

2.5V SEQUENTIAL FLOW-CONTROL DEVICE 48 BIT WIDE CONFIGURATION

For use with 128Mb to 256Mb DDR SDRAM

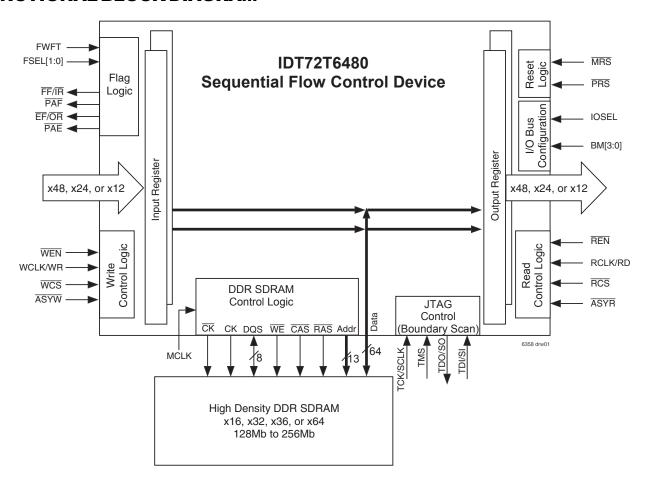
IDT72T6480

FEATURES

- Product to be used with single or multiple external DDR SDRAM to provide significant storage capability of up to 1Gb density
- 133MHz operation (7.5ns read/write cycle time)
- User selectable input and output port bus-sizing
 - x48in to x48out
 - x48in to x24out
 - x48in to x12out
 - x24in to x48out
 - x24in to x24out
 - x24in to x12out
 - x12in to x48out
 - 1211110 140001
 - x12in to x24out
 - x12in to x12out
- For other bus configurations see IDT72T6360 (x9, x18, or x36)
- 2.5V-LVTTL or 3.3V-LVTTL configured ports
- · Independent and simultaneous read and write access
- User selectable synchronous/asynchronous read and write port timing

- IDT Standard mode or FWFT mode of operation
- . Empty and full flags for monitoring memory status
- Programmable Almost-Empty and Almost-Full flags, each flag can default to one of four preselected offsets or serially programmed to a specific value
- Selectable synchronous/asynchronous timing modes for Almost-Empty and Almost-Full flags
- Master Reset clears all data and settings
- Partial Reset clears data, but retains programmable settings
- Depth expandable with multiple devices for densities greater than 1Gb
- Width expandable with multiple devices for bus widths greater than 36 bits
- JTAG functionality (Boundary Scan)
- Available in a 324-pin PBGA, 1mm pitch, 19mm x 19mm
- HIGH performance 0.18 µm CMOS technology
- Industrial temperature range (-40°C to +85°C) is available
- Supports industry standard DDR specifications, including Samsung, Micron, and Infineon memories

FUNCTIONAL BLOCK DIAGRAM



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COMMERCIAL AND INDUSTRIAL TEMPERATURE RANGES

OCTOBER 2005

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DESCRIPTION

The IDT72T6480 sequential flow-control device is a device incorporating a seamless connection to external DDR SDRAM for significant storage capacity supporting high-speed applications. Both read and write ports of the sequential flow-control can operate independently at up to 133MHz. There is a user selectable correction feature that will correct any erroneous single data bit when reading from the SDRAM.

The independent read and write ports each has associated read and write clocks, enables, and chip selects. Both ports can operate either synchronously or asynchronously. Other features include bus-matching, programmable status flags with selectable synchronous/asynchronous timing modes, IDT Standard or FWFT mode timing, and JTAG boundary scan functionality.

The bus-matching feature will allow the inputs and outputs to be configured to x48, x24, or x12 bus width. There are four default offset values available

for the programmable flags (PAE/PAF), as well as the option of serially programming the offsets to a specific value.

The device package is $19 \, \text{mm} \times 19 \, \text{mm} \times 324$ -pin PBGA. It operates at a 2.5V core voltage with selectable 2.5V or 3.3V I/Os. The I/O interface to the SDRAM will be 2.5V SSTL_2 only and not 3.3V tolerant. Both industrial and commercial temperature ranges will be offered.

The sequential flow-control device controls individual DDR SDRAM of either 128Mb or 256Mb. The device will support industry standard DDR specification memories (note DDR II is not supported), which include vendors such as Samsung, Micron, and Infineon. The data bus connected to the DDR SDRAM can be 16-bit, 32-bit, or 64-bits wide. The sequential flow-control device can independently control up to four separate external memories for a maximum of density of 1Gb (128MB). Depth expansion mode is available for applications that require more than 1Gb of storage memory.

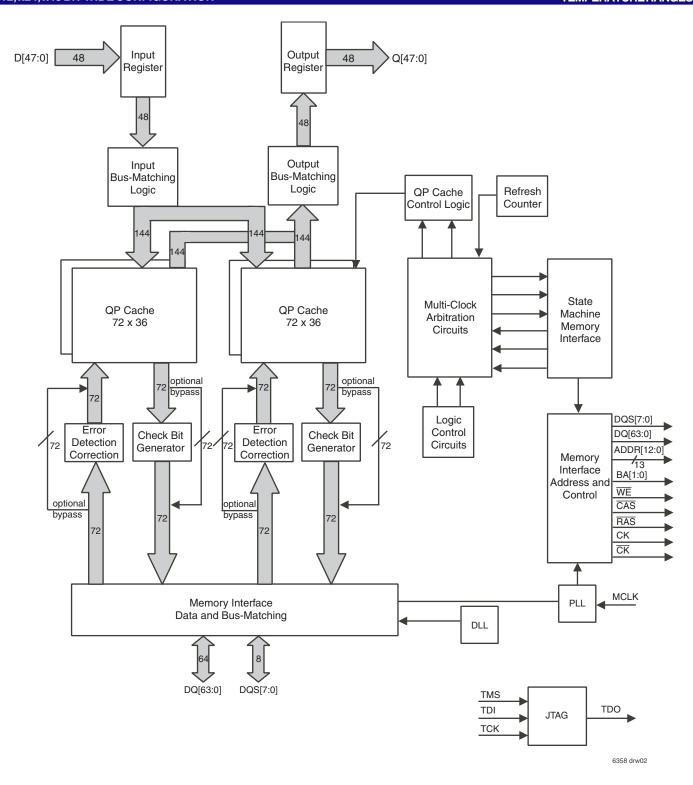
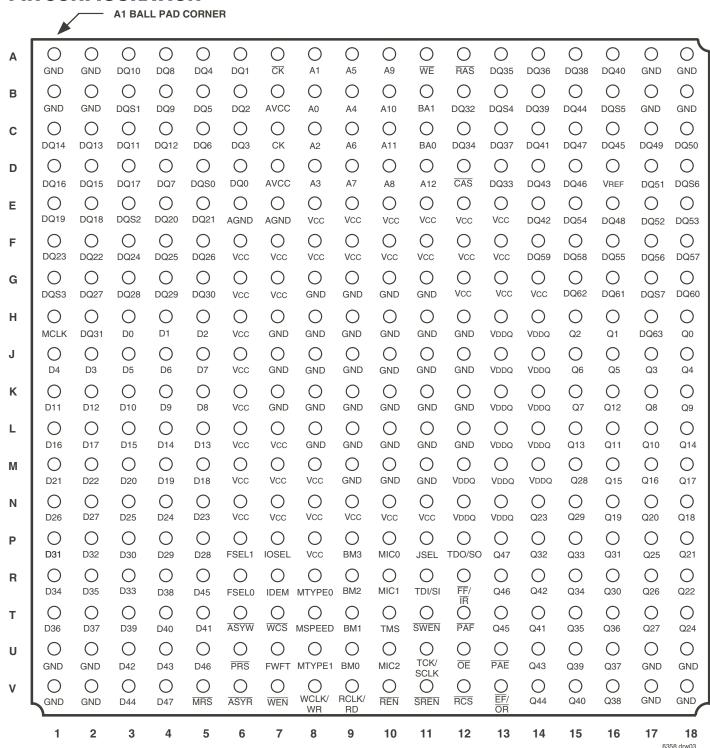


Figure 1. Sequential Flow-Control Device Block Diagram

PIN CONFIGURATION



PBGA (BB324-1, order code: BB) TOP VIEW

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PIN DESCRIPTIONS

		110113		
Symbol	Pin No. Location	Name	I/O TYPE	Description
READ POI	RT INTERFA	CE		
ASYR ⁽¹⁾	V6	Asynchronous Read Port	INPUT 3.3V or 2.5V LVTTL	A HIGH on this input during master reset will select synchronous read operation for the output port. A LOW will select asynchronous operation. If asynchronous is selected the device must operate in IDT Standard mode and the read enable must be tied to GND.
EF/OR	V13	Empty Flag/ Output Ready	OUTPUT 3.3V or 2.5V LVTTL	In IDT Standard mode, the \overline{EF} function is selected. \overline{EF} indicates whether or not the device memory is empty. In FWFT mode, the \overline{OR} function is selected. \overline{OR} indicates whether or not there is valid data available at the outputs.
ŌĒ	U12	Output Enable	INPUT 3.3V or 2.5V LVTTL	Asynchronous three-state control of the data outputs. All data outputs $Q[47:0]$ will be placed in high-impedance if this pin is HIGH. Conversely, all data outputs will be active when this pin is LOW.
PAE	U13	Programmable Almost Empty Flag	OUTPUT 3.3V or 2.5V LVTTL	This is the programmable almost empty flag that can be used as an early indicator for the empty boundary condition of the internal memory. \overline{PAE} goes LOW if the number of words in the sequential flow-control device is less than offset n, which is stored in the empty offset register. \overline{PAE} goes HIGH if the number of words in the sequential flow-control device is greater than or equal to the offset n.
Q[47:0]	See Pin No. table	Data Output Bus	OUTPUT 3.3V or 2.5V LVTTL	Data outputs for a 48, 24, and 12-bit bus.
RCLK/ RD	V9	Read Clock/ Read Strobe	INPUT 3.3V or 2.5V LVTTL	This is a dual function pin. If synchronous operation of the read port is selected, the rising edge of RCLK reads data from the sequential flow-control device when $\overline{\text{REN}}$ is enabled. If asynchronous operation of the read port is selected, a rising edge on RD reads data from the sequential flow-control device without the need of a free-running input read clock.
RCS	V12	Read Chip Select	INPUT 3.3V or 2.5V LVTTL	Synchronous three-state control of the data outputs. Provides another means of controlling the data outputs synchronous to RCLK. Can be regarded as a second output enable signal.
REN	V10	Read Enable	INPUT 3.3V 2.5V LVTTL	REN enables RCLK for reading data from the sequential flow-control device. If asynchronous mode is selected on the read port, this signal should be tied to GND.
SREN	V11	Serial Read Enable	INPUT 3.3V or 2.5V LVTTL	When \overline{SREN} is brought LOW before the rising edge of SCLK, the contents of the \overline{PAE} and \overline{PAF} offset registers are copied to a serial shift register. While \overline{SREN} is maintained LOW, on each rising edge of SCLK, one bit of data is shifted out of this serial shift register through the SO output pin used only when JSEL = 0.
WRITE PO	RT INTERF	4 <i>CE</i>		
ASYW ⁽¹⁾	T6	Asynchronous Write Port	INPUT 3.3V or 2.5V LVTTL	A HIGH on this input during master reset will select synchronous write operation for the input port. A LOW will select asynchronous operation. If asynchronous is selected the device must operate in IDT Standard mode and the write enable must be tied to GND.
D[47:0]	See Pin No. table	Data Inputs	INPUT 3.3V or 2.5V LVTTL	Data inputs for a 48, 24, and 12-bit bus.
FF/IR	R12	Full Flag/ Input Ready	OUTPUT 3.3V or 2.5V LVTTL	In IDT Standard mode, the \overline{FF} function is selected. \overline{FF} indicates whether or not the device memory is full. In FWFT mode, the \overline{IR} function is selected. \overline{IR} indicates whether or not there is space available for writing to the device memory.
PAF	T12	Programmable Almost Full Flag	OUTPUT 3.3V or 2.5V LVTTL	This is the programmable almost full flag that can be used as an early indicator for the full boundary condition of the internal memory. \overline{PAF} goes HIGH if the number of free locations in the sequential flow-control device is more than offset m, which is stored in the full offset register. \overline{PAF} goes LOW if the number of free locations in the sequential flow-control device is less than or equal to the offset m.
SWEN	T11	Serial Write Enable	INPUT 3.3V or 2.5V LVTTL	On each rising edge of SCLK when \overline{SWEN} is LOW, data from the SI pin is serially loaded into the \overline{PAE} and \overline{PAF} registers used only when JSEL = 0.

PIN DESCRIPTIONS (Continued)

Symbol	Pin No. Location	Name	I/O TYPE	Description
WRITE PO	RT INTERF	ACE (Continued)		
WCLKWR	V8	Write Clock/ Write Strobe	INPUT 3.3V or 2.5V LVTTL	This is a dual function pin. If synchronous operation of the write port is selected, the rising edge of WCLK writes data into the sequential flow-control device when $\overline{\text{WEN}}$ is enabled. If asynchronous operation of the write port is selected, a rising edge on WR writes data into the sequential flow-control device without the need of a free-running input write clock.
WCS	Т7	Write Chip Select	INPUT 3.3V or 2.5V LVTTL	Synchronous three-state control of the data inputs. Provides a means of controlling the data inputs synchronous to WCLK. Typically used to avoid bus-contention when multiple devices are sharing the same input data bus.
WEN	V7	Write Enable	INPUT 3.3V or 2.5V LVTTL	WEN enables WCLK for writing data into the sequential flow-control device. If asynchronous mode is selected on the write port, this signal should be tied to GND.
MEMORY	NTERFACE			
A[12:0]	See Pin No. table	Memory Address Bus	OUTPUT SSTL_2	Output address bus to be connected to the input address bus of the external memory to provide row and column address.
BA[1:0]	BA1-B11 BA0-C11	Memory Bank Address Input Bit	OUTPUT SSTL_2	Address bits to be connected to the external memory's BA inputs to determine which bank an ACTIVE, READ, WRITE, or PRECHARGE command is being applied.
CK	C7	Memory Clock	OUTPUT SSTL_2	Clock output to be connected to the external memory's input clock.
CK	A7	Memory Clock Inverted	OUTPUT SSTL_2	Differential clock output to be connected to the external memory's differential input clock.
CAS	D12	Memory Column Address Strobe	OUTPUT SSTL_2	Output enable signal to be connected to the external memory's $\overline{\sf CAS}$ pin to activate and deactivate the column address strobe.
DQ[63:0]	See Pin No. table	Memory Data Bus	Bi-Directional SSTL_2	Input/output data bus for the external memory's data bus.
DQS[7:0]	See Pin No. table	Memory Data Strobe	Bi-Directional SSTL_2	Input/output data strobe to be connected to the external memory's data strobe.
RAS	A12	Memory Row Address Strobe	OUTPUT SSTL_2	Output strobe signal to be connected to the external memory's RAS pin to activate and deactivate the row address strobe.
WE	A11	Memory Write Enable	OUTPUT SSTL_2	Output strobe signal to be connected to the external memory's WE pin to activate and deactivate the write address strobe.
CONTROL	AND FEAT	URE INTERFACE		
BM[3:0] ⁽¹⁾	See Pin No. table	Bus-Matching Bit	INPUT 3.3V or 2.5V LVTTL	Selects the bus width of the read and write ports.
FSEL[1:0] ⁽¹⁾	FSEL1-P6 FSEL0-R6	Flag Select Bit	INPUT 3.3V or 2.5V LVTTL	During master reset, these inputs will select one of four default values for the programmable flags \overline{PAE} and \overline{PAF} . The selected value will apply to both \overline{PAE} and \overline{PAF} offset.
FWFT ⁽¹⁾	U7	First Word Fall Through	INPUT 3.3V or 2.5V LVTTL	During master reset, a HIGH on this input selects FWFT timing mode. A LOW selects IDT Standard timing mode.
IDEM ⁽¹⁾	R7	IDT Standard Mode Depth Expansion Mode Select	INPUT 3.3V or 2.5V LVTTL	This select pin is used for depth expansion configuration in IDT Standard mode. If this pin is tied HIGH, then the $\overline{\text{FF/IR}}$ signal will be inverted to provide a seamless depth expansion interface. If depth expansion in FWFT mode is desired, this pin should be tied to GND. If no depth expansion is used, this pin should be tied to GND.
IOSEL ⁽¹⁾	P7	I/O VDDQ Select	INPUT 3.3V or 2.5V LVTTL	This input determines whether the inputs and outputs will tolerate a 2.5V or 3.3V voltage signals. If IOSEL is HIGH, then all I/Os will be 2.5V tolerant. If IOSEL is LOW, then all I/Os will be 3.3V tolerant. See table 15, for a list of affected I/O signals.

PIN DESCRIPTIONS (Continued)

Symbol	Pin No. Location	Name	I/O TYPE	Description
CONTROL	AND FEAT	URE INTERFACE (C	Continued)	
JSEL ⁽¹⁾	P11	JTAG Select	INPUT 3.3V or 2.5V LVTTL	This pin selects whether the JTAG pins will be used for serial programming. If JSEL is HIGH, the JTAG pins will only be used for JTAG boundary-scan function. If JSEL is LOW, the JTAG function is disabled and the JTAG pins will be used for serial programming of the PAE/PAF offset registers.
MIC[2:0] ⁽¹⁾	MIC2-U10 MIC1-R10 MIC0-P10	Memory Configuration	INPUT 3.3V or 2.5V LVTTL	These signals enable the EDC feature of the device. See Table 8, MIC[2:0] Configurations for details.
MCLK	H1	Master Clock	INPUT 3.3V or 2.5V LVTTL	33MHz reference clock used to generate CK and $\overline{\text{CK}}$ for external memory interface.
MRS	V 5	Master Reset	INPUT 3.3V or 2.5V LVTTL	Master reset initializes the read and write pointers to zero and sets the output register to all zeros. All initialized settings for the device will be configured during master reset.
MSPEED ⁽¹⁾	Т8	Memory Speed	INPUT 3.3V or 2.5V LVTTL	This input select the speed of the external memory interfacing the sequential flow-control device. A LOW selects 133MHz, and HIGH selects 166MHz.
MTYPE ⁽¹⁾ [1:0]		Memory Type [1:0]	INPUT 3.3V or 2.5V LVTTL	These inputs select which type of external memory is interfacing the sequential flow-control device. See Table 14 for the list of selectable memories.
PRS	U6	Partial Reset	INPUT 3.3V or 2.5V LVTTL	Partial reset initializes the read and write pointers to zero and sets the output registers to all zeros. All existing configurations in the sequential flow-control device will not be affected. This includes the IDT Standard or FWFT mode timing, programmable flag settings, and bus width and data rate mode.
TCK/ SCLK	U11	JTAG Clock/ Serial Clock	INPUT 3.3V or 2.5V LVTTL	This is a dual function pin. When the JSEL pin is HIGH, this is the clock input for JTAG boundary-scan function. One of four terminals required by IEEE Standard 1149.1-1990. Test operations of the device are synchronous to TCK. Data from TMS and TDI are sampled on the rising edge of TCK and outputs change on the falling edge of TCK. When the JSEL pin is LOW, this is the serial clock input for writing and reading the $\overline{PAE}/\overline{PAF}$ offset registers. On the rising edge of every SCLK when \overline{SWEN} is LOW, one bit of data from the SI pin is shifted into the \overline{PAE} and \overline{PAF} offset registers. On the rising edge of each SCLK when SREN is LOW, one bit of data from the SO pin is shifted out of the \overline{PAE} and \overline{PAF} offset registers. If the JTAG or serial programming is not used this signal needs to be tied to GND.
TDI/SI	R11	JTAG Test Data Input/ Serial Input	INPUT 3.3V or 2.5V LVTTL	This is a dual function pin. When the JSEL pin is HIGH, this is the JTAG test data input pin. One of four terminals required by IEEE Standard 1149.1-1990. During the JTAG boundary scan operation, test data serially loaded via the TDI on the rising edge of TCK to the Instruction Register, ID Register and Bypass Register. When the JSEL pin is LOW, this is the serial input pin for the PAE/PAF offset registers. An internal pull-up resistor forces TDI/SI HIGH if left unconnected.
TDO/SO	P12	JTAG Test Data Output/Serial Output	OUTPUT 3.3V or 2.5V LVTTL	This is a dual function pin. When the JSEL pin is HIGH, this is the JTAG test data output pin. One of four terminals required by IEEE Standard 1149.1-1990. During the JTAG boundary scan operation, test data serially loaded output via the TDO on the falling edge of TCK from either the Instruction Register, ID Register and Bypass Register. This output is high-impedance except when shifting, while in SHIFT-DR and SHIFT-IR controller states. When the JSEL pin is LOW, this is the serial data output pin for the PAE/PAF offset registers.
TMS	T10	JTAG Mode Select	INPUT 3.3V or 2.5V LVTTL	TMS is a serial input pin. One of four terminals required by IEEE Standard 1149.1-1990. TMS directs the device through its TAP controller states. An internal pull-up resistor forces TMS HIGH if left unconnected.

NOTE: 1. These pins should not change after master reset.

Please see <u>next</u> page for Power & Ground pins and Pin Number Location Table.

PIN DESCRIPTIONS (Continued)

Symbol	Pin No.	Name	I/O TYPE	Description	
	Location				
POWER AND GROUND SIGNALS					
Vcc	See Pin No. table	Core Vcc and Output voltage for DDR SDRAM	Power	The core power supply pins for the device as well as to the external DDR SDRAM. Needs to be connected to a +2.5V Vcc power plane.	
AVcc	B7, D7	Internal PLL Vcc	Power	The power supply pins for the internal PLL of the device. Needs to be connected to a +2.5V supply rail.	
VDDQ	See Pin No. table	Output rail voltage for I/Os	Power	This pin is used to provide power to the output drivers. The nominal values are 2.5V or 3.3V, depending on the state of the IOSEL pin.	
VREF	D16	Reference Voltage	Power	This is a voltage reference input to the SDRAM and must be connected to Vcc/2.	
GND	See Pin table	Ground Pin	Ground	The ground pins for the device that must be connected to the ground plane.	
AGND	E6, E7	Ground pin for analog circuit	Ground	The ground pins for the analog circuitry in the device that must be connected to the ground plane.	

PIN NUMBER LOCATION TABLE

Symbol	Name	I/O TYPE	Pin Number
A[12:0]	Memory Address Bus	OUTPUT SSTL_2	A12-D11, A11-C10, A10-B10, A9-A10, A8-D10, A7-D9, A6-C9, A5-A9, A4-B9, A3-D8, A2-C8, A1-A8, A0-B8
BM[3:0]	Bus-Matching	INPUT 3.3V or 2.5V LVTTL	BM3-P9, BM2-R9, BM1-T9, BM0-U9
D[47:0]	Data Inputs	INPUT 3.3V or 2.5V LVTTL	D47-V4, D46-U5, D45-R5, D44-V3, D43-U4, D42-U3, D41-T5, D40-T4, D39-T3, D38-R4, D37-T2, D36-T1, D35-R2, D34-R1, D33-R3, D32-P2, D31-P1, D30-P3, D29-P4, D28-P5, D27-N2, D26-N1, D25-N3, D24-N4, D23-N5, D22-M2, D21-M1, D20-M3, D19-M4, D18-M5, D17-L2, D16-L1, D15-L3, D14-L4, D13-L5, D12-K2, D11-K1, D10-K3, D9-K4, D8-K5, D7-J5, D6-J4, D5-J3, D4-J1, D3-J2, D2-H5, D1-H4, D0-H3
DQ[63:0]	Memory Data Bus	Bi-Directional SSTL_2	DQ63-H17, DQ62-G15, DQ61-G16, DQ60-G18, DQ59-F14, DQ58-F15, DQ57-F18, DQ56-F17, DQ55-F16, DQ54-E15, DQ53-E18, DQ52-E17, DQ51-D17, DQ50-C18, DQ49-C17, DQ48-E16, DQ47-C15, DQ46-D15, DQ45-C16, DQ44-B15, DQ43-D14, DQ42-E14, DQ41-C14, DQ40-A16, DQ39-B14, DQ38-A15, DQ37-C13, DQ36-A14, DQ35-A13, DQ34-C12, DQ33-D13, DQ32-B12, DQ31-H2, DQ30-G5, DQ29-G4, DQ28-G3, DQ27-G2, DQ26-F5, DQ25-F4, DQ24-F3, DQ23-F1, DQ22-F2, DQ21-E5, DQ20-E4, DQ19-E1, DQ18-E2, DQ17-D3, DQ16-D1, DQ15-D2, DQ14-C1, DQ13-C2, DQ12-C4, DQ11-C3, DQ10-A3, DQ9-B4, DQ8-A4, DQ7-D4, DQ6-C5, DQ5-B5, DQ4-A5, DQ3-C6, DQ2-B6, DQ1-A6, DQ0-D6,
DQS[7:0]	Memory Data Strobe	Bi-Directional SSTL_2	DQS7-G17, DQS6-D18, DQS5-B16, DQS4-B13, DQS3-G1, DQS2-E3, DQS1-B3, DQS0-D5
Q[47:0]	Data Outputs	Output 3.3V or 2.5V LVTTL	Q47-P13, Q46-R13, Q45-T13, Q44-V14, Q43-U14, Q42-R14, Q41-T14, Q40-V15, Q39-U15, Q38-V16, Q37-U16, Q36-T16, Q35-T15, Q34-R15, Q33-P15, Q32-P14, Q31-P16, Q30-R16, Q29-N15, Q28-M15, Q27-T17, Q26-R17, Q25-P17, Q24-T18, Q23-N14, Q22-R18, Q21-P18, Q20-N17, Q19-N16, Q18-N18, Q17-M18, Q16-M17, Q15-M16, Q14-L18, Q13-L15, Q12-K16, Q11-L16, Q10-L17, Q9-K18, Q8-K17, Q7-K15, Q6-J15, Q5-J16, Q4-J18, Q3-J17, Q2-H15, Q1-H16, Q0-H18
Vcc	Core Vcc & Output voltage for DDR SDRAM	Power	E(8-13), F(6-13), G(6,7,12-14), H6, J6, K6, L(6,7), M(6-8), N(6-11), P8
VDDQ	Output rail voltage for I/Os	Power	H(13,14), J(13,14), K(13,14), L(13,14), M(12-14), N(12,13)
GND	Ground Pin	Ground	A(1,2,17,18), B(1,2,17,18), G(8-11), H(7-12), J(7-12), K(7-12), L(8-12), M(9-11), U(1,2,17,18), V(1,2,17,18)

DETAILED DESCRIPTIONS

SEQUENTIAL FLOW-CONTROL STRUCTURE

The IDT sequential flow-control (SFC) device is comprised of three interfaces: input port, output port, and memory interface. The input and output port can operate independently of each other with selectable bus widths of x12, x24, or x48 bits wide. The third interface, or memory interface, is connected directly to an external memory, which can be used to offload data entering the SFC device.

WRITING AND READING FROM THE SEQUENTIAL FLOW-CONTROL DEVICE

Writing into the SFC device is accomplished by setting the write enable signal (\overline{WEN}) and write chip select (\overline{WCS}) low with a free running write clock (WCLK). Data will be written on the rising edge of every WCLK into the Quad-Port (QP) cache of the SFC device. The internal state machine of the device will determine whether to send the data to the DDR SDRAM or send it directly through to the output bus, depending on when the data is to be accessed. This provides "data coherency" and minimizes the path that the data has to travel.

Reading from the SFC device is accomplished by setting the read enable signal (\overline{REN}) and read chip select (\overline{RCS}) low with a free running read clock (RCLK). Data will be sent to the output bus on the rising edge of every RCLK. This data will be accessed either from the QP cache or the external DDR SDRAM.

EXTERNAL MEMORY SELECTION

The DDR SDRAM interface of the SFC device can support DDR SDRAM with standard DDR I specifications. The SFC device can support any external memory within the following characteristics:

Bus width: 16-bit or 32-bit wide
Speed: 133MHz or 166MHz
Density: 128Mb or 256Mb

Table 1 lists the DDR SDRAM minimum specifications that are required to meet the sequential flow-control device requirements. Table 2 lists the memory vendors and associated part numbers of DDR SDRAMs that have been validated by IDT to meet the requirements for the DDR SDRAM interface.

TABLE 1 – DDR SDRAM MINIMUM SPECIFICATIONS

		DDR SDRAM Minimum S	Specifications		
Sym	bol	Parameter	16-bit DDR SDRAM	32-bit DDR SDRAM	Units
tcĸ	CL = 2.5	Clock cycle time	6	n/a	ns
	CL = 3.0		n/a	6	
trfc		Auto refresh command period	75	63	ns
trcd		Active to read/write delay	20	n/a	ns
trp		Precharge comman period	20	18	ns
twr		Write recovery time	15	1.5	ns
trcdrd		Active to read delay	n/a	18	ns
trcdwr		Active to write delay	n/a	9	ns

NOTE:

TABLE 2 – SUPPORTED MEMORY VENDORS

Density	Bus Width	Vendor	Part#
128Mb	32	Samsung	K4D263238"X"-GC45
256Mb	16	Samsung	K4H561638"X"-TCLB3 K4H561638"X"-GCLB3
256Mb	16	Micron	MT46V16M16TG-6T MT46V16M16TG-75
256Mb	16	Infineon	HYB25D256160BTL-6 HYB25D256160BTL-7
256Mb	32	Samsung	K4D553238"X"-JC50

- The part numbers listed above include packages that are recommended and validated by IDT.
 Other packages (such as lead free PCB, FBGA, etc.) may also be used but have not been validated by IDT.
- The letter "X" for Samsung memory part numbers denotes the latest die revision for that particular device. Check with Samsung for the latest updated part number.

^{1.} These are the minimum specifications that the DDR SDRAM must meet.

EXTERNAL MEMORY CONFIGURATIONS

The DDR SDRAM interface of the sequential flow-control (SFC) device has a 64-bit output data bus that provides up to four (16-bit SDRAM) external DDR SDRAM connections. For multiple memory connections, they must be of the same density configuration and speed grade. For example, two device connected cannot consist of one 128Mb and one 256Mb memory nor two 128Mb with one at 100MHz and the other at 133MHz. Below is a summary of the possible configurations:

- One 16-bit device connecting a x16 interface to the DDR SDRAM
- One 32-bit device connecting a x32 interface to the DDR SDRAM

- Two 16-bit devices connecting a x32 interface to the DDR SDRAM
- Two 32-bit devices connecting a x36 interface to the DDR SDRAM
- Two 32-bit devices connecting a x64 interface to the DDR SDRAM
- Three 16-bit devices connecting a x36 interface to the DDR SDRAM
- Four 16-bit devices connecting a x64 interface to the DDR SDRAM

These various configurations determine the storage density of the SFC device. The storage density can range from a minimum of 128Mb to a maximum of 1Gb. Table 3 lists the possible ways to connect the DDR SDRAMs and the number of chipset solutions to obtain the various storage densities.

TABLE 3 – TOTAL POSSIBLE EXTERNAL MEMORY CONFIGURATIONS

Two Chip Solution ⁽¹⁾	Three Chip Solution(1)	Four Chip Solution ⁽¹⁾	Five Chip Solution ⁽¹⁾
⁽²⁾ Configuration 1, 2	(2)Configurations 3, 4, 5	⁽²⁾ Configuration 6	⁽²⁾ Configuration 7
1 x128Mb [4M x 32] Total memory: 128Mb	2 x 128Mb [4M x 32] Total memory: 256Mb	N/A	N/A
1 x 256Mb [8M x 32] Total memory: 256Mb	2 x 256Mb [8M x 32] Total memory: 512Mb	N/A	N/A
1 x 128Mb [8M x 16] Total memory: 128Mb	2 x 128Mb [8M x 16] Total memory: 256Mb	3 x 128Mb [8M x 16] Total memory: 384Mb	4 x 128Mb [8M x 16] Total memory: 512Mb
1 x 256Mb [16M x 16] Total memory: 256Mb	2 x 256Mb [16M x 16] Total memory: 512Mb	3 x 256Mb [16M x 16] Total memory: 768Mb	4 x 256Mb [16M x 16] Total memory: 1Gb

- 1. The chip solution number includes the sequential flow-control device and external DDR SDRAM
- 2. See Figure 2a-2g for the 7 different configurations referenced in the table above.

CONNECTING THE DDR SDRAM

Below are the various chipset solution configurations available to the sequential flow-control device (see Figure 2a-2g). The external memory interface is designed to seamlessly connect one or more DDR SDRAMs. The output signal names should be connected directly to its corresponding input signal on the DDR SDRAM. There are three signals on the DDR SDRAM that must be tied to a static state. CKE, $\overline{\text{CS}}$, and DM. Table 4 outlines how to connect the many interface pins to the DDR SDRAM(s). Figure 3 and 4 are some examples of the memory interface connections for various density configurations. For information on DDR SDRAM layout recommendations, please see IDT application note AN-423.

DDR SDRAM: 128Mb [4Mb x 32] or 256Mb [8Mb x 32]

Total Memory Density: 128Mb or 256Mb **Useable Memory**⁽²⁾: 108Mb or 252Mb



Figure 2a. Configuration 1 - Two Chip Solution

DDR SDRAM: 256Mb [16Mb x 16] Total Memory Density: 256Mb Useable Memory⁽²⁾: 216Mb

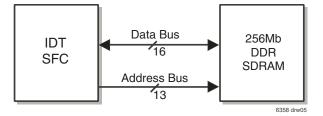


Figure 2b⁽¹⁾. Configuration 2 - Two Chip Solution

DDR SDRAM: 128Mb [4Mb x 32] or 256Mb [8Mb x 32]

Total Memory Density: 256Mb or 512Mb **Useable Memory**⁽²⁾: 216Mb or 504Mb

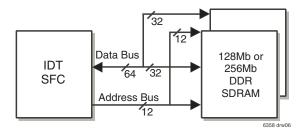


Figure 2c. Configuration 3 - Three Chip Solution

NOTES:

- 1. 12-bit address bus for 8Mb x16
- 13-bit address bus for 16Mb x16
- 2. Refer to Total Available Memory Usage section for details.

DDR SDRAM: 128Mb [4Mb x 32] or 256Mb [8Mb x 32]

Total Memory Density: 256Mb or 512Mb **Useable Memory**⁽²⁾: 108Mb or 252Mb

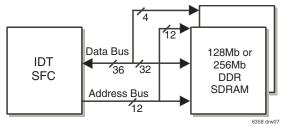


Figure 2d. Configuration 4 - Three Chip Solution

DDR SDRAM: 256Mb [16Mb x 16]
Total Memory Density: 512Mb
Useable Memory⁽²⁾: 504Mb

IDT
SFC
Address Bus

256Mb
DDR
SDRAM

Figure 2e⁽¹⁾. Configuration 5 - Three Chip Solution

DDR SDRAM: 256Mb [16Mb x 16]
Total Memory Density: 768Mb
Useable Memory(2): 567Mb

Data Bus
13

256Mb
DDR
SDRAM
SDRAM

Figure 2f⁽¹⁾. Configuration 6 - Four Chip Solution

DDR SDRAM: 256Mb [16Mb x 16]

Total Memory Density: 1Gb
Useable Memory⁽²⁾: 1008Mb

Data Bus

16

256Mb
DDR
SDRAM

6358 dnw10

Figure 2g⁽¹⁾. Configuration 7 - Five Chip Solution

TABLE 4 – SFC TO DDR SDRAM INTERFACE CONNECTIONS



CONFIGURATION 1

SFC Outputs	DDR SDRAM		
DQ[31:0]	DQ[31:0]		
DQS[3:0]	DQS[3:0]		
A[11:0]	A[11:0]		
CK, CK	CK, CK		
RAS, CAS	RAS, CAS		
BA[1:0]	BA[1:0]		
WE	WE WE		
DDR SDRAM F	lard wired pins		
$\begin{array}{c} \textbf{DDR SDRAM F} \\ \textbf{CKE} \rightarrow \textbf{Vcc} \end{array}$	lard wired pins		
	lard wired pins		
$CKE \rightarrow VCC$			
$\frac{CKE \to Vcc}{\overline{CS} \to GND}$	D		
$\begin{array}{c} CKE \to Vcc \\ \hline \overline{CS} \to GND \\ DM[3:0] \to GNI \end{array}$	D d pins		
$\begin{array}{c} CKE \to Vcc \\ \hline CS \to GND \\ DM[3:0] \to GNI \\ \\ \textbf{SFC Hard wire} \end{array}$	D d pins		



CONFIGURATION 2

 $LDM \rightarrow GND$

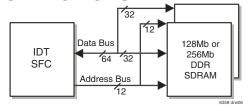
 $\mathsf{UDM} \mathop{\rightarrow} \mathsf{GND}$

SFC Hard wired pins

 $DQ[63:16] \rightarrow VCC$

 $DQS[7:2] \rightarrow VCC$

OOM IOOMATION 2				
SFC Outputs	DDR SDRAM			
DQ[15:0]	DQ[15:0]			
DQS0	LDQS			
DQS1	UDQS			
A[12:0]	A[12:0]			
CK, CK	CK, $\overline{\text{CK}}$			
RAS, CAS	RAS, CAS			
BA[1:0]	BA[1:0]			
WE	WE			
DDR SDRAM Hard wired pins				
$\frac{CKE \to Vcc}{\overline{CS} \to GND}$				



CONFIGURATION 3

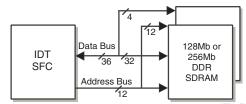
SFC Outputs	DDR SDRAM #1	DDR SDRAM #2			
DQ[31:0]	DQ[31:0]				
DQ[63:32]		DQ[31:0]			
DQS[3:0]	DQS[3:0]				
DQS[7:4]		DQS[3:0]			
A[11:0]	A[11:0]	A[11:0]			
CK, CK	CK, CK	CK, \overline{CK}			
RAS, CAS	RAS, CAS	RAS, CAS			
BA[1:0]	BA[1:0]	BA[1:0]			
WE	WE	WE			
DDD CDDAMAIL I I I I					

DDR SDRAM Hard wired pins

$CKE \rightarrow Vcc$;
$\overline{CS} \to GND$	

$\frac{\mathsf{DM}[3:0] \to \mathsf{GND}}{\mathsf{SFC} \; \mathsf{Hard} \; \mathsf{wired} \; \mathsf{pins}}$

$$A12 \rightarrow VCC$$



CONFIGURATION 4

SFC Outputs	DDR SDRAM #1	DDR SDRAM #2
DQ[31:0]	DQ[31:0]	
DQ[35:32]		DQ[3:0]
DQ[63:36]		
DQS[3:0]	DQS[3:0]	
DQS[7:4]		DQS[3:0]
A[11:0]	A[11:0]	A[11:0]
CK, CK	CK, CK	CK, \overline{CK}
RAS, CAS	RAS, CAS	RAS, CAS
BA[1:0]	BA[1:0]	BA[1:0]
WE	WE	WE

DDR SDRAM Hard wired pins

CKE	\rightarrow	Vcc

 $\overline{\mathsf{CS}} \to \mathsf{GND}$

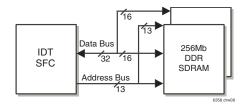
 $DM[3:0] \rightarrow GND$

DQ[31:4] → Vcc

SFC Hard wired pins

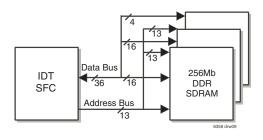
 $A12 \rightarrow VCC$

TABLE 4 – SFC TO DDR SDRAM INTERFACE CONNECTIONS(Continued)



CONFIGURATION 5

SFC Outputs	DDR SDRAM #1	DDR SDRAM #2				
DQ[15:0]	DQ[15:0]					
DQ[31:16]		DQ[15:0]				
DQS0	LDQS					
DQS1	UDQS					
DQS2		LDQS				
DQS3		UDQS				
A[12:0]	A[12:0]	A[12:0]				
CK, \overline{CK}	CK, CK	CK, $\overline{\text{CK}}$				
RAS, CAS	RAS, CAS	RAS, CAS				
BA[1:0]	BA[1:0]	BA[1:0]				
WE	WE	WE				
DDR SDRAM Hard wired pins						
$CKE \rightarrow Vcc$						
$\overline{CS} \to GND$						
$LDM \rightarrow GND$	$LDM \rightarrow GND$					
$UDM \to GND$						
SFC Hard wired pins						
DQ[63:32] → VCC						
$DQS[7:4] \rightarrow VC$	CC					



CONFIGURATION 6

SFC Outputs	DDR SDRAM #1	DDR SDRAM #2	DDR SDRAM #3
DQ[15:0]	DQ[15:0]		
DQ[31:16]		DQ[15:0]	
DQ[35:32]			DQ[3:0]
DQS0	LDQS		
DQS1	UDQS		
DQS2		LDQS	
DQS3		UDQS	
DQS4			LDQS
DQS5			UDQS
A[12:0]	A[12:0]	A[12:0]	A[12:0]
CK, CK	CK, $\overline{\text{CK}}$	CK, CK	CK, $\overline{\text{CK}}$
RAS, CAS	RAS, CAS	RAS, CAS	RAS, CAS
BA[1:0]	BA[1:0]	BA[1:0]	BA[1:0]
WE	WE	WE	WE

DDR SDRAM Hard wired pins

 $\mathsf{CKE} \to \mathsf{Vcc}$

 $\overline{\text{CS}} \to \text{GND}$

 $LDM \rightarrow GND$

 $\mathsf{UDM} \to \mathsf{GND}$

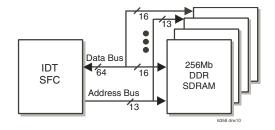
 $DQ[15:4] \rightarrow VCC$

SFC Hard wired pins

 $DQ[63:36] \rightarrow VCC$

 $\mathsf{DQS} [7:6] \to \mathsf{VCC}$

TABLE 4 – SFC TO DDR SDRAM INTERFACE CONNECTIONS(Continued)



CONFIGURATION 7

SFC Outputs	DDR SDRAM #1	DDR SDRAM #2	DDR SDRAM #3	DDR SDRAM #4
DQ[15:0]	DQ[15:0]			
DQ[31:16]		DQ[15:0]		
DQ[47:32]			DQ[15:0]	
DQ[63:48]				DQ[15:0]
DQS0	LDQS			
DQS1	UDQS			
DQS2		LDQS		
DQS3		UDQS		
DQS4			LDQS	
DQS5			UDQS	
DQS6				LDQS
DQS7				UDQS
A[12:0]	A[12:0]	A[12:0]	A[12:0]	A[12:0]
CK, CK	CK, CK	CK, CK	CK, CK	CK, \overline{CK}
RAS, CAS	RAS, CAS	RAS, CAS	RAS, CAS	RAS, CAS
BA[1:0]	BA[1:0]	BA[1:0]	BA[1:0]	BA[1:0]
WE	WE	WE	WE	WE

DDR SDRAM Hard wired pins

 $\mathsf{CKE} \to \mathsf{Vcc}$

 $\overline{\text{CS}} \rightarrow \text{GND}$

 $\mathsf{LDM} \mathop{\rightarrow} \mathsf{GND}$

 $\mathsf{UDM} \mathop{\rightarrow} \mathsf{GND}$

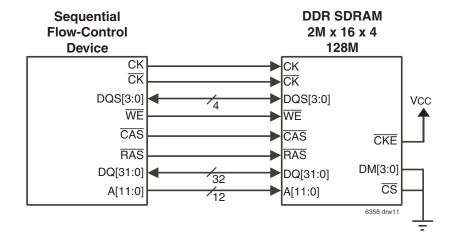


Figure 3. Memory Interface Connection (Single Chip)

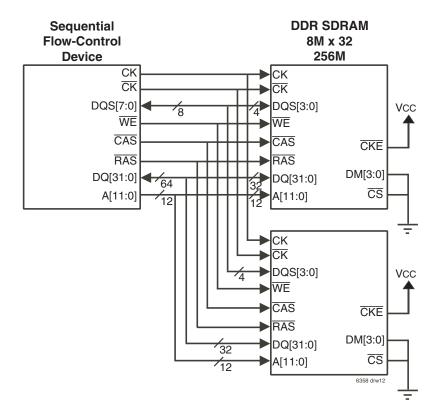


Figure 4. Memory Interface Connection (Two Chip)

TOTAL AVAILABLE MEMORY USAGE

The sequential flow-control (SFC) is designed to efficiently use as much of the DDR SDRAM memory as possible, but due to the discontinuity between the SFC bus width (x48) and the DDR SDRAM interface (x16 or x32), some columns in a row of the SDRAM will not be used. As a result, the total usable memory will be slightly less than the total available memory in the SDRAM. Table 5 outlines the total usable memory for the various configurations depending on

whether or not the Error Detection and Correction (EDC) feature is selected. If the EDC feature is selected, 8 syndrome bits will be generated per every 64 bits of data. Therefore every third write burst to the SDRAM will send out the 8 syndrome bits, resulting in 24 unused bits in the column. Therefore, using the EDC feature, there will be significantly less usable memory of data storage. The EDC function is described in the Error Detection and Correction section of this datasheet.

TABLE 5 – TOTAL USEABLE MEMORY BASED ON VARIOUS CONFIGURATIONS

	Total DDR SDRAM Density	Total Usable Memory (EDC off)	Total Usable Memory (EDC on)	
Configuration 1				
1 x [4Mb x 32]	128Mb	108Mb	72Mb	
1 x [8Mb x 32]	256Mb	252Mb	144Mb	
Configuration 2				
1 x [16Mb x 16]	256Mb	216Mb	144Mb	
Configuration 3				
2 x [4Mb x 32]	256Mb	216Mb	144Mb	
2 x [8Mb x 32]	512Mb	504Mb	288Mb	
Configuration 4				
2 x [4Mb x 32]	256Mb	122Mb	108Mb	
2 x [8Mb x 32]	512Mb	284Mb	252Mb	
Configuration 5				
2 x [8Mb x 16]	256Mb	252Mb	144Mb	
Configuration 6				
3 x [8Mb x 16]	384Mb	284Mb	252Mb	
3 x [16Mb x 16]	3 x [16Mb x 16] 768Mb		504Mb	
Configuration 7				
4 x [16Mb x 16]	1Gb	1008Mb	576Mb	

MAXIMUM I/O OPERATING FREQUENCY

The sequential flow-control (SFC) device is designed to operate at the maximum frequency of 133MHz. There are certain configurations however, that can increase or decrease the maximum frequency of the input and output ports. In some configurations (e.g. x24 I/O width), the I/O speeds can run up to

166MHz. The main factors that determine the usable memory are the I/O buswidth of the SFC, the density and number of DDR SDRAMs connected, and whether or not EDC is used. Tables 6 and 7 lists the maximum frequency for the input and output ports of the SFC based on the various configurations.

TABLE 6 – IDT72T6480 MAXIMUM FREQUENCY BASED ON 166MHz DDR SDRAM

	Bus-Width x48		Bus-Width x24		Bus-Width x12	
	EDC On	EDC Off	EDC On	EDC Off	EDC On	EDC Off
Configuration 1	50MHz	66MHz	100MHz	133MHz	166MHz	166MHz
Configuration 2	33MHz	33MHz	66MHz	66MHz	133MHz	133MHz
Configuration 3	100MHz	133MHz	166MHz	166MHz	166MHz	166MHz
Configuration 4	66MHz	66MHz	133MHz	133MHz	166MHz	166MHz
Configuration 5	50MHz	66MHz	100MHz	133MHz	166MHz	166MHz
Configuration 6	66MHz	66MHz	133MHz	133MHz	166MHz	166MHz
Configuration 7	100MHz	133MHz	166MHz	166MHz	166MHz	166MHz

TABLE 7 – IDT72T6480 MAXIMUM FREQUENCY BASED ON 133MHz DDR SDRAM

	Bus-Width x48		Bus-Width x24		Bus-Width x12	
	EDC On	EDC Off	EDC On	EDC Off	EDC On	EDC Off
Configuration 1	33MHz	50MHz	66MHz	100MHz	133MHz	166MHz
Configuration 2	25MHz	25MHz	50MHz	66MHz	100MHz	133MHz
Configuration 3	66MHz	100MHz	133MHz	166MHz	166MHz	166MHz
Configuration 4	50MHz	50MHz	100MHz	100MHz	166MHz	166MHz
Configuration 5	33MHz	50MHz	66MHz	100MHz	133MHz	166MHz
Configuration 6	50MHz	50MHz	100MHz	100MHz	166MHz	166MHz
Configuration 7	66MHz	100MHz	133MHz	166MHz	166MHz	166MHz

ERROR DETECTION AND CORRECTION

The Error Detection and Correction (EDC) feature is available to ensure data integrity between the DDR SDRAM interface and the SFC. The EDC corrects all single bit hard and soft errors that are accessed from the DDR SDRAM. Multiple bit errors are not detected nor corrected.

The EDC logic blocks consist of a check bit generator and error detection correction logic. When the EDC is enabled, the check bit generator will generate 8 syndrome bits on the 8-byte boundary. The 8 syndrome bits are written into the DDR SDRAM along with the data. The SFC will burst write two cycles for data, and one cycle for syndrome bits. In order to minimize overhead and

increase throughput, not all memory in the DDR SDRAM is utilized. Table 5 lists the total usable memory for all 7 configurations when the EDC is enabled.

When a read operation is performed, the syndrome bits will be transferred to the error detection correction logic block and decoded to determine whether there are any single bit errors on the data. Single bit errors will be corrected and data is passed through to the QP cache.

The EDC is enabled using the MIC[2:0] pins. When the EDC is enabled, the dynamics of the total usable memory in the DDR SDRAM and the SFC operating speed will vary, listed in Tables 6 and 7. Table 8 shows how to enable the EDC feature for the 7 configurations

TABLE 8 - MIC[2:0] CONFIGURATIONS

	EDC Off	EDC On
Configuration 1	MIC [2:0] = 000	MIC [2:0] = 010
Configuration 2	MIC [2:0] = 001	MIC [2:0] = 011
Configuration 3	MIC [2:0] = 111	MIC [2:0] = 101
Configuration 4	MIC [2:0] = 100	MIC [2:0] = 110
Configuration 5	MIC [2:0] = 000	MIC [2:0] = 010
Configuration 6	MIC [2:0] = 100	MIC [2:0] = 110
Configuration 7	MIC [2:0] = 111	MIC [2:0] = 101

SETTING THE MEMORY INTERFACE SIGNALS

The configurations listed in Figure 2a-2g can be programmed into the sequential flow-control device by using the MIC[2:0], MTYPE[1:0], and

MSPEED. For information about these signals, please refer to the Signal Description section. Table 9 is a list that shows the settings for the different configurations.

TABLE 9 – MEMORY CONFIGURATIONS SETTINGS

	MIC[2:0]	MTYPE[1:0]	MSPEED
Configuration 1	000 - EDC Off	00 - (4Mb x 32)	0 - 133MHz
_	010 - EDC On	10 - (8Mb x 32)	1 - 166MHz
Configuration 2	001 - EDC Off	_	0 - 133MHz
	011 - EDC On	11 - (16Mb x 16)	1 - 166MHz
Configuration 3	111 - EDC Off	00 - (4Mb x 32)	0 - 133MHz
	101 - EDC On	10 - (8Mb x 32)	1 - 166MHz
Configuration 4	110 - EDC Off	00 - (4Mb x 32)	0 - 133MHz
	100 - EDC On	10 - (8Mb x 32)	1 - 166MHz
Configuration 5	000 - EDC Off	_	0 - 133MHz
	010 - EDC On	11 - (16Mb x 16)	1 - 166MHz
Configuration 6	110 - EDC Off	_	0 - 133MHz
	100 - EDC On	11 - (16Mb x 16)	1 -166MHz
Configuration 7	111 - EDC Off	_	0 - 133MHz
	101 - EDC On	11 - (16Mb x 16)	1 - 166MHz

TABLE 10 – DEVICE CONFIGURATION

Signal Pins	Static State	Configuration
ĀSYR	0 1	Read port configured in asynchronous mode Read port configured in synchronous mode
ĀSYW	0 1	Write port configured in asynchronous mode Write port configured in synchronous mode
BM[3:0]	_	See Table 13 - Bus-Matching Configurations
FSEL[1:0]	00 01 10 11	Programmable flag register offset value = 127 Programmable flag register offset value = 1,023 Programmable flag register offset value = 4,095 Programmable flag register offset value = 16,383
FWFT	0 1	IDT Standard mode FWFT mode
IDEM	0 1	Depth expansion in FWFT mode Depth expansion in IDT Standard mode
IOSEL	0 1	I/O voltage set to 3.3V levels I/O voltage set to 2.5V levels
JSEL	0 1	JTAG function is disabled JTAG function is enabled
MIC[2:0]	_	See Table 8 - MIC[2:0] Configurations for description
MSPEED	0 1	External memory interface clocks set to 133MHz External memory interface clocks set to 166MHz
MTYPE[1:0]	00 01 10 11	External memory configuration is: 4M x 32 Not used External memory configuration is: 8M x 32 External memory configuration is: 16M x 16

TABLE 11-DEFAULT PROGRAMMABLE FLAG OFFSETS

FSEL1	FSEL0	Offset n,m
0	0	127
0	1	1,023
1	0	4,095
1	1	16,383

FUNCTIONAL DESCRIPTIONS

MASTER RESET AND DEVICE CONFIGURATION

During master reset the sequential flow-control configuration and settings are determined, this includes the following:

- 1. Synchronous or Asynchronous read and write port operation
- 2. Bus-width configuration
- 3. Default offset register values
- 4. IDT standard or first word fall through (FWFT) timing mode
- 5. Depth expansion in IDT standard or FWFT mode
- 6. I/O voltage set to 2.5V or 3.3V levels
- 7. JTAG function enabled or disabled
- 8. Configuration of the external memory interface

The state of the configuration inputs during master reset will determine which of the above modes are selected. A master reset comprises of pulsing the $\overline{\text{MRS}}$ input pin from high to low for a period of time (trs) with the configuration inputs held in their respective states. Table 10, Device Configuration summarizes the configuration modes available during master reset. These signals are described in detail in the signal description section.

PROGRAMMABLE ALMOST EMPTY/ALMOST FULL FLAGS

The SFC has a set of programmable flags (PAE/PAF) that can be used as an early indicator for the empty and full boundary conditions. These flags have an offset value (n, m) that will determine the almost empty and almost full boundary conditions. There are four default offset values selectable during master reset, these values are shown in Table 11, Default Programmable Flag Offsets.

Offset values can also be programmed using the serial programming pins (SCLK, SI, and \$\overline{SWEN}\$). The SFC has two internal offset registers that are used to store the specific offset value, one for the \$\overline{PAE}\$ and one for the \$\overline{PAF}\$. The total number of bits (shown in Table 12, Number of Bits Required for Offset Registers) must be completely programmed to the offset registers. The serial programming sequence begins by writing data into the \$\overline{PAE}\$ register followed by the \$\overline{PAF}\$ register. See Figure 29, \$Social Loading of Programmable Flag Registers for the associated timing diagram. The total number of bits required to program the offset registers will vary depending on the type of configuration that is shown in Figure 2a-2q, the bus-width selected, and whether EDC is used.

The values of n, m are used such that the \overline{PAE} will become active (LOW) when there are at least one to nwords written in the device. Similarly \overline{PAF} will become active (LOW) when there are at least D – M words or more in the device, where D is the density of the SFC.

TABLE 12– NUMBER OF BITS REQUIRED FOR OFFSET REGISTERS

Write Port Bus-Width	x4	x48		x48 x24		x12	
	EDC On	EDC Off	EDC On	EDC Off	EDC On	EDC Off	
Configuration 1 (128Mb)	21	22	22	23	23	24	
Configuration 1 (256Mb)	22	23	23	24	24	25	
Configuration 2 (256Mb)	22	23	23	24	24	25	
Configuration 3 (256Mb)	22	23	23	24	24	25	
Configuration 3 (512Mb)	23	24	24	25	25	26	
Configuration 4 (256Mb)	22	22	23	23	24	24	
Configuration 4 (512Mb)	23	23	24	24	25	25	
Configuration 5 (512Mb)	23	24	24	25	25	26	
Configuration 6 (768Mb)	24	24	25	25	26	26	
Configuration 7 (1Gb)	24	25	25	26	26	27	

SIGNAL DESCRIPTIONS INPUTS

DATA INPUTS (Do - D47)

Data inputs for 48-bit wide data (Do - D47), data inputs for 24-bit wide data (Do - D23) or data inputs for 12-bit wide data (Do - D11).

CONTROLS

MASTER RESET (MRS)

A Master Reset is accomplished whenever the $\overline{\text{MRS}}$ input is toggled LOW then HIGH. This operation sets the internal read and write pointers to the first location of the RAM array. $\overline{\text{PAE}}$ will go LOW, $\overline{\text{PAF}}$ will go HIGH.

If FWFT is LOW during Master Reset then the IDT Standard mode, along with \overline{EF} and \overline{FF} are selected. \overline{EF} will go LOW and \overline{FF} will go HIGH. If FWFT is HIGH, then the First Word Fall Through mode (FWFT), along with \overline{IR} and \overline{OR} , are selected. \overline{OR} will go HIGH and \overline{IR} will go LOW.

All configuration control signals must be set prior to the LOW to HIGH transition of $\overline{\text{MRS}}$.

During a Master Reset, the output register is initialized to all zeroes. A Master Reset is required after power up, before a write operation can take place. $\overline{\text{MRS}}$ is an asynchronous function.

See Figure 6, Master Reset and Initialization, for the relevant timing diagram.

PARTIAL RESET (PRS)

A Partial Reset is accomplished whenever the PRS input is toggled LOW then HIGH. As in the case of the Master Reset, the internal read and write pointers are set to the first location of the RAM array, PAE goes LOW, and PAF goes HIGH.

Whichever mode is active at the time of Partial Reset, IDT Standard mode or First Word Fall Through, that mode will remain selected. If the IDT Standard mode is active, then $\overline{\text{FF}}$ will go HIGH and $\overline{\text{EF}}$ will go LOW. If the First Word Fall Through mode is active, then $\overline{\text{OR}}$ will go HIGH, and $\overline{\text{IR}}$ will go LOW.

Following Partial Reset, all values held in the offset registers remain unchanged. The output register is initialized to all zeroes. PRS is asynchronous. A Partial Reset is useful for resetting the device during the course of operation, when reprogramming programmable flag offset settings may not be convenient.

See Figure 7, *Partial Reset*, for the relevant timing diagram.

ASYNCHRONOUS WRITE (ASYW)

The write port can be configured for either synchronous or asynchronous mode of operation. If during Master Reset the $\overline{\text{ASYW}}$ input is LOW, then asynchronous operation of the write port will be selected. During asynchronous operation of the write port the WCLK input becomes WR input, this is the asynchronous write strobe input. A rising edge on WR will write data present on the data inputs into the sequential flow-control device (SFC). $\overline{\text{(WEN)}}$ must be LOW when using the write port in asynchronous mode).

When the write port is configured for asynchronous operation the device must be operating on IDT standard mode, FWFT mode is not permissable. The full flag ($\overline{\text{FF}}$) and programmable almost full flag ($\overline{\text{PAF}}$) operates in an asynchronous manner, that is, the full flag and $\overline{\text{PAF}}$ flag will be updated based in both a write operation and read operation. Note, if asynchronous mode is selected, FWFT is not permissible. Refer to Figure 24, Asynchronous Write and $\overline{\text{PAF}}$ flag – IDT Standard mode and Figure 25, Asynchronous Write and $\overline{\text{PAF}}$ flag – IDT Standard mode for relevant timing and operational waveforms.

ASYNCHRONOUS READ (ASYR)

The read port can be configured for either synchronous or asynchronous mode of operation. If during a Master Reset the $\overline{\text{ASYR}}$ input is LOW, then

asynchronous operation of the read port will be selected. During asynchronous operation of the read port the RCLK input becomes RD input, this is the asynchronous read strobe input. A rising edge on RD will read data from the SFC via the output register and data output port. (\overline{REN} must be tied LOW during asynchronous operation of the read port).

The $\overline{\text{OE}}$ input provides three-state control of the Qn output bus, in an asynchronous manner.

When the read port is configured for asynchronous operation the device must be operating on IDT standard mode, FWFT mode is not permissible if the read port is asynchronous. The Empty Flag ($\overline{\text{EF}}$) and programmable almost empty flag ($\overline{\text{PAF}}$) operates in an asynchronous manner, that is, the empty flag and $\overline{\text{PAE}}$ will be updated based on both a read operation and a write operation. Refer to Figure 23, Asynchronous Read and $\overline{\text{PAF}}$ flag – IDT Standard mode, Figure 26, Asynchronous Empty Boundary – IDT Standard mode, Figure 27, Asynchronous Full Boundary – IDT Standard mode, and Figure 28, Asynchronous Read and $\overline{\text{PAE}}$ flag – IDT Standard mode, for relevant timing and operational waveforms.

FIRST WORD FALL THROUGH (FWFT)

During Master Reset, the state of the FWFT input determines whether the device will operate in IDT standard mode or First Word Fall Through (FWFT) mode.

If, at the time of Master Reset, FWFT is LOW, then IDT Standard mode will be selected. This mode uses the Empty Flag ($\overline{\text{EF}}$) to indicate whether or not there are any words present in the SFC. It also uses the Full Flag function ($\overline{\text{FF}}$) to indicate whether or not the SFC has any free space for writing. In IDT Standard mode, every word read from the SFC, including the first, must be requested using the Read Enable ($\overline{\text{REN}}$) and RCLK.

If, at the time of Master Reset, FWFT is HIGH, then FWFT mode will be selected. This mode uses Output Ready (\overline{OR}) to indicate whether or not there is valid data at the data outputs (Q_n) . It also uses Input Ready (\overline{IR}) to indicate whether or not the SFC has any free space for writing. In the FWFT mode, the first word written to an empty SFC goes directly to Q_n after three RCLK rising edges, \overline{REN} = LOW is not necessary. Subsequent words must be accessed using the Read Enable (\overline{REN}) and RCLK.

WRITE STROBE AND WRITE CLOCK (WR/WCLK)

If synchronous operation of the write port has been selected via $\overline{\text{ASYW}}$, this input behaves as WCLK.

A write cycle is initiated on the rising edge of the WCLK input. Data setup and hold times must be met with respect to the LOW-to-HIGH transition of the WCLK. It is permissible to stop the WCLK. Note that while WCLK is idle, the $\overline{FF/IR}$, and \overline{PAF} flags will not be updated. The Write and Read Clocks can either be independent or coincident.

If asynchronous operation has been selected this input is WR (write strobe). Data is asynchronously written into the SFC via the Dn inputs whenever there is a rising edge on WR. In this mode the \overline{WEN} input must be LOW.

WRITE ENABLE (WEN)

When the WEN input is LOW, data may be loaded into the SFC on the rising edge of every WCLK cycle if the device is not full. Data is stored in the RAM array sequentially and independently of any ongoing read operation.

When WEN is HIGH, no new data is written in the SFC.

To prevent data overflow in the IDT Standard mode, \overline{FF} will go LOW, inhibiting further write operations. Upon the completion of a valid read cycle, \overline{FF} will go HIGH allowing a write to occur. The \overline{FF} is updated by two WCLK cycles + tskew after the RCLK cycle.

To prevent data overflow in the FWFT mode, \overline{IR} will go HIGH, inhibiting further write operations. Upon the completion of a valid read cycle, \overline{IR} will go LOW allowing a write to occur. The \overline{IR} flag is updated by two WCLK cycles + tskew after the valid RCLK cycle.

WEN is ignored when the SFC is full in either FWFT or IDT Standard mode. If asynchronous operation of the write port has been selected, then WEN must be held active.

READ STROBE AND READ CLOCK (RD/RCLK)

If synchronous operation of the read port has been selected via \overline{ASYR} , this input behaves as RCLK. A read cycle is initiated on the rising edge of the RCLK input. Data can be read on the outputs, on the rising edge of the RCLK input. It is permissible to stop the RCLK. Note that while RCLK is idle, the $\overline{EF/OR}$ and \overline{PAE} flags will not be updated. The Write and Read Clocks can be independent or coincident.

If asynchronous operation has been selected this input is RD (Read Strobe). Data is asynchronously read from the SFC whenever there is a rising edge on RD. In this mode the \overline{REN} and \overline{RCS} inputs must be tied LOW. The \overline{OE} input is used to provide asynchronous control of the three-state Qn outputs.

WRITE CHIP SELECT (WCS)

The WCS disables all Write data operations (data only) if it is held HIGH. To perform normal operations on the write port, the WCS must be enabled, held LOW.

READ ENABLE (REN)

When Read Enable is LOW, data is loaded from the RAM array into the output register on the rising edge of every RCLK cycle if the device is not empty.

When the $\overline{\text{REN}}$ input is HIGH, the output register holds the previous data and then no new data is loaded into the output register. The data outputs Qo-Qn maintain the previous data value.

In the IDT Standard mode, every word accessed at Qn, including the first word written to an empty cache, must be requested using \overline{REN} provided that \overline{RCS} is LOW. When the last word has been read from the SFC, the Empty Flag (\overline{EF}) will go LOW, inhibiting further read operations. \overline{REN} is ignored when the SFC is empty. Once a write is performed, \overline{EF} will go HIGH allowing a read to occur. The \overline{EF} flag is updated by two RCLK cycles + tskEw after the valid WCLK cycle. Both \overline{RCS} and \overline{REN} must be active, LOW for data to be read out on the rising edge of RCLK.

In the FWFT mode, the first word written to an empty SFC automatically goes to the outputs Qn, on the third valid LOW-to-HIGH transition of RCLK + tskew after the first write. \overline{REN} and \overline{RCS} do not need to be asserted LOW for the First Word to fall through to the output register. In order to access all other words, a read must be executed using \overline{REN} and \overline{RCS} . The RCLK LOW-to-HIGH transition after the last word has been read from the SFC, Output Ready (\overline{OR}) will go HIGH with a true read (RCLK with \overline{REN} = LOW; \overline{RCS} = LOW), inhibiting further read operations. \overline{REN} is ignored when the SFC is empty.

If asynchronous operation of the Read port has been selected, then REN must be held active, (LOW).

OUTPUT ENABLE (OE)

When Output Enable is enabled (LOW), the parallel output buffers receive data from the output register. When \overline{OE} is HIGH, the output data bus (Qn) goes into a high impedance state. During Master or a Partial Reset the \overline{OE} is the only input that can place the output bus Qn, into High-Impedance. During Reset the \overline{RCS} input can be HIGH or LOW, it has no effect on the Qn outputs.

READ CHIP SELECT (RCS)

The Read Chip Select input provides synchronous control of the Read output port. When \overline{RCS} goes LOW, the next rising edge of RCLK causes the Qnoutputs to go to the Low-Impedance state. When \overline{RCS} goes HIGH, the next RCLK rising edge causes the Qnoutputs to return to HIGHZ. During a Master or Partial Reset the \overline{RCS} input has no effect on the Qnoutput bus, \overline{OE} is the only input that provides High-Impedance control of the Qn outputs. If \overline{OE} is LOW the Qn data outputs will be Low-Impedance regardless of \overline{RCS} until the first rising edge of RCLK after a Reset is complete. Then if \overline{RCS} is HIGH the data outputs will go to High-Impedance.

The \overline{RCS} input does not effect the operation of the flags. For example, when the first word is written to an empty SFC, the \overline{EF} will still go from LOW to HIGH based on a rising edge of RCLK, regardless of the state of the \overline{RCS} input.

Also, when operating the SFC in FWFT mode the first word written to an empty SFC will still be clocked through to the output register based on RCLK, regardless of the state of \overline{RCS} . For this reason the user must take care when a data word is written to an empty SFC in FWFT mode. If \overline{RCS} is disabled when an empty SFC is written into, the first word will fall through to the output register, but will not be available on the Qn outputs which are in HIGH-Z. The user must take \overline{RCS} active LOW to access this first word, place the output bus in LOW-Z. \overline{REN} must remain disabled HIGH for at least one cycle after \overline{RCS} has gone LOW. A rising edge of RCLK with \overline{RCS} and \overline{REN} active LOW, will read out the next word. Care must be taken so as not to lose the first word written to an empty SFC when \overline{RCS} is HIGH. See Figure 15 for Read Chip Select. If asynchronous operation of the Read port has been selected, then \overline{RCS} must be held active, (tied LOW). \overline{OE} provides three-state control of Qn.

BUS-MATCHING (BM[3:0])

These pins are used to define the input and output bus widths. During Master Reset, the state of these pins is used to configure the device bus sizes. All flags will operate on the word/byte size boundary as defined by the selection of bus width. See Figures 17-20 for *Bus-Matching Configurations*. See Table 13, Bus-Matching Configurations for the available configurations.

TABLE 13 – BUS-MATCHINGS

BM3	BM2	BM1	BM0	Read Bus Width	Write Bus Width
1	0	0	0	х48	х48
1	0	0	1	x24	x48
1	1	0	1	x12	х48
1	0	1	1	х48	x24
1	1	1	1	х48	x12
0	0	0	1	x24	x24
0	1	0	1	x12	x24
0	0	1	1	x24	x12
0	1	1	1	x12	x12

FLAG SELECT (FSEL[1:0])

During master reset, these inputs will select one of four default values for the programmable flags \overline{PAE} and \overline{PAF} . The selected value (listed in Table 14 - MTYPE[1:0] Configurations) will apply to both \overline{PAE} and \overline{PAF} offset.

MEMORY CONFIGURATION (MIC[2:0])

These signals enable the EDC feature of the device. See Table 8, MIC[2:0] Configurations for more information.

MEMORY SPEED (MSPEED)

This pin is used to determine the memory interface clock speed (CK and $\overline{\text{CK}}$) for the external memory used. If MSPEED is HIGH, external memory CK and $\overline{\text{CK}}$ will be operating at 166MHz. If MSPEED is LOW, then the external memory CK and $\overline{\text{CK}}$ will be operating at 133MHz.

MASTER CLOCK (MCLK)

33MHz reference clock used to generate CK and $\overline{\text{CK}}$ for external memory interface.

MEMORY TYPE (MTYPE[1:0])

These signals select the density configuration of the external DDR SDRAM used. See Table 14, MTYPE [1:0] Configurations for selection of the memory density configuration.

TABLE 14-MTYPE[1:0] CONFIGURATIONS

	D	Density Configurations					
	4M x 32	4M x 32 8M x 32 Reserved 16M x 16					
MTYPE0	0	0	1	1			
MTYPE1	1						

DEPTH EXPANSION MODE SELECT (IDEM)

This select pin is used for depth expansion configuration in IDT Standard mode. If this pin is tied HIGH, then the $\overline{\text{FF}/\text{IR}}$ signal will be inverted to provide a seamless depth expansion interface. If this pin is tied LOW, the depth expansion in IDT Standard mode will be deactivated. For details on depth expansion configuration, see Figure 34, Depth Expansion Configuration in IDT Standard Mode and Figure 35, Depth Expansion Configuration in FWFT Mode.

SERIAL READ ENABLE (SREN)

The serial read enable input is an enable used for reading the value of the programmable offset registers. By setting the JSEL pin to LOW, the serial data output (SO) and serial clock (SCLK) signals can be used with \overline{SREN} to program the offset registers. When \overline{SREN} is LOW, data at the SO can be read from the offset register, one bit for each LOW-to-HIGH transition of SCLK. When serial read enable is HIGH, the reading of the offset registers will stop. \overline{SREN} must be kept LOW in order to read the entire contents of the scan out register. If at any point \overline{SREN} is toggled HIGH, the read pointer of the offset registers will reset to the first location. The next time \overline{SREN} is enabled the first contents in the offset register will be read back. Serial read enable functions the same way in both IDT Standard and FWFT modes. See Figure 30, Reading of Programmable Flag Registers, for the timing diagram.

SERIAL WRITE ENABLE (SWEN)

The serial write enable input is an enable used for serial programming of the programmable offset registers. By setting the JSEL pin to LOW, the serial input (SI) and serial clock (SCLK) signals can be used with $\overline{\text{SWEN}}$ to program the offset registers. When $\overline{\text{SWEN}}$ is LOW, data at the SI input are loaded into the offset register, one bit for each LOW-to-HIGH transition of SCLK. When $\overline{\text{SWEN}}$ is HIGH, the offset registers retain the previous settings and no offsets are loaded. Serial write enable functions the same way in both Standard IDT and FWFT

modes. See Figure 29, *Serial Loading of Programmable Flag Registers*, for the timing diagram.

I/O VDDQ SELECT (IOSEL)

This input determines whether the inputs and outputs will tolerate a 2.5V or 3.3V voltage signals. If IOSEL is HIGH, then all I/Os will be 2.5V levels. If IOSEL is LOW, then all I/Os will be 3.3V levels. See Table 15, Parameters affected by I/O selection for a list of affected I/O signals.

TABLE 15 – PARAMETERS AFFECTED BY I/O SELECTION

SFCI/O	SFC I/O affected by I/O selection			ORAM I/O - Iffected ⁽¹⁾
ASYR ASYW BM[3:0] D[47:0] EF/OR FF/IR FSEL[1:0] FWFT IDEM IOSEL JSEL	MIC[2:0] MCLK MRS MSPEED MTYPE[1:0] OE PAE PAF PRS Q[47:0] RCLK/RD	RCS REN SREN SWEN TCK/SCLK TDI/SI TDO/SO TMS WCLK/WR WCS WEN	A[12:0] BA[1:0] CK CK CAS	DQ[63:0] DQS[7:0] RAS WE

NOTE:

1. I/O to DDR SDRAM is not affected by I/O voltage selection

JTAG SELECT (JSEL)

This input determines whether the JTAG port will be activated or deactivated. If JSEL is HIGH, then the JTAG port is activated and the associated JTAG pins (TCK, TDI, TDO, TMS) are used for the boundary-scan function. If JSEL is LOW, the JTAG port is disabled and the serial programming pins (SCLK, SI, SO) will be used to program and read the offset register values for \overline{PAE} and \overline{PAF} . See Figure 29 and 30, Serial Loading and Reading of Programmable Registers for information on how to program the registers.

OUTPUTS

FULL FLAG/INPUT READY (FF/IR)

This is a dual purpose pin. In IDT Standard mode, the Full Flag (\overline{FF}) function is selected. When the SFC is full, \overline{FF} will go LOW, inhibiting further write operations. When \overline{FF} is HIGH, the SFC is not full. If no reads are performed after a reset (either \overline{MRS} or \overline{PRS}), \overline{FF} will go LOW See *Figure 12*, *Full Boundary - IDT Standard Mode*, for the relevant timing information.

In FWFT mode, the Input Ready ($\overline{\mathbb{R}}$) function is selected. $\overline{\mathbb{R}}$ goes LOW when memory space is available for writing in data. When there is no longer any free space left, $\overline{\mathbb{R}}$ goes HIGH, inhibiting further write operations. If no reads are performed after a reset (either $\overline{\mathbb{MRS}}$ or $\overline{\mathbb{PRS}}$), $\overline{\mathbb{R}}$ will go HIGH see Figure 9 *Write First Word Cycles - FWFT Mode*, for the relevant timing information.

The $\overline{\mathbb{IR}}$ status not only measures the contents of the SFC memory, but also counts the presence of a word in the output register. Thus, in FWFT mode, the total number of writes necessary to de-assert $\overline{\mathbb{IR}}$ is one greater than needed to assert $\overline{\mathbb{FF}}$ in IDT Standard mode.

 $\overline{FF/IR}$ is synchronous and updated on the rising edge of WCLK. $\overline{FF/IR}$ are double register-buffered outputs.

EMPTY FLAG (EF/OR)

This is a dual purpose pin. In the IDT Standard mode, the Empty Flag (\overline{EF}) function is selected. When the SFC is empty, \overline{EF} will go LOW, inhibiting further read operations. When \overline{EF} is HIGH, the SFC is not empty. Figure 10, Empty Boundary – IDT Standard Mode for the relevant timing information.

In FWFT mode, the Output Ready (\overline{OR}) function is selected. \overline{OR} goes LOW at the same time that the first word written to an empty SFC appears valid on the outputs. \overline{OR} stays LOW after the RCLK LOW to HIGH transition that shifts the last word from the SFC to the outputs. \overline{OR} goes HIGH only with a true read (RCLK with \overline{REN} = LOW). The previous data stays at the outputs, indicating the last word was read. Further data reads are inhibited until \overline{OR} goes LOW again. See Figure 11, *Empty Boundary (FWFT Mode)*, for the relevant timing information.

EF/OR is synchronous and updated on the rising edge of RCLK.

In IDT Standard mode, $\overline{\mathsf{EF}}$ is a double register-buffered output. In FWFT mode, $\overline{\mathsf{OR}}$ is a triple register-buffered output.

PROGRAMMABLE ALMOST-FULL FLAG (PAF)

The Programmable Almost-Full flag (\overline{PAF}) will go LOW when the SFC reaches the almost-full condition. In IDT Standard mode, if no reads are performed after reset (\overline{MRS}), \overline{PAF} will go LOW after (D - m) words are written to the SFC. See *Figure 22*, *Synchronous* \overline{PAF} *Flag - IDT Standard Mode and FWFT Mode*, for the relevant timing information.

If asynchronous PAF configuration is selected, the PAF is asserted LOW on the LOW-to-HIGH transition of the Write Clock (WCLK). PAF is reset to HIGH on the LOW-to-HIGH transition of the Read Clock (RCLK). If synchronous PAF configuration is selected, the PAF is updated on the rising edge of WCLK.

PROGRAMMABLE ALMOST-EMPTY FLAG (PAE)

The Programmable Almost-Empty flag (\overline{PAE}) will go LOW when the SFC reaches the almost-empty condition. In IDT Standard mode, \overline{PAE} will go LOW when there are nwords or less in the SFC. The offset "n" is the empty offset value. The default setting for this value is in Table 10, Device Configuration.

In FWFT mode, the \overline{PAE} will go LOW when there are n+1 words or less in the SFC. See *Figure 21, Synchronous* \overline{PAE} *Flag - IDT Standard Mode and FWFT Mode*, for the relevant timing information.

If asynchronous \overline{PAE} configuration is selected, the \overline{PAE} is asserted LOW on the LOW-to-HIGH transition of the Read Clock (RCLK). \overline{PAE} is reset to HIGH on the LOW-to-HIGH transition of the Write Clock (WCLK). If synchronous \overline{PAE} configuration is selected, the \overline{PAE} is updated on the rising edge of RCLK.

DATA OUTPUTS (Q0-Q47)

(Q0-Q47) are data outputs for 48-bit wide data, (Q0 - Q23) are data outputs for 24-bit wide data or (Q0-Q11) are data outputs for 12-bit wide data.

MEMORY CLOCK OUTPUT (CK)

These signals are to be connected to the external DDR SDRAM's clock input.

MEMORY CLOCK OUTPUT INVERTED (CK)

These signals are to be connected to the external DDR SDRAM's differential clock input.

MEMORY BANK ADDRESS INPUT BIT (BA[1:0])

These signals are to be connected to the external DDR SDRAM's bank address input bits.

MEMORY COLUMN ADDRESS STROBE (CAS)

These signals are to be connected to the external DDR SDRAM's column address strobe input.

MEMORY ADDRESS BUS (A[12:0])

These signals are to be connected to the external DDR SDRAM's address bus.

MEMORY WRITE ENABLE (WE)

These signals are to be connected to the external DDR SDRAM's write enable.

MEMORY ROW ADDRESS STROBE (RAS)

These signals are to be connected to the external DDR SDRAM's row address strobe input.

BI-DIRECTIONAL I/O

MEMORY DATA INPUTS/OUTPUTS DQ[63:0]

These signals are to be connected to the external DDR SDRAM's data input bus.

MEMORY DATA STROBE OUTPUT DQS[7:0]

These signals are to be connected to the external DDR SDRAM's data strobe inputs.

ABSOLUTE MAXIMUM RATINGS

Symbol	Rating	Com'l & Ind'l	Unit
VTERM	Terminal Voltage with respect to GND	-0.5 to +3.6 ⁽²⁾	٧
Tstg	Storage Temperature	-55 to +125	°C
Тлмах	Maximum Junction Temp.	150	°C
Іоит	DC Output Current	-50 to +50	mA

NOTES:

- 1. Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
- 2. Compliant with JEDEC JESD8-5. VCC terminal only.

CAPACITANCE (TA = +25°C, f = 1.0MHz)

Symbol	Parameter ⁽¹⁾	Conditions	Max.	Unit
CIN ^(2,3)	Input Capacitance	VIN = 0V	10 ⁽³⁾	pF
Cout ^(1,2)	Output Capacitance	Vout = 0V	10	pF

NOTES:

- 1. With output deselected, $(\overline{OE} \ge V_{IH})$.
- 2. Characterized values, not currently tested.
- 3. CIN for Vref is 20pF.

PACKAGE THERMAL DATA

Symbol	Parameter	Industrial/ Commercial	Unit
Өлс	Junction to case thermal resistance	3.8	C/W
θја	Junction to air thermal resistance		C/W
	airflow @ 0m/s	27.4	
	@ 1m/s	22.8	
	@ 2m/s	20.3	
	@ 3m/s	19.5	
	@ 4m/s	18.2	
	@ 5m/s	17.8	
MSL	Moisture sensitivity level	3	

RECOMMENDED DC OPERATING CONDITIONS

Symbol	Parameter	Min.	Тур.	Max.	Unit
Vcc	Supply Voltage	2.375	2.5	2.625	V
AV cc	Analog Supply Voltage	2.375	2.5	2.625	V
VDDQ	Output Rail Voltage for I/Os	2.375	_	3.45	V
GND	Supply Ground	0	0	0	٧
VREF ⁽¹⁾	SSTL_2 Voltage Reference Input	1.13	1.25	1.38	V
TA	Operating Temperature (Commercial)	0	I	70	°C
TA	Operating Temperature (Industrial)	-40	_	85	°C

NOTE

1. Typically the value of VREF is expected to be (0.49-0.51) x VCC.

DC ELECTRICAL CHARACTERISTICS

(Commercial: $VCC = 2.5V \pm 0.125V$, $TA = 0^{\circ}C$ to $+70^{\circ}C$; Industrial: $VCC = 2.5V \pm 0.125V$, $TA = -40^{\circ}C$ to $+85^{\circ}C$)

I/O Type	Symbol	Parameter		Min.	Max.	Unit
SFC Input	lu	Input leakage current		-10	10	μΑ
(LVTTL)	ViH	Input High Voltage	VDDQ = 3.3V VDDQ = 2.5V	2.0 1.7	5.5 3.45	V V
	VIL	Input Low Voltage	VDDQ = 3.3V VDDQ = 2.5V	 -0.3	0.8 0.7	V V
SFC Output	llo	Output leakage current		-10	10	μΑ
(LVTTL)	Vон	Read/Write interface output logic "1" voltage with lон1	VDDQ = 3.3V VDDQ = 2.5V	VDDQ - 0.4 VDDQ - 0.4	_	V V
	Vol	Read/Write interface output logic "0" voltage with IoL1	VDDQ = 3.3V VDDQ = 2.5V	_ _	0.4 0.4	V V
	Іон	Read/Write interface output high current (source current)	VDDQ = 3.3V VDDQ = 2.5V	-2 -8	_	mA mA
	loL	Read/Write interface output low current (sink current)	$V_{DDQ} = 3.3V$ $V_{DDQ} = 2.5V$	8 8	_	mA mA
DDR SDRAM	Іон	Memory interface output high current (source current)		-7.6	_	mA
I/O (SSTL_2) ⁽¹⁾	lol	Memory interface output low current (sink current)		7.6	_	mA
	ViH	Memory Interface Input High Voltage		1.7	3.0	V
	VIL	Memory Interface Input Low Voltage		-0.3	0.7	V
	Vон	Memory Interface Output High Voltage		1.5		V
	Vol	Memory Interface Output Low Voltage		_	1.00	٧

POWER CONSUMPTION

Symbol	Parameter	Min.	Max.	Unit
ICC1 ⁽²⁾	Active Vcc current	_	650	mA
ICC2 ⁽²⁾	Active AVcc current	_	18	mA
ICC3 ⁽²⁾	Active VDDQ current	_	1	mA
ISB1 ⁽³⁾	Standby Vcc current	_	600	mA
ISB2 ⁽³⁾	Standby VDDQ current	_	1	mA

General DC Test Conditions

- Measurements taken with Vcc = 2.625V, OE = HIGH, WCLK = RCLK = 16.7MHz, MCLK = 33.3MHz
- Data toggles alternately at 1/2 WCLK and RCLK frequency
- $\bullet \quad \ 0.4 \leq \text{Vin} \leq \text{Vcc, } 0.4 \leq \text{Vout} \leq \text{Vcc}$
- Outputs are unloaded (IOUT = 0)

- 1. These parameters are compliant under JEDEC standard for SSTL_2 (JESD8-9A). These parameters are classified as SSTL_2 Class I output buffers under section 3.2.1 of JESD8-9A.
- 2. ICC (active current) is measured with MCLK = 33.3MHz, RCLK = WCLK = 16.7MHz, and alternate 101010 data pattern toggling on the outputs.
- 3. ISB (standby current) is measured with MCLK = RCLK = WCLK = 0MHz with no output data toggling.
- 4. VSDREF is the VREF of the DDR SDRAM. It is not to be confused with the VREF of the SFC.
- 5. The maximum value may not represent the maximum current dissipated from the SFC. ICC values are dependent upon various factors that include: VCC, temperature, capacitive load, frequency, bus-width, and output switching characteristics. For calculating ICC with specific parameters, please contact IDT technical support for assistance.

2.5V LVTTL AC TEST CONDITIONS

Input Pulse Levels	GND to 2.5V
Input Rise/Fall Times	1ns
Input Timing Reference Levels	1.25V
Output Reference Levels	1.25V

2.5V SSTL AC TEST CONDITIONS

Input Pulse Levels	GND to 2.5V
Input Rise/Fall Times	1ns
Input Timing Reference Levels	1.25V
Output Reference Levels	1.25V

3.3V LVTTL AC TEST CONDITIONS

Input Pulse Levels	GND to 3.0V
Input Rise/Fall Times	3ns
Input Timing Reference Levels	1.5V
Output Reference Levels	1.5V

AC TEST LOADS

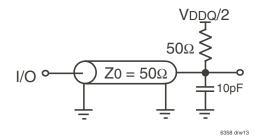


Figure 5a. AC Test Load

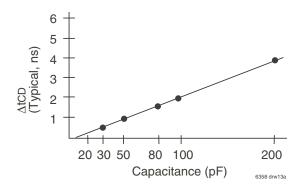


Figure 5b. Lumped Capacitive Load, Typical Derating

AC ELECTRICAL CHARACTERISTICS(1)—SYNCHRONOUS TIMING

(Commercial: Vcc = $2.5V \pm 5\%$, Ta = 0° C to $+70^{\circ}$ C;Industrial: Vcc = $2.5V \pm 5\%$, Ta = -40° C to $+85^{\circ}$ C)

			Comr	Com'l	↓			
		(x24 or x12 l/	IDT72T					
Cumbal	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
Symbol fs	Synchronous Clock Cycle Frequency	IVIIII.	166	IVIIII.	133	IVIII I.	100	MHz
tA	Data Access Time	1	4	1 1	5	1	6.5	ns
tclk	Clock Cycle Time	6	_	7.5	_	10	0.0	ns
tclkh	Clock High Time	2.7		3.5	_	4.5		
tclkh	Clock Low Time	2.7		3.5		4.5		ns
tDS	Data Setup Time	2.7	_	2.5	_	3.5		ns
tDH tDH	Data Hold Time	0.5	_	0.5	_	0.5	_	ns
	Enable Setup Time	2	_	2.5	_	3.5		ns
tens	Enable Hold Time	0.5	_	0.5	_	0.5		ns
tENH	Reset Pulse Width		_	10	_	10	_	ns
trs		10 15	_		_	15	_	ns
trsu	Reset Setup Time		_	15	_		_	ns
trsh	Reset Hold Time	10	_	10	_	10		ns
tPL tpss	Resetto PLL Lock	20		20		20		μs
trsf	Reset to Flag and Output	_	15		15	_	15	ns
tohz	Output enable to High-Z	1	4	1	5	1	6.5	ns
toE	Output Enable Valid	1	4	1	5	1	6.5	ns
fMC	Master Clock Cycle Frequency	32	34	32	34	32	34	MHz
tMCYC	Master Clock Cycle Time	29.4	31.3	29.4	31.3	29.4	31.3	ns
tMCKH	Master Clock Cycle HIGH	0.45	0.55	0.45	0.55	0.45	0.55	tMCYC
tMCKL	Master Clock Cycle LOW	0.45	0.55	0.45	0.55	0.45	0.55	tMCYC
fsc	Serial Clock Cycle Frequency		10	100	10		10	MHz
tsclk	Serial Clock Cycle	100	_	100	_	100		ns
tsclkh	Serial Clock High	45	_	45	_	45		ns
tsclkl	Serial Clock Low	45	_	45	_	45		ns
tsds	Serial Data Setup	15	_	15	_	15	_	ns
tsdh	Serial Data Hold	5	_	5	_	5	_	ns
tsens	Serial Enable Setup	5	_	5	_	5		ns
tsenh	Serial Enable Hold	5	_	5	_	5	_	ns
taso	Serial Output Data Access Time		20		20	_	20	ns
tWFFs	Write Clock to Synchronous FF/IR		4		5		6.5	ns
tREFs	Read Clock to Synchronous EF/OR		4		5		6.5	ns
tPAFs	WCLK to Synchronous PAF		4		5	_	6.5	ns
tPAEs	RCLK to Synchronous PAE		4		5	_	6.5	ns
tskew1	Skew time between RCLK & WCLK for EF/OR and FF/IR in SDR		_	5	_	7	_	ns
tskew2	Skew time between RCLK and WCLK for PAE/PAF	5		7	_	10	_	ns
twcss	WCS Setup Time	2	_	2.5	_	3.5	_	ns
twcsh	WCS Hold Time	0.5		0.5	_	0.5		ns
fC1	Memory Clock Cycle Frequency at 166MHz	160	170	160	170	_		MHz
fC2	Memory Clock Cycle Frequency at 133MHz	128	136	128	136	128	136	MHz
tCK1	Memory Clock Cycle Time at 166MHz	6.2	5.9	 -	_	_		ns
tck2	Memory Clock Cycle Time at 133MHz	7.8	7.3	7.8	7.3	7.8	7.3	ns
tckh1	Memory Clock Cycle HIGH at 166MHz	0.45	0.55	 -				tck1
tckh2	Memory Clock Cycle HIGH at 133MHz	0.45	0.55	0.45	0.55	0.45	0.55	tck2
tckl1	Memory Clock Cycle LOW at 166MHz	0.45	0.55		_			tck1
tckl2	Memory Clock Cycle LOW at 133MHz	0.45	0.55	0.45	0.55	0.45	0.55	tck2

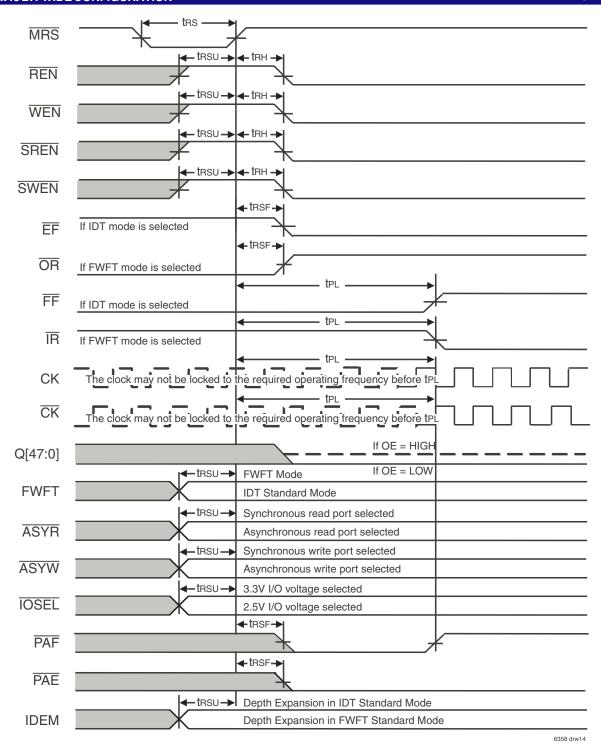
- 1. All AC timings apply to both Standard IDT mode and First Word Fall Through mode.
- 2. Industrial temperature range product for the 10ns speed grade is available as a standard device. All other speed grades are available by special order.
- 3. To achieve 166MHz read and write port operation, the input and/or output bus must be configured to x24 or x18.

AC ELECTRICAL CHARACTERISTICS—ASYNCHRONOUS TIMING

(Commercial: Vcc = $2.5V \pm 5\%$, Ta = 0° C to $+70^{\circ}$ C;Industrial: Vcc = $2.5V \pm 5\%$, Ta = -40° C to $+85^{\circ}$ C)

		Commercial		Commercial		Com'l & Ind'l ⁽²⁾		
		IDT72T6480L7-5 (x24 or x12 I/O width only) ⁽³⁾		IDT72T6480L7-5		IDT72T6480L10		
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
fA	Asynchronous Clock Cycle Frequency	_	100	_	83	_	50	MHz
t Aa	Data Access Time	0.6	8	0.6	10	1	12	ns
tcyc	Cycle Time	10	-	12	_	20	_	ns
tcych	Cycle High Time	4.5	_	5	_	8	_	ns
tcycl	Cycle Low Time	4.5	_	5	_	8	_	ns
tFFa	Rising Edge to FF	_	8	_	10	_	14	ns
tEFa	Rising Edge to EF	_	8	_	10	_	14	ns
tPAFa	Rising Edge to PAF	_	8	_	10	_	14	ns
t PAEa	Rising Edge to PAE	_	8	_	10	_	14	ns
trpe	Read Pulse after EF HIGH	8	_	10	_	14	_	ns

- 1. All AC timings apply to both Standard IDT mode and First Word Fall Through mode.
- 2. Industrial temperature range product for the 10ns speed grade is available as a standard device. All other speed grades are available by special order.
- 3. To achieve 166MHz read and write port operation, the input and/or output bus must be configured to x24 or x18.

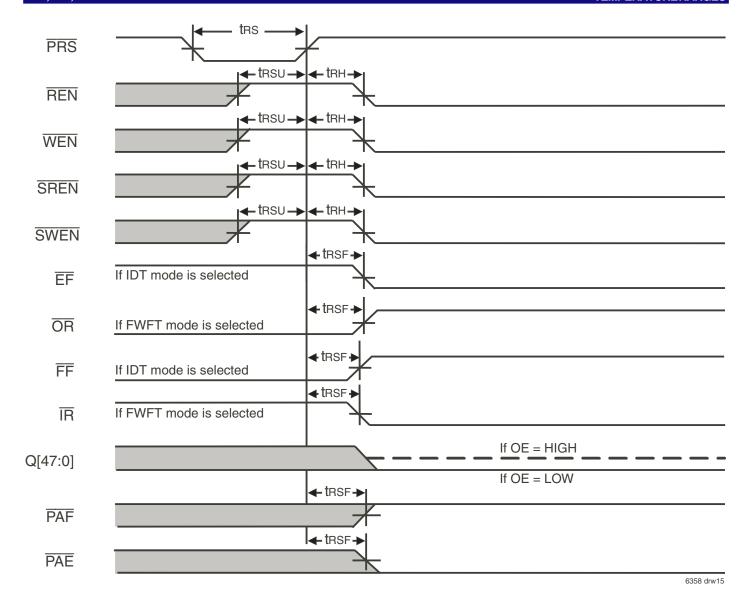


NOTE:

1. For other signals that are latched during master reset, refer to Master Reset and Device Configuration section.

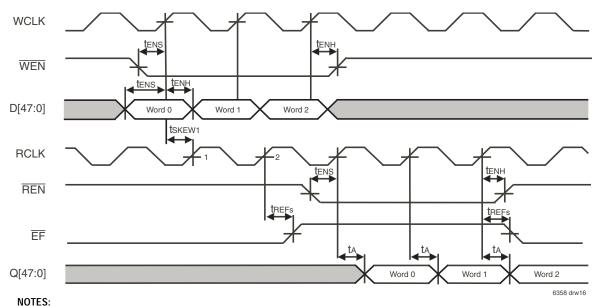
Symbol	Parameter	Min.	Max.	Unit
trs	Reset Pulse Width	10	ı	ns
trsu	Reset Setup Time	15	ı	ns
trsh	Reset Hold Time	10	-	ns
tPL	Reset to PLL Lock	20	_	μs
trsf	Reset to Flag and Output	_	15	ns

Figure 6. Master Reset and Initialization



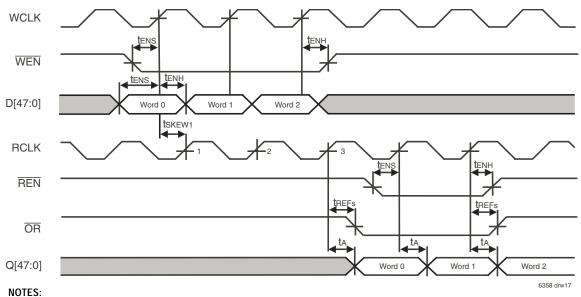
Symbol	Parameter	Min.	Max.	Unit
trs	Reset Pulse Width	10	_	ns
trsu	Reset Setup Time	15	_	ns
trsh	Reset Hold Time	10	_	ns
tPL	Reset to PLL Lock	20	_	μs
trsf	Reset to Flag and Output	_	15	ns

Figure 7. Partial Reset



- 1. tSKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then $\overline{\text{EF}}$ de-assertion may be delayed one extra RCLK cycle. 2. Settings: $\overline{\text{OE}} = \text{LOW}$, $\overline{\text{RCS}} = \text{LOW}$, $\overline{\text{WCS}} = \text{LOW}$, BM[3:0] = 1000, FWFT = LOW, $\overline{\text{ASYR}} = \text{HIGH}$, and $\overline{\text{ASYW}} = \text{HIGH}$.

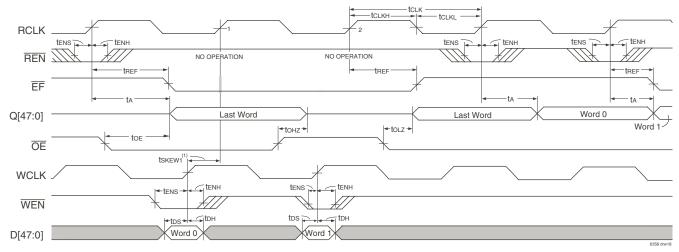
Figure 8. Write First Word Cycles - IDT Standard Mode



- 1. tskew1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus trees). If tskew1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.
- 2. Settings: OE = LOW, RCS = LOW, WCS = LOW, BM[3:0] = 1000, FWFT = HIGH, ASYR = HIGH, and ASYW = HIGH.

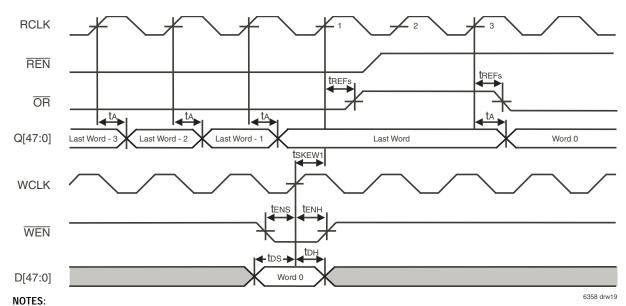
Figure 9. Write First Word Cycles - FWFT Mode

		7-5ns (x24 or x12 I/O only)			5ns width only)	10		
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tsens	Serial Enable Setup	5	_	5	_	5	_	ns
tsenh	Serial Enable Hold	5	_	5	_	5	_	ns
t A	Data Access Time	1	4	1	5	1	6.5	ns
tskew1	Skew time between RCLK and WCLK for $\overline{\text{EF}}/\overline{\text{OR}}$ and $\overline{\text{FF}}/\overline{\text{IR}}$ in SDR	4	_	5	_	7	_	ns
tREFs	Read Clock to Synchronous EF/OR	_	4	_	5	_	6.5	ns



- 1. tskew1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that $\overline{\mathsf{EF}}$ will go HIGH after one RCLK cycle (plus trees). If tskew1 is not met, then $\overline{\mathsf{EF}}$ de-assertion may be delayed one extra RCLK cycle.
- 2. Settings: \overline{RCS} = LOW, \overline{WCS} = LOW, BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

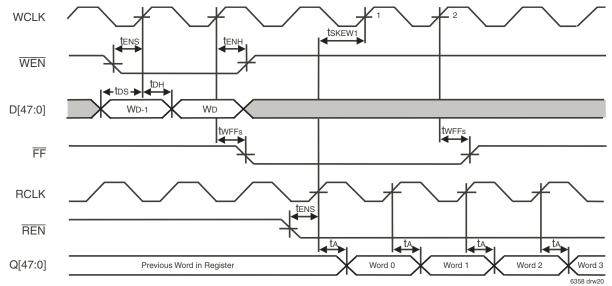
Figure 10. Empty Boundary - IDT Standard Mode



- 1. tskew1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that $\overline{\mathsf{EF}}$ will go HIGH after one RCLK cycle (plus trefs). If tskew1 is not met, then $\overline{\mathsf{EF}}$ de-assertion may be delayed one extra RCLK cycle.
- 2. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, \overline{WCS} = LOW, BM[3:0] = 1000, FWFT = HIGH, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

Figure 11. Empty Boundary - FWFT Mode

			7-5ns (x24 or x12 I/O only)		7-5ns (x48 I/O width only)		10ns	
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tclk	Clock Cycle Time	6	_	7.5	-	10	_	ns
tclkh	Clock High Time	2.7	_	3.5	_	4.5	1	ns
tclkl	Clock Low Time	2.7	_	3.5	-	4.5	ı	ns
tos	Data Setup Time	2	_	2.5	_	3.5	1	ns
tDH .	Data Hold Time	0.5	-	0.5	_	0.5	ı	ns
tens	Enable Setup Time	2	_	2.5	_	3.5	-	ns
tenh	Enable Hold Time	0.5	_	0.5		0.5	_	ns
tA	Data Access Time	1	4	1	5	1	6.5	ns
tREFs	Read Clock to Synchronous EF/OR	_	4	_	5		6.5	ns
tskew1	Skew time between RCLK and WCLK for $\overline{\text{EF}}/\overline{\text{OR}}$ and $\overline{\text{FF}}/\overline{\text{IR}}$ in SDR	4	_	5	_	7		ns



- 1. tskew1 is the minimum time between a rising RCLK edge and a rising WCLK edge to guarantee that FF will go HIGH after one WCLK cycle (plus tWFFs). If tskew1 is not met, then FF de-assertion may be delayed one extra WCLK cycle.

 2. Settings: OE = LOW, RCS = LOW, WCS = LOW, BM[3:0] = 1000, FWFT = LOW, ASYR = HIGH, and ASYW = HIGH.

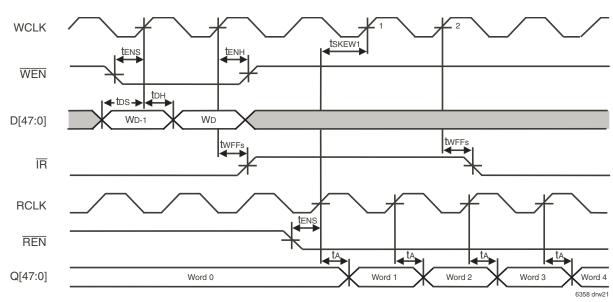
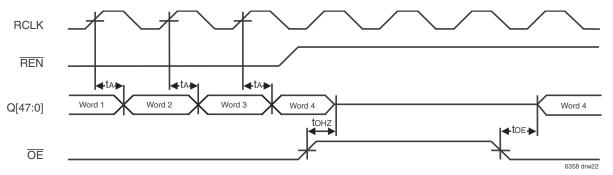


Figure 12. Full Boundary - IDT Standard Mode

- 1. ISKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.
- 2. Settings: RCS = LOW, WCS = LOW, BM[3:0] = 1000, FWFT = HIGH, ASYR = HIGH, and ASYW = HIGH.

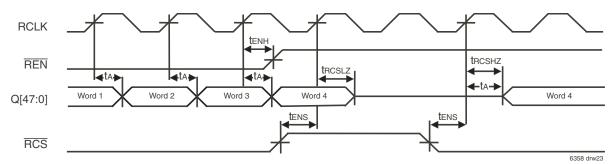
Figure 13. Full Boundary - FWFT Mode

		_	7-5ns (x24 or x12 I/O only)		7-5ns (x48 I/O width only		10ns	
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tDS	Data Setup Time	2		2.5	_	3.5	_	ns
tDH .	Data Hold Time	0.5		0.5	_	0.5	_	ns
tens	Enable Setup Time	2	_	2.5	_	3.5	_	ns
tenh	Enable Hold Time	0.5	_	0.5	_	0.5	_	ns
tA	Data Access Time	1	4	1	5	1	6.5	ns
twFFs	Write Clock to Synchronous FF/IR	_	4	_	5	_	6.5	ns
tskew1	Skew time between RCLK and WCLK for EF/OR and FF/IR in SDR	4	_	5	_	7	_	ns



1. Settings: \overline{RCS} = LOW, BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

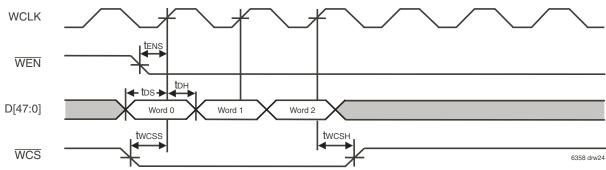
Figure 14. Output Enable



NOTE:

1. Settings: \overline{OE} = LOW, BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

Figure 15. Read Chip Select

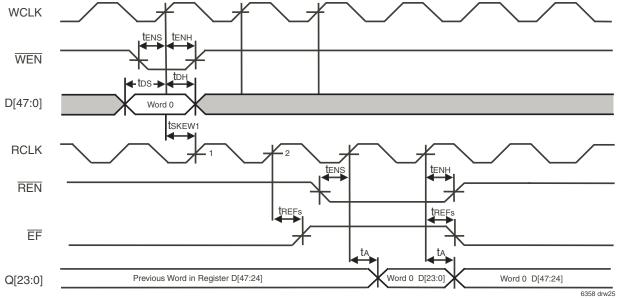


NOTE:

1. Settings: BM[3:0] = 1000, FWFT = LOW, $\overline{\text{ASYR}}$ = HIGH, and $\overline{\text{ASYW}}$ = HIGH.

Figure 16. Write Chip Select

		7-5ı (x24 or x1	ns 2 I/O only)	7-5i (x48 I/O	ns width only	10n	S	
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tos	Data Setup Time	2	_	2.5	_	3.5	-	ns
tDH	Data Hold Time	0.5	_	0.5	_	0.5	_	ns
tens	Enable Setup Time	2	-	2.5	_	3.5	_	ns
tenh	Enable Hold Time	0.5	-	0.5	_	0.5	-	ns
tA	Data Access Time	1	4	1	5	1	6.5	ns
tohz	Output enable to High-Z	1	4	1	5	1	6.5	ns
toe	Output Enable Valid	1	4	1	5	1	6.5	ns
twcss	WCS Setup Time	2	_	2.5	_	3.5	-	ns
twcsh	WCS Hold Time	0.5	_	0.5	_	0.5	_	ns



- 1. tskew1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then $\overline{\text{EF}}$ de-assertion may be delayed one extra RCLK cycle. 2. Settings: $\overline{\text{OE}} = \text{LOW}$, $\overline{\text{RCS}} = \text{LOW}$, $\overline{\text{WCS}} = \text{LOW}$, BM[3:0] = 1011, FWFT = LOW, $\overline{\text{ASYR}} = \text{HIGH}$, and $\overline{\text{ASYW}} = \text{HIGH}$.

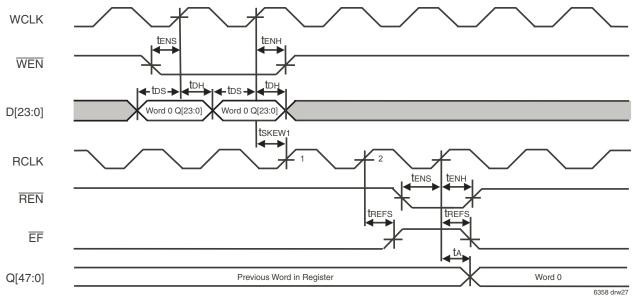
WCLK WEN D[47:0] tskew1 **RCLK** REN ĒĒ Previous Word in Register D[47:36] Q[11:0] Word 0 D[11:0] Word 0 D[23:12 . Vord 0 D[35:24 Word 0 D[47:36]

Figure 17. Bus-Matching Configuration - x48 In to x24 Out - IDT Standard Mode

- 1. ISKEW1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus tREFs). If tSKEW1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.
 2. Settings: OE = LOW, RCS = LOW, WCS = LOW, BM[3:0] = 1111, FWFT = LOW, ASYR = HIGH, and ASYW = HIGH.

Figure 18. Bus-Matching Configuration - x48 In to x12 Out - IDT Standard Mode

		7-5ns (x24 or x12 I/O only)		7-5ns (x48 I/O width only		10ns		
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tos	Data Setup Time	2	_	2.5	_	3.5	_	ns
tDH .	Data Hold Time	0.5		0.5	1	0.5	_	ns
tens	Enable Setup Time	2	_	2.5	-	3.5	_	ns
tenh	Enable Hold Time	0.5	_	0.5	_	0.5	_	ns
tA	Data Access Time	1	4	1	5	1	6.5	ns
tREFs	Read Clock to Synchronous EF/OR	_	4	ı	5	ı	6.5	ns
tskew1	Skew time between RCLK and WCLK for $\overline{\text{EF}}/\overline{\text{OR}}$ and $\overline{\text{FF}}/\overline{\text{IR}}$ in SDR	4	_	5		7	_	ns



- 1. tskew1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus trees). If tskew1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.
- 2. Settings: $\overline{OE} = LOW$, $\overline{RCS} = LOW$, $\overline{WCS} = LOW$, BM[3:0] = 1001, FWFT = LOW, $\overline{ASYR} = HIGH$, and $\overline{ASYW} = HIGH$.

WCLK WEN toh Word 0 Q[11:0] . Word 0 Q[23:12 . Word 0 Q[35:24 Word 0 Q[47:36 D[11:0] tskew1 **RCLK** REN trefs **t**REF ĒĒ Q[47:0] Previous Word in Register Word 0

Figure 19. Bus-Matching Configuration - x24 In to x48 Out - IDT Standard Mode

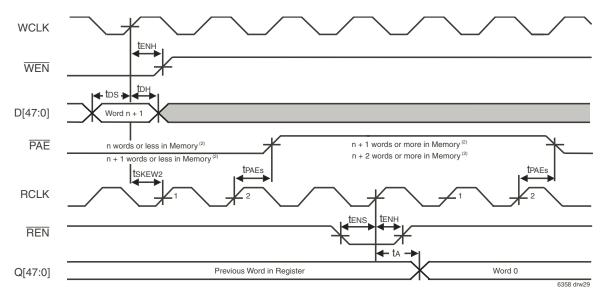
NOTES:

- 1. tskew1 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that EF will go HIGH after one RCLK cycle (plus trees). If tskew1 is not met, then EF de-assertion may be delayed one extra RCLK cycle.
- 2. Settings: $\overline{\text{OE}} = \text{LOW}$, $\overline{\text{RCS}} = \text{LOW}$, $\overline{\text{WCS}} = \text{LOW}$, $\overline{\text{BM}}[3:0] = 1101$, $\overline{\text{FWFT}} = \text{LOW}$, $\overline{\text{ASYR}} = \text{HIGH}$, and $\overline{\text{ASYW}} = \text{HIGH}$.

Figure 20. Bus-Matching Configuration - x12 In to x48 Out - IDT Standard Mode

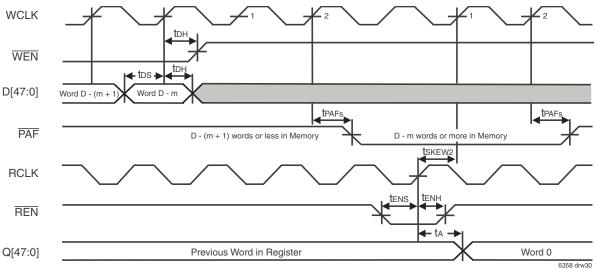
		7-5ns (x24 or x12 I/O only)		7-5ns (x48 I/O width only		10ns		
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tos	Data Setup Time	2	_	2.5	_	3.5		ns
tDH .	Data Hold Time	0.5	-	0.5		0.5	ı	ns
tens	Enable Setup Time	2	_	2.5		3.5	ı	ns
tenh	Enable Hold Time	0.5	_	0.5	_	0.5		ns
tA	Data Access Time	1	4	1	5	1	6.5	ns
tREFs	Read Clock to Synchronous EF/OR	_	4		5	_	6.5	ns
tskew1	Skew time between RCLK and WCLK for EF/OR and FF/IR in SDR	4	_	5	_	7	_	ns

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- 1. tskew2 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that PAE will go HIGH after one RCLK cycle (plus tPAEs). If tskew2 is not met, then PAE de-assertion may be delayed one extra RCLK cycle.
- 2. $n = \overline{PAE}$ offset, see Table 10 for information on setting \overline{PAE} offset values.
- 3. Settings: $\overline{OE} = LOW$, $\overline{RCS} = LOW$, BM[3:0] = 1000, $\overline{ASYR} = HIGH$, and $\overline{ASYW} = HIGH$.

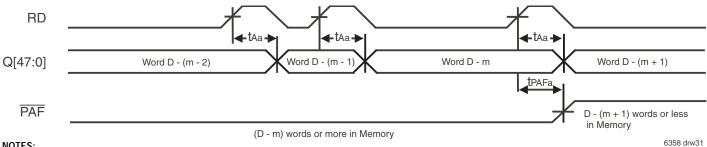
Figure 21. Synchronous PAE Flag - IDT Standard Mode and FWFT Mode



- 1. tskew2 is the minimum time between a rising WCLK edge and a rising RCLK edge to guarantee that PAF will go HIGH after one RCLK cycle (plus tPAFs). If tskew2 is not met, then PAF de-assertion may be delayed one extra RCLK cycle.
- 2. $m = \overline{PAF}$ offset, $D = \overline{density}$ of SFC, see Table 11 for information on setting \overline{PAF} offset values.
- 3. Settings: \overline{OE} = LOW, \overline{RCS} = LOW, BM[3:0] = 1000, \overline{ASYR} = HIGH, and \overline{ASYW} = HIGH.

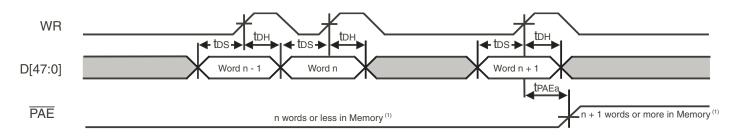
Figure 22. Synchronous PAF Flag - IDT Standard Mode and FWFT Mode

		7-5ns (x24 or x12 I/O only)		7-5ns (x48 I/O width only		10ns		
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tDS	Data Setup Time	2	-	2.5		3.5	_	ns
tDH	Data Hold Time	0.5	_	0.5	_	0.5	_	ns
tenh	Enable Hold Time	0.5	ı	0.5	_	0.5	_	ns
tA	Data Access Time	1	4	1	5	1	6.5	ns
tPAFs	WCLK to Synchronous PAF	_	4	_	5	_	6.5	ns
tPAEs	RCLK to Synchronous PAE	_	4	_	5		6.5	ns
tskew2	Skew time between RCLK and WCLK for PAE/PAF	5	_	7	_	10	_	ns



- 1. m = PAF offset, see Table 10 for information on PAF offset values. D = density of SFC.
 2. Settings: OE = LOW, RCS = LOW, BM[3:0] = 1000, FWFT = LOW, ASYR = LOW, and ASYW = LOW.
- 3. Asynchronous read is available in IDT standard mode only.

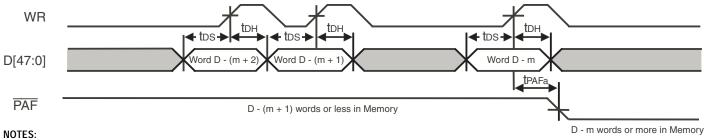
Figure 23. Asynchronous Read and PAF Flag - IDT Standard Mode



NOTES: 6358 drw32

- 1. $n = \overline{PAE}$ offset, see Table 11 for information on \overline{PAE} offset values.
- 2. Settings: \overline{WCS} = LOW, BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = LOW, and \overline{ASYW} = LOW.
- 3. Asynchronous read is available in IDT standard mode only.

Figure 24. Asynchronous Write and PAE Flag - IDT Standard Mode

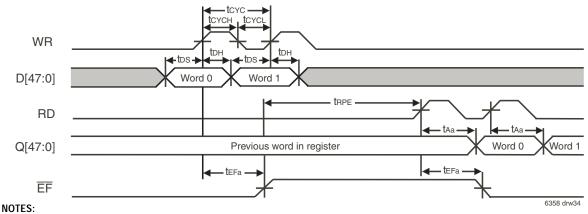


- 1. m = \overline{PAF} offset, see Table 11 for information on \overline{PAF} offset values. D = density of SFC.
- 2. Settings: \overline{WCS} = LOW, BM[3:0] = 1000, FWFT = LOW, \overline{ASYR} = LOW, and \overline{ASYW} = LOW.
- 3. Asynchronous read is available in IDT standard mode only.

Figure 25. Asynchronous Write and PAF Flag - IDT Standard Mode

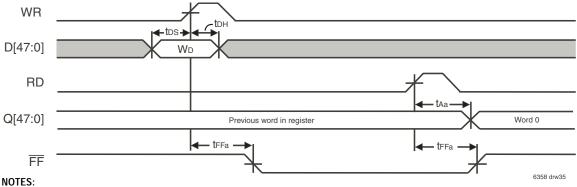
		7-5ns 7-5ns 10ns (x24 or x12 I/O only) (x48 I/O width only)		IS				
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tDS	Data Setup Time	2	-	2.5	-	3.5	ı	ns
t DH	Data Hold Time	0.5	-	0.5	-	0.5	1	ns
t Aa	Data Access Time	0.6	8	0.6	10	1	12	ns
tPAFa	Rising Edge to PAF	_	8	_	10	_	14	ns

6358 drw33



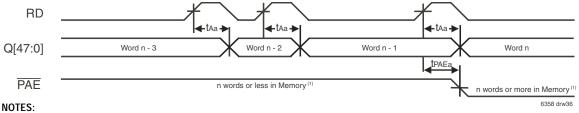
- 1. Settings: $\overline{OE} = LOW$, $\overline{RCS} = LOW$, $\overline{WCS} = LOW$, $\overline{FWFT} = LOW$, $\overline{ASYR} = LOW$, and $\overline{ASYW} = LOW$.
- 2. Asynchronous read is available in IDT standard mode only.

Figure 26. Asynchronous Empty Boundary - IDT Standard Mode



- 1. Settings: $\overline{OE} = LOW$, $\overline{RCS} = LOW$, $\overline{WCS} = LOW$, FWFT = LOW, $\overline{ASYR} = LOW$, and $\overline{ASYW} = LOW$.
- 2. Asynchronous read is available in IDT standard mode only.

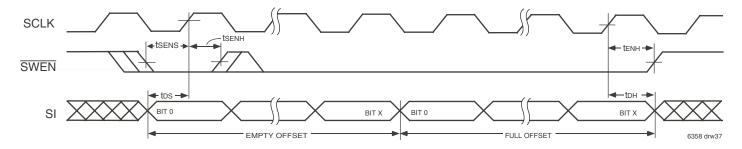
Figure 27. Asynchronous Full Boundary - IDT Standard Mode



- 1. $n = \overline{PAE}$ offset, see Table 11 for information on \overline{PAE} offset values.
- 2. Asynchronous read is available in IDT standard mode only.

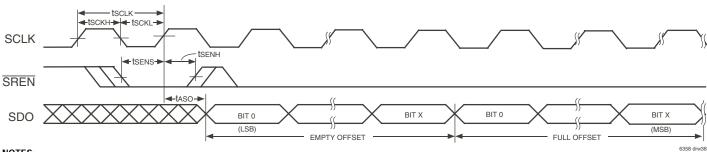
Figure 28. Asynchronous Read and PAE Flag - IDT Standard Mode

		7-5ı (x24 or x1	ns 2 I/O only)	7-5 (x48 I/O	ns width only)	10n	ıs	
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tAa	Data Access Time	0.6	8	0.6	10	1	12	ns
tcyc	Cycle Time	10	_	12	_	20	_	ns
tcych	Cycle HIGH Time	4.5	_	5	_	8	_	ns
tcycl	Cycle LOW Time	4.5	_	5	-	8	_	ns
tDH .	Data Hold Time	0.5	_	0.5	_	0.5	_	ns
tos	Data Setup Time	2	_	2.5	_	3.5	_	ns
tEFa	Rising Edge to EF	_	8	1	10	1	14	ns
tFFa	Rising Edge to FF	_	8	_	10	-	14	ns
tPAEa	Rising Edge to PAE	_	8		10		14	ns
trpe	Read Pulse after EF HIGH	8	_	10	_	14	_	ns



- 1. Settings: JSEL = LOW.
- 2. x is the required number of bits to program the PAE and PAF offset registers. See Table 12 for the numbers based on the values external configurations.

Figure 29. Serial Loading of Programmable Flag Registers (IDT Standard and FWFT Modes)



- 1. Settings: JSEL = LOW.
- 2. x is the required number of bits to program the PAE and PAF offset registers. See Table 12 for the numbers based on the values external configurations.

Figure 30. Reading of Programmable Flag Registers (IDT Standard and FWFT Modes)

		7-5ns (x24 or x12 I/O only)		7-5ns (x48 I/O width only)		10ns		
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
tDH .	Data Hold Time	0.5	_	0.5	-	0.5		ns
tos	Data Setup Time	2	_	2.5	-	3.5	-	ns
taso	Serial Output Data Access Time	_	20	-	20	_	20	ns
tsens	Serial Enable Setup	5	_	5	1	5	_	ns
tsenh	Serial Enable Hold	5	_	5	1	5	_	ns
tsclk	Serial Clock Cycle	10	_	10	_	10	_	ns
tsclkh	Serial Clock HIGH	45	_	45	_	45	_	ns
tsclkl	Serial Clock LOW	45	_	45	-	45	_	ns

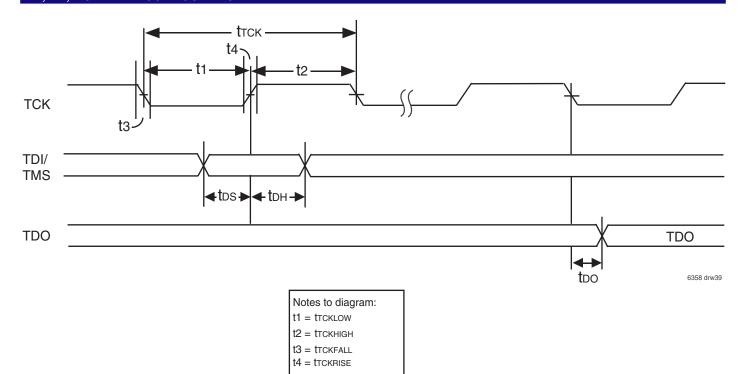


Figure 31. Standard JTAG Timing

SYSTEM INTERFACE PARAMETERS

			ID.	Г72Т648	30
Parameter	Symbol	Test Conditions	Min.	Max.	Units
Data Output	tDO ⁽¹⁾		-	20	ns
Data Output Hold	tdoh ⁽¹⁾		0	-	ns
Data Input	tds tdh	trise=3ns tfall=3ns	10 10		ns

NOTE:

1. 50pf loading on external output signals.

JTAG AC ELECTRICAL CHARACTERISTICS

($Vcc = 2.5V \pm 5\%$; Tambient (Industrial) = 0°C to +85°C)

Parameter	Symbol	Test			
		Conditions	Min.	Max.	Units
JTAG Clock Input Period	tтск	-	100	-	ns
JTAG Clock HIGH	ttckhigh	-	40	-	ns
JTAG Clock Low	ttcklow	-	40		ns
JTAG Clock Rise Time	ttckrise	-	1	5 ⁽¹⁾	ns
JTAG Clock Fall Time	ttckfall	-	1	5 ⁽¹⁾	ns

NOTE:

1. Guaranteed by design.

JTAG TIMING SPECIFICATIONS (IEEE 1149.1 COMPLIANT)

The JTAG test port in this device is fully compliant with the IEEE Standard Test Access Port (IEEE 1149.1) specifications. Four additional pins (TDI, TDO, TMS and TCK) are provided to support the JTAG boundary scan interface. Note that IDT provides appropriate Boundary Scan Description Language program files for these devices.

The Standard JTAG interface consists of seven basic elements:

- Test Access Port (TAP)
- TAP controller
- Instruction Register (IR)
- Data Register Port (DR)
- Bypass Register (BYR)
- ID Code Register

The following sections provide a brief description of each element. For a complete description refer to the IEEE Standard Test Access Port Specification (IEEE Std. 1149.1-1990).

The Figure below shows the standard Boundary-Scan Architecture

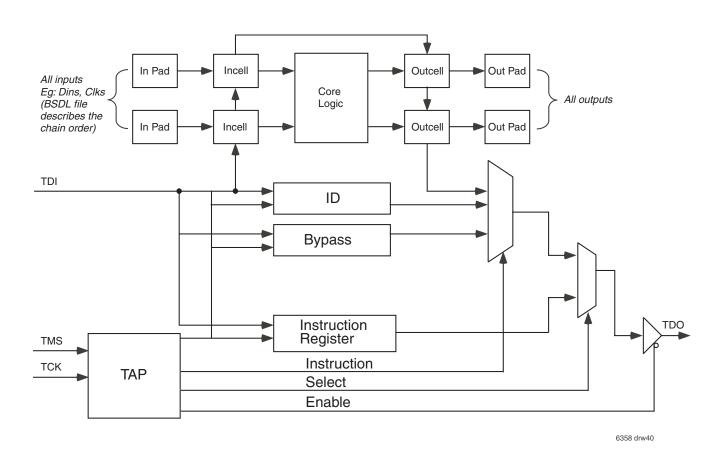


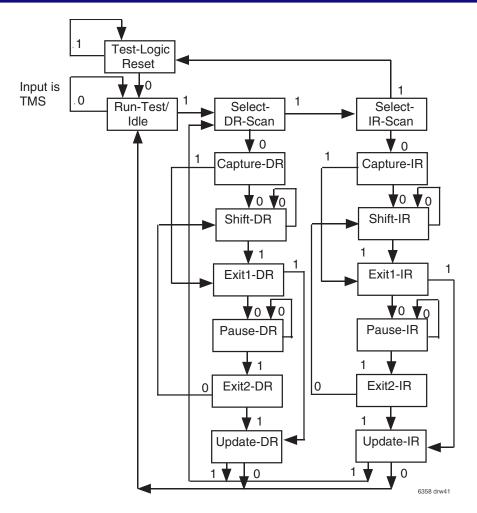
Figure 32. JTAG Architecture

TEST ACCESS PORT (TAP)

The TAP interface is a general-purpose port that provides access to the internal JTAG state machine. It consists of three input ports (TCLK, TMS, TDI) and one output port (TDO).

THE TAP CONTROLLER

The TAP controller is a synchronous finite state machine that responds to TMS and TCLK signals to generate clock and control signals to the Instruction and Data Registers for capture and updating of data passed through the TDI serial input.



- 1. Five consecutive 1's at TMS will reset the TAP.
- 2. TAP controller resets automatically upon power-up.

Figure 33. TAP Controller State Diagram

Refer to the IEEE Standard Test Access Port Specification (IEEE Std. 1149.1) for the full state diagram

All state transitions within the TAP controller occur at the rising edge of the TCLK pulse. The TMS signal level (0 or 1) determines the state progression that occurs on each TCLK rising edge.

 $\label{thm:controller} \textbf{Test-Logic-Reset} \ All \ test \ logic \ is \ disabled \ in \ this \ controller \ state \ enabling \ the \ normal \ operation \ of \ the \ IC. \ The \ TAP \ controller \ state \ machine \ is \ designed \ in \ such \ a \ way \ that, \ no \ matter \ what \ the \ initial \ state \ of \ the \ controller \ is, \ the \ Test-Logic-Reset \ state \ can \ be \ entered \ by \ holding \ TMS \ at \ high \ and \ pulsing \ TCK \ five \ times.$

Run-Test-Idle In this controller state, the test logic in the IC is active only if certain instructions are present. For example, if an instruction activates the self test, then it will be executed when the controller enters this state. The test logic in the IC is idle otherwise.

Select-DR-Scan This is a controller state where the decision to enter the Data Path or the Select-IR-Scan state is made.

Select-IR-Scan This is a controller state where the decision to enter the Instruction Path is made. The Controller can return to the Test-Logic-Reset state otherwise.

Capture-IR In this controller state, the shift register bank in the Instruction Register parallel loads a pattern of fixed values on the rising edge of TCK. The last two significant bits are always required to be "01".

Shift-IR In this controller state, the instruction register gets connected between TDI and TDO, and the captured pattern gets shifted on each rising edge of TCK. The instruction available on the TDI pin is also shifted in to the instruction register. TDO changes on the falling edge of TCK.

Exit1-IR This is a controller state where a decision to enter either the Pause-IR state or Update-IR state is made.

Pause-IR This state is provided in order to allow the shifting of instruction register to be temporarily halted.

Exit2-DR This is a controller state where a decision to enter either the Shift-IR state or Update-IR state is made.

Update-IR In this controller state, the instruction in the instruction register scanchain is latched into the register of the Instruction Register on every falling edge of TCK. This instruction also becomes the current instruction once it is latched.

Capture-DR In this controller state, the data is parallel loaded in to the data registers selected by the current instruction on the rising edge of TCK.

Shift-DR, **Exit1-DR**, **Pause-DR**, **Exit2-DR** and **Update-DR** These controller states are similar to the Shift-IR, Exit1-IR, Pause-IR, Exit2-IR and Update-IR states in the Instruction path.

THE INSTRUCTION REGISTER

The instruction register (IR) is eight bits long and tells the device what instruction is to be executed. Information contained in the instruction includes the mode of operation (either normal mode, in which the device performs its normal logic function, or test mode, in which the normal logic function is inhibited or altered), the test operation to be performed, which of the four data registers is to be selected for inclusion in the scan path during data-register scans, and the source of data to be captured into the selected data register during Capture-DR.

TEST DATA REGISTER

The Test Data register contains three test data registers: the Bypass, the Boundary Scan register and Device ID register.

These registers are connected in parallel between a common serial input and a common serial data output.

The following sections provide a brief description of each element. For a complete description, refer to the IEEE Standard Test Access Port Specification (IEEE Std. 1149.1-1990).

TEST BYPASS REGISTER

The register is used to allow test data to flow through the device from TDI to TDO. It contains a single stage shift register for a minimum length in the serial path. When the bypass register is selected by an instruction, the shift register stage is set to a logic zero on the rising edge of TCLK when the TAP controller is in the Capture-DR state.

The operation of the bypass register should not have any effect on the operation of the device in response to the BYPASS instruction.

THE BOUNDARY-SCAN REGISTER

The boundary-scan register (BSR) contains one boundary-scan cell (BSC) for each normal-function input pin and one BSC for each normal-function I/O pin (one single cell for both input data and output data). The BSR is used 1) to store test data that is to be applied externally to the device output pins, and/or 2) to capture data that appears internally at the outputs of the normal on-chip logic and/or externally at the device input pins.

THE DEVICE IDENTIFICATION REGISTER

The Device Identification Register is a Read Only 32-bit register used to specify the manufacturer, part number and version of the device to be determined through the TAP in response to the IDCODE instruction.

IDT JEDEC ID number is 0xB3. This translates to 0x33 when the parity is dropped in the 11-bit Manufacturer ID field.

For the IDT72T6480, the Part Number field contains the following values:

Device	Part# Field
IDT72T6480	0438 (hex)

31(MSB) 28	27 12	11 1	0(LSB)
Version (4 bits) 0000	, ,	Manufacturer ID (11-bit) 0033 (hex)	1

IDT72T6480 JTAG Device Identification Register

JTAG INSTRUCTION REGISTER

The Instruction register allows an instruction to be serially input into the device when the TAP controller is in the Shift-IR state. The instruction is decoded to perform the following:

- Select test data registers that may operate while the instruction is current. The other test data registers should not interfere with chip operation and the selected data register.
- Define the serial test data register path that is used to shift data between TDI and TDO during data register scanning.

The Instruction Register is a 4 bit field (i.e. IR3, IR2, IR1, IR0) to decode 16 different possible instructions. Instructions are decoded as follows.

Hex	Instruction	Function
Value		
0000	EXTEST	Test external pins
0001	SAMPLE/PRELOAD	Select boundary scan register
0002	IDCODE	Selects chip identification register
0003	HIGH-IMPEDANCE	Puts all outputs in high-impedance state
8000	CLAMP	Fix the output chains to scan chain values
000F	BYPASS	Select bypass register
	Private	Several combinations are private (for IDT
		internal use). Do not use codes other than
		those identified above.

JTAG INSTRUCTION REGISTER DECODING

The following sections provide a brief description of each instruction. For a complete description refer to the IEEE Standard Test Access Port Specification (IEEE Std. 1149.1-1990).

EXTEST

The required EXTEST instruction places the device into an external boundary-test mode and selects the boundary-scan register to be connected between TDI and TDO. During this instruction, the boundary-scan register is accessed to drive test data off-chip via the boundary outputs and receive test data off-chip via the boundary inputs. As such, the EXTEST instruction is the workhorse of IEEE. Std 1149.1, providing for probe-less testing of solder-joint opens/shorts and of logic cluster function.

SAMPLE/PRELOAD

The required SAMPLE/PRELOAD instruction allows the device to remain in a normal functional mode and selects the boundary-scan register to be connected between TDI and TDO. During this instruction, the boundary-scan register can be accessed via a data scan operation, to take a sample of the functional data entering and leaving the device. This instruction is also used to preload test data into the boundary-scan register before loading an EXTEST instruction.

IDCODE

The optional IDCODE instruction allows the device to remain in its functional mode and selects the optional device identification register to be connected between TDI and TDO. The device identification register is a 32-bit shift register containing information regarding the device manufacturer, device type, and version code. Accessing the device identification register does not interfere with the operation of the device. Also, access to the device identification register should be immediately available, via a TAP data-scan operation, after power-up of the device or by otherwise moving to the Test-Logic-Reset state.

CLAMP

The optional CLAMP instruction sets the outputs of an device to logic levels determined by the contents of the boundary-scan register and selects the one-bit bypass register to be connected between TDI and TDO. Before loading this instruction, the contents of the boundary-scan register can be preset with the SAMPLE/PRELOAD instruction. During this instruction, data can be shifted through the bypass register from TDI to TDO without affecting the condition of the outputs.

HIGH-IMPEDANCE

The optional High-Impedance instruction sets all outputs (including two-state as well as three-state types) of an device to a disabled (high-impedance) state

and selects the one-bit bypass register to be connected between TDI and TDO. During this instruction, data can be shifted through the bypass register from TDI to TDO without affecting the condition of the device outputs.

BYPASS

The required BYPASS instruction allows the device to remain in a normal functional mode and selects the one-bit bypass register to be connected between TDI and TDO. The BYPASS instruction allows serial data to be transferred through the IC from TDI to TDO without affecting the operation of the device.

DEPTH EXPANSION CONFIGURATION

The sequential flow-control (SFC) device can be connected with multiple SFCs in depth expansion to provide additional storage density that's greater than 1Gb. In depth expansion mode, two or mode devices are connected through a common transfer interface, as shown in Figure 34. The transfer clock can be a separate free-running clock or driven from the same system write or read clock.

In depth expansion configuration, the first word written to an empty configuration will pass from the first SFC to the next until it appears on the second (or last) SFC in the chain. If no reads are performed, data will begin accumulating in the second SFC until it is full. Once the second SFC is full it will disable the REN to the first SFC. At this point data will begin accumulating in the first SFC. Once both devices are full, the entire configuration is full and the full flag indicator will go LOW.

For an empty configuration, the amount of time it takes for the empty flag of the second (or last) SFC in the chain to go LOW (i.e. valid data available to be

read out of the device) after a word has been written into the first FIFO is the sum of the delays for each individual SFC:

Where N is the number of SFCs in the chain and RCLK is the RCLK period in ns. This latency is only noticeable for the first word written to an empty configuration. There will be no delay evident for subsequent words written into the chain.

In the full configuration, the amount of time it takes for the FF of the first SFC to go from LOW to HIGH after reading one word from the chain is the sum of the delays for each individual SFC:

Depth expansion is available in both IDT Standard mode and First Word Fall Through (FWFT) mode. If IDT Standard mode is selected, the IDEM signal needs to be HIGH. If FWFT mode is selected, the IDEM signal needs to be LOW.

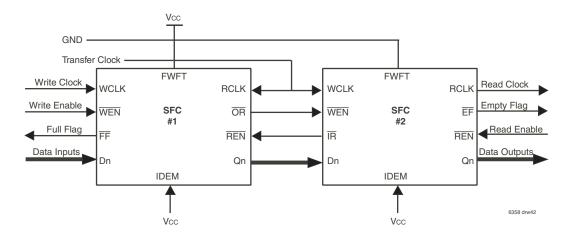


Figure 34. Depth Expansion Configuration in IDT Standard Mode

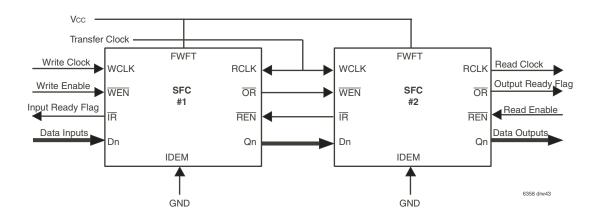
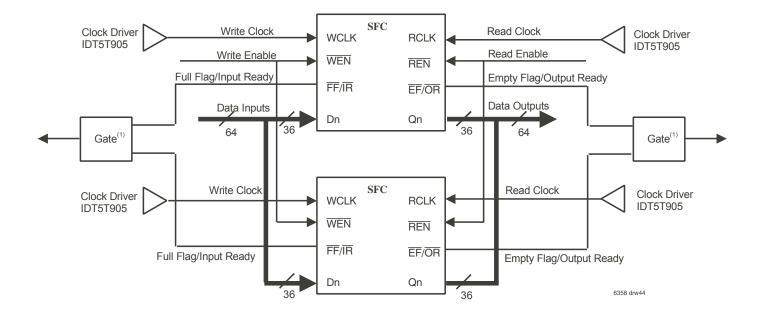


Figure 35. Depth Expansion Configuration in FWFT Mode

WIDTH EXPANSION CONFIGURATION

The sequential flow-control (SFC) device can be connected with another SFCs in width expansion to support bus-widths greater than 36-bits. This configuration connects the input and output bus of two devices together to create a wider bus. The read and write clocks for each device are driven with a clock driver. The empty and full flags of both devices are connected to a logic gate (AND/OR) depending on whether IDT Standard mode or FWFT mode is selected. Because of the variation in skew between the read clock and write

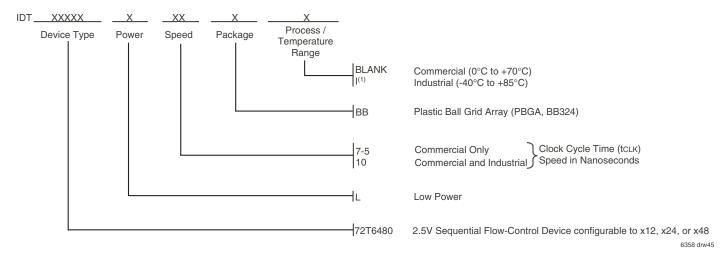
clock, it is possible for $\overline{\text{EF/FF}}$ deassertion and $\overline{\text{IR/OR}}$ assertion to vary from one cycle between the devices. The logic gate connected to the status flags will create a composite flag that will update the status of both SFC devices to represent a more accurate status of the configuration. To minimize the skew between the two write and read clocks, a clock driver (IDT5T905 recommended) is used to drive the input clocks for both SFC devices. Figure 36 illustrates the width expansion configuration.



- 1. Use an AND gate in IDT Standard mode, an OR gate in FWFT mode.
- 2. Do not connect any output signals directly together.

Figure 36. Width Expansion Configuration in IDT Standard Mode and FWFT Mode

ORDERING INFORMATION



DATASHEET DOCUMENT HISTORY

07/29/2004 pgs. 1, 4, 7-11, 13-25, 27-29, 31-43, 47, 49, and 51.

04/11/2005 pg. 10. 04/15/2005 pg. 10 and 51. 06/28/2005 pgs. 16 and 24. 10/10/2005 pgs. 1, 15 and 16.



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