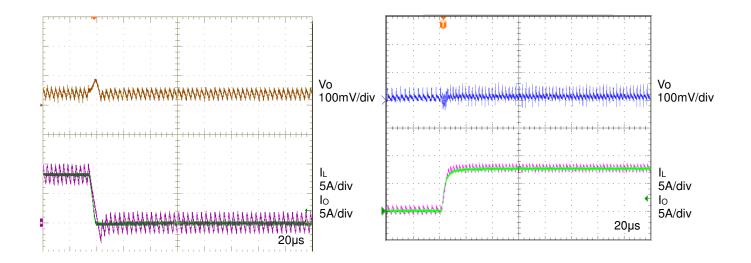


Figure 28. Transient Response (Vo= 3.3V, PWM, Io= 8A→0A)

Figure 29. Transient Response (Vo= 1V, PWM, Io= 0A→8A)

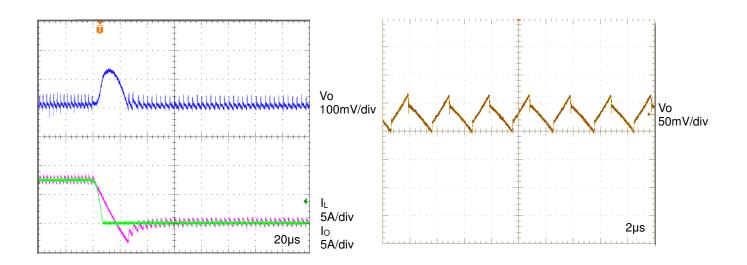


Figure 30. Transient Response (Vo= 1V, PWM, Io= 8A→0A)

Figure 31. Output Voltage (Vo= 5V, PWM, Io= 0A)

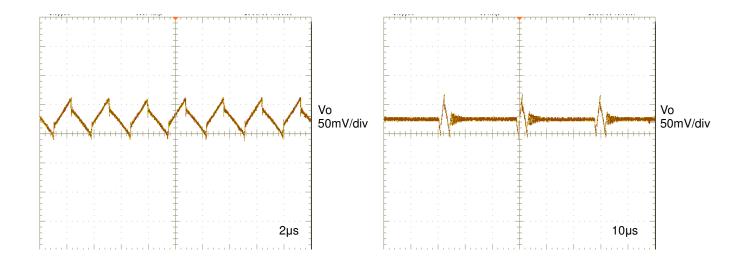


Figure 32. Output Voltage (Vo= 5V, PWM, Io= 8A)

Figure 33. Output Voltage (Vo= 5V, QLLM, Io= 0A)

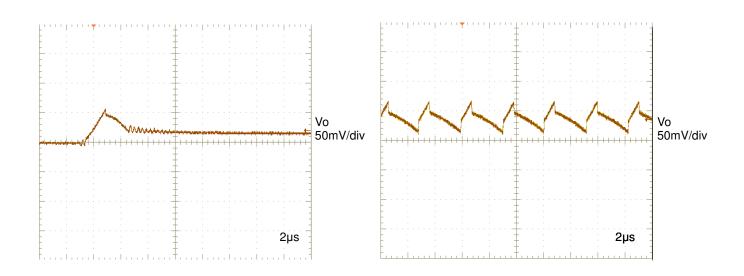


Figure 34. Output Voltage (Vo= 5V, SLLM, Io= 0A)

Figure 35. Output Voltage (Vo= 3.3V, PWM, Io= 0A)

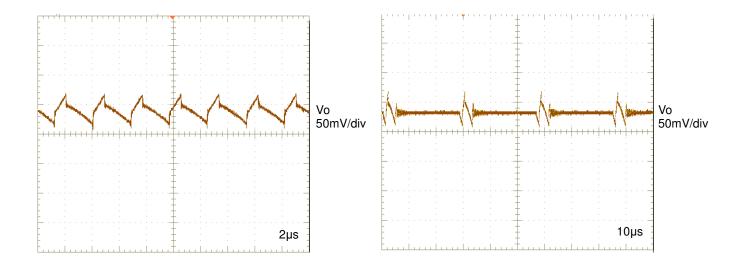


Figure 36. Output Voltage (Vo= 3.3V, PWM, Io= 8A)

Figure 37. Output Voltage (Vo= 3.3V, QLLM, Io= 0A)

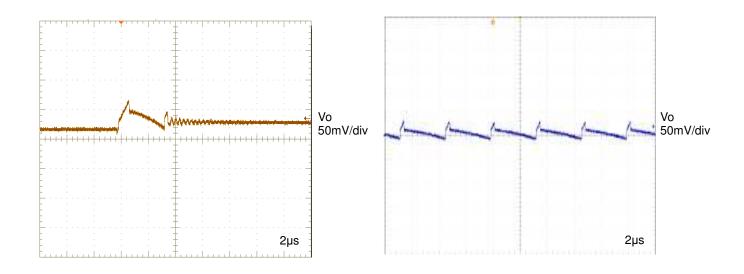


Figure 38. Output Voltage (Vo= 3.3V, SLLM, Io= 0A)

Figure 39. Output Voltage (Vo= 1V, PWM, Io= 0A)

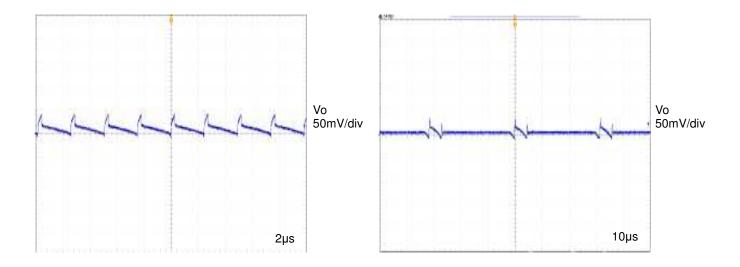


Figure 40. Output Voltage (Vo= 1V, PWM, Io= 8A)

Figure 41. Output Voltage (Vo= 1V, QLLM, Io= 0A)

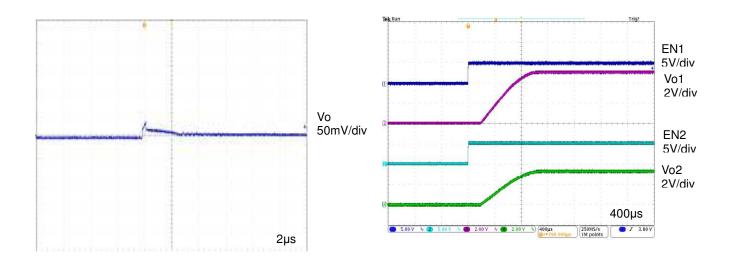
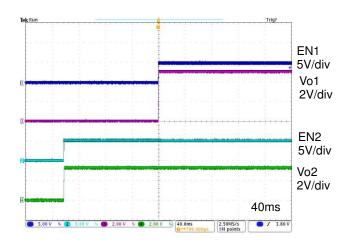


Figure 42. Output Voltage (Vo= 1V, SLLM, Io= 0A)

Figure 43. Start-up (EN1= EN2)



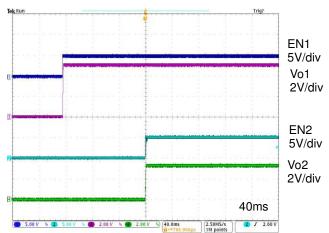
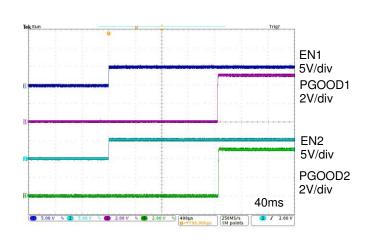


Figure 44. Start-up (EN2→EN1)

Figure 45. Start-up (EN1→EN2)



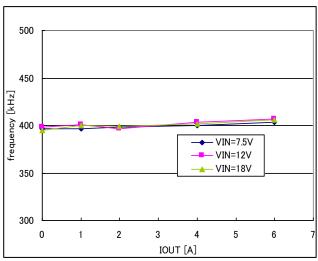
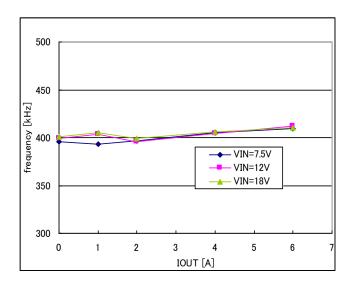


Figure 46. Start-up (EN1/2→PGOOD1/2)

Figure 47. Io-frequency (Vo= 5V, PWM, RFS=  $68k\Omega$ )



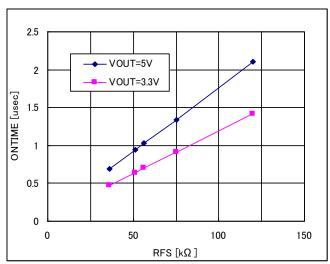
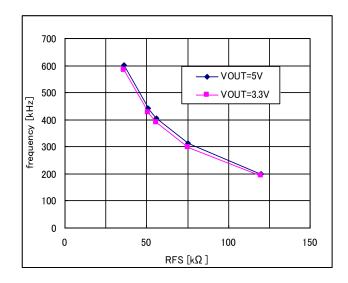


Figure 48. lo-frequency (Vo= 3.3V, PWM, RFS= 68kΩ)

Figure 49. On time-RFS



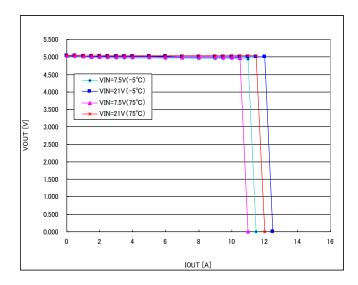
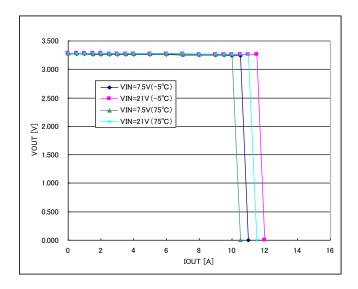


Figure 50. SW Frequency-RFS

Figure 51. Current Limit (Vo= 5V)



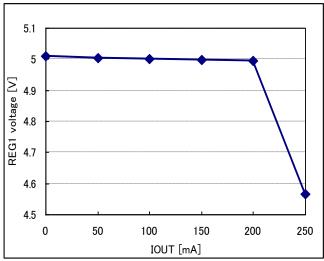


Figure 52. Current Limit (Vo= 3.3V)

Figure 53. REG1 Load Regulation

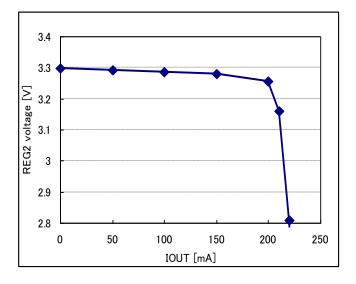


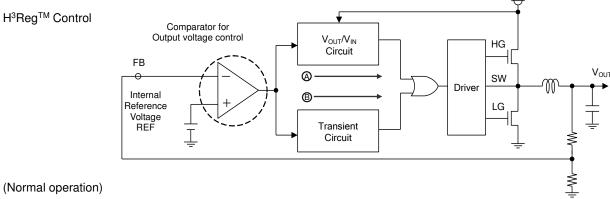
Figure 54. REG2 Load Regulation

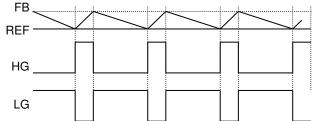
# **Description of Block**

BD95602MUV is a dual channel synchronous buck regulator using H3Reg<sup>TM</sup>, Rohm's latest constant on-time controller technology. Fast load response is achieved by controlling the output voltage using a comparator without relying on the switching frequency.

When Vout drops due to a rapid load change, the system quickly restores Vout by extending the ton time interval. Thus, it serves to improve the regulator's transient response. Activation of the light load mode further increases efficiency by using

Simple Light Load Mode (SLLM) control.





When FB falls to a reference voltage (REF), the drop is detected, activating the H<sup>3</sup>Reg<sup>TM</sup> control system

$$ton = \frac{V_{OUT}}{V_{IN}} \times \frac{1}{f} [sec] \cdot \cdot \cdot (1)$$

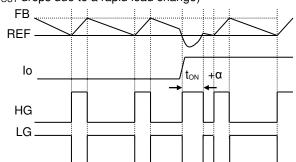
normal operation.

HG output on-time is determined by the formula (1). When HG is off, LG is on until the output voltage becomes

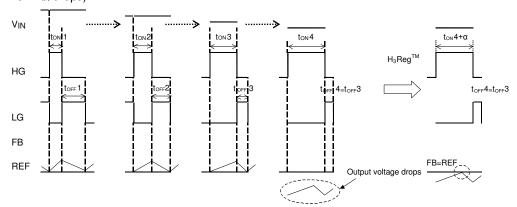
After the status of HG is off, LG go on outputting until output voltage become FB= REF.

When Vout drops due to a rapid load change, and the voltage remains below the output setting following the programmed ton time, the system quickly restores Vout by extending the ton time, thus improving the transient response. Once Vout is restored, the controller continues

(V<sub>OUT</sub> drops due to a rapid load change)



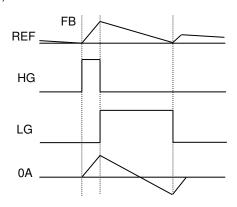
(When V<sub>IN</sub> drops)



Based on the value of VIN, the on-time ton and off-time toff are determined by ton= Vout / VIN x I/f and toff= (VIN- VOUT )/VIN. As the V<sub>IN</sub> voltage drops, in order to maintain the output voltage, toN becomes longer and toFF is shorter. However, for normal operation, if V<sub>IN</sub> drops further, t<sub>ON</sub> is longer and t<sub>OFF</sub>= tminoff (minimum off- time is defined internally), the output voltage will decrease because toFF cannot be any shorter than the minimum off-time. With H³Reg™, if V<sub>IN</sub> goes even lower, the output voltage is maintained as the ton time is extended. (ton time is extended until FB>REF). In this case, the switching frequency is lowered so that the  $t_{\mbox{\scriptsize ON}}$  time can be extended.

# **Description of Block** - continued

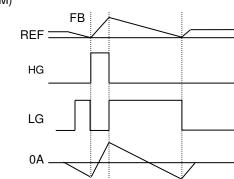
Light Load Control (SLLM)



SLLM will activate when the LG pin is off and the coil current is near 0A (current flows from  $V_{\text{OUT}}$  to SW).

When the FB input is lower than the REF voltage again, HG will be enabled once again.



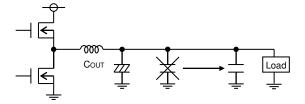


QLLM will activate when the LG pin is off and the coil current is near 0A (current flows from  $V_{\text{OUT}}$  to SW). In this case, the next HG is prevented. Then, when FB falls below the output programmed voltage within the programmed time (Typ= 40µs), HG will resume. In the case where FB doesn't fall in the programmed time, LG is forced on causing  $V_{\text{OUT}}$  to fall. As a result, the next HG is on.

MCTL1	MCTL2	Control Mode	Start-up
L	L	SLLM	PWM
L	Н	QLLM	PWM
Н	Х	PWM	PWM
			i i

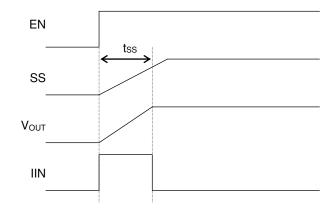
The BD95602MUV operates in PWM mode until the SS input reaches the clamp voltage (2.5V), regardless of the control mode setting, this assures stable operation while the during soft start.

\*Attention: To effect the rapid transient response, the H³Reg™ control monitors the current from the output capacitor to the load using the ESR of the output capacitor Do not use ceramic capacitors on Cout side of power supply. Ceramic bypass capacitors can be used near the individual loads if desired.



# **Timing Chart**

· Soft Start Function



Soft start is exercised with the EN pin set high. Current control takes effect at startup, enabling a moderate output voltage "ramping start." Soft start timing and incoming current are calculated with formulas (2) and (3) below.

· Soft start time

$$tss = \frac{0.7(Typ) \times Css}{2.3\mu A(Typ)} \quad [sec] \cdot \cdot \cdot (2)$$

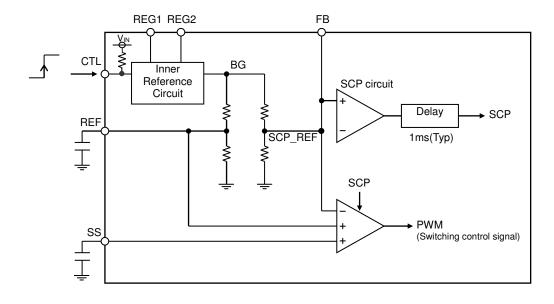
Css(pF)	Soft start time(ms)
18000	5
33000	10
68000	20

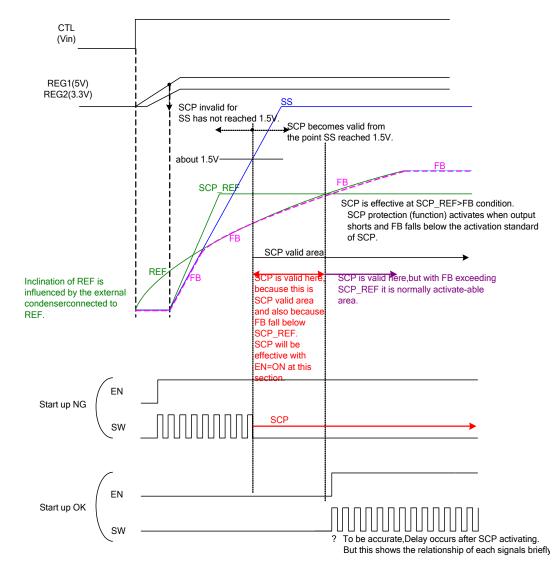
· Inrush current

$$\lim = \frac{\text{Co x V}_{\text{OUT}}}{\text{tss}} \times \frac{\text{V}_{\text{OUT}}}{\text{V}_{\text{IN}}} [A] \cdot \cdot \cdot (3)$$

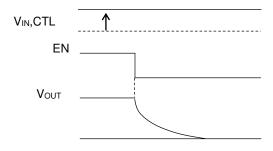
# Timing Chart - continued

• Notes when waking up with CTL pin or V<sub>IN</sub> pin If EN pin is high or short (or pull up resistor) to REG1 pin, IC starts up by switching CTL pin, the IC might fail to start up (SCP function) with the reason below, please be careful of SS pin and REF pin capacitor capacity.





# **Output Discharge**

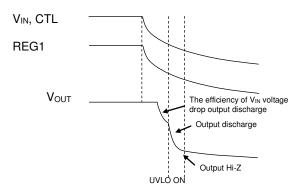


It will be available to use if connecting V<sub>OUT</sub> pin to DC/DC output. (about  $100\Omega$ ) . Discharge function operates when <1> EN='L' <2> UVLO= ON(If input voltage is low) <3> SCP latch <4> TSD= ON.

The function at output discharge time is shown as left.

[1] When switch to low from high with EN pin.

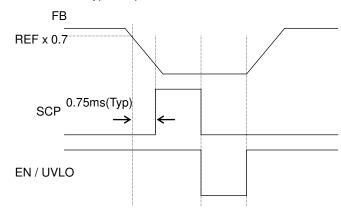
If EN pin voltage is below than EN threshold voltage, output discharge function is operated, and discharge output capacitor charge.



[2] When switch to low from high with EN pin

- 1) IC is in normal operation until REG1 voltage becomes lower than UVLO voltage. However, because  $V_{\text{IN}}$  voltage also becomes low, output voltage will drop, too.
- 2) If REG1 voltage reaches the UVLO voltage, output discharge function is operated, and discharge output capacitor charge.
- In addition, if REG1 voltage drops, inner IC logic cannot operate, so that output discharge function does not work, and becomes output Hi-z. (In case, FB has resistor against ground, discharge at the resistor.)

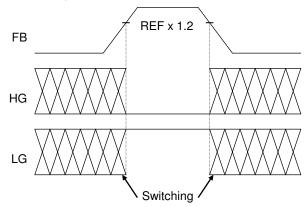
• Timer Latch Type Output Short Circuit Protection



Short protection is enabled when the output voltage falls to or below REF X 0.7.

Once the programmed time period has elapsed, the output is latched off to prevent destruction of the circuit. (HG= Low, LG= Low) Output voltage can be restored either by cycling the EN pin or disabling UVLO.

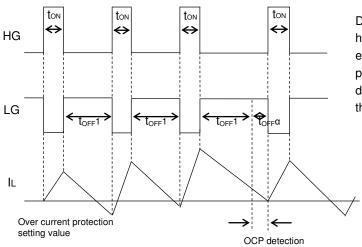
Over Voltage Protection



When the output voltage increases to or above REF x 1.2(Typ), output over voltage protection is enabled, and the Low-side FET turns on to reduce the output. (LG= High, HG= Low).

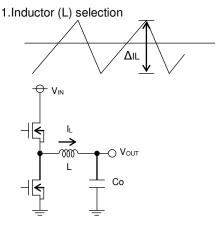
When the output falls to within normal operation, the function is restored to normal operation.

· Over current protection circuit



During normal operation, if FB is less than REF, HG is high during the time  $t_{\text{ON}}$ , but when the coil current exceeds the  $I_{\text{LIMIT}}$  threshold, HG is set to off. The next pulse returns to normal operation if the output voltage drops after the maximum on-time or  $I_{\text{L}}$  becomes lower than  $I_{\text{LIMIT}}$ .

# **Selection of Components Externally Connected**



Output ripple current

The inductor value is a major influence on the output ripple current. As formula (4) below indicates, the greater the inductor or the switching frequency, the lower the ripple current.

$$\Delta IL = \frac{(V_{IIN} - V_{OUT}) \times V_{OUT}}{L \times V_{IN} \times f} [A] \cdot \cdot \cdot (4)$$

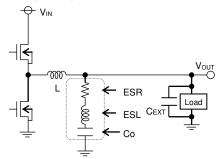
Generally, lower inductance values offer faster response times but also result in increased output ripple and lower efficiency.

0.47μH to 2.2μH are recommended as appropriate setting value.

The peak current rating of coil is approximated by formula (5). Please select inductor which is higher than this value.

$$I_{LPEAK} = I_{OUTMAX} + \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{2 \times L \times V_{IN} \times f} [A] \cdot \cdot \cdot (5)$$

### 2. Output Capacitor (Co) Selection



**Output Capacitor** 

The output capacitor should be determined by equivalent series resistance and equivalent series inductance so that the output ripple voltage is 30mV or more.

The rating of the capacitor is selected with sufficient margin given the output voltage.

$$\Delta V_{OUT} = \Delta IL \times ESR + ESL \times \Delta IL / t_{ON} \cdot \cdot \cdot \cdot (6)$$

ΔIL: Output ripple current

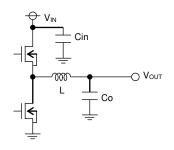
ESR: Equivalent series resistance, ESL: Equivalent series inductance

Please give due consideration to the conditions in formula (7) below for the output capacitor, bearing in mind that the output start-up time must be established within the soft start timeframe. Capacitors used as bypass capacitors are connected to the load side affect the overall output capacitance (Cext, figure above). Please set the soft start time or over-current detection value, regarding these capacities.

$$Co+C_{EXT} \le \frac{T_{SS} \ x \ (Limit-l_{OUT})}{V_{OUT}} \cdot \cdot \cdot (7)$$
 $T_{SS} : Soft start time$ 
Limit : Over current detection

Note: If an inappropriate capacitor is used, OCP may be detected during activation and may cause startup malfunctions.

### 3. Input Capacitor (Cin) Selection



Input Capacitor

The input capacitor selected must have low enough ESR to fully support high output ripple so as to prevent extreme over current conditions. The formula for ripple current IRMS is given in (8) below.

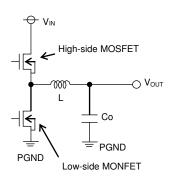
IRMS= I<sub>OUT</sub> x 
$$\frac{\sqrt{V_{OUT} (V_{IN}-V_{OUT})}}{V_{IN}}$$
 [A] · · · (8)  
Where V<sub>IN</sub>= 2 x V<sub>OUT</sub>, IRMS=  $\frac{I_{OUT}}{2}$ 

A ceramic capacitor is recommended to reduce ESR loss and maximize efficiency.

<sup>\*</sup>Passing a current larger than inductor's rated current will cause magnetic saturation in the inductor and decrease system efficiency. In selecting the inductor, be sure to allow enough margin to assure that peak current does not exceed the inductor rated current value.

<sup>\*</sup>To minimize possible inductor damage and maximize efficiency, choose an inductor with a low (DCR, ACR) resistance.

### 4.MOSFET Selection



High-side driver and Low-side driver are designed to activate N channel MOSFET's with low on-resistance.

The chosen MOSFET may result in the loss described below, please select a proper FET for each considering the input-output and load current.

< Loss of High-side MOSFET >

Pmain= PRON+PTRAN

$$= \frac{V_{OUT}}{V_{IN}} \times Ron \times I_{OUT}^2 + \frac{(Tr+Tf) \times V_{IN} \times I_{OUT} \times f}{6} \cdot \cdot \cdot (9)$$

(Ron: On-resistance of FET f: Switching frequency

Tr: Rise time, Tf: Fall time)

< Loss of Low-side MOSFET >

Psyn= PRON

$$= \frac{V_{IN} - V_{OUT}}{V_{IN}} \times RON \times I_{OUT}^{2} \qquad \cdot \cdot \cdot (10)$$

The High-side MOSFET generates loss when switching, along with the loss due to on-resistance. Good efficiency is achieved by selecting a MOSFET with low on-resistance and low Qg (gate total charge amount). Recommended MOSFETs for various current values are as follows:

Output current	High-side MOSFET	Low-side MOSFET
to 5A	RQ3E080GN	RQ3E100GN
5 to 8A	RQ3E120GN	RQ3E150GN
8 to 10A	RQ3E150GN	RQ3E180GN

### 5. Output Voltage Set Point

This IC operates such that output voltage is REF ≅ FB.

<Output Voltage>

$$V_{OUT} = \frac{(R1+R2)}{R2} \times REF(0.7V) + \frac{1}{2} \Delta V_{OUT}$$

(ΔV<sub>OUT</sub>: Output ripple voltage)

 $\Delta V_{OUT} = \Delta I_L \times ESR$ 

(ΔI<sub>L</sub>: ripple current of coil)

$$\Delta I_L = (V_{IN} - V_{OUT}) \times \frac{V_{OUT}}{(L \times V_{IN} \times f)}$$

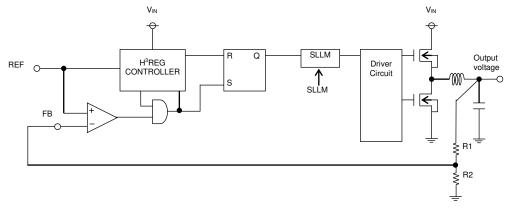
L: inductance[H] f: switching frequency[Hz]

(Example) V\_{IN=} 20V, V\_{OUT=} 5V, f= 300kHz, L= 
$$2.5\mu H$$
, ESR=  $20m\Omega$ , R1=  $56k\Omega$ , R2=  $9.1k\Omega$ 

$$\Delta I_L = (20V-5V) \times \frac{5V}{(2.5 \times 10^{-6} H \times 20V \times 300 \times 10^3 Hz)} = 5(A)$$

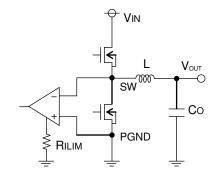
 $\Delta V_{OUT} = 5A \times 20 \times 10^{-3}\Omega = 0.1(V)$ 

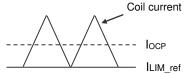
$$V_{OUT} = 0.7V \times \frac{(51k\Omega + 9.1k\Omega)}{9.1k\Omega} + \frac{1}{2} \times 0.1V = 5.057(V)$$



<sup>\*(</sup>Notice)Please set output ripple voltage more than 30mV to 50mV.

### 6. Setting over current protection





The on resistance (between SW and PGND) of the low side MOSFET is used to set the over current protection.

Over current reference voltage (I<sub>LIM\_ref</sub>) is determined as in formula(11) below.

$$I_{\text{LIM\_ref}} = \frac{10k}{R_{\text{ILIM}}[k\Omega] \ x \ R_{\text{ON}}[m\Omega]} \ [A] \cdot \cdot \cdot (11)$$

 $(R_{ILIM}$ : Resistance for setting of over current voltage protection value[ $k\Omega$ ]  $R_{ON}$ : Low-side on resistance value of  $FET[m\Omega]$ )

Over current protection is actually determined by the formula (12) below.

$$I_{\text{ocp}} = I_{\text{LIM\_ref}} + \frac{1}{2} \Delta I_{\text{L}}$$

$$= I_{\text{LIM\_ref}} + \frac{1}{2} \times \frac{V_{\text{IN}} - V_{\text{O}}}{I} \times \frac{I}{f} \times \frac{V_{\text{O}}}{V_{\text{IN}}} \cdot \cdot \cdot (12)$$

ΔIL:Coil ripple current[A]

V<sub>IN</sub>:Input voltage[V]

Vo:Output voltage [V]

f:Switching frequency [Hz]

L:Inductance [H]

### (Example)

If a load current 5A is desired with V<sub>IN</sub>=6 to 19V, V<sub>OUT</sub>=5V, f=400kHZ, L=2.5μH, RON=20mΩ, the formula would be:

$$I_{\text{OCP}} = \frac{10k}{-\text{RILIM}[k\Omega] \times \text{RON}[m\Omega]} + \frac{1}{2} \times \frac{V_{\text{IN}} - V_{\text{O}}}{L} \times \frac{I}{f} \times \frac{V_{\text{O}}}{V_{\text{IN}}} > 5$$

When  $V_{IN}=6V$ ,  $I_{OCP}$  will be minimum(this is because the ripple current is also minimum) so that if each condition is input, the formula will be the following: RILIM<109.1[k $\Omega$ ].

\*To design the actual board, please consider enough margin for FET on resistance variation, Inductance variation, IC over current reference value variation, and frequency variation.

### 7. Relation between output voltage and ton time

For BD95602MUV, both channels, are high efficiency synchronous regulator controllers with variable frequency.  $t_{ON}$  time varies with Input voltage [ $V_{IN}$ ], output voltage [ $V_{OUT}$ ], and RFS of FS pin resistance. See Figure 52 and Figure 53 for  $t_{ON}$  time.

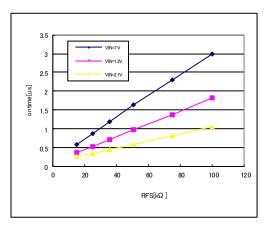


Figure 55. RFS - ontime (Vout = 5V)

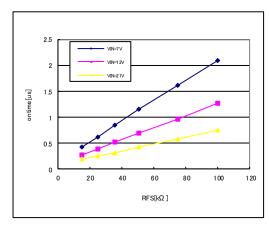


Figure 56. RFS - ontime (Vout = 3.3V)

From ton time, frequency on application condition is following:

Frequency = 
$$\frac{V_{OUT}}{V_{IN}} \times \frac{1}{t_{ON}} [kHz] \cdot \cdot \cdot (13)$$

However, real-life considerations (such as the external MOSFET gate capacitor and switching speed) must be factored in as they affect the overall switching rise and fall time, so please confirm by experiment.

**Application Example** (Vin= 12V, Vo1= 3.3V/8A, f1= 400kHz, Vo2= 2.5V/8A, f2= 400kHz)

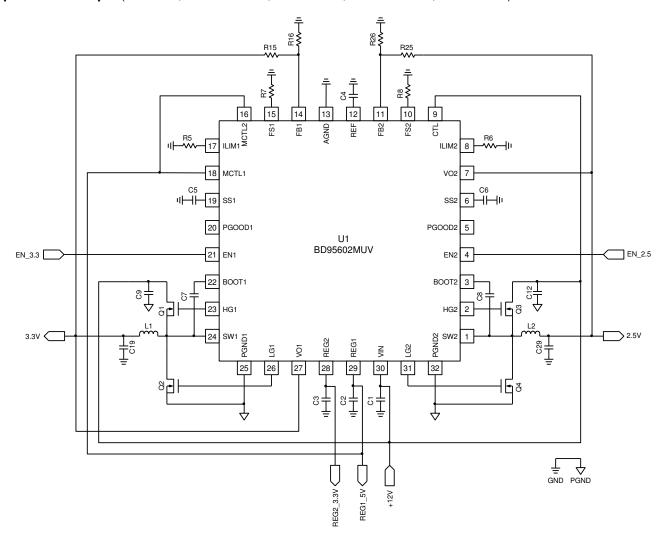
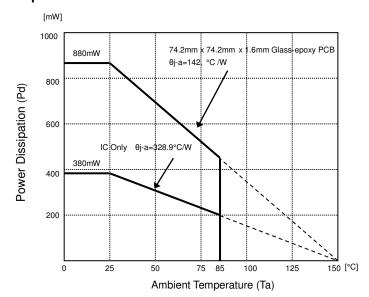


Figure 57. Application Example

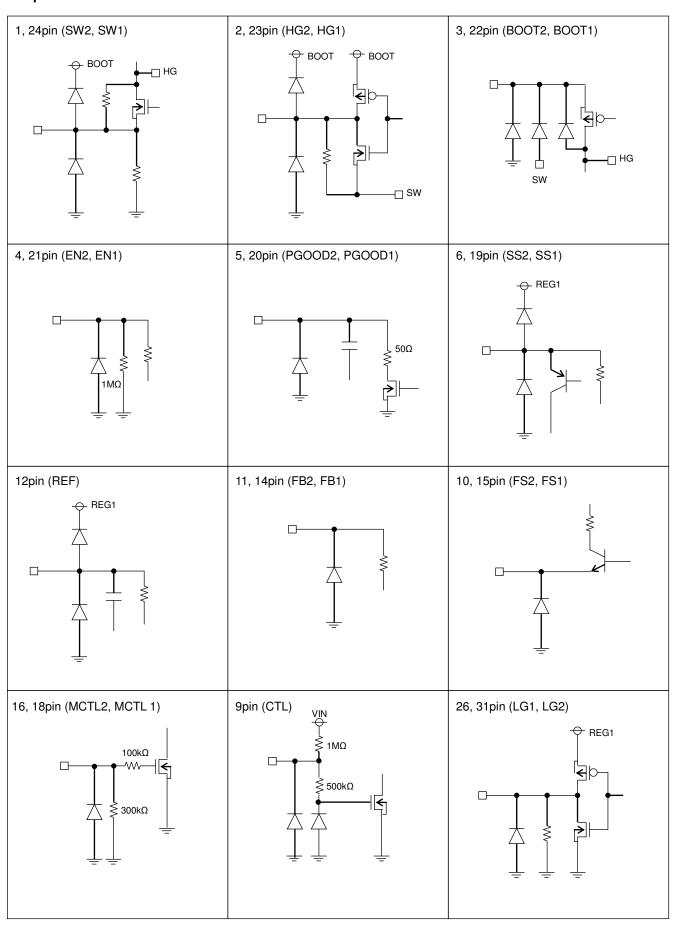
Reference Designator	Туре	Value	Description	Manufacturer Part Number	Manufacturer	Configuration (mm)
C1, C9, C10, C11, C12	Ceramic Capacitor	10μF	35V, X5R, ±10%	GRM32ER6YA106KA12	MURATA	3225
C2, C3, C4	Ceramic Capacitor	10μF	16V, X5R, ±10%	GRM21BR61C106ME15	MURATA	2012
C5, C6	Ceramic Capacitor	0.1μF	16V, X5R, ±10%	GRM155R61C104KA88	MURATA	1005
C7, C8	Ceramic Capacitor	0.47μF	10V, X5R, ±10%	GRM188R61A474KA61	MURATA	1608
C18, C19, C28, C29	POSCAP	330μF	6.3V, ±20%, ESR 18mΩmax	6TPE330MIL	SANYO	7343
L1,L2	Inductor	1μΗ	±20%,10A(L=-30%), DCR=5.8mΩ±10%	GLMC1R003A	ALPS	6565
Q1, Q3	MOSFET	-	N-ch, Vdss 30V, ld 15A, Ron 4.7m $\Omega$	RQ3E150GN	ROHM	3333
Q2, Q4	MOSFET	-	N-ch, Vdss 30V, ld 18A, Ron $3.3m\Omega$	RQ3E180GN	ROHM	3333
R5, R6	Resistor	62kΩ	1/16W, 50V, 5%	MCR01MZPJ623	ROHM	1005
R7, R8	Resistor	51kΩ	1/16W, 50V, 5%	MCR01MZPJ513	ROHM	1005
R15	Resistor	16kΩ	1/16W, 50V, 0.5%	MCR01MZPD1602	ROHM	1005
R16	Resistor	4.3kΩ	1/16W, 50V, 0.5%	MCR01MZPD4301	ROHM	1005
R24	Resistor	100Ω	1/16W, 50V, 5%	MCR01MZPJ101	ROHM	1005
R25	Resistor	12kΩ	1/16W, 50V, 0.5%	MCR01MZPD1202	ROHM	1005
R26	Resistor	4.7kΩ	1/16W, 50V, 0.5%	MCR01MZPD4701	ROHM	1005
U1	IC	-	Buck DC/DC Controller	BD95602MUV	ROHM	VQFN032V5050

Without any ripple (about 10mV), there is a possibility that the FB signal is not stable due to the adoption of the comparator control method. Please ensure enough ripple voltage either by (1)reducing the L-value of inductor, or (2)using high ESR output capacitor. Ripple voltage can be generated in FB terminal by adding a capacitor in parallel to resistor (R17, R19) of the FB input, but the circuit will be sensitive to noise from the output (Vo1/Vo2) line and is not recommended. Stability of the circuit is influenced by the layout of the PCB, please pay careful attention to the layout.

# **Power Dissipation**

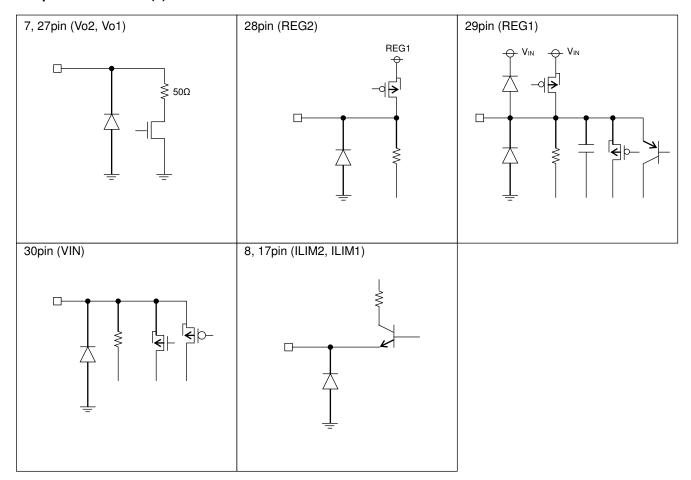


# I/O equivalence circuits



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# I/O equivalence circuit(s) - continued



### **Operational Notes**

### 1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

### 2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

### 3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

### 4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

### 5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. The absolute maximum rating of the Pd stated in this specification is when the IC is mounted on a 70mm x 70mm x 1.6mm glass epoxy board. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

### 6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

### 7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

### 8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

### 9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

### 10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

# **Operational Notes - continued**

### 11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

### 12. Regarding the Input Pin of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode.

When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

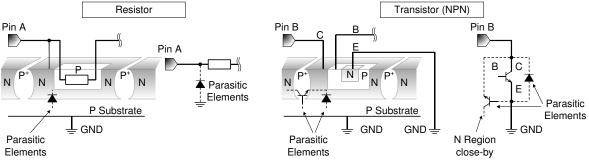


Figure 58. Example of monolithic IC structure

### 13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

### 14. Area of Safe Operation (ASO)

Operate the IC such that the output voltage, output current, and power dissipation are all within the Area of Safe Operation (ASO).

### 15. Thermal Shutdown Circuit(TSD)

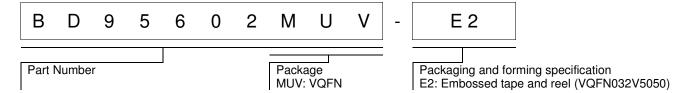
This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's power dissipation rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF all output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

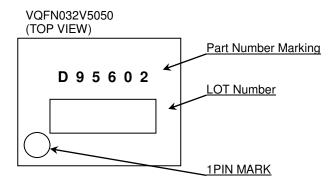
### 16. Over Current Protection Circuit (OCP)

This IC incorporates an integrated overcurrent protection circuit that is activated when the load is shorted. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation or transitioning of the protection circuit.

# **Ordering Information**



# **Marking Diagrams**



Physical Dimension, Tape and Reel Information Package Name VQFN032V5050 5.  $0\pm0$ . 1 0±0 1PIN MARK 0 MAX  $0.2_{\,-0.02}^{\,+0.03}$ 0. 08 S (0) C0. 2 3.  $4\pm0.1$ 32  $4 \pm 0.1$ 0 25 (UNIT:mm) PKG: VQFN032V5050  $0.25_{\,-0.04}^{\,+0.05}$ 0.75 0. 5 Drawing No. EX461-5001-2 <Tape and Reel information> Tape Embossed carrier tape Quantity 2500pcs Direction ( The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand of feed Direction of feed Reel \*Order quantity needs to be multiple of the minimum quantity.

# **Revision History**

Date	Revision	Changes
6.Sep.2013	001	New Release
26.Jun.2015	002	P.31 Change "the description" of L1,L2

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JAPAN	USA	EU	CHINA
CLASSⅢ	CL ACCTI	CLASSIIb	CI Λ00π
CLASSIV	CLASSⅢ	CLASSⅢ	- CLASSIII

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  - [f] Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
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- 8. Confirm that operation temperature is within the specified range described in the product specification.
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For details, please refer to ROHM Mounting specification

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This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

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  - [c] the Products are exposed to direct sunshine or condensation
  - [d] the Products are exposed to high Electrostatic
- 2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.
- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
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