

SYNCHRONOUS SRAM

64K x 18 SRAM

+3.3V SUPPLY, PIPELINED AND
SELECTABLE BURST MODE

SYNCHRONOUS PIPELINED SRAM

FEATURES

- Fast access times: 4.5, 5, 6, 7 and 8ns
- Fast \overline{OE} access time: 5 and 6ns
- Single +3.3V $\pm 5\%$ power supply
- 5V-tolerant I/O
- SNOOZE MODE for reduced power standby*
- Common data inputs and data outputs
- Individual BYTE WRITE control and GLOBAL WRITE*
- Three chip enables for simple depth expansion and address pipelining*
- Clock controlled, registered, address, data I/O and control for fully pipelined applications
- Internally self-timed WRITE cycle
- WRITE pass-through capability
- Burst control pin (interleaved or linear burst)*
- Automatic power-down for portable applications
- High density, high speed packages
- Low capacitive bus loading
- High 30pF output drive capability at rated access time
- DIMMs also available

OPTIONS

- Timing

4.5ns access/8ns cycle	-4.5
5ns access/10ns cycle	-5
6ns access/12ns cycle	-6
7ns access/15ns cycle	-7
8ns access/20ns cycle	-8
- Packages

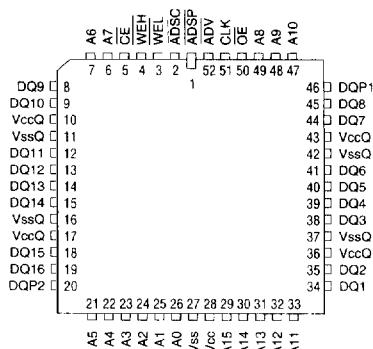
52-pin PLCC	EJ
100-pin TQFP	LG
- Low power P
- 2V data retention, low power L
- Part Number Example: MT58LC64K18C4LG-7 P

*TQFP package only

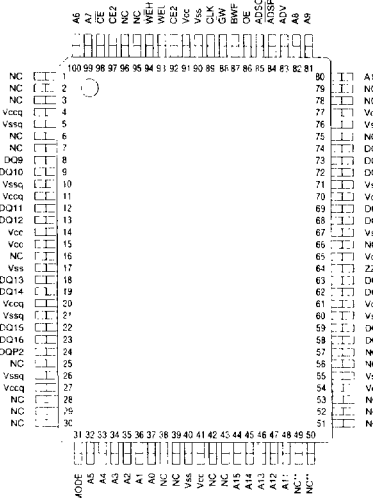
MARKING

PIN ASSIGNMENT (Top View)

52-Pin PLCC (SA-1)



100-Pin TQFP (SB-1)



**Pin 49 is reserved for A16, pin 50 for A17

GENERAL DESCRIPTION

The Micron SyncBurst™ SRAM family employs high-speed, low-power CMOS designs using a four-transistor memory cell. Micron SRAMs are fabricated using an advanced CMOS process.

The MT58LC64K18 SRAM integrates a 64K x 18 SRAM core with advanced synchronous peripheral circuitry and a 2-bit burst counter. All synchronous inputs pass through registers controlled by a positive-edge-triggered single clock input (CLK). The synchronous inputs include all addresses, all data inputs, active LOW chip enable (\overline{CE}), two additional chip enables for easy depth expansion ($\overline{CE2}$, $\overline{CE2}$), burst control inputs (\overline{ADSC} , \overline{ADSP} , \overline{ADV}), byte write enables (\overline{WEH} , \overline{WEL} , \overline{BWE}) and global write (\overline{GW}).

Asynchronous inputs include the output enable (\overline{OE}), clock (CLK), snooze enable (\overline{ZZ}) and burst mode (MODE). The data-out (Q), enabled by \overline{OE} , is also asynchronous. WRITE cycles can be from 1 to 2 bytes wide as controlled by the write control inputs.

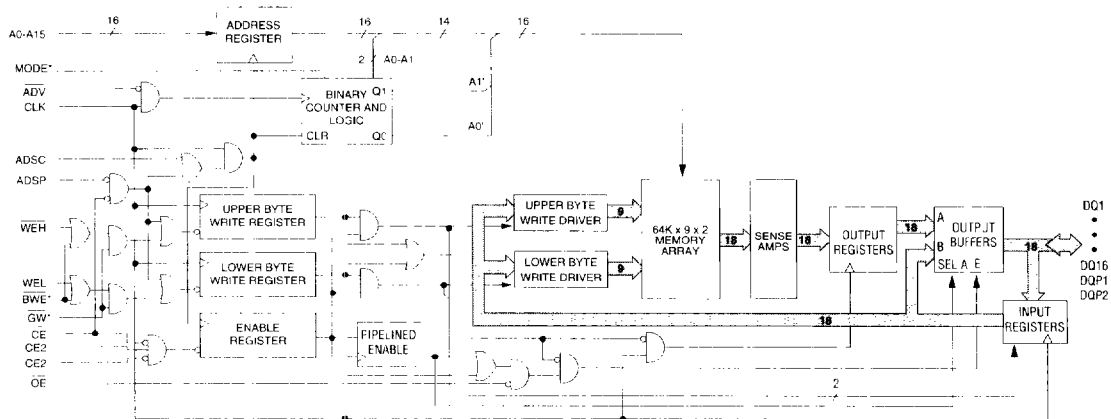
Burst operation can be initiated with either address status processor (\overline{ADSP}) or address status controller (\overline{ADSC}) input pins. Subsequent burst addresses can be internally generated as controlled by the burst advance pin (\overline{ADV}).

Address and write control are registered on-chip to simplify WRITE cycles. This allows self-timed WRITE cycles. Individual byte enables allow individual bytes to be written. \overline{WEL} controls DQ1-DQ8 and DQP1. \overline{WEH} controls DQ9-DQ16 and DQP2, conditioned by \overline{BWE} being LOW. \overline{GW} LOW causes all bytes to be written. WRITE pass-through makes written data immediately available at the output register during the READ cycle following a WRITE as controlled solely by \overline{OE} to improve cache system response. The device incorporates an additional pipelined enable register to allow depth expansion without penalizing system performance.

The "L" version of this device has a data retention option which is useful for battery backup mode of operation. Although the part is not guaranteed to operate functionally below $V_{CC\ MIN}$ (3.1V), it will retain data with a minimum of power dissipation.

The MT58LC64K18 operates from a +3.3V power supply and all inputs and outputs are TTL-compatible and 5V-tolerant. The device is ideally suited for Pentium™ and PowerPC™ pipelined systems and systems that benefit from a very wide high-speed data bus. The device is also ideal in generic 18-, 36- and 72-bit-wide applications.

FUNCTIONAL BLOCK DIAGRAM



*LG package only

NOTE: 1. The Functional Block Diagram illustrates simplified device operation. See Truth Table, Pin Descriptions and timing diagrams for detailed information.

PIN DESCRIPTIONS

PLCC PINS	TQFP PINS	SYMBOL	TYPE	DESCRIPTION
26, 25, 24, 23, 22, 21, 7, 6, 49, 48, 47, 33, 32, 31, 30, 29	37, 36, 35, 34, 33, 32, 100, 99, 82, 81, 80, 48, 47, 46, 45, 44	A0-A15	Input	Synchronous Address Inputs: These inputs are registered and must meet the setup and hold times around the rising edge of CLK.
4, 3	94, 93	WEH, WEL	Input	Synchronous Byte Write Enables: These active LOW inputs allow individual bytes to be written and must meet the setup and hold times around the rising edge of CLK. A byte write enable is LOW for a WRITE cycle and HIGH for a READ cycle. WEL controls DQ1-DQ8 and DQP1. WEH controls DQ9-DQ16 and DQP2. Data I/O are tristated if either of these inputs are LOW.
n/a	87	BWE	Input	Byte Write Enable: This active LOW input permits byte write operations and must meet the setup and hold times around the rising edge of CLK.
n/a	88	GW	Input	Global Write: This active LOW input allows a full 18-bit WRITE to occur independent of the BWE and WEN lines and must meet the setup and hold times around the rising edge of CLK.
51	89	CLK	Input	Clock: This signal registers the address, data, chip enable, byte write enables and burst control inputs on its rising edge. All synchronous inputs must meet setup and hold times around the clock's rising edge.
5	98	CE	Input	Synchronous Chip Enable: This active LOW input is used to enable the device and conditions internal use of ADSP. This input is sampled only when a new external address is loaded.
n/a	92	CE2	Input	Synchronous Chip Enable: This active LOW input is used to enable the device. This input is sampled only when a new external address is loaded.
n/a	64	ZZ	Input	Snooze Enable: This active HIGH asynchronous input causes the device to enter a low-power standby mode in which all data in the memory array is retained.
n/a	97	CE2	Input	Synchronous Chip Enable: This active HIGH input is used to enable the device. This input is sampled only when a new external address is loaded.
50	86	OE	Input	Output Enable: This active LOW asynchronous input enables the data I/O output drivers.
52	83	ADV	Input	Synchronous Address Advance: This active LOW input is used to advance the internal burst counter, controlling burst access after the external address is loaded. A HIGH on this pin effectively causes wait states to be generated (no address advance). This pin must be HIGH at the rising edge of the first clock after an ADSP cycle is initiated if a WRITE cycle is desired (to ensure use of correct address).

PIN DESCRIPTIONS (continued)

PLCC PINS	TQFP PINS	SYMBOL	TYPE	DESCRIPTION
1	84	ADSP	Input	Synchronous Address Status Processor: This active LOW input interrupts any ongoing burst, causing a new external address to be registered. A READ is performed using the new address, independent of the byte write enables and ADSC but dependent upon CE being LOW.
2	85	ADSC	Input	Synchronous Address Status Controller: This active LOW input interrupts any ongoing burst, causing a new external address to be registered. A READ or WRITE is performed using the new address if \overline{CE} is LOW. ADSC is also used to place the chip into power-down state when \overline{CE} is HIGH.
n/a	31	MODE	Input	Mode: This input selects the burst sequence. A LOW on this pin selects LINEAR BURST. A NC or HIGH on this pin selects INTERLEAVED BURST. Do not alter input state while device is operating.
34, 35, 38, 39, 40, 41, 44, 45, 8, 9, 12, 13, 14, 15, 18, 19	58, 59, 62, 63, 68, 69, 72, 73, 8, 9, 12, 13, 18, 19, 22, 23	DQ1-DQ16	Input/Output	SRAM Data I/O: Low Byte is DQ1-DQ8. High Byte is DQ9-DQ16. Input data must meet setup and hold times around the rising edge of CLK.
46, 20	74, 24	DQP1, DQP2	Input/Output	Parity Data I/O: Low Byte Parity is DQP1. High Byte Parity is DQP2.
10, 17, 28, 36, 43	4, 11, 14, 15, 20, 27, 41, 54, 61, 65, 70, 77, 91	Vcc	Supply	Power Supply: +3.3V $\pm 5\%$
11, 16, 27, 37, 42	5, 10, 17, 21, 26, 40, 55, 60, 71, 76, 67, 90	Vss	Supply	Ground: GND
	1, 2, 3, 6, 7, 16, 25, 28, 29, 30, 38*, 39*, 42*, 43*, 49, 50, 51, 52, 53, 56, 57, 66, 75, 78, 79, 95, 96	NC	-	No Connect: These signals are not internally connected. These signals may be connected to ground to improve package heat dissipation.

*These pins are reserved as DNU pins (Do Not Use) on the 2 Meg and 4 Meg versions of the SyncBurst family. It is recommended that these pins be left unconnected in any designs to allow for future upgradability.

BURST ADDRESS TABLE (MODE = NC OR HIGH)

First Address (external)	Second Address (internal)	Third Address (internal)	Fourth Address (internal)
X...X00	X...X01	X...X10	X...X11
X...X01	X...X00	X...X11	X...X10
X...X10	X...X11	X...X00	X...X01
X...X11	X...X10	X...X01	X...X00

BURST ADDRESS TABLE (MODE = GND)

First Address (external)	Second Address (internal)	Third Address (internal)	Fourth Address (internal)
X...X00	X...X01	X...X10	X...X11
X...X01	X...X10	X...X11	X...X00
X...X10	X...X11	X...X00	X...X01
X...X11	X...X00	X...X01	X...X10

PARTIAL TRUTH TABLE FOR WRITE COMMANDS

Function	GW	BWE	WEL	WEH
READ	H	H	X	X
READ	H	L	H	H
WRITE Low Byte	H	L	L	H
WRITE High Byte	H	L	H	L
WRITE all bytes	H	L	L	L
WRITE all bytes	L	X	X	X

PASS-THROUGH TRUTH TABLE

PREVIOUS CYCLE ¹		PRESENT CYCLE				NEXT CYCLE
OPERATION	Wes	OPERATION	CE	Wes	OE	OPERATION
Initiate WRITE cycle, all bytes Address = A(n-1), data = D(n-1)	All L ^{2,3}	Initiate READ cycle Register A(n), Q = D(n-1)	L	H	L	Read D(n)
Initiate WRITE cycle, all bytes Address = A(n-1), data = D(n-1)	All L ^{2,3}	No new cycle Q = D(n-1)	H	H	L	No carry-over from previous cycle
Initiate WRITE cycle, all bytes Address = A(n-1), data = D(n-1)	All L ^{2,3}	No new cycle Q = HIGH-Z	H	H	H	No carry-over from previous cycle
Initiate WRITE cycle, one byte Address = A(n-1), data = D(n-1)	One L ²	No new cycle Q = D(n-1) for one byte	H	H	L	No carry-over from previous cycle

- NOTE:**
1. Previous cycle may be either BURST or NONBURST cycle.
 2. BWE is LOW when one or two WEn is LOW.
 3. GW LOW will yield identical results.

TRUTH TABLE

SYNCHRONOUS PIPELINED SRAM

OPERATION	ADDRESS USED	CE	CE2	CE2	ZZ	ADSP	ADSC	ADV	WRITE	OE	CLK	DQ
Deselected Cycle, Power-down	None	H	X	X	L	X	L	X	X	X	L-H	High-Z
Deselected Cycle, Power-down	None	L	X	L	L	L	X	X	X	X	L-H	High-Z
Deselected Cycle, Power-down	None	L	H	X	L	L	X	X	X	X	L-H	High-Z
Deselected Cycle, Power-down	None	L	X	L	L	H	L	X	X	X	L-H	High-Z
Deselected Cycle, Power-down	None	L	H	X	L	H	L	X	X	X	L-H	High-Z
SNOOZE MODE, Power-down	None	X	X	X	H	X	X	X	X	X	X	High-Z
READ Cycle, Begin Burst	External	L	L	H	L	L	X	X	X	L	L-H	Q
READ Cycle, Begin Burst	External	L	L	H	L	L	X	X	X	H	L-H	High-Z
WRITE Cycle, Begin Burst	External	L	L	H	L	H	L	X	L	X	L-H	D
READ Cycle, Begin Burst	External	L	L	H	L	H	L	X	H	L	L-H	Q
READ Cycle, Begin Burst	External	L	L	H	L	H	L	X	H	H	L-H	High-Z
READ Cycle, Continue Burst	Next	X	X	X	L	H	H	L	H	L	L-H	Q
READ Cycle, Continue Burst	Next	X	X	X	L	H	H	L	H	H	L-H	High-Z
READ Cycle, Continue Burst	Next	H	X	X	L	X	H	L	H	L	L-H	Q
READ Cycle, Continue Burst	Next	H	X	X	L	X	H	L	H	H	L-H	High-Z
WRITE Cycle, Continue Burst	Next	X	X	X	L	H	H	L	L	X	L-H	D
WRITE Cycle, Continue Burst	Next	H	X	X	L	X	H	L	L	X	L-H	D
READ Cycle, Suspend Burst	Current	X	X	X	L	H	H	H	H	L	L-H	Q
READ Cycle, Suspend Burst	Current	X	X	X	L	H	H	H	H	H	L-H	High-Z
READ Cycle, Suspend Burst	Current	H	X	X	L	X	H	H	H	L	L-H	Q
READ Cycle, Suspend Burst	Current	H	X	X	L	X	H	H	H	H	L-H	High-Z
WRITE Cycle, Suspend Burst	Current	X	X	X	L	H	H	H	L	X	L-H	D
WRITE Cycle, Suspend Burst	Current	H	X	X	L	X	H	H	L	X	L-H	D

- NOTE:**
1. X means "don't care." H means logic HIGH. L means logic LOW. $\overline{\text{WRITE}}=\text{L}$ means any one or more byte write enable signals ($\overline{\text{WEL}}$ or $\overline{\text{WEH}}$) and $\overline{\text{BWE}}$ are LOW or $\overline{\text{GW}}$ is LOW. $\overline{\text{WRITE}}=\text{H}$ means all byte write enable signals are HIGH.
 2. $\overline{\text{WEL}}$ enables WRITES to DQ1-DQ8, DQP1. $\overline{\text{WEH}}$ enables WRITES to DQ9-DQ16, DQP2.
 3. All inputs except $\overline{\text{OE}}$ must meet setup and hold times around the rising edge (LOW to HIGH) of CLK.
 4. Wait states are inserted by suspending burst.
 5. For a WRITE operation following a READ operation, $\overline{\text{OE}}$ must be HIGH before the input data required setup time and held HIGH throughout the input data hold time.
 6. This device contains circuitry that will ensure the outputs will be in High-Z during power-up.
 7. ADSP LOW always initiates an internal READ at the L-H edge of CLK. A WRITE is performed by setting one or more byte write enable signals and $\overline{\text{BWE}}$ LOW or $\overline{\text{GW}}$ LOW for the subsequent L-H edge of CLK. Refer to WRITE timing diagram for clarification.

ABSOLUTE MAXIMUM RATINGS*

Voltage on V _{CC} Supply Relative to V _{SS}	-0.5V to +4.6V
V _{IN}	-0.5V to +6V
Storage Temperature (plastic)	-55°C to +150°C
Junction Temperature**	+150°C
Short Circuit Output Current	100mA

*Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

**Maximum junction temperature depends upon package type, cycle time, loading, ambient temperature and airflow. See technical note TN-05-14 for more information.

ELECTRICAL CHARACTERISTICS AND RECOMMENDED DC OPERATING CONDITIONS

(0°C ≤ T_A ≤ 70°C; V_{CC} = +3.3V ±5% unless otherwise noted)

DESCRIPTION	CONDITIONS	SYMBOL	MIN	MAX	UNITS	NOTES
Input High (Logic 1) Voltage		V _{IH}	2.0	5.5	V	1, 2
Input High (Logic 1) Voltage	For MODE and ZZ	V _{IH}	2.4	5.5	V	1, 2
Input Low (Logic 0) Voltage		V _{IL}	-0.3	0.8	V	1, 2
Input Leakage Current	0V ≤ V _{IN} ≤ V _{CC}	I _{LI}	-1	1	μA	14
Output Leakage Current	Output(s) disabled, 0V ≤ V _{OUT} ≤ V _{CC}	I _{LO}	-1	1	μA	
Output High Voltage	I _{OH} = -4.0mA	V _{OH}	2.4		V	1, 11, 17
Output Low Voltage	I _{OL} = 8.0mA	V _{OL}		0.4	V	1, 11
Supply Voltage		V _{CC}	3.135	3.465	V	1

DESCRIPTION	CONDITIONS	SYM	VER	TYP	MAX					UNITS	NOTES
					-4.5	-5	-6	-7	-8		
Power Supply Current: Operating	Device selected; all inputs ≤ V _{IL} or ≥ V _{IH} ; cycle time ≥ 1KC MIN; V _{CC} = MAX; outputs open	I _{CC}	ALL	180	400	335	300	250	210	mA	3, 12, 13
Power Supply Current: Idle	Device selected; V _{CC} = MAX; ADSC, ADSP, GW, BWS, ADV ≥ V _{IH} ; all inputs ≤ V _{SS} +0.2 or ≥ V _{CC} -0.2; cycle time ≥ 1KC MIN	I _{CC1}	ALL	30	70	65	60	55	45	mA	12, 13
CMOS Standby	Device deselected; V _{CC} = MAX; all inputs ≤ V _{SS} +0.2 or ≥ V _{CC} -0.2; all inputs static; CLK frequency = 0	I _{SB2}	STD	0.5	5	5	5	5	5	mA	12, 13
			P	0.2	2	2	2	2	2	mA	
TTL Standby	Device deselected; V _{CC} = MAX; all inputs ≤ V _{IL} or ≥ V _{IH} ; all inputs static; CLK frequency = 0	I _{SB3}	STD	15	25	25	25	25	25	mA	12, 13
			P	8	18	18	18	18	18	mA	
Clock Running	Device deselected; V _{CC} = MAX; all inputs ≤ V _{SS} +0.2 or ≥ V _{CC} -0.2; CLK cycle time ≥ 1KC MIN	I _{SB4}	ALL	30	70	65	60	55	45	mA	12, 13

CAPACITANCE

DESCRIPTION	CONDITIONS	SYMBOL	TYP	MAX	UNITS	NOTES
Control Input Capacitance	$T_A = 25^\circ\text{C}; f = 1\text{ MHz}$ $V_{CC} = 3.3\text{V}$	C_i	3	4	pF	4
Input/Output Capacitance (DQ)		C_o	6	8	pF	4
Address and Clock Input Capacitance		C_A	2.5	3	pF	4

THERMAL CONSIDERATIONS

DESCRIPTION	CONDITIONS	SYMBOL	PLCC TYP	TQFP TYP	UNITS	NOTES
Thermal resistance - Junction to Ambient	Still air, soldered on 4.25 x 1.125 inch 4-layer PCB	θ_{JA}	45	20	$^\circ\text{C/W}$	
Thermal resistance - Junction to Case		θ_{JC}	15	1	$^\circ\text{C/W}$	

ELECTRICAL CHARACTERISTICS AND RECOMMENDED AC OPERATING CONDITIONS

(Note 5) ($0^\circ\text{C} \leq T_A \leq 70^\circ\text{C}; V_{CC} = +3.3\text{V} \pm 5\%$)

DESCRIPTION			-4.5		-5		-6		-7		-8		UNITS	NOTES
	SYM	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX			
Clock														
Clock cycle time	¹ KC	8		10		12		15		20		ns		
Clock HIGH time	¹ KH	3		4		4.5		5		6		ns		
Clock LOW time	¹ KL	3		4		4.5		5		6		ns		
Output Times														
Clock to output valid	¹ KQ		4.5		5		6		7		8	ns		
Clock to output invalid	¹ KQX	2		2		2		2		2		ns		
Clock to output in Low-Z	¹ KQLZ	2		2		2		2		2		ns	4, 6, 7	
Clock to output in High-Z	¹ KQHZ		4.5		5		5		6		6	ns	4, 6, 7	
$\overline{\text{OE}}$ to output valid	¹ OEQ		4.5		5		5		5		6	ns	9	
$\overline{\text{OE}}$ to output in Low-Z	¹ OELZ	0		0		0		0		0		ns	4, 6, 7	
$\overline{\text{OE}}$ to output in High-Z	¹ OEHZ		3		4		5		6		6	ns	4, 6, 7	
Setup Times														
Address	¹ AS	2.5		2.5		2.5		2.5		3.5		ns	8, 10	
Address Status (ADSC, ADSP)	¹ ADSS	2.5		2.5		2.5		2.5		3.5		ns	8, 10	
Address Advance (ADV)	¹ AAS	2.5		2.5		2.5		2.5		3.5		ns	8, 10	
Write Signals (WEL, WEH, BWE, GW)	¹ WS	2.5		2.5		2.5		2.5		3.5		ns	8, 10	
Data-in	¹ DS	2.5		2.5		2.5		2.5		3.5		ns	8, 10	
Chip Enables ($\overline{\text{CE}}$, $\overline{\text{CE2}}$, CE2)	¹ CES	2.5		2.5		2.5		2.5		3.5		ns	8, 10	
Hold Times														
Address	¹ AH	0.5		0.5		0.5		0.5		0.8		ns	8, 10	
Address Status (ADSC, ADSP)	¹ ADSH	0.5		0.5		0.5		0.5		0.8		ns	8, 10	
Address Advance (ADV)	¹ AAH	0.5		0.5		0.5		0.5		0.8		ns	8, 10	
Write Signals (WEL, WEH, BWE, GW)	¹ WH	0.5		0.5		0.5		0.5		0.8		ns	8, 10	
Data-in	¹ DH	0.5		0.5		0.5		0.5		0.8		ns	8, 10	
Chip Enables ($\overline{\text{CE}}$, $\overline{\text{CE2}}$, CE2)	¹ CEH	0.5		0.5		0.5		0.5		0.8		ns	8, 10	

AC TEST CONDITIONS

Input pulse levels	V _{SS} to 3.0V
Input rise and fall times	2.5ns
Input timing reference levels	1.5V
Output reference levels	1.5V
Output load	See Figures 1 and 2

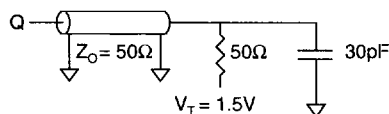


Fig. 1 OUTPUT LOAD EQUIVALENT

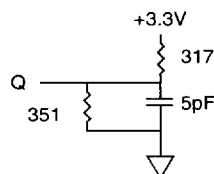


Fig. 2 OUTPUT LOAD EQUIVALENT

NOTES

1. All voltages referenced to V_{SS} (GND).
2. Overshoot: V_{IH} ≤ +6.0V for t ≤ t_{KC} / 2.
Undershoot: V_{IL} ≥ -2.0V for t ≤ t_{KC} / 2.
Power-up: V_{IH} ≤ +6.0V and V_{CC} ≤ 3.135V for t ≤ 200ms.
3. I_{CC} is given with no output current. I_{CC} increases with greater output loading and faster cycle times.
4. This parameter is sampled.
5. Test conditions as specified with the output loading as shown in Fig. 1 unless otherwise noted.
6. Output loading is specified with C_L = 5pF as in Fig. 2. Transition is measured ±500mV from steady state voltage.
7. At any given temperature and voltage condition, t_{KQHZ} is less than t_{KQLZ} and t_{OEHZ} is less than t_{OELZ}.
8. A WRITE cycle is defined by at least one byte write enable LOW and ADSP HIGH for the required setup and hold times. A READ cycle is defined by all byte write enables HIGH and (ADSC or ADV LOW) or ADSP LOW for the required setup and hold times.
9. OE is a "don't care" when a byte write enable is sampled LOW.
10. This is a synchronous device. All addresses must meet the specified setup and hold times for all rising

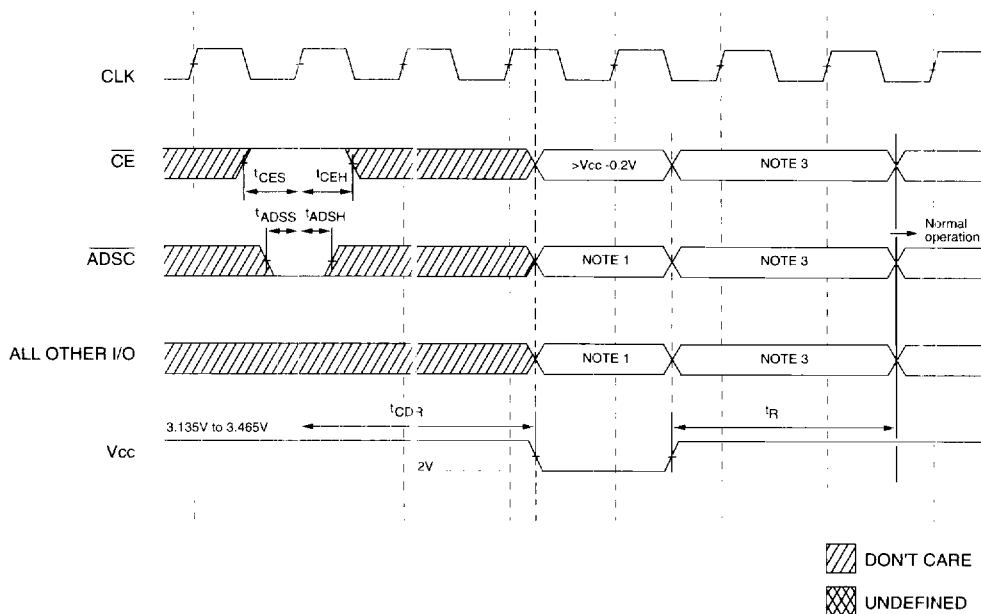
edges of CLK when either ADSP or ADSC is LOW and chip enabled. All other synchronous inputs must meet the setup and hold times with stable logic levels for all rising edges of clock (CLK) when the chip is enabled. Chip enable must be valid at each rising edge of CLK (when either ADSP or ADSC is LOW) to remain enabled.

11. The load used for V_{OH}, V_{OL} testing is shown in Fig. 2. AC load current is higher than the shown DC values. AC I/O curves are available upon request.
12. "Device Deselected" means device is in POWER-DOWN mode as defined in the Truth Table. "Device Selected" means device is active (not in POWER-DOWN mode).
13. Typical values are measured at 3.3V, 25°C and 20ns cycle time.
14. MODE pin has an internal pull-up and exhibits an input leakage current of ±10μA.
15. Typical values are measured at 25°C.
16. The device must have a deselect cycle applied at least two clock cycles before data retention mode is entered.
17. DQs are guaranteed to meet V_{OH} MIN for up to 10ms after outputs become static.

DATA RETENTION ELECTRICAL CHARACTERISTICS (L version only)

DESCRIPTION	CONDITIONS	SYMBOL	MIN	MAX	UNITS	NOTES
V _{CC} for Retention Data		V _{DR}	2		V	
Data Retention Current Method 1	$\overline{CE}, \overline{CE2} \geq (V_{CC} - 0.2V), \overline{CE2} \leq 0.2V$ $V_{IN} \geq (V_{CC} - 0.2V) \text{ or } \leq 0.2V$ $V_{CC} = 2V, ZZ \leq 0.2V$	I _{CCDR}		TBD	μA	15
Data Retention Current Method 2	$ZZ \geq V_{CC} - 0.2V$ $V_{CC} = 2V$	I _{CCDR}		TBD	μA	15
Chip Deselect to Data Retention Time		t _{CDR}	2(μs)		ns	4, 16
Operation Recovery Time		t _R		2(μs)	ns	4

LOW V_{CC} DATA RETENTION WAVEFORM



- NOTE:**
1. If ZZ is inactive ($ZZ \leq 0.2V$), $\overline{CE} > V_{CC} - 0.2V$ and other inputs must be $\geq V_{CC} - 0.2V$ or $\leq 0.2V$ to guarantee I_{CCDR} in data retention mode. If inputs are between these levels or left floating, I_{CCDR} may be exceeded. If ZZ is active ($ZZ \geq V_{CC} - 0.2V$), then this restriction on input may be ignored.
 2. Only one of the available deselect cycle sequences is shown above ($\overline{CE} = \text{HIGH}, \overline{ADSC} = \text{LOW}$). Any of the other deselect cycle sequences may also be used.
 3. The device control signals should be in a deselect state between the rising edge of V_{CC} and until t_R is met.
 4. All inputs must be $\leq V_{CC} + 2V$ while the device is in data retention mode.

SNOOZE MODE

SNOOZE MODE is a low current, "power down" mode in which the device is deselected and current is reduced to I_{SB2} . The duration of SNOOZE MODE is dictated by the length of time the ZZ pin is in a HIGH state. After entering SNOOZE MODE, the clock and all other inputs are ignored.

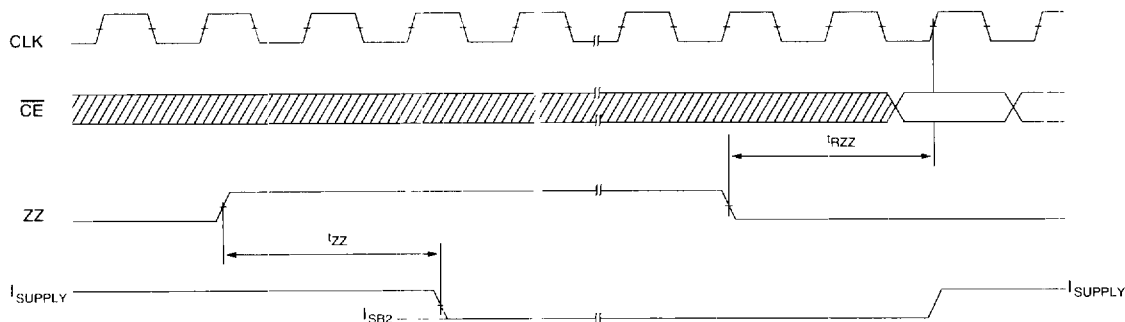
The ZZ pin (pin 64) is an asynchronous, active HIGH input that causes the device to enter SNOOZE MODE.

When the ZZ pin becomes a logic HIGH, I_{SB2} is guaranteed after the setup time t_{ZZ} is met. Any access pending when entering SNOOZE MODE is not guaranteed to successfully complete. Therefore, SNOOZE MODE must not be initiated until valid pending operations are completed.

SNOOZE MODE ELECTRICAL CHARACTERISTICS

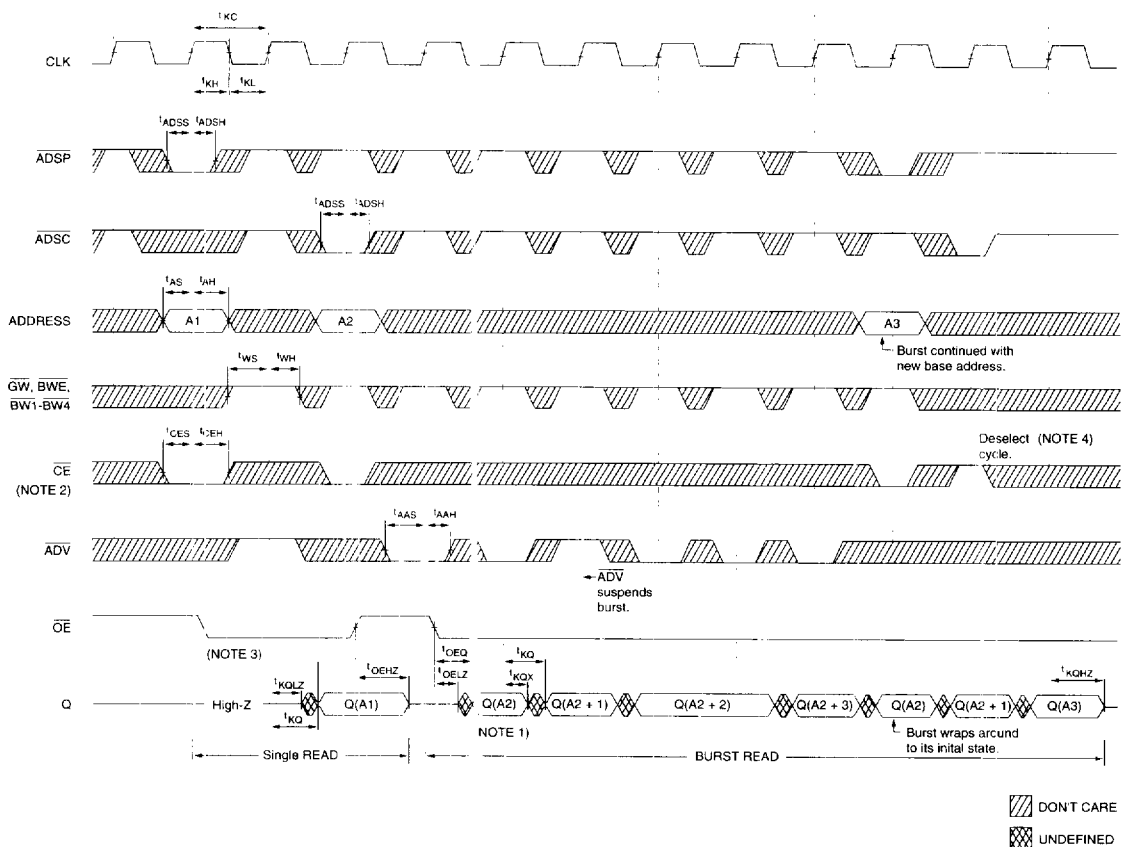
DESCRIPTION	CONDITIONS	SYMBOL	MIN	MAX	UNITS	NOTES
Current during SNOOZE MODE	$ZZ \geq V_{IH}$	I_{SB2}		5	mA	
Current during SNOOZE MODE (P Version)	$ZZ \geq V_{IH}$	I_{SB2}		2	mA	
ZZ HIGH to SNOOZE MODE time		t_{ZZ}	$2(t_{KC})$		ns	4
SNOOZE MODE Operation Recovery Time		t_{RZZ}		$2(t_{KC})$	ns	4

SNOOZE MODE WAVEFORM



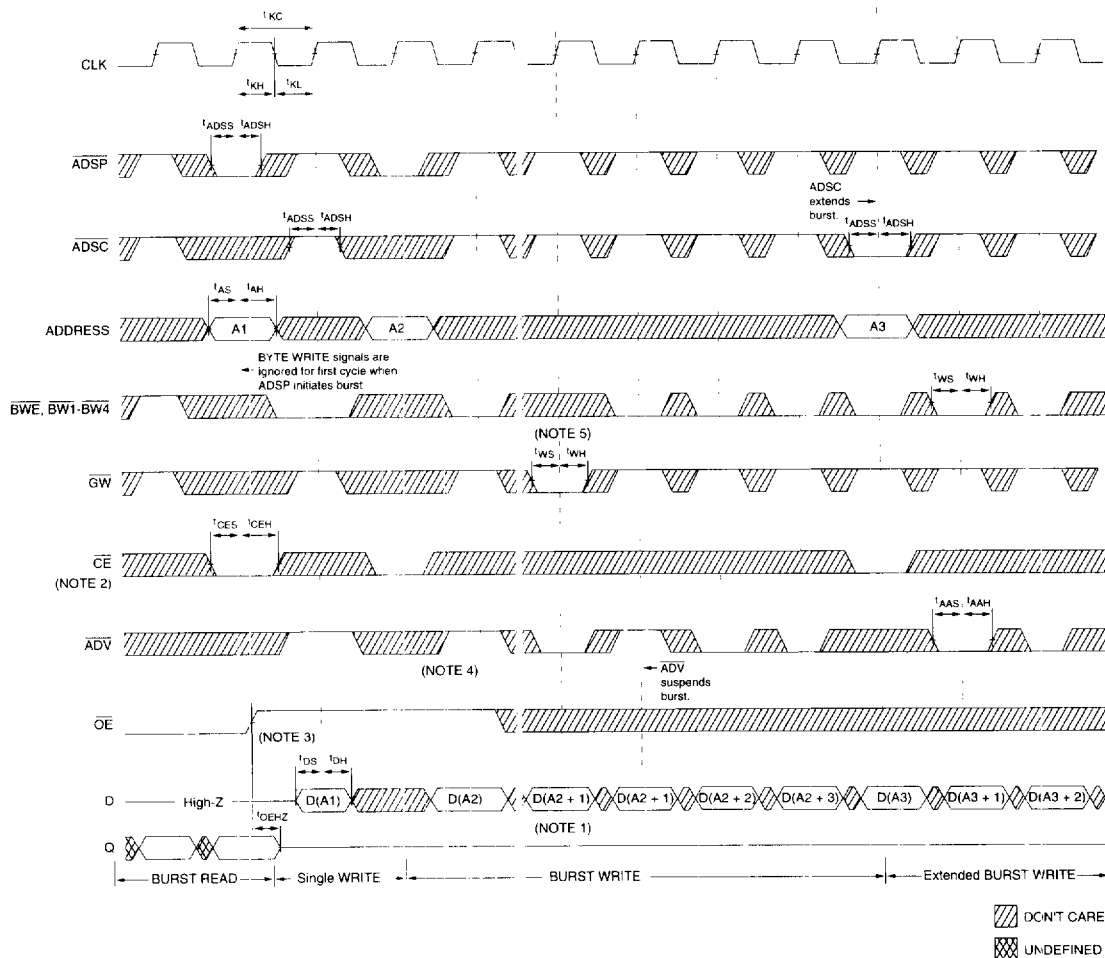
NOTE: 1. The \overline{CE} signal shown above refers to a TRUE state on all chip selects for the device.

READ TIMING



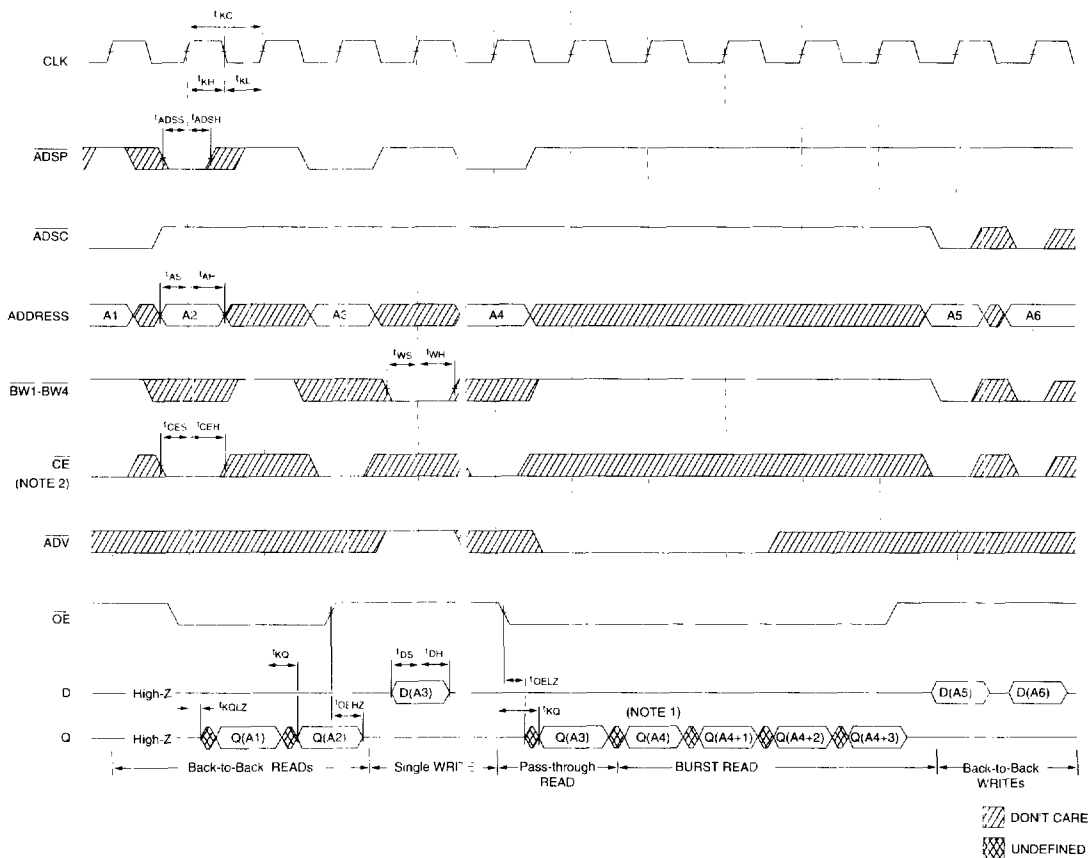
- NOTE:**
1. Q(A2) refers to output from address A2. Q(A2+1) refers to output from the next internal burst address following A2.
 2. $\overline{CE2}$ and CE2 have timing identical to \overline{CE} . On this diagram, when \overline{CE} is LOW, $\overline{CE2}$ is LOW and CE2 is HIGH. When \overline{CE} is HIGH, $\overline{CE2}$ is HIGH and CE2 is LOW.
 3. Timing is shown assuming that the device was not enabled before entering into this sequence. \overline{OE} does not cause Q to be driven until after the following clock rising edge.
 4. Outputs are disabled within two clock cycles after deselect.

WRITE TIMING



- NOTE:**
1. D(A2) refers to input for address A2. D(A2+1) refers to input for the next internal burst address following A2.
 2. $\overline{CE2}$ and CE2 have timing identical to $\overline{CE1}$. On this diagram, when $\overline{CE1}$ is LOW, $\overline{CE2}$ is LOW and CE2 is HIGH. When $\overline{CE1}$ is HIGH, $\overline{CE2}$ is HIGH and CE2 is LOW.
 3. \overline{OE} must be HIGH before the input data set up and held HIGH throughout the data hold time. This prevents input/output data contention for the time period prior to the byte write enable inputs being sampled.
 4. \overline{ADV} must be HIGH to permit a WRITE to the loaded address.
 5. Full width WRITE can be initiated by \overline{GW} LOW or \overline{GW} HIGH and \overline{BWE} , $\overline{WE1}$ and \overline{WEH} LOW.

READ/WRITE TIMING



- NOTE:**
1. Q(A4) refers to output from address A4 Q(A4+1) refers to output from the next internal burst address following A4.
 2. $\overline{CE2}$ and CE2 have timing identical to \overline{CE} . On this diagram, when \overline{CE} is LOW, $\overline{CE2}$ is LOW and CE2 is HIGH. When CE is HIGH, $\overline{CE2}$ is HIGH and CE2 is LOW.
 3. The data bus (Q) remains in High-Z following a WRITE cycle unless an \overline{ADSP} , \overline{ADSC} or \overline{ADV} cycle is performed.
 4. \overline{GW} is HIGH.
 5. Back-to-back READS may be controlled by either \overline{ADSP} or \overline{ADSC} .

APPLICATION INFORMATION

LOAD DERATING CURVES

The Micron 64K x 18 Synchronous SRAM timing is dependent upon the capacitive loading on the outputs. The data sheet is written assuming a load of 30pF. Access time change with load capacitance as follows:

$$\Delta t_{KQ} = 0.016 \text{ ns/pF} \times \Delta C_L \text{ pF}$$

(Note: this is preliminary information subject to change.)

For example, if the SRAM loading is 22pF, ΔC_L is -8pF (8pF less than rated load). The clock to valid output time of the SRAM is reduced by $0.016 \times 8 = 0.128\text{ns}$. If the device is an 8ns part, the worst case t_{KQ} becomes 7.87ns (approximately).

Consult the factory for copies of I/O current versus voltage curves. For capacitive loading derating curves see technical note TN-05-20, "3.3V SRAM Capacitive Loading."