



AN10981

GreenChip TEA1738 series fixed frequency flyback controller

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Application note

Document information

Info	Content
Keywords	GreenChip, TEA1738, SMPS, flyback, adapter, notebook, LCD monitor.
Abstract	The TEA1738 is a low cost member of the GreenChip family. It is a fixed-frequency flyback controller intended for power supplies up to 75 W for applications such as notebooks, printers and LCD monitors.



Revision history

Rev	Date	Description
v.1.1	20110418	second issue
Modifications:		<ul style="list-style-type: none">• TEA1738GT added throughout the application note.• Position of RT1 and R17 changed on Figure 1 and Figure 22.
v.1	20101206	first issue

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1. Introduction

The TEA1738 is a fixed frequency flyback controller that can be used for Discontinuous Conduction Mode (DCM) as well as Continuous Conduction Mode (CCM).

1.1 Scope

This application note describes the functionality of the TEA1738 series. Fixed-frequency flyback fundamentals and calculation of transformer and other large signal parts are not dealt with in this application note.

1.2 Features

- SMPS controller IC enabling low cost applications
- Large input voltage range (12 V to 30 V, 35 V peak allowed for 100 ms)
- Very low supply current during start and restart (typically 10 μ A)
- Low supply current during normal operation (typically 500 μ A, no load)
- Overpower compensation (high/low line compensation)
- Adjustable overpower time-out
- Adjustable overpower restart timer
- Fixed frequency with frequency jitter to reduce EMI
- Frequency reduction with fixed minimum peak current at low power operation to maintain high efficiency at low output power levels
- Frequency increase during peak power (for more output power from same core)
- Slope compensation for CCM operation
- Low and adjustable OverCurrent Protection (OCP) trip level
- Soft start
- Two independent general purpose protection inputs combined on a single pin (e.g. for OverTemperature Protection (OTP) and output OverVoltage Protection (OVP))
- Internal OverVoltage Protection (triggers latched protection mode if VCC pin exceeds 30 V)
- Internal OTP

1.3 Applications

The TEA1738 is intended for applications that require an efficient and cost-effective power supply solution up to 75 W such as:

- Notebooks
- LCD monitors
- Printers

1.4 New features compared to the TEA1733

The relevant changes with respect to the TEA1733 are:

- Internal overvoltage protection added (triggers latched protection mode if VCC pin exceeds 30 V)
- Increased rating of the VCC clamp (730 μ A instead of 200 μ A)
- Maximum duty cycle increased to 80 %
- Maximum on-time protection added (ensures well defined restart at mains dip)
- Improved switching frequency curve for higher efficiency at low load
- Increased switching frequency during peak load (more output power possible with same core)
- Input overvoltage protection removed from VINSENSE pin

Latch version (TEA1738L) only:

- UVLO changed into latched protection (this ensures that a shorted output always triggers latched protection and when VCC drops below UVLO before overpower protection has a chance to respond)

Table 1. TEA1738 series type overview

This table only shows the differences between the various TEA1738 versions, all other properties are identical.

Property	T	LT	FT	GT
Overpower protection	restart	latch		restart
UVLO protection	restart	latch		restart
Maximum on-time protection	restart			no action
VCC startup voltage	20.6 V			13 V
Peak power frequency	78 kHz		78 kHz	118 kHz

1.5 Latched version TEA1738LT

The TEA1738 is available in a restart version and a latch version. The only difference between the two versions is how the OverPower Protection (OPP) and UnderVoltage LockOut events are handled:

- TEA1738T, TEA1738FT, TEA1738GT: OPP or UVLO event initiates safe restart
- TEA1738LT: OPP or UVLO event sets IC in latched off-state

See [Section 3.4](#) for more detailed information on these protection features.

1.6 Low startup voltage versions TEA1738FT and TEA1738GT

The TEA1738FT and TEA1738GT versions are intended for applications with a separate standby power supply such as LCD television. In this case, the controller obtains its VCC supply directly from a separate standby supply. If the available voltage is lower than the 20.6 V starting voltage of the TEA1738T, the solution is to use TEA1738FT or TEA1738GT with a start-up voltage of only 13 V.

1.7 Application schematic

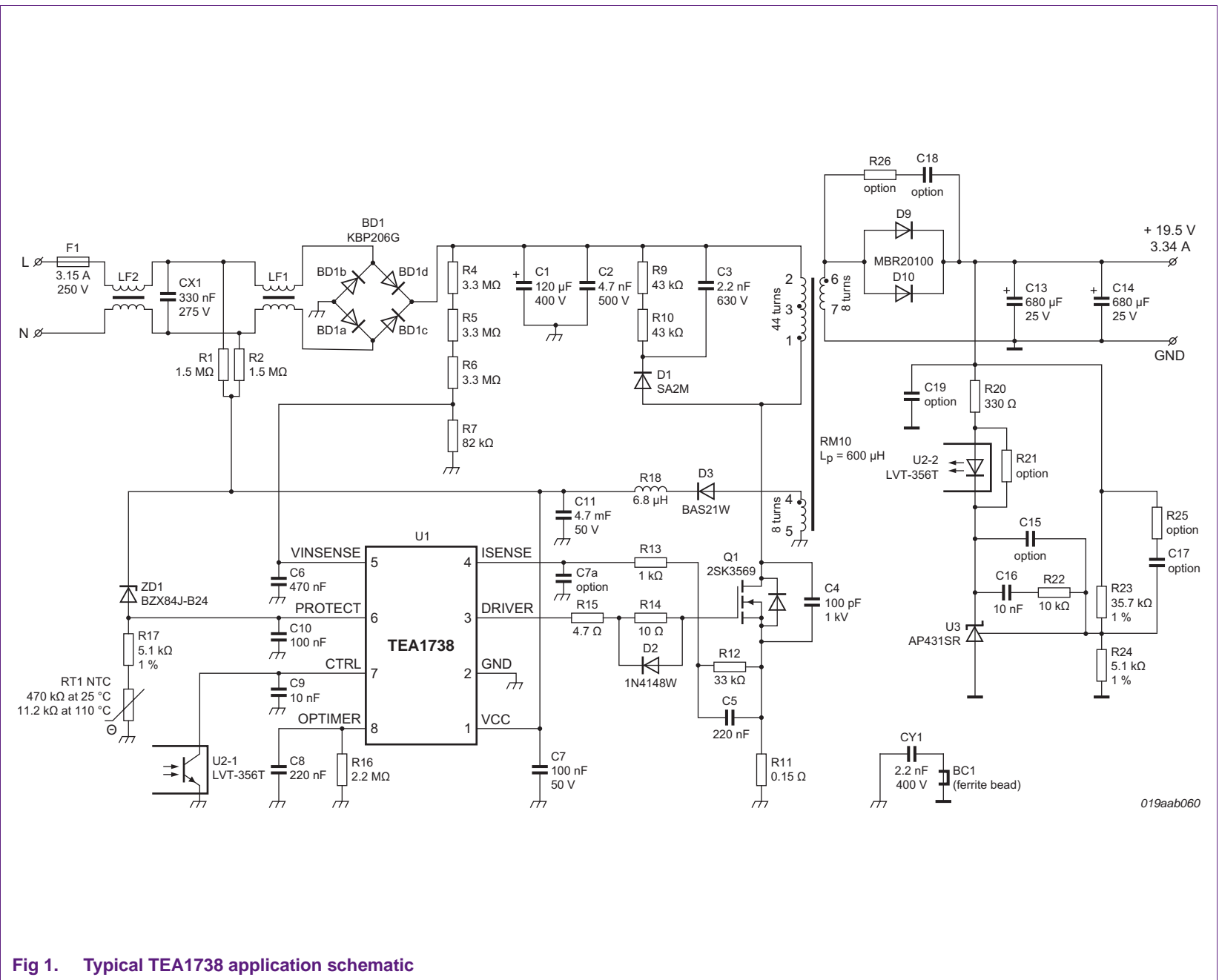


Fig 1. Typical TEA1738 application schematic

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2. Pin description

Table 2. Pin description

Pin number	Pin name	Description
1	VCC	<p>Supply voltage</p> <p>At mains switch-on, the capacitor connected to this pin is charged by an external start-up circuit.</p> <p>When the voltage on the pin exceeds V_{startup} the IC wakes up from Power-down mode and checks if all other conditions are met to start switching.</p> <p>When the voltage on the pin drops below $V_{\text{th(UVLO)}}$ the TEA1738 stops switching and enters Power-down mode. (When the voltage rises above V_{startup} a normal start-up procedure is carried out.)</p> <p>During a safe restart procedure, this pin is internally clamped to a voltage just above V_{startup}.</p> <p>During latched protection this pin is internally clamped to a voltage just above $V_{\text{rst(latch)}}$ to enable fast latch reset after unplugging the mains.</p> <p>An internal OverVoltage Protection sets the IC to latched off-state when the voltage on the VCC pin exceeds 30 V for 8 consecutive switching cycles.</p> <ul style="list-style-type: none"> • $V_{\text{startup}} = 20.6 \text{ V}$ (typ. for TEA1738T and TEA1738LT or 13V (typ.) for TEA1738FT and TEA1738GT) • $V_{\text{th(UVLO)}} = 12.2 \text{ V}$ (typ.) • $V_{\text{clamp(VCC)}}$ during restart = $V_{\text{startup}} + 1\text{V}$ • $V_{\text{clamp(VCC)}}$ during latched protection = $V_{\text{rst(latch)}} + 1\text{V}$ • $V_{\text{rst(latch)}} = 5\text{V}$ <p>Absolute maximum rating: $V_{\text{CC}} = 30 \text{ V}$ (35 V for 100 ms).</p>
2	GND	Ground
3	DRIVER	<p>Gate driver output for MOSFET</p> <ul style="list-style-type: none"> • $I_{\text{source(DRIVER)}} = 0.3 \text{ A}$ (typ.) at $V_{\text{DRIVER}} = 2\text{V}$ • $I_{\text{sink(DRIVER)}} = 0.3 \text{ A}$ (typ.) at $V_{\text{DRIVER}} = 2 \text{ V}$ • $I_{\text{sink(DRIVER)}} = 0.75 \text{ A}$ (typ.) at $V_{\text{DRIVER}} = 10\text{V}$ <p>Frequency modulation</p> <ul style="list-style-type: none"> • Modulation range = $\pm 4\text{ kHz}$ • Modulation frequency = 280 Hz

Table 2. Pin description ...continued

Pin number	Pin name	Description
4	ISENSE	<p>Current sense input</p> <p>General</p> <p>This pin senses the primary current across an external resistor and compares it to an internal control voltage. This internal control voltage, $V_{ctrl(lpeak)}$ is proportional to the CTRL pin voltage: $V_{ctrl(lpeak)} = (V_{CTRL} - 1.1) / 5.6$.</p> <hr/> <p>Overpower protection</p> <p>When the voltage on the ISENSE pin exceeds the overpower protection limit, the overpower timer is started: $V_{th(sense)opp} = 400\text{ mV}$.</p> <hr/> <p>Overcurrent protection</p> <p>The internal control voltage $V_{ctrl(lpeak)}$ is limited to 500 mV which also limits the voltage on the ISENSE input: $V_{sense(max)} = 500\text{ mV}$.</p> <hr/> <p>Leading edge blanking</p> <p>The first 300 ns of each switching cycle, the ISENSE input is internally blanked to prevent the spike caused by parasitic capacitance triggering the peak current comparator prematurely.</p> <hr/> <p>Propagation delay</p> <p>Going from detecting the level to switching off the driver takes time. During that time the primary current continues to increase. How much it is able to increase depends on the di/dt slope and thus on the mains voltage. So the resulting peak current not only depends on the CTRL voltage but also on the mains voltage.</p> <hr/> <p>Overpower compensation (high/low line compensation)</p> <p>Without counter measures, the maximum output power (in CCM) would be higher for high input voltages. To compensate this effect the input voltage measured on the VINSENSE pin is internally converted to a small current on the ISENSE input. This current causes a voltage drop over the series resistor, limiting the maximum peak current for high input voltage. By tuning the series resistor, the maximum output power can be made the same for high and low mains.</p> <hr/> <p>Soft start</p> <p>Just before the converter starts, the soft start capacitor (C5 in Figure 1) is charged by an internal current source (55 μA). After the capacitor has been sufficiently charged, the current source is switched off and the controller starts switching. The soft start capacitor now slowly discharges through the soft start resistor (R12 in Figure 1), slowly enabling the primary peak current to grow.</p> <hr/> <p>Slope compensation</p> <p>Amount of slope compensation (related to ISENSE pin): 19 mV/μs</p> <p>The slope compensation is only active at duty cycles higher than 45 %.</p> <hr/> <p>Remark: R13 should be placed close to the IC. Its purpose is to prevent negative spikes from reaching the pin (these can be rectified by the internal ESD protection diode which causes a DC offset across C5).</p>

Table 2. Pin description ...continued

Pin number	Pin name	Description
5	VINSENSE	<p>Input voltage sense pin</p> <p>This pin monitors the mains input voltage. It can detect three levels. The voltage on the VINSENSE pin should exceed $V_{start(VINSENSE)}$ to be able to start (or restart) the converter. During operation the voltage must remain above $V_{det(L)(VINSENSE)}$ (for brownout protection), otherwise the device will carry out a safe restart procedure.</p> <p>This pin is intended to be connected to the rectified mains voltage via a resistor divider, a capacitor to ground is required to filter out the ripple on the rectified mains voltage.</p> <ul style="list-style-type: none"> $V_{start(VINSENSE)} = 0.94\text{ V}$ $V_{det(L)(VINSENSE)} = 0.72\text{ V}$ (brownout protection) <p>See Section 3.3 for how to translate these levels to mains voltages.</p> <p>Overpower compensation</p> <p>The voltage on the VINSENSE pin is also used internally for the overpower compensation, see Section 3.5.</p>
6	PROTECT	<p>General purpose protection input</p> <p>Two independent protection features can be connected to this pin. An internal current source attempts to keep this pin at 0.65 V. This current source can sink 107 μA and source 32 μA. If more current is required to keep the voltage at 0.65 V the voltage will rise above 0.8 V or fall below 0.5 V and the TEA1738 will enter Latched protection mode.</p>
7	CTRL	<p>Peak current control input</p> <p>The CTRL pin voltage is converted to an internal control voltage $V_{ctrl(Ipeak)}$. If the voltage measured on the ISENSE pin exceeds this internal control voltage the driver is switched off.</p> <ul style="list-style-type: none"> V_{CTRL} for minimum flyback peak current = 1.8 V (typ.) ($V_{ctrl(Ipeak)} = 125\text{ mV}$) V_{CTRL} for maximum flyback peak current = 3.9 V (typ.) ($V_{ctrl(Ipeak)} = 500\text{ mV}$) $R_{INT(CTRL)} = 7\text{ k}\ \Omega$ (internally connected to 5.4 V) <p>Relation between the CTRL pin voltage and the internal control voltage:</p> <ul style="list-style-type: none"> $V_{ctrl(Ipeak)} = (V_{CTRL} - 1.1) / 5.6$ (typical at 25 °C) <p>Relationship between the CTRL pin current and the CTRL pin voltage:</p> <ul style="list-style-type: none"> $V_{CTRL} = 5.4\text{ V} - 7 * 10^3 * I_{O(CTRL)}$ (typical at 25 °C)
80	PTIMER	<p>Overpower timer and restart timer</p> <p>Both timer functions can be more or less independently adjusted. See Section 3.7 for the calculation. The ratio of these times determines the maximum input power during a continuous overload (e.g. shorted output).</p> <p>Overpower timer</p> <p>If the internal control voltage, $V_{ctrl(Ipeak)}$ exceeds the overpower threshold of 400 mV, the overpower timer is activated. An internal 10.7 μA current source charges the external OPTIMER capacitor. If the overpower condition lasts long enough to charge the OPTIMER pin to 2.5 V, the controller carries out a safe restart procedure (or enters Latched protection mode in the latched version). If the internal control voltage drops below 400 mV before the OPTIMER pin reaches 2.5 V, the OPTIMER capacitor is immediately discharged. The minimum recommended value for the OPTIMER resistor is 470 kΩ (otherwise there is a chance that 10.7 μA is not sufficient to charge the capacitor to 2.5 V). The overpower function can be disabled by choosing a resistor lower than 180 kΩ.</p> <p>Restart timer</p> <p>When a safe restart procedure is triggered by one of the protection features (via the VINSENSE pin or the OPTIMER pin), the OPTIMER capacitor will be quickly charged to 4.5 V by an internal 107 μA current source. The TEA1738 enters Power-down mode and does not start again until the external resistor on the OPTIMER pin has discharged the capacitor to less than 1.2 V.</p>

3. Functional description

3.1 General

The TEA1738 has been designed for fixed-frequency CCM flyback power supplies.

The TEA1738 uses peak current control. The output voltage is measured and transferred back via an optocoupler to the CTRL pin of the TEA1738.

3.2 Start-up

3.2.1 Charging the VCC capacitor

A capacitor on the VCC pin (C11) is charged by a resistor to provide the start-up power. As long as V_{CC} is below $V_{start-up}$ (20.6 V typ.), the IC current consumption is low (only 10 μ A). When the capacitor is charged above $V_{start-up}$ (20.6 V typ.) and all other conditions have been met, the controller starts to switch. Once the supply has started, the TEA1738 is supplied by the auxiliary winding.

For fast latch reset, the resistor must be connected before the bridge rectifier.¹

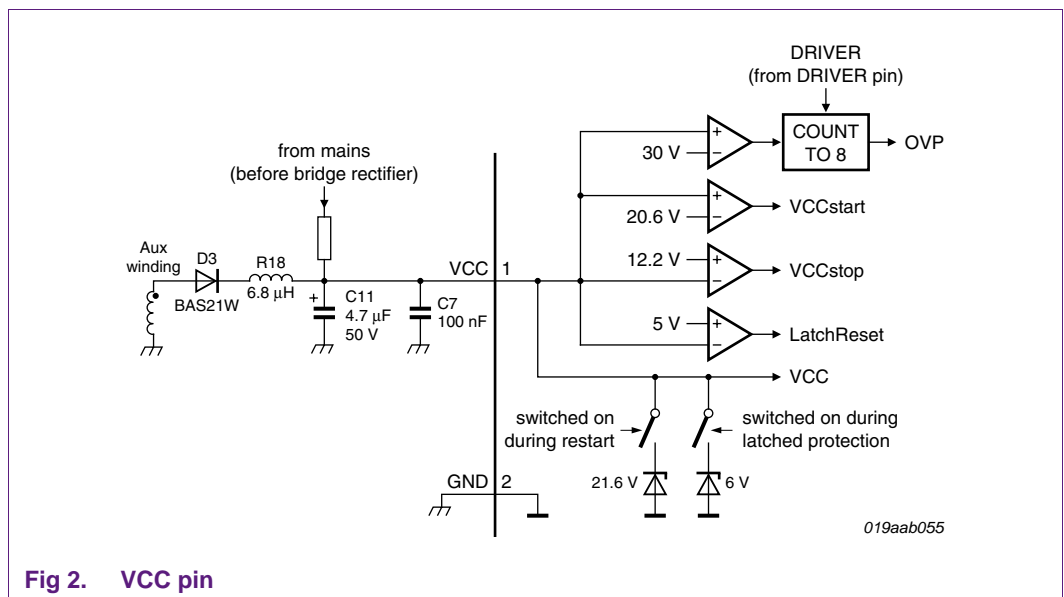


Fig 2. VCC pin

A low-cost and efficient implementation for the start-up circuit is to combine it with the X-cap (CX1) discharge resistor. See [Figure 3a](#) (Start-up circuit with two resistors).

1. The only way to reset the latched protection is to bring the VCC pin below 5 V. During latched protection, the supply current is only 10 μ A. So if the start-up resistor is connected after the bridge rectifier, the bulk capacitor would continue to feed it for a long time after unplugging the mains.

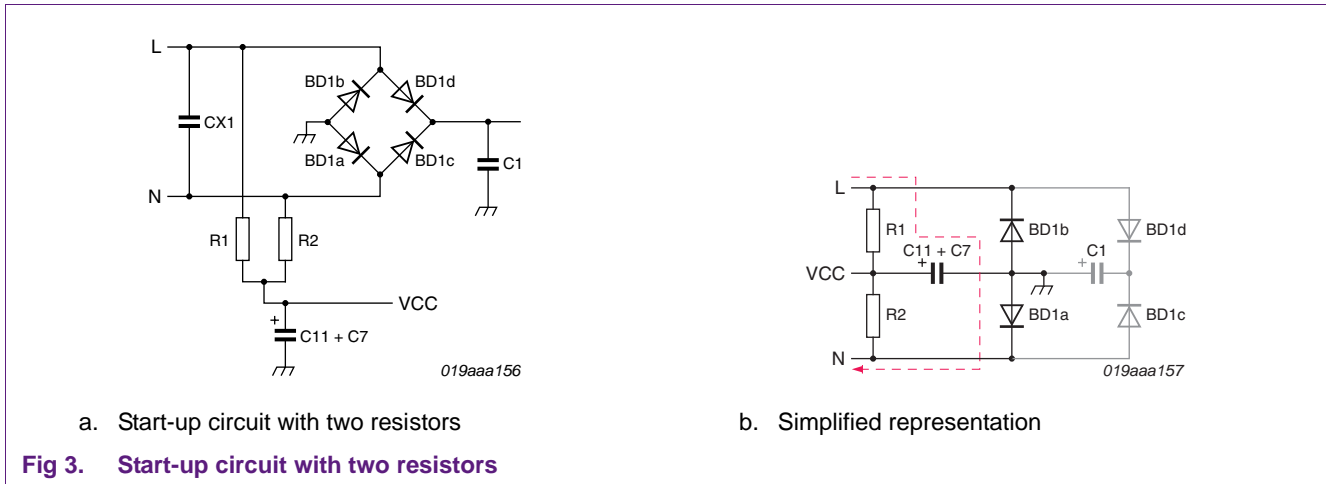


Figure 3b, shows the circuit shown in Figure 3a but drawn to show more clearly how the VCC capacitor is charged. Once the bulk capacitor C1 is fully charged, diode c and diode d stop conducting. During the positive half mains cycle diode a conducts and the current through R1 charges the VCC capacitor (C11 + C7). During this positive half cycle, part of the charge current leaks away into R2. The worst case current that leaks into R2 occurs is when the VCC capacitor is almost charged:

$$I_{leak} = \frac{V_{startup}}{R2} = \frac{20.6 V}{1.2 M\Omega} = 17 \mu A \tag{1}$$

The value of R1 and R2 must be low enough to ensure the required discharge time of the X-cap ($RC < 1 s$) and also low enough to obtain an acceptable start-up time at low mains voltage. But it must also be chosen to be as high as possible to keep the no-load power consumption as low as possible.

Some examples of start-up times for different resistors are shown in Table 3.

Table 3. Start-up times for different start-up resistor values

VCC capacitance: $4.7 \mu F + 100 nF = 4.8 \mu F$.

Resistor R1 = R2	Start-up time at 90 V (AC)	Start-up time at 115 V (AC)	Power at 230 V (AC) ^[1]
680 kΩ	1.6 s	1.1 s	70 mW
820 kΩ	2.0 s	1.4 s	59 mW
1 MΩ	2.5 s	1.75 s	48 mW
1.2 MΩ	3.1 s	2.1 s	40 mW
1.5 MΩ	4.15 s	2.75 s	33 mW

[1] Power consumption of the combined X-cap discharge and start-up circuit at 230 V (AC).

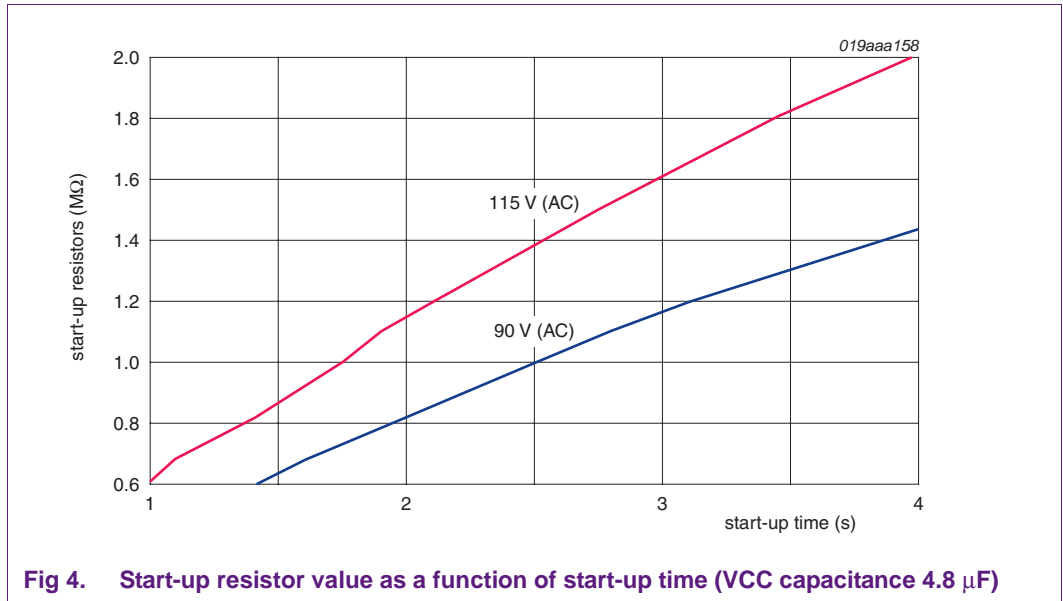


Fig 4. Start-up resistor value as a function of start-up time (VCC capacitance 4.8 μF)

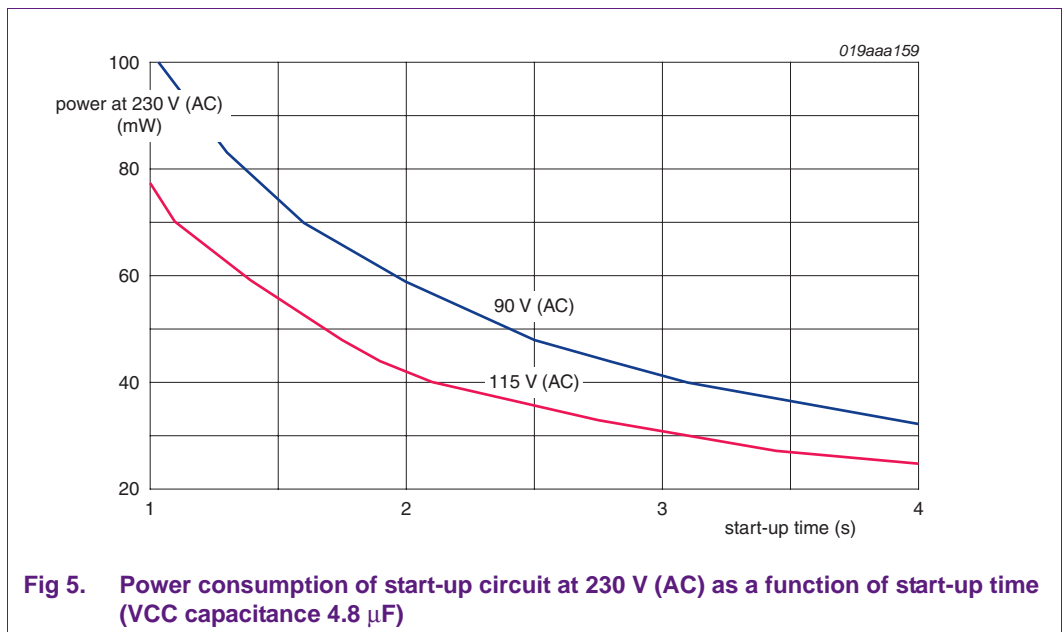


Fig 5. Power consumption of start-up circuit at 230 V (AC) as a function of start-up time (VCC capacitance 4.8 μF)

Figure 5 shows the power consumed by the combined start-up and X-cap discharge circuit as a function of the start-up time. The graph shows how to save power:

- More than 10 mW no-load power can be saved by increasing the start-up time (at 115 V (AC)) from 2 s to 3 s.
- Approximately 17 mW no-load power can be saved by specifying the start-up time at 115 V (AC) instead of 90 V (AC).

3.2.2 Measuring start-up time

Capacitance across the bridge diodes changes the wave shape of the voltage before the bridge rectifier with respect to the primary ground. This can significantly decrease the start-up time. Connecting the ground clip of an oscilloscope to the primary ground of the flyback converter can add a few nF across the bridge diodes (depending on the capacitance of the mains supply to ground).

To measure the correct worst case start-up time, make sure the board has no capacitive coupling to primary ground:

- Use a current probe in the mains input cable to detect mains switch-on.
- The same current probe in the mains input cable can also be used to detect when the supply starts switching. The time, from the moment the supply starts to switch until it reaches 90 % of the output voltage, is only a few ms and can be ignored with respect to the total start-up time. (If it is really required to measure the output voltage with an oscilloscope, the Y-cap must be removed so that there is no capacitive coupling to primary ground.)
- Use a resistor load instead of an electronic load. Remove Y-cap if electronic load must be used.

Also important when measuring the start-up time:

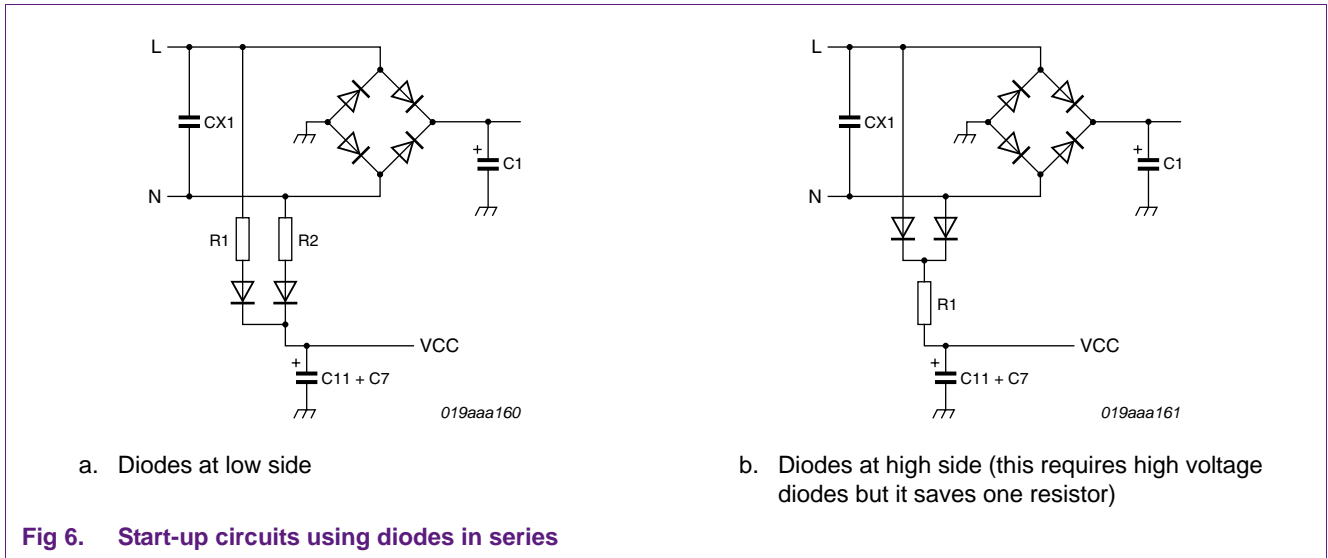
- Make sure the VCC capacitor is entirely discharged before starting a measurement.
- Do not connect a probe or multimeter to the VCC, even a 10 M Ω impedance will influence the measurement.

3.2.3 Start-up circuit with diodes

As explained in [Section 3.2.1](#), the start-up circuit with two resistors also has a disadvantage. Some current does not flow into the VCC capacitor but is lost in one of the resistors. This can be prevented by placing diodes in series with the resistors as shown in [Figure 6a](#) and [Figure 6b](#).

[Figure 6a](#) requires two resistors and two low voltage diodes. [Figure 6b](#) saves one resistor but requires two high voltage diodes.

At 90 V (AC), adding the diodes reduces the start-up time by approximately 20 % without increasing the no-load power consumption. (Approximately 10 % at 115 V.)



The diodes do not block the X-cap discharge path! The discharge of the X-cap takes place via R1 or R2 through the series diode to VCC. From VCC there are several paths to ground (even when the IC is in Power-down mode a clamp on the VCC pin is active). From ground it can find its return path to the X-cap through one of the bridge diodes.

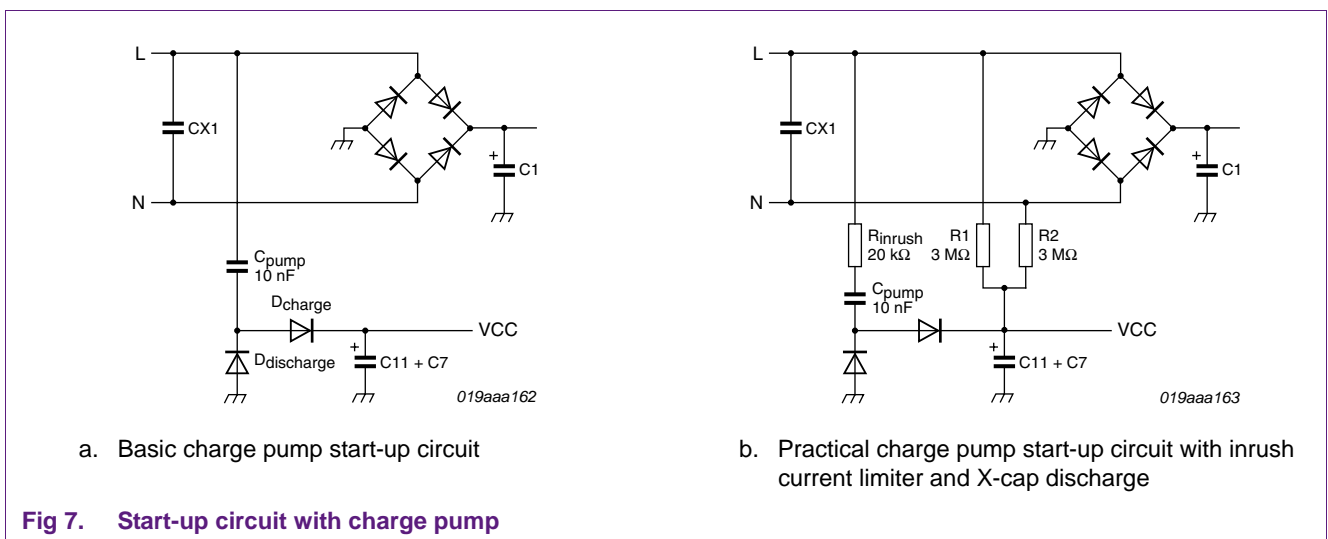
3.2.4 Start-up circuit with charge pump

If the no-load power requirements cannot be combined with the start-up time requirements, there is a more efficient way to decrease the start-up time using the charge pump circuit illustrated in [Figure 7a](#).

During the positive half of each mains cycle, current flows from L via C_{pump} and D_{charge} to the VCC capacitor. This process stops when C_{pump} is fully charged.

During the negative half mains cycle, C_{pump} is discharged: From C_{pump} via C1 to ground. From ground via $D_{discharge}$ back to C_{pump} .

Unlike in the resistor start-up circuit, no significant power is lost in the circuit itself.



The charge pump circuit does not provide a discharge path for the X-cap. An efficient way to provide the X-cap discharge path is to use the resistor start-up circuit because it not only discharges the X-cap but also helps to charge the VCC capacitor, see [Figure 7b](#).

- The value of R1 and R2 should be chosen as high as possible but low enough to comply with the X-cap discharge requirement: $R \times C < 1 \text{ s}$:
 - For a 330 nF X-cap: $R < 3 \text{ M}\Omega$
 - For a 220 nF X-cap: $R < 4.5 \text{ M}\Omega$
- The value of C_{pump} must be chosen just high enough to reach the start-up time target (start with 10 nF and increase or decrease for correct start-up value). It must be a high voltage capacitor.
- The purpose of the resistor R_{inrush} is to limit the inrush current when the supply is plugged in at the top of the sine wave. To minimize losses the value should be as low as possible but high enough to comply with the pulsed power rating of the resistor to survive the inrush current.
- For the diodes, any low voltage type will do (breakdown voltage $> 30 \text{ V}$).
- If the average start-up current at maximum input voltage exceeds the maximum current of the clamp on the VCC pin, $D_{\text{discharge}}$ should be replaced by a 24 V Zener diode.

CAUTION

The rated maximum voltage of the high-voltage bulk capacitor can be exceeded if it is overcharged by the charge pump.

Remark: This can occur in the latched off-state when the power consumption is very low. In that case the charge pump not only charges the VCC capacitor but also very slowly charges the high voltage bulk capacitor (C1) on the other side of the bridge rectifier. It has to be checked that in latched protection mode the charge pump does not charge the high voltage bulk capacitor above its rated voltage (check at maximum input voltage). There are two ways to solve the problem:

- Increase the load on the rectified mains voltage. (e.g. lower impedance of voltage divider on the VINSENSE pin.) Even if some load has to be added to the rectified mains voltage to prevent the charge pump damaging the high voltage bulk capacitor, the charge pump remains a more efficient solution than the resistor circuit.
- Another solution is to add an identical charge pump but connect its input to N instead of L (see [Figure 8](#)). In this case the value of C_{pump} can be divided by two.

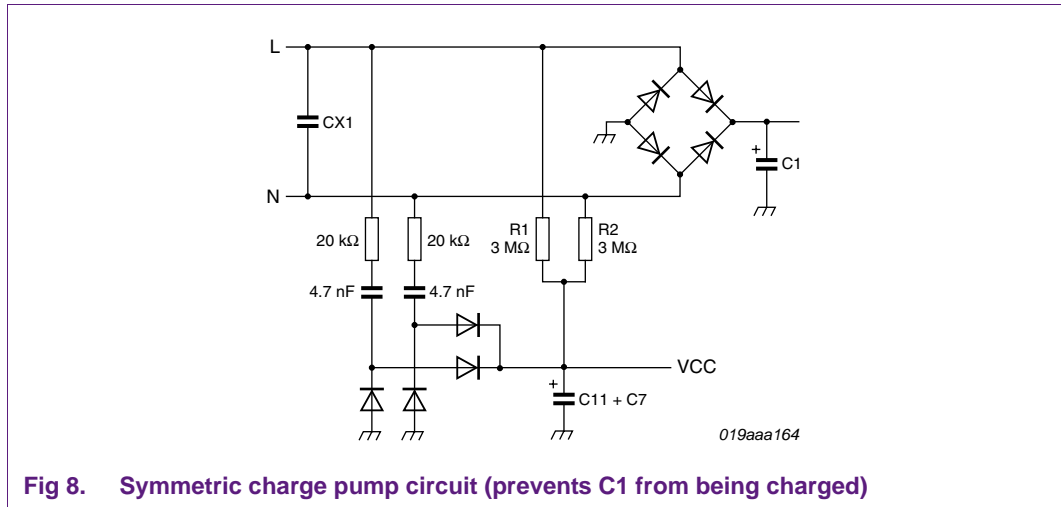


Fig 8. Symmetric charge pump circuit (prevents C1 from being charged)

3.2.4.1 Charge pump in combination with PFC

If a PFC (Power Factor Corrector) is used, the voltage on the bulk capacitor can be (much) higher than the rectified mains voltage. Under these circumstances, the start-up current provided by the charge pump can be reduced or even entirely stopped.

If a restart occurs during this condition, the start-up time can be very long. This can be solved by using a symmetrical charge pump.

3.2.5 VCC capacitor

The VCC capacitor should be as small as possible to make the start-up time as short as possible (and also the latch reset time).

First of all the value of the capacitor should be sufficient to supply the TEA1738 until the auxiliary winding can take over. This depends on the configured soft start time, the load on the output and the values of the secondary capacitors.

But usually the minimum value of the capacitor is determined by other factors, some worst case tests to determine the minimum value of the VCC capacitor are:

- No-load operation

The supply runs at low frequency so there is a long interval between two consecutive charge pulses from the auxiliary winding. V_{CC} should not drop near $V_{th(UVLO)}$ before the next cycle.
- Transient from full load to no load

A transient from full load to no load may cause a small overshoot on the output voltage. Because of the absence of any external load it may take a long time for the output capacitor to discharge to the level at which the supply starts to switch again.

During that time the VCC capacitor is not charged by the auxiliary winding. This overshoot can be limited by the following modifying loop: Add R25 and C17 in [Figure 1](#) at e.g. 3.9 kΩ and 1 nF respectively.

The VCC capacitor should be a low ESR type.

3.2.6 Start-up conditions

When the VCC pin reaches $V_{startup}$ (20.6 V typ.), the controller wakes up from Power-down mode and checks if the following conditions are met:

- The PROTECT pin must be between 0.5 V and 0.8 V.
- The VISENSE pin must be between 0.94 V and 3.52 V.
- The OPTIMER pin must be below 1.2 V.

If one or more of these conditions is not met, the controller will not switch. Due to the increased power consumption when the IC is switched on, the voltage on the VCC will eventually drop below $V_{th(UVLO)}$ and the IC will enter Power-down mode. The start-up circuit will charge the VCC capacitor and the cycle repeats itself.

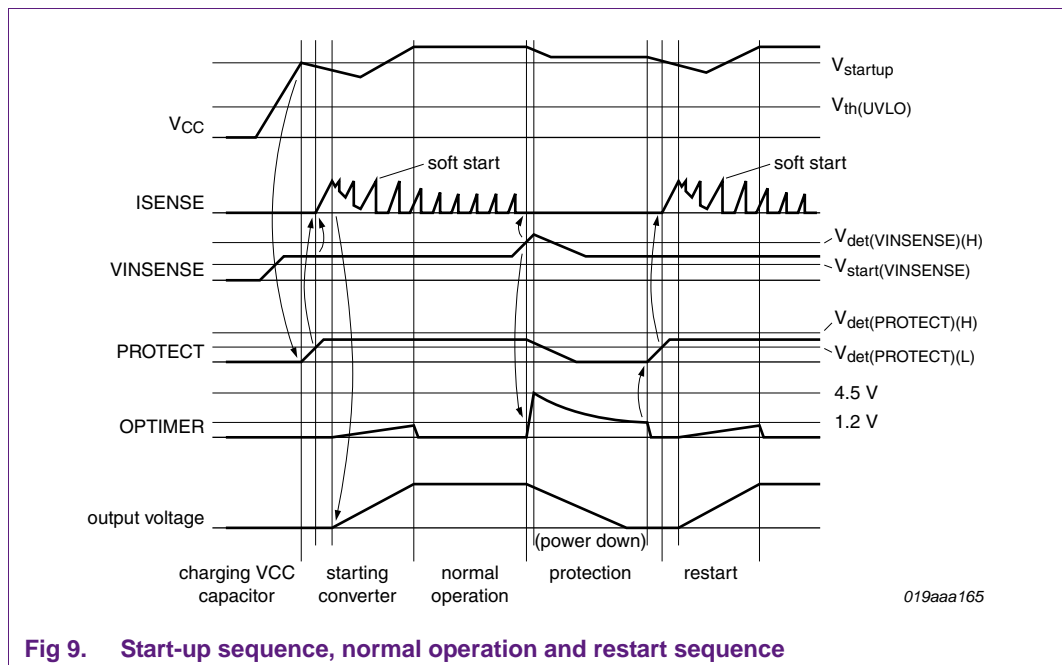


Fig 9. Start-up sequence, normal operation and restart sequence

3.2.7 Soft start

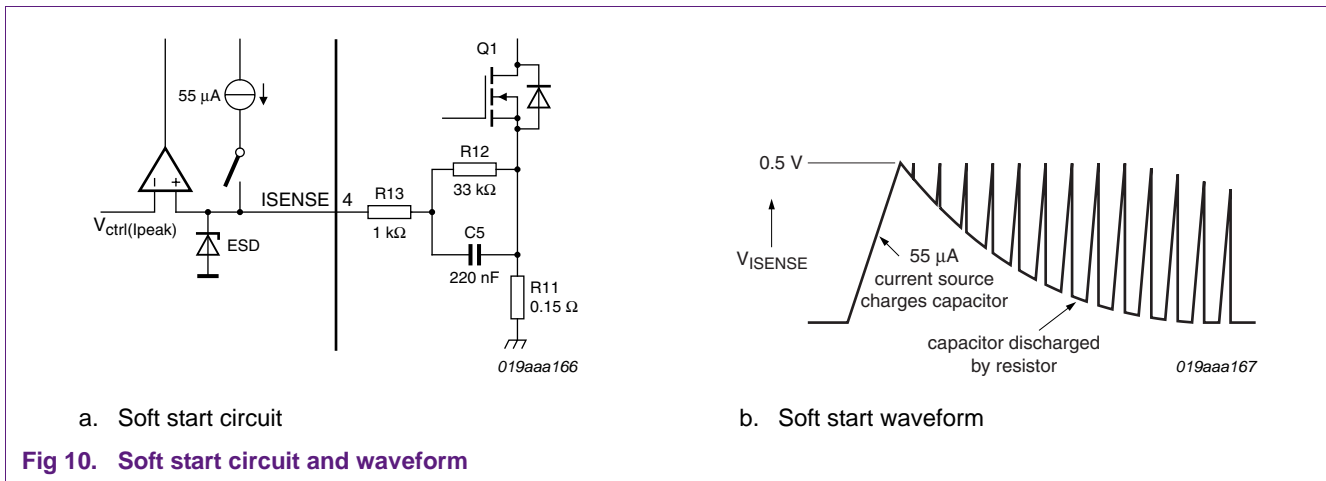
When all start-up conditions have been met, the IC charges the soft start capacitor by switching on a 55 μ A current source on the ISENSE pin. As soon as the ISENSE pin reaches the internal control voltage (which is 0.5 V when the output is still low), the current source is switched off and the controller starts to switch.

At start-up the output capacitors are still empty and the control input will ask for maximum peak current, increasing the primary duty cycle until V_{ISENSE} reaches 0.5 V. But because of the charged soft start capacitor, the voltage on V_{ISENSE} is already 0.5 V. As the soft start resistor discharges the soft start capacitor, the peak current slowly increases.

The purpose of the soft start is to avoid audible noise at start-up. Increasing peak current instantly from 0 A to maximum would be audible. A soft start duration of 4 ms is a good value for most applications.

The duration of the soft start can be configured by changing the value of the soft start capacitor. (Do not use the soft start resistor for this purpose as this resistor also configures the overpower compensation. It is better to first configure the overpower compensation and later change the soft start capacitor to obtain the required soft start time). The duration of the soft start is roughly equal to: $T_{start(soft)} = R_{start(soft)} \times C_{start(soft)}$.

$R_{start(soft)}$ must be a minimal 12 kΩ, otherwise the 55 μA current source is not be able to charge the capacitor to 0.5 V and the controller will not start switching.



The purpose of the extra series resistor R13 is to filter out negative spikes that would otherwise be rectified by the internal ESD protection diode, charging C5 and causing a positive offset voltage on the ISENSE pin.

For high output voltages, the peak current may show a short peak at the start. The empty output capacitors behave like a short circuit and the supply immediately goes into continuous conduction mode. During this peak the power is limited by the minimum on-time.

3.2.8 Safe restart

If a protection is triggered the controller stops switching. Depending on which protection is triggered and on the version of the IC, the protection causes a restart or latches the converter to an off-state. See [Section 3.3](#) for an overview of the protection features.

A restart caused by a protection quickly charges the OPTIMER pin to 4.5 V. The TEA1738 then enters Power-down mode until the capacitor on the OPTIMER pin has been discharged by the resistor on the OPTIMER pin to 1.2 V. During Power-down mode the power consumption is very low (10 μA) and the VCC pin is clamped to 21.6 V (which is just above $V_{startup}$) by an internal clamp circuit.

When the OPTIMER pin drops below 1.2 V and VCC is above the VCC start-up voltage (20.6 V), the controller wakes up from Power-down mode and does a normal start-up as described in [Section 3.2](#).

3.2.9 Clamps

The 21.6 V clamp on the VCC pin is only active during the restart delay. The purpose of the clamp is to keep the VCC pin just above $V_{start-up}$, so that after the restart delay the system will behave exactly like a normal start-up.

The 6 V clamp on the VCC pin is only active during latched off-state. The purpose of this clamp is to keep the VCC pin just above the latch reset level. This is to ensure a fast latch reset after unplugging the mains.

It is recommended to keep the clamp current below 0.73 mA. (So the start-up circuit should not be able to deliver more than 0.73 mA at maximum mains voltage.) Above a certain current, the clamp behaves like a current source: The voltage increases and the current remains constant.

If it is required to achieve a very fast start-up time, it should be checked that at the highest mains input voltage, the current during restart or latched off-state remains below 0.73 mA.

3.3 Input voltage sensing (VINSENSE pin)

3.3.1 General

For accurate input voltage sensing it is best to sense the input voltage after the bridge rectifier. The detection levels for start-up, brownout protection, and input OVP have been designed to be connected to the rectified mains voltage via resistor divider ratio 1:122, e.g. 10 MΩ and 82 kΩ. To filter out the ripple on the rectified mains voltage, a capacitor must be connected.

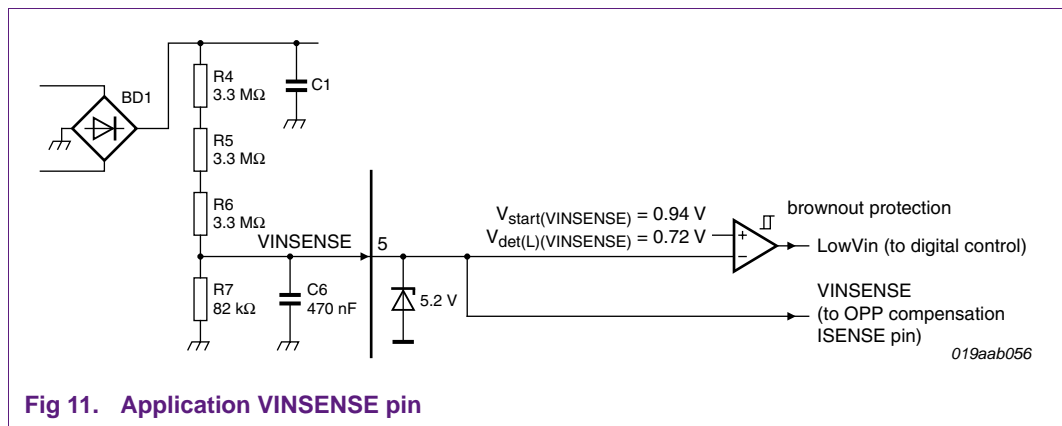


Fig 11. Application VINSENSE pin

Table 4. Detection levels VINSENSE pin
Voltage divider as in [Figure 7](#): $3 \times 3.3\text{ M}\Omega$ and $82\text{ k}\Omega$.

VINSENSE pin detection voltages	V_{mains} (V (RMS))	Condition	V_{bulk} (average V(DC))	VINSENSE pin (V (DC))
$V_{start(VINSENSE)}$	80	no load ^[2]	111	0.94
$V_{det(L)(VINSENSE)} = \text{brownout}$	61	0 V ripple on V_{bulk} ^[3]	88	0.72
	68	20 V ripple on V_{bulk}	88	0.72
	71	30 V ripple on V_{bulk}	88	0.72
	75	40 V ripple on V_{bulk}	88	0.72

- [1] At full load there will be a ripple on V_{bulk} but because of the high input voltage this ripple will be very low. The mains input detection level at full load will be approximately 5 V higher.
- [2] The $V_{\text{start(VINSENSE)}}$ level is only relevant when the supply is not running. In that case there is no load on V_{bulk} and there will be no ripple.
- [3] The brownout detection level depends on the load. At a lower load it allows a lower mains input voltage. This is not a problem because at a lower load the input current is also lower.

For slightly different detection levels the ratio of the resistor divider can be changed. Increasing the division factor to 133 ($3 \times 3.3 \text{ M}\Omega$ and $75 \text{ k}\Omega$) results in:

- Start level = 87 V (RMS)
- Brownout level = 77 V (RMS) (at 30 V ripple on V_{bulk})

3.3.2 Start-up voltage

The controller should not start up if the mains voltage is too low. If VINSENSE is below $V_{\text{start(VINSENSE)}}$ (0.94 V typ.) the supply will not start. There is 220 mV hysteresis on this level, so once the IC is switched on, it does not stop until VINSENSE is lowered below $V_{\text{det(L)(VINSENSE)}}$ (0.72 V typ.).

3.3.3 Brownout protection

When the voltage on the VINSENSE pin drops below 0.72 V, the brownout protection is activated. The controller immediately stops switching and initiates a safe restart (valid for all TEA1738 versions).

3.3.4 Overpower compensation

The VINSENSE pin is also used to provide the input voltage information needed for the overpower compensation. The voltage is translated into a small current and injected on the ISENSE output. On the ISENSE output the current is converted into a voltage across a series resistor. At a high input voltage it creates an offset voltage on the ISENSE pin, limiting the maximum peak current. See [Section 3.5](#) for more about the OPP.

3.3.5 Filter capacitor

A capacitor (C6 in [Figure 11](#)) directly on the VINSENSE pin filters out the mains ripple. For a time constant of a few 100 Hz cycles (e.g. 40 ms), so the capacitor value should be:

$$C6 > \frac{40 \text{ ms}}{R7} .$$

The capacitor also prevents the supply switching off when the rectified mains voltage temporarily drops below the brownout level during a short (5 ms or 10 ms) mains interruption.

3.3.6 Clamp

An internal clamp protects the pin against input voltages that are too high. The clamp voltage is 5.2 V at 50 μA . The clamp voltage remains unchanged during power-down. (The clamp voltage only drops when V_{CC} drops below 5 V.)

3.4 Protection features

3.4.1 General

[Table 5](#) shows which protection features lead to a safe restart and which to a latched off-state. See [Section 3.2.8](#).

Table 5. Protection handling TEA1738 series

Protection	T	FT and GT	LT
Brownout (VINSENSE pin LOW)	restart		latch
Maximum on-time protection	restart	no action	restart
OTP (internal)	latch		
OPP (OPTIMER pin)	restart		latch
OVP (internal)	latch		
OVP (PROTECT pin HIGH)	latch		
OTP (PROTECT pin LOW)	latch		
UnderVoltage LockOut (UVLO)	restart ^[1]		latch

[1] Switches off and waits in Power-down mode until V_{CC} rises above $V_{startup}$. This is not the same as safe restart procedure.

3.4.2 Brownout protection

When the mains input voltage is too low (and with full load), the primary current increases, causing increased losses in many of the primary components. The purpose of the brownout protection is to protect the supply against overheating at input voltages that are too low.

When the mains voltage becomes too low (VINSENSE drops below 0.72 V), the brownout protection is activated. The controller immediately stops switching and performs a safe restart (valid for all TEA1738 versions). See [Section 3.3](#) for application of the VINSENSE pin.

3.4.3 Maximum on-time protection (TEA1738T/TEA1738LT)

If a switching cycle does not reach the peak current set by the CTRL pin, the driver pulse will be ended by the maximum on-time. If this happens eight times in a row, the maximum on-time protection triggers a restart.

As an extra measure against false triggering, the protection can only be activated during overpower power ($V_{ISENSE} > 400$ mV).

The purpose of this protection is to ensure a well defined response to mains supply dips.

3.4.4 Internal OverTemperature Protection (Internal OTP)

When the temperature in the chip rises to above 140 °C, the internal OTP sets the controller to the latched off-state (in all TEA1738 versions).

3.4.5 OverPower Protection (OPP)

When the rated output power is continuously exceeded for an adjustable duration, the OPP is activated. The controller immediately stops switching and performs a safe restart or enters the latched off-state, depending on the version. See [Section 3.5](#) for more about OPP.

3.4.6 Internal output OverVoltage Protection (Internal OVP)

An internal OverVoltage Protection sets the IC to latched off-state when the voltage on the VCC pin exceeds 30 V for eight consecutive switching cycles.

It is also possible to implement an external OVP with a lower threshold value by adding a circuit to the protection pin (e.g. Zener from VCC to protection pin).

3.4.7 External output OverVoltage Protection (External OVP)

The purpose of the OVP is to protect the devices connected to the output but also the supply itself against output voltages that are too high (e.g. when the voltage feedback loop is disturbed).

If an overvoltage at the output occurs, the application pulls the PROTECT pin above 0.8 V and the OVP is activated. The controller immediately stops switching and enters the latched-off state (in all TEA1738 versions). See [Section 3.8](#) for how to apply the PROTECT pin.

Connection of an external OVP application is only required if the threshold voltage needs to be lower than 30 V or extra filtering is required. Without external OVP application the fixed internal OVP will latch the IC when VCC exceeds 30 V.

3.4.8 External OverTemperature Protection (External OTP)

When the temperature in the supply rises above the rated level, the application pulls the PROTECT pin below 0.5 V and the OTP is activated. The controller immediately stops switching and enters the latched-off state (in all TEA1738 versions). See [Section 3.8](#) for how to apply the PROTECT pin.

3.4.9 Latched protection

When one of the protection features triggers the latched off-state, the IC immediately stops switching and enters Power-down mode. It clamps the VCC pin to 6 V, which is just above the reset level (5 V).

3.4.10 Resetting a latched protection

In order to reset a latched protection, the VCC pin should be brought below 5 V.

If a latched protection is triggered, the VCC pin is automatically clamped to a voltage just above the reset level. As soon as the mains is unplugged, the start-up current stops and the VCC capacitor is discharged by the 10 μ A supply current to the TEA1738. Because it only has to be discharged from 6 V to 5 V it resets quite fast.

With $C_{VCC} = 4.7 \mu\text{F}$ the discharge time is 0.47 s (In practice the start-up current does not always immediately stop charging the VCC capacitor after unplugging the mains because the X-cap may still be charged for about one second).

3.4.11 UnderVoltage LockOut (UVLO)

Restart versions (TEA1738T, TEA1738FT, TEA1738GT) — When during normal operation the VCC voltage drops below the undervoltage lockout threshold ($V_{th(UVLO)} = 12.2 \text{ V typ.}$), the IC stops switching and enters Power-down mode. The VCC pin is clamped to 21.6 V (typ.) by an internal clamp circuit. The start-up circuit will charge the VCC capacitor and a normal start-up sequence follows.

A restart caused by undervoltage lockout is not exactly the same as a restart caused by one of the other protection features. It will not trigger the restart delay (so it will not charge the OPTIMER capacitor and waits until it is discharged again).

Latch version (TEA1738LT) — When during normal operation VCC drops below the undervoltage lockout threshold, the IC is set to the latched protection mode. This ensures that a shorted output always triggers the latched protection mode, also if VCC drops below $V_{th(UVLO)}$ before the OPP has a chance to respond.

3.5 OverPower Protection (OPP)

3.5.1 Continuous and temporary output power limitation

The TEA1738 has two mechanisms to protect against overload:

- Overpower protection
Overpower protection performs a safe restart (or enters the Latched protection mode in the latched version) if the rated power is continuously exceeded. OPP is delayed to allow temporary overloads.
- Cycle by cycle primary inductor current limitation
Peak current limitation prevents the core from going into saturation and thus the MOSFET from currents that are too high.

3.5.2 How the OPP operates

When the internal control voltage exceeds the overpower threshold (400 mV on the ISENSE pin), the overpower timer is activated (see [Figure 16 on page 29](#) and [Figure 20 on page 31](#)). An internal 10.7 μA current source charges the external capacitor on the OPTIMER pin. When the overpower condition lasts long enough to charge the OPTIMER pin to 2.5 V, the controller carries out a safe restart procedure (or enters Latched protection mode in the latched version). If the internal control voltage drops below 400 mV before the OPTIMER pin reaches 2.5 V, the OPTIMER capacitor is immediately discharged. The minimum recommended value for OPTIMER resistor is 470 k Ω (otherwise there is a chance that 10.7 μA is not sufficient to charge the capacitor to 2.5 V).

3.5.3 Peak current limitation (OCP)

When the voltage on the ISENSE pin exceeds 500 mV the current switching cycle is immediately ended. When the OCP limits the peak current, the output voltage can no longer be maintained. The converter will continue to switch until the OPP is triggered or until V_{CC} has dropped below $V_{th(UVLO)}$.

3.5.4 Input voltage compensation

In fixed frequency DCM the peak current limitation can also act as overpower protection because the maximum output power is independent of the input voltage. But in fixed frequency CCM the maximum amount of power that can be transferred to the output does not only depend on the primary peak current but also on the duty cycle and therefore also on the input voltage.

The TEA1738 has built-in input voltage compensation to ensure accurate overpower protection, independent of the input voltage. It has been implemented by making the current sense signal dependent on the input voltage measured on the VINSENSE pin.

The input voltage measured on the VINSENSE pin is internally converted to a current and injected in the ISENSE pin. The current flows through the external series resistor R12 (see [Figure 1](#)) on the ISENSE pin, converting it to a voltage. The value of the series resistor should be tuned in such a way that the maximum power becomes independent of the input voltage.

3.5.5 How to configure the current sense resistor

Before the correct value of the current sense resistor can be calculated, the maximum primary peak current must be calculated. This is done with [Equation 2](#) or [Equation 3](#).

In DCM mode:

$$I_{peak, DCM} = \sqrt{\frac{2P_o}{\eta \times L \times f_{sw}}} \quad (2)$$

In CCM mode:

$$I_{peak, CCM} = \frac{P_o}{\eta} \times \frac{V_i + NV_o}{V_i \times NV_o} + \frac{I}{2L \times f_{sw}} \times \frac{V_i \times NV_o}{V_i + NV_o} \quad (3)$$

Where:

- I_{peak} is the peak current
- P_o is the maximum continuous output power
- η is the expected efficiency of the flyback at maximum output power
- V_i is the minimum input voltage ($= \sqrt{2} \times$ the minimum mains voltage) at which the supply must be able to deliver the maximum continuous output power²
- N is the winding ratio of the coil
- V_o is the output voltage
- f_{sw} is the switching frequency, in this case 63 kHz (the "high power" area of the frequency curve, see [Figure 18](#))

Now the (maximum) current sense resistor value can be calculated with [Equation 4](#):

$$R_{ISENSE} = \frac{V_{th(sense_opp)}}{I_{peak}} = \frac{400\text{ mV}}{I_{peak}} \quad (4)$$

Where:

- I_{peak} is the peak current

Another way to determine the correct value for the sense resistor is by trial and error:

1. Connect a load to the output and set the load to the rated maximum continuous output power of the application.
2. Apply the minimum mains voltage at which the supply must be able to deliver the maximum continuous output power.

2. The peak current will be larger during the valley of the mains ripple. So during the majority of the time $I_{peak} \times R_{ISENSE}$ exceeds $V_{th(sense_opp)}$. This is will however not trigger the OPP because each 100 Hz or 120 Hz cycle during the top of the ripple $I_{peak} \times R_{ISENSE}$ will be just below $V_{th(sense_opp)}$ and this discharges the OPTIMER capacitor.

3. Increase the current sense resistor until the supply keeps running and the OPTIMER pin remains just below 2.5 V.

3.5.6 Calculating the maximum temporary output power

The maximum temporary peak current can now be calculated with [Equation 5](#):

$$I_{peak(max)} = \frac{V_{sense(max)}}{R_{ISENSE}} = \frac{500\text{ mV}}{R_{ISENSE}} \quad (5)$$

Where:

- $I_{peak(max)}$ is the maximum peak current

Now the maximum temporary output power can be calculated³.

In DCM mode:

$$P_{out(max),DCM} = \eta \times IZ \times L \times I_{peak(max)}^2 \times f_{sw} \quad (6)$$

Where:

- $I_{peak(max)}$ is the maximum peak current

In CCM mode:

$$P_{out(max),CCM} = \eta \times \frac{V_i \times NV_o}{V_i + NV_o} \times I_{peak(max)} \times \frac{V_i \times NV_o}{2L \times f_{sw} \times (V_i + NV_o)} \quad (7)$$

Where:

- $I_{peak(max)}$ is the maximum peak current
- f_{sw} is the switching frequency, in this case 78 kHz (the "peak power" area of the frequency curve, see [Figure 18](#))

This is the maximum temporary output power at which the output voltage remains intact.

V_i is the value of the rectified mains voltage during the valley of the ripple.

If the temporary output power is not high enough, the only way to increase it is by decreasing the current sense resistor value. This also increases the maximum continuous output power.

3.5.7 How to configure the OPP compensation ($R_{start(soft)}$)

Once the current sense resistor value has been determined, the soft start resistor can be tuned to obtain equal maximum output power for low and high mains.

The relationship between the voltage on the VINSENSE pin and the resulting compensation current out of the ISENSE pin is fixed in the chip (see [Figure 12](#)):

$$I_{OPP} = 0.71 \times 10^{-6} \times V_{VINSENSE} - 0.43 \times 10^{-6} \quad 0.71 \times 10^{-6} \times V_{bulk(av)} - 0.43 \times 10^{-6} \quad (8)$$

3. Calculating the maximum temporary output power is complicated because it depends on the mains ripple on the bulk capacitor, which itself depends on the output power.

Where:

- $V_{VINSENSE}$ is the voltage on the VINSENSE pin
- $V_{bulk(av)}$ is the average rectified mains voltage
- K is the ratio of the resistor divider on the VINSENSE pin (around 1 : 122 for universal mains)

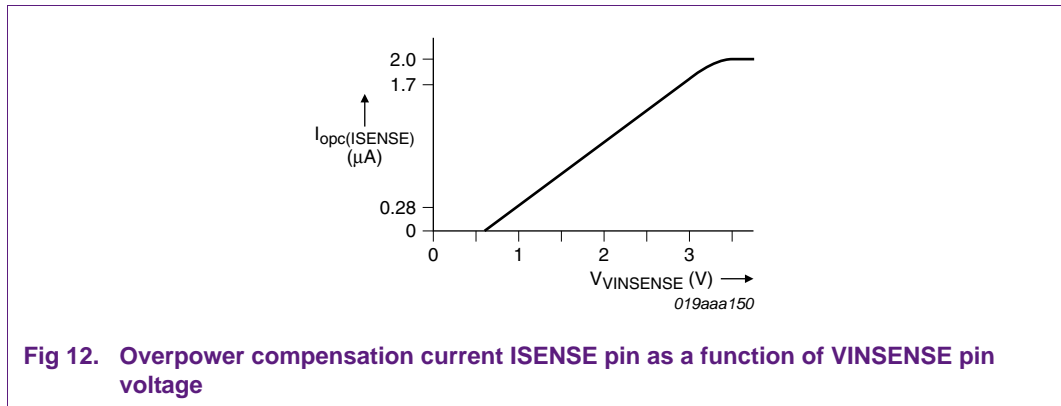


Fig 12. Overpower compensation current ISENSE pin as a function of VINSENSE pin voltage

The resulting peak current reduction (ΔI_{peak} in equation) can be calculated with [Equation 9](#):

$$\Delta I_{peak} = \frac{I_{opc(ISENSE)} \times R_{start(soft)(tot)}}{R_{ISENSE}} \tag{9}$$

$$= \frac{(0.71 \times 10^{-6} \times K \times V_{i(av)}) - 0.43 \times 10^{-6} \times R_{start(soft)(tot)}}{R_{ISENSE}}$$

Where:

- ΔI_{peak} is the peak current reduction
- $R_{start(soft)(tot)}$ is the total resistance from the ISENSE pin to the current sense resistor (R12 + R13 in [Figure 1](#))
- R_{ISENSE} is the value of the current sense resistor (R11 in [Figure 1](#))
- K is the ratio of the resistor divider on the VINSENSE pin (e.g. 1 : 122)

[Section 3.5.5](#) describes how to calculate the peak current and the resulting output power without input voltage compensation. To calculate the output power with input voltage compensation, the ΔI_{peak} must be subtracted from the peak current before calculating the maximum output power.

Although it should be possible to calculate⁴ the optimal value of the soft start resistor, it is probably faster to tune it in the application.

1. Connect a load and set it to the rated maximum continuous output power of the flyback converter.
2. Apply the highest rated input voltage (usually 264 V (AC)).

4. Exact calculation is complicated because the VINSENSE pin measures the average bulk voltage but the maximum continuous output power depends on the top of the ripple.

3. Increase the soft start resistor value until the voltage on the OPTIMER pin almost exceeds 2.5 V (e.g. start with 15 k Ω).

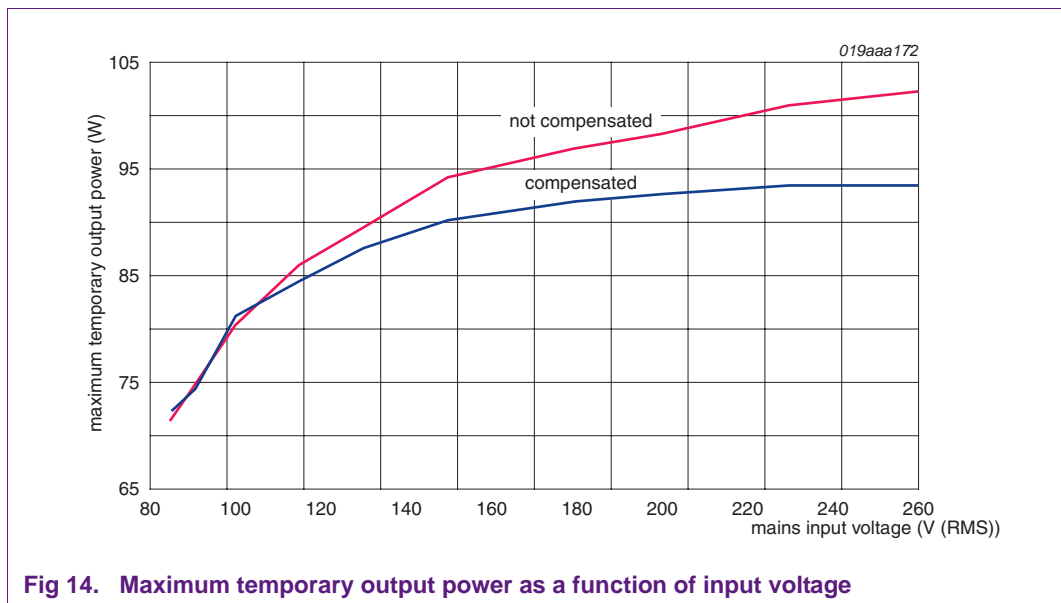
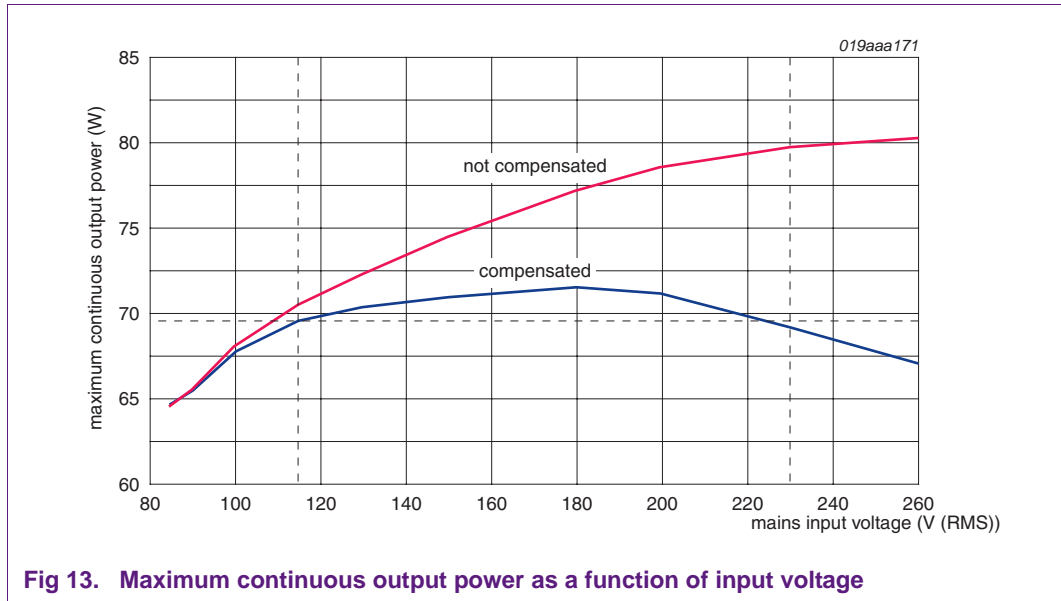
Now the maximum output power at the minimum and the maximum input voltage should be exactly the same.

Remarks:

- The value of the total soft start resistance (the sum of R12 and R13) should not be lower than 12 k Ω , otherwise the 55 μ A current source may not be able to charge the soft start capacitor to 0.5 V during start-up.
- Changing the soft start resistor value also slightly influences the maximum output power at absolute minimum input voltage. So after configuring $R_{\text{start(soft)}}$ it should be checked if it is necessary to retune the current sense resistor.
- The output power as a function of the input voltage is not a linear function (see [Figure 13](#)). When the maximum output power has been tuned to be equal for the absolute highest and lowest input voltage, the actual maximum output power will be slightly higher between these limits.

Another way to configure the compensation is to tune it in such a way that the maximum output power at nominal low mains (115 V) is exactly equal to the maximum output power at high mains (230 V). In that case the maximum output power will be exactly right at the nominal input voltages, somewhat lower at the absolute minimum and maximum input voltage and somewhat higher between the high and low nominal input voltage.

- For accurate overpower compensation it is best to connect the VINSENSE input voltage after the bridge rectifier.
- At low input power, the OPP compensation is switched off so that the minimum peak current is not influenced by the OPP compensation current.
- The maximum temporary output power also depends on the input voltage. When the OPP compensation has been configured optimally for the maximum continuous output power, it will not be compensated optimally for the maximum temporary output power. See [Figure 14](#).



3.5.8 How to disable the OPP compensation (for DCM)

In DCM, the maximum output power does not depend on the mains voltage, so there is nothing to be compensated.

The obvious way to disable the OPP compensation would be to reduce the soft start resistor to 0 Ω, but that would cause a problem at start-up: The total soft start resistance (the sum of R12 and R13) should be at least 12 kΩ, otherwise the 55 μA current source may not be able to charge the soft start resistor to 0.5 V during start-up.

The only way to disable the OPP compensation is to clamp the VINSENSE pin as shown in [Figure 12](#). Instead of clamping it to 3 V it should be clamped to e.g. 1.2 V so that the clamp disables most of the OPP compensation without influencing the start-up and brownout detection levels on VINSENSE. Of course this also disables the input OVP. (To clamp at approximately 1.2 V: R6a = 1.8 MΩ, R6b = 1.6 MΩ).

3.5.9 OPP delay and restart delay

If a shorted output occurs, the supply keeps switching on and off (only valid for the non-latched version). The ratio of the on-time and off-time can be manipulated to control the maximum average output power. Both timings are defined at the OPTIMER pin. See [Section 3.7 on page 31](#) for OPTIMER pin information.

3.5.10 Disabling the overpower protection

If the OPP is not appreciated it can be disabled by connecting a 180 kΩ resistor from the OPTIMER pin to ground. Because of the 180 kΩ resistor, the 10.7 μA current source of the OPP is not able to charge the capacitor to 2.5 V anymore ($10.7 \mu\text{A} \times 180 \text{ k}\Omega = 1.9 \text{ V}$).

The 180 kΩ resistor also influences the restart delay, but this can be compensated by choosing a higher OPTIMER capacitor value.

It is not recommended to reduce the resistor value below 100 kΩ, so that the internal 107 μA current source is always able to charge the OPTIMER pin to 4.5 V in case of a restart event.

3.5.11 Leading edge blanking

The ISENSE input is internally blanked for the first 300 ns of each switching cycle to prevent the spike caused by parasitic capacitance (gate-source capacitance of the MOSFET and the parasitic capacitance of the transformer) triggering the peak current comparator prematurely.

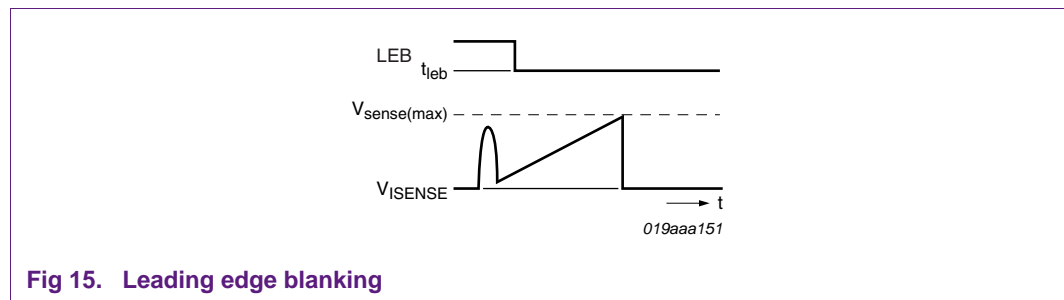


Fig 15. Leading edge blanking

3.6 CTRL pin

3.6.1 General

The CTRL pin controls the amount of output power, this is done by changing both the peak current and the switching frequency, see [Figure 18](#).

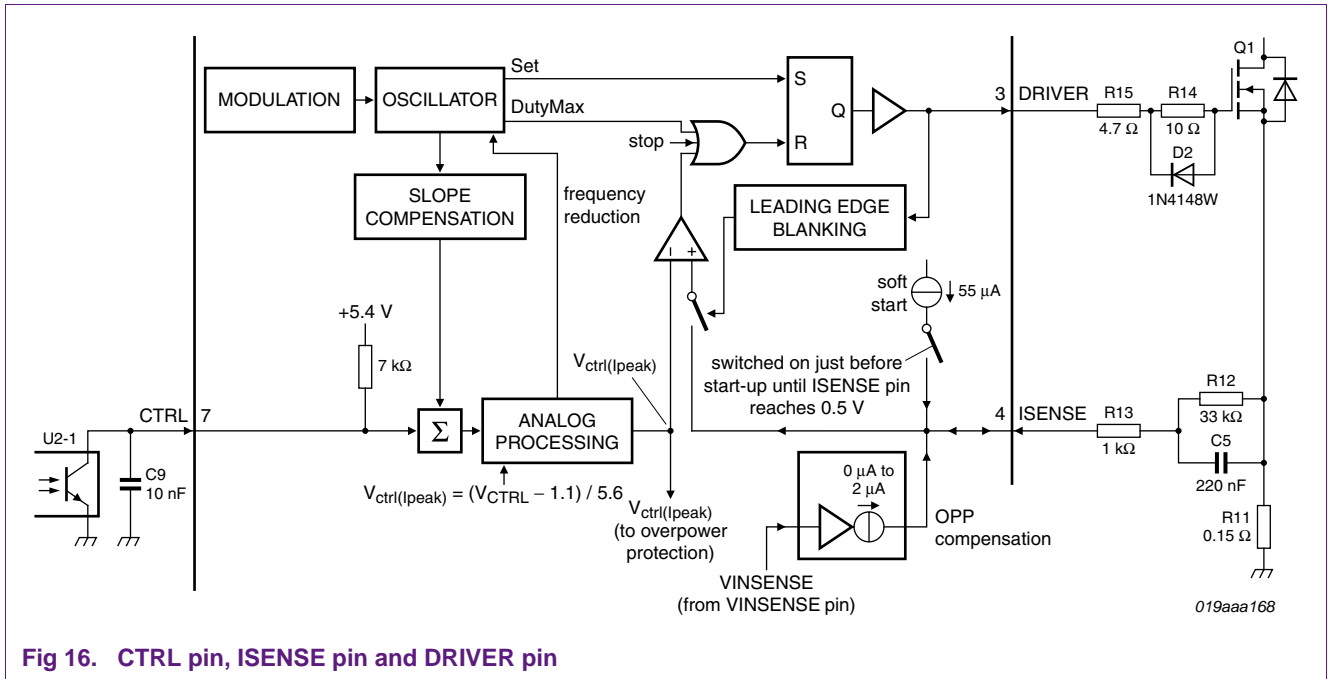


Fig 16. CTRL pin, ISENSE pin and DRIVER pin

3.6.2 Input biasing

An internal resistor of 7 kΩ connected to 5.4 V enables direct connection of an optocoupler transistor without any external components, to convert the output current of the optocoupler into the control voltage. The relationship between the CTRL pin current and CTRL pin voltage can be calculated with Equation 10 (see Figure 17).

$$V_{CTRL} = 5.4 V - 7 \times 10^3 \times I_{OCTRL} \tag{10}$$

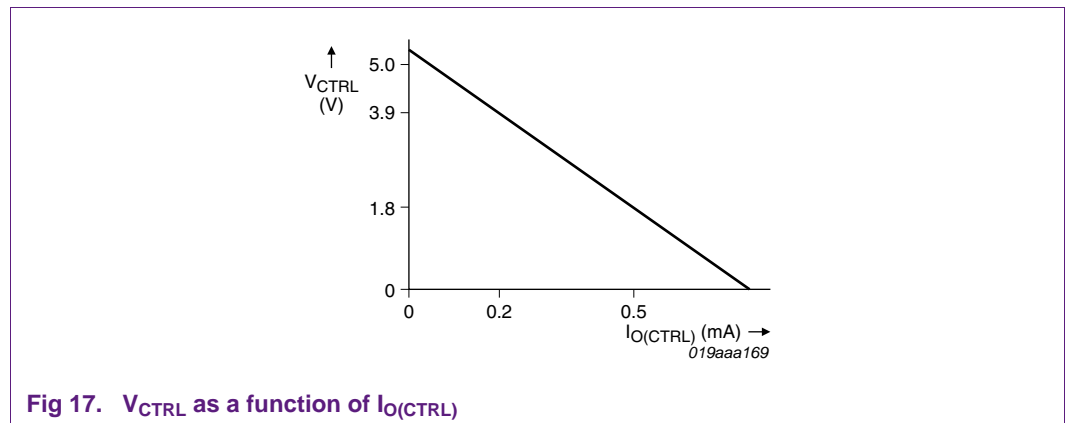


Fig 17. V_{CTRL} as a function of I_{O(CTRL)}

3.6.3 Peak current control

The CTRL voltage sets the primary peak current. The primary current is measured by the ISENSE pin and is compared to the peak current set by the CTRL pin. As soon as the primary peak current measured by the ISENSE pin exceeds the limit set by the CTRL pin, the DRIVER output is switched LOW. The relationship between CTRL input and ISENSE output is calculated with Equation 11.

$$V_{ctrl(lpeak)} = \frac{V_{CTRL} - 1.1}{5.6} \tag{11}$$

See [Figure 18](#).

3.6.4 Frequency control

Frequency reduction at medium power — To ensure efficient operation at medium output power, the frequency for medium output power is reduced to 26.5 kHz. This frequency reduction decreases the switching losses. The frequency is still well above the audible spectrum preventing audible noise.

Frequency reduction at low power — To ensure efficient operation at low output power, the peak current cannot be reduced below 25 % of its maximum value. Instead, to reduce the output power, the switching frequency is reduced. See [Figure 18](#).

It is important to use the entire CTRL pin input range. If the chosen current sense resistor value is too low, only the lower part of the control curve is used. This means that frequency reduction already starts at a relatively high peak current which may result in audible noise.

If overpower protection is not appreciated (e.g. because it is handled by a secondary IC), it can be disabled (see [Section 3.5.10](#)). So if the overpower protection is not used, it is still possible to use the full input range of the CTRL input.

Frequency increase at peak power — At peak power, the switching frequency is increased to enable higher output power from the same core. This also increases the switching losses but this is usually irrelevant during temporary peak loads. For maximum benefit of the frequency increase, the supply must operate (mainly) in DCM, (in CCM mode, the frequency increase does not have much influence).

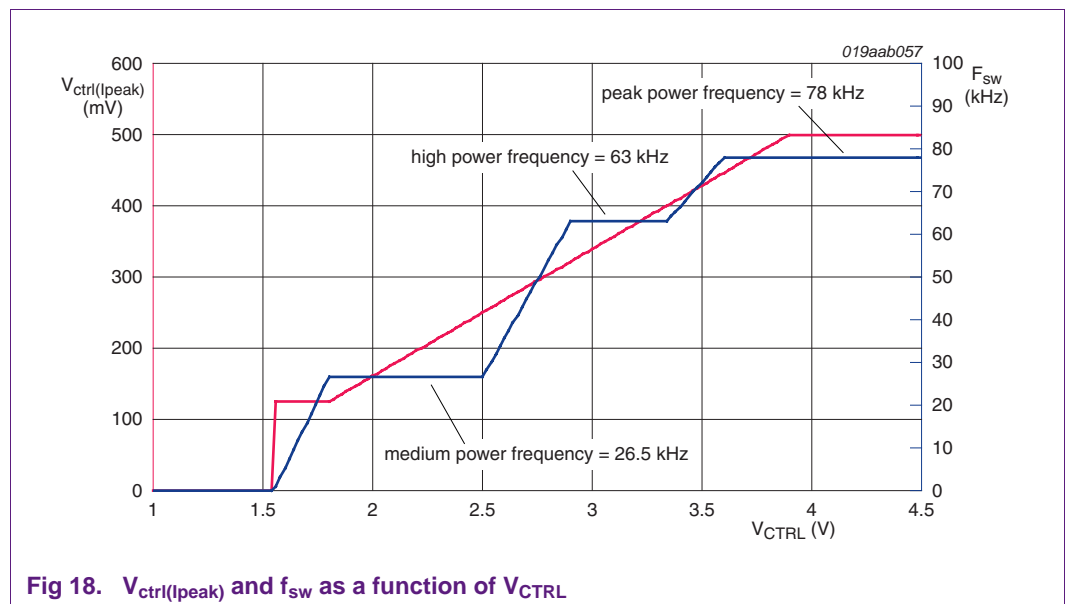


Fig 18. V_{ctrl(lpeak)} and f_{sw} as a function of V_{CTRL}

Remark: The peak power frequency of TEA1738GT is 118 kHz instead of 78 kHz.

3.6.5 Slope compensation

To prevent subharmonic oscillation in CCM mode at duty cycles above 50 %, the TEA1738 has built-in slope compensation. The slope compensation is internally added to the CTRL input signal (see Figure 19). Referred to the ISENSE pin, the amount of slope compensation is 19 mV/μs. The slope compensation is only active on duty cycles higher than 45 %.

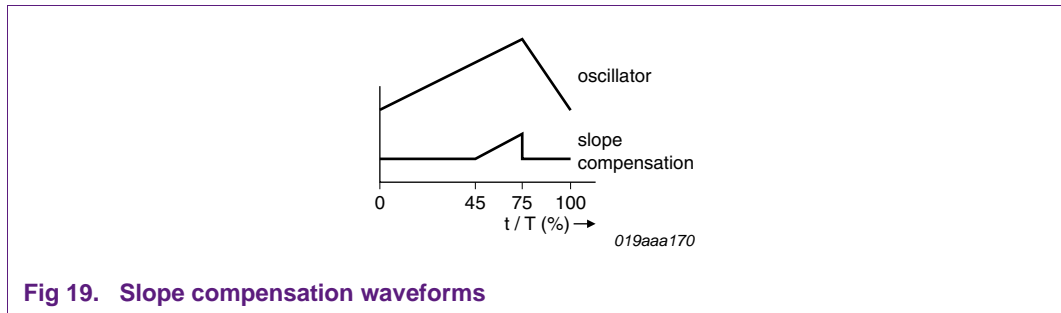


Fig 19. Slope compensation waveforms

3.7 OPTIMER pin

3.7.1 Overpower delay and restart delay

The OPTIMER pin provides two different time constants for:

- OPP delay (the time from exceeding the power limit to triggering the protection)
- Restart delay (the time from triggering the protection until the next restart attempt)

Both timer functions can be more or less independently adjusted. The ratio of these times determines the maximum power that can be delivered when the supply is continuously restarting, e.g. if the output is shorted.

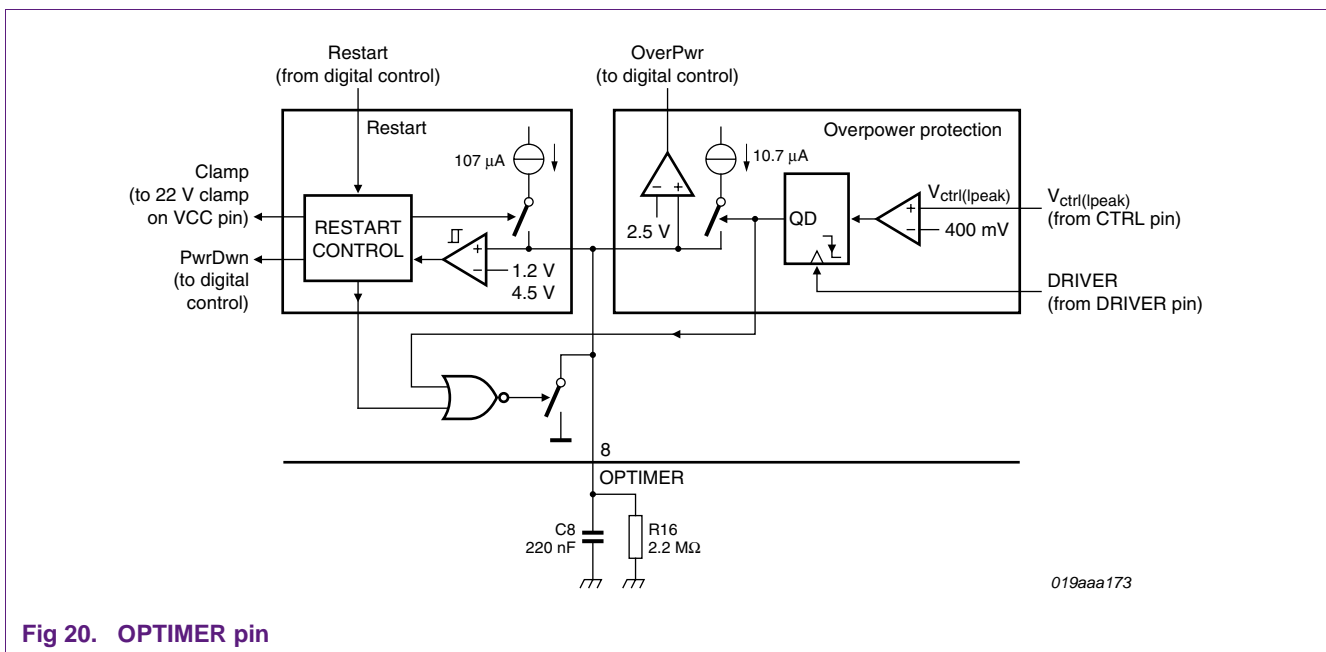


Fig 20. OPTIMER pin

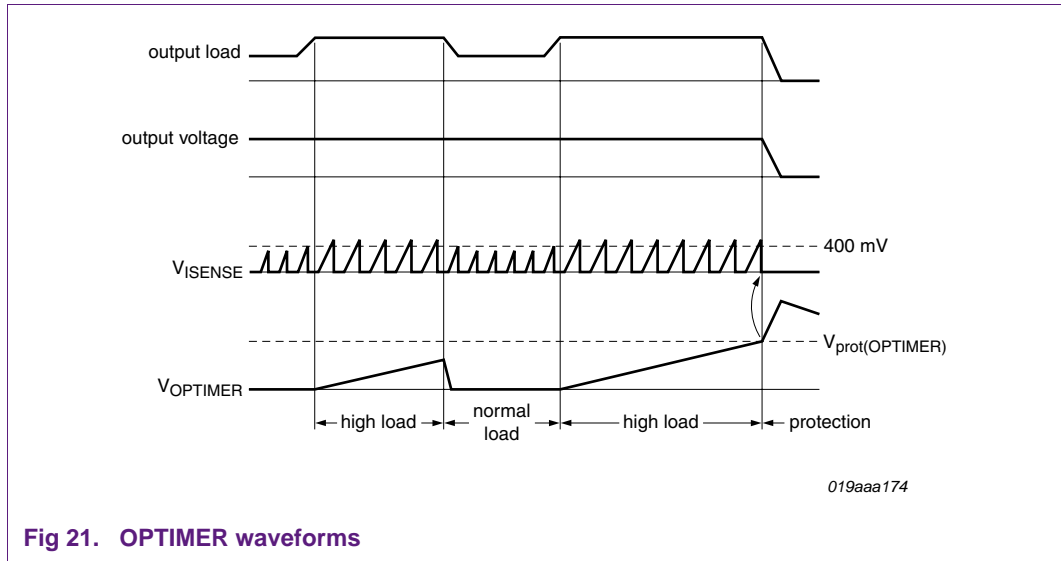


Fig 21. OPTIMER waveforms

3.7.2 Overpower delay

When the internal control voltage exceeds the overpower threshold of 400 mV, the overpower timer is activated (see Figure 20). An internal 10.7 μA current source charges the external OPTIMER capacitor (C8). When the overpower condition lasts long enough to charge the OPTIMER pin to 2.5 V, the controller carries out a safe restart procedure (or enters Latched protection mode in the latched version). If the internal control voltage drops below 400 mV before the OPTIMER pin reaches 2.5 V, the OPTIMER capacitor is immediately discharged. The minimum recommended value for the OPTIMER resistor (R16) is 470 kΩ (otherwise there is a chance that 10.7 μA is not sufficient to charge the capacitor up to 2.5 V). The OPP attack time can be calculated with Equation 12.

$$T_{OPP} = -R \times C \times \ln\left(1 - \frac{V_{prot(OPTIMER)}}{R \times I_{n(OPTIMER)}}\right) = -R \times C \times \ln\left(\frac{2.5 \text{ V}}{R \times 10.7 \mu\text{A}}\right) \tag{12}$$

Where R = R_{OPTIMER} (R16) and C = C_{OPTIMER} (C8).

3.7.3 Restart delay

When a safe restart procedure is triggered by one of the protection features (via the VINSENSE pin or the OPTIMER pin), the OPTIMER capacitor will be quickly charged to 4.5 V by an internal 107 μA current source. The TEA1738 enters Power-down mode and does not start again until the external resistor on the OPTIMER pin has discharged the capacitor to below 1.2 V.

The restart time consists of 2 periods:

1. Charging the capacitor from 2.5 V to 4.5 V by a 107 μA current source.
2. Discharging the capacitor from 4.5 V to 1.2 V by the external resistor.

The restart time is mainly determined by the capacitor discharging from 4.5 V to 1.2 V by R_{OPTIMER} (Equation 13).

$$T_{restart, discharge} = -R \times C \times \ln\left(\frac{V_{restart(OPTIMER, low)}}{V_{restart(OPTIMER, high)}}\right) = -R \times C \times \ln\left(\frac{1.2 \text{ V}}{4.5 \text{ V}}\right) \tag{13}$$

Where $R = R_{OPTIMER}$ (R16) and $C = C_{OPTIMER}$ (C8).

For a more accurate calculation the time required to charge the capacitor from 2.5 V to 4.5 V should also be calculated and added to the discharge time ([Equation 14](#)).

$$\begin{aligned}
 T_{restart, charge} &= R \times C \times \left(I_n \right) - \frac{V_{prot(OPTIMER)}}{R \times I_{restart(OPTIMER)}} - I_n \left(\right) - \frac{V_{restart(OPTIMER_high)}}{R \times I_{restart(OPTIMER)}} \\
 &= R \times C \times \left(I_n \right) - \frac{2.5\text{ V}}{R \times 107\ \mu\text{A}} - I_n \left(\right) - \frac{4.5\text{ V}}{R \times 07\ \mu\text{A}}
 \end{aligned}
 \tag{14}$$

Where $R = R_{OPTIMER}$ (R16) and $C = C_{OPTIMER}$ (C8).

3.7.4 How to configure R and C

The capacitor value has the same influence on both delays. When the resistor value is large enough (> 2 MΩ) it only influences the restart delay. So tuning these components is most convenient in the following order:

1. Tune or calculate the capacitor value to obtain the required OPP time.
2. Tune or calculate the resistor value to obtain the required restart time.

Some examples of OPP delay and restart delay for some different RC combinations are shown in [Table 6](#).

Table 6. Examples of OPP attack time and restart time

$R_{OPTIMER}$ (MΩ)	$C_{OPTIMER}$ (nF)	T_{OPP} (ms)	$T_{restart}$ (ms)	Ratio $T_{OPP} / T_{restart}$
2.2	100	25	293	1:12
2.2	220	54	644	1:12
2.2	470	116	1376	1:12
1	220	59	295	1:5
4.7	220	53	1371	1:26

3.8 PROTECT pin

3.8.1 General

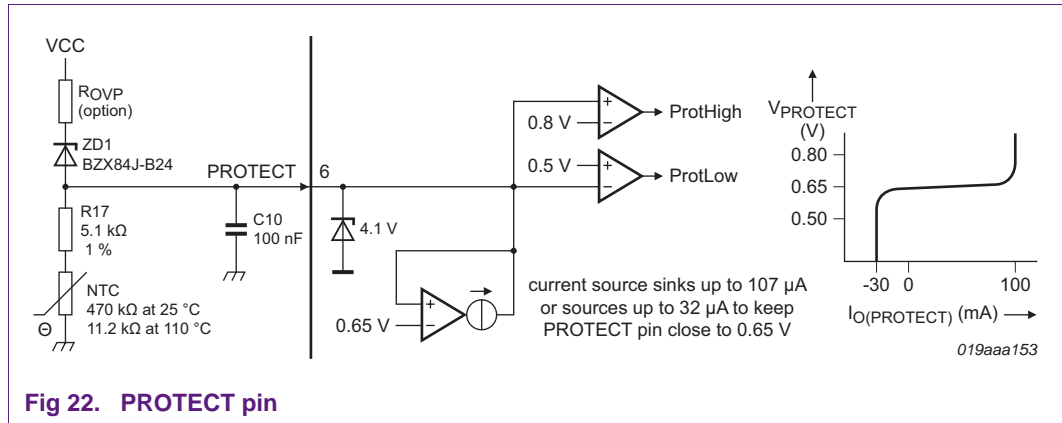
Two protection features can be implemented on the same PROTECT pin using only a minimum number of components:

- OverVoltage Protection (output OVP)
- OverTemperature Protection (OTP)

The protection features on the PROTECT pin are always latched (also in the non-latched version).

3.8.2 Circuit description

An internal current source attempts to keep the voltage on the PROTECT pin equal to 0.65 V. This internal current source has a range of -107 μA to +32 μA (i.e. it can sink 107 μA and source 32 μA). If the internal current source is out of range the pin can no longer be kept in the 0.5 V to 0.8 V window and activates the protection.



3.8.3 External output overvoltage protection

Output OVP is activated when the VCC voltage exceeds the voltage of the Zener diode (at 107 μA) plus 0.8 V. The OVP can be tuned by placing a resistor (R_{OVP} in [Figure 22](#)) in series with the Zener diode. A series resistor of 10 kΩ increases the OVP voltage by approximately 1 V ($\Delta V = R_{OVP} \times 107 \text{ mA}$).

An *external* OVP application is optional and is only required if the OVP level must be lower than the fixed 30 V level of the *internal* OVP protection (or if extra filtering of the auxiliary winding voltage is required).

3.8.4 Overtemperature protection

The OTP is triggered when the voltage on the PROTECT pin drops below 0.5 V. This happens when the resistance of the NTC + series resistor has dropped below $0.5 \text{ V} / 32 \mu\text{A} = 15.6 \text{ k}\Omega$. The OTP is not influenced by VCC variations because the PROTECT pin is internally biased. The OTP is most accurate when the value of the NTC is chosen to be as high as possible.

It is often required for thermal reasons, that the NTC is placed relatively far away from the controller. Placing R17 as close as possible to the protection pin helps to improve the immunity to disturbances picked up by the long PCB track. Capacitor C10 should also be placed as close as possible to the protection pin. The ground connection of C10 should be directly to the ground pin of the controller.

3.8.5 Clamp

An internal clamp keeps the PROTECT pin voltage at 4.1 V to prevent damage to the PROTECT pin in case of spikes. The clamp voltage is specified at a 200 μA input current (the exact voltage depends on the current). In Power-down mode, the clamp voltage drops to approximately 2 V.

3.9 DRIVER pin

3.9.1 Gate driver

The driver circuit has a current sourcing capability of typically 250 mA and a current sink capability of typically 750 mA. This permits fast turn-on and turn-off of the power MOSFET for efficient operation. See [Figure 16 on page 29](#) for DRIVER pin control.

3.9.2 Frequency modulation

The switching frequency and its harmonics are usually responsible for a large part of the conducted EMI problems. Modulation of the switching frequency spreads all frequency peaks that are related to the switching frequency over 8 kHz wide bands, significantly decreasing the so called "average measurement". See [Figure 16 on page 29](#) for location of oscillator and frequency modulation.

The oscillator is continuously modulated at a rate of 280 Hz and a range of ± 4 kHz.

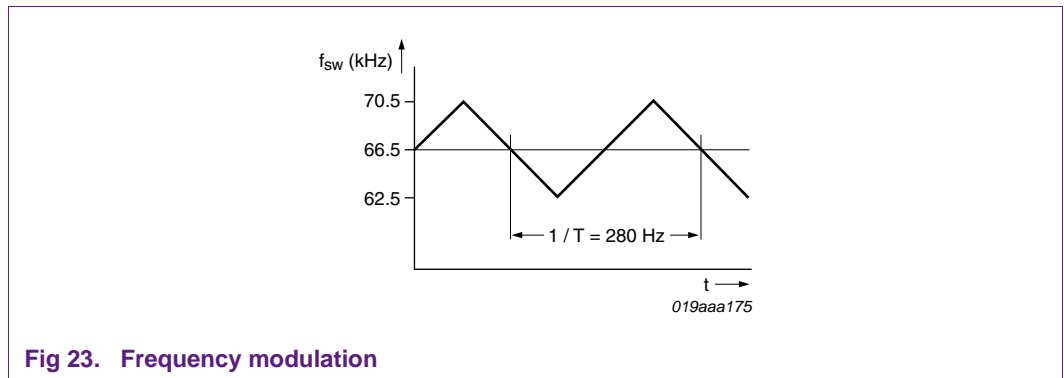


Fig 23. Frequency modulation

4. Ways to reduce no-load power

This section describes how the no-load power can be minimized in any TEA1738-based flyback converter.

4.1 Remove power LED

Some adapters have a LED connected to the output to indicate that the power is present. A LED current of 2.5 mA supplied from a 20 V output voltage already adds 50 mW to the no-load power.

A (high efficiency) LED in series with the LED of the optocoupler does not add to the power consumption but its brightness will slightly vary with the load. Another option is to supply the LED from a separate low voltage winding.

4.2 Change the primary RDC clamp to a Zener clamp

The advantage of the Zener clamp is that it only conducts when it is really needed and is independent of the switching frequency. Compared to a Resistor Diode Capacitor (RDC) clamp it reduces no-load power but increases costs and EMI.

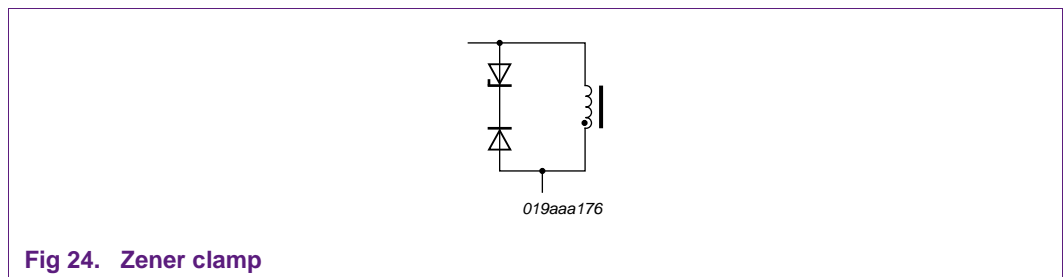


Fig 24. Zener clamp

4.3 Modify RDC clamp with a Zener diode

A Zener diode in series with the R of the RDC clamp prevents the capacitor from almost entirely discharging at each switching cycle when running at low frequency during no load. Adding the Zener diode increases costs and may also increase EMI (but not as much as a Zener clamp). Replacing R9 ([Figure 1](#)) by a 100 V Zener saves 5 mW at 230 V (AC).

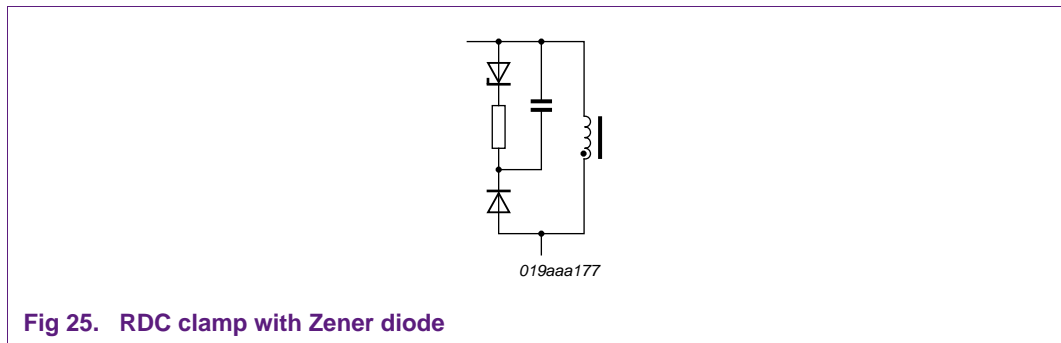


Fig 25. RDC clamp with Zener diode

4.4 Reconsider start-up time specification

Usually the maximum start-up time of a power supply is specified at low nominal mains voltage (115 V (AC)). But occasionally the maximum start-up time is specified at the absolute minimum mains voltage (90 V (AC)). In this case it is worth reconsidering this requirement: 90 V (AC) will probably be encountered in less than 1 % of the field but to achieve a 2 s start-up time at 90 V (AC) requires 17 mW extra start-up power at 230 V (AC)⁵.

Another 11 mW can be saved by allowing a maximum start-up time of 3 s instead of 2 s. See figure [Figure 5 on page 11](#).

4.5 Reduce VCC capacitor value

With a smaller VCC capacitor the efficiency of the start-up circuit can be significantly improved. Charging only half the VCC capacitor in the same time requires only half the power. For a maximum start-up time of 2 s at 115 V (AC), reducing the VCC capacitance from 4.8 μF to 2.3 μF and doubling the start-up resistor values saves approximately 20 mW.

4.6 X-cap quality

Use a good quality X-cap. A poor quality X-cap (330 nF) may dissipate as much as 25 mW at 230 V (AC) at 60 Hz. A good quality X-cap dissipates less than 2 mW.

4.7 X-cap value

Reducing the value of the X-cap also decreases the X-cap losses. It is better to solve EMI problems at the source than by solving them with a very large X-cap. Reducing the X-cap value not only reduces the losses in the X-cap itself but also in the required X-cap discharge circuit.

5. If the two resistor start-up circuit is used and the VCC capacitance is 4.8 μF (4.7 μF + 100 nF).

4.8 Active X-cap discharge

Replace a passive X-cap discharge (resistor) by an active discharge circuit (requires a high voltage transistor).

4.9 Active start-up circuit

Replace a passive start-up circuit (resistors) by an active charge circuit that is only active during start-up (requires a high voltage transistor).

4.10 Increasing the impedance of the voltage divider on VINSENSE

With $R4 = R5 = R6 = 10\text{ M}\Omega$ and $R7 = 240\text{ k}\Omega$ approximately 7 mW can be saved.

In this case C6 can be reduced from 470 nF to 180 nF to keep the same time constant.

4.11 Increase the impedance of the output voltage divider

Doubling the impedance of the voltage divider on the output (R23 and R24 in [Figure 1](#)) saves approximately 5 mW. In this case C16 and R22 also have to be adapted to keep the same loop response. How high the impedance can be increased depends very much on the layout of the PCB and the input current of the shunt regulator.

4.12 Replacing the integrated shunt regulator (TL431) by a discrete shunt regulator

The widely available integrated TL431 shunt regulator versions usually require 1 mA for proper regulation. Some manufacturers specify 0.5 mA or 0.6 mA. It is not difficult to make a low (temperature stable) discrete alternative, see [Figure 26](#).

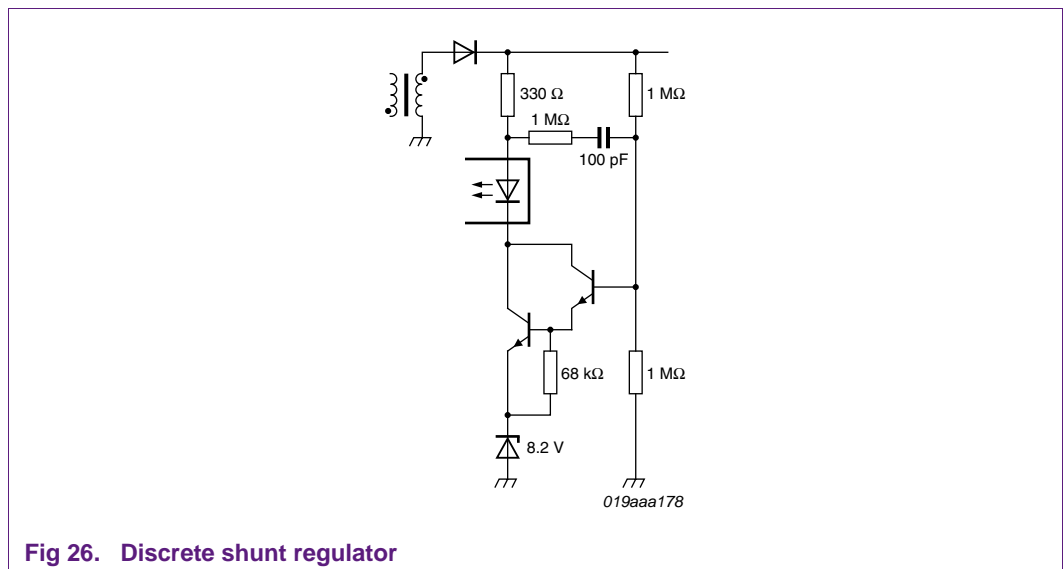


Fig 26. Discrete shunt regulator

5. "Zero Watt" standby power design ideas

5.1 Less than 30 mW standby power

The standby power can be reduced to less than 30 mW by switching the application off entirely. (So no output voltage is available.) The solutions described in the following sections do require an external signal to switch the supply on or off. So the device that is connected to the power supply switches the power supply off when it is no longer needed. This should be no problem for battery operated equipment.

5.2 Active on

Figure 27 shows how the supply can be switched on by an external active-on control signal. The components in red have to be added with respect to the existing application.

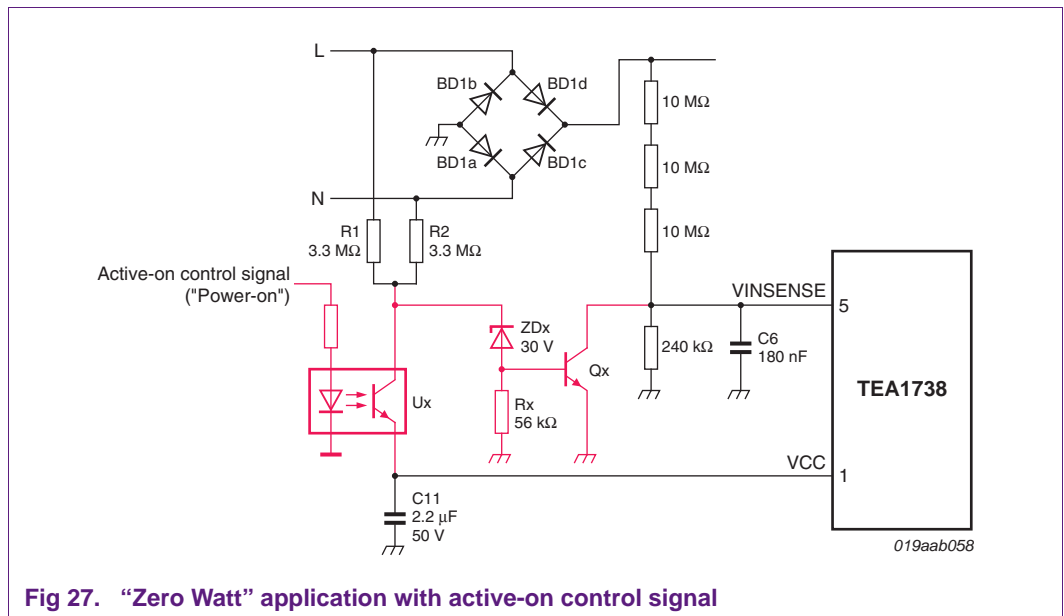


Fig 27. "Zero Watt" application with active-on control signal

5.2.1 Shut down

Suppose the supply is running and suddenly the voltage on the external power-on signal is made low. The transistor of the optocoupler blocks and the current through R1 and R2 is forced into Zener diode ZDx. Transistor Qx pulls VINSENSE pin LOW. The TEA1738 immediately stops switching. The auxiliary winding does not supply the IC anymore and the voltage on the VCC pin drops below V_{UVLO} . The IC enters Power-down mode.

5.2.2 Wake-up

When the power-on signal is made HIGH, the optocoupler conducts. The voltage on the Zener diode drops to 0 V and stops conducting. Qx blocks and the VINSENSE pin is released. The current through R1 and R2 now charges the VCC capacitor. The start-up time will be the same as the normal start-up time.

5.3 Active off

Figure 28 shows how the supply can be switched on by an external active-off control signal. The components in red have to be added with respect to the existing application.

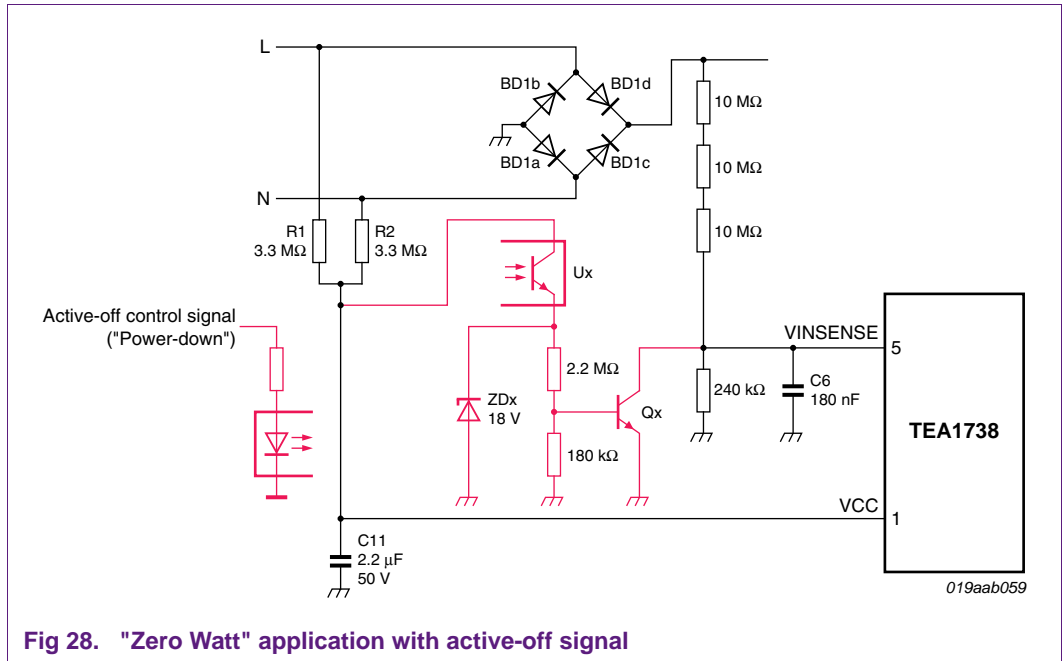


Fig 28. "Zero Watt" application with active-off signal

5.3.1 Shut down

Suppose the supply is running and the active-off control signal is suddenly made HIGH. The transistor of the optocoupler conducts and two things happen:

- Transistor Qx conducts and pulls VINSENSE pin LOW. The TEA1738 immediately stops switching and the IC enters Power-down mode.
- VCC is clamped to 18 V which is just below $V_{startup}$. Because of this, TEA1738 cannot do any start-up attempts.

5.3.2 Wake-up

When the power-down signal is made LOW, the optocoupler blocks and the VINSENSE pin is immediately released. The VCC capacitor was clamped just below $V_{startup}$. This guarantees a short start-up time.

6. Layout recommendations

6.1 Input section

- Keep the mains tracks (L and N) low ohmic and close to each other to avoid loops.
- Position common mode chokes away from the power section (MOSFET and transformer) and from each other to prevent magnetic coupling to any of the other components.
- Keep tracks from the bridge rectifier to C1 low ohmic and close to each other.

6.2 Power section

- The connection from the negative terminal of the bridge rectifier to the current sense resistor R11 must go via C1.
- The connection from the positive terminal of the bridge rectifier to the transformer must go via C1.
- Keep the cross section of the loop from C1 via the transformer, MOSFET Q1 and the current sense resistor R11 back to C1 as small as possible.
- Place C2 close to C1.
- Place peak clamp circuit R9, R10, C3 and D1 close to the transformer and away from TEA1738.
- If MOSFET Q1 has a metal tab it must be insulated from the heat sink. The heat sink must be connected to the primary power ground.

6.3 Auxiliary winding

- Place rectifier D3, R18 and VCC capacitor C11 close to the auxiliary winding.
- The connection of the ground of the auxiliary winding to the central signal ground point must go via C11 (use a separate track to avoid the noise in this ground causing noise in VINSENSE pin, PROTECT pin, etc.).
- Connect the central signal ground with a low ohmic track to the central power ground (C1).
- Keep the cross section of the loop from the auxiliary winding (via D3 and R18) to VCC capacitor C11 and back to the auxiliary winding as small as possible.

6.4 Flyback controller

- Place the TEA1738 away from the transformer and the MOSFET Q1.
- Keep connection from current sense resistor R11 to TEA1738 close to ground track.
- Place VCC decoupling capacitor C7 close to the VCC pin.
- The connection from the VCC pin to the VCC capacitor, C11, must go via the VCC decoupling capacitor, C7.
- The connection from the GND pin to the central signal ground must go via the VCC decoupling capacitor, C7.
- Place R13 close to the ISENSE pin.

- Place C10 and R17 close to the PROTECT pin. Other terminal of C10 should have short connection to GND pin
- Place C9 close to the CTRL pin.
- Place C6 close to the VINSENSE pin.
- Place C8 close to the OPTIMER pin.

6.5 Mains isolation

- Keep at least 6 mm distance between the copper tracks of the primary and the secondary side.
- Place the Y-cap CY1 close to the transformer.

6.6 Secondary side

- Heatsink secondary diode D9 and D10:
Connect the metal tab (which is usually internally connected to the cathode) directly to the heat sink. Connect the heatsink to the positive output track.
- Keep the cross section of the loop from the transformer via diodes D9 and D10 and capacitors C13 and C14 back to the transformer as small as possible. Keep output tracks close to each other.
- Use a separate signal ground for R24 and shunt regulator U3. Connect the signal ground from R24 and U3 via C19 to the power ground at C13 and C14.
- Place C19 close to R20 and R23.
- The connection of R20 and R23 to the positive output voltage must go via C19 to C13 and C14.
- Place the shunt regulator U3 and surrounding components away from transformer.

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