

**MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®** 



MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®



Ordering information

Туре	Part no.
SFS60-H1AB0K02	On request

Other models and accessories → www.sick.com/SFS\_SFM60

Illustration may differ



#### Detailed technical data

Performance	
Number of sine/cosine periods per revolu- tion	1,024

Number of sine/cosine periods per revolu- tion	1,024
Number of the absolute ascertainable revo- lutions	1
Total number of steps	32,768
Measuring step	0.3 Winkelsekunden For interpolation of the sine/cosine signals with, e. g., 12 bits
Integral non-linearity typ.	$\pm$ 45 Winkelsekunden, Error limits for evaluating sine/cosine period, without mechanical tension of the stator coupling
Differential non-linearity	$\pm$ 7 Winkelsekunden, Non-linearity within a sine/cosine period
Operating speed	6,000 min <sup>-1</sup> , up to which the absolute position can be reliably produced
Interfaces	
Type of code for the absolute value	Binary
Code sequence	Rising, for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE®
Available memory area	1,792 Byte
Electrical data	
Supply voltage range	7 V DC 12 V DC
Recommended supply voltage	8 V DC
Operating power consumption (no load)	< 80 mA <sup>1)</sup>
Output frequency for sine/cosine signals	0 kHz 200 kHz
<sup>1)</sup> Without load.	
Mechanical data	
Shaft version	Blind hollow shaft
Shaft material	Stainless steel
Flange material	Zinc diecast

 $^{1)}$  Take into account self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Aluminum die cast

Stator coupling

Flange type/stator coupling

Housing material

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Dimensions	See dimensional drawing
Weight	≤ 0.25 kg
Moment of inertia of the rotor	40 gcm <sup>2</sup>
Operating speed	≤ 9,000 min <sup>-1 1)</sup>
Angular acceleration	≤ 500,000 rad/s²
Operating torque	0.6 Ncm (+20 °C)
Start up torque	0.8 Ncm (+20 °C)
Permissible shaft movement, radial, static	± 0.3 mm
Permissible shaft movement, radial, dynam- ic	± 0.1 mm
Permissible shaft movement, axial, static	± 0.5 mm
Permissible shaft movement, axial, dynamic	± 0.2 mm
Life of ball bearings	3.6 x 10^9 revolutions
Connection type	Male connector M23, 12-pin, radial

 $^{(1)}$  Take into account self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

#### Ambient data

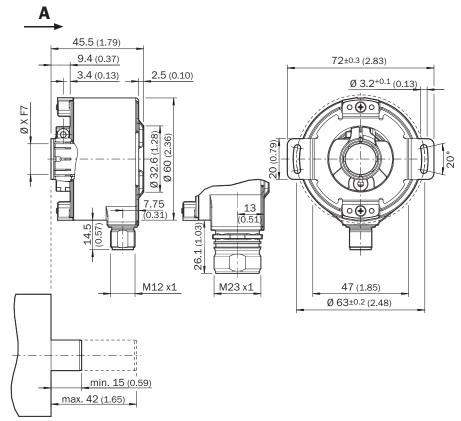
Operating temperature range	-40 °C +115 °C
Storage temperature range	-40 °C +115 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	20 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)
EMC	According to EN 61000-6-2 and EN 61000-6-3 $^{1)}$
Enclosure rating	IP65, with mating connector inserted (according to IEC 60529)

<sup>1)</sup> The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND (OV) connection of the supply voltage is also grounded here. If other screening concepts are used, users must perform their own tests.

#### Classifications

ECI@ss 5.0	27270590
ECI@ss 5.1.4	27270590
ECI@ss 6.0	27270590
ECI@ss 6.2	27270590
ECI@ss 7.0	27270590
ECI@ss 8.0	27270590
ECI@ss 8.1	27270590
ECI@ss 9.0	27270590
ETIM 5.0	EC001486
ETIM 6.0	EC001486
UNSPSC 16.0901	41112113

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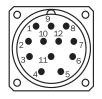


#### Dimensional drawing (Dimensions in mm (inch))

General tolerances according to DIN ISO 2768-mk

#### **PIN** assignment

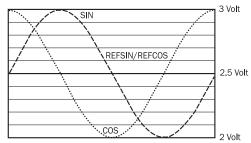
View of the M23 male connector plug-in face



#### MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®

PIN	Signal	Explanation
1	REFCOS	Process data channel
2	Data +	Parameter channel RS 485
3	N. C.	Not assigned
4	N. C.	Not assigned
5	+ SIN	Process data channel
6	REFSIN	Process data channel
7	Data -	Parameter channel RS 485
8	+ COS	Process data channel
9	N. C.	Not assigned
10	GND	Ground connection
11	N. C.	Not assigned
12	U <sub>S</sub>	Supply voltage
Housing	Screen	Screen connected with encoder housing

#### Diagram



Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period = 360 °: 1024

#### **Recommended accessories**

Other models and accessories -> www.sick.com/SFS\_SFM60

	Brief description	Туре	Part no.
Flanges			
-	Stator coupling, 16.5 mm high	BEF-DS05XFX	2057423
UÇ.	Stator coupling with hole circle diameter 63 mm	BEF-DS07XFX	2059368

# **SFS60-H1ABOK02 | SFS/SFM60** MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®

	Brief description	Туре	Part no.	
Plug connecto	Plug connectors and cables			
	Head A: female connector, M23, 12-pin, straight Head B: cable Cable: HIPERFACE®, HIPERFACE®, drag chain use, PUR, shielded, 3 m	DOL-2308-G03MJB2	2031070	
	Head A: female connector, M23, 12-pin, straight Head B: cable Cable: HIPERFACE®, HIPERFACE®, drag chain use, PUR, shielded, 5 m	DOL-2308-G05MJB2	2031071	
	Head A: female connector, M23, 12-pin, straight Head B: cable Cable: HIPERFACE®, HIPERFACE®, drag chain use, PUR, shielded, 10 m	DOL-2308-G10MJB2	2031072	
	Head A: female connector, M23, 12-pin, straight Head B: cable Cable: HIPERFACE®, HIPERFACE®, drag chain use, PUR, shielded, 15 m	DOL-2308-G15MJB2	2031073	
	Head A: female connector, M23, 12-pin, straight Head B: cable Cable: HIPERFACE®, HIPERFACE®, drag chain use, PUR, shielded, 1.5 m	DOL-2308-G1M5JB2	2031069	
	Head A: female connector, M23, 12-pin, straight Head B: male connector, M23, 17-pin, straight Cable: HIPERFACE®, unshielded, 1 m	DSL-2317-G01MJB2	2071328	
	Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 17-pin, straight Cable: HIPERFACE®, unshielded, 1 m	DSL-2317-G01MJB6	2071327	
	Head A: female connector, M12, 8-pin, straight Head B: male connector, M23, 17-pin, straight Cable: HIPERFACE®, unshielded, 1 m	DSL-2317-G01MJC1	2071329	
	Head A: female connector, terminal box, 8-pin, straight Head B: male connector, M23, 17-pin, straight Cable: HIPERFACE®, unshielded, 1 m	DSL-2317-G01MJC6	2071330	
	Head A: female connector, M23, 12-pin, straight Head B: - Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-G	6027538	
(H=0)	Head A: female connector, M23, 12-pin, angled Head B: - Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-W01	2072580	
(Co	Head A: male connector, M23, 12-pin, straight Head B: - Cable: HIPERFACE®, SSI, Incremental, RS-422, shielded	STE-2312-G	6027537	
Programming	and configuration tools			
	SVip® LAN programming tool for all motor feedback systems	PGT-11-S LAN	1057324	
60.00	SVip® WLAN programming tool for all motor feedback systems	PGT-11-S WLAN	1067474	

# SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

## WORLDWIDE PRESENCE:

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Online data sheet

