## **FEATURES**

- 600...1100 mbar, 800...1100 mbar barometric ranges
- Output: 0.25...4.25 V and I<sup>2</sup>C-bus (SPI and switching outputs optional)
- · Precision ASIC conditioning
- Calibrated and temperature compensated
- Miniature SMT or SIL housing
- RoHS compliant



### **SPECIFICATIONS**

#### **Maximum ratings**

Supply voltage  $V_s$  4.5 V ... 5.5  $V_{DC}$ 

(optional 2.7 ... 3.3 V<sub>DC</sub>)

Output current

Sink 1 mA Source 1 mA Proof pressure³ 3000 mbara Burst pressure⁴ 5000 mbara

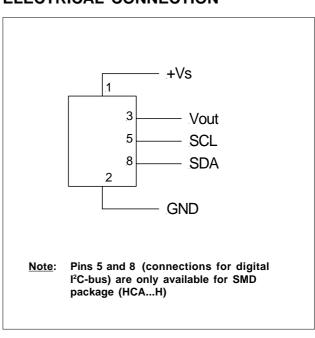
Lead specifications

Average preheating temperature gradient 2.5 K/s
Soak time ca. 3 min
Time above 217°C 50 s
Time above 230°C 40 s
Time above 250°C 15 s
Peak temperature 260°C
Cooling temperature gradient -3.5 K/s

Temperature ranges

Compensated 0 ... +85°C
Operating -25 ... +85°C
Storage -40 ... +125°C
Humidity limits (non-condensing) 0 ... 95 %RH

### **ELECTRICAL CONNECTION**



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### PERFORMANCE CHARACTERISTICS

 $(V_s = 5.0 \text{ V}, T_A = 25 \text{ °C}, \text{ analog output signal is } \underline{\textbf{ratiometric}} \text{ to } V_s, \text{ digital output signal is } \underline{\textbf{not ratiometric}} \text{ to } V_s, \text{ pressure applied to high pressure port)}$ 

Characteristics		Min.	Тур.	Max.	Unit			
Operating pressure range HCA06	311AR	600		1100	mbara			
HCA08	311AR	800		1100	Прага			
Total accuracy (0 85 °C) <sup>1</sup>				±1.0	%FSS			
Response delay <sup>5, 6</sup>			2		ms			
A/D resolution <sup>6</sup>			15		bit			
D/A resolution				11	Dit			
Current consumption (no load) <sup>7</sup>			5		mA			
DIGITAL PERFORMANCE CHARACTERISTICS								
Output at min. pressure		0560	0666	076C				
Full scale span (FSS) <sup>2</sup>			6666		Count Hex			
Full scale output		6BC6	6CCC	6DD2				
ANALOGUE PERFORMANCE CHARACTERISTICS								
Output at min. pressure		0.21	0.25	0.29				
Full scale span (FSS) <sup>2</sup>			4.00		V			
Full scale output		4.21	4.25	4.29				

#### **Specification notes:**

- 1. Total accuracy is the combined error from offset and span calibration, linearity, pressure hysteresis, and temperature effects. Linearity is the measured deviation based on a straight line. Hysteresis is the maximum output difference at any point within the operating pressure range for increasing and decreasing pressure. Calibration errors include the deviation of offset and full scale from nominal values.
- 2. Full Scale Span (FSS) is the algebraic difference between the output signal for the highest and lowest specified pressure.
- 3. Proof pressure is the maximum pressure which may be applied without causing durable shifts of the electrical parameters of the sensing element.
- 4. Burst pressure is the maximum pressure which may be applied without causing damage to the sensing element or leaks to the housing.
- 5. Max. delay time between pressure change at the pressure die and signal change at the output.
- **6.** The response time depends on the adjusted internal A/D resolution of the sensor. For 15 bit it is typ. 2 ms. Other A/D resolutions and reponse times are available on request. Please contact Sensortechnics for further information.
- 7. Sensors with lower current consumption are available on request. Please contact Sensortechnics for further information.



#### I<sup>2</sup>C BUS

#### Introduction

The HCA-BARO is capable to generate a digital output signal. The device runs a cyclic program, which will store a corrected pressure value with 15 bit resolution about every 1 ms within the output registers of the internal ASIC. In order to use the sensor for digital signal readout, it should be connected to a bidirectional I<sup>2</sup>C-bus.

According to the I<sup>2</sup>C-bus specification, the bus is controlled by a master device, which generates the clock signal, controls the bus access and generates START and STOP conditions. The HCA-BARO is designed to work as a slave, hence it will only respond to requests from a master device.

## Digital I<sup>2</sup>C interface

The HCA-BARO complies with the following protocol (Fig. 1):

**Bus not busy**: During idle periods both data line (SDA) and clock line (SCL) remain HIGH.

**START condition (S)**: HIGH to LOW transition of SDA line while clock (SCL) is HIGH is interpreted as START condition. START conditions are always generated by the master. Each initial request for a pressure value has to begin with a START condition.

**STOP condition (P):** LOW to HIGH transition of SDA line while clock (SCL) is HIGH determines STOP condition. STOP conditions are always generated by the master. More than one request for the current pressure value can be transmitted without generation of intermediate STOP condition.

**DATA valid (D):** State of data line represents valid data when, after START condition, data line is stable for duration of HIGH period of clock signal. Data on line must be changed during LOW period of clock signal. There is one clock pulse per bit of data.

Acknowledge (A): Data is transferred in pieces of 8 bits (1 byte) on serial bus, MSB first. After each byte receiving device — whether master or slave — is obliged to pull data line LOW as acknowledge for reception of data. Master must generate an extra clock pulse for this purpose. When acknowledge is missed, slave transmitter becomes inactive. It is on master either to send last command again or to generate STOP condition in that case.

Slave address: The I<sup>2</sup>C-bus master-slave concept requires a unique address for each device. The HCA-BARO has a preconfigured slave address (1111000xb). By factory programming it is possible to define a secondary slave address additional to the general one. According to I<sup>2</sup>C specification 127 different addresses are available. The sensor will then listen to both slave addresses. After generating a START condition the master sends the address byte containing a 7 bit address followed by a data direction bit (R/W). A "0" indicates a transmission from master to slave (WRITE), a "1" indicates a data request (READ).

**DATA operation**: The HCA-BARO starts to send 2 data bytes containing the current pressure value as a 15 bit information placed in the output registers.

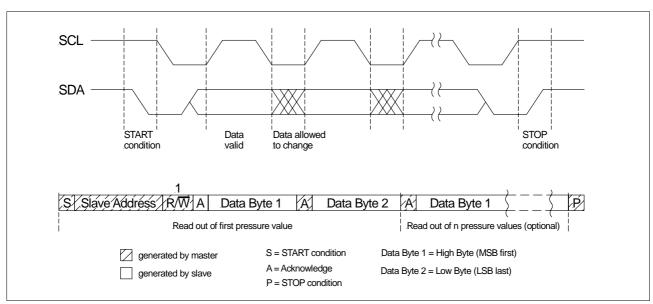


Fig. 1: I<sup>2</sup>C bus protocol

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## I<sup>2</sup>C Interface Parameters

Parameter	Symbol	Min.	Тур.	Max.	Unit
Input high level		90		100	
Input low level		0		10	% of Vs
Output low level				10	
Pull-up resistor		500			Ω
Load capacitance @ SDA	C <sub>SDA</sub>			400	nE
Input capacitance @ SDA/SCL	C <sub>I2C_IN</sub>			10	pF
SCL clock frequency	F <sub>SCL</sub>	100*		400	kHz
Bus free time between STOP and START condition	t <sub>BUF</sub>	1.3			
Hold time (repeated) START condition, to first clock pulse	t <sub>HD.STA</sub>	8.0			
LOW period of SCL	t <sub>LOW</sub>	1.3			
HIGH period of SCL	t <sub>HIGH</sub>	0.6			
Setup time repeated START condition	t <sub>su.sta</sub>	1			
Data hold time	t <sub>HD.DAT</sub>	0			μs
Data setup time	t <sub>SU.DAT</sub>	0.2			
Rise time of both SDA and SCL	t <sub>R</sub>			0.3	]
Fall time of both SDA and SCL	t <sub>F</sub>			0.3	
Setup time for STOP condition	t <sub>su.sto</sub>	0.6			

<sup>\*</sup> recommended

Note: First Sensor recommends communication speeds of at least 100 kHz (max. 400 kHz). Please contact us for further information.

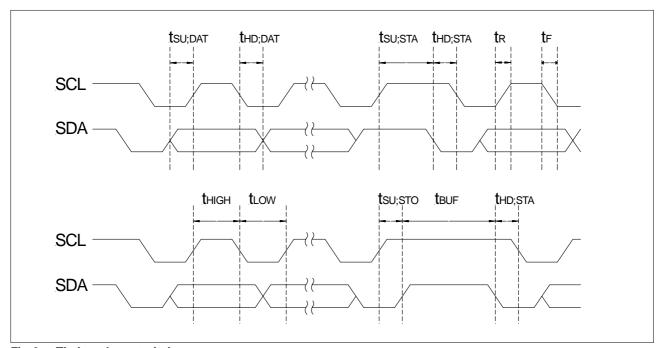


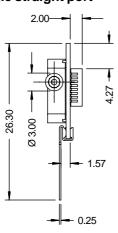
Fig. 2: Timing characteristics

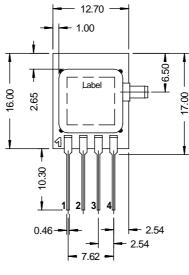
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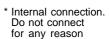
## PHYSICAL DIMENSIONS AND ELECTRICAL CONNECTIONS

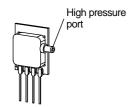
HCA...G8
SIL single straight port

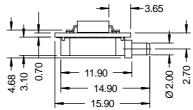




Pin	Connection
1	+Vs
2	GND
3	Vout
4	I/C *



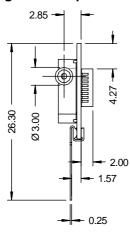


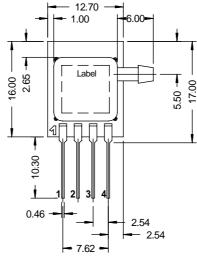




first angle projection dimensions in mm

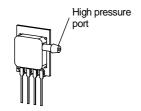
HCA...G9 SIL single barbed port

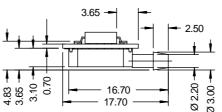




Pin	Connection
1	+Vs
2	GND
3	Vout
4	I/C *

\* Internal connection. Do not connect for any reason







dimensions in mm

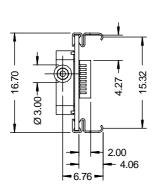
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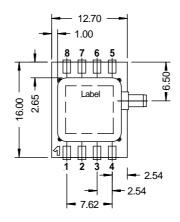


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## PHYSICAL DIMENSIONS AND ELECTRICAL CONNECTIONS

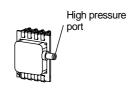
HCA...H8
SMD single straight port

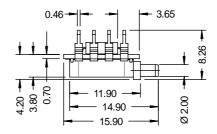




Pin	Connection
1	+Vs
2	GND
3	Vout
4	I/C *
5	SCL
6	1/0 *
7	I/C*
8	SDA

\* Internal connection. Do not connect for any reason

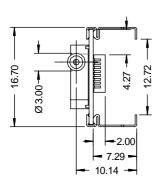


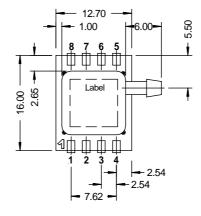




first angle projection dimensions in mm

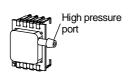
HCA...H9 SMD single barbed port

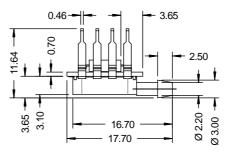


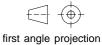


Pin	Connection					
1	+Vs					
2	GND					
3	Vout					
4	I/C *					
5	SCL					
6	I/C*					
7	1/0					
8	SDA					

\* Internal connection.
Do not connect
for any reason







dimensions in mm

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# Miniature amplified barometric pressure sensors

## **ORDERING INFORMATION**

	Series	Pressure range		Pressure mode		Calibration		Housing		Porting	
Options	HCA	0611	6001100 mbar	Α	Absolute	R	Barometric	G*	SIL	8	Straight
		0811	8001100 mbar					Н	SMD	9	Barbed
								available digital output			
Example:	HCA	0611		Α		R		Н		8	

## Custom specific mechanical or electronic sensor modifications are widely available:

- · 3 V power supply
- · SPI, switching and custom specific outputs
- · Dual inline packages (DIP)

etc

Please contact First Sensor for further information.

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