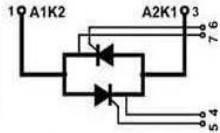


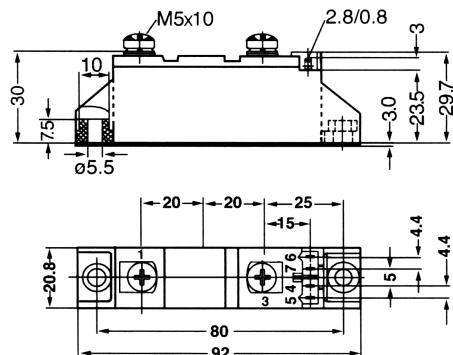
# SSAC18

## Solid State AC Controller(Anti-Parallel Thyristor-Thyristor Modules)



Type	$V_{RSM}$ V	$V_{RRM}$ V
	$V_{DSM}$	$V_{DRM}$
<b>SSAC18GK08</b>	900	800
<b>SSAC18GK12</b>	1300	1200
<b>SSAC18GK14</b>	1500	1400
<b>SSAC18GK16</b>	1700	1600
<b>SSAC18GK18</b>	1900	1800

Dimensions in mm (1mm=0.0394")



Symbol	Test Conditions	Maximum Ratings	Unit
$I_{TRMS}, I_{FRMS}$ $I_{TAVM}, I_{FAVM}$	$T_{VJ}=T_{VJM}$ $T_c=85^\circ C$ ; $180^\circ$ sine	40 18	A
$I_{TSM}, I_{FSM}$	$T_{VJ}=45^\circ C$ $V_R=0$	400 420	A
	$T_{VJ}=T_{VJM}$ $V_R=0$	350 370	
$\int i^2 dt$	$T_{VJ}=45^\circ C$ $V_R=0$	800 730	$A^2 s$
	$T_{VJ}=T_{VJM}$ $V_R=0$	600 570	
$(di/dt)_{cr}$	$T_{VJ}=T_{VJM}$ $f=50Hz, t_p=200\mu s$ $V_D=2/3V_{DRM}$ $I_G=0.45A$ $dI/dt=0.45A/\mu s$	150 500	$A/\mu s$
	repetitive, $I_T=45A$ non repetitive, $I_T=I_{TAVM}$		
$(dv/dt)_{cr}$	$T_{VJ}=T_{VJM};$ $R_{GK}=\infty$ ; method 1 (linear voltage rise)	1000	$V/\mu s$
$P_{GM}$	$T_{VJ}=T_{VJM}$ $I_T=I_{TAVM}$	10 5	W
$P_{GAV}$		0.5	W
$V_{RGM}$		10	V
$T_{VJ}$ $T_{VJM}$ $T_{stg}$		-40...+125 125 -40...+125	$^\circ C$
$V_{ISOL}$	50/60Hz, RMS $I_{ISOL}\leq 1mA$	3000 3600	$V_\sim$
$M_d$	Mounting torque (M5) Terminal connection torque (M5)	2.5-4.0/22-35 2.5-4.0/22-35	Nm/lb.in.
<b>Weight</b>	Typical including screws	90	g

# SSAC18

## Solid State AC Controller(Anti-Parallel Thyristor-Thyristor Modules)

Symbol	Test Conditions	Characteristic Values	Unit
$I_{RRM}, I_{DRM}$	$T_{VJ}=T_{VJM}; V_R=V_{RRM}; V_D=V_{DRM}$	3	mA
$V_T, V_F$	$I_T, I_F=80A; T_{VJ}=25^\circ C$	2.05	V
$V_{TO}$	For power-loss calculations only ( $T_{VJ}=125^\circ C$ )	0.85	V
$r_T$		18	$m\Omega$
$V_{GT}$	$V_D=6V; T_{VJ}=25^\circ C$ $T_{VJ}=-40^\circ C$	1.5 1.6	V
$I_{GT}$	$V_D=6V; T_{VJ}=25^\circ C$ $T_{VJ}=-40^\circ C$	100 200	mA
$V_{GD}$	$T_{VJ}=T_{VJM}; V_D=2/3V_{DRM}$	0.2	V
$I_{GD}$		10	mA
$I_L$	$T_{VJ}=25^\circ C; t_p=10\mu s; V_D=6V$ $I_G=0.45A; dI/dt=0.45A/\mu s$	450	mA
$I_H$	$T_{VJ}=25^\circ C; V_D=6V; R_{GK}=\infty$	200	mA
$t_{gd}$	$T_{VJ}=25^\circ C; V_D=1/2V_{DRM}$ $I_G=0.45A; dI/dt=0.45A/\mu s$	2	us
$t_q$	$T_{VJ}=T_{VJM}; I_T=20A; t_p=200\mu s; -dI/dt=10A/\mu s$ $V_R=100V; dv/dt=20V/\mu s; V_D=2/3V_{DRM}$	typ. 150	us
$Q_s$	$T_{VJ}=T_{VJM}; I_T, I_F=25A; -dI/dt=0.64A/\mu s$	50	uC
$I_{RM}$		6	A
$R_{thJC}$	per thyristor/diode; DC current per module	1.3 0.65	K/W
$R_{thJK}$	per thyristor/diode; DC current per module	1.5 0.75	K/W
$ds$	Creeping distance on surface	12.7	mm
$da$	Strike distance through air	9.6	mm
$a$	Maximum allowable acceleration	50	$m/s^2$

### FEATURES

- \* International standard package
- \* Copper Base Plate with Inter-DCB
- \* Planar passivated chips
- \* Isolation voltage 3600 V~

### APPLICATIONS

- \* DC motor control
- \* Softstart AC motor controller
- \* Light, heat and temperature control

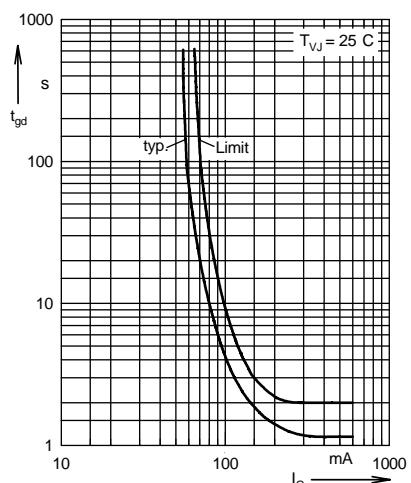
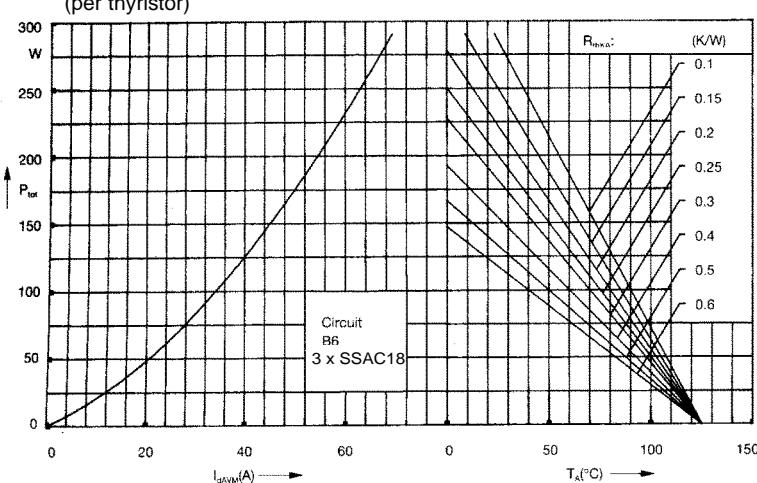
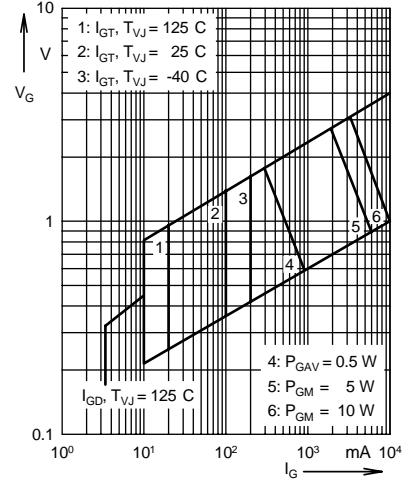
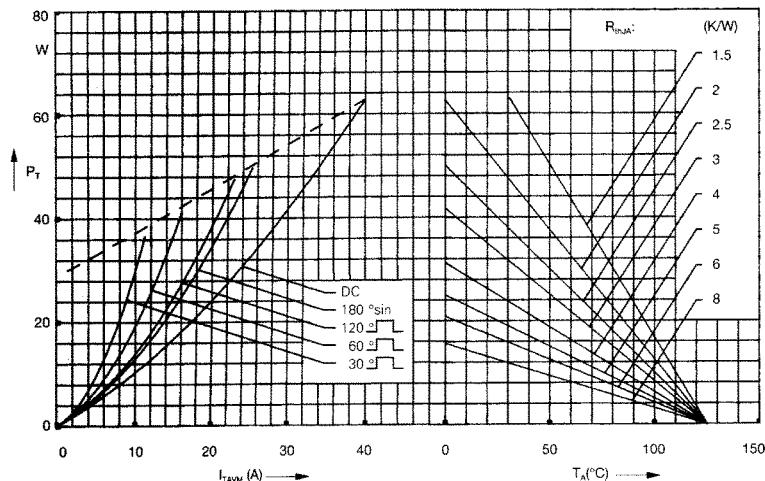
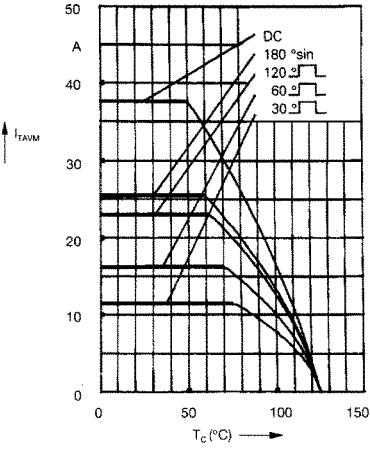
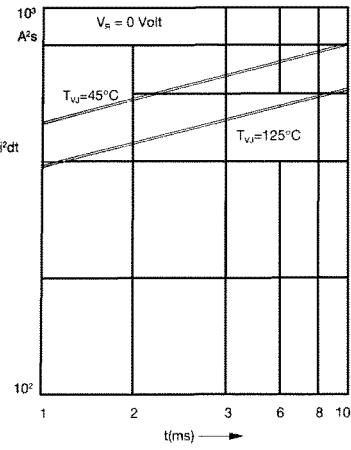
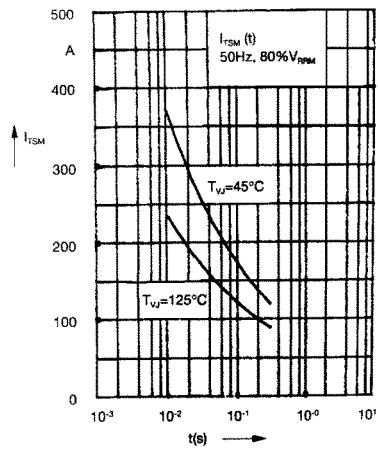
### ADVANTAGES

- \* Space and weight savings
- \* Simple mounting with two screws
- \* Improved temperature and power cycling
- \* Reduced protection circuits



# SSAC18

## Solid State AC Controller(Anti-Parallel Thyristor-Thyristor Modules)



# SSAC18

## Solid State AC Controller(Anti-Parallel Thyristor-Thyristor Modules)

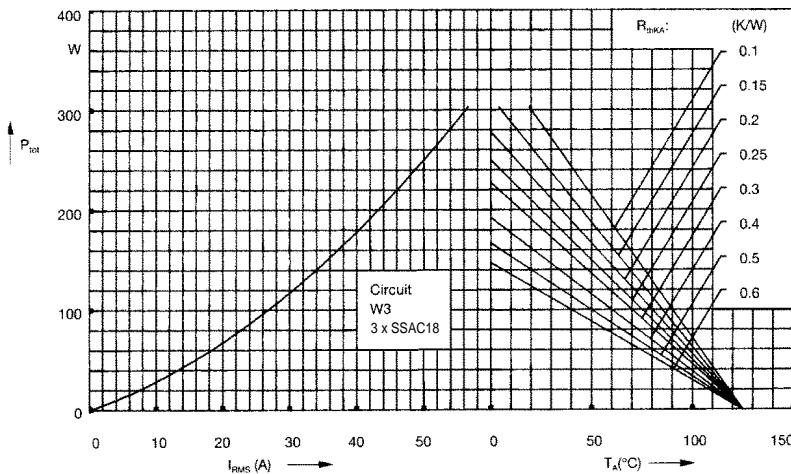


Fig. 7 Three phase AC-controller:  
Power dissipation versus RMS  
output current and ambient  
temperature

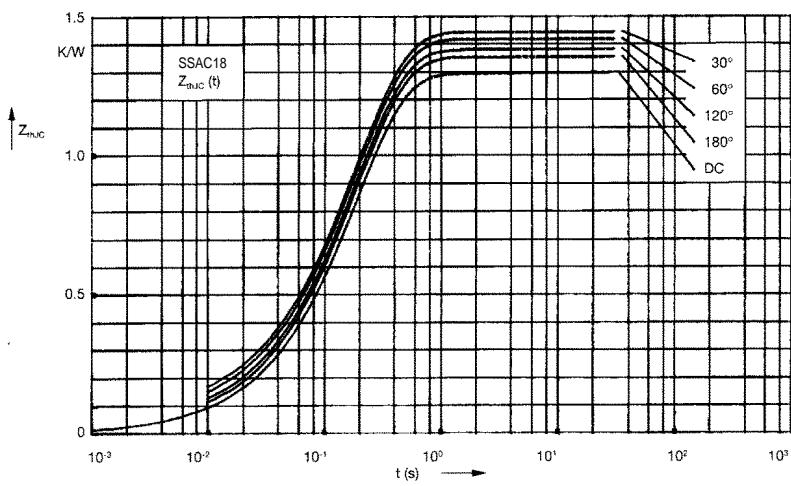


Fig. 8 Transient thermal impedance  
junction to case (per thyristor)

$R_{thJC}$  for various conduction angles d:

d	$R_{thJC}$ (K/W)
DC	1.3
180°C	1.35
120°C	1.39
60°C	1.42
30°C	1.45

Constants for  $Z_{thJC}$  calculation:

i	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.018	0.0033
2	0.041	0.0216
3	1.241	0.191

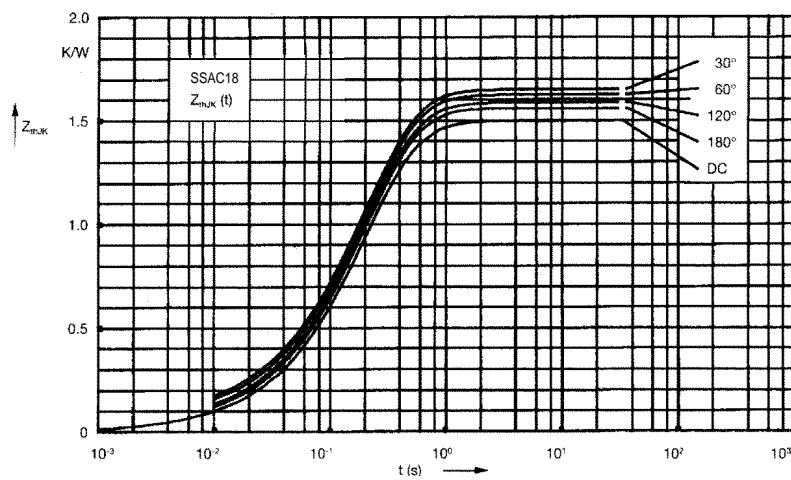


Fig. 9 Transient thermal impedance  
junction to heatsink (per thyristor)

$R_{thJK}$  for various conduction angles d:

d	$R_{thJK}$ (K/W)
DC	1.5
180°C	1.55
120°C	1.59
60°C	1.62
30°C	1.65

Constants for  $Z_{thJK}$  calculation:

i	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.018	0.0033
2	0.041	0.0216
3	1.241	0.191
4	0.2	0.46