# 3361 AND 3362 

## 2-WIRE, CHOPPER-STABILIZED, HALL-EFFECT SWITCHES



Pinning is shown viewed from branded side.
ABSOLUTE MAXIMUM RATINGSat $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$Supply Voltage, $\mathrm{V}_{\mathrm{CC}}$26.5 V
Reverse Battery Voltage, $\mathrm{V}_{\text {RCC }}$ ..... -16 V
Magnetic Flux Density, B

$\qquad$
UnlimitedPackage Power Dissipation, $P_{D}$. See GraphJunction Temperature, $\mathrm{T}_{\mathrm{J}}$
$\qquad$ $+170^{\circ} \mathrm{C}$
Operating Temperature Range,
$\qquad$
Storage Temperature Range,

$$
\mathrm{T}_{\mathrm{S}}
$$

$\qquad$ $-65^{\circ} \mathrm{C}$ to $+170^{\circ} \mathrm{C}$

The A3361x and A3362x Hall-effect switches are extremely temperature-stable and stress-resistant sensors. Superior performance over temperature is made possible through dynamic offset cancellation, which reduces the residual offset voltage normally caused by device overmolding, temperature dependencies, and thermal stress. The two devices differ only in output polarity; the A3361x output current goes low in the presence of a south pole of sufficient strength; the A3362x output current goes high.

Each device includes on a single silicon chip a voltage regulator, Hall-voltage generator, small-signal amplifier, chopper stabilization, Schmitt trigger, and a constant-current open-collector output. An on-board regulator permits operation with supply voltages of 3.5 to 24 volts. Noise radiation is limited by control of the output current slew rate.

Three package styles provide a magnetically optimized package for most applications. Suffix 'xLH' is a miniature SOT23W low-profile surface-mount package, and suffix 'xUA' is a three-lead ultra-mini SIP for through-hole mounting.

## FEATURES

- Internal Current Regulator for 2-Wire Operation
- Resistant to Physical Stress
- Superior Temperature Stability
- Operation From Unregulated Supply
- Solid-State Reliability

■ Small Size

Always order by complete part number: the prefix ' A ' + the basic four-digit part number + a suffix to indicate operating temperature range (E) + a two-letter suffix to indicate package style, e.g., A3361ELH.

FUNCTIONAL BLOCK DIAGRAM


Suffix Code 'UA' Pinning
(ultra-mini SIP)


Dwg. PH-003-7A
Pinning is shown viewed from branded side.

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ELECTRICAL CHARACTERISTICS over operating temperature range.

| Characteristic | Symbol | Test Conditions | Limits |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. | Typ. | Max. | Units |
| Supply Voltage | $\mathrm{V}_{\mathrm{Cc}}$ | Operating | 3.5 | 12 | 24 | V |
| Output Current | $\mathrm{I}_{\mathrm{GND}(\mathrm{L})}$ | Output Current Low | 5.0 | - | 6.9 | mA |
|  | $\mathrm{I}_{\text {GND(H) }}$ | Output Current High | 12 | - | 17 | mA |
| Chopping Frequency | $\mathrm{f}_{\mathrm{C}}$ |  | - | 340 | - | kHz |
| Output Settling Time | $\mathrm{t}_{\text {sd }}$ | $\mathrm{C}_{\mathrm{L}}=20 \mathrm{pF}$ | - | - | 50 | $\mu \mathrm{s}$ |
| Output Rise Time | $\mathrm{t}_{\mathrm{r}}$ | $\mathrm{C}_{\mathrm{L}}=20 \mathrm{pF}$ | - | 3.5 | - | $\mu \mathrm{s}$ |
| Output Fall Time | $\mathrm{t}_{\mathrm{f}}$ | $\mathrm{C}_{\mathrm{L}}=20 \mathrm{pF}$ | - | 3.5 | - | $\mu \mathrm{s}$ |
| Reverse Battery Current | $\mathrm{I}_{\mathrm{cc}}$ | $V_{R C C}=-16 \mathrm{~V}$ | - | - | -15 | mA |

NOTE: Typical Data is at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ and $\mathrm{V}_{\mathrm{CC}}=12 \mathrm{~V}$ and is for design information only.

A3361 MAGNETIC CHARACTERISTICS over operating supply voltage and temperature ranges.

|  |  |  | Limits |  |  |  |
| :--- | :---: | :--- | :---: | :---: | :---: | :---: |
| Characteristic | Symbol | Test Conditions | Min. $\quad$ Typ. Max. | Units |  |  |
| Operate Point | $\mathrm{B}_{\mathrm{OP}}$ | $\mathrm{B}>\mathrm{B}_{\mathrm{OP}}, \mathrm{I}_{\mathrm{GND}}=\mathrm{LOW}$ | - | - | 125 | G |
| Release Point | $\mathrm{B}_{\mathrm{RP}}$ | $\mathrm{B}<\mathrm{B}_{\mathrm{RP}}, \mathrm{I}_{\mathrm{GND}}=\mathrm{HIGH}$ | 40 | - | - | G |
| Hysteresis | $\mathrm{B}_{\text {hys }}$ | $\mathrm{B}_{\mathrm{OP}}-\mathrm{B}_{\mathrm{RP}}$ | 5.0 | - | 30 | G |

A3362 MAGNETIC CHARACTERISTICS over operating supply voltage and temperature ranges.

|  |  |  | Limits |  |  |  |
| :--- | :---: | :--- | :---: | :---: | :---: | :---: |
| Characteristic | Symbol | Test Conditions | Min. | Typ. Max. | Units |  |
| Operate Point | $\mathrm{B}_{\mathrm{OP}}$ | $\mathrm{B}>\mathrm{B}_{\mathrm{OP}}, \mathrm{I}_{\mathrm{GND}}=\mathrm{HIGH}$ | - | - | 125 | G |
| Release Point | $\mathrm{B}_{\mathrm{RP}}$ | $\mathrm{B}<\mathrm{B}_{\mathrm{RP}}, \mathrm{I}_{\mathrm{GND}}=$ LOW | 40 | - | - | G |
| Hysteresis | $\mathrm{B}_{\text {hys }}$ | $\mathrm{B}_{\mathrm{OP}}-\mathrm{B}_{\mathrm{RP}}$ | 5.0 | - | 30 | G |

NOTE: 1 gauss is exactly equal to 0.1 millitesla ( mt ).


## SENSOR LOCATIONS

## Package Designator "LH"



Package Designator "UA"


Dwg. MH-011-9B

Although sensor location is accurate to three sigma for a particular design, product improvements may result in small changes to sensor location.


## APPLICATIONS INFORMATION

Extensive applications information for Hall-effect sensors is available in:

- Hall-Effect IC Applications Guide, Application Note 27701;
- Hall-Effect Devices: Soldering, Gluing, Potting, Encapsulating, and Lead Forming, Application Note 27703.1;
- Soldering of Through-Hole Hall-Sensor Dervices, Application Note 27703; and
- Soldering of Surface-Mount Hall-Sensor Devices, Application Note 27703.2.
More detailed descriptions of the chopper-stabilized circuit operation can be found in:
- Monolithic Magnetic Hall Sensor Using Dynamic Quadrature Offset Cancelation, Technical Paper STP 97-10; and
- Chopper-Stabilized Amplifiers With A Track-and-Hold Signal Demodulator, Technical Paper STP 99-1.
All are provided at
www.allegromicro.com


## FUNCTIONAL DESCRIPTION

Chopper-Stabilized Technique. The Hall element can be considered as a resistor array similar to a Wheatstone bridge. A large portion of the offset is a result of the mismatching of these resistors. These devices use a proprietary dynamic offset cancellation technique, with an internal high-frequency clock to reduce the residual offset voltage of the Hall element that is normally caused by device overmolding, temperature dependencies, and thermal stress. The chopper-stabilizing technique cancels the mismatching of the resistor circuit by changing the direction of the current flowing through the Hall plate using CMOS switches and Hall voltage measurement taps, while maintaing the Hall-voltage signal that is induced by the external magnetic flux. The signal is then captured by a sample-andhold circuit and further processed using low-offset bipolar circuitry. This technique produces devices that have an extremely stable quiescent Hall output voltage, are immune to thermal stress, and have precise recoverability after temperature cycling. This technique will also slightly degrade the device output repeatability. A relatively high sampling frequency is used in order that faster signals can be processed.

Operation. As shown in the output characteristic graphs, the output of the A3362 turns on when a magnetic field (south pole) perpendicular to the Hall sensor is increased above the operate point threshold $\left(\mathrm{B}_{\mathrm{OP}}\right)$. After turn on, the output will source current equal to the device operating current plus a current source $\left(\mathrm{I}_{\mathrm{GND}(\mathrm{H})}\right)$. When the magnetic field is decreased below the release point $\left(\mathrm{B}_{\mathrm{RP}}\right)$, the output turns off and will source current equal only to the Hall-effect sensor operating current $\left(\mathrm{I}_{\mathrm{GND}(\mathrm{L})}\right)$. The A 3361 output is inverted and the device turns off at $\mathrm{B}_{\mathrm{OP}}$ and on at $\mathrm{B}_{\mathrm{RP}}$. The difference in the magnetic operate and release points is the hysteresis ( $\mathrm{B}_{\text {hys }}$ ) of the device. The hysteresis allows clean switching of the output even in the presence of external mechanical vibration or electrical noise.
Applications. It is strongly recommended that an external bypass capacitor be connected (in close proximity to the Hall sensor) between the supply and ground of the device to reduce both external noise and noise generated by the chopperstabilization technique.


## Operating Characteristics



3361 AND 3362
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CHOPPER-STABILIZED, HALL-EFFECT SWITCHES

Operating Characteristics










## PACKAGE DESIGNATOR 'LH'

(fits SC-59A solder-pad layout)


NOTES: 1. Tolerances on package height and width represent allowable mold offsets. Dimensions given are measured at the widest point (parting line).
2. Exact body and lead configuration at vendor's option within limits shown.
3. Height does not include mold gate flash.
4. Where no tolerance is specified, dimension is nominal.
5. Add "TR" to part number for tape and reel.

## PACKAGE DESIGNATOR 'UA’

Dimensions in Inches (controlling dimensions)


NOTES: 1. Tolerances on package height and width represent allowable mold offsets. Dimensions given are measured at the widest point (parting line).
2. Exact body and lead configuration at vendor's option within limits shown.
3. Height does not include mold gate flash.
4. Recommended minimum PWB hole diameter to clear transition area is $0.035^{\prime \prime}(0.89 \mathrm{~mm})$.
5. Where no tolerance is specified, dimension is nominal.
6. Supplied in bulk pack ( 500 pieces per bag).

Dimensions in Millimeters
(for reference only)


Radial Lead Form (order A326xEUA-LC)


NOTE: Lead-form dimensions are the nominals produced on the forming equipment. No dimensional tolerance is implied or guaranteed for bulk packaging ( 500 pieces per bag).

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