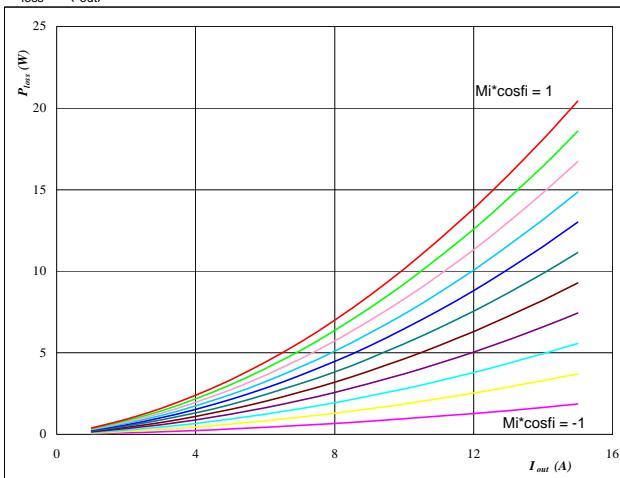


**flowPIM 0**
**Output Inverter Application**
**600V/6A**
**General conditions**
**3phase SPWM**

$V_{GEon}$	=	15 V
$V_{GEoff}$	=	0 V
$R_{gon}$	=	32 Ω
$R_{goff}$	=	16 Ω

**Figure 1**
**IGBT**
**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$

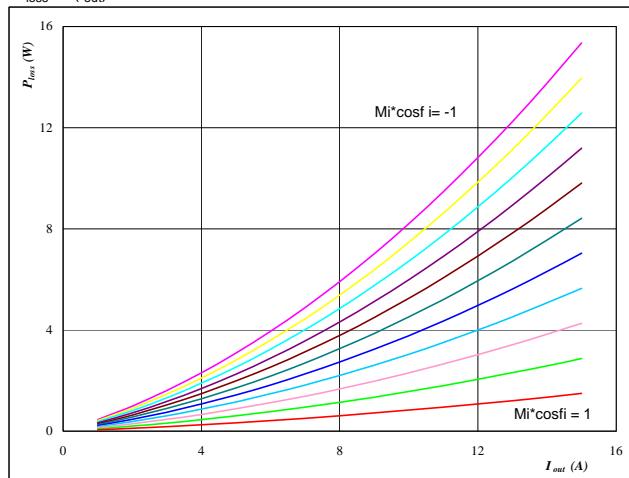

**At**

$$T_j = 125 \text{ } ^\circ\text{C}$$

 $Mi \cdot \cos\phi$  from -1 to 1 in steps of 0,2

**Figure 2**
**FWD**
**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$

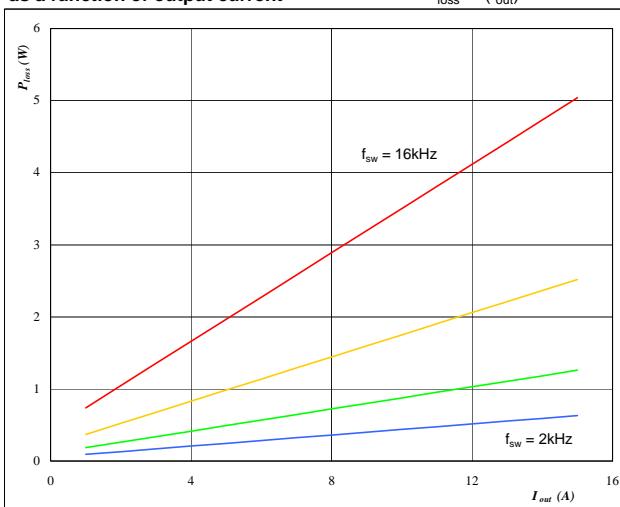

**At**

$$T_j = 125 \text{ } ^\circ\text{C}$$

 $Mi \cdot \cos\phi$  from -1 to 1 in steps of 0,2

**Figure 3**
**IGBT**
**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$


**At**

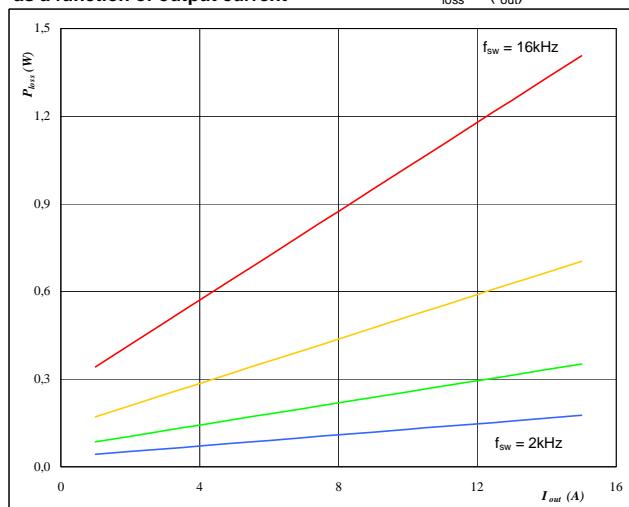
$$T_j = 125 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 320 \text{ } \text{V}$$

 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 4**
**FWD**
**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$


**At**

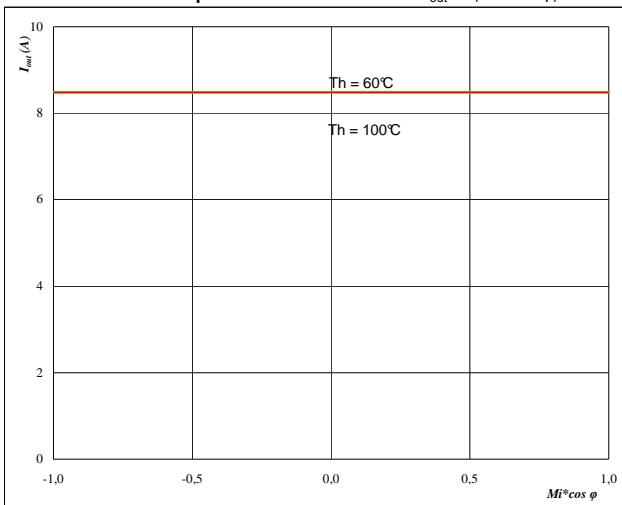
$$T_j = 125 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 320 \text{ } \text{V}$$

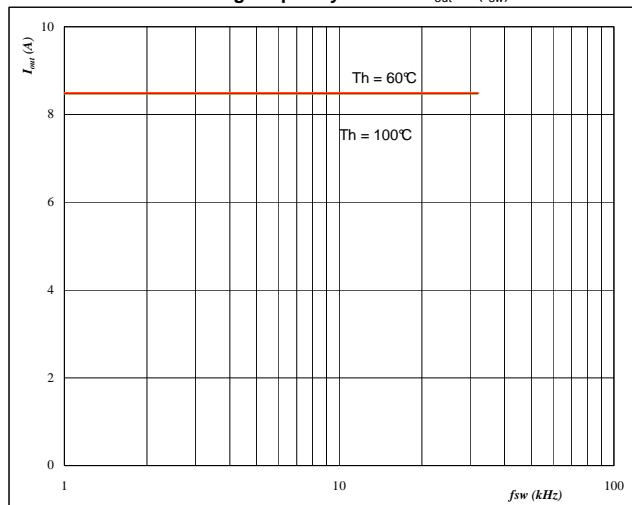
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**flowPIM 0**
**Output Inverter Application**
**600V/6A**
**Figure 5**
**Typical available 50Hz output current  
as a function  $M_i \cos \varphi$** 

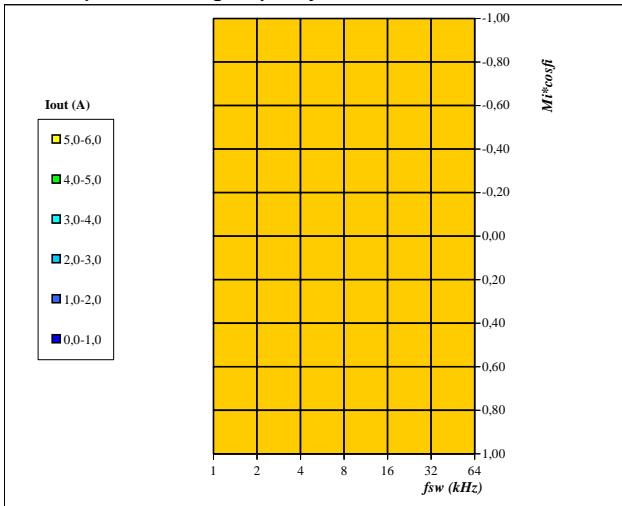
$$I_{out} = f(M_i \cos \varphi)$$


**At**
 $T_j = 125 \quad ^\circ\text{C}$ 
 $\text{DC link} = 320 \quad \text{V}$ 
 $f_{sw} = 4 \quad \text{kHz}$ 
 $T_h \text{ from } 60 \text{ }^\circ\text{C} \text{ to } 100 \text{ }^\circ\text{C} \text{ in steps of } 5 \text{ }^\circ\text{C}$ 
**Figure 6**
**Typical available 50Hz output current  
as a function of switching frequency**

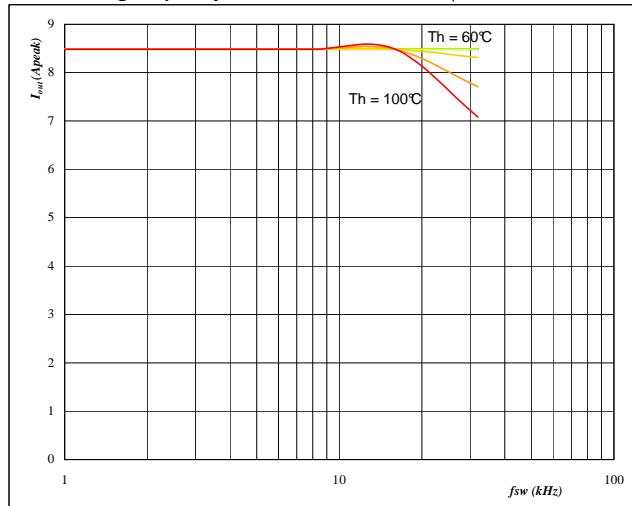
$$I_{out} = f(f_{sw})$$


**At**
 $T_j = 125 \quad ^\circ\text{C}$ 
 $\text{DC link} = 320 \quad \text{V}$ 
 $M_i \cos \varphi = 0,8$ 
 $T_h \text{ from } 60 \text{ }^\circ\text{C} \text{ to } 100 \text{ }^\circ\text{C} \text{ in steps of } 5 \text{ }^\circ\text{C}$ 
**Figure 7**
**Typical available 50Hz output current as a function of  
 $M_i \cos \varphi$  and switching frequency**

$$I_{out} = f(f_{sw}, M_i \cos \varphi)$$

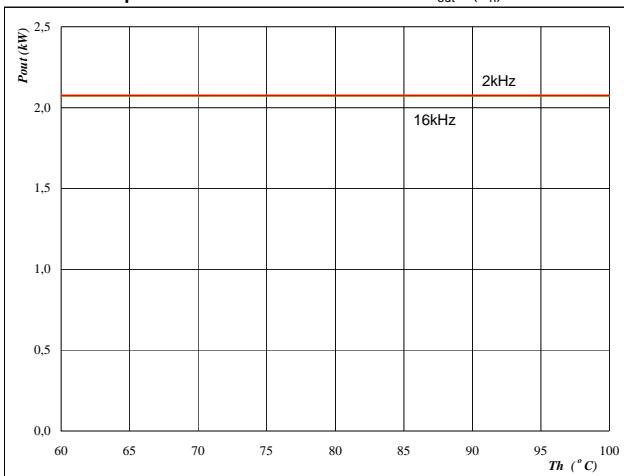

**At**
 $T_j = 125 \quad ^\circ\text{C}$ 
 $\text{DC link} = 320 \quad \text{V}$ 
 $T_h = 80 \quad ^\circ\text{C}$ 
**Figure 8**
**Typical available 0Hz output current as a function  
of switching frequency**

$$I_{outpeak} = f(f_{sw})$$


**At**
 $T_j = 125 \quad ^\circ\text{C}$ 
 $\text{DC link} = 320 \quad \text{V}$ 
 $T_h \text{ from } 60 \text{ }^\circ\text{C} \text{ to } 100 \text{ }^\circ\text{C} \text{ in steps of } 5 \text{ }^\circ\text{C}$ 
 $M_i = 0$

**flowPIM 0**
**Output Inverter Application**
**600V/6A**
**Figure 9**
**Inverter**
**Typical available peak output power as a function of heatsink temperature**

$$P_{out}=f(T_h)$$


**At**

T<sub>j</sub> = 125 °C

DC link = 320 V

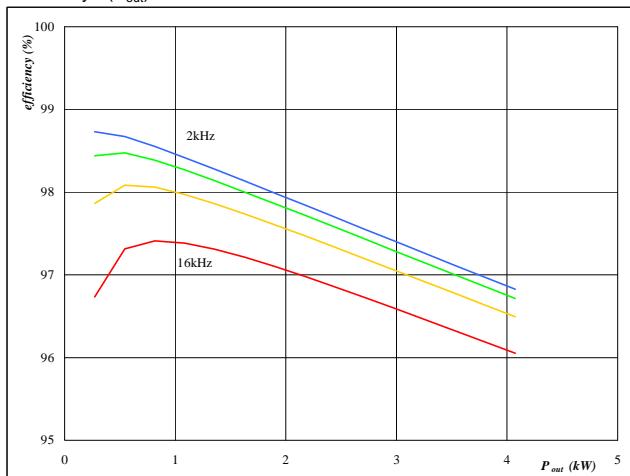
Mi = 1

cos φ = 0,80

f<sub>sw</sub> from 2 kHz to 16 kHz in steps of factor 2

**Figure 10**
**Inverter**
**Typical efficiency as a function of output power**

$$\text{efficiency}=f(P_{out})$$


**At**

T<sub>j</sub> = 125 °C

DC link = 320 V

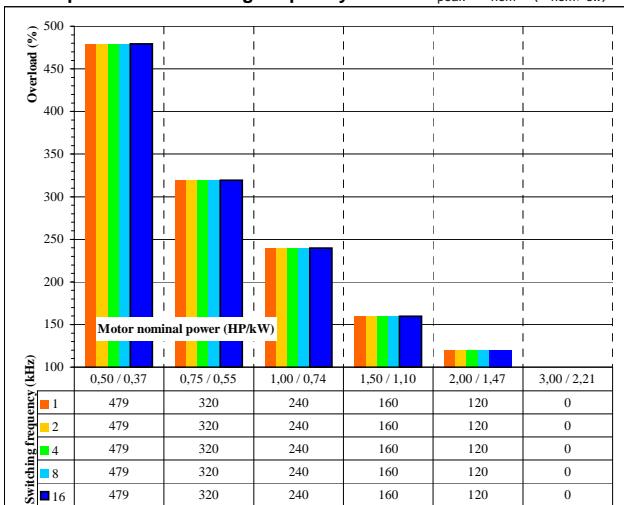
Mi = 1

cos φ = 0,80

f<sub>sw</sub> from 2 kHz to 16 kHz in steps of factor 2

**Figure 11**
**Inverter**
**Typical available overload factor as a function of motor power and switching frequency**

$$P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$$


**At**

T<sub>j</sub> = 125 °C

DC link = 320 V

Mi = 1

cos φ = 0,8

f<sub>sw</sub> from 1 kHz to 16 kHz in steps of factor 2

T<sub>h</sub> = 80 °C

Motor eff = 0,85