

UNISONIC TECHNOLOGIES CO., LTD

UL497

Preliminary

LINEAR INTEGRATED CIRCUIT

HALL EFFECT PICKUP **IGNITION CONTROLLER**

DESCRIPTION

As an integrated electronic ignition controller for breakerless ignition systems which uses Hall effect sensors, the UTC UL497 drives an NPN external darlington to control the coil current providing the required stored energy with low dissipation.

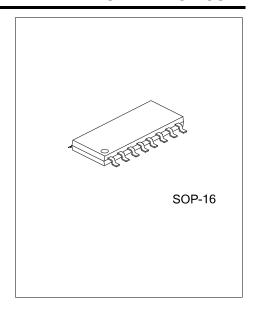
One of the UTC **UL497** special features is the programmable time for the recovery of the correct dwell ratio Td/T while the coil peak current fails to reach 94 % of the nominal value.

FEATURES

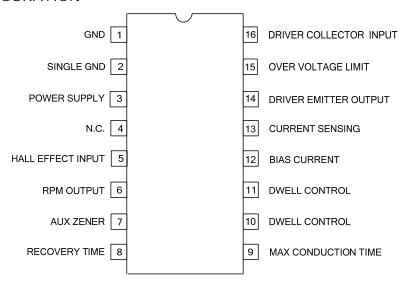
- * Direct driving of the external power darlington
- * Coil current charent charging angle control
- * Programme coil current peak limitation
- * When 94% nominal current not reached programmable dwell recovery time
- * RPM output
- * Has peranent conduction protection
- * Overvoltage protection
- * Internal supply zener
- * Reverse battery protection

■ ORDERING INFORMATION					
Orderin	g Number	Dooleans	Dealing		
Lead Free	Halogen Free	Package	Packing		
UL497L-S16-R	UL497G-S16-R	SOP-16	Tape Reel		
UL497L-S16-T	UL497G-S16-T	SOP-16	Tube		

UL497 <u>L-S16</u> -R)Packing Type	(1) R: Tape Reel, T: Tube
(2)	2)Package Type	(2) S16: SOP-16
(3)	3)Halogen Free	(3) L: Lead Free, G: Halogen Free



■ PIN CONFIGURATION



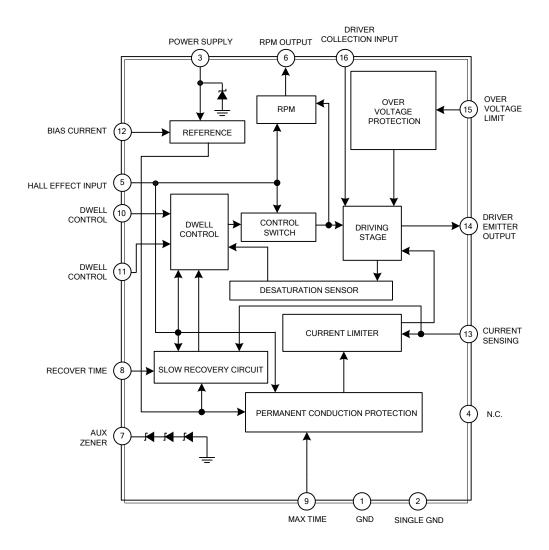
■ PIN DESCRIPTION (refer to APPLICATION CIRCUIT)

PIN NO.	PIN NAME	DESCRIPTION
1	GND	This pin must be connected to ground.
2	SIGNAL GND	This pin must be connected to ground.
3	POWER SUPPLY	The input of supply voltage. Its voltage will be limited by an 7.5V zener. The R5 inside will limit the current by the zener for high supply voltage.
4	N.C.	Connected to ground or left open.
5	HALL-EFFECT INPUT	The input of the hall-effect pickup signal. This input is dwell control circuit output to enable the current driving into the coil.
6	RPM OUTPUT	As a open collector output, it's at low level when current flows in the ignition coil. It should be connected pin7 zener for high volteges protection. Then R_8 must limit the zener current, too, and R_1 limits pin 6 current if RPM module pad is accidentally connected to V_S .
7	AUX. ZENER	A 21V Zener whose current must be limited by an internal resistor.
8	RECOVERY TIME	A capacitor connected between this pin and ground sets the slope of the dwell time variation as it rises from zero to the correct value. It occurs just following the detection of I $_{coll} \le 94\%$ I $_{nom}$, only before the low transition of the hall-effect signal pulse. The duration is given : $t_{src} = 12.9 \times R_{7src} \times C_{src}$ (ms) PS: R_7 (K Ω) is the biasing resistor at pin 12 and C_{src} (μF) is the delay capacitor at pin 8.
9	MAX CONDUCTION TIME	Between this pin and ground there's a capacitor which determines the intervention delay of the permanent conduction protection. The coil current is slowly reduced to zero after the delay time. Delay Time T_P is given by : $t_P = 16 \times R_7 \ C_P \ (ms)$ PS: $R_7 \ (K\Omega)$ is the biasing resistor at pin 12 and $C_P \ (\mu F)$ is the delay capacitor at pin 9.
10	DWELL CONTROL TIMER	Connected between this pin and ground there's a capacitor C_T which is charged when the Hall effect output is High and is discharged at the High to Low transition of the Hall effect signal. When using a $62K\Omega$ resistor at pin12 C_T should be 100nF.

■ PIN DESCRIPTION (Cont.)

PIN NO.	PIN NAME	DESCRIPTION
11	DWELL CONTROL	The average voltage on the capacitor CW connected between this pin and ground depends on the motor speed and the voltage supply. The comparison between V $_{\text{CW}}$ and V $_{\text{CT}}$ voltage determines the timing for the dwell control.
12	BIAS CURRENT	The internal current which used to drive the external capacitors of the dwell control(pin10 and11)permanent conduction protection (pin 9) and slow recovery time (pin 8) can be set by a resistor(recommended $62K\Omega$) connected between this pin and ground.
13	CURRENT SENSING	Connection for the Coil Current Limitation. The current limitation value is given by: I _{sens} =0.32×(R10+R11)÷(R _S ×R11) RS: sensing resistor
14	DRIVER EMITTER OUTPUT	Current Driver for the External Darlington.
15	OVER VOLTAGE LIMIT	The internal divider R_3/R_2 defines the limitation value given by: V_{OVP} =(22.5/R3+5×10 ⁻³)×R ₂ +22.5
16	DRIVER COLLECTOR INPUT	Through this pin The collector current of the internal driver which drives the external limits darlington is supplied. Then the external resistor R_6 the maximum current supplied to the base of the external darlington.

■ BLOCK DIAGRAM



■ ABSOLUTE MAXIMUM RATING

PARAMETER		SYMBOL	RATINGS	UNIT
D.C. Supply Current			200	mA
Transient Supply Current t _f fall time constant=100ms		l ₃	800	mA
Supply Voltage		V ₃	Internal Limited to Vz ₃	
RPM Voltage		V ₆	28	V
D.C. Driver Collector Current			300	mA
Pulse (t ≤ 3ms)		I ₁₆	600	mA
Driver Collector Voltage		V ₁₆	28	V
Auxiliary Zener Current		l ₇	40	mA
D.C. Overvoltage Zener Pulse t _{fall} =300µs			15	mA
Current	t _{rep} Repetition Time≥3ms	I ₁₅	35	mA
Reverse Battery Voltage if Application Circuit		V_R	-16	V
Power Dissipation T _C =90°C		P_D	1.2	W
Junction Temperature		TJ	-55~150	°C
Storage Temperature		T _{STG}	-55~150	°C

Note: Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

■ THERMAL DATA

PARAMETER	SYMBOL	RATINGS	UNIT
Junction to Ambient (Note)	θ_{JA}	50 (MAX)	°C/W

Note: Thermal resistance junction Ambient with the device soldered on the middle of an Ambient supporting substrate measuring 15x20; 0.65mm thickness.

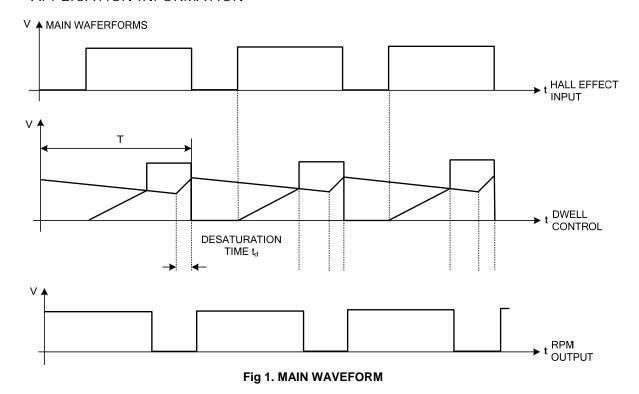
■ ELECTRICAL CHARACTERISTICS (V_S=14.4V, -40 °C<T_J<125°C, unless otherwise specified)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Min Operating Voltage	V_3		3.5			V
Supply Current	I ₃	V ₃ =6V	5	18	25	mA
Supply Current		V ₃ =4V	7		13	mA
Voltage Supply	V_S				28	V
Supply Clamping Zener Voltage	V_{Z3}	I _{Z3} =70mA	6.8	7.5	8.2	V
Input Voltage	V_5	Low Status			0.6	V
input voltage	V 5	High Status	2.5			V
Input Current	I_5	V ₅ =LOW	-400		-50	μA
Darlington Driver Saturation Current	V _{16–14}	I ₁₄ =50mA			0.5	V
Danington Driver Saturation Current	V 16–14	I ₁₄ =180mA			0.9	V
Current Limit Sensing Voltage	V_{SENSE}	V _S =6~16V	260	320	370	mV
C _W Charge Current	I _{11C}	V _S =5.3~16V,V ₁₁ =0.5V,	-11.0	-9.3	-7.8	μA
Cw Charge Current	1110	T=10~33ms	-11.0		-7.0	μΛ
C _W Charge Current	I _{11D}	V _S =5.3~16V, V ₁₁ =0.5V,	0.5	0.7	1.0	μA
Ow Charge Current		T=10~33ms	0.5			μ/ τ
C _W Charge Discharge ratio	I _{11C} /I _{11D}	V _S = 5.3~16V, V ₁₁ =0.5V,	7.8		22.0	
		T=10~33ms (Note 1)	7.0			
Percentage of Output Current						
Determining the Slow Recovery	I _{SRC} /I _{SENSE}		90	94	98.5	%
Control Start (Note 2)						
Duration of Altered Small Control	T_{SRC}	C_{SRC} =1 μ F, R ₇ =62 $K\Omega$		0.8		s
Ratio after SRC Function Start			40	00.5	00	
External Darlington over V Prot	V_{Z15}	I ₁₅ =5mA	19	22.5	26	V
Zener Voltage		I ₁₅ =2mA	18	21.5	25	
Permanent Conduction Time	T _P	V_5 =High, C_P =1μF, R_7 =62K Ω	0.4	1.1	1.8	S
RPM Output Saturation Voltage	V _{6SAT}	I ₆ =18.5mA			0.5	V
		I ₆ =25mA			0.8	V
RPM Output Leakage Current	I _{6 LEAK}	V _S =20V	4-		50	μA
Auxiliary Zener Voltage	V_{Z7}	I ₇ =20mA	19		27	V
Reference Voltage	V ₁₂		1.20	1.25	1.30	V

Notes: 1. td/t desaturation ratio is given by: $td/T=1/[1+I_{11C}/I_{11D}]$

^{2.} I_{SENSE}=I_{coil} when the external Darlington is in the active region.

■ APPLICATION INFORMATION



TYPICAL APPLICATION CIRCUIT

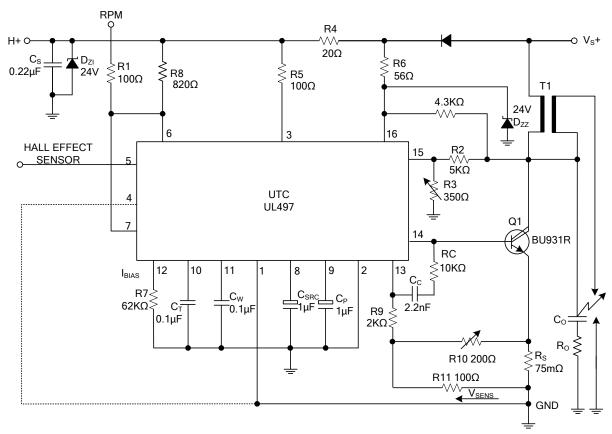


Fig 2. APPLICATION CIRCUIT

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