

# KM48C2004C, KM48C2104C KM48V2004C, KM48V2104C

# CMOS DRAM

## 2M x 8Bit CMOS Dynamic RAM with Extended Data Out

### DESCRIPTION

This is a family of 2,097,152 x 8 bit Extended Data Out CMOS DRAMs. Extended Data Out Mode offers high speed random access of memory cells within the same row, so called Hyper Page Mode. Power supply voltage (+5.0V or +3.3V), refresh cycle (2K Ref. or 4K Ref.), access time (-5 or -6), power consumption(Normal or Low power) and package type(SOJ or TSOP-II) are optional features of this family. All of this family have  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh,  $\overline{\text{RAS}}$ -only refresh and Hidden refresh capabilities. Furthermore, Self-refresh operation is available in L-version. This 2Mx8 EDO Mode DRAM family is fabricated using Samsung's advanced CMOS process to realize high band-width, low power consumption and high reliability. It may be used as graphic memory unit for microcomputer and personal computer.

### FEATURES

#### • Part Identification

- KM48C2004C/C-L (5V, 4K Ref.)
- KM48C2104C/C-L (5V, 2K Ref.)
- KM48V2004C/C-L (3.3V, 4K Ref.)
- KM48V2104C/C-L (3.3V, 2K Ref.)

#### • Active Power Dissipation

Unit : mW

Speed	3.3V		5V	
	4K	2K	4K	2K
-5	324	396	495	605
-6	288	360	440	550

#### • Refresh Cycles

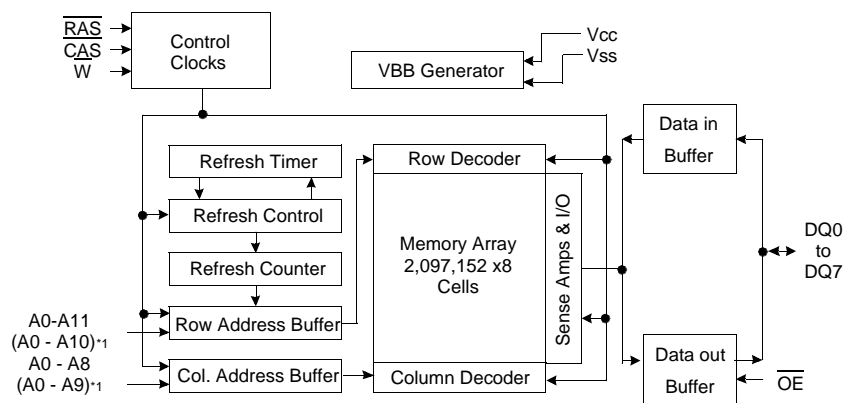
Part NO.	Vcc	Refresh cycle	Refresh period	
			Normal	L-ver
C2004C	5V	4K	64ms	128ms
V2004C	3.3V			
C2104C	5V	2K	32ms	
V2104C	3.3V			

#### • Performance Range

Speed	t <sub>TRAC</sub>	t <sub>CAC</sub>	t <sub>RC</sub>	t <sub>HPC</sub>	Remark
-5	50ns	13ns	84ns	20ns	5V/3.3V
-6	60ns	15ns	104ns	25ns	5V/3.3V

- Extended Data Out Mode operation (Fast page mode with Extended Data Out)
- $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh capability
- $\overline{\text{RAS}}$ -only and Hidden refresh capability
- Self-refresh capability (L-ver only)
- Fast parallel test mode capability
- TTL(5V)/LVTTTL(3.3V) compatible inputs and outputs
- Early Write or output enable controlled write
- JEDEC Standard pinout
- Available in Plastic SOJ and TSOP(II) packages
- Single +5V±10% power supply (5V product)
- Single +3.3V±0.3V power supply (3.3V product)

### FUNCTIONAL BLOCK DIAGRAM



Note) \*1 : 2K Refresh

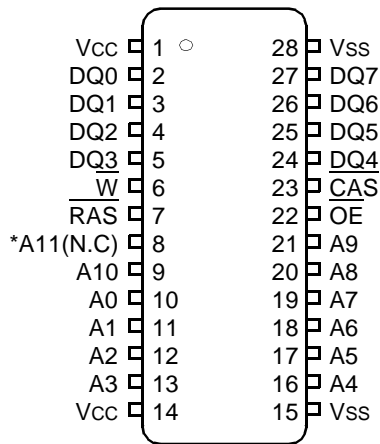
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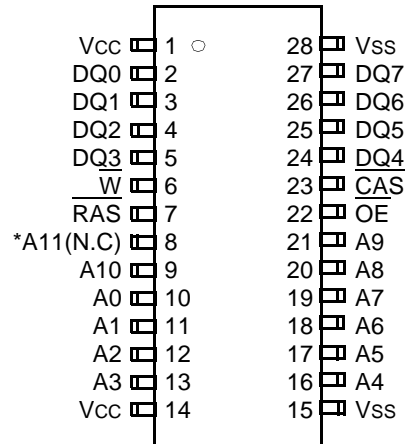
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**PIN CONFIGURATION (Top Views)**

• **KM48C/V20(1)04CK**



• **KM48C/V20(1)04CS**



\*A11 is N.C for KM48C/V2104C(5V/3.3V, 2K Ref. product)

K : 300mil 28 SOJ  
S : 300mil 28 TSOP II

Pin Name	Pin Function
A0 - A11	Address Inputs (4K Product)
A0 - A10	Address Inputs (2K Product)
DQ0 - 7	Data In/Out
Vss	Ground
RAS	Row Address Strobe
CAS	Column Address Strobe
W	Read/Write Input
OE	Data Output Enable
Vcc	Power(+5V)
	Power(+3.3V)
N.C	No Connection (2K Ref. product)

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## CMOS DRAM

### ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Rating		Units
		3.3V	5V	
Voltage on any pin relative to Vss	V <sub>IN</sub> , V <sub>OUT</sub>	-0.5 to +4.6	-1.0 to +7.0	V
Voltage on Vcc supply relative to Vss	V <sub>CC</sub>	-0.5 to +4.6	-1.0 to +7.0	V
Storage Temperature	T <sub>stg</sub>	-55 to +150	-55 to +150	°C
Power Dissipation	P <sub>D</sub>	1	1	W
Short Circuit Output Current	I <sub>OS</sub> Address	50	50	mA

\* Permanent device damage may occur if "ABSOLUTE MAXIMUM RATINGS" are exceeded. Functional operation should be restricted to the conditions as detailed in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### RECOMMENDED OPERATING CONDITIONS (Voltage referenced to Vss, T<sub>A</sub> = 0 to 70°C)

Parameter	Symbol	3.3V			5V			Units
		Min	Typ	Max	Min	Typ	Max	
Supply Voltage	V <sub>CC</sub>	3.0	3.3	3.6	4.5	5.0	5.5	V
Ground	V <sub>SS</sub>	0	0	0	0	0	0	V
Input High Voltage	V <sub>IH</sub>	2.0	-	V <sub>CC</sub> +0.3 <sup>*1</sup>	2.4	-	V <sub>CC</sub> +1.0 <sup>*1</sup>	V
Input Low Voltage	V <sub>IL</sub>	-0.3 <sup>*2</sup>	-	0.8	-1.0 <sup>*2</sup>	-	0.8	V

\*1 : V<sub>CC</sub>+1.3V/15ns(3.3V), V<sub>CC</sub>+2.0V/20ns(5V), Pulse width is measured at V<sub>CC</sub>

\*2 : -1.3V/15ns(3.3V), -2.0V/20ns(5V), Pulse width is measured at V<sub>SS</sub>

### DC AND OPERATING CHARACTERISTICS (Recommended operating conditions unless otherwise noted.)

Max	Parameter	Symbol	Min	Max	Units
3.3V	Input Leakage Current (Any input 0 ≤ V <sub>IN</sub> ≤ V <sub>IN</sub> +0.3V, all other input pins not under test=0 Volt)	I <sub>I(L)</sub>	-5	5	uA
	Output Leakage Current (Data out is disabled, 0V ≤ V <sub>OUT</sub> ≤ V <sub>CC</sub> )	I <sub>O(L)</sub>	-5	5	uA
	Output High Voltage Level(I <sub>OH</sub> =-2mA)	V <sub>OH</sub>	2.4	-	V
	Output Low Voltage Level(I <sub>OL</sub> =2mA)	V <sub>OL</sub>	-	0.4	V
5V	Input Leakage Current (Any input 0 ≤ V <sub>IN</sub> ≤ V <sub>IN</sub> +0.5V, all other input pins not under test=0 Volt)	I <sub>I(L)</sub>	-5	5	uA
	Output Leakage Current (Data out is disabled, 0V ≤ V <sub>OUT</sub> ≤ V <sub>CC</sub> )	I <sub>O(L)</sub>	-5	5	uA
	Output High Voltage Level(I <sub>OH</sub> =-5mA)	V <sub>OH</sub>	2.4	-	V
	Output Low Voltage Level(I <sub>OL</sub> =4.2mA)	V <sub>OL</sub>	-	0.4	V



**DC AND OPERATING CHARACTERISTICS** (Continued)

Symbol	Power	Speed	Max				Units
			KM48V2004C	KM48V2104C	KM48C2004C	KM48C2104C	
I <sub>CC1</sub>	Don't care	-5	90	110	90	110	mA
		-6	80	100	80	100	
I <sub>CC2</sub>	Normal L	Don't care	1	1	2	2	mA
			1	1	1	1	
I <sub>CC3</sub>	Don't care	-5	90	110	90	110	mA
		-6	80	100	80	100	
I <sub>CC4</sub>	Don't care	-5	80	90	80	90	mA
		-6	70	80	70	80	
I <sub>CC5</sub>	Normal L	Don't care	0.5	0.5	1	1	mA
			200	200	250	250	
I <sub>CC6</sub>	Don't care	-5	90	110	90	110	mA
		-6	80	100	80	100	
I <sub>CC7</sub>	L	Don't care	250	250	300	300	uA
I <sub>CCS</sub>	L	Don't care	200	200	250	250	uA

I<sub>CC1</sub>\* : Operating Current ( $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$  cycling @t<sub>RC</sub>=min.)

I<sub>CC2</sub> : Standby Current ( $\overline{\text{RAS}}=\overline{\text{CAS}}=\overline{\text{W}}=V_{IH}$ )

I<sub>CC3</sub>\* : RAS-only Refresh Current ( $\overline{\text{CAS}}=V_{IH}$ ,  $\overline{\text{RAS}}$  cycling @t<sub>RC</sub>=min.)

I<sub>CC4</sub>\* : Hyper Page Mode Current ( $\overline{\text{RAS}}=V_{IL}$ ,  $\overline{\text{CAS}}$ , Address cycling @t<sub>HPC</sub>=min.)

I<sub>CC5</sub> : Standby Current ( $\overline{\text{RAS}}=\overline{\text{CAS}}=\overline{\text{W}}=V_{CC}-0.2V$ )

I<sub>CC6</sub>\* : CAS-Before-RAS Refresh Current ( $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$  cycling @t<sub>RC</sub>=min.)

I<sub>CC7</sub> : Battery back-up current, Average power supply current, Battery back-up mode

Input high voltage(V<sub>IH</sub>)=V<sub>CC</sub>-0.2V, Input low voltage(V<sub>IL</sub>)=0.2V,  $\overline{\text{CAS}}=0.2V$ ,

DQ=Don't care, t<sub>RC</sub>=31.25us(4K/L-ver), 62.5us(2K/L-ver),

t<sub>RAS</sub>=t<sub>RASmin</sub>~300ns

I<sub>CCS</sub> : Self Refresh Current

$\overline{\text{RAS}}=\overline{\text{CAS}}=V_{IL}$ ,  $\overline{\text{W}}=\overline{\text{OE}}=A0 \sim A11=V_{CC}-0.2V$  or 0.2V,

DQ0 ~ DQ7=V<sub>CC</sub>-0.2V, 0.2V or Open

**\*Note** : I<sub>CC1</sub>, I<sub>CC3</sub>, I<sub>CC4</sub> and I<sub>CC6</sub> are dependent on output loading and cycle rates. Specified values are obtained with the output open.

I<sub>CC</sub> is specified as an average current. In I<sub>CC1</sub>, I<sub>CC3</sub> and I<sub>CC6</sub>, address can be changed maximum once while  $\overline{\text{RAS}}=V_{IL}$ . In I<sub>CC4</sub>,

address can be changed maximum once within one Hyper page mode cycle time, t<sub>HPC</sub>.

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### CAPACITANCE (TA=25°C, VCC=5V or 3.3V, f=1MHz)

Parameter	Symbol	Min	Max	Units
Input capacitance [A0 ~ A11]	CIN1	-	5	pF
Input capacitance [ $\overline{\text{RAS}}$ , $\overline{\text{CAS}}$ , $\overline{\text{W}}$ , $\overline{\text{OE}}$ ]	CIN2	-	7	pF
Output capacitance [DQ0 - DQ7]	CDQ	-	7	pF

### AC CHARACTERISTICS (0°C ≤ TA ≤ 70°C, See note 1,2)

Test condition (5V device) : VCC=5.0V±10%, Vih/Vil=2.4/0.8V, Voh/Vol=2.0/0.8V

Test condition (3.3V device) : VCC=3.3V±0.3V, Vih/Vil=2.0/0.8V, Voh/Vol=2.0/0.8V

Parameter	Symbol	-5		-6		Units	Notes
		Min	Max	Min	Max		
Random read or write cycle time	tRC	84		104		ns	
Read-modify-write cycle time	tRWC	116		140		ns	
Access time from $\overline{\text{RAS}}$	tRAC		50		60	ns	3,4,10
Access time from $\overline{\text{CAS}}$	tCAC		13		15	ns	3,4,5
Access time from column address	tAA		25		30	ns	3,10
$\overline{\text{CAS}}$ to output in Low-Z	tCLZ	3		3		ns	3
Output buffer turn-off delay from $\overline{\text{CAS}}$	tCEZ	3	13	3	15	ns	6,14
$\overline{\text{OE}}$ to output in Low-Z	tOLZ	3		3		ns	3
Transition time (rise and fall)	tT	2	50	2	50	ns	2
$\overline{\text{RAS}}$ precharge time	tRP	30		40		ns	
$\overline{\text{RAS}}$ pulse width	tRAS	50	10K	60	10K	ns	
$\overline{\text{RAS}}$ hold time	tRSH	13		15		ns	
$\overline{\text{CAS}}$ hold time	tCSH	38		45		ns	
$\overline{\text{CAS}}$ pulse width	tCAS	8	10K	10	10K	ns	
$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ delay time	tRCD	20	37	20	45	ns	4
$\overline{\text{RAS}}$ to column address delay time	tRAD	15	25	15	30	ns	10
$\overline{\text{CAS}}$ to $\overline{\text{RAS}}$ precharge time	tCRP	5		5		ns	
Row address set-up time	tASR	0		0		ns	
Row address hold time	tRAH	10		10		ns	
Column address set-up time	tASC	0		0		ns	
Column address hold time	tCAH	8		10		ns	
Column address to $\overline{\text{RAS}}$ lead time	tRAL	25		30		ns	
Read command set-up time	tRCS	0		0		ns	
Read command hold time referenced to $\overline{\text{CAS}}$	tRCH	0		0		ns	8
Read command hold time referenced to $\overline{\text{RAS}}$	tRRH	0		0		ns	8
Write command hold time	tWCH	10		10		ns	
Write command pulse width	tWP	10		10		ns	
Write command to $\overline{\text{RAS}}$ lead time	tRWL	13		15		ns	
Write command to $\overline{\text{CAS}}$ lead time	tCWL	8		10		ns	



**AC CHARACTERISTICS** (Continued)

Parameter	Symbol	-5		-6		Units	Notes
		Min	Max	Min	Max		
Data set-up time	tDS	0		0		ns	9
Data hold time	tDH	8		10		ns	9
Refresh period (2K, Normal)	tREF		32		32	ms	
Refresh period (4K, Normal)	tREF		64		64	ms	
Refresh period (L-ver)	tREF		128		128	ms	
Write command set-up time	twCS	0		0		ns	7
CAS to $\overline{W}$ delay time	tcWD	30		34		ns	7
RAS to $\overline{W}$ delay time	trWD	67		79		ns	7
Column address to $\overline{W}$ delay time	tAWD	42		49		ns	7
CAS precharge to $\overline{W}$ delay time	tcPWD	47		54		ns	
CAS set-up time (CAS -before-RAS refresh)	tCSR	5		5		ns	
CAS hold time (CAS -before-RAS refresh)	tCHR	10		10		ns	
RAS to CAS precharge time	trPC	5		5		ns	
Access time from CAS precharge	tCPA		28		35	ns	3
Hyper Page cycle time	tHPC	20		25		ns	13
Hyper Page read-modify-write cycle time	tHPRWC	47		56		ns	13
CAS precharge time (Hyper Page cycle)	tCP	8		10		ns	
RAS pulse width (Hyper Page cycle)	trASP	50	200K	60	200K	ns	
RAS hold time from CAS precharge	trHCP	30		35		ns	
$\overline{OE}$ access time	tOEA		13		15	ns	
$\overline{OE}$ to data delay	tOED	13		15		ns	
Output buffer turn off delay time from $\overline{OE}$	tOEZ	3	13	3	15	ns	6
$\overline{OE}$ command hold time	tOEH	13		15		ns	
Write command set-up time (Test mode in)	twTS	10		10		ns	11
Write command hold time (Test mode in)	twTH	10		10		ns	11
$\overline{W}$ to RAS precharge time ( $\overline{C}$ - $\overline{B}$ - $\overline{R}$ refresh)	twRP	10		10		ns	
$\overline{W}$ to RAS hold time ( $\overline{C}$ - $\overline{B}$ - $\overline{R}$ refresh)	twRH	10		10		ns	
Output data hold time	tDOH	5		5		ns	
Output buffer turn off delay from RAS	treZ	3	13	3	15	ns	6,14
Output buffer turn off delay from $\overline{W}$	twEZ	3	13	3	15	ns	6
$\overline{W}$ to data delay	twED	15		15		ns	
$\overline{OE}$ to CAS hold time	tOCH	5		5		ns	
CAS hold time to $\overline{OE}$	tCHO	5		5		ns	
$\overline{OE}$ precharge time	tOEP	5		5		ns	
$\overline{W}$ pulse width (Hyper Page Cycle)	twPE	5		5		ns	
RAS pulse width ( $\overline{C}$ - $\overline{B}$ - $\overline{R}$ self refresh)	trASS	100		100		us	15,16,17
RAS precharge time ( $\overline{C}$ - $\overline{B}$ - $\overline{R}$ self refresh)	trPS	90		110		ns	15,16,17
CAS hold time ( $\overline{C}$ - $\overline{B}$ - $\overline{R}$ self refresh)	tCHS	-50		-50		ns	15,16,17

**TEST MODE CYCLE**

( Note 11 )

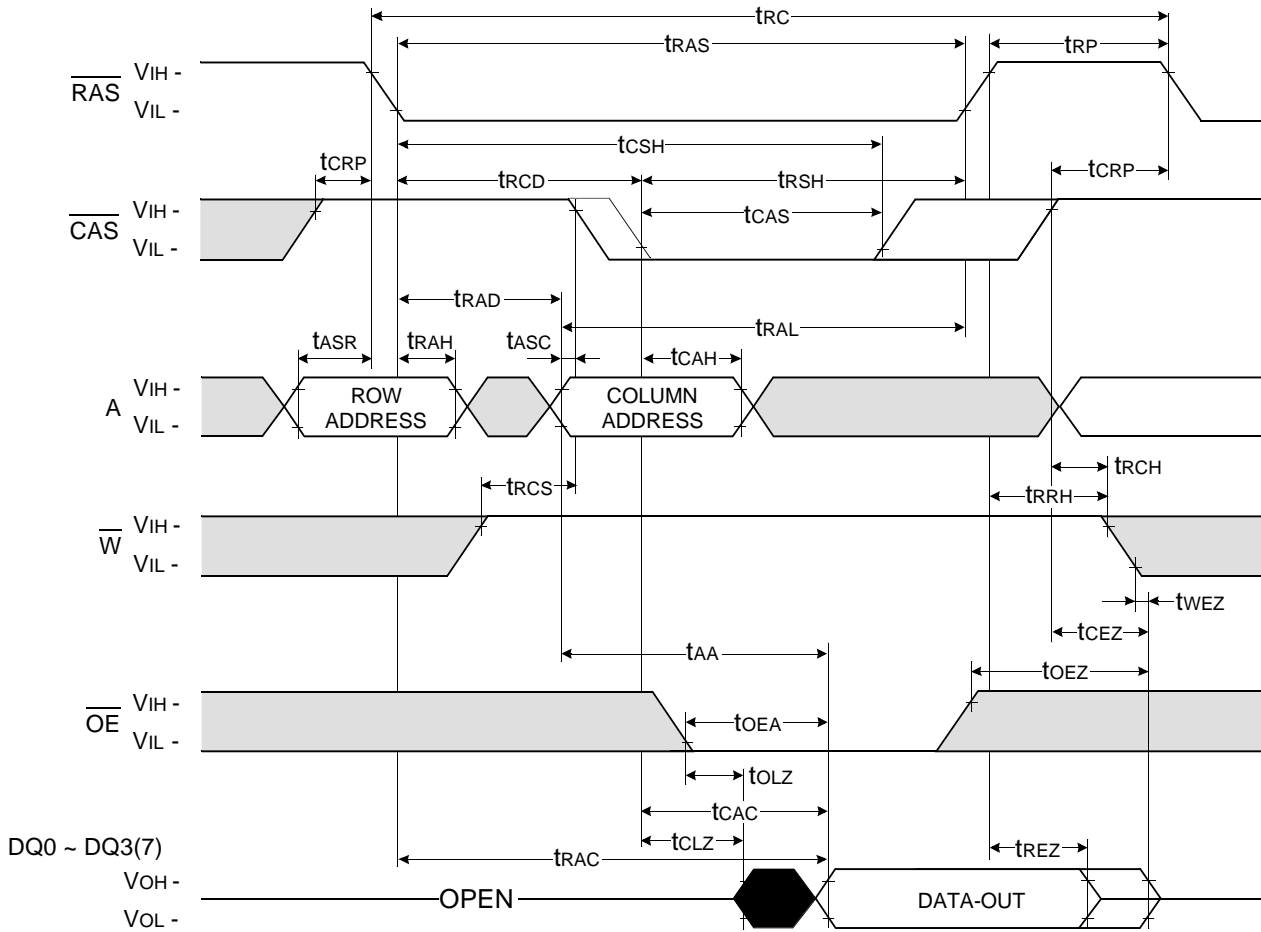
Parameter	Symbol	-5		-6		Units	Note
		Min	Max	Min	Max		
Random read or write cycle time	t <sub>RC</sub>	89		109		ns	
Read-modify-write cycle time	t <sub>RWC</sub>	121		145		ns	
Access time from $\overline{\text{RAS}}$	t <sub>RAC</sub>		55		65	ns	3,4,10,12
Access time from $\overline{\text{CAS}}$	t <sub>CAC</sub>		18		20	ns	3,4,5,12
Access time from column address	t <sub>AA</sub>		30		35	ns	3,10,12
$\overline{\text{RAS}}$ pulse width	t <sub>RAS</sub>	55	10K	65	10K	ns	
$\overline{\text{CAS}}$ pulse width	t <sub>CAS</sub>	13	10K	15	10K	ns	
$\overline{\text{RAS}}$ hold time	t <sub>RSH</sub>	18		20		ns	
$\overline{\text{CAS}}$ hold time	t <sub>CSH</sub>	43		50		ns	
Column address to $\overline{\text{RAS}}$ lead time	t <sub>RAL</sub>	30		35		ns	
$\overline{\text{CAS}}$ to $\overline{\text{W}}$ delay time	t <sub>CWD</sub>	35		39		ns	7
$\overline{\text{RAS}}$ to $\overline{\text{W}}$ delay time	t <sub>RWD</sub>	72		84		ns	7
Column address to $\overline{\text{W}}$ delay time	t <sub>AWD</sub>	47		54		ns	7
$\overline{\text{CAS}}$ precharge to $\overline{\text{W}}$ delay time	t <sub>CPWD</sub>	52		59		ns	
Hyper Page cycle time	t <sub>HPC</sub>	25		30		ns	13
Hyper Page read-modify-write cycle time	t <sub>HPRWC</sub>	53		61		ns	13
$\overline{\text{RAS}}$ pulse width (Hyper Page cycle)	t <sub>RASP</sub>	55	200K	65	200K	ns	
Access time from $\overline{\text{CAS}}$ precharge	t <sub>CPA</sub>		33		40	ns	3
$\overline{\text{OE}}$ access time	t <sub>OE A</sub>		18		20	ns	
$\overline{\text{OE}}$ to data delay	t <sub>OE D</sub>	18		20		ns	
$\overline{\text{OE}}$ command hold time	t <sub>OE H</sub>	18		20		ns	

**NOTES**

1. An initial pause of 200us is required after power-up followed by any 8  $\overline{\text{RAS}}$ -only refresh or  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh cycles before proper device operation is achieved.
2.  $V_{IH}(\text{min})$  and  $V_{IL}(\text{max})$  are reference levels for measuring timing of input signals. Transition times are measured between  $V_{IH}(\text{min})$  and  $V_{IL}(\text{max})$  and are assumed to be 2ns for all inputs.
3. Measured with a load equivalent to 2 TTL(5V)/1 TTL(3.3V) loads and 100pF.
4. Operation within the  $t_{\text{RCD}}(\text{max})$  limit insures that  $t_{\text{RAC}}(\text{max})$  can be met.  $t_{\text{RCD}}(\text{max})$  is specified as a reference point only. If  $t_{\text{RCD}}$  is greater than the specified  $t_{\text{RCD}}(\text{max})$  limit, then access time is controlled exclusively by  $t_{\text{CAC}}$ .
5. Assumes that  $t_{\text{RCD}} \geq t_{\text{RCD}}(\text{max})$ .
6. This parameter defines the time at which the output achieves the open circuit condition and is not referenced to  $V_{OH}$  or  $V_{OL}$ .
7.  $t_{\text{WCS}}$ ,  $t_{\text{RWD}}$ ,  $t_{\text{CWD}}$  and  $t_{\text{AWD}}$  are non restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If  $t_{\text{WCS}} \geq t_{\text{WCS}}(\text{min})$ , the cycle is an early write cycle and the data output will remain high impedance for the duration of the cycle. If  $t_{\text{CWD}} \geq t_{\text{CWD}}(\text{min})$ ,  $t_{\text{RWD}} \geq t_{\text{RWD}}(\text{min})$  and  $t_{\text{AWD}} \geq t_{\text{AWD}}(\text{min})$ , then the cycle is a read-modify-write cycle and the data output will contain the data read from the selected address. If neither of the above conditions is satisfied, the condition of the data out is indeterminate.
8. Either  $t_{\text{RCH}}$  or  $t_{\text{RRH}}$  must be satisfied for a read cycle.
9. These parameters are referenced to  $\overline{\text{CAS}}$  falling edge in early write cycles and to  $\overline{\text{W}}$  falling edge in  $\overline{\text{OE}}$  controlled write cycle and read-modify-write cycles.
10. Operation within the  $t_{\text{RAD}}(\text{max})$  limit insures that  $t_{\text{RAC}}(\text{max})$  can be met.  $t_{\text{RAD}}(\text{max})$  is specified as a reference point only. If  $t_{\text{RAD}}$  is greater than the specified  $t_{\text{RAD}}(\text{max})$  limit, then access time is controlled by  $t_{\text{AA}}$ .
11. These specifications are applied in the test mode.
12. In test mode read cycle, the value of  $t_{\text{RAC}}$ ,  $t_{\text{AA}}$ ,  $t_{\text{CAC}}$  is delayed by 2ns to 5ns for the specified values. These parameters should be specified in test mode cycles by adding the above value to the specified value in this data sheet.
13.  $t_{\text{ASC}} \geq 6\text{ns}$ , Assume  $t_{\text{T}} = 2.0\text{ns}$
14. If  $\overline{\text{RAS}}$  goes high before  $\overline{\text{CAS}}$  high going, the open circuit condition of the output is achieved by  $\overline{\text{CAS}}$  high going. If  $\overline{\text{CAS}}$  goes high before  $\overline{\text{RAS}}$  high going, the open circuit condition of the output is achieved by  $\overline{\text{RAS}}$  high going.
15. If  $t_{\text{RASS}} \geq 100\text{us}$ , then  $\overline{\text{RAS}}$  precharge time must use  $t_{\text{RPS}}$  instead of  $t_{\text{RP}}$ .
16. For  $\overline{\text{RAS}}$ -only refresh and burst  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh mode, 4096(4K)/2048(2K) cycles of burst refresh must be executed within 64ms/32ms before and after self refresh, in order to meet refresh specification.
17. For distributed  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  with 15.6us interval  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh should be executed with in 15.6us immediately before and after self refresh in order to meet refresh specification.



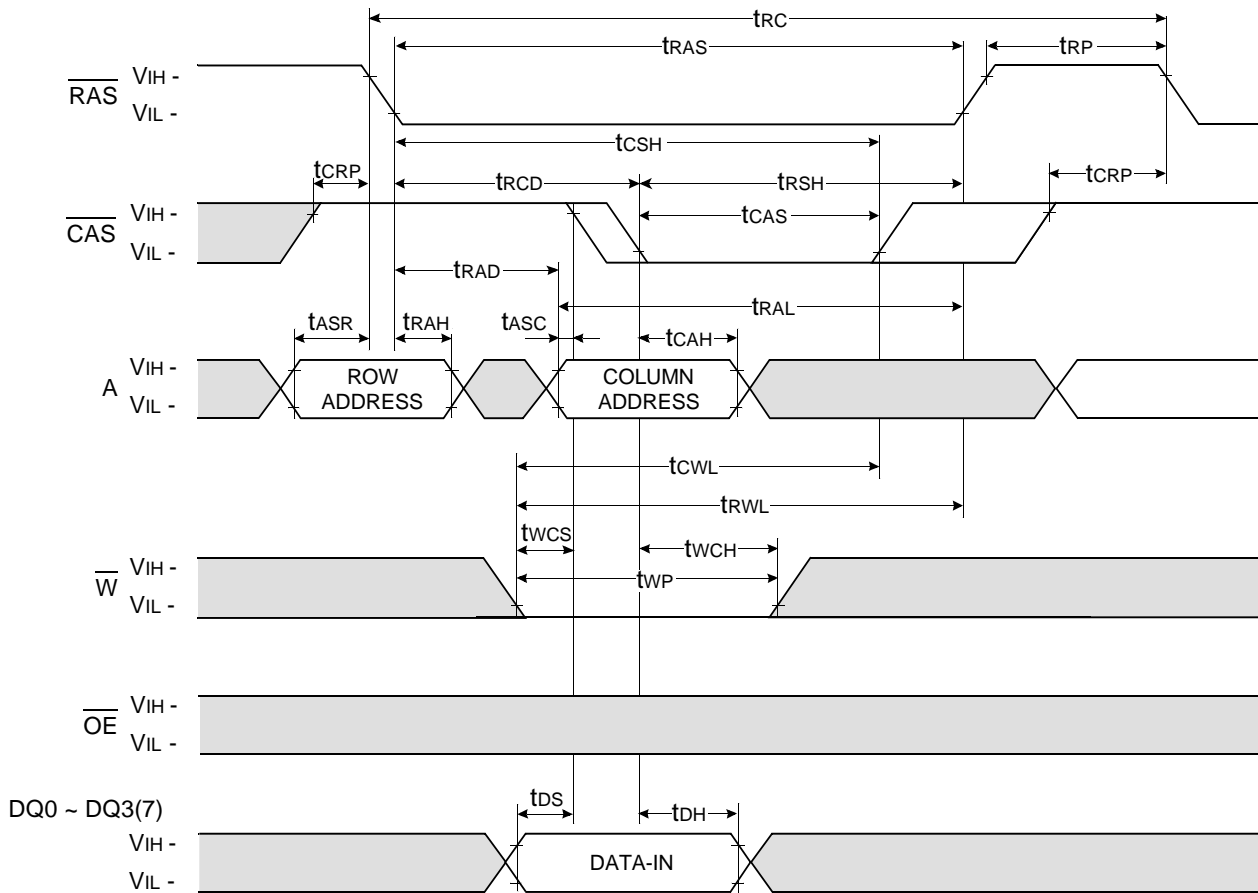
**READ CYCLE**



Don't care  
 Undefined

**WRITE CYCLE ( EARLY WRITE )**

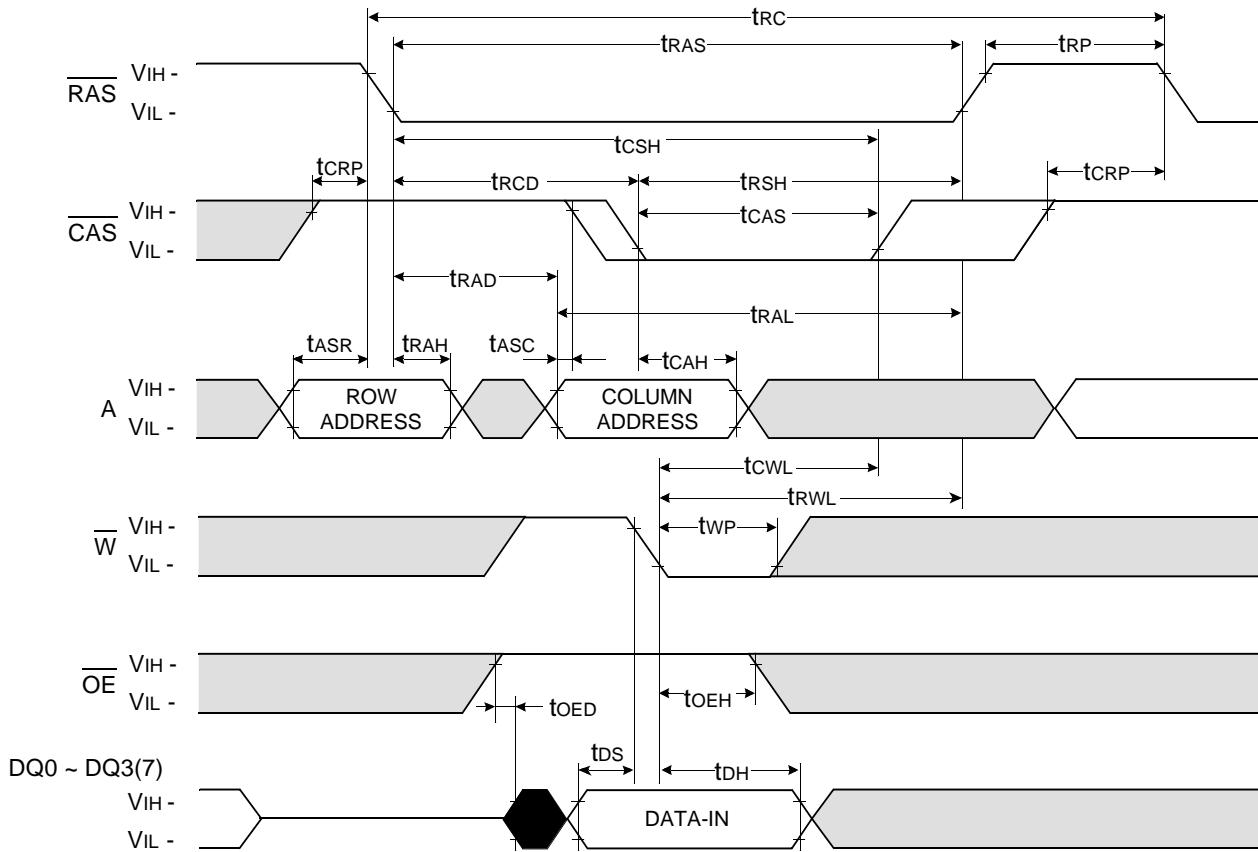
NOTE : DOUT = OPEN



□ Don't care  
■ Undefined

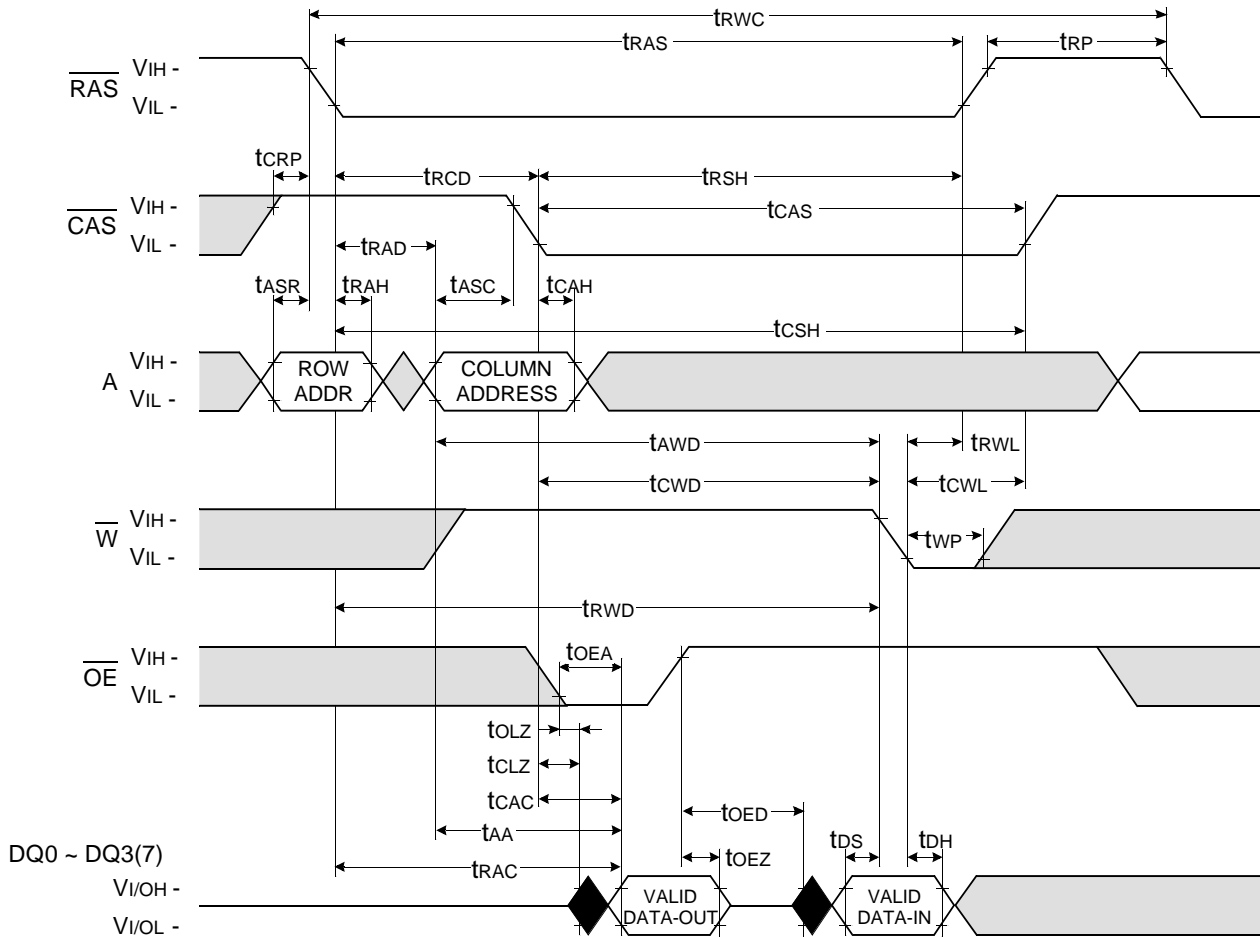
**WRITE CYCLE (  $\overline{\text{OE}}$  CONTROLLED WRITE )**

NOTE : DOUT = OPEN



□ Don't care  
■ Undefined

**READ - MODIFY - WRITE CYCLE**

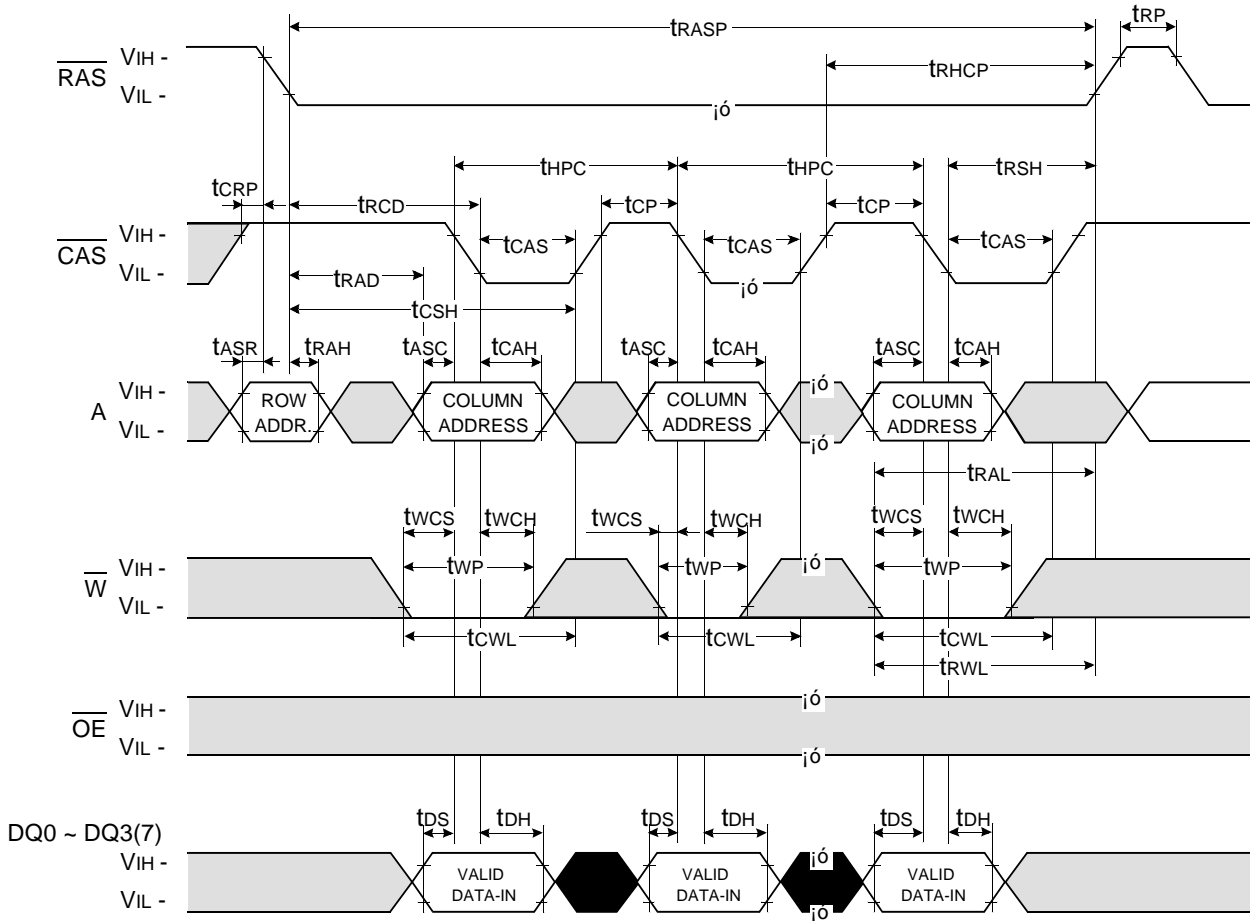


Don't care  
 Undefined



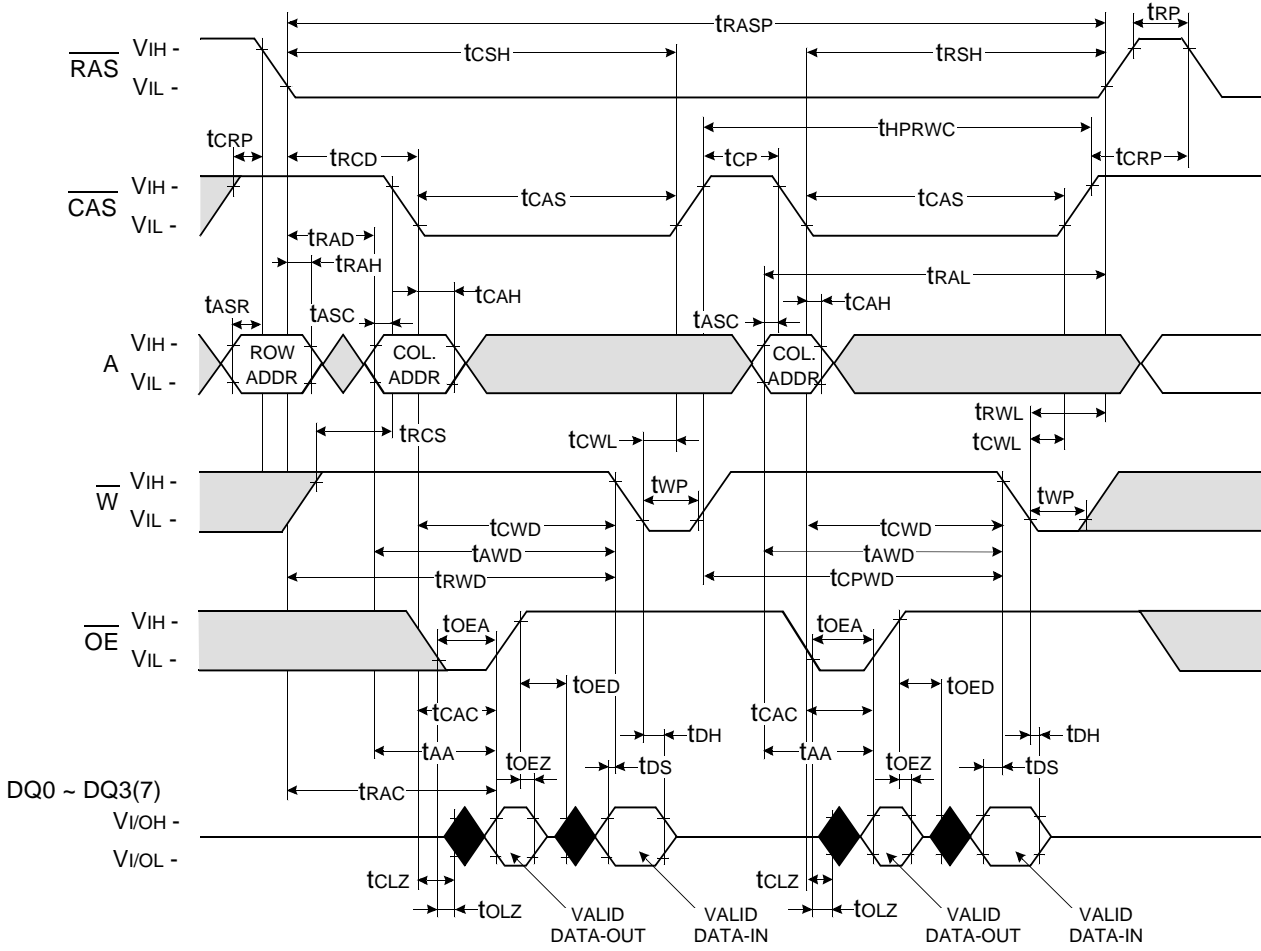
**HYPER PAGE WRITE CYCLE ( EARLY WRITE )**

NOTE : DOUT = OPEN



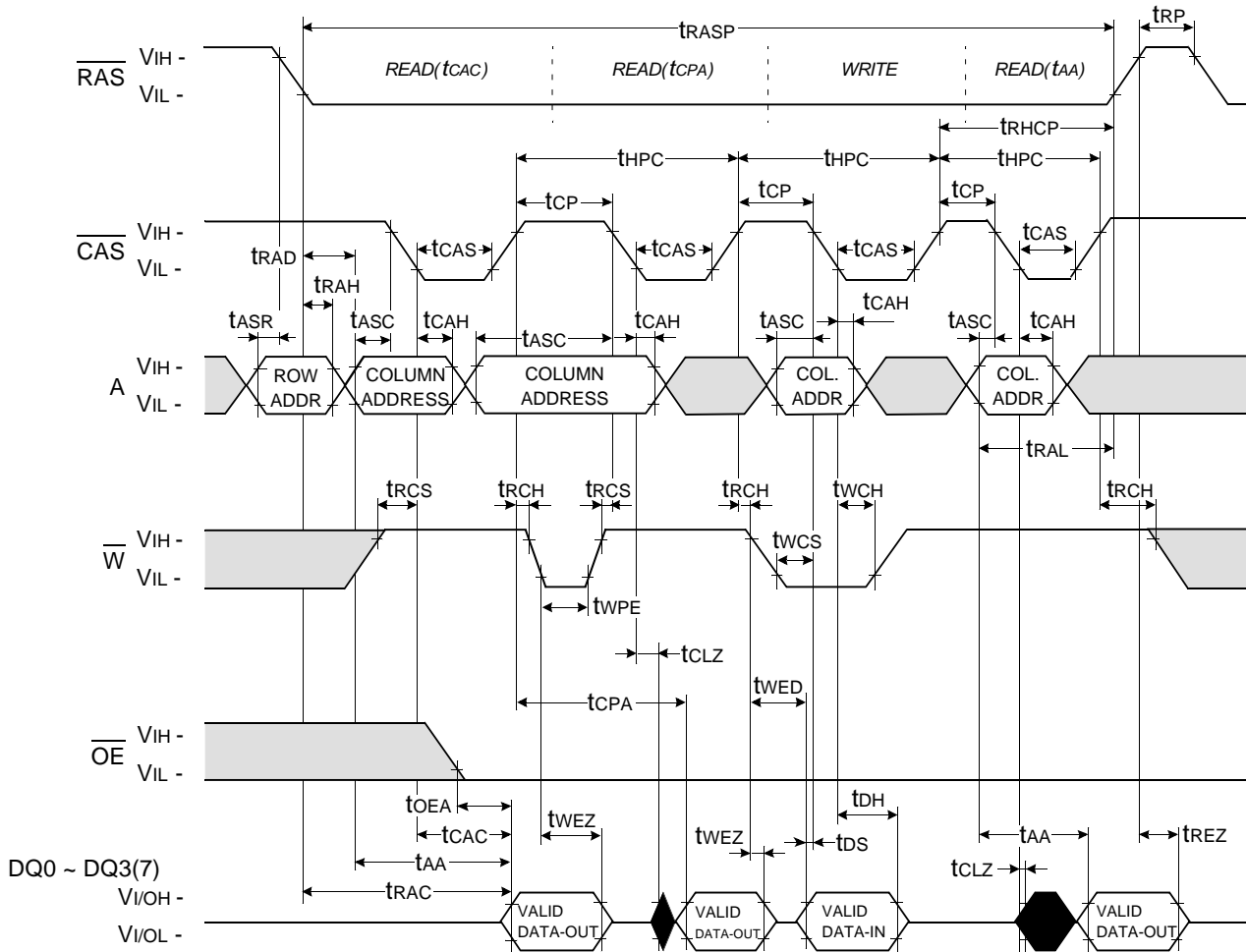
□ Don't care  
■ Undefined

**HYPER PAGE READ-MODIFY-WRITE CYCLE**



Don't care  
 Undefined

**HYPER PAGE READ AND WRITE MIXED CYCLE**



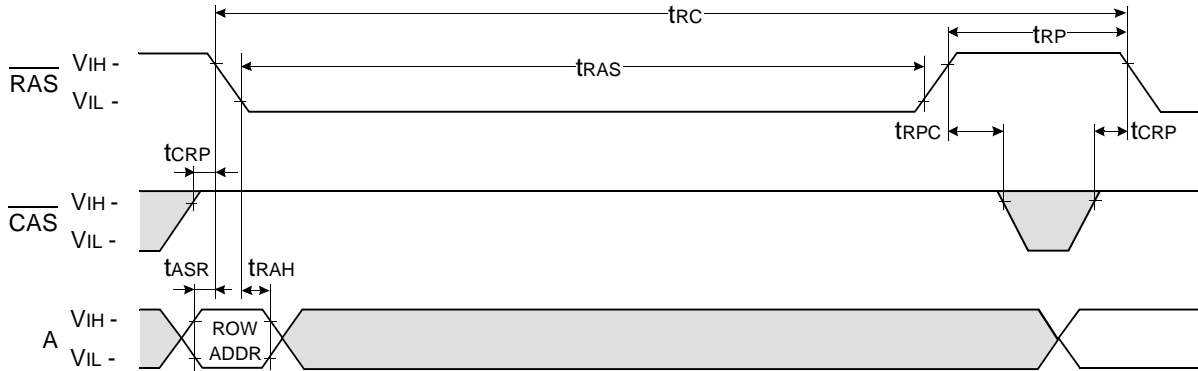
Don't care  
 Undefined



**$\overline{\text{RAS}}$  - ONLY REFRESH CYCLE\***

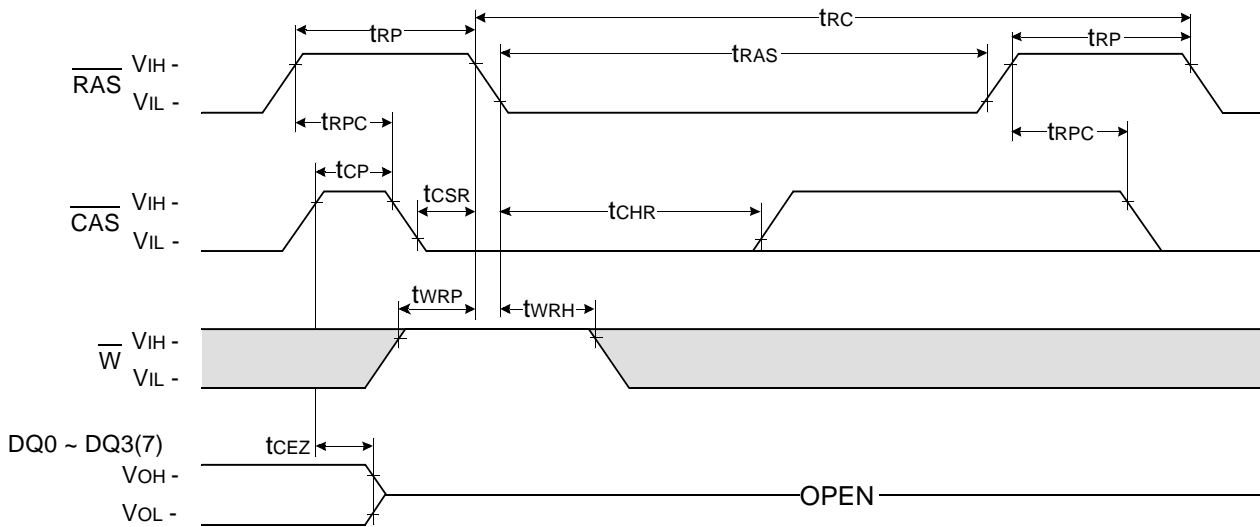
NOTE :  $\overline{\text{W}}$ ,  $\overline{\text{OE}}$ ,  $\text{DIN}$  = Don't care

$\text{DOUT}$  = OPEN



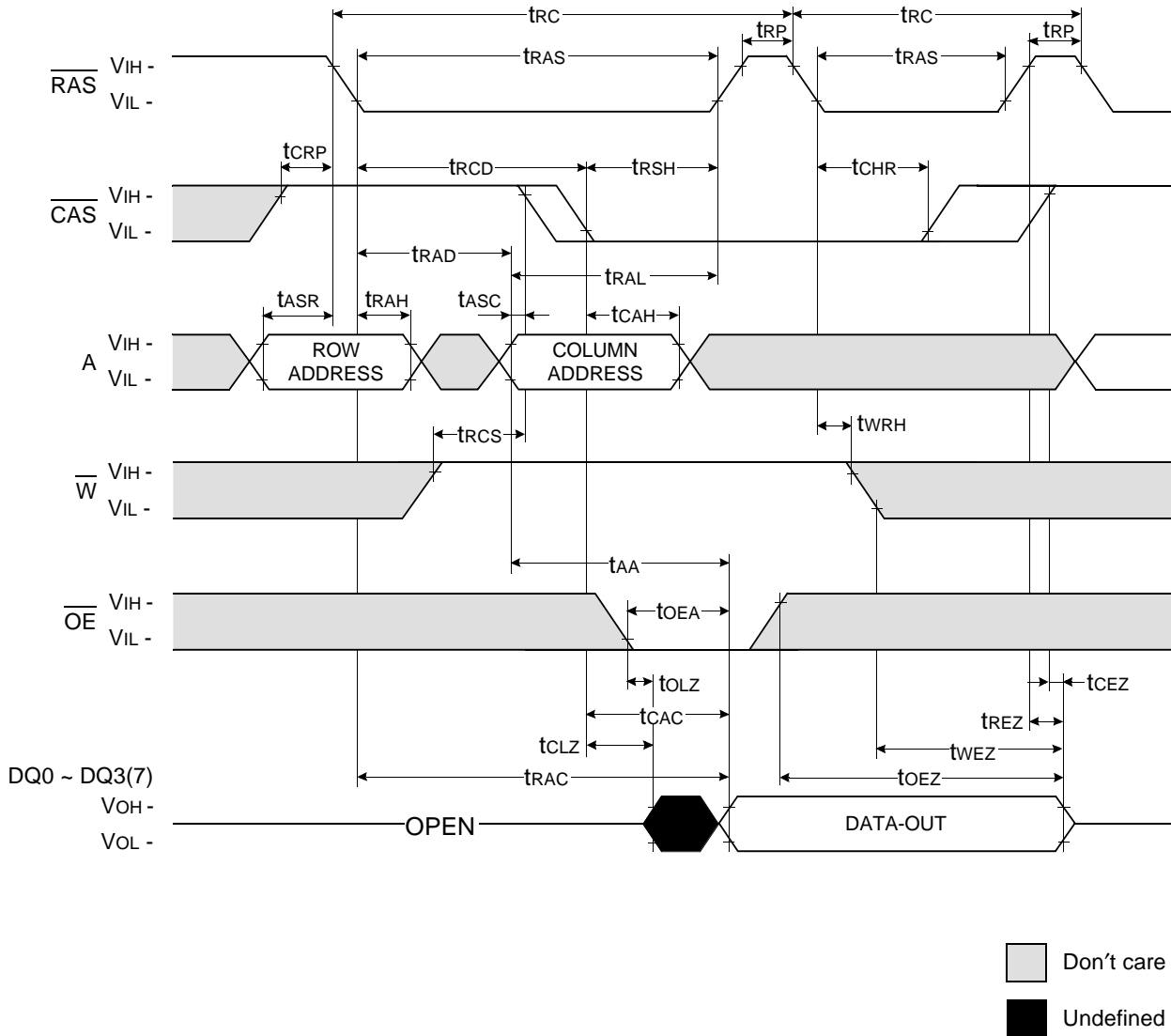
**$\overline{\text{CAS}}$  - BEFORE -  $\overline{\text{RAS}}$  REFRESH CYCLE**

NOTE :  $\overline{\text{OE}}$ ,  $\text{A}$  = Don't care



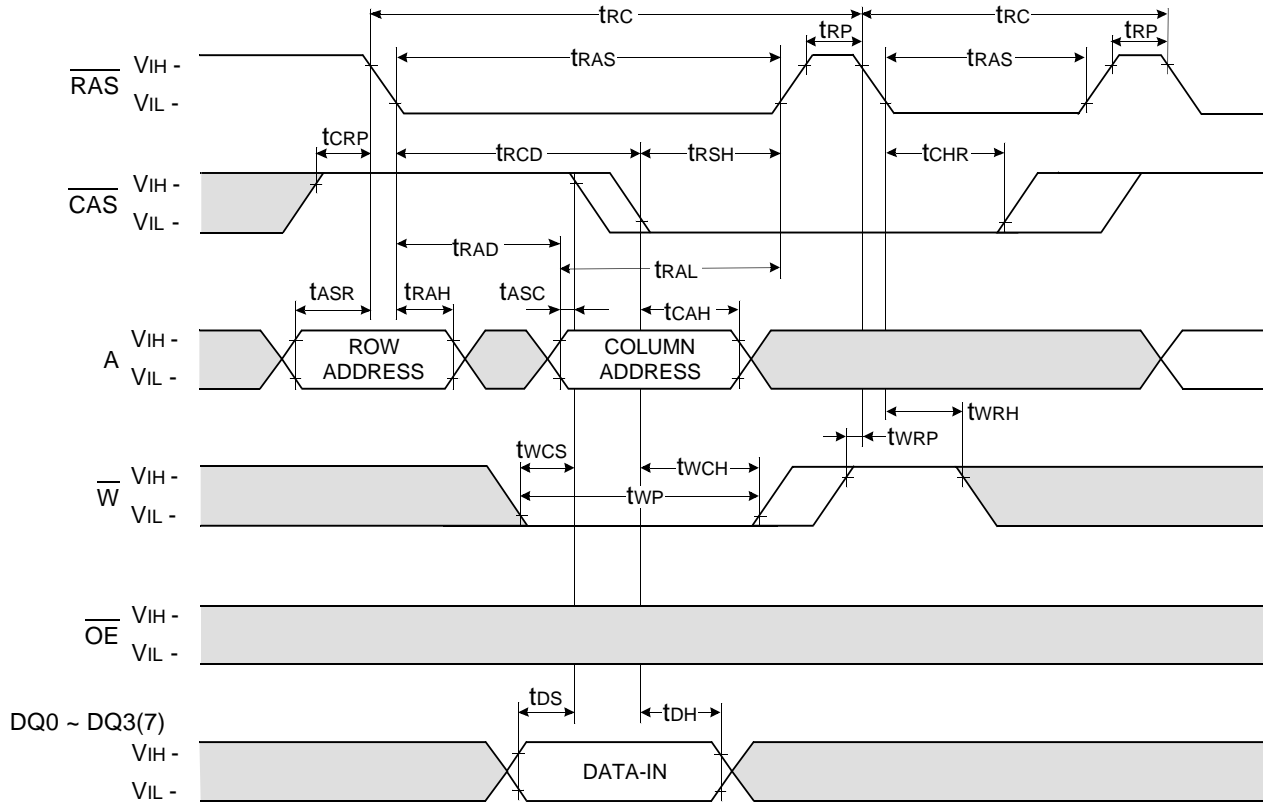
□ Don't care  
■ Undefined

**HIDDEN REFRESH CYCLE ( READ )**



**HIDDEN REFRESH CYCLE ( WRITE )**

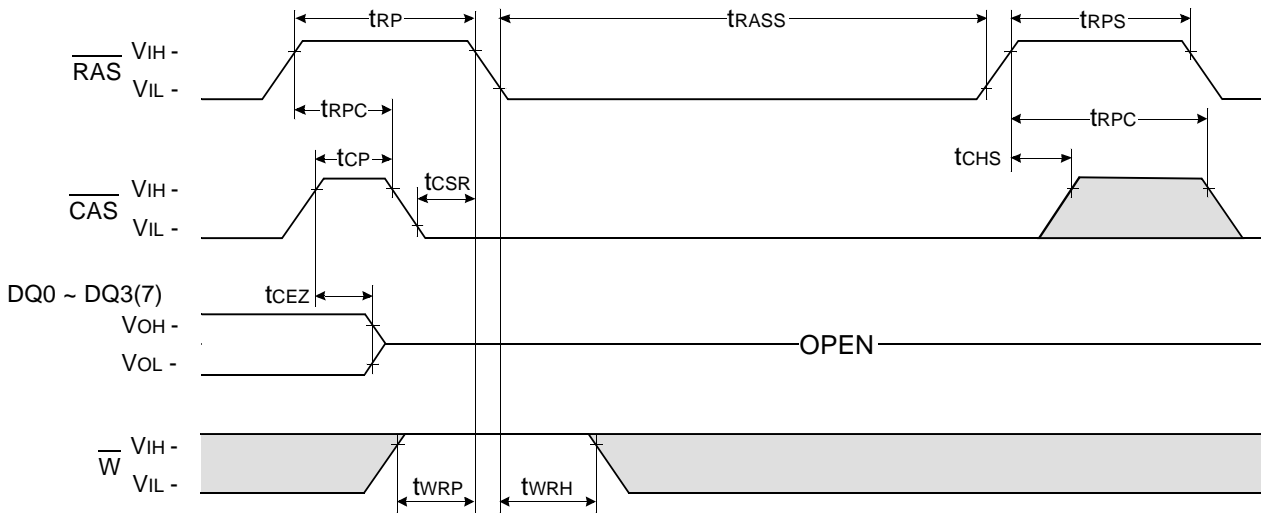
NOTE : DOUT = OPEN



□ Don't care  
■ Undefined

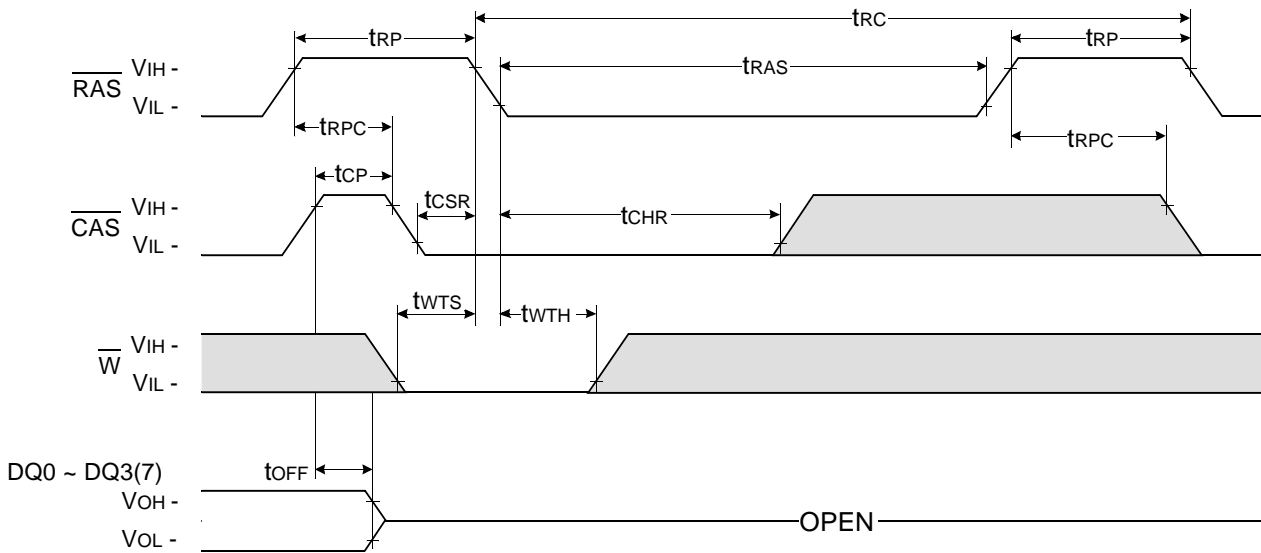
**CAS - BEFORE - RAS SELF REFRESH CYCLE**

NOTE :  $\overline{OE}$ , A = Don't care



**TEST MODE IN CYCLE**

NOTE :  $\overline{OE}$ , A = Don't care



Don't care  
 Undefined

**PACKAGE DIMENSION**

