FAIRCHILD SEMICONDUCTOR®

April 2013

FSB50550AS
Motion SPM® 5 FRFET® Series

Features

- 500 V $R_{DS(on)}$= 1.4 Ω(Max) FRFET MOSFET 3-Phase Inverter Including HVICs
- Three Separate Open-Source Pins from Low Side MOSFETs for Three Leg Current Sensing
- HVIC for Gate Driving and Undervoltage Protection
- Active-High Interface, Can Work With 3.3 V / 5 V Logic
- Optimized for Low Electromagnetic Interference
- Isolation Voltage Rating of 1500 Vrms for 1 min.
- Temperature Sensing Built in HVIC
- Embedded Bootstrap Diode in the Package
- Moisture Sensitive Level (MSL) 3
- RoHS Compliant
-

Applications

- 3-Phase Inverter Driver for Small Power AC Motor Drives

General Description

FSB50550AS is an Advanced Motion SPM5 Series Based on Fast-Recovery MOSFET(FRFET) Technology as a Compact Inverter Solution for Small Power Motor Drive Applications Such as Fans and Pumps. FSB50-550AS Contains Six FRFET MOSFETs, Three Half-Bridge Gate Drive HVICs with Temperature Sensing, and Three Bootstrap Diodes in a Compact Package Fully Isolated and Optimized for Thermal Performance. FSB50550AS Features Low Electromagnetic Interfe-rence(EMI) Characteristics Through Optimizing Switch-ing Speed and Reducing Parasitic Inductance. Since FSB50550AS Employs MOSFETs as Power Switches, It Povides Much More Ruggedness and Larger Safe Operating Area(SOA) than IGBT-Based Power Modules. FSB50550AS is the Right Solution for Compact and Reliable Inverter Designs Where the Assembly Space is Constrained.

Related Source

- *RD-FSB50450A : Reference Design for Motion SPM5 Series Ver.2*
- *AN-9082 : Motion SPM5 Series Thermal Performance by Contact Pressure*

Package Marking & Ordering Information

Device Marking	Device	Package	Reel Size	Packing Type	Quantity
FSB50550AS	FSB50550AS	SPM5Q-023	330mm	TAPE-REEL	450

Absolute Maximum Ratings

Inverter Part (Each MOSFET® Unless Otherwise Specified)

Symbol	Parameter	Conditions	Rating	Unit
V_{PN}	DC Link Input Voltage, Drain-Source Voltage of Each MOSFET		500	V
*$I_{D\ 25}$	Each MOSFET Drain Current, Continuous	T_C = 25°C	2.0	A
*$I_{D\ 80}$	Each MOSFET Drain Current, Continuous	T_C = 80°C	1.5	A
*I_{DP}	Each MOSFET Drain Current, Peak	T_C = 25°C, PW < 100 μs	5	A
*I_{DRMS}	Each MOSFET Drain Current, Rms	T_C = 80°C, F_{PWM} < 20 KHz	1.1	A_{rms}
*P_D	Maximum Power Dissipation	T_C = 25°C, For Each MOSFET	14.5	W

Control Part (Each HVIC Unless Otherwise Specified)

Symbol	Parameter	Conditions	Rating	Unit
V_{CC}	Control Supply Voltage	Applied Between V_{CC} and COM	20	V
V_{BS}	High-side Bias Voltage	Applied Between V_B and V_S	20	V
V_{IN}	Input Signal Voltage	Applied Between IN and COM	-0.3 ~ V_{CC}+0.3	V

Bootstrap Diode Part (Each Bootstrap diode Unless Otherwise Specified)

Symbol	Parameter	Conditions	Rating	Unit
V_{RRMB}	Maximum Repetitive Reverse Voltage		500	V
* I_{FB}	Forward Current	T_C = 25°C	0.5	A
* I_{FPB}	Forward Current (Peak)	T_C = 25°C, Under 1ms Pulse Width	1.5	A

Thermal Resistance

Symbol	Parameter	Conditions	Rating	Unit
$R_{\theta JC}$	Junction to Case Thermal Resistance	Each MOSFET under Inverter Operating Condition (Note 1)	8.6	°C/W

Total System

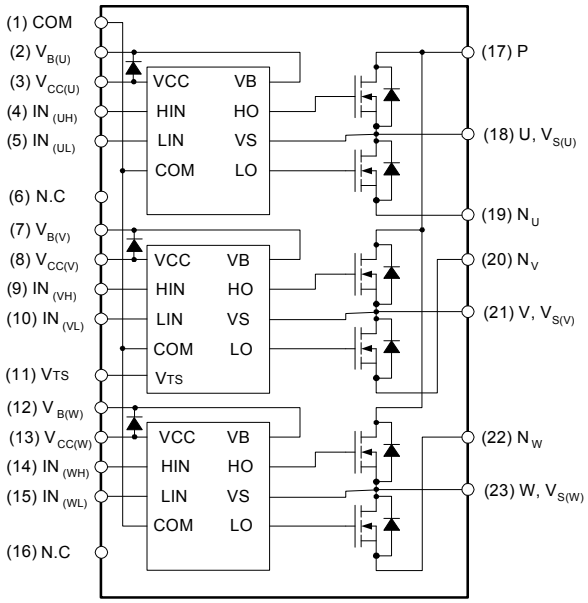
Symbol	Parameter	Conditions	Rating	Unit
T_J	Operating Junction Temperature		-40 ~ 150	°C
T_{STG}	Storage Temperature		-40 ~ 125	°C
V_{ISO}	Isolation Voltage	60 Hz, Sinusoidal, 1 minute, Connection Pins to Heatsink	1500	V_{rms}

Note:

1. For the Measurement Point of Case Temperature T_C, Please refer to Figure 4.
2. Marking " * " Is Calculation Value or Design Factor.

Pin descriptions

Pin Number	Pin Name	Pin Description
1	COM	IC Common Supply Ground
2	$V_{B(U)}$	Bias Voltage for U Phase High Side MOSFET® Driving
3	$V_{CC(U)}$	Bias Voltage for U Phase IC and Low Side MOSFET Driving
4	$IN_{(UH)}$	Signal Input for U Phase High-Side
5	$IN_{(UL)}$	Signal Input for U Phase Low-Side
6	N.C	N.C
7	$V_{B(V)}$	Bias Voltage for V Phase High Side MOSFET Driving
8	$V_{CC(V)}$	Bias Voltage for V Phase IC and Low Side MOSFET Driving
9	$IN_{(VH)}$	Signal Input for V Phase High-Side
10	$IN_{(VL)}$	Signal Input for V Phase Low-Side
11	V_{TS}	Output for HVIC Temperature Sensing
12	$V_{B(W)}$	Bias Voltage for W Phase High Side MOSFET Driving
13	$V_{CC(W)}$	Bias Voltage for W Phase IC and Low Side MOSFET Driving
14	$IN_{(WH)}$	Signal Input for W Phase High-Side
15	$IN_{(WL)}$	Signal Input for W Phase Low-Side
16	N.C	N.C
17	P	Positive DC–Link Input
18	U, $V_{S(U)}$	Output for U Phase & Bias Voltage Ground for High Side MOSFET Driving
19	N_U	Negative DC–Link Input for U Phase
20	N_V	Negative DC–Link Input for V Phase
21	V, $V_{S(V)}$	Output for V Phase & Bias Voltage Ground for High Side MOSFET Driving
22	N_W	Negative DC–Link Input for W Phase
23	W, $V_{S(W)}$	Output for W Phase & Bias Voltage Ground for High Side MOSFET Driving



Note:

Source Terminal of Each Low-Side MOSFET is Not Connected to Supply Ground or Bias Voltage Ground Inside Motion SPM®.

External Connections Should be Made as Indicated in Figure 3

Figure 1. Pin Configuration and Internal Block Diagram (Bottom View)

Electrical Characteristics (T_J = 25°C, V_{CC}=V_{BS}= 15 V Unless Otherwise Specified)

Inverter Part (Each MOSFET® Unless Otherwise Specified)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
BV_{DSS}	Drain-Source Breakdown Voltage	V_{IN}= 0V, I_D = 1 mA (Note 1)	500	-	-	V
I_{DSS}	Zero Gate Voltage Drain Current	V_{IN}= 0V, V_{DS} = 500 V	-	-	1	mA
$R_{DS(on)}$	Static Drain-Source On-Resistance	V_{CC} = V_{BS} = 15 V, V_{IN} = 5 V, I_D = 1.2 A	-	1.0	1.4	Ω
V_{SD}	Drain-Source Diode Forward Voltage	V_{CC} = V_{BS} = 15V, V_{IN} = 0V, I_D = -1.2 A	-	-	1.2	V
t_{ON}	Switching Times	V_{PN} = 300 V, V_{CC} = V_{BS} = 15 V, I_D = 1.2 A V_{IN} = 0 V ↔ 5 V, Inductive Load L= 3 mH High- and Low-Side MOSFET Switching (Note 2)	-	600	-	ns
t_{OFF}			-	500	-	ns
t_{rr}			-	100	-	ns
E_{ON}			-	60	-	μJ
E_{OFF}			-	10	-	μJ
RBSOA	Reverse-Bias Safe Operating Area	V_{PN} = 400 V, V_{CC} = V_{BS} = 15 V, I_D = I_{DP}, V_{DS}=BV_{DSS}, T_J = 150°C High- and Low-Side MOSFET Switching (Note 3)	Full Square			

Control Part (Each HVIC Unless Otherwise Specified)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
I_{QCC}	Quiescent V_{CC} Current	V_{CC}=15 V, V_{IN}=0V	Applied Between V_{CC} and COM	-	-	200	μA
I_{QBS}	Quiescent V_{BS} Current	V_{BS}=15 V, V_{IN}=0V	Applied Between $V_{B(U)}$-U, $V_{B(V)}$-V, $V_{B(W)}$-W	-	-	100	μA
UV_{CCD}	Low-Side Undervoltage Protection (Figure 8)	V_{CC} Undervoltage Protection Detection Level		7.4	8.0	9.4	V
UV_{CCR}		V_{CC} Undervoltage Protection Reset Level		8.0	8.9	9.8	V
UV_{BSD}	High-Side Undervoltage Protection (Figure 9)	V_{BS} Undervoltage Protection Detection Level		7.4	8.0	9.4	V
UV_{BSR}		V_{BS} Undervoltage Protection Reset Level		8.0	8.9	9.8	V
V_{TS}	HVIC Temperature Sensing Voltage Output	V_{CC}= 15 V, T_{HVIC}= 25°C (Note 4)		600	790	980	mV
V_{IH}	ON Threshold Voltage	Logic High Level	Applied between IN and COM	-	-	2.9	V
V_{IL}	OFF Threshold Voltage	Logic Low Level		0.8	-	-	V

Bootstrap Diode Part (Each Bootstrap diode Unless Otherwise Specified)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{FB}	Forward Voltage	I_F = 0.1 A, T_C = 25°C (Note 5)	-	2.5	-	V
t_{rrB}	Reverse Recovery Time	I_F = 0.1 A, T_C = 25°C	-	80	-	ns

Note:

1. BV_{DSS} is the Absolute Maximum Voltage Rating Between Drain and Source Terminal of Each MOSFET Inside Motion SPM®. V_{PN} Should be Sufficiently Less Than This Value Considering the Effect of the Stray Inductance so that V_{DS} Should Not Exceed BV_{DSS} in Any Case.
2. t_{ON} and t_{OFF} Include the Propagation Delay Time of the Internal Drive IC. Listed Values are Measured at the Laboratory Test Condition, and They Can be Different According to the Field Applications Due to the Effect of Different Printed Circuit Boards and Wirings. Please see Figure 6 for the Switching Time Definition with the Switching Test Circuit of Figure 7.
3. The peak current and voltage of each MOSFET during the switching operation should be included in the safe operating area (SOA). Please see Figure 7 for the RBSOA test circuit that is same as the switching test circuit.
4. V_{ts} is only for sensing temperature of module and cannot shutdown MOSFETs automatically.
5. Built in bootstrap diode includes around 15Ω resistance characteristic. Please refer to Figure 2.

Recommended Operating Condition

Symbol	Parameter	Conditions	Value			Unit
			Min.	Typ.	Max.	
V_{PN}	Supply Voltage	Applied Between P and N	-	300	400	V
V_{CC}	Control Supply Voltage	Applied Between V_{CC} and COM	13.5	15	16.5	V
V_{BS}	High-Side Bias Voltage	Applied Between V_B and V_S	13.5	15	16.5	V
$V_{IN(ON)}$	Input ON Threshold Voltage	Applied Between IN and COM	3.0	-	V_{CC}	V
$V_{IN(OFF)}$	Input OFF Threshold Voltage		0	-	0.6	V
t_{dead}	Blanking Time for Preventing Arm-Short	V_{CC}=V_{BS}= 13.5 ~ 16.5 V, $T_J \leq 150°C$	1.0	-	-	µs
f_{PWM}	PWM Switching Frequency	$T_J \leq 150°C$	-	15	-	kHz

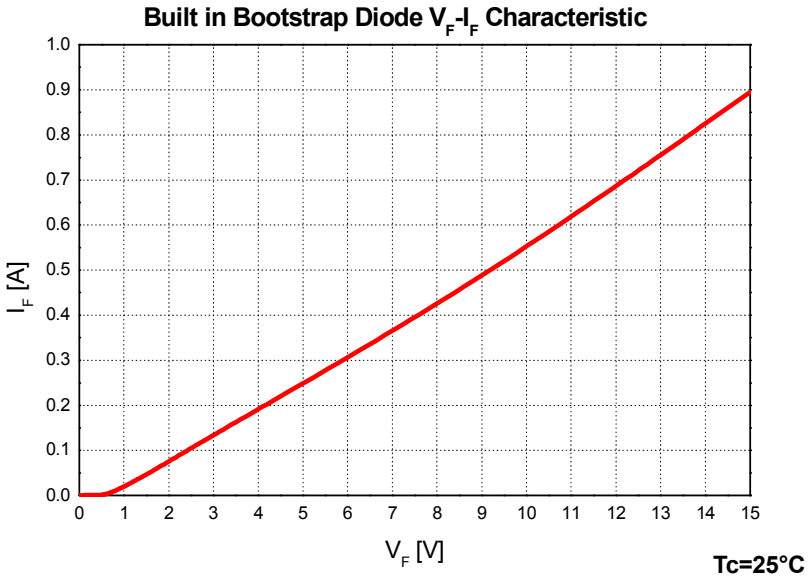
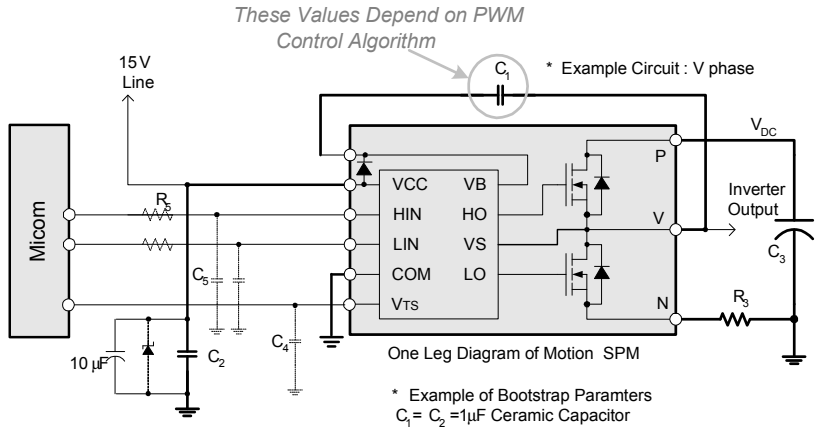


Figure 2. Built in Bootstrap Diode Characteristics (Typ.)

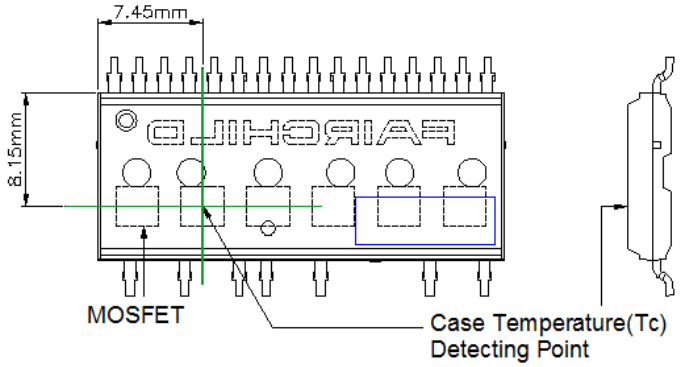


HIN	LIN	Output	Note
0	0	Z	Both FRFET Off
0	1	0	Low side FRFET On
1	0	V_{DC}	High side FRFET On
1	1	Forbidden	Shoot through
Open	Open	Z	Same as (0,0)

Note:

1. Parameters for Bootstrap Circuit Elements are Dependent on PWM Algorithm. For 15 kHz of Switching Frequency, Typical Example of Parameters is Shown Above.
2. RC coupling (R_5 and C_5) and C_4 at Each Input of Motion SPM® and Micom (Indicated as Dotted Lines) May be Used to Prevent Improper Signal Due to Surge Noise.
3. Bold lines should be short and thick in PCB pattern to have small stray inductance of circuit, which results in the reduction of surge voltage. Bypass capacitors such as C_1, C_2 and C_3 Should Have Good High-Frequency characteristics to Absorb High-Frequency Ripple Current.

Figure 3. Recommended MCU Interface and Bootstrap Circuit with Parameters



Note:

Attach the thermocouple on top of the heatsink-side of Motion SPM (between Motion SPM and heatsink if applied) to get the correct temperature measurement.

Figure 4. Case Temperature Measurement

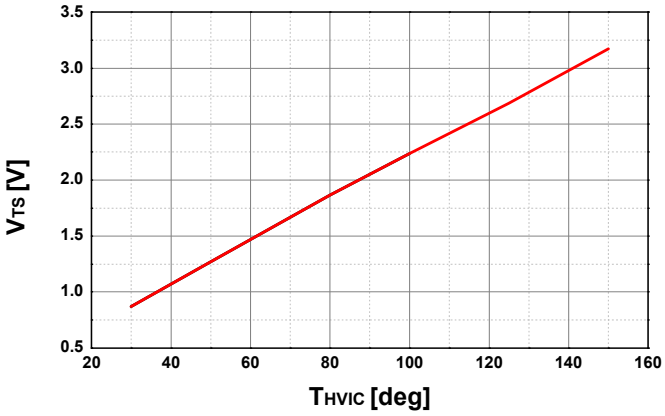
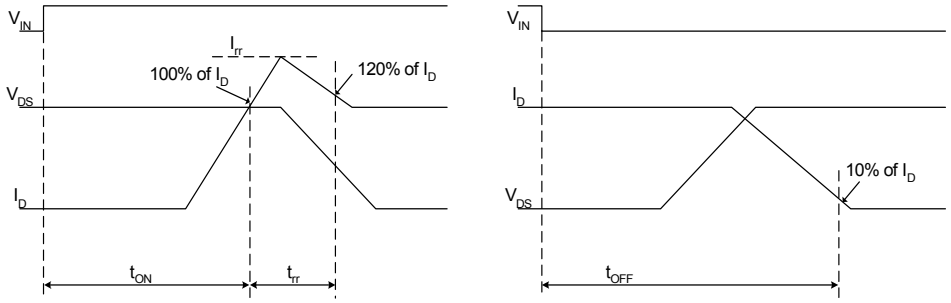


Figure 5. Temperature Profile of V_{TS} (Typ.)



(a) Turn-on **(b) Turn-off**

Figure 6. Switching Time Definitions

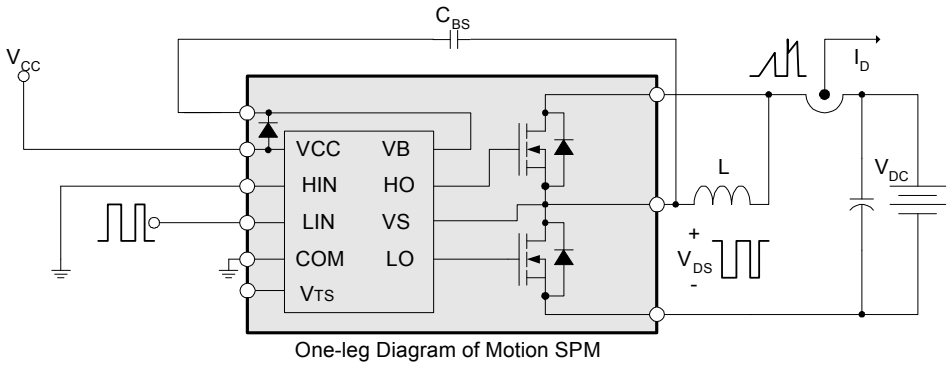


Figure 7. Switching and RBSOA (Single-pulse) Test Circuit (Low-side)

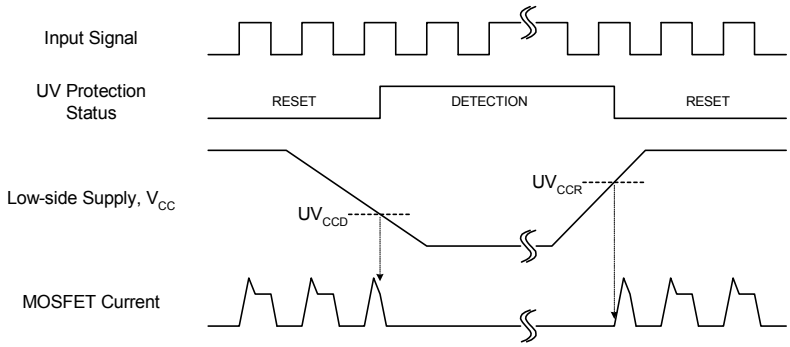


Figure 8. Undervoltage Protection (Low-side)

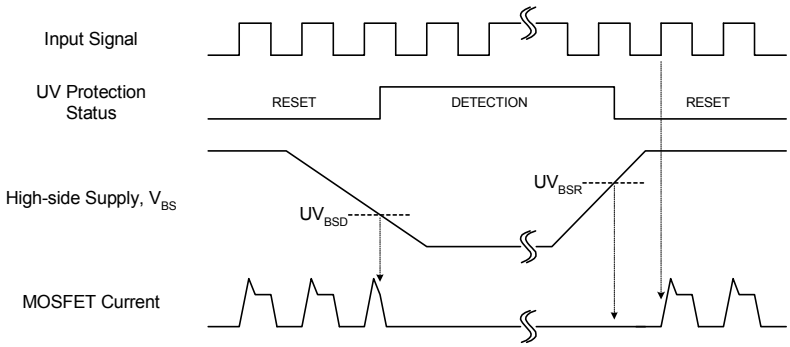
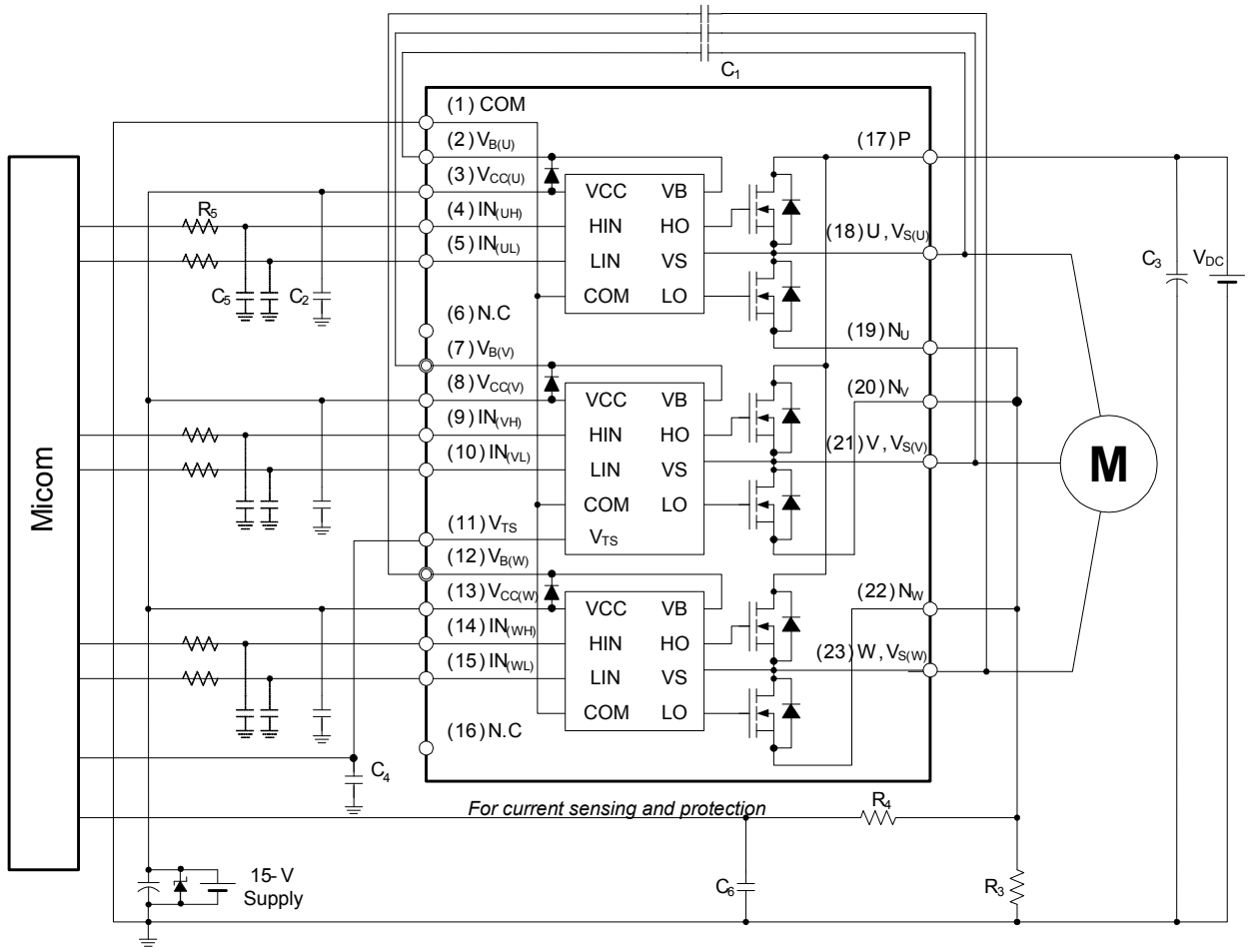


Figure 9. Undervoltage Protection (High-side)

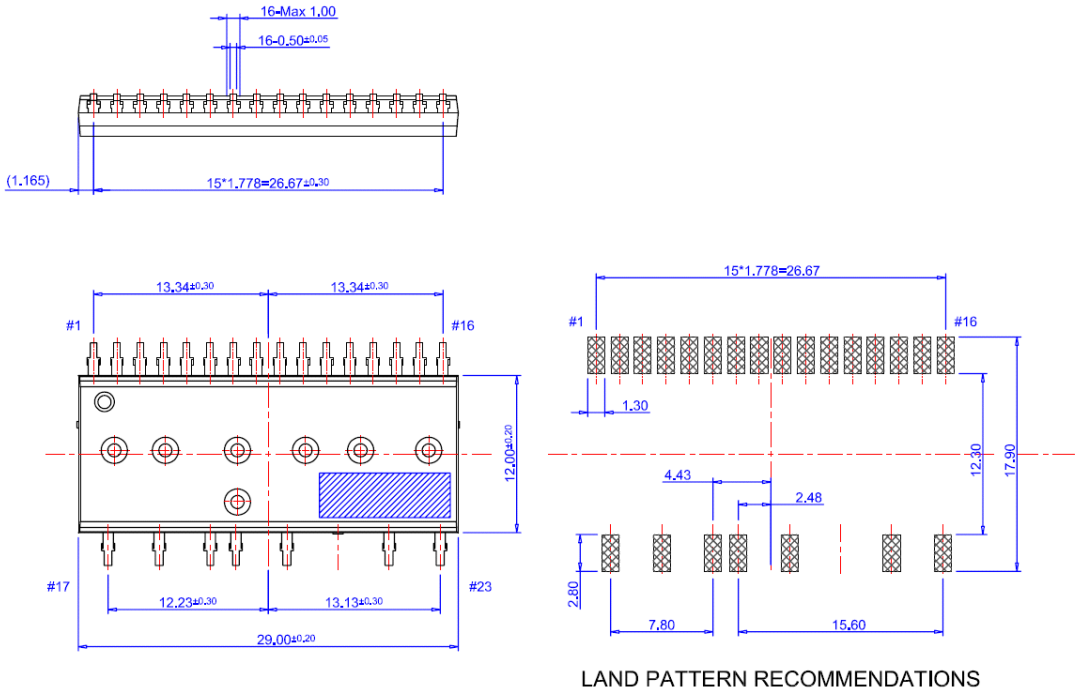


Note:

1. About Pin Position, Refer to Figure 1.
2. RC Coupling (R_5 and C_5, R_4 and C_6) and C_4 at Each Input of Motion SPM® and Micom are Useful to Prevent Improper Input Signal Caused by Surge Noise.
3. The voltage Drop Across R_3 Affects the Low Side Switching Performance and the Bootstrap Characteristics Since it is Placed Between COM and the Source Terminal of the Low Side MOSFET. For this Reason, the Voltage Drop Across R_3 Should Be Less Than 1 V in the Steady-State.
4. Ground Wires and Output Terminals, Should Be Thick and Short in Order to Avoid Surge Voltage and Malfunction of HVIC.
5. All the Filter Capacitors Should Be Connected Close to Motion SPM, and They Should Have Good Characteristics for Rejecting High-Frequency Ripple Current.

Figure 10. Example of Application Circuit

Detailed Package Outline Drawings



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