

# **BGU8004**

# SiGe:C Low Noise Amplifier MMIC for GPS, GLONASS, Galileo and Compass

Rev. 1 — 31 January 2014

Preliminary data sheet

# 1. Product profile

### 1.1 General description

The BGU8004 is a Low Noise Amplifier (LNA) for GNSS receiver applications. It comes as extremely small and thin Wafer Level Chip Scale Package (WLCSP). The BGU8004 requires one external matching inductor.

The BGU8004 adapts itself to the changing environment resulting from co-habitation of different radio systems in modern cellular handsets. It has been designed for low power consumption and optimized performance when jamming signals from co-existing cellular transmitters are present. At low jamming power levels it delivers 17 dB gain at a noise figure of 0.60 dB. During high jamming power levels, resulting for example from a cellular transmit burst, it temporarily increases its bias current to improve sensitivity.

#### 1.2 Features and benefits

- Covers full GNSS L1 band, from 1559 MHz to 1610 MHz
- Noise figure (NF) = 0.60 dB
- Gain 17.0 dB
- High input 1 dB compression point of -7.5 dBm
- High out of band IP3<sub>i</sub> of 6 dBm
- Supply voltage 1.5 V to 3.1 V
- Optimized performance at very low 3.4 mA supply current
- Power-down mode current consumption < 1 μA
- Integrated temperature stabilized bias for easy design
- Requires only one input matching inductor
- Input and output DC decoupled
- ESD protection on all pins (HBM > 2 kV)
- Integrated matching for the output
- Extremely small Wafer Level Chip Scale Package (WLCSP)  $0.65 \times 0.44 \times 0.2$  mm; 6 solder bumps; 0.22 mm bump pitch
- 180 GHz transit frequency SiGe:C technology

### 1.3 Applications

LNA for GPS, GLONASS, Galileo and Compass (BeiDou) in smart phones, feature phones, tablet, digital still cameras, digital video cameras, RF front-end modules, complete GNSS modules and personal health applications.



### SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass

#### 1.4 Quick reference data

Table 1. Quick reference data

f = 1575 MHz;  $V_{CC} = 1.8$  V;  $V_{I(ENABLE)} \ge 0.8$  V;  $P_i < -40$  dBm;  $T_{amb} = 25$  °C; input matched to 50  $\Omega$  using a 5.6 nH inductor, see <u>Figure 1</u>; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>CC</sub>	supply voltage	RF input AC coupled	1.5	-	3.1	V
I <sub>CC</sub>	supply current	P <sub>i</sub> < −40 dBm	-	3.4	-	mA
		$P_i = -20 \text{ dBm}$	-	7.5	-	mA
Gp	power gain	no jammer	-	17.0	-	dB
		$P_i = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	-	19.0	-	dB
NF	noise figure	no jammer	[1] -	0.60	-	dB
		no jammer	[2] _	0.65	-	dB
P <sub>i(1dB)</sub>	input power at 1 dB gain compression	V <sub>CC</sub> = 1.8 V	-	-10	-	dBm
		V <sub>CC</sub> = 2.85 V	-	-7.5	-	
IP3 <sub>i</sub>	input third-order intercept point	V <sub>CC</sub> = 1.8 V	[3] _	4	-	dBm
		V <sub>CC</sub> = 2.85 V	[3] _	6	-	dBm

<sup>[1]</sup> PCB losses are subtracted.

# 2. Pinning information

Table 2. Pinning

	•		
Pin	Description	Simplified outline	Graphic symbol
1	GND_RF		
2	RF_IN	(1) (6)	3 5
3	ENABLE		2—6
4	GND	(2) (5)	Ţļ
5	V <sub>CC</sub>	(3) (4)	1 4 aaa-004308
6	RF_OUT		
		Bump side view	

# 3. Ordering information

Table 3. Ordering information

, ·	Package		
number	Name	Description	Version
BGU8004	WLCSP6	wafer level chip-size package; 6 balls; body $0.65 \times 0.44 \times 0.29$ mm	BGU8004

<sup>[2]</sup> Including PCB losses.

<sup>[3]</sup>  $f_1 = 1713$  MHz;  $f_2 = 1851$  MHz;  $P_i = -20$  dBm at  $f_1$ ;  $P_i = -65$  dBm at  $f_2$ .

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# 4. Marking

Table 4. Marking codes

Type number	Marking code
BGU8004	single character, indicating assembly month.[1]

<sup>[1]</sup> Month code see Table 5.

Table 5. Calender marking month code

Double underscore indicate pin 1.

Year	[1] Mon	th										
	J	F	M	Α	M	J	J	Α	S	0	N	D
2013	M	N	<u>o</u>	<u>P</u>	Q	R	<u>s</u>	Ţ	<u>U</u>	V	W	X
2014	<u>Y</u>	<u>Z</u>	<u>b</u>	<u>d</u>	<u>f</u>	<u>h</u>	<u>3</u>	<u>4</u>	<u>5</u>	<u>6</u>	<u>7</u>	9
2015	<u>A</u>	B	<u>C</u>	<u>D</u>	<u>E</u>	F	<u>G</u>	H	Ī	<u>J</u>	<u>K</u>	<u>L</u>

<sup>[1]</sup> Rotates every 3 years.

# 5. Limiting values

Table 6. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions		Min	Max	Unit
$V_{CC}$	supply voltage	RF input AC coupled	<u>[1]</u>	-0.5	+5.0	V
V <sub>I(ENABLE</sub> )	input voltage on pin ENABLE	$V_{I(ENABLE)} < V_{CC} + 0.6 V$	[1][2]	-0.5	+5.0	V
V <sub>I(RF_IN)</sub>	input voltage on pin RF_IN	DC, $V_{I(RF_IN)} < V_{CC} + 0.6 V$	[1][2][3]	-0.5	+5.0	V
$V_{I(RF\_OUT)}$	input voltage on pin RF_OUT	DC, $V_{I(RF\_OUT)} < V_{CC} + 0.6 V$	[1][2][3]	-0.5	+5.0	V
Pi	input power	f = 1575 MHz	<u>[1]</u>	-	10	dBm
P <sub>tot</sub>	total power dissipation	$T_{sp} \le 130  ^{\circ}C$		-	55	mW
T <sub>stg</sub>	storage temperature			-65	+150	°C
Tj	junction temperature			-	150	°C
V <sub>ESD</sub>	electrostatic discharge voltage	Human Body Model (HBM) According to ANSI/ESDA/JEDEC standard JS-001		-	±2	kV
		Machine Model (MM) According to JEDEC standard JESD22-A115		-	±0.2	kV
		Charged Device Model (CDM) According to JEDEC standard JESD22-C101		-	±1	kV

<sup>[1]</sup> Stressed with pulses of 200 ms in duration, with application circuit as in  $\underline{\text{Figure 1}}$ .

<sup>[2]</sup> Warning: due to internal ESD diode protection, the applied DC voltage should not exceed V<sub>CC</sub> + 0.6 V and shall not exceed 5.0 V in order to avoid excess current.

<sup>[3]</sup> The RF input and RF output are AC coupled through internal DC blocking capacitors.

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# 6. Recommended operating conditions

Table 7. Operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{CC}$	supply voltage		1.5	-	3.1	V
T <sub>amb</sub>	ambient temperature		-40	+25	+85	°C
$V_{I(ENABLE)}$	input voltage on pin ENABLE	OFF state	-	-	0.3	V
		ON state	0.8	-	-	V

# 7. Thermal characteristics

Table 8. Thermal characteristics

Symbol	Parameter	Conditions	Тур	Unit
$R_{th(j-sp)}$	thermal resistance from junction to solder point		217	K/W

### 8. Characteristics

Table 9. Characteristics at  $V_{cc} = 1.8 \text{ V}$ 

f = 1575 MHz;  $V_{CC}$  = 1.8 V;  $V_{I(ENABLE)} \ge$  0.8 V;  $P_{I}$  < -40 dBm;  $T_{amb}$  = 25 °C; input matched to 50  $\Omega$  using a 5.6 nH inductor, see <u>Figure 1</u>; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$I_{CC}$	supply current	$V_{I(ENABLE)} \ge 0.8 \text{ V}$				
		$P_i < -40 \text{ dBm}$	-	3.4	-	mΑ
		$P_i = -20 \text{ dBm}$	-	7.5	-	mΑ
		$V_{I(ENABLE)} \leq 0.3 \text{ V}$	-	-	1	μΑ
$G_p$	power gain	no jammer	-	17.0	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	-	17.5	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	-	19.0	-	dB
$RL_in$	input return loss	$P_i < -40 \text{ dBm}$	-	10	-	dB
		$P_i = -20 \text{ dBm}$	-	15	-	dB
$RL_{out}$	output return loss	$P_i < -40 \text{ dBm}$	-	11	-	dB
		$P_i = -20 \text{ dBm}$	-	11	-	dB
ISL	isolation		-	27	-	dB
NF	noise figure	$P_i = -40 \text{ dBm}$ , no jammer	<u>[1]</u> _	0.60	-	dB
		$P_i = -40 \text{ dBm}$ , no jammer	[2] _	0.65	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	[2] _	1.0	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	[2] _	1.0	-	dB
P <sub>i(1dB)</sub>	input power at 1 dB gain compression		-	-10	-	dBm

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Table 9. Characteristics at V<sub>cc</sub> = 1.8 V ...continued

f = 1575 MHz;  $V_{CC}$  = 1.8 V;  $V_{I(ENABLE)} \ge 0.8$  V;  $P_i$  < -40 dBm;  $T_{amb}$  = 25 °C; input matched to 50  $\Omega$  using a 5.6 nH inductor, see <u>Figure 1</u>; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
IP3 <sub>i</sub>	input third-order intercept point		[3]	-	4	-	dBm
t <sub>on</sub>	turn-on time	time from $V_{I(\mbox{\footnotesize{ENABLE}})}$ ON, to 90 % of the gain		-	-	2	μS
t <sub>off</sub>	turn-off time	time from $V_{I(\mbox{\footnotesize{ENABLE}})}$ OFF, to 10 % of the gain		-	-	1	μS

<sup>[1]</sup> PCB losses are subtracted

Table 10. Characteristics at  $V_{cc} = 2.85 \text{ V}$ 

f = 1575 MHz;  $V_{CC}$  = 2.85 V;  $V_{I(ENABLE)} \ge 0.8$  V;  $P_i$  < -40 dBm;  $T_{amb}$  = 25 °C; input matched to 50  $\Omega$  using a 5.6 nH inductor, see <u>Figure 1</u>; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
I <sub>CC</sub>	supply current	$V_{I(ENABLE)} \ge 0.8 \text{ V}$					
		$P_i < -40 \text{ dBm}$		-	3.6	-	mΑ
		$P_i = -20 \text{ dBm}$		-	7.5	-	mΑ
		$V_{I(ENABLE)} \le 0.3 \text{ V}$		-	-	1	μΑ
$G_p$	power gain	no jammer		-	17.0	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$		-	18.0	-	dB
		$P_{jam} = -20 \text{ dBm}$ ; $f_{jam} = 1850 \text{ MHz}$		-	19.0	-	dB
$RL_{in}$	input return loss	$P_i < -40 \text{ dBm}$		-	11	-	dB
		$P_i = -20 \text{ dBm}$		-	15	-	dB
$RL_{out}$	output return loss	$P_i < -40 \text{ dBm}$		-	11	-	dB
		$P_i = -20 \text{ dBm}$		-	11	-	dB
ISL	isolation			-	27	-	dB
NF	noise figure	$P_i = -40 \text{ dBm}$ , no jammer	[1]	-	0.60	-	dB
		P <sub>i</sub> = −40 dBm, no jammer	[2]	-	0.65	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	[2]	-	1.0	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	[2]	-	1.0	-	dB
$P_{i(1dB)} \\$	input power at 1 dB gain compression			-	-7.5	-	dBm
IP3 <sub>i</sub>	input third-order intercept point		[3]	-	6	-	dBm
t <sub>on</sub>	turn-on time	time from $V_{I(\mbox{\footnotesize{ENABLE}})}$ ON, to 90 % of the gain		-	-	2	μS
t <sub>off</sub>	turn-off time	time from $V_{I(\mbox{\footnotesize{ENABLE}})}$ OFF, to 10 % of the gain		-	-	1	μS

<sup>[1]</sup> PCB losses are subtracted

<sup>[2]</sup> Including PCB losses

<sup>[3]</sup>  $f_1 = 1713 \text{ MHz}$ ;  $f_2 = 1851 \text{ MHz}$ ;  $P_i = -20 \text{ dBm at } f_1$ ;  $P_i = -65 \text{ dBm at } f_2$ .

<sup>[2]</sup> Including PCB losses

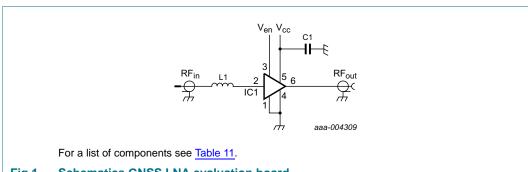
<sup>[3]</sup>  $f_1 = 1713 \text{ MHz}$ ;  $f_2 = 1851 \text{ MHz}$ ;  $P_i = -20 \text{ dBm at } f_1$ ;  $P_i = -65 \text{ dBm at } f_2$ .

**BGU8004 NXP Semiconductors** 

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# **Application information**

#### 9.1 GNSS LNA



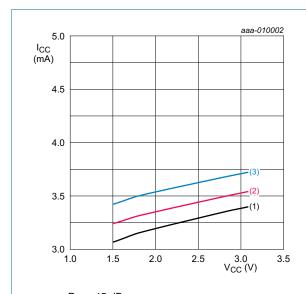
**Schematics GNSS LNA evaluation board** Fig 1.

Table 11. List of components

For schematics see Figure 1.

Component	Description	Value	Remarks
C1	decoupling capacitor	1 nF	optional component
IC1	BGU8004	-	NXP
L1	high quality matching inductor	6.8 nH	Murata LQW15A

### 9.2 Graphs



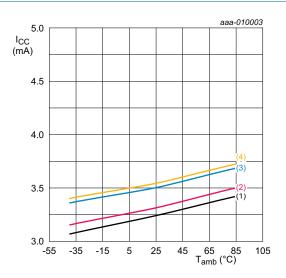
 $P_i = -45 \text{ dBm}.$ 

(1) 
$$T_{amb} = -40 \, ^{\circ}C$$

(2) 
$$T_{amb} = +25 \, ^{\circ}C$$

(3)  $T_{amb} = +85 \, ^{\circ}C$ 

Supply current as a function of supply voltage; Fig 2. typical values



 $P_i = -45 \text{ dBm}.$ 

(1) 
$$V_{CC} = 1.5 \text{ V}$$

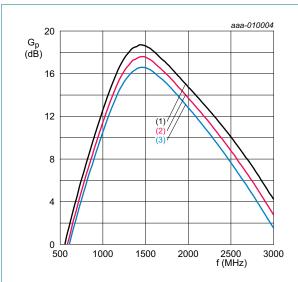
(2) 
$$V_{CC} = 1.8 \text{ V}$$

(3) 
$$V_{CC} = 2.85 \text{ V}$$

(4)  $V_{CC} = 3.1 \text{ V}$ 

Supply current as a function of ambient Fig 3. temperature; typical values

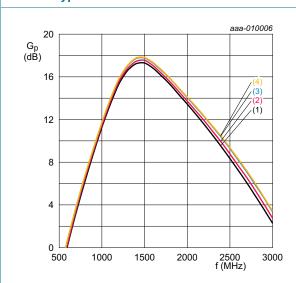
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$$P_i = -45 \text{ dBm}$$
;  $V_{CC} = 1.8 \text{ V}$ .

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

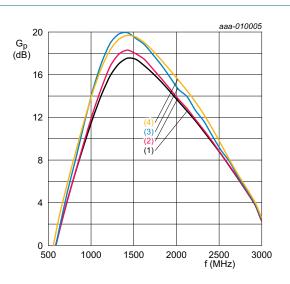
Fig 4. Power gain as a function of frequency; typical values



 $P_i = -45 \text{ dBm}$ ;  $T_{amb} = 25 \text{ }^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

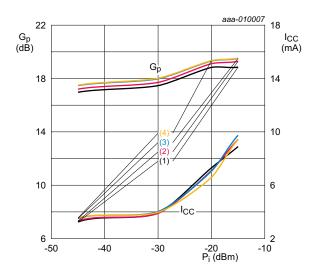
Fig 6. Power gain as a function of frequency; typical values



 $T_{amb}$  = 25 °C;  $V_{CC}$  = 1.8 V.

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

Fig 5. Power gain as a function of frequency; typical values

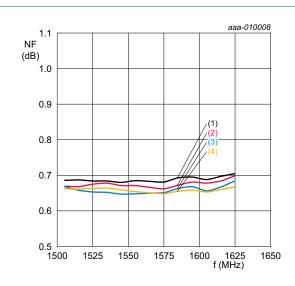


 $f = 1575 \text{ MHz}; T_{amb} = 25 \,^{\circ}\text{C}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 7. Power gain and supply current as function of input power; typical values

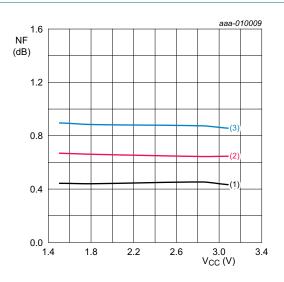
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 $T_{amb}$  = 25 °C; no jammer, including PCB losses.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

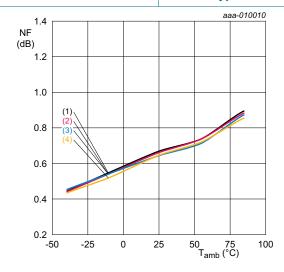
Fig 8. Noise figure as a function of frequency; typical values



f = 1575 MHz; no jammer, including PCB losses.

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 9. Noise figure as a function of supply voltage; typical values

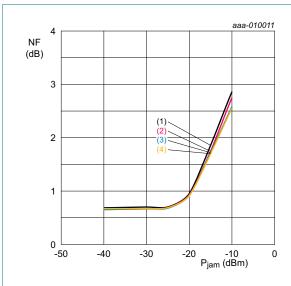


f = 1575 MHz; no jammer, including PCB losses.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 10. Noise figure as a function of ambient temperature; typical values

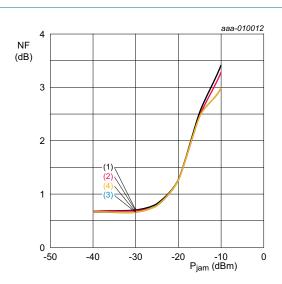
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 $f_{jam}$  = 850 MHz;  $T_{amb}$  = 25 °C; f = 1575 MHz; including PCB losses.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

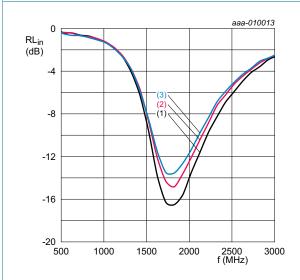
Fig 11. Noise figure as a function of jamming power; typical values



 $f_{jam}$  = 1850 MHz;  $T_{amb}$  = 25 °C; f = 1575 MHz; including PCB losses.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

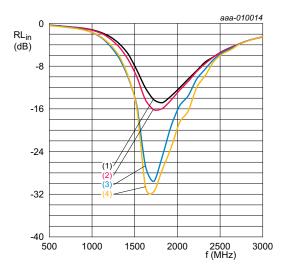
Fig 12. Noise figure as a function of jamming power; typical values



 $P_i = -45 \text{ dBm}; V_{CC} = 1.8 \text{ V}.$ 

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 13. Input return loss as a function of frequency; typical values

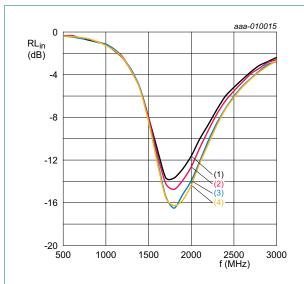


 $T_{amb} = 25 \, ^{\circ}C; \, V_{CC} = 1.8 \, V.$ 

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

Fig 14. Input return loss as a function of frequency; typical values

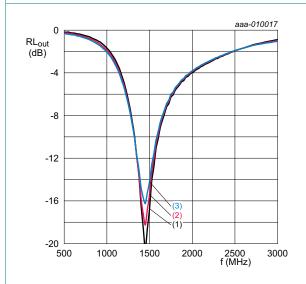
#### SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass



 $P_i = -45 \text{ dBm}$ ;  $T_{amb} = 25 \,^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

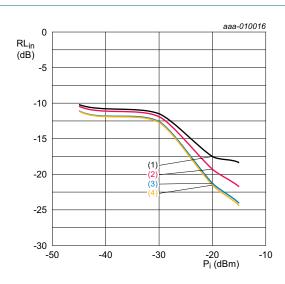
Fig 15. Input return loss as a function of frequency; typical values



 $P_i = -45 \text{ dBm}$ ;  $V_{CC} = 1.8 \text{ V}$ .

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

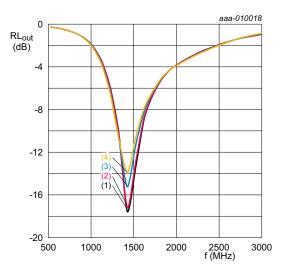
Fig 17. Output return loss as a function of frequency; typical values



f = 1575 MHz;  $T_{amb} = 25 \,^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 16. Input return loss as a function of input power; typical values

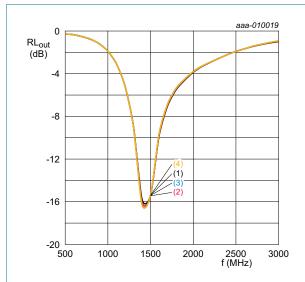


 $T_{amb} = 25 \, ^{\circ}C; \, V_{CC} = 1.8 \, V.$ 

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

Fig 18. Output return loss as a function of frequency; typical values

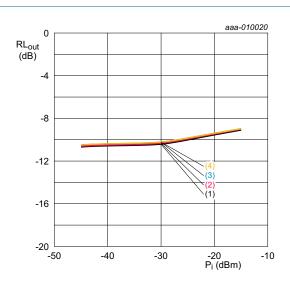
#### SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass



 $P_i = -45 \text{ dBm}$ ;  $T_{amb} = 25 \,^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

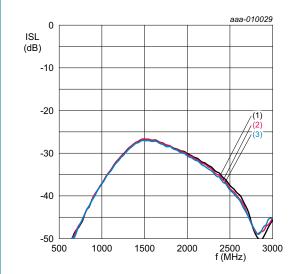
Fig 19. Output return loss as a function of frequency; typical values



f = 1575 MHz;  $T_{amb} = 25 \,^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

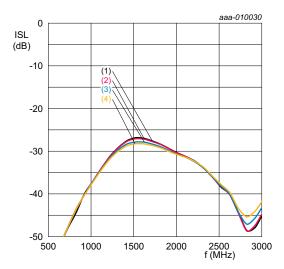
Fig 20. Output return loss as a function of input power; typical values



 $P_i = -45 \text{ dBm}; V_{CC} = 1.8 \text{ V}.$ 

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 21. Isolation as a function of frequency; typical values

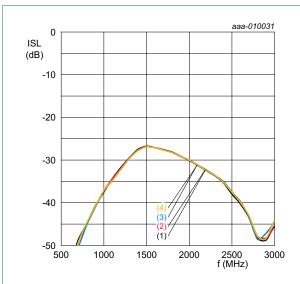


 $T_{amb} = 25 \, ^{\circ}C; \, V_{CC} = 1.8 \, V.$ 

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

Fig 22. Isolation as a function of frequency; typical values

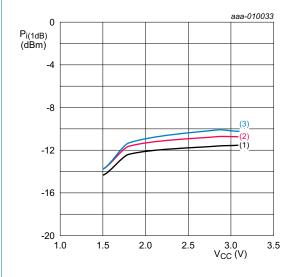
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 $P_i = -45 \text{ dBm}$ ;  $T_{amb} = 25 \,^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

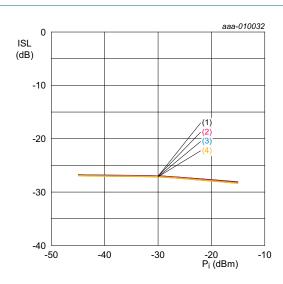
Fig 23. Isolation as a function of frequency; typical values



f = 850 MHz.

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

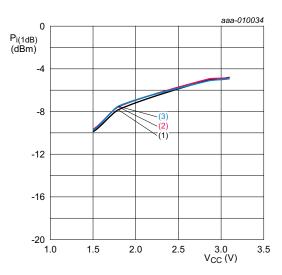
Fig 25. Input power at 1 dB gain compression as a function of supply voltage; typical values



f = 1575 MHz;  $T_{amb} = 25 \, ^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 24. Isolation as a function of input power; typical values

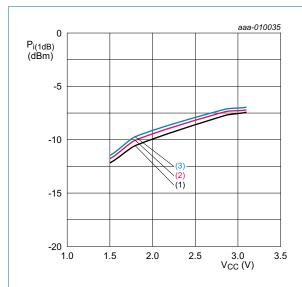


f = 1850 MHz.

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 26. Input power at 1 dB gain compression as a function of supply voltage; typical values

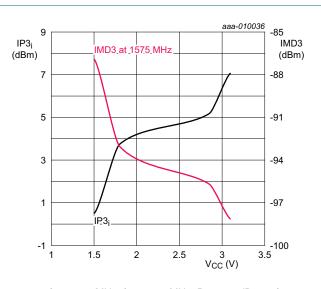
#### SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass



f = 1575 MHz.

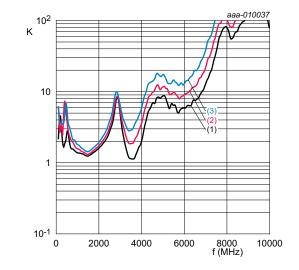
- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 27. Input power at 1 dB gain compression as a function of supply voltage; typical values



 $f_1 = 1713 \text{ MHz}; f_2 = 1851 \text{ MHz}; P_i = -20 \text{ dBm at } f_1; P_i = -65 \text{ dBm at } f_2; T_{amb} = 25 \,^{\circ}\text{C}.$ 

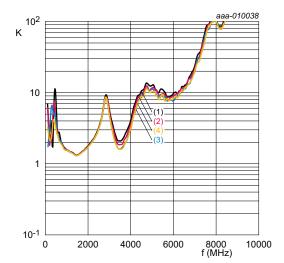
Fig 28. Input third order intercept point and third order intermodulation distortion as function of supply voltage; typical values



 $P_i = -45 \text{ dBm}; V_{CC} = 1.8 \text{ V}.$ 

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 29. Rollett stability factor as a function of frequency; typical values



 $P_i = -45 \text{ dBm}$ ;  $T_{amb} = 25 \text{ }^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 30. Rollett stability factor as a function of frequency; typical values

### SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass

# 10. Package outline

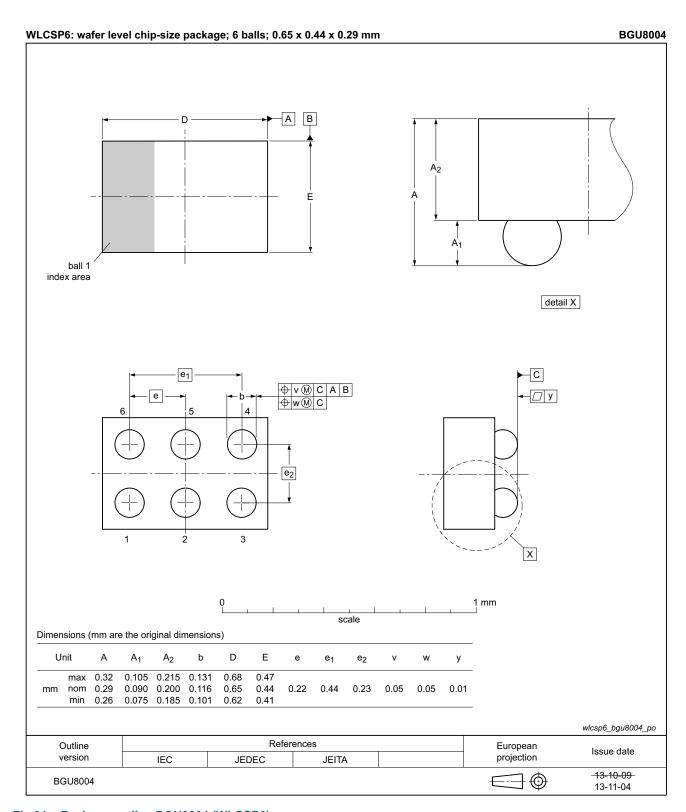


Fig 31. Package outline BGU8004 (WLCSP6)

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# 11. Handling information

#### CAUTION



This device is sensitive to ElectroStatic Discharge (ESD). Observe precautions for handling electrostatic sensitive devices.

Such precautions are described in the ANSI/ESD S20.20, IEC/ST 61340-5, JESD625-A or equivalent standards.

### 12. Abbreviations

Table 12. Abbreviations

Acronym	Description
GLONASS	GLObal NAvigation Satellite System
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
HBM	Human Body Model
MMIC	Monolithic Microwave Integrated Circuit
PCB	Printed Circuit Board
SiGe:C	Silicon Germanium Carbon

# 13. Revision history

Table 13. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
BGU8004 v.1	20140131	Preliminary data sheet	-	-

#### SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

# 14. Legal information

#### 14.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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