

SPI/Digital or I<sup>2</sup>C µModule Isolator with Adjustable ±12.5V and 5V Regulated Power

#### **FEATURES**

- UL Rated 6-Channel Logic Isolator: 2500V<sub>RMS</sub>
  UL Recognized File #E151738
- Isolated Adjustable DC Power: 3V to 5V at Up to 30mA ±12.5V at Up to 20mA
- No External Components Required
- SPI (LTM2883-S) or I<sup>2</sup>C (LTM2883-I) Options
- High Common Mode Transient Immunity: 30kV/µs
- High Speed Operation:
  10MHz Digital Isolation
  4MHz/8MHz SPI Isolation
  400kHz I<sup>2</sup>C Isolation
- 3.3V (LTM2883-3) or 5V (LTM2883-5) Operation
- 1.62V to 5.5V Logic Supply
- ±10kV ESD HBM Across the Isolation Barrier
- Common Mode Working Voltage: 560V<sub>PFAK</sub>
- Low Current Shutdown Mode (<10µA)
- Low Profile (15mm × 11.25mm × 3.42mm) BGA Package

### **APPLICATIONS**

- Isolated SPI or I<sup>2</sup>C Interfaces
- Industrial Systems
- Test and Measurement Equipment
- Breaking Ground Loops

### DESCRIPTION

The LTM®2883 is a complete galvanic digital  $\mu$ Module® isolator. No external components are required. A single 3.3V or 5V supply powers both sides of the interface through an integrated, isolated DC/DC converter. A logic supply pin allows easy interfacing with different logic levels from 1.62V to 5.5V, independent of the main supply.

Available options are compliant with SPI and  $I^2C$  (master mode only) specifications.

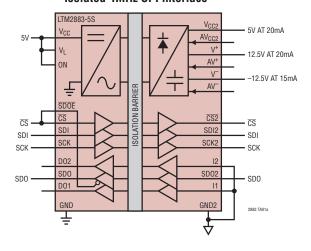
The isolated side includes  $\pm 12.5$ V and 5V nominal power supplies, each capable of providing more than 20mA of load current. Each supply may be adjusted from its nominal value using a single external resistor.

Coupled inductors and an isolation power transformer provide  $2500V_{RMS}$  of isolation between the input and output logic interface. This device is ideal for systems where the ground loop is broken, allowing for a large common mode voltage range. Communication is uninterrupted for common mode transients greater than  $30kV/\mu s$ .

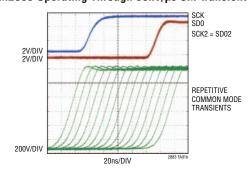
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## TYPICAL APPLICATION

#### Isolated 4MHz SPI Interface



#### LTM2883 Operating Through 35kV/µs CM Transient



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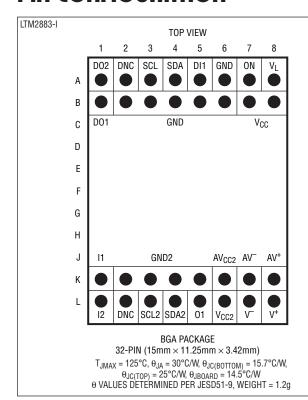
## **ABSOLUTE MAXIMUM RATINGS**

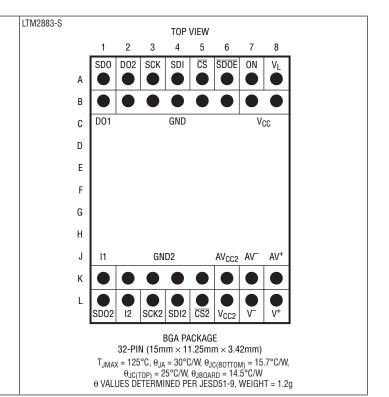
#### (Note 1)

V <sub>CC</sub> to GND	0.3V to 6V
V <sub>L</sub> to GND	0.3V to 6V
V <sub>CC2</sub> , AV <sub>CC2</sub> , AV <sup>+</sup> to GND2	0.3V to 6V
V+ to GND2	0.3V to 16V
V <sup>-</sup> , AV <sup>-</sup> to GND2	0.3V to -16V
Logic Inputs	
DI1, SCK, SDI, $\overline{\text{CS}}$ , SCL, SDA	, <del>SDOE</del> ,
ON to GND	0.3V to $(V_L + 0.3V)$
I1, I2, SDA2,	
SD02 to GND2	$-0.3V$ to $(V_{CC2} + 0.3V)$

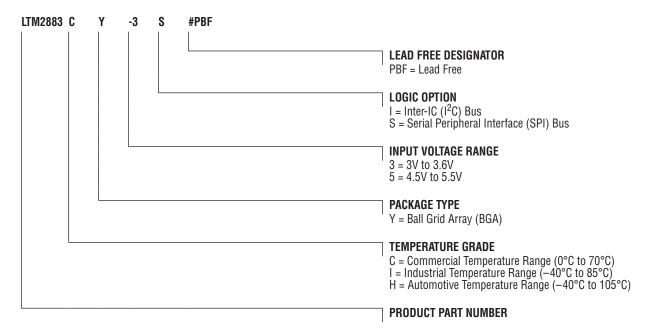
Logic Outputs
D01, D02, SD0 to GND0.3V to (V <sub>L</sub> + 0.3V)
01, SCK2, SDI2, <del>CS2</del> ,
SCL2 to GND2 $-0.3V$ to $(V_{CC2} + 0.3V)$
Operating Temperature Range (Note 4)
$LTM2883C \dots 0^{\circ}C \leq T_{A} \leq 70^{\circ}C$
LTM2883I $-40^{\circ}\text{C} \le T_{A} \le 85^{\circ}\text{C}$
LTM2883H $40^{\circ}$ C $\leq T_{A} \leq 105^{\circ}$ C
Maximum Internal Operating Temperature 125°C
Storage Temperature Range –55°C to 125°C
Peak Body Reflow Temperature

# PIN CONFIGURATION





#### ORDER INFORMATION



### PRODUCT SELECTION GUIDE

PART NUMBER	PART MARKING*	PACKAGE	INPUT VOLTAGE	LOGIC OPTION
LTM2883-31	LTM2883Y-31	BGA	3V to 3.6V	Inter-IC Bus (I <sup>2</sup> C)
LTM2883-3S	LTM2883Y-3S	BGA	3V to 3.6V	Serial Peripheral Interface Bus (SPI)
LTM2883-5I	LTM2883Y-5I	BGA	4.5V to 5.5V	Inter-IC Bus (I <sup>2</sup> C)
LTM2883-5S	LTM2883Y-5S	BGA	4.5V to 5.5V	Serial Peripheral Interface Bus (SPI)

Consult LTC Marketing for parts specified with wider operating temperature ranges. \*The temperature grade is identified by a label on the shipping container. Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: http://www.linear.com/leadfree/

This product is only offered in trays. For more information go to: http://www.linear.com/packaging/

This product is moisture sensitive. For more information go to: http://www.linear.com/packaging/

**ELECTRICAL CHARACTERISTICS** The ullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^{\circ}C$ . LTM2883-3  $V_{CC} = 3.3V$ , LTM2883-5  $V_{CC} = 5V$ ,  $V_L = 3.3V$ , and GND = GND2 = 0V, ON =  $V_L$  unless otherwise noted. Specifications apply to all options unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
Input Sup	plies						
$V_{CC}$	Input Supply Range	LTM2883-3 LTM2883-5	•	3 4.5	3.3 5	3.6 5.5	V
$V_L$	Logic Supply Range	LTM2883-S LTM2883-I	•	1.62 3	5	5.5 5.5	V
I <sub>CC</sub>	Input Supply Current	ON = OV LTM2883-3, $ON = V_L$ , No Load LTM2883-5, $ON = V_L$ , No Load	•		0 25 19	10 35 28	μA mA mA
IL	Logic Supply Current	ON = 0V LTM2883-S, ON = V <sub>L</sub> LTM2883-I, ON = V <sub>L</sub>	•		0 10	10 150	μΑ μΑ μΑ
		·		•			2883f



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SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
Output Si	upplies						
V <sub>CC2</sub>	Regulated Output Voltage	No Load	•	4.75	5	5.25	V
	Output Voltage Operating Range	(Note 2)		3		5.5	V
	Line Regulation	$I_{LOAD} = 1 \text{mA}, \text{MIN} \le V_{CC} \le \text{MAX}$	•		25	100	mV
	Load Regulation	I <sub>LOAD</sub> = 100μA to 20mA	•		8	80	mV
	ADJ Pin Voltage	I <sub>LOAD</sub> = 100μA to 20mA	•	585	600	615	mV
	Voltage Ripple	I <sub>LOAD</sub> = 20mA (Note 2)			1		mV <sub>RMS</sub>
	Efficiency	I <sub>LOAD</sub> = 20mA (Note 2)			45		%
I <sub>CC2</sub>	Output Short Circuit Current	V <sub>CC2</sub> = 0V			45		mA
	Current Limit	$\Delta V_{CC2} = -5\%$	•	20			mA
V <sup>+</sup>	Regulated Output Voltage	No Load	•	12	12.5	13	V
	Line Regulation	$I_{LOAD} = 1 \text{mA}, \text{MIN} \le V_{CC} \le \text{MAX}$	•		5	30	mV
	Load Regulation	I <sub>LOAD</sub> = 100μA to 20mA	•			200	mV
	ADJ Pin Voltage	I <sub>LOAD</sub> = 100μA to 20mA	•	1.170	1.220	1.260	mV
	Voltage Ripple	I <sub>LOAD</sub> = 20mA (Note 2)			3		mV <sub>RMS</sub>
	Efficiency	I <sub>LOAD</sub> = 20mA (Note 2)			45		%
I <sup>+</sup>	Output Short Circuit Current	V+ = 0V			70		mA
	Current Limit	$\Delta V^{+} = -0.5V$	•	20			mA
V-	Regulated Output Voltage	No Load	•	-12	-12.5	-13	V
	Line Regulation	$I_{LOAD} = -1 \text{ mA}, \text{ MIN} \leq V_{CC} \leq \text{MAX}$	•		4	15	mV
	Load Regulation	I <sub>LOAD</sub> = 100μA to 15mA I <sub>LOAD</sub> = 100μA to 15mA, H-Grade	•		35	35 150	mV mV
	ADJ Pin Voltage	I <sub>LOAD</sub> = 100μA to 15mA	•	-1.184	-1.220	-1.256	mV
	Voltage Ripple	I <sub>LOAD</sub> = 15mA (Note 2)			2		mV <sub>RMS</sub>
	Efficiency	I <sub>LOAD</sub> = 15mA (Note 2)			45		%
<u> -</u>	Output Short-Circuit Current	V <sup>-</sup> = 0V			30		mA
	Current Limit	$\Delta V^{-} = 0.5V, V^{+} = 1.5mA$	•	10	15		mA
Logic/SP	l						
V <sub>ITH</sub>	Input Threshold Voltage	ON, DI1, $\overline{\text{SD0E}}$ , SCK, SDI, $\overline{\text{CS}}$ 1.62V $\leq$ V <sub>L</sub> $<$ 2.35V ON, DI1, $\overline{\text{SD0E}}$ , SCK, SDI, $\overline{\text{CS}}$ 2.35V $\leq$ V <sub>L</sub> I1, I2, SD02	•	0.25 • V <sub>L</sub> 0.33 • V <sub>L</sub> 0.33 • V <sub>CC2</sub>		0.75 • V <sub>L</sub> 0.67 • V <sub>L</sub> 0.67 • V <sub>CC2</sub>	V V V
I <sub>INL</sub>	Input Current		•			±1	μA
V <sub>HYS</sub>	Input Hysteresis	(Note 2)			150		mV
V <sub>OH</sub>	Output High Voltage	D01, D02, SD0 $I_{LOAD} = -1mA$ , 1.62V $\leq V_L < 3V$ $I_{LOAD} = -4mA$ , $3V \leq V_L \leq 5.5V$	•	V <sub>L</sub> - 0.4			V
		O1, SCK2, SDI2, $\overline{CS2}$ , $I_{LOAD} = -4mA$	•	V <sub>CC2</sub> - 0.4			V
V <sub>OL</sub>	Output Low Voltage	D01, D02, SD0 $I_{LOAD} = 1 \text{mA}, 1.62 \text{V} \le \text{V}_{L} < 3 \text{V}$ $I_{LOAD} = 4 \text{mA}, 3 \text{V} \le \text{V}_{L} \le 5.5 \text{V}$	•			0.4	V
		01, SCK2, SDI2, $\overline{\text{CS2}}$ , $I_{\text{LOAD}} = 4\text{mA}$	•			0.4	V
I <sub>SC</sub>	Short-Circuit Current	$ \begin{array}{l} 0V \leq (D01,D02,SD0) \leq V_L \\ 0V \leq (01,SCK2,SDI2,\overline{CS2}) \leq V_{CC2} \end{array} $	•		±60	±85	mA mA

**TLINEAR** 

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SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
I <sup>2</sup> C		,		'			
V <sub>IL</sub>	Low Level Input Voltage	SCL, SDA SDA2	•			0.3 • V <sub>L</sub> 0.3 • V <sub>CC2</sub>	V
V <sub>IH</sub>	High Level Input Voltage	SCL, SDA SDA2	•	0.7 • V <sub>L</sub> 0.7 • V <sub>CC2</sub>			V
I <sub>INL</sub>	Input Current	SCL, SDA = V <sub>L</sub> or 0V	•			±1	μА
V <sub>HYS</sub>	Input Hysteresis	SCL, SDA SDA2			0.05 • V <sub>L</sub> 0.05 • V <sub>CC2</sub>		mV mV
V <sub>OH</sub>	Output High Voltage	SCL2, $I_{LOAD} = -2mA$ DO2, $I_{LOAD} = -2mA$	•	$V_{CC2} - 0.4$ $V_L - 0.4$			V
V <sub>OL</sub>	Output Low Voltage	SDA, $V_L = 3V$ , $I_{LOAD} = 3mA$ D02, $V_L = 3V$ , $I_{LOAD} = 2mA$ SCL2, $I_{LOAD} = 2mA$ SDA2, No Load, SDA = 0V, $4.5V \le V_{CC2} < 5.5V$ SDA2, No Load, SDA = 0V, $3V < V_{CC2} < 4.5V$	•		0.3	0.4 0.4 0.4 0.45 0.55	V V V V
C <sub>IN</sub>	Input Pin Capacitance	SCL, SDA, SDA2 (Note 2)	•			10	pF
C <sub>B</sub>	Bus Capacitive Load	SCL2, Standard Speed (Note 2) SCL2, Fast Speed SDA, SDA2, SR ≥ 1V/µs, Standard Speed (Note 2) SDA, SDA2, SR ≥ 1V/µs, Fast Speed	•			400 200 400 200	pF pF pF pF
	Minimum Bus Slew Rate	SDA, SDA2	•	1			V/µs
I <sub>SC</sub>	Short-Circuit Current	$\begin{array}{l} SDA2 = 0, \ SDA = V_L \\ 0V \leq SCL2 \leq V_{CC2} \\ 0V \leq D02 \leq V_L \\ SDA = 0, \ SDA2 = V_{CC2} \\ SDA = V_L, \ SDA2 = 0 \end{array}$	•		±30 ±30 6 –1.8	100	mA mA mA mA
ESD (HBN	M) (Note 2)						
	Isolation Boundary	(V <sub>CC2</sub> , V <sup>+</sup> , V <sup>-</sup> , GND2) to (V <sub>CC</sub> , V <sub>L</sub> , GND)			±10		kV

**SWITCHING CHARACTERISTICS** The  $\bullet$  denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^{\circ}C$ . LTM2883-3  $V_{CC} = 3.3V$ , LTM2883-5  $V_{CC} = 5V$ ,  $V_L = 3.3V$ , and GND = GND2 = 0V, ON =  $V_L$  unless otherwise noted. Specifications apply to all options unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
Logic							
	Maximum Data Rate	$Ix \rightarrow DOx$ , $C_L = 15pF$ (Note 3)	•	10			MHz
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation Delay	C <sub>L</sub> = 15pF (Figure 1)	•	35	60	100	ns
t <sub>R</sub>	Rise Time	C <sub>L</sub> = 15pF (Figure 1) LTM2883-I, D02, C <sub>L</sub> = 15pF (Figure 1)	•		3 20	12.5 35	ns ns
t <sub>F</sub>	Fall Time	C <sub>L</sub> = 15pF (Figure 1) LTM2883-I, D02, C <sub>L</sub> = 15pF (Figure 1)	•		3 20	12.5 35	ns ns
SPI							
	Maximum Data Rate	Bidirectional Communication (Note 3) Unidirectional Communication (Note 3)	•	4 8			MHz MHz
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation Delay	C <sub>L</sub> = 15pF (Figure 1)	•	35	60	100	ns
t <sub>PWU</sub>	Output Pulse Width Uncertainty	SDI2, CS2 (Note 2)		-20		50	ns



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SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
$\overline{t_R}$	Rise Time	C <sub>L</sub> = 15pF (Figure 1)	•		3	12.5	ns
t <sub>F</sub>	Fall Time	C <sub>L</sub> = 15pF (Figure 1)	•		3	12.5	ns
t <sub>PZH</sub> , t <sub>PZL</sub>	Output Enable Time	$\overline{\text{SDOE}} = \downarrow$ , R <sub>L</sub> = 1k $\Omega$ , C <sub>L</sub> = 15pF (Figure 2)	•			50	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Output Disable Time	$\overline{SDOE} = \uparrow$ , R <sub>L</sub> = 1k $\Omega$ , C <sub>L</sub> = 15pF (Figure 2)	•			50	ns
I <sup>2</sup> C							
	Maximum Data Rate	(Note 3)	•	400			kHz
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation Delay	$\begin{array}{l} SCL \rightarrow SCL2, \ C_L = 15pF \ (Figure \ 1) \\ SDA \rightarrow SDA2, \ R_L = 0pen, \ C_L = 15pF \ (Figure \ 3) \\ SDA2 \rightarrow SDA, \ R_L = 1.1k\Omega, \ C_L = 15pF \ (Figure \ 3) \end{array}$	•		150 150 200	225 250 350	ns ns ns
t <sub>PWU</sub>	Output Pulse Width Uncertainty	SDA, SDA2 (Note 2)		-20		50	ns
t <sub>HD;DAT</sub>	Data Hold Time	(Note 2)			600		ns
t <sub>R</sub>	Rise Time	SDA2, $C_L$ = 200pF (Figure 3) SDA2, $C_L$ = 200pF (Figure 3) SDA, $R_L$ = 1.1k $\Omega$ , $C_L$ = 200pF (Figure 3) SCL2, $C_L$ = 200pF (Figure 1)	•	40 40 40		250 300 250 250	ns ns ns
t <sub>F</sub>	Fall Time	SDA2, $C_L$ = 200pF (Figure 3) SDA, $R_L$ = 1.1k $\Omega$ , $C_L$ = 200pF (Figure 3) SCL2, $C_L$ = 200pF (Figure 1)	•	40 40		250 250 250	ns ns ns
t <sub>SP</sub>	Pulse Width of Spikes Suppressed by Input Filter		•	0		50	ns
Power Sup	pply						
	Power-Up Time	$ \begin{array}{c} \text{ON} = \uparrow \text{ to V}_{CC2} \text{ (Min)} \\ \text{ON} = \uparrow \text{ to V}^+ \text{ (Min)} \\ \text{ON} = \uparrow \text{ to V}^- \text{ (Min)} \\ \end{array} $	•		0.6 0.6 0.6	2 2 2.5	ms ms ms

## **ISOLATION CHARACTERISTICS** $T_A = 25$ °C.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
V <sub>ISO</sub>	Rated Dielectric Insulation Voltage	1 Minute, Derived from 1 Second Test	2500			V <sub>RMS</sub>
		1 Second (Note 5)	±4400			V
	Common Mode Transient Immunity	LTM2883-3 $V_{CC}$ = 3.3V, LTM2883-5 $V_{CC}$ = 5V, $V_{L}$ = 0N = 3.3V, $V_{CM}$ = 1kV, $\Delta t$ = 33ns (Note 2)	30			kV/μs
V <sub>IORM</sub>	Maximum Working Insulation Voltage	(Notes 2, 5)	560 400			V <sub>PEAK</sub> V <sub>RMS</sub>
	Partial Discharge	V <sub>PD</sub> = 1050V <sub>PEAK</sub> (Notes 2, 5)			5	pC
	Input to Output Resistance	(Notes 2, 5)	10 <sup>9</sup>			Ω
	Input to Output Capacitance	(Notes 2, 5)		6		pF
	Creepage Distance	(Note 2)		9.48		mm

**Note 1:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

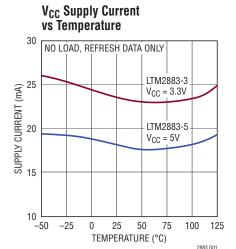
Note 2: Guaranteed by design and not subject to production test.

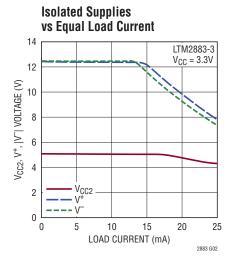
**Note 3:** Maximum data rate is guaranteed by other measured parameters and is not tested directly.

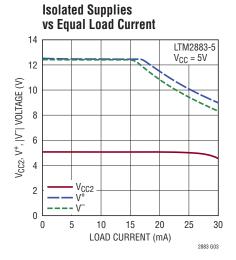
**Note 4:** This module includes overtemperature protection that is intended to protect the device during momentary overload conditions. Junction temperature will exceed 125°C when overtemperature protection is active. Continuous operation above specified maximum operating junction temperature may result in device degradation or failure.

**Note 5:** Device considered a 2-terminal device. Pin group A1 through B8 shorted together and pin group K1 through L8 shorted together.

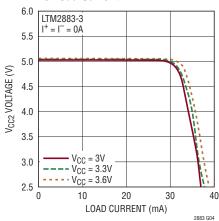
LINEAR TECHNOLOGY

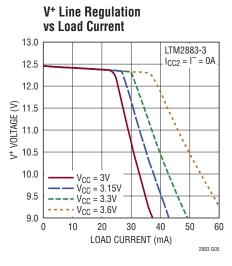


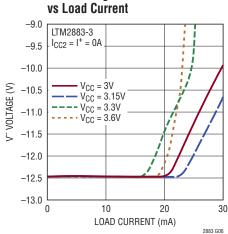




V<sub>CC2</sub> Line Regulation vs Load Current

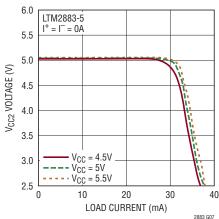


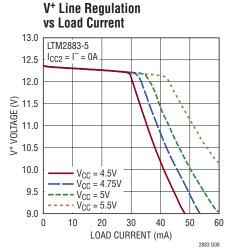


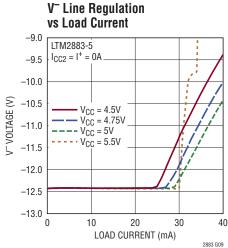


V- Line Regulation

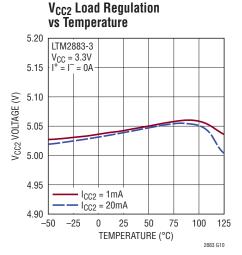
V<sub>CC2</sub> Line Regulation vs Load Current

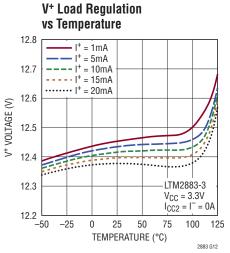


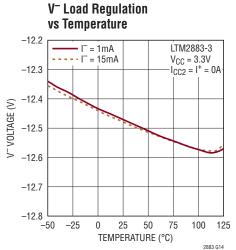




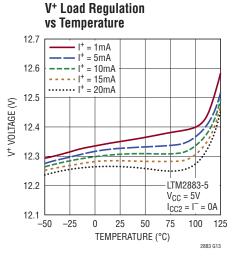
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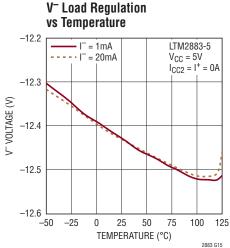


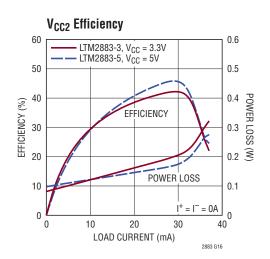




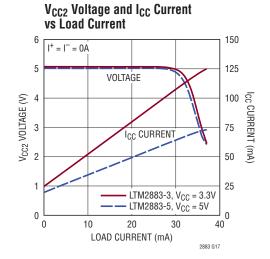
V<sub>CC2</sub> Load Regulation vs Temperature 5.20 LTM2883-5 V<sub>CC</sub> = 5V I<sup>+</sup> = I<sup>-</sup> = 0A 5.15 V<sub>CC2</sub> VOLTAGE (V) 5.10 5.05 5.00 4.95  $I_{CC2} = 1mA$  $I_{CC2} = 20 \text{mA}$ 4.90 \_50 -25 25 50 75 100 125 TEMPERATURE (°C)

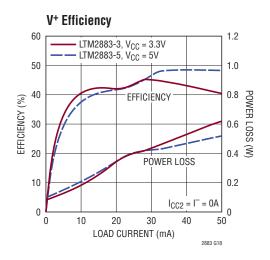


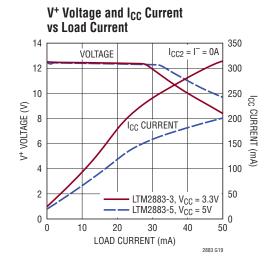


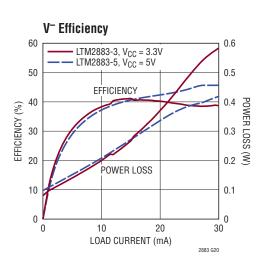


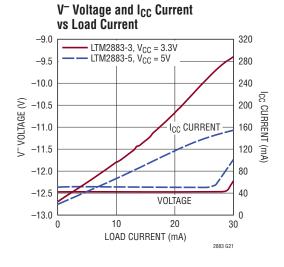
2883 G11

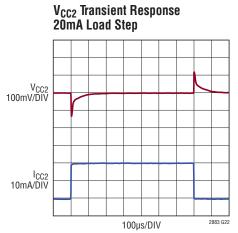


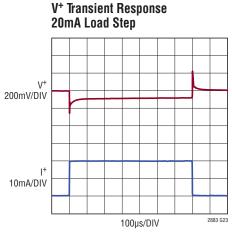


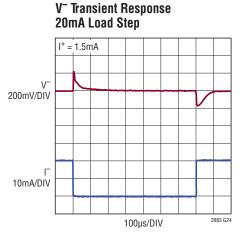




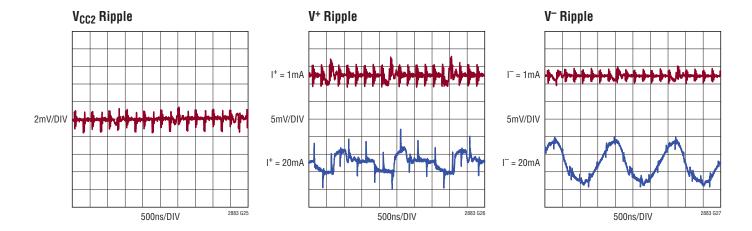


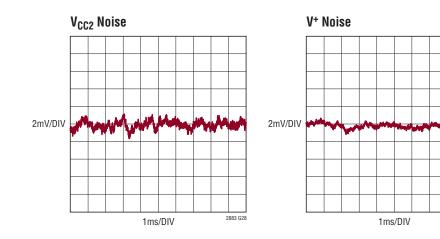


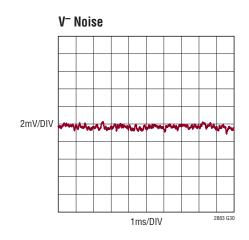


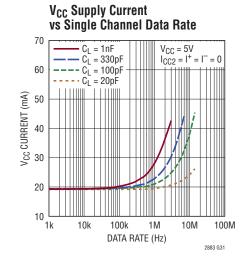


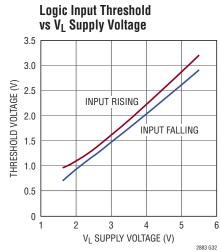
2883f

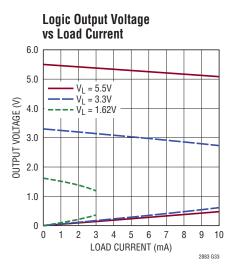






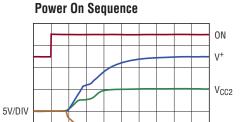






2883f

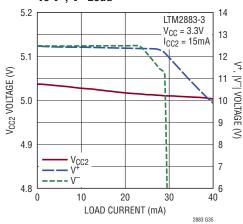




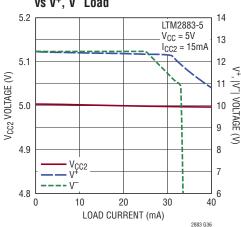
200µs/DIV

2883 G34

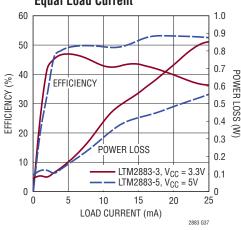
 $V_{CC2}$  Cross Regulation vs V+, V^ Load



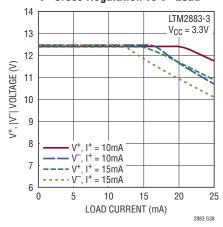




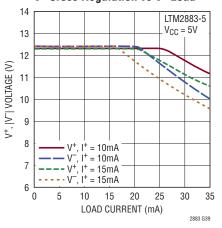
#### **Isolated Supply Efficiency with Equal Load Current**



#### V+ Cross Regulation vs V- Load



#### V+ Cross Regulation vs V- Load



## PIN FUNCTIONS (LTM2883-I)

#### **Logic Side**

**D02 (A1):** Digital Output, Referenced to  $V_L$  and GND. Logic output connected to I2 through isolation barrier. Under the condition of an isolation communication failure this output is in a high impedance state.

**DNC (A2):** Do Not Connect Pin. Pin connected internally.

**SCL (A3):** Serial  $I^2C$  Clock Input, Referenced to  $V_L$  and GND. Logic input connected to isolated side SCL2 pin through isolation barrier. Clock is unidirectional from logic to isolated side. Do not float.

**SDA (A4):** Serial I<sup>2</sup>C Data Pin, Referenced to  $V_L$  and GND. Bidirectional logic pin connected to isolated side SDA2 pin through isolation barrier. Under the condition of an isolation communication failure this pin is in a high impedance state. Do not float.

**DI1 (A5):** Digital Input, Referenced to  $V_L$  and GND. Logic input connected to O1 through isolation barrier. The logic state on DI1 translates to the same logic state on O1. Do not float.

GND (A6, B2 to B6): Circuit Ground.

**ON (A7):** Enable. Enables power and data communication through the isolation barrier. If ON is high the part is enabled and power and communications are functional to the isolated side. If ON is low the logic side is held in reset, all digital outputs are in a high impedance state, and the isolated side is unpowered. Do not float.

**V<sub>L</sub> (A8):** Logic Supply. Interface supply voltage for pins DI1, SCL, SDA, DO1, DO2, and ON. Operating voltage is 3V to 5.5V. Internally bypassed with 2.2μF.

**D01 (B1):** Digital Output, Referenced to  $V_L$  and GND. Logic output connected to I1 through isolation barrier. Under the condition of an isolation communication failure this output is in a high impedance state.

**V<sub>CC</sub> (B7 to B8):** Supply Voltage. Operating voltage is 3V to 3.6V for LTM2883-3 and 4.5V to 5.5V for LTM2883-5. Internally bypassed with 2.2µF.

#### **Isolated Side**

**I2 (L1):** Digital Input, Referenced to  $V_{CC2}$  and GND2. Logic input connected to DO2 through isolation barrier.

The logic state on I2 translates to the same logic state on DO2. Do not float.

**DNC (L2):** Do Not Connect Pin. Pin connected internally.

**SCL2 (L3):** Serial  $I^2C$  Clock Output, Referenced to  $V_{CC2}$  and GND2. Logic output connected to logic side SCL pin through isolation barrier. Clock is unidirectional from logic to isolated side. SCL2 has a push-pull output stage, do not connect an external pull-up device. Under the condition of an isolation communication failure this output defaults to a high state.

**SDA2 (L4):** Serial  $I^2C$  Data Pin, Referenced to  $V_{CC2}$  and GND2. Bidirectional logic pin connected to logic side SDA pin through isolation barrier. Output is biased high by a 1.8mA current source. Do not connect an external pullup device to SDA2. Under the condition of an isolation communication failure this output defaults to a high state.

**01 (L5):** Digital Output, Referenced to  $V_{CC2}$  and GND2. Logic output connected to DI1 through isolation barrier. Under the condition of an isolation communication failure O1 defaults to a high state.

 $V_{CC2}$  (L6): 5V Nominal Isolated Supply Voltage. Internally generated from  $V_{CC}$  by an isolated DC/DC converter and regulated to 5V. Internally bypassed with 2.2µF.

 $V^-(L7)$ : -12.5V Nominal Isolated Supply Voltage. Internally generated from  $V_{CC}$  by an isolated DC/DC converter and regulated to -12.5V. Internally bypassed with 1µF.

**V**<sup>+</sup> **(L8):** 12.5V Nominal Isolated Supply Voltage. Internally generated from  $V_{CC}$  by an isolated DC/DC converter and regulated to 12.5V. Internally bypassed with 1 $\mu$ F.

**I1 (K1):** Digital Input, Referenced to  $V_{CC2}$  and GND2. Logic input connected to DO1 through isolation barrier. The logic state on I1 translates to the same logic state on DO1. Do not float.

**GND2 (K2 to K5):** Isolated Ground.

**AV<sub>CC2</sub>** (**K6**): 5V Nominal Isolated Supply Voltage Adjust. The adjust pin voltage is 600mV referenced to GND2.

**AV**<sup>-</sup> **(K7)**: –12.5V Nominal Isolated Supply Voltage Adjust. The adjust pin voltage is –1.22V referenced to GND2.

**AV**<sup>+</sup> **(K8):** 12.5V Nominal Isolated Supply Voltage Adjust. The adjust pin voltage is 1.22V referenced to GND2.

20031



## PIN FUNCTIONS (LTM2883-S)

#### **Logic Side**

**SDO (A1):** Serial SPI Digital Output, Referenced to  $V_L$  and GND. Logic output connected to isolated side SDO2 pin through isolation barrier. Under the condition of an isolation communication failure this output is in a high impedance state.

**D02 (A2):** Digital Output, Referenced to  $V_L$  and GND. Logic output connected to I2 through isolation barrier. Under the condition of an isolation communication failure this output is in a high impedance state.

**SCK (A3):** Serial SPI Clock Input, Referenced to  $V_L$  and GND. Logic input connected to isolated side SCK2 pin through isolation barrier. Do not float.

**SDI (A4):** Serial SPI Data Input, Referenced to  $V_L$  and GND. Logic input connected to isolated side SDI2 pin through isolation barrier. Do not float.

 $\overline{\textbf{CS}}$  (A5): Serial SPI Chip Select, Referenced to V<sub>L</sub> and GND. Logic input connected to isolated side  $\overline{\text{CS2}}$  pin through isolation barrier. Do not float.

**SDOE** (A6): Serial SPI Data Output Enable, Referenced to  $V_L$  and GND. A logic high on  $\overline{SDOE}$  places the logic side SDO pin in a high impedance state, a logic low enables the output. Do not float.

**ON (A7):** Enable. Enables power and data communication through the isolation barrier. If ON is high the part is enabled and power and communications are functional to the isolated side. If ON is low the logic side is held in reset, all digital outputs are in a high impedance state, and the isolated side is unpowered. Do not float.

**V<sub>L</sub>** (A8): Logic Supply. Interface supply voltage for pins SDI, SCK, SDO, DO1, DO2,  $\overline{CS}$ , and ON. Operating voltage is 1.62V to 5.5V. Internally bypassed with 2.2 $\mu$ F.

**D01 (B1):** Digital Output, Referenced to  $V_L$  and GND. Logic output connected to I1 through isolation barrier. Under the condition of an isolation communication failure this output is in a high impedance state.

GND (B2 to B6): Circuit Ground.

**V<sub>CC</sub> (B7 to B8):** Supply Voltage. Operating voltage is 3V to 3.6V for LTM2883-3 and 4.5V to 5.5V for LTM2883-5. Internally bypassed with 2.2µF.

#### **Isolated Side**

**SD02 (L1):** Serial SPI Digital Input, Referenced to  $V_{\text{CC2}}$  and GND2. Logic input connected to logic side SD0 pin through isolation barrier. Do not float.

**I2 (L2):** Digital Input, Referenced to  $V_{CC2}$  and GND2. Logic input connected to DO2 through isolation barrier. The logic state on I2 translates to the same logic state on DO2. Do not float.

**SCK2 (L3):** Serial SPI Clock Output, Referenced to  $V_{CC2}$  and GND2. Logic output connected to logic side SCK pin through isolation barrier. Under the condition of an isolation communication failure this output defaults to a low state.

**SDI2 (L4):** Serial SPI Data Output, Referenced to  $V_{CC2}$  and GND2. Logic output connected to logic side SDI pin through isolation barrier. Under the condition of an isolation communication failure this output defaults to a low state.

 $\overline{\text{CS2}}$  (L5): Serial SPI Chip Select, Referenced to  $V_{CC2}$  and GND2. Logic output connected to logic side  $\overline{\text{CS}}$  pin through isolation barrier. Under the condition of an isolation communication failure this output defaults to a high state.

 $V_{CC2}$  (L6): 5V Nominal Isolated Supply Voltage. Internally generated from  $V_{CC}$  by an isolated DC/DC converter and regulated to 5V. Internally bypassed with 2.2 $\mu$ F.

 $V^-(L7)$ : -12.5V Nominal Isolated Supply Voltage. Internally generated from  $V_{CC}$  by an isolated DC/DC converter and regulated to -12.5V. Internally bypassed with 1 $\mu$ F.

**V**<sup>+</sup> **(L8):** 12.5V Nominal Isolated Supply Voltage. Internally generated from  $V_{CC}$  by an isolated DC/DC converter and regulated to 12.5V. Internally bypassed with 1 $\mu$ F.

**I1 (K1):** Digital Input, Referenced to  $V_{CC2}$  and GND2. Logic input connected to DO1 through isolation barrier. The logic state on I1 translates to the same logic state on DO1. Do not float.

**GND2 (K2 to K5):** Isolated Ground.

**AV<sub>CC2</sub>** (**K6**): 5V Nominal Isolated Supply Voltage Adjust. The adjust pin voltage is 600mV Referenced to GND2.

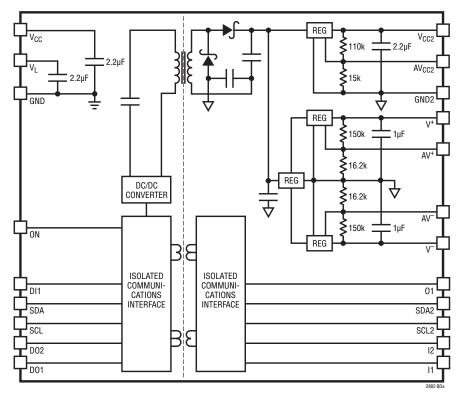
**AV**<sup>-</sup> **(K7)**: –12.5V Nominal Isolated Supply Voltage Adjust. The adjust pin voltage is –1.22V Referenced to GND2.

**AV**<sup>+</sup> (**K8**): 12.5V Nominal Isolated Supply Voltage Adjust. The adjust pin voltage is 1.22V Referenced to GND2.

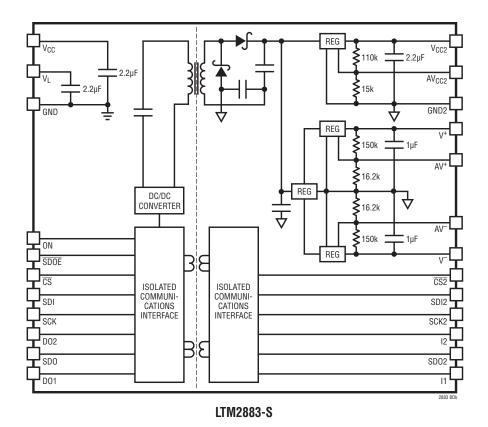




# **BLOCK DIAGRAM**

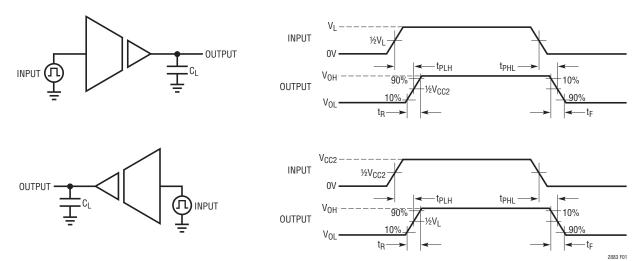


LTM2883-I



LINEAR TECHNOLOGY

# **TEST CIRCUITS**



**Figure 1. Logic Timing Measurements** 

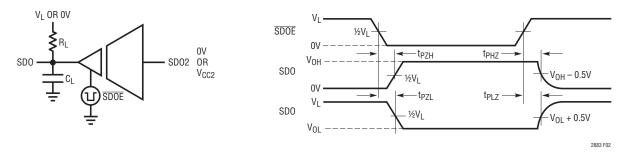


Figure 2. Logic Enable/Disable Time

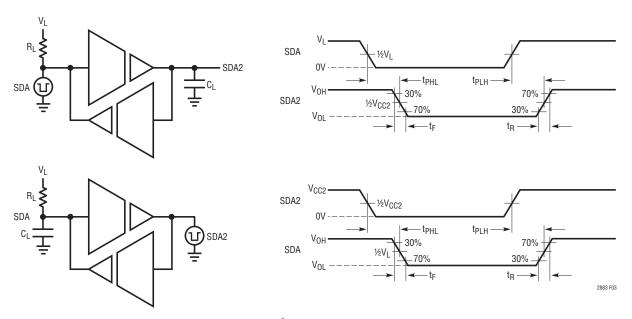


Figure 3. I<sup>2</sup>C Timing Measurements



#### Overview

The LTM2883 digital µModule isolator provides a galvanically-isolated robust logic interface, powered by an integrated, regulated DC/DC converter, complete with decoupling capacitors. The LTM2883 is ideal for use in networks where grounds can take on different voltages. Isolation in the LTM2883 blocks high voltage differences, eliminates ground loops and is extremely tolerant of common mode transients between ground planes. Error-free operation is maintained through common mode events greater than 30kV/µs providing excellent noise isolation.

#### Isolator µModule Technology

The LTM2883 utilizes isolator  $\mu$ Module technology to translate signals and power across an isolation barrier. Signals on either side of the barrier are encoded into pulses and translated across the isolation boundary using coreless transformers formed in the  $\mu$ Module substrate. This system, complete with data refresh, error checking, safe shutdown on fail, and extremely high common mode immunity, provides a robust solution for bidirectional signal isolation. The  $\mu$ Module technology provides the means to combine the isolated signaling with multiple regulators and a powerful isolated DC/DC converter in one small package.

#### DC/DC Converter

The LTM2883 contains a fully integrated DC/DC converter, including the transformer, so that no external components are necessary. The logic side contains a full-bridge driver, running at 2MHz, and is AC-coupled to a single transformer primary. A series DC blocking capacitor prevents transformer saturation due to driver duty cycle imbalance. The transformer scales the primary voltage, and is rectified by a full-wave voltage doubler. This topology allows for a single diode drop, as in a center tapped full-wave bridge, and eliminates transformer saturation caused by secondary imbalances.

The DC/DC converter is connected to a low dropout regulator (LDO) to provide a regulated 5V output.

An integrated boost converter generates a regulated 14V supply and a charge pumped –14V supply. These rails are regulated to ±12.5V respectively by low dropout regulators.

Performance of the -12.5V supply is enhanced by loading the 12.5V supply. A load current of 1.5mA is sufficient to improve static and dynamic load regulation characteristics of the -12.5V output. The increased load allows the boost regulator to operate continuously and in turn improves the regulation of the inverting charge pump.

The internal power solution is sufficient to provide a minimum of 20mA of current from  $V_{CC2}$  and  $V^+$ , and 15mA from  $V^-$ .  $V_{CC}$  and  $V_{CC2}$  are each bypassed with 2.2 $\mu$ F ceramic capacitors, and  $V^+$  and  $V^-$  are bypassed with 1 $\mu$ F ceramic capacitors.

#### **V<sub>L</sub> Logic Supply**

A separate logic supply pin  $V_L$  allows the LTM2883 to interface with any logic signal from 1.62V to 5.5V as shown in Figure 4. Simply connect the desired logic supply to  $V_L$ .

There is no interdependency between  $V_{CC}$  and  $V_L$ ; they may simultaneously operate at any voltage within their specified operating ranges and sequence in any order.  $V_L$  is bypassed internally by a  $2.2\mu F$  capacitor.

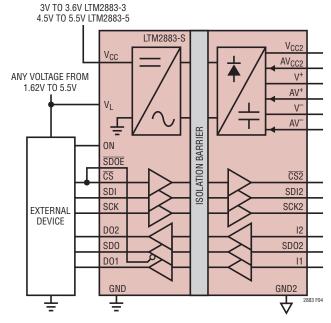


Figure 4. V<sub>CC</sub> and V<sub>L</sub> Are Independent

#### **Hot-Plugging Safely**

Caution must be exercised in applications where power is plugged into the LTM2883's power supplies,  $V_{CC}\,\text{or}\,V_L,$  due to the integrated ceramic decoupling capacitors. The



parasitic cable inductance along with the high Q characteristics of ceramic capacitors can cause substantial ringing which could exceed the maximum voltage ratings and damage the LTM2883. Refer to Linear Technology Application Note 88, entitled Ceramic Input Capacitors Can Cause Overvoltage Transients for a detailed discussion and mitigation of this phenomenon.

#### **Isolated Supply Adjustable Operation**

The three isolated power rails may be adjusted by connection of a single resistor from the adjust pin of each output to its associated output voltage or to GND2. The pre-configured voltages represent the maximums for guaranteed performance. Figure 5 illustrates configuration of the output power rails for  $V_{CC2} = 3.3V$ ,  $V^+ = 10V$ , and  $V^- = -10V$ .

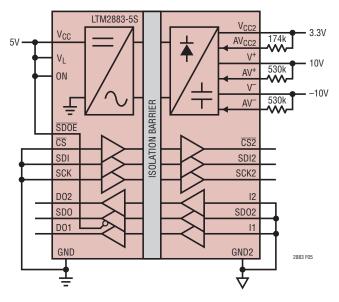


Figure 5. Adjustable Voltage Rails

To decrease the output voltage a resistor must be connected from the output voltage pin to the associated adjust pin. To increase the output voltage connect a resistor to the adjust pin to GND2. Use the equations listed in Table 1 to calculate the resistances required to adjust each output. The output voltage adjustment range for  $V_{CC2}$  is 3V to 5.5V. Adjustment range for V+ and V- is  $\pm 1.22$ V to approximately  $\pm 13.5$ V. Operation at low output voltages for V+ or V- may result in thermal shutdown due to low dropout regulator power dissipation.

Table 1. Voltage Adjustment Formula

OUTPUT VOLTAGE	RESISTOR (Ax TO Vx) TO REDUCE OUTPUT	RESISTOR (Ax TO GND2) TO INCREASE OUTPUT
V <sub>CC2</sub>	$\frac{110k \bullet (V_{CC2} - 0.6)}{5 - V_{CC2}}$	$\frac{66k}{V_{CC2} - 5}$
V+, V <sup>-</sup>	$\frac{150k \bullet ( V^+, V^-  - 1.22)}{12.5 -  V^+, V^- }$	183k  V <sup>+</sup> ,V <sup>-</sup>  -12.5

#### **Channel Timing Uncertainty**

Multiple channels are supported across the isolation boundary by encoding and decoding of the inputs and outputs. Up to three signals in each direction are assembled as a serial packet and transferred across the isolation barrier. The time required to transfer all 3 bits is 100ns maximum, and sets the limit for how often a signal can change on the opposite side of the barrier. Encoding transmission is independent for each data direction. The technique used assigns SCK or SCL on the logic side, and SDO2 or I2 on the isolated side. the highest priority such that there is no jitter on the associated output channels, only delay. This preemptive scheme will produce a certain amount of uncertainty on the other isolation channels. The resulting pulse width uncertainty on these low priority channels is typically ±6ns, but may vary up to ±44ns if the low priority channels are not encoded within the same high priority serial packet.

#### Serial Peripheral Interface (SPI) Bus

The LTM2883-S provides a SPI compatible isolated interface. The maximum data rate is a function of the inherent channel propagation delays, channel to channel pulse width uncertainty, and data direction requirements. Channel timing is detailed in Figures 5 through 8 and Tables 3 and 4. The SPI protocol supports four unique timing configurations defined by the clock polarity (CPOL) and clock phase (CPHA) summarized in Table 2.

Table 2. SPI Mode

CPOL	СРНА	DATA TO (CLOCK	() RELATIONSHIP				
0	0	Sample (Rising)	Set-Up (Falling)				
0	1	Set-Up (Rising) Sample (Falling)					
1	0	Sample (Falling)	Set-Up (Rising)				
1	1	Set-Up (Falling)	Sample (Rising)				
		•					





The maximum data rate for bidirectional communication is 4MHz, based on a synchronous system, as detailed in the timing waveforms. Slightly higher data rates may be achieved by skewing the clock duty cycle and minimizing the SDO to SCK set-up time, however the clock rate is still dominated by the system propagation delays. A discussion of the critical timing paths relative to Figure 6 and 7 follows.

•  $\overline{\text{CS}}$  to SCK (master sample SDO, 1st SDO valid)

 $t_0 \to t_1 \ \ \approx \! 50 \text{ns}, \, \overline{CS} \text{ to } \overline{CS2} \text{ propagation delay}$ 

 $t_1 \rightarrow t_{1+}$  Isolated slave device propagation (response time), asserts SDO2

 $t_1 \rightarrow t_3$  ≈50ns, SD02 to SD0 propagation delay

 $t_3 \rightarrow t_5$  Set-up time for master SDO to SCK

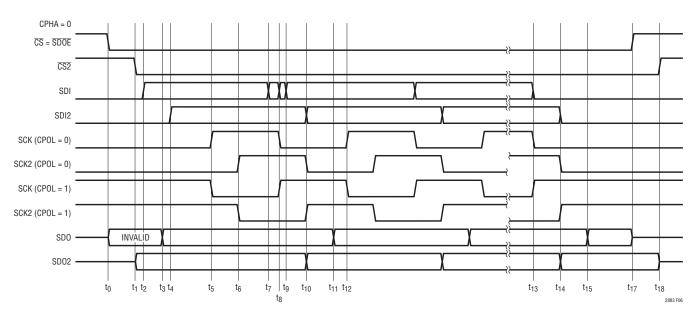


Figure 6. SPI Timing, Bidirectional, CPHA = 0

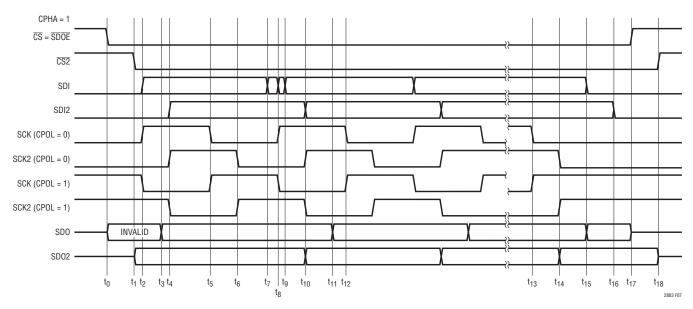


Figure 7. SPI Timing, Bidirectional, CPHA = 1

/ TLINEAR

• SDI to SCK (master data write to slave)

 $t_2 \rightarrow t_4$  ≈50ns, SDI to SDI2 propagation delay

 $t_5 \rightarrow t_6 \approx 50$ ns, SCK to SCK2 propagation delay

 $t_2 \rightarrow t_5 \quad \geq 50 \text{ns}, \, \text{SDI to SCK}, \, \text{separate packet}$ 

non-zero set-up time

 $t_4 \rightarrow t_6 \ge 50$ ns, SDI2 to SCK2, separate packet

non-zero set-up time

SD0 to SCK (master sample SD0, subsequent SD0 valid)

t<sub>8</sub> set-up data transition SDI and SCK

 $t_8 \rightarrow t_{10} \quad {\approx} 50 \text{ns}, \, \text{SDI} \text{ to SDI2} \text{ and SCK to SCK2}$ 

propagation delay

t<sub>10</sub> SD02 data transition in response to SCK2

 $t_{10} \rightarrow t_{11} \approx 50$ ns, SD02 to SD0 propagation delay

 $t_{11} \rightarrow t_{12}$  Set-up time for master SDO to SCK

Table 3. Bidirectional SPI Timing Event Description

TIME	СРНА	EVENT DESCRIPTION
t <sub>0</sub>	0, 1	Asynchronous chip select, may be synchronous to SDI but may not lag by more than 3ns. Logic side slave data output enabled, initial data is not equivalent to slave device data output
t <sub>0</sub> to t <sub>1</sub> , t <sub>17</sub> to t <sub>18</sub>	0, 1	Propagation delay chip select, logic to isolated side, 50ns typical
t <sub>1</sub>	0, 1	Slave device chip select output data enable
t <sub>2</sub>	0	Start of data transmission, data set-up
	1	Start of transmission, data and clock set-up. Data transition must be within -13ns to 3ns of clock edge
t <sub>1</sub> to t <sub>3</sub>	0, 1	Propagation delay of slave data, isolated to logic side, 50ns typical
$\overline{t_3}$	0, 1	Slave data output valid, logic side
t <sub>2</sub> to t <sub>4</sub>	0	Propagation delay of data, logic side to isolated side
	1	Propagation delay of data and clock, logic side to isolated side
t <sub>5</sub>	0, 1	Logic side data sample time, half clock period delay from data set-up transition
t <sub>5</sub> to t <sub>6</sub>	0, 1	Propagation delay of clock, logic to isolated side
t <sub>6</sub>	0, 1	Isolated side data sample time
t <sub>8</sub>	0, 1	Synchronous data and clock transition, logic side
t <sub>7</sub> to t <sub>8</sub>	0, 1	Data to clock delay, must be ≤13ns
t <sub>8</sub> to t <sub>9</sub>	0, 1	Clock to data delay, must be ≤3ns
t <sub>8</sub> to t <sub>10</sub>	0, 1	Propagation delay clock and data, logic to isolated side
t <sub>10,</sub> t <sub>14</sub>	0, 1	Slave device data transition
t <sub>10</sub> to t <sub>11,</sub> t <sub>14</sub> to t <sub>15</sub>	0, 1	Propagation delay slave data, isolated to logic side
t <sub>11</sub> to t <sub>12</sub>	0, 1	Slave data output to sample clock set-up time
t <sub>13</sub>	0	Last data and clock transition logic side
	1	Last sample clock transition logic side
t <sub>13</sub> to t <sub>14</sub>	0	Propagation delay data and clock, logic to isolated side
	1	Propagation delay clock, logic to isolated side
t <sub>15</sub>	0	Last slave data output transition logic side
	1	Last slave data output and data transition, logic side
t <sub>15</sub> to t <sub>16</sub>	1	Propagation delay data, logic to isolated side
t <sub>17</sub>	0, 1	Asynchronous chip select transition, end of transmission. Disable slave data output logic side
t <sub>18</sub>	0, 1	Chip select transition isolated side, slave data output disabled



Maximum data rate for single direction communication, master to slave, is 8MHz, limited by the systems encoding/decoding scheme or propagation delay. Timing details for both variations of clock phase are shown in Figures 8 and 9 and Table 4.

Additional requirements to insure maximum data rate are:

•  $\overline{\text{CS}}$  is transmitted prior to (asynchronous) or within the same (synchronous) data packet as SDI

• SDI and SCK set-up data transition occur within the same data packet. Referencing Figure 6, SDI can precede SCK by up to 13ns  $(t_7 \rightarrow t_8)$  or lag SCK by 3ns  $(t_8 \rightarrow t_9)$  and not violate this requirement. Similarly in Figure 8, SDI can precede SCK by up to 13ns  $(t_4 \rightarrow t_5)$  or lag SCK by 3ns  $(t_5 \rightarrow t_6)$ .

## Inter-IC Communication (I<sup>2</sup>C) Bus

The LTM2883-I provides an I<sup>2</sup>C compatible isolated interface, Clock (SCL) is unidirectional, supporting master mode only, and data (SDA) is bidirectional. The maximum data

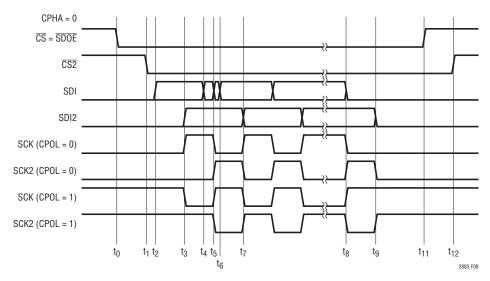


Figure 8. SPI Timing, Unidirectional, CPHA = 0

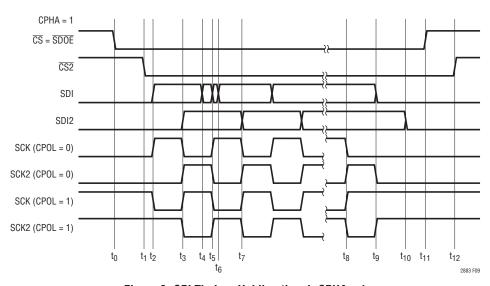


Figure 9. SPI Timing, Unidirectional, CPHA = 1

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Table 4. Unidirectional SPI Timing Event Description

TIME	СРНА	EVENT DESCRIPTION		
$\overline{t_0}$	0, 1	Asynchronous chip select, may be synchronous to SDI but may not lag by more than 3ns		
t <sub>0</sub> to t <sub>1</sub>	0, 1	Propagation delay chip select, logic to isolated side		
t <sub>2</sub>	0	Start of data transmission, data set-up		
	1	Start of transmission, data and clock set-up. Data transition must be within -13ns to 3ns of clock edge		
t <sub>2</sub> to t <sub>3</sub>	0	Propagation delay of data, logic side to isolated side		
	1	Propagation delay of data and clock, logic side to isolated side		
t <sub>3</sub>	0, 1	Logic side data sample time, half clock period delay from data set-up transition		
t <sub>3</sub> to t <sub>5</sub>	0, 1	Clock propagation delay, clock and data transition		
t <sub>4</sub> to t <sub>5</sub>	0, 1	Data to clock delay, must be ≤13ns		
t <sub>5</sub> to t <sub>6</sub>	0, 1	Clock to data delay, must be ≤3ns		
t <sub>5</sub> to t <sub>7</sub>	0, 1	Data and clock propagation delay		
t <sub>8</sub>	0	Last clock and data transition		
	1	Last clock transition		
t <sub>8</sub> to t <sub>9</sub>	0	Clock and data propagation delay		
	1	Clock propagation delay		
t <sub>9</sub> to t <sub>10</sub>	1	Data propagation delay		
t <sub>11</sub>	0, 1	Asynchronous chip select transition, end of transmission		
t <sub>12</sub>	0, 1	Chip select transition isolated side		

rate is 400kHz which supports fast-mode  $I^2C$ . Timing is detailed in Figure 10. The data rate is limited by the slave acknowledge setup time ( $t_{SU;ACK}$ ), consisting of the  $I^2C$  standard minimum setup time ( $t_{SU;DAT}$ ) of 100ns, maximum clock propagation delay of 225ns, glitch filter and isolated data delay of 350ns maximum, and the combined isolated and logic data fall time of 500ns at maximum bus loading. The total setup time reduces the  $I^2C$  data hold time ( $t_{HD;DAT}$ ) to a maximum of 125ns, guaranteeing sufficient data setup time ( $t_{SU;ACK}$ ).

The isolated side bidirectional serial data pin, SDA2, simplified schematic is shown in Figure 11. An internal

1.8mA current source provides a pull-up for SDA2. Do not connect any other pull-up device to SDA2. This current source is sufficient to satisfy the system requirements for bus capacitances greater than 200pF in FAST mode and greater than 400pF in STANDARD mode.

Additional proprietary circuitry monitors the slew rate on the SDA and SDA2 signals to manage directional control across the isolation barrier. Slew rates on both pins must be greater than 1V/µs for proper operation.

The logic side bidirectional serial data pin, SDA, requires a pull-up resistor or current source connected to  $V_{\rm I}$ . Follow

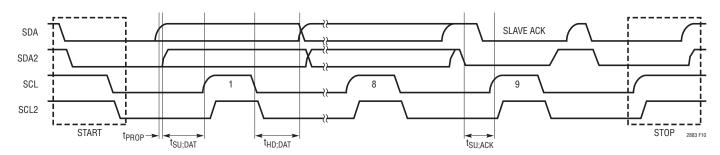


Figure 10. I<sup>2</sup>C Timing Diagram





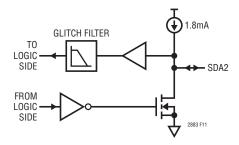


Figure 11. Isolated SDA2 Pin Schematic

the requirements in Figures 12 and 13 for the appropriate pull-up resistor on SDA that satisfies the desired rise time specifications and  $V_{OL}$  maximum limits for FAST and STANDARD modes. The resistance curves represent the maximum resistance boundary; any value may be used to the left of the appropriate curve.

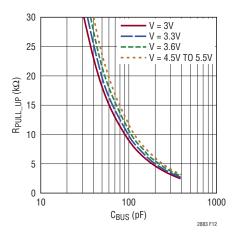


Figure 12. Maximum Standard Speed Pull-Up Resistance on SDA

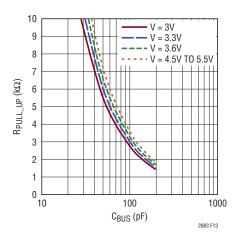


Figure 13. Maximum Fast Speed Pull-Up Resistance on SDA

The isolated side clock pin, SCL2, has a weak push-pull output driver; do not connect an external pull-up device. SCL2 is compatible with I $^2$ C devices without clock stretching. On lightly loaded connections, a 100pF capacitor from SCL2 to GND2 or RC low-pass filter (R =  $500\Omega$  C = 100pF) can be used to increase the rise and fall times and minimize noise.

Some consideration must be given to signal coupling between SCL2 and SDA2. Separate these signals on a printed circuit board or route with ground between. If these signals are wired off board, twist SCL2 with  $V_{CC2}$  and/or GND2 and SDA2 with GND2 and/or  $V_{CC2}$ , do not twist SCL2 and SDA2 together. If coupling between SCL2 and SDA2 is unavoidable, place the aforementioned RC filter at the SCL2 pin to reduce noise injection onto SDA2.

#### **RF**, Magnetic Field Immunity

The isolator µModule technology used within the LTM2883 has been independently evaluated, and successfully passed the RF and magnetic field immunity testing requirements per European Standard EN 55024, in accordance with the following test standards:

EN 61000-4-3	Radiated, Radio-Frequency, Electromagnetic Field Immunity
EN 61000-4-8	Power Frequency Magnetic Field Immunity
EN 61000-4-9	Pulsed Magnetic Field Immunity

Tests were performed using an unshielded test card designed per the data sheet PCB layout recommendations. Specific limits per test are detailed in Table 5.

Table 5.

143.5 6.						
TEST	FREQUENCY	FIELD STRENGTH				
EN 61000-4-3 Annex D	80MHz to 1GHz	10V/m				
	1.4MHz to 2GHz	3V/m				
	2GHz to 2.7GHz	1V/m				
EN 61000-4-8 Level 4	50Hz and 60Hz	30A/m				
EN 61000-4-8 Level 5	60Hz	100A/m*				
EN 61000-4-9 Level 5	Pulse	1000A/m				

<sup>\*</sup>non IEC method



#### **PCB** Layout

The high integration of the LTM2883 makes PCB layout very simple. However, to optimize its electrical isolation characteristics, EMI, and thermal performance, some layout considerations are necessary.

- Under heavily loaded conditions V<sub>CC</sub> and GND current can exceed 300mA. Sufficient copper must be used on the PCB to insure resistive losses do not cause the supply voltage to drop below the minimum allowed level. Similarly, the V<sub>CC2</sub> and GND2 conductors must be sized to support any external load current. These heavy copper traces will also help to reduce thermal stress and improve the thermal conductivity.
- Input and output decoupling is not required, since these components are integrated within the package. An additional bulk capacitor with a value of 6.8µF to 22µF is recommended. The high ESR of this capacitor reduces board resonances and minimizes voltage spikes caused by hot plugging of the supply voltage. For EMI sensitive applications, an additional low ESL ceramic capacitor of 1µF to 4.7µF, placed as close to the power and ground terminals as possible, is recommended. Alternatively, a number of smaller value parallel capacitors may be used to reduce ESL and achieve the same net capacitance.
- Do not place copper on the PCB between the inner columns of pads. This area must remain open to withstand the rated isolation voltage.
- The use of solid ground planes for GND and GND2 is recommended for non-EMI critical applications to optimize signal fidelity, thermal performance, and to minimize RF emissions due to uncoupled PCB trace conduction. The drawback of using ground planes, where EMI is of concern, is the creation of a dipole antenna structure which can radiate differential voltages formed between GND and GND2. If ground planes are used it is recommended to minimize their area, and use contiguous planes as any openings or splits can exacerbate RF emissions.
- For large ground planes a small capacitance (≤330pF) from GND to GND2, either discrete or embedded within the substrate, provides a low impedance current return path for the module parasitic capacitance, minimizing

any high frequency differential voltages and substantially reducing radiated emissions. Discrete capacitance will not be as effective due to parasitic ESL. In addition, voltage rating, leakage, and clearance must be considered for component selection. Embedding the capacitance within the PCB substrate provides a near ideal capacitor and eliminates component selection issues; however, the PCB must be 4 layers. Care must be exercised in applying either technique to insure the voltage rating of the barrier is not compromised.

The PCB layout in Figures 14a and 14b shows the low EMI demo board for the LTM2883. The demo board uses a combination of EMI mitigation techniques, including both embedded PCB bridge capacitance and discrete GND to GND2 capacitors. Two safety rated type Y2 capacitors are used in series, manufactured by MuRata, part number GA342QR7GF471KW01L. The embedded capacitor effectively suppresses emissions above 400MHz, whereas the discrete capacitors are more effective below 400MHz.

EMI performance is shown in Figure 15, measured using a Gigahertz Transverse Electromagnetic (GTEM) cell and method detailed in IEC 61000-4-20, Testing and Measurement Techniques – Emission and Immunity Testing in Transverse Electromagnetic Waveguides.

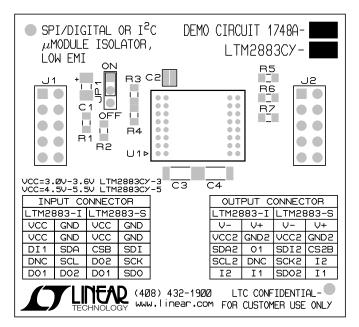
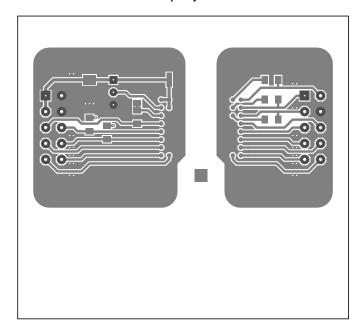


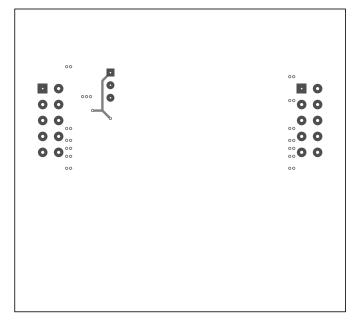
Figure 14a. LTM2883 Low EMI Demo Board Layout



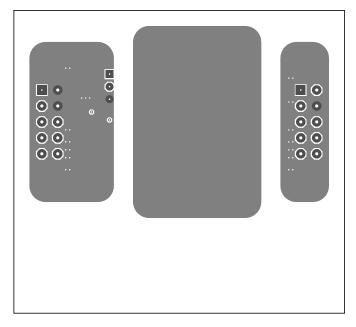
**Top Layer** 



Inner Layer 2



Inner Layer 1



**Bottom Layer** 

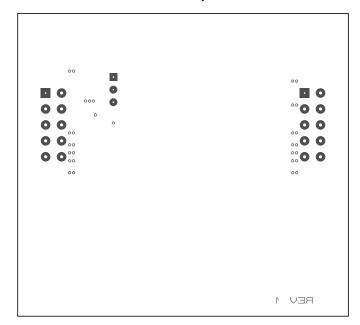


Figure 14b. LTM2883 Low EMI Demo Board Layout (DC1748A)

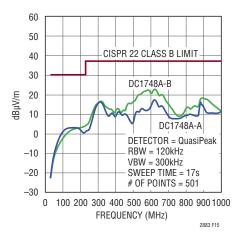


Figure 15. LTM2883 Low EMI Demo Board Emissions

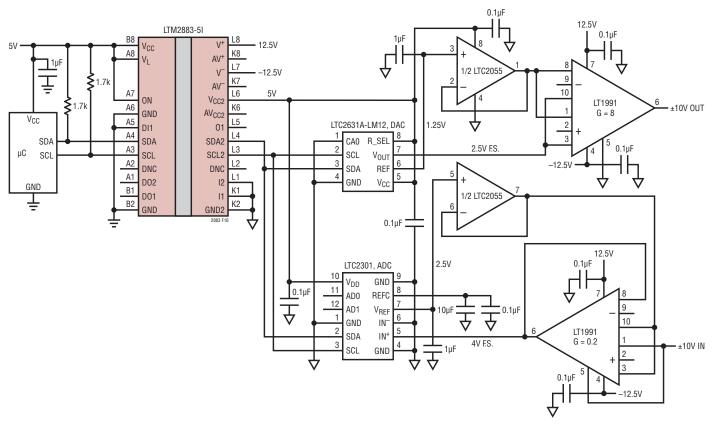


Figure 16. Isolated I<sup>2</sup>C 12-Bit, ±10V Analog Input and Output

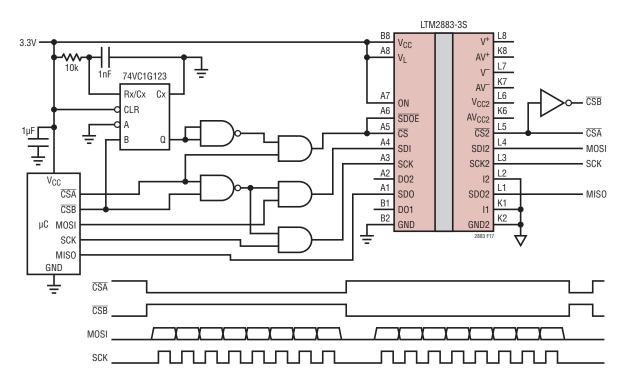


Figure 17. Isolated SPI Device Expansion

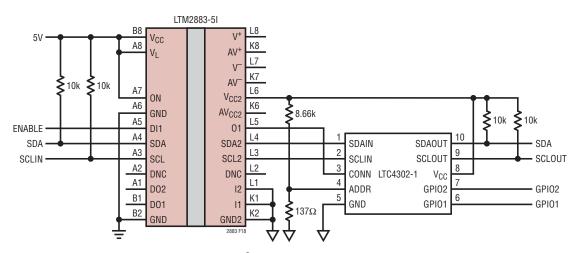


Figure 18. Isolated I<sup>2</sup>C Buffer with Programmable Outputs

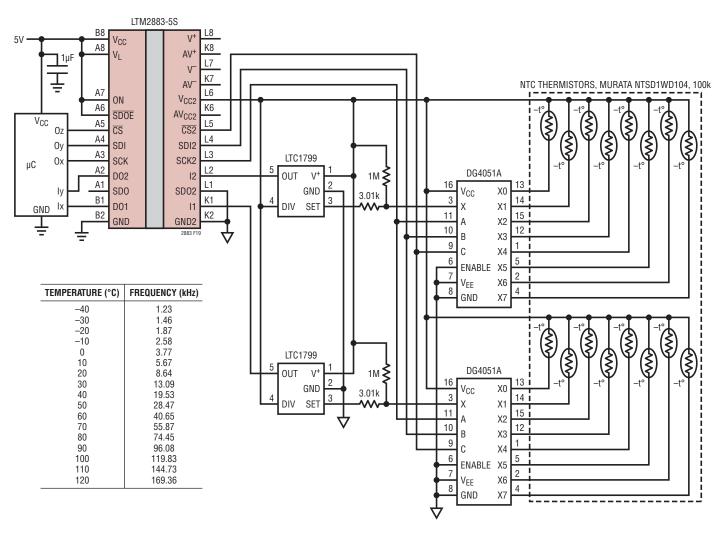


Figure 19. 16-Channel Isolated Temperature to Frequency Converter

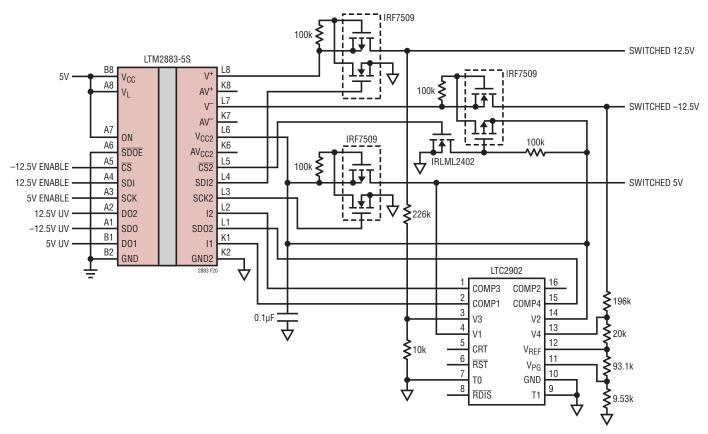


Figure 20. Digitally Switched Triple Power Supply with Undervoltage Monitor

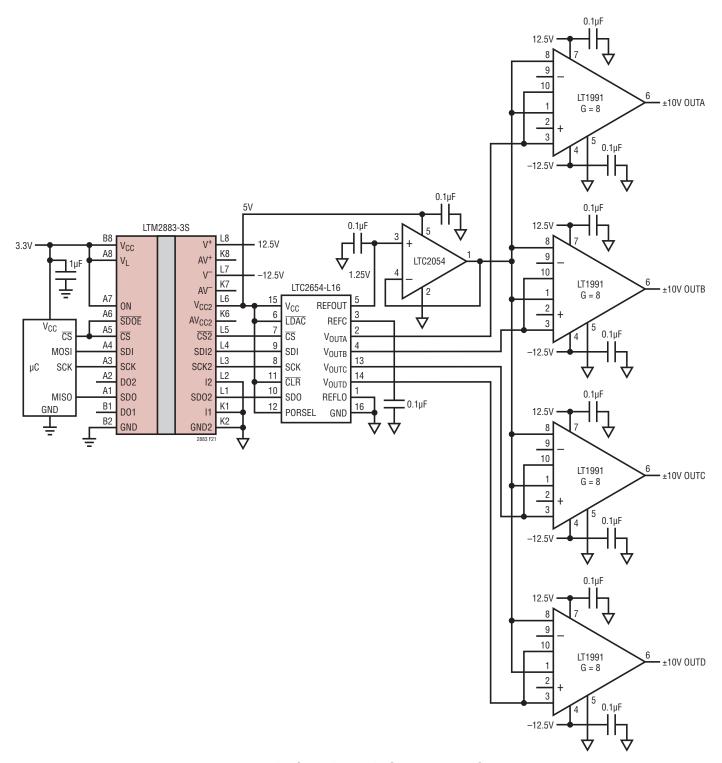


Figure 21. Quad 16-Bit ±10V Output Range DAC

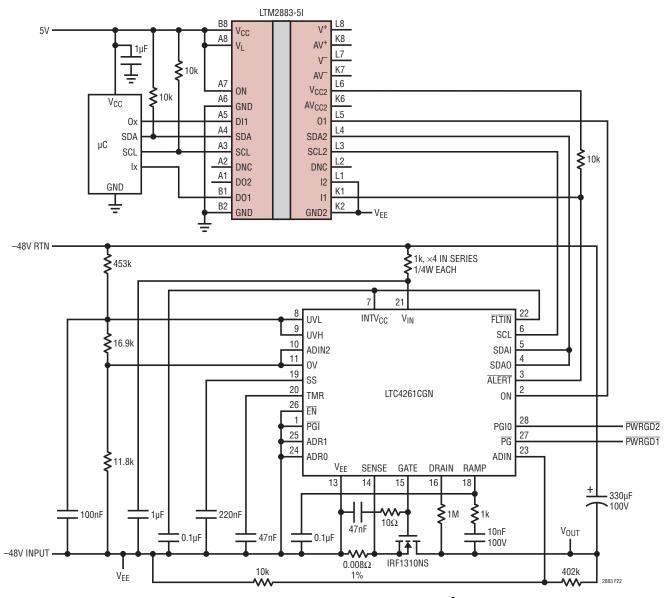


Figure 22. -48V, 200W Hot Swap Controller with Isolated I<sup>2</sup>C Interface



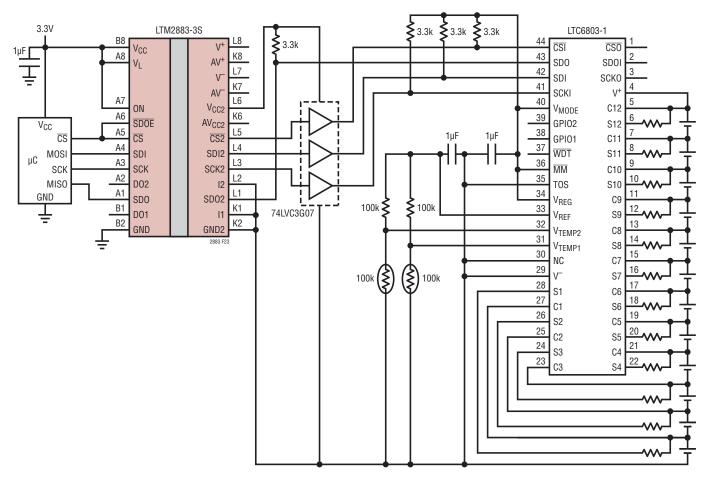


Figure 23. 12-Cell Battery Stack Monitor with Isolated SPI Interface and Low Power Shutdown

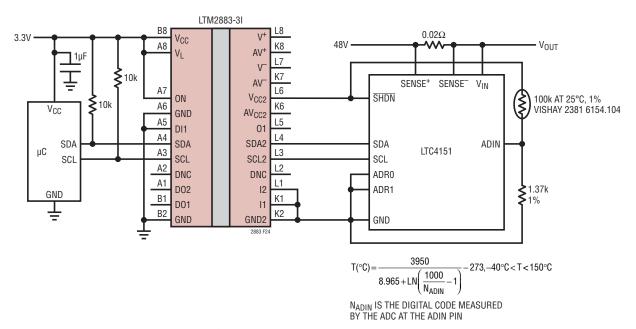


Figure 24. Isolated I<sup>2</sup>C Voltage, Current and Temperature Power Supply Monitor

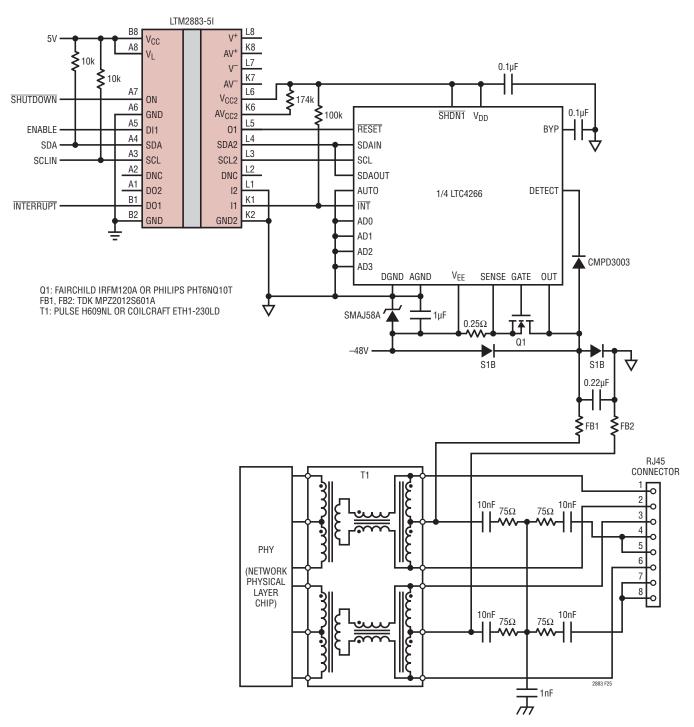
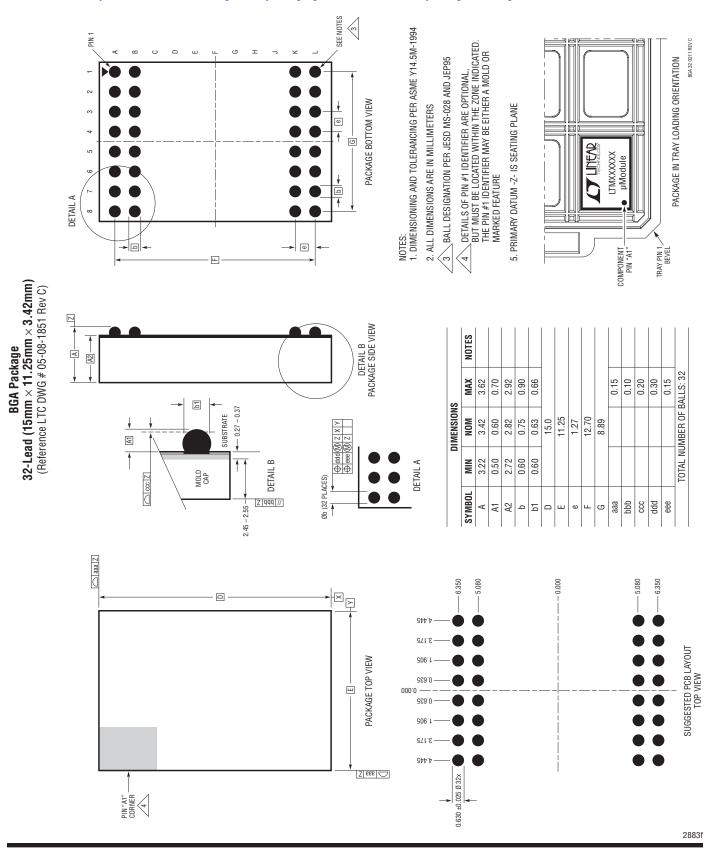


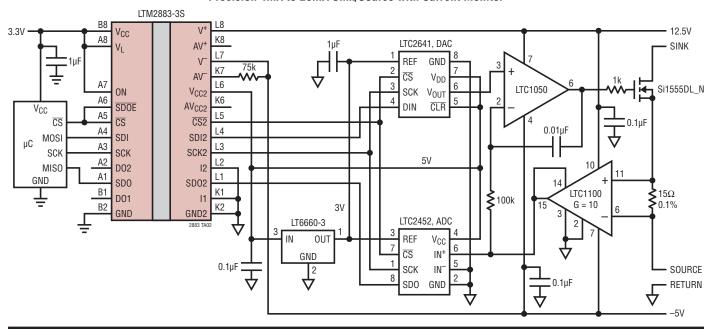
Figure 25. One Complete Isolated Powered Ethernet Port

### PACKAGE DESCRIPTION

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.



#### Precision 4mA to 20mA Sink/Source with Current Monitor



# **RELATED PARTS**

PART NUMBER	DESCRIPTION	COMMENTS	
LTM2881	Isolated RS485/RS422 µModule Transceiver Plus Power	20Mbps 2500V <sub>RMS</sub> Isolation with Power in LGA/BGA Package	
LTM2882	Dual Isolated RS232 µModule Transceiver Plus Power	20Mbps 2500V <sub>RMS</sub> Isolation with Power in LGA/BGA Package	
LTC4310	Hot-Swappable I <sup>2</sup> C Isolators	Bidirectional I <sup>2</sup> C Communication, Low Voltage Level Shifting	
LTC6803	Multistack Battery Monitor	Individual Battery Cell Monitoring of High Voltage Battery Stacks, Multiple Devices Interconnected via SPI	
LTC2309/LTC2305/ LTC2301	12-Bit, 8-/2-/1-Channel, 14ksps SAR ADCs with I <sup>2</sup> C	5V, Internal Reference, Software Compatible Family	
LTC2631/LTC2630	Single 12-/10-/8-Bit I <sup>2</sup> C or SPI V <sub>OUT</sub> DACs with 10ppm/°C Reference	180µA per DAC, 2.7V to 5.5V Supply Range, 10ppm/°C Reference, Rail-to-Rail Output	
LTC2641/LTC2642	16-/14-/12-Bit V <sub>OUT</sub> DACs	±1LSB INL/DNL, 0.5nV • s Glitch, 1µs Settling, 3mm × 3mm DFN	
LTC2452/LTC2453	Ultra-Tiny 16-Bit Differential $\pm 5.5$ V $\Delta\Sigma$ ADCs, SPI/I $^2$ C	2LSB INL, 50nA Sleep Current, Tiny 3mm × 2mm DFN-8 or TSOT Packages	
LTC1859/LTC1858/ LTC1857	8-Channel 16-/14-/12-Bit, 100ksps, ±10V SoftSpan™ SAR ADCs with SPI	5V Supply, Up to ±10V Configurable Unipolar/Bipolar Input Range, Pin Compatible Family in SSOP-28 package	
LTC2487/LTC2486	16-Bit 2- or 4-Channel ΔΣ ADCs with Easy Drive™ Inputs and I <sup>2</sup> C/SPI Interface	16-Bit and 24-Bit $\Delta\Sigma$ ADC Family, Up to 16 Input Channels and Integrated Temperature Sensor	
LTC4303/LTC4304	Hot Swappable I <sup>2</sup> C Bus Buffers	2.7V to 5.5V Supply, Rise Time Acceleration, Stuck Bus Protection, ±15kV ESD	
LTC1100	Zero-Drift Instrumentation Amplifier	Fixed Gain of 10 or 100	
LT1991	Precision, Pin Configurable Gain Difference Amplifier	Gain Range –13 to +14	
LTC2054/LTC2055	Micropower Zero-Drift Op Amps	3V/5V/±5V Supply	
LTC4151	High Voltage I <sup>2</sup> C Current and Voltage Monitor	Wide Operating Range: 7V to 80V	
LTC4261	Negative Voltage Hot Swap™ Controller with ADC and I <sup>2</sup> C Monitoring	Floating Topology Allows Very High Voltage Operation	
LTC1799	Wide Frequency Range Silicon Oscillator	1kHz to 30MHz	
LTC6990	TimerBlox™ Voltage Controlled Oscillator	488Hz to 2MHz	