

STA335W

2.0-channel high-efficiency digital audio system

Features

- Wide voltage supply range
 - 5 V to 26 V (operating range)
 - 30 V (absolute maximum rating)
- 2 channels of ternary PWM (stereo mode) (2 x 20 W into 8 Ω at 18 V)
- 2.0 channels of 24-bit FFX 100 dB SNR and dynamic range
- Selectable 32 to 192 kHz input sample rates
- I²C control with selectable device address
- Digital gain/attenuation +48 dB to -80 dB with 0.5 dB/step resolution
- Soft volume update with programmable ratio
- Individual channel and master gain/attenuation
- Individual channel and master soft/hard mute
- Automatic zero-detect mute
- Automatic invalid input-detect mute
- 2-channel I²S input data interface
- Advanced AM interference frequency switching and noise suppression modes
- Selectable high- or low-bandwidth noise-shaping topologies
- Variable max power correction for lower full-power THD
- Selectable clock input ratio

Table 1. **Device summary**

Order code	Package	Packaging	
STA335W	PowerSSO-36 slug down	Tube	
STA335W13TR	PowerSSO-36 slug down	Tape and reel	



- 96 kHz internal processing sample rate, 24 to 28-bit precision
- Thermal overload and short-circuit protection embedded
- Video apps: 576 x Fs input mode supported
- Fully compatible with STA335BW (on the common registers).



STA335W



1 Description FFX

The STA335W is an integrated solution of digital audio processing, digital amplifier control, and FFX -power output stage, thereby creating a high-power single-chip FFX solution comprising high-quality, high-efficiency, all digital amplification.

STA335W is based on FFX (Full Flexible Amplification) processor.

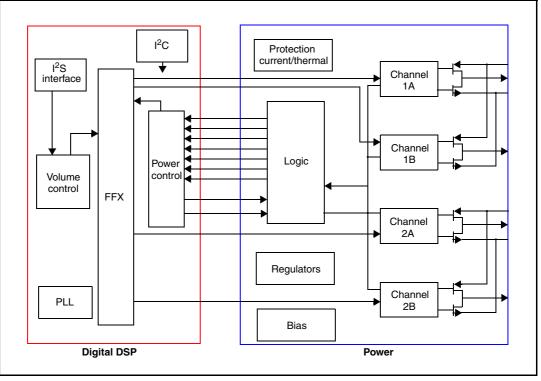
The STA335W is part of the Sound TerminalTM family that provides full digital audio streaming to the speaker, offering cost effectiveness, low power dissipation and sound enrichment.

The STA335W power section consists of two full-bridges. The two channels can provide up to 2 x 20 W of power.

The serial audio data input interface accepts all possible formats, including the popular I²S format. Two channels of FFX processing are provided. This high-quality conversion from PCM audio to FFX PWM switching waveform provides over 100 dB SNR and dynamic range.

1.1 Block diagram



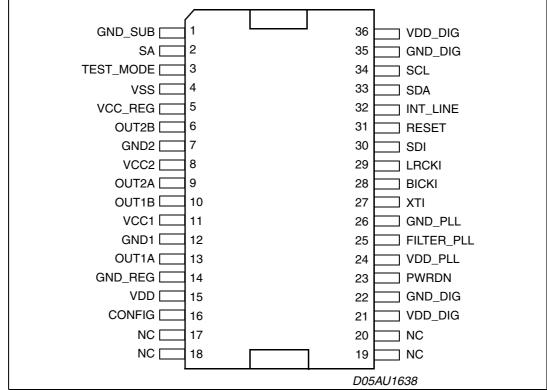




2 Pin connections

2.1 Connection diagram





2.2 Pin description

Table 2. Pin description

Pin	Туре	Name	Description
1	GND	GND_SUB	Substrate ground
2	1	SA	I ² C select address (pull-down)
3	1	TEST_MODE	This pin must be connected to ground (pull-down)
4	I/O	VSS	Internal reference at Vcc-3.3 V
5	I/O	VCC_REG	Internal Vcc reference
6	0	OUT2B	Output half bridge 2B
7	GND	GND2	Power negative supply
8	Power	VCC2	Power positive supply
9	0	OUT2A	Output half bridge 2A
10	0	OUT1B	Output half bridge 1B



Pin	Туре	Name	Description
11	Power	VCC1	Power positive supply
12	GND	GND1	Power negative supply
13	0	OUT1A	Output half bridge 1A
13	GND	GND_REG	Internal ground reference
15	Power	VDD	Internal 3.3 V reference voltage
16	1	CONFIG	Paralleled mode command
17	0	N.C.	Not to be connected
18	0	N.C.	Not to be connected
19	0	N.C.	Not to be connected
20	I/O	N.C.	Not to be connected
21	Power	VDD_DIG	Digital supply voltage
22	GND	GND_DIG	Digital ground
23	I	PWRDN	Power down (pull-up)
24	Power	VDD_PLL	Positive supply for PLL
25	I	FILTER_PLL	Connection to PLL filter
26	GND	GND_PLL	Negative supply for PLL
27	I	XTI	PLL input clock
28	I	BICKI	I ² S serial clock
29	I	LRCKI	I ² S left/right clock
30	I	SDI	I ² S serial data channels 1 and 2
31	I	RESET	Reset (pull-up)
32	0	INT_LINE	Fault interrupt
33	I/O	SDA	I ² C serial data
34	I	SCL	I ² C serial clock
35	GND	GND_DIG	Digital ground
36	Power	VDD_DIG	Digital supply voltage

 Table 2.
 Pin description (continued)



3 Electrical specifications

3.1 Absolute maximum ratings

Symbol	Parameter		Тур	Max	Unit
V _{cc}	Power supply voltage (VCCxA, VCCxB)	-0.3		30	V
VDD_DIG	Digital supply voltage	-0.3		4	V
VDD_PLL	PLL supply voltage	-0.3		4	
T _{op}	Operating junction temperature	-20		150	°C
T _{stg}	Storage temperature	-40		150	°C

Table 3. Absolute maximum ratings

Warning: Stresses beyond those listed in *Table 3* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "Recommended operating conditions" are not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability. In the real application, power supplies with nominal values rated within the recommended operating conditions, may experience some rising beyond the maximum operating conditions for a short time when no or very low current is sinked (amplifier in mute state). In this case the reliability of the device is guaranteed, provided that the absolute maximum ratings are not exceeded.

3.2 Thermal data

Table 4. Thermal data

	Parameter	Min	Тур	Max	Unit
R _{th j-case}	Thermal resistance junction-case (thermal pad)			1.5	°C/W
T _{th-sdj}	Thermal shut-down junction temperature		150		°C
T _{th-w}	Thermal warning temperature		130		°C
T _{th-sdh}	Thermal shut-down hysteresis		20		°C
R _{th j-amb}	Thermal resistance junction-ambient ⁽¹⁾				

1. See Section 7: Package thermal characteristics on page 39 for details.



3.3 Recommended operating conditions

 Table 5.
 Recommended operating condition

Symbol	Parameter	Min	Тур	Мах	Unit
V _{cc}	Power supply voltage (VCCxA, VCCxB)	5		26	V
VDD_DIG	Digital supply voltage	2.7	3.3	3.6	V
VDD_PLL	PLL supply voltage	2.7	3.3	3.6	V
T _{amb}	Ambient temperature	-20		70	°C

3.4 Electrical specifications for the digital section

Table 6.	Electrical specifications - digital section
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Symbol	Parameter	Conditions	Min	Тур	Max	Unit
l _{il}	Low level input current without pull-up/down device	Vi = 0 V		1	10	μA
l _{ih}	High level input current without pull-up/down device	Vi = VDD_DIG = 3.6 V		1	10	μA
V _{il}	Low level input voltage				0.2 * VDD_DIG	V
V _{ih}	High level input voltage		0.8 * VDD_DIG			V
V _{ol}	Low level output voltage	lol=2 mA			0.4 * VDD_DIG	V
V _{oh}	High level output voltage	loh=2 mA	0.8 * VDD_DIG			V
I _{pu}	Pull-up/down current		25	66	125	μA
R _{pu}	Equivalent pull-up/down resistance			50		kΩ

3.5 Electrical specifications for the power section

The specifications given in this section are valid for the operating conditions: $V_{CC} = 18 \text{ V}$, f = 1 kHz, f_{sw} = 384 kHz, T_{amb} = 25° C and R_L = 8 Ω , unless otherwise specified.

Symbol Parameter Conditions Min Тур Max Unit THD = 1% 16 Po Output power BTL W THD = 10% 20 Power Pchannel/Nchannel MOSFET 250 R_{dsON} $I_{d} = 1.5 A$ 180 mΩ (total bridge) gP Power Pchannel RdsON matching l_d = 1.5 A 95 % gΝ Power Nchannel RdsON matching l_d = 1.5 A 95 % VCC = 20 V μA ldss Power Pchannel/Nchannel leakage 10 Resistive load⁽¹⁾ Low current dead time (static) 8 15 ns I_{LDT} $I_{load} = 1.5 A^{(1)}$ High current dead time (dynamic) 30 I_{HDT} 15 ns Resistive load⁽¹⁾ Rise time 10 18 tr ns Fall time Resistive load⁽¹⁾ 10 18 t_f ns Supply voltage operating voltage 5 26 V V_{cc} Supply current from Vcc in power down PWRDN = 00.1 1 mΑ PCM Input signal = -60 dBfs, Ivcc Supply current from Vcc in operation Switching frequency 52 60 mΑ = 384 kHz, No LC filters Supply current FFX processing (reference Internal clock = 70 I_{vdd} 55 mΑ only) 49.152 MHz (2) llim Overcurrent limit A 3.0 3.8 lsc Short circuit protection Hi-Z output 4.0 4.2 А UVL v Under voltage protection 3.5 4.3 Output minimum pulse width No load 20 30 60 ns t_{min} DR Dynamic range 100 dB Signal to noise ratio, ternary mode A-Weighted 100 dB SNR Signal to noise ratio binary mode 90 dB FFX stereo mode, <5 kHz PSSR Power supply rejection ratio V_{RIPPLE} = 1 V RMS 80 dB Audio input = dither only FFX stereo mode, Po = 1 WTotal harmonic distortion + noise 0.2 % THD+N f = 1 kHz

Table 7.	Electrical sr	pecifications -	power section
	Lieutical sp		



Symbol	Parameter	Conditions	Min	Тур	Мах	Unit
X _{TALK}	Crosstalk	FFX stereo mode, <5 kHz One channel driven at 1 W Other channel measured		80		dB
	Peak efficiency, FFX mode	Po = 2 x 20 W into 8 Ω		90		%
η	Peak efficiency, binary modes	$Po = 2 \times 9 \text{ W into } 4 \Omega$ + 1 x 20 W into 8 Ω		87		/0

 Table 7.
 Electrical specifications - power section (continued)

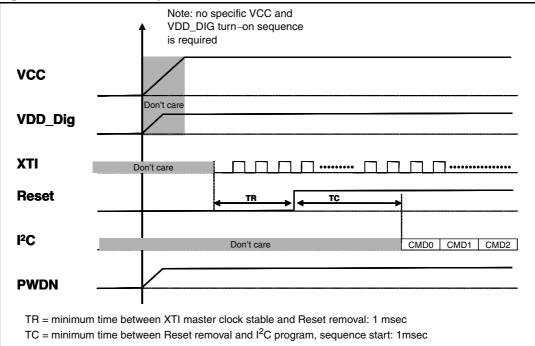
1. Refer to Figure 5: Test circuit 1.

2. Limit current if the register (OCRB par 6.1.3.3) overcurrent warning detect adjustment bypass is enabled. When disabled refer to the lsc.



Power on/off sequence 3.6

Figure 3. **Power-on sequence**

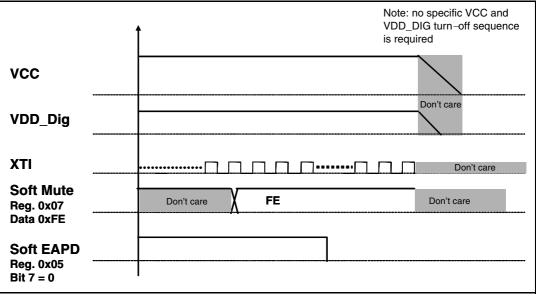


Note:

clock stable means: $f_{max} - f_{min} < 1 MHz$

see Chapter 5.2.3: Serial data first bit, for additional info. Note:





3.7 Testing

3.7.1 Functional pin definition

Table 8. Functional pin definition

Pin name	Number	Logic value	IC status
PWRDN	23	0	Low consumption
	23	1	Normal operation
TWARN	20	0	A temperature warning is indicated by the external power stage
		1	Normal operation
EAPD	19	0	Low consumption for power stage All internal regulators are switched off
		1	Normal operation

Figure 5. Test circuit 1

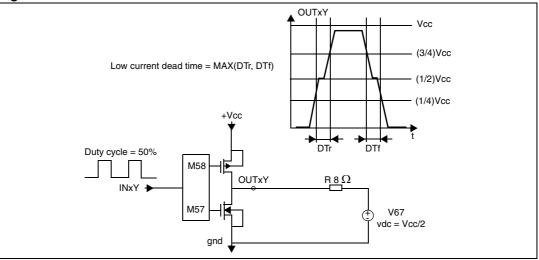
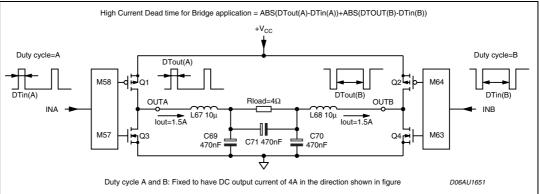


Figure 6. Test circuit 2





4 I²C bus specification

The STA335W supports the I²C protocol via the input ports SCL and SDA_IN (master to slave) and the output port SDA_OUT (slave to master). This protocol defines any device that sends data on to the bus as a transmitter and any device that reads the data as a receiver. The device that controls the data transfer is known as the master and the other as the slave. The master always starts the transfer and provides the serial clock for synchronization. STA335W is always a slave device in all of its communications. It supports up to 400 kb/s rate (fast-mode bit rate). STA335W I²C is a slave only interface.

4.1 Communication protocol

4.1.1 Data transition or change

Data changes on the SDA line must only occur when the SCL clock is low. SDA transition while the clock is high is used to identify a START or STOP condition.

4.1.2 Start condition

START is identified by a high to low transition of the data bus SDA signal while the clock signal SCL is stable in the high state. A START condition must precede any command for data transfer.

4.1.3 Stop condition

STOP is identified by low to high transition of the data bus SDA signal while the clock signal SCL is stable in the high state. A STOP condition terminates communication between STA335W and the bus master.

4.1.4 Data input

During the data input the STA335W samples the SDA signal on the rising edge of clock SCL. For correct device operation the SDA signal must be stable during the rising edge of the clock and the data can change only when the SCL line is low.

4.2 Device addressing

To start communication between the master and the STA335W, the master must initiate with a start condition. Following this, the master sends onto the SDA line 8-bits (MSB first) corresponding to the device select address and read or write mode.

The seven most significant bits are the device address identifiers, corresponding to the I^2C bus definition. In the STA335W the I^2C interface has two device addresses depending on the SA port configuration, 0x38 when SA = 0, and 0x3A when SA = 1.

The eighth bit (LSB) identifies read or write operation RW, this bit is set to 1 in read mode and to 0 for write mode. After a START condition the STA335W identifies on the bus the device address and if a match is found, it acknowledges the identification on SDA bus during the 9th bit time. The byte following the device identification byte is the internal space address.



4.3 Write operation

Following the START condition the master sends a device select code with the RW bit set to 0. The STA335W acknowledges this and the writes for the byte of internal address. After receiving the internal byte address the STA335W again responds with an acknowledgement.

4.3.1 Byte write

In the byte write mode the master sends one data byte, this is acknowledged by the STA335W. The master then terminates the transfer by generating a STOP condition.

4.3.2 Multi-byte write

The multi-byte write modes can start from any internal address. The master generating a STOP condition terminates the transfer.

4.4 Read operation

4.4.1 Current address byte read

Following the START condition the master sends a device select code with the RW bit set to 1. The STA335W acknowledges this and then responds by sending one byte of data. The master then terminates the transfer by generating a STOP condition.

4.4.2 Current address multi-byte read

The multi-byte read modes can start from any internal address. Sequential data bytes are read from sequential addresses within the STA335W. The master acknowledges each data byte read and then generates a STOP condition terminating the transfer.

4.4.3 Random address byte read

Following the START condition the master sends a device select code with the RW bit set to 0. The STA335W acknowledges this and then the master writes the internal address byte. After receiving, the internal byte address the STA335W again responds with an acknowledgement. The master then initiates another START condition and sends the device select code with the RW bit set to 1. The STA335W acknowledges this and then responds by sending one byte of data. The master then terminates the transfer by generating a STOP condition.

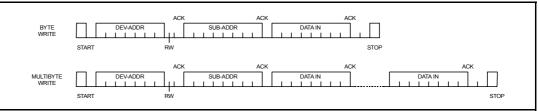
4.4.4 Random address multi-byte read

The multi-byte read modes could start from any internal address. Sequential data bytes are read from sequential addresses within the STA335W. The master acknowledges each data byte read and then generates a STOP condition terminating the transfer.



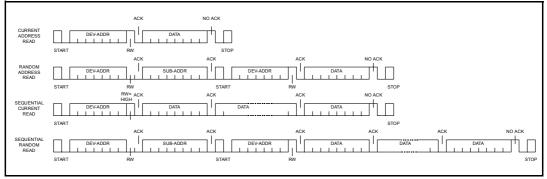
4.4.5 Write mode sequence

Figure 7. Write mode sequence



4.4.6 Read mode sequence

Figure 8. Read mode sequence





5 Register description

Table 9.Register summary

Addr	Name	D7	D6	D5	D4	D3	D2	D1	D0
0x00	CONFA	FDRB	TWAB	TWRB	IR1	IR0	MCS2	MCS1	MCS0
0x01	CONFB	C2IM	C1IM	Reserved	SAIFB	SAI3	SAI2	SAI1	SAI0
0x02	CONFC	OCRB		CSZ3	CSZ2	CSZ1	CSZ0	OM1	OM0
0x03	CONFD	Reserved	ZDE	Reserved	Reserved	PSL	Reserved	Reserved	Reserved
0x04	CONFE	SVE	ZCE	DCCV	PWMS	AME	NSBW	MPC	MPCV
0x05	CONFF	EAPD	PWDN	ECLE	LDTE	BCLE	IDE	Reserved	Reserved
0x06	MUTE/LOC	Reserved	Reserved	Reserved	Reserved	Reserved	C2M	C1M	MMUTE
0x07	MVOL	MV7	MV6	MV5	MV4	MV3	MV2	MV1	MV0
0x08	C1VOL	C1V7	C1V6	C1V5	C1V4	C1V3	C1V2	C1V1	C1V0
0x09	C2VOL	C2V7	C2V6	C2V5	C2V4	C2V3	C2V2	C2V1	C2V0
0x0A					Rese	erved			
0x0B	AUTO1	Reserved							
0x0C	AUTO2	Reserved	Reserved	Reserved	Reserved	AMAM2	AMAM1	AMAM0	AMAME
0x0D					Rese	erved			
0x0E	C1CFG	Reserved	Reserved	Reserved	Reserved	C1BO	Reserved	Reserved	Reserved
0x0F	C2CFG	Reserved	Reserved	Reserved	Reserved	C2BO	Reserved	Reserved	Reserved
0x10					Rese	erved			
0x11					Rese	erved			
0x12					Rese	erved			
0x13					Rese	erved			
0x14					Rese	erved			
0x15					Rese	erved			
0x16	CFADDR	Reserved	Reserved	CFA5	CFA4	CFA3	CFA2	CFA1	CFA0
0x17	B1CF1	C1B23	C1B22	C1B21	C1B20	C1B19	C1B18	C1B17	C1B16
0x18	B1CF2	C1B15	C1B14	C1B13	C1B12	C1B11	C1B10	C1B9	C1B8
0x19	B1CF3	C1B7	C1B6	C1B5	C1B4	C1B3	C1B2	C1B1	C1B0
0x1A					Rese	erved			
0x1B					Rese	erved			
0x1C					Rese	erved			
0x1D					Rese	erved			
0x1E					Rese	erved			
0x1F					Rese	erved			



Addr	Name	D7	D6	D5	D4	D3	D2	D1	D0
0x20				1	Rese	erved	1		1
0x21			Reserved						
0x22					Rese	erved			
0x23					Rese	erved			
0x24					Rese	erved			
0x25					Rese	erved			
0x26	CFUD		Res	erved		Reserved	R1	Reserved	W1
0x27	MPCC1	MPCC15	MPCC14	MPCC13	MPCC12	MPCC11	MPCC10	MPCC9	MPCC8
0x28	MPCC2	MPCC7	MPCC6	MPCC5	MPCC4	MPCC3	MPCC2	MPCC1	MPCC0
0x29	DCC1	DCC15	DCC14	DCC13	DCC12	DCC11	DCC10	DCC9	DCC8
0x2A	DCC2	DCC7	DCC6	DCC5	DCC4	DCC3	DCC2	DCC1	DCC0
0x2B	FDRC1	FDRC15	FDRC14	FDRC13	FDRC12	FDRC11	FDRC10	FDRC9	FDRC8
0x2C	FDRC2	FDRC7	FDRC6	FDRC5	FDRC4	FDRC3	FDRC2	FDRC1	FDRC0
0x2D	STATUS	PLLUL	FAULT	UVFAULT	OVFAULT	OCFAULT	OCWARN	TFAULT	TWARN
0x2E	Reserved	Rese	erved	RO1BACT	R5BACT	R4BACT	R3BACT	R2BACT	R1BACT
0x2F	Reserved	Rese	erved	R01BEND	R5BEND	R4BEND	R3BEND	R2BEND	R1BEND
0x30	Reserved		Reserved		R5BBAD	R4BBAD	R3BBAD	R2BBAD	R1BBAD
0x31	EQCFG	ХОВ	Reserved	Reserved	AMGC3	AMGC2	Reserved	SEL1	SEL0
0x32					Rese	erved			
0x33					Rese	erved			
0x34			Reserved						
0x35					Rese	erved			
0x36					Rese	erved			
0x37		Reserved	Reserved	SVUPE	SVUP[4]	SVUP[3]	SVUP[2]	SVUP[1]	SVUP[0]
0x38		Reserved	Reserved	SVDWE	SVDW[4]	SVDW[3]	SVDW[2]	SVDW[1]	SVDW[0]

Table 9.	Register summary	(continued)
Table 9.	Register summary	(continued)

5.1 Configuration register A (addr 0x00)

D7	D6	D5	D4	D3	D2	D1	D0
FDRB	TWAB	TWRB	IR1	IR0	MCS2	MCS1	MCS0
0	1	1	0	0	0	1	1

5.1.1 Master clock select

	Table 10.	Master clock select
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Bit	R/W	RST	Name	Description
0	R/W	1	MCS0	
1	R/W	1	MCS1	Selects the ratio between the input I ² S sample frequency and the input clock.
2	R/W	0	MCS2	

The STA335W supports sample rates of 32 kHz, 44.1 kHz, 48 kHz, 88.2 kHz, 96 kHz, 176.4 kHz, and 192 kHz. Therefore the internal clock is:

- 32.768 MHz for 32 kHz
- 45.1584 MHz for 44.1 kHz, 88.2 kHz, and 176.4 kHz
- 49.152 MHz for 48 kHz, 96 kHz, and 192 kHz

The external clock frequency provided to the XTI pin must be a multiple of the input sample frequency (f_s) .

The relationship between the input clock and the input sample rate is determined by both the MCSx and the IR (input rate) register bits. The MCSx bits determine the PLL factor generating the internal clock and the IR bit determines the oversampling ratio used internally.

Input sample rate <i>fs</i> (kHz)	IR	MCS[2:0]					
		101	100	011	010	001	000
32, 44.1, 48	00	576 * fs	128 * fs	256 * fs	384 * fs	512 * fs	768 * fs
88.2, 96	01	NA	64 * fs	128 * fs	192 * fs	256 * fs	384 * fs
176.4, 192	1X	NA	32 * fs	64 * fs	96 * fs	128 * fs	192 * fs

Table 11. Input sampling rates



5.1.2 Interpolation ratio select

Table 12. Internal interpolation ratio

Bit	R/W	RST	Name	Description
4:3	R/W	00	IR [1:0]	Selects internal interpolation ratio based on input I ² S sample frequency

The STA335W has variable interpolation (oversampling) settings such that internal processing and FFX output rates remain consistent. The first processing block interpolates by either 2-times or 1-time (pass-through) or provides a 2-times downsample. The oversampling ratio of this interpolation is determined by the IR bits.

Table 13.	IR bit settings as a function of input sample rate
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Input sample rate fs (kHz)	IR	1st stage interpolation ratio
32	00	2 times oversampling
44.1	00	2 times oversampling
48	00	2 times oversampling
88.2	01	Pass-through
96	01	Pass-through
176.4	10	2 times downsampling
192	10	2 times downsampling

5.1.3 Thermal warning recovery bypass

Table 14. Thermal warning recovery bypass

Bit	R/W	RST	Name	Description
5	R/W	1	IWBB	0: Thermal warning recovery enabled 1: Thermal warning recovery disabled

If the thermal warning adjustment is enabled (TWAB = 0), then the thermal warning recovery determines if the -3 dB output limit is removed when thermal warning is negative.

If TWRB = 0 and TWAB = 0, then when a thermal warning disappears the -3 dB output limit is removed and the gain is added back to the system. If TWRB = 1 and TWAB = 0, then when a thermal warning disappears the -3 dB output limit remains until TWRB is changed to zero or the device is reset.

5.1.4 Thermal warning adjustment bypass

Table 15. Thermal warning adjustment bypass

Bit	R/W	RST	Name	Description
6	R/W	1	IWAR	0: Thermal warning adjustment enabled 1: Thermal warning adjustment disabled

The on-chip STA335W power output block provides feedback to the digital controller using inputs to the power control block. Input TWARN is used to indicate a thermal warning



condition. When TWARN is asserted (set to 0) for a period of time greater than 400 ms, the power control block forces a -3 dB output limit (determined by TWOCL in the coefficient RAM) to the modulation limit in an attempt to eliminate the thermal warning condition. Once the thermal warning output limit adjustment is applied, it remains in this state until reset, unless FDRB = 0.

5.1.5 Fault detect recovery bypass

Table 16. Fault detect recovery bypass

Bit	R/W	RST	Name	Description
7	R/W	0	FDRB	0: fault detect recovery enabled 1: fault detect recovery disabled

The on-chip STA335W power output block provides feedback to the digital controller using inputs to the power control block. The FAULT input is used to indicate a fault condition (either over-current or thermal). When FAULT is asserted (set to 0), the power control block attempts a recovery from the fault by asserting the tri-state output (setting it to 0 which directs the power output block to begin recovery), holds it at 0 for period of time in the range of 0.1 ms to 1 second as defined by the fault-detect recovery constant register (FDRC registers 0x29-0x2A), then toggles it back to 1. This sequence is repeated as log as the fault indication exists. This feature is enabled by default but can be bypassed by setting the FDRB control bit to 1.

5.2 Configuration register B (addr 0x01)

D7	D6	D5	D4	D3	D2	D1	D0
C2IM	C1IM	DSCKE	SAIFB	SAI3	SAI2	SAI1	SAI0
1	0	0	0	0	0	0	0

5.2.1 Serial audio input interface format

Bit	R/W	RST	Name	Description
0	R/W	0	SAI0	
1	R/W	0	SAI1	Determines the interface format of the input serial
2	R/W	0	SAI2	digital audio interface.
3	R/W	0	SAI3	

 Table 17.
 Serial audio input interface





5.2.2 Serial data interface

The STA335W audio serial input was designed to interface with standard digital audio components and to accept a number of serial data formats. STA335W always acts as slave when receiving audio input from standard digital audio components. Serial data for two channels is provided using three inputs: left/right clock LRCKI, serial clock BICKI, and serial data 1 and 2 SDI12.

The SAI bits (D3 to D0) and the SAIFB bit (D4) are used to specify the serial data format. The default serial data format is I^2 S, MSB-first. Available formats are shown in the tables and figure that follow.

5.2.3 Serial data first bit

Table 18.Serial data first bit

SAIFB	Format
0	MSB-first
1	LSB-first

Table 19. Support serial audio input formats for MSB-first (SAIFB = 0)

BICKI	SAI [3:0]	SAIFB	Interface format
32 * fs	0000	0	I ² S 15-bit data
32 15	0001	0	Left/right-justified 16-bit data
	0000	0	I ² S 16 to 23-bit data
	0001	0	Left-justified 16 to 24-bit data
48 * fs	0010	0	Right-justified 24-bit data
40 15	0110	0	Right-justified 20-bit data
	1010	0	Right-justified 18-bit data
	1110	0	Right-justified 16-bit data
	0000	0	I ² S 16 to 24-bit data
	0001	0	Left-justified 16 to 24-bit data
64 * fs	0010	0	Right-justified 24-bit data
04 15	0110	0	Right-justified 20-bit data
	1010	0	Right-justified 18-bit data
	1110	0	Right-justified 16-bit data



BICKI	SAI [3:0]	SAIFB	Interface Format
32 * fs	1100	1	I ² S 15-bit data
32 15	1110	1	Left/right-justified 16-bit data
	0100	1	I ² S 23-bit data
	0100	1	I ² S 20-bit data
	1000	1	I ² S 18-bit data
	1100	1	LSB first I ² S 16-bit data
	0001	1	Left-justified 24-bit data
40 * 6-	0101	1	Left-justified 20-bit data
48 * fs	1001	1	Left-justified 18-bit data
	1101	1	Left-justified 16-bit data
	0010	1	Right-justified 24-bit data
	0110	1	Right-justified 20-bit data
	1010	1	Right-justified 18-bit data
	1110	1	Right-justified 16-bit data
	0000	1	I ² S 24-bit data
	0100	1	I ² S 20-bit data
	1000	1	I ² S 18-bit data
	1100	1	LSB first I ² S 16-bit data
	0001	1	Left-justified 24-bit data
04 * 6-	0101	1	Left-justified 20-bit data
64 * fs	1001	1	Left-justified 18-bit data
	1101	1	Left-justified 16-bit data
	0010	1	Right-justified 24-bit data
	0110	1	Right-justified 20-bit data
	1010	1	Right-justified 18-bit data
	1110	1	Right-justified 16-bit data

Table 20. Supported serial audio input formats for LSB-first (SAIFB = 1)

To make the STA335W work properly, the serial audio interface LRCKI clock must be synchronous to the PLL output clock. It means that:

- the frequency of PLL clock / frequency of LRCKI = N ±4 cycles, where N depends on the settings in *Table 13 on page 19*
- the PLL must be locked.

If these two conditions are not met, and IDE bit (reg 0x05 bit 2) is set to 1, the STA335W will immediately mute the I^2S PCM data out (provided to the processing block) and it will freeze any active processing task.

To avoid any audio side effects (like pop noise), it is strongly recommended to soft mute any audio streams flowing into STA335W data path before the desynchronization event



happens. At the same time any processing related to the I²C configuration should be issued only after the serial audio interface and the internal PLL are synchronous again.

Note: Any mute or volume change causes some delay in the completion of the I²C operation due to the soft volume feature. The soft volume phase change must be finished before any clock desynchronization.

5.2.4 Channel input mapping

Bit	R/W	RST	Name	Description
6	R/W	0	C1IM	0: Processing channel 1 receives Left I ² S Input 1: Processing channel 1 receives Right I ² S Input
7	R/W	1	C2IM	0: Processing channel 2 receives Left I ² S Input 1: Processing channel 2 receives Right I ² S Input

Table 21. Channel input mapping

Each channel received via I²S can be mapped to any internal processing channel via the Channel Input Mapping registers. This allows for flexibility in processing. The default settings of these registers map each I²S input channel to its corresponding processing channel.



5.3 Configuration register C (addr 0x02)

D7	D6	D5	D4	D3	D2	D1	D0
OCRB		CSZ3	CSZ2	CSZ1	CSZ0	OM1	OM0
1		0	1	1	1	1	1

5.3.1 FFX power output mode

Table 22. FFX power output mode

Bit	R/W	RST	Name	Description
0	R/W	1	OM0	Selects configuration of FFX output.
1	R/W	1	OM1	

The FFX power output mode selects how the FFX output timing is configured.

Different power devices use different output modes.

Table 23.Output modes

OM[1,0]	Output stage mode		
00	Drop compensation		
01	Discrete output stage - tapered compensation		
10	Full power mode		
11	Variable drop compensation (CSZx bits)		

5.3.2 FFX compensating pulse size register

Table 24. FFX compensating pulse size bits

Bit	R/W	RST	Name	Description
2	R/W	1	CSZ0	
3	R/W	1	CSZ1	When OM[1,0] = 11, this register determines the size of the FFX compensating pulse from 0 clock ticks to
4	R/W	1	CSZ2	15 clock periods.
5	R/W	0	CSZ3	

Table 25.Compensating pulse size

CSZ[3:0]	Compensating Pulse Size
0000	0 ns (0 tick) compensating pulse size
0001	20 ns (1 tick) clock period compensating pulse size
1111	300 ns (15 tick) clock period compensating pulse size



5.3.3 Over-current warning detect adjustment bypass

Table 26. Ov	er-current warning bypass
--------------	---------------------------

Bit	R/W	RST	Name	Description
7	R/W	1	OCRB	0: Over-Current warning adjustment enabled 1: Over-Current warning adjustment disabled

The OCWARN input is used to indicate an over-current warning condition. When OCWARN is asserted (set to 0), the power control block forces an adjustment to the modulation limit (default is -3 dB) in an attempt to eliminate the over-current warning condition. Once the over-current warning volume adjustment is applied, it remains in this state until reset is applied. The level of adjustment can be changed via the TWOCL (thermal warning/over current limit) setting which is address 0x37 of the user defined coefficient RAM.

5.4 Configuration register D (addr 0x03)

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	ZDE	Reserved	Reserved	PSL	Reserved	Reserved	Reserved
0	1	0	0	0	0	0	0

5.4.1 Post-scale link

Table 27.Post-scale link

Bit	R/W	RST	Name	Description
3	R/W	0	PSI	0: Each channel uses individual post-scale value 1: Each channel uses channel 1 post-scale value

Post-scale functionality can be used for power-supply error correction. For multi-channel applications running off the same power-supply, the post-scale values can be linked to the value of channel 1 for ease of use and update the values faster.

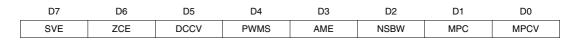
5.4.2 Zero-detect mute enable

Table 28. Zero-detect mute enable

Bit	R/W	RST	Name	Description
6	R/W	1	ZDE	Setting of 1 enables the automatic zero-detect mute

Setting the ZDE bit enables the zero-detect automatic mute. The zero-detect circuit looks at the data for each processing channel at the output of the crossover (bass management) filter. If any channel receives 2048 consecutive zero value samples (regardless of fs) then that individual channel is muted if this function is enabled.

5.5 Configuration register E (addr 0x04)





D7	D6	D5	D4	D3	D2	D1	D0
1	1	0	0	0	0	1	0

5.5.1 Max power correction variable

Table 29.Max power correction variable

Bit	R/W	RST	Name	Description
0	R/W	0	MPCV	0: Use standard MPC coefficient 1: Use MPCC bits for MPC coefficient

5.5.2 Max power correction

Table 30.Max power correction

Bit	R/W	RST	Name	Description
1	R/W	1	MPC.	Setting of 1 enables Power Bridge correction for THD reduction near maximum power output.

Setting the MPC bit turns on special processing that corrects the STA335W power device at high power. This mode should lower the THD+N of a full FFX system at maximum power output and slightly below. If enabled, MPC is operational in all output modes except tapered (OM[1,0] = 01) and binary. When OCFG = 00, MPC will not effect channels 3 and 4, the line-out channels.

5.5.3 Noise-shaper bandwidth selection

Table 31. Noise-shaper bandwidth selection

Bit	R/W	RST	Name	Description
2	R/W	0	NSBW	1: Third order NS 0: Fourth order NS

5.5.4 AM mode enable

Table 32. AM mode enable

Bit	R/W	RST	Name	Description
3	R/W	0	AME	0: Normal FFX operation. 1: AM reduction mode FFX operation

STA335W features aFFX processing mode that minimizes the amount of noise generated in frequency range of AM radio. This mode is intended for use when FFX is operating in a device with an AM tuner active. The SNR of the FFX processing is reduced to approximately 83 dB in this mode, which is still greater than the SNR of AM radio.



5.5.5 PWM speed mode

Table 33.PWM speed mode

Bit	R/W	RST	Name	Description
4	R/W	0	PWMS	0: Normal speed (384 kHz) all channels 1: Odd speed (341.3 kHz) all channels

5.5.6 Distortion compensation variable enable

Table 34. Distortion compensation variable enable

Bit	R/W	RST	Name	Description
5	R/W	0	DCCV	0: Use preset DC coefficient 1: Use DCC coefficient

5.5.7 Zero-crossing volume enable

Table 35. Zero-crossing volume enable

Bit	R/W	RST	Name	Description
6	R/W	1	ZCE	 1: Volume adjustments only occur at digital zero- crossings 0: Volume adjustments occur immediately

The ZCE bit enables zero-crossing volume adjustments. When volume is adjusted on digital zero-crossings no clicks are audible.

5.5.8 Soft volume update enable

Table 36.Soft volume update enable

Bit	R/W	RST	Name	Description
7	R/W	1	SVE	 Volume adjustments ramp according to SVR settings Volume adjustments occur immediately

5.6 Configuration register F (addr 0x05)

D7	D6	D5	D4	D3	D2	D1	D0
EAPD	PWDN	ECLE	LDTE	BCLE	IDE	Reserved	Reserved
0	1	0	1	1	1	0	0



5.6.1 Invalid input detect mute enable

Table 37. Invalid input detect mute enable

Bit	R/W	RST	Name	Description
2	R/W	1	IDE	Setting of 1 enables the automatic invalid input detect mute

Setting the IDE bit enables this function, which looks at the input I²S data and automatically mutes if the signals are perceived as invalid.

5.6.2 Binary output mode clock loss detection

Table 38. Binary output mode clock loss detection

Bit	R/W	RST	Name	Description
3	R/W	1	BCLE	Binary output mode clock loss detection enable

Detects loss of input MCLK in binary mode and will output 50% duty cycle.

5.6.3 LRCK double trigger protection

Table 39. LRCK double trigger protection

Bit	R/W	RST	Name	Description		
4	R/W	1	LDTE	LRCLK double trigger protection enable		

Actively prevents double trigger of LRCLK.

5.6.4 Auto EAPD on clock loss

Table 40. Auto EAPD on clock loss

Bit	R/W	RST	Name	Description			
5	R/W	0	ECLE	Auto EAPD on clock loss			

When active, issues a power device power down signal (EAPD) on clock loss detection.

5.6.5 IC power down

Table 41. IC power down

Bit	R/W	RST	Name	Description
6	R/W	1	PWDN	0: IC power down low-power condition 1: IC normal operation

The PWDN register is used to place the IC in a low-power state. When PWDN is written as 0, the output begins a soft-mute. After the mute condition is reached, EAPD is asserted to power down the power-stage, then the master clock to all internal hardware expect the I^2C block is gated. This places the IC in a very low power consumption state.



5.6.6 Amplifier power down

Table 42.External amplifier power down

Bit	R/W	RST Name		Description
7	R/W	0	FAPU	0: Power stage power down active 1: Normal operation

The EAPD register directly disables/enables the internal power circuitry.

When EAPD = 0, the internal power section is placed on a low-power state (disabled).

5.7 Volume control registers (addr 0x06 - 0x0A)

5.7.1 Mute/line output configuration register

D7	D6	D5	D4	D3	D2	D1	D0
LOC1	LOC0	Reserved	Reserved	C3M	C2M	C1M	MMUTE
0	0	0	0	0	0	0	0

Table 43.Line output configuration

LOC[1:0]	Line output configuration						
00	Line output fixed - no volume, no EQ						
01	Line output variable - CH3 volume effects line output, no EQ						
10	Line output variable with EQ - CH3 volume effects line output						

Line output is only active when OCFG = 00. In this case LOC determines the line output configuration. The source of the line output is always the channel 1 and 2 inputs.

5.7.2 Master volume register

D7	D6	D5	D4	D3	D2	D1	D0
MV7	MV6	MV5	MV4	MV3	MV2	MV1	MV0
1	1	1	1	1	1	1	1

5.7.3 Channel 1 volume

D7	D6	D5	D4	D3	D2	D1	D0
C1V7	C1V6	C1V5	C1V4	C1V3	C1V2	C1V1	C1V0
0	1	1	0	0	0	0	0

5.7.4 Channel 2 volume

D7	D6	D5	D4	D3	D2	D1	D0
C2V7	C2V6	C2V5	C2V4	C2V3	C2V2	C2V1	C2V0
0	1	1	0	0	0	0	0



The Volume structure of the STA335W consists of individual volume registers for each channel and a master volume register that provides an offset to each channels volume setting. The individual channel volumes are adjustable in 0.5 dB steps from +48 dB to -80 dB.

As an example if C1V = 0x00 or +48 dB and MV = 0x18 or -12 dB, then the total gain for channel 1 = +36 dB.

The master mute, when set to 1, mutes all channels at once, whereas the individual channel mutes (CxM) mutes only that channel. Both the master mute and the channel mutes provide a "soft mute" with the volume ramping down to mute in 4096 samples from the maximum volume setting at the internal processing rate (approximately 96 kHz).

A "hard (instantaneous) mute" can be obtained by programming a value of 0xFF (255) to any channel volume register or the master volume register. When volume offsets are provided via the master volume register any channel whose total volume is less than -80 dB is muted.

All changes in volume take place at zero-crossings when ZCE = 1 (*Configuration register E (addr 0x04) on page 25*) on a per channel basis as this creates the smoothest possible volume transitions. When ZCE = 0, volume updates occur immediately.

MV[7:0]	Volume offset from channel value
00000000 (0x00)	0 dB
00000001 (0x01)	-0.5 dB
00000010 (0x02)	-1 dB
01001100 (0x4C)	-38 dB
1111110 (0xFE)	-127.5 dB
11111111 (0xFF)	Hard master mute

 Table 44.
 Master volume offset as a function of MV[7:0]

Table 45.Channel volume as a function of CxV[7:0]

CxV[7:0]	Volume
00000000 (0x00)	+48 dB
00000001 (0x01)	+47.5 dB
00000010 (0x02)	+47 dB
01011111 (0x5F)	+0.5 dB
01100000 (0x60)	0 dB
01100001 (0x61)	-0.5 dB
11010111 (0xD7)	-59.5 dB
11011000 (0xD8)	-60 dB



CxV[7:0]	Volume							
11011001 (0xD9)	-61 dB							
11011010 (0xDA)	-62 dB							
11101100 (0xEC)	-80 dB							
11101101 (0xED)	Hard channel mute							
11111111 (0xFF)	Hard channel mute							

 Table 45.
 Channel volume as a function of CxV[7:0] (continued)

5.8 Audio preset registers (0x0C)

5.8.1 Audio preset register 2 (addr 0x0C)

D7	D6	D5	D4	D3	D2	D1	D0
XO3	XO2	XO1	XO0	AMAM2	AMAM1	AMAM0	AMAME
0	0	0	0	0	0	0	0

5.8.2 AM interference frequency switching

Table 46. AM interference frequency switching bits

Bi	R/W	RST	Name	Description		
0	R/W	0	AMAME	Audio preset AM enable 0: switching frequency determined by PWMS setting 1: switching frequency determined by AMAM settings		

Table 47. Audio preset AM switching frequency selection

	3 1 <i>7</i>	
AMAM[2:0]	48 kHz/96 kHz input fs	44.1 kHz/88.2 kHz input fs
000	0.535 MHz - 0.720 MHz	0.535 MHz - 0.670 MHz
001	0.721 MHz - 0.900 MHz	0.671 MHz - 0.800 MHz
010	0.901 MHz - 1.100 MHz	0.801 MHz - 1.000 MHz
011	1.101 MHz - 1.300 MHz	1.001 MHz - 1.180 MHz
100	1.301 MHz - 1.480 MHz	1.181 MHz - 1.340 MHz
101	1.481 MHz - 1.600 MHz	1.341 MHz - 1.500 MHz
110	1.601 MHz - 1.700 MHz	1.501 MHz - 1.700 MHz



5.9 User-defined coefficient control registers (addr 0x16 - 0x26)

5.9.1 Coefficient address register

D7	D6	D5	D4	D3	D2	D1	D0
		CFA5	CFA4	CFA3	CFA2	CFA1	CFA0
		0	0	0	0	0	0

5.9.2 Coefficient data register bits 23:16

D7	D6	D5	D4	D3	D2	D1	D0
C1B23	C1B22	C1B21	C1B20	C1B19	C1B18	C1B17	C1B16
0	0	0	0	0	0	0	0

5.9.3 Coefficient data register bits 15:8

D7	D6	D5	D4	D3	D2	D1	D0
C1B15	C1B14	C1B13	C1B12	C1B11	C1B10	C1B9	C1B8
0	0	0	0	0	0	0	0

5.9.4 Coefficient data register bits 7:0

D7	D6	D5	D4	D3	D2	D1	D0
C1B7	C1B6	C1B5	C1B4	C1B3	C1B2	C1B1	C1B0
0	0	0	0	0	0	0	0

5.9.5 Coefficient write/read control register

D7	D6	D5	D4	D3	D2	D1	D0
Reserved				Reserved	R1	Reserved	W1
	0			0	0	0	0

Coefficients for user-defined scaling are handled internally in the STA335W via RAM. Access to this RAM is available to the user via an I^2C register interface. A collection of I^2C registers are dedicated to this function. One contains a coefficient base address, five sets of three store the values of the 24-bit coefficients to be written or that were read, and one contains bits used to control the write/read of the coefficient(s) to/from RAM.

Note: The read and write operation on RAM coefficients works only if LRCKI (pin 29) is switching.

Reading a coefficient from RAM

- 1. Select the RAM block with register 0x31 bit1, bit0.
- 2. Write 6-bits of address to I²C register 0x16.
- 3. Write 1 to R1 bit in I^2C address 0x26.
- 4. Read top 8-bits of coefficient in I^2C address 0x17.
- 5. Read middle 8-bits of coefficient in I^2C address 0x18.
- 6. Read bottom 8-bits of coefficient in I^2C address 0x19.



Writing a single coefficient to RAM

- 1. Select the RAM block with register 0x31 bit1, bit0.
- 2. Write 6-bits of address to I^2C register 0x16.
- 3. Write top 8-bits of coefficient in I^2C address 0x17.
- 4. Write middle 8-bits of coefficient in I^2C address 0x18.
- 5. Write bottom 8-bits of coefficient in I^2C address 0x19.
- 6. Write 1 to W1 bit in I^2C address 0x26.

5.9.6 Post-scale

The STA335W provides one additional multiplication after the last interpolation stage and the distortion compensation on each channel. This post-scaling is accomplished by using a 24-bit signed fractional multiplier, with 0x800000 = -1 and 0x7FFFFF = 0.9999998808. The scale factor for this multiply is loaded into RAM using the same I²C registers as the biquad coefficients and the bass-management. This post-scale factor can be used in conjunction with an ADC equipped micro-controller to perform power-supply error correction. All channels can use the channel-1 post-scale factor by setting the post-scale link bit. By default, all post-scale factors are set to 0x7FFFFF. When line output is being used, channel-3 post-scale will affect both channels 3 and 4.

5.9.7 Over-current post-scale

The STA335W provides a simple mechanism for reacting to over-current detection in the power-block. When the ocwarn input is asserted, the over-current post-scale value is used in place of the normal post-scale value to provide output attenuation on all channels. The default setting provides 3 dB of output attenuation when ocwarn is asserted.

The amount of attenuation to be applied in this situation can be adjusted by modifying the Over-current Post-scale value. As with the normal post-scale, this scaling value is a 24-bit signed fractional multiplier, with 0x800000 = -1 and 0x7FFFFF = 0.9999998808. By default, the over-current post-scale factor is set to 0x5A9DF7. Once the over-current attenuation is applied, it remains until the device is reset.

Index (Decimal)	Index (Hex)		Coefficient	Default
0		Reserved		
		Reserved		
52	0x34	Channel 1 - Post-Scale	C1PstS	0x7FFFFF
53	0x35	Channel 2 - Post-Scale	C2PstS	0x7FFFFF
54	0x36	Reserved		
55	0x37	TWARN/OC - Limit	TWOCL	0x5A9DF7

Table 48. RAM block for scaling management

5.10 Variable max power correction registers (addr 0x27 - 0x28)

D7	D6	D5	D4	D3	D2	D1	D0
MPCC15	MPCC14	MPCC13	MPCC12	MPCC11	MPCC10	MPCC9	MPCC8



D7	D6	D5	D4	D3	D2	D1	D0
0	0	0	1	1	0	1	0
D7	D6	D5	D4	D3	D2	D1	D0
MPCC7	MPCC6	MPCC5	MPCC4	MPCC3	MPCC2	MPCC1	MPCC0
1	1	0	0	0	0	0	0

MPCC bits determine the 16 MSBs of the MPC compensation coefficient. This coefficient is used in place of the default coefficient when MPCV = 1.

5.11 Variable distortion compensation registers (addr 0x29 - 0x2A)

D7	D6	D5	D4	D3	D2	D1	D0
DCC15	DCC14	DCC13	DCC12	DCC11	DCC10	DCC9	DCC8
1	1	1	1	0	0	1	1
					•		
D7	D6	D5	D4	D3	D2	D1	D0
DCC7	DCC6	DCC5	DCC4	DCC3	DCC2	DCC1	DCC0
0	0	1	1	0	0	1	1

DCC bits determine the 16 MSBs of the Distortion compensation coefficient. This coefficient is used in place of the default coefficient when DCCV = 1.

5.12 Fault detect recovery constant registers (addr 0x2B - 0x2C)

D7	D6	D5	D4	D3	D2	D1	D0
FDRC15	FDRC14	FDRC13	FDRC12	FDRC11	FDRC10	FDRC9	FDRC8
0	0	0	0	0	0	0	0
							·
D7	D6	D5	D4	D3	D2	D1	D0
FDRC7	FDRC6	FDRC5	FDRC4	FDRC3	FDRC2	FDRC1	FDRC0
0	0	0	0	1	1	0	0

FDRC bits specify the 16-bit fault detect recovery time delay. When FAULT is asserted, the TRISTATE output is immediately asserted low and held low for the time period specified by this constant. A constant value of 0x0001 in this register is approximately 0.083 ms. The default value of 0x000C gives approximately 0.1 ms.

5.13 Device status register (addr 0x2D)

D7	D6	D5	D4	D3	D2	D1	D0	
PLLUL	FAULT	UVFAULT	OVFAULT	OCFAULT	OCWARN	TFAULT	TWARN]

This read-only register provides fault and thermal-warning status information from the power control block. Logic value 1 for faults or warning means normal state. Logic 0 means a fault or warning detected on power bridge. The PLLUL = 1 means that the PLL is not locked.



Table										
Bit	R/W	RST	Name	Description						
7	R	-	PLLUL	0: PLL locked 1: PLL not locked						
6	R	-	FAULT	0: fault detected on power bridge 1: normal operation						
5	R	-	UVFAULT	0: VCCxX internally detected < undervoltage threshold						
4	R	-	OVFAULT	0: VCCxX internally detected > overvoltage threshold						
3	R	-	OCFAULT	0: overcurrent fault detected						
2	R	-	OCWARN	0: overcurrent warning						
1	R	-	TFAULT	0: thermal fault, junction temperature over limit detection						
0	R	-	TWARN	0: thermal warning, junction temperature is close to the fault condition						

Table 49. Status register bits

5.13.1 Extended Soft Volume configuration registers (addr 0x37 - 0x38)

D7	D6	D5	D4	D3	D2	D1	D0
		SVUPE	SVUP[4]	SVUP[3]	SVUP[2]	SVUP[1]	SVUP[0]
0	0	0	0	0	0	0	0
D7	D6	D5	D4	D3	D2	D1	D0
		SVDWE	SVDW4]	SVDW[3]	SVDW[2]	SVDW[1]	SVDW[0]
0	0	0	0	0	0	0	0

Soft volume update has a fixed rate by default. Using register 0x37 and 0x38 it is possible to override the default behavior allowing different volume change rates.

It is also possible to independently define the fade-in (volume is increased) and fade-out (volume is decreased) rates according to the desired behavior.

SVUPE	Mode
0	When volume is increased, use the default rate
1	When volume is increased, use the rates defined by SVUP[4:0].

When SVUPE = 1 the fade-in rate is defined by the SVUP[4:0] bits according to the following formula:

Fade-in rate = 48 / (N + 1) dB/ms

where N is the SVUP[4:0] value.

SVDWE	Mode
0	When volume is decreased, use the default rate
1	When volume is decreased, use the rates defined by SVDW[4:0] .



When SVDWE = 1 the fade-out rate is defined by the SVDW[4:0] bits according to the following formula:

Fade-in rate = 48 / (N + 1) dB/ms

where N is the SVDW[4:0] value.



6 Application

6.1 Application scheme for power supplies

Here in the next figure the typical application scheme for STA335W concerning the power supplies. A particular care has to be devoted to the layout of the PCB. In particular all the decoulpling capacitors have to be put as much as possible closed to the device to limit spikes on all the supplies.

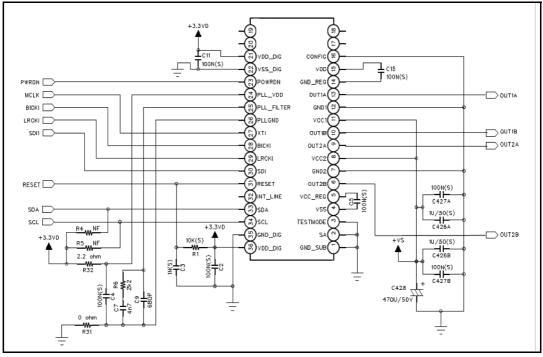


Figure 9. Application scheme for power supplies

6.2 PLL filter schematic

It is recommended to use the above scheme and values for the PLL loop filter to achieve the best performances from the device in general application. Please be noted that the ground of this filter scheme has to be connected to the ground of the PLL without any resistive path. Concerning the component values, please take into account that the greater is the filter bandwidth, the less is the lock time but the higher is the PLL output jitter.

6.3 Typical output configuration

Here after the typical output configuration used for BTL stereo mode. Please refer to the application note for all the other possible output configuration recommended schematics.



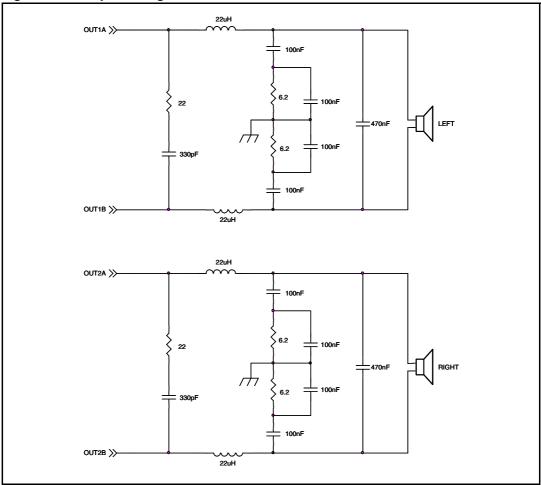


Figure 10. Output configuration for stereo BTL mode





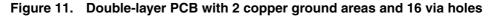
7 Package thermal characteristics

Using a double-layer PCB the thermal resistance junction to ambient with 2 copper ground areas of $3 \times 3 \text{ cm}^2$ and with 16 via holes (see *Figure 11*) is 24 °C/W in natural air convection.

The dissipated power within the device depends primarily on the supply voltage, load impedance and output modulation level.

Thus, the maximum estimated dissipated power for the STA335W is:

 $2 \times 10 \text{ W} + 1 \times 20 \text{ W} @ 4 \Omega$, 8Ω , 18 V Pd max < 5 W



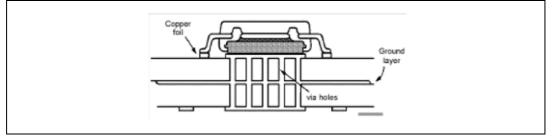
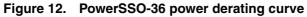
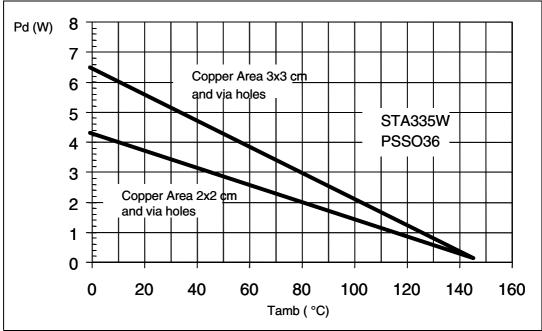


Figure 12 shows the power derating curve for the PowerSSO-36 package on PCBs with copper areas of 2 x 2 cm² and 3 x 3 cm².







STA335W

8 Package information

Figure 13 shows the package outline and *Table 50* gives the dimensions.

Figure 13. PowerSSO-36 slug down outline drawing

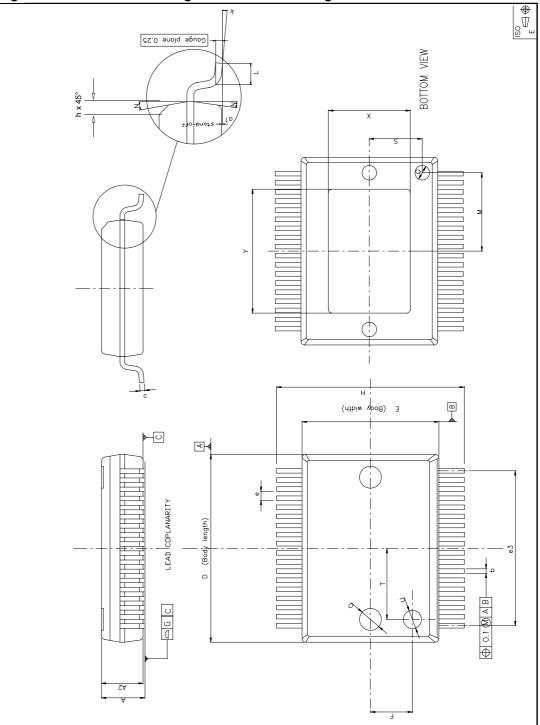




Table 50. PowerSSO-36 slug down dimensions									
Symbol		mm		inch					
Symbol	Min	Тур	Max	Min	Тур	Max			
А	2.15	-	2.47	0.085	-	0.097			
A2	2.15	-	2.40	0.085	-	0.094			
a1	0	-	0.10	0	-	0.004			
b	0.18	-	0.36	0.007	-	0.014			
с	0.23	-	0.32	0.009	-	0.013			
D	10.10	-	10.50	0.398	-	0.413			
E	7.40	-	7.60	0.291	-	0.299			
е	-	0.5	-	-	0.020				
e3	-	8.5	-	-	0.335				
F	-	2.3	-	-	0.091				
G	-	-	0.10	-	-	0.004			
Н	10.10	-	10.50	0.398		0.413			
h	-	-	0.40			0.016			
k	0	-	8 degrees			8 degrees			
L	0.60	-	1.00	0.024		0.039			
М	-	4.30	-		0.169				
N	-	-	10 degrees			10 degrees			
0	-	1.20	-		0.047				
Q	-	0.80	-		0.031				
S	-	2.90	-		0.114				
Т	-	3.65	-		0.144				
U	-	1.00	-		0.039				
Х	4.10		4.70	0.161		0.185			
Y	4.90		7.10	0.193		0.280			

Table 50. PowerSSO-36 slug down dimensions

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK[®] packages, depending on their level of environmental compliance. ECOPACK[®] specifications, grade definitions and product status are available at: www.st.com. ECOPACK[®] is an ST trademark.



9 Revision history

Table 51. Document revision history

Date	Revision	Changes
03-July-2009	1	Initial release



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