

MiniSKiiP® 3 PIM
Output Inverter Application
1200V/100A
General conditions
3phase SPWM

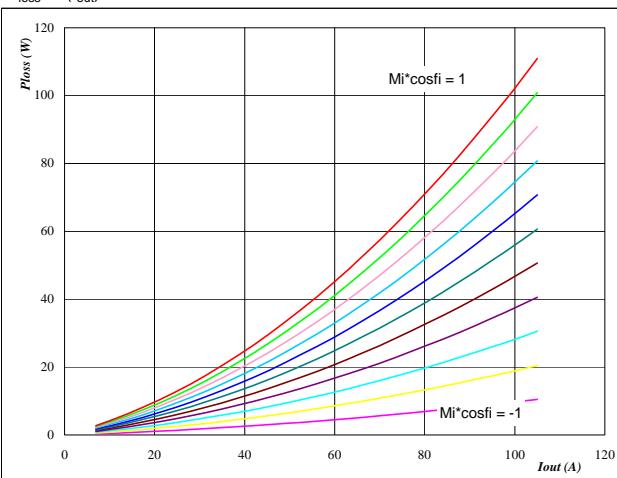
| | | |
|-------------|---|-------|
| V_{GEon} | = | 15 V |
| V_{GEoff} | = | -15 V |
| R_{gon} | = | 4 Ω |
| R_{goff} | = | 4 Ω |

Figure 1

IGBT

Typical average static loss as a function of output current

$$P_{loss} = f(I_{out})$$



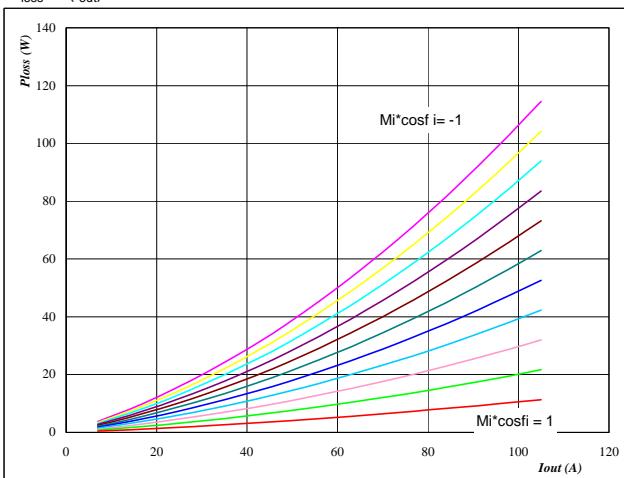
IGBT

Figure 2

FRED

Typical average static loss as a function of output current

$$P_{loss} = f(I_{out})$$

**At**

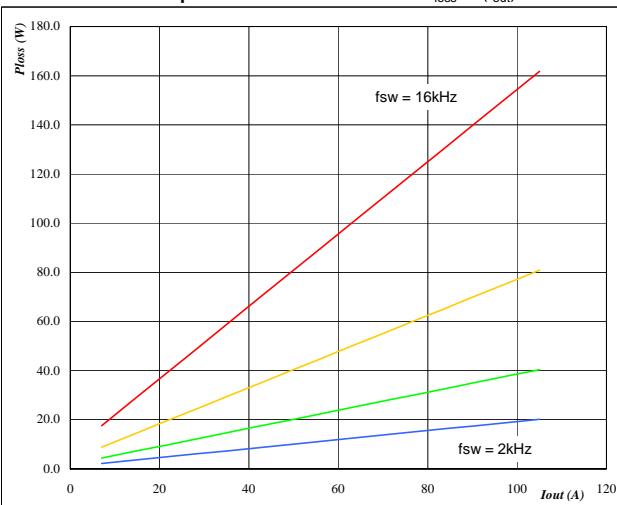
$$T_j = 151^\circ\text{C}$$

 $Mi \cdot \cos \phi$ from -1 to 1 in steps of 0,2**Figure 3**

IGBT

Typical average switching loss as a function of output current

$$P_{loss} = f(I_{out})$$



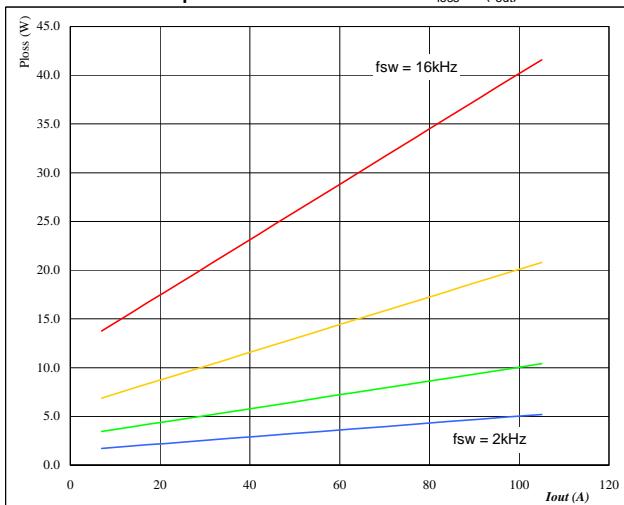
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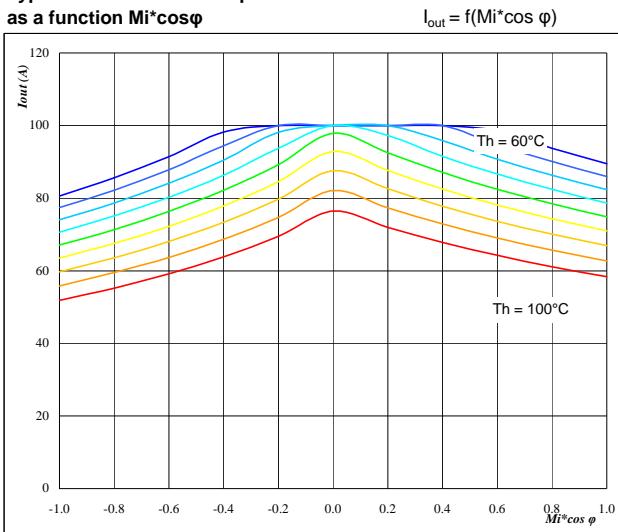
Figure 4

FRED

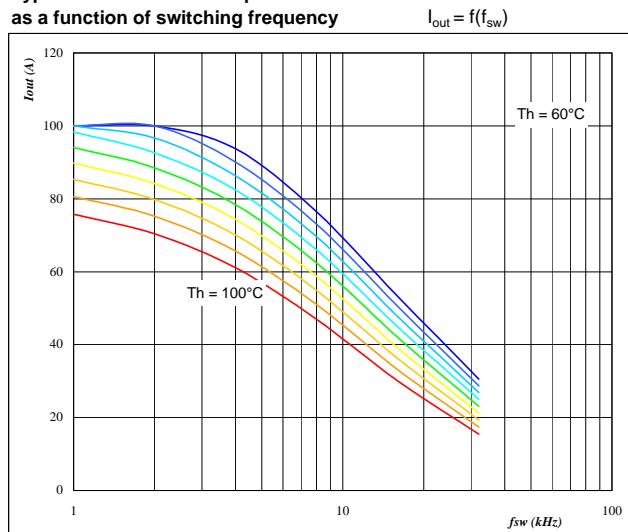
Typical average switching loss as a function of output current

$$P_{loss} = f(I_{out})$$

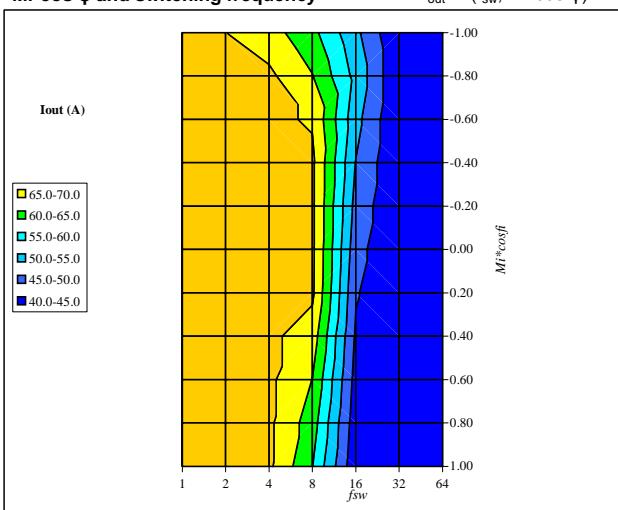


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Figure 5
**Typical available 50Hz output current
as a function $M_i \cos \varphi$**
Phase**At**

$T_j = 151 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $f_{sw} = 4 \text{ kHz}$
 T_h from 60 °C to 100 °C in steps of 5 °C

Figure 6
**Typical available 50Hz output current
as a function of switching frequency**
Phase**At**

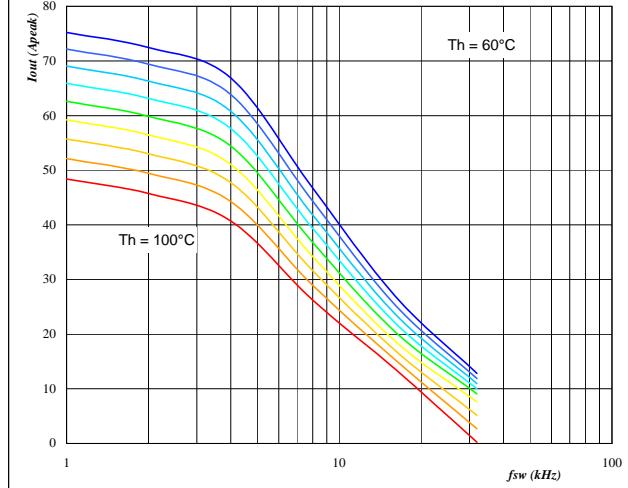
$T_j = 151 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i \cos \varphi = 0.8$
 T_h from 60 °C to 100 °C in steps of 5 °C

Figure 7
**Typical available 50Hz output current as a function of
 $M_i \cos \varphi$ and switching frequency**
Phase**At**

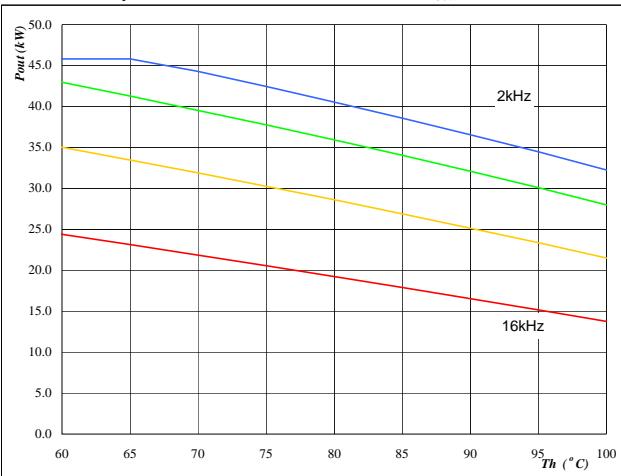
$T_j = 151 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $T_h = 80 \text{ } ^\circ\text{C}$

Figure 8
**Typical available 0Hz output current as a function
of switching frequency**
Phase

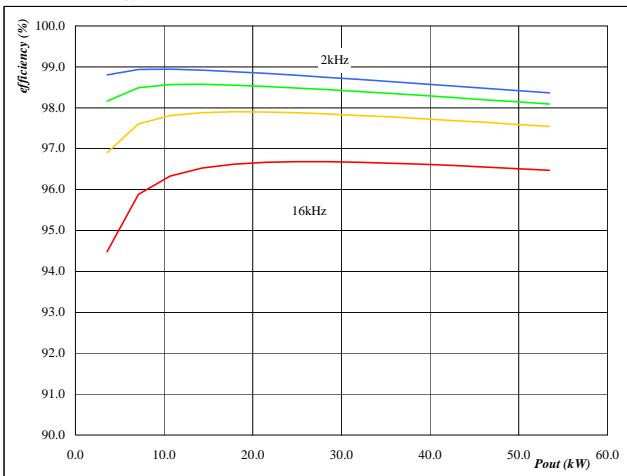
$I_{outpeak} = f(f_{sw})$

**At**

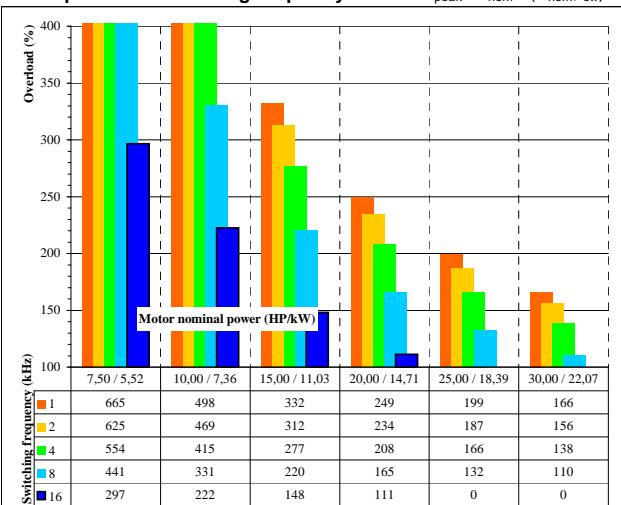
$T_j = 151 \text{ } ^\circ\text{C}$
 DC link = 600 V
 T_h from 60 °C to 100 °C in steps of 5 °C
 $M_i = 0$

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Figure 9
Typical available peak output power as a function of heatsink temperature
 $P_{out}=f(T_h)$
**At**

$T_j = 151 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i = 1$
 $\cos \varphi = 0.80$
 $f_{sw} \text{ from } 2 \text{ kHz to } 16 \text{ kHz in steps of factor 2}$

Inverter**Figure 10**
Typical efficiency as a function of output power
 $\text{efficiency}=f(P_{out})$
**At**

$T_j = 151 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i = 1$
 $\cos \varphi = 0.80$
 $f_{sw} \text{ from } 2 \text{ kHz to } 16 \text{ kHz in steps of factor 2}$

Figure 11
Typical available overload factor as a function of motor power and switching frequency
 $P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$
**At**

$T_j = 151 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i = 1$
 $\cos \varphi = 0.8$
 $f_{sw} \text{ from } 1 \text{ kHz to } 16 \text{ kHz in steps of factor 2}$
 $T_h = 80 \text{ } ^\circ\text{C}$
 Motor eff = 0.85