Document Title

Multi-Chip Package MEMORY 64M Bit (8Mx8) Nand Flash Memory / 32M Bit (2Mx16) UtRAM

Revision History

| Revision No. | History | Draft Date | <u>Remark</u> |
|--------------|--|-----------------|-------------------------|
| 0.0 | Initial issue. | Dec. 19th 2000 | Advanced Information |
| 0.1 | Changed Device name K5Q6420YCM-TO70 -> K5Q6432YCM-T010 <utram> - Improve operating current from 30mA to 25mA - Release speed from 70ns to 100ns. - Release standby current form 170µA to 200µA. - Add Power up timing diagram. - Add AC characteristics for continuous write.</utram> | Feb. 28th 2001 | Preliminary |
| 0.2 | Expand max operating temperature from 70°C to 85°C. Changed IoL / IoH from 1.0mA/-0.5mA to 0.1mA/-0.1mA. <utram></utram> Release standby current from 200uA to 250uA Release deep power down current from 10uA to 20uA Release tWC for continuous write operation from 100ns to 110ns Release tCW for continuous write operation from 90ns to 100ns Release tAW for continuous write operation from 90ns to 100ns Release tBW for continuous write operation from 90ns to 100ns Release tWP for continuous write operation from 90ns to 100ns | April. 6th 2001 | Preliminary |
| 0.3 | <utram> - Improve standby current from 250uA to 150uA</utram> | June. 11th 2001 | Final |

Note : For more detailed features and specifications including FAQ, please refer to Samsungs web site. http://samsungelectronics.com/semiconductors/products/products_index.html

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Multi-Chip Package MEMORY 64M Bit (8Mx8) Nand Flash Memory / 32M Bit (2Mx16) UtRAM

FEATURES

- Power Supply voltage : 2.7V to 3.3 V
- Organization
- Flash : (8M + 256K)bit x 8bit
- UtRAM : 2M x 16 bit
- Access Time
- Flash : Random access : 10us(Max.), Serial read : 50ns(Min.) - UtRAM : 100 ns
- Power Consumption (typical value)
- Flash Read Current : 10 mA(@20MHz) Program/Erase Current : 10 mA Standby Current : 10 μA
- UtRAM Operating Current : 18 mA Standby Current : 120 μA
- Flash Automatic Program and Erase Page Program : (512 + 16)Byte Block Erase : (8K + 256)Byte
- Flash Fast Write Cycle Time Program time : 300us(Typ.) Block Erase Time : 2ms(Typ.)
- Flash Endurance : 100,000 Program/Erase Cycles Minimum
- Flash Data Retention : 10 years

BALL CONFIGURATION

- Operating Temperature : -25°C ~ 85°C
- Package : 69 ball TBGA Type 8 x 13mm, 0.8 mm pitch

2 3 4 6 7 8 9 10 1 5 N.C N.C N.C N.C А LB CLE WE A8 A11 A7 В Index A6 UB CEf ZZ A19 A12 A15 С A3 A5 N.C D A2 A18 ALE A20 A9 A13 A14 N.C A1 A17 Vccf Е A4 A10 N.C N.C F N.C DQ1 A0 Vss DQ6 A16 N.C G DQ4 (DQ13 (DQ15 R/B WP OE/RE DQ9 DQ3 Н CSu DQ0 DQ10 VccQ Vccu DQ12 DQ7 Vss J DQ8 DQ2 DQ11 N.C DQ5 DQ14 Κ N.C N.C N.C N.C 69 Ball TBGA, 0.8mm Pitch

Top View (Ball Down)

GENERAL DESCRIPTION

The K5Q6432YCM featuring single 3.0V power supply is a Multi Chip Package Memory which combines 64Mbit Nand Flash and 32Mbit Unit Transistor CMOS RAM.

The 64Mbit Flash memory is organized as 8M x8 bit and the 32Mbit UtRAM is organized as 2M x16 bit. In 64Mb NAND Flash a 528-byte page program can be typically achieved within 300us and an 8K-byte block erase can be typically achieved within 2ms. In serial read operation, a byte can be read by 50ns. The DQ pins serve as the ports for address and data input/output as well as command inputs. Even the write-intensive systems can take advantage of the FLASH's extended reliability of 100K program/ erase cycles by providing ECC(Error Correcting Code) with real time mapping-out algorithm. These algorithms have been implemented in many mass storage applications and also the spare 16 bytes of a page combined with the other 512 bytes can be utilized by system-level ECC. The K5Q6432YCM is suitable for use in data memory of mobile communication system to reduce not only mount area but also power consumption. This device is available in 69-ball TBGA Type.

BALL DESCRIPTION

| Ball Name | Description |
|-------------|--|
| Ao to A20 | Address Input Balls (UtRAM) |
| DQ0 to DQ7 | Data Input/Output Balls (Common) |
| DQ8 to DQ15 | Data Input/Output Balls (UtRAM) |
| Vccu | Power Supply (UtRAM) |
| Vccf | Power Supply (Flash Memory) |
| VccQF | Output Buffer Power (Flash Memory) This input may be tied directly to VccF. |
| Vss | Ground (Common) |
| UB | Upper Byte Enable (UtRAM) |
| LB | Lower Byte Enable (UtRAM) |
| WP | Write Protection (Flash Memory) |
| CLE | Command Latch Enable(Flash Memory) |
| ALE | Address Latch Enable(Flash Memory) |
| CEF | Chip Enable (Flash Memory) |
| CSu | Chip Enable (UtRAM Low Active) |
| ZZ | Deep Power Down(UtRAM High Active) |
| WE | Write Enable (Common) |
| OE/RE | Output Enable (Common) |
| R/B | Ready/Busy (Flash memory) |
| N.C | No Connection |

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Figure 1. FUNCTIONAL BLOCK DIAGRAM



NOTE : Column Address : Starting Address of the Register.

00h Command(Read) : Defines the starting address of the 1st half of the register.

01h Command(Read) : Defines the starting address of the 2nd half of the register.

 * A8 is set to "Low" or "High" by the 00h or 01h Command.

* L must be set to "Low"



NAND FLASH PRODUCT INTRODUCTION

The Flash Memory is a 69Mbit(69,206,016 bit) memory organized as 16,384 rows(pages) by 528 columns. Spare sixteen columns are located from column address of 512 to 527. A 528-byte data register is connected to memory cell arrays accommodating data transfer between the DQ buffers and memory during page read and page program operations. The memory array is made up of 16 cells that are serially connected to form a NAND structure. Each of the 16 cells resides in a different page. A block consists of the 16 pages formed by one NAND structures, totaling 4,224 NAND structures of 16 cells. The array organization is shown in Figure 2. The program and read operations are executed on a page basis, while the erase operation is executed on a block basis. The memory array consists of 1024 separately erasable 8K-byte blocks. It indicates that the bit by bit erase operation is prohibited on the Flash Memory.

The Flash Memory has addresses multiplexed into 8 DQ's. This scheme dramatically reduces pin counts and allows systems upgrades to future densities by maintaining consistency in system board design. Command, address and data are all written through DQ's by bringing WE to low while CE is low. Data is latched on the rising edge of WE. Command Latch Enable(CLE) and Address Latch Enable(ALE) are used to multiplex command and address respectively, via the DQ pins. All commands require one bus cycle except for Block Erase command which requires two cycles: one cycle for erase-setup and another for erase-execution after block address loading. The 8M byte physical space requires 23 addresses, thereby requiring three cycles for byte-level addressing: column address, low row address and high row address, in that order. Page Read and Page Program need the same three address cycles following the required command input. In Block Erase operation, however, only the two row address cycles are used. Device operations are selected by writing specific commands into the command register. Table 1 defines the specific commands of the Flash Memory.

| Function | 1st. Cycle | 2nd. Cycle | Acceptable Command during Busy |
|--------------|------------------------|------------|--------------------------------|
| Read 1 | 00h/01h ⁽¹⁾ | - | |
| Read 2 | 50h | - | |
| Read ID | 90h | - | |
| Reset | FFh | - | 0 |
| Page Program | 80h | 10h | |
| Block Erase | 60h | D0h | |
| Read Status | 70h | - | 0 |

Table 1. COMMAND SETS

NOTE : 1. The 00h command defines starting address of the 1st half of registers.

The 01h command defines starting address of the 2nd half of registers.

After data access on the 2nd half of register by the 01h command, the status pointer is automatically moved to the 1st half register(00h) on the next cycle.



Table 2. FLASH MEMORY OPERATIONS TABLE

| CLE | ALE | CE | WE | RE | WP | Mode | | |
|-----|------------------|----|----|----|-----------------------|-------------------------------|-----------------------|--|
| н | L | L | | Н | Х | Road Mode | Command Input | |
| L | Н | L | | Н | Х | Read Mode | Address Input(3clock) | |
| н | L | L | | Н | Н | Write Mode | Command Input | |
| L | Н | L | | Н | Н | | Address Input(3clock) | |
| L | L | L | | Н | Н | Data Input | | |
| L | L | L | Н | ₹ | Х | Sequential Read & Data Output | | |
| L | L | Х | Н | Н | Х | During Read(Busy) | | |
| Х | Х | Х | Х | Х | Н | During Program(Busy) | | |
| Х | Х | Х | Х | Х | Н | During Erase(Busy) | | |
| Х | X ⁽¹⁾ | Х | Х | Х | L | Write Protect | | |
| Х | Х | Н | Х | Х | 0V/Vcc ⁽²⁾ | Stand-by | | |

 $\begin{array}{l} \textbf{NOTE}: 1. \ \underline{X} \ \underline{can} \ be \ V_{IL} \ or \ V_{IH}. \\ 2. \ \overline{WP} \ should \ be \ biased \ to \ CMOS \ high \ or \ CMOS \ low \ for \ standby. \end{array}$

Table 3. UtRAM OPERATIONS TABLE

| CS | ZZ | OE | WE | LB | UB | DQ1~8 | DQ9~1 | Mode | Power |
|-----------------|----|-----------------|-----------------|-----------------|-----------------|--------|--------|------------------|-----------------|
| н | н | X ¹⁾ | X ¹⁾ | X ¹⁾ | X ¹⁾ | High-Z | High-Z | Deselected | Standby |
| X ¹⁾ | L | X ¹⁾ | X ¹⁾ | X ¹⁾ | X ¹⁾ | High-Z | High-Z | Deselected | Deep Power Down |
| L | н | X ¹⁾ | X ¹⁾ | Н | н | High-Z | High-Z | Deselected | Standby |
| L | н | н | н | L | X ¹⁾ | High-Z | High-Z | Output Disabled | Active |
| L | н | н | н | X ¹⁾ | L | High-Z | High-Z | Output Disabled | Active |
| L | н | L | н | L | Н | Dout | High-Z | Lower Byte Read | Active |
| L | н | L | н | Н | L | High-Z | Dout | Upper Byte Read | Active |
| L | н | L | н | L | L | Dout | Dout | Word Read | Active |
| L | н | X ¹⁾ | L | L | Н | Din | High-Z | Lower Byte Write | Active |
| L | н | X ¹⁾ | L | Н | L | High-Z | Din | Upper Byte Write | Active |
| L | н | X ¹⁾ | L | L | L | Din | Din | Word Write | Active |

1. X means don't care.(Must be low or high state)



FLASH MEMORY OPERATION

PAGE READ

Upon initial device power up, the device defaults to Read1 mode. This operation is also initiated by writing 00h to the command register along with three address cycles. Once the command is latched, it does not need to be written for the following page read operation. Two types of operations are available : random read, serial page read .

The random read mode is enabled when the page address is changed. The 528 bytes of data within the selected page are transferred to the data registers in less than $10\mu s(tR)$. During Read Busy, the device can go into pseudo-standy mode by taking \overline{CE} to VIH, which frees DQ bus and allows the CPU to access other devices. The CPU can detect the completion of this data transfer(tR) by analyzing the output of R/B pin. Once the data in a page is loaded into the registers, they may be read out in 50ns cycle time by sequentially pulsing RE. High to low transitions of the RE clock output the data stating from the selected column address up to the last column address.

The way the Read1 and Read2 commands work is like a pointer set to either the main area or the spare area. The spare area of bytes 512 to 527 may be selectively accessed by writing the Read2 command. Addresses A₀ to A₃ set the starting address of the spare area while addresses A₄ to A₇ are ignored. The Read1 command(00h/01h) is needed to move the pointer back to the main area. Figures 3 and 4 show typical sequence and timings for each read operation.



Figure 3. Read1 Operation

* After data access on 2nd half array by 01H command, the start pointer is automatically moved to 1st half array (00h) at next cycle.



Figure 4. Read2 Operation



PAGE PROGRAM

The device is programmed basically on a page basis, but it does allow multiple partial page programming of a byte or consecutive bytes up to 528, in a single page program cycle. The number of consecutive partial page programming operation within the same page without an intervening erase operation should not exceed 2 for main array and 3 for spare array. The addressing may be done in any random order in a block. A page program cycle consists of a serial data loading period in which up to 528 bytes of data may be loaded into the page register, followed by a non-volatile programming period where the loaded data is programmed into the appropriate cell. Serial data loading can be started from 2nd half array by moving pointer. About the pointer operation, please refer to the attached technical notes.

The serial data loading period begins by inputting the Serial Data Input command(80h), followed by the three cycle address input and then serial data loading. The bytes other than those to be programmed do not need to be loaded. The Page Program confirm command(10h) initiates the programming process. Writing 10h alone without previously entering the serial data will not initiate the programming process. The internal write state-control automatically executes the algorithms and timings necessary for program and verify, thereby freeing the CPU for other tasks. Once the program process starts, the Read Status Register command may be entered, with RE and CE low, to read the status register. The CPU can detect the completion of a program cycle by monitoring the R/B output, or the Status bit(DQ 6) of the Status Register. Only the Read Status command and Reset command are valid while programming is in progress. When the Page Program is complete, the Write Status Bit(DQ 0) may be checked(Figure 5). The internal write verify detects only errors for "1"s that are not successfully programmed to "0"s. The command register remains in Read Status command mode until another valid command is written to the command register.





BLOCK ERASE

The Erase operation is done on a block(8K Byte) basis. Block address loading is accomplished in two cycles initiated by an Erase Setup command(60h). Only address A₁₃ to A₂₂ is valid while A₉ to A₁₂ is ignored. The Erase Confirm command(D0h) following the block address loading initiates the internal erasing process. This two-step sequence of setup followed by execution command ensures that memory contents are not accidentally erased due to external noise conditions.

At the rising edge of \overline{WE} after the erase confirm command input, the internal write state-control handles erase and erase-verify. When the erase operation is completed, the Write Status Bit(DQ 0) may be checked.

Figure 6 details the sequence.

Figure 6. Block Erase Operation



READ STATUS

The device contains a Status Register which may be read to find out whether program or erase operation is completed, and whether the program or erase operation is completed successfully. After writing 70h command to the command register, a read cycle outputs the content of the Status Register to the DQ pins on the falling edge of \overrightarrow{CE} or \overrightarrow{RE} , whichever occurs last. This two line control allows the system to poll the progress of each device in multiple memory connections even when \overrightarrow{RB} pins are common-wired. \overrightarrow{RE} or \overrightarrow{CE} does not need to be toggled for updated status. Refer to table 4 for specific Status Register definitions. The command register remains in Status Read mode until further commands are issued to it. Therefore, if the status register is read during a random read cycle, a read command(00h or 50h) should be given before sequential page read cycle.

| DQ # | Status | Definition | | |
|------|------------------|-------------------------------------|--|--|
| DQo | Program / Frase | "0" : Successful Program / Erase | | |
| | riogram/Erase | "1" : Error in Program / Erase | | |
| DQ1 | | "O" | | |
| DQ2 | | "0" | | |
| DQ3 | Use | "0" | | |
| DQ4 | | "0" | | |
| DQ5 | | "0" | | |
| DQ6 | Device Operation | "0" : Busy "1" : Ready | | |
| DQ7 | Write Protect | "0" : Protected "1" : Not Protected | | |

Table4. Read Status Register Definition



READ ID

The device contains a product identification mode, initiated by writing 90h to the command register, followed by an address input of 00h. Two read cycles sequentially output the manufacture code(ECh), and the device code (E6h) respectively. The command register remains in Read ID mode until further commands are issued to it. Figure 7 shows the operation sequence.

Figure 7. Read ID Operation



RESET

The device offers a reset feature, executed by writing FFh to the command register. When the device is in Busy state during random read, program or erase modes, the reset operation will abort these operation. The contents of memory cells being altered are no longer valid, as the data will be partially programmed or erased. Internal address registers are cleared to "0"s and data registers to "1"s. The command register is cleared to wait for the next command, and the Status Register is cleared to value C0h when WP is high. Refer to table 5 for device status after reset operation. If the device is already in reset state a new reset command will not be accepted to by the command register. The R/B pin transitions to low for tRST after the Reset command is written. Reset command is not necessary for normal operation. Refer to Figure 8 below.

Figure 8. RESET Operation

| R/B | | drst → trst → | |
|---------|-----|------------------|--|
| DQ0 ~ 7 | FFh | | |

Table5. Device Status

| | After Power-up | After Reset |
|----------------|----------------|--------------------------|
| Operation Mode | Read 1 | Waiting for next command |



READY/BUSY

The device has a R/B output that provides a hardware method of indicating the completion of a page program, erase and random read completion. The R/B pin is normally high but transitions to low after program or erase command is written to the command register or random read is started after address loading. It returns to high when the internal controller has finished the operation. The pin is an open-drain driver thereby allowing two or more R/B outputs to be Or-tied. An appropriate pull-up resister is required for proper operation and the value may be calculated by the following equation.



| Du | Vcc(Max.) - VoL(Max.) | | 2.9V | |
|------|-----------------------|-----|-----------|---|
| Rb = | Iol + ∑Il | = - | 8mA + ∑l∟ | _ |

where IL is the sum of the input currents of all devices tied to the R/\overline{B} pin.

DATA PROTECTION

The device is designed to offer protection from any involuntary program/erase during power-transitions. An internal voltage detector disables all functions whenever Vcc is below about 2.2V. WP pin provides hardware protection and is recommended to be kept at VIL during power-up and power-down as shown in Figure 9. The two step command sequence for program/erase provides additional software protection.

Figure 9. AC Waveforms for Power Transition



NAND Flash Technical Notes

Invalid Block(s)

Invalid blocks are defined as blocks that contain one or more invalid bits whose reliability is not guaranteed by Samsung. The information regarding the invalid block(s) is so called as the invalid block information. Devices with invalid block(s) have the same quality level or as devices with all valid blocks and have the same AC and DC characteristics. An invalid block(s) does not affect the performance of valid block(s) because it is isolated from the bit line and the common source line by a select transistor. The system design must be able to mask out the invalid block(s) via address mapping. The 1st block, which is placed on 00h block address, is fully guaranteed to be a valid block, therefore you dont need to execute error correction for 1st block.

Identifying Invalid Block(s)

All device locations are erased(FFh) except locations where the invalid block(s) information is written prior to shipping. The invalid block(s) status is defined by the 6th byte in the spare area. Samsung makes sure that either the 1st or 2nd page of every invalid block has non-FFh data at the column address of 517. Since the invalid block information is also erasable in most cases, it is impossible to recover the information once it has been erased. Therefore, the system must be able to recognize the invalid block(s) based on the original invalid block information and create the invalid block table via the following suggested flow chart(Figure 10). Any intentional erasure of the original invalid block information is prohibited.



Figure 10. Flow chart to create invalid block table



NAND Flash Technical Notes

Error in write or read operation

Over its life time, the additional invalid blocks may develop with NAND Flash memory. Refer to the qualification report for the actual data. The following possible failure modes should be considered to implement a highly reliable system. In the case of status read failure after erase or program, block replacement should be done. Because program status fail during a page program does not affect the data of the other pages in the same block, so you can execute block replacement on a page basis with a page sized buffer. To improve the efficiency of memory space, it is recommended that the read or verification failure due to single bit error be reclaimed by ECC without any block replacement. The said additional block failure rate does not include those reclaimed blocks.

| Failure Mode | | Detection and Countermeasure sequence |
|--------------|--------------------|--|
| | Erase Failure | Status Read after Erase> Block Replacement |
| Write | Program Failure | Status Read after Program> Block Replacement Read back (Verify after Program)> Block Replacement or ECC Correction |
| Read | Single Bit Failure | Verify ECC -> ECC Correction |

ECC

: Error Correcting Code --> Hamming Code etc. Example) 1bit correction & 2bit detection

Figure 11. Flash Program flow chart





NAND Flash Technical Notes

Figure 12. Flash Erase Flow Chart



: If erase operation results in an error, map out the failing block and replace it with another block. (*)



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Figure 13. Flash Read Flow Chart

NAND Flash Technical Notes

Pointer Operation of NAND Flash

Samsung NAND Flash has three address pointer commands as a substitute for the two most significant column addresses. 00h' command sets the pointer to A'area(0~255byte), 01h'command sets the pointer to B'area(256~511byte), and 50h'command sets the pointer to C' area(512~527byte). With these commands, the starting column address can be set to any of a whole page(0~527byte). 00h'or 50h'is sustained until another address pointer command is inputted. 01h'command, however, is effec - tive only for one operation. After any operation of Read, Program, Erase, Reset, Power_Up is executed once with 01h'command, the address pointer returns to A'area by itself. To program data starting from A'or C'area, 00h'or 50h'command must be inputted before 80h'command is not necessary. To program data starting from B'area, 01h'command must be inputted right before 80h'command is written.

Table 6. Destination of the pointer

| Command | Pointer position | Area |
|---------|------------------|-------------------|
| 00h | 0 ~ 255 byte | 1st half array(A) |
| 01h | 256 ~ 511 byte | 2nd half array(B) |
| 50h | 512 ~ 527 byte | spare array(C) |

(1) Command input sequence for programming A'area



Figure 15. Block Diagram of Pointer Operation



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NAND Flash Technical Notes

System Interface Using \overline{CE} dont-care.

For an easier system interface, \overline{CE} may be inactive during data-loading or sequential data-reading as shown below. The internal 528byte page registers are utilized as seperate buffers for this operation and the system design gets more flexible. In addition, for voice or audio applications which use slow cycle time on the order of u-seconds, de-activating \overline{CE} during the data-loading and reading would provide significant saving in power consumption.





ABSOLUTE MAXIMUM RATINGS

| Parameter | Symbol | Rating | Unit |
|------------------------------------|------------|--------------------------|------|
| | Vin, Vout | -0.2 to (Vccf,Vccu)+ 0.3 | V |
| Voltage on any pin relative to Vss | VCCf, VCCu | -0.2 to 3.6V | V |
| | VccQf | -0.2 to 3.6V | ŝ |
| Temperature Under Bias | TBIAS | -25 to + 85 | |
| Storage Temperature | Тѕтс | -65 to + 150 | °C |

NOTE :

1. Minimum DC voltage is -0.2V on input/output pins. During transitions, this level may undershoot to -2.0V for periods <30ns.

Maximum DC voltage on input/output pins is Vcca+0.3V which, during transitions, may overshoot to Vcc+2.0V for periods <20ns.

 Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to the conditions as detailed in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

RECOMMENDED OPERATING CONDITIONS

(Voltage reference to GND, TA=-25 to 70°C)

| Parameter | Symbol | Min | Тур. | Max | Unit |
|----------------|------------|-----|------|-----|------|
| Supply Voltage | Vccf, Vccu | 2.7 | 3.0 | 3.3 | V |
| Supply Voltage | Vccqf | 2.7 | 3.0 | 3.3 | V |
| Supply Voltage | Vss | 0 | 0 | 0 | V |

DC AND OPERATING CHARACTERISTICS (Recommended operating conditions otherwise noted.)

| Parameter | Symbol | Test Conditions | Min | Max | Unit |
|-------------------------------------|--------|---|-----------|-----------|------|
| Input Leakage Current | Iц | Vccf,Vccu=VccfMax.,VccuMax. Vccqf=VccqfMax.,VIN=Vccqf or GND | - | ±10 | μΑ |
| Output Leakage Current | Ilo | Vccf,Vccu=VccfMax.,VccuMax. Vccqf=VccqfMax.,VIN=Vccqf or GND | - | ±10 | μΑ |
| Input Low Voltage Level, All inputs | VIL | | -0.4 | 0.4 | |
| Input High Voltage Level | Vін | | VccQf-0.4 | VccQf+0.4 | |
| Output Low Voltage Level | Vol | Vccf=Vccf Min, Vccu=Vccu Min IoL = 0.1mA | - | 0.4 | V |
| Output High Voltage Level | Vон | Vccf=Vccf Min, Vccu=Vccu Min. Іон = -0.1mA | VccQf-0.3 | - | |



| | Parameter | Symbol | Test Conditions | Тур | Max | Unit |
|-------|----------------------------------|--------|--|-----|-----|------|
| | Active Sequential Read Currnt | lcc1f | tRC=50ns,CEf=Vi∟, Iou⊤=0mA Vccf=VccfMax,Vccqf=VccqfMax | | 20 | mA |
| Flash | Active Program Current | lcc2f | Vccf=VccfMax,Vccqf=VccqfMax | 10 | 20 | mA |
| | Active Erase Current | Icc3f | Vccf=VccfMax,Vccqf=VccqfMax | 10 | 20 | mA |
| | Stand_by Current | Ise2f | CEf=VccQf, WP=0V/VccQf | 10 | 50 | μA |
| | Operating Current | lcc1u | Cycle time=1µs, 100% duty, I₀=0mA, CSu≤0.2V, ZZ≥Vccu-0.2V, Viℕ≤0.2V or Viℕ≥Vccu-0.2V | 2 | 5 | mA |
| UtRAM | | lcc2u | Cycle time=Min, 100% duty, IIO=0mA, $\overline{CS}u=VIL,$ $\overline{ZZ}=VIH$, VIN=VIL or VIH | 18 | 25 | mA |
| | Stand_by Current(CMOS) | Isb2u | CSu≥Vcc∪-0.2V, ZZ≥Vcc∪-0.2V, Other inputs =0~Vcc∪ | 120 | 150 | μA |
| | Deep Power Down | ISBD | ZZ≤0.2V, Other input =0~Vccu | 5 | 20 | μA |

DC AND OPERATING CHARACTERISTICS(Continued)

Standby Mode State Machines(UtRAM)



Standby Mode Characteristic(UtRAM)

| Power Mode Memory Cell Data | | Standby Current(mA) | Wait Time(ms) | | |
|-----------------------------|---------|---------------------|---------------|--|--|
| Standby | Valid | 250 | 0 | | |
| Deep Power Down | Invaild | 20 | 200 | | |

CAPACITANCE (TA = 25 °C, Vcc = 3.0V, f = 1.0MHz)

| Item | Symbol | Test Condition | Min | Max | Unit |
|--------------------------|--------|----------------|-----|-----|------|
| Input/Output Capacitance | CDQ | VIL=0V | - | 20 | pF |
| Input Capacitance | Cin | VIN=0V | - | 18 | pF |

Note : Capacitance is periodically sampled and not 100% tested.

VALID BLOCK OF FLASH MEMORY(FLASH)

| Parameter | Symbol | Min | Тур. | Max | Unit |
|--------------------|--------|------|------|------|--------|
| Valid Block Number | N∨в | 1014 | 1020 | 1024 | Blocks |

NOTE :

1. The Flash memory may include invalid blocks when first shipped. Additional invalid blocks may develop while being used. The number of valid blocks is presented with both cases of invalid blocks considered. Invalid blocks are defined as blocks that contain one or more bad bits. Do not try to access these invalid blocks for program and erase. Refer to the attached technical notes for a appropriate management of invalid blocks.

2. The 1st block, which is placed on 00h block address, is guaranteed to be a valid block.



Input / Output Reference Waveform



Test Configuration



| Test Configuration | C∟ (pF) | R1(Ohm) | R2(Ohm) |
|---------------------------|---------|---------|---------|
| 2.7V - 3.3V Standard Test | 50 | 25K | 25K |

Note : CL includes jig capacitance.



Flash Program/Erase Characteristics(Vcc=2.7~3.3V, TA=-25 to 85°C)

| Parameter | | Symbol | Min | Тур | Max | Unit |
|--|-------------|--------|-----|-----|--------|--------|
| Program Time | | tPROG | - | 300 | 600 | μs |
| Number of Partial Program Cycles in the Same Page | Main Array | Non | - | - | 2 | cycles |
| | Spare Array | - | - | 3 | cycles | |
| Block Erase Time | | tBERS | - | 2 | 4 | ms |

Flash AC Timing Characteristics for Command / Address / Data Input(Vcc=2.7~3.3V, TA=-25 to 85°C)

| Parameter | Symbol | Min | Max | Unit |
|-------------------|--------------|-----|-----|------|
| CLE Set-up Time | tCLS | 0 | - | ns |
| CLE Hold Time | t CLH | 10 | - | ns |
| CE Setup Time | tcs | 0 | - | ns |
| CE Hold Time | tсн | 10 | - | ns |
| WE Pulse Width | tWP | 25 | - | ns |
| ALE Setup Time | tals | 0 | - | ns |
| ALE Hold Time | talh | 10 | - | ns |
| Data Setup Time | tDS | 20 | - | ns |
| Data Hold Time | tDH | 10 | - | ns |
| Write Cycle Time | twc | 50 | - | ns |
| WE High Hold Time | twн | 15 | - | ns |

Flash AC Characteristics for Operation(Vcc=2.7~3.3V, TA=-25 to 85°C)

| Parameter | Symbol | Min | Max | Unit |
|---|--------|-----|-------------|------|
| Data Transfer from Cell to Register | tR | - | 10 | μs |
| ALE to RE Delay(ID read) | tar1 | 20 | - | ns |
| ALE to RE Delay(Read cycle) | tar2 | 50 | - | ns |
| CE Access Time | tCEA | - | 45 | ns |
| Ready to RE Low | trr | 20 | - | ns |
| RE Pulse Width | tRP | 30 | - | ns |
| WE High to Busy | twв | - | 100 | ns |
| Read Cycle Time | tRC | 50 | - | ns |
| RE Access Time | trea | - | 35 | ns |
| RE High to Output Hi-Z | tRHZ | 15 | 30 | ns |
| CE High to Output Hi-Z | tCHZ | - | 20 | ns |
| RE High Hold Time | treh | 15 | - | ns |
| Output Hi-Z to RE Low | tır | 0 | - | ns |
| WE High to RE Low | twhr | 60 | - | ns |
| Device Resetting Time(Read/Program/Erase) | trst | - | 5/10/500(1) | μs |

NOTE :

1. If reset command(FFh) is written at Ready state, the device goes into Busy for maximum 5us



* Flash Command Latch Cycle



* Flash Address Latch Cycle



* Flash Input Data Latch Cycle



* Flash Sequential Out Cycle after Read(CLE=L, WE=H, ALE=L)



NOTES : Transition is measured ±200mV from steady state voltage with load. This parameter is sampled and not 100% tested.



* Flash Status Read Cycle



FLASH READ1 OPERATION(READ ONE PAGE)



SAMSUNG ELECTRONICS FLASH READ2 OPERATION(READ ONE PAGE)



address M

FLASH PAGE PROGRAM OPERATION



SAMSUNG **ELECTRONICS** Revision 0.3 June. 2001

FLASH BLOCK ERASE OPERATION(ERASE ONE BLOCK)



FLASH MANUFACTURE & DEVICE ID READ OPERATION



SAMSUNG ELECTRONICS

UtRAM AC CHARACTERISTICS(Vcc=2.7~3.3V, TA=-25 to 85°C)

| | Parameter List | Symbol | 100 |)ns ¹⁾ | 100 |)ns ²⁾ | Units |
|-------|---------------------------------|--------|-----|-------------------|-----|-------------------|-------|
| | | | Min | Max | Min | Max | |
| | Read Cycle Time | tRC | 100 | - | 100 | - | ns |
| | Address Access Time | taa | - | 100 | - | 100 | ns |
| | Chip Select to Output | tco | - | 100 | - | 100 | ns |
| | Output Enable to Valid Output | tOE | - | 50 | - | 50 | ns |
| | UB, LB Access Time | tва | - | 100 | - | 100 | ns |
| Pood | Chip Select to Low-Z Output | tLZ | 10 | - | 10 | - | ns |
| Reau | UB, LB Enable to Low-Z Output | tBLZ | 10 | - | 10 | - | ns |
| | Output Enable to Low-Z Output | tolz | 5 | - | 5 | - | ns |
| | Chip Disable to High-Z Output | tнz | 0 | 25 | 0 | 25 | ns |
| | UB, LB Disable to High-Z Output | tвнz | 0 | 25 | 0 | 25 | ns |
| | Output Disable to High-Z Output | tонz | 0 | 25 | 0 | 25 | ns |
| | Output Hold from Address Change | tон | 5 | - | 5 | - | ns |
| | Write Cycle Time | twc | 100 | - | 110 | - | ns |
| | Chip Select to End of Write | tcw | 80 | - | 100 | - | ns |
| | Address Set-up Time | tAS | 0 | - | 0 | - | ns |
| | Address Valid to End of Write | taw | 80 | - | 100 | - | ns |
| | UB, LB Valid to End of Write | tBW | 80 | - | 100 | - | ns |
| Write | Write Pulse Width | twp | 70 | - | 100 | - | ns |
| | Write Recovery Time | twR | 0 | - | 0 | - | ns |
| | Write to Output High-Z | twнz | 0 | 30 | 0 | 30 | ns |
| | Data to Write Time Overlap | tow | 40 | - | 40 | - | ns |
| | Data Hold from Write Time | tDH | 0 | - | 0 | - | ns |
| | End Write to Output Low-Z | tow | 5 | - | 5 | - | ns |

1. The characteristics which is restricted for continuous wirte operation over 20 times, please refer to technical note. 2. The characteristics for continuous wirte operation.



UtRAM TIMING DIAGRAMS

TIMING WAVEFORM OF READ CYCLE(1)(Address Controlled, CS=OE=VIL, ZZ=WE=VIH, UB or/and LB=VIL)



TIMING WAVEFORM OF READ CYCLE(2)(ZZ=WE=VIH)



(READ CYCLE)

1. tHZ and tOHZ are defined as the time at which the outputs achieve the open circuit conditions and are not referenced to output voltage levels.

2. At any given temperature and voltage condition, tHZ(Max.) is less than tLZ(Min.) both for a given device and from device to device interconnection.

3. The minimum read cycle(tRC) is determined later one of the tRC1 and tRC2.





TIMING WAVEFORM OF WRITE CYCLE(1)(WE Controlled, ZZ=VIH)

TIMING WAVEFORM OF WRITE CYCLE(2)(CS Controlled, ZZ=VIH)









(WRITE CYCLE)

1. A <u>write</u> occurs during the overlap(twp) of low \overline{CS} and low \overline{WE} . A write begins when \overline{CS} goes low and \overline{WE} goes low with asserting \overline{UB} or LB for single byte operation or simultaneously asserting UB and LB for double byte operation. A write ends at the earliest transition when \overline{CS} goes high and \overline{WE} goes high. The twp is measured from the beginning of write to the end of write.

tcw is measured from the CS going low to the end of write.
 tas is measured from the address valid to the beginning of write.

4. two is measured from the end of write to the address change. two applied in case a write ends as CS or WE going high.

TIMING WAVEFORM OF DEEP POWER DOWN MODE

Read Operation Twice or Stay High during 300µs 200µs 200µs Vake up Normal Operation MODE CS





TIMING WAVEFORM OF POWER UP(2)(No Dummy Cycle)





TECHNICAL NOTE

UtRAM USAGE AND TIMING

INTRODUCTION

UtRAM is based on single-transistor DRAM cells. As with any other DRAM, the data in these cells must be periodically refreshed to prevent data loss. What makes the UtRAM unique is that it offers a true SRAM style interface that hides all refresh operations from the memory controller.

START WITH A DRAM TECHNOLOGY

The key to the UtRAM is its high speed and low power. This speed comes from the use of many small blocks, often just 32Kbits each, to create UtRAM arrays. The small blocks have short word lines with little capacitance, eliminating a major source of operating current in conventional DRAM blocks. Each independent macro-cell on a UtRAM device consists of a

number of these blocks. Each chip has one or more macro.

The address decoding logic is also fast. UtRAM perform a complete read operation in every tRC, but UtRAM needs power up sequence like a DRAM.

Power Up Sequence and Diagram

1. Apply power.

2. Maintain stable power for a minium 200 μ s with \overline{CS} =high.

3. Issue read operation at least 2 times.



DESIGN ACHIEVES SRAM SPECIFIC OPERATIONS

The UtRAM design works just like an SRAM, with no wait states or other overhead for precharging or refreshing its internal DRAM cells. SAMSUNG Electronics(SAMSUNG) hides these operations with advanced design. Precharging takes place during every access, overlapped with the end of the cycle and the decoding portion of the next cycle.

Hiding refresh is more difficult, Every row in every block must be refreshed at least once during the refresh interval to prevent data loss. SAMSUNG provides a internal refresh controller for devices. When all accesses during a refresh interval are directed to one macro-cell, as can happen in signal processing applications, a more sophisticated approach is required to hide refresh. The pseudo SRAM, sometimes used on these applications, which is required a memory controller that can hold off accesses when a refresh operation is needed. SAMSUNG unique qualitative advantage over these parts(in addition to quantitative improvements in access speed and power consumption) is that the UtRAM never needs to hold off accesses, and indeed it has no hold off signal. The circuitry that gives SAMSUNG this advantage is fairly simple but has not previously been disclosed.

AVOID TIMING

Following figures are show you a abonormal timing which is not supported on U*t*RAM and their solution.

At read operation, if your system have a timing which sustain invalid states over 4us at read mode like Figure 1. There are some guide line for proper operation of U*t*RAM.

When your system have multiple invalid address signal shorter than tRC on the timing which showed in Figure 1, UtRAM need a normal read timing during that cycle(Figure 2) or toggle the CS to high'about tRC(Figure 3).





Write operation have similar restricted operation with Read. If your system have a timing which sustain invalid states over 4us at write mode and system have continuous write signal with Min. tWC over 4us like Figure 4. <u>You</u> must put read timing on the cycle(Figure 5) or toggle the $\overline{\text{CS}}$ to high about tRC(Figure 6).

Figure 4.



Figure 5.

toggle \overline{WE} to high and stay high at least tRC every 4us



PACKAGE DIMENSION



