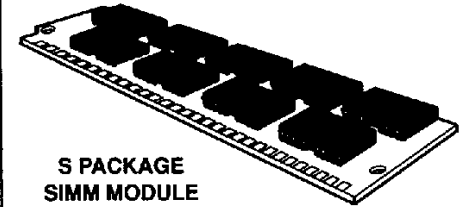


4Mx9 Bit Dynamic Random Access Memory Module

The MCM94000S is a 36M, dynamic random access memory (DRAM) module organized as 4,194,304 × 9 bits. The module is a 30-lead single-in-line memory module (SIMM) consisting of nine MCM54100A DRAMs housed in a 20/26 J-lead small outline packages (SOJ) mounted on a substrate along with a 0.22 μF (min) decoupling capacitor mounted under each DRAM. The MCM54100A is a CMOS high speed, dynamic random access memory organized as 4,194,304 one-bit words and fabricated with CMOS silicon-gate process technology.

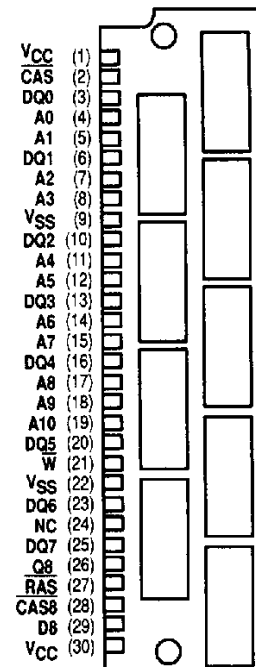
- Three-State Data Output
- Early-Write Common I/O Capability
- Fast Page Mode Capability
- TTL-Compatible Inputs and Outputs
- $\overline{\text{RAS}}$ Only Refresh
- $\overline{\text{CAS}}$ Before $\overline{\text{RAS}}$ Refresh
- Hidden Refresh
- 1024 Cycle Refresh:
 - MCM94000 = 16 ms
 - MCM9L4000 = 128 ms
- Consists of Nine 4M × 1 DRAMs and Nine 0.22 μF (Min) Decoupling Capacitors
- Unlatched Data Out at Cycle End Allows Two Dimensional Chip Selection
- Fast Access Time (t_{RAC})
 - MCM94000S-80 = 80 ns (Max)
 - MCM94000S-10 = 100 ns (Max)
- Low Active Power Dissipation:
 - MCM94000S-80 and MCM9L4000S-80 = 4.95 W (Max)
 - MCM94000S-10 and MCM9L4000S-10 = 4.21 W (Max)
- Low Standby Power Dissipation:
 - TTL Levels = 99 mW (Max)
 - CMOS Levels (MCM94000) = 50 mW (Max)
 - (MCM9L4000) = 20 mW (Max)
- $\overline{\text{CAS}}$ Control for Eight Common I/O Lines
- $\overline{\text{CAS}}$ Control for Separate I/O Pair
- Available in Edge Connector (MCM94000S) or Low Height Pin Connector (MCM94000LH)

MCM94000 MCM9L4000



S PACKAGE
SIMM MODULE
CASE 839B

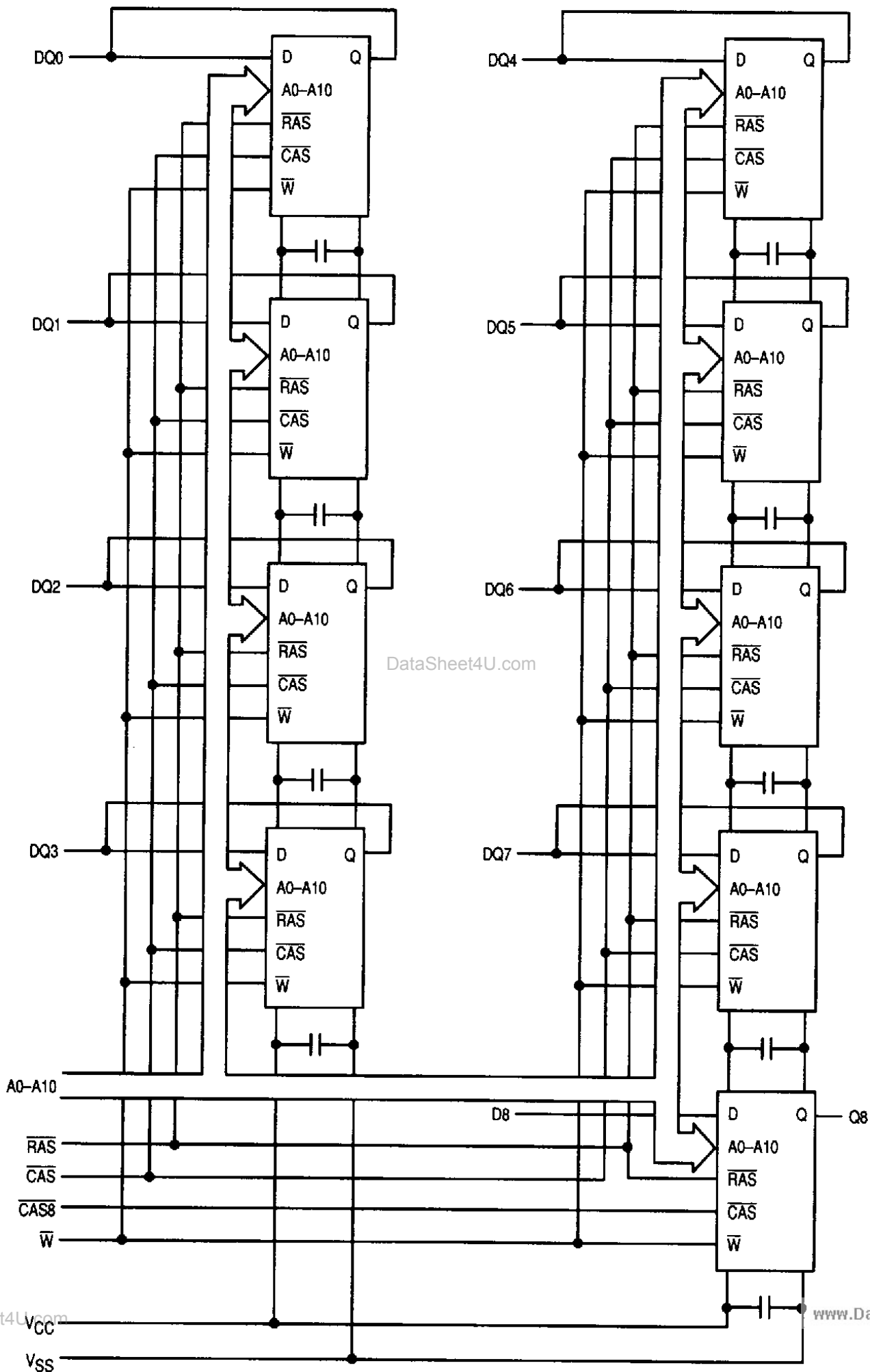
30-PIN SINGLE IN-LINE PACKAGE (TOP VIEW, MCM94000S/9L4000S)



PIN NAMES

A0-A10	Address Inputs
DQ0-DQ7	Data Input/Output
D8	Data Input
Q8	Data Output
$\overline{\text{CAS}}$	Column Address Strobe
$\overline{\text{RAS}}$	Row Address Strobe
$\overline{\text{W}}$	Read/Write Input
CAS8	Column Address Strobe
VCC	Power (+5 V)
VSS	Ground
NC	No Connection

FUNCTIONAL BLOCK DIAGRAM



et4U.com

DataSheet4U.com

DataShe

DataSheet4U.com

www.DataSheet4U.com

DataSheet4U.com

DataSheet4U.com

ABSOLUTE MAXIMUM RATING (See Note)

Rating	Symbol	Value	Unit
Power Supply Voltage	V_{CC}	-1 to +7	V
Voltage Relative to V_{SS} for Any Pin Except V_{CC}	V_{in}, V_{out}	-1 to +7	V
Data Out Current per DQ Pin	I_{out}	50	mA
Power Dissipation	P_D	5.4	W
Operating Temperature Range	T_A	0 to +70	°C
Storage Temperature Range	T_{stg}	-25 to +125	°C

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high-impedance circuit.

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPERATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

DC OPERATING CONDITIONS AND CHARACTERISTICS

($V_{CC} = 5.0 \text{ V} \pm 10\%$, $T_A = 0 \text{ to } 70^\circ\text{C}$, Unless Otherwise Noted)

RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Min	Typ	Max	Unit	Notes
Supply Voltage (Operating Voltage Range)	V_{CC}	4.5	5.0	5.5	V	1
	V_{SS}	0	0	0		
Logic High Voltage, All Inputs	V_{IH}	2.4	—	6.5	V	1
Logic Low Voltage, All Inputs	V_{IL}	-1.0	—	0.8	V	1

DC CHARACTERISTICS

Characteristic	Symbol	Min	Max	Unit	Notes
V_{CC} Power Supply Current MCM94000-80, $t_{RC} = 150 \text{ ns}$ MCM94000-10, $t_{RC} = 180 \text{ ns}$	I_{CC1}	—	900 765	mA	2
V_{CC} Power Supply Current (Standby) ($\overline{RAS} = \overline{CAS} = V_{IH}$)	I_{CC2}	—	18	mA	
V_{CC} Power Supply Current During \overline{RAS} Only Refresh Cycles MCM94000-80, $t_{RC} = 150 \text{ ns}$ MCM94000-10, $t_{RC} = 180 \text{ ns}$	I_{CC3}	—	900 765	mA	2
V_{CC} Power Supply Current During Fast Page Mode Cycle MCM94000-80, $t_{PC} = 45 \text{ ns}$ MCM94000-10, $t_{PC} = 55 \text{ ns}$	I_{CC4}	—	540 450	mA	2
V_{CC} Power Supply Current (Standby) ($\overline{RAS} = \overline{CAS} = V_{CC} - 0.2 \text{ V}$) MCM94000 MCM9L4000	I_{CC5}	—	9 3.6	mA	
V_{CC} Power Supply Current During \overline{CAS} Before \overline{RAS} Refresh Cycle MCM94000-80, $t_{RC} = 150 \text{ ns}$ MCM94000-10, $t_{RC} = 180 \text{ ns}$	I_{CC6}	—	900 765	mA	2
V_{CC} Power Supply Current, Battery Backup Mode—MCM9L4000 Only ($t_{RC} = 125 \mu\text{s}$; $\overline{CAS} = \overline{CAS}$ Before \overline{RAS} Cycling or 0.2 V; $\overline{W} = V_{CC} - 0.2 \text{ V}$; $DQ = V_{CC} - 0.2 \text{ V}$, 0.2 V or Open; $A0-A10 = V_{CC} - 0.2 \text{ V}$ or 0.2 V) $t_{RAS} = \text{Min to } 1 \mu\text{s}$)	I_{CC7}	—	4.5	mA	
Input Leakage Current ($V_{SS} \leq V_{in} \leq V_{CC}$)	$I_{lkg(I)}$	-90	90	μA	
Output Leakage Current (\overline{CAS} at Logic 1, $V_{SS} \leq V_{out} \leq V_{CC}$)	$I_{lkg(O)}$	-20	20	μA	
Output High Voltage ($I_{OH} = -5 \text{ mA}$)	V_{OH}	2.4	—	V	
Output Low Voltage ($I_{OL} = 4.2 \text{ mA}$)	V_{OL}	—	0.4	V	

CAPACITANCE ($f = 1.0 \text{ MHz}$, $T_A = 25^\circ\text{C}$, $V_{CC} = 5 \text{ V}$, Periodically Sampled Rather Than 100% Tested)

Parameter	Symbol	Max	Unit	Notes
Input Capacitance	$A0-A10, \overline{W}, \overline{CAS}, \overline{RAS}$ $D8, \overline{CAS8}$	60	pF	3
		7	pF	3
Input/Output Capacitance	$DQ0-DQ7$	15	pF	3
Output Capacitance ($\overline{CAS} = V_{IH}$ to Disable Output)	$Q8$	10	pF	3

NOTES:

- All voltages referenced to V_{SS} .
- Current is a function of cycle rate and output loading; maximum current is measured at the fastest cycle rate with the output open.
- Capacitance measured with a Boonton Meter or effective capacitance calculated from the equation: $C = I\Delta t/\Delta V$.

AC OPERATING CONDITIONS AND CHARACTERISTICS(V_{CC} = 5.0 V ±10%, T_A = 0 to 70°C, Unless Otherwise Noted)**READ AND WRITE CYCLES** (See Notes 1, 2, 3, and 4)

Parameter	Symbol		MCM94000-80		MCM94000-10		Unit	Notes
	Standard	Alternate	Min	Max	Min	Max		
Random Read or Write Cycle Time	t _{RELREL}	t _{RC}	150	—	180	—	ns	5
Page Mode Cycle Time	t _{CELCEL}	t _{PC}	50	—	60	—	ns	
Access Time from $\overline{\text{RAS}}$	t _{RELQV}	t _{RAC}	—	80	—	100	ns	6, 7
Access Time from $\overline{\text{CAS}}$	t _{CELQV}	t _{CAC}	—	20	—	25	ns	6, 8
Access Time from Column Address	t _{AVQV}	t _{AA}	—	40	—	50	ns	6, 9
Access Time from Precharge $\overline{\text{CAS}}$	t _{CEHQV}	t _{CPA}	—	45	—	55	ns	6
$\overline{\text{CAS}}$ to Output in Low-Z	t _{CELQX}	t _{CLZ}	0	—	0	—	ns	6
Output Buffer and Turn-Off Delay	t _{CEHQZ}	t _{OFF}	0	20	0	20	ns	10
Transition Time (Rise and Fall)	t _T	t _T	3	50	3	50	ns	
RAS Precharge Time	t _{REHREL}	t _{RP}	60	—	70	—	ns	
RAS Pulse Width	t _{RELREH}	t _{RAS}	80	10,000	100	10,000	ns	
RAS Pulse Width (Fast Page Mode)	t _{RELREH}	t _{RASP}	80	200,000	100	200,000	ns	
RAS Hold Time	t _{CELREH}	t _{RSH}	20	—	25	—	ns	
$\overline{\text{CAS}}$ Hold Time	t _{RELCEH}	t _{CSH}	80	—	100	—	ns	
$\overline{\text{CAS}}$ Pulse Width	t _{CELCEH}	t _{CAS}	20	10,000	25	10,000	ns	
RAS to $\overline{\text{CAS}}$ Delay Time	t _{RELCEL}	t _{RCD}	20	60	25	75	ns	11
RAS to Column Address Delay Time	t _{RELAV}	t _{RAD}	15	40	20	50	ns	12
$\overline{\text{CAS}}$ to RAS Precharge Time	t _{CEHREL}	t _{CRP}	5	—	10	—	ns	
$\overline{\text{CAS}}$ Precharge Time	t _{CEHCEL}	t _{CP}	10	—	10	—	ns	
Row Address Setup Time	t _{AVREL}	t _{ASR}	0	—	0	—	ns	
Row Address Hold Time	t _{RELAX}	t _{RAH}	10	—	15	—	ns	
Column Address Setup Time	t _{AVCEL}	t _{ASC}	0	—	0	—	ns	
Column Address Hold Time	t _{CELAX}	t _{CAH}	15	—	20	—	ns	
Column Address Hold Time Referenced to $\overline{\text{RAS}}$	t _{RELAX}	t _{AR}	60	—	75	—	ns	
Column Address to $\overline{\text{RAS}}$ Lead Time	t _{AVREH}	t _{RAL}	40	—	50	—	ns	

(continued)

NOTES:

1. V_{IH} min and V_{IL} max are reference levels for measuring timing of input signals. Transition times are measured between V_{IH} and V_{IL}.
2. An initial pause of 200 μs is required after power-up followed by 8 RAS cycles before proper device operation is guaranteed.
3. The transition time specification applies for all input signals. In addition to meeting the transition rate specification, all input signals must transition between V_{IH} and V_{IL} (or between V_{IL} and V_{IH}) in a monotonic manner.
4. AC measurements t_T = 5.0 ns.
5. The specification for t_{RC} (min) is used only to indicate cycle time at which proper operation over the full temperature range (0°C ≤ T_A ≤ 70°C) is assured.
6. Measured with a current load equivalent to 2 TTL (−200 μA, +4 mA) loads and 100 pF with the data output trip points set at V_{OH} = 2.0 V and V_{OL} = 0.8 V.
7. Assumes that t_{RCD} ≤ t_{RCD} (max).
8. Assumes that t_{RCD} ≥ t_{RCD} (max).
9. Assumes that t_{RAD} ≥ t_{RAD} (max).
10. t_{OFF} (max) defines the time at which the output achieves the open circuit condition and is not referenced to output voltage levels.
11. Operation within the t_{RCD} (max) limit ensures that t_{RAC} (max) can be met. t_{RCD} (max) is specified as a reference point only; if t_{RCD} is greater than the specified t_{RCD} (max) limit, then access time is controlled exclusively by t_{CAC}.
12. Operation within the t_{RAD} (max) limit ensures that t_{RAC} (max) can be met. t_{RAD} (max) is specified as a reference point only; if t_{RAD} is greater than the specified t_{RAD} (max) limit, then access time is controlled exclusively by t_{AA}.

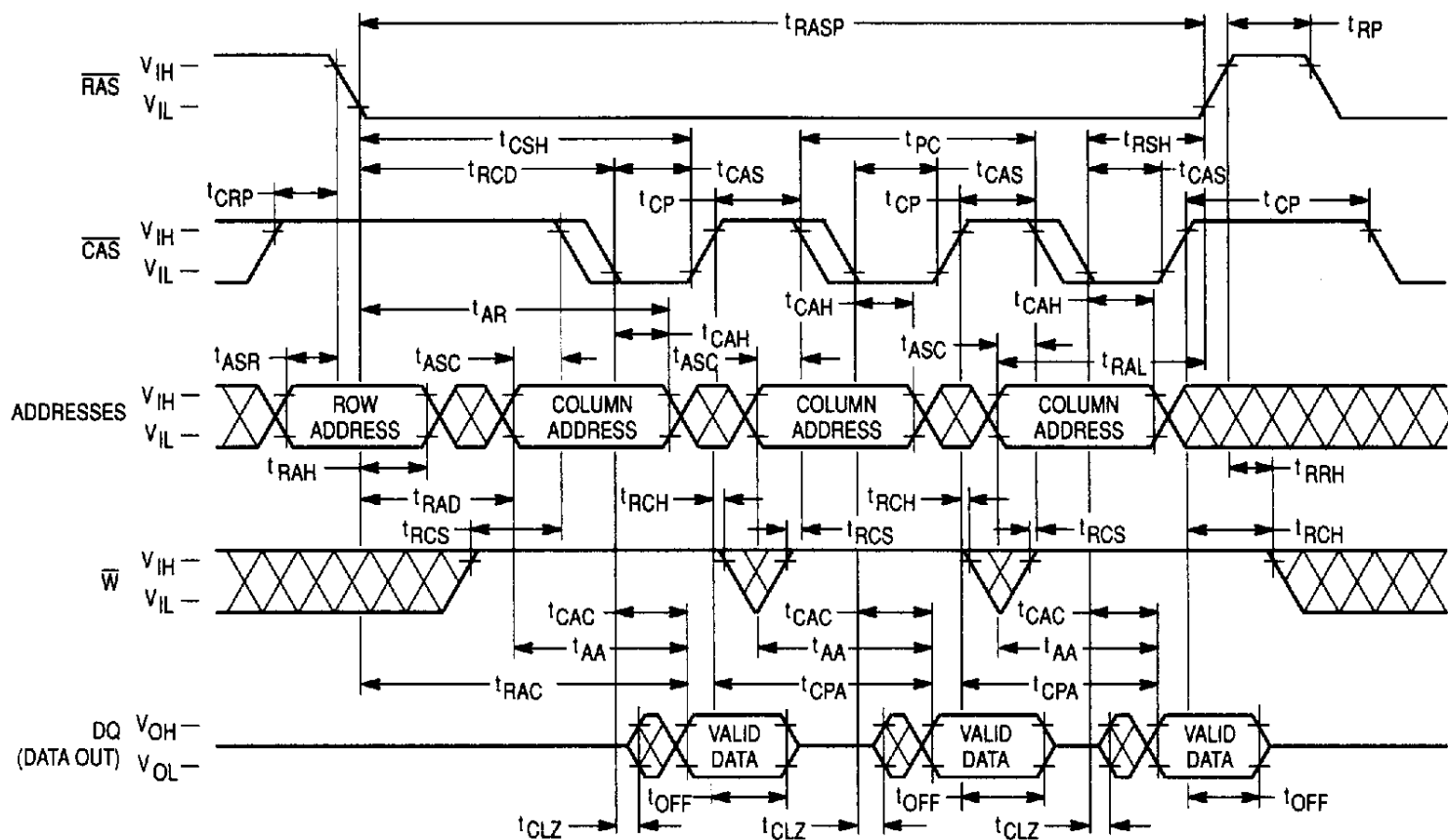
READ AND WRITE CYCLES (Continued)

Parameter	Symbol		MCM94000-80		MCM94000-10		Unit	Notes
	Standard	Alternate	Min	Max	Min	Max		
Read Command Setup Time	t _{WHCEL}	t _{RCS}	0	—	0	—	ns	
Read Command Hold Time Referenced to $\overline{\text{CAS}}$	t _{CEHWX}	t _{RCH}	0	—	0	—	ns	13
Read Command Hold Time Referenced to $\overline{\text{RAS}}$	t _{REHWX}	t _{RRH}	0	—	0	—	ns	13
Write Command Hold Time Referenced to $\overline{\text{CAS}}$	t _{CELWH}	t _{WCH}	15	—	20	—	ns	
Write Command Hold Time Referenced to $\overline{\text{RAS}}$	t _{RELWH}	t _{WCR}	60	—	75	—	ns	
Write Command Pulse Width	t _{WLWH}	t _{WCP}	15	—	20	—	ns	
Write Command to $\overline{\text{RAS}}$ Lead Time	t _{WLREH}	t _{RWL}	20	—	25	—	ns	
Write Command to $\overline{\text{CAS}}$ Lead Time	t _{WLCEH}	t _{CWL}	20	—	25	—	ns	
Data in Setup Time	t _{DVCEL}	t _{DS}	0	—	0	—	ns	14, 15
Data in Hold Time	t _{CELDX}	t _{DH}	15	—	20	—	ns	14, 15
Data in Hold Time Referenced to $\overline{\text{RAS}}$	t _{RELDX}	t _{DHR}	60	—	75	—	ns	
Refresh Period	MCM94000 MCM9L4000	t _{RVRV} t _{RFSH}	— —	16 128	— —	16 128	ms	
Write Command Setup Time	t _{WLCEL}	t _{WCS}	0	—	0	—	ns	15, 16
$\overline{\text{CAS}}$ Setup Time for $\overline{\text{CAS}}$ Before $\overline{\text{RAS}}$ Refresh	t _{RELCEL}	t _{CSR}	5	—	10	—	ns	
$\overline{\text{CAS}}$ Hold Time for $\overline{\text{CAS}}$ Before $\overline{\text{RAS}}$ Refresh	t _{RELCEH}	t _{CHR}	15	—	20	—	ns	
$\overline{\text{CAS}}$ Precharge to $\overline{\text{CAS}}$ Active Time	t _{REHCEL}	t _{RPC}	0	—	0	—	ns	
$\overline{\text{CAS}}$ Precharge Time for $\overline{\text{CAS}}$ Before $\overline{\text{RAS}}$ Counter Test	t _{CEHCEL}	t _{CPT}	40	—	50	—	ns	

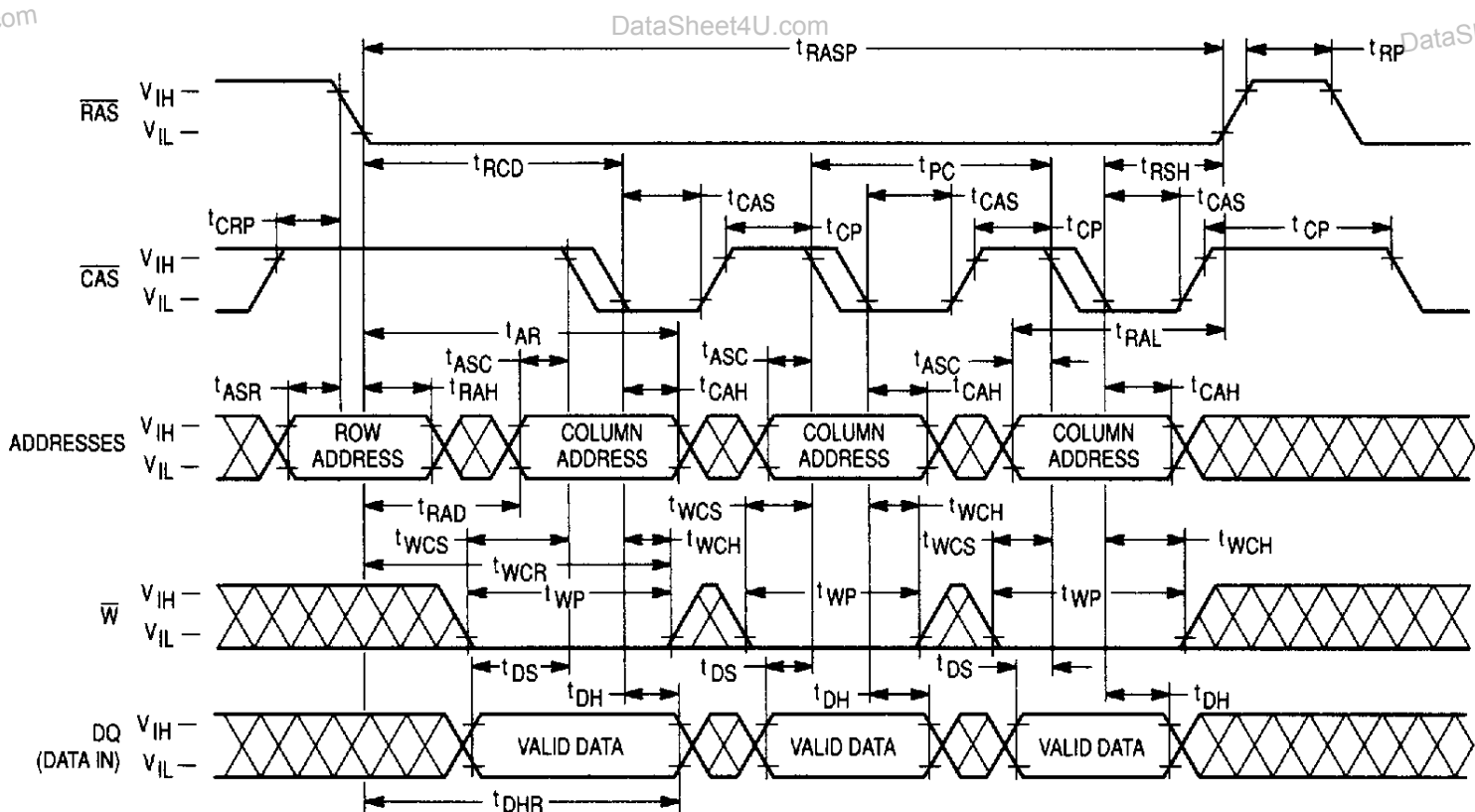
NOTES:

13. Either t_{RRH} or t_{RCH} must be satisfied for a read cycle.
14. These parameters are referenced to $\overline{\text{CAS}}$ leading edge in random write cycles.
15. Early write only (t_{WCS} ≥ t_{WCS} (min)).
16. t_{WCS} is not a restrictive operating parameter. It is included in the data sheet as an electrical characteristic only; if t_{WCS} ≥ t_{WCS} (min), the cycle is an early write cycle and the data out pin will remain open circuit (high impedance) throughout the entire cycle. If this condition is not satisfied, the condition of the data out (at access time) is indeterminate.

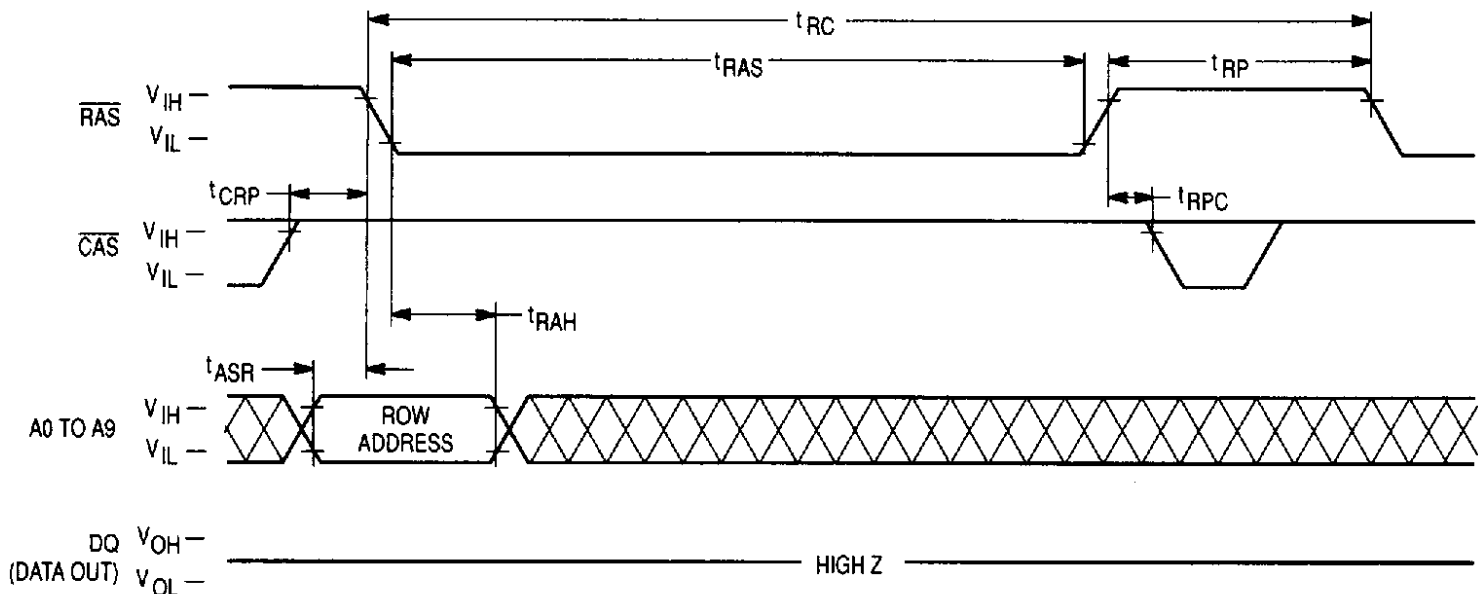
FAST PAGE MODE READ CYCLE



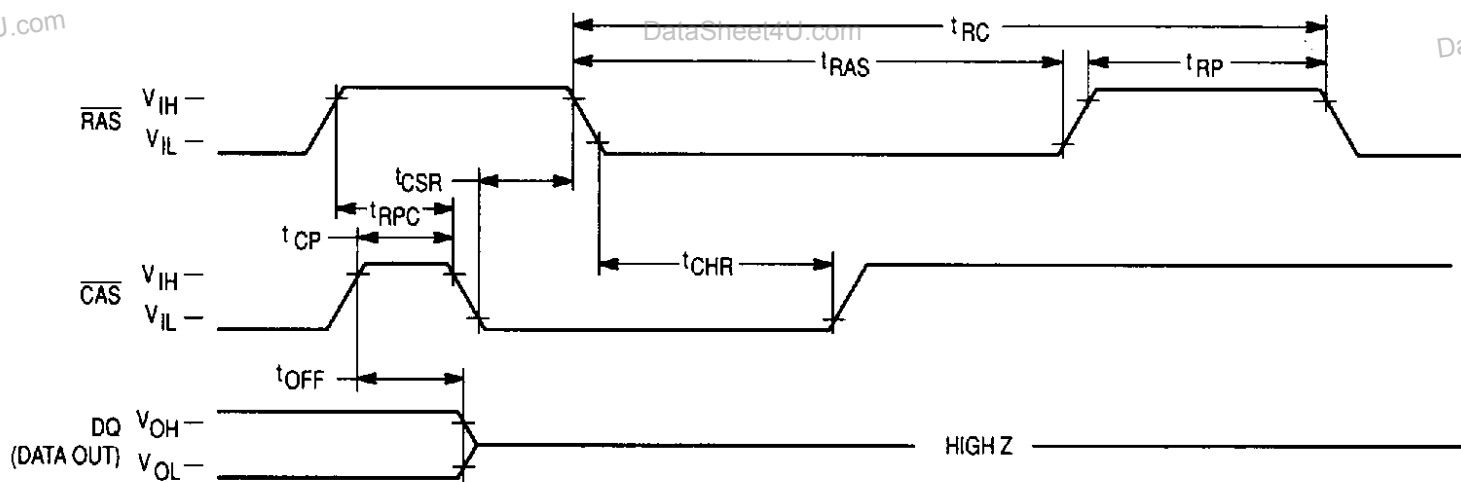
FAST PAGE MODE WRITE CYCLE (EARLY WRITE)



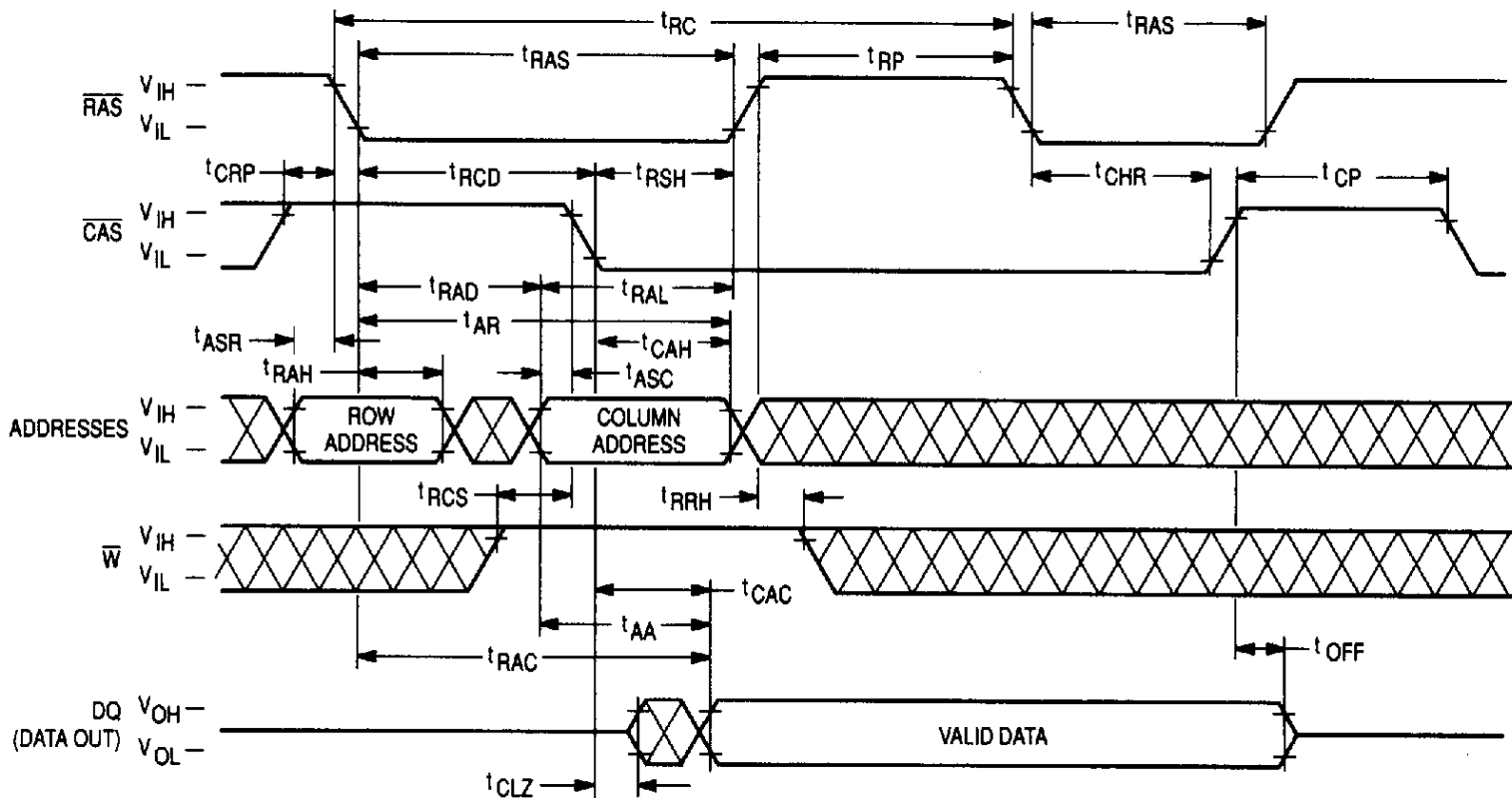
RAS ONLY REFRESH CYCLE
 (\overline{W} and A10 are Don't Care)



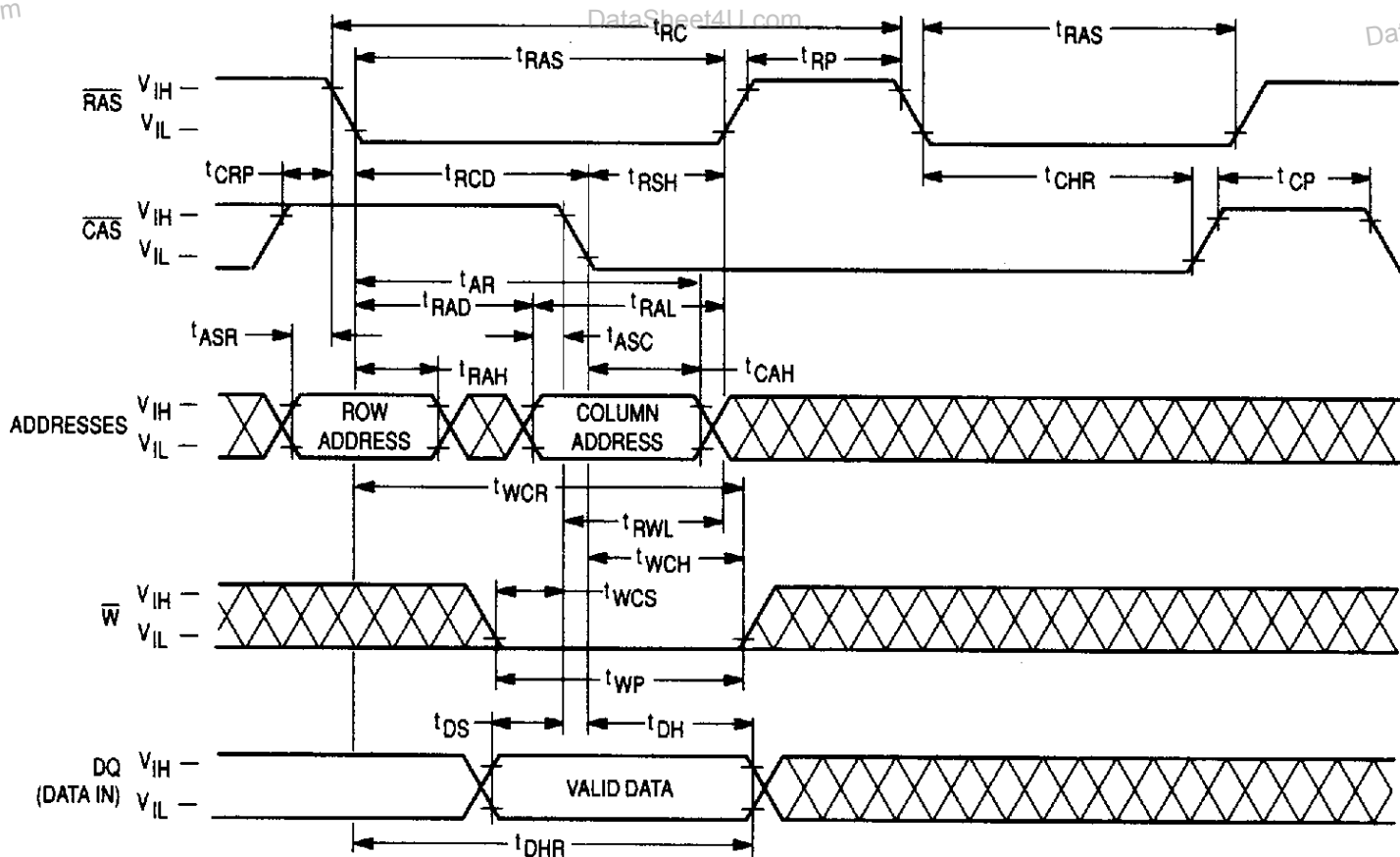
\overline{CAS} BEFORE \overline{RAS} REFRESH CYCLE
 (A0 to A10 are Don't Care)

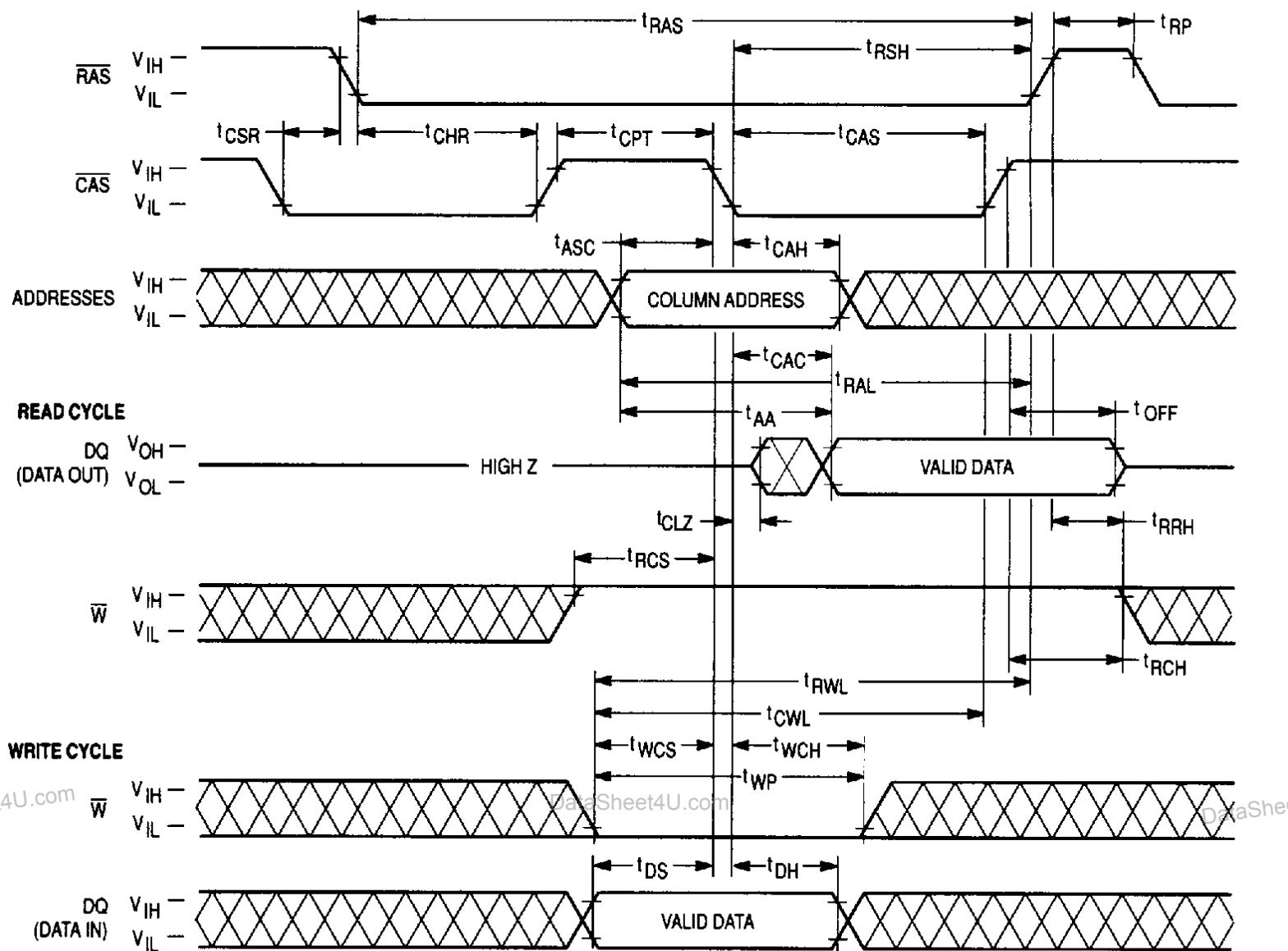


HIDDEN REFRESH CYCLE (READ)



HIDDEN REFRESH CYCLE (WRITE)



CAS BEFORE RAS REFRESH COUNTER TEST CYCLE

DEVICE INITIALIZATION

On power-up an initial pause of 200 microseconds is required for the internal substrate generator to establish the correct bias voltage. This must be followed by a minimum of eight active cycles of the row address strobe (clock) to initialize all dynamic nodes within the RAM. During an extended inactive state (greater than 16 milliseconds with device powered up), a wake up sequence of eight active cycles is necessary to assure proper operation.

ADDRESSING THE RAM

The eleven address pins on the device are time multiplexed at the beginning of a memory cycle by two clocks, row address strobe ($\overline{\text{RAS}}$) and column address strobe ($\overline{\text{CAS}}$), into two separate 11-bit address fields. A total of twenty two address bits, eleven rows and eleven columns, will decode one of the 4,194,304 word locations in the device. $\overline{\text{RAS}}$ active transition is followed by $\overline{\text{CAS}}$ active transition (active = V_{IL} , t_{RCD} minimum) for all read or write cycles. The delay between $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ active transition, referred to as the **multiplex window**, gives a system designer flexibility in setting up the external addresses into the RAM.

The external $\overline{\text{CAS}}$ signal is ignored until an internal $\overline{\text{RAS}}$ signal is available. This "gate" feature on the external $\overline{\text{CAS}}$ clock enables the internal $\overline{\text{CAS}}$ line as soon as the row address hold time (t_{RAH}) specification is met (and defines t_{RCD} minimum). The multiplex window can be used to absorb skew delays in switching the address bus from row to column addresses and in generating the $\overline{\text{CAS}}$ clock.

There are three other variations in addressing the 4M RAM: **$\overline{\text{RAS}}$ only refresh cycle**, **$\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ refresh cycle**, and **page mode**. All three are discussed in separate sections that follow.

READ CYCLE

The DRAM may be read with two different cycles: "normal" random read cycle, and page mode read cycle. The normal read cycle is outlined here, while the page mode cycle is discussed in a separate section.

The normal read cycle begins as described in **ADDRESSING THE RAM**, with the $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ active transitions latching the desired bit location. The write ($\overline{\text{W}}$) input level must be high (V_{IH}), t_{RCS} (minimum) before the $\overline{\text{CAS}}$ active transition, to enable read mode.

Both the $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ clocks trigger a sequence of events which are controlled by several delayed internal clocks. The internal clocks are linked in such a manner that the read access time of the device is independent of the address multiplex window. However, $\overline{\text{CAS}}$ must be active before or at t_{RCD} maximum to guarantee valid data out (DQ) at t_{RAC} (access time from $\overline{\text{RAS}}$ active transition). If the t_{RCD} maximum is exceeded, read access time is determined by the $\overline{\text{CAS}}$ clock active transition (t_{CAC}).

The $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ clocks must remain active for a minimum time of t_{RAS} and t_{CAS} respectively, to complete the read cycle. $\overline{\text{W}}$ must remain high throughout the cycle, and for time t_{RRH} or t_{RCH} after $\overline{\text{RAS}}$ or $\overline{\text{CAS}}$ inactive transition, respectively, to maintain the data at that bit location. Once $\overline{\text{RAS}}$ transitions to inactive, it must remain inactive for a minimum time of t_{RP} to precharge the internal device circuitry for the next active cycle. DQ is valid, but not latched, as long as the $\overline{\text{CAS}}$ clock is

active. When the $\overline{\text{CAS}}$ clock transitions to inactive, the output will switch to High Z (three-state).

WRITE CYCLE

The user can write to the DRAM with two cycles; early write and page mode early write. Early write mode is discussed here, while the page mode write operation is covered in another section.

A write cycle begins as described in **ADDRESSING THE RAM**. Write mode is enabled by the transition of $\overline{\text{W}}$ to active (V_{IL}). Minimum active time t_{RAS} and t_{CAS} , and precharge time t_{RP} apply to write mode, as in the read mode.

An early write cycle is characterized by $\overline{\text{W}}$ active transition at minimum time t_{WCS} before $\overline{\text{CAS}}$ active transition. Data in (DQ) is referenced to $\overline{\text{CAS}}$ in an early write cycle. $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ clocks must stay active for t_{RWL} and t_{CWL} , respectively, after the start of the early write operation to complete the cycle.

PAGE MODE CYCLES

Page mode allows fast successive data operations at all 2048 column locations on a selected row of the dynamic RAM. Read access time in page mode (t_{CAC}) is typically half the regular $\overline{\text{RAS}}$ clock access time, t_{RAC} . Page mode operation consists of keeping $\overline{\text{RAS}}$ active while toggling $\overline{\text{CAS}}$ between V_{IH} and V_{IL} . The row is latched by $\overline{\text{RAS}}$ active transition, while each $\overline{\text{CAS}}$ active transition allows selection of a new-column location on the row.

A page mode cycle is initiated by a normal read or write cycle, as described in prior sections. Once the timing requirements for the first cycle are met, $\overline{\text{CAS}}$ transitions to inactive for minimum of t_{CP} , while $\overline{\text{RAS}}$ remains low (V_{IL}). The second $\overline{\text{CAS}}$ active transition while $\overline{\text{RAS}}$ is low initiates the first page mode cycle (t_{PC}). Either a read or write operation can be performed in a page mode cycle, subject to the same conditions as in normal operation (previously described). These operations can be intermixed in consecutive page mode cycles and performed in any order. The maximum number of consecutive page mode cycles is limited by t_{RASP} . Page mode operation is ended when $\overline{\text{RAS}}$ transitions to inactive, coincident with or following $\overline{\text{CAS}}$ inactive transition.

REFRESH CYCLES

The dynamic RAM design is based on capacitor charge storage for each bit in the array. This charge will tend to degrade with time and temperature. Each byte must be periodically **refreshed** (recharged) to maintain the correct byte state. Bytes in the MCM94000 require refresh every 16 milliseconds, while refresh time for the MCM9L4000 is 128 milliseconds.

This is accomplished by cycling through the 1024 row addresses in sequence within the specified refresh time. All the bytes on a row are refreshed simultaneously when the row is addressed. Distributed refresh implies a row refresh every 15.6 microseconds for the MCM94000, and 124.8 microseconds for the MCM9L4000. Burst refresh, a refresh of all 1024 rows consecutively, must be performed every 16 milliseconds on the MCM94000 and 128 milliseconds on the MCM9L4000.

A normal read or write operation to the RAM will refresh all the bytes (4096) associated with the particular row decoded. Three other methods of refresh, **$\overline{\text{RAS}}$ -only refresh**, **$\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ refresh**, and **hidden refresh** are available on this device for greater system flexibility.

RAS-Only Refresh

RAS-only refresh consists of $\overline{\text{RAS}}$ transition to active, latching the row address to be refreshed, while $\overline{\text{CAS}}$ remains high (V_{IH}) throughout the cycle. An external counter is employed to ensure all rows are refreshed within the specified limit.

CAS Before RAS Refresh

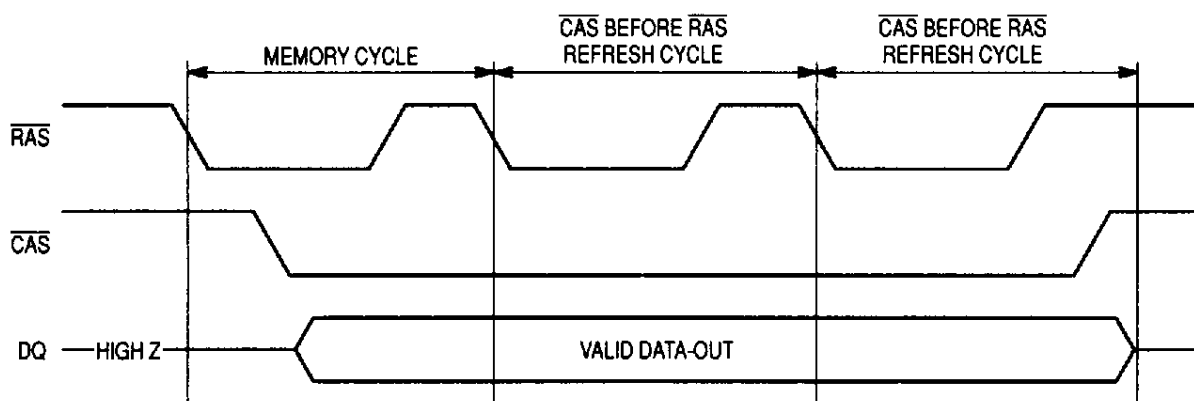
CAS before RAS refresh is enabled by bringing $\overline{\text{CAS}}$ active before $\overline{\text{RAS}}$. This clock order activates an internal refresh counter that generates the row address to be refreshed. External address lines are ignored during the automatic refresh cycle. The output buffer remains at the same state it was in during the previous cycle (hidden refresh).

Hidden Refresh

Hidden refresh allows refresh cycles to occur while main-

taining valid data at the output pin. Holding $\overline{\text{CAS}}$ active the end of a read or write cycle, while $\overline{\text{RAS}}$ cycles inactive for t_{RP} and back to active, starts the hidden refresh. This is essentially the execution of a CAS before RAS refresh from a cycle in progress (see Figure 1).

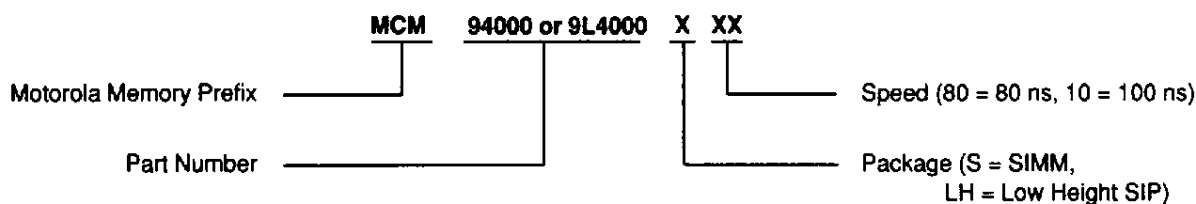
1. Write "0"s into all memory cells (normal write mode).
2. Select a column address, and read "0" out of the cell by performing **CAS before RAS refresh counter test, read cycle**. Repeat this operation 1024 times.
3. Select a column address, and write "1" into the cell by performing **CAS before RAS refresh counter test, write cycle**. Repeat this operation 1024 times.
4. Read "1"s (normal read mode), which were written at step 3.
5. Repeat steps 1 to 4 using complement data.



DataSheet4U.com

Figure 1. Hidden Refresh Cycle

ORDERING INFORMATION (Order by Full Part Number)



Full Part Numbers—	MCM94000S80	MCM94000LH80
	MCM94000S10	MCM94000LH10
	MCM9L4000S80	MCM9L4000LH80
	MCM9L4000S10	MCM9L4000LH10