ST52F501L/F502L

8-BIT INTELLIGENT CONTROLLER UNIT (ICU)
IR Driver, Timer/PWM, I^2C, SPI, SCI, Low Voltage

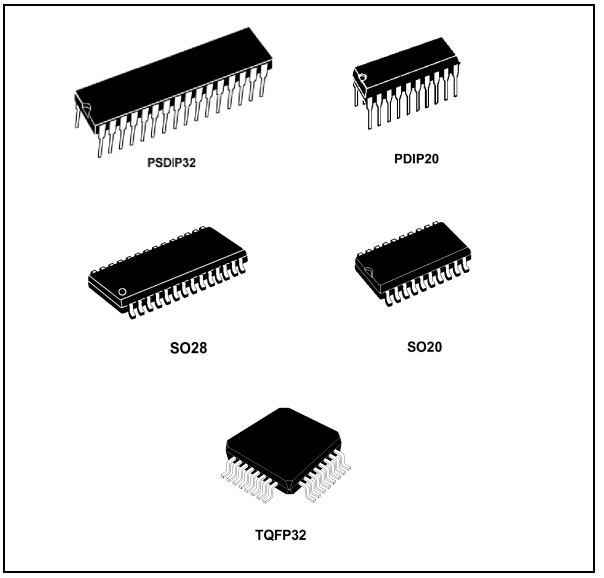
PRODUCT PREVIEW

Memories
- Up to 8 Kbytes Single Voltage Flash Memory
- 256 bytes of Register File
- 256 bytes of RAM
- 256 bytes Data EEPROM (F502L only)
- In Situ Programming in Flash devices (ISP)
- Single byte and Page modes and In Application Programming for writing data in Flash memory
- Readout protection and flexible write protection

Core
- Register File based architecture
- 107 basic instructions
- Hardware multiplication and division
- Decision Processor for the implementation of Fuzzy Logic algorithms
- Deep System and User Stacks

Clock and Power Supply
- Up to 16 MHz clock frequency
- Programmable Oscillator modes:
  - Internal Oscillator with four programmable frequencies (1.25, 2.5, 5, 10 MHz ± 1%)
  - External Clock/ Oscillator
- Low Voltage supply (1.8 - 3.6 V)
- Power Down Reset (PDR) protection
- Power-On Reset (POR)
- Programmable Low Voltage Detector (PLVD)
- Power Saving features
- Programmable Halt mode Wakeup (PHW) with internal 32 KHz oscillator
- Low consumption in Halt Mode with PHW and PDR enabled.

I/O Ports
- From 14 up to 24 I/O PINs configurable in pull-up, push-pull, weak pull-up, open-drain and high-impedance
- High current sink/source in all pins



Interrupts
- 10 interrupt vectors with one SW Trap
- Non-Maskable Interrupt (NMI)
- Two Port Interrupts with up to 24 sources

Peripherals
- Programmable 8-bit Timer/PWM with internal 16-bit Prescaler featuring PWM or Pulse output, Input capture and Output compare.
- Programmable 8-bit Timer/PWM with internal 16-bit Prescaler and IR Driver for remote control
- Watchdog timer
- I^2C™ Peripheral with master and slave mode
- 3-wire SPI™ Peripheral supporting Single Master and Multi Master SPI modes
- Serial Communication Interface (SCI) with asynchronous protocol (UART)

Development tools
- High level Software tools
- 'C' Compiler
- Emulator
- Low cost Programmer
- Gang Programmer

This is preliminary information on a new product foreseen to be developed. Details are subject to change without notice.

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1 GENERAL DESCRIPTION

1.1 Introduction

ST52F501L/F502L are devices of ST FIVE family of 8-bit Intelligent Controller Units (ICU), which can perform, both boolean and Fuzzy algorithms in an efficient manner, in order to reach the best performances that the two methodologies allow.

Produced by STMicroelectronics using the reliable high performance low power/low voltage CMOS process for Single Voltage Flash versions, ST52F501L/F502L include integrated on-chip peripherals that allow maximization of system reliability, and decreased system costs in order to minimize the number of external components, in particular it is suitable for portable applications.

The flexible I/O configuration of ST52F501L/F502L allow one to interface with a wide range of external devices (for example D/A converters or power control devices), and to communicate with the most common serial standards.

ST52F501L/F502L pins are configurable. The user can set input or output signals on each single pin in 8 different modes, reducing the need for external components in order to supply a suitable interface with the port pins.

A hardware multiplier and divider, together with a wide instruction set, allow the implementation of complex functions by using a single instruction. Therefore, program memory utilization and computational speed is optimized.

Fuzzy Logic dedicated structures in ST52F501L/F502L ICU's can be exploited to model complex system with high accuracy in a useful and simple manner.

Fuzzy Expert Systems for overall system management and Fuzzy Real time Controls can be designed to increase performance at competitive costs.

The linguistic approach characterizing Fuzzy Logic is based on a set of IF-THEN rules, which describe the control behavior and on Membership Functions associated with input and output variables.

Up to 340 Membership Functions, with triangular and trapezoidal shapes, or singleton values are available to describe fuzzy variables.

The Timer/PWM peripheral allows one to manage power devices and timing signals, by implementing different operating modes and high frequency PWM (Pulse Width Modulation) controls. Input Capture and Output Compare functions are available on the Timers.

The Timer has a 16-bit programmable internal Prescaler and a 8-bit Counter, which can use internal or external START/STOP signals and clock.

In addition to the features described previously, a second PWM/Timer includes an IR Driver that can directly support a wide set of codification types for remote control signals.

The outputs of the two Timers/PWM can also be easily combined in AND, OR, XOR and NOT to generate complex digital waveforms.

An internal programmable WATCHDOG is available to avoid loop errors and reset the ICU.

ST52F501L/F502L supply different peripherals to implement the most common serial communication protocols. I^2C, SPI and SCI peripherals allow the implementation of synchronous and asynchronous serial protocols. I^2C peripherals can work both in master and slave mode. SPI implements Single and Multi Master modes using 3-wire. SCI implements the standard UART protocols.

Up to 10 interrupt vectors are available, which allow synchronization with peripherals and external devices. Non-Maskable Interrupt and S/W TRAP are available. All interrupts have configurable priority levels and are maskable excluding the Non-Maskable Interrupt, which has fixed top level priority. Two versatile Port Interrupts are available for synchronization with external sources.

The ST52F501L/F502L also include an on-chip Power-on-Reset (POR), which provides an internal chip reset during power up situation and a Programmable Low Voltage Detector (PLVD), which causes the ICU to send an interrupt request or a reset if the voltage source V_{DD} dips below a threshold. Three programmable thresholds are available to work with different supply voltages. The Power Down Reset (PDR) provides a reset of the device if the voltage source V_{DD} dips below the safe supply voltage level (around 1.8 V) even in Halt mode.

In order to optimize energy consumption, two different power saving modes are available: Wait mode and Halt mode.

The Programmable Halt mode Wake-up (PHW) allows the CPU to wake-up from Halt mode at user programmed times, either servicing a dedicated interrupt routine or resetting the device. The PHW is driven by a dedicated 32 KHz low consumption internal oscillator.

Internal Oscillator with programmable frequency (1.25 to 10 MHz ± 1%) is available. External clock or quartz oscillator are also applicable. The device always starts with the Internal Oscillator, then it reads an Option Byte where the clock mode to be used is programmed.

Program Memory addressing capability addresses up to 8 Kbytes of memory location to store both program instructions and data.

Memory can be locked by the user in order to prevent external undesired operations.

Operations may be performed on data stored in RAM, allowing direct combination of new inputs and feedback data. All RAM bytes are used like Register File.

An additional RAM bench is added to the Program Memory addressing space in order to allow the management of the System/User Stacks and user data storage.

ST52F501L/F502L supply the system stack and the user stack located in the additional RAM bench. The user stack can be located anywhere in the additional RAM by writing the top address in the configuration registers, in order to avoid overlap with other data.

Single Voltage Flash allows the user to reprogram the devices on-board by means of the In Situ Programming (ISP) feature. It is possible to store in safe way up to 256 bytes of data in the available EEPROM memory benches (ST52F502L only). Permanent data, both in Flash and EEPROM can be managed by means of the In-Application-Programming (IAP) feature. Single byte and Page write modes are supported. Flexible write protection, of permanent data or program instructions, is also available.

The Instruction Set composed of up to 107 instructions allows code compression and high speed in the program implementation.

A powerful development environment consisting of a board and software tools allows an easy configuration and use of ST52F501L/F502L.

The Visual FIVE software tool allows the development and debugging of projects via a user-friendly graphical interface and optimization of generated microcode.

Third-party Hardware Emulators and 'C' Compiler are available to speed-up the application implementation and time-to-market.

1.2 Functional Description

ST52F501L/F502L ICU's can work in two modes according to the Vpp signal levels:

- Memory Programming Mode
- Working Mode

During Working Mode Vpp must be tied to Vss. To enter the Memory Programming Mode, the Vpp pin must be tied to Vdd.

A RESET signal must be applied to the device to switch from one mode to the other.

1.2.1 Memory Programming Mode.

The ST52F501L/F502L memory is loaded in the Memory Programming Mode. All instructions and data are written inside the memory during this phase. The Option Bytes are loaded during this phase by using the programming tools. The Option Bytes can only be loaded in this phase and cannot be modified run-time.

Data and commands are transmitted by using the I^2C protocol, implemented using the internal I^2C peripheral. The In-Situ Programming protocol (ISP) uses the following pins:

- SDA and SCL for transmission
- Vpp for entering in the mode
- RESET for starting the protocol in a stable status
- Vdd and Vss for the power supply.

The Internal clock is used in this phase.

1.2.2 Working Mode.

The processor starts the working phase following the instructions, which have been previously loaded in the first locations of the memory. The first instruction must be a jump to the first program instruction, skipping the data (interrupt vectors, Membership Functions, user data) stored in the first memory page.

ST52F501L/F502L's internal structure includes two computational blocks, the CONTROL UNIT (CU) and the DATA PROCESSING UNIT (DPU), which performs boolean functions. The DECISION PROCESSOR (DP) block cooperates with these blocks to perform Fuzzy algorithms.

The DP can manage up to 340 different Membership Functions for the antecedent part of fuzzy rules. The consequent terms of the rules are "crisp" values (real numbers). The maximum number of rules that can be defined is limited by the dimensions of the standard algorithm implemented.

The Program/Data Memory is shared between Fuzzy and standard algorithms. Within this memory, the user data can be stored both in non volatile memory as well as in the RAM locations.

The Control Unit (CU) reads information and the status of the peripherals.

Arithmetic calculus can be performed on these values by using the internal CU and Register File, which supports all computations. The peripheral inputs can be Fuzzy and/or arithmetic output values contained in the Register File or Program/ Data Memory.

Table 1.1 ST52F501L/F502L Device Summary

Device	NVM	RF	RAM	EEPROM	Timers	IR-DRV	PHW	Comms	I/O	Package
ST52F501LF1B6	2K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	DIP 20
ST52F501LF1M6	2K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	SO 20
ST52F501LG1M6	2K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	22	SO 28
ST52F501LG1B6	2K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	SDIP 32
ST52F501LK1T6	2K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	TQFP 32
ST52F501LF2B6	4K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	DIP 20
ST52F501LF2M6	4K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	SO 20
ST52F501LG2M6	4K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	22	SO 28
ST52F501LG2B6	4K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	SDIP 32
ST52F501LK2T6	4K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	TQFP 32
ST52F501LF3B6	8K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	DIP 20
ST52F501LF3M6	8K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	SO 20
ST52F501LG3M6	8K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	22	SO 28
ST52F501LG3B6	8K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	SDIP 32
ST52F501LK3T6	8K FLASH	256	256	-	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	TQFP 32
ST52F502LF1B6	2K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	DIP 20
ST52F502LF1M6	2K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	SO 20
ST52F502LG1M6	2K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	22	SO 28
ST52F502LG1B6	2K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	SDIP 32
ST52F502LK1T6	2K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	TQFP 32
ST52F502LF2B6	4K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	DIP 20
ST52F502LF2M6	4K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	SO 20
ST52F502LG2M6	4K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	22	SO 28
ST52F502LG2B6	4K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	SDIP 32
ST52F502LK2T6	4K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	TQFP 32
ST52F502LF3B6	8K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	DIP 20
ST52F502LF3M6	8K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	14	SO 20
ST52F502LG3M6	8K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	22	SO 28
ST52F502LG3B6	8K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	SDIP 32
ST52F502LK3T6	8K FLASH	256	256	256	2X8-bit	Yes	Yes	I^2C-SCI-SPI	24	TQFP 32

Table 1.2 ST52F501L/F502L Common Features

COMMON FEATURES	ST52F501L/F502L
Watchdog	Yes
Other Features	NMI, PLVD, POR, PDR
Temperature Range	From -40° to + 85°
Operating Supply	1.8 - 3.6 V
CPU Frequency	up to 16 MHz.

Figure 1.1 ST52F501L/F502L Block Diagram

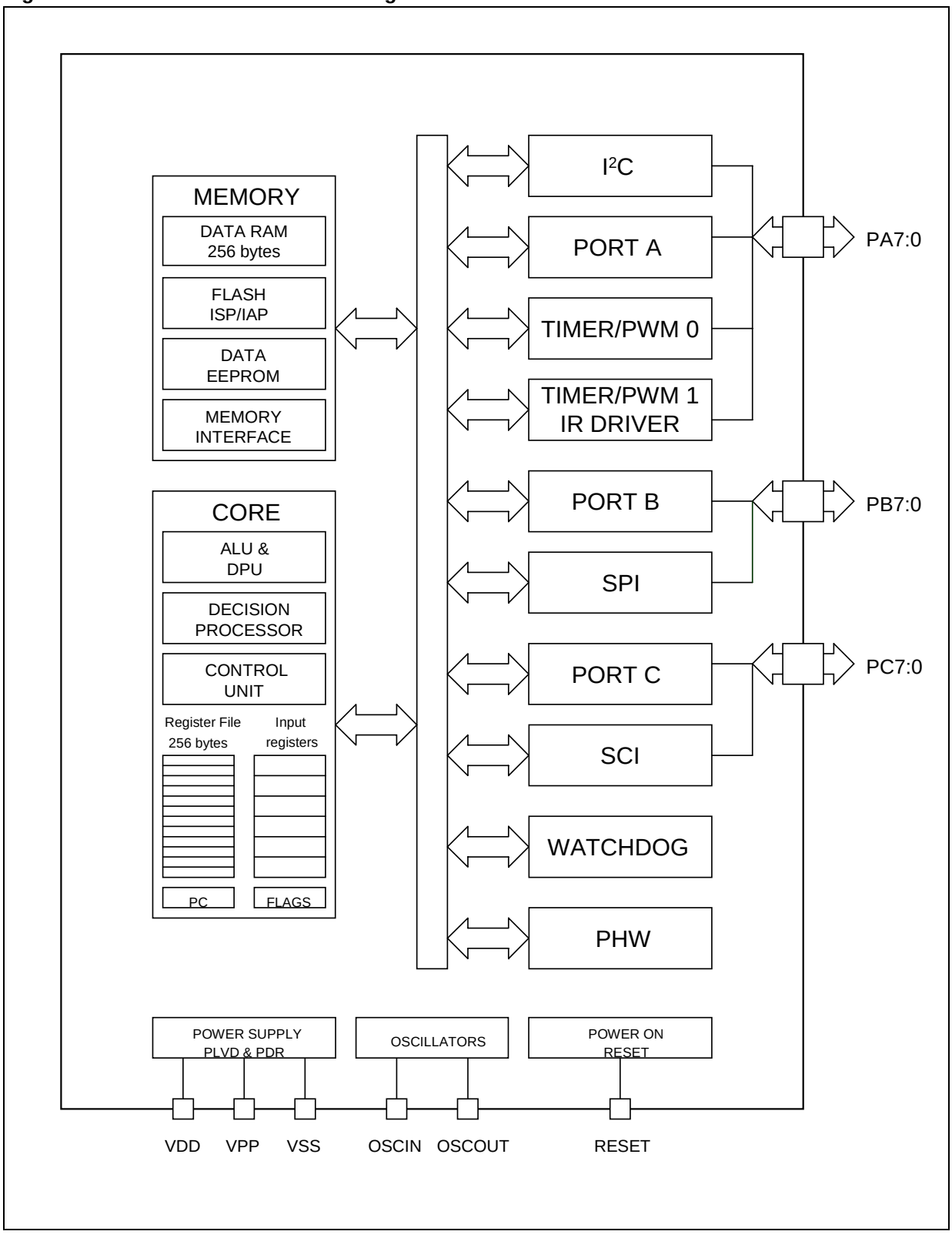


Figure 1.2 ST52F501L/F502L SDIP32/SO28 Pin Configuration

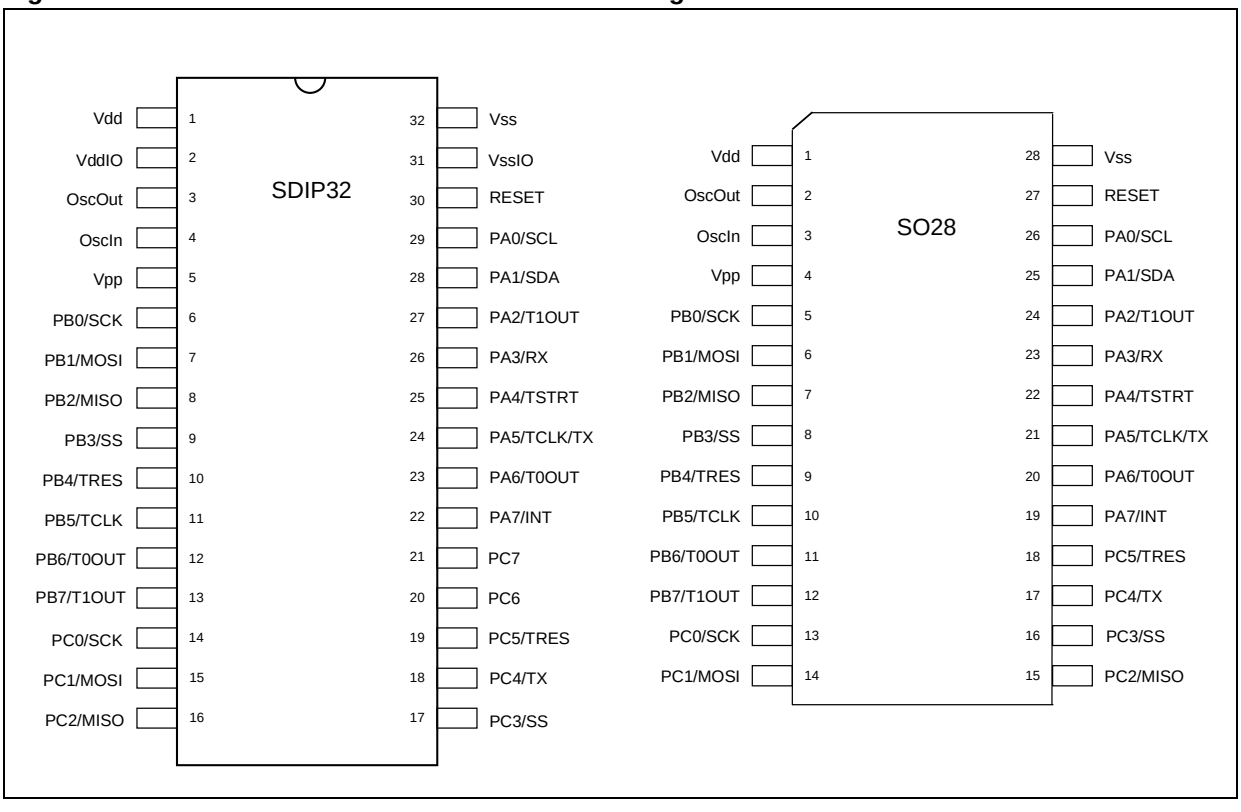


Figure 1.3 ST52F501L/F502L SO20/DIP20 Pin Configuration

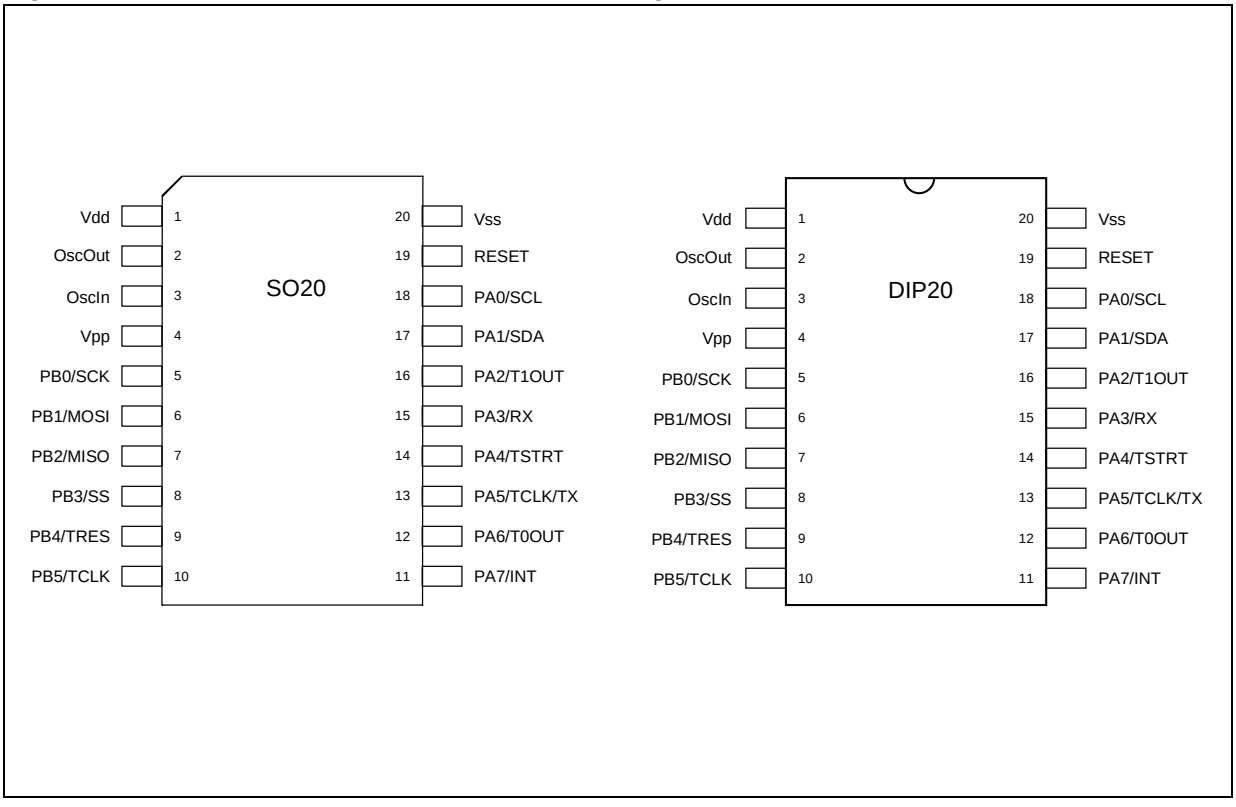


Figure 1.4 ST52F501L/F502L TQFP32 Pin Configuration

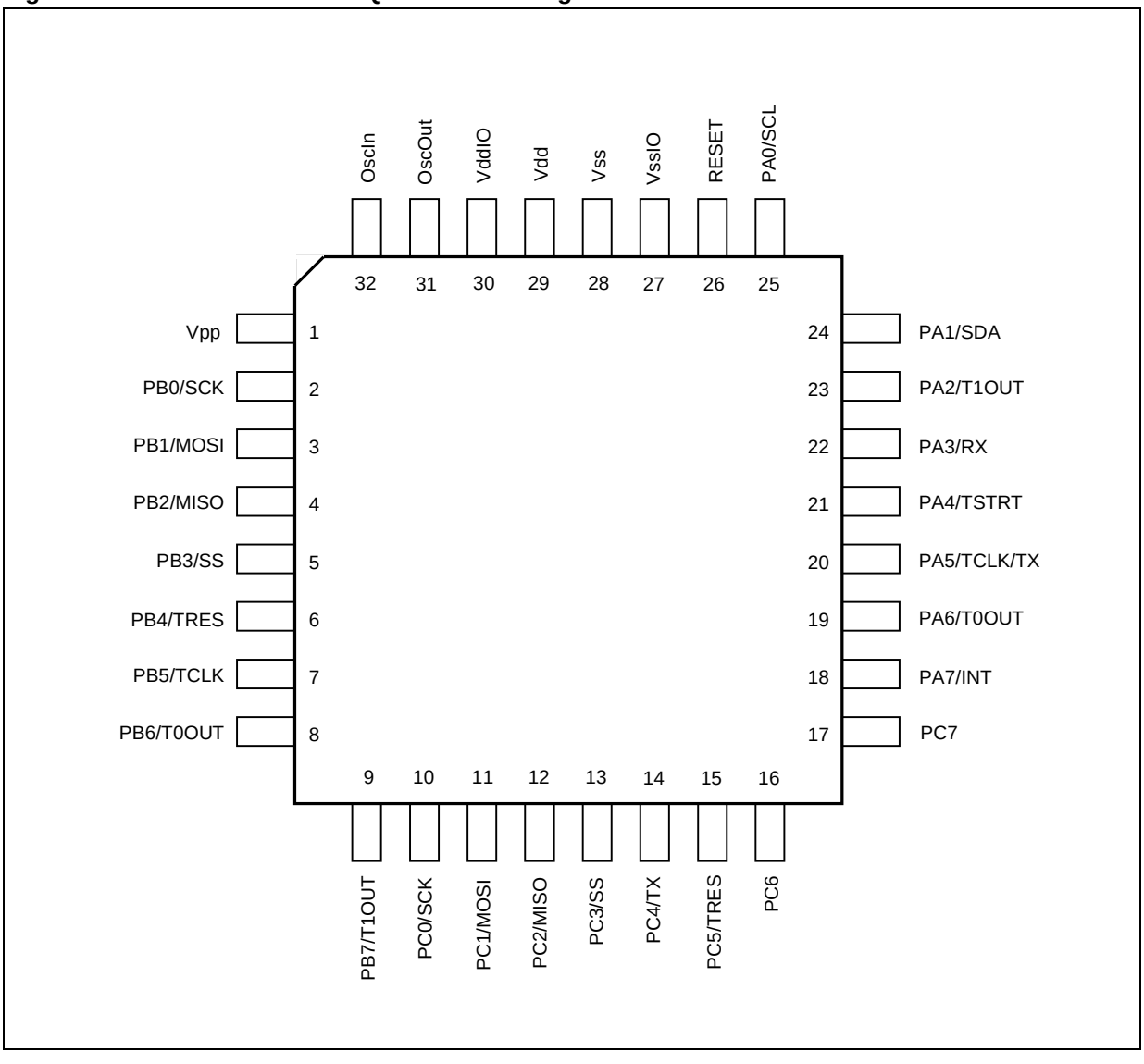


Table 1.3 ST52F501L/F502L SO28, SO20 & DIP20 Pin List

SO28	SO20 DIP20	NAME	Programming Phase	Working Phase
1	1	Vdd	Digital Power Supply	Digital Power Supply
2	2	OSCOUT		Oscillator Output
3	3	OSCIN		Oscillator Input
4	4	Vpp	Programming Mode Selector	Programming Mode Selector
5	5	PB0/SCK		Digital I/O, SPI Serial Clock
6	6	PB1/MOSI		Digital I/O, SPI Master out Slave in
7	7	PB2/MISO		Digital I/O, SPI Master in Slave out
8	8	PB3/SS		Digital I/O, SPI Slave Select
9	9	PB4/TRES		Digital I/O, Timer/PWM 0 Reset
10	10	PB5/TCLK		Digital I/O, Timer/PWM 0 clock
11	-	PB6/T0OUT		Digital I/O, Timer/PWM 0 output
12	-	PB7/T1OUT		Digital I/O, Timer/PWM 1 output
13	-	PC0/SCK		Digital I/O, SPI Serial Clock
14	-	PC1/MOSI		Digital I/O, SPI Master out Slave in
15	-	PC2/MISO		Digital I/O, SPI Master in Slave out
16	-	PC3/SS		Digital I/O, SPI Slave Select
17	-	PC4/TX		Digital I/O, SCI Transmission
18	-	PC5/TRES		Digital I/O, Timer/PWM 0 Reset
19	11	PA7/INT		Digital I/O, Non Maskable Interrupt
20	12	PA6/T0OUT		Digital I/O, Timer/PWM 0 output
21	13	PA5/TCLK/TX		Digital I/O, Timer/PWM 0 clock, SCI Transmission
22	14	PA4/TSTRT		Digital I/O, Timer/PWM 0 start/stop
23	15	PA3/RX		Digital I/O, SCI Reception
24	16	PA2/T1OUT		Digital I/O, Timer/PWM 1 output
25	17	PA1/SDA	Serial Data I/O	Digital I/O, I^2C Serial Data I/O
26	18	PA0/SCL	Serial Clock	Digital I/O, I^2C Serial Clock
27	19	RESET	General Reset	General Reset
28	20	Vss	Digital Ground	Digital Ground

Table 1.4 ST52F501L/F502L SDIP32/TQFP32 Pin List

SDIP32	TQFP32	NAME	Programming Phase	Working Phase
1	29	Vdd	Digital Power Supply	Digital Power Supply
2	30	VddIO	Digital Power Supply	Digital I/O Ports Power Supply
3	31	OSCOUT		Oscillator Output
4	32	OSCIN		Oscillator Input
5	1	Vpp	Programming Mode Selector	Programming Mode Selector
6	2	PB0/SCK		Digital I/O, SPI Serial Clock
7	3	PB1/MOSI		Digital I/O, SPI Master out Slave in
8	4	PB2/MISO		Digital I/O, SPI Master in Slave out
9	5	PB3/SS		Digital I/O, SPI Slave Select
10	6	PB4/TRES		Digital I/O, Timer/PWM 0 Reset
11	7	PB5/TCLK		Digital I/O, Timer/PWM 0 clock
12	8	PB6/T0OUT		Digital I/O, Timer/PWM 0 output
13	9	PB7/T1OUT		Digital I/O, Timer/PWM 1 output
14	10	PC0/SCK		Digital I/O, SPI Serial Clock
15	11	PC1/MOSI		Digital I/O, SPI Master out Slave in
16	12	PC2/MISO		Digital I/O, SPI Master in Slave out
17	13	PC3/SS		Digital I/O, SPI Slave Select
18	14	PC4/TX		Digital I/O, SCI Transmission
19	15	PC5/TRES		Digital I/O, Timer/PWM 0 Reset
20	16	PC6		Digital I/O
21	17	PC7		Digital I/O
22	18	PA7/INT		Digital I/O, Non Maskable Interrupt
23	19	PA6/T0OUT		Digital I/O, Timer/PWM 0 output
24	20	PA5/TCLK/TX		Digital I/O, Timer/PWM 0 clock, SCI
25	21	PA4/TSTRT		Digital I/O, Timer/PWM 0 start/stop
26	22	PA3/RX		Digital I/O, SCI Reception
27	23	PA2/T1OUT		Digital I/O, Timer/PWM 1 output
28	24	PA1/SDA	Serial Data I/O	Digital I/O, I^2C Serial Data I/O
29	25	PA0/SCL	Serial Clock	Digital I/O, I^2C Serial Clock
30	26	RESET	General Reset	General Reset
31	27	VssIO	Digital Ground	Digital I/O Ports Ground
32	28	Vss	Digital Ground	Digital Ground

1.3 Pin Description

ST52F501L/F502L pins can be set in digital input mode, digital output mode, interrupt mode or in Alternate Functions. Pin configuration is achieved by means of the configuration registers. The functions of the ST52F501L/F502L pins are described below:

V_{DD}. Main Power Supply Voltage.

V_{DDIO}. I/O Ports Power Supply Voltage. It is reccomended to connect this pin with a supply voltage de-coupled with V_{DD} in order to improve the immunity from the noise generated by the I/O switching (only 32 pin packages).

V_{SS}. Digital circuit Ground.

V_{SSIO}. I/O Ports Ground. See V_{DDIO}

V_{PP}. Programming/Working mode selector. During the Programming phase V_{PP} must be set to V_{DD}. In Working phase V_{PP} must be equal to V_{SS}.

OSCin and **OSCout.** These pins are internally connected to the on-chip oscillator circuit. A quartz crystal or a ceramic resonator can be connected between these two pins in order to allow correct use of ST52F501L/F502L with various stability/ cost trade-offs. An external clock signal can be applied to OSCin: in this case OSCout can be floating. Without any connection, the device can work with its internal clock generator (10 MHz)

RESET. This signal is used to reset the ST52F501L/F502L and re-initialize the registers and control signals. It is also used when switching from the Programming Mode to Working Mode and vice versa.

PA0-PA7, PB0-PB7,PC0-PC7. These lines are organized as I/O ports. Each pin can be configured as an input, output (with pull-up, push-pull, weak-pull-up, open-drain, high-impedance), or as an interrupt source.

T0OUT, T1OUT. These pins output the signals generated by the PWM/Timer 0 and PWM/Timer 1 peripheral.

TRES, **TSTRT, TCLK**. These pins are related to the PWM/Timer 0 peripheral and are used for Input Capture and event counting. The TRES pin is used to set/reset the Timer; the TSTRT pin is used to start/stop the counter. The Timer can be driven by the internal clock or by an external signal connected to the TCLK pin.

INT. This pin is used as input for the Non-Maskable (top level) interrupt. The interrupt signal is detected only if the pin is configured in Alternate Function.

SCL, SDA. These pin are used respectively as Serial Clock and Serial Data I/O in I^2C peripheral protocol. They are used also in Programming Mode to receive and transmit data.

SCK, MISO, MOSI, SS. These pins are used by the Serial Peripheral Interface (SPI) peripheral. SCK is the serial clock line. MISO (Master In Slave Out) and MOSI (Master Out Slave In) are the serial data lines, which work in input or in output depending on if the device is working in slave or master mode. The SS pin allows the selection of the device master/slave mode.

TX, RX. Serial data output of SCI Transmitter block (TX) and Serial data input of the SCI Receiver block (RX).

2 INTERNAL ARCHITECTURE

ST52F501L/F502L's architecture is Register File based and is composed of the following blocks and peripherals:

- Control Unit (CU)
- Data Processing Unit (DPU)
- Decision Processor (DP)
- ALU
- Memory Interface
- up to 256 bytes Register File
- Program/Data Memory
- Data EEPROM
- Interrupts Controller
- Clock Oscillator
- PLVD, PDR and POR
- Digital I/O ports
- Timer/PWM
- Timer/PWM with IR Driver
- I^2C
- SPI
- SCI
- PHW

2.1 Control Unit and Data Processing Unit

The Control Unit (CU) decodes the instructions stored in the Program Memory and generates the appropriate control signals. The main parts of the CU are illustrated in Figure 2.1.

The five different parts of the CU manage Loading, Logic/Arithmetic, Jump, Control and the Fuzzy instruction set.

The block called "Collector" manages the signals deriving from the different parts of the CU. The collector defines the signals for the Data Processing Unit (DPU) and Decision Processor (DP), as well as for the different peripherals of the ICU.

The block called "Arbiter" manages the different parts of the CU, so that only one part of the system is activated during working mode.

The CU structure is extremely flexible and was designed with the purpose of easily adapting the core of the microcontroller to market needs. New instruction sets or new peripherals can easily be included without changing the structure of the microcontroller, maintaining code compatibility.

A set of 107 different instructions is available. Each instruction requires a number of clock pulses to be performed that depends on the complexity of the instruction itself. The clock pulses to execute the instructions are driven directly by the masterclock, which has the same frequency of the oscillator signal supplied.

Figure 2.1 CU Block Diagram

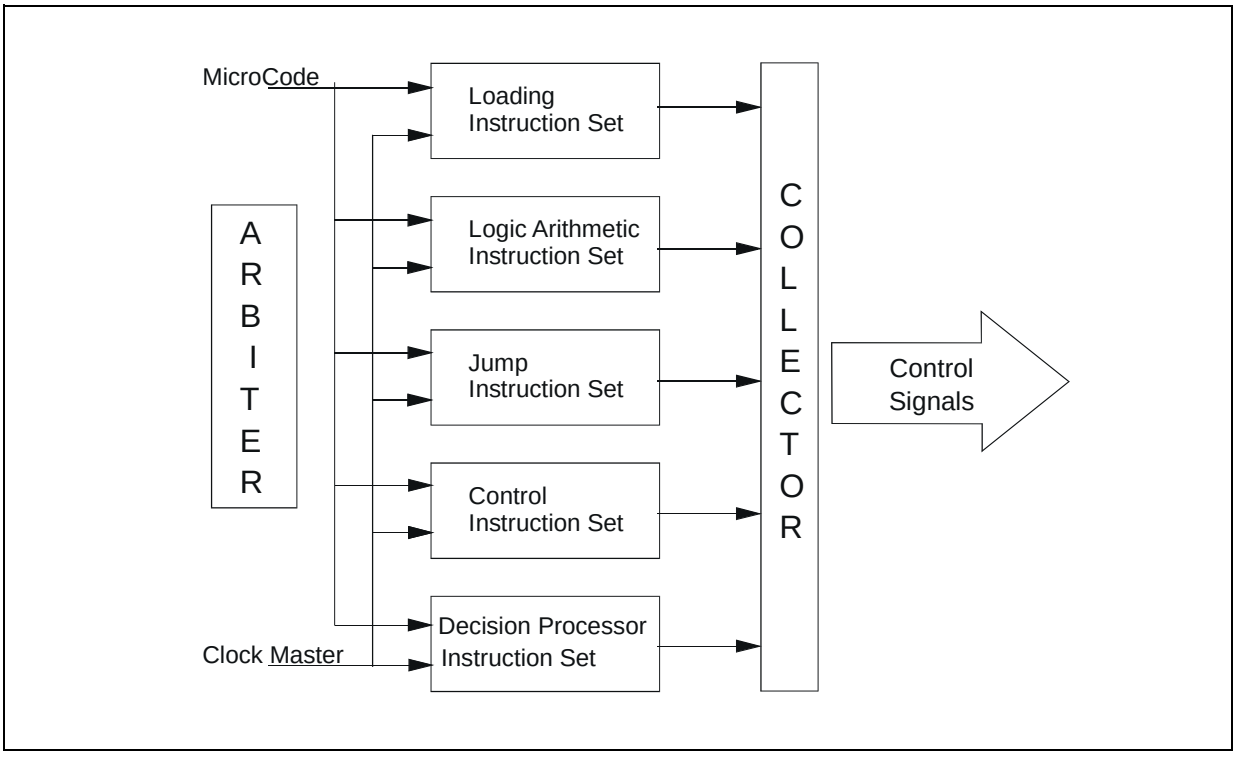
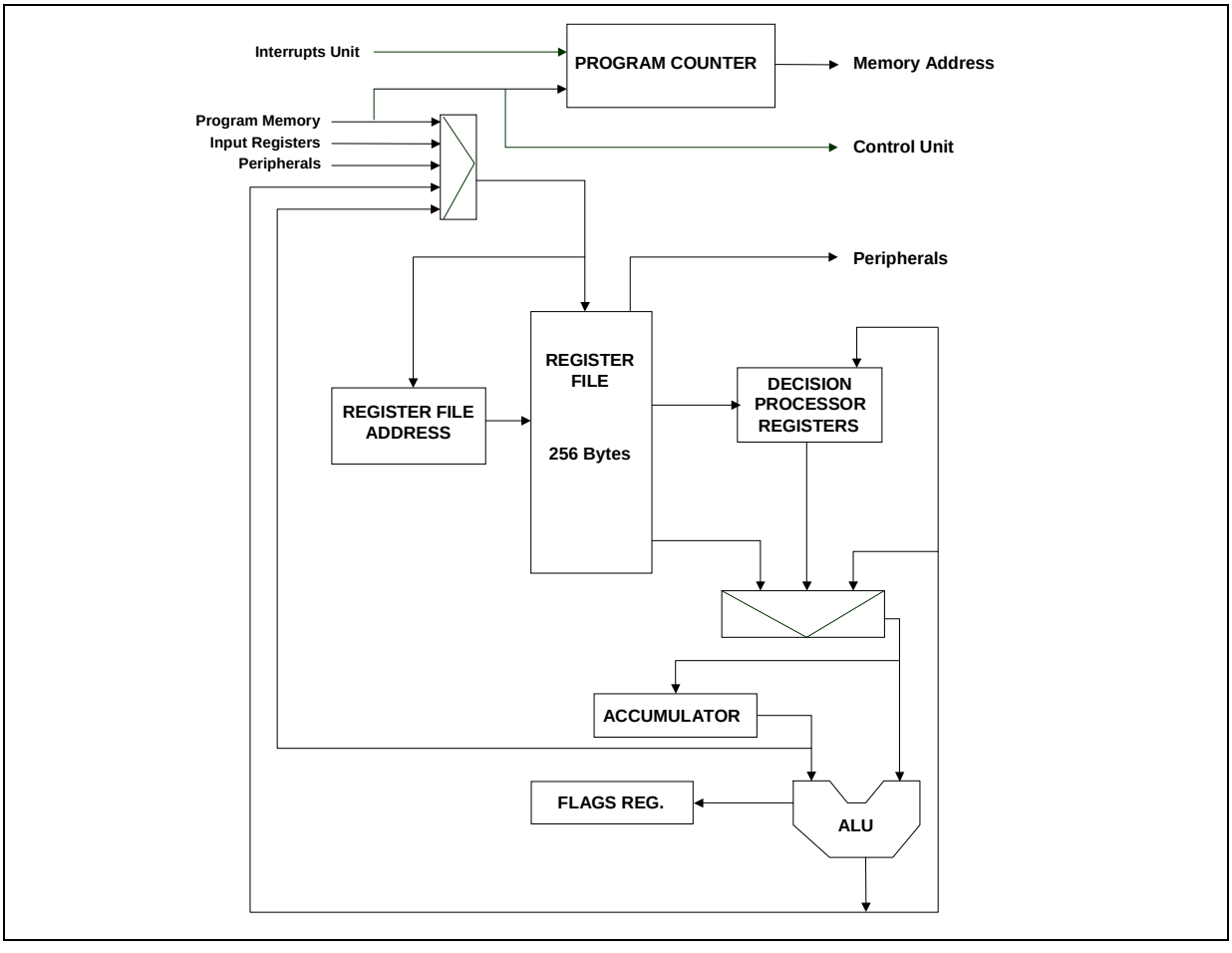


Figure 2.2 Data Processing Unit (DPU)



The DPU receives, stores and sends the instructions deriving from the Program/Data Memory, Register File or from the peripherals. It is controlled by the CU on the basis of the decoded instruction. The Fuzzy registers store the partial results of the fuzzy computation. The accumulator register is used by the ALU and is not accessible directly: the instructions used by the ALU can address all the Register File locations as operands, allowing a more compact code and a faster execution.

The following addressing modes are available: inherent, immediate, direct, indirect, bit direct.

2.1.1 Program Counter.

The Program Counter (PC) is a 16-bit register that contains the address of the next memory location to be processed by the core. This memory location may be both an instruction or data address.

The Program Counter's 16-bit length allows the direct addressing of a maximum of 64 Kbytes in the Program/Data Memory space.

The PC can be changed in the following ways:

- JP (Jump) PC = Jump Address
- Interrupt PC = Interrupt Vector
- RETI PC = Pop (stack)
- RET PC = Pop (stack)
- CALL PC = Subroutines address
- Reset PC = Reset Vector
- Normal Instruction PC = PC + instr. lenght

2.1.2 Flags.

The ST FIVE core includes different sets of flags that correspond to 2 different modes: normal mode and interrupt mode. Each set of flags consist of a CARRY flag (C), ZERO flag (Z) and SIGN flag (S). Each set is stacked: one set of flags is used during normal operation and other sets are used during each level of interrupt. Formally, the user has to manage only one set of flags: C, Z and S since the flag stack operation is performed automatically.

Each interrupt level has its own set of flags, which is saved in the Flag Stack during interrupt servicing. These flags are restored from the Flag Stack automatically when a RETI instruction is executed.

If the ICU was in normal mode before an interrupt, after the RETI instruction is executed, the normal flags are restored.

Note: *A subroutine CALL is a normal mode execution. For this reason a RET instruction, consequent to a CALL instruction, doesn't affect the normal mode set of flags.*

Flags are not cleared during context switching and remain in the state they were in at the exit of the last interrupt routine switching.

The Carry flag is set when an overflow occurs during arithmetic operations, otherwise it is cleared.The Sign flag is set when an underflow occurs during arithmetic operations, otherwise it is cleared.

The flags, related to the current context, can be checked by reading the FLAGS Input Register 38 (026h).

2.2 Arithmetic Logic Unit

The 8-bit Arithmetic Logic Unit (ALU) performs arithmetic calculations and logic instructions such as: sum, subtraction, bitwise AND, OR, XOR, bit set and reset, bit test and branch, right/left shift and rotate (see Chapter 9 Instruction Set for further details).

In addition, the ALU of ST52F501L/F502L can perform multiplication (MULT) and division (DIV). Multiplication is performed by using 8 bit operands storing the result in 2 registers (16 bit values); the division instruction addresses the MSB of the dividend (the LSB is stored in the next address): the result and remainder are stored in these source addresses (see Figure 2.3 and Figure 2.4).

In order to manage signed type values, the ALU also performs addition and subtraction with offset (ADDO and SUBO). These instructions respectively subtract and add 128 to the overall result, in order to manage values logically in the range between -128,127.

Figure 2.3 Multiplication

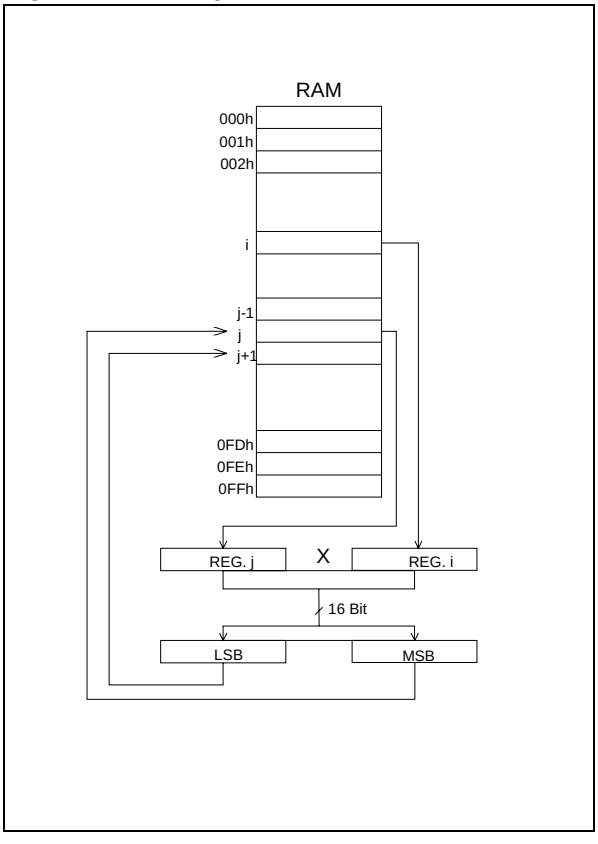
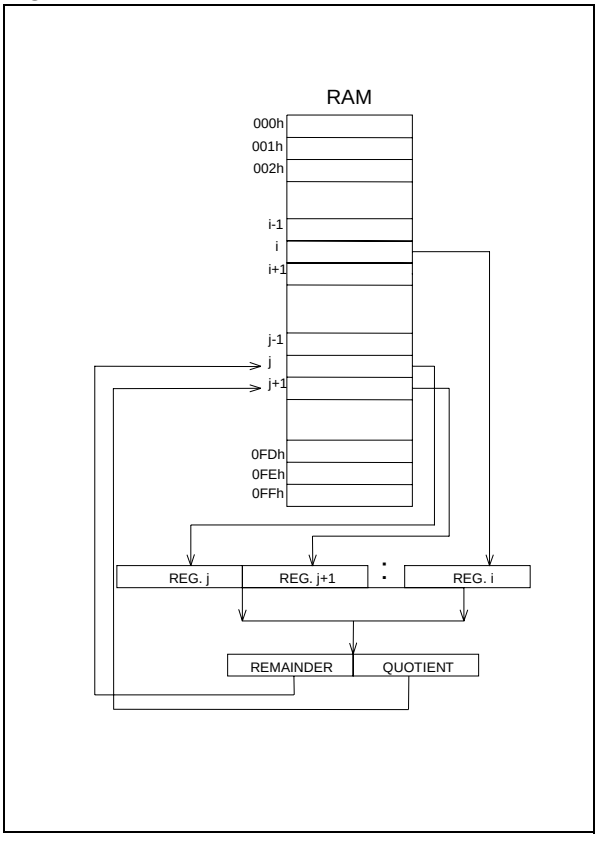


Figure 2.4 Division



2.3 Register Description

Flags Register (FLAG)
Input Register 38 (026h) Read Only
Reset Value: 0000 0000 (00h)

7							0
-	-	-	-	-	Z	S	C

Bit 7-3: Not Used

Bit 2: **Z** Zero flag

Bit 1: **S** Sign flag

Bit 0: **C** Carry flag

3 ADDRESSING SPACES

ST52F501L/F502L has six separate addressing spaces:

- Register File
- Program/Data Memory & Stacks
- Input Registers
- Output Registers
- Configuration Registers
- Fuzzy Registers

Note: *stack is in the same address space of Program memory.*

Each space is addressed by a load type instruction that indicates the source and the destination space in the mnemonic code (see Figure 3.1).

3.1 Memory Interface

The read/write operation in the space addresses are managed by the Memory Interface, which can recognize the type of memory addressed and set the appropriate access time and mode.

In addition, the Memory Interface manages the In Application Programming (IAP) functions in Flash devices like writing cycle and memory write protection.

3.2 Register File

The Register File consists of 256 general purpose 8-bit RAM locations called “registers” in order to recall the functionality.

The Register File exchanges data with all the other addressing spaces and is used by the ALU to perform all the arithmetic and logic instructions. These instructions have any Register File address as operands.

Data can be moved from one location to another by using the LDRR instruction; see further ahead for information on the instruction used to move data between the Register File and the other addressing spaces.

3.3 Program/Data Memory

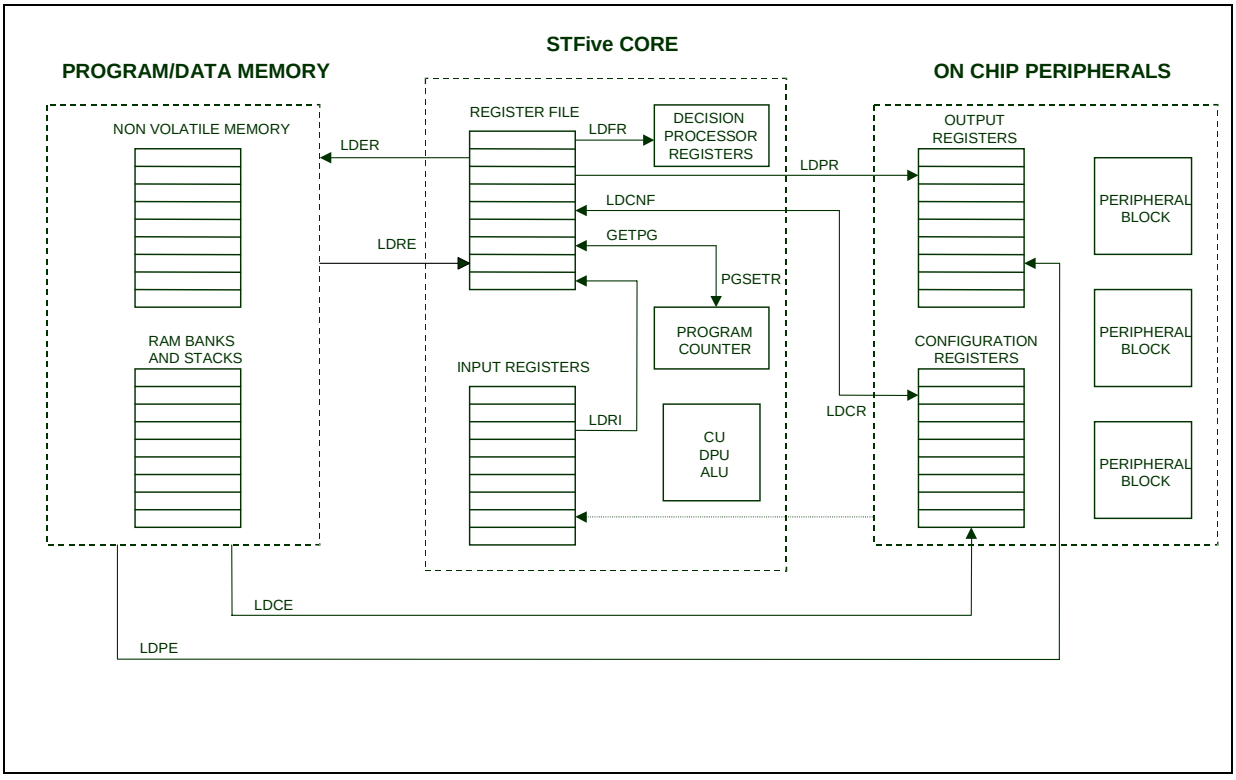
The Program/Data Memory consists of both non-volatile memory (Flash, EEPROM) and RAM memory benches.

Non-volatile memory (NVM) is mainly used to store the user program and can also be used to store permanent data (constant, look-up tables).

Each RAM bench consists of 256 locations used to store run-time user data. At least one bench is present in the devices. RAM benches are also used to implement both System and User Stacks.

NVM & RAM locations can be accessed by means of the LDER and LDRE instructions.

Figure 3.1 Addressing Spaces

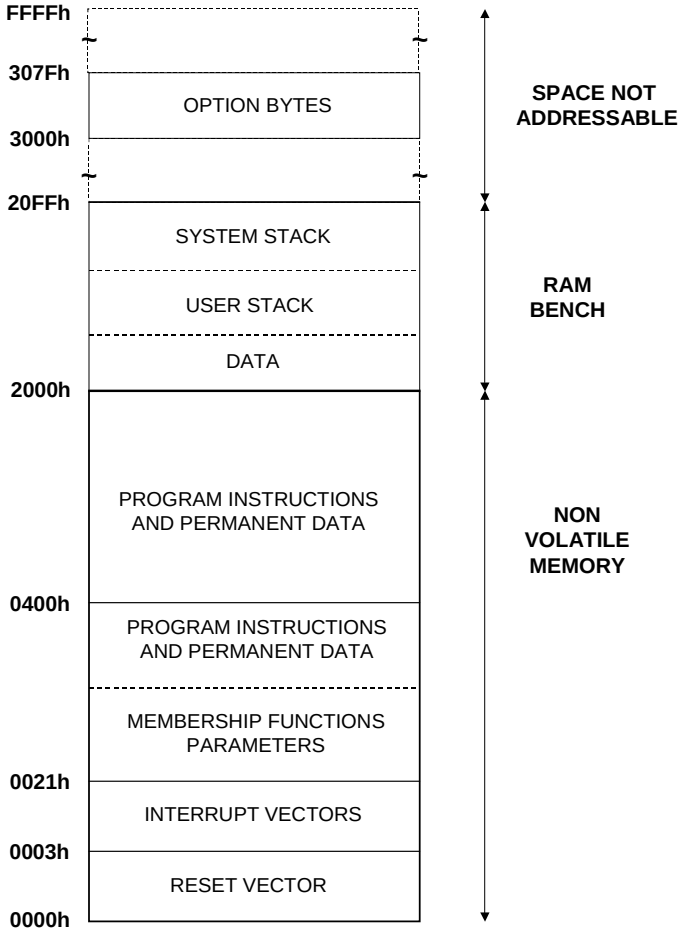


NVM is always located beginning after the first locations of the addressing space. RAM banks are always located after NVM.

NVM is organized in accordance to the following blocks (see Figure 3.2):

- *Reset Vector block* (from address 0 to 2) contains an absolute jump instruction to the first user program instruction. The Assembler tool automatically fills these locations with correct data.
- *Interrupt Vectors block* (from location 3 up to 32) contains the interrupt vectors. Each address is composed of three bytes (the jump opcode and the 16 bit address). Interrupt vectors are set by using IRQ pseudo-instruction (see the Programming Manual).
- *Mbfs Setting block* (just after the interrupt vectors) contains the coordinates of the vertexes of every Mbf defined in the program. The last address that can be assigned to this block is 1023. This area is dynamically assigned according to the size of the fuzzy routines. The memory area that remains unused, if any, is assigned to the Program Instructions block.
- *The Program Instructions block* (just after the last Mbf data through the last NVM address) contains the instruction of the user program and the permanent data.
- *Option bytes block* (from location 3000h to 307Fh) is the addressing space reserved for the option bytes. In ST52F501L/F502L, only the location from 3000h to 3007h are used.

Figure 3.2 Program/Data Memory Organization



Flash and EEPROM are programmed electrically just applying the supply voltage and they are also erased electrically; this feature allows the user to easily reprogram the memory without taking the device off from the board (In Situ Programming ISP). Data and commands are transmitted through the I^2C serial communication protocol. Data can also be written run-time with the In Application Programming (IAP)

NVM can be locked by the user during the programming phase, in order to prevent external operation such as reading the program code and assuring protection of user intellectual property. Flash and EEPROM pages can be protected by unintentional writings.

The operations that can be performed on the NVM during the Programming Phase, ISP and IAP are described in detail in the Section 4.

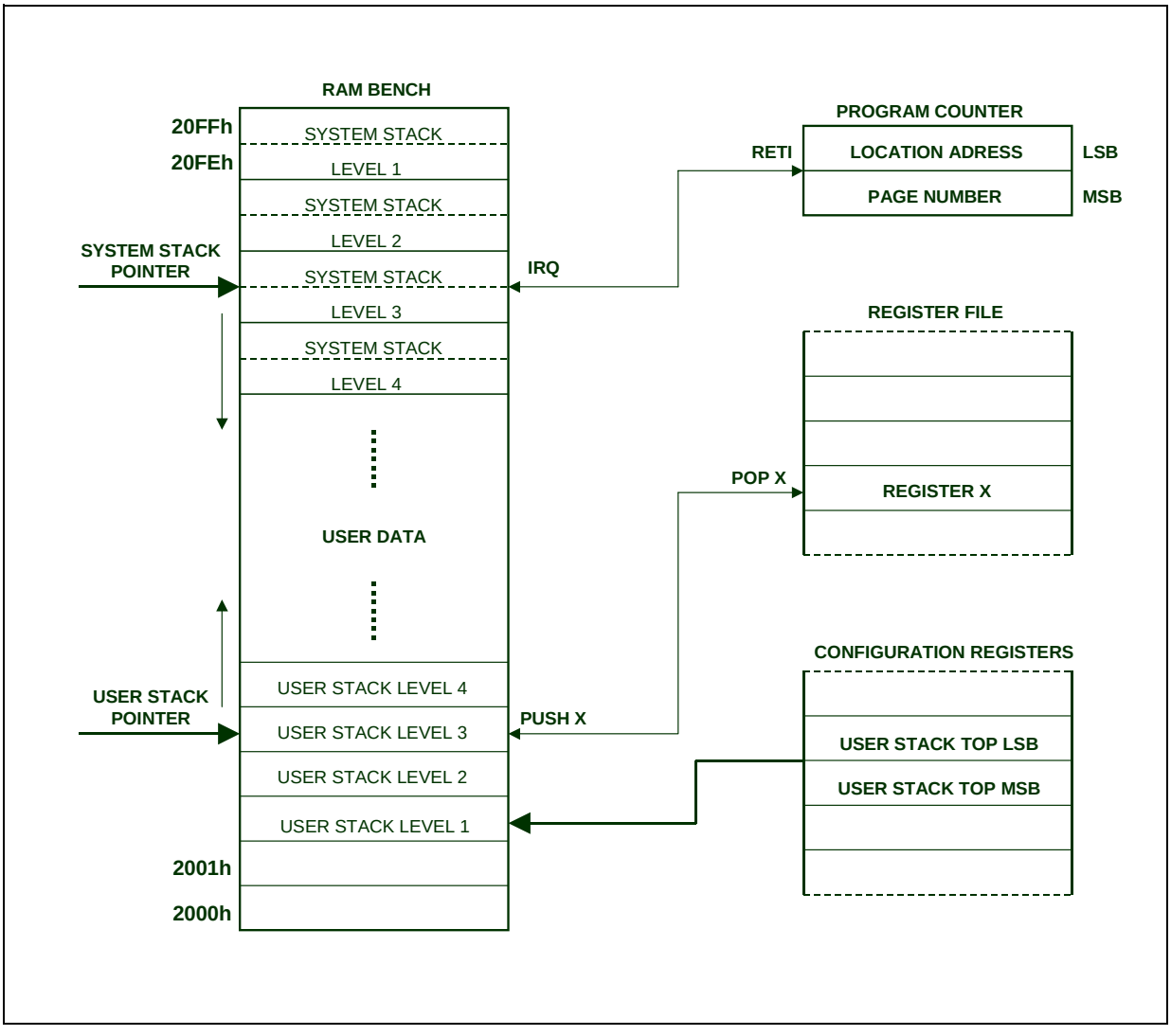
3.4 System and User Stacks

The System and User Stacks are located in the Program/Data memory in the RAM benches.

System Stacks are used to push the Program Counter (PC) after an Interrupt Request or a Subroutine Call. After a RET (Return from a subroutine) or a RETI (Return from an interrupt) the PC that is saved is popped from the stack and restored. After an interrupt request, the flags are also saved in a reserved stack inside the core, so each interrupt has its own flags.

The System Stack is located in the last RAM bench starting from the last address (20FFh) inside the bench page. The System Stack Pointer (SSP) can be read and modified by the user. For each level of stack 2 bytes of the RAM are used. The SSP points to the first currently available stack position. When a subroutine call or interrupt request occurs, the content of the PC is stored in a couple of locations pointed to by the SSP that is decreased by 2.

Figure 3.3 System and User Stack



When a return occurs (RET or RETI instruction), the SSP is increased by 2 and the data stored in the pointed locations couple is restored back into the PC.

The current SSP can be read and write in the couple of Configuration Registers 44 02Ch (MSB: page number, always 32 020h) and 45 02Dh (LSB: location address) (see Figure 3.3). In ST52F501L/F502L the user can only consider the LSB because the MSB is always the same.

The User Stack is used to store user data and is located beginning from a RAM bench location set by the user (USTP) by writing the couple of Configuration Registers 5 005h (MSB: page number) and 6 006h (LSB: location address) (see Figure 3.3). Register 5, which is the page number, must always be set to a value between 32 (020h) and 255 (0FFh): values higher than 32 always address RAM on page 32.

This feature allows a flexible use of the User Stack in terms of dimension and to avoid overlaps. The User Stack Pointer (USP) points to the first currently available stack location. When the user stores a byte value contained in the Register File by using the PUSH instruction, the value is stored in the position pointed to by the USP that is increased (the User Stack order is opposite to the System Stack one). When the user takes a value from the User Stack with the POP instruction, the USP is decreased and the value pointed to is copied in the specified Register File location.

By writing the USTP, the new address is automatically written in the USP. The current USP can be read from the Input Registers 11 0Bh (MSB: page number, always 32 020h) and 12 0Ch (LSB: location address) (see Figure 3.3). In ST52F501L/F502L the user can only consider the LSB because the MSB is always the same.

Note: *The user must pay close attention to avoid overlapping user and Stacks data. The User Stack Top location and the System Stack Pointer should be configured with care in order to have enough space between the two stacks.*

3.5 Input Registers

The ST52F501L/F502L Input Registers bench consists of a file of 8-bit registers containing data or the status of the peripherals. For example, the Input Registers contain data converted by the ADC, Ports, serial communication peripherals, Timers, etc.

The Input Registers can be accessed by using the LDRI instruction that loads the specified Register File address with the contents of the specified Input Register. See the Programming Manual for further details on this instruction. The Input Registers are read-only registers.

In order to simplify the concept, a mnemonic name is assigned to each register. The list of the Input Registers is shown in Table 3.1.

3.6 Output registers

The ST52F501L/F502L Output Registers bench consists of a file of 8-bit registers containing data sent to the Peripherals and the I/O Ports (for example: Timer Counters, data to be transmitted by the serial communication peripherals, data to be sent to the Port pins in output, etc.).

The registers are located inside the Peripherals and Ports, which allow flexibility and modularity in the design of new family devices.

The Output Registers are write only. In order to access the configuration Register the user can use the following instructions:

- LDPI: loads the immediate value in the specified Output Register.
- LDPR: loads the contents of the specified Register File location into the output register specified. This instruction allows computed data to be sent to Peripherals and Ports.
- LDPE direct: loads the contents of the specified Program/Data Memory location into the output register specified. This instruction allows data to be sent to Peripherals and Ports from a table.
- LDPE indirect: loads the contents of the Program/Data Memory location whose address is contained in the specified Register File location into the output register specified. This instruction allows data to be sent to Peripherals and Ports from a table pointed to by a register.

See the Programming manual for further details about these instructions.

In order to simplify the concept, a mnemonic name is assigned to each register. The list of the Output Registers is shown in Table 3.2.

3.7 Configuration Registers & Option Bytes

The ST52F501L/F502L Configuration Registers bench consists of a file of 8-bit registers that allows the configuration of all the ICU blocks. The registers are located inside the block they configure in order to obtain greater flexibility and modularity in the design of new family devices. In the Configuration Registers, each bit has a particular use, so the logic level of each of them must be considered.

Some special configuration data, that needs to be load at the start-up and not further changed, are stored in Option Bytes. These are loaded only during the device programming phase. See Table 3.3 and Section 4 for a detailed description of the Option Bytes.

The Configuration Registers are readable and writable; the addresses refer to the same register both in read and in write. In order to access the Configuration Register the user can work in several modes by utilizing the following instructions:

- LDCI: loads the immediate value in the Configuration Register specified and is the most commonly used to write configuration data.
- LDCR: loads the Configuration Register specified with the contents of the specified Register File location, allowing a parametric configuration.
- LDCE: loads the Configuration Register specified with the contents of the specified Program/Data Memory location, allowing the configuration data to be taken from a table.
- LDCNF: loads the Register File location specified with the contents of the Configuration Register indicated, allowing for the inspection of the configuration of the device (permitting safe run-time modifications).

In order to simplify the concept, a mnemonic name is assigned to each register. The list of the Configuration Registers is shown in Table 3.4.

3.8 Fuzzy registers

The Decision Processor for Fuzzy computation is accessed by means of 8 dedicated registers. These registers are used to load values in input to the Decision Processor.

The values are loaded in the Fuzzy Register by mean of the LDFR instruction. This instruction set the specified Fuzzy Register (addresses from 0 to 7) with the value stored in the specified address of the Register File.

See Chapter 8 FUZZY COMPUTATION (DP) for further informations.

Table 3.1 Input Registers

Mnemonic	Description	Address	
PORT_A_IN	Port A data Input Register	0	00h
PORT_B_IN	Port B data Input Register	1	01h
PORT_C_IN	Port C data Input Register	2	02h
-	Not Used	3-4	03h-04h
SPI_IN	Serial Peripheral Interface data Input Register	5	05h
I2C_IN	I^2C Interface data Input Register	6	06h
I2C_SR1	I^2C Interface Status Register 1	7	07h
I2C_SR2	I^2C Interface Status Register 2	8	08h
-	Not Used	9	09h
-	Not Used	10	0Ah
USP_H	User Stack Pointer (MSB)	11	0Bh
USP_L	User Stack Pointer (LSB)	12	0Ch
-	Not Used	13-21	0Dh-015h
PWM0_COUNT_IN	PWM/Timer 0 Counter Input Register	22	016h
PWM0_STATUS	PWM/Timer 0 Status Register	23	017h
-	Not Used	24	018h
PWM0_CAPTURE	PWM/Timer 0 Capture Input Register	25	019h
-	Not Used	26	01Ah
PWM1_COUNT_IN	PWM/Timer 1 Counter Input Register	27	01Bh
PWM1_STATUS	PWM/Timer 1 Status Register	28	01Ch
-	Not Used	29	01Dh
PWM1_CAPTURE	PWM/Timer 1 Capture Input Register	30	01Eh
-	Not Used	31-35	01Fh-023h
SCI_IN	Serial Communication Interface RX data Input Register	36	024h
SCI_STATUS	Serial Communication Interface Status Register	37	025h
FLAGS	Flag Register	38	026h
-	Not Used	39	027h
IAP_SR	Programmable Low Voltage Detector and In Application Programming Status Register	40	028h
-	Not Used	41-56	029h-038h

Table 3.2 Output Registers

Mnemonic	Description	Address	
PORT_A_OUT	Port A data Output Register	0	00h
PORT_B_OUT	Port B data Output Register	1	01h
PORT_C_OUT	Port C data Output Register	2	02h
-	Not Used	3-4	03h-04h
SPI_OUT	Serial Peripheral Interface data Output Register	5	05h
I2C_OUT	I^2C Interface data Output Register	6	06h
-	Not Used	7	07h
PWM0_COUNT_OUT	PWM/Timer 0 Counter Output Register	8	08h
-	Not Used	9	09h
PWM0_RELOAD	PWM/Timer 0 Reload Register	10	0Ah
-	Not Used	11	0Bh
PWM1_COUNT_OUT	PWM/Timer 1 Counter Output Register	12	0Ch
-	Not Used	13	0Dh
PWM1_RELOAD	PWM/Timer 1 Reload Register	14	0Eh
-	Not Used	15-22	0Fh-016h
SCI_OUT	Serial Communication Interface TX data Output Register	23	017h

Table 3.3 Option Bytes

Mnemonic	Description	Address	
OSC_CR	Oscillator Control Register	0	00h
CLK_SET	Clock Parameters	1	01h
OSC_SET	Oscillator Set-Up	2	02h
PLVD_SET	PLVD and PDR Set-Up Register	3	03h
WDT_EN	HW/SW Watchdog selector	4	04h
PG_LOCK	First Page Write Protected	5	05h
PG_UNLOCK	First Page not Write Protected	6	06h
WAKEUP	Wake Up from Halt Time	7	07h

Table 3.4 Configuration Registers

Mnemonic	Description	Address	
INT_MASK	Interrupt Mask Register	0	00h
INT_POL	Interrupts Polarity	1	01h
INT_PRL_L	Interrupt Priority Register (lower priority)	2	02h
INT_PRL_M	Interrupt Priority Register (medium priority)	3	03h
INT_PRL_H	Interrupt Priority Register (higher priority)	4	04h
USTP_H	User Stack Top Pointer (MSB)	5	05h
USTP_L	User Stack Top Pointer (LSB)	6	06h
WDT_CR	Watchdog Configuration Register	7	07h
-	not used	8	08h
PWM0_CR1	PWM/Timer 0 Configuration Register 1	9	09h
PWM0_CR2	PWM/Timer 0 Configuration Register 2	10	0Ah
PWM0_CR3	PWM/Timer 0 Configuration Register 3	11	0Bh
PWM1_CR1	PWM/Timer 1 Configuration Register 1	12	0Ch
PWM1_CR2	PWM/Timer 1 Configuration Register 2	13	0Dh
-	Not Used	14-15	0Eh-0Fh
I2C_CR	I^2C Interface Control Register	16	010h
I2C_CCR	I^2C Interface Clock Control Register	17	011h
I2C_OAR1	I^2C Interface Own Address Register 1	18	012h
I2C_OAR2	I^2C Interface Own Address Register 2	19	013h
SPI_CR	Serial Peripheral Interface Control Register	20	014h
SPI_STATUS_CR	Serial Peripheral Interface Control-Status Register	21	015h
SCI_CR1	Serial Communication Interface Control Register 1	22	016h
SCI_CR2	Serial Communication Interface Control Register 2	23	017h
PORT_A_PULLUP	Port A Pull Up enable/disable Register	24	018h
PORT_A_OR	Port A Option Register	25	019h
PORT_A_DDR	Port A Data Direction Register	26	01Ah

Table 3.4 Configuration Registers

Mnemonic	Description	Address	
PORT_A_AF	Port A Alternate Function selection Register	27	01Bh
PORT_B_PULLUP	Port B Pull Up enable/disable Register	28	01Ch
PORT_B_OR	Port B Option Register	29	01Dh
PORT_B_DDR	Port B Data Direction Register	30	01Eh
PORT_B_AF	Port B Alternate Function selection Register	31	01Fh
PORT_C_PULLUP	Port C Pull Up enable/disable Register	32	020h
PORT_C_OR	Port C Option Register	33	021h
PORT_C_DDR	Port C Data Direction Register	34	022h
PORT_C_AF	Port C Alternate Function selection Register	35	023h
-	Not Used	36-42	024h-02Ah
SCI_CR3	Serial Communication Interface Control Register 3	43	02Bh
SSP_H	System Stack Pointer (MSB)	44	02Ch
SSP_L	System Stack Pointer (LSB)	45	02Dh
CPU_CLK	CPU Clock Prescaler	46	02Eh
-	Not Used	47	02Fh
IR_CR1	IR Driver Control Register 1	48	030h
IR_CR2	IR Driver Control Register 2	49	031h
PWM_LU_CR	PWM/Timers' Logic Unit Control Register	50	032h
PLVD_CR	Programmable Low Voltage Detector (PLVD)	51	033h
PHW_CR	Programmable Halt Wake-up Control Register	52	034h

4 MEMORY PROGRAMMING

ST52F501L/F502L provides an on-chip user programmable non-volatile memory, which allows fast and reliable storage of user data.

Program/Data Memory addressing space is composed by a Single Voltage Flash Memory and a RAM memory bench. The ST52F502L devices also have a Data EEPROM bench to store permanent data with long term retention and a high number of write/erase cycles.

All the Program Data memory addresses can execute code, including RAM and EEPROM benches.

The memory is programmed by setting the V_{pp} pin equal to V_{dd}. Data and commands are transmitted through the I^2C serial communication protocol. The same procedure is used to perform “In-Situ” the programming of the device after it is mounted in the user system. Data can also be written in run-time with the In-Application Programming (IAP) instructions.

The Memory can be locked by the user during the programming phase, in order to prevent external operation such as reading the program code and assuring protection of user intellectual property.

Flash and EEPROM pages can be protected by unintentional writings.

Remark: *the memory contents are protected by the Error Correction Code (ECC) algorithm that uses a 4-bit redundancy to correct one bit errors.*

4.1 Program/Data Memory Organization

The Program/Data Memory is organized as described in Section 3.3. The various sales types have different amounts of each type of memory. Table 4.1 describes the memory benches amount and page allocation for each sales type.

The addressing spaces are organized in pages of 256 bytes. Each page is composed by blocks of 32 bytes. Memory programming is performed one block at a time in order to speed-up the programming time (about 2.5 ms per block).

The whole location address is composed as follows:

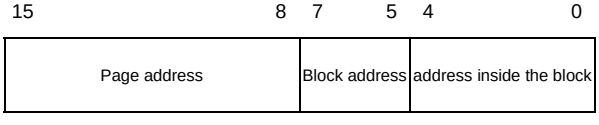


Table 4.1 Sales Types Memory Organization

Device	Flash Memory		RAM Memory		EEPROM Memory	
	Amount	Pages	Amount	Page	Amount	Page
ST52F501Lc1p6	2048 bytes	0 to 7	256 bytes	32	-	-
ST52F501Lc2p6	4096 bytes	0 to 15	256 bytes	32	-	-
ST52F501Lc3p6	8192 bytes	0 to 31	256 bytes	32	-	-
ST52F502Lc1p6	1792 bytes	0 to 6	256 bytes	32	256 bytes	7
ST52F502Lc2p6	3840 bytes	0 to 14	256 bytes	32	256 bytes	15
ST52F502Lc3p6	7936 bytes	0 to 30	256 bytes	32	256 bytes	31

Legend:
c: Y=16 pins, F=20 pins, G=28 pins, K=32/34 pin
p: B=DIP, M=SO, T=TQFP

4.2 Memory Programming

The Programming procedure writes the user program and data into the Flash Memory, EEPROM and Option Bytes. The programming procedures are entered by setting the V_{pp} pin equal to V_{dd} and releasing the Reset signal. The following pins are used in Programming mode:

- V_{PP} used to switch to programming mode
- V_{DD} device supply
- V_{SS} device ground
- RESET device reset
- SCL I^2C serial clock
- SDA I^2C serial data

During the device programming, the internal clock is used, so the OSCin and OSCout pins don't have to be considered.

Remark: *The Option Bytes must be always programmed, otherwise these bytes will be loaded with unpredictable values, determining unpredictable device configuration.*

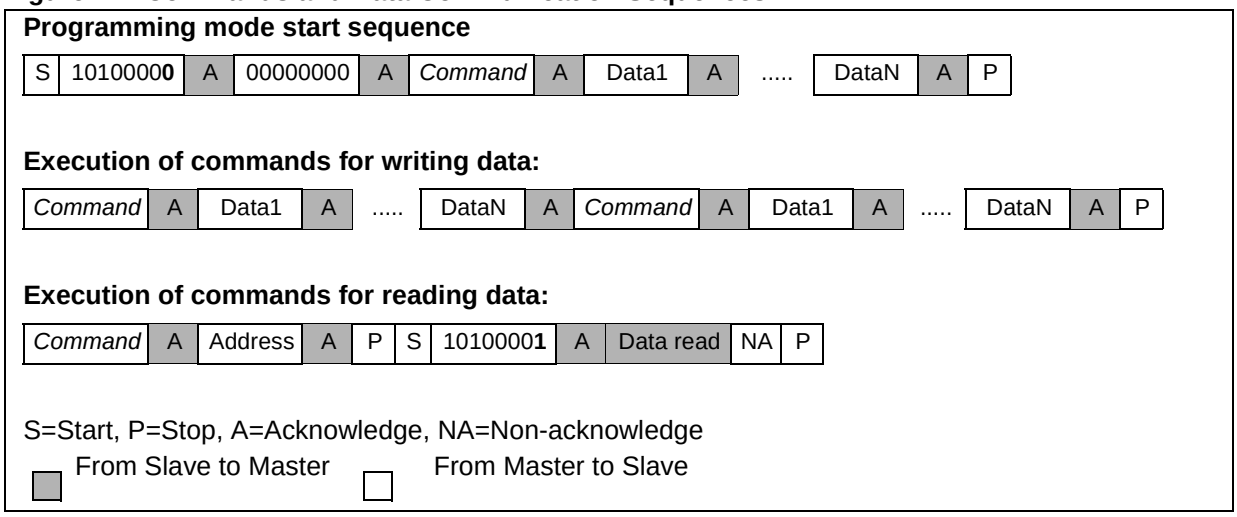
4.2.1 Programming Mode start. The following sequence starts the Programming Mode:

1. V_{PP} is set to V_{DD}
2. The device is Reset (RESET=V_{SS})
3. The Reset is released (RESET=V_{DD})
4. The internal oscillator starts at 10 MHz
5. The memory is turned on
6. The I^2C Interface and Ports are initialized
7. The I^2C Interface is configured to work as Slave, Receiver, 7-bit address and waits for data
8. The Start signal is sent to the chip followed by the Slave Address 1010000 and the direction bit set to 0 (the addressed slave waits for data). The device sends the acknowledge
9. The Programming Mode code 00000000 is sent and acknowledged
10. A command code is sent to the device
11. The procedure related to the command is executed

Table 4.2 Programming Mode Commands

Command	Code	Data in	Data out	Erase	Description
BlockWrite	00000001	32	-	Yes	Write the currently addressed block with the 32 bytes following the command. The Block locations are erased before being written.
ByteWrite	00000010	2	-	Yes	Write the byte addressed by the next data sent in the currently addressed page.
BlockErase	00000011	1		Yes	Erase the block addressed by 3 MSB of the next data sent and inside the currently addressed page.
ByteErase	00000100	1		Yes	Erase the byte addressed by the next data sent and inside the currently addressed page.
ByteRead	00000101	1	1	-	Read the byte addressed by the next data sent and inside the current page. The read data is sent by the device after the re-send of the Slave Address with the R/W bit changed. The current memory absolute address is post-incremented.
GlobalErase	00001001	-	-	Yes	All the memory is erased.
FastBlockWrite	00001011	32	-	No	Write the currently addressed block with the 32 bytes following the command. The Block locations aren't erased.
SetPage	00001100	1	-	-	The currently addressed page is set with the next data sent.
ReadData	00001101	-	N	-	Read N consecutive bytes starting from the memory location currently addressed. The read data is sent by the device after the command is acknowledged. The current memory absolute address is post-incremented.
IncBlock	00001111	-	-	-	The current block address is incremented modulo 8 (address 0 follows after address 7 and the Page is post-incremented)
ReadStatus	00010011	-	1	-	This command is followed by a status data byte. Mostly used in error condition and to check if the device is locked

Figure 4.1 Commands and Data Communication Sequences



The generic procedure of commands execution, with the data communication in both directions is displayed in Figure 4.1.

Remark: *the Slave Address 1010000 must be sent after a Stop (i.e. each time the data direction changes, to specify the R/W bit). For example: if a command to send data to the device has been executed, a command for receiving data must be followed by the slave address and the R/W bit must be set to 1. The Programming Mode code doesn't need to be specified again.*

Warning: *After entering the Programming Mode, the currently pointed address is the Page 48, Block 3, byte 0 (Lock Byte).*

The list of the available commands in Programming Mode is showed in Table 4.2

4.2.2 Fast Programming procedure. The fastest way to program the device memory is the use of the *FastBlockWrite* command. The following procedure can be used to write the memory with a new program and new data, starting from the first memory location:

1. The Programming Mode is entered with the sequence described above
2. The memory is erased (all bits are put to 0) with the *GlobalErase* command. The device holds the SCL line low, releasing it after the command is completed (about 2 ms). This command also unlocks the device if locked.
3. The *FastBlockWrite* command is sent and the device acknowledges it
4. The 32 bytes of data to be written in the first memory Block are sent in a sequence. The device acknowledges each of them
5. After the device acknowledges the 32nd byte, it holds the SCL line until the parallel writing of the 32 byte is completed (about 2.5 ms)
6. The Block Pointer is incremented by sending the *IncBlock* command
7. The procedure is repeated from point 3 until there is data to be sent to the memory

Note: *the Block Pointer assumes values between 0 to 7 (there are 8 blocks in a page). When the Block Pointer is equal to 7, the IncBlock command puts this pointer to 0 and increments the Page Pointer. The Page Pointer, after page writing is completed, doesn't have to be incremented in the procedure above described.*

4.2.3 Random data writing. A single byte can be written in a specified memory location by using the following procedure:

1. The Programming Mode is entered with the sequence described in Section 4.2.1
2. The *SetPage* command is sent, followed by the page number where the data should be written
3. The *ByteWrite* command is sent followed by two bytes
4. The first bytes that follows the ByteWrite command is the address inside the pointed page where the data must be written.
5. The second byte is the data to be written
6. The device held the SCL line low until the data is not stored in the memory (about 4.5 ms: 2 ms for erasing and 2.5 for writing)

A similar procedure can be used to write a single block:

1. The *SetPage* command is sent, followed by the page number where the data should be written
2. The *IncBlock* command is sent as many times as the block number inside the page (for example: to address the block 3 the *IncBlock* must be sent 3 times)
3. The *BlockWrite* command is sent followed by the 32 data bytes to be written.
4. After the 32th byte is sent, the device holds the SCL line low until all the data are not stored in the memory (about 4.5 ms: 2 ms for erasing and 2.5 for writing: the same time for a single byte)

The procedures described previously can be repeated as many time as needed, without exiting from Programming Mode or re-sending the Slave Address again.

The commands ByteErase and BlockErase, used instead of ByteWrite and BlockWrite, erase (put all bit to 0) the specified memory location or block.

4.2.4 Option Bytes Programming. The Option Byte addresses cannot be accessed with a sequential procedure like the one described in Section 4.2.2. Actually, the pointers are automatically incremented up to the last block or address in page 31. A further increment sets all the pointers to 0.

The Option Byte addresses (located at page 48, block 0, addresses 0-7) must be accessed with a direct addressing procedure as the one described in Section 4.2.3.

If the Fast Programming procedure is used, it must be followed by a Random Block Writing procedure to program the Option Bytes. The other 24 bytes of the block can be written with dummy values or user values. The blocks 0, 1, 2 and 3 of Page 48 can be used for writing data as well (see Section 4.5) and for locking the device (see Section 4.4).

Figure 4.2 Programming Procedures

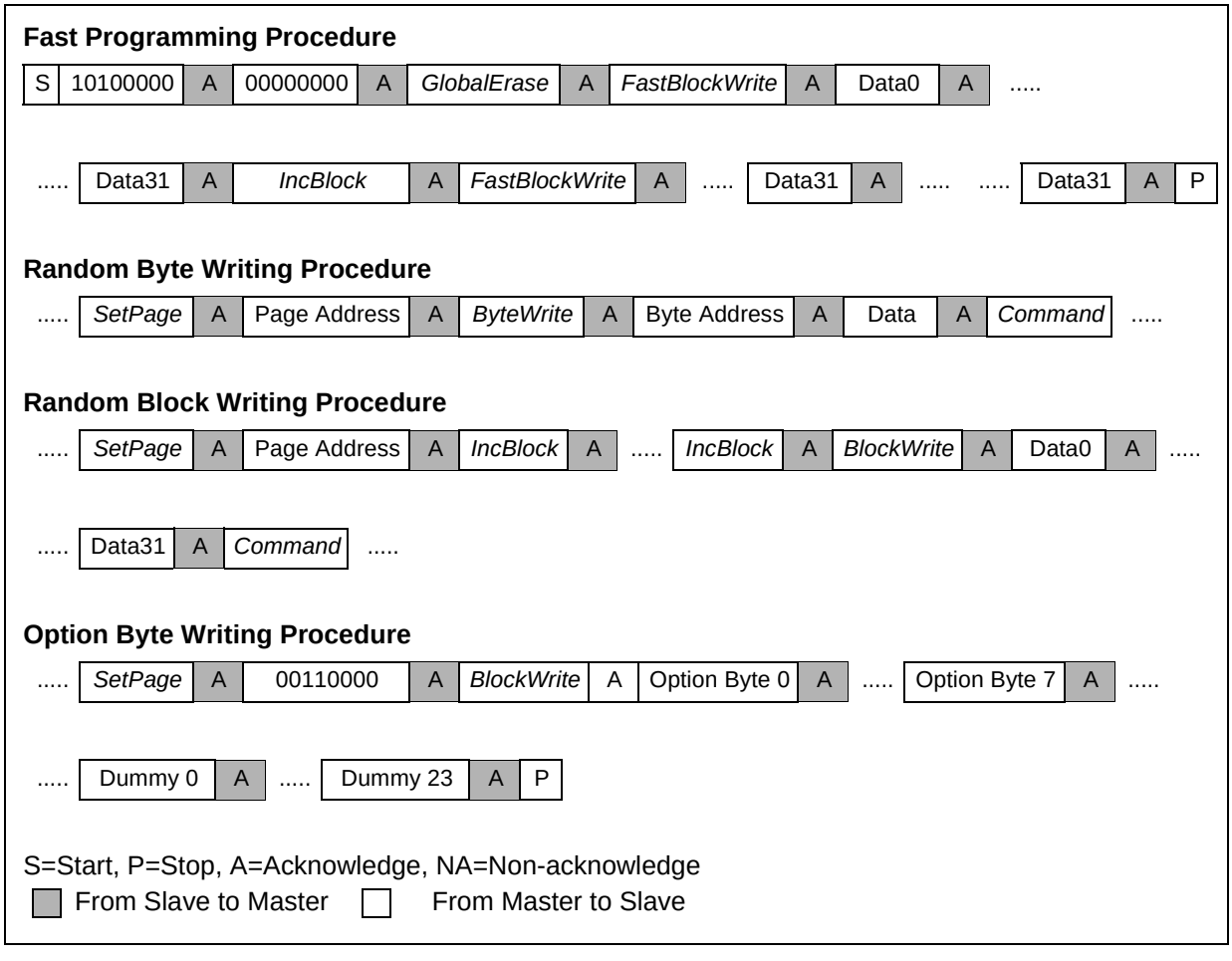
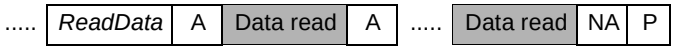
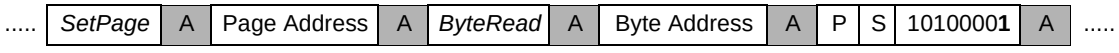


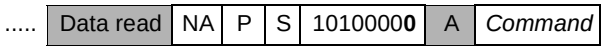
Figure 4.3 Reading and Erasing Procedures

Fast Reading Procedure

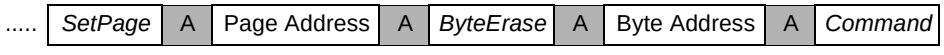


Random Byte Reading Procedure

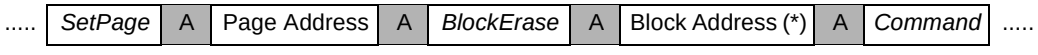




Byte Erasing Procedure



Block Erasing Procedure



(*) Block address is specified by the 3 most significative bits of the whole given address (less significative bits are don't care)

S=Start, P=Stop, A=Acknowledge, NA=Non-acknowledge

From Slave to Master From Master to Slave

4.3 Memory Verify

To verify the memory contents or just to read part of data stored in memory, the *ByteRead* and the *ReadData* command can be used. The first instruction needs the specification of the address; the second one allows the sequential reading of consecutive memory locations.

Since the device is "Slave" for the I^2C protocol, after receiving a command for reading, it must be configured as Slave Transmitter to send the data. In order to do so, the Slave Address (1010000) must be sent again with the R/W byte set to 1, as stated by the communication protocol.

4.3.1 Fast read procedure. The memory can be read sequentially by using the following procedure:

1. The Programming mode is entered with the sequence described in Section 4.2.1
2. The pointers address the memory location 0
3. The *ReadData* command is sent and the device acknowledges it.
4. The Master generates a Stop condition followed by a Start condition
5. The Slave Address with the R/W byte set to 1 (10100001) is sent. The device receives the Slave Address and acknowledges it.
6. The device sends the data to be read in the serial data line SDA. The current absolute address is post-incremented.
7. The Master device send the acknowledge to read the contents of the next location.
8. The sequence restarts from point 6 until the master not acknowledge the data read and generates a Stop condition, in order to stop the reading sequence.

Remark: *for the same reasons explained in Section 4.2.4 the Option Bytes cannot be read with this procedure: they can be read with a direct addressing procedure as the one explained in the next section.*

4.3.2 Random data reading. To read a specified memory location, the following procedure should be used:

1. The Programming mode is entered with the sequence described in Section 4.2.1
2. The *SetPage* command is sent, followed to the page number where the data to be read is located
3. The *ByteRead* command is sent, followed by an address inside the page
4. The Master generates a Stop condition followed by a Start condition
5. The Slave Address with the R/W byte set to 1 (10100001) is sent. The device receives the Slave Address and acknowledges it.
6. The device sends the data to be read in the serial data line SDA. The address pointer is incremented.
7. The Master device doesn't send the acknowledge and generates a stop condition.
8. To send the next command, the Master should generate a Start condition followed by the Slave Address with the R/W byte set to 0 (10100000).

4.4 Memory Lock

The Program/Data Memory space can be locked to inhibit the reading of contents and protect the intellectual property.

To lock the device, the user must set all the bit of the Lock Byte to '1'. The Lock Byte is located on Page 48 (030h), Block 3, byte 0 inside the block i.e. byte 96 (060h) inside the page.

After writing 255 (0FFh) into the Lock Byte, with the procedure described in the Section 4.2.3, the memory is locked and the only command allowed are the following:

– *GlobalErase*: this command, writing '0' in all the memory, also unlock the device.
– *ReadData*: the only block that can be read is the Block 3 in Page 48 (030h); this allows the reading of the Lock Byte and the ID Code locations (see Section 4.5).
– *ReadStatus*: this command allows the detection of an error condition in Programming mode operation (see Section 4.6). It can also be used to check if the device is locked. The most significative bit return the Lock Bit (0=unlocked, 1=locked).

Remark: *the Lock Byte is checked when entering the Programming Mode. For this reason after writing the Lock Byte, all the commands can be carried out until the Programming mode is exited.*

Figure 4.4 Device Lock Procedure

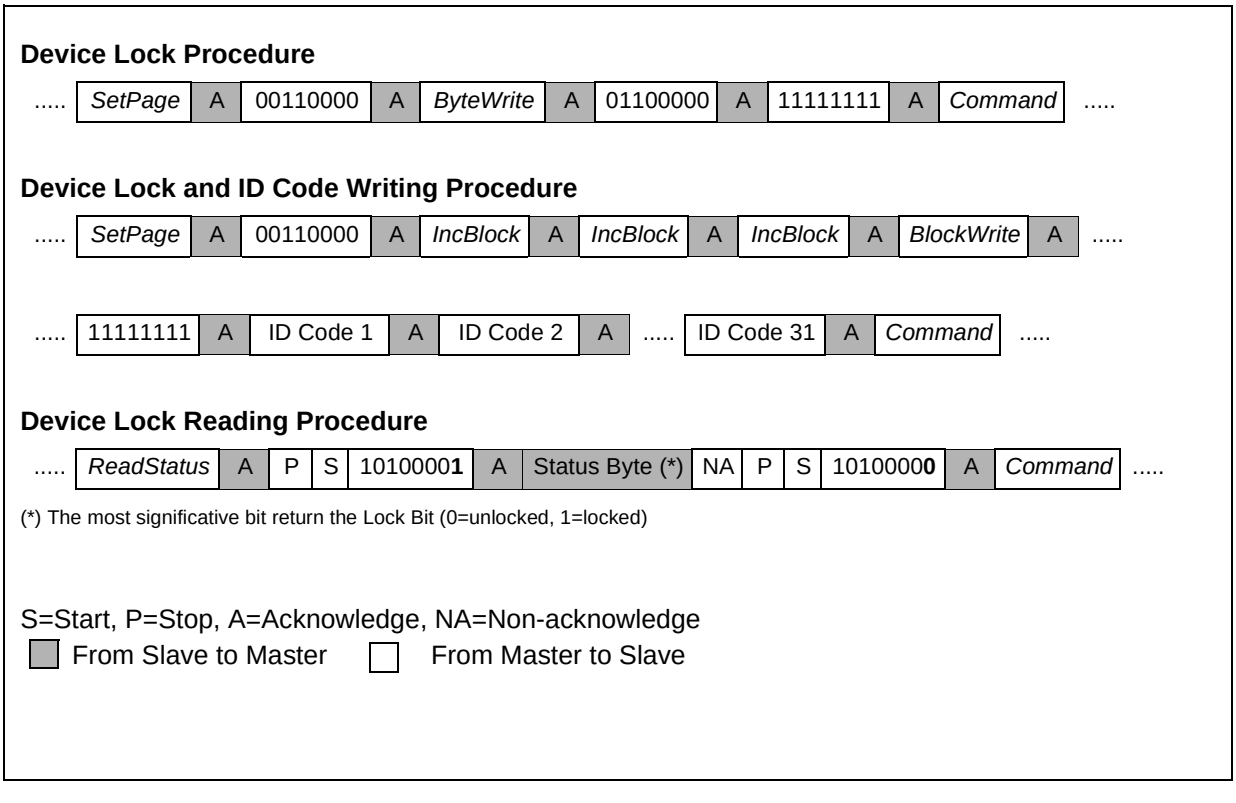
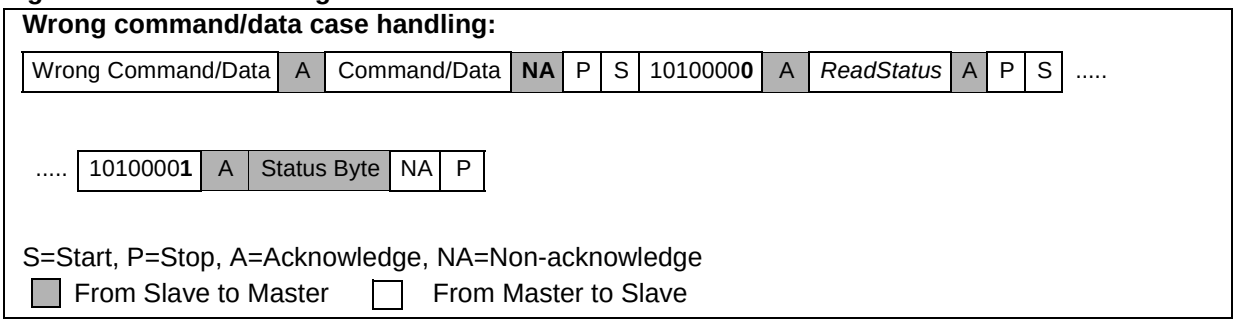


Figure 4.5 Error Handling Procedure



When the device is locked, if memory reading is attempted, with the exception of the Lock Byte and ID Code block, the device returns no data and an error sequence. If memory writing is attempted in any memory location, the device doesn't carry out the command and returns an error sequence.

To unlock the device the *GlobalErase* command must be executed before any writing or reading command.

4.5 ID Code

Block 3 on Page 48 (030h) can also be read if the device is locked. The first byte of the block is the Lock Byte, the following 21 locations (bytes 1-21) are available to the user for writing data, as for example identification codes to distinguish the firmware version loaded in the device.

Warning: *do not perform writing on the last 8 bytes (bytes 22 to 31), because they are reserved.*

The ID Code must be written before locking the device: after the device is locked it can only be read. The blocks 0, 1 and 2 on Page 48 can be also be used for writing data, but they cannot be accessed when the device is locked.

Note: *the ID Code cannot be modified if the device is locked: it can only be read.*

4.6 Error cases

If a wrong command or data is sent to the device, it generates an error condition by not sending the acknowledge after the first successive data or command. Figure 4.5 shows the error sequence.

The error case can be handled by using the *ReadStatus* command. This command can be sent after the error condition is detected; the device returns a Status Byte containing the error code. The *ReadStatus* command sequence is showed in Figure 4.5. The list of the error codes is illustrated in Table 4.3.

Remark: *after the ReadStatus command execution or after any error, the Start Sequence must be carried out before sending a new command.*

The Most Significative Bit of the error codes indicates (when set to '1') that the memory is locked. When a command, that is not allowed when the memory is locked, is sent, the "*Not Allowed*" code is sent. If another code is sent with the MSB to '1' it indicates that the error condition is not caused by the memory lock, but by the event related with the code sent.

Warning: *when the data writing into a non existing location is attempted, no error condition is generated. The user must take care in specifying the correct page address.*

Table 4.3 Error codes

Name	Code	Description
Device Locked	xyyyyyyy	x=lock bit (1=device locked), yyyyyyy=error code
Wrong Command	x0000101	The Master sent a wrong command code
Not Allowed	x0000110	A command not allowed when the device is locked has been sent
Wrong Mode	x0010000	A code different form the Programming mode code (00000000) has been sent

4.7 In-Situ Programming (ISP)

The Program/Data Memory can be programmed using the ISP mode. This mode allows the device to be programmed when it is mounted in the user application board.

This feature can be implemented by adding a minimum number of components and board impact.

The programming procedures and pins used are identical to the ones described before for the standard Programming Mode. All the features previously described in this chapter are applicable in ISP mode.

If RESET, SCL and SDA pins are used in the user application board for other purposes, it is recommended to provide an adequate isolation to avoid a conflict when the other devices force the signal level.

The ISP can be applied by using the standard tools for the device programming. The ST52F501L Starter Kit supplies a cable to perform the ISP. The user application board should supply a suited connector type for the cable (see Starter Kit User Manual).

4.8 In-Application Programming (IAP)

The In Application Programming Mode (IAP) allows the writing of user data in the Flash and EEPROM memories when the user program is running.

There are two ways to write data in IAP mode: single byte write and Block write. Both procedures take about 4.5 ms to complete the writing: the Block write allows the writing of 32 byte in parallel.

Remark: *during data writing, the execution of the user program is stopped until the procedure is completed. Interrupt requests stop the writing operation and the data may be not stored. The bit ABRT in the IAP_SR Input register signals that the data writing hasn't been completed. To assure writing completion, the user should globally disable the interrupts (UDGI instruction) before starting IAP data writing.*

4.8.1 Single byte write. Writing of a single byte in the Non-Volatile Program/Data memory is performed by using the LDER instructions (both direct and indirect addressing). The memory page should be indicated before the LDER instruction with the PGSET or PGSETR instruction. The byte address inside the page is specified by the LDER instruction itself.

As soon as the instruction is executed, the data writing starts and is performed in about 4.5 ms.

4.8.2 Block write. This procedure allows the writing of 32 bytes in parallel. These bytes should belong to the same block.

Before the writing in the Program/Data memory, data must be buffered in the Register File in the first 32 locations (0-31, 00h-020h) by using the normal instructions to load the Register File locations.

Then the data writing starts by using the BLKSET instruction. The destination block is addressed by specifying the memory page with the PGSET or PGSETR instruction before to start the writing; the block inside the page is addressed with the argument of the BLKSET instruction.

Example:

```
PGSET 5
BLKSET 4
```

This instruction sequence writes the contents of the first 32 bytes of the Register File in the locations 1408-1439 (0580h-059Fh).

Warning: *the user should be careful in specifying the correct page and block: the addressing of an not existing block can cause the unwanted writing of a different block.*

As soon as the BLKSET instruction is executed, the data writing starts and is performed in about 4.5 ms.

This procedure may also be used to write few data, taking in account that all the 32 byte are written in the block anyway.

4.8.3 Memory Corruption Prevention.

The user can protect some pages (or all the memory) from unintentional writings. The only constraint is that the protected pages must be consecutive.

Two Option Bytes allow the specification of the page to be protected: PG_LOCK (Option Byte 5) and PG_UNLOCK (Option Byte 6). PG_LOCK is used to specify the first protected page; PG_UNLOCK is used to specify the first page not protected after the protected ones. The pages between the two addresses are protected.

When writing in a protected page is attempted, the procedure is aborted and the bit PRTCD of IAP_SR Input register is set.

If the PG_LOCK and PG_UNLOCK have the same value, no page is protected.

In Programming Mode the protection is not considered and the pages can be written unless the device is locked.

4.8.4 Option Bytes.

First Protected Page (PG_LOCK)

Option Byte 5 (05h)

7							0
LCK7	LCK6	LCK5	LCK4	LCK3	LCK2	LCK1	LCK0

Bit 7-0: **LCK7-0** First Page write protected

In this register the address of first page to be protected in writing is specified. The pages following this one are protected up to the page specified by the PG_UNLOCK Option Byte (not included among the protected ones).

First Page not Protected (PG_UNLOCK)

Option Byte 6 (06h)

7							0
UNLCK7	UNLCK6	UNLCK5	UNLCK4	UNLCK3	UNLCK2	UNLCK1	UNLCK0

Bit 7-0: **UNLCK7-0** First Page not write protected

In this register the address of first page not write protected after the protected ones is specified. The pages following this one aren't protected.

4.8.5 Input Register.

IAP Status Register (IAP_SR)

Input Register 40 (028h) Read only

Reset Value: 0000 0000 (00h)

7							0
PLVDST	-	-	-	-	-	PRTCD	ABRT

Bit 7: See Section 6.6.3

Bit 6-2: Not Used

Bit 1: **PRTCD** Page Protected

0: The writing has been completed

1: The writing has been aborted because the page is protected.

Bit 0: **ABRT** Writing operation aborted

0: The writing has been completed

1: The writing has been aborted because an interrupt or another unspecified cause occurred.

The ABRT and PRTCD bits are reset after the next successful data writing in the Flash of EEPROM memory.

5 INTERRUPTS

The Control Unit (CU) responds to peripheral events and external events through its interrupt channels.

When such events occur, if the related interrupt is not masked and doesn't have a priority order, the current program execution can be suspended to allow the CU to execute a specific response routine.

Each interrupt is associated with an interrupt vector that contains the memory address of the related interrupt service routine. Each vector is located in the Program/Data Memory space at a fixed address (see Figure 3.2 Program/Data Memory Organization).

5.1 Interrupt Processing

If interrupts are pending at the end of an arithmetic or logic instruction, the interrupt with the highest priority is acknowledged. When the interrupt is acknowledged the flags and the current PC are saved in the stacks and the associated Interrupt routine is executed. The start address of this routine (Interrupt Vector) is located in two bytes of the Program/Data Memory between address 3 and 32 (03h-020h). See Table 5.1 for the list of the Interrupt Vector addresses.

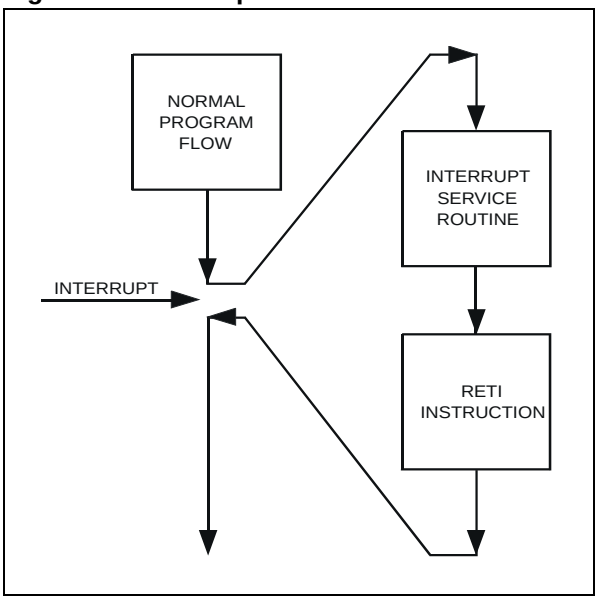
The Interrupt routine is performed as a normal code. At the end of any instruction, the CU checks if a higher priority interrupt has sent an interrupt request. An Interrupt request with a higher priority stops lower priority Interrupts. The Program Counter and the flags are stored in their own stacks.

With the instruction RETI (Return from Interrupt) the flags and the Program Counter (PC) are restored from the top of the stacks. These stacks have already been described in Section 3.4.

An Interrupt request cannot stop fuzzy rule processing. The request is acknowledged only after the end of a fuzzy rule or at the end of a logic or arithmetic instruction, unless a Global Interrupt Disable instruction has been executed before.

Remark: *A fuzzy routine can be interrupted only in the Main program. When a Fuzzy function is running inside another interrupt routine an interrupt request can cause side effects in the Control Unit. For this reason, in order to use a Fuzzy function inside an interrupt routine, the user MUST include the Fuzzy function between an UDGI (MDGI) instruction and an UEGI (MEGI) instruction (see the following paragraphs), in order to disable the interrupt request during the execution of the fuzzy function.*

Figure 5.1 Interrupt Flow



5.2 Global Interrupt Request Enabling

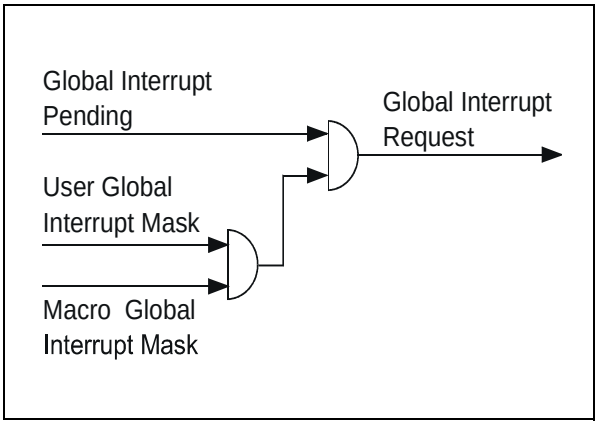
When an Interrupt occurs, it generates a Global Interrupt Pending (GIP). After a GIP a Global Interrupt Request (GIR) will be generated and Interrupt Service Routine associated with the interrupt with higher priority will start.

In order to avoid possible conflicts between the interrupt masking set in the main program, or inside high level language compiler macros, the GIP is put in AND through the User Global Interrupt Mask or the Macro Global Interrupt Mask (see Figure 5.2).

The UEGI/UDGI instruction switches the User Global Interrupt Mask enabling/disabling the GIR for the main program.

MEGI/MDGI instructions switch the Macro Global Interrupt Mask on/off in order to ensure that the macro will not be interrupted.

Figure 5.2 Global Interrupt Request



5.3 Interrupt Sources

ST52F501L/F502L manages interrupt signals generated by the internal peripherals or generated by software by the TRAP instruction or coming from the Port pins. There are two kinds of interrupts coming from the Port pins: the NMI and the Ports Interrupts. NMI (Not Maskable Interrupt) is associated with pin PA7 when it is configured as Alternate Function. This interrupt source doesn't have a configurable level priority and cannot be masked. The fixed priority level is lower than the software TRAP and higher than all the other interrupts. The NMI can be configured to be active on the rising or the falling edge.

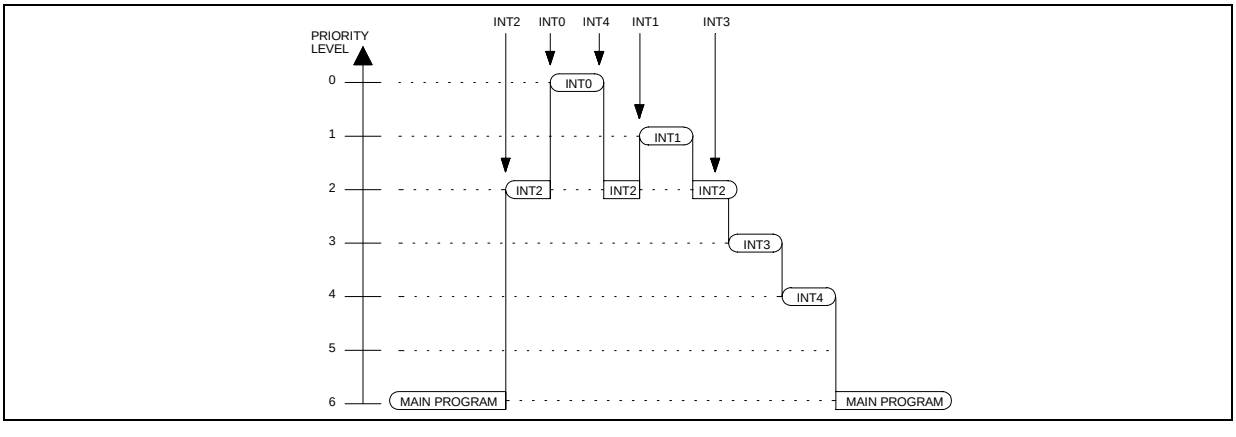
The Port Interrupts sources are connected with Port A, Port B and Port C pins. The pins belonging to the same Port are associated with the same interrupt vector: one vector for Port A and one shared by Port B and C. In order to use one port pin as interrupt, it must be configured as an interrupt source (see I/O Ports chapter). In this manner, up to 24 Port Interrupt sources are available. By reading the Port the sources that belong to the same Port can be discriminated. The Port Interrupts can be configured to be active on the rising or the falling edge, by using the INT_POL register.

Warning: *changing the NMI or Port Interrupt polarity an interrupt request is generated.*

All the interrupt sources are filtered, in order to avoid false interrupt requests caused by glitches. The Trap instruction is something between a interrupt and a call: it generated an interrupt request at top priority level and the control is passed to the associated interrupt routine which vector is located in the fixed addresses 31-32. This routine cannot be interrupted and it is serviced even if the interrupts are globally disabled.

Note: *Similarly to the CALL instruction, after a TRAP the flags are not stacked.*

Figure 5.3 Example of Interrupt Requests



5.4 Interrupt Maskability and Priority Levels

Interrupts can be masked by the corresponding INT_MASK Configuration Register 0 (00h). An interrupt is enabled when the mask bit is "1". Vice versa, when the bit is "0", the interrupt is masked and the eventual requests are kept pending. All the interrupts, with the exception of the NMI and TRAP that have fixed level priority, have a configurable priority level. The configuration of the priority levels is completed by writing three consecutive Configuration Registers: INT_PRL_L, INT_PRL_M, INT_PRL_H, addresses from 2 to 4 (02h-04h). The 24 bits of these registers are divided into 8 groups of three bits: each group is associated with a priority level. The three bits of each group are written with the code number associated with the interrupt source. See Table 5.1 to know the codes.

Warning: *The priority levels Configuration Registers must be programmed with different values for each 3-bit groups to avoid erroneous operation. After the RESET the priority registers are loaded with a default priority configuration. Each time the priority is modified, each priority register must be configured with consistent values. During program execution the interrupt priority can only be modified within the Main Program: it cannot be changed within an interrupt service routine. In addition the interrupts must be disabled by means of the UDGI instruction. In order to avoid side effect the interrupts must be disabled before the priority register configuration.*

5.5 Interrupt RESET

When an interrupt is masked, all requests are not acknowledged and remain pending. When the pending interrupt is enabled it is immediately serviced, if it has proper priority. This event may be undesired; in order to avoid this a RINT instruction may be inserted followed by the code number that identifies the interrupt to reset the pending request. The RINT instruction has no effect if the interrupt is being serviced.

See Table 5.1 to know the codes.

5.6 Register Description

Interrupt Mask Register (INT_MASK)
Configuration Register 0 (00h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
MSKPB	MSKPA	MSKI2C	MSKLVD	MSKSCI	MSKT1	MSKT0	MSKPHW

Bit 7: **MSKPB** Interrupt Mask Port B OR C
0: Port B OR C interrupt masked
1: Port B OR C interrupt enabled

Bit 6: **MSKPA** Interrupt Mask Port A
0: Port A interrupt masked
1: Port A interrupt enabled

Bit 5: **MSKI2C** Interrupt Mask I^2C Interface
0: I^2C Interface interrupt masked
1: I^2C Interface interrupt enabled

Bit 4: **MSKLVD** Interrupt Mask PLVD
0: PLVD interrupt masked
1: PLVD interrupt enabled

Bit 3: **MSKSCI** Interrupt Mask SCI OR SPI
0: SCI OR SPI interrupt masked
1: SCI OR SPI interrupt enabled

Bit 2: **MSKT1** Interrupt Mask PWM/Timer 1
0: Pwm/Timer 1 interrupt masked
1: Pwm/Timer 1 interrupt enabled

Bit 1: **MSKT0** Interrupt Mask Pwm/Timer 0
0: Pwm/Timer 0 interrupt masked
1: Pwm/Timer 0 interrupt enabled

Bit 0: **MSKPHW** Interrupt Mask PHW
0: PHW interrupt masked
1: PHW interrupt enabled

Interrupt Polarity Register (INT_POL)
Configuration Register 1 (01h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
-	-	-	RESPOL	STRPOL	POLPB	POLPA	POLNMI

Bit 7-3: Not Used

Bit 4-3: See Timer 0 Registers Description

Bit 2: **POLPB** Port B & C Interrupt Polarity
0: The Port B & C interrupt is triggered on the rising edge of the applied external signal.
1: The Port B & C interrupt is triggered on the falling edge of the applied external signal.

Bit 1: **POLPA** Port A Interrupt Polarity
0: The Port A interrupt is triggered on the rising edge of the applied external signal.
1: The Port A interrupt is triggered on the falling edge of the applied external signal.

Bit 0: **POLNMI** Non Maskable Interrupt Polarity
0: The NMI is triggered on the rising edge of the applied external signal.
1: The NMI is triggered on the falling edge of the applied external signal.

Low Priority Register (INT_PRL_L)
Configuration Register 2 (02h) Read/Write
Reset Value: 1111 1010 (FAh)

7							0
PRL23	PRL22	PRL21	PRL20	PRL19	PRL18	PRL17	PRL16

Medium Priority Register (INT_PRL_M)
Configuration Register 3 (03h) Read/Write
Reset Value: 1100 0110 (C6h)

7							0
PRL15	PRL14	PRL13	PRL12	PRL11	PRL10	PRL9	PRL8

High Priority Register (INT_PRL_H)

Configuration Register 4 (04h) Read/Write

Reset Value: 1000 1000 (88h)

7							0
PRL7	PRL6	PRL5	PRL4	PRL3	PRL2	PRL1	PRL0

These three register are used to configure the priority level of each interrupt source. The 24 bits of these registers (PRL23-PRL0) are divided into 8 groups of three bits: each group is associated with a priority level (from level 1, the highest, to level 8, the lowest: level 0 is fixed for the NMI that can be interrupted only by the TRAP). The three bits of each group are written with the code number associated with the interrupt source (see Table 5.1).

PRL2-PRL0: Interrupt priority level 1 (highest)
PRL5-PRL3: Interrupt priority level 2
PRL8-PRL6: Interrupt priority level 3
PRL11-PRL9:Interrupt priority level 4
PRL14-PRL12: Interrupt priority level 5
PRL17-PRL15: Interrupt priority level 6
PRL20-PRL18: Interrupt priority level 7
PRL23-PRL21: Interrupt priority level 8 (lowest)

Example: writing the code 110 into PRL8-PRL6 bits the priority level 3 is assigned to the Port A Interrupt.

Warning: *the Priority Level configuration registers must be always configured with consistent values.*

Table 5.1 Interrupt sources parameters

Interrupt Source	Priority type	PRL code	RINT code	Maskable	Vector Addresses
PHW	Programmable	000	0	Yes	3-5 (03h-05h)
PWM/Timer 0	Programmable	001	1	Yes	6-8 (06h-08h)
PWM/Timer 1 IR Driver	Programmable	010	2	Yes	9-11 (09h-0Bh)
SCI / SPI (*)	Programmable	011	3	Yes	12-14 (0Ch-0Eh)
PLVD	Programmable	100	4	Yes	15-17 (0Fh-011h)
I^2C Interface	Programmable	101	5	Yes	18-20 (012h-014h)
Port A	Programmable	110	6	Yes	21-23 (015h-017h)
Port B OR C	Programmable	111	7	Yes	24-26 (018h-01Ah)
NMI	Fixed	-	8	No	27-29 (01Bh-01Dh)
TRAP	Fixed to highest	-	-	No	30-32 (01Eh-020h)

Warning: *(*) The interrupt 3 is shared between SCI and SPI. The two sources can be enabled selectively by their own interrupt enable bit in the Configuration Register.* ***It is strongly reccomended to not enable both interrupts at the same time to avoid the device to go to an umpredictable status.***

6 CLOCK, RESET & POWER SAVING MODES

6.1 Clock

The ST52F501L/F502L Clock Generator module generates the internal clock for the internal Control Unit, ALU and on-chip peripherals. The Clock is designed to require a minimum of external components.

ST52F501L/F502L devices supply the internal oscillator in four clock modes:

- External quartz oscillator
- External clock
- Internal oscillator

The device always starts in internal clock mode, excluding any external clock source. After the start-up phase the clock is configured according to the user definition programmed in the Option Byte 0 (OSC_CR). The internal clock generator can supply an internal clock signal with a fixed frequency of 10 MHz ± 1%, without the need for external components. In order to obtain the maximum accuracy, the frequency can be calibrated by configuring the related Option byte 2 (OSC_SET). The internal clock can be divided by the configurable prescaler, set with the OSC_SET Option byte, by a factor 2, 4 or 8 thus obtaining 5 MHz, 2.5 MHZ and 1.25 MHZ clock frequency.

The external oscillator mode uses a quartz crystal or a ceramic resonator connected to OSCin and OSCout as illustrated in Figure 6.1. This figure also illustrates the connection of an external clock.

The ST52F501L/F502L oscillator circuit generates an internal clock signal with the same period and phase as the OSCIN input pin. The maximum frequency allowed is 16 MHz.

When the external oscillator is used, the loop gain can be adapted to the various frequencies values by configuring the three bits of the Option Byte 1 CLK_SET (see Register Description, Table 6.1).

***Warning:** when using high level loop gains with quartz crystal, it could be necessary a resistor to comply with the crystal manufacturer drive level specification.*

When an external clock is used, it must be connected to the pin OSCIN while OSCOUT can be floating. In this case, Option Byte 1 bits must be written with 0 (000).

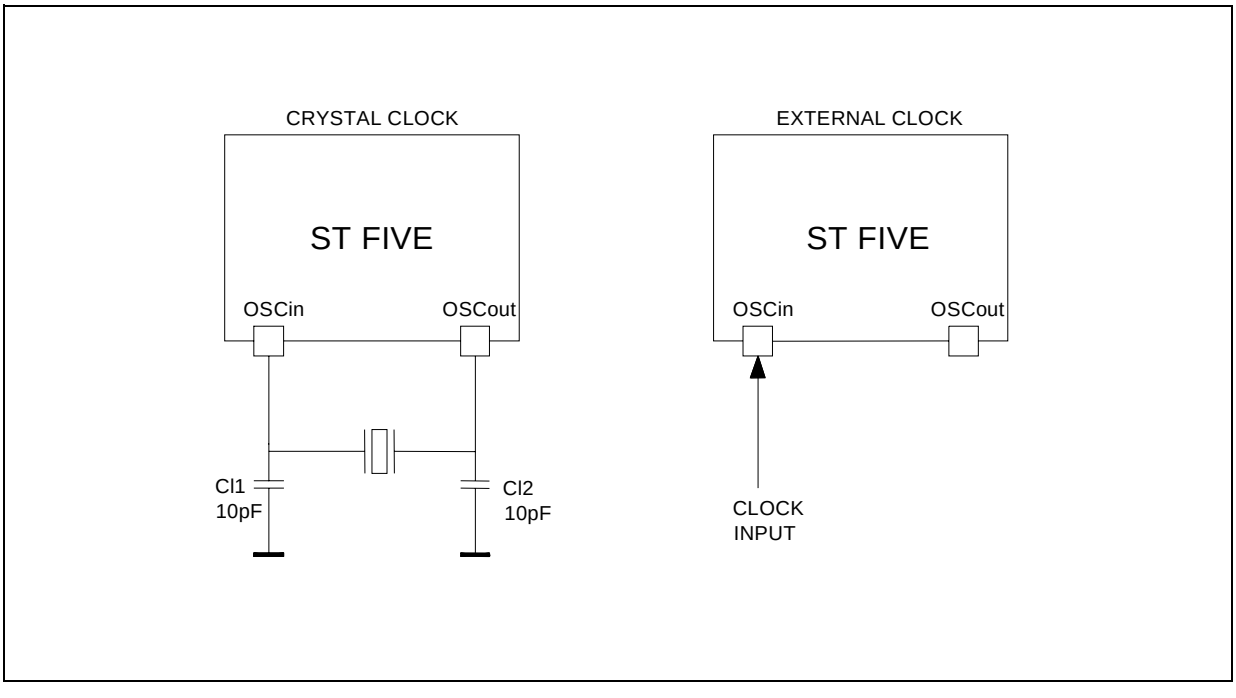
The crystal oscillator start-up time is a function of many variables: crystal parameters (especially R_S), oscillator load capacitance (CL), IC parameters, environment temperature and supply voltage.

The crystal or ceramic leads and circuit connections must be as short as possible. Typical values for CL1, CL2 are 10pF for a 16 MHz crystal.

Figure 6.1 illustrates the possible connections.

The clock signal generates two internal clock signals: one for the CPU and one for the peripherals. The CPU clock frequency can be reduced, in order to decrease current consumption, by setting the CPU_CLK Configuration Register 46 (02Eh). The CPU clock can be reduced up to 64 times (see Register Description)

Figure 6.1 Oscillator Connections



6.2 . Reset

Six reset sources are available:

- RESET pin (external source)
- WATCHDOG (internal source)
- POWER ON Reset (Internal source)
- Low Voltage Detector (internal source)
- Power Down Reset (Internal source)
- Programmable Halt Wake-up (Internal source)

When a Reset event occurs, the user program restarts from the beginning.

6.2.1 External Reset. Reset is an input pin. An internal reset does not affect this pin. A Reset signal originated by external sources is recognized immediately. The RESET pin may be used to ensure Vdd has risen to a point where the ICU can operate correctly before the user program is run. Reset must be set to Vdd in working mode.

An internal Pull up resistor guarantees that the RESET pin is at level “1” when no HALT or Power-On events occur.

6.2.2 Power Down Reset (PDR). In order to assure the device has correctly restarted, after the supply voltage has gone below the working level (around 1.75 V typical), the PDR supplies an internal reset of the device. The threshold is fixed in the range 1.7 V -1.85 V (typical: see electrical characteristics). An analog spike filtering of around 10 µs is considered to avoid unwanted resets.

The PDR works also in Wait and Halt modes, assuring a continuous monitoring of the device supply voltage. The PDR can be enabled/disabled with the Option Byte 3 (PLVD_SET) bit 7.

6.2.3 POR & Reset Procedures.

After the Reset pin is set to Vdd or following a Power-On Reset event, a Power Down Reset or a Programmable Halt Wake-up reset (occurred in Halt mode), the device does not start until the external supply voltage has reached a threshold level (typical value Vdd=1.75V, see electrical characteristics) when the PDR releases the reset.

Warning: *If the PDR is off, the POR cannot restart. To make the device restart correctly in this situation, the supply voltage VDD must drop to 0 V before restarting the device.*

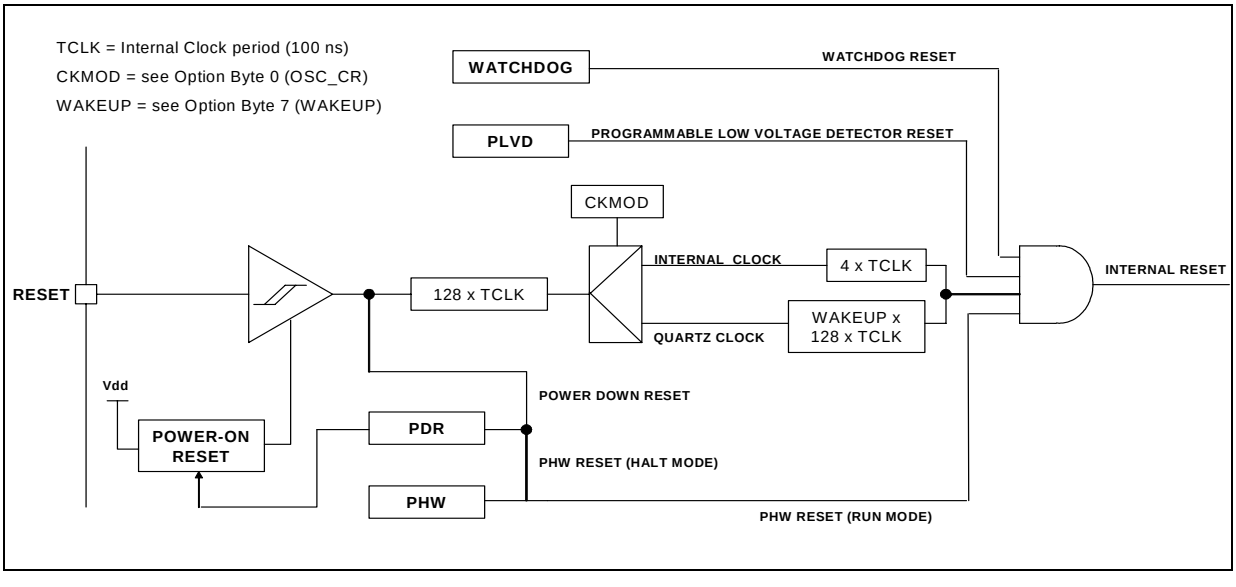
After this level has been reached, the internal oscillator (10 MHz) is started and a delay period of 128 Internal clock cycles (12.8 µs) is initiated, in order to allow the oscillator to stabilize and to ensure that recovery has taken place from the Reset state.

Then, unless an external quartz clock is configured to be used, another short count of 4 Internal clock cycles (400 ns) starts before running the user program.

Otherwise, if an external quartz clock has been configured to be used, the Option Byte 7 (WAKEUP) is read and counting starts before running the user program. The duration of the counting depends on the contents of the Option Byte 7 (WAKEUP), that works as a prescaler, according to the following formula:

$$Delay = 128 \times (WAKEUP + 1) \times Tclk$$

Figure 6.2 Reset Block Diagram



This delay has been introduced in order to ensure that the oscillator has become stable after its restart, when a quartz clock is used.

If the Reset is generated by the Programmable Low Voltage Detector or the Watchdog or the PHW (only in Run mode), the oscillator is not turned off; for this reason the CPU is then restarted immediately, without the delay.

After a RESET procedure is completed, the core reads the instruction stored in the first 3 bytes of the Program/Data Memory, which contains a JUMP instruction to the first instruction of the user program. The Assembler tool automatically generates this Jump instruction with the first instruction address.

6.3 Programmable Low Voltage Detector

The on-chip Programmable Low Voltage Detector (PLVD) circuit generates an interrupt request or a reset if the power supply drops below a configured level. The Reset/Interrupt option can be chosen by setting bit 2 of Option Byte 3 (PLVD_SET).

If the interrupt option is chosen, the PLVD can be started choosing a threshold level by means of the Configuration Register 51 (033h) (PLVD_CR).

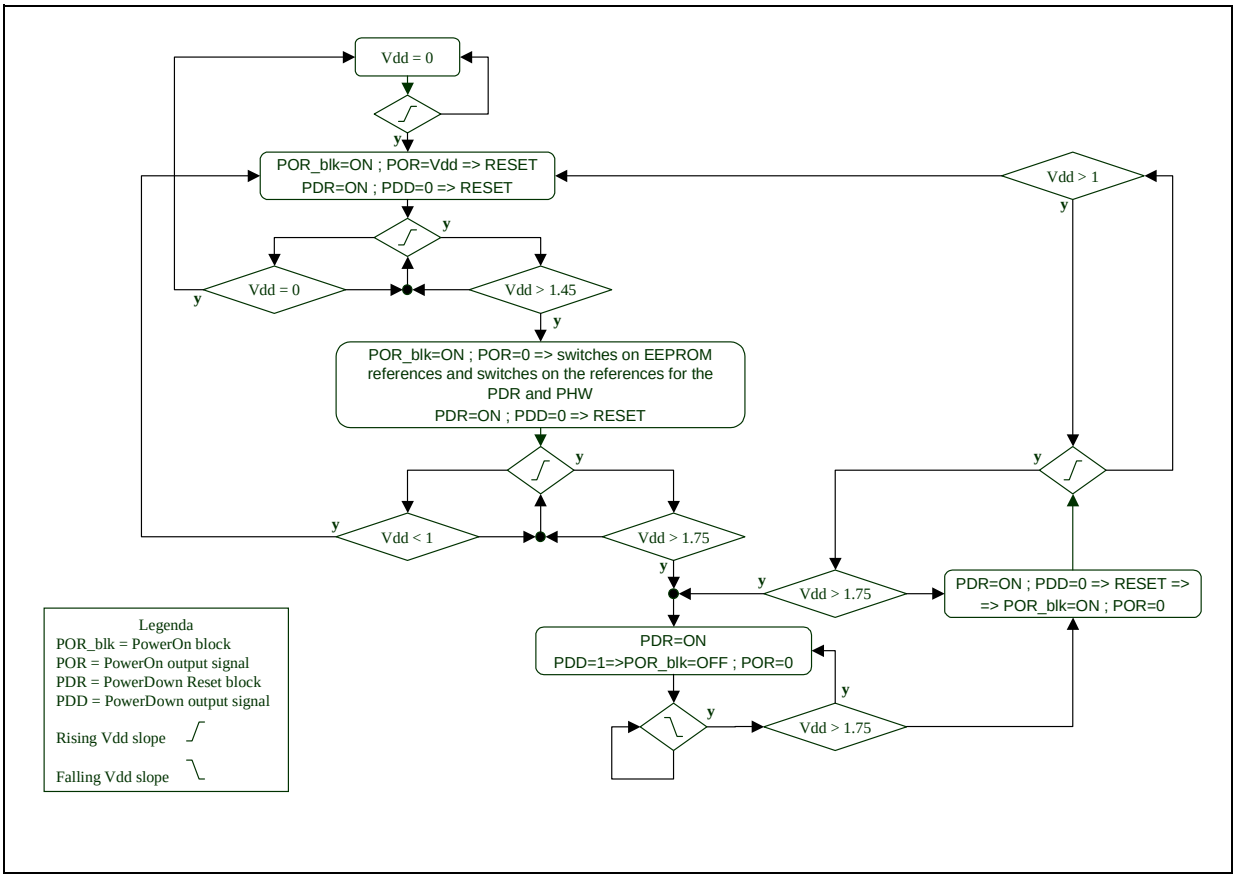
In this case the PLVD can be enabled/disabled and the threshold changed in run time. When Vdd drops below the detection level, the related interrupt is served if enabled and the PLVD status bit 0 (PLVDST) in the PLVD_SR Input Register 57 (039h) is set to '1'. A new interrupt request cannot be generated until the Vdd rises up the trigger level. When the Vdd is above the trigger level the PLVDST bit is '0'.

If the Reset option has been set, the PLVD can be enabled and the threshold can be chosen only at start-up by means of the Option Byte 3 (PLVD_SET) bit 1:0. When the Vdd goes below the detection level, the device reset is generated; the reset is released only after the Vdd rises above the detection level.

There are three levels with hysteresis for the PLVD falling voltages (see Electrical Characteristics). The PLVD circuit will only detect a drop if Vdd voltage stays below the safe threshold for at least 5µs before activation/deactivation of the PLVD in order to filter voltage spikes.

Remark: *the PLVD function isn't active when it is in HALT mode.*

Figure 6.3 Reset procedures flow



6.4 Power Saving modes

There are two types of Power Saving modes: WAIT and HALT mode. These conditions may be entered by using the WAIT or HALT instructions. In Halt mode only the Programmable Halt mode Wake-up peripheral (PHW) can run, thus allowing the exiting from the Halt mode after a programmed time.

6.4.1 Wait Mode. Wait mode places the ICU in a low power consumption status by stopping the CPU. All peripherals and the watchdog remain active. During WAIT mode the Interrupts are enabled. The ICU remains in Wait mode until an Interrupt or a RESET occurs, whereupon the Program Counter jumps to the interrupt service routine or, if a Reset occurs, to the beginning of the user program.

6.4.2 Halt Mode. Halt mode is the lowest ICU power consumption mode, which is entered by executing the HALT instruction. The internal oscillator is turned off, causing all internal processing to be terminated, including the operations of the on-chip peripherals, with the exception of the PHW (see below) and PDR.

Halt mode cannot be used when the watchdog is enabled. If the HALT instruction is executed while the watchdog system is enabled, it will be skipped without modifying the normal CPU operations.

The ICU can exit Halt mode upon reception of an NMI, a Port Interrupt, a PHW interrupt (see below) or a Reset. The internal oscillator (10 MHZ) is started and a delay period of 128 clock cycles (12.8 µs) is initiated, in order to allow the oscillator to stabilize and to ensure that recovery has taken place from the Reset state.

Unless an external quartz clock is configured to be used, another short count of 4 Internal clock cycles (400 ns) starts before running the user program.

Otherwise, if an external quartz clock has been configured to be used, the Option Byte 7 (WAKEUP) is read and another count is started before running the user program. The count duration depends on the contents of the Option Byte 7 (WAKEUP), that works as prescaler, according to the following formula:

$$Delay = 128 \times (WAKEUP + 1) \times Tclk$$

This delay has been introduced in order to ensure that the oscillator has become stable after it is restarted.

After the start up delay, by exiting with the NMI, a Port interrupt or PHW interrupt, the CPU restarts operations by serving the associated interrupt routine.

6.5 Programmable Halt mode Wake-up (PHW)

The PHW is a very low consumption Timer, designed to work even in Halt mode. Its working is based on a low power 32 kHz Internal Clock that drives a counter. The end of count can generate an interrupt or a reset and, if the device is in Halt mode, a wake-up from this state.

The counter can execute a count from 2^6 to 2^{16}, corresponding to a time period from 2 ms to 2 s. Up to six configurable times are possible by setting Configuration Register 52 (034h) PHW_CR. It also allows the enabling/disabling or the selection of the interrupt/reset option (see Register Description). When the PHW_CR is latched, the counting is restarted with the new value.

This peripheral has been designed to operate a wake-up from Halt mode at programmed time; nevertheless it can be used as a normal timer.

Figure 6.4 WAIT Flow Chart

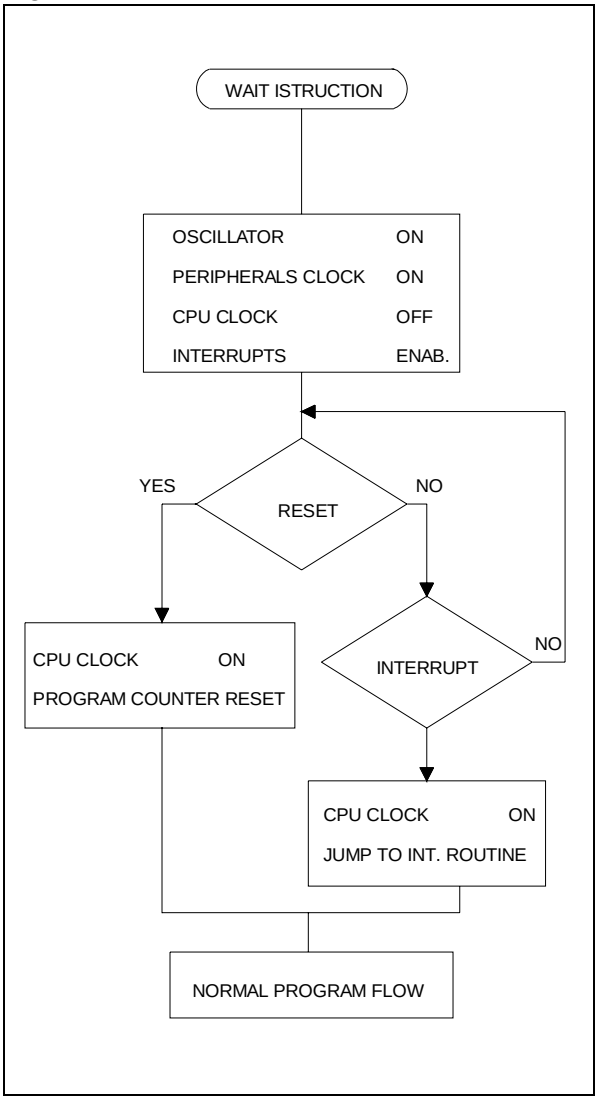
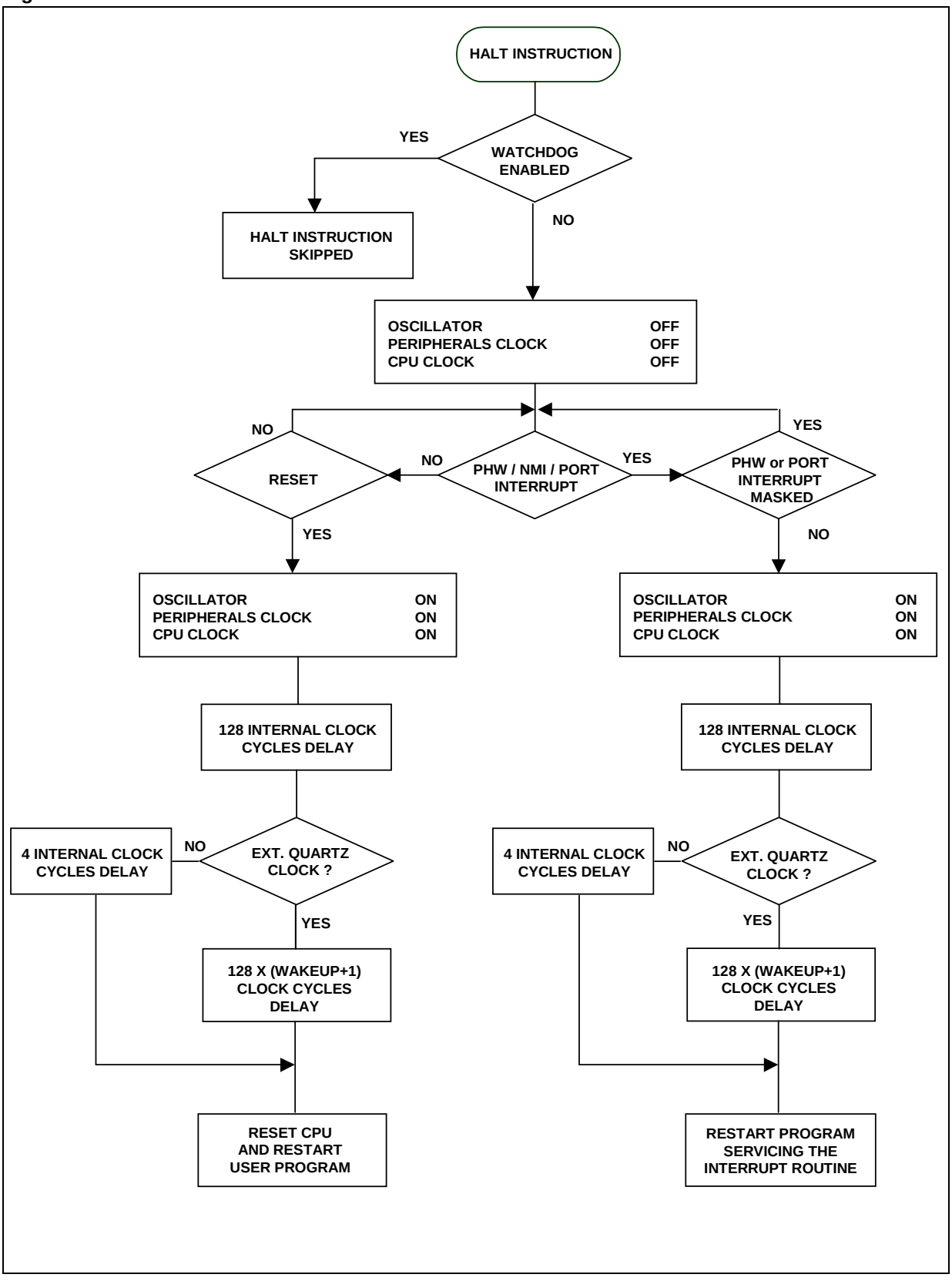


Figure 6.5 HALT Flow Chart



6.6 Register Description

The following section describes the Register which are used to configure the Clock, Reset, PLVD and PHW.

6.6.1 Configuration Register.

CPU Clock Prescaler (CPU_CLK)

Configuration Register 46 (02Eh) Read/Write

Reset Value: 0000 0000 (00h)

7							0
-	-	CPUCK5	CPUCK4	CPUCK3	CPUCK2	CPUCK1	CPUCK0

Bit 7-6: Not Used

Bit 5-0: **CPUCK5-0** CPU Clock Prescaler bits

The CPU Clock frequency is divided by a factor described in the following table

CPUCK5-0	CPU Clock
000000	$f_{CPU}=f_{OSC}$
000001	$f_{CPU}=f_{OSC}/2$
000010	$f_{CPU}=f_{OSC}/4$
000100	$f_{CPU}=f_{OSC}/8$
001000	$f_{CPU}=f_{OSC}/16$
010000	$f_{CPU}=f_{OSC}/32$
100000	$f_{CPU}=f_{OSC}/64$
others	$f_{CPU}=f_{OSC}/64$

PLVD Control Register (PLVD_CR)

Configuration Register 51 (033h) Read/Write

Reset Value: 0000 0000 (00h)

7							0
-	-	-	-	-	-	PLVDI1	PLVDI0

Bit 7-2: Not Used

Bit 1-0: **PLVDI1-0** PLVD interrupt detection levels

00: PLVD disabled

01: Lowest detection level

10: Medium detection level

11: Highest detection level

Remark: *The PLVDI1-0 bits are used only if the PLVD has been configured to generate a interrupt (PVDSEL=1 in PLVD_SET Option Byte), otherwise the PLVDR1-0 of the PLVD_SET Option Byte are used (see below)*

PHW Control Register (PHW_CR)

Configuration Register 52 (034h) Read/Write

Reset Value: 0000 0000 (00h)

7		5					0
PHWEN	PHWSEL	PHWC5	PHWC4	PHWC3	PHWC2	PHWC1	PHWC0

Bit 7: **PHWEN** Programmable Halt Wakeup Enable

0: PHW disabled

1: PHW enabled

Bit 6: **PHWSEL** PHW Action selection

0: PHW generates a Interrupt

1: PHW generates a Reset

Bit 5-0: **PHWC5-0** PHW Counter

000000: Counter = 2^6 ~ 2 ms

000001: Counter = 2^6 ~ 2 ms

000010: Counter = 2^8 ~ 8 ms

000100: Counter = 2^{10} ~ 32 ms

001000: Counter = 2^{12} ~ 128 ms

010000: Counter = 2^{14} ~ 512 ms

100000: Counter = 2^{16} ~ 2 s

Note: *if more than one bit is set in the PHW Counter, only the less significative will be considered. When a new value is latched, the count restarts.*

6.6.2 Option Bytes.

Clock Mode (OSC_CR)

Option Byte 0 (00h)

7							0
-	-	-	-	OSPR1	OSPR0	-	CKMOD

Bit 7-4: Not used

Bit 3-2: **OSPR1-0** Internal Oscillator Prescaler

00: Internal Clock frequency = 10 MHz
01: Internal Clock frequency = 5 MHz
10: Internal Clock frequency = 2.5 MHz
11: Internal Clock frequency = 1.25 MHz

Bit 1: Must be set to 0

Bit 0: **CKMOD** Clock Mode

0: Internal Oscillator
1: External Clock or quartz

External Clock Parameters (CLK_SET)

Option Byte 1 (01h)

7							0
-	-	-	-	-	CKPAR2	CKPAR1	CKPAR0

Bit 7-3: Not Used

Bit 2-0: **CKPAR2-0** Oscillator Gains

These three bits enable/disable the loop gains when a external clock or quartz are used for generating the clock. The following table describes the possible configuration options. Table 6.1 illustrates the recommended values for the most common frequencies used, time to start the oscillations and the settling time to have a duty cycle of 40%-60% (at steady state it is 50%).

CKPAR2-0	Enabled Gain Stages
000	No Gains (External Clock Mode)
001	1 gain stage enabled
010	2 gain stage enabled
011	3 gain stage enabled
100	4 gain stage enabled
101	5 gain stage enabled
110	6 gain stage enabled
111	7 gain stage enabled

Warning: *If an External Clock is used instead of a quartz or ceramic resonator, it is recommended that no gain be enabled (CKPAR2-0=000) in order to lower the current consumption.*

Table 6.1 Recommended Gain Stages for the most common frequencies

Frequency	Recommend Gain Stages (1)	CKPAR2-0	Oscillation Start Times (2)	Settling Times for 60% duty-cycle (2)
External Clock	0	000	-	-
1 MHz	1	001	280	150
5 MHz	2	010	20.4	60
10 MHz	4	100	9.2	11
16 MHz	5	101	187	50

(1) The recommended values have been chosen to have the best trade off between start time and current consumption. Higher gains give shorter Start times; lower gains give less current consumption.

(2) Indicative values by design at 25° Celsius, V_{DD}=1.8 V. Not Tested in production.

Internal Oscillator Calibration (OSC_SET)
Option Byte 2 (02h)

7							0
-	-	OSPAR5	OSPAR4	OSPAR3	OSPAR2	OSPAR1	OSPAR0

Bit 7-6: Not Used

Bit 5-0: **OSPAR5-0** Internal Oscillator Parameters
These bits are used in order to calibrate the precision of the internal oscillator working at 10 MHz. The six bits enable some current generators with steps of 0.05 µA corresponding to interval of frequency of 100KHz.

Warning: *the maximum configuration value allowed is 101000 (40). The value corresponding to the 10 MHz by design is 010100 (20). Loading values over 40 the oscillator is stopped.*

PLVD & PDR Setup Register (PLVD_SET)
Option Byte 3 (03h)

7							0
PDREN	-	-	-	-	PLVDSEL	PLVDR1	PLVDR0

Bit 7: **PDREN** Power Down Reset Enable
0: PDR disabled
1: PDR enabled

Bit 6-3: Not Used

Bit 2: **PLVDSEL** PLVD Action selection
0: PLVD generates a Reset
1: PLVD generates a Interrupt

Bit 1-0: **PLVDR1-0** PLVD detection levels for reset
00: PLVD disabled
01: Lowest detection level
10: Medium detection level
11: Highest detection level

Remark: *The PLVDR1-0 bits are used only if the PLVD has been configured to generate a reset (PVDSEL=0), otherwise the PLVDI1-0 of the PLVD_CR configuration register are used (see above)*

Wake-Up Time Prescaler (WAKEUP)
Option Byte 7 (07h)

7							0
WK7	WK6	WK5	WK4	WK3	WK2	WK1	WK0

Bit 7-0: **WK7-0** Wake-up prescaler
This byte determinates the time delay for the stabilization of the oscillator after an External Reset or a POR and after the wake-up from Halt. The time delay is computed according to the following formula:

$$Delay = 128 \times (WAKEUP + 1) \times Tclk$$

Warning: *If the internal clock is used as clock source the prescaler is not used.*

6.6.3 Input Registers.

IAP Status Register (IAP_SR)
Input Register 40 (028h) Read only
Reset Value: 0000 0000 (00h)

7							0
PLVDST	-	-	-	-	-	PRTCD	ABRT

Bit 7: **PLVDST** PLVD Status Register
0: Vdd below the current PLVD threshold
1: Vdd above the current PLVD threshold

Bit 6-2: Not used

Bit 1-0: See EEPROM Input Register paragraph

7 I/O PORTS

7.1 Introduction

ST52F501L/F502L are characterized by flexible individually programmable multi-functional I/O lines. The ST52F501L/F502L supplies devices with up to 3 Ports (named from A to C) with up to 24 I/O lines.

Each pin can be used as a digital I/O or can be connected with a peripheral (Alternate Function). The I/O lines belonging to Port A and Port B can also be used to generate Port Interrupts.

The I/O Port pins can be configured in the following modes:

- Input high impedance (reset state)
- Input with pull-up
- Output with pull-up
- Output push-pull
- Output with weak pull-up
- Output open drain
- Interrupt with pull-up
- Interrupt without pull-up

These eight modes can be selected by programming three Configuration Registers for each Port. All the pins that belong to the same Port can be configured separately by setting the corresponding bits in the three registers (see Register Description).

To avoid side effects, the Configuration Registers are latched only when the Data Direction Register (PORT_x_DDR) is written. For this reason this register must be always written when modifying the pin configuration.

All the I/O digital pins have a Schmitt Trigger. The output buffer can supply high current sink (up to 8mA).

Note: *With the aim to reduce current consumption it is recommended that no floating pins are left; all unused pins must be kept at fixed voltage. Furtehrmore it is recommended that bits of IO Configuration Registers related to not used or non available port/pins are set as Input Pull-Up.*

7.2 Input Mode

The pins configured as input can be read by accessing the corresponding Port Input Register by means of the LDRI instruction. The addresses for Port A, B and C are respectively 0 (00h), 1 (01h), and 2 (02h).

When executing the LDRI instruction all the signals connected to the input pins of the Port are read and the logical value is copied in the specified Register File location. If some pins are configured in output, the port buffer contents, which are the last written logical values in the output pins, are read.

7.3 Output Mode

The pins configured as output can be written by accessing the corresponding Port Output Register by means of the LDPR, LDPI and LDPE instructions. The addresses for Port A, B and C are respectively, 0 (00h), 1 (01h), and 2 (02h).

When executing the above mentioned instructions, the Port buffer is written and the Port pin signals are modified. If some pins are configured as input or as interrupt, the values are ignored.

7.4 Interrupt Mode

The pins configured as Interrupt Mode can generate a Port Interrupt request. One Interrupt vector is associated to Port A and one to Port B and C. More pins of the ports can act as source at the same time. The Configuration Registers switch the signals deriving from interrupt pins to an OR gate that generates the interrupt request signal. The signal deriving from the pins can be read, allowing the discrimination of the interrupt sources when more than one pin can generate the interrupt signal.

The interrupt trigger can be configured either in the rising or falling edge of the external signal by using the INT_POL register..

7.5 Alternate Functions

The Alternate Function allows the pins to be connected with the peripheral signals or NMI. Not all Port pins have an Alternate Function associated.

A Configuration Register (PORT_x_AF) for each Port is used to switch from the Digital I/O function or the Alternate Function.

NMI is considered an Alternate Function. For this reason an NMI interrupt request can't be generated unless the PA7 pin is configured in Alternate Function and in one of the Input modes.

When an on-chip peripheral is configured to use a pin, the correct I/O mode of the related pin should be selected by selecting one of the appropriate modes. See the Registers description in order to obtain the right configurations.

Some peripherals, as for example the I^2C peripheral, directly drive the pin configuration according to the current function, overriding the user configuration.

Figure 7.1 Digital Pin

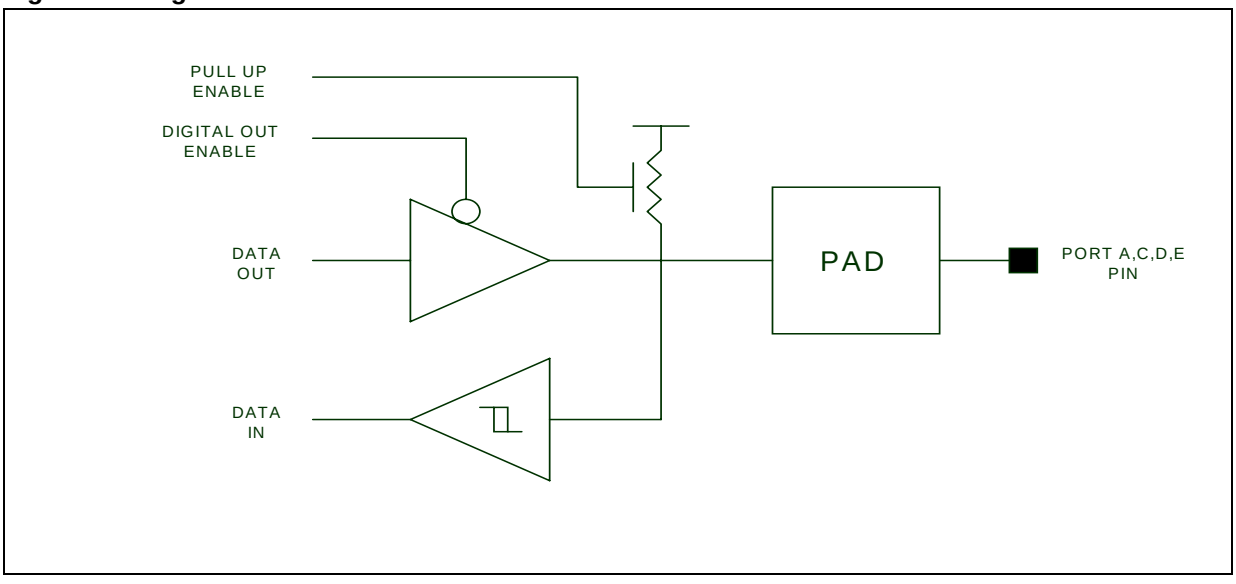
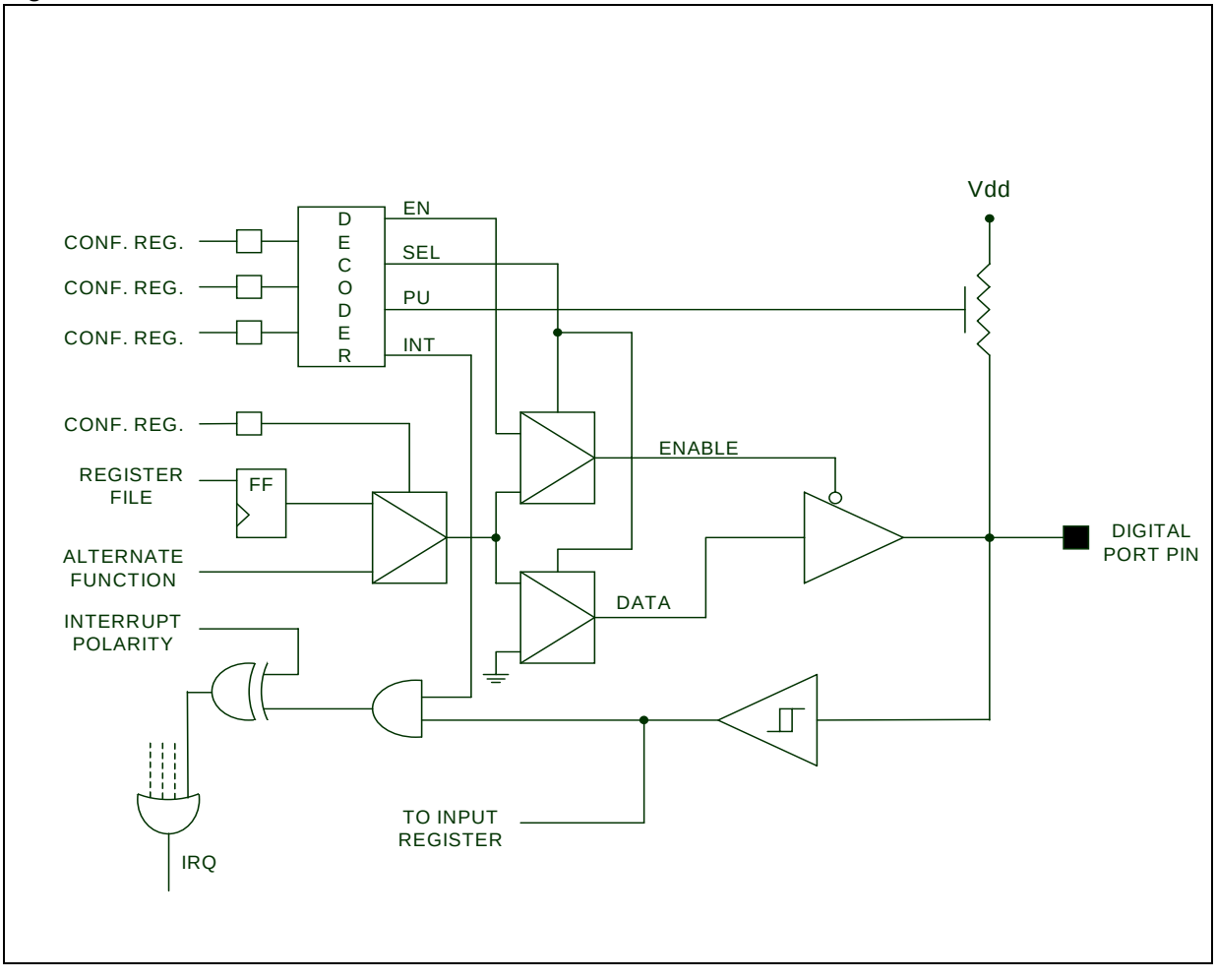


Figure 7.2 Port Pin Architecture



7.6 Register Description

In order to configure the Port's pins, the three Configuration Registers PORT_x_PULLUP, PORT_x_OR and PORT_x_DDR must be configured. The combination of these three registers determine the pin's configuration, according to the scheme shown in Table 7.1.

In order to select between the digital functions or Alternate functions PORT_x_AF register must be configured. Each bit of the configuration registers configures the pin of the corresponding position (example: PORT_A_DDR bit 5 configures the pin PA5).

7.6.1 Configuration Registers.

Port A Pull-Up Register (PORT_A_PULLUP)
Configuration Register 24 (018h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
PUA7	PUA6	PUA5	PUA4	PUA3	PUA2	PUA1	PUA0

Bit 7-0: **PUA7-0** Port A pull-up (see Table 7.1)
0: Port A pin without pull-up
1: Port A pin with pull-up

Port A Option Register (PORT_A_OR)
Configuration Register 25 (019h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
ORA7	ORA6	ORA5	ORA4	ORA3	ORA2	ORA1	ORA0

Bit 7-0: **ORA7-0** Port A option (see Table 7.1)

Port A Data Direction Register (PORT_A_DDR)
Configuration Register 26 (01Ah) Read/Write
Reset Value: 0000 0000 (00h)

7							0
DDRA7	DDRA6	DDRA5	DDRA4	DDRA3	DDRA2	DDRA1	DDRA0

Bit 7-0: **DDRA7-0** Port A direction (see Table 7.1)
0: Port A pin configured as input
1: Port A pin configured as output

Port A Alternate Function (PORT_A_AF)
Configuration Register 27 (01Bh) Read/Write
Reset Value: 0000 0000 (00h)

7							0
AFA7	AFA6	AFA5	AFA4	AFA3	AFA2	AFA1	AFA0

Bit 7: **AFA7** Alternate Function PA7
0: Digital I/O
1: INT

Bit 6: **AFA6** Alternate Function PA6
0: Digital I/O
1: T0OUT

Bit 5: **AFA5** Alternate Function PA5
0: Digital I/O
1: TCLK, TX

Bit 4: **AFA4** Alternate Function PA4
0: Digital I/O
1: TSTRT

Bit 3: **AFA3** Alternate Function PA3
0: Digital I/O
1: RX

Bit 2: **AFA2** Alternate Function PA2
0: Digital I/O
1: T1OUT

Bit 1: **AFA1** Alternate Function PA1
0: Digital I/O
1: SDA

Bit 0: **AFA0** Alternate Function PA0
0: Digital I/O
1: SCL

Table 7.1 Pin mode configuration

MODE	PU	OR	DDR
Input high impedance	0	0	0
Input with pull-up	1	0	0
Interrupt without pull-up	0	1	0
Interrupt with pull-up	1	1	0
Output push-pull	0	0	1
Output with pull-up	1	0	1
Output open drain	0	1	1
Output weak pull-up	1	1	1

Port B Pull-Up Register (PORT_B_PULLUP)

Configuration Register 28 (01Ch) Read/Write
Reset Value: 0000 0000 (00h)

7							0
PUB7*	PUB6*	PUB5	PUB4	PUB3	PUB2	PUB1	PUB0

(*) Pin not available in 20 pin package devices. Set to '1'

Bit 7-0: **PUB7-0** Port B pull-up (see Table 7.1)
0: Port B pin without pull-up
1: Port B pin with pull-up

Port B Option Register (PORT_B_OR)

Configuration Register 29 (01Dh) Read/Write
Reset Value: 0000 0000 (00h)

7							0
ORB7*	ORB6*	ORB5	ORB4	ORB3	ORB2	ORB1	ORB0

(*) Pin not available in 20 pin package devices. Set to '0'

Bit 7-0: **ORB7-0** Port B option (see Table 7.1)

Port B Data Direction Register (PORT_B_DDR)

Configuration Register 30 (01Eh) Read/Write
Reset Value: 0000 0000 (00h)

7							0
DDRB7*	DDRB6*	DDRB5	DDRB4	DDRB3	DDRB2	DDRB1	DDRB0

(*) Pin not available in 20 pin package devices. Set to '0'

Bit 7-0: **DDRB7-0** Port B direction (see Table 7.1)
0: Port B pin configured as input
1: Port B pin configured as output

Port B Alternate Function (PORT_B_AF)

Configuration Register 31 (01Fh) Read/Write
Reset Value: 0000 0000 (00h)

7							0
AFB7*	AFB6*	AFB5	AFB4	AFB3	AFB2	AFB1	AFB0

(*) Not used in 20 pin package devices

Bit 7: **AFB7** Alternate Function PB7
0: Digital I/O
1: T1OUT

Bit 6: **AFB6** Alternate Function PB6
0: Digital I/O
1: T0OUT

Bit 5: **AFB5** Alternate Function PB5
0: Digital I/O
1: TCLK

Bit 4: **AFB4** Alternate Function PB4
0: Digital I/O
1: TRES

Bit 3: **AFB3** Alternate Function PB3
0: Digital I/O
1: SS

Bit 2: **AFB2** Alternate Function PB2
0: Digital I/O
1: MISO

Bit 1: **AFB1** Alternate Function PB1
0: Digital I/O
1: MOSI

Bit 0: **AFB0** Alternate Function PB0
0: Digital I/O
1: SCK

Port C Pull-Up Register (PORT_C_PULLUP)

Configuration Register 32 (020h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
PUC7*	PUC6*	PUC5	PUC4	PUC3	PUC2	PUC1	PUC0

(*) Pin not available in 28 pin package devices. Set to '1'

Note: *The corresponding pins are not available in 20 pin devices.*

Bit 7-0: **PUC7-0** Port C pull-up (see Table 7.1)
0: Port C pin without pull-up
1: Port C pin with pull-up

Port C Option Register (PORT_C_OR)

Configuration Register 33 (021h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
ORC7*	ORC6*	ORC5	ORC4	ORC3	ORC2	ORC1	ORC0

(*) Pin not available in 28 pin package devices. Set to '0'

Note: *The corresponding pins are not available in 20 pin devices.*

Bit 7-0: **ORC7-0** Port C option (see Table 7.1)

Port C Data Direction Register (PORT_C_DDR)

Configuration Register 34 (022h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
DDRC7*	DDRC6*	DDRC5	DDRC4	DDRC3	DDRC2	DDRC1	DDRC0

(*) Pin not available in 28 pin package devices. Set to '0'

Note: *The corresponding pins are not available in 20 pin devices.*

Bit 7-0: **DDRC7-0** Port C direction (see Table 7.1)
0: Port C pin configured as input
1: Port C pin configured as output

Port C Alternate Function (PORT_C_AF)

Configuration Register 35 (023h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
-	-	AFB5	AFB4	-	-	-	-

Note: *The corresponding pins are not available in 20 pin devices.*

Bit 7-6: Not Used

Bit 5: **AFC5** Alternate Function PC5
0: Digital I/O
1: TRES

Bit 4: **AFC4** Alternate Function PC4
0: Digital I/O
1: TX

Bit 3: **AFC3** Alternate Function PC3
0: Digital I/O
1: SS

Bit 2: **AFC2** Alternate Function PC2
0: Digital I/O
1: MISO

Bit 1: **AFC1** Alternate Function PC1
0: Digital I/O
1: MOSI

Bit 0: **AFC0** Alternate Function PC0
0: Digital I/O
1: SCK

Note: *in order to achieve low current consumption, the port pins must be configured as input pull-up, even though they are not existing in the package. For example in 20 pin devices, the pins PB6-7 and PC0-7 must be configured in input pull-up.*

7.6.2 Input Registers.

Port A Data Input Register (PORT_A_IN)
Input Register 0 (00h) Read only
Reset Value: XXXX XXXX

7							0
PAI7	PAI6	PAI5	PAI4	PAI3	PAI2	PAI1	PAI0

Bit 7-0: **PAI7-0** Port A Input data

The logical level applied in the Port A pins, configured as digital input, can be achieved by reading this register.

Port B Data Input Register (PORT_B_IN)
Input Register 1 (01h) Read only
Reset Value: XXXX XXXX

7							0
P**BI**7*	PBI6*	PBI5	PBI4	PBI3	PBI2	PBI1	PBI0

(*) Not used in 20 pin package devices

Bit 7-0: **PBI7-0** Port B Input data

The logical level applied in the Port B pins, configured as digital input, can be achieved by reading this register.

Port C Data Input Register (PORT_C_IN)
Input Register 2 (02h) Read only
Reset Value: XXXX XXXX

7							0
PCI7*	PCI6*	PCI5	PCI4	PCI3	PCI2	PCI1	PCI0

(*) Not used in 28 pin package devices

Note: *This register is not used in 20 pin devices*

Bit 7-0: **PCI7-0** Port C Input data

The logical level applied in the Port C pins, configured as digital input, can be achieved by reading this register.

7.6.3 Output Registers.

Port A Data Output Register (PORT_A_OUT)
Output Register 0 (00h) Write only
Reset Value: 0000 0000 (00h)

7							0
PAO7	PAO6	PAO5	PAO4	PAO3	PAO2	PAO1	PAO0

Bit 7-0: **PAO7-0** Port A Output data

The logical values written in these register bits are put in the Port A pins configured as digital output.

Port B Data Output Register (PORT_B_OUT)
Output Register 1 (01h) Write only
Reset Value: 0000 0000 (00h)

7							0
P**BO**7*	PBO6*	PBO5	PBO4	PBO3	PBO2	PBO1	PBO0

(*) Not used in 20 pin package devices

Bit 7-0: **PBO7-0** Port B Input data
The logical values written in these register bits are put in the Port B pins configured as digital output.

Port C Data Output Register (PORT_C_OUT)
Output Register 2 (02h) Write only
Reset Value: 0000 0000 (00h)

7							0
PCO7*	PCO6*	PCO5	PCO4	PCO3	PCO2	PCO1	PCO0

(*) Not used in 28 pin package devices

Note: *This register is not used in 20 pin devices*

Bit 7-0: **PCO7-0** Port C Input data

The logical values written in these register bits are put in the Port C pins configured as digital output.

8 FUZZY COMPUTATION (DP)

The ST52F501L/F502L Decision Processor (DP) main features are:

- Up to 8 Inputs with 8-bit resolution;
- 1 Kbyte of Program/Data Memory available to store more than 300 to Membership Functions (Mbfs) for each Input;
- Up to 128 Outputs with 8-bit resolution;
- Possibility of processing fuzzy rules with an UNLIMITED number of antecedents;
- UNLIMITED number of Rules and Fuzzy Blocks.

The limits on the number of Fuzzy Rules and Fuzzy program blocks are only related to the Program/Data Memory size.

8.1 Fuzzy Inference

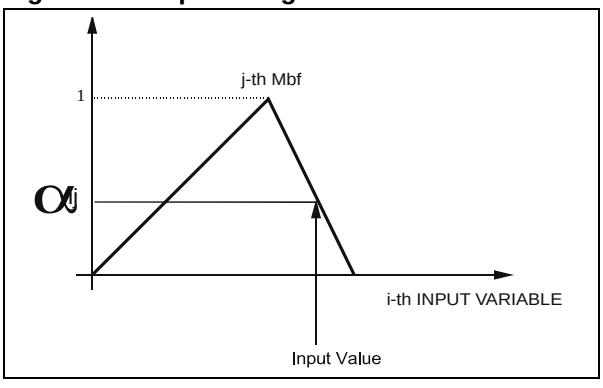
The block diagram shown in Figure 8.1 describes the different steps performed during a Fuzzy algorithm. The ST52F501L/F502L Core allows for the implementation of a Mamdami type fuzzy inference with crisp consequents. Inputs for fuzzy inference are stored in 8 dedicated Fuzzy input registers. The LDFR instruction is used to set the Input Fuzzy registers with values stored in the Register File. The result of a Fuzzy inference is stored directly in a location of the Register File.

8.2 Fuzzyfication Phase

In this phase the intersection (alpha weight) between the input values and the related Mbfs (Figure 8.2) is performed.

Eight Fuzzy Input registers are available for Fuzzy inferences.

Figure 8.2 Alpha Weight Calculation



After loading the input values by using the LDFR assembler instruction, the user can start the fuzzy inference by using the FUZZY assembler instruction. During fuzzyfication: input data is transformed in the activation level (alpha weight) of the Mbf's.

8.3 Inference Phase

The Inference Phase manages the alpha weights obtained during the fuzzyfication phase to compute the truth value (ω) for each rule.

This is a calculation of the maximum (for the OR operator) and/or minimum (for the AND operator) performed on alpha values according to the logical connectives of Fuzzy Rules.

Several conditions may be linked together by linguistic connectives AND/OR, NOT operators and brackets.

The truth value ω and the related output singleton are used by the Defuzzyfication phase, in order to complete the inference calculation.

Figure 8.1 Fuzzy Inference

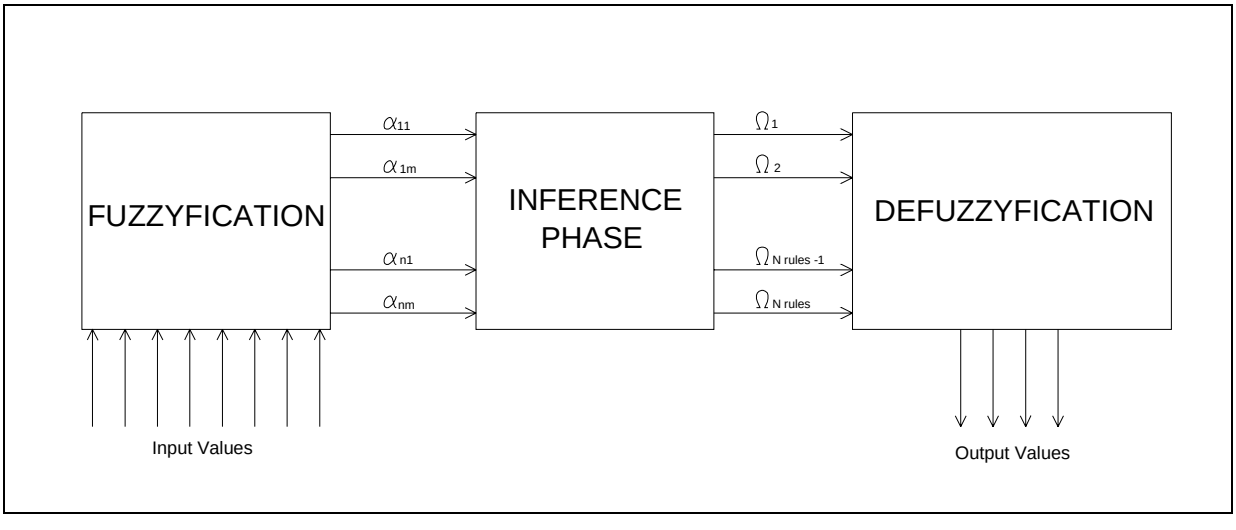
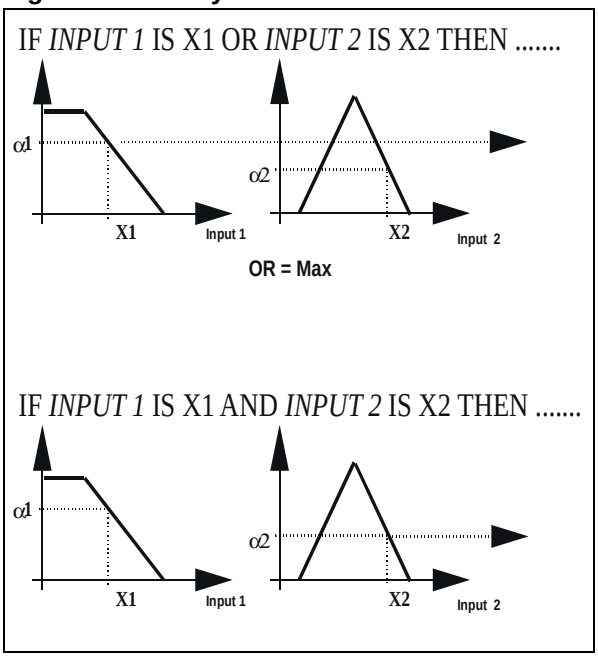


Figure 8.3 Fuzzyfication



8.4 Defuzzyfication

In this phase the output crisp values are determined by implementing the consequent part of the rules.

Each consequent Singleton X_i is multiplied by its weight values ω_i, calculated by the Decision processor, in order to compute the upper part of the Defuzzyfication formula.

Each output value is obtained from the consequent crisp values (X_i) by carrying out the following Defuzzyfication formula:

$$Y_i = \frac{\sum_{j}^{N} X_{ij}\omega_{ij}}{\sum_{j} \omega_{ij}}$$

where:

i = identifies the current output variable

N = number of the active rules on the current output

ω_{ij} = weight of the j-th singleton

X_{ij} = abscissa of the j-th singleton

The Decision Processor outputs are stored in the RAM location i-th specified in the assembler instruction OUT i.

8.5 Input Membership Function

The Decision Processor allows the management of triangular Mbfs. In order to define an Mbf, three different parameters must be stored on the Program/Data Memory (see Figure 8.4):

- the vertex of the Mbf: **V**;
- the length of the right semi-base: **RVD**;
- the length of the left semi-base: **LVD**;

In order to reduce the size of the memory area and the computational effort the vertical range of the vertex is fixed between 0 and 15 (4 bits)

By using the previous memorization method different kinds of triangular Membership Functions may be stored. Figure 8.5 shows some examples of valid Mbfs that can be defined in ST52F501L/F502L.

Each Mbf is then defined storing 3 bytes in the first Kbyte of the Program/Data Memory.

The Mbf is stored by using the following instruction:

MBF *n_mbf lvd v rvd*

where:

n_mbf is a tag number that identifies the Mbf

lvd, *v*, and *rvd* are the parameters that describe the Mbf's shape as described above.

Figure 8.4 Mbfs Parameters

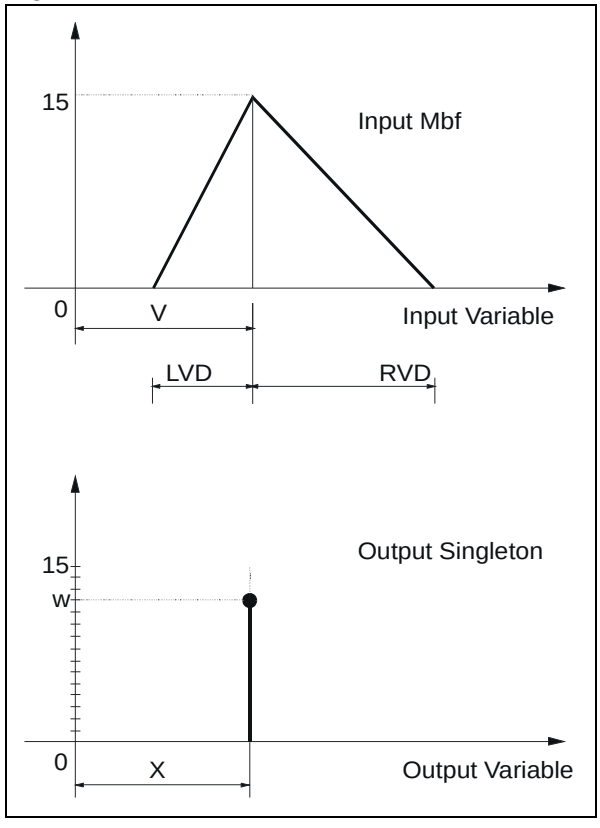


Figure 8.5 Example of valid Mbfs

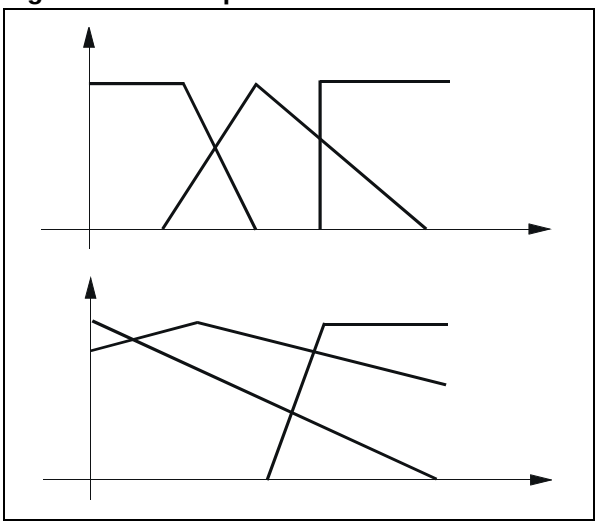
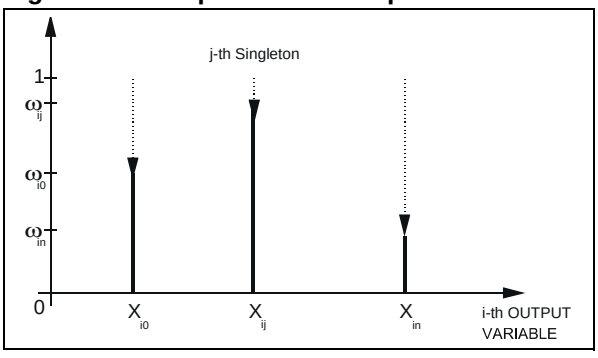


Figure 8.6 Output Membership Functions



8.6 Output Singleton

The Decision Processor uses a particular kind of membership function called Singleton for its output variables. A Singleton doesn't have a shape, like a traditional Mbf, and is characterized by a single point identified by the couple (X, w), where w is calculated by the Inference Unit as described earlier. Often, a Singleton is simply identified with its Crisp Value X.

8.7 Fuzzy Rules

Rules can have the following structures:

if A op B op C.....then Z

if (A op B) op (C op D op E...) .....then Z

where *op* is one of the possible linguistic operators (AND/OR)

In the first case the rule operators are managed sequentially; in the second one, the priority of the operator is fixed by the brackets.

Each rule is codified by using an instruction set, the inference time for a rule with 4 antecedents and 1 consequent is about 3 microseconds at 20 MHz.

The Assembler Instruction Set used to manage the Fuzzy operations is reported in the table below.

Table 8.1 Fuzzy Instructions Set

Instruction	Description
MBF *n_mbf lvd v rvd*	Stores the Mbf *n_mbf* with the shape identified by the parameters *lvd*, *v* and *rvd*
IS *n m*	Fixes the alpha value of the input n with the Mbf m
ISNOT *n m*	Calculates the complementary alpha value of the input n with the Mbf m.
FZAND	Implements the Fuzzy operation AND
FZOR	Implements the Fuzzy operation OR
CON *crisp*	Multiplies the crisp value with the last ω weight
OUT *n_out*	Performs Defuzzyfication and stores the currently Fuzzy output in the register *n_out*
FUZZY	Starts the computation of a single fuzzy variable
( )	Modify the priority in the rule evaluation

Example 1:

IF Input$_1$ IS NOT Mbf$_1$ AND Input$_4$ is Mbf$_{12}$ OR Input$_3$ IS Mbf$_8$ THEN Crisp$_1$

is codified by the following instructions:

ISNOT 1 1	calculates the NOT α value of Input$_1$ with Mbf$_1$ and stores the result in internal registers
FZAND	implements the operation AND between the previous and the next alpha value evaluated
IS 4 12	fixes the α value of Input$_4$ with Mbf$_{12}$ and stores the result in internal registers
FZOR	implements the operation OR between the previous and the next alpha value evaluated
IS 3 8	fixes the α value of Input$_3$ with Mbf$_8$ and stores the result in internal registers
CON *crisp$_1$*	multiplies the result of the last Ω operation with the crisp value *crisp$_1$*

Example 2, the priority of the operator is fixed by the brackets:

IF (Input$_3$ IS Mbf$_1$ AND Input$_4$ IS NOT Mbf$_{15}$) OR (Input$_1$ IS Mbf$_6$ OR Input$_6$ IS NOT Mbf$_{14}$) THEN Crisp$_2$

(	parenthesis open to change the priority
IS 3 1	fixes the α value of Input$_3$ with Mbf$_1$ and stores the result in internal registers
FZAND	implements the operation AND between the previous and the next alpha value evaluated
ISNOT 4 15	calculates the NOT α value of Input$_4$ with Mbf$_{15}$ and stores the result in internal registers
)	parenthesis closed
FZOR	implements the operation OR between the previous and the next alpha value evaluated
(	parenthesis open to change the priority
IS 1 6	fixes the α value of Input$_1$ with Mbf$_6$ and stores the result in internal registers
FZOR	implements the operation OR between the previous and the next alpha value evaluated
ISNOT 2 14	calculates the NOT α value of Input$_6$ with Mbf$_{14}$ and stores the result in internal registers
)	parenthesis closed
CON *crisp$_2$*	multiplies the result of the last Ω operation with the crisp value *crisp$_2$*

At the end of the fuzzy rules related to the current Fuzzy Variable, by using the instruction **OUT *reg***, the specified register is written with the computed value. Afterwards, the control of the algorithm returns to the CU. The next Fuzzy Variable evaluation must start again with a FUZZY instruction.

9 INSTRUCTION SET

ST52F501L/F502L supplies 107 (98 + 9 Fuzzy) instructions that perform computations and control the device. Computational time required for each instruction consists of one clock pulse for each Cycle plus 2 clock pulses for the decoding phase. Total computation time for each instruction is reported in Table 9.1

The ALU of ST52F501L/F502L can perform multiplication (MULT) and division (DIV). Multiplication is performed by using 8 bit operands storing the result in 2 registers (16 bit values), see Figure 2.3.

Division is performed between a 16 bit dividend and an 8 bit divider, the result and the remainder are stored in two 8-bit registers (see Figure 2.4).

9.1 Addressing Modes

ST52F501L/F502L instructions allow the following addressing modes:

- Inherent: this instruction type does not require an operand because the opcode specifies all the information necessary to carry out the instruction. Examples: NOP, SCF.
- Immediate: these instructions have an operand as a source immediate value. Examples: LDRC, ADDI.
- Direct: the operands of these instructions are specified with the direct addresses. The operands can refer (according to the opcode) to addresses belonging to the different addressing spaces. Example: SUB, LDRE.
- Indirect: data addresses that are required are found in the locations specified as operands. Both source and/or destination operands can be addressed indirectly. The operands can refer, (according to the opcode) to addresses belonging to different addressing spaces. Examples: LDRR(reg1),(reg2);
  LDER mem_addr,(reg1).
- Bit Direct: operands of these instructions directly address the bits of the specified Register File locations. Examples: BSET, BTEST.

9.2 Instruction Types

ST52F501L/F502L supplies the following instruction types:

- Load Instructions
- Arithmetic and Logic Instructions
- Bitwise instructions
- Jump Instructions
- Interrupt Management Instructions
- Control Instructions

The instructions are listed in Table 9.1

Table 9.1 Instruction Set

Load Instructions						
Mnemonic	**Instruction**	**Bytes**	**Cycles**	**Z**	**S**	**C**
BLKSET	BLKSET const	2	(*)	-	-	-
GETPG	GETPG regx	2	7	-	-	-
LDCE	LDCE confx,memy	3	8/10	-	-	-
LDCI	LDCI confx, const	3	7	-	-	-
LDCNF	LDCNF regx, conf	3	7	-	-	-
LDCR	LDCR confx, regy	3	8	-	-	-
LDER	LDER memx, regy	3	11	-	-	-
LDER	LDER (regx),(regy)	3	12	-	-	-
LDER	LDER (regx), regy	3	11	-	-	-
LDER	LDER memx,(regy)	3	12	-	-	-
LDFR	LDFR fuzzyx, regy	3	8	-	-	-

Load Instructions (continued)						
LDPE	LDPE outx, memy	3	8/10	-	-	-
LDPE	LDPE outx, (regy)	3	9/11	-	-	-
LDPI	LDPI outx, const	3	7	-	-	-
LDPR	LDPR outx, regy	3	8	-	-	-
LDRC	LDRC regx, const	3	7	-	-	-
LDRE	LDRE regx, memy	3	8/10	-	-	-
LDRE	LDRE (regx), (regy)	3	10/12	-	-	-
LDRE	LDRE (regx), memy	3	9/11	-	-	-
LDRE	LDRE regx, (regy)	3	9/11	-	-	-
LDRI	LDRI regx, inpx	3	7	-	-	-
LDRR	LDRR regx, regy	3	9	-	-	-
LDRR	LDRR (regx), (regy)	3	10	-	-	-
LDRR	LDRR (regx), regy	3	9	-	-	-
LDRR	LDRR regx, (regy)	3	10	-	-	-
PGSET	PGSET const	2	4	-	-	-
PGSETR	PGSETR regx	2	5	-	-	-
POP	POP regx	2	7	-	-	-
PUSH	PUSH regx	2	8	-	-	-

Arithmetic Instructions						
Mnemonic	**Instruction**	**Bytes**	**Cycles**	**Z**	**S**	**C**
ADD	ADD regx, regy	3	9	I	-	I
ADDC	ADDC regx, regy	3	9	I	-	I
ADDI	ADDI regx, const	3	8	I	-	I
ADDIC	ADDIC regx, const	3	8	I	-	I
ADDO	ADDO regx, regy	3	11	I	I	I
ADDOC	ADDOC regx, regy	3	11	I	I	I
ADDOI	ADDOI regx, const	3	10	I	I	I
ADDOIC	ADDOICregx,cons	3	10	I	I	I
AND	AND regx, regy	3	9	I	-	-
ANDI	ANDI regx,const	3	8	I	-	-
CP	CP regx, regy	3	8	I	I	-
CPI	CPI regx,const	3	7	I	I	-
DEC	DEC regx	2	7	I	I	-

Arithmetic Instructions (continued)						
DIV	DIV regx, regy	3	16	I	I	I
INC	INC regx	2	7	I	-	I
MIRROR	MIRROR regx	2	7	I	-	-
MULT	MULT regx, regy	3	11	I	-	-
NOT	NOT regx	2	7	I	-	-
OR	OR regx, regy	3	9	I	-	-
ORI	ORI regx, const	3	8	I	-	-
SUB	SUB regx, regy	3	9	I	I	-
SUBI	SUBI regx, const	3	8	I	I	-
SUBIS	SUBIS regx, const	3	8	I	I	-
SUBO	SUBO regx, regy	3	11	I	I	I
SUBOI	SUBOI regx,	3	10	I	I	I
SUBOIS	SUBOISregx,const	3	10	I	I	I
SUBOS	SUBOS regx, regy	3	11	I	I	I
SUBS	SUBS regx, regy	3	9	I	I	-
RCF	RCF	1	4	-	-	I
RSF	RSF	1	4	-	I	-
RZF	RZF	1	4	I	-	-
SCF	SCF	1	4	-	-	I
SSF	SSF	1	4	-	I	-
SZF	SZF	1	4	I	-	-
XOR	XOR regx, regy	3	9	I	-	-
XORI	XORI regx, cons	3	8	I	-	-

Bitwise Instructions						
Mnemonic	**Instruction**	**Bytes**	**Cycles**	**Z**	**S**	**C**
ASL	ASL regx	2	7	I	-	I
ASR	ASR regx	2	7	I	I	-
BNOT	BNOT regx, bit	3	8	I	-	-
BRES	BRES regx, bit	3	8	I	-	-
BSET	BSET regx, bit	3	8	I	-	-
BTEST	BTEST regx, bit	3	7	I	-	-
MTEST	MTEST regx,const	3	7	I	-	-
RLC	RLC regx	2	7	I	-	I

Bitwise Instructions (continued)						
ROL	ROL regx	2	7	I	-	I
ROR	ROR regx	2	7	I	I	-
RRS	RRS regx	2	7	I	I	-

Jump Instructions						
Mnemonic	**Instruction**	**Bytes**	**Cycles**	**Z**	**S**	**C**
CALL	CALL addr	3	11	-	-	-
JP	JP addr	3	6	-	-	-
JPC	JPC addr	3	5/6	-	-	-
JPNC	JPNC addr	3	5/6	-	-	-
JPNS	JPNS addr	3	5/6	-	-	-
JPNZ	JPNZ addr	3	5/6	-	-	-
JPS	JPS addr	3	5/6	-	-	-
JPZ	JPZ addr	3	5/6	-	-	-
RET	RET	1	8	-	-	-

Interrupt Management Instructions						
Mnemonic	**Instruction**	**Bytes**	**Cycles**	**Z**	**S**	**C**
HALT	HALT	1	4/13	-	-	-
MEGI	MEGI	1	6/11	-	-	-
MDGI	MDGI	1	5	-	-	-
RETI	RETI	1	9	-	-	-
RINT	RINT INT	2	6	-	-	-
UDGI	UDGI	1	5	-	-	-
UEGI	UEGI	1	6/11	-	-	-
TRAP	TRAP	1	9	-	-	-
WAITI	WAITI	1	7/10	-	-	-

Control Instructions						
Mnemonic	**Instruction**	**Bytes**	**Cycles**	**Z**	**S**	**C**
FUZZY	FUZZY	1	4	-	-	-
NOP	NOP	1	6	-	-	-
WDTRFR	WDTRFR	1	6	-	-	-
WDTSLP	WDTSLP	1	5	-	-	-

Notes:

regx, regy:	Register File Address
memx, memy:	Program/Data Memory Addresses
confx, confy:	Configuration Registers Addresses
outx:	Output Registers Addresses
inpx:	Input Registers Addresses
const:	Constant value
fuzzyx:	Fuzzy Input Registers
I	flag affected
-	flag not affected

(*) The instruction BLKSET determines the start of a 32 byte block writing in Flash or EEPROM Program/ Data Memory. During this phase (about 4 ms), the CPU is stopped to executing program instructions. The duration of the BLKSET instruction can be identified with this time.

10 WATCHDOG TIMER

10.1 Functional Description

The Watchdog Timer (WDT) is used to detect the occurrence of a software fault, usually generated by external interference or by unforeseen logical conditions, which causes the application program to abandon its normal sequence. The WDT circuit generates an ICU reset on expiry of a programmed time period, unless the program refreshes the WDT before the end of the programmed time delay. Sixteen different delays can be selected by using the WDT configuration register.

After the end of the delay programmed by the configuration register, if the WDT is active, it starts a reset cycle pulling the reset signal low.

Once the WDT is activated, the application program has to refresh the counter (by the WDTRFR instruction) during normal operation in order to prevent an ICU reset.

In ST52F501L/F502L devices it is possible to choose between “Hardware” or “Software” Watchdog. The Hardware WDT allows the counting to avoid unwanted stops for external interferences. The first mode is always enabled unless the Option Byte 4 (WDT_EN) is written with a special code (10101010b): only this code can switch the WDT in “Software” Mode, the other 255 possibilities keep the “Hardware” Mode enabled.

The WDT is started and refreshed by using the WDTRFR instruction. When the software mode is enabled, the WDTSLP instruction stops the WDT avoiding timeout resets.

When the WDT is in Hardware Mode, neither the WDTSLP instruction nor external interference can stop the counting. The “Hardware” WDT is always enabled after a Reset.

The working frequency of WDT (PRES CLK in the Figure 10.1) is equal to the clock master. The clock master is divided by 500, obtaining the WDT CLK signal that is used to fix the timeout of the WDT.

According to the WDT_CR Configuration Register values, a WDT delay between 0.1ms and 937.5ms can be defined when the clock master is 5 MHz. By changing the clock master frequency the timeout delay can be calculated according to the configuration register values. The first 4 bits of the WDT_CR register are used, obtaining 16 different delays.

Table 10.1 Watchdog Timing Range (5 MHz)

WDT timeout period (ms)	
min	0.1
max	937.5

10.2 Register Description

SW Watchdog Enable (WDT_EN)

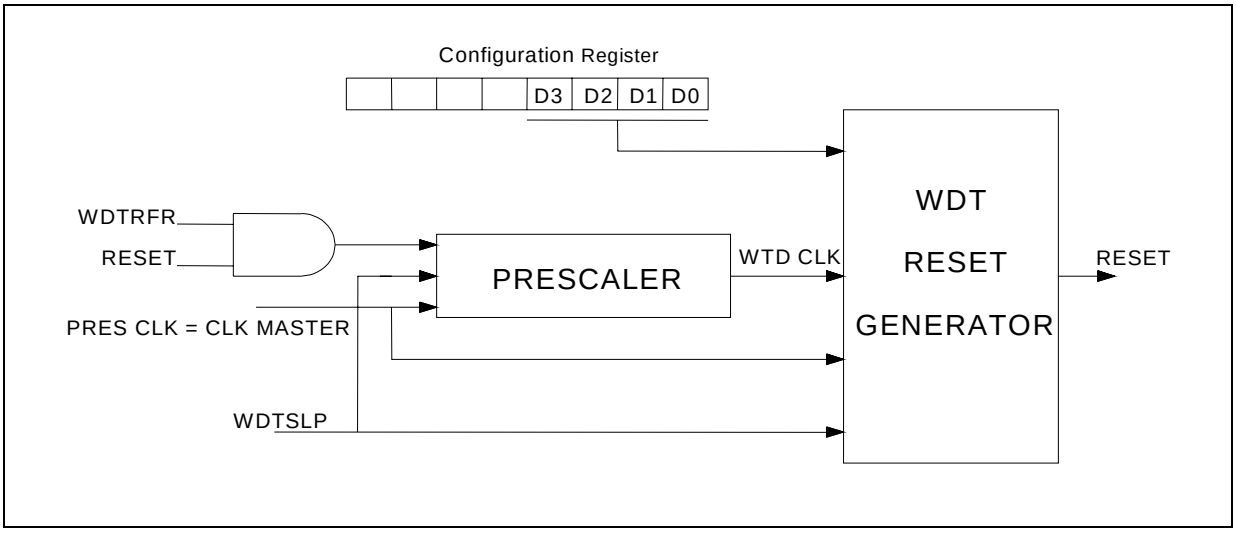
Option Byte 4 (04h)

7							0
WDTEN7	WDTEN6	WDTEN5	WDTEN4	WDTEN3	WDTEN2	WDTEN1	WDTEN0

Bit 7-0: **WDTEN7-0** SW Watchdog Enable byte

Writing the code 10101010 in this byte the Software Watchdog mode is enabled.

Figure 10.1 Watchdog Block Diagram



Watchdog Control Register (WDT_CR)

Configuration Register 7 (07h) Read/Write

Reset Value: 0000 0001 (01h)

7							0
-	-	-	-	D3	D2	D1	D0

Bit 7-4: Not Used

Bit 3-0: **D3-0** Watchdog Clock divisor factor bits

The Watchdog Clock (WDT CLK) is divided by the numeric factor determined by these bits, according with Table 10.2 and the following formula:

$$Timeout(ms) = \frac{5 \times 10^5 \times DivisionFactor}{Clock(MHz)}$$

Table 10.2 Watchdog Timeout configuration examples

WDT_CR(3:0)	Division Factor	Timeout Values (ms)		
		5 MHz	10 MHz	20MHz
0000	1	0.1	0.05	0.025
0001	625	62.5	31.25	15.625
0010	1250	125	62.5	31.25
0011	1875	187.5	93.75	46.875
0100	2500	250	125	62.5
0101	3125	312.5	156.25	78.125
0110	3750	375	187.5	93.75
0111	4375	437.5	218.75	109.375
1000	5000	500	250	125
1001	5625	562.5	281.25	140.625
1010	6250	625	312.5	156.25
1011	6875	687.5	343.75	171.875
1100	7500	750	375	187.5
1101	8125	812.5	406.25	203.125
1110	8750	875	437.5	218.75
1111	9375	937.5	468.75	234.375

11 PWM/TIMERS AND IR DRIVER

11.1 Introduction

ST52F501L/F502L offers two on-chip PWM/Timer peripherals. All ST52F501L/F502L PWM/Timers have the same internal structure. The timer consists of a 8-bit counter with a 16-bit programmable Prescaler, giving a maximum count of 2^{24} (see Figure 11.1).

Each timer has two different working modes, which can be selected by setting the correspondent bit TxMOD of the PWMx_CR1 Configuration Register: Timer Mode and PWM (Pulse Width Modulation) Mode. In addition the PWM/Timer 1 output can be used as input of the IR Driver (see below) to perform digital modulation of the digital carrier generated by the PWM/Timer 1 itself.

All the Timers have Autoreload Functions; in PWM Mode the reload value can be set by the user.

Each timer output is available on the apposite external pins configured in Alternate Function and in one of the Output modes. The outputs of both PWM/Timers can be synchronized and combined in OR, AND, XOR and NOT in order to generate complex wave modulation.

PWM/Timer 0 can also use external START/STOP signals in order to perform Input capture and Output compare, external RESET signal, and external CLOCK to count external events: TSTRT, TRES and TCLK pins. In addition, the START/STOP and RESET signals have configurable polarity (falling or rising edge).

Remark: *To use TRES, TSTRT, TCLK external signals the related pins must be configured in Alternate Function and in one of Input modes.*

For each timer, the contents of the 8-bit counter are incremented on the Rising Edge of the 16-bit prescaler output (PRESCOUT) and they can be read at any instant of the counting phase by accessing the Input Register PWMx_COUNT_IN.

The Input Register PWMx_CAPTURE stores the counter value after the last Stop signal (only Timer Mode). The counter value is not stored after a Reset Signal.

The peripheral status can also be read from the Input Registers PWMx_STATUS (one for each Timer). These registers report START/STOP, SET/RESET status, TxOUT signal and the counter overflow flag. This last signal is set after the first EOC and it is reset by a Timer RESET (internal or external).

11.2 Timer Mode

Timer Mode is selected writing 0 in the TxMOD bit.

Each Timer requires three signals: Timer Clock (TMRCLKx), Timer Reset (TxRES) and Timer Start (TxSTRT) (see Figure 11.1). Each of these signals can be generated internally, and/or externally only for Timer 0, by using TRES, TSTRT and TCLK pins.

The Prescaler output (PRESCOUT) increments the Counter value on the rising edge. PRESCOUT is obtained from the internal clock signal (CLKM) or, only for Timer 0, from the external signal provided on the apposite pin.

Note: *The external clock signal applied on the TCLK pin must have a frequency that is at least two times smaller than the internal master clock.*

The prescaler output period can be selected by setting the TxPRESC bits with one of the 17 division factors available. PRESCOUT frequency is divided by a factor equal to the power of two of the prescaler values (up to 2^{16}).

TxRES resets the content of the 8-bit counter to zero. It is generated by writing 0 in the TxRES bit of the PWMx_CR1 Configuration Register and/or it can be driven by the TRES pin if configured (only Timer0).

Figure 11.1 PWM/Timer Counter block diagram

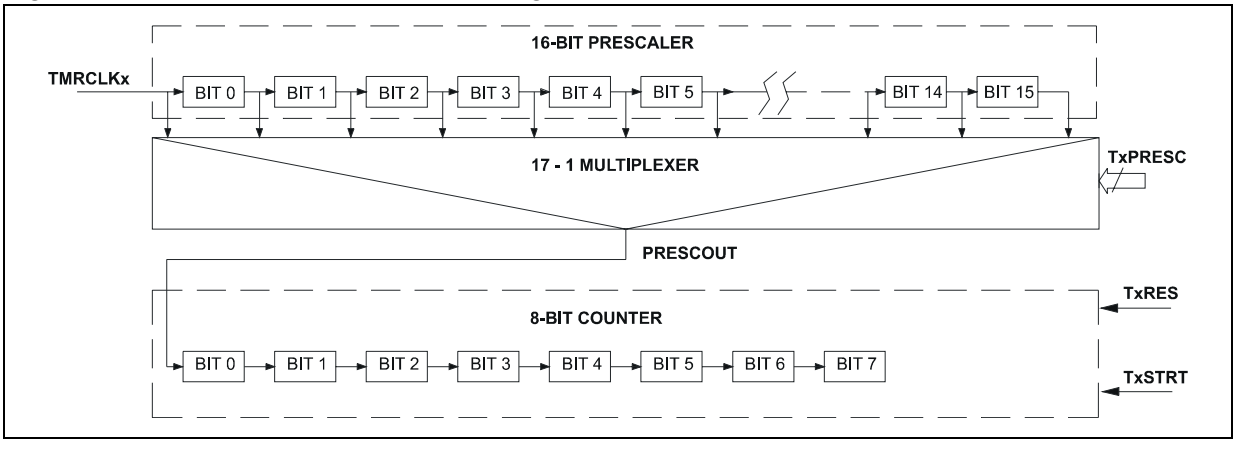
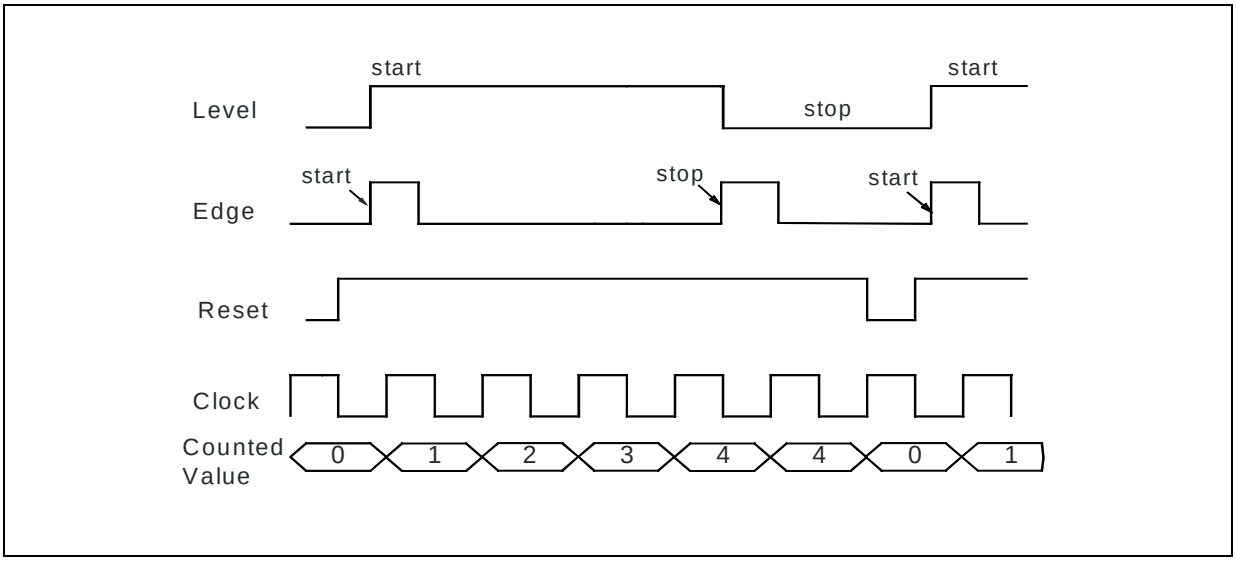


Figure 11.2 Timer 0 External Start/Stop Mode



TxSTRT signal starts/stops the Timer from counting only if the peripherals are configured in Timer mode. The Timers are started by writing 1 in the TXSTRT bit of the PWMx_CR1 and are stopped by writing 0. This signal can be generated internally and/or externally by forcing the TSTRT pin (only TIMER0).

TIMER 0 START/STOP can be given externally on the TSTRT pin. In this case, the T0STRT signal allows the user to work in two different configurable modes:

- LEVEL (Time Counter): If the T0STRT signal is high, the Timer starts counting. When the T0STRT is low the timer stops counting and the 8-bit current value is stored in the PWM0_COUNT_IN Input Registers.
- EDGE (Period Counter): After reset, on the first T0STRT rising edge, TIMER 0 starts counting and at the next rising edge it stops. In this manner the period of an external signal may be measured.

The same above mentioned modes, can be used to reset the Timer0 by using the TRES pin signal.

The polarity of the T0SRTR Start/Stop signal can be changed by setting the STRPOL and RESPOL bits in the INT_POL Configuration Register (01h bit 3 and 4). When these bits are set, the PWM/Timer 0 is Started/Set on the low level or in the falling edge of the signal applied in the pins.

The Timer output signal, TxOUT, is a signal with a frequency equal to the one of the 16 bit-Prescaler output signal, PRESCOUTx, divided by a 8-bit counter set by writing the Output Register PWMx_COUNT_OUT.

There can be two types of TxOUT waveforms:

- type 1: TxOUT waveform equal to a square wave with a 50% duty-cycle
- type 2: TxOUT waveform equal to a pulse signal with the pulse duration equal to the Prescaler output signal.

11.3 PWM Mode

The PWM working mode for each timer is obtained by setting the TxMOD bit of the Configuration Register PWMx_CR1.

The TxOUT signal in PWM Mode consists of a signal with a fixed period, whose duty cycle can be modified by the user.

The TxOUT period is fixed by setting the 16-bit Prescaler bits (TxPRESC) in the PWMx_CR2 and the 8-bit Reload value by writing the relative Output Register PWMx_RELOAD. The 16-bit Prescaler divides the master clock CLKM by powers of two, determining the maximum length period.

Figure 11.3 TxOUT Signal Types

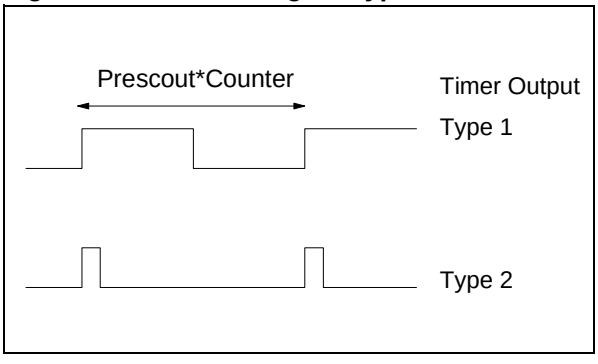
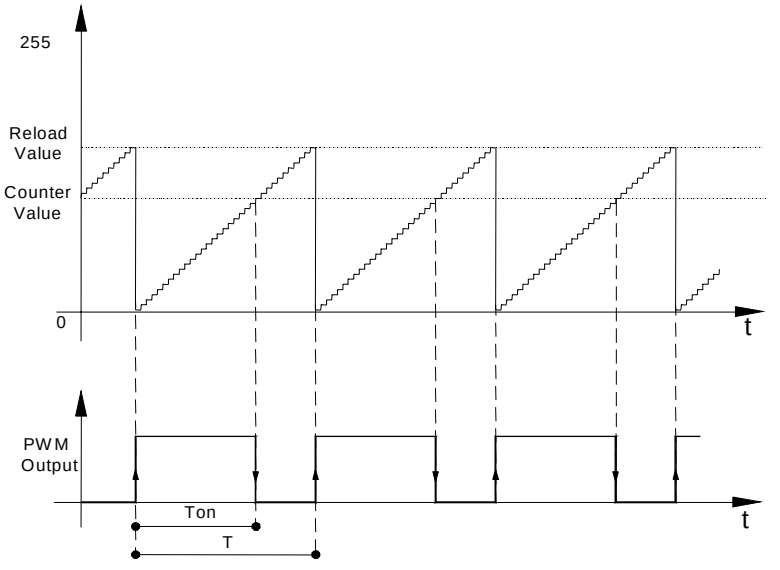


Figure 11.4 PWM Mode with Reload



Reload determines the maximum value that the counter can count before starting a new period. By decreasing the Reload value the counting resolution decreases. In order to obtain the maximum resolution, Reload value should be set to 0FFh and the period corresponds to the one established by the Prescaler value.

The value set in the 8-bit counter by writing the Counter Output Register, determines the duty-cycle: when count reaches the Counter value the TxOUT signal changes from high to low level.

The period of the PWM signal is obtained by using the following formula:

$$T = PWMx_RELOAD * 2^{TxPRESC} * TMRCLKx$$

where TxPRESC equals the value set in the TxPRESC bits of the PWMx_CR2 Configuration Register and TMRCLKx is the period of the Timer clock that drives the Prescaler.

The duty cycle of the PWM signal is obtained by the following formula:

$$d_{cycle} = \frac{T_{on}}{T} = \frac{PWMxCOUNT}{PWMxRELOAD}$$

Note: *the PWM_x_COUNT value must be lower than or equal to the PWM_X_RELOAD value. When it is equal, the TxOUT signal is always at high level. If the Output Register PWM_x_COUNT is 0, TxOUT signal is always at a low level.*

By using a 20 MHz clock a PWM frequency that is close to 78 Khz can be obtained with the higher resolution.

The TIMER0 clock CLKM can also be supplied with an external signal, applied on the TCLK pin, which must have a frequency that is at least two times smaller than the internal master clock.

Note: *the Timers have to complete the previous counting phase before using a new value of the Counter. If the Counter value is changed during counting, the new values of the timer Counter are only used at the end of the previous counting phase. Nevertheless, it is recommended that the Reload value be written when the Timer is stopped in order to avoid incongruence with the Counter value. A Reload value greater than 1 must always be used.*

When the Timers are in Reset status, or when the device is reset, the TxOUT pins goes in threestate. If these outputs are used to drive external devices, it is recommended that the related pins be left in the default configuration (Input threestate) or change them in this configuration.

In PWM mode the PWM/Timers can only be Set or Reset: Start/Stop signals do not affect the Timers. TxRES resets the content of the 8-bit counter to zero. It is generated by writing 0 in the corresponding TxRES bit of the PWMx_CR1 Configuration Register and/or it can be driven by the TRES pin if it is configured (only Timer0).

11.3.1 Simultaneous Start. The PWM/Timers can be started simultaneously.

The T0SYNC and T1SYNC bits in PWM0_CR3 Configuration Registers mask the reset of each timer. After enabling each single PWM/Timer, they are started by putting off the mask with a single writing in the PWM0_CR3 Register.

The timers start counting simultaneously, but the output pulses are generated according to the modality configured (square or pulse mode).

11.4 Timer Interrupts

The PWM/Timer can be programmed to generate an Interrupt Request, both on the falling and the rising of the TxOUT signal and when there's a STOP signal (external or internal). The PWM/ TIMER 1, when the IR Driver is active, can be configured to generate the IR interrupt (see below), excluding the other possible sources.

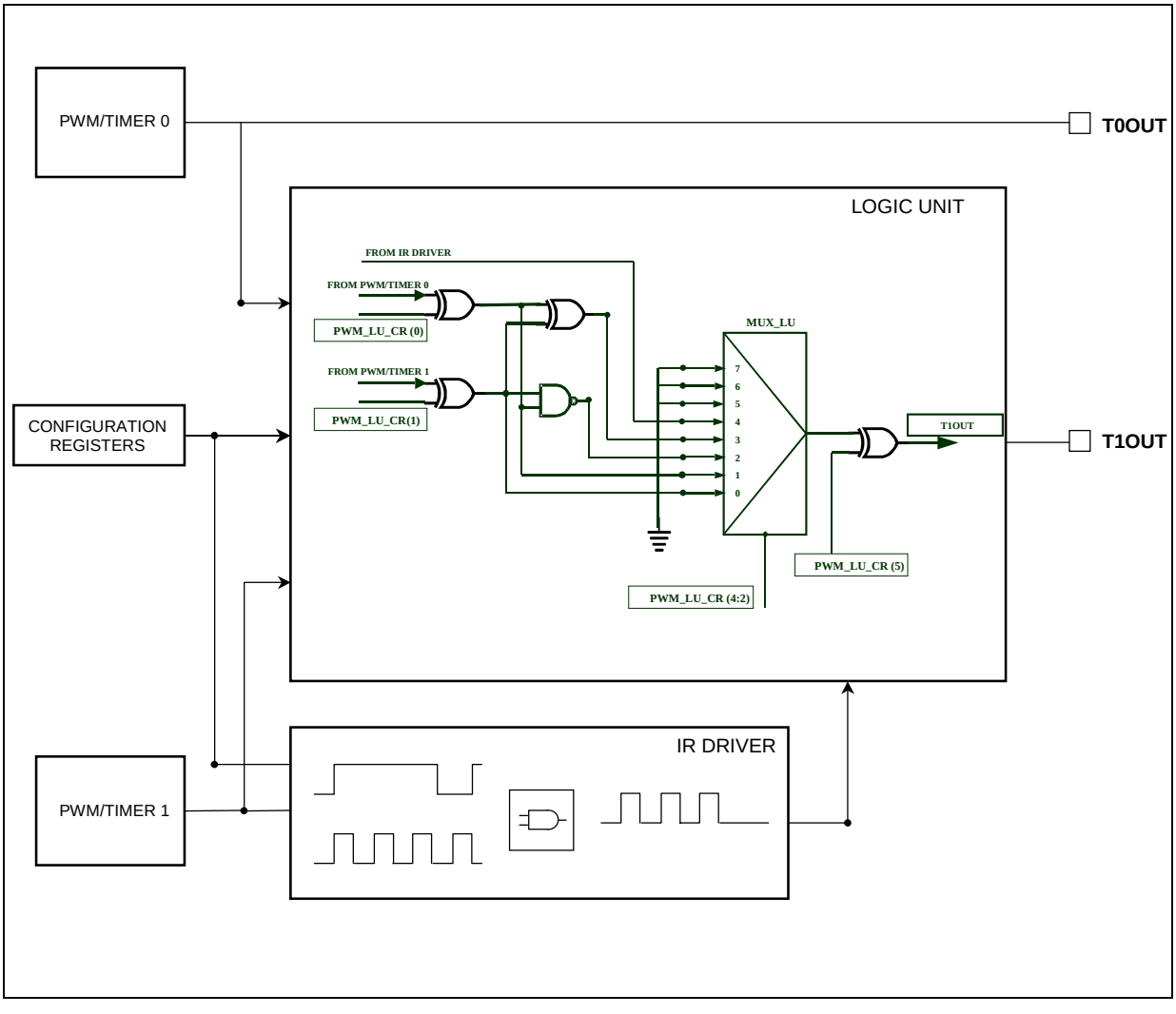
By using the TxIES, TxIER and TxIEF bits of the Configuration Registers PWMx_CR1, the interrupt sources can be switched on/off. All the interrupt sources may be activated at the same time: sources can be distinguished by reading the PWMx_STATUS Input Register.

The interrupt on the falling edge corresponds to half of a counting period in Timer mode when the waveform is set to Square Wave and to the end of the Ton phase in PWM mode.

Note: *when the PWM Counter is set to 0 or 255, the interrupt occurs at the end of each control period.*

In order to be active, the PWM/Timers interrupts must be enabled by writing the Interrupt Mask Register (INT_MASK) in the Configuration Register Space, bits MSKT0 And MSKT1.

Figure 11.5 PWM/Timers Output Modulation Architecture



11.5 PWM/Timer output modulation

The PWM/Timer outputs can be used to generate signal modulation for IR transmission in applications like Remote Control.

This can be achieved by means of the Logic Unit or the IR Driver. Configuring register 50 (032h) PWM_LU_CR, T1OUTSEL bits, the T1OUT can output the signal coming from PWM/Timer 1, Logic Unit or the IR Driver (see Figure 11.5).

11.5.1 Logic Unit. The Logic Unit allows the combination of the T0OUT and T1OUT signals in order to generate digital signals, where one output is used as a carrier and the other as modulator. The resulting output goes to T1OUT pin.

By setting the Configuration Register 50 (032h) PWM_LU_CR it is possible to combine the two outputs with the logic operators AND, OR NOT, XOR. The Logic Unit function should be used with the Simultaneous Start function to correctly synchronize the two signals.

11.5.2 IR Driver. The IR Driver implements the digital modulation of the digital carrier, T1OUT signal coming from the PWM/TIMER 1, and outputs it on the T1OUT pin. The resulting signal frequency can cover all the range of the typical IR applications by modifing the Clock frequency and the programmed Counter and Reload values.

The IR Driver has been built to implement the most common protocols for Infrared Remote Control, such as:

- Pulse Coded Signals
- Shape Coded Signals
- Shift Coded Signals
- RC5

The carrier is generated by the PWM/Timer 1 which generates a square wave with a period and duty cycle programmed by means of the PWM1_COUNT and PWM1_RELOAD 8-bit register, as explained in the previous paragraphs.

When the start bit IRSTRT of the Configuration Register IR_CR1 is set to '1', the IR Driver generates a PWM signal with a period equal to IR_PERIOD (bits 6:0 of IR_CR1) times of the carrier period and duty cycle proportional to IR_DUTY (bits 6:0 of the IR_CR2 Configuration Register).

The IRPOL bit (bit 7 of the IR_CR2 register) is used to define the polarity (i.e. the logical level) of the PWM signal at the start period: if IRPOL bit is '0" the PWM signal is at low level during the Ton and it is high during the Toff; vice versa if IRPOL is "1".

The PWM signal obtained is used as a mask (logical AND) with the carrier signal, implementing the digital modulation. The figures below show some examples of modulation.

By configuring the PWM_LU_CR Configuration Registers with the IR Driver output on T1OUT, the IR interrupt is automatically enabled. The interrupt is generated at the start of the "symbol" transmission, i.e. at the beginning of the period of the PWM modulator signal, to avoid dead times between two transmissions.

Note: *When the IR Interrupt is enabled, the other PWM/Timer 1 interrupt sources are automatically disabled*

Figure 11.6 Pulse Coding signal modulation

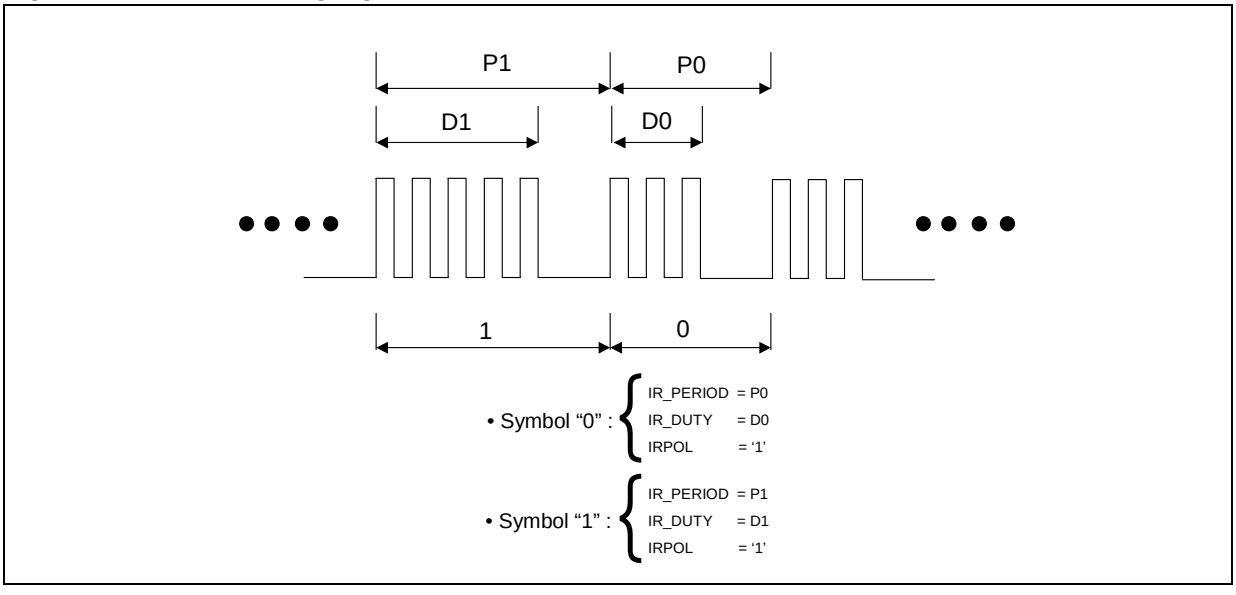


Figure 11.7 Space Coding signal modulation

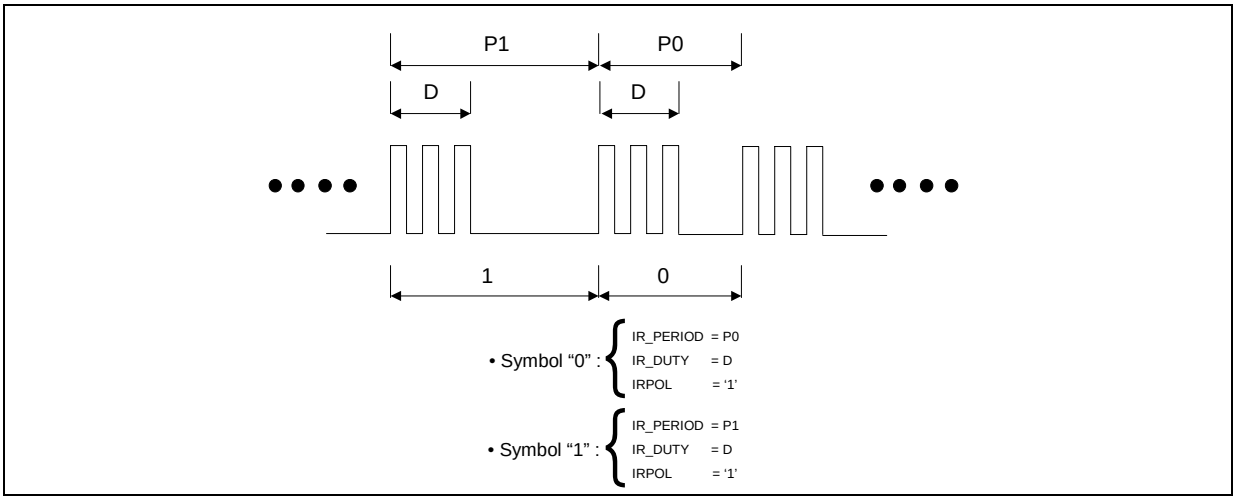


Figure 11.8 Shift Coding signal modulation

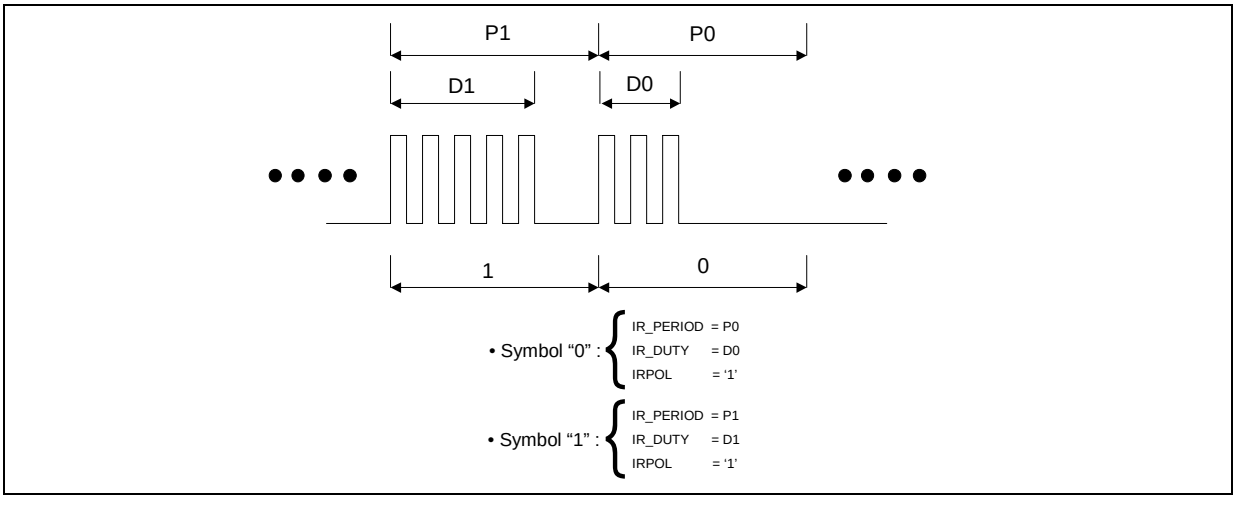
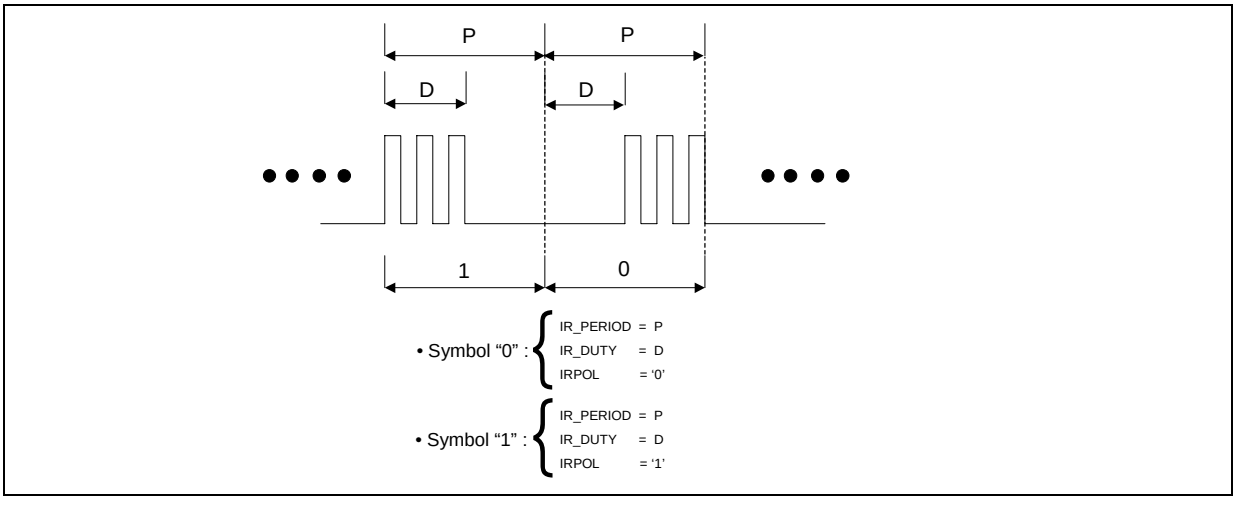


Figure 11.9 RC5 Coding signal modulation



11.6 PWM/Timer 0 Register Description

The following registers are related to the use of the PWM/Timer 0.

PWM/Timer 0 Control Register 1 (PWM0_CR1)

Configuration Register 9 (09h) Read/Write

Reset Value: 0000 0000 (00h)

7							0
T0MOD	T0IES	T0IEF	T0IER	STRMOD	T0STRT	RESMOD	T0RES

Bit 7: **T0MOD** PWM/Timer 0 Mode
- 0: Timer Mode
- 1: PWM Mode

Bit 6: **T0IES** Interrupt on Stop signal Enable
- 0: interrupt disabled
- 1: interrupt enabled

Bit 5: **T0IEF** Interrupt on T0OUT falling Enable
- 0: interrupt disabled
- 1: interrupt enabled

Bit 4: **T0IER** Interrupt on T0OUT rising Enable
- 0: interrupt disabled
- 1: interrupt enabled

Bit 3: **STRMOD** Start signal mode
- 0: start/stop on level
- 1: start/stop on edge

Bit 2: **T0STRT** PWM/Timer 0 Start bit
- 0: Timer 0 stopped
- 1: Timer 0 started

Bit 1: **RESMOD** Reset signal mode
- 0: set/reset on level
- 1: set/reset on edge

Bit 0: **T0RES** PWM/Timer 0 Reset bit
- 0: PWM/Timer 0 reset
- 1: PWM/Timer 0 set

PWM/Timer 0 Control Register 2 (PWM0_CR2)

Configuration Register 10 (0Ah) Read/Write

Reset Value: 0000 0000 (00h)

7		4	0
-	-	T0WAV	T0PRESC

Bit 7-6: Not Used

Bit 5: **T0WAV** T0OUT Waveform
- 0: pulse (type2)
- 1: square (type1)

Bit 4-0: **T0PRESC** PWM/Timer 0 Prescaler

The PWM/Timer 0 clock is divided by a factor equal to $2^{T0PRESC}$. **The maximum value allowed for T0PRESC is 10000 (010h).**

PWM/Timer 0 Control Register 3 (PWM0_CR3)

Configuration Register 11 (0Bh) Read/Write

Reset Value: 0000 0000 (00h)

7					0
T1SYNC	-	T0SYNC	T0CKS	STRSRC	RESSRC

Bit 7: **T1SYNC** PWM/Timer 1 Set/Reset mask
- 0: Set/Reset activated
- 1: Set/Reset masked

Bit 6: not used

Bit 5: **T0SYNC** PWM/Timer 0 Set/Reset mask
- 0: Set/Reset activated
- 1: Set/Reset masked

Bit 4: **T0CKS** PWM/Timer 0 Clock Source
- 0: Internal clock
- 1: External Clock from TCLK

Bit 3-2: **STRSRC** PWM/Timer 0 Start signal source
- 00: Internal from T0STRT bit
- 01: External from TSTRT pin
- 10: Both internal and external

Bit 1-0: **RESSRC** PWM/Timer 0 Reset source
00: Internal from T0RES bit
01: External from TRES pin
10: Both internal and external

Interrupt Polarity Register (INT_POL)
Configuration Register 1 (01h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
-	-	-	RESPOL	STRPOL	POLPB	POLPA	POLNMI

Bit 7-5: Not Used

Bit 4: **RESPOL** Reset signal polarity
0: Set/Reset on low level/rising edge
1: Set/Reset on high level/falling edge

Bit 3: **STRPOL** Start signal polarity
0: Start on high level/rising edge
1: Start on low level/falling edge

Bit 2-0: See Interrupt Registers Description

11.6.1 PWM/Timer 0 Input Registers.

PWM/Timer 0 Counter Input Register (PWM0_COUNT_IN)
Input Register 22 (016h) Read only
Reset Value: 0000 0000 (00h)

7							0
T0CI7	T0CI6	T0CI5	T0CI4	T0CI3	T0CI2	T0CI1	T0CI0

Bit 7-0: **T0CI7-0** PWM/Timer 0 Counter

In this register the current value of the Timer 0 Counter can be read.

PWM/Timer 0 Status Register (PWM0_STATUS)
Input Register 23 (017h) Read only
Reset Value: 0000 0000 (00h)

7							0
-	-	-	-	T0OVFL	T0OUT	T0RST	T0SST

Bit 7-4: Not Used

Bit 3: **T0OVFL** PWM/Timer 0 counter overflow flag
0: no overflow occurred since last reset
1: overflow occurred

Bit 2: **T0OUT** T0OUT pin value
0: T0OUT pin is at logical level 0
1: T0OUT pin is at logical level 1

Bit 1: **T0RST** Reset Status
0: PWM/Timer 0 is reset
1: PWM/Timer 0 is set

Bit 0: **T0SST** Start Status
0: PWM/Timer 0 is stopped
1: PWM/Timer 0 is running

PWM/Timer 0 Capture Input Register (PWM0_CAPTURE)
Input Register 25 (019h) Read only
Reset Value: 0000 0000 (00h)

7							0
T0CP7	T0CP6	T0CP5	T0CP4	T0CP3	T0CP2	T0CP1	T0CP0

Bit 7-0: **T0CP7-0** PWM/Timer 0 Capture LSB

In this register the counter value after the last stop can be read.

11.6.2 PWM/Timer 0 Output Registers.

PWM/Timer 0 Counter Output Register (PWM0_COUNT_OUT)

Output Register 8 (08h) Write only

Reset Value: 0000 0000 (00h)

7							0
T0CO7	T0CO6	T0CO5	T0CO4	T0CO3	T0CO2	T0CO1	T0CO0

Bit 7-0: **T0CO7-0** PWM/Timer 0 Counter

This register is used to write the Timer 0 Counter value.

PWM/Timer 0 Reload Output Register (PWM0_RELOAD)

Output Register 10 (0Ah) Write only

Reset Value: 1111 1111 (0FFh)

7							0
T0REL7	T0REL6	T0REL5	T0REL4	T0REL3	T0REL2	T0REL1	T0REL0

Bit 7-0: **T0REL7-0** PWM/Timer 0 Reload

This register is used to write the Timer 0 Reload value.

11.7 PWM/Timer 1 Register Description

The following registers are related to the use of the PWM/Timer 1, Logic Unit and IR Driver.

11.7.1 PWM/Timer 1 Configuration Registers.

PWM/Timer 1 Control Register 1 (PWM1_CR1)

Configuration Register 12 (0Ch) Read/Write

Reset Value: 0000 0000 (00h)

7							0
T1MOD	T1IES	T1IEF	T1IER	-	T1STRT	-	T1RES

Bit 7: **T1MOD** PWM/Timer 1 Mode
- 0: Timer Mode
- 1: PWM Mode

Bit 6: **T1IES** Interrupt on Stop signal Enable
- 0: interrupt disabled
- 1: interrupt enabled

Bit 5: **T1IEF** Interrupt on T1OUT falling Enable
- 0: interrupt disabled
- 1: interrupt enabled

Bit 4: **T1IER** Interrupt on T1OUT rising Enable
- 0: interrupt disabled
- 1: interrupt enabled

Bit 3: not used: it must be left at reset status

Bit 2: **T1STRT** PWM/Timer 1 Start bit
- 0: Timer 1 stopped
- 1: Timer 1 started

Bit 1: not used: it must be left at reset status

Bit 0: **T1RES** PWM/Timer 1 Reset bit
- 0: PWM/Timer 1 reset
- 1: PWM/Timer 1 set

PWM/Timer 1 Control Register 2 (PWM1_CR2)

Configuration Register 13 (0Dh) Read/Write

Reset Value: 0000 0000 (00h)

7			4				0
-	-	T1WAV	T1PRESC				

Bit 7-6: Not Used

Bit 5: **T1WAV** T1OUT Waveform
- 0: pulse (type2)
- 1: square (type1)

Bit 4-0: **T1PRESC** PWM/Timer 1 Prescaler

The PWM/Timer 1 clock is divided by a factor equal to $2^{T1PRESC}$. **The maximum value allowed for T1PRESC is 10000 (010h)**.

IR Driver Control Register 1 (IR_CR1)

Configuration Register 48 (030h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
IRSTRT	IR_PERIOD						

Bit 7: **IRSTRT** IR Driver Start/Stop
0: IR Driver Stopped
1: IR Driver Started

Bit 6-0: **IR_PERIOD** PWM modulator wave period
The period of the modulator wave is equal to the carrier period multiplied the IR_PERIOD value.

IR Driver Control Register 2 (IR_CR2)

Configuration Register 49 (031h) Read/Write
Reset Value: 0000 0000 (00h)

7							0
IRPOL	IR_DUTY						

Bit 7: **IRPOL** Modulator wave Polarity
0: Modulator wave start with a low level
1: Modulator wave start with a high level

Bit 6-0: **IR_DUTY** PWM modulator wave duty-cycle
The duty-cycle of the modulator wave is equal to IR_DUTY/IR_PERIOD.

Logic Unit Control Register (PWM_LU_CR)

Configuration Register 50 (032h) Read/Write
Reset Value: 0000 0000 (00h)

7					3		0
-	-	LUPOL	LUSEL			POLT1	POLT0

Bit 7-6: Not Used

Bit 5: **LUPOL** Logic Unit output polarity
0: Logic Unit output not inverted
1: Logic Unit output inverted

Bit 4-2: **LUSEL** Logic Unit function selector
These bits are used to select the input of the Logic Unit according to the polarity selected for Timer0 and Timer1 selected by means of the POLT0 and POLT1 configuration bits. See Table 11.1 for the function selection.

Bit 1: **POLT1** Logic Unit input from Timer1 polarity
0: Timer1 signal is used into Logic Unit
1: Inverted Timer1 signal is used into L.U.

Bit 0: **POLT0** Logic Unit input from Timer0 polarity
0: Timer0 signal is used into L. U.
1: Inverted Timer0 signal is used into L.U.

Table 11.1 Logic Unit Operators Configuration Table

PWM_LU_CR(5:0)						T1OUT
LUPOL	LUSEL			POLT1	POLT0	
0	0	0	0	0	X	T1
0	0	0	0	1	X	NOT(T1)
0	0	0	1	X	0	T0
0	0	0	1	X	1	NOT(T0)
0	0	1	0	0	0	NAND(T0,T1) = OR(NOT(T0),NOT(T1))
0	0	1	0	0	1	NAND(NOT(T0),T1) = OR(T0,NOT(T1))
0	0	1	0	1	0	NAND(T0,NOT(T1)) = OR(NOT(T0),T1)
0	0	1	0	1	1	NAND(NOT(T0),NOT(T1)) = OR(T0,T1)
0	0	1	1	0	0	XOR(T0,T1)

Table 11.1 Logic Unit Operators Configuration Table

PWM_LU_CR(5:0)						T1OUT
0	0	1	1	0	1	XOR(NOT(T0),T1)
0	0	1	1	1	0	XOR(T0,NOT(T1))
0	0	1	1	1	1	XOR(NOT(T0),NOT(T1))
0	1	0	0	X	X	IR DRIVER OUTPUT
X	1	0	1	X	X	RESERVED
X	1	1	0	X	X	RESERVED
X	1	1	1	X	X	RESERVED
1	0	0	0	0	X	NOT(T1)
1	0	0	0	1	X	T1
1	0	0	1	X	0	NOT(T0)
1	0	0	1	X	1	T0
1	0	1	0	0	0	AND(T0,T1) = NOR(NOT(T0),NOT(T1))
1	0	1	0	0	1	AND(NOT(T0),T1) = NOR(T0,NOT(T1))
1	0	1	0	1	0	AND(T0,NOT(T1)) = OR(NOT(T0),T1)
1	0	1	0	1	1	AND(NOT(T0),NOT(T1)) = NOR(T0,T1)
1	0	1	1	0	0	NOT(XOR(T0,T1))
1	0	1	1	0	1	NOT(XOR(NOT(T0),T1))
1	0	1	1	1	0	NOT(XOR(T0,NOT(T1)))
1	0	1	1	1	1	NOT(XOR(NOT(T0),NOT(T1)))
1	1	0	0	X	X	NOT(IR DRIVER OUTPUT)

Note:
Tx = PWM/Timer x output signal
X = don't care

11.7.2 PWM/Timer 1 Input Registers.

PWM/Timer 1 Counter Input Register (PWM1_COUNT_IN)

Input Register 27 (01Bh) Read only

Reset Value: 0000 0000 (00h)

7							0
T1CI7	T1CI6	T1CI5	T1CI4	T1CI3	T1CI2	T1CI1	T1CI0

Bit 7-0: **T1CI7-0** PWM/Timer 1 Counter

In this register the current value of the Timer 1 Counter can be read.

PWM/Timer 1 Status Register (PWM1_STATUS)

Input Register 28 (01Ch) Read only

Reset Value: 0000 0000 (00h)

7							0
-	-	-	-	T1OVFL	T1OUT	T1RST	T1SST

Bit 7-4: Not Used

Bit 3: **T1OVFL** PWM/Timer 1 counter overflow flag

0: no overflow occurred since last reset

1: overflow occurred

Bit 2: **T1OUT** T1OUT pin value

0: T1OUT pin is at logical level 0

1: T1OUT pin is at logical level 1

Bit 1: **T1RST** Reset Status
0: PWM/Timer 1 is reset
1: PWM/Timer 1 is set

Bit 0: **T1SST** Start Status
0: PWM/Timer 1 is stopped
1: PWM/Timer 1 is running

PWM/Timer 1 Capture Input Register (PWM1_CAPTURE)

Input Register 30 (01Eh) Read only

Reset Value: 0000 0000 (00h)

7							0
T1CP7	T1CP6	T1CP5	T1CP4	T1CP3	T1CP2	T1CP1	T1CP0

Bit 7-0: **T1CP7-0** PWM/Timer 1 Capture LSB

In this register the counter value after the last stop can be read.

11.7.3 PWM/Timer 1 Output Registers.

PWM/Timer 1 Counter Output Register (PWM1_COUNT_OUT)

Output Register 12 (0Ch) Write only

Reset Value: 0000 0000 (00h)

7							0
T1CO7	T1CO6	T1CO5	T1CO4	T1CO3	T1CO2	T1CO1	T1CO0

Bit 7-0: **T1CO7-0** PWM/Timer 0 Counter

This register is used to write the Timer 1 Counter value.

PWM/Timer 1 Reload Output Register (PWM0_RELOAD)

Output Register 14 (0Eh) Write only

Reset Value: 1111 1111 (0FFh)

7							0
T1REL7	T1REL6	T1REL5	T1REL4	T1REL3	T1REL2	T1REL1	T01REL0

Bit 7-0: **T1REL7-0** PWM/Timer 1 Reload

This register is used to write the Timer 1 Reload value.

12 SERIAL COMMUNICATION INTERFACE

The Serial Communication Interface (SCI) integrated into ST52F501L/F502L provides a general purpose shift register peripheral, several widely distributed devices to be linked, through their SCI subsystem. SCI gives a serial interface providing communication with the speed from less than 300 up to over 115200 baud, and a flexible character format.

SCI is a full-duplex UART-type asynchronous system with standard Non Return to Zero (NRZ) format for the transmitted/received bit. The length of the transmitted word is 10/11 bits (1 start bit, 8/9 data bits, 1 stop bit).

SCI is composed of three modules: Receiver, Transmitter and Baud-Rate Generator.

12.1 SCI Receiver block

The SCI Receiver block manages the synchronization of the serial data stream and stores the data characters. The SCI Receiver is mainly composed of two sub-systems: Recovery Buffer Block and SCDR_RX Block.

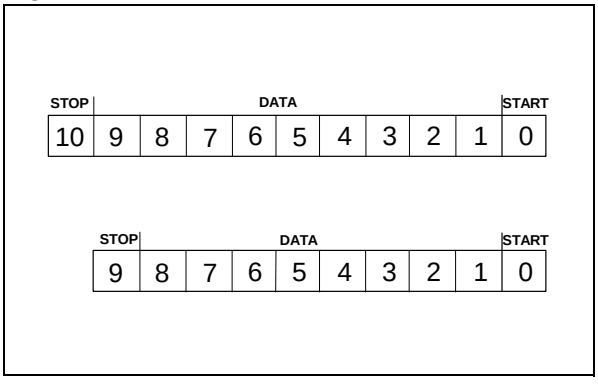
SCI receives data deriving from the RX pin and drives the Recovery Buffer Block, which is a high-speed shift register operating at a clock frequency (CLOCK_RX) 16 times higher than the fixed baud rate (CLOCK_TX). This sampling rate, higher than the Baud Rate clock, detects the START condition, Noise error and Frame error.

When the SCI Receiver is in IDLE status, it is waiting for the START condition, which is obtained with a logic level of 0, consecutive to a logic level 1. This condition is detected if, with the fixed sampling time, a logic level 0 is sampled after three logic levels of 1.

The recognition of the START bit forces the SCI Receiver Block to start a data acquisition sequence.

The data acquisition sequence is configured by the apposite Configuration Register, allowing the following data frame formats (see Figure 12.1):

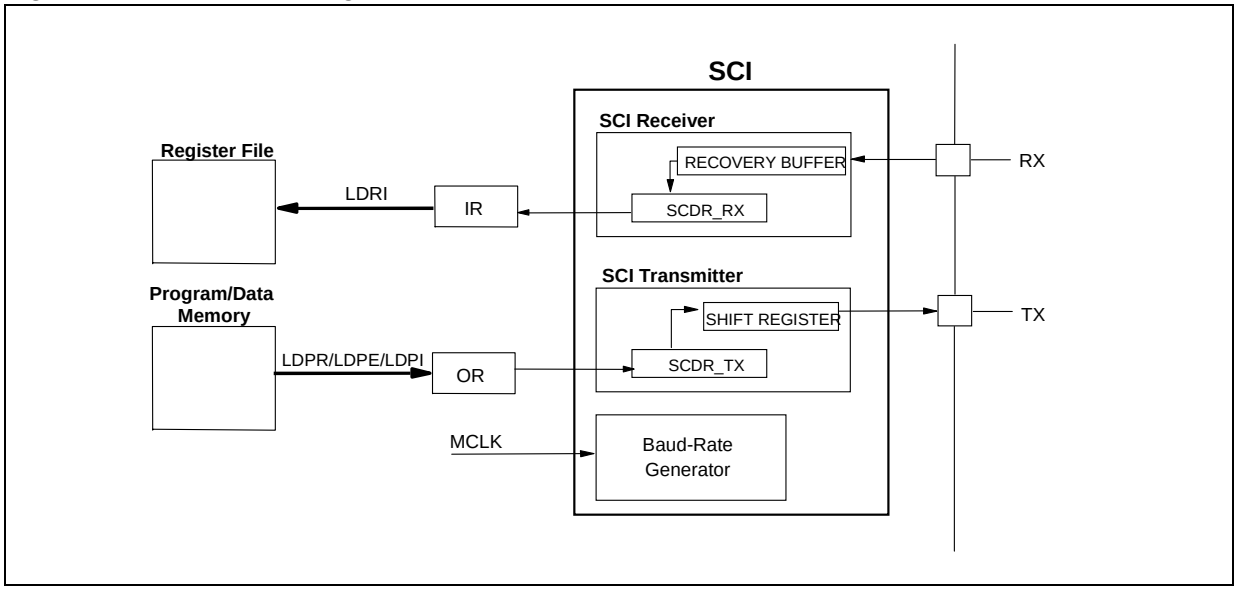
Figure 12.1 SCI transmitted word structures



- 8 bit length, 1 stop bit, no parity bit
- 8 bit length, 2 stop bit, no parity bit
- 8 bit length, 1 stop bit, with parity bit
- 9 bit length, 1 stop bit, no parity bit

The parity bit (if used) can be configured for even or odd parity check. If the 9-bit length format is configured, this bit is used in transmission for the ninth bit (see below). The ninth bit received can be read in the R8 bit of the SCI Status Register, address 37 (035h) bit 2 (see Figure 12.3).

Figure 12.2 SCI Block Diagram



Recognition of a STOP condition transfers data received from the Recovery Buffer to the SCDR_RX buffer, adding the eventual ninth data bit. After this operation, RXF flag (bit 5) of SCI Status Input Register is set to logic level 1. The Control Unit reads data from the SCDR_RX buffer (in read-only mode) by reading the SCI_IN Input Register (address 36 024h) with the LDRI instruction and provides a reset at logic level 0 to the RXF flag.

If data of the Recovery Buffer is ready to be transferred into the SCDR_RX buffer, but the previous one has not been read by the Core, an OVERRUN Error takes place: the SCI Status Register flag OVERR (bit 4) indicates the error condition. In this case, information that is stored in the SCDR_RX buffer is not altered, but the one that has caused the OVERRUN error can be overwritten by new data deriving from the serial data line.

12.1.1 Recovery Buffer Block .

This block is structured as a synchronized finite state machine on the CLOCK_RX signal.

When the Recovery Buffer Block is in IDLE state it waits for the reception of the correct 1 and 0 sequence representing START.

Recognition takes place by sampling the input RX at CLOCK_RX frequency, which has a frequency that is 16 times higher than CLOCK_TX. For this reason, while the external transmitter sends a single bit, the Recovery Buffer Block samples 16 states (from SAMPLE1 to SAMPLE16).

Analysis of the RX input signal is carried out by checking three samples for each bit received.

If these three samples are not equal, then the noise error flag, NSERR (bit 7), of SCI Status Register is set to 1 and the data received value will be the one assumed by the majority of the samples.

The procedure described above, allows SCI not to becomes IDLE, because of a limited noise due to an erroneous sampling, the transmission is recognized as correct and the noise flag error is set.

At the end of the cycle of the reception of a bit, the Recovery Buffer Block will repeat the same steps 9 times: one step for each bit received, plus one for the stop acquisition (10 times in case of 9-bit data, double stop or parity check).

At the end of data reception the Recovery Buffer Block will supply information about eventual frame errors by setting the 1 FRERR flag (bit 6) of the SCI Status Register to 1.

A frame error can occur if the parity check hasn't been successfully achieved or if the STOP bit has not been detected.

If the Recovery Buffer Block receives 10 consecutive bits at logic level 0, a Line Break condition occurs, the related Interrupt Request is sent and the BRK flag in the SCI Status Register is set.

12.1.2 SCDR_RX Block.

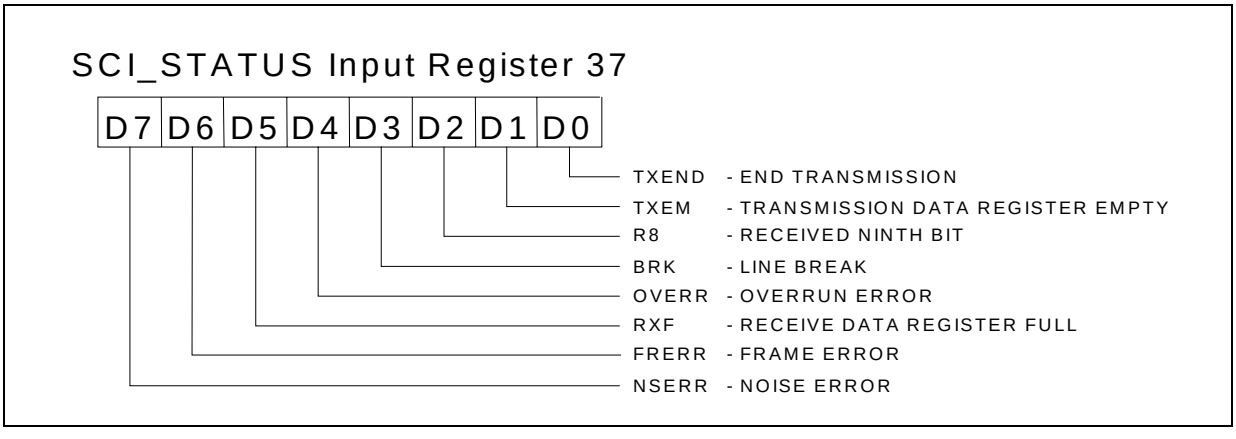
It is a finite state machine synchronized with the clock master signal, fCKM.

The SCDR_RX block waits for the signal of complete reception from the Recovery Buffer in order to load the word received. Moreover, the SCDR_RX block loads the values of FRERR and NSERR flag bits of the Status Register, and sets the RXF flag to 1.

By using the LDRI instruction data is transferred to Register File and RXF flag is reset to 0, to indicate that the SCDR_RX block is empty.

If new data arrives before the previous one has been transferred to Register File, the overrun error occurs and the OVERR flag of Status Register is set to 1.

Figure 12.3 SCI Status Register



12.2 SCI Transmitter Block

The SCI Transmitter Block consists of the following blocks: SCDR_TX and SHIFT REGISTER, synchronized, respectively, with the clock master signal (fCKM) and the CLOCK_TX.

The whole block receives the settings for the following transmission modes through the Configuration Register:

- 8 bit length, 1 stop bit, no parity bit
- 8 bit length, 2 stop bit, no parity bit
- 8 bit length, 1 stop bit, with parity bit
- 9 bit length, 1 stop bit, no parity bit

In case of 9 bit frame transmission, the most significative bit arrives through the bit PAR/T8 (bit 2) of the SCI_CR1 Configuration Register. In an 8-bit transmission, instead, this bit is used to configure the data format: in particular to choose the polarity control (even or odds) to implement the parity check (see above).

After a RESET, the SCDR_TX block is in IDLE state until it receives an enabling signal by writing the TXSTRT bit of the SCI_CR2 Configuration Register.

The data is loaded on the Peripheral Register SCI_OUT (address 23 017h) by using the instruction LPPR, LDPI or LDPE. If the transmission is enabled (TXTSTRT bit of the SCI_CR2 configuration register), the data to be transmitted is transferred from the Output Register to SCDR_TX block and the TXEM flag (bit 1) of the SCI Status Register is reset to 0 to indicate SCDR_TX block is full.

If the core supplies new data, this could not be loaded in the SCDR_TX block until the current data has not been unloaded on the Shift Register block. Meaning that only when TXEM is 1 data can be loaded in the SCDR_TX Block.

When the SHIFT REGISTER Block loads the data to be transmitted on an internal buffer, the TXEND flag (bit 0) of the SCI Status Register is reset to 0 to indicate the beginning of a new transmission. At the end of transmission TXEND is set to 1, allowing new data coming from SCDR_TX to be loaded in the SHIFT REGISTER.

It is important to underline that TXEND = 1 does not mean SCDR_TX is ready to receive a new data. For this reason, it is better to utilize the TXEM signal to synchronize the load instruction to the SCI TRANSMITTER block

If the TXSTRT bit is reset, the transmission is stopped, but the SCI Transmitter block completes the transmission in progress before resetting.

12.3 Baud Rate Generator Block

The Baud Rate Generator Block performs the division of the clock master signal (fCKM) in a set of synchronism frequencies for the serial bit reception/transmission on the external line.

Reception frequency (CLOCK_RX) is 16 times higher than the transmission frequency (CLOCK_TX).

To adapt the Baud Rate Generator to the clock master frequency supplied by the user, a 12-bit Prescaler must be programmed by loading the Configuration Registers SCI_CR2 (PRESC_H bit 11:8 of the 12 bit prescaler) and SCI_CR3 (PRESC_L bit 7:0 of the 12 bit prescaler). The prescaler allows the programming of all standard Baud Rates by using the most common clock master sources.

The Prescaler value can be obtained by the following formula:

$$PRESC = round\left(\frac{CKM}{16 \times BAUD}\right)$$

Where fCKM is the clock master frequency (expressed in Hz) and BAUD is the desired Baud Rate (expressed in bit/second). The obtained value is rounded to the nearest integer value. This rounding can cause an error in the obtained Baud Rate. This error must be lower than 3%. To verify that the PRESC value satisfies this constrain, the obtained Baud Rate must be computed by inverting the previous formula:

$$\overline{BAUD} = \frac{CKM}{16 \times PRESC}$$

then the following relation can be used to verify that the difference with the desired Baud Rate is lower than 3%:

$$\frac{\left|BAUD - \overline{BAUD}\right|}{BAUD} < 0{,}03$$

Table 12.1 shows the recommended Prescaler values for common clock master frequencies. To get more precision in Baud Rate, standard quartz frequencies for serial communication can be used. The corresponding Prescaler values for these frequencies are showed in the Table 12.2.

Table 12.1 Recommended Prescaler values for common frequencies (Baud/MHz)

	1	4	5	8	10	12	16	20	24
1200	52	208	260	417	521	625	833	1042	1250
2400	26	104	130	208	260	313	417	521	625
4800	13	52	65	104	130	156	208	260	313
9600	-	26	33	52	65	78	104	130	156
19200	-	13	16	26	33	39	52	65	78
38400	-	-	8	13	16	20	26	33	39
57600	-	-	-	-	11	13	17	22	26
115200	-	-	-	-	-	-	-	11	13

Table 12.2 Recommended Prescaler values for serial communication quartz (Baud/MHz)

	1.843	2.458	3.686	4.915	6.144	7.373	9.830	11.059	12.288	14.746	19.661	22.118
1200	96	128	192	256	320	384	512	576	640	768	1024	1152
2400	48	64	96	128	160	192	256	288	320	384	512	576
4800	24	32	48	64	80	96	128	144	160	192	256	288
9600	12	16	24	32	40	48	64	72	80	96	128	144
19200	6	8	12	16	20	24	32	36	40	48	64	72
38400	3	4	6	8	10	12	16	18	20	384	32	36
57600	2	-	4	-	-	8	-	12	13	16	21	24
115200	1	-	2	-	-	4	-	6	-	8	-	12

12.4 SCI Register Description

The following registers are related to the use of the SCI peripheral.

12.4.1 SCI Configuration Registers.

SCI Control Register 1 (SCI_CR1)

Configuration Register 22 (016h) Read/Write

Reset Value: 0000 0000 (00h)

7					2	0
RXFINT	OVRINT	BRKINT	TXEMINT	TXENINT	PAR/T8	FRM

Bit 7: **RXFINT** SCDR_RX buffer full interrupt mask
- 0: interrupt disabled
- 1: interrupt enabled

Bit 6: **OVRINT** Overrun interrupt mask
- 0: interrupt disabled
- 1: interrupt enabled

Bit 5: **BRKINT** Break interrupt mask
- 0: interrupt disabled
- 1: interrupt enabled

Bit 4: **TXEMINT** SCDR_TX buffer empty interrupt
- 0: interrupt disabled
- 1: interrupt enabled

Bit 3: **TXENINT** TX end interrupt mask
- 0: interrupt disabled
- 1: interrupt enabled

Bit 2: **PAR/T8** Parity type selection or TX 9th bit
- 0: parity odd if enabled, else TX 9th bit=0
- 1: parity even if enabled, else TX 9th bit=1

Bit 1-0: **FRM** Frame type selection
- 00: 8 bit, no parity, 1 stop bit
- 01: 8 bit, no parity, 2 stop bit
- 10: 8 bit, parity, 1 stop bit
- 11: 9 bit, no parity, 1 stop bit

Note: *the SCI interrupts are not enabled unless the bit 3 (MSKSCI) of the Configuration Register 0 (INT_MASK) is enabled (set to 1).*

SCI Control Register 2 (SCI_CR2)

Configuration Register 23 (017h) Read/Write

Reset Value: 0000 0000 (00h)

7	4	2	0
PRESC_H	-	RXSTRT	TXSTRT

Bit 7-4: **PRESC_H** Baud Rate prescaler (bit 11:8)

These bits are the higher part of the prescaler (see SCI_CR3 Configuration Register) which determinates the baud rate of the communication, according to Table 12.1 and Table 12.2, as explained in Section 12.3.

Bit 3-2: not used

Bit 1: **RXSTRT** Reception enable
- 0: RX disabled
- 1: RX enabled

Bit 0: **TXSTRT** Transmission enable
- 0: TX disabled
- 1: TX enabled

SCI Control Register 3 (SCI_CR3)

Configuration Register 43 (02Bh) Read/Write

Reset Value: 0000 0000 (00h)

7	0
PRESC_L	

Bit 7-0: **PRESC_L** Baud Rate prescaler (bit 7:0)

These bits are the lower part of the prescaler (see SCI_CR2 Configuration Register) which determinates the baud rate of the communication, according to Table 12.1 and Table 12.2, as explained in Section 12.3.

12.4.2 SCI Input Registers.

SCI RX data Input Register (SCI_IN)
Input Register 36 (024h) Read only
Reset Value: 0000 0000 (00h)

7							0
RX7	RX6	RX5	RX4	RX3	RX2	RX1	RX0

Bit 7-0: **RX7-0** RX Data

In this register the last received serial data can be read.

SCI Status Register (SCI_STATUS)
Input Register 37 (025h) Read only
Reset Value: 0000 0011 (03h)

7							0
NSERR	FRERR	RXF	OVERR	BRK	R8	TXEM	TXEND

Bit 7: **NSERR** Noise error
0: noise error not occurred
1: noise error occurred

Bit 6: **FRERR** Frame error
0: frame error not occurred
1: frame error occurred

Bit 5: **RXF** RX data register full
0: RX data register already read
1: RX data register full but not read yet

Bit 4: **OVERR** Overrun error
0: overrun error not occurred
1: overrun error occurred

Bit 3: **BRK** Line Break
0: Line Break not occurred
1: Line Break occurred

Bit 2: **R8** Received 9th bit
0: RX 9th bit=0
1: RX 9th bit=1

Bit 1: **TXEM** TX data register empty
0: TX data register full
1: TX data register empty

Bit 0: **TXEND** TX end flag
0: data transferred to the shift register
1: data transmission completed

12.4.3 SCI Output Register.

SCI TX data Output Register (SCI_OUT)
Output Register 23 (017h) Write only
Reset Value: 0000 0000 (00h)

7							0
TX7	TX6	TX5	TX4	TX3	TX2	TX1	TX0

Bit 7-0: **TX7-0** TX Data

In this register the serial data to be transmitted can be written.

13 I²C BUS INTERFACE (I²C)

13.1 Introduction

The I²C Bus Interface serves as an interface between the microcontroller and the serial I²C bus, providing both multimaster and slave functions and controls all I²C bus-specific sequencing, protocol, arbitration and timing. The I²Bus Interface supports fast I²C mode (400kHz).

13.2 Main Features

- Parallel-bus/I²C protocol converter
- Multi-master capability
- 7-bit/10-bit Addressing
- Transmitter/Receiver flag
- End-of-byte transmission flag
- Transfer problem detection
- Aknowledge Failure Flag

I²C Master Features:

- Clock generation
- I²C bus busy flag
- Arbitration Lost Flag
- End of byte transmission flag
- Transmitter/Receiver Flag
- Start bit detection flag
- Start and Stop generation

I²C Slave Features:

- Stop bit detection
- I²C bus busy flag
- Detection of misplaced start or stop condition
- Programmable I²C Address detection
- Transfer problem detection
- End-of-byte transmission flag
- Transmitter/Receiver flag

13.3 General Description

In addition to receiving and transmitting data, this interface converts it from serial to parallel format and vice versa, using either an interrupt or polled handshake. The interrupts are enabled or disabled via software. The interface is connected to the I²C bus by a data pin (SDA) and by a clock pin (SCL).

The interface can be connected both with a standard I²C bus and a Fast I²C bus. This selection is made via software.

13.3.1 Mode Selection.

The interface can operate in the following four modes:

– Slave transmitter/receiver

– Master transmitter/receiver

By default, it operates in slave mode.

The interface automatically switches from slave to master after it generates a START condition and from master to slave in case of arbitration loss or a STOP generation, providing Multi-Master capability.

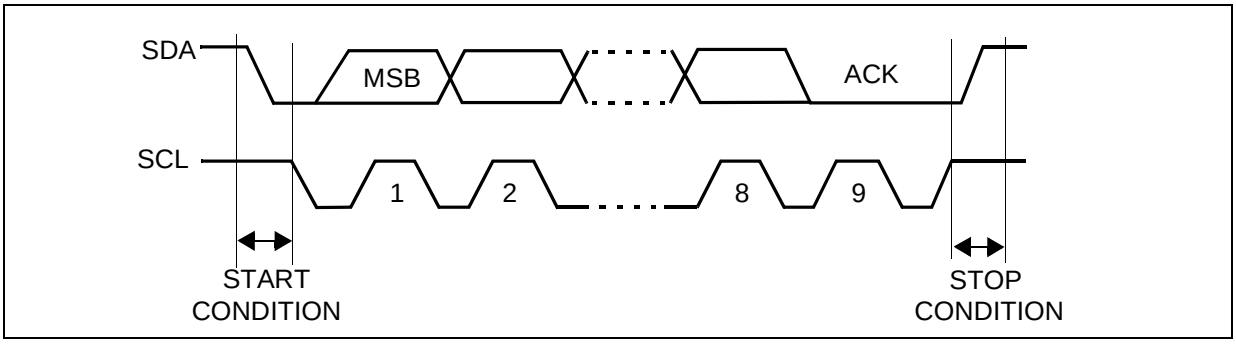
13.3.2 Communication Flow.

In Master mode, Communication Flow initiates data transfer and generates the clock signal. A serial data transfer always begins with a start condition and ends with a stop condition. Both start and stop conditions are generated in master mode by software.

In Slave mode the interface is capable of recognizing its own address (7 or 10-bit) and the General Call address. The General Call address detection may be enabled or disabled by software.

Data and addresses are transferred as 8-bit bytes, (MSB first). The first byte following the start condition is the address (one in 7-bit mode, two in 10-bit mode), which is always transmitted in Master mode.A 9th clock pulse follows the 8 clock cycles of a byte transfer, during which the receiver must send an acknowledge bit to the transmitter. Refer to Figure 13.1.

Figure 13.1 I²C BUS Protocol



Acknowledge may be enabled and disabled via software.

The I^2C interface address and/or general call address can be selected via software.

The speed of the I^2C interface may be selected between Standard (0-100KHz) and Fast I^2C (100-400KHz).

13.3.3 SDA/SCL Line Control.

Transmitter mode: the interface holds the clock line low before transmission, in order to wait for the microcontroller to write the byte in the Data Register.

Receiver mode: the interface holds the clock line low after reception to wait for the microcontroller to read the byte in the Data Register.

SCL frequency is controlled by a programmable clock divider which depends on the I^2C bus mode.

When the I^2C cell is enabled, the SDA and SCL pins must be configured as open-drain with or without pull-up. The value of the external pull-up resistance used depends on the application.

13.4 Functional Description

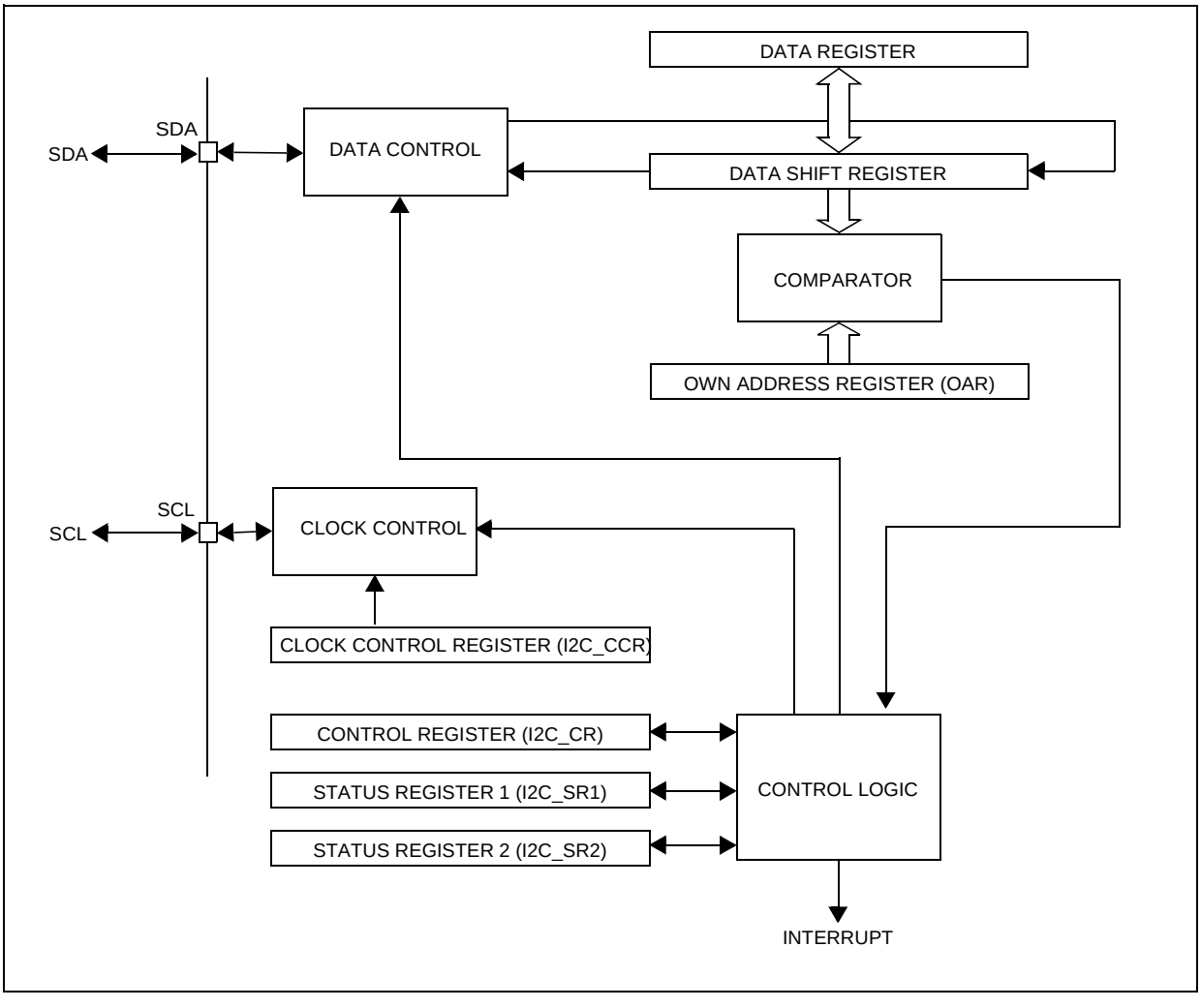
By default the I^2C interface operates in Slave mode (M/SL bit is cleared) except when it initiates a transmit or receive sequence.

First, the interface frequency must be configured using the related bits of the Configuration Registers.

13.4.1 Slave Mode.

As soon as a start condition is detected, the address is received from the SDA line and sent to the shift register; then it is compared with the address of the interface or the General Call address (if selected by software).

Figure 13.2 I^2C Interface Block Diagram



Note: *In 10-bit addressing mode, the comparison includes the header byte (11110xx0) where xx are the two most significant bits of the address.*

Header matched (10-bit mode only): the interface generates an acknowledgement pulse if the ACK bit is set.

Address not matched: the interface ignores it and waits for another Start condition.

Address matched: the interface generates in sequence:

– Acknowledge pulse if the ACK bit is set.

– EVF and ADSL bits are set with an interrupt if the ITE bit is set.

Afterwards, the interface waits for the I2C_SR1 register to be read, **holding the SCL line low** (see Figure 13.3 Transfer sequencing EV1).

Next, in 7-bit mode read the I2C_IN register to determine from the least significant bit (Data Direction Bit) if the slave must enter Receiver or Transmitter mode.

In 10-bit mode, after receiving the address sequence the slave is always in receive mode. It will enter transmit mode on receiving a repeated Start condition followed by the header sequence with matching address bits and the least significant bit set (11110xx1).

Slave Receiver

Following reception of the address and after the I2C_SR1 register has been read, the slave receives bytes from the SDA line into the I2C_IN register via the internal shift register. After each byte, the interface generates the following in sequence:

– Acknowledge pulse if the ACK bit is set

– EVF and BTF bits are set with an interrupt if the ITE bit is set.

Afterwards, the interface waits for the I2C_SR1 register to be read followed by a read of the I2C_IN register, **holding the SCL line low** (see Figure 13.3 Transfer sequencing EV2).

Slave Transmitter

Following the address reception and after the I2C_SR1 register has been read, the slave sends bytes from the I2C_OUT register to the SDA line via the internal shift register.

The slave waits for a read of the I2C_SR1 register followed by a write in the I2C_OUT register, **holding the SCL line low** (see Figure 13.3 Transfer sequencing EV3).

When the acknowledge pulse is received:

– The EVF and BTF bits are set by hardware with an interrupt if the ITE bit is set.

Closing slave communication

After the last data byte is transferred a Stop Condition is generated by the master. The interface detects this condition and sets:

– EVF and STOPF bits with an interrupt if the ITE bit is set.

Afterwards, the interface waits for a read of the I2C_SR2 register (see Figure 13.3 Transfer sequencing EV4).

Error Cases

– **BERR**: Detection of a Stop or a Start condition during a byte transfer. In this case, the EVF and the BERR bits are set with an interrupt if the ITE bit is set.

If it is a Stop then the interface discards the data, releases the lines and waits for another Start condition.

If it is a Start then the interface discards the data and waits for the next slave address on the bus.

– **AF**: Detection of a non-acknowledge bit. In this case, the EVF and AF bits are set with an interrupt if the ITE bit is set.

Note: *In both cases, the SCL line is not held low; however, SDA line can remain low due to possible «0» bits transmitted last. At this point, both lines must be released by software.*

How to release the SDA / SCL lines

Set and subsequently clear the STOP bit while BTF is set. The SDA/SCL lines are released after the current byte is transferred.

13.4.2 Master Mode.

To switch from default Slave mode to Master mode a Start condition generation is needed.

Start condition

Setting the START bit while the BUSY bit is cleared causes the interface to switch to Master mode (M/SL bit set) and generates a Start condition.

Once the Start condition is sent:

– The EVF and SB bits are set by hardware with an interrupt if the ITE bit is set.

Afterwards, the master waits for a read of the I2C_SR1 register followed by a write in the I2C_OUT register with the Slave address, **holding the SCL line low** (see Figure 13.3 Transfer sequencing EV5).

Slave address transmission

At this point, the slave address is sent to the SDA line via the internal shift register.

In 7-bit addressing mode, one address byte is sent.

In 10-bit addressing mode, sending the first byte including the header sequence causes the following event:

– The EVF and ADD10 bit is set by hardware with interrupt generation if the ITE bit is set.

Afterwards, the master waits for a read of the I2C_SR1 register followed by a write in the I2C_OUT register, **holding the SCL line low** (see Figure 13.3 Transfer sequencing EV9).

The second address byte is sent by the interface.

After completion of this transfer (and acknowledge from the slave if the ACK bit is set):

– The EVF bit is set by hardware with interrupt generation if the ITE bit is set.

Afterwards, the master waits for a read of the I2C_SR1 register followed by a write in the I2C_CR register (for example set PE bit), **holding the SCL line low** (see Figure 13.3 Transfer sequencing EV6).

Next, the master must enter Receiver or Transmitter mode.

Note: *In 10-bit addressing mode, in order to switch the master to Receiver mode, software must generate a repeated Start condition and resend the header sequence with the least significant bit set (11110xx1).*

Master Receiver

Following the address transmission and after I2C_SR1 and I2C_CR registers have been accessed, the master receives bytes from the SDA line into the I2C_IN register via the internal shift register. After each byte the interface generates in sequence:

– Acknowledge pulse if the ACK bit is set

– EVFand BTF bits are set by hardware with an interrupt if the ITE bit is set.

Afterwards, the interface waits for a read of the I2C_SR1 register followed by a read of the I2C_IN register, **holding the SCL line low** (see Figure 13.3 Transfer sequencing EV7).

In order to close the communication: before reading the last byte from the I2C_IN register, set the STOP bit to generate the Stop condition. The interface automatically goes back to slave mode (M/SL bit cleared).

Note: *In order to generate the non-acknowledge pulse after the last data byte received, the ACK bit must be cleared just before reading the second last data byte.*

Master Transmitter

Following the address transmission and after the I2C_SR1 register has been read, the master sends bytes from the I2C_OUT register to the SDA line via the internal shift register.

The master waits for a read of the I2C_SR1 register followed by a write in the I2C_OUT register, **holding the SCL line low** (see Figure 13.3 Transfer sequencing EV8).

When the acknowledge bit is received, the interface sets:

– EVF and BTF bits with an interrupt if the ITE bit is set.

In order to close the communication: after writing the last byte to the I2C_OUT register, set the STOP bit to generate the Stop condition. The interface automatically returns to slave mode (M/SL bit cleared).

Error Cases

– **BERR**: Detection of a Stop or a Start condition during a byte transfer. In this case, the EVF and BERR bits are set by hardware with an interrupt if ITE is set.

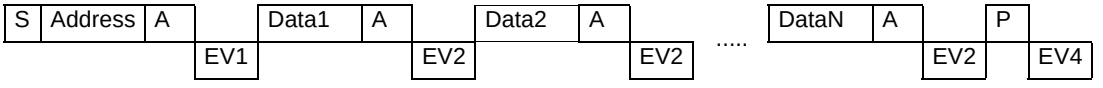
– **AF**: Detection of a non-acknowledge bit. In this case, the EVF and AF bits are set by hardware with an interrupt if the ITE bit is set. To resume, set the START or STOP bit.

– **ARLO**: Detection of an arbitration lost condition. In this case the ARLO bit is set by hardware (with an interrupt if the ITE bit is set and the interface automatically goes back to slave mode (the M/SL bit is cleared).

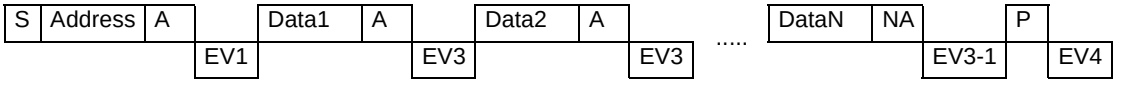
Note: *In all these cases, the SCL line is not held low; however, the SDA line can remain low due to possible «0» bits transmitted last. Both lines must be released via software.*

Figure 13.3 Transfer Sequencing

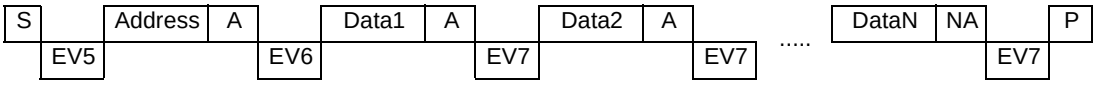
7-bit Slave receiver:



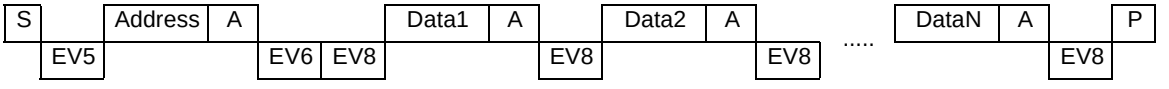
7-bit Slave transmitter:



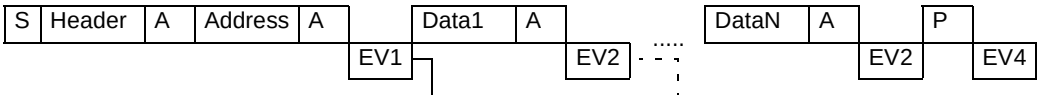
7-bit Master receiver:



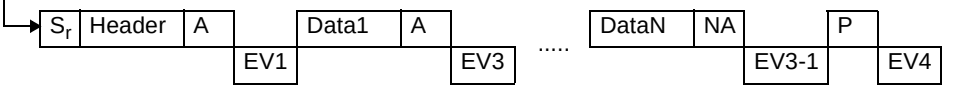
7-bit Master transmitter:



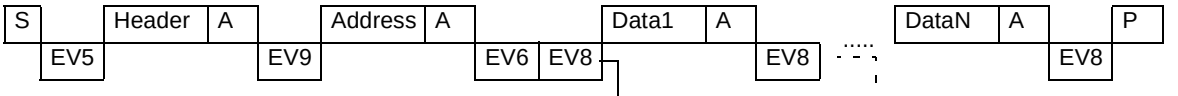
10-bit Slave receiver:



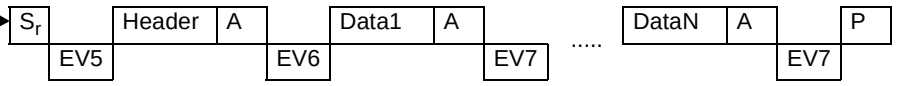
10-bit Slave transmitter:



10-bit Master transmitter:



10-bit Master receiver:



Legend:

S=Start, P=Stop, A=Acknowledge, NA=Non-acknowledge, S_r=Intermediate Start without a previous Sto

EVx=Event (with interrupt if ITE=1)

EV1: EVF=1, ADSL=1, cleared by reading I2C_SR1 register.

EV2: EVF=1, BTF=1, cleared by reading I2C_SR1 register followed by reading I2C_IN register.

EV3: EVF=1, BTF=1, cleared by reading I2C_SR1 register followed by writing I2C_OUT register.

EV3-1: EVF=1, AF=1, BTF=1, SCL=0; AF is cleared by reading I2C_SR2. BTF is cleared by releasing the lines (STOP=1,STOP=0) or by readyng I2C_SR1 and writing I2C_OUT register (I2C_OUT=FFh).**Note:** If lines are released by STOP=1, STOP=0, the subsequent EV4 is not seen. I2C_SR1 and I2C_SR2 registers can be read only after the falling edge of the ninth data clock cycle

EV4: EVF=1, STOPF=1, cleared by reading I2C_SR2 register.

EV5: EVF=1, SB=1, cleared by reading I2C_SR1 register followed by writing I2C_OUT register.

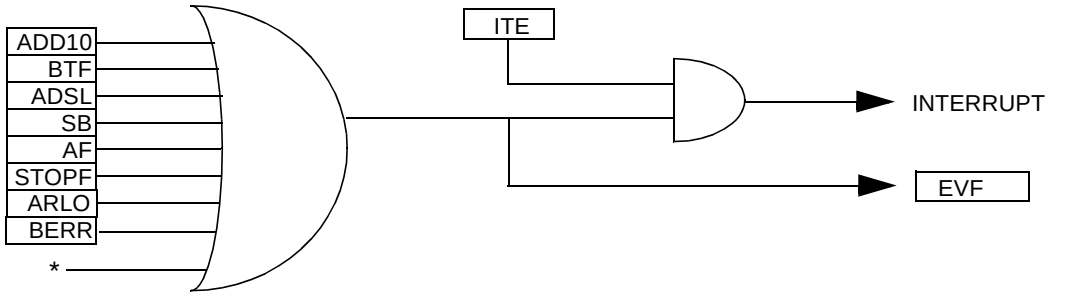
EV6: EVF=1, cleared by reading I2C_SR1 register followed by writing I2C_CR (for example PE=1)

EV7: EVF=1, BTF=1, cleared by reading I2C_SR1 register followed by reading I2C_IN register.

EV8: EVF=1, BTF=1, cleared by reading I2C_SR1, followed by writing I2C_OUT register or an S_r.

EV9: EVF=1, ADD10=1, cleared by reading I2C_SR1 register followed by writing I2C_OUT register

Figure 13.4 Event Flags and Interrupt Generation



* EVF can also be set by EV6 or an error from the I2C_SR2 register.

Interrupt Event	Event Flag	Enable Control Bit	Exit from Wait	Exit from Halt
10-bit Address Sent Event (Master Mode)	ADD10	ITE	Yes	No
End of Byte Transfer Event	BTF		Yes	No
Address Matched Event (Slave Mode)	ADSEL		Yes	No
Start Bit Generation Event (Master Mode)	SB		Yes	No
Acknowledge Failure Event	AF		Yes	No
Stop Detection Event (Slave Mode)	STOPF		Yes	No
Arbitration Lost Event (Multimaster configuration)	ARLO		Yes	No
Bus Error Event	BERR		Yes	No

Note: *The I^2C interrupt events are connected to the same interrupt vector. They generate an interrupt if the corresponding Enable Control Bit (ITE) is set and the Interrupt Mask bit (MSKI2C) in the INT_MASK Configuration Register is unmasked (set to 1, see Interrupts Chapter).*

13.5 Register Description

In the following sections describe the registers used by the I²C Interface are described.

13.5.1 I²C Interface Configuration Registers.

I²C Control Register (I2C_CR)

Configuration Register 16 (010h) Read/Write

Reset Value: 0000 0000 (00h)

7							0
-	-	PE	ENGC	START	ACK	STOP	ITE

Bit 7-6: Not Used.They must be held to 0.

Bit 5: **PE** Peripheral Enable.

This bit is set and cleared by software

0: peripheral disabled

1: peripheral enabled

Notes:

– When PE=0, all the bits of the I2C_CR register and the SR register except the Stop bit are reset. All outputs are released while PE=0

– When PE=1, the corresponding I/O pins are selected by hardware as alternate functions.

– To enable the I²C interface, write the I2C_CR register **TWICE** with PE=1 as the first write only activates the interface (only PE is set).

Bit 4: **ENGC** Enable General Call

This bit is set and cleared by software. It is also cleared by hardware when the interface is disabled (PE=0).

0: General Call disabled

1: General Call enabled

Note: *The 00h General Call address is acknowledged (01h ignored).*

Bit 3: **START** Generation of a Start Condition

This bit is set and cleared by software. It is also cleared by hardware when the interface is disabled (PE=0) or when the Start condition is sent (with interrupt generation if ITE=1).

– In Master Mode

0: No Start generation

1: Repeated Start generation

– In Slave Mode

0: No Start generation

1: Start generation when the bus is free

Bit 2: **ACK** Acknowledge enable

This bit is set and cleared by software. It is also cleared by hardware when the interface is disabled (PE=0).

0: No acknowledge returned

1: Acknowledge returned after an address byte or a data byte is received

Bit 1: **STOP** Generation of a Stop Condition

This bit is set and cleared by software. It is also cleared by hardware in master mode. Note: This bit is not cleared when the interface is disabled (PE=0).

– In Master Mode

0: No Stop generation

1: Stop generation after the current byte transfer or after the current Start condition is sent. The STOP bit is cleared by hardware when the Stop condition is sent.

– In Slave Mode

0: No actions performed

1: Release the SCL and SDA lines after the last byte transfer (BTF=1) in slave transmitter mode. In this mode the STOP bit has to be cleared by software.

Bit 0: **ITE** Interrupt Enable

0: Interrupt disabled

1: Interrupt enabled

I²C Clock Control Register (I2C_CCR)

Configuration Register 17 (011h) Read/Write

Reset Value: 0000 0000 (00h)

7							0
FM/SM	CC6	CC5	CC4	CC3	CC2	CC1	CC0

Bit 7: **FM/SM** Fast/Standard I²C Mode.

This bit is set and cleared by software. It is not cleared when the interface is disabled (PE=0).

1: Standard I^2C Mode (recommended up to 100 kHz)

0: Fast I^2C Mode (recommended up to 400 kHz)

Bit 6-0: **CC6-CC0** 7-bit clock divider

These bits select the speed of the bus (F_{SCL}) depending on the I^2C mode. They are not cleared when the interface is disabled (PE=0). The speed can be computed as follows:

– Standard mode (FM/SM=1): F_{SCL} <= 100kHz

$F_{SCL} = f_{CPU}/(3x[CC6..CC0]+11)$

– Fast mode (FM/SM=0): F_{SCL} > 100kHz

$F_{SCL} = f_{CPU}/(2x[CC6..CC0]+9)$

Warning: *For safety reason, CC6-CC0 bits must be configured with a value >= 3 for the Standard mode and >=2 for the Fast mode.*

I^2C Own Address Register 1 (I2C_OAR1)

Configuration Register 18 (012h) Read/Write

Reset Value: 0000 0000 (00h)

7							0
ADD7	ADD6	ADD5	ADD4	ADD3	ADD2	ADD1	ADD0

7-bit Addressing Mode

bit 7-1: **ADD7-ADD1** Interface address.

These bits define the I^2C bus address of the interface. They are not cleared when the interface is disabled (PE=0).

Bit 0: **ADD0** *Address direction bit.*

This bit is “don’t care”, the interface acknowledges either 0 or 1. It is not cleared when the interface is disabled (PE=0).

Note: *Address 01h is always ignored.*

10-bit Addressing Mode

bit 7-0: **ADD7-ADD0** Interface address.

These are the least significant bits of the I^2C bus address of the interface. They are not cleared when the interface is disabled (PE=0).

I^2C Own Address Register 2 (I2C_OAR2)

Configuration Register 19 (013h) Read/Write

Reset Value: 0000 0000 (00h)

7					2		0
-	-	-	-	-	ADD9	ADD8	-

Bit 7-3: Not Used

bit 2-1: **ADD9-ADD8** Interface address.

These are the most significant bits of the I^2C bus address of the interface (10-bit mode only). They are not cleared when the interface is disabled (PE=0).

Bit 0: Reserved, it must be left to 0.

13.5.2 I^2C Interface Input Registers.

I^2C Data Input Register (I2C_IN)

Input Register 6 (06h) Read only

Reset Value: 0000 0000 (00h)

7							0
I2CDI7	I2CDI6	I2CDI5	I2CDI4	I2CDI3	I2CDI2	I2CDI1	I2CDI0

bit 7-0: **I2CDI7-I2CDI0** Received data.

These bits contain the byte to be received from the bus in Receiver mode: the first data byte is received automatically in the I2C_IN register using the least significant bit of the address.

Then, the next data bytes are received one by one after reading the I2C_IN register.

I^2C Status Register 1 (I2C_SR1)

Input Register 7 (07h) Read only

Reset Value: 0000 0000 (00h)

7							0
EVF	ADD10	TRA	BUSY	BTF	ADSL	M/SL	SB

Bit 7: **EVF** Event Flag

This bit is set by hardware as soon as an event occurs. It is cleared by software reading I2C_SR2 register in case of error event or as described in Figure 13.3. It is also cleared by hardware when the interface is disabled (PE=0).

0: No event

1: One of the following events has occurred:

- BTF=1 (Byte received or transmitted)
- ADSL=1 (Address matched in Slave mode while ACK=1)
- SB=1 (Start condition generated in Master mode)
- AF=1 (No acknowledge received after byte transmission)
- STOPF=1 (Stop condition detected in Slave mode)
- ARLO=1 (Arbitration lost in Master mode)
- BERR=1 (Bus error, misplaced Start or Stop condition detected)
- ADD10=1 Address byte successfully transmitted in Master mode.

Bit 6: **ADD10** 10 bit addressing in Master Mode

This bit is set by hardware when the master has sent the first byte in 10-bit address mode. It is cleared by software reading I2C_SR1 register followed by a write in the I2C_OUT register of the second address byte. It is also cleared by hardware when the peripheral is disabled (PE=0).

0: No ADD10 event occurred

1: The Master has sent the first address byte

Bit 5: **TRA** Transmitter/Receiver

When BTF is set, TRA=1 if a data byte has been transmitted. It is cleared automatically when BTF is cleared. It is also cleared by hardware after detection of Stop condition (STOPF=1), loss of bus arbitration (ARLO=1) or when the interface is disabled (PE=0).

0: Data byte received (if BTF=1)

1: Data byte transmitted

Bit 4: **BUSY** Bus busy

This bit is set by hardware on detection of a Start condition and cleared by hardware either on detection of a Stop condition or when a bus error occurs. It indicates a communication in progress on the bus.

This information is not updated when the interface is disabled (PE=0).

0: No communication on the bus

1: Communication ongoing on the bus

Bit 3: **BTF** Byte transfer finished

This bit is set by hardware as soon as a byte is correctly received or transmitted with interrupt generation if ITE=1. It is cleared by software reading I2C_SR1 register followed by a read of I2C_IN or write of I2C_OUT registers. It is also cleared by hardware when the interface is disabled (PE=0).

- Following a byte transmission, this bit is set after reception of the acknowledge clock pulse. In case an address byte is sent, this bit is set only after the EV6 event (see Figure 13.3). BTF is cleared by reading I2C_SR1 register followed by writing the next byte in I2C_OUT register.
- Following a byte reception, this bit is set after transmission of the acknowledge clock pulse if ACK=1. BTF is cleared by reading I2C_SR1 register followed by reading the byte from I2C_IN register.

The SCL line is held low while BTF=1.

0: Byte transfer not done

1: Byte transfer succeeded

Bit 2: **ADSL** Address matched (Slave Mode)

This bit is set by hardware as soon as the slave address received matched with the OAR register content or a general call is recognized. An interrupt is generated if ITE=1. It is cleared by software reading I2C_SR1 register or by hardware when the interface is disabled (PE=0).

The SCL line is held low while ADSL=1.

0: Address mismatched or not received

1: Received address matched

Bit 1: **M/SL** Master/Slave

This bit is set by hardware as soon as the interface is in Master mode (writing START=1). It is cleared by hardware after detecting a Stop condition on the bus or a loss of arbitration (ARLO=1). It is also cleared when the interface is disabled (PE=0).

0: Slave mode

1: Master mode

Bit 0: **SB** Start bit (Master Mode)

This bit is set by hardware as soon as the Start condition is generated (following a write START=1). An interrupt is generated if ITE=1. It is cleared by software reading I2C_SR1 register followed by writing the address byte in I2C_OUT register. It is also cleared by hardware when the interface is disabled (PE=0).

0: No Start condition

1: Start condition generated

I²C Status Register 2 (I2C_SR2)

Input Register 8 (08h) Read only

Reset Value: 0000 0000 (00h)

7							0
-	-	-	AF	STOPF	ARLO	BERR	GCAL

Bit 7-5: Reserved.

Bit 4: **AF** *Acknowledge failure*.

This bit is set by hardware when no acknowledge is returned. An interrupt is generated if ITE=1. It is cleared by software reading the I2C_SR2 register or by hardware when the interface is disabled (PE=0).

The SCL line is not held low while AF=1.

0: No acknowledge failure

1: Acknowledge failure

Bit 3: **STOPF** *Stop detection (Slave mode).*

This bit is set by hardware when a Stop condition is detected on the bus after an acknowledge (if ACK=1). An interrupt is generated if ITE=1. It is cleared by software reading I2C_SR2 register or by hardware when the interface is disabled (PE=0).

The SCL line is not held low while STOPF=1.

0: No Stop condition detected

1: Stop condition detected

Bit 2: **ARLO** *Arbitration lost*.

This bit is set by hardware when the interface loses the arbitration of the bus to another master. An interrupt is generated if ITE=1. It is cleared by software reading I2C_SR2 register or by hardware when the interface is disabled (PE=0).

After an ARLO event the interface switches back automatically to Slave mode (M/SL=0).

The SCL line is not held low while ARLO=1.

0: No arbitration lost detected

1: Arbitration lost detected

Bit 1: **BERR** *Bus error.*

This bit is set by hardware when the interface detects a misplaced Start or Stop condition. An interrupt is generated if ITE=1. It is cleared by software reading I2C_SR2 register or by hardware when the interface is disabled (PE=0).

The SCL line is not held low while BERR=1.

0: No misplaced Start or Stop condition

1: Misplaced Start or Stop condition

Note: *Also a polling on BUSY bit has to be done to detect a bus error (BUSY bit cleared by hardware).*

Bit 0: **GCAL** *General Call (Slave mode).*

This bit is set by hardware when a general call address is detected on the bus while ENGC=1. It is cleared by hardware detecting a Stop condition (STOPF=1) or when the interface is disabled (PE=0).

0: No general call address detected on bus

1: general call address detected on bus

13.5.3 I²C Interface Output Registers.

I²C Data Output Register (I2C_OUT)

Output Register 6 (06h) Write only

Reset Value: 0000 0000 (00h)

7							0
I2CDO7	I2CDO6	I2CDO5	I2CDO4	I2CDO3	I2CDO2	I2CDO1	I2CDO0

bit 7-0: **I2CDO7-I2CDO0** Data to be transmitted.

These bits contain the byte to be transmitted in the bus in Transmitter mode: Byte transmission start automatically when the software writes in the I2C_OUT register.

14 SERIAL PERIPHERAL INTERFACE (SPI)

14.1 Introduction

The Serial Peripheral Interface (SPI) allows full-duplex, synchronous, serial communication with external devices. An SPI system may consist of a master, one or more slaves, or a system, in which devices may be either masters or slaves.

SPI is normally used for communication between the ICU and external peripherals or another ICU.

Refer to the Pin Description section in this datasheet for the device-specific pin-out.

14.2 Main Features

- Full duplex, three-wire synchronous transfers
- Master or slave operation
- Four master mode frequencies
- Maximum slave mode frequency = fCKM/4.
- Four programmable master bit rates
- Programmable clock polarity and phase
- End of transfer interrupt flag
- Write collision flag protection
- Master mode fault protection capability.

14.3 General description

SPI is connected to external devices through 4 alternate pins:

– MISO: Master In / Slave Out pin
– MOSI: Master Out / Slave In pin
– SCK: Serial Clock pin
– $\overline{SS}$: Slave select pin (if not done through software)

A basic example of interconnections between a single master and a single slave is illustrated in Figure 14.1

The MOSI pins are connected together as the MISO pins. In this manner, data is transferred serially between master and slave (most significant bit first).

When the master device transmits data to a slave device via the MOSI pin, the slave device responds by sending data to the master device via the MISO pin. This implies full duplex transmission with both data out and data in synchronized with the same clock signal (which is provided by the master device via the SCK pin).

The transmitted byte is replaced by the byte received and eliminates the need for separate transmit-empty and receiver-full bits. A status flag is used to indicate that the I/O operation is complete.

Four possible data/clock timing relationships may be chosen (see Figure 14.4), but master and slave must be programmed with the same timing mode.

14.4 Functional Description

Figure 14.2 shows the serial peripheral interface (SPI) block diagram.

This interface contains 4 dedicated registers:

– A Control Register (SPI_CR)
– A Status Register (SPI_STATUS_CR)
– A Data Register for transmission (SPI_OUT)
– A Data Register for reception (SPI_OUT)

14.4.1 Master Configuration.

In a master configuration, the serial clock is generated on the SCK pin.

Figure 14.1 SPI Master Slave

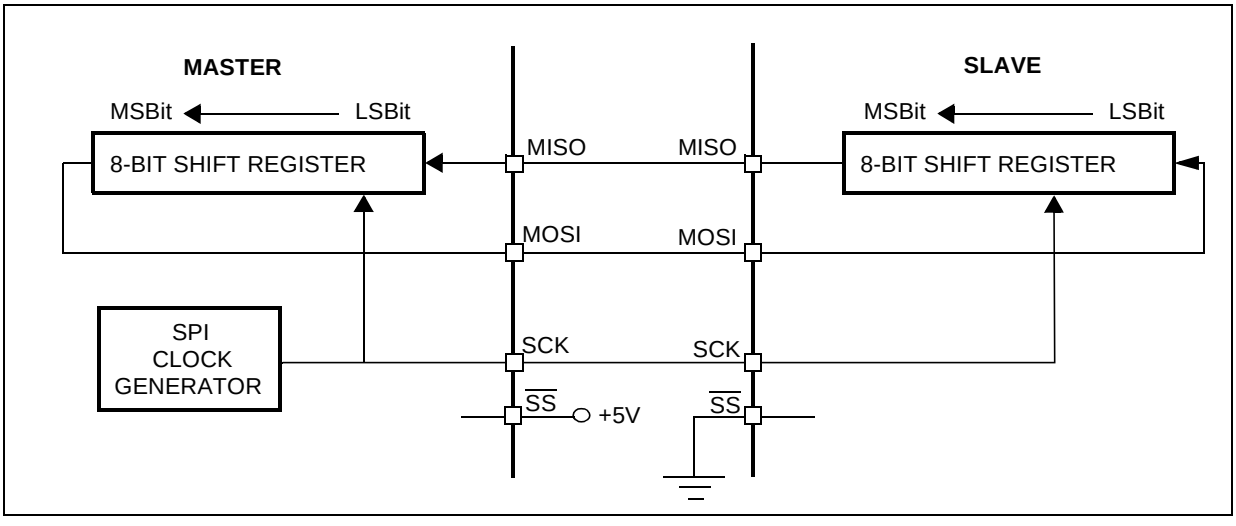
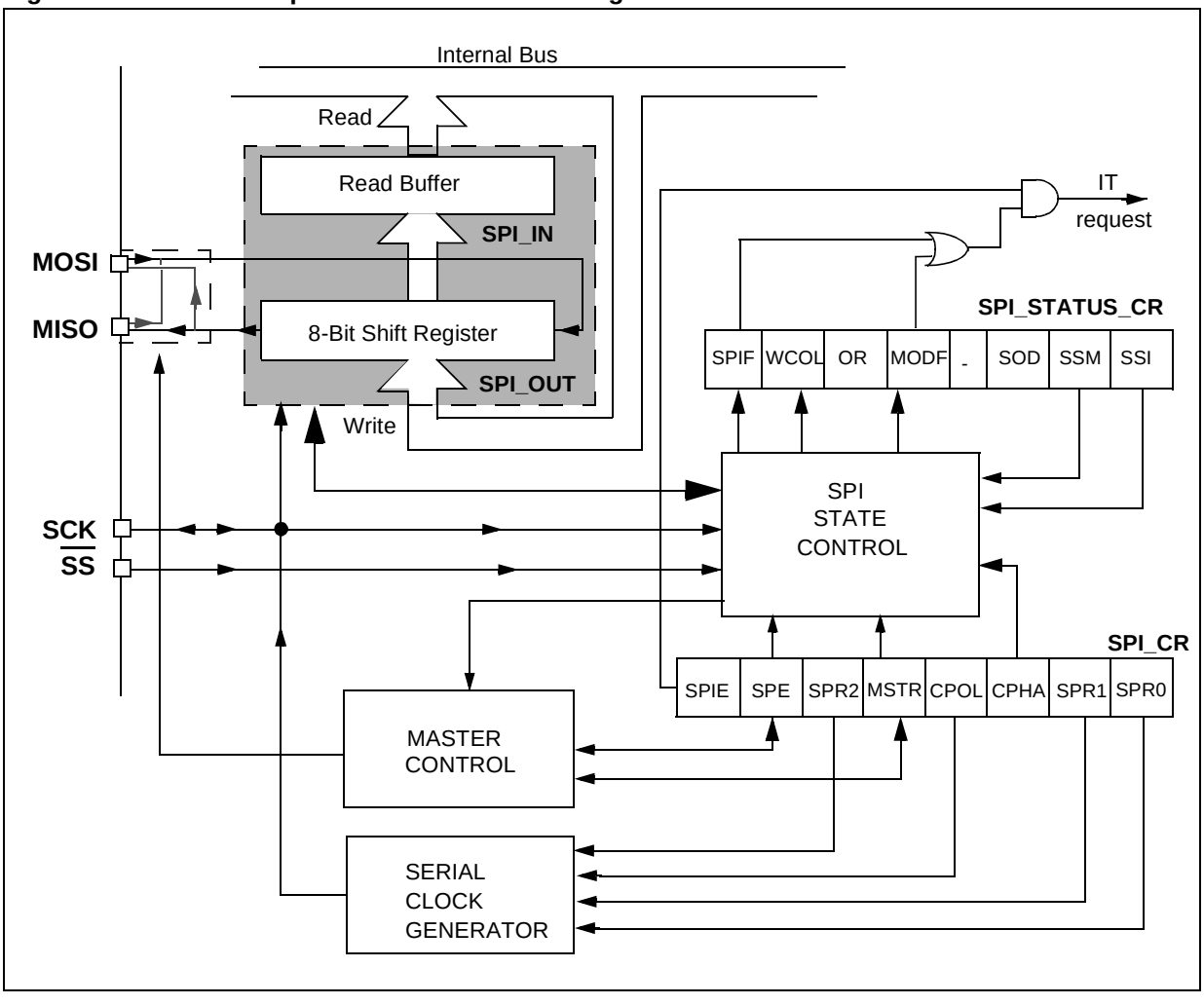


Figure 14.2 Serial Peripheral Interface Block Diagram



Procedure

– Select the SPR0, SPR1 and SPR2 bits to define the serial clock baud rate (see SPI_CR register).
– Select the CPOL and CPHA bits to define one of the four relationships between the data transfer and the serial clock (see Figure 14.4).
– The $\overline{SS}$ pin must be connected to a high level signal during the complete byte transmit sequence, if this pin is used.
– The MSTR and SPE bits must be set (they remain set only if the $\overline{SS}$ pin is connected to a high level signal).

In this configuration the MOSI pin is a data output and to the MISO pin is a data input.

Transmit sequence

Transmit sequence begins when a byte is written in the SPI_OUT register.

The data byte is loaded in parallel into the 8-bit shift register (from the internal bus) during a write cycle and then shifted out serially to the MOSI pin most significant bit first.

When data transfer is complete:

– The SPIF bit is set by hardware
– An interrupt is generated if the SPIE bit is set.

During the last clock cycle the SPIF bit is set, a copy of the data byte received in the shift register is moved to a buffer. When the SPI_IN register is read, the SPI peripheral returns this buffered value. Clearing the SPIF bit is performed by the following software sequence:

1. An access to the SPI_STATUS_CR register while the SPIF bit is set
2. A read to the SPI_IN register.

Note: *While the SPIF bit is set, all writes to the SPI_OUT register are inhibited until the SPI_STATUS_CR register is read.*

14.4.2 Slave Configuration.

In slave configuration, the serial clock is received on the SCK pin from the master device.

The value of the SPR0, SPR1 and SPR2 bits is not used for data transfer.

Procedure

– For correct data transfer, the slave device must be in the same timing mode as the master device (CPOL and CPHA bits). See Figure 14.4.
– The $\overline{SS}$ pin must be connected to a low level signal during the complete byte transmit sequence, if this pin is used.
– Clear the MSTR bit and set the SPE bit to assign the pins to alternate function.

In this configuration the MOSI pin is a data input and the MISO pin is a data output.

Transmit Sequence

The data byte is loaded into the 8-bit shift register (from the internal bus) during a write cycle and then shifted out serially to the MISO pin most significant bit first.

The transmit sequence begins when the slave device receives the clock signal and the most significant bit of the data on its MOSI pin.

When data transfer is complete:

– The SPIF bit is set by hardware
– An interrupt is generated if SPIE bit is set.

During the last clock cycle the SPIF bit is set, a copy of the data byte received in the shift register is moved to a buffer. When the SPI_IN register is read, the SPI peripheral returns the buffer value.

The SPIF bit is cleared by the following software sequence:

1. An access to the SPI_STATUS_CR register while the SPIF bit is set.
2. A read to the SPI_IN register.

Note: *While the SPIF bit is set, all writes to the SPI_OUT register are inhibited until the SPI_STATUS_CR register is read.*

The SPIF bit can be cleared during a second transmission; however, it must be cleared before the second SPIF bit in order to prevent an overrun condition (see Section 14.4.6).

Depending on the CPHA bit, the $\overline{SS}$ pin has to be set to write to the SPI_OUT register between each data byte transfer to avoid a write collision (see Section 14.4.4).

14.4.3 Data Transfer Format.

During an SPI transfer, data is simultaneously transmitted (shifted out serially) and received (shifted in serially). The serial clock is used to synchronize data transfer during a sequence of eight clock pulses.

The $\overline{SS}$ pin allows individual selection of a slave device; the other slave devices that are not selected do not interfere with SPI transfer.

Clock Phase and Clock Polarity

Four possible timing relationships may be chosen by software, using the CPOL and CPHA bits.

The CPOL (clock polarity) bit controls the steady state value of the clock when data isn't being transferred. This bit affects both master and slave modes.

The combination between the CPOL and CPHA (clock phase) bits select the data capture clock edge.

Figure 14.4, shows an SPI transfer with the four combinations of the CPHA and CPOL bits. The diagram may be interpreted as a master or slave timing diagram where the SCK pin, the MISO pin, the MOSI pin are directly connected between the master and the slave device.

The $\overline{SS}$ pin is the slave device select input and can be driven by the master device.

The master device applies data to its MOSI pin-clock edge before the capture clock edge.

CPHA bit is set

The second edge on the SCK pin (falling edge if the CPOL bit is reset, rising edge if the CPOL bit is set) is the MSBit capture strobe. Data is latched on the occurrence of the second clock transition.

A write collision should not occur even if the $\overline{SS}$ pin stays low during a transfer of several bytes (see Figure 14.3).

CPHA bit is reset

The first edge on the SCK pin (falling edge if CPOL bit is set, rising edge if CPOL bit is reset) is the MSBit capture strobe. Data is latched on the occurrence of the first clock transition.

The $\overline{SS}$ pin must be toggled high and low between each byte transmitted (see Figure 14.3).

In order to protect the transmission from a write collision a low value on the $\overline{SS}$ pin of a slave device freezes the data in its SPI_OUT register and does not allow it to be altered. Therefore, the $\overline{SS}$ pin must be high to write a new data byte in the SPI_OUT without producing a write collision.

14.4.4 Write Collision Error.

A write collision occurs when the software tries to write to the SPI_OUT register while a data transfer

is taking place with an external device. When this occurs, the transfer continues uninterrupted; and the software writing will be unsuccessful.

Write collisions can occur both in master and slave mode.

Note: *a "read collision" will never occur since the data byte received is placed in a buffer, in which access is always synchronous with the ICU operation.*

In Slave mode

When the CPHA bit is set:

The slave device will receive a clock (SCK) edge prior to the latch of the first data transfer. This first clock edge will freeze the data in the slave device SPI_OUT register and output the MSBit on to the external MISO pin of the slave device.

The $\overline{SS}$ pin low state enables the slave device, but the output of the MSBit onto the MISO pin does not take place until the first data transfer clock edge occurs.

When the CPHA bit is reset:

Data is latched on the occurrence of the first clock transition. The slave device doesn't have a way of knowing when that transition will occur; therefore, the slave device collision occurs when software attempts to write the SPI_OUT register after its $\overline{SS}$ pin has been pulled low.

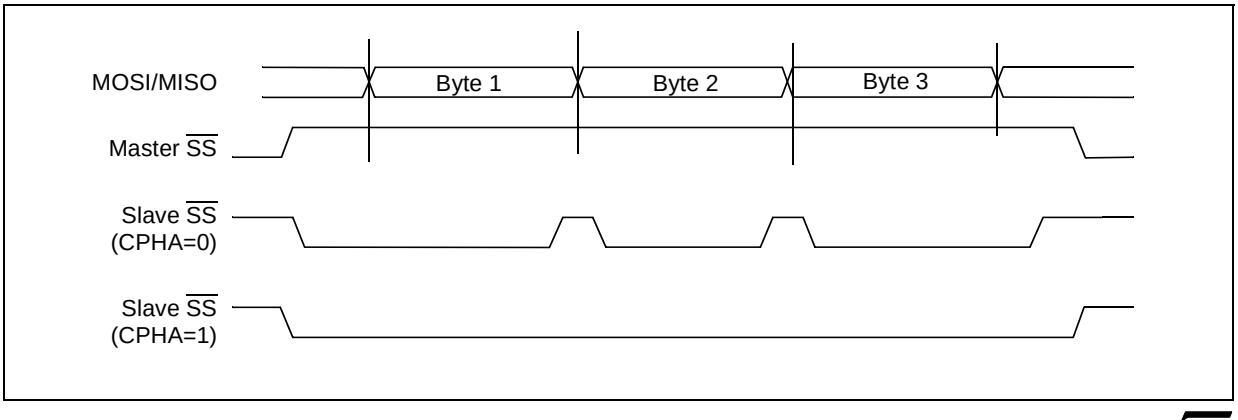
For this reason, the $\overline{SS}$ pin must be high, between each data byte transfer, in order to allow the CPU to write in the SPI_OUT register without generating a write collision.

In Master mode

Collision in the master device is defined as a write of the SPI_OUT register, while the internal serial clock (SCK) is in the process of transfer.

The $\overline{SS}$ pin signal must always be high on the master device.

Figure 14.3 CHPA/$\overline{SS}$ Timing Diagram



WCOL bit

The WCOL bit in the SPI_STATUS_CR register is set if a write collision occurs.

No SPI interrupt is generated when the WCOL bit is set (the WCOL bit is a status flag only).

The WCOL bit is cleared by a software sequence (see Section 14.5).

14.4.5 Master Mode Fault.

Master mode fault occurs when the master device has its $\overline{SS}$ pin pulled low, then the MODF bit is set.

Master mode fault affects the SPI peripheral in the following ways:

– The MODF bit is set and an SPI interrupt is generated if the SPIE bit is set.

– The SPE bit is reset. This blocks all output from the device and disables the SPI peripheral.

– The MSTR bit is reset, forcing the device into slave mode.

Clearing the MODF bit is done through a software sequence:

1. A read or write access to the SPI_STATUS_CR register while the MODF bit is set.
2. A write to the SPI_CR register.

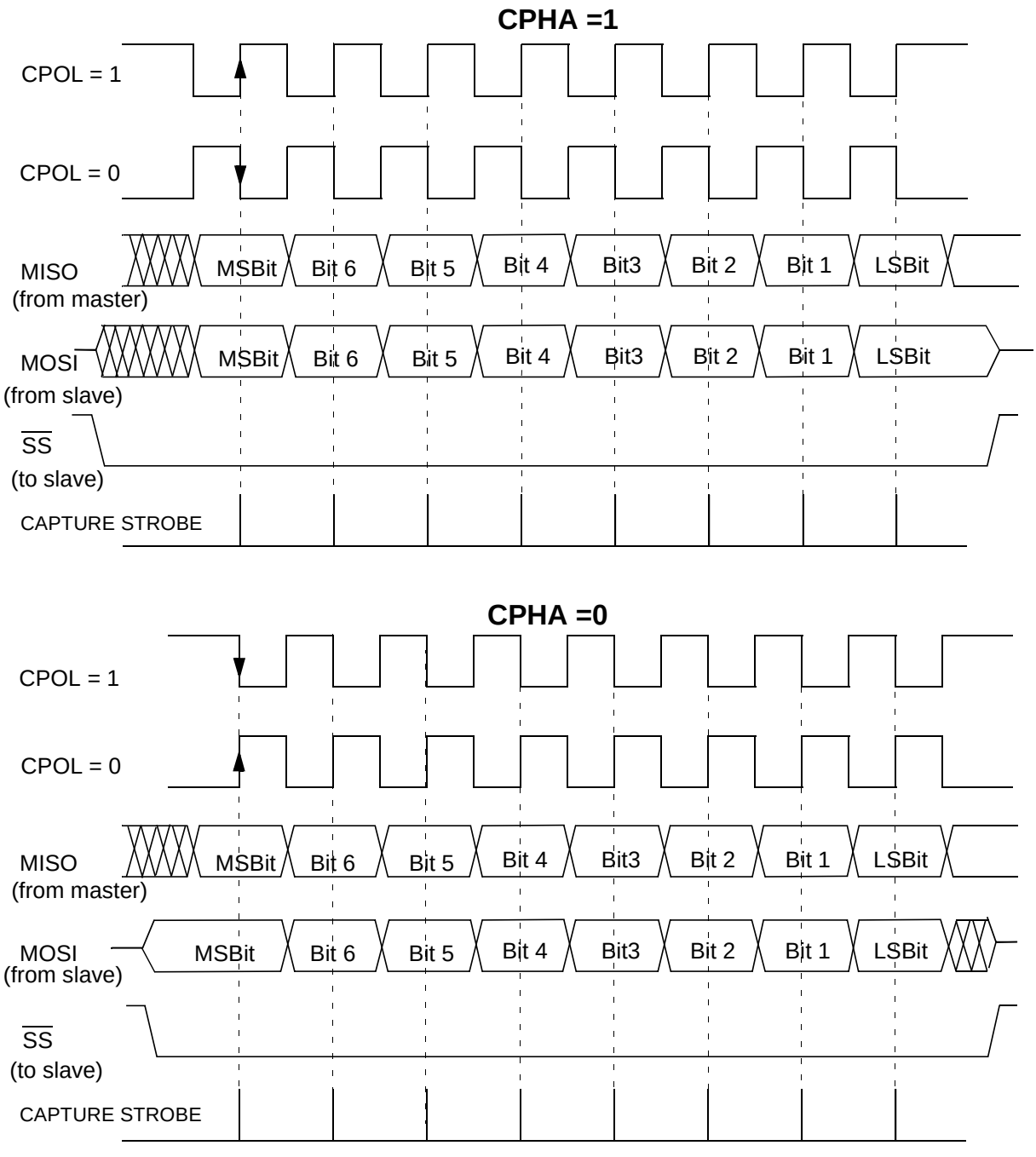
Note: *To avoid any multiple slave conflicts in the case of a system comprising several MCUs, the $\overline{SS}$ pin must be pulled high during the clearing sequence of the MODF bit. The SPE and MSTR bits may be restored to their original state during or after this clearing sequence.*

Hardware does not allow the user to set the SPE and MSTR bits, while the MODF bit is set (except in the MODF bit clearing sequence).

In a slave device the MODF bit can't be set, but in a multi master configuration the device can be in slave mode with this MODF bit set.

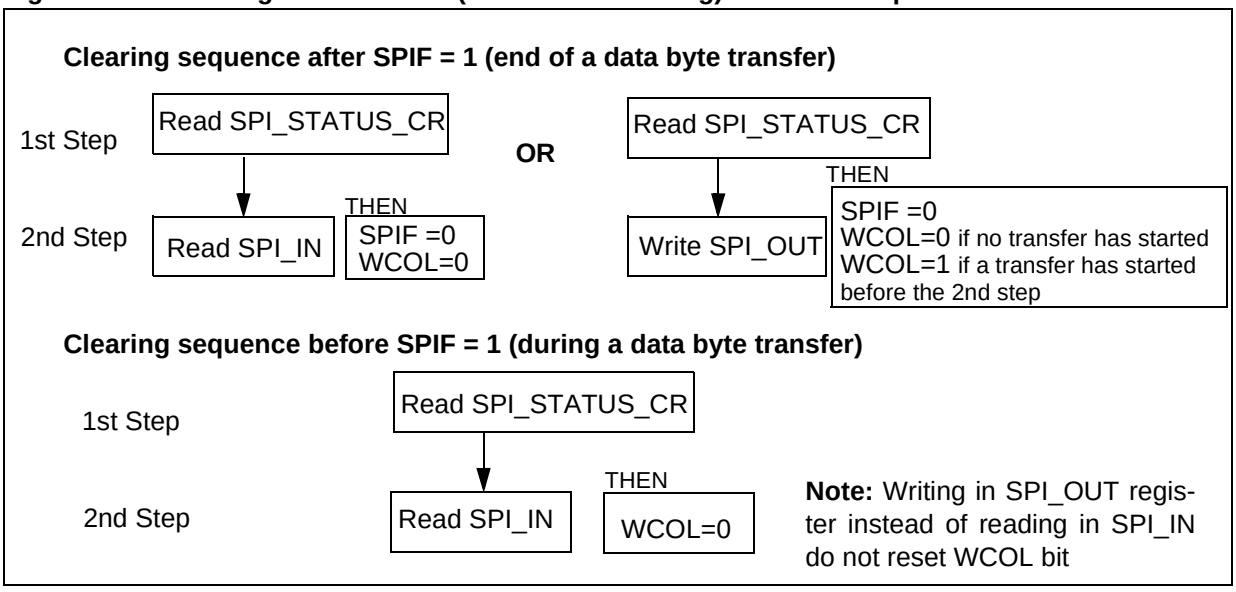
The MODF bit indicates that there might have been a multi-master conflict for system control and allows a proper exit from system operation to a reset or default system state using an interrupt routine.

Figure 14.4 Data Clock Timing Diagram



Note: This figure should not be used as a replacement for parametric information. Refer to the Electrical Characteristics chapter.

Figure 14.5 Clearing the WCOL bit (Write Collision Flag) Software Sequence



14.4.6 Overrun Condition.

An overrun condition occurs when the master device has sent several data bytes and the slave device hasn't cleared the SPIF bit issued from the previous data byte transmitted.

In this case, the receiver buffer contains the byte sent after the SPIF bit was last cleared. A read to the SPI_IN register returns this byte. All other bytes are lost.

This condition is not detected by the SPI peripheral.

14.4.7 Single Master and Multimaster Configurations.

There are two types of SPI systems:

– Single Master System

– Multimaster System

Single Master System

A typical single master system may be configured, using an ICU as the master and four ICUs as slaves (see Figure 14.6).

The master device selects the individual slave devices by using four pins of a parallel port to control the four $\overline{SS}$ pins of the slave devices.

The $\overline{SS}$ pins are pulled high during reset since the master device ports will be forced to be inputs at that time, thus disabling the slave devices.

Note: *In order to prevent a bus conflict on the MISO line the master allows only one active slave device during a transmission.*

For more security, the slave device may respond to the master with the data byte received. Then the master will receive the previous byte back from the slave device if all MISO and MOSI pins are connected and the slave has not written its SPI_OUT register.

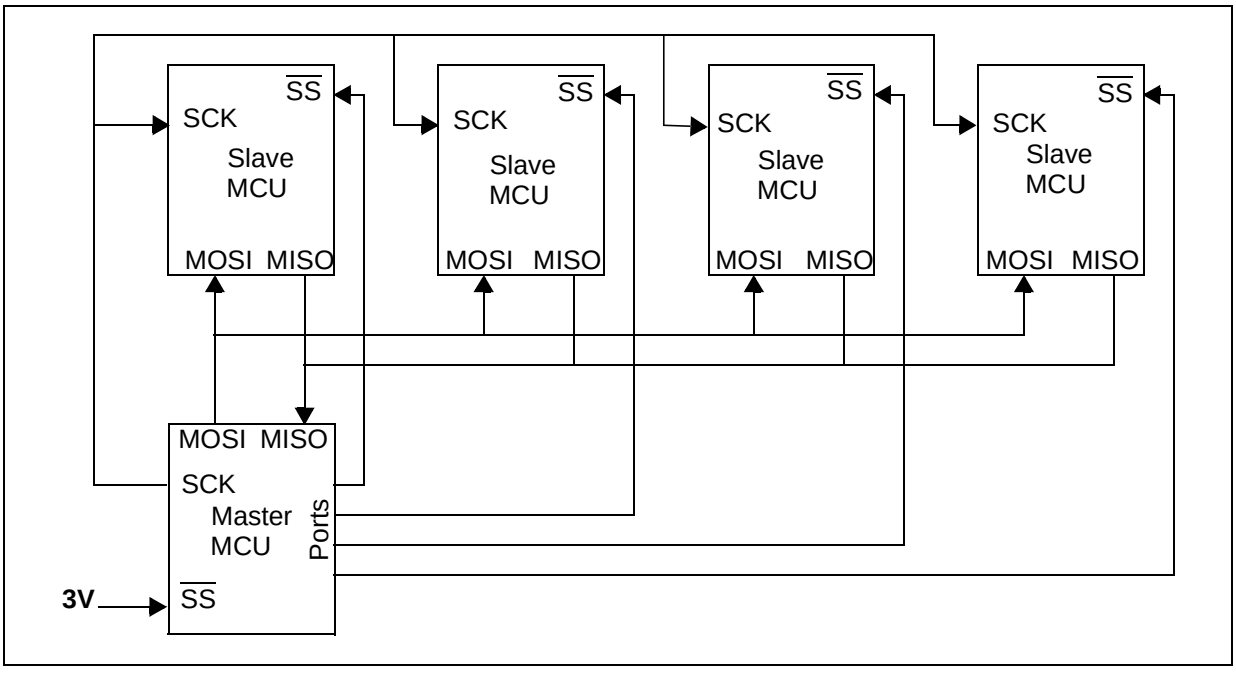
Other transmission security methods can use ports for handshake lines or data bytes with command fields.

Multi-master System

A multi-master system may also be configured by the user. Transfer of master control could be implemented using a handshake method through the I/O ports or by an exchange of code messages through the serial peripheral interface system.

The multi-master system is principally handled by the MSTR bit in the SPI_CR register and the MODF bit in the SPI_STATUS_CR register.

Figure 14.6 Single Master Configuration



14.4.8 Interrupts

Interrupt Event	Event Flag	Enable Control Bit	Exit from Wait	Exit from Halt
SPI End of Transfer Event	SPIF	SPIE	Yes	No
Master Mode Fault Event	MODF		Yes	No

Note: *The SPI interrupt events are connected to the same interrupt vector (see Interrupts chapter). They generate an interrupt if the corresponding Enable Control Bit (SPIE) and the interrupt mask bit (MSKSPI) in the INT_MASK Configuration Register is set.*

14.5 SPI Register Description

In the following sections describe the registers used by the SPI. In the 16 pin devices the SPI is not present and the described register aren't used

14.5.1 SPI Configuration Registers.

SPI Control Register (SPI_CR)

Configuration Register 20 (014h) Read/Write

Reset Value: 0000 0000 (00h)

7							0
SPIE	SPE	SPR2	MSTR	CPOL	CPHA	SPR1	SPR2

Bit 7: **SPIE** Serial peripheral interrupt enable.

This bit is set and cleared by software.

0: Interrupt is inhibited

1: An SPI interrupt is generated whenever SPIF=1 or MODF=1 in SPI_STATUS_CR

Bit 6: **SPE** Serial peripheral output enable.

This bit is set and cleared by software. It is also cleared by hardware when, in master mode, SS=0 (see Section 14.4.5 Master Mode Fault).

0: I/O port connected to pins

1: SPI alternate functions connected to pins

Note: *The SPE bit is cleared by reset, so the SPI peripheral is not initially connected to the pins.*

Bit 5: **SPR2** Divider Enable.

This bit is set and cleared by software and it is cleared by reset. It is used with the SPR[1:0] bits to set the baud rate. Refer to Table 14.1.

0: Divider by 2 enabled

1: Divider by 2 disabled

Note: *This bit has no effect in slave mode.*

Bit 4: **MSTR** Master/Slave mode select.

This bit is set and cleared by software. It is also cleared by hardware when, in master mode, SS=0 (see Section 14.4.5 Master Mode Fault).

0: Slave mode is selected

1: Master mode is selected, the function of the SCK pin changes from an input to an output and the functions of the MISO and MOSI pins are reversed.

Bit 3: **CPOL** Clock polarity.

This bit is set and cleared by software. This bit determines the steady state of the serial Clock. The CPOL bit affects both the master and slave modes.

0: The steady state is a low value at the SCK pin.

1: The steady state is a high value at the SCK pin.

Note: *SPI must be disabled by resetting the SPE bit if CPOL is changed at the communication byte boundaries.*

Bit 2: **CPHA** Clock phase.

This bit is set and cleared by software.

0: The first clock transition is the first data capture edge.

1: The second clock transition is the first capture edge.

Bit 1-0: **SPR1**-**SPR0** Serial peripheral rate.

These bits are set and cleared by software. Used with the SPR2 bit, they select one of six baud rates to be used as the serial clock when the device is a master (see Table 14.1).

These 2 bits have no effect in slave mode.

Remark: *It is recommended to write the SPI_CR register after the SPI_STATUS_CR register when working in master mode, vice versa when working in slave mode.*

Table 14.1 Serial Peripheral Baud Rate

Serial Clock	SPR2	SPR1	SPR0
$f_{CKM}/2$	1	0	0
$f_{CKM}/4$	0	0	0
$f_{CKM}/8$	0	0	1
$f_{CKM}/16$	1	1	0
$f_{CKM}/32$	0	1	0
$f_{CKM}/64$	0	1	1

SPI Control-Status Register (SPI_STATUS_CR)

Configuration Register 21 (015h) Read/Write

Reset Value: 0000 0000 (00h)

7							0
SPIF	WCOL	OR	MODF	-	SOD	SSM	SSI

Bit 7: **SPIF** Serial Peripheral data transfer flag. (read only)

This bit is set by hardware when a transfer has been completed. An interrupt is generated if SPIE=1 in the SPI_CR register. It is cleared by a software sequence (an access to the SPI_STATUS_CR register followed by a read or write to the SPI_IN/ SPI_OUT registers).

0: Data transfer is in progress or has been approved by a clearing sequence.

1: Data transfer between the device and an external device has been completed.

Note: *While the SPIF bit is set, all writes to the SPI_OUT register are inhibited.*

Bit 6: **WCOL** Write Collision status (read only).

This bit is set by hardware when a write to the SPI_OUT register is done during a transmit sequence. It is cleared by a software sequence (see Figure 14.5).

0: No write collision occurred

1: A write collision has been detected

Bit 5: **OR** SPI overrun error (read only).

This bit is set by hardware when the byte currently being received in the shift register is ready to be transferred into the SPI_IN register while SPIF = 1 (See Section 14.4.6 Overrun Condition). It is cleared by a software sequence (read of the SPI_STATUS_CR register followed by a read in SPI_IN or write of the SPI_OUT register).

0: No overrun error.

1: Overrun error detected.

Bit 4: **MODF** Mode Fault flag (read only).

This bit is set by hardware when the $\overline{SS}$ pin is pulled low in master mode (see Section 14.4.5 Master Mode Fault). An SPI interrupt can be generated if SPIE=1 in the SPI_CR register. This bit is cleared by a software sequence (An access to the SPI_STATUS_CR register while MODF=1 followed by a write to the SPI_CR register).

0: No master mode fault detected

1: A fault in master mode has been detected

Bit 3: Not used.

Bit 2: **SOD** SPI output disable

This bit is set and cleared by software. When set, it disables the alternate function of the SPI output (MOSI in master mode / MISO in slave mode)

0: SPI output not disable

1: SPI output disable.

Bit 1: **SSM** $\overline{SS}$ mode selection

This bit is set and cleared by software. When set, it disables the alternate function of the SPI Slave Select pin and use the SSI bit value instead of.

0: $\overline{SS}$ pin used by the SPI.

1: $\overline{SS}$ pin not used (I/O mode), SSI bit value is used.

Bit 0: **SSI** $\overline{SS}$ internal mode

This bit is set and cleared by software. It replaces pin $\overline{SS}$ of the SPI when bit SSM is set to 1. SSI bit is active low slave select signal when SSM is set to 1.

0 : Slave selected

1 : Slave not selected.

Remark: *It is recommended to write the SPI_CR register after the SPI_STATUS_CR register when working in master mode, vice versa when working in slave mode.*

14.5.2 SPI Input Register.

SPI Data Input Register (SPI_IN)

Input Register 5 (05h) Read only

Reset Value: 0000 0000 (00h)

7							0
SPIDI7	SPIDI6	SPIDI5	SPIDI4	SPIDI3	SPIDI2	SPIDI1	SPIDI0

bit 7-0: **SPIDI7-SPIDI0** Received data.

The SPI_IN register is used to receive data on the serial bus.

Note: *During the last clock cycle the SPIF bit is set, a copy of the data byte received in the shift register is moved to a buffer. When the user reads the serial peripheral data I/O register, the buffer is actually being read.*

Warning: *A read to the SPI_IN register returns the value located in the buffer and not the contents of the shift register (see Figure 14.2).*

14.5.3 SPI Output Register.

SPI Data Output Register (SPI_OUT)

Output Register 5 (05h) Write only

Reset Value: 0000 0000 (00h)

7							0
SPIDO7	SPIDO6	SPIDO5	SPIDO4	SPIDO3	SPIDO2	SPIDO1	SPIDO0

bit 7-0: **SPIDO7-SPIDO0** Data to be transmitted.

The SPI_OUT register is used to transmit data on the serial bus. In the master device only a write to this register will initiate transmission/reception of another byte.

Warning: *A write to the SPI_OUT register places data directly into the shift register for transmission.*

15 REVISION HISTORY

Table 15.1

Date	Revision	Description of Changes
April 04	1.10	Table 4.1 Sales Types Memory Organization on page 28 modified Table 4.2 Programming Mode Commands on page 29 ByteRead command description modified Table 4.3 Error codes on page 34 modified Paragraph 5.6 Register Description on page 39 **High Priority Register (INT_PRL_H)** (PRL24-PRL0) became (PRL23-PRL0) Paragraph 6.2.1 External Reset on page 42 “An internal pull up...” sentence modified Paragraph 7.1 Introduction on page 49 Added note Paragraph 8.5 Input Membership Function on page 56 Rows 6 and 7 exchanged Paragraph 10.2 Register Description on page 64 WDT_CR exadecimal value modified to 1 Figure 11.6 PWM/Timer 0 Register Description on page 72 modified (STRMOD, RESMOD, RESPOL) description Paragraph 11.7.2 PWM/Timer 1 Input Registers on page 76 **PWM/Timer 1 Status Register (PWM1_STATUS)** bit description modified Paragraph 12.4.3 SCI Output Register on page 84 row 2 “input register” became “output register” Paragraph 13.3.2 Communication Flow on page 85 small modifications Chapter 15 REVISION HISTORY on page 105 added
May 04	1.11	All hyperlink coloured in blue Document pagination modified All references to RC external oscillator removed Section 6.1 Clock on page 41 warning added Section 13.5.2 I2C Interface Input Registers on page 92 “Bit 4: **BUSY** Bus busy” modified. “Bit 1: **BERR** *Bus error”* added note

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