SONY

Diagonal 4.5mm (Type 1/4) Progressive Scan CCD Image Sensor with Square Pixel for B/W Cameras

ICX614ALA

Description

The ICX614ALA is a diagonal 4.5mm (Type 1/4) interline CCD solid-state image sensor with a square pixel array which supports VGA format. Progressive scan enables all pixel signals to be output separately within approximately 1/60 second. This chip features an electronic shutter with variable charge-storage time which makes it possible to realize full-frame still images without a mechanical shutter. High sensitivity and low dark current are achieved through the adoption of HAD (Hole-Accumulation Diode) sensors. This chip is suitable for applications such as security cameras and network cameras.

Features

- ◆ High sensitivity
- ♦ High saturation signal
- ◆ Progressive scan enables individual readout of the image signals from all pixels.
- ◆ Square pixel
- ◆ Supports VGA format
- ♦ Horizontal drive frequency: Supports 24.54MHz
- ◆ No voltage adjustments (Reset gate and substrate bias need no adjustment.)
- ◆ High resolution, high sensitivity, low dark current
- ◆ Continuous variable-speed shutter
- ◆ Low smear
- ◆ Excellent anti-blooming characteristics
- ◆ Horizontal register: 3.3V drive
- ◆ 14-pin high accuracy plastic package (dual-surface reference available)

Super HAD CCD TM

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- 1 - E06242

Element Structure

- ◆ Interline CCD image sensor
- ◆ Image size Diagonal 4.5mm (Type 1/4)
- ◆ Number of effective pixels 659 (H) × 494 (V) approx. 330K pixels
- ◆ Total number of pixels 692 (H) \times 504 (V) approx. 350K pixels
- ◆ Chip size 4.46mm (H) × 3.80mm (V)
- ◆ Unit cell size
- $5.6\mu m (H) \times 5.6\mu m (V)$ ◆ Optical black

Horizontal (H) direction: Front 2 pixels, rear 31 pixels Vertical (V) direction: Front 8 pixels, rear 2 pixels

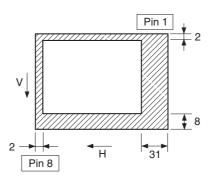
◆ Number of dummy bits

Horizontal: 16 Vertical: 4

◆ Substrate material Silicon

Optical Black Position

(Top View)



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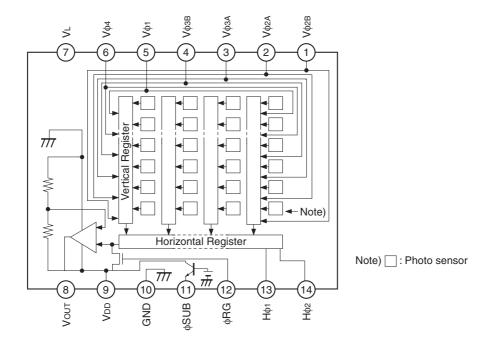
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Block Diagram and Pin Configuration

(Top View)



Pin Description

Pin No.	Symbol	Description
1	Vф2B	Vertical register transfer clock
2	Vф2A	Vertical register transfer clock
3	Vф3A	Vertical register transfer clock
4	V ф3В	Vertical register transfer clock
5	V _φ 1	Vertical register transfer clock
6	V ₀ 4	Vertical register transfer clock
7	VL	Protective transistor bias
8	Vout	Signal output
9	VDD	Supply voltage
10	GND	GND
11	φSUB	Substrate clock
12	φRG	Reset gate clock
13	Нф1	Horizontal register transfer clock
14	Нф2	Horizontal register transfer clock

Absolute Maximum Ratings

	Item	Ratings	Unit	Remarks
	Vdd, Vout, фRG – фSUB	-40 to +13	V	
Against &SUB	Vф2A, Vф2B, Vф3A, Vф3B – фSUB	-50 to +15	V	
Against ∳SUB	Vφ1, Vφ4 – φSUB	-50 to +0.3	V	
	Hφ1, Hφ2, GND – φSUB	-40 to +0.3	V	
	Vdd, Vout, фRG – GND	-0.3 to +18	V	
Against GND	Vφ1, Vφ2A, Vφ2B, Vφ3A, Vφ3B, Vφ4 – GND	-10 to +18	V	
	Hφ1, Hφ2 – GND	-10 to +5	V	
Against V	Vф2A, Vф2B, Vф3A, Vф3B – VL	-0.3 to +28	V	
Against V∟	Vφ1, Vφ4, Hφ1, Hφ2 – VL	-0.3 to +15	V	
	Potential difference between vertical clock input pins	to +15	V	*1
Between input clock pins	Hφ1 – Hφ2	−5 to +5	V	
	Hφ1, Hφ2 – Vφ3	-13 to +13	V	
Storage temper	ature	-30 to +80	°C	
Operating temp	erature	-10 to +60	°C	

 $^{^{*1}}$ +24V (Max.) is guaranteed when clock width < 10 μ s, clock duty factor < 0.1%.

Bias Conditions

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Supply voltage	VDD	14.55	15.0	15.45	V	
Protective transistor bias	VL		*1			
Substrate clock	φSUB		*2			
Reset gate clock	φRG		*2			

^{*1} VL setting is the VvL voltage of the vertical clock waveform, or the same voltage as the VL power supply for the V driver should be used.

DC Characteristics

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Supply current	IDD		6.0		mA	

^{*2} Do not apply a DC bias to the substrate clock and reset gate clock pins, because a DC bias is generated internally.

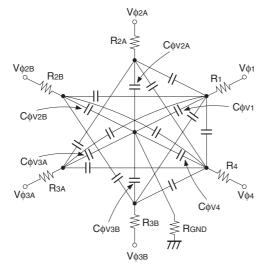


Clock Voltage Conditions

Item	Symbol	Min.	Тур.	Max.	Unit	Waveform diagram	Remarks
Readout clock voltage	VvT	14.55	15.0	15.45	V	1	
	VVH02A	-0.05	0	0.05	V	2	Vvh = Vvho2A
	VVH1, VVH2 (A, B), VVH3 (A, B), VVH4	-0.2	0	0.05	V	2	
Vertical	VVL1, VVL2 (A, B), VVL3 (A, B), VVL4	-5.8	-5.5	-5.2	V	2	VvL = (VvL1 + VvL3 (A, B))/2
transfer clock voltage	V\$1, V\$2 (A, B), V\$3 (A, B), V\$4	5.0	5.5	5.85	V	2	
	VVL3 (A, B), VVL4 - VVL			0.1	٧	2	
	Vvнн			0.3	V	2	High-level coupling
	Vvhl			1.0	V	2	High-level coupling
	VVLH			0.5	V	2	Low-level coupling
	VVLL			0.5	V	2	Low-level coupling
Horizontal	Vфн	3.0	3.3	5.25	V	3	
transfer clock voltage	VHL	-0.05	0	0.05	V	3	
	Vørg	3.0	3.3	5.5	V	4	
Reset gate clock voltage	VRGLH – VRGLL			0.4	V	4	Low-level coupling
	VRGL - VRGLm			0.5	V	4	Low-level coupling
Substrate clock voltage	Vфsuв	19.75	20.5	21.25	V	5	

Clock Equivalent Circuit Constants

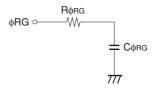
Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
	СфV1		1000		pF	
Capacitance between vertical transfer clock	Сфу2А, Сфу2В		820		pF	
and GND	Сфуза, Сфузв		390		pF	
	СфV4		1500		pF	
	СфV12А, СфV12В		56		pF	
	СфV13А, СфV13В		2		pF	
Capacitance between vertical transfer	СфV14		180		pF	
clocks	СфV2А3А, СфV2В3В		220		pF	
	Сфу2А4, Сфу2В4		270		pF	
	Сфузач, Сфузвч		180		pF	
Capacitance between horizontal transfer	Сфн1		15		pF	
clock and GND	Сфн2		15		pF	
Capacitance between horizontal transfer clocks	Сфнн		47		pF	
Capacitance between reset gate clock and GND	Сфяс		5		pF	
Capacitance between substrate clock and GND	Сфѕив		270		pF	
	R ₁		47		Ω	
Vertical transfer clock series resistor	R2A, R2B		91		Ω	
Vertical transfer clock series resistor	Rза, Rзв		68		Ω	
	R4		24		Ω	
Vertical transfer clock ground resistor	RGND		47		Ω	
Horizontal transfer clock series resistor	Rфн1, Rфн2		15		Ω	
Reset gate clock series resistor	Rørg		56		Ω	



Vertical transfer clock equivalent circuit



Horizontal transfer clock equivalent circuit

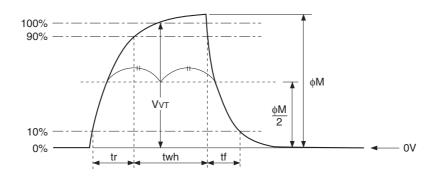


Reset gate clock equivalent circuit

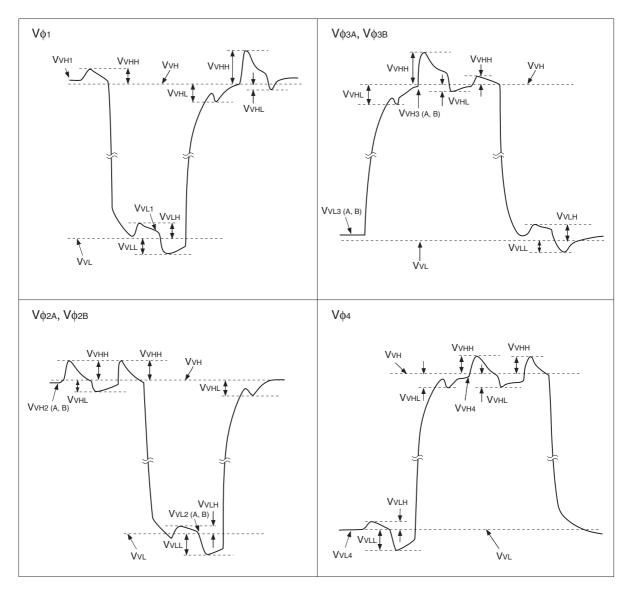


Drive Clock Waveform Conditions

1. Readout clock waveform



2. Vertical transfer clock waveform



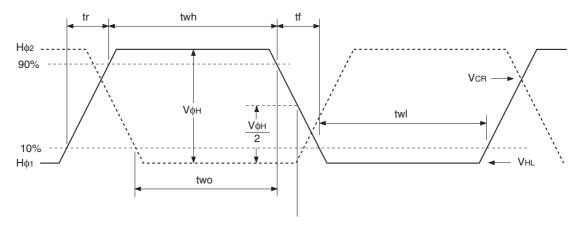
 $V_{VH} = (V_{VH1} + V_{VH2}(A, B))/2$

 $V_{VL} = (V_{VL3}(A, B) + V_{VL4})/2$

 $V_{\phi V} = V_{VHN} - V_{VLN} (n = 1 \text{ to } 4)$

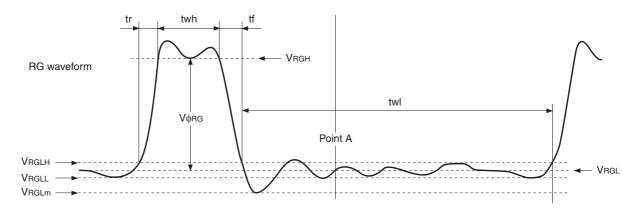


3. Horizontal transfer clock waveform



Cross-point voltage for the H ϕ 1 rising side of the horizontal transfer clocks H ϕ 1 and H ϕ 2 waveforms is Vcr. The overlap period for twh and twl of horizontal transfer clocks H ϕ 1 and H ϕ 2 is "two".

4. Reset gate clock waveform



VRGLH is the maximum value and VRGLL is the minimum value of the coupling waveform during the period from Point A in the above diagram until the rising edge of RG.

In addition, VRGL is the average value of VRGLH and VRGLL.

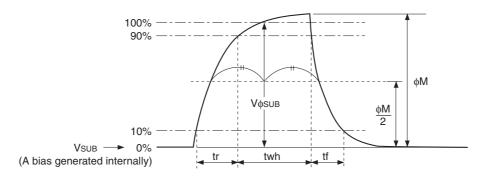
 $V_{RGL} = (V_{RGLH} + V_{RGLL})/2$

Assuming VRGH is the minimum value during the interval twh, then:

 $V\phi RG = VRGH - VRGL$

Negative overshoot level during the falling edge of RG is VRGLm.

5. Substrate clock waveform





Clock Switching Characteristics

144	em	Cumbal		twh			twl			tr			tf		Linit	Remarks
100	3111	Symbol	Min.	Тур.	Max.	Min.	Тур.	Max.	Min.	Тур.	Max.	Min.	Тур.	Max.	Offic	Remarks
Readout cl	ock	VT	1.8	2.0						0.5			0.5		μS	During readout
Vertical tra	nsfer clock	Vφ1, Vφ2(A,B), Vφ3(A,B), Vφ4										15		250	ns	*1
	During	Нф1	10.5	14.6		10.5	14.6			6.4	10.5		6.4	10.5		*2
Horizontal	imaging	Нф2	10.5	14.6		10.5	14.6			6.4	10.5		6.4	10.5	ns	_
transfer	During	Нф1								0.001						
clock	parallel- serial conversion	Нф2								0.001					μS	
Reset gate	clock	φRG	6	8			25.8			4			3		ns	
Substrate of	clock	φSUB	0.63	0.73							0.5			0.5	μS	When draining charge

^{*1} When vertical transfer clock driver CXD1267AN is used.

^{*2} tf \geq tr - 2ns, and the cross-point voltage (VcR) for the H ϕ 1 rising side of the H ϕ 1 and H ϕ 2 waveforms must be at least V ϕ H/2[V].

Item	Symbol	two		Unit	Remarks	
item	Symbol	Min.	Тур.	Мах.	Offic	Remarks
Horizontal transfer clock	Ηφ1, Ηφ2	10.5	14.6		ns	

Spectral Sensitivity Characteristics

(excludes lens characteristics and light source characteristics)

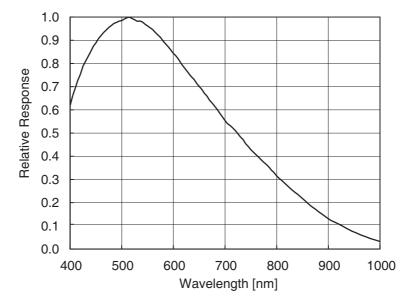


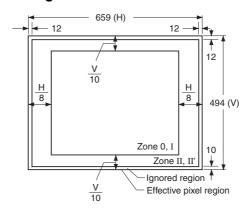


Image Sensor Characteristics

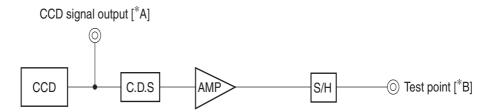
(Ta = 25°C)

Item	Symbol	Min.	Тур.	Max.	Unit	Measurement method	Remarks
Sensitivity	S	640	800		mV	1	1/30s accumulation
Saturation signal	Vsat	650			mV	2	Ta = 60°C
Smear	Sm	-92	-102		dB	3	
Video signal shading	SH			20	%	4	Zone 0 and I
Video signal snading	311			25	%	4	Zone 0 to II'
Dark signal	Vdt			4	mV	5	Ta = 60°C, 1/30s accumulation
Dark signal shading	ΔVdt			1	mV	6	Ta = 60°C, 1/30s accumulation
Lag	Lag			0.5	%	7	

Zone Definition of Video Signal Shading



Measurement System



Note) Adjust the amplifier gain so that the gain between [*A] and [*B] equals 1.

Image Sensor Characteristics Measurement Method

Measurement conditions

- 1. In the following measurements, the device drive conditions are at the typical values of the bias and clock voltage conditions.
- 2. In the following measurements, spot pixels are excluded and, unless otherwise specified, the optical black level (OB) is used as the reference for the signal output, which is taken as the value measured at point [*B] of the measurement system.

Definition of standard imaging conditions

◆ Standard imaging condition I:

Use a pattern box (luminance: 706cd/m², color temperature of 3200K halogen source) as a subject. (Pattern for evaluation is not applicable.) Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter and image at F8. The luminous intensity to the sensor receiving surface at this point is defined as the standard sensitivity testing luminous intensity.

◆ Standard imaging condition II:

Image a light source (color temperature of 3200K) with a uniformity of brightness within 2% at all angles. Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter. The luminous intensity is adjusted to the value indicated in each testing item by the lens diaphragm.

1. Sensitivity

Set to the standard imaging condition I. After setting the electronic shutter mode with a shutter speed of 1/100s, measure the signal output (Vs) at the center of the screen and substitute the value into the following formula.

$$S = Vs \times (100/30) [mV]$$

2. Saturation signal

Set to the standard imaging condition II. After adjusting the luminous intensity to 10 times the intensity with the average value of the signal output, 150mV, measure the minimum value of the signal output.

3. Smear

Set to the standard imaging condition II. With the lens diaphragm at F5.6 to F8, first adjust the average value of the signal output to 150mV. After the readout clock is stopped and the charge drain is executed by the electronic shutter at the respective H blankings, measure the maximum value (Vsm [mV]) of the signal output and substitute the value into the following formula.

Sm =
$$20 \times \log \{(Vsm/150) \times (1/500) \times (1/10)\} [dB]$$
 (1/10V method conversion value)

4. Video signal shading

Set to the standard imaging condition III. With the lens diaphragm at F5.6 to F8, adjusting the luminous intensity so that the average value of the signal output is 150mV. Then measure the maximum value (Vmax [mV]) and minimum value (Vmin [mV]) of the signal and substitute the values into the following formula.

SH =
$$(Vmax - Vmin)/150 \times 100 [\%]$$

5. Dark signal

Measure the average value of the signal output (Vdt [mV]) with the device ambient temperature of 60°C and the device in the light-obstructed state, using the horizontal idle transfer level as a reference.

6. Dark signal shading

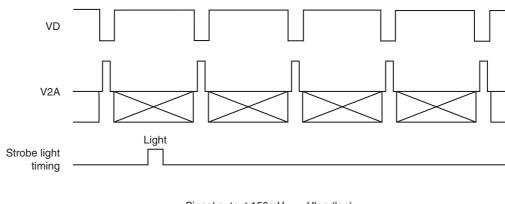
After the measurement item 5, measure the maximum (Vdmax [mV]) and minimum (Vdmin [mV]) values of the dark signal output and substitute the values into the following formula.

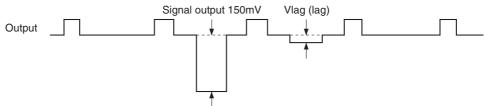
$$\Delta Vdt = Vdmax - Vdmin [mV]$$

7. Lag

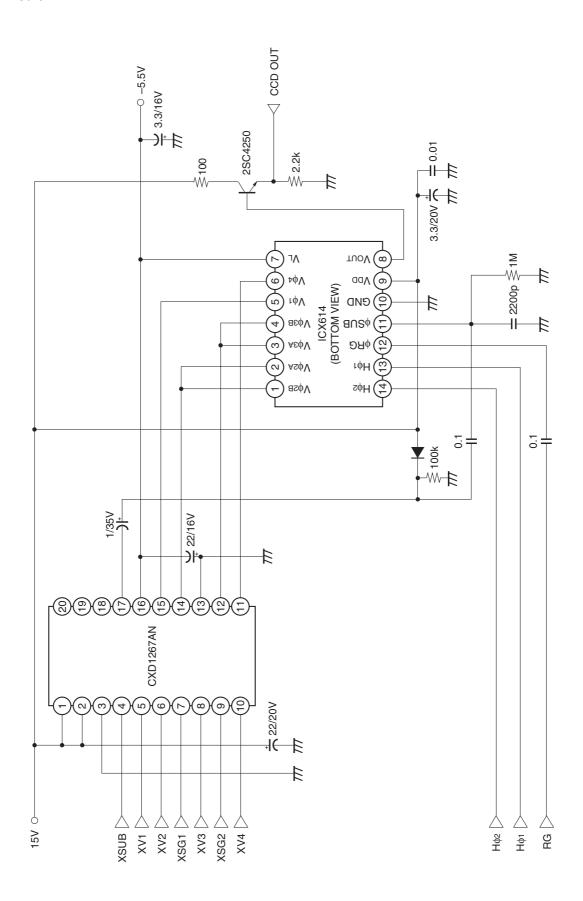
Adjust the signal output value generated by strobe light to 150mV. After setting the strobe light so that it strobes with the following timing, measure the residual signal (Vlag). Substitute the value into the following formula.







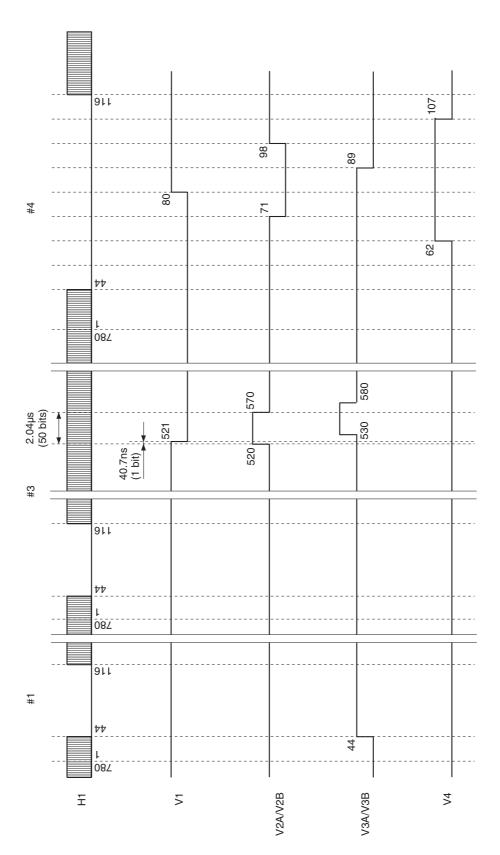
Drive Circuit





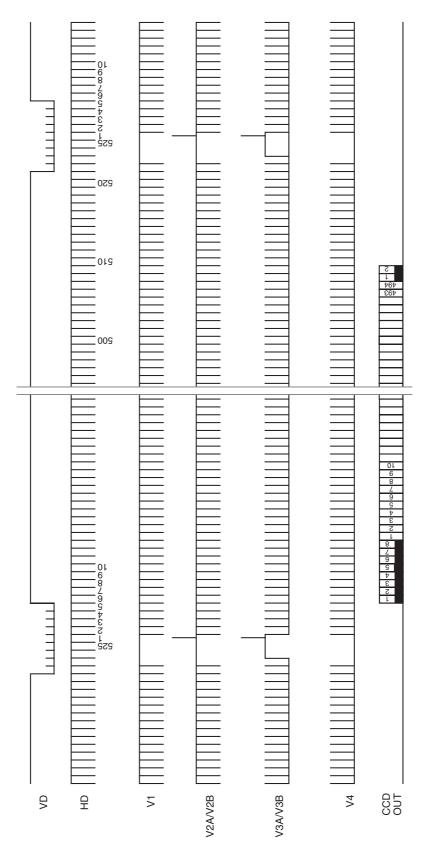
Drive Timing Chart

Readout Portion



Drive Timing Chart

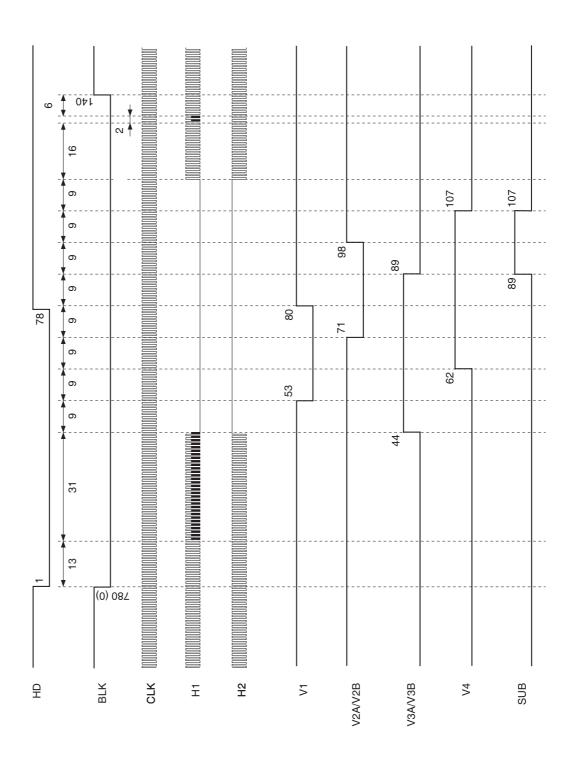
Vertical Sync





Drive Timing Chart

Horizontal Sync



Notes On Handling

1. Static charge prevention

CCD image sensors are easily damaged by static discharge. Before handling be sure to take the following protective measures.

- (1) Either handle bare handed or use non-chargeable gloves, clothes or material. Also use conductive shoes.
- (2) Use a wrist strap when handling directly.
- (3) Install grounded conductive mats on the floor and working table to prevent the generation of static electricity.
- (4) Ionized air is recommended for discharge when handling CCD image sensors.
- (5) For the shipment of mounted boards, use boxes treated for the prevention of static charges.

2. Soldering

- (1) Make sure the package temperature does not exceed 80°C.
- (2) Solder dipping in a mounting furnace causes damage to the glass and other defects. Use a 30W soldering iron with a ground wire and solder each pin in 2 seconds or less. For repairs and remount, cool sufficiently.
- (3) To dismount an image sensor, do not use solder suction equipment. When using an electric desoldering tool, use a thermal controller of the zero-cross On/Off type and connect it to ground.

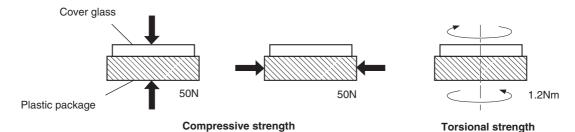
3. Protection from dust and dirt

Image sensors are packed and delivered with care taken to protect the element glass surfaces from harmful dust and dirt. Clean glass surfaces with the following operations as required before use.

- (1) Perform all lens assembly and other work in a clean room (class 1000 or less).
- (2) Do not touch the glass surface with hand and make any object contact with it. If dust or other is stuck to a glass surface, blow it off with an air blower. (For dust stuck through static electricity, ionized air is recommended.)
- (3) Clean with a cotton bud and ethyl alcohol if grease stained. Be careful not to scratch the glass.
- (4) Keep in a dedicated case to protect from dust and dirt. To prevent dew condensation, preheat or precool when moving to a room with great temperature differences.
- (5) When a protective tape is applied before shipping, remove the tape applied for electrostatic protection just before use. Do not reuse the tape.

4. Installing (attaching)

(1) Remain within the following limits when applying a static load to the package. Do not apply any load more than 0.7mm inside the outer perimeter of the glass portion, and do not apply any load or impact to limited portions. (This may cause cracks in the package.)



- (2) If a load is applied to the entire surface by a hard component, bending stress may be generated and the package may fracture, etc., depending on the flatness of the bottom of the package. Therefore, for installation, use either an elastic load, such as a spring plate, or an adhesive.
- (3) The adhesive may cause the marking on the rear surface to disappear, especially in case the regulated voltage value is indicated on the rear surface. Therefore, the adhesive should not be applied to this area, and indicated values should be transferred to the other locations as a precaution.
- (4) The notch of the package is used for directional index, and that can not be used for reference of fixing. In addition, the cover glass and seal resin may overlap with the notch of the package.

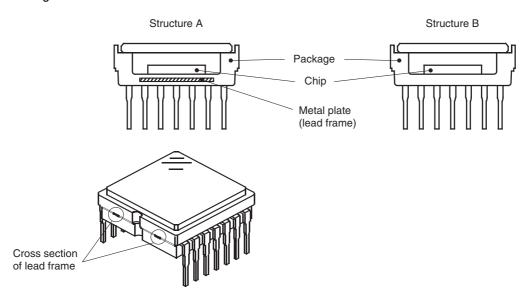
SONY ICX614ALA

(5) If the lead bend repeatedly and the metal, etc., clash or rub against the package, dust may be generated by the fragments of resin.

(6) Acrylate anaerobic adhesives are generally used to attach CCD image sensors. In addition, cyanoacrylate instantaneous adhesives are sometimes used jointly with acrylate anaerobic adhesives. (reference)

5. Others

- (1) Do not expose to strong light (sun rays) for long periods, as color filters will be discolored. When high luminance objects are imaged with the exposure level controlled by electronic-iris, the luminance of the image-plane may become excessive and discoloration of the color filters may be accelerated. In such a case, arrangements such as using an automatic iris with the imaging lens or automatically closing the shutter during power-off are advisable. For continuous use under harsh conditions exceeding the normal conditions of use, consult your Sony representative.
- (2) Exposure to high temperature or humidity will affect the characteristics. Accordingly avoid storage or use in such conditions.
- (3) Brown stains may be seen on the bottom or side of the package. But this does not affect the CCD characteristics.
- (4) This package has 2 kinds of internal structure. However, their package outline, optical size, and strength are the same.

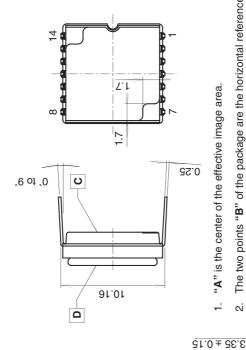


The cross section of lead frame can be seen on the side of the package for structure A.

Package Outline

(Unit: mm)

14 pin DIP (400mil)



1.0 ± 0.01

6.8

"A" is the center of the effective image area.

The two points "B" of the package are the horizontal reference. The point "B" of the package is the vertical reference.

٥i

0.1

2.5

7.0

2.6

m

The bottom "C" of the package, and the top of the cover glass "D" are the height reference.

The center of the effective image area relative to "**B**" and "**B**" is (H, V) = $(5.0, 5.0) \pm 0.15$ mm.

The rotation angle of the effective image area relative to H and V is $\pm~1\,^{\circ}.$ 2

The height from the top of the cover glass "**D**" to the effective image area is 1.94 \pm 0.15mm. The height from the bottom "C" to the effective image area is 1.41 \pm 0.10mm.

8.0 ± 8.5

(2)

0.3

 \oplus

0.46

0.3 72.

1.27

The tilt of the effective image area relative to the top "D" of the cover glass is less than 25µm. The tilt of the effective image area relative to the bottom " \mathbf{C} " is less than 25 μ m. 7

The thickness of the cover glass is 0.75mm, and the refractive index is 1.5.

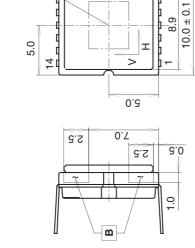
The notch of the package is used only for directional index, that must not be used for reference

10. Cover glass defect

Length: no matter, Width: less than 0.5mm, Depth: less than the thickness of the glass.

Length: less than 1.5mm, Depth: less than the thickness of the glass.

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PACKAGE STRUCTURE

Plastic	GOLD PLATING	42 ALLOY	0.60g	AS-D3-02(E)
PACKAGE MATERIAL	LEAD TREATMENT	LEAD MATERIAL	PACKAGE MASS	DRAWING NUMBER