8-bit Proprietary Microcontrollers

CMOS

F²MC-8FX MB95110H Series

MB95117H/F118HS/F118TS/F118HW/F118TW/ MB95FV100B-103

■ DESCRIPTION

The MB95110H series is general-purpose, single-chip microcontrollers. In addition to a compact instruction set, the microcontrollers contain a variety of peripheral functions.

Note: F2MC is the abbreviation of FUJITSU Flexible Microcontroller.

■ FEATURES

• F2MC-8FX CPU core

Instruction set optimized for controllers

- · Multiplication and division instructions
- 16-bit arithmetic operations
- · Bit test branch instruction
- Bit manipulation instructions etc.
- Clock
 - Main clock
 - Main PLL clock
 - Sub clock (for dual clock product)
 - Sub PLL clock (for dual clock product)
- Timer
 - 8/16-bit compound timer × 2 channels
 - 8/16-bit PPG × 2 channels
 - 16-bit PPG
 - Timebase timer
 - Watch prescaler (for dual clock product)

(Continued)

Be sure to refer to the "Check Sheet" for the latest cautions on development.

"Check Sheet" is seen at the following support page

URL: http://www.fujitsu.com/global/services/microelectronics/product/micom/support/index.html

"Check Sheet" lists the minimal requirement items to be checked to prevent problems beforehand in system development.



(Continued)

- LIN-UART
 - Full duplex double buffer
 - Clock asynchronous or clock synchronous serial data transfer capable
- UART/SIO
 - Full duplex double buffer
 - Clock asynchronous or clock synchronous serial data transfer capable
- I2C*

Built-in wake-up function

- External interrupt
 - Interrupt by edge detection (rising, falling, or both edges can be selected)
 - Can be used to recover from low-power consumption (standby) modes.
- 8/10-bit A/D converter

8-bit or 10-bit resolution can be selected

- Low-power consumption (standby) mode
 - Stop mode
 - Sleep mode
 - Watch mode (for dual clock product)
 - Timebase timer mode
- I/O port
 - The number of maximum ports
 - Single clock product : 39 ports
 - Dual clock product : 37 ports
 - Configuration
 - General-purpose I/O ports (N-ch open drain) : 2 ports
 - General-purpose I/O ports (CMOS) : Single clock product : 37 ports

 Dual clock product : 35 ports
- *: Purchase of Fujitsu I²C components conveys a license under the Philips I²C Patent Rights to use, these components in an I²C system provided that the system conforms to the I²C Standard Specification as defined by Philips.

■ PRODUCT LINEUP

	Part number	MB95117H	MB95F118HS	MB95F118TS	MD05E449HW	MB95F118TW		
Par	rameter	WID95117H WID95F116H		MD93F11613	MB95F118HW	MIDAZELIOLAA		
Тур	pe	MASK ROM product	Flash memory product					
RO	M capacity	48 Kbytes		60 K	bytes			
RAI	M capacity	2 Kbytes		2 Kb	ytes			
Res	set output			Yes				
Option*2	Clock system	Selectable single/dual clock*1	Single	clock	Dual	clock		
ဝီ	Low voltage detection reset	Yes / No	No	Yes	No	Yes		
CPU functions		Number of basic instructions: 136Instruction bit length: 8 bitsInstruction length: 1 to 3 bytesData bit length: 1, 8, and 16 bitsMinimum instruction execution time: 0.1 μs (at machine clock frequency 10 MHz)Interrupt processing time: 0.9 μs (at machine clock frequency 10 MHz)						
	General purpose I/O ports		 Single clock product : 39 ports (N-ch open drain : 2 ports, CMOS : 37 ports) Dual clock product : 37 ports (N-ch open drain : 2 ports, CMOS : 35 ports) 					
	Timebase timer	Interrupt cycle: 0.5 ms, 2.1 ms, 8.2 ms, 32.8 ms (at main oscillation clock 4 MHz)						
	Watchdog timer	Reset generated cycle At main oscillation clock 10 MHz : Min 105 ms At sub oscillation clock 32.768 kHz (for dual clock product) : Min 250 ms						
ions	Wild register	Capable of repla	cing 3 bytes of R	OM data				
Peripheral functions	I ² C	Master/slave sending and receiving Bus error function and arbitration function Detecting transmitting direction function Start condition repeated generation and detection functions Built-in wake-up function						
Δ.	UART/SIO	Data transfer capable in UART/SIO Full duplex double buffer, variable data length (5/6/7/8-bit), built-in baud rate generator Transfer rate: 2400 bps to 1250000 bps (at machine clock 10 MHz) NRZ type transfer format, error detected function LSB-first or MSB-first can be selected. Clock synchronous (SIO) or clock asynchronous (UART) serial data transfer capable						

(Continued)

	Part number	MB95117H	MB95F118HS	MB95F118TS	MB95F118HW	MB95F118TW			
Parameter		MIDSSIILU	MIDAOLIIOUO	MIDARLIGIR	MIDAOLIIOUAA	MIDAOLIIOIAA			
	LIN-UART	Full duplex doub Capable of seria	Dedicated reload timer allowing a wide range of communication speeds to be set. Full duplex double buffer. Capable of serial data transfer synchronous or asynchronous to clock signal. LIN functions available as the LIN master or LIN slave.						
	8/10-bit A/D converter (8 channels)	8-bit or 10-bit re	solution can be s	elected.					
ctions	8/16-bit compound timer (2 channels)	× 1 channel". Built-in timer fun waveform outpu	Built-in timer function, PWC function, PWM function, capture function, and square						
Peripheral functions	16-bit PPG	PWM mode or one-shot mode can be selected. Counter operating clock : 8 selectable clock sources Support for external trigger start							
Peri	8/16-bit PPG (2 channels)	Each channel of the PPG can be used as "8-bit PPG × 2 channels" or "16-bit PPG × 1 channel". Counter operating clock: Eight selectable clock sources							
Watch counter (for dual clock product) Count clock: 4 selectable clock sources (125 ms, 250 m Counter value can be set from 0 to 63. (Capable of counter value can be set from 0 to 63. (Capable of counter value can be set from 0 to 63.)						of counting for 1minute when			
	Watch prescaler (for dual clock product)	4 selectable interval times (125 ms, 250 ms, 500 ms, or 1 s)							
External interrupt (12 channels) Interrupt by edge detection (rising, falling, or both edges can be selected (12 channels) Can be used to recover from standby modes.						lected.)			
Sta	ndby mode	Sleep, stop, wat	ch (for dual clock	product), and til	mebase timer				

The evaluation device of this product is MB95FV100B-103. MCU board is MB2146-303.

Note: Part number of the evaluation device in MB95110H series is MB95FV100B-103. When using it, the MCU board (MB2146-303) is required.

^{*1 :} Specify clock mode when ordering MASK ROM.

^{*2 :} For details of option, refer to "■ MASK OPTION".

■ OSCILLATION STABILIZATION WAIT TIME

The initial value of the main clock oscillation stabilization wait time is fixed to the maximum value. The maximum value is shown as follows.

Oscillation stabilization wait time	Remarks		
(2 ¹⁴ –2) /Fcн	Approx. 4.10 ms (at main oscillation clock 4 MHz)		

■ PACKAGES AND CORRESPONDING PRODUCTS

Part number Package	MB95117H	MB95F118HS MB95F118TS	MB95F118HW MB95F118TW	MB95FV100B-103
FPT-52P-M01	0	0	0	×
BGA-224P-M08	×	×	×	0

○ : Available× : Unavailable

■ DIFFERENCES AMONG PRODUCTS AND NOTES ON SELECTING PRODUCTS

Notes on Using Evaluation Products

The Evaluation product has not only the functions of the MB95110H series but also those of other products to support software development for multiple series and models of the F²MC-8FX family. The I/O addresses for peripheral resources not used by the MB95110H series are therefore access-barred. Read/write access to these access-barred addresses may cause peripheral resources supposed to be unused to operate, resulting in unexpected malfunctions of hardware or software.

Particularly, do not use word access to odd numbered byte address in the prohibited areas (If these access are used, the address may be read or write unexpectedly).

Note that the values read from barred addresses are different between the Evaluation product and the Flash memory or MASK ROM product. Therefore, the data must not be used for software processing.

The Evaluation product do not support the functions of some bits in single-byte registers. Read/write access to these bits does not cause hardware malfunctions. Since the Evaluation, Flash memory, and MASK ROM products are designed to behave completely the same way in terms of hardware and software.

Difference of Memory Spaces

If the amount of memory on the Evaluation product is different from that of the Flash memory or MASK ROM product, carefully check the difference in the amount of memory from the model to be actually used when developing software.

For details of memory space, refer to "■ CPU CORE".

Current Consumption

- The current consumption of Flash memory product is typically greater than for MASK ROM product.
- For details of current consumption, refer to "■ ELECTRICAL CHARACTERISTICS".

Package

For details of information on each package, refer to "■ PACKAGE AND CORRESPONDING PRODUCTS" and "■ PACKAGE DIMENSIONS".

Operating Voltage

The operating voltage are different among the Evaluation, Flash memory, and MASK ROM products.

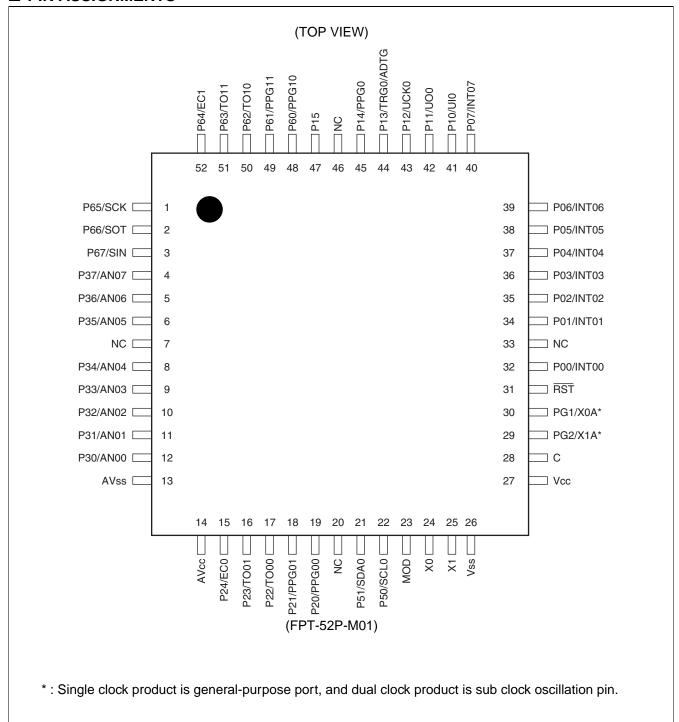
For details of operating voltage, refer to "■ ELECTRICAL CHARACTERISTICS"

• Difference between RST and MOD Pins

The input type of RST and MOD pins is CMOS inputs on the Flash memory product.

The \overline{RST} and MOD pins are hysteresis inputs on the MASK ROM product. A pull-down resistor is provided for the MOD pin of the MASK ROM product.

■ PIN ASSIGNMENTS



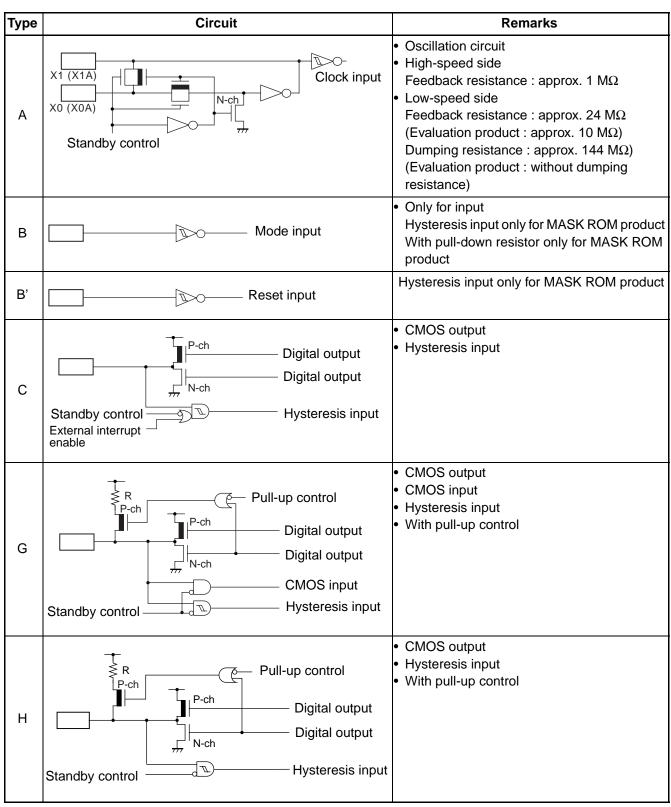
■ PIN DESCRIPTION

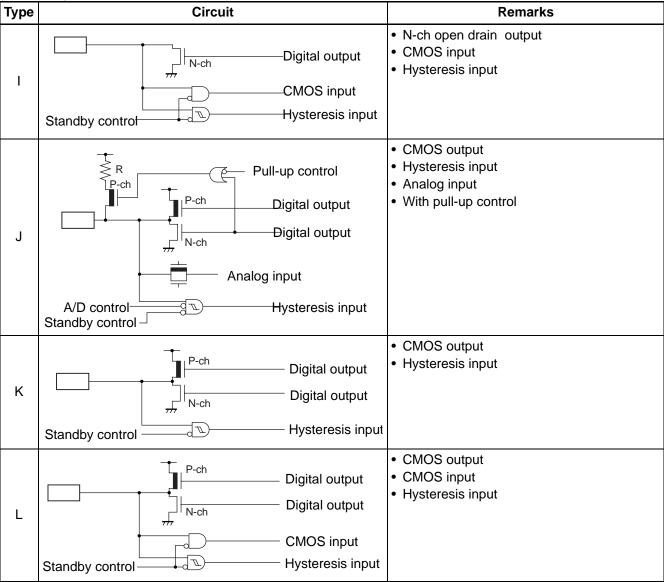
Pin no.	Pin name	I/O Circuit type*	Function	
1	P65/SCK	К	General-purpose I/O port. The pin is shared with LIN-UART clock I/O.	
2	P66/SOT		General-purpose I/O port. The pin is shared with LIN-UART data output.	
3	P67/SIN	L	General-purpose I/O port. The pin is shared with LIN-UART data input.	
4	P37/AN07			
5	P36/AN06			
6	P35/AN05			
8	P34/AN04	J	General-purpose I/O port.	
9	P33/AN03		The pins are shared with A/D converter analog input.	
10	P32/AN02			
11	P31/AN01			
12	P30/AN00			
13	AVss	_	A/D converter power supply pin (GND)	
14	AVcc	_	A/D converter power supply pin	
15	P24/EC0		General-purpose I/O port. The pin is shared with 8/16-bit compound timer ch.0 clock input.	
16	P23/TO01	- Н	Н	General-purpose I/O port.
17	P22/TO00			1 H
18	P21/PPG01		General-purpose I/O port.	
19	P20/PPG00		The pins are shared with 8/16-bit PPG ch.0 output.	
21	P51/SDA0	ı	General-purpose I/O port. The pin is shared with I ² C ch.0 data I/O.	
22	P50/SCL0	'	General-purpose I/O port. The pin is shared with I ² C ch.0 clock I/O.	
23	MOD	В	Operating mode designation pin	
24	X0	Α	Main clock oscillation input pin	
25	X1	_ ^	Main clock oscillation I/O pin	
26	Vss	_	Power supply pin (GND)	
27	Vcc	_	Power supply pin	
28	С	_	Capacitor connection pin	
29	PG2/X1A	H/A	Single clock product is general-purpose port (PG2). Dual clock product is sub clock I/O oscillation pin (32 kHz).	
30	PG1/X0A	11/7	Single clock product is general-purpose port (PG1). Dual clock product is sub clock input oscillation pin (32 kHz).	
31	RST	B'	Reset pin	

Pin no.	Pin name	I/O Circuit type*	Function	
32	P00/INT00			
34	P01/INT01			
35	P02/INT02			
36	P03/INT03	С	General-purpose I/O port.	
37	P04/INT04		The pins are shared with external interrupt input. Large current port.	
38	P05/INT05			
39	P06/INT06			
40	P07/INT07			
41	P10/UI0	G	General-purpose I/O port. The pin is shared with UART/SIO ch.0 data input.	
42	P11/UO0		General-purpose I/O port. The pin is shared with UART/SIO ch.0 data output.	
43	P12/UCK0		General-purpose I/O port. The pin is shared with UART/SIO ch.0 clock I/O.	
44	P13/TRG0/ ADTG	н	General-purpose I/O port. The pin is shared with 16-bit PPG ch.0 trigger input (TRG0) and A/D trigger input (ADTG).	
45	P14/PPG0		General-purpose I/O port. The pin is shared with 16-bit PPG ch.0 output.	
47	P15		General-purpose I/O port.	
48	P60/PPG10		General-purpose I/O port.	
49	P61/PPG11		The pins are shared with 8/16-bit PPG ch.1 output.	
50	P62/TO10	K	General-purpose I/O port.	
51	P63/TO11	'`	The pins are shared with 8/16-bit compound timer ch.1 output.	
52	P64/EC1		General-purpose I/O port. The pin is shared with 8/16-bit compound timer ch.1 clock input.	
7, 20, 33, 46	NC	_	Internal connect pin. Be sure this pin is left open.	

^{*:} For the I/O circuit type, refer to "■ I/O CIRCUIT TYPE"

■ I/O CIRCUIT TYPE





■ HANDLING DEVICES

• Preventing Latch-up

Care must be taken to ensure that maximum voltage ratings are not exceeded when they are used.

Latch-up may occur on CMOS ICs if voltage higher than V_{CC} or lower than V_{SS} is applied to input and output pins other than medium- and high-withstand voltage pins or if higher than the rating voltage is applied between V_{CC} pin and V_{SS} pin.

When latch-up occurs, power supply current increases rapidly and might thermally damage elements.

Also, take care to prevent the analog power supply voltage (AVcc) and analog input voltage from exceeding the digital power supply voltage (Vcc) when the analog system power supply is turned on or off.

Stable Supply Voltage

Supply voltage should be stabilized.

A sudden change in power-supply voltage may cause a malfunction even within the guaranteed operating range of the Vcc power-supply voltage.

For stabilization, in principle, keep the variation in Vcc ripple (p-p value) in a commercial frequency range (50/60 Hz) not to exceed 10% of the standard Vcc value and suppress the voltage variation so that the transient variation rate does not exceed 0.1 V/ms during a momentary change such as when the power supply is switched.

Precautions for Use of External Clock

Even when an external clock is used, oscillation stabilization wait time is required for power-on reset, wake-up from sub clock mode or stop mode.

■ PIN CONNECTION

• Treatment of Unused Pin

Leaving unused input pins unconnected can cause abnormal operation or latch-up, leaving to permanent damage. Unused input pins should always be pulled up or down through resistance of at least 2 $k\Omega$. Any unused input/output pins may be set to output mode and left open, or set to input mode and treated the same as unused input pins. If there is unused output pin, make it open.

• Treatment of Power Supply Pins on A/D Converter

Connect to be AVcc = Vcc and AVss = Vss even if the A/D converter is not in use.

Noise riding on the AV $_{\text{CC}}$ pin may cause accuracy degradation. So, connect approx. 0.1 μ F ceramic capacitor as a bypass capacitor between AV $_{\text{CC}}$ and AV $_{\text{SS}}$ pins in the vicinity of this device.

Power Supply Pins

In products with multiple V_{CC} or V_{SS} pins, the pins of the same potential are internally connected in the device to avoid abnormal operations including latch-up. However, you must connect the pins to external power supply and a ground line to lower the electro-magnetic emission level, to prevent abnormal operation of strobe signals caused by the rise in the ground level, and to conform to the total output current rating.

Moreover, connect the current supply source with the Vcc and Vss pins of this device at the low impedance.

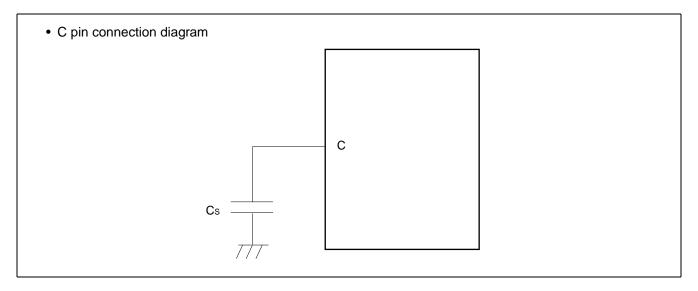
It is also advisable to connect a ceramic bypass capacitor of approximately 0.1 μ F between Vcc and Vss pins near this device.

• Mode Pin (MOD)

Connect the mode pin directly to Vcc or Vss pins.

To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the mode pins to Vcc or Vss pins and to provide a low-impedance connection.

Use a ceramic capacitor or a capacitor with equivalent frequency characteristics. A bypass capacitor of Vcc pin must have a capacitance value higher than Cs. For connection of smoothing capacitor Cs, see the diagram below.



• NC Pins

Any pins marked "NC" (not connected) must be left open.

• Analog Power Supply

Always set the same potential to AVcc and Vcc. When Vcc > AVcc, the current may flow through the AN00 to AN07 pins.

■ PROGRAMMING FLASH MEMORY MICROCONTROLLERS USING PARALLEL PROGRAMMER

• Supported Parallel Programmers and Adapters

Package	Applicable adapter model	Parallel programmers
FPT-52P-M01	under development	AF9708 (Ver 02.35G or more) AF9709/B (Ver 02.35G or more) AF9723+AF9834 (Ver 02.08E or more)

Note: For information on applicable adapter models and parallel programmers, contact the following: Flash Support Group, Inc. TEL: +81-53-428-8380

• Sector Configuration

The individual sectors of Flash memory correspond to addresses used for CPU access and programming by the parallel programmer as follows:

Flash memory	CPU address	Programmer address*	
SA1 (4 Kbytes)	1000н	71000 _H	
<i>5,</i> ()	1FFF _H	71FFF _H	\ <u>~</u>
SA2 (4Kbytes)		72000 _H	Lower bank
- (2FFF _H	72FFFн) We
SA3 (4 Kbytes)	3000н	73000н	1
OAS (4 Royles)	3FFF _H	73FFFн	
CAA (16 Khytos)	4000н	74000н	
SA4 (16 Kbytes)	7FFF _H	77FFFн	
0.45 (4.0 1/1 (+)	8000 _H	78000 _H	
SA5 (16 Kbytes)	BFFF _H	7BFFFн	
0.40 (4.16) (5.5)	С000н	7C000H	
SA6 (4 Kbytes)	CFFFH	7CFFFн	bank
0.07 (4.16)	D000H	7D000H	Upper bank
SA7 (4 Kbytes)	DFFFH	7DFFFн	하
		7E000H	
SA8 (4 Kbytes)	EFFFH	7000.	
	<u>Еггн</u> F000н	<u>7ЕFF</u> н 7F000н	
SA9 (4 Kbytes)			7 }
	<u>FFFF</u> H	<u>7FFFF</u>	

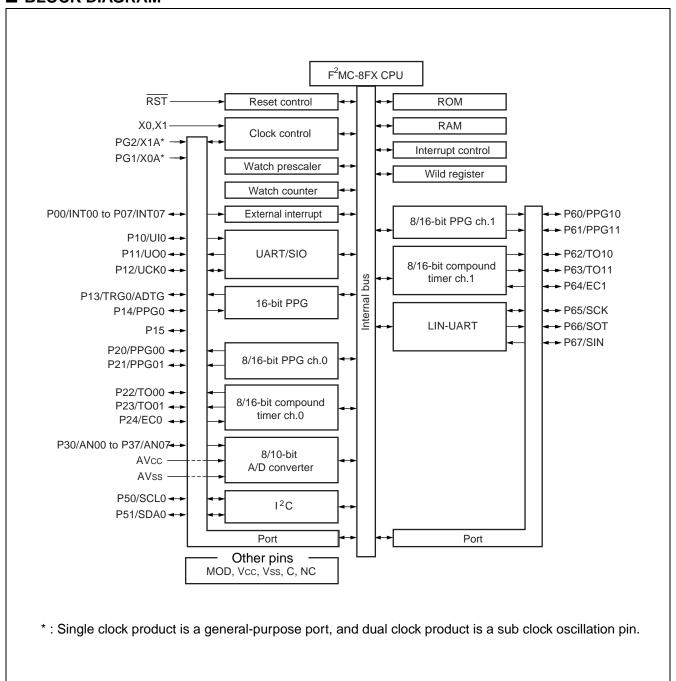
^{*:} Programmer addresses are corresponding to CPU addresses, used when the parallel programmer programs data into Flash memory.

These programmer addresses are used for the parallel programmer to program or erase data in Flash memory.

• Programming Method

- 1) Set the type code of the parallel programmer to "17222".
- 2) Load program data to programmer addresses 71000H to 7FFFFH.
- 3) Programmed by parallel programmer

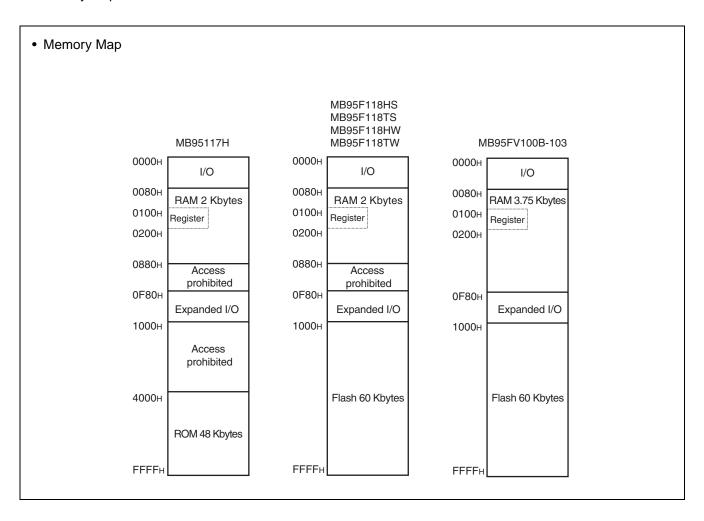
■ BLOCK DIAGRAM



■ CPU CORE

1. Memory space

Memory space of the MB95110H series is 64 Kbytes and consists of I/O area, data area, and program area. The memory space includes special-purpose areas such as the general-purpose registers and vector table. Memory map of the MB95110H series is shown below.



2. Register

The MB95110H series has two types of registers; dedicated registers in the CPU and general-purpose registers in the memory. The dedicated registers are as follows:

Program counter (PC) : A 16-bit register to indicate locations where instructions are stored.

Accumulator (A) : A 16-bit register for temporary storage of arithmetic operations. In the case of

an 8-bit data processing instruction, the lower 1 byte is used.

Temporary accumulator (T) : A 16-bit register which performs arithmetic operations with the accumulator.

In the case of an 8-bit data processing instruction, the lower 1 byte is used.

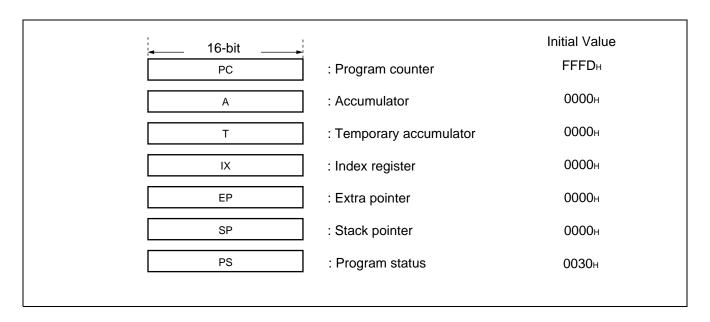
Index register (IX) : A 16-bit register for index modification.

Extra pointer (EP) : A 16-bit pointer to point to a memory address.

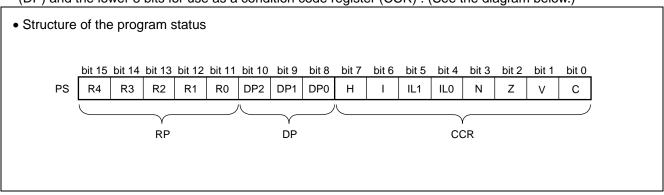
Stack pointer (SP) : A 16-bit register to indicate a stack area.

Program status (PS) : A 16-bit register for storing a register bank pointer, a direct bank pointer, and

a condition code register.



The PS can further be divided into higher 8 bits for use as a register bank pointer (RP) and a direct bank pointer (DP) and the lower 8 bits for use as a condition code register (CCR). (See the diagram below.)



The RP indicates the address of the register bank currently being used. The relationship between the content of RP and the real address conforms to the conversion rule illustrated below:

 Rule for Conversion of Actual Addresses in the General-purpose Register Area RP upper OP code lower "0" "1" R4 R3 R2 R1 R0 b2 b0 ¥ ¥ ¥ ¥ ¥ Generated address A₁₅ A14 A13 A12 A11 A10 Α9 **A8** Α7 A6 Α5 Α4 АЗ A2 Α1 A0

The DP specifies the area for mapping instructions (16 different instructions such as MOV A, dir) using direct addresses to 0080_H to 00FF_H.

Direct bank pointer (DP2 to DP0)	Specified address area	Mapping area
XXX _B (no effect to mapping)	0000н to 007Fн	0000н to 007Fн (without mapping)
000 _B (initial value)		0080н to 00FFн (without mapping)
001в		0100н to 017Fн
010в		0180н to 01FFн
011в	0080н to 00FFн	0200н to 027Fн
100в	- 0000H 10 00FFH	0280н to 02FFн
101в		0300н to 037Fн
110в		0380н to 03FFн
111в		0400н to 047Fн

The CCR consists of the bits indicating arithmetic operation results or transfer data contents and the bits that control CPU operations at interrupt.

H flag : Set to "1" when a carry or a borrow from bit 3 to bit 4 occurs as a result of an arithmetic operation.

Cleared to "0" otherwise. This flag is for decimal adjustment instructions.

I flag : Interrupt is enabled when this flag is set to "1". Interrupt is disabled when this flag is set to "0".

The flag is set to "0" when reset.

IL1, IL0 : Indicates the level of the interrupt currently enabled. Processes an interrupt only if its request level

is higher than the value indicated by these bits.

IL1	IL0	Interrupt level	Priority
0	0	0	High
0	1	1	1 ★
1	0	2	
1	1	3	Low = no interruption

N flag : Set to "1" if the MSB is set to "1" as the result of an arithmetic operation. Cleared to "0" when the bit is set to "0".

Dit is set to 0

Z flag : Set to "1" when an arithmetic operation results in "0". Cleared to "0" otherwise.

V flag : Set to "1" if the complement on 2 overflows as a result of an arithmetic operation. Cleared to "0" otherwise.

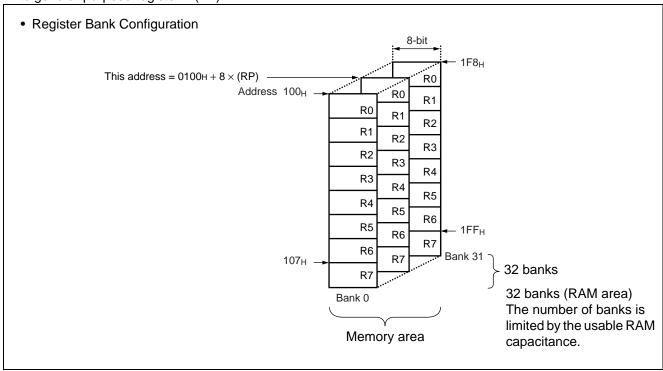
C flag : Set to "1" when a carry or a borrow from bit 7 occurs as a result of an arithmetic operation. Cleared

to "0" otherwise. Set to the shift-out value in the case of a shift instruction.

The following general-purpose registers are provided:

General-purpose registers: 8-bit data storage registers

The general-purpose registers are 8 bits and located in the register banks on the memory. 1-bank contains 8-register. Up to a total of 32 banks can be used on the MB95110H series. The bank currently in use is specified by the register bank pointer (RP), and the lower 3 bits of OP code indicates the general-purpose register 0 (R0) to general-purpose register 7 (R7).



■ I/O MAP

Address	Register abbreviation	Register name	R/W	Initial value
0000н	PDR0	Port 0 data register	R/W	00000000в
0001н	DDR0	Port 0 direction register	R/W	00000000В
0002н	PDR1	Port 1 data register	R/W	00000000В
0003н	DDR1	Port 1 direction register	R/W	0000000В
0004н	_	(Disabled)	_	
0005н	WATR	Oscillation stabilization wait time setting register	R/W	11111111В
0006н	PLLC	PLL control register	R/W	0000000В
0007н	SYCC	System clock control register	R/W	1010Х011в
0008н	STBC	Standby control register	R/W	00000000В
0009н	RSRR	Reset source register	R	XXXXXXXX
000Ан	TBTC	Timebase timer control register	R/W	00000000В
000Вн	WPCR	Watch prescaler control register	R/W	0000000В
000Сн	WDTC	Watchdog timer control register	R/W	00000000В
000Дн	_	(Disabled)	_	
000Ен	PDR2	Port 2 data register	R/W	0000000В
000Fн	DDR2	Port 2 direction register	R/W	00000000В
0010н	PDR3	Port 3 data register	R/W	00000000В
0011н	DDR3	Port 3 direction register	R/W	00000000В
0012н, 0013н	_	(Disabled)	_	_
0014н	PDR5	Port 5 data register	R/W	00000000в
0015н	DDR5	Port 5 direction register	R/W	00000000В
0016н	PDR6	Port 6 data register	R/W	00000000В
0017н	DDR6	Port 6 direction register	R/W	00000000В
0018н to 0029н	_	(Disabled)	_	_
002Ан	PDRG	Port G data register	R/W	0000000В
002Вн	DDRG	Port G direction register	R/W	00000000в
002Сн	_	(Disabled)	<u> </u>	_
002Dн	PUL1	Port 1 pull-up register	R/W	00000000в
002Ен	PUL2	Port 2 pull-up register	R/W	00000000в
002Fн	PUL3	Port 3 pull-up register	R/W	00000000В
0030н to 0034н	_	(Disabled)	_	_

Address	Register abbreviation	Register name		Initial value
0035н	PULG	Port G pull-up register	R/W	00000000В
0036н	T01CR1	8/16-bit compound timer 01 control status register 1 ch.0		00000000В
0037н	T00CR1	8/16-bit compound timer 00 control status register 1 ch.0	R/W	00000000В
0038н	T11CR1	8/16-bit compound timer 11 control status register 1 ch.1	R/W	00000000В
0039н	T10CR1	8/16-bit compound timer 10 control status register 1 ch.1	R/W	00000000в
003Ан	PC01	8/16-bit PPG1 control register ch.0	R/W	00000000В
003Вн	PC00	8/16-bit PPG0 control register ch.0	R/W	00000000В
003Сн	PC11	8/16-bit PPG1 control register ch.1	R/W	00000000В
003Dн	PC10	8/16-bit PPG0 control register ch.1	R/W	0000000В
003Ен to 0041н	_	(Disabled)	_	_
0042н	PCNTH0	16-bit PPG status control register (Upper byte) ch.0	R/W	0000000В
0043н	PCNTL0	16-bit PPG status control register (Lower byte) ch.0	R/W	0000000В
0044н to 0047н	_	(Disabled)	_	_
0048н	EIC00	External interrupt circuit control register ch.0/1	R/W	0000000В
0049н	EIC10	External interrupt circuit control register ch.2/3	R/W	0000000В
004Ан	EIC20	External interrupt circuit control register ch.4/5	R/W	0000000В
004Вн	EIC30	External interrupt circuit control register ch.6/7	R/W	0000000В
004Сн to 004Fн	_	(Disabled)	_	_
0050н	SCR	LIN-UART serial control register	R/W	0000000В
0051н	SMR	LIN-UART serial mode register	R/W	0000000В
0052н	SSR	LIN-UART serial status register	R/W	00001000в
0053н	RDR/TDR	LIN-UART reception/transmission data register	R/W	00000000В
0054н	ESCR	LIN-UART extended status control register	R/W	00000100в
0055н	ECCR	LIN-UART extended communication control register	R/W	000000XXB
0056н	SMC10	UART/SIO serial mode control register 1 ch.0	R/W	0000000В
0057н	SMC20	UART/SIO serial mode control register 2 ch.0	R/W	00100000в
0058н	SSR0	UART/SIO serial status register ch.0	R/W	0000001в
0059н	TDR0	UART/SIO serial output data register ch.0	R/W	00000000в
005Ан	RDR0	UART/SIO serial input data register ch.0	R	00000000В
005Вн to 005Fн	_	(Disabled)	_	_

Address	Register abbreviation	Register name	R/W	Initial value
0060н	IBCR00	I ² C bus control register 0 ch.0	R/W	00000000в
0061н	IBCR10	I ² C bus control register 1 ch.0	R/W	00000000в
0062н	IBSR0	I ² C bus status register ch.0	R	00000000в
0063н	IDDR0	I ² C data register ch.0	R/W	00000000в
0064н	IAAR0	I ² C address register ch.0	R/W	00000000в
0065н	ICCR0	I ² C clock control register ch.0	R/W	00000000в
0066н to 006Вн	_	(Disabled)	_	_
006Сн	ADC1	8/10-bit A/D converter control register 1	R/W	00000000в
006Dн	ADC2	8/10-bit A/D converter control register 2	R/W	00000000в
006Ен	ADDH	8/10-bit A/D converter data register (Upper byte)	R/W	00000000в
006Fн	ADDL	8/10-bit A/D converter data register (Lower byte)	R/W	00000000в
0070н	WCSR	Watch counter status register	R/W	00000000В
0071н	_	(Disabled)	_	_
0072н	FSR	Flash memory status register	R/W	000Х0000в
0073н	SWRE0	Flash memory sector writing control register 0	R/W	00000000в
0074н	SWRE1	Flash memory sector writing control register 1	R/W	00000000в
0075н	_	(Disabled)	_	_
0076н	WREN	Wild register address compare enable register	R/W	00000000В
0077н	WROR	Wild register data test setting register	R/W	0000000В
0078н	_	(Mirror of register bank pointer (RP) and direct bank pointer (DP))	_	_
0079н	ILR0	Interrupt level setting register 0	R/W	111111111
007Ан	ILR1	Interrupt level setting register 1	R/W	111111111
007Вн	ILR2	Interrupt level setting register 2	R/W	11111111В
007Сн	ILR3	Interrupt level setting register 3	R/W	111111111
007Dн	ILR4	Interrupt level setting register 4	R/W	111111111
007Ен	ILR5	Interrupt level setting register 5	R/W	111111111
007Fн	_	(Disabled)	_	_
0F80н	WRARH0	Wild register address setting register (Upper byte) ch.0	R/W	0000000В
0F81н	WRARL0	Wild register address setting register (Lower byte) ch.0	R/W	00000000в
0F82н	WRDR0	Wild register data setting register ch.0	R/W	00000000в
0F83н	WRARH1	Wild register address setting register (Upper byte) ch.1	R/W	00000000в
0F84н	WRARL1	Wild register address setting register (Lower byte) ch.1	R/W	0000000В
0F85н	WRDR1	Wild register data setting register ch.1	R/W	00000000в

Address	Register abbreviation	Register name	R/W	Initial value
0F86н	WRARH2	Wild register address setting register (Upper byte) ch.2	R/W	00000000В
0F87н	WRARL2	Wild register address setting register (Lower byte) ch.2	R/W	00000000В
0F88н	WRDR2	Wild register data setting register ch.2	R/W	00000000в
0F89н to 0F91н	_	(Disabled)	_	_
0F92н	T01CR0	8/16-bit compound timer 01 control status register 0 ch.0	R/W	00000000в
0F93н	T00CR0	8/16-bit compound timer 00 control status register 0 ch.0	R/W	00000000в
0F94н	T01DR	8/16-bit compound timer 01 data register ch.0	R/W	00000000в
0F95н	T00DR	8/16-bit compound timer 00 data register ch.0	R/W	00000000в
0F96н	TMCR0	8/16-bit compound timer 00/01 timer mode control register ch.0	R/W	00000000в
0F97н	T11CR0	8/16-bit compound timer 11 control status register 0 ch.1	R/W	00000000в
0F98н	T10CR0	8/16-bit compound timer 10 control status register 0 ch.1	R/W	0000000В
0F99н	T11DR	8/16-bit compound timer 11 data register ch.1	R/W	00000000в
0F9Ан	T10DR	8/16-bit compound timer 10 data register ch.1	R/W	00000000в
0F9Вн	TMCR1	8/16-bit compound timer 10/11 timer mode control register ch.1	R/W	00000000в
0 F9Сн	PPS01	8/16-bit PPG1 cycle setting buffer register ch.0	R/W	11111111в
0F9Dн	PPS00	8/16-bit PPG0 cycle setting buffer register ch.0	R/W	11111111в
0F9Eн	PDS01	8/16-bit PPG1 duty setting buffer register ch.0	R/W	11111111в
0F9Fн	PDS00	8/16-bit PPG0 duty setting buffer register ch.0	R/W	11111111в
0FА0н	PPS11	8/16-bit PPG1 cycle setting buffer register ch.1	R/W	11111111в
0FA1н	PPS10	8/16-bit PPG0 cycle setting buffer register ch.1	R/W	11111111в
0FA2н	PDS11	8/16-bit PPG1 duty setting buffer register ch.1	R/W	11111111в
0FА3н	PDS10	8/16-bit PPG0 duty setting buffer register ch.1	R/W	11111111в
0FА4н	PPGS	8/16-bit PPG starting register	R/W	00000000в
0FА5н	REVC	8/16-bit PPG output inversion register	R/W	00000000в
0FA6н to 0FA9н	_	(Disabled)	_	_
0ГААн	PDCRH0	16-bit PPG down counter register (Upper byte) ch.0	R	0000000В
0FАВн	PDCRL0	16-bit PPG down counter register (Lower byte) ch.0	R	00000000в
0FAСн	PCSRH0	16-bit PPG cycle setting buffer register (Upper byte) ch.0	R/W	11111111в
0FAD _н	PCSRL0	16-bit PPG cycle setting buffer register (Lower byte) ch.0	R/W	11111111в
0FAEн	PDUTH0	16-bit PPG duty setting buffer register (Upper byte) ch.0	R/W	11111111в
0FAFн	PDUTL0	16-bit PPG duty setting buffer register (Lower byte) ch.0	R/W	11111111в

(Continued)

Address	Register abbreviation	Register name	R/W	Initial value
0FB0н to 0FBBн	_	(Disabled)	_	_
0FВСн	BGR1	LIN-UART baud rate generator register 1	R/W	0000000в
0FBDн	BGR0	LIN-UART baud rate generator register 0	R/W	0000000в
0FВЕн	PSSR0	UART/SIO dedicated baud rate generator prescaler selection register ch.0	R/W	00000000в
0FBFн	BRSR0	UART/SIO dedicated baud rate generator baud rate setting register ch.0	R/W	00000000в
0FC0н to 0FC2н	_	(Disabled)	_	_
0FС3н	AIDRL	A/D input disable register (Lower byte)	R/W	0000000в
0FC4н to 0FE2н	_	(Disabled)	_	_
0FE3н	WCDR	Watch counter data register	R/W	00111111в
0FE4н to 0FEDн	_	(Disabled)	_	_
0FEEн	ILSR	Input level select register	R/W	0000000в
0FEFн	WICR	Interrupt pin control register	R/W	01000000в
0FF0н to 0FFFн	_	(Disabled)	_	_

• R/W access symbols

R/W : Readable/Writable

R : Read only W : Write only

• Initial value symbols

0 : The initial value of this bit is "0".1 : The initial value of this bit is "1".

X : The initial value of this bit is undefined.

Note: Do not write to the "(Disabled)". Reading the "(Disabled)" returns an undefined value.

■ INTERRUPT SOURCE TABLE

	Interrupt	Vector tab	le address	Bit name of	Same level
Interrupt source	request number	Upper	Lower	interrupt level setting register	priority order (atsimultaneous occurrence)
External interrupt ch.0	IRQ0	FFFA _H	FFFB⊦	L00 [1 : 0]	High
External interrupt ch.4	INQU	FFFAH	ГГГОН	L00 [1 . 0]	A
External interrupt ch.1	IRQ1	FFF8 _H	FFF9 _H	L01 [1 : 0]	
External interrupt ch.5	INQI	ГГГОН	ГГГЭН	LOT [T.O]	
External interrupt ch.2	IRQ2	FFF6 _H	FFF7 _H	L02 [1 : 0]	
External interrupt ch.6	IRQZ	ГГГОН	FFF/H	L02 [1 . 0]	
External interrupt ch.3	IRQ3	FFF4 _H	FFF5 _H	1.02 [4 - 0]	
External interrupt ch.7	IRQS		ГГГЭН	L03 [1 : 0]	
UART/SIO ch.0	IRQ4	FFF2 _H	FFF3 _H	L04 [1 : 0]	
8/16-bit compound timer ch.0 (Lower)	IRQ5	FFF0 _H	FFF1 _H	L05 [1 : 0]	
8/16-bit compound timer ch.0 (Upper)	IRQ6	FFEEH	FFEFH	L06 [1 : 0]	
LIN-UART (reception)	IRQ7	FFECH	FFEDH	L07 [1:0]	
LIN-UART (transmission)	IRQ8	FFEAH	FFEBH	L08 [1 : 0]	
8/16-bit PPG ch.1 (Lower)	IRQ9	FFE8 _H	FFE9 _H	L09 [1 : 0]	
8/16-bit PPG ch.1 (Upper)	IRQ10	FFE6 _H	FFE7 _H	L10 [1 : 0]	
(Unused)	IRQ11	FFE4 _H	FFE5 _H	L11 [1 : 0]	
8/16-bit PPG ch.0 (Upper)	IRQ12	FFE2 _H	FFE3 _H	L12 [1 : 0]	
8/16-bit PPG ch.0 (Lower)	IRQ13	FFE0 _H	FFE1 _H	L13 [1 : 0]	
8/16-bit compound timer ch.1 (Upper)	IRQ14	FFDEH	FFDF _H	L14 [1 : 0]	
16-bit PPG ch.0	IRQ15	FFDCH	FFDDH	L15 [1 : 0]	
I ² C ch.0	IRQ16	FFDA _H	FFDB⊦	L16 [1 : 0]	
(Unused)	IRQ17	FFD8 _H	FFD9⊦	L17 [1:0]	
8/10-bit A/D converter	IRQ18	FFD6 _H	FFD7 _H	L18 [1 : 0]	
Timebase timer	IRQ19	FFD4 _H	FFD5 _H	L19 [1 : 0]	
Watch timer/counter	IRQ20	FFD2 _H	FFD3 _H	L20 [1 : 0]	
(Unused)	IRQ21	FFD0 _H	FFD1 _H	L21 [1 : 0]	
8/16-bit compound timer ch.1 (Lower)	IRQ22	FFCEH	FFCFH	L22 [1 : 0]	▼
Flash memory	IRQ23	FFCCH	FFCDH	L23 [1 : 0]	Low

■ ELECTRICAL CHARACTERISTICS

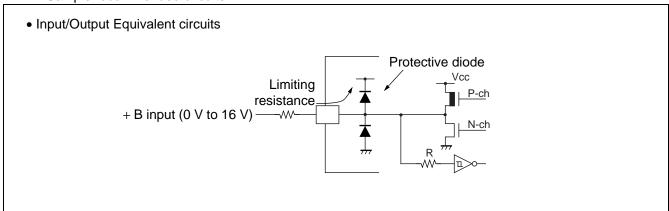
1. Absolute Maximum Ratings

Parameter	Symbol	Rat	ting	Unit	Remarks
Parameter	Symbol	Min	Max	Unit	Remarks
Power supply voltage*1	Vcc AVcc	Vss - 0.3	Vss + 6.0	V	*2
Input voltage*1	Vı	Vss - 0.3	Vss + 6.0	V	*3
Output voltage*1	Vo	Vss - 0.3	Vss + 6.0	V	*3
Maximum clamp current	CLAMP	- 2.0	+ 2.0	mA	Applicable to pins*4
Total maximum clamp current	$\Sigma I_CLAMP $	_	20	mA	Applicable to pins*4
"L" level maximum	lol1		15	m /	Other than P00 to P07
output current	l _{OL2}	_	15	mA	P00 to P07
"L" level average	lolav1		4	mA	Other than P00 to P07 Average output current = operating current × operating ratio (1 pin)
current	lolav2		12	TIIA	P00 to P07 Average output current = operating current × operating ratio (1 pin)
"L" level total maximum output current	Σ loL	_	100	mA	
"L" level total average output current	Σ lolav	_	50	mA	Total average output current = operating current × operating ratio (Total of pins)
"H" level maximum	І он1		– 15	Л	Other than P00 to P07
output current	10н2	<u> </u>	– 15	mA	P00 to P07
"H" level average	Іонаv1		- 4	mA	Other than P00 to P07 Average output current = operating current × operating ratio (1 pin)
current	Iонаv2		- 8	IIIA	P00 to P07 Average output current = operating current × operating ratio (1 pin)
"H" level total maximum output current	ΣІон	_	- 100	mA	
"H" level total average output current	ΣΙΟΗΑΥ	_	- 50	mA	Total average output current = operating current × operating ratio (Total of pins)

(Continued)

Parameter	Symbol	Rat	ing	Unit	Remarks
raiametei	Syllibol	Min	Max	Onne	Kemarks
Power consumption	Pd	_	320	mW	
Operating temperature	TA	- 40	+ 85	°C	
Storage temperature	Tstg	– 55	+ 150	°C	

- *1 : The parameter is based on AVss = Vss = 0.0 V.
- *2 : Apply equal potential to AVcc and Vcc.
- *3 : V_1 and V_2 should not exceed $V_{CC} + 0.3$ V. V_1 must not exceed the rating voltage. However, if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supersedes the V_1 rating.
- *4 : Applicable to pins : P00 to P07, P10 to P15, P20 to P24, P30 to P37, P60 to P67
 - Use within recommended operating conditions.
 - Use at DC voltage (current).
 - +B signal is an input signal that exceeds Vcc voltage. The + B signal should always be applied a limiting resistance placed between the + B signal and the microcontroller.
 - The value of the limiting resistance should be set so that when the + B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
 - Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input
 potential may pass through the protective diode and increase the potential at the Vcc pin, and this affects
 other devices.
 - Note that if the + B signal is inputted when the microcontroller power supply is off (not fixed at 0 V), the power supply is provided from the pins, so that incomplete operation may result.
 - Note that if the + B input is applied during power-on, the power supply is provided from the pins and the resulting power supply voltage may not be sufficient to operate the power-on reset.
 - Care must be taken not to leave the + B input pin open.
 - Sample recommended circuits :



WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

2. Recommended Operating Conditions

(AVss = Vss = 0.0 V)

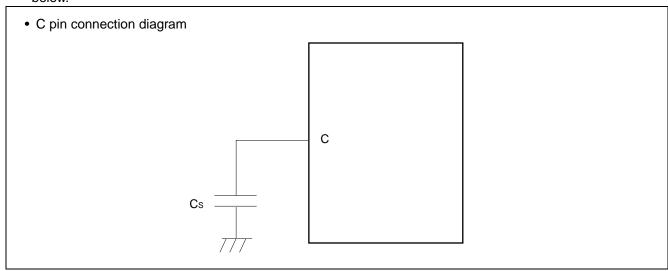
			Condi-	Va	lue		`_	
Parameter	Symbol	Pin name	tions	Min	Max	Unit	Re	marks
				2.5*1	5.5	V	In normal operation	MB95117H MB95F118HS/
Power supply	Vcc, AVcc	_		2.3	5.5	V	Hold condition in STOP mode	118TS/ MB95F118HW/ 118TW
voltage		_		2.7	5.5	٧	In normal operation Hold 103 condition in STOP mode	
				2.3	5.5	>		
	V _{IH1}	P10, P67	*2	0.7 Vcc	Vcc + 0.3	٧	At selecting of level	of CMOS input
	V _{IH2}	P50, P51	*2	0.7 Vcc	Vss + 5.5	٧	At selecting of level	of CMOS input
"H" level input voltage	V _{IHS1}	P00 to P07, P10 to P15, P20 to P24, P30 to P37, P60 to P67, PG1*3, PG2*3	*2	0.8 Vcc	Vcc + 0.3	V	Hysteresis input	
	V _{IHS2}	P50, P51	*2	0.8 Vcc	Vss + 5.5	V	Hysteresis input	
	V _{ІНМ}	RST, MOD	_	0.7 Vcc	Vcc + 0.3	V	CMOS input (Flash memory product)	
	VIEW	NOT, MOD	_	0.8 Vcc	Vcc + 0.3	٧	Hysteresis in (MASK ROM	
	VIL	P10, P50, P51, P67	*2	Vss - 0.3	0.3 Vcc	٧	At selecting of level	of CMOS input
"L" level input voltage	Vils	P00 to P07, P10 to P15, P20 to P24, P30 to P37, P50, P51, P60 to P67, PG1*3, PG2*3	*2	Vss – 0.3	0.2 Vcc	٧	Hysteresis input	
	\/	RST, MOD	_	Vss - 0.3	0.3 Vcc	٧	CMOS input (Flash memory product)	
	VILM	K31, WUD	_	Vss - 0.3	0.2 Vcc	V	Hysteresis in (MASK ROM	

(Continued)

(AVss = Vss = 0.0 V)

Parameter	Symbol	Pin name	Condi-	Value		Unit	Remarks
Parameter	Syllibol	riii iiaiiie	tions	Min	Max	Unit	Remarks
Smoothing capacitor	Cs	_	_	0.1	1.0	μF	*4
Operating temperature	Та	_	_	- 40	+ 85	°C	MB95117H MB95F118HS/118TS/ MB95F118HW/118TW
				+ 5	+ 35	°C	MB95FV100B-103

- *1 : The value is 2.9 V when the low voltage detection reset is used.
- *2: P10, P50, P51, and P67 can switch the input level to either the "CMOS input level" or "hysteresis input level". The switching of the input level can be set by the input level selection register (ILSR).
- *3: Single clock products only
- *4: Use a ceramic capacitor or a capacitor with equivalent frequency characteristics. A bypass capacitor of Vcc pin must have a capacitance value higher than Cs. For connection of smoothing capacitor Cs, see the diagram below.



WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.

3. DC Characteristics

(Vcc = AVcc = 5.0 V \pm 10%, AVss = Vss = 0.0 V, T_A = - 40 °C to + 85 °C)

Donomotor	Sym-	Din nome	Conditions		Value		11:4:4	Domonico
Parameter	bol	Pin name	Conditions	Min	Тур	Max	Unit	Remarks
"H" level output voltage	Vон1	Output pin other than P00 to P07	Іон = - 4.0 mA	4.0	_		V	
	V _{OH2}	P00 to P07	$I_{OH} = -8.0 \text{ mA}$	4.0		_	V	
"L" level output voltage	V _{OL1}	Output pin other than P00 to P07	IoL = 4.0 mA	_		0.4	V	
	V _{OL2}	P00 to P07	IoL = 12 mA	_	_	0.4	V	
Open-drain output application voltage	VD	P50, P51	_	Vss - 0.3	_	Vss + 5.5	V	
Input leakage current (Hi-Z output leakage current)	lы	Port other than P50, P51	0.0 V < Vı < Vcc	– 5	_	+ 5	μΑ	When the pull- up prohibition setting
Open-drain out- put leakage current	LIOD	P50, P51	0.0 V < V _I < Vss + 5.5 V	_		5	μΑ	
Pull-up resistor	Rpull	P10 to P15, P20 to P24, P30 to P37, PG1*1, PG2*1	Vı = 0.0 V	25	50	100	kΩ	When the pull- up permission setting
Pull-down resistor	Rмор	MOD	Vı = Vcc	25	50	100	kΩ	MASK ROM product

 $(Vcc = AVcc = 5.0 \ V \pm 10\%, \underline{AVss = Vss = 0.0 \ V, \ T_A = \ -40 \ ^{\circ}C \ to \ +85 \ ^{\circ}C)}$

Parameter	Sym	Pin name	Conditions		Value		Unit	Remarks			
rarameter	bol	riii iiaiiie	Conditions	Min	Тур	Max	Oill	Remarks			
	lcc		Vcc = 5.5 V Fcн = 20 MHz		9.5	12.5	mA	Flash memory product (at other than Flash memory writing and erasing)			
					FMP = 10 MHz Main clock mode (divided by 2)	F _{MP} = 10 MHz Main clock mode	F _{MP} = 10 MHz Main clock mode		30	35	mA
					7.2	9.5	mΑ	MASK ROM product			
Power supply current*2	Iccs	Vcc (External clock operation)	Vcc = 5.5 V FcH = 20 MHz FMP = 10 MHz Main sleep mode (divided by 2)		4.5	7.5	mA				
	Iccl	,	$Vcc = 5.5 V$ $FcL = 32 \text{ kHz}$ $F_{MPL} = 16 \text{ kHz}$ Sub clock mode (divided by 2), $T_{A} = +25 \text{ °C}$		45	100	μΑ				
	Iccls		Vcc = 5.5 V $FcL = 32 kHz$ $FMPL = 16 kHz$ $Sub sleep mode$ $(divided by 2) ,$ $TA = +25 °C$		10	81	μΑ				

(Continued)

(Vcc = AVcc = 5.0 V \pm 10%, AVss = Vss = 0.0 V, TA = - 40 °C to + 85 °C)

Doromotor	Sym-	Din nama	Conditions		Value		l lmi4	Remarks
Parameter	bol	Pin name	Conditions	Min	Тур	Max	Unit	Remarks
	Ісст		$V_{CC} = 5.5 \text{ V}$ $F_{CL} = 32 \text{ kHz}$ Watch mode Main stop mode $T_{A} = +25 \text{ °C}$	_	4.6	27	μА	
			Vcc = 5.5 V Fch = 4 MHz		9.3	12.5	mA	Flash memory product
	ICCMPLL		FMP = 10 MHz Main PLL mode (multiplied by 2.5)		7.0	9.5	mA	MASK ROM product
	ICCSPLL	Vcc (External clock operation) *2	$V_{CC} = 5.5 \text{ V}$ $F_{CL} = 32 \text{ kHz}$ $F_{MPL} = 128 \text{ kHz}$ Sub PLL mode (multiplied by 4) $T_A = +25 \text{ °C}$		160	400	μΑ	
Power supply current*2	Істѕ		$V_{CC} = 5.5 \text{ V}$ $F_{CH} = 10 \text{ MHz}$ $Timebase timer mode$ $T_A = +25 ^{\circ}C$		0.15	1.10	mA	
	Іссн		$V_{CC} = 5.5 \text{ V}$ Sub stop mode $T_A = +25 \text{ °C}$		5	20	μΑ	Main stop mode for single clock product
	ILVD	Vcc	Current consumption for low voltage detection circuit only		38	50	μΑ	
	IA		Vcc = 5.5 V FcH = 10 MHz At operating of A/D conversion		2.4	4.7	mA	
	Іан	AVcc	Vcc = 5.5 V FcH = 10 MHz At stopping A/D conversion TA = +25 °C	_	1	5	μΑ	
Input capacitance	Cin	Other than AVcc, AVss, Vcc, Vss	f = 1 MHz	_	5	15	pF	

^{*1:} Single clock product only

^{*2: •} The power-supply current is determined by the external clock. When low voltage detection option is selected, the power-supply current will be a value of adding current consumption of the low voltage detection circuit (ILVD) to the specified value.

[•] Refer to "4. AC Characteristics (1) Clock Timing" for Fch and Fcl.

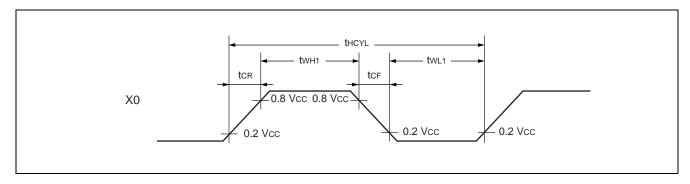
[•] Refer to "4. AC Characteristics (2) Source Clock/Machine Clock" for FMP and FMPL.

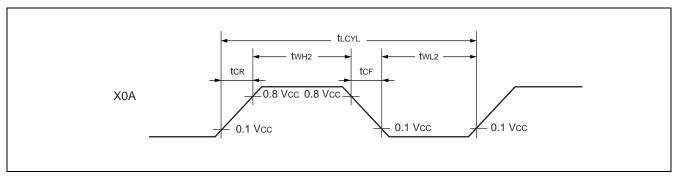
4. AC Characteristics

(1) Clock Timing

(Vcc = 2.5 V to 5.5 V, AVss = Vss = 0.0 V, $T_A = -40$ °C to +85 °C)

Parameter	Sym-	Pin name	Condi-		Value		Unit	Remarks
Parameter	bol	Pin name	tions	Min	Тур	Max	Unit	Remarks
				1	_	10	MHz	When using main oscillation circuit
	_			1	_	20	MHz	When using external clock
	Fсн	X0, X1		3		10	MHz	Main PLL multiplied by 1
Clock frequency				3	_	5	MHz	Main PLL multiplied by 2
				3		4	MHz	Main PLL multiplied by 2.5
	FcL	X0A, X1A			32.768		kHz	When using sub oscillation circuit
					32.768		kHz	When using sub PLL Vcc = 2.3 V to 3.6 V
	t HCYL	X0, X1	_	100	_	1000	ns	When using main oscillation circuit
Clock cycle time				50		1000	ns	When using external clock
	tLCYL	X0A, X1A		_	30.5	_	μs	When using sub oscillation circuit
Input clock pulse width	twh1	X0		10	_	_	ns	When using external clock Duty ratio is about 30% to
Imput Glock pulse Width	twH2	X0A			15.2		μs	70%.
Input clock rise time and fall time	t cr t cf	X0, X0A			_	5	ns	When using external clock



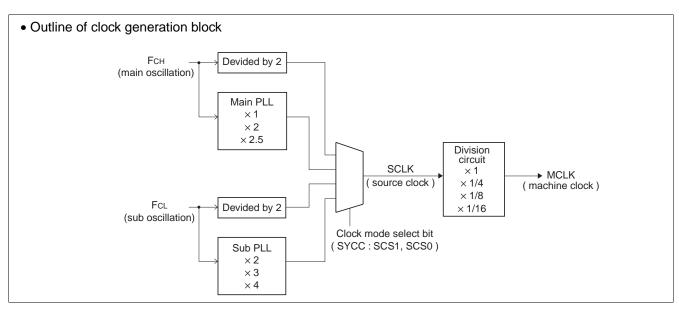


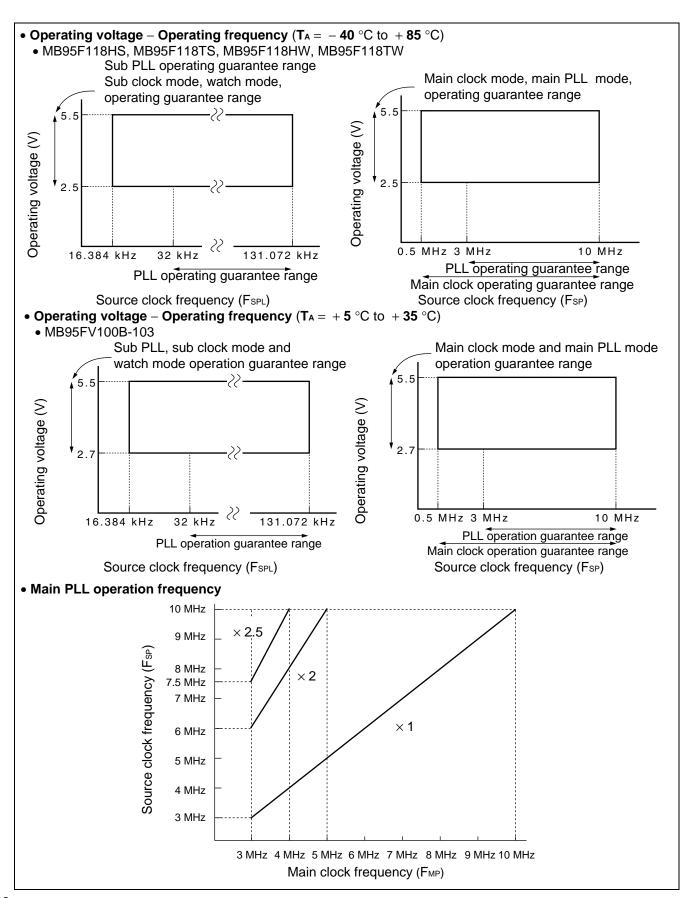
(2) Source Clock/Machine Clock

$$(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C} \text{ to } +85 \,^{\circ}\text{C})$$

Parameter	Sym- bol	Pin name	Value			Unit	Remarks
			Min	Тур	Max	Oilit	Remarks
Source clock cycle time*1 (Clock before setting division)	tsclк		100	_	2000	ns	When using main clock Min: FcH = 10 MHz, PLL multiplied by 1 Max: FcH = 1 MHz, divided by 2
		_	7.6	_	61.0	μs	When using sub clock Min: FcL = 32 kHz, PLL multiplied by 4 Max: FcL = 32 kHz, divided by 2
Source clock frequency	Fsp		0.5		10.0	MHz	When using main clock
	FSPL	_	16.384	_	131.072	kHz	When using sub clock
Machine clock cycle time*2 (Minimum instruction execution time)	t mclk		100	_	32000	ns	When using main clock Min: F _{SP} = 10 MHz, no division Max: F _{SP} = 0.5 MHz, divided by 16
			7.6	_	976.5	μs	When using sub clock Min: F _{SPL} = 131 kHz, no division Max: F _{SPL} = 16 kHz, divided by 16
Machine clock frequency	FMP		0.031	_	10.000	MHz	When using main clock
	FMPL		1.024		131.072	kHz	When using sub clock

- *1: Clock before setting division due to machine clock division ratio selection bit (SYCC: DIV1 and DIV0). This source clock is divided by the machine clock division ratio selection bit (SYCC: DIV1 and DIV0), and it becomes the machine clock. Further, the source clock can be selected as follows.
 - Main clock divided by 2
 - PLL multiplication of main clock (select from 1, 2, 2.5 multiplication)
 - Sub clock divided by 2
 - PLL multiplication of sub clock (select from 2, 3, 4 multiplication)
- *2: Operation clock of the microcontroller. Machine clock can be selected as follows.
 - Source clock (no division)
 - · Source clock divided by 4
 - Source clock divided by 8
 - Source clock divided by 16



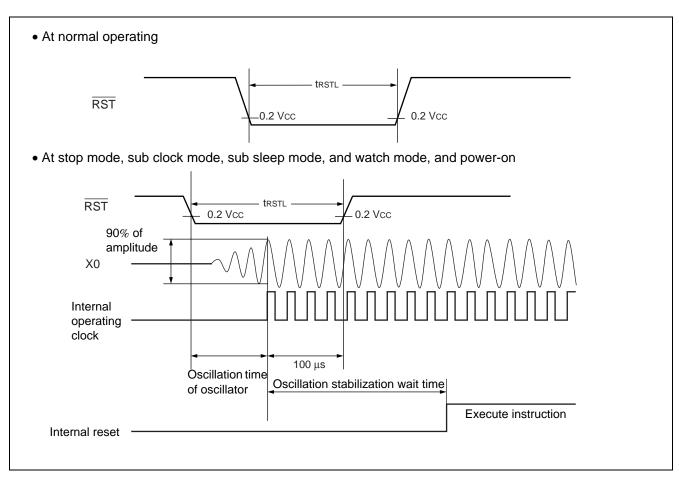


(3) External Reset

$$(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_A = -40 \,^{\circ}\text{C} \text{ to } +85 \,^{\circ}\text{C})$$

Parameter	Symbol	Value			Remarks
	Syllibol	Min	Max	Unit	iverilai kā
		2 tmcLK*1	_	ns	At normal operating
RST "L" level pulse width	t RSTL	Oscillation time of oscillator*2 + 100		μs	At stop mode, sub clock mode, sub sleep mode, and watch mode
		100		μs	At timebase timer mode

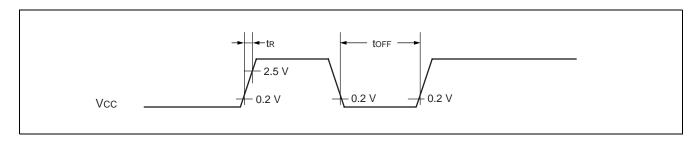
- *1 : Refer to "(2) Source Clock/Machine Clock" for tmclk.
- *2 : Oscillation start time of oscillator is the time that the amplitude reaches 90 %. In the crystal oscillator, the oscillation time is between several ms and tens of ms. In ceramic oscillators, the oscillation time is between hundreds of μ s and several ms. In the external clock, the oscillation time is 0 ms.



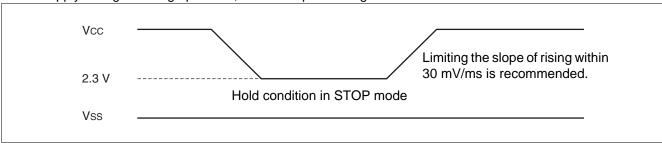
(4) Power-on Reset

(AVss = Vss = 0.0 V,
$$T_A = -40 \, ^{\circ}\text{C}$$
 to $+85 \, ^{\circ}\text{C}$)

Parameter	Symbol	Conditions	Val	lue	Unit	Remarks	
Faranietei	Syllibol	Conditions	Min	Max	Ollit		
Power supply rising time	t R		_	50	ms		
Power supply cutoff time	t off	_	1	_	ms	Waiting time until power-on	



Note: Sudden change of power supply voltage may activate the power-on reset function. When changing power supply voltages during operation, set the slope of rising within 30 mV/ms as shown below.

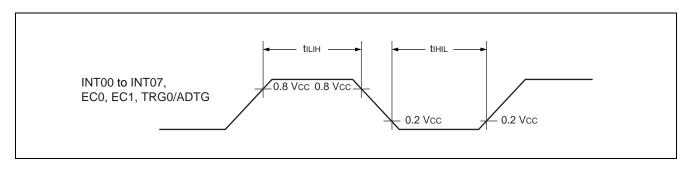


(5) Peripheral Input Timing

(Vcc = 5.0 V \pm 10%, AVss = Vss = 0.0 V, T_A = -40 °C to +85 °C)

Parameter	Symbol	Pin name	Va	lue	Unit	Remarks
Farailleter	Symbol	r III IIdille	Min	Max	Oilit	Remarks
Peripheral input "H" pulse width	tılıн	INT00 to INT07,	2 tмськ*	_	ns	
Peripheral input "L" pulse width	tıнı∟	EC0, EC1, TRG0/ADTG	2 tmclk*	_	ns	

^{*:} Refer to "(2) Source Clock/Machine Clock" for tmclk.

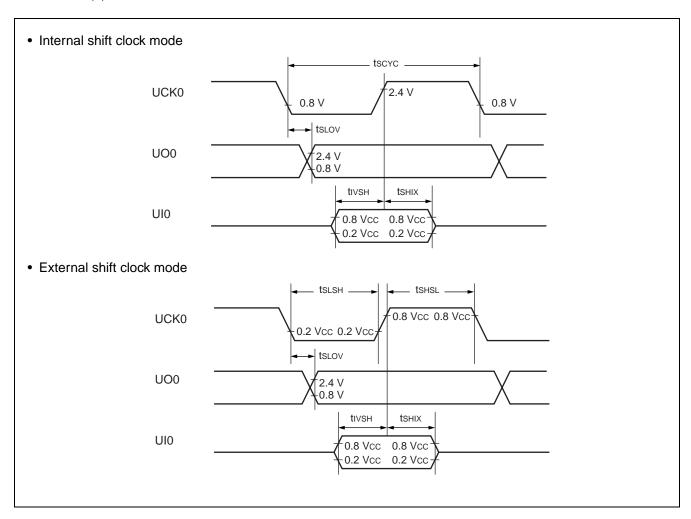


(6) UART/SIO, Serial I/O Timing

 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C} \text{ to } +85 \,^{\circ}\text{C})$

Parameter	Symbol	Pin name	Conditions	Val	ue	Unit	Remarks	
raiailletei	Syllibol	riii iiaiiie	Conditions	Min	Max	Onn	Kemarks	
Serial clock cycle time	t scyc	UCK0	Internal	4 t мськ*	_	ns		
UCK $\downarrow \rightarrow$ UO time	t sLov	UCK0, UO0	clock operation	- 190	+ 190	ns		
Valid UI → UCK ↑	tıvsн	UCK0, UI0	Output pin:	2 t мськ*		ns		
UCK ↑ → valid UI hold time	t shix	UCK0, UI0	C _L = 80 pF + 1TTL.	2 tmclk*	_	ns		
Serial clock "H" pulse width	t shsl	UCK0	External	4 t мськ*	_	ns		
Serial clock "L" pulse width	t slsh	UCK0	clock	4 t мськ*	_	ns		
$UCK\downarrow \to UO$ time	t sLov	UCK0, UO0	operation Output pin:	_	190	ns		
Valid UI → UCK ↑	t ıvsH	UCK0, UI0	C _L = 80 pF	2 t мськ*	_	ns		
UCK $\uparrow \rightarrow$ valid UI hold time	t shix	UCK0, UI0	+ 1TTL.	2 t мськ*		ns		

^{*:} Refer to "(2) Source Clock/Machine Clock" for tmclk.



(7) LIN-UART Timing

Sampling at the rising edge of sampling clock¹¹ and prohibited serial clock delay²

(ESCR register : SCES bit = 0, ECCR register : SCDE bit = 0)

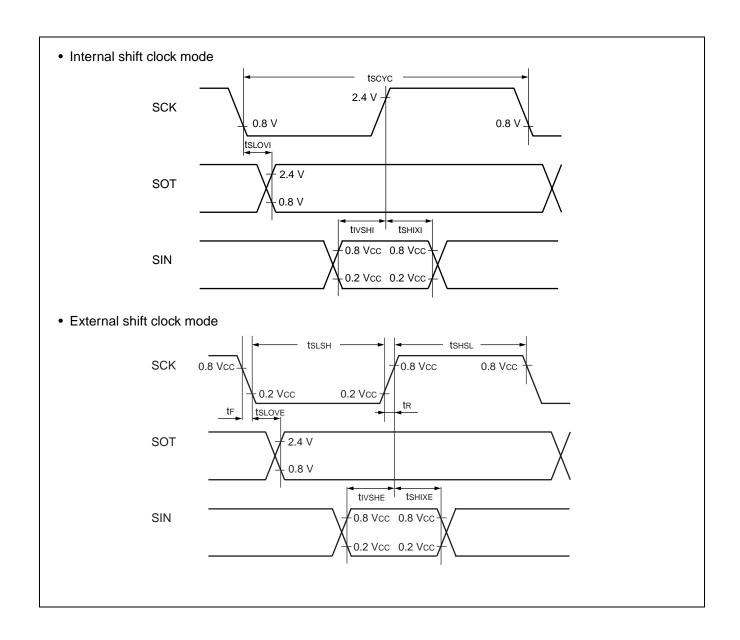
 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$

Parameter	Sym-	Pin name	Conditions	Va	lue	Unit
Farameter	bol	Finitianie	in name Gondidons		Max	Ollit
Serial clock cycle time	tscyc	SCK		5 t мськ* ³	_	ns
$SCK \downarrow \to SOT$ delay time	tslovi	SCK, SOT	Internal clock operation output pin:	-95	+ 95	ns
Valid SIN → SCK ↑	t ıvshı	SCK, SIN	$C_L = 80 \text{ pF} + 1 \text{ TTL}.$	tmcLK*3 + 190	_	ns
$SCK \uparrow \rightarrow valid SIN hold time$	t shixi	SCK, SIN	-	0	_	ns
Serial clock "L" pulse width	t slsh	SCK		3 tмськ*3 — tR	_	ns
Serial clock "H" pulse width	tshsl	SCK		tмськ*3 + 95	_	ns
$SCK \downarrow \to SOT$ delay time	t SLOVE	SCK, SOT	External clock		2 tmclk*3 + 95	ns
Valid SIN → SCK ↑	tivshe	SCK, SIN	operation output pin:	190	_	ns
$SCK \uparrow \rightarrow valid SIN hold time$	tshixe	SCK, SIN	$C_L = 80 \text{ pF} + 1 \text{ TTL}.$	tмськ*3 + 95	_	ns
SCK fall time	t⊧	SCK		_	10	ns
SCK rise time	t R	SCK		_	10	ns

^{*1 :} Provide switch function whether sampling of reception data is performed at rising edge or falling edge of the serial clock.

^{*2 :} Serial clock delay function is used to delay half clock for the output signal of serial clock.

^{*3:} Refer to " (2) Source Clock/Machine Clock" for tmclk.



Sampling at the falling edge of sampling clock¹ and prohibited serial clock delay²

(ESCR register : SCES bit = 1, ECCR register : SCDE bit = 0)

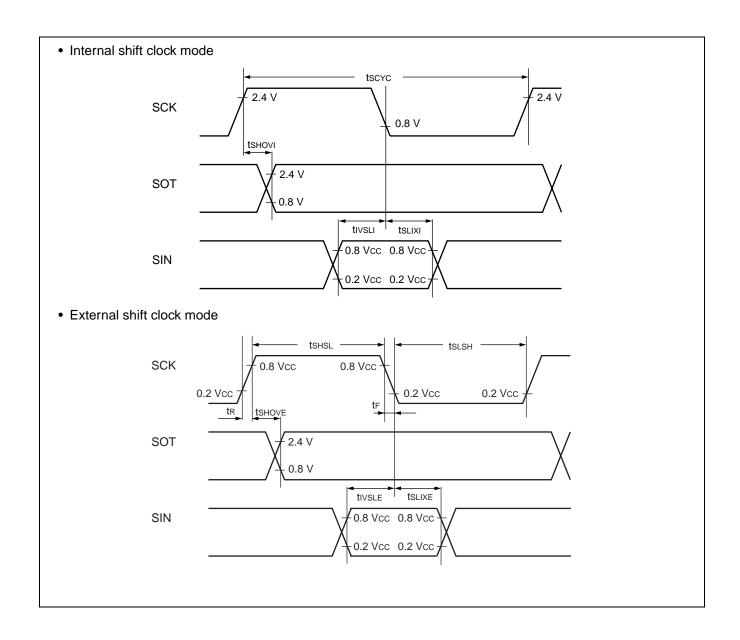
 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$

Parameter	Sym-	Pin name	Conditions	Va	lue	Unit
Farameter	bol	Fill Hallie	Conditions	Min	Max	Ollit
Serial clock cycle time	tscyc	SCK		5 t мськ* ³	_	ns
$SCK \uparrow \to SOT$ delay time	t shovi	SCK, SOT	Internal clock	-95	+ 95	ns
Valid SIN \rightarrow SCK $↓$	t ıvslı	SCK, SIN	operation output pin : C∟ = 80 pF + 1 TTL.	tмськ*3 + 190	_	ns
$SCK \downarrow \to valid \ SIN \ hold \ time$	t slixi	SCK, SIN	·	0	_	ns
Serial clock "H" pulse width	t shsl	SCK		3 tмськ*3 − tR		ns
Serial clock "L" pulse width	t slsh	SCK		t мськ*3 + 95	_	ns
$SCK \uparrow \to SOT$ delay time	t shove	SCK, SOT	External clock	_	2 tmclk*3 + 95	ns
Valid SIN → SCK \downarrow	tivsle	SCK, SIN	operation output pin :	190		ns
$SCK \downarrow \to valid \; SIN \; hold \; time$	t SLIXE	SCK, SIN	C _L = 80 pF + 1 TTL.	t мськ*3 + 95	_	ns
SCK fall time	t⊧	SCK		_	10	ns
SCK rise time	t R	SCK		_	10	ns

^{*1 :} Provide switch function whether sampling of reception data is performed at rising edge or falling edge of the serial clock.

^{*2 :} Serial clock delay function is used to delay half clock for the output signal of serial clock.

^{*3:} Refer to "(2) Source Clock/Machine Clock" for tmclk.



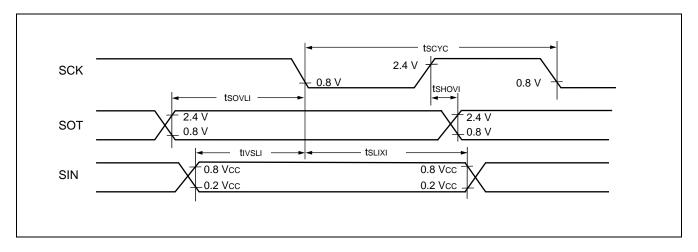
Sampling at the rising edge of sampling clock*1 and enabled serial clock delay*2

(ESCR register : SCES bit = 0, ECCR register : SCDE bit = 1)

 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$

Parameter	Sym-	Pin name	Conditions	Val	ue	Unit
Parameter	bol		Conditions	Min	Max	Onit
Serial clock cycle time	tscyc	SCK		5 t мськ* ³	_	ns
$SCK \uparrow \to SOT$ delay time	t shovi	SCK, SOT	Internal clock	-95	+ 95	ns
Valid SIN \rightarrow SCK $↓$	t ıvslı	SCK, SIN	operation output pin:	tмськ*3 + 190	_	ns
$SCK \downarrow \to valid \ SIN \ hold \ time$	t slixi	SCK, SIN	$C_L = 80 \text{ pF} + 1 \text{ TTL}.$	0	_	ns
$SOT \to SCK \downarrow delay \; time$	tsovu	SCK, SOT			4 tmclk*3	ns

- *1 : Provide switch function whether sampling of reception data is performed at rising edge or falling edge of the serial clock.
- *2 : Serial clock delay function is used to delay half clock for the output signal of serial clock.
- *3: Refer to "(2) Source Clock/Machine Clock" for tmclk.



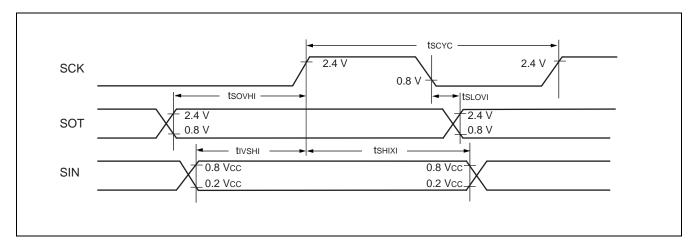
Sampling at the falling edge of sampling clock¹ and enabled serial clock delay²

(ESCR register : SCES bit = 1, ECCR register : SCDE bit = 1)

 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$

Parameter	Sym-	Pin name	Conditions	Valu	Unit	
Parameter	bol	Fin name	Conditions	Min	Max	Offic
Serial clock cycle time	tscyc	SCK		5 t мськ* ³	_	ns
$SCK \downarrow \to SOT$ delay time	tslovi	SCK, SOT	Internal clock	-95	+ 95	ns
Valid SIN → SCK ↑	tıvsнı	SCK, SIN	operating output pin:	tмськ*3 + 190		ns
$SCK \uparrow \to valid \; SIN \; hold \; time$	t shixi	SCK, SIN	$C_L = 80 \text{ pF} + 1 \text{ TTL}.$	0		ns
$SOT \to SCK \uparrow delay time$	t sovнı	SCK, SOT			4 tмськ*3	ns

- *1 : Provide switch function whether sampling of reception data is performed at rising edge or falling edge of the serial clock.
- *2 : Serial clock delay function is used to delay half clock for the output signal of serial clock.
- *3: Refer to "(2) Source Clock/Machine Clock" for tmclk.

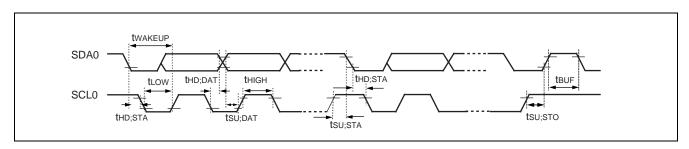


(8) I2C Timing

(Vcc = 5.0 V \pm 10%, AVss = Vss = 0.0 V, TA = - 40 °C to + 85 °C)

					Val	ue			
Parameter	Symbol	Pin name	Conditions	Standard- mode		Fast-mode		Unit	Remarks
				Min	Max	Min	Max		
SCL clock frequency	fscL	SCL0		0	100	0	400	kHz	
(Repeat) Start condition hold time SDA $\downarrow \to$ SCL \downarrow	t hd;sta	SCL0 SDA0		4.0	_	0.6	_	μs	
SCL clock "L" width	t LOW	SCL0		4.7	_	1.3	_	μs	
SCL clock "H" width	t HIGH	SCL0		4.0	_	0.6	_	μs	
(Repeat) Start condition setup time SCL $\uparrow \rightarrow$ SDA \downarrow	t su;sta	SCL0 SDA0	$R = 1.7 \text{ k}\Omega,$	4.7	_	0.6	_	μs	
Data hold time SCL \downarrow \rightarrow SDA \downarrow \uparrow	t hd;dat	SCL0 SDA0	$C = 50 \text{ pF}^{*1}$	0	3.45*2	0	0.9*3	μs	
Data setup time SDA $\downarrow \uparrow \rightarrow$ SCL \uparrow	t su;dat	SCL0 SDA0		0.25	_	0.1		μs	
Stop condition setup time SCL $\uparrow \rightarrow$ SDA \uparrow	t su;sто	SCL0 SDA0		4		0.6		μs	
Bus free time between stop condition and start condition	t BUF	SCL0 SDA0		4.7		1.3		μs	

- *1: R, C: Pull-up resistor and load capacitor of the SCL and SDA lines.
- *2: The maximum thd; DAT have only to be met if the device dose not stretch the "L" width (tLOW) of the SCL signal.
- *3 : A fast-mode I²C-bus device can be used in a standard-mode I²C-bus system, but the requirement $t_{SU;DAT} \ge 250$ ns must then be met.



(Vcc = 5.0 V \pm 10%, AVss = Vss = 0.0 V, T_A = -40 °C to + 85 °C)

.	Sym-	Pin	0 1141	Valu			TA = -40 C to + 65 C)
Parameter	bol	name	Condition	Min	Max	Unit	Remarks
SCL clock "L" width	tLOW	SCL0		(2 + nm / 2) tmclk - 20	_	ns	Master mode
SCL clock "H" width	tніgн	SCL0		(nm / 2) tmclk - 20	(nm / 2) tmcLK + 20	ns	Master mode
Start condition hold time	t HD;STA	SCL0 SDA0		(-1 + nm / 2) tmcLk - 20	(-1 + nm) tmclk + 20	ns	Master mode Maximum value is applied when m, n = 1, 8. Otherwise, the minimum value is applied.
Stop condition setup time	t su;sto	SCL0 SDA0		(1 + nm / 2) tmcLk - 20	(1 + nm / 2) tmclk + 20	ns	Master mode
Start condition setup time	t su;sta	SCL0 SDA0		(1 + nm / 2) tmcLK - 20	(1 + nm / 2) t _{MCLK} + 20	ns	Master mode
Bus free time between stop condition and start condition	t BUF	SCL0 SDA0		(2 nm + 4) tmclk - 20	ı	ns	
Data hold time	t hd;dat	SCL0 SDA0		3 tмськ — 20	_	ns	Master mode
Data setup time	tsu;dat	SCL0 SDA0	$R = 1.7 \text{ k}\Omega,$ $C = 50 \text{ pF}^{*1}$	(-2 + nm / 2) t _{MCLK} - 20	(-1 + nm / 2) tmclk + 20	ns	Master mode When assuming that "L" of SCL is not extended, the minimum value is applied to first bit of continuous data. Otherwise, the maximum value is applied.
Setup time between clearing interrupt and SCL rising	tsu;int	SCL0		(nm / 2) t _{MCLK} — 20	(1 + nm / 2) tmcLK + 20	ns	Minimum value is applied to interrupt at 9th SCL↓. Maximum value is applied to interrupt at 8th SCL↓.
SCL clock "L" width	tLOW	SCL0		4 tmclk - 20		ns	At reception
SCL clock "H" width	t HIGH	SCL0		4 tmclk - 20	<u> </u>	ns	At reception
Start condition detection	t hd;sta	SCL0 SDA0		2 tmclk - 20	_	ns	Undetected when 1 tmclk is used at reception
Stop condition detection	t su;sто	SCL0 SDA0		2 tmcLK - 20	_	ns	Undetected when 1 tmclk is used at reception
Restart condition detection condition	t su;sta	SCL0 SDA0		2 tmcLK - 20	_	ns	Undetected when 1 tmclk is used at reception
Bus free time	t BUF	SCL0 SDA0		2 tmcLK - 20	_	ns	At reception
Data hold time	t hd;dat	SCL0 SDA0		2 tmcLK - 20	_	ns	At slave transmission mode
Data setup time	tsu;dat	SCL0 SDA0		tLOW - 3 tMCLK - 20		ns	At slave transmission mode

(Continued)

(Continued)

$$(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$$

Parameter	Sym-	Pin	Condition Value*2			Unit	Remarks	
i arameter	bol	name	Condition	Min		Oilit	Remarks	
Data hold time	t hd;dat	SCL0 SDA0		0	_	ns	At reception	
Data setup time	t su;dat		$R = 1.7 \text{ k}\Omega$, $C = 50 \text{ pF}^{*1}$	tмськ — 20	_	ns	At reception	
SDA↓→SCL↑ (at wake-up function)	t WAKEUP	SCL0 SDA0	о оор.	Oscillation stabilization wait time + 2 tmclk - 20	_	ns		

- *1: R, C: Pull-up resistor and load capacitor of the SCL and SDA lines.
- *2: Refer to "(2) Source Clock/Machine Clock" for tmclk.
 - m is CS4 bit and CS3 bit (bit 4 and bit 3) of clock control register (ICCR).
 - n is CS2 bit to CS0 bit (bit 2 to bit 0) of clock control register (ICCR) .
 - Actual timing of I²C is determined by m and n values set by the machine clock (t_{MCLK}) and CS4 to CS0 of ICCR0 register.
 - Standard-mode:

m and n can be set at the range : 0.9 MHz < t_{MCLK} (machine clock) < 10 MHz.

Setting of m and n limits the machine clock that can be used below.

$$(m, n) = (1, 8)$$
 : 0.9 MHz < t_{MCLK} \leq 1 MHz

$$(m, n) = (1, 22), (5, 4), (6, 4), (7, 4), (8, 4) : 0.9 \text{ MHz} < t_{MCLK} \le 2 \text{ MHz}$$

$$(m,\,n) \; = \; (1,\,38) \;, \; (5,\,8) \;, \; (6,\,8) \;, \; (7,\,8) \;, \; (8,\,8) \quad : 0.9 \; MHz < t_{MCLK} \leq 4 \; MHz \;, \\$$

(m, n) = (1, 98) : 0.9 MHz < $t_{MCLK} \le 10$ MHz

• Fast-mode :

m and n can be set at the range : 3.3 MHz < tMCLK (machine clock) < 10 MHz.

Setting of m and n limits the machine clock that can be used below.

(m, n) = (1, 8) : 3.3 MHz < tmclk ≤ 4 MHz

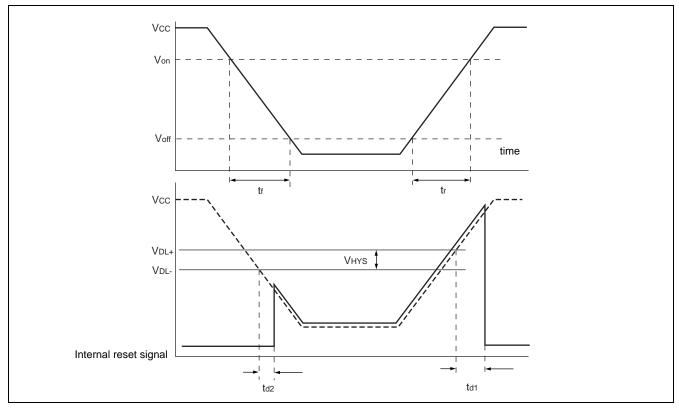
 $(m, n) = (1, 22), (5, 4) : 3.3 \text{ MHz} < t_{MCLK} \le 8 \text{ MHz}$

(m, n) = (6, 4) : 3.3 MHz < tmclk \leq 10 MHz

(9) Low Voltage Detection

(AVss = Vss = 0.0 V, $T_A = -40~^{\circ}\text{C}$ to $+85~^{\circ}\text{C}$)

Parameter	Symbol		Value		Unit	Remarks
Parameter	Symbol	Min	Тур	Max	Unit	Remarks
Release voltage	V _{DL+}	2.55	2.70	2.85	V	At power-supply rise
Detection voltage	V _{DL} -	2.45	2.60	2.75	V	At power-supply fall
Hysteresis width	V _{HYS}	70	100	_	mV	
Power-supply start voltage	Voff	_		2.3	V	
Power-supply end voltage	Von	4.9		_	V	
Power-supply voltage	t r	0.3	_	_	μs	Slope of power supply that reset release signal generates
change time (at power supply rise)	u u	_	3000	_	μs	Slope of power supply that reset release signal generates within rating (V _{DL+})
Power-supply voltage		300	_	_	μs	Slope of power supply that reset detection signal generates
change time (at power supply fall)	t _f 300 μ		μs	Slope of power supply that reset detection signal generates within rating (V _{DL} -)		
Reset release delay time	t d1	_		400	μs	
Reset detection delay time	t d2	_	_	30	μs	
Current consumption	ILVD	_	38	50	μА	Current consumption for low voltage detection circuit only



5. A/D Converter

(1) A/D Converter Electrical Characteristics

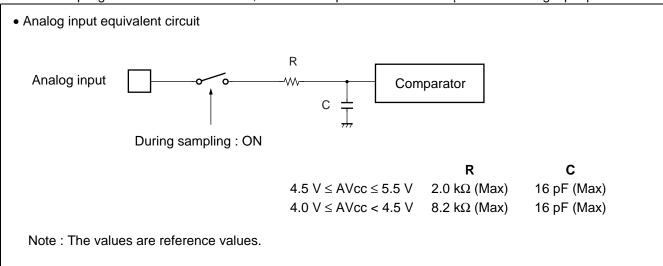
(AVcc = Vcc = 4.0 V to 5.5 V, AVss = Vss = 0.0 V, $T_A = -40$ °C to +85 °C)

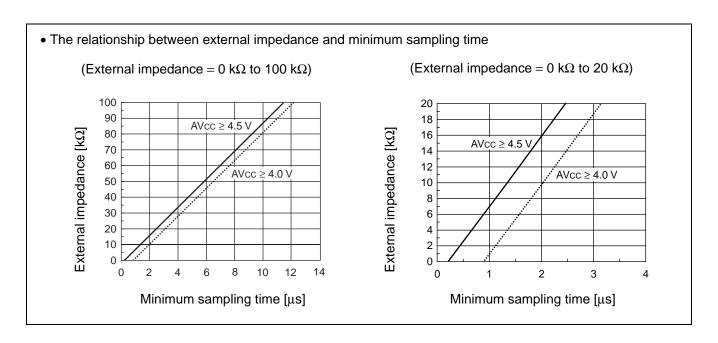
Davamatar	Cumbal	Value				
Parameter	Symbol	Min	Тур	Max	Unit	Remarks
Resolution		_	_	10	bit	
Total error		- 3.0	_	+ 3.0	LSB	
Linearity error	_	- 2.5	_	+ 2.5	LSB	
Differential linear error	=	- 1.9	_	+ 1.9	LSB	
Zero transition voltage	Vот	AVss – 1.5 LSB	AVss + 0.5 LSB	AVss + 2.5 LSB	V	
Full-scale transition voltage	VFST	AVcc – 3.5 LSB	AVcc – 1.5 LSB	AVcc + 0.5 LSB	٧	
Compare time	_	0.9	_	16500	μs	4.5 V ≤ AVcc ≤ 5.5 V
		1.8	_	16500	μs	4.0 V ≤ AVcc < 4.5 V
Sampling time	_	0.6	_	∞	μs	$4.5 \text{ V} \le \text{AVcc} \le 5.5 \text{ V},$ At external impedance < $5.4 \text{ k}\Omega$
		1.2	_	∞	μs	$4.0~V \le AVcc < 4.5~V$, At external impedance < $2.4~k\Omega$
Analog input current	Iain	-0.3	_	+ 0.3	μΑ	
Analog input voltage	Vain	AVss	_	AVcc	V	
Reference voltage	_	AVss + 4.0	_	AVcc	V	AVcc pin
Reference voltage supply current	I R	_	600	900	μΑ	AVcc pin, During A/D operation
	Iкн	_	_	5	μΑ	AVcc pin, At stop mode

(2) Notes on Using A/D Converter

. About the external impedance of analog input and its sampling time

A/D converter with sample and hold circuit. If the external impedance is too high to keep sufficient sampling time, the analog voltage charged to the internal sample and hold capacitor is insufficient, adversely affecting A/D conversion precision, Therefore, to satisfy the A/D conversion precision standard, consider the relationship between the external impedance and minimum sampling time and either adjust the register value and operating frequency or decrease the external impedance so that the sampling time is longer than the minimum value. Also, if the sampling time cannot be sufficient, connect a capacitor of about $0.1~\mu F$ to the analog input pin.





About errors

As |AVcc - AVss| becomes smaller, values of relative errors grow larger.

(3) Definition of A/D Converter Terms

Resolution

The level of analog variation that can be distinguished by the A/D converter.

When the number of bits is 10, analog voltage can be divided into $2^{10} = 1024$.

• Linearity error (unit: LSB)

The deviation between the value along a straight line connecting the zero transition point ("00 0000 0000" $\leftarrow \rightarrow$ "00 0000 0001") of a device and the full-scale transition point

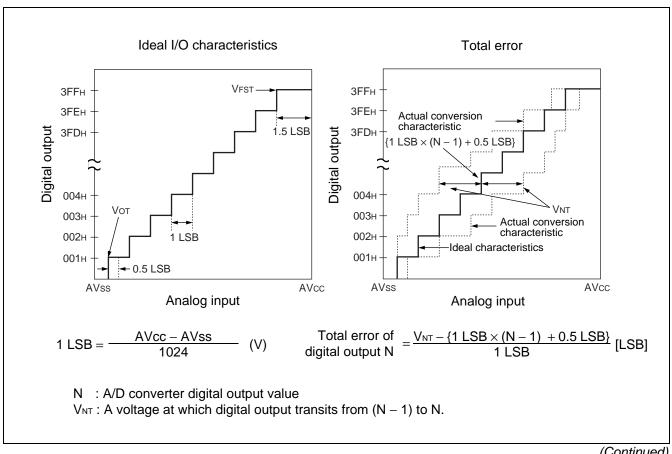
("11 1111 1111" \leftarrow \rightarrow "11 1111 1110") compared with the actual conversion values obtained.

• Differential linear error (Unit : LSB)

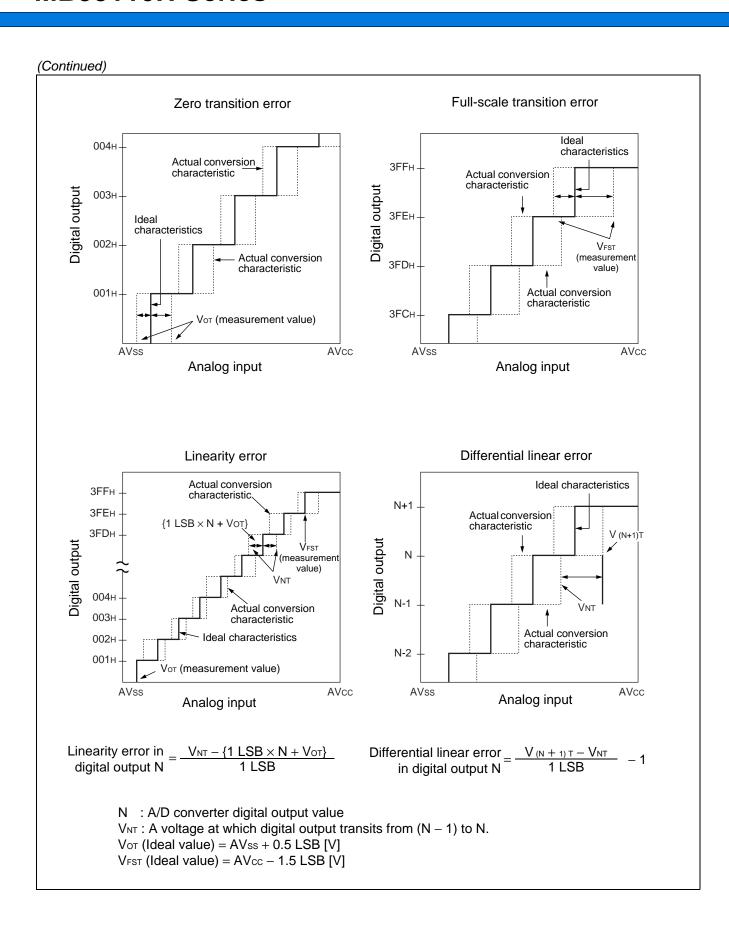
Deviation of input voltage, which is required for changing output code by 1 LSB, from an ideal value.

Total error (unit: LSB)

Difference between actual and theoretical values, caused by a zero transition error, full-scale transition error, linearity error, quantum error, and noise.



(Continued)



6. Flash Memory Program/Erase Characteristics

Dorometer	Value			Unit	Remarks	
Parameter	Min	Тур	Max	Unit	Remarks	
Sector erase time (4 Kbytes sector)	_	0.2*1	0.5*2	S	Excludes 00 _H programming prior erasure.	
Sector erase time (16 Kbytes sector)	_	0.5*1	7.5*2	S	Excludes 00 _H programming prior erasure.	
Byte programming time		32	3600	μs	Excludes system-level overhead.	
Program/erase cycle	10000	_	_	cycle		
Power supply voltage at program/erase	4.5		5.5	V		
Flash memory data retention time	20*3	_	_	year	Average T _A = +85 °C	

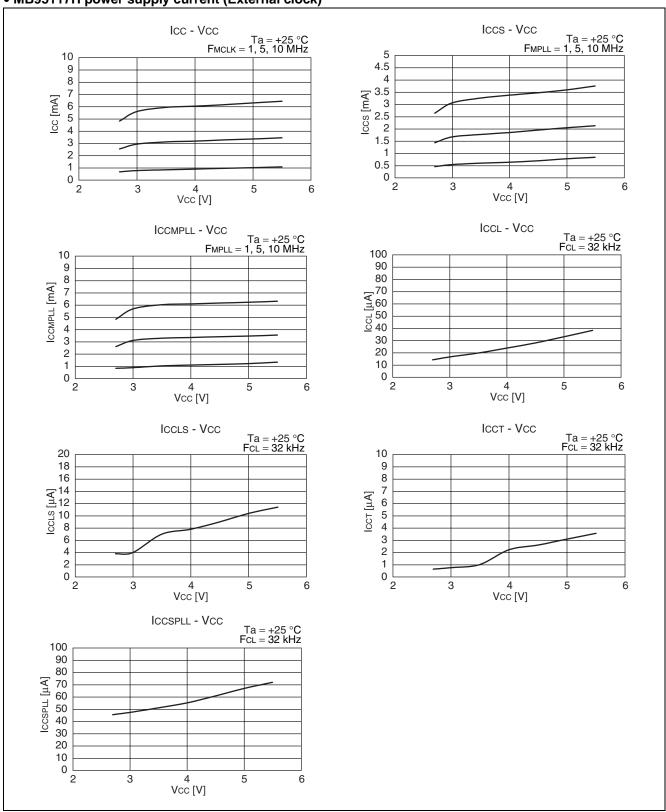
^{*1 :} $T_A = +25 \, {}^{\circ}C$, $V_{CC} = 5.0 \, V$, 10000 cycles

^{*2 :} $T_A = +85 \, ^{\circ}\text{C}$, $V_{CC} = 4.5 \, \text{V}$, 10000 cycles

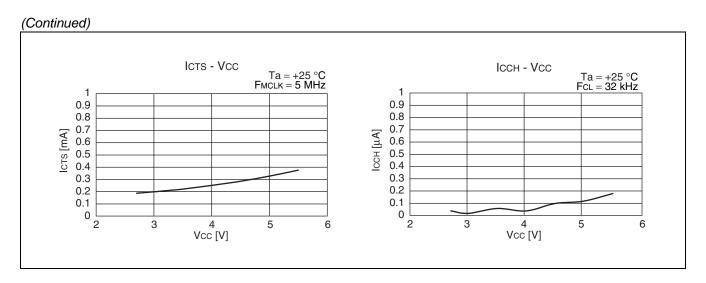
 $^{^*3}$: This value comes from the technology qualification (using Arrhenius equation to translate high temperature measurements into normalized value at +85 $^\circ$ C).

■ EXAMPLE CHARACTERISTICS

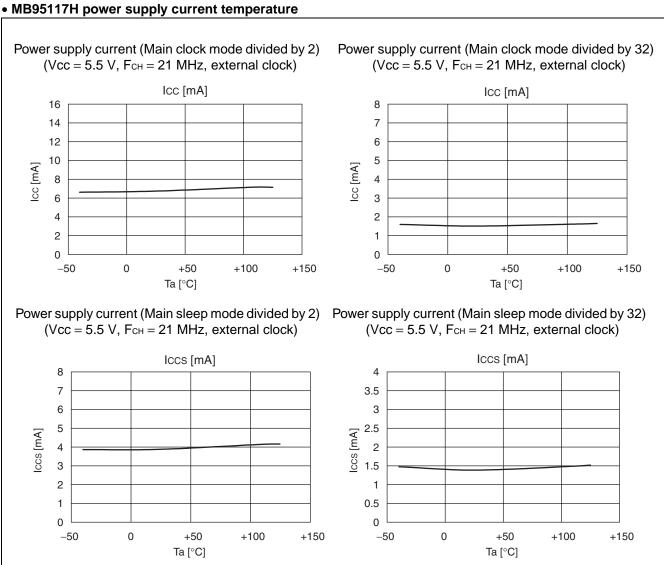
• MB95117H power supply current (External clock)



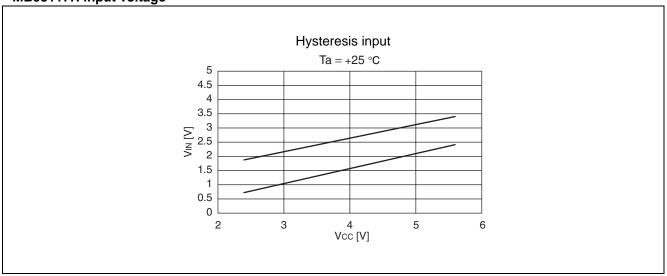
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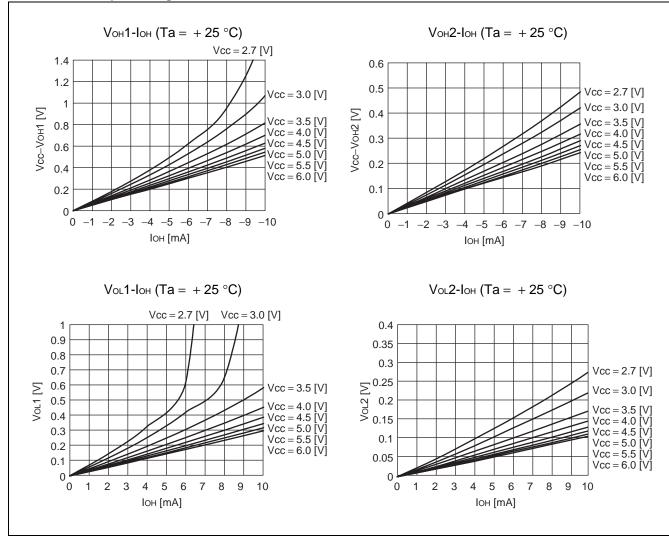


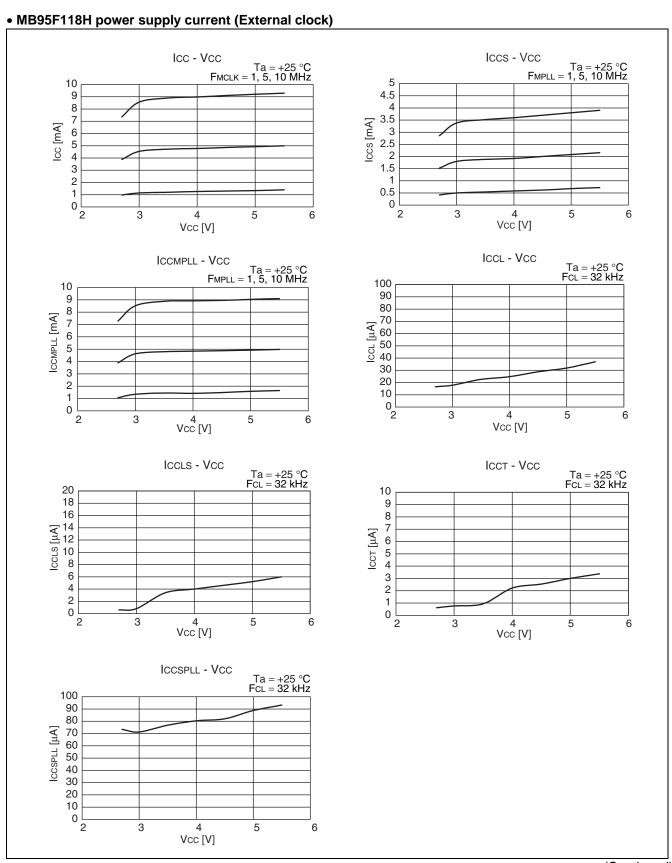




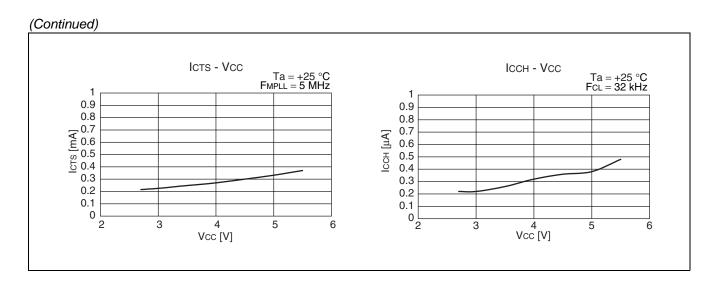


• MB95117H output voltage



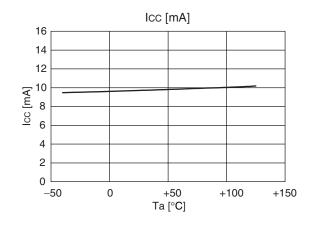


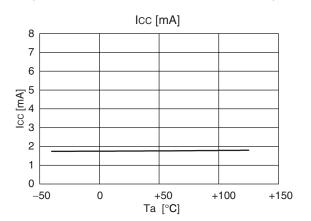
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• MB95F118H power supply current temperature

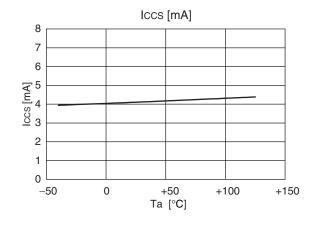
Power supply current (Main clock mode divided by 2) Power supply current (Main clock mode divided by 32) (Vcc = 5.5 V, FcH = 21 MHz, external clock) (Vcc = 5.5 V, FcH = 21 MH, external clock)

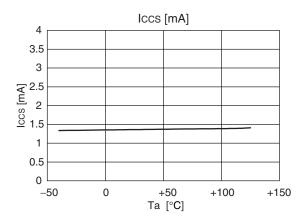




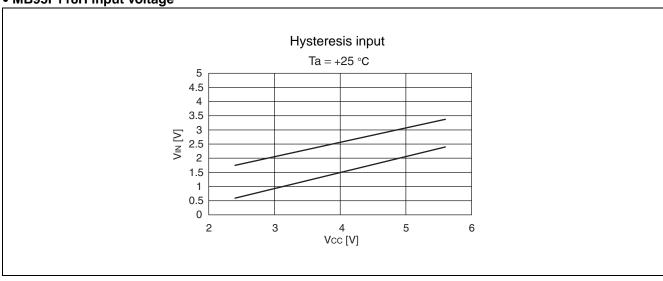
Power supply current (Main clock mode divided by 2) (Vcc = 5.5 V, FcH = 21 MHz, external clock)

Power supply current (Main clock mode divided by 32) $(Vcc = 5.5 \text{ V}, \text{ F}_{CH} = 21 \text{ MHz}, \text{ external clock})$

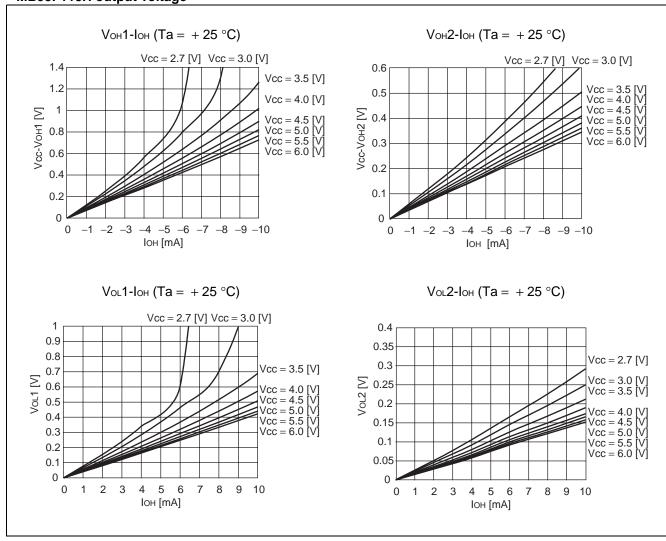








• MB95F118H output voltage



■ MASK OPTION

No.	Part number	MB95117H	MB95F118HS MB95F118TS	MB95F118HW MB95F118TW	MB95FV100B-103
NO.	Specifying procedure	Setting disabled	Setting disabled	Setting disabled	Setting disabled
1	Clock mode select Single-system clock mode Dual-system clock mode	Specify when ordering MASK	Single-system clock mode	Dual-system clock mode	Changing by the switch on MCU board
2	Low voltage detection reset* • With low voltage detection reset • Without low voltage detection reset	Specify when ordering MASK	Specified by part number	Specified by part number	Changing by the switch on MCU board
3	Oscillation stabilization wait time	i osciliation		tion stabilization	Fixed to oscillation stabilization wait time of (2 ¹⁴ –2) /FcH

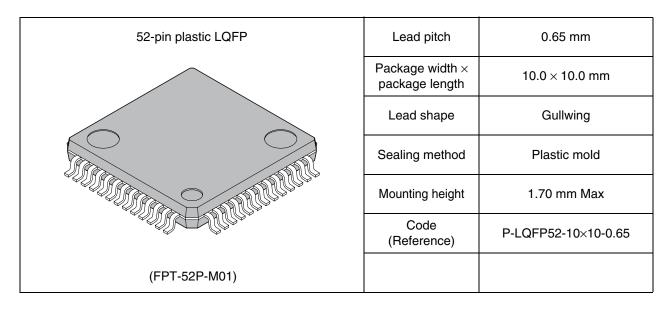
^{*:} Refer to table below about clock mode select, low voltage detection reset and reset output.

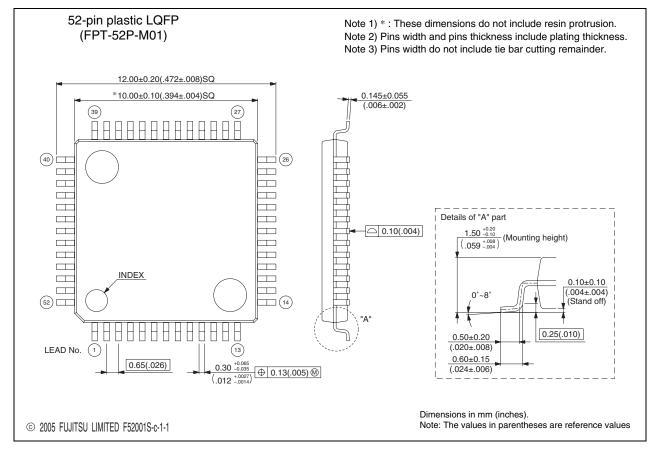
Part number	Clock mode select	Low voltage detection reset	Reset output
	Single-system	No	Yes
MB95117H	Single-system	Yes	Yes
	Dual avetem	No	Yes
	Dual-system	Yes	Yes
MB95F118HS	Single avetem	No	Yes
MB95F118TS	Single-system	Yes	Yes
MB95F118HW	Dual-system	No	Yes
MB95F118TW	Dual-system	Yes	Yes
	Single-system	No	Yes
MB95FV100B-103	Single-system	Yes	Yes
MD30L A 100D-100	Dual-system	No	Yes
	Dual-system	Yes	Yes

■ ORDERING INFORMATION

Part number	Package	Remarks
MB95117HPMC MB95F118HSPMC MB95F118HWPMC MB95F118TSPMC MB95F118TWPMC	52-pin plastic LQFP (FPT-52P-M01)	
MB2146-303 (MB95FV100B-103PBT)	MCU board (224-pin plastic PFBGA (BGA-224P-M08)	

■ PACKAGE DIMENSIONS





The information for microcontroller supports is shown in the following homepage. http://www.fujitsu.com/global/services/microelectronics/product/micom/support/index.html

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