



# ±10V, Dual, 12-Bit, Serial, Voltage-Output DAC

MAX5322

## General Description

The MAX5322 dual, 12-bit, serial-interface, digital-to-analog converter (DAC) provides bipolar  $\pm 5V$  to  $\pm 10V$  outputs from  $\pm 12V$  to  $\pm 15V$  analog power-supply voltages, or unipolar 5V to 10V outputs from a single 12V to 15V analog power-supply voltage.

The MAX5322 features excellent linearity with both integral nonlinearity (INL) and differential nonlinearity (DNL) guaranteed to  $\pm 1$  LSB (max). The device also features a fast 10 $\mu s$  to 0.5 LSB settling time, and a hardware-shutdown feature that reduces current consumption to 2.8 $\mu A$ . The output goes to midscale at power-up in bipolar mode (0V), and to zero scale at power-up in unipolar mode (0V). A clear input (CLR) asynchronously clears the DAC register and sets the outputs to 0V. The outputs can be asynchronously updated with the load DAC (LDAC) input.

The device features a fast 10MHz SPI™-/QSPI™-/MICROWIRE™-compatible serial interface that operates with 3V or 5V logic. Additional features include a serial-data output (DOUT) for daisy chaining and read-back functions. The MAX5322 requires external reference voltages of 2V to 5.25V and is available in a 28-pin SSOP package that operates over the extended (-40°C to +85°C) temperature range.

## Applications

Motor Control	Automatic Test Equipment (ATE)
Industrial Process Controls	Analog I/O Boards
Industrial Automation	Data-Acquisition Systems

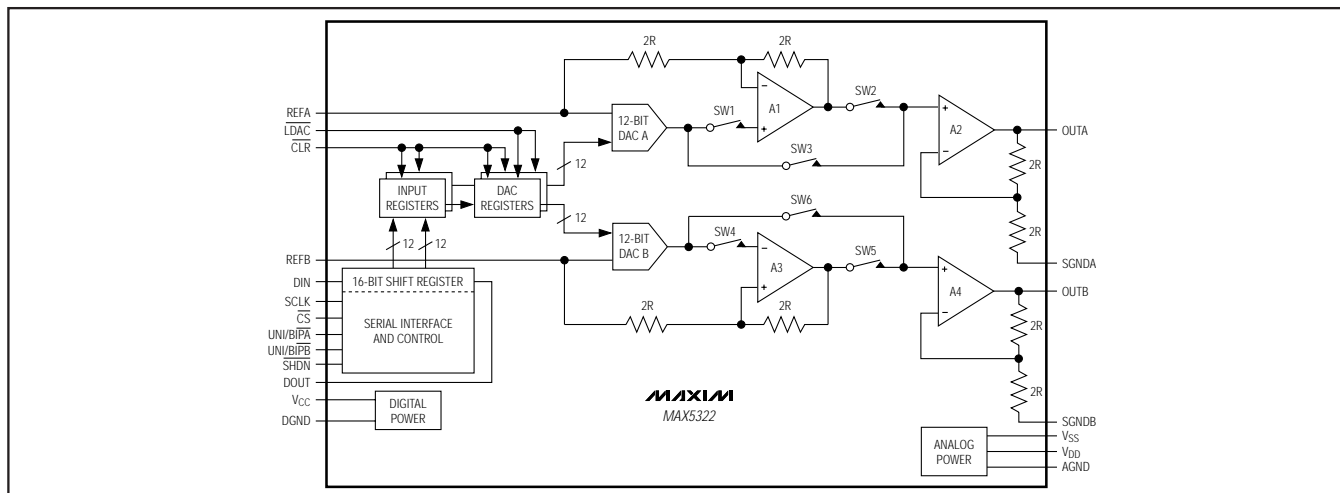
## Features

- ◆ **Unipolar or Bipolar Output-Voltage Ranges**
  - Unipolar: 0 to +2 x VREF (Single or Dual Supply)
  - Bipolar: -2 x VREF to +2 x VREF (Dual Supply)
- ◆ **Guaranteed INL  $\leq \pm 1$  LSB (max)**
- ◆ **Guaranteed Monotonic: DNL  $\leq \pm 1$  LSB (max)**
- ◆ **10 $\mu s$  Settling Time to 0.5 LSB**
- ◆ **Low 2.8 $\mu A$  Shutdown Current**
- ◆ **Fast 10MHz SPI-/QSPI-/MICROWIRE-Compatible Serial Interface**
- ◆ **Power-On Reset Sets DAC Output to 0V**
- ◆ **Schmitt Trigger Inputs for Direct Optocoupler Interface**
- ◆ **Serial-Data Output Allows Daisy-Chaining of Devices**
- ◆ **28-Pin SSOP (8mm x 10mm)**

## Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX5322EAI	-40°C to +85°C	28 SSOP

## Functional Diagram



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MICROWIRE is a trademark of National Semiconductor Corp.



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## ABSOLUTE MAXIMUM RATINGS

V <sub>DD</sub> to AGND.....	-0.3V to +17V	REF_ to AGND.....	-0.3V to +6V
V <sub>SS</sub> to AGND.....	-17V to +0.3V	Maximum Current into REF_.....	±10mA
V <sub>DD</sub> to V <sub>SS</sub> .....	+34V	Maximum Current into Any Pin Excluding REF_.....	±50mA
V <sub>CC</sub> to DGND.....	-0.3V to +6V	Continuous Power Dissipation (T <sub>A</sub> = +70°C)	
AGND to DGND.....	-0.3V to +0.3V	28-Pin SSOP (derate 9.5mW/°C above +70°C).....	761.9mW
SGND_ to AGND.....	-0.3V to +0.3V	Operating Temperature Range.....	-40°C to +85°C
SCLK, DIN, CS, SHDN, UNI/BIP_, CLR, LDAC, DOUT to DGND.....	-0.3V to (V <sub>CC</sub> + 0.3V)	Junction Temperature.....	+150°C
OUT_ to AGND.....	(V <sub>SS</sub> - 0.3V) to (V <sub>DD</sub> + 0.3V)	Storage Temperature Range.....	-65°C to +150°C
		Lead Temperature (soldering, 10s).....	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS (DUAL SUPPLY)

(V<sub>DD</sub> = +15V ±5%, V<sub>SS</sub> = -15V ±5%, V<sub>CC</sub> = +5V ±10%, AGND = DGND = SGND\_ = 0V, V<sub>REF\_</sub> = 5V, R<sub>LOAD</sub> = 2kΩ, C<sub>LOAD</sub> = 250pF, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>STATIC ACCURACY</b>						
Resolution	N		12			Bits
Integral Nonlinearity	INL				±1	LSB
Differential Nonlinearity	DNL	Guaranteed monotonic			±1	LSB
Zero-Scale Error		Bipolar, code = 800hex			±2	LSB
		Unipolar, code = 000hex			±2	
Zero-Scale Temperature Coefficient		Bipolar		0.9		ppm FSR/°C
		Unipolar		0.09		
Gain Error		Bipolar (output unloaded)			±2	LSB
		Unipolar (output unloaded)			±2	
Gain-Error Temperature Coefficient		Bipolar (output unloaded)		2		ppm FSR/°C
		Unipolar (output unloaded)		2		
<b>ANALOG OUTPUTS (OUTA, OUTB)</b>						
Output Voltage Range		(V <sub>SS</sub> + 1.5V) < V <sub>OUT</sub> < (V <sub>DD</sub> - 1.5V)	-2 x V <sub>REF</sub>		+2 x V <sub>REF</sub>	V
Resistive Load to GND	R <sub>LOAD</sub>		2			kΩ
Capacitive Load to GND	C <sub>LOAD</sub>				250	pF
DC Output Resistance				0.5		Ω
<b>SGND INPUTS (SGNDA, SGND B)</b>						
Input Impedance				92		kΩ
<b>REFERENCE INPUTS (REFA, REFB)</b>						
Reference Voltage Input Range			2.00		5.25	V
Input Resistance	R <sub>REF</sub>	Code = 555hex, worst-case code	15	22		kΩ
Reference Bandwidth		V <sub>REF</sub> = 200mV <sub>p-p</sub> + 5V <sub>DC</sub>		200		kHz

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## ELECTRICAL CHARACTERISTICS (DUAL SUPPLY) (continued)

( $V_{DD} = +15V \pm 5\%$ ,  $V_{SS} = -15V \pm 5\%$ ,  $V_{CC} = +5V \pm 10\%$ ,  $AGND = DGND = SGND_ = 0V$ ,  $V_{REF_} = 5V$ ,  $R_{LOAD} = 2k\Omega$ ,  $C_{LOAD} = 250pF$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>DIGITAL INPUTS (SCLK, DIN, CS, SHDN, UNI/BIPA, UNI/BIPB, CLR, LDAC)</b>						
Input Voltage High	$V_{IH}$	$+2.7V \leq V_{CC} \leq +3.6V$	0.7 x $V_{CC}$			V
		$+4.5V \leq V_{CC} \leq +5.5V$	2.4			
Input Voltage Low	$V_{IL}$	$+2.7V \leq V_{CC} \leq +3.6V$			0.8	V
		$+4.5V \leq V_{CC} \leq +5.5V$			0.8	
Input Capacitance	C	$+2.7V \leq V_{CC} \leq +3.6V$		10		pF
		$+4.5V \leq V_{CC} \leq +5.5V$		10		
Input Current (Note 1)		$0 \leq$ all digital inputs $\leq V_{CC}$ , $+2.7V \leq V_{CC} \leq +3.6V$			$\pm 1$	$\mu A$
		$0 \leq$ all digital inputs $\leq V_{CC}$ , $+4.5V \leq V_{CC} \leq +5.5V$			$\pm 1$	
<b>DIGITAL OUTPUT (DOUT)</b>						
Output Voltage High	$V_{OH}$	$I_{SOURCE} = 2mA$	$V_{CC} - 0.5$			V
Output Voltage Low	$V_{OL}$	$I_{SINK} = 2mA$			0.4	V
Tri-State Leakage Current				0.1		$\mu A$
Tri-State Capacitance				10		pF
<b>DYNAMIC PERFORMANCE</b>						
Voltage Output Slew Rate				2.5		V/ $\mu s$
Output Settling Time		To $\pm 0.5$ LSB of full scale, code 000 to code FFF		10		$\mu s$
Digital Feedthrough		$\overline{CS} =$ high, $f_{SCLK} = 10MHz$ , $V_{OUT} = 0V$		10		nV-s
DAC-to-DAC Crosstalk				2.5		nV-s
Output-Noise Spectral Density at 10kHz				130		nV/ $\sqrt{Hz}$
<b>POWER SUPPLIES</b>						
Positive Analog-Supply Voltage	$V_{DD}$		10.80		15.75	V
Negative Analog-Supply Voltage	$V_{SS}$		-10.80		-15.75	V
Positive Digital-Supply Voltage	$V_{CC}$		2.7		5.5	V
Positive Analog-Supply Current	$I_{DD}$	Output unloaded, $V_{OUT} = 0$		2.8	8	mA
Negative Analog-Supply Current	$I_{SS}$	Output unloaded, $V_{OUT} = 0$		-1.5	-8	mA
Digital-Supply Current	$I_{CC}$	All digital inputs = 0 or $V_{CC}$			200	$\mu A$
Power-Supply Rejection Ratio (Note 2)	PSRR	Positive analog supply		0.0006		LSB/V
		Negative analog supply		0.03		
Shutdown Current		Positive analog supply		2.8	50	$\mu A$
		Negative analog supply		4	50	
		Digital supply		4	10	

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## ELECTRICAL CHARACTERISTICS (SINGLE SUPPLY)

( $V_{DD} = +15V \pm 5\%$ ,  $V_{SS} = 0V$ ,  $V_{CC} = +5V \pm 10\%$ ,  $AGND = DGND = SGND_{-} = 0V$ ,  $V_{REF-} = 5V$ ,  $R_{LOAD} = 10k\Omega$ ,  $C_{LOAD} = 250pF$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>STATIC ACCURACY</b>						
Resolution	N		12			Bits
Integral Nonlinearity	INL	(Note 3)			±1	LSB
Differential Nonlinearity	DNL	Guaranteed monotonic			±1	LSB
Unipolar Zero-Scale Error					±2	LSB
Unipolar Zero-Scale Temperature Coefficient				0.09		ppm FSR/°C
Gain Error		No load			±2	LSB
Gain-Error Temperature Coefficient		No load		2		ppm FSR/°C
<b>ANALOG OUTPUTS (OUTA, OUTB)</b>						
Output Voltage Range			0		+2 x $V_{REF}$	V
Resistive Load to GND	$R_{LOAD}$		10			k $\Omega$
Capacitive Load to GND	$C_{LOAD}$				250	pF
DC Output Resistance				0.5		$\Omega$
<b>SGND INPUTS (SGNDA, SGND B)</b>						
Input Impedance				92		k $\Omega$
<b>REFERENCE INPUTS (REFA, REFB)</b>						
Reference Voltage Input Range			2.00		5.25	V
Input Resistance		Code = 555hex, worst-case code	15	22		k $\Omega$
Reference Input Bandwidth		$V_{REF} = 200mV_{P-P} + 5V_{DC}$		150		kHz
<b>DIGITAL INPUTS (SCLK, DIN, CS, SHDN, UNI/B1PA, UNI/B1PB, CLR, LDAC)</b>						
Input Voltage High	$V_{IH}$	$+2.7V \leq V_{CC} \leq +3.6V$	0.7 x $V_{CC}$			V
		$+4.5V \leq V_{CC} \leq +5.5V$	2.4			
Input Voltage Low	$V_{IL}$	$+2.7V \leq V_{CC} \leq +3.6V$			0.8	V
		$+4.5V \leq V_{CC} \leq +5.5V$			0.8	
Input Capacitance	$C_{IN}$	$+2.7V \leq V_{CC} \leq +3.6V$		10		pF
		$+4.5V \leq V_{CC} \leq +5.5V$		10		
Input Current	$I_{IN}$	$0 \leq V_{IN} \leq V_{CC}$ , $+2.7V \leq V_{CC} \leq +3.6V$			±1	$\mu A$
		$0 \leq V_{IN} \leq V_{CC}$ , $+4.5V \leq V_{CC} \leq +5.5V$			±1	
<b>DIGITAL OUTPUT (DOUT)</b>						
Output Voltage High	$V_{OH}$	$I_{SOURCE} = 2mA$	$V_{CC} - 0.5$			V
Output Voltage Low	$V_{OL}$	$I_{SINK} = 2mA$			0.4	V
Tri-State Leakage Current				0.1		$\mu A$

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## ELECTRICAL CHARACTERISTICS (SINGLE SUPPLY) (continued)

( $V_{DD} = +15V \pm 5\%$ ,  $V_{SS} = 0V$ ,  $V_{CC} = +5V \pm 10\%$ ,  $AGND = DGND = SGND_ = 0V$ ,  $V_{REF_} = 5V$ ,  $R_{LOAD} = 10k\Omega$ ,  $C_{LOAD} = 250pF$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Tri-State Capacitance				10		pF
<b>DYNAMIC PERFORMANCE</b>						
Voltage Output Slew Rate				2.5		V/ $\mu$ s
Output Settling Time		To $\pm 0.5$ LSB of full scale		10		$\mu$ s
Digital Feedthrough		$\overline{CS} = \text{high}$ , $f_{SCLK} = 10\text{MHz}$ , $V_{OUT} = 0V$		10		nV-s
DAC-to-DAC Crosstalk				2.5		nV-s
Output-Noise Spectral Density at 10kHz				130		nV/ $\sqrt{\text{Hz}}$
<b>POWER SUPPLIES</b>						
Positive Analog Supply Voltage	$V_{DD}$		10.80		15.75	V
Negative Analog Supply Voltage	$V_{SS}$			0		V
Positive Digital Supply Voltage	$V_{CC}$		2.7		5.5	V
Positive Analog Supply Current	$I_{DD}$	Output unloaded, $V_{OUT} = 0$		2.5	8	mA
Negative Analog Supply Current	$I_{SS}$	Output unloaded, $V_{OUT} = 0$		-0.5	-8	mA
Digital Supply Current	$I_{CC}$	All digital inputs = 0 or $V_{CC}$		9	200	$\mu$ A
Power-Supply Rejection Ratio	PSRR			0.001		LSB/V
Shutdown Current		Analog supply		2.8	5	$\mu$ A
		Digital supply		2.8	5	

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## TIMING CHARACTERISTICS

( $V_{DD} = +15V$ ,  $V_{SS} = -15V$  or  $0V$ ,  $V_{CC} = +2.7V$  to  $+5.5V$ ,  $AGND = DGND = SGND_{-} = 0$ ,  $V_{REF_{-}} = 5V$ ,  $R_{LOAD} = 2k\Omega$ ,  $C_{LOAD} = 250pF$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Frequency					10	MHz
SCLK Clock Period	$t_{CP}$		100			ns
SCLK Pulse-Width High	$t_{CH}$	For nondaisy-chain use	45			ns
SCLK Pulse-Width Low	$t_{CL}$	For nondaisy-chain use	45			ns
		For daisy-chain use		98		
$\overline{CS}$ Fall to SCLK Rise Setup Time	$t_{CSS}$		40			ns
SCLK Rise to $\overline{CS}$ Rise Hold Time	$t_{CSH}$	$+2.7V \leq V_{CC} \leq +3.6V$	15			ns
		$+4.5V \leq V_{CC} \leq +5.5V$	10			
DIN Setup Time	$t_{DS}$		20			ns
DIN Hold Time	$t_{DH}$		10			ns
$\overline{LDAC}$ Pulse Width	$t_{LD}$		50			ns
$\overline{CS}$ Rise to $\overline{LDAC}$ Low Setup Time	$t_{LDS}$	$+2.7V \leq V_{CC} \leq +3.6V$	100			ns
		$+4.5V \leq V_{CC} \leq +5.5V$	50			
SCLK Fall to DOUT Valid Propagation Delay	$t_{DO1}$	$C_{LOAD} = 20pF$ , $+2.7V \leq V_{CC} \leq +3.6V$			100	ns
		$C_{LOAD} = 20pF$ , $+4.5V \leq V_{CC} \leq +5.5V$			80	
SCLK Rise to $\overline{CS}$ Fall Delay	$t_{CS0}$		10			ns
$\overline{CS}$ Low to DOUT Valid Time	$t_{CSE}$	$C_{LOAD} = 20pF$			120	ns
$\overline{CS}$ High to DOUT Disabled Time	$t_{CSD}$				120	ns
$\overline{CS}$ Rise to SCLK Rise Hold Time	$t_{CS1}$		50			ns
$\overline{CS}$ Pulse-Width High	$t_{CSW}$	$+2.7V \leq V_{CC} \leq +3.6V$	200			ns
		$+4.5V \leq V_{CC} \leq +5.5V$	100			
$\overline{CLR}$ Pulse-Width Low	$t_{CLR}$		50			ns

**Note 1:** Output unloaded, digital inputs =  $V_{CC}$  or DGND.

**Note 2:**  $\Delta V_{DD} = 15.5V$  to  $14.5V$ ,  $\Delta V_{SS} = -15.5V$  to  $-14.5V$ , input code = 14hex to FFFhex

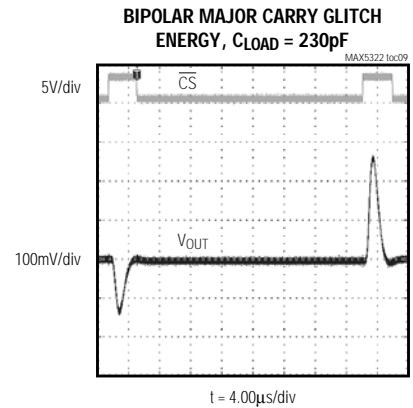
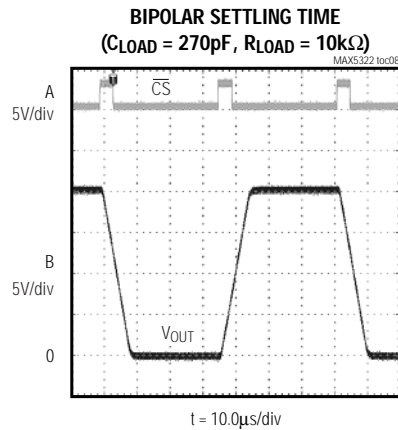
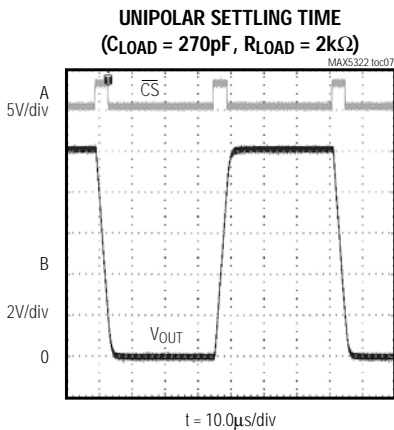
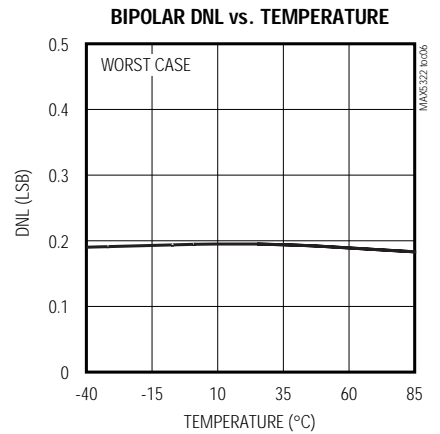
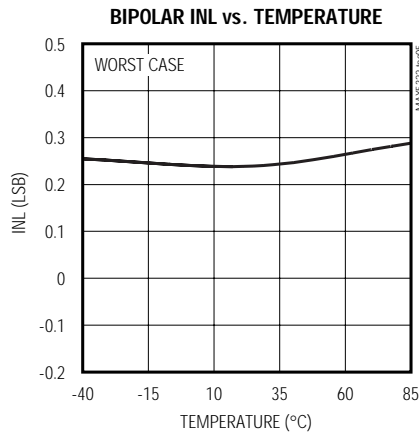
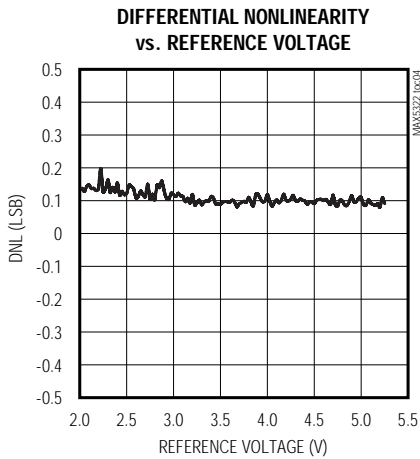
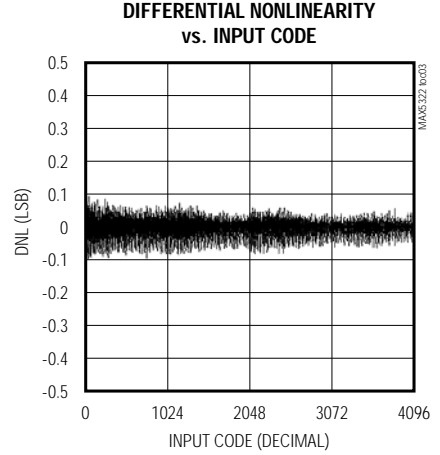
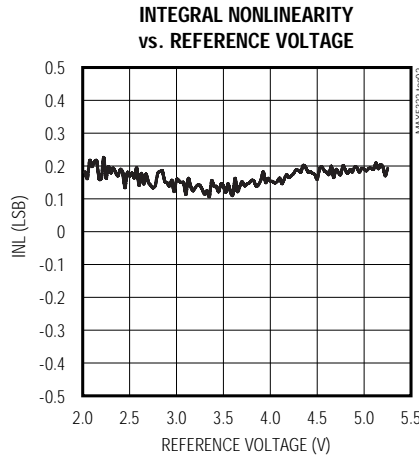
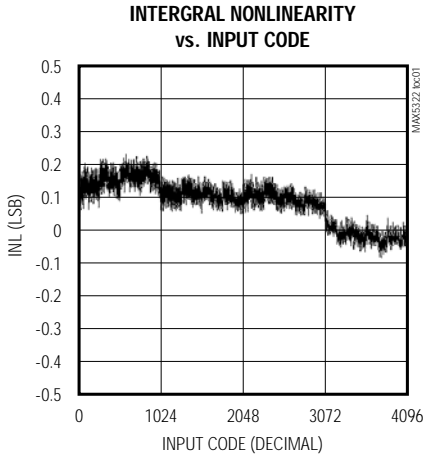
**Note 3:** Accuracy is guaranteed from code 14hex to FFFhex

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## Typical Operating Characteristics

( $V_{DD} = +15V$ ,  $V_{SS} = -15V$  for bipolar graphs,  $V_{SS} = 0$  for unipolar graphs,  $V_{CC} = +5V$ ,  $AGND = DGND = SGND_ = 0$ ,  $V_{REF_} = +5.0V$ , output unloaded,  $T_A = +25^\circ C$ , all graphs apply to both unipolar and bipolar, unless otherwise noted.)

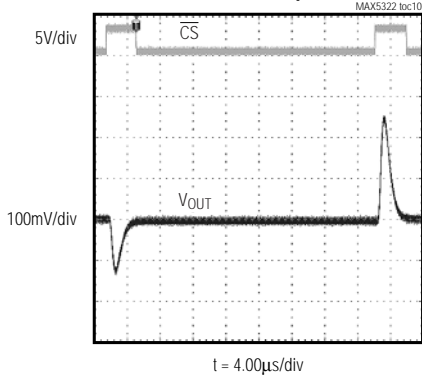


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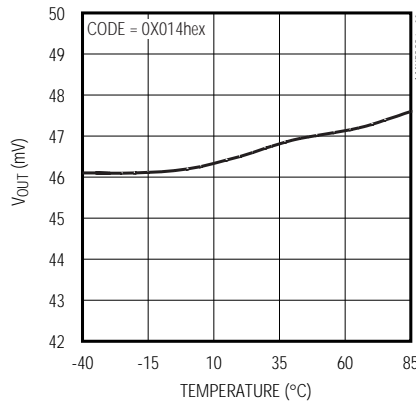
## Typical Operating Characteristics (continued)

( $V_{DD} = +15V$ ,  $V_{SS} = -15V$  for bipolar graphs,  $V_{SS} = 0$  for unipolar graphs,  $V_{CC} = +5V$ ,  $AGND = DGND = SGND_ = 0$ ,  $V_{REF_} = +5.0V$ , output unloaded,  $T_A = +25^\circ C$ , all graphs apply to both unipolar and bipolar, unless otherwise noted.)

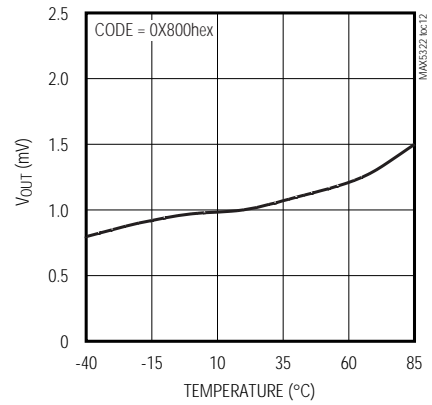
**BIPOLAR MAJOR CARRY GLITCH**  
LOAD = 10pF



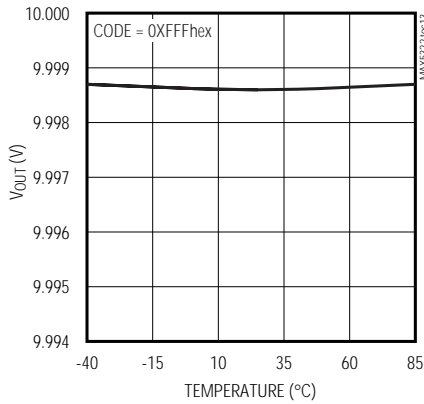
**UNIPOLAR ZERO-SCALE VOLTAGE vs. TEMPERATURE**



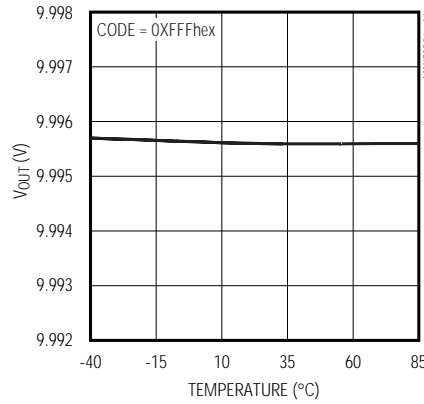
**BIPOLAR ZERO-SCALE VOLTAGE vs. TEMPERATURE**



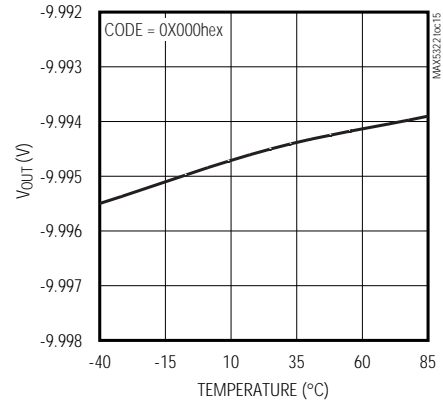
**UNIPOLAR FULL-SCALE VOLTAGE vs. TEMPERATURE**



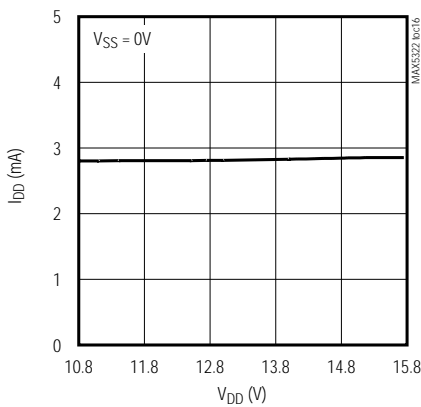
**POSITIVE BIPOLAR FULL-SCALE VOLTAGE vs. TEMPERATURE**



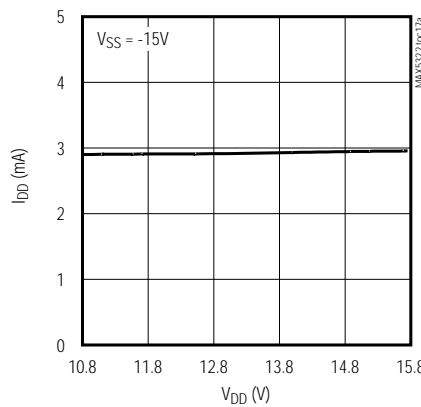
**NEGATIVE BIPOLAR FULL-SCALE VOLTAGE vs. TEMPERATURE**



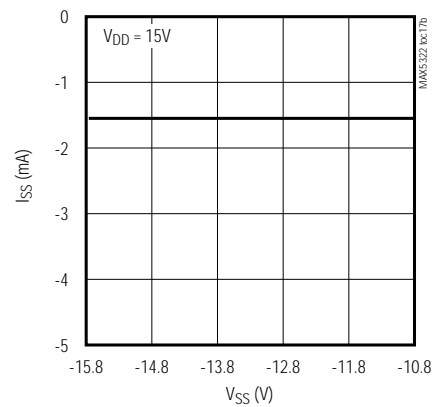
**UNIPOLAR SUPPLY CURRENT vs. SUPPLY VOLTAGE**



**BIPOLAR POSITIVE SUPPLY CURRENT vs. SUPPLY VOLTAGE**



**BIPOLAR NEGATIVE SUPPLY CURRENT vs. SUPPLY VOLTAGE**





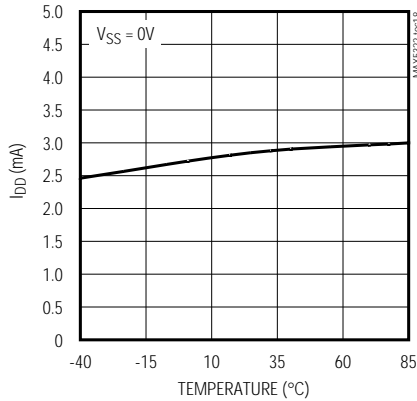
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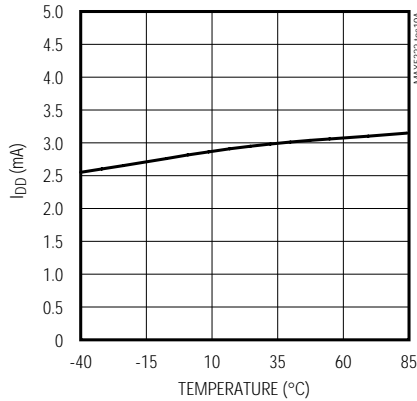
## Typical Operating Characteristics (continued)

( $V_{DD} = +15V$ ,  $V_{SS} = -15V$  for bipolar graphs,  $V_{SS} = 0$  for unipolar graphs,  $V_{CC} = +5V$ ,  $AGND = DGND = SGND_{-} = 0$ ,  $V_{REF_{-}} = +5.0V$ , output unloaded,  $T_A = +25^{\circ}C$ , all graphs apply to both unipolar and bipolar, unless otherwise noted.)

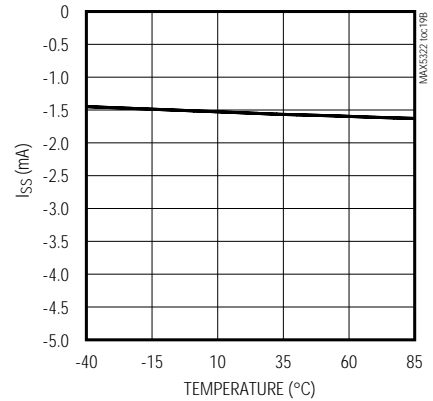
**UNIPOLAR SUPPLY CURRENT vs. TEMPERATURE**



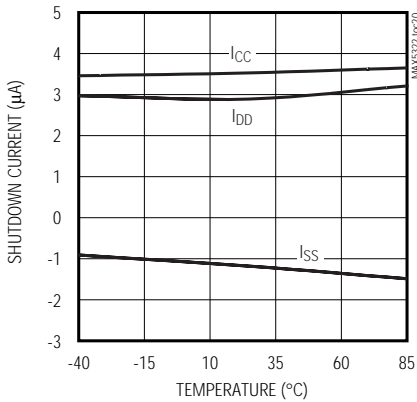
**BIPOLAR POSITIVE SUPPLY CURRENT vs. TEMPERATURE**



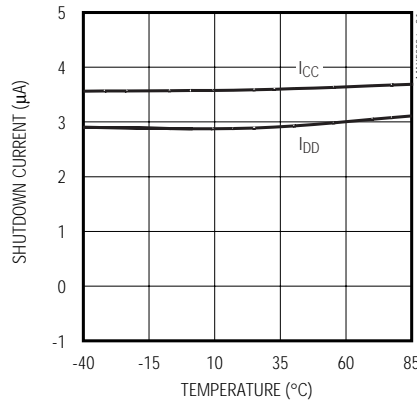
**BIPOLAR NEGATIVE SUPPLY CURRENT vs. TEMPERATURE**



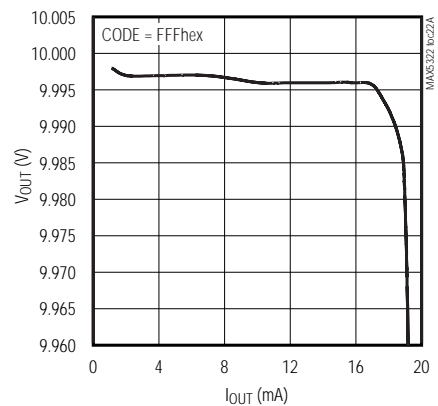
**BIPOLAR SHUTDOWN CURRENT vs. TEMPERATURE**



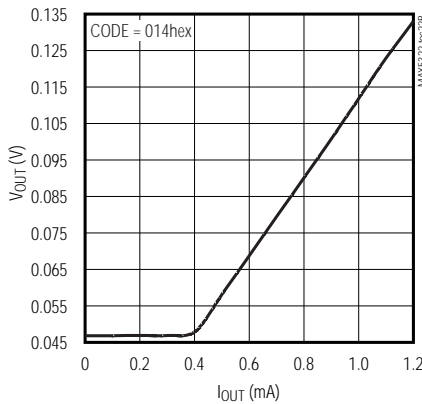
**UNIPOLAR SHUTDOWN CURRENT vs. TEMPERATURE**



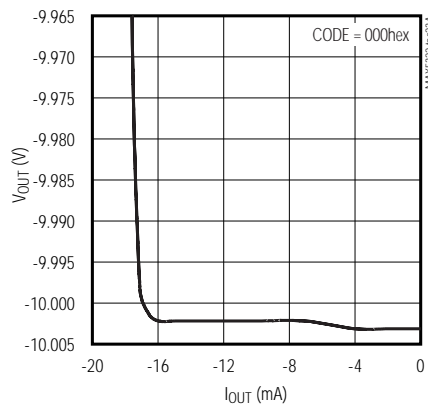
**UNIPOLAR OUTPUT VOLTAGE vs. OUTPUT CURRENT**



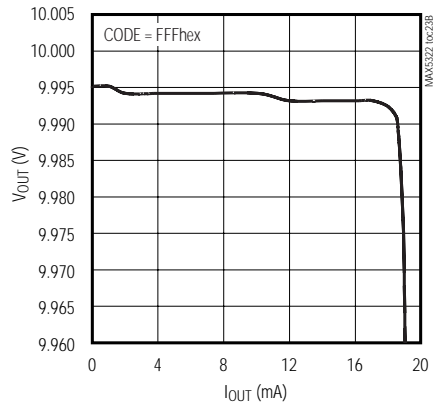
**UNIPOLAR OUTPUT VOLTAGE vs. OUTPUT CURRENT**



**BIPOLAR OUTPUT VOLTAGE vs. OUTPUT CURRENT**



**BIPOLAR OUTPUT VOLTAGE vs. OUTPUT CURRENT**

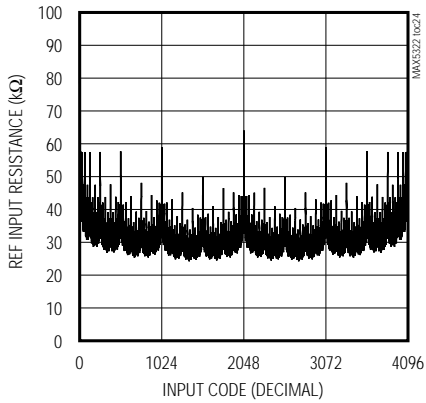


# ±10V, Dual, 12-Bit, Serial, Voltage-Output DAC

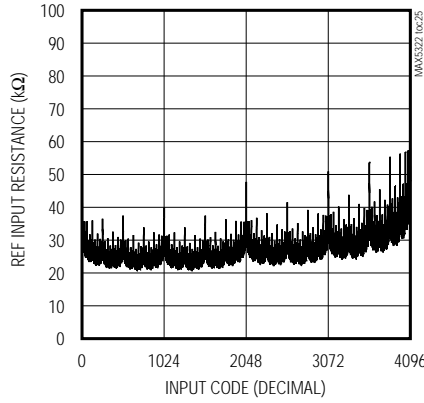
## Typical Operating Characteristics (continued)

( $V_{DD} = +15V$ ,  $V_{SS} = -15V$  for bipolar graphs,  $V_{SS} = 0$  for unipolar graphs,  $V_{CC} = +5V$ ,  $AGND = DGND = SGND_ = 0$ ,  $V_{REF_} = +5.0V$ , output unloaded,  $T_A = +25^\circ C$ , all graphs apply to both unipolar and bipolar, unless otherwise noted.)

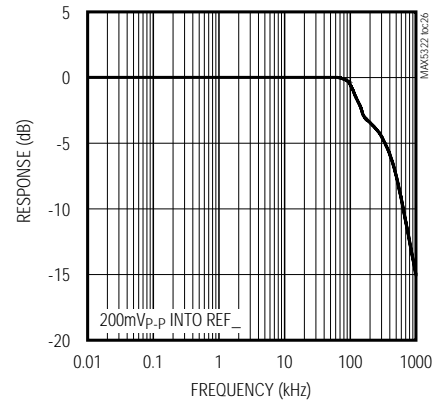
**UNIPOLAR REFERENCE INPUT RESISTANCE vs. INPUT CODE**



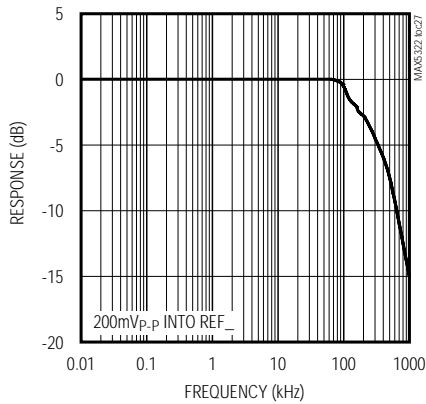
**BIPOLAR REFERENCE INPUT RESISTANCE vs. INPUT CODE**



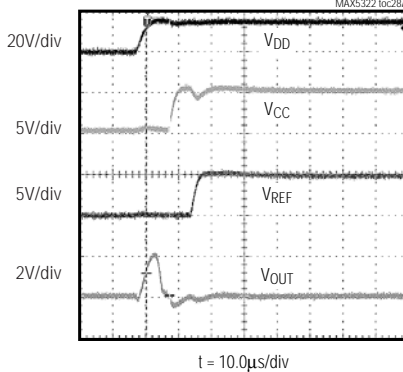
**UNIPOLAR REFERENCE INPUT BANDWIDTH**



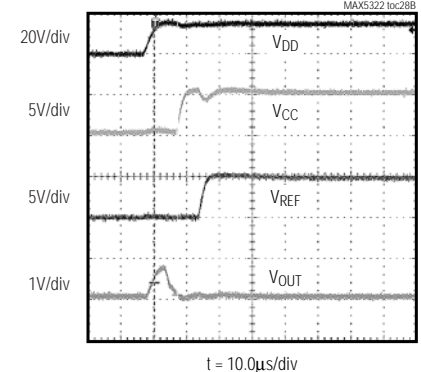
**BIPOLAR REFERENCE INPUT BANDWIDTH**



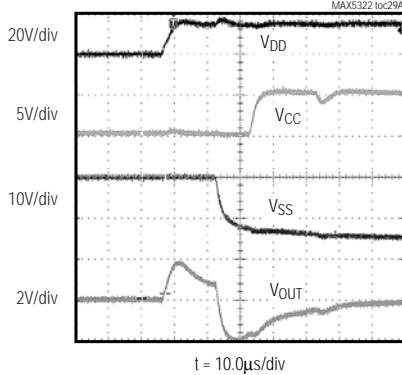
**UNIPOLAR STARTUP RESPONSE, C<sub>LOAD</sub> = 10pF**



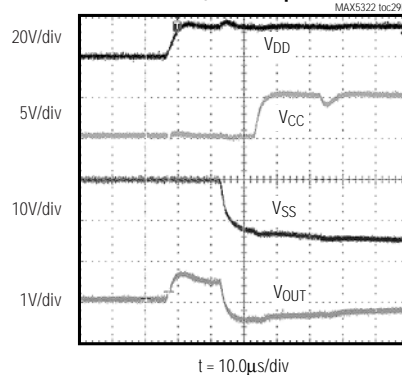
**UNIPOLAR STARTUP RESPONSE, C<sub>LOAD</sub> = 230pF**



**BIPOLAR STARTUP RESPONSE, C<sub>LOAD</sub> = 10pF**



**BIPOLAR STARTUP RESPONSE, C<sub>LOAD</sub> = 230pF**



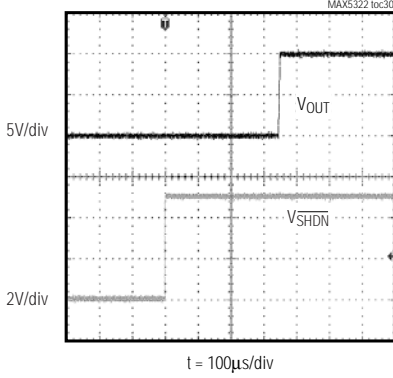
# $\pm 10V$ , Dual, 12-Bit, Serial, Voltage-Output DAC

MAX5322

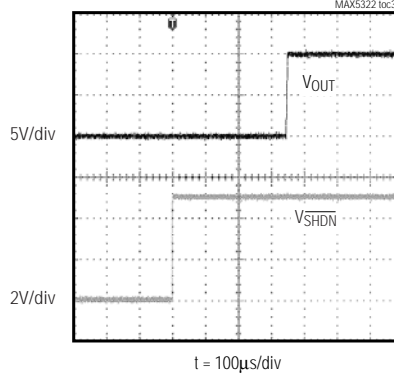
## Typical Operating Characteristics (continued)

( $V_{DD} = +15V$ ,  $V_{SS} = -15V$  for bipolar graphs,  $V_{SS} = 0$  for unipolar graphs,  $V_{CC} = +5V$ ,  $AGND = DGND = SGND_{-} = 0$ ,  $V_{REF_{-}} = +5.0V$ , output unloaded,  $T_A = +25^{\circ}C$ , all graphs apply to both unipolar and bipolar, unless otherwise noted.)

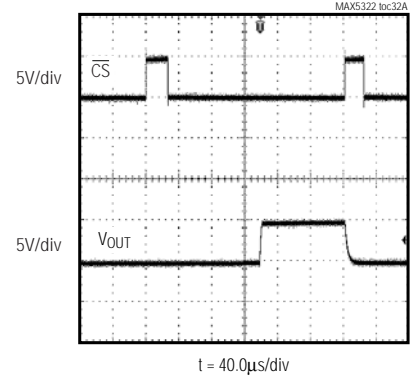
**UNIPOLAR RELEASE FROM  
HARDWARE SHUTDOWN RESPONSE**



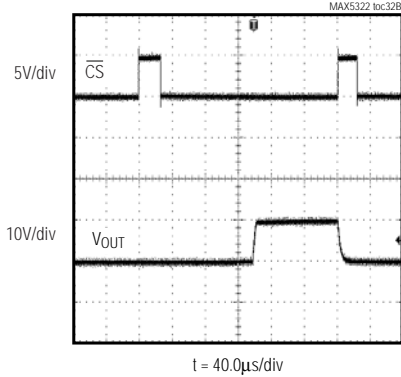
**BIPOLAR RELEASE FROM  
HARDWARE SHUTDOWN RESPONSE**



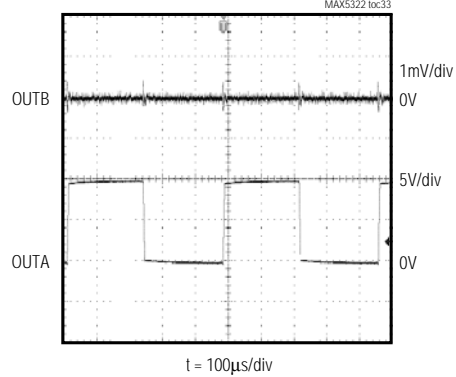
**UNIPOLAR  
SOFTWARE-SHUTDOWN RESPONSE**



**BIPOLAR  
SOFTWARE-SHUTDOWN RESPONSE**



**DAC-TO-DAC CROSSTALK**



# ±10V, Dual, 12-Bit, Serial, Voltage-Output DAC

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## Pin Description

PIN	NAME	FUNCTION
1, 2, 13–16, 27, 28	N.C.	No Connection. Not internally connected.
3	UNI/BIPB	DAC B Output-Mode Selection Input. Selects unipolar or bipolar output. Logic high = unipolar, logic low = bipolar. In unipolar mode, the analog output range is 0 to 2 x V <sub>REF</sub> . In bipolar mode, the analog output range is (-2 x V <sub>REF</sub> ) to (+2 x V <sub>REF</sub> ).
4	$\overline{\text{SHDN}}$	Active-Low Shutdown Input. Pulling $\overline{\text{SHDN}}$ low forces the DAC buffers into high impedance. Drive $\overline{\text{SHDN}}$ high for normal operation.
5	$\overline{\text{LDAC}}$	Active-Low Load DAC Input. DAC A and DAC B are updated with information in the input register on the $\overline{\text{LDAC}}$ falling edge.
6	$\overline{\text{CLR}}$	Active-Low Asynchronous Clear DAC Input. Pulling $\overline{\text{CLR}}$ low clears all DACs and input registers; resets all outputs to zero.
7	DGND	Digital Ground
8	V <sub>CC</sub>	Digital Power Input. Connect V <sub>CC</sub> to a +2.7V to +5.5V power supply. Bypass V <sub>CC</sub> to DGND with a 10μF and 0.1μF capacitor in parallel as close to the device as possible.
9	DOUT	Serial-Data Output. Data is clocked out on SCLK's falling edge. DOUT is high impedance when $\overline{\text{CS}}$ is high. Data shifted into DIN appears at DOUT 16.5 clock cycles later.
10	SCLK	Serial-Clock Input. SCLK clocks data in and out of the serial interface.
11	DIN	Serial-Data Input. Data is clocked in on the rising edge of SCLK.
12	$\overline{\text{CS}}$	Active-Low Chip-Select Input. Data is not clocked into DIN unless $\overline{\text{CS}}$ is low.
17	UNI/BIPA	DAC A Output-Mode Selection. Selects unipolar or bipolar output. Logic high = unipolar, logic low = bipolar. In unipolar mode, the analog output range is 0 to 2 x V <sub>REF</sub> . In bipolar mode, the analog output range is (-2 x V <sub>REF</sub> ) to (+2 x V <sub>REF</sub> ).
18	OUTA	DAC A Output
19	SGNDA	DAC A Sense Ground. Connect to AGND.
20	REFA	Reference Input for DAC A
21	V <sub>DD</sub>	Positive Analog-Power Input. Connect V <sub>DD</sub> to a +10.8V to +15.75V power supply. Bypass V <sub>DD</sub> to AGND with a 10μF and 0.1μF capacitor in parallel as close to the device as possible.
22	REFB	DAC B Reference Input
23	AGND	Analog Ground
24	SGNDB	DAC B Sense Ground. Connect to AGND.
25	OUTB	DAC B Output
26	V <sub>SS</sub>	Negative Analog-Power Input. For single-supply operation, connect V <sub>SS</sub> to AGND. For dual-supply operation, connect V <sub>SS</sub> to a -10.8V to -15.75V power supply and bypass V <sub>SS</sub> to AGND with a 10μF and 0.1μF capacitor in parallel, as close to the device as possible.

# ±10V, Dual, 12-Bit, Serial, Voltage-Output DAC

MAX5322

## Detailed Description

The MAX5322 dual, 12-bit DAC operates from either single or dual analog supplies. Dual ±12V to ±15V power supplies provide bipolar ±5V to ±10V outputs, or unipolar 0V to 10V outputs. Single 12V to 15V analog power supplies only provide unipolar 0 to 10V outputs. The reference inputs accept voltages from 2V to 5.25V. The DAC features INL and DNL less than ±1 LSB (max), a fast 10µs settling time, and a hardware shutdown mode that reduces current consumption to 2.8µA. The device features a 10MHz SPI-/QSPI-/MICROWIRE-compatible serial interface that operates with 3V or 5V logic, an asynchronous load input, and a serial-data output. The device offers a CLR that sets the DAC outputs to 0V. Figure 1 shows the functional diagram of the MAX5322.

## Serial Interface

An SPI-/QSPI-/MICROWIRE-compatible serial interface allows complete control of the DAC through a 16-bit control word. The first 4 bits form the control bits that determine register loading and software shutdown functions. The last 12 bits form the DAC data. The 16-bit word is entered MSB first.

Table 1 shows the serial-data control-word format. Table 2 shows the interface commands. The MAX5322 can be programmed while in shutdown.

The serial interface contains five registers: a 16-bit shift register, two 12-bit input registers, and two 12-bit DAC registers (Figure 1). The shift register accepts data from the serial interface. The input registers act as holding registers for data going to the DAC registers

**Table 1. Control-Word Format**

CONTROL BITS				DATA BITS												
MSB																LSB
C3	C2	C1	C0	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	

**Table 2. Serial-Interface Programming Commands**

16-BIT SERIAL WORD					FUNCTION
CONTROL BITS				DATA BITS	
C3	C2	C1	C0	D11–D0	
0	0	0	0	XXXXXXXXXXXX	No operation (NOP).
0	0	0	1	12-bit DAC data	Load both DAC registers and both input registers from the shift register. (Start both DACs with new data.)
0	0	1	0	12-bit DAC data	Load input register A from the shift register; DAC registers are unchanged.
0	0	1	1	12-bit DAC data	Load input register B from the shift register; DAC registers are unchanged.
0	1	0	0	12-bit DAC data	Load DAC register A and input register A from the shift register.
0	1	0	1	12-bit DAC data	Load DAC register B and input register B from the shift register.
0	1	1	0	XXXXXXXXXXXX	Update DAC register A from input register A (no data sent).
0	1	1	1	XXXXXXXXXXXX	Update DAC register B from input register B (no data sent).
1	0	0	0	XXXXXXXXXXXX	Shut down DAC A (provided $\overline{\text{SHDN}} = 1$ ).
1	0	0	1	XXXXXXXXXXXX	Shut down DAC B (provided $\overline{\text{SHDN}} = 1$ ).
1	0	1	0	XXXXXXXXXXXX	Update both DAC registers from their respective input registers. (Start both DACs with data previously stored in the input register.)
1	0	1	1	XXXXXXXXXXXX	Shut down both DACs (provided $\overline{\text{SHDN}} = 1$ ).
1	1	0	0	XXXXXXXXXXXX	Power up DAC A (no change to any registers).
1	1	0	1	XXXXXXXXXXXX	Power up DAC B (no change to any registers).
1	1	1	0	XXXXXXXXXXXX	Power up both DACs (no change to any registers).
1	1	1	1	XXXXXXXXXXXX	Not used.

X = Don't care.

**Note:** The DACs can be programmed in shutdown mode.

# ±10V, Dual, 12-Bit, Serial, Voltage-Output DAC

and isolate the shift register from the DAC registers. The DAC registers control the DAC ladder and thus the output voltage. Any update to a DAC register updates the respective output voltage.

Data in the shift register is transferred to the input registers during the appropriate software command only. Data in the input registers is transferred to the DAC registers in two ways: using the software command, or through external logic control using the asynchronous load input (LDAC). Table 2 shows the software commands that transfer the data from the shift register to the input and/or DAC registers. The CLR, an external logic control, asynchronously forces all outputs to 0V, in both unipolar and bipolar modes. Interface timing is shown in Figures 2 and 3.

Wait a minimum of 100ns after CS goes high before implementing LDAC or CLR. If either of these logic inputs activates during a data transfer, the incoming data is corrupted and needs to be reloaded. For software control only, tie LDAC and CLR high.

## DAC Architecture

The MAX5322 uses an inverted DAC ladder architecture to convert the digital input into an analog output voltage. The digital input controls weighted switches that connect the DAC-ladder nodes to either REFA (REFB) or GND (Figure 4). The sum of the weights produces the analog equivalent of the digital-input word and is then buffered at the output.

## External Reference and Transfer Functions

Connect an external reference of 2V to 5.25V to REFA and REFB. Set the output voltage range with the reference and the input code by using the equations below.

Unipolar output voltage:

$$V_{OUT\_UNI} = LSB_{UNI} \times CODE$$

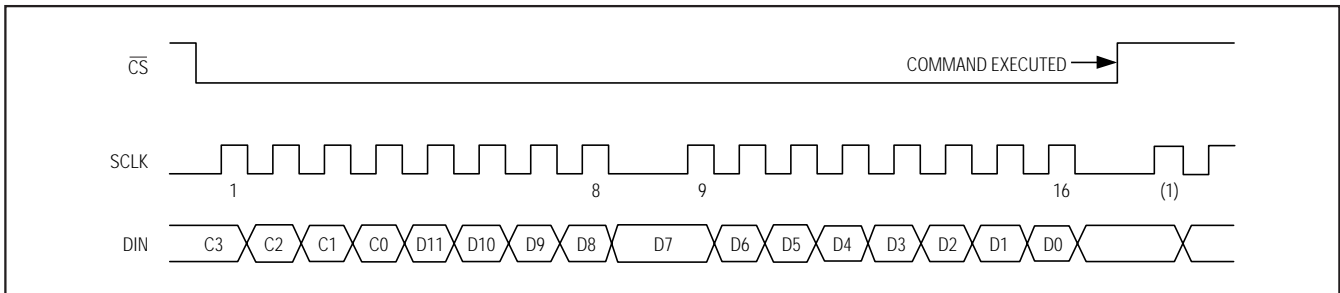


Figure 2. Serial-Interface Signals

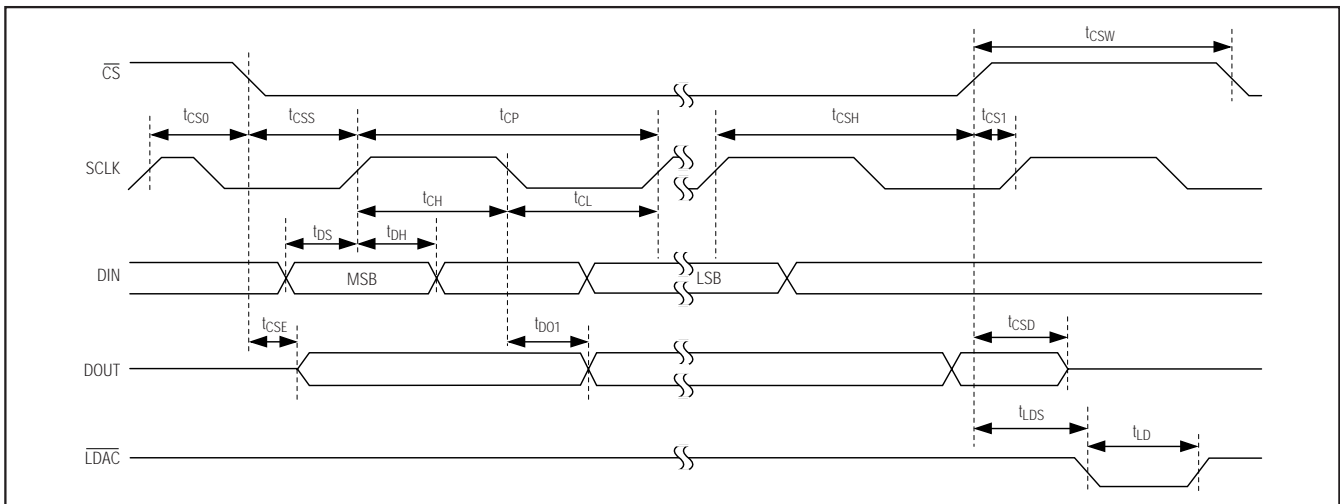


Figure 3. Serial-Interface Timing Diagram

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where:

$$LSB_{UNI} = \frac{2 \times V_{REF}}{2^{12}}$$

Bipolar output voltage:

$$V_{OUT\_BIP} = (LSB_{BIP} \times CODE) - (2 \times V_{REF})$$

where:

$$LSB_{BIP} = \frac{4 \times V_{REF}}{2^{12}}$$

where  $V_{OUT\_UNI}$  is the unipolar output voltage,  $V_{OUT\_BIP}$  is the bipolar output voltage,  $LSB_{UNI}$  is the unipolar LSB step size,  $LSB_{BIP}$  is the bipolar LSB step size,  $V_{REF}$  is the reference voltage, and CODE is the decimal equivalent of the binary, 12-bit, DAC input code.

In either case, a 000hex input code produces the minimum output ( $-2 \times V_{REF}$  for bipolar and zero for unipolar), an 800hex input code produces the midscale output (zero for bipolar and  $V_{REF}$  for unipolar), and a FFFhex input code produces the full-scale output ( $2 \times V_{REF}$  for bipolar and unipolar).

### Output Amplifiers

The output-amplifier section can be configured as either unipolar or bipolar by the  $UNI/\overline{BIP}$  logic input. With  $UNI/\overline{BIP}$  forced low, SW1 (SW4) and SW2 (SW5) are closed, and SW3 (SW6) is open.

This configuration channels the DAC output through two output stages to generate the  $\pm 2 \times V_{REF}$  output swing. The first amplifier generates the  $\pm V_{REF}$  voltage range and the second amplifier gains it up by two. When configured for bipolar operation, the MAX5322 must be driven with dual  $\pm 12V$  to  $\pm 15V$  power supplies.

With  $UNI/\overline{BIP}$  (  $UNI/\overline{BIPB}$  ) forced high, switches SW1 (SW4) and SW2 (SW5) are open and SW3 (SW6) is closed. This configuration channels the DAC output through only a single gain stage to generate a 0 to  $2 \times V_{REF}$  output swing.

### Daisy-Chaining

SPI-/QSPI-/MICROWIRE-compatible devices can be daisy-chained to reduce I/O lines from the host controller (Figure 7). Daisy-chain devices by connecting the DOUT of one device to the DIN of the next, and connect the SCLK of all devices to a common clock. Data is shifted out of DOUT 16.5 clock cycles after it is shifted into DIN, and is available on the rising edge of the 17th clock cycle. The SPI-/QSPI-/MICROWIRE-compatible serial interface normally works at up to 10MHz, but must be slowed to 6MHz if daisy-chaining. DOUT is high impedance when  $\overline{CS}$  is high.

### Shutdown

Shutdown is controlled by software commands or by the  $\overline{SHDN}$  logic input. The  $\overline{SHDN}$  logic input may be implemented at any time. The SPI-/QSPI-/MICROWIRE-compatible serial interface remains fully functional, and the device is programmable while shutdown. When shutdown, the MAX5322 supply current reduces to 2.8 $\mu$ A.

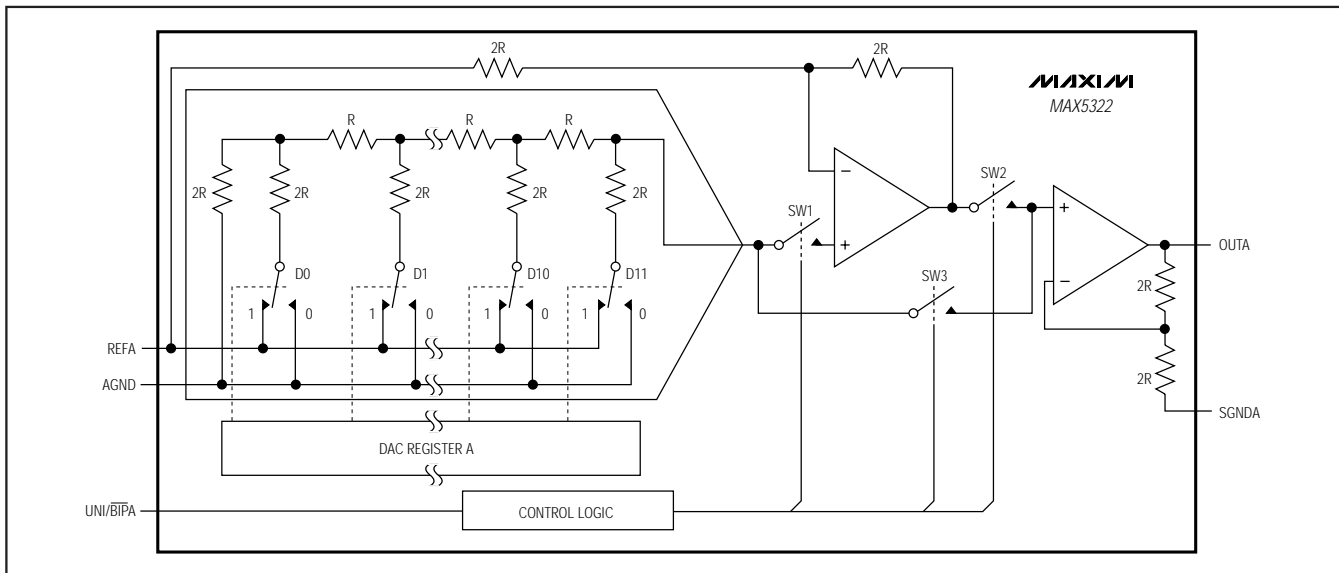


Figure 4. Basic Inverted DAC Ladder

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(max), DOUT is high impedance, and OUTA and OUTB are pulled to SGND<sub>A</sub> and SGND<sub>B</sub>, respectively, through the internal feedback resistors of the output amplifier (Figure 1). When coming out of shutdown, or during device power-up, allow 350µs for the output to stabilize.

## Applications Information

### Power Supplies

A single supply of +12V to +15V is required to realize an output swing of 0 to 10V. A dual supply of ±12V to ±15V is required to realize an output swing of ±10V, and allows unipolar, 0 to +10V output if  $\overline{\text{UNI/BIP}}_-$  is forced high. A +3V to +5V digital power supply and two +2.000V to +5.250V external reference voltages are also required. Always bring up the reference voltages last; the other power supplies do not require sequencing.

### Power-Supply Bypassing and Ground Management

Bypass  $V_{DD}$  and  $V_{SS}$  with 1.0µF and 0.1µF capacitors to AGND, and bypass  $V_{CC}$  with a 1.0µF and 0.1µF capacitors to DGND. Minimize trace lengths to reduce inductance. Digital and AC transient signals on AGND or DGND can create noise at the output. Connect AGND and DGND to the highest quality ground available. Use proper grounding techniques, such as a multilayer board with a low-inductance ground plane or star connect all ground return paths back to AGND. Carefully lay out the traces between channels to reduce AC cross coupling and crosstalk. Wire-wrapped boards, sockets, and breadboards are not recommended.

**Table 3. Output Voltage as Input Code Examples**

BINARY DAC CODE		ANALOG OUTPUT	
MSB	LSB	UNIPOLAR ( $\overline{\text{UNI/BIP}}_- = \text{HIGH}$ )	BIPOLAR ( $\overline{\text{UNI/BIP}}_- = \text{LOW}$ )
1111	1111 1111	+2 x $V_{REF}$ (4095 / 4096)	+2 x $V_{REF}$ (2047 / 2048)
1000	0000 0001	+2 x $V_{REF}$ (2049 / 4096)	+2 x $V_{REF}$ (1 / 2048)
1000	0000 0000	+2 x $V_{REF}$ (2048 / 4096) = $V_{REF}$	0
0111	1111 1111	+2 x $V_{REF}$ (2047 / 4096)	-2 x $V_{REF}$ (1 / 2048)
0000	0000 0001	+2 x $V_{REF}$ (1 / 4096)	-2 x $V_{REF}$ (2047 / 2048)
0000	0000 0000	0	-2 x $V_{REF}$ (2048 / 2048) = -2 x $V_{REF}$

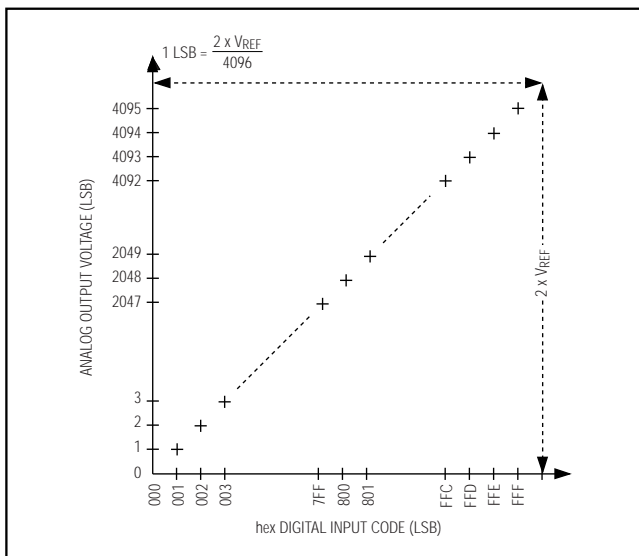


Figure 5. Unipolar Transfer Function

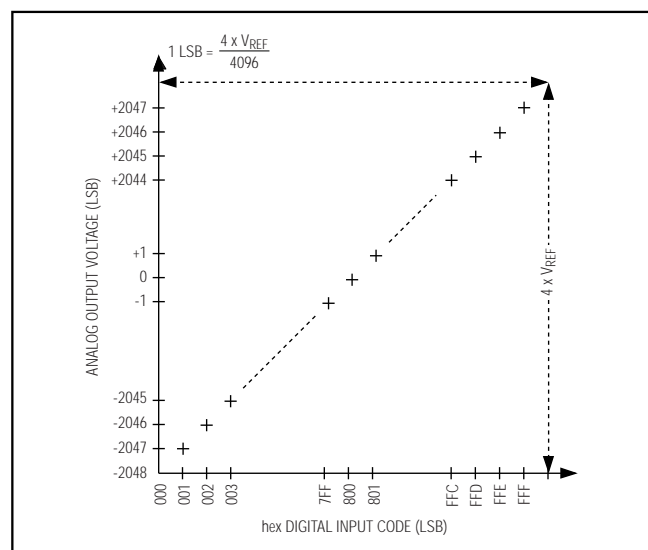


Figure 6. Bipolar Transfer Function



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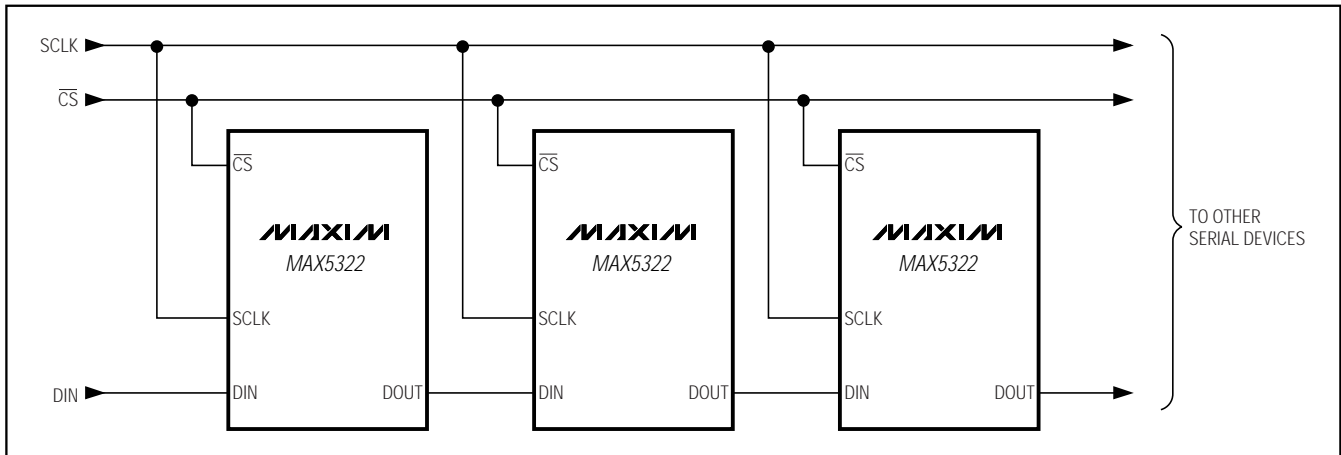
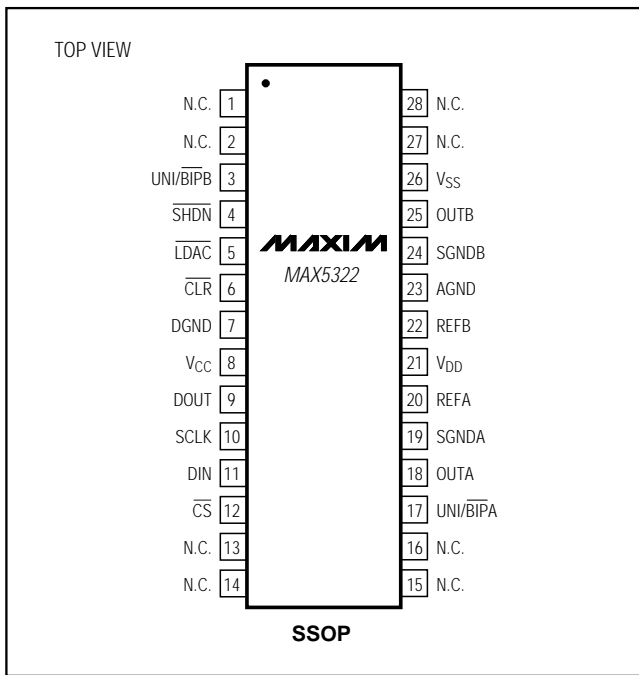


Figure 7. Daisy-Chaining Devices

## Pin Configuration



## Chip Information

TRANSISTOR COUNT: 5914  
PROCESS: BICMOS

# ±10V, Dual, 12-Bit, Serial, Voltage-Output DAC

MAX5322

## Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).)

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.068	0.078	1.73	1.99
A1	0.002	0.008	0.05	0.21
B	0.010	0.015	0.25	0.38
C	0.004	0.008	0.09	0.20
D	SEE VARIATIONS			
E	0.205	0.212	5.20	5.38
e	0.0256 BSC		0.65 BSC	
H	0.301	0.311	7.65	7.90
L	0.025	0.037	0.63	0.95
$\alpha$	0 $^\circ$	8 $^\circ$	0 $^\circ$	8 $^\circ$

D	INCHES		MILLIMETERS		N
	MIN	MAX	MIN	MAX	
D	0.239	0.249	6.07	6.33	14L
D	0.239	0.249	6.07	6.33	16L
D	0.278	0.289	7.07	7.33	20L
D	0.317	0.328	8.07	8.33	24L
D	0.397	0.407	10.07	10.33	28L

**NOTES:**

- D & E DO NOT INCLUDE MOLD FLASH.
- MOLD FLASH OR PROTRUSIONS NOT TO EXCEED .15 MM (.006").
- CONTROLLING DIMENSION: MILLIMETERS.
- MEETS JEDEC MO150.
- LEADS TO BE COPLANAR WITHIN 0.10 MM.

<b>DALLAS SEMICONDUCTOR</b>		<b>MAXIM</b>	
PROPRIETARY INFORMATION			
TITLE: PACKAGE OUTLINE, SSOP, 5.3 MM			
APPROVAL	DOCUMENT CONTROL NO. 21-0056	REV. C	1/1

SSOP EPS

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