**CMOS** Watchdog Timer

# **HITACHI**

## **Description**

The HA16117F Series of ICs make a micro-processor (MPU) system fail-safe by monitoring its power supply to detect voltage drops, and monitoring a P-RUN (program running) pulse to detect system crashes. Also referred to as watchdog timers, these devices are essential in systems that aim for high levels of crash protection. Fabricated by a CMOS process, they consume little power and are ideally suited for battery-operated systems.

These ICs are available in versions for industrial and communications equipment and automotive applications, as well as for consumer products.

#### **Functions**

- Power-on reset
  - Sends a RES signal to the MPU for a fixed time at power-on
- Watchdog timer (WDT)
  - Monitors a P-RUN signal from the MPU and sends the MPU a RES signal if P-RUN departs from a set frequency range
- Auto-reset
  - Outputs RES signals to the MPU at clocked intervals while P-RUN remains abnormal
- Supply voltage supervision
  - Outputs a low  $\overline{RES}$  signal if the supply voltage (same as the MPU's  $V_{CC}$ ) falls below a low threshold level ( $V_{TL}$ ). The threshold differs for different ICs in the series, allowing designers to choose an IC matching system requirements (see ordering information)

### **Features**

- Low power consumption : Operating (ACC pin low) = 0.5 mW (Typ)
  - : Standby (ACC pin high) = 0.2 mW (Typ)
- Watchdog timer on/off control by ACC input signal
- Independent auto-reset high and low times  $(t_{RH} \text{ and } t_{RI})$
- Watchdog monitoring by frequency filtering (independent of duty cycle)
- High-precision low voltage detection (±2%)
- Space- and weight-saving 8-pin SOP package

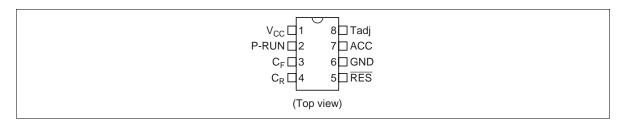


# **Ordering Information**

The HA16117F Series includes three ICs with different low threshold levels ( $V_{TL}$ ).

Type No.	Low Threshold Voltage (V <sub>TL</sub> )
HA16117FPA/FPAJ	4.4 V Typ
HA16117FPB/FPBJ	4.2 V Typ
HA16117FPC/FPCJ	4.0 V Typ

## **Pin Arrangement**

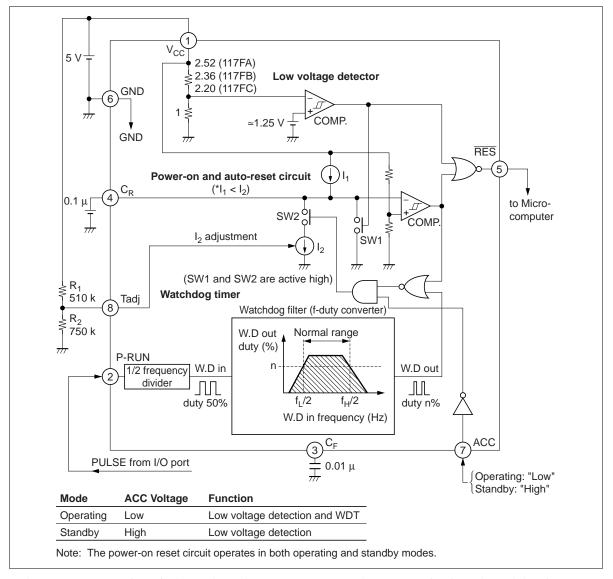


# **Pin Description**

Pin No.	Symbol	Function
1	V <sub>cc</sub>	Power supply voltage input
2	P-RUN	Watchdog timer (WDT) input
3	$C_{\scriptscriptstyle F}$	Connected capacitor $C_{\scriptscriptstyle F}$ determines WDT filter characteristic (normal frequency range)
4	$C_R$	Connected capacitor $C_{\text{R}}$ determines $t_{\text{ON}}$ for power-on reset and $t_{\text{OFF}},t_{\text{RH}},$ and $t_{\text{RL}}$ for auto-reset
5	RES	Reset signal output from WDT and voltage supervision circuits
6	GND	Ground
7	ACC	WDT on/off control input (on when ACC is low)
8	Tadj *	For adjusting $t_{\mbox{\tiny RH}}$ and $t_{\mbox{\tiny OFF}}$ (divide $V_{\mbox{\tiny CC}}$ to get the adjustment voltage)

Note: The low-voltage threshold cannot be modified by changing the external resistors connected to the Tadj pin.

# **Block Diagram**



The HA16117F consists of a low voltage detector, power-on and auto-reset circuit, and watchdog timer.

#### Low Voltage Detector

Uses a reference voltage source (≈ 1.25 V) and high-precision comparator to detect drops in the supply voltage.

#### Power-On and Auto-Reset Circuit

Generates the  $\overline{RES}$  waveform, using a multivibrator consisting of a current source  $I_1$  that charges the external capacitor  $C_R$ , a current source  $I_2$  that discharges  $C_R$ , and a comparator.

#### Watchdog Timer

Reshapes the P-RUN signal (programming-running pulse) from the MPU to obtain a 50% duty cycle, then converts frequency to duty cycle in the watchdog filter (WD filter).

The watchdog filter is a bandpass filter. The duty cycle of the filter output is highest in the normal frequency range of P-RUN.

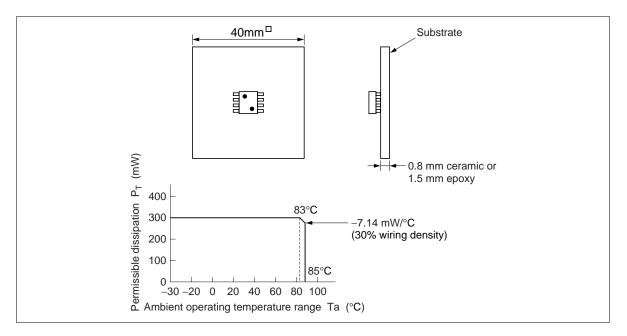
The watchdog filter output controls  $I_2$  in the multivibrator, the higher the duty cycle of the watchdog filter output, the shorter the time during which  $I_2$  discharges  $C_R$ . If the duty cycle is high enough then  $C_R$  is held at a high potential, preventing the multivibrator from firing, and the  $\overline{RES}$  output remains high.

## **Absolute Maximum Ratings** (Ta = 25°C)

R	at	ii	10	as
				,-

Item	Symbol	HA16117FPA/FPB/FPC	HA16117FPAJ/FPBJ/FPCJ	Unit
Power supply voltage	$V_{cc}$	-0.3 to +14	-0.3 to +14	V
P-RUN input voltage	V <sub>P</sub>	V <sub>cc</sub>	V <sub>cc</sub>	V
ACC input voltage	V <sub>ACC</sub>	14	14	V
RES output current	I <sub>RES</sub>	10	10	mA
Permissible dissipation *1	P <sub>T</sub>	300	300	mW
Operating temperature range	Topr	-30 to +85	-40 to +85	°C
Storage temperature	Tstg	-55 to +125	-55 to +125	°C

Note: 1. This is the value when mounted on a glass epoxy substrate with 30% wiring density, up to an ambient temperature of 83°C. Above that temperature, derate by 7.14 mW/°C.

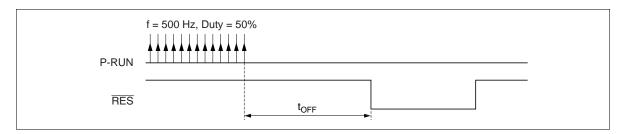


## **Electrical Characteristics**

$$(V_{CC} = 5~V,~Ta = 25^{\circ}C,~C_{_F} = 0.01~\mu\text{F},~C_{_R} = 0.1~\mu\text{F},~R_{_1} = 510~\text{k}\Omega,~R_{_2} = 750~\text{k}\Omega)$$

Item			Symbol	Min	Тур	Max	Unit	<b>Test Conditions</b>
General	Operating sup	oply current	I <sub>CC1</sub>	_	100	_	μΑ	$V_{ACC} = 0 \text{ V},$ $f_{P-RUN} = 100 \text{ Hz}$
			I <sub>CC2</sub>	_	200	600	μΑ	$V_{ACC} = 0 \text{ V},$ $f_{P-RUN} = 20 \text{ kHz}$
	Standby supp	oly current	I <sub>STBY</sub>	_	43	100	μΑ	V <sub>ACC</sub> = 12 V
Low voltage detector	Low voltage threshold level	HA16117FPA/FPAJ	$V_{TL}$	4.3	4.4	4.5	V	When V <sub>CC</sub> drops
		HA16117FPB/FPBJ	<del>-</del>	4.1	4.2	4.3	V	-
		HA16117FPC/FPCJ	_	3.9	4.0	4.1	V	-
	Hysteresis wi	dth	V <sub>HYS</sub>	50	100	150	mV	
ACC	Low input vol	tage	V <sub>IL1</sub>	_	_	0.8	V	
	High input vo	Itage	V <sub>IH1</sub>	2.0	_	_	V	
P-RUN	Low input voltage		V <sub>IL2</sub>	_	_	0.8	V	
input	High input vo	Itage	V <sub>IH2</sub>	2.0	_	_	V	
WDT	Power-on res	et time	t <sub>ON</sub>	24	40	56	ms	
	Reset-clock of	off time	t <sub>OFF</sub> *1	78	130	182	ms	
	Reset low tim	e	t <sub>RL</sub>	12	20	28	ms	
	Reset high tir	ne	t <sub>RH</sub>	36	60	84	ms	P-RUN pin = 0 V
	Low setup tim	ne	t <sub>SL</sub>	1	_	_	ms	
	High setup tir	ne	t <sub>SH</sub>	_	_	1	ms	
RES	RES low volta	age	$V_{OL}$	_	_	0.4	V	$I_{OL} = 1 \text{ mA}$
output	RES high vol	tage	$V_{OH}$	_	$V_{CC}$	_	V	Open
	Reset functio	n starting voltage	V <sub>RES</sub>	_	0.8	1.4	V	
Constant range	Constant rang	ge of R <sub>1</sub> and R <sub>2</sub>	К	0.55	0.6	0.8	_	$K = R_2 / (R_1 + R_2)$
Operating s	supply voltage ra	ange	V <sub>CCRNG</sub>	V <sub>TL</sub>	_	6.0	V	

Note: 1. Reset-clock off time  $t_{\text{OFF}}$  is provided a shown in the under figure.



## **Timing Waveforms and Functional Description**

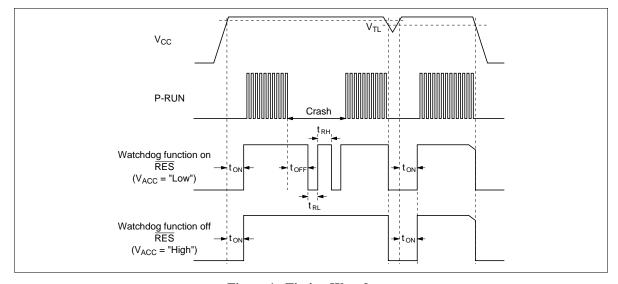


Figure 1 Timing Waveforms

### Watchdog On/Off Function

A feature of the HA16117F is that watchdog supervision can be switched on and off. When the watchdog function is switched on, both the supply voltage and

P-RUN input are monitored to detect abnormal conditions. When the watchdog function is switched off (standby mode), only the supply voltage is monitored. Watchdog supervision is switched on and off by the input at the ACC pin (pin 7): Supervision is on when ACC is low, and off when ACC is high.

Many MPUs have a standby mode in which the CPU stops running but memory contents are retained. In standby mode, program execution halts and I/O ports go to the high-impedance state, so there is no need for the watchdog timer to supervise pulse output from an I/O port to detect abnormal conditions. Power can be saved by placing both the MPU and HA16117F in standby mode at the same time. The HA16117F is designed to draw a typical standby current  $I_{STBY}$  of only 43  $\mu$ A Typ when the watchdog function is switched off.

## ACC Pin (pin 7) and $\overline{RES}$ Output

When the MPU returns from standby mode to normal operation it generally takes 10 to 200 ms for the clock oscillator in the MPU to stabilize. The  $\overline{RES}$  signal is not output during this setup time. After the setup time ( $t_{SL}$ ) has elapsed,  $\overline{RES}$  is output if the P-RUN signal from the MPU is still abnormal.

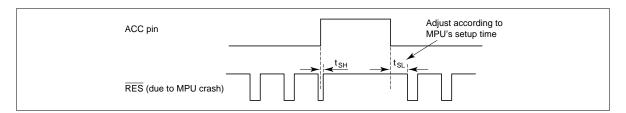


Figure 2 ACC Pin and RES Output

## **Internal Operation and Usage Notes**

Figure 3 shows an equivalent circuit of the watchdog timer block with a  $V_{CC}$  pin level of 5 V and ACC pin level of 0 V, and the following pages show internal operation timing charts for different P-RUN frequencies. (Descriptions apply to conditions  $C_F = 0.01 \, \mu F$ ,  $C_R = 0.1 \, \mu F$ ,  $R_2/(R_1 + R_2) = 0.6$ .)

#### **Operation**

The power-on and auto-reset circuit is a multivibrator with timing controlled by  $C_R$  charge current  $I_1$  and discharge current  $I_2$ . As  $I_1:I_2\approx 3:1$  (Typ design value), when the (WD) (watchdog filter circuit output) on-duty is 25% or above, the  $C_R$  pin potential does not fall below 1.6 V. Therefore, (C) in the figure below is fixed low, and  $\overline{RES}$  is not output. The (WD) on-duty varies according to the P-RUN frequency. If the frequency is lower or higher than the design value, the (WD) on-duty decreases, and at 25% or below,  $\overline{RES}$  is output. Refer to the timing charts on the following pages for an explanation of the operation of the watchdog filter.

### **Usage Notes**

- When the P-RUN frequency reaches 20 kHz or above, t<sub>OFF</sub> is short (see the timing charts on the following pages). This must be borne in mind in the design stage.
- If the P-RUN frequency fluctuates,  $\overline{RES}$  may also be output within the normal detection set frequency (see the timing charts on the following pages).
- Detection frequencies f<sub>H</sub> and f<sub>L</sub> described in the Data Book are Typ values, and a certain amount of dispersion can be expected. A margin of ±30% or more should be allowed for in the design.

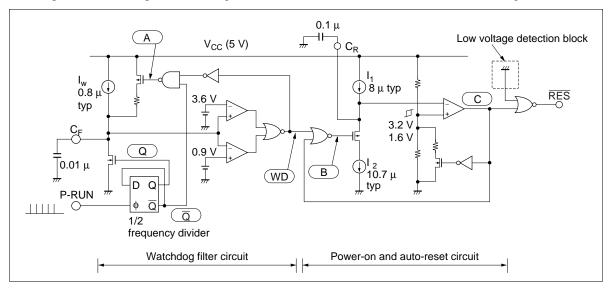
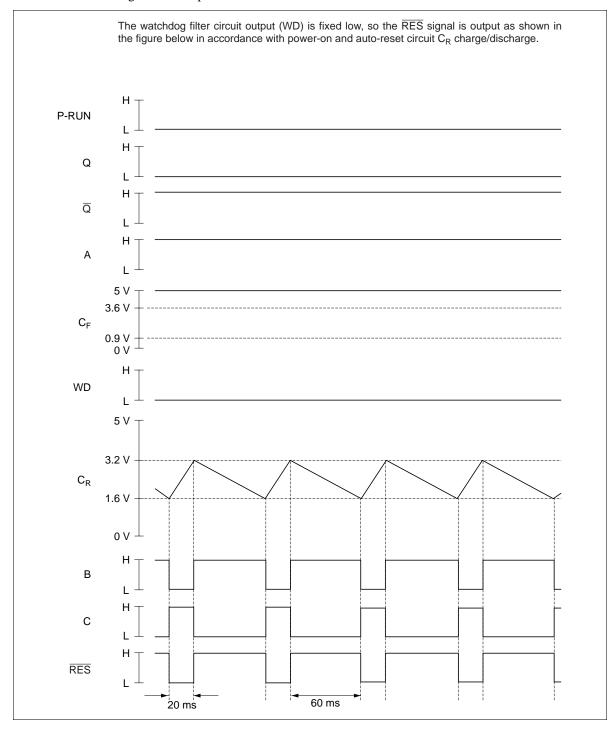
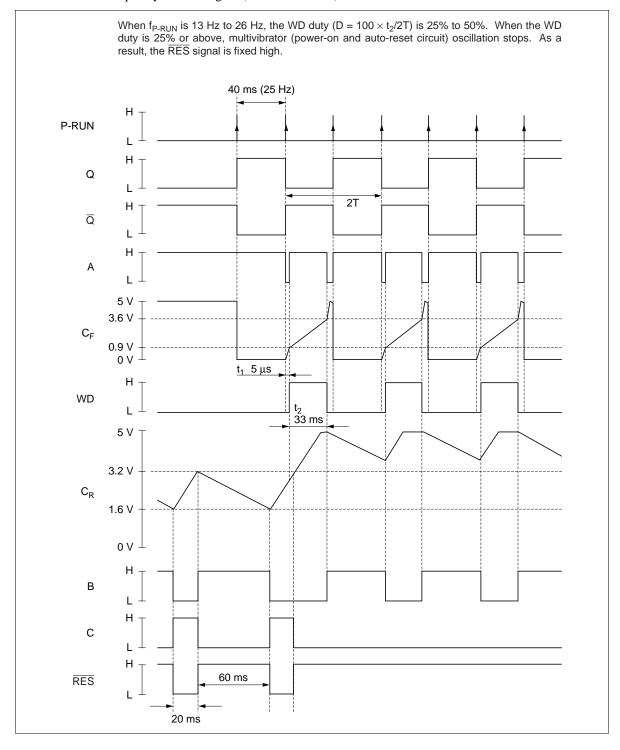


Figure 3 Watchdog Timer Evaliation Circuit

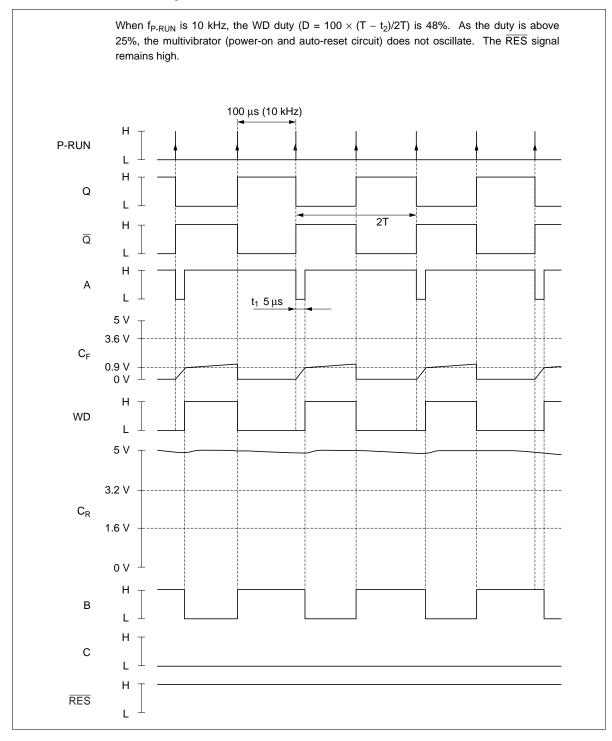
## 1. When P-RUN signal is not input



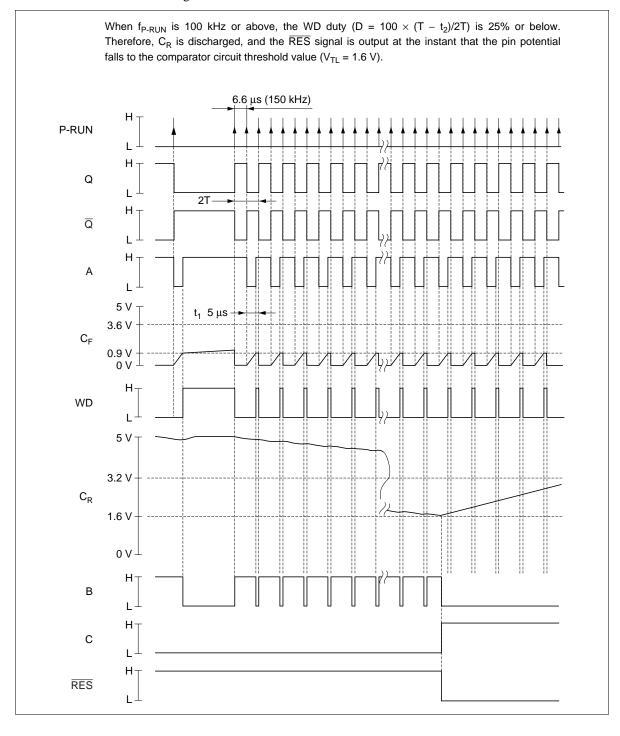
## 2. With a low-frequency P-RUN signal ( 13 Hz to 26 Hz)



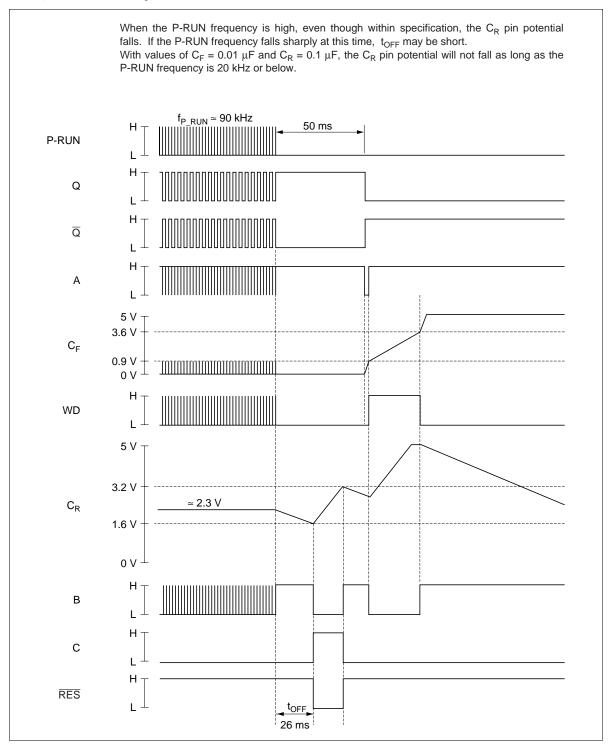
## 3. With a 10 kHz P-RUN signal



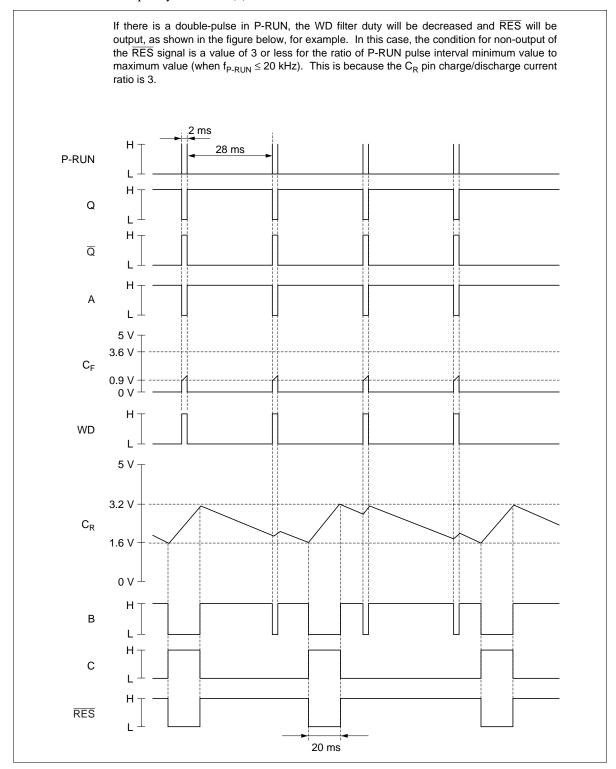
## 4. With a 150 kHz P-RUN signal



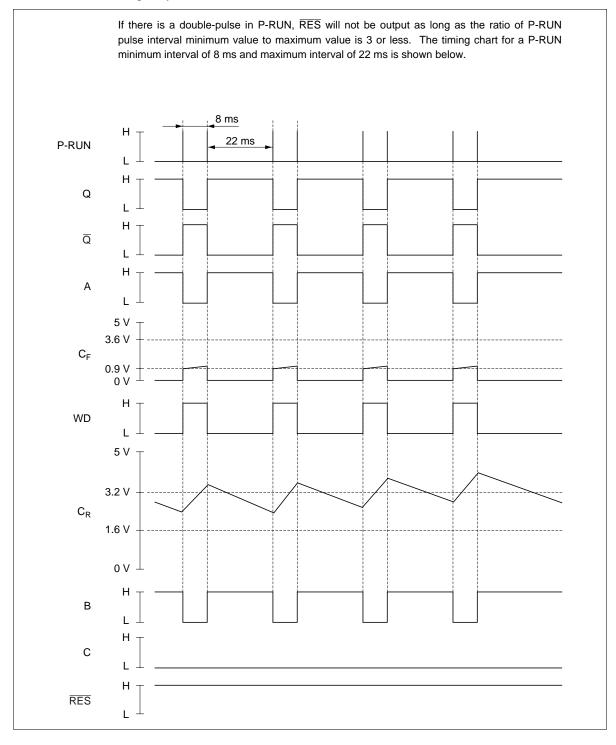
## 5. t<sub>OFF</sub> when P-RUN signal 90 kHz



## 6. When P-RUN frequency fluctuates (1)

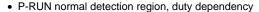


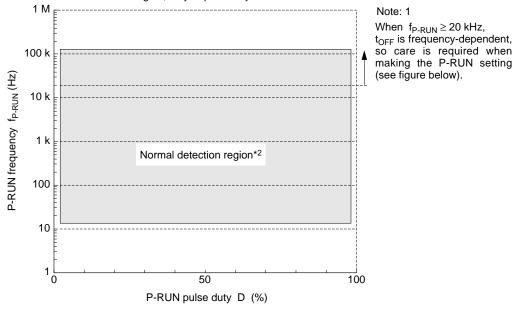
## 7. When P-RUN frequency fluctuates (2)



#### 8. Summary of cases where P-RUN frequency fluctuates

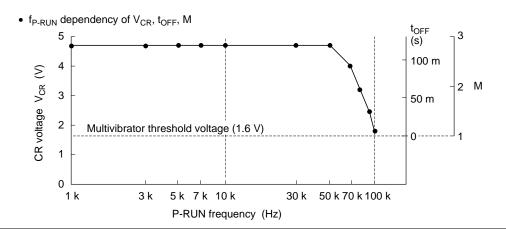
If there is a double-pulse in P-RUN,  $\overline{\text{RES}}$  may be output if the double-pulse has multiple frequency components. If the P-RUN frequency fluctuates, refer to the following when making the P-RUN setting.





Note: 2. This is the region when  $f_{P-RUN}$  is constant. If  $f_{P-RUN}$  fluctuates within the normal detection region, the following applies:

Normal detection is performed when the condition  $f_{P-RUN H}/f_{P-RUN L} < M$  is satisfied.



## Setting of RES Timing and Watchdog Frequency Range

Different MPUs have different  $\overline{RES}$  timing requirements. The minimum reset time ( $t_{ON}$ ) required at power-on (rise of  $V_{CC}$ ) is 20 ms for some MPUs and 100 ms for others.

 $\overline{RES}$  timing waveform parameters must be selected according to the MPU. With the HA16117F the timing of the  $\overline{RES}$  output and the watchdog frequency range can both be set by external constants ( $C_F$ ,  $C_R$ , and K).

		Parameters		
Item	Symbol	CR (pin 4)	CF (pin 3)	K (pin 8) *1
Power-on reset time	t <sub>on</sub>	•		
Reset-clock off time	t <sub>OFF</sub>	•	<b>▲</b> * <sup>2</sup>	•
Reset low time	t <sub>RL</sub>	•		
Reset high time	t <sub>RH</sub>	•		•
Watchdog frequency high	$f_{H}$		•	•
Watchdog frequency low	f <sub>L</sub>	•	•	•

Notes: 1.  $K = R_2 / (R_1 + R_2)$ 

- 2. Variability of  $t_{\text{OFF}}$  increases with increasing  $C_{\text{F}}$ . The variability  $\Delta t_{\text{OFF}}$  is approximately 3.3 (M $\Omega$ )  $\times$   $C_{\text{F}}$  ( $\mu$ F), so  $C_{\text{F}} \le 0.01$  ( $\mu$ F) is recommended.
- 3. External constants should be selected with reference to the formulas in tables 1 and 2.

 Table 1
 Calculation of RES Output Timing

Item	Formula	Notes
t <sub>on</sub> (ms)	400 ( $\Omega$ ) × $C_R$ ( $\mu$ F)	$t_{\mbox{\scriptsize ON}}$ and $t_{\mbox{\scriptsize OFF}}$ can be set independently
t <sub>OFF</sub> (ms)	$1.99 \times t_{RH}$ (ms)	
t <sub>RL</sub> (ms)	$0.5 \times t_{ON}$ (ms)	$t_{\mbox{\tiny RL}}$ and $t_{\mbox{\tiny RH}}$ can be set independently
t <sub>RH</sub> (ms)	$\frac{1.6 \text{ (V)}}{\text{K} \times 31 \text{ (}\mu\text{A)} - 15.8 \text{ (}\mu\text{A)}} \times \text{C}_{\text{R}} \text{ (}\mu\text{F)} \times 10^{3}$	_
t <sub>sL</sub> (ms)	≈ t <sub>OFF</sub> (ms)	

Table 2 Calculation of Watchdog Frequency Range

Item	Formula
f <sub>H</sub> (MHz)	$\frac{1}{500~(\Omega)\times C_{_{F}}~(\mu\text{F})}\times~\frac{t_{_{RH}}~(ms)-t_{_{RL}}~(ms)}{t_{_{RH}}~(ms)+t_{_{RL}}~(ms)}$
f <sub>L</sub> (Hz)	$\frac{1}{1.7~(\text{M}\Omega)\times\text{C}_{\text{F}}~(\mu\text{F})}~\times~\frac{t_{\text{RL}}~(\text{ms})}{t_{\text{RH}}~(\text{ms})+t_{\text{RL}}~(\text{ms})}~~\text{or}~~\frac{1}{t_{\text{OFF}}~(\text{ms})}~\times10^3$
	Whichever is larger

#### **Selection of External Constants**

If the reset duration necessary for the MPU to operate reliably at power-on is known, there is a simple procedure for selecting external constants, starting from the power-on reset time  $(t_{ON})$ .

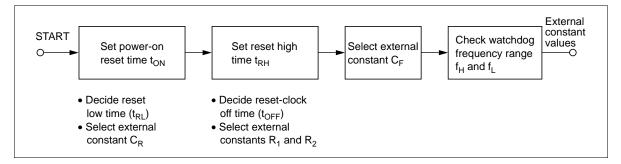
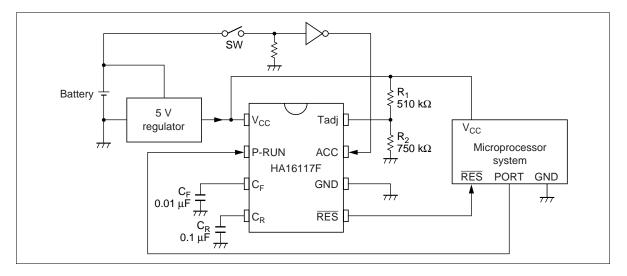
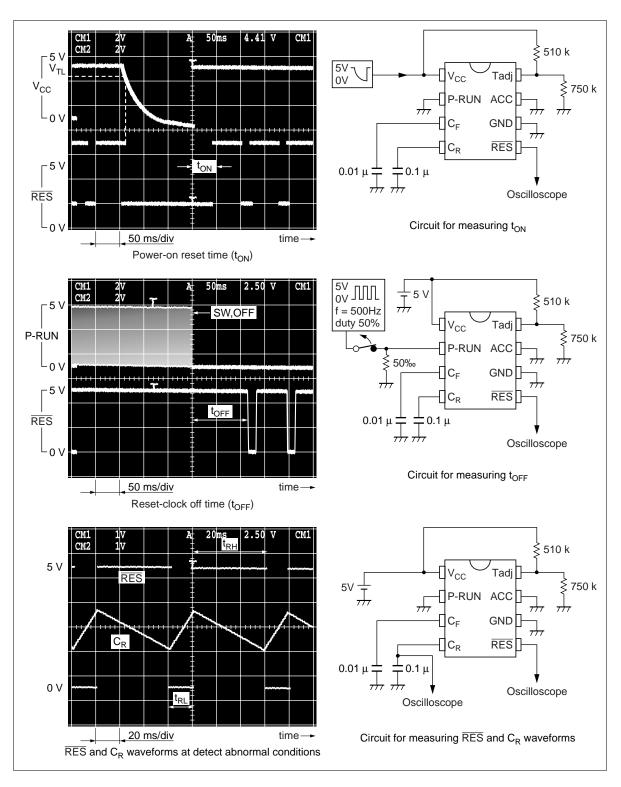


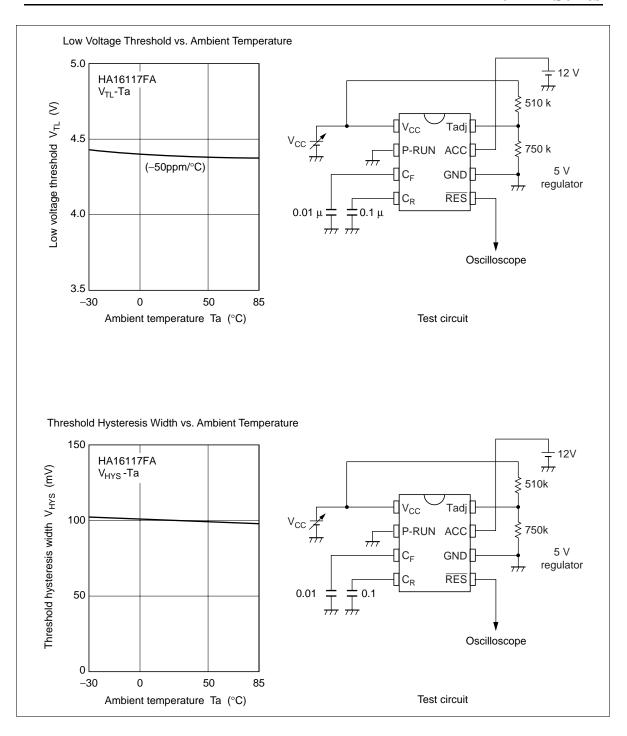
Figure 4 Procedure for Selecting External Constants

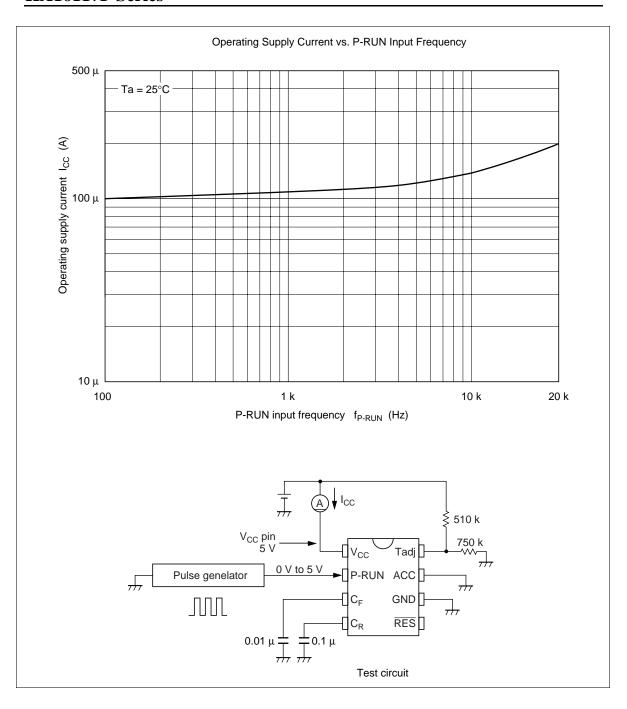
## **Application Example**

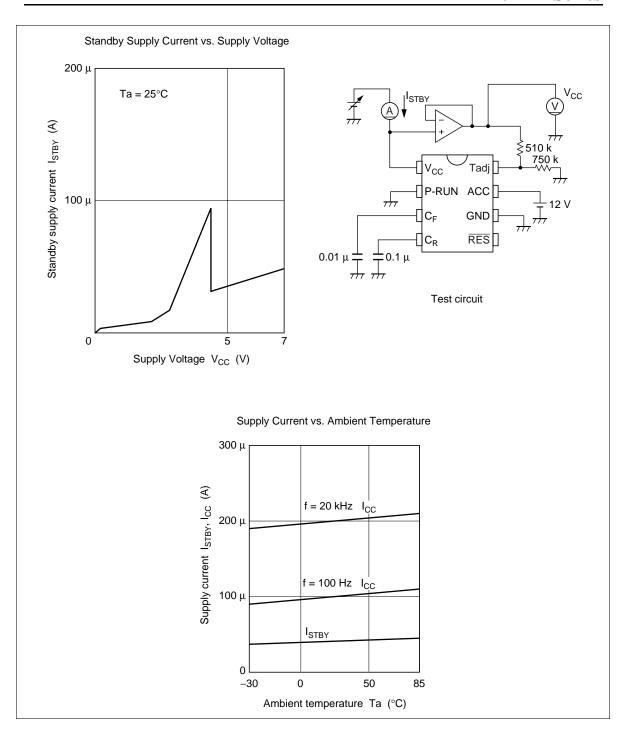


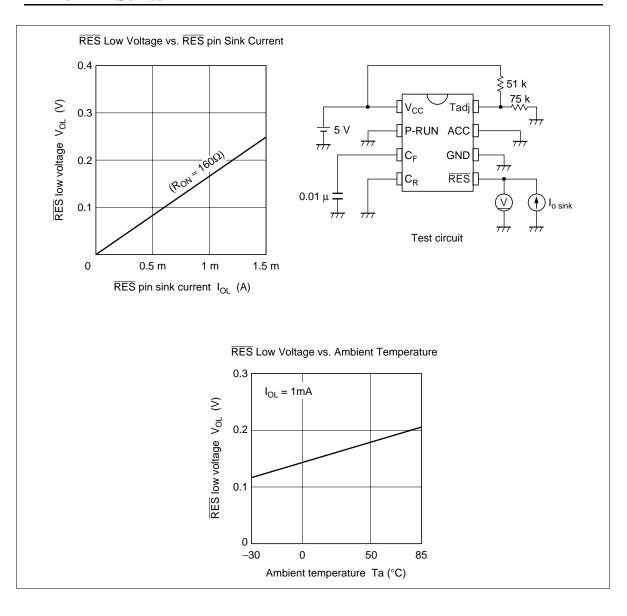
## **Operating Characteristics and Test Circuits**

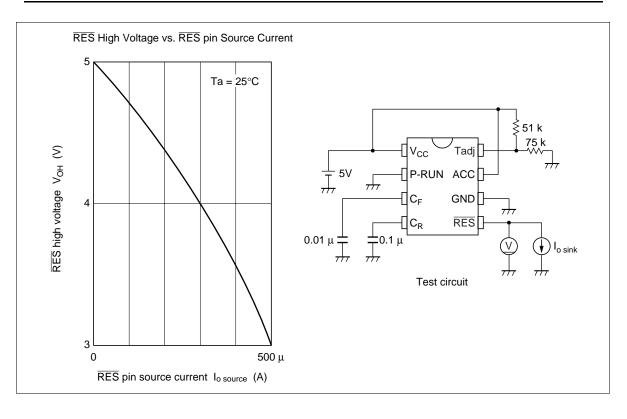


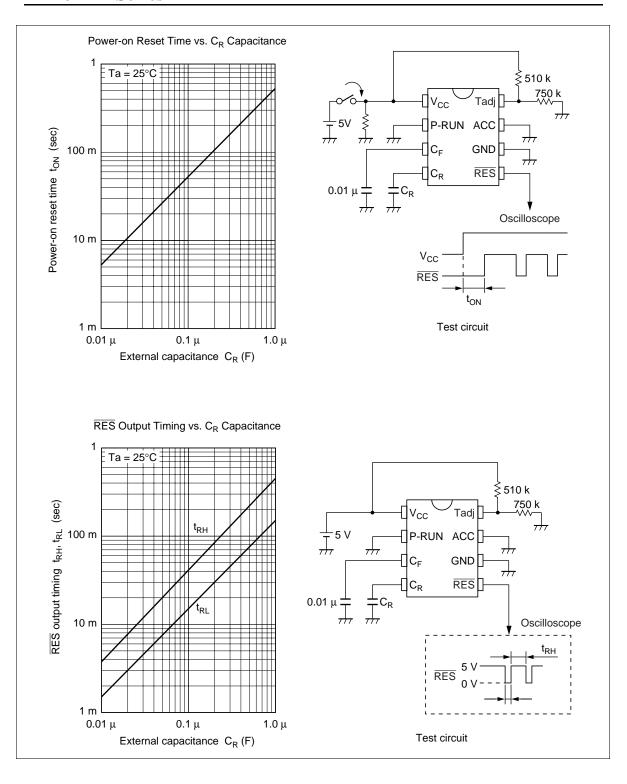


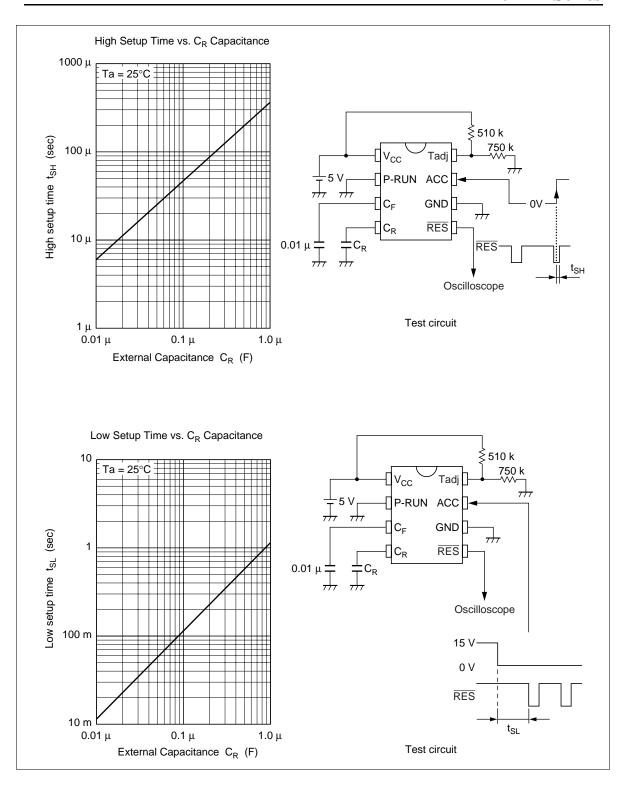


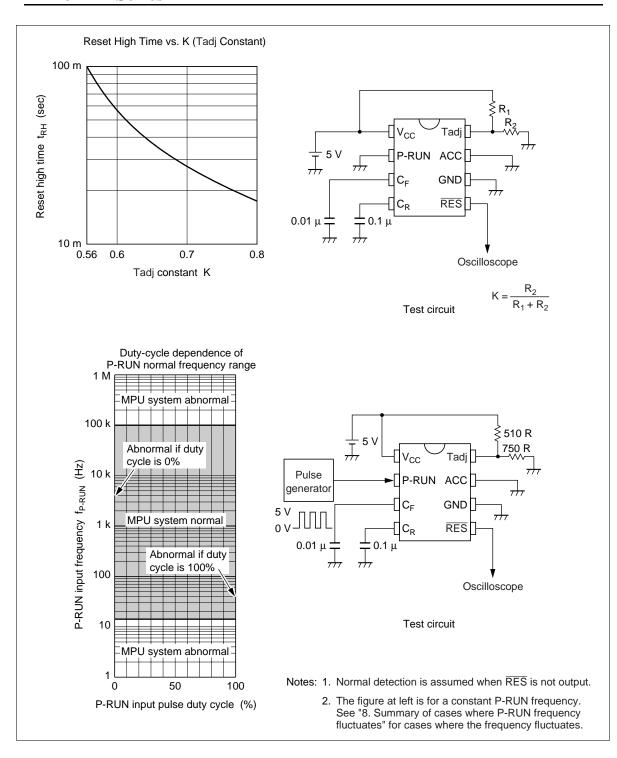




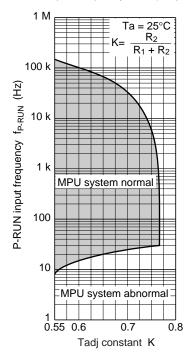


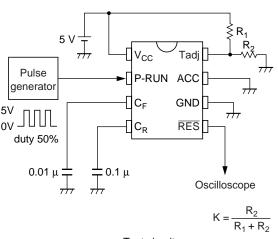






#### P-RUN Input Frequency vs. K (Tadj constant)



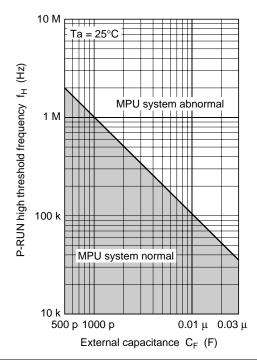


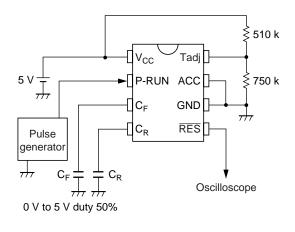
Test circuit

Notes: 1. Normal detection is assumed when  $\overline{\text{RES}}$  is not output.

2. The figure at left is for a constant P-RUN frequency.

### P-RUN High Threshold Frequency vs. C<sub>F</sub> Capacitance





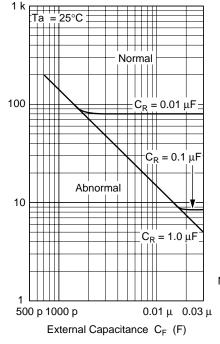
Test circuit

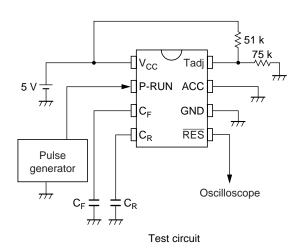
Notes: 1. Normal detection is assumed when RES is not output.

2. The figure at left is for a constant P-RUN frequency.

P-RUN low threshold frequency f<sub>L</sub> (Hz)

#### P-RUN Low Threshold Frequency vs. C<sub>F</sub> Capacitance

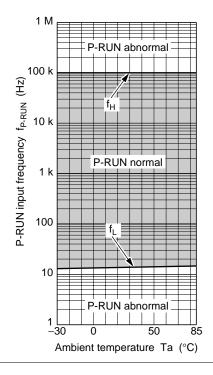


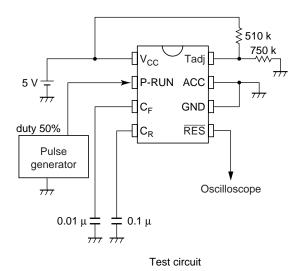


Notes: 1. Normal detection is assumed when  $\overline{\text{RES}}$  is not output.

2. The figure at left is for a constant P-RUN frequency.

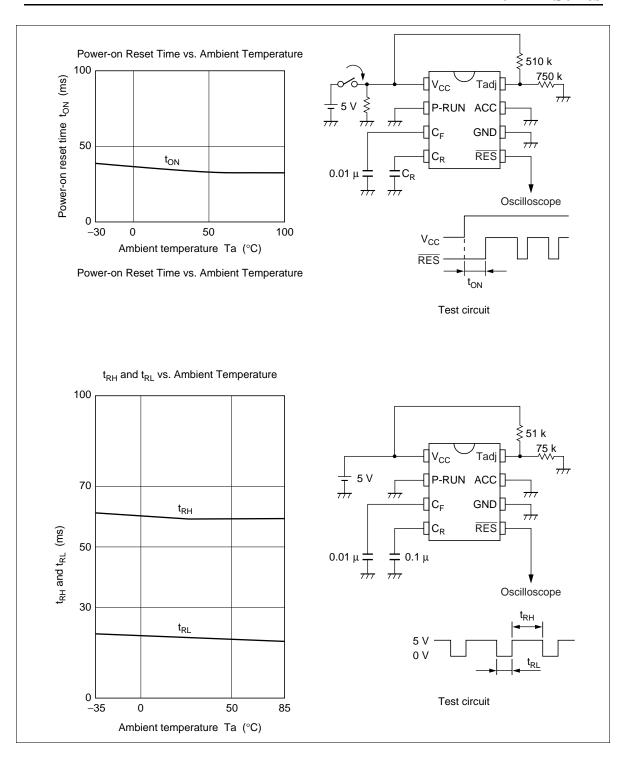
#### P-RUN Input Frequency vs. Ambient Temperature



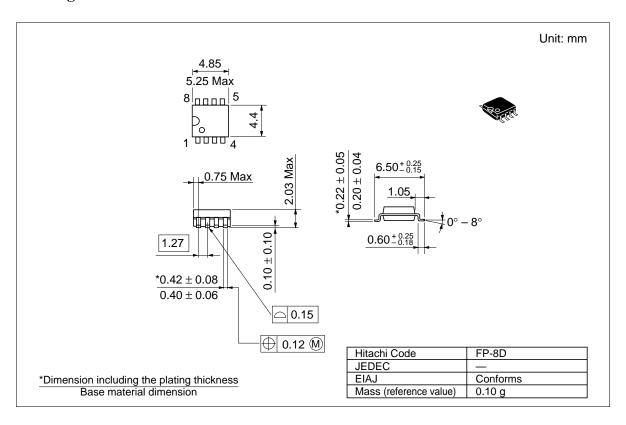


Notes: 1. Normal detection is assumed when  $\overline{\text{RES}}$  is not output.

2. The figure at left is for a constant P-RUN frequency.



## **Package Dimensions**



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