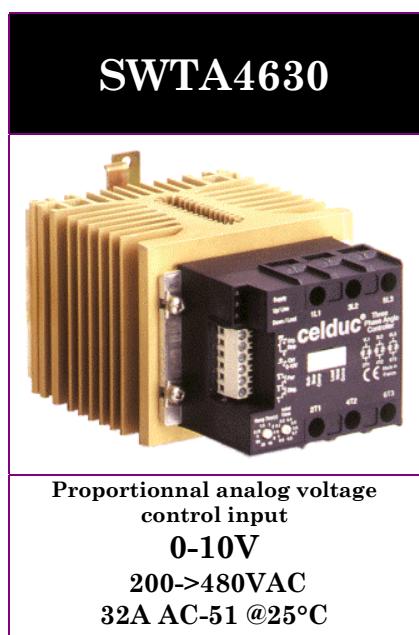


## DIGITAL THREE PHASE ANGLE CONTROLLER

- ▶ Allows to set the voltage applied to different sort of loads with 3 wires, 4 wires or inside the delta wiring:
  - ▶ Resistive (Bulbs, UV and IR lamps, ovens, ...),
  - ▶ Inductive (inductors, transformers, ...),
  - ▶ Motor (motorfan speed control (60 to 100% from the nominal speed),
  - ▶ Rectified (power supplies, ...).
- ▶ Small housing, easy and ready to use.
- ▶ Large mains frequency and voltage range.
- ▶ Fully optoisolated full cycle three phase phase angle controller (balanced currents, less harmonics, ...)
- ▶ Dynamic control voltage range according to the power factor of the load.
- ▶ Softstart and softstop functions (increase lifetime expectancy of the load).
- ▶ Adjustable filter regarding fast input voltage changes (ramps).
- ▶ Motor softstarting functions to control its speed within the stable area.
- ▶ Input-output transfert characteristic linearization function (resistive load).
- ▶ Diagnostic features : Status given on LED and AC/DC switches.



Mains Voltage	Mains Frequency	Max AC-51 Current	Max AC-53a Current	Control Input	Status Outputs	In / Out Insulation	Wire Size	Dimensions (WxHxD)	Weight
200 to 480VAC	40 to 65Hz	25A @40°C	25A @40°C	0-10VDC	0 to 24VDC 1A AC/DC	4kV	In=2.5mm² Out=10mm²	110x110x180 (mm)	2000g

Fig. 1

### TYPICAL APPLICATIONS

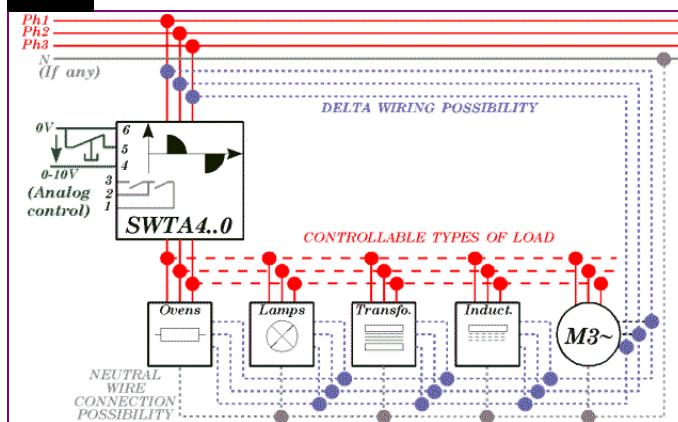


Fig. 2

### WIRING DIAGRAM

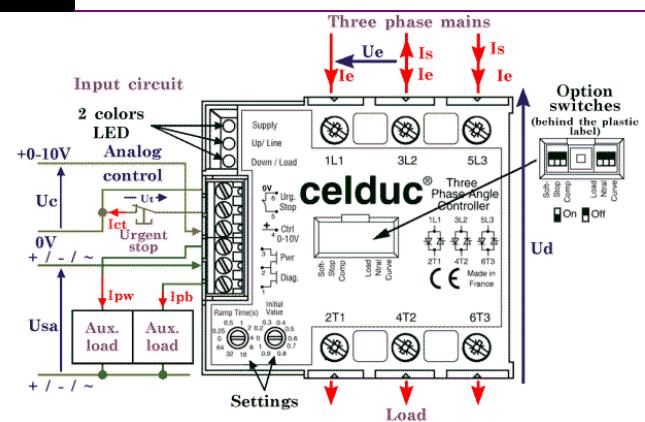


Fig. 3

### PHASE ANGLE CONTROL DESCRIPTION

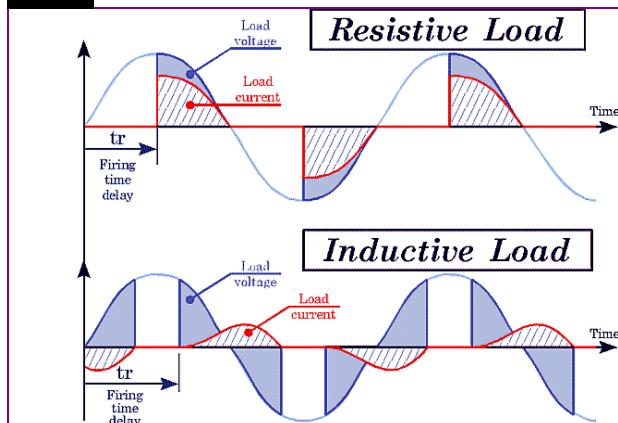
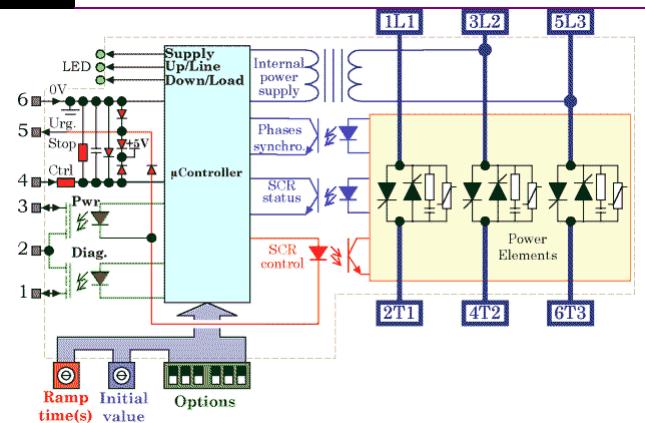


Fig. 4

### INTERNAL DIAGRAM



Proud to serve you

## SETTINGS

SETTINGS AND OPTIONS	Label	“Ramp Time (s)”	“Initial Value”	“Soft Stop”	“Comp”	“Load”	“Ntrl”	“Curve”
	Description	Ramp Time(s) 0.5 1 0.25 0.4 0 0.5 64 16 32 8	Initial Value 0.2 0.3 0.4 0.5 0.6 0.7 0.9 0.8					
Function	Ramp up time (Softstart and smooth transients)	Initial load voltage (footstep)	Ramp down time	Allows to adapt the control signal range whatever the power factor of the load	Ask the unit to make a softstart up to the max. before analog control.	Tells the unit the load star point is connected to the mains neutral	Tells the unit what kind of in-out response to use (angle or RMS voltage linearity)	
Setting possibilities	White squares = buttons Example :  = all switches down (OFF) (factory setting)	Ts= 0 to 64s	Vi=0 to 100 %	 <b>0 x ts =</b>  <b>0,5 x ts =</b>  <b>ts =</b>  <b>2 x ts =</b> 	<b>On (Up)</b>  <b>Inductive load</b>	<b>On (Up)</b>  Motor	<b>On (Up)</b>  Star wiring with neutral (4 wires)	<b>On (Up)</b>  RMS voltage control
				<b>Off (Down)</b>  Resistive load	<b>Off (Down)</b>  Other loads than motors	<b>Off (Down)</b>  Delta or star without neutral	<b>Off (Down)</b>  Phase angle control	

## INPUT CHARACTERISTICS

INPUT CIRCUIT	CHARACTERISTIC	LABEL	VALUE		INFO.
	Labels		“0-10V”	“Urg. Stop”	
	Function		Analog control input		Stop the thyristor controls
	Control type		DC control voltage		Opening the connection between 5 & 6
	Terminals		4 & 6		5 & 6
	Control voltage range	Uc	0-10VDC		-
	Release and control threshold voltage	Ucsmin	0.3VDC		-
	Full power threshold control voltage	Ucsmax	9.7VDC		-
	Max. input voltage	Ucmax	30VDC		6VDC
	Max. reverse voltage	-Ucmax	30VDC		6VDC
	Release voltage	Ut	>1,5V		
	Input impedance	Re	100kΩ		-
	Current to switch	Ict	-		Ict=f(Ut)

STATUS OUTPUTS	Labels		“Diag. “	“Pwr“	
	Terminals		1 & 2	2 & 3	
	Function		Indicates a problem detected in the circuit configuration	Indicates the load is supplied	
	Nominal operating voltage	Usan	24VAC/DC		
	Operating voltage range	Usa	0->28VAC/DC		
	Max. peak voltage	Usap	60V		
	Overvoltage protection		Built-in 25V size7 varistors		
	Minimum load current	Ipw/Ipb	0A		
	Maximum load current	Ipw/Ipb	1A AC/DC		
	Maximum overload current	Ipw/Ipb	2.4A AC/DC		
	On and off state switch resistance	Ron / Roff	500mΩ / 100MΩ		
	On and off time delay	Ton / Toff	0.5ms / 2ms		

## OUTPUT CHARACTERISTICS

POWER CIRCUIT	CHARACTERISTIC	LABEL	VALUE				INFO.
	Mains voltage range	Ue	200 -> 480VAC				
	Non-repetitive peak voltage	Uep	1200V				
	Overvoltage protection	VDR	Built-in 510V size 14 varistors				
	Maximum nominal currents	Ie	Resistive I <sub>thmax AC51</sub>	Resistive I <sub>th AC51</sub>	Motor I <sub>emax AC53a</sub>	Motor I <sub>e AC53a</sub>	@40°C See fig. 7 Delta wiring : See installation manual
			25A	16A (EN60947-4-3)	25A	16A (EN60947-4-2)	
	Maximum line currents in delta wiring	ILine	43A	28A (EN60947-4-3)	43A	28A (EN60947-4-2)	
	Max motor power	Pe	11kW @400VAC star connection				@40°C
	Non-repetitive peak overload current (1 cycle of 10ms)	ITSM	1500A				See fig. 8
	Melting limit for choosing the protective fuses	I <sup>2</sup> t	11000A <sup>2</sup> s				@10ms
	Minimum load current	Iemin	100mA				
	Maximum leakage current	Ielk	7mA				@400VAC 50Hz
	Power factor	Pf	0->1				
	Mains frequency range	F	40->65Hz				
	Max. off-state voltage rise	dv/dt	500V/μs				
	Protection against fast voltage transients		Buit-in RC network				
	Max. current rise	di/dt	50A/μs				
	On-state voltage drop	Ud	1.4V				@Ith
	Resistive part of the voltage drop	rt	3.5mΩ				@125°C
	Potential part of the voltage drop	Vto	0.9V				@125°C
	Maximum junction temperature	Tjmax	125°C				
	Junction/case thermal resistance per power element	Rthjc	0.3K/W				Total = 3 power elements
	Case heatsink thermal resistance	Rthcs	0.05K/W				
	Built-in heatsink thermal resistance vertically mounted	Rthra	0.9K/W				@ΔTra=60°C
	Heatsink thermal time constant	Tthra	35min				@ΔTra=60°C
	Inputs/power ouputs insulation voltage	Uimp	4kV				
	Input/status outputs insulation voltage	Uied	2.5kV				
	Inputs/case insulation voltage	Uimp	4kV				
	Status outputs/case insulation voltage	Uimp	4kV				
	Isolation resistance	Rio	1GΩ				
	Isolation capacitance	Cio	<8pF				
	Storage ambient temperature	Tstg	-40->+100°C				
	Operating ambient temperature	Tamb	-40->+90°C				See fig. 7
	Max. heatsink temperature	Te	100°C				

**INTERNAL POWER SUPPLY**

<b>INTERNAL POWER SUPPLY</b>	<b>CHARACTERISTIC</b>	<b>LABEL</b>	<b>VALUE</b>	<b>INFO.</b>
Terminals			3L2 & 5L3	
Mains voltage range	Ue		200->480VAC	
Consumption	Is		1mA typical	
Mains frequency range	F		40-65Hz	
Turn-on time	tm		100ms	

**GENERAL INFORMATION**

<b>CONNEC-TIONS</b>	<b>Connections</b>	<b>Power</b>	<b>Input terminal block</b>	
Screwdriver advised		Posidriv 2 or 0.8 x 5.5mm	0.8 x 2mm	
Min and max tightening torque		1.8->3N.m		
Number and cross section of the wires		2 x 1.5->6mm <sup>2</sup> (10mm <sup>2</sup> without ferrule)	1 x 2.5mm <sup>2</sup>	
Screwdriver for settings			0.8 x 2mm	

<b>MISC.</b>	<b>Housing</b>	<b>UL94V0</b>	
Mounting		Omega DIN rail (DIN50022) or screwed	
Noise level		Low audible vibrations	
Weight		2000g	

**STANDARDS**

<b>GENERAL</b>	<b>Standards</b>	EN60947-4-2 & EN60947-4-3	
	<b>Protection level</b>	IP2L0	
	<b>Protection against direct touch</b>	Accordin to V.D.E. 160 part 100 : Back hand and finger safety	
	<b>CE marking</b>	Yes	
	<b>UL, cULUS and VDE approvals</b>	Pending	

<b>E.M.C. IMMUNITY</b>	<b>TYPE OF TEST</b>	<b>STANDARD</b>	<b>LEVEL</b>	<b>EFFECT</b>
E.S.D. (Electrostatic discharges)	EN61000-4-2		8kV (air) 4kV (touch)	No effect
Radiated electromagnetic fields	EN61000-4-3		10V/m	No effect
Fast transients bursts	EN61000-4-4		2kV direct coupling on the power side 2kV coupling by clamp on the input side	No effect
Electric chocks	EN61000-4-5		1kV direct coupling differential mode (input and output) 2kV direct coupling common mode (input and output)	No effect
Voltage drop	EN61000-4-11		-	

<b>E.M.C. EMISSION</b>	<b>Radiated and conducted disturbances</b>	NFEN55011	The conducted or radiated disturbances generated by solid state relays depend on the wiring and load configuration. The test method recommended by the European standards and concerning electromagnetic compatibility leading to results far from reality, we decided to advise our customer in order to adapt their filtering scheme to their application. <b>Please refer to the SVTA - SWTA installation manual.</b>
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## CHARACTERISTIC CURVES

Fig. 5

## INPUT CHARACTERISTIC

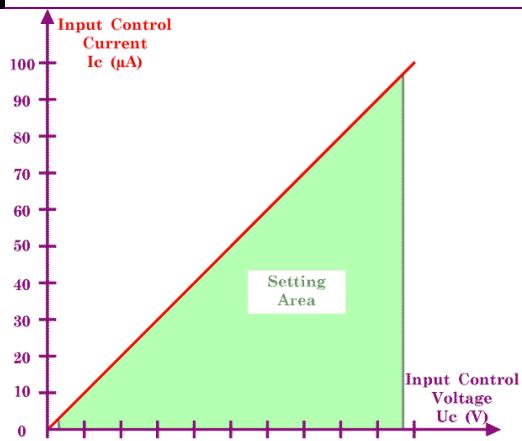


Fig. 6

## CURRENT AND ON RESISTANCE VS TEMPERATURE

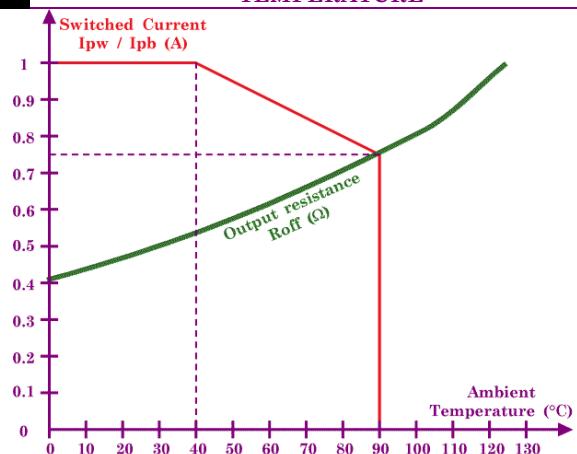


Fig. 7

## POWER DISSIPATED AND LOAD CURRENT LIMIT VS TEMPERATURE

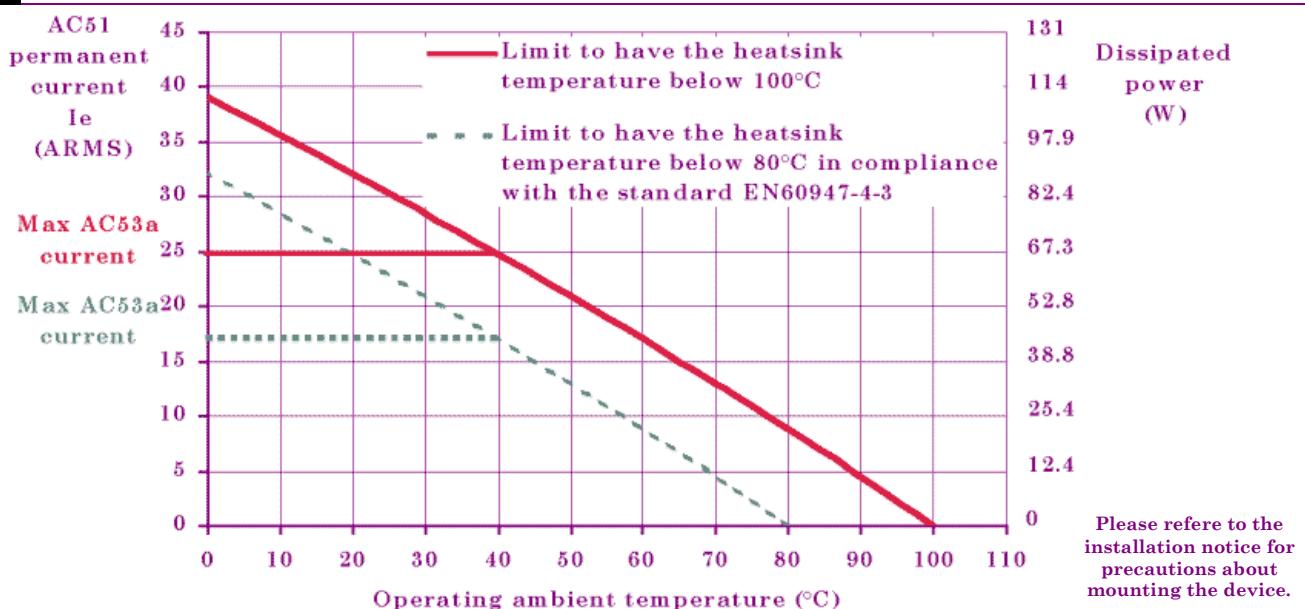
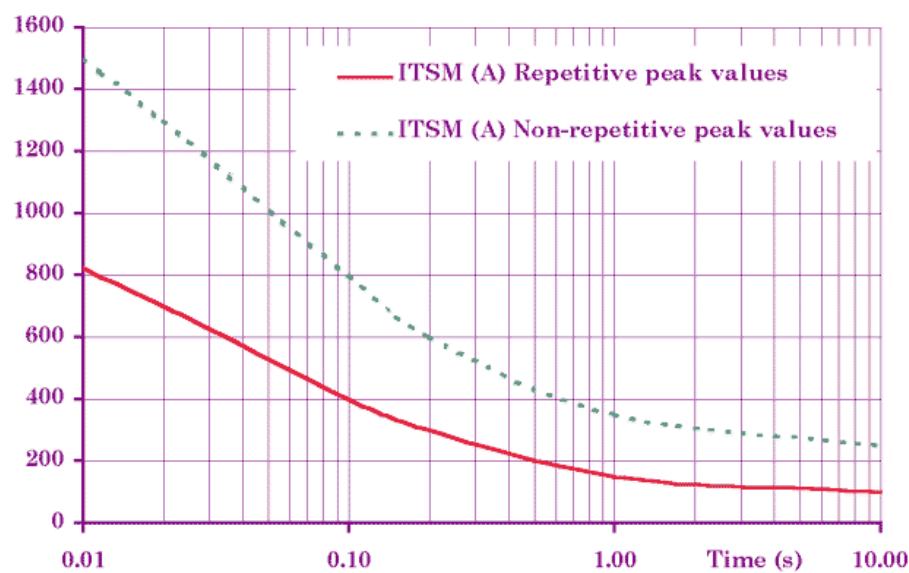


Fig. 8

## CURRENT OVERLOAD CHARACTERISTIC (ITSM PER POWER ELEMENT)



## DIMENSIONS AND ACCESSORIES

Fig. 9

DIMENSIONS

