



RCV420

Precision 4mA to 20mA CURRENT LOOP RECEIVER

FEATURES

- COMPLETE 4-20mA TO 0-5V CONVERSION
- INTERNAL SENSE RESISTORS
- PRECISION 10V REFERENCE
- BUILT-IN LEVEL-SHIFTING
- ±40V COMMON-MODE INPUT RANGE
- 0.1% OVERALL CONVERSION ACCURACY
- HIGH NOISE IMMUNITY: 86dB CMR

DESCRIPTION

The RCV420 is a precision current-loop receiver designed to convert a 4–20mA input signal into a 0–5V output signal. As a monolithic circuit, it offers high reliability at low cost. The circuit consists of a premium grade operational amplifier, an on-chip precision resistor network, and a precision 10V reference. The RCV420 features 0.1% overall conversion accuracy, 86dB CMR, and ±40V common-mode input range.

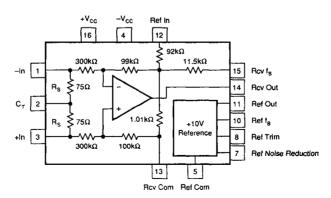
The circuit introduces only a 1.5V drop at full scale, which is useful in loops containing extra instrument burdens or in intrinsically safe applications where

APPLICATIONS

- PROCESS CONTROL
- INDUSTRIAL CONTROL
- FACTORY AUTOMATION
- DATA ACQUISITION
- SCADA
- RTUs
- ESD
- MACHINE MONITORING

transmitter compliance voltage is at a premium. The 10V reference provides a precise 10V output with a typical drift of 5ppm/°C.

The RCV420 is completely self-contained and offers a highly versatile function. No adjustments are needed for gain, offset, or CMR. This provides three important advantages over discrete, board-level designs: 1) lower initial design cost, 2) lower manufacturing cost, and 3) easy, cost-effective field repair of a precision circuit.



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SPECIFICATIONS

ELECTRICAL

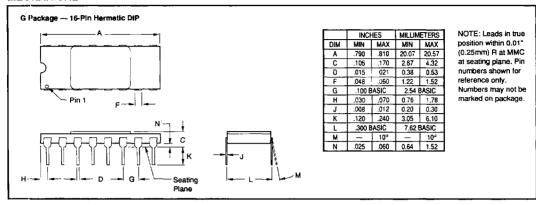
T = +25°C and $\pm V_{cc} \approx \pm 15$ V unless otherwise noted.

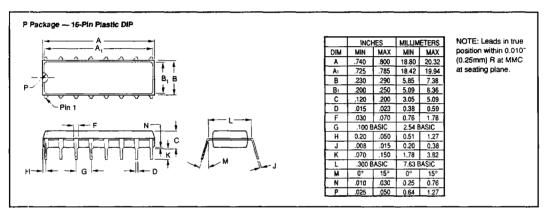
	RCV420AG			RCV420BG		RCV420KP				
CHARACTERISTICS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	UNITS
GAIN Initial Error vs Temp Nonlinearity''		0.3125 0.025 15 0.0002	0.1 50 0.002		:	0.05 25		0.05	0.15	V/mA % of span ppm.∾C % of span
OUTPUT Rated Voltage (I _o = +10mA, -5mA) Rated Current (E _o ≈ 10V) Impedance (Differential) Current Limit (To Common) Capacitive Load (Stable Operation)	10 +10, <i>-</i> 5	12 0.01 +49, -13 1000		:			:	•		V mA Ω mA pF
INPUT Sense Resistance Input Impedance (Common Mode) Common Mode Voltage CMR ¹²⁾ vs Temp (DC) (T _A = T _{Men} to T _{MAX}) AC 60H2	74.25 72 66	75 200 80 76 80	75.75 ±40	86 80	94 90 94	•	70		•	Ω kΩ ∨ dB dB dB
OFFSET VOLTAGE (RTO) (3) Initial vs Temp vs Supply (±11.4V to ±18V) vs Time	74	10 90 200	1 50	80	:	25		:	•	mV μV/°C dB μV/mo
ZERO ERROR ⁴⁾ Initial vs Temp		0.01 10	0.05 50		:	0.025 25		0.025	0.075	% of span ppm of span/°C
OUTPUT NOISE VOLTAGE f _g = 0.1Hz to 10Hz f _o = 10kHz		50 800			•			:		μVp-p nV/\Hz
DYNAMIC RESPONSE Gain Bandwidth Full Power Bandwidth Slew Rate Settling Time (0.01%)		150 30 1.5 10			•			:		kHz kHz V/μs μs
VOLTAGE REFERENCE Initial Trim Range ⁽⁵⁾ vs Temp ⁽⁶⁾ vs Supply (±11.4V to ±18V) vs Output Current (I _o = 0 to +10mA) vs Time Noise (0.1Hz to 10Hz) Output Current	9.995	±4 5 0.0002 0.0002 15 5	10.005		:		9.99		10.01	V % pprn/°C %/V %/mA ppm/kHr µVp-p mA
POWER SUPPLY Rated Voltage Range(*) Quiescent Current (V _o = 0V)	±11.4	±15	±18 4	•		:	•			V V mA
TEMPERATURE RANGE Specification Operation Storage	-25 55 65		+85 +125 +150	:		:	0 25 40		+70 +85 +85	, , ,

^{*}Specification same as RCV420AG.

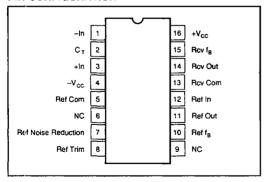
NOTES: (1) Nonlinearity is the max peak deviation from best fit straight line. (2) With 0 source impedance on Rcv Compin. (3) Referred to output with all inputs grounded including Rel In. (4) With 4mA input signal and Voltage Reference connected (includes V_{os}, Gain Error, and Voltage Reference Errors). (5) External trim slightly affects drift. (6) The "box method" is used to specify output voltage drift vs temperature. (7) I_o Rel = 5mA, I_o Rov = 2mA.

MECHANICAL





PIN CONFIGURATION



ABSOLUTE MAXIMUM RATINGS

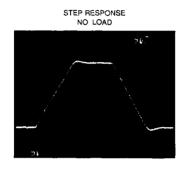
Supply	±22V
Input Current, Continuous	
Input Current Momentary, 0.1s	250mA, 1% Duty Cycle
Common Mode Input Voltage, Continuous	±40V
Lead Temperature (soldering, 10s)	+300°C
Output Short Circuit to Common (Rcv and Ref)	Continuous

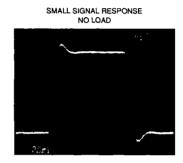
ORDERING INFORMATION

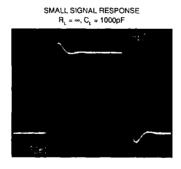
MODEL	PERFORMANCE GRADE	PACKAGE
RCV420AG	-25°C to +85°C	16-Pin Hermetic DIP
RCV420BG	-25°C to +85°C	16-Pin Hermetic DIP
RCV420KP	0°C to +70°C	16-Pin Plastic DIP

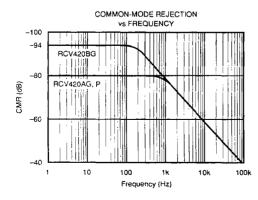
TYPICAL PERFORMANCE CURVES

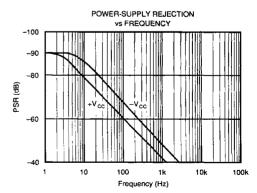
 $\Gamma_{s} = +25$ °C, $\pm V_{cc} = 15$ V unless otherwise noted.











THEORY OF OPERATION

Refer to the figure on the first page. For 0-5V output with 4-20mA input, the required transimpedance of the circuit is:

$$V_{OUT}/I_{IN} = 5V/16mA = 0.3125V/mA$$
.

To achieve the desired output levels, 0V for 4mA and 5V for 20mA, the output of the amplifier must be offset by an amount:

$$V_{os} \approx -(4mA)(0.3125V/mA) = -1.25V.$$

The input current signal is connected to either +In or -In, depending on the polarity of the signal, and returned to ground through the center tap, $C_{\rm T}$. The balanced input—two matched 75 Ω sense resistors, $R_{\rm S}$ —provides maximum rejection of common-mode voltage signals on $C_{\rm T}$ and true differential current-to-voltage conversion. The sense resistors convert the input current signal into a proportional voltage, which is amplified by the differential amplifier. The voltage gain of the amplifier is:

$$A_p = 5V/(16mA)(75\Omega) = 4.1667V/V.$$

The tee network in the feedback path of the amplifier provides a summing junction used to generate the required -1.25V offset voltage. The input resistor network provides high-input impedance and attenuates common-mode input voltages to levels suitable for the operational amplifier's common-mode signal capabilities.

BASIC POWER SUPPLY AND SIGNAL CONNECTIONS

Figure 1 shows the proper connections for power supply and signal. Both supplies should be decoupled with 1μ F tantalum capatitors as close to the amplifier as possible. To avoid gain and CMR errors introduced by the external circuit, connect grounds as indicated, being sure to minimize ground resistance. The input signal should be connected to either +In or -In, Jepending on its polarity, and returned to ground through the center tap, C_T . The output of the voltage reference, Ref Out, should be connected to Ref In for the necessary level

shifting. If the Ref In pin is not used for level shifting, then it must be grounded to maintain high CMR.

GAIN AND OFFSET ADJUSTMENT

Figure 2 shows the circuit for adjusting the RCV420 gain. Increasing the gain of the RCV420 is accomplished by inserting a small resistor in the feedback path of the amplifier. Increasing the gain using this technique results in CMR degradation, and therefore, gain adjustments should be kept as small as possible. For example, a 1% increase in gain is typically realized with a 125Ω resistor, which degrades CMR by about 6dB.

A decrease in gain can be achieved by placing matched resistors in parallel with the sense resistors, also shown in Figure 2. The adjusted gain is given by the following expression

$$V_{OUT}/I_{IN} = 0.3125 \times R_{\chi}/(R_{\chi} + R_{s}).$$

A 1% decrease in gain can be achieved with a $7.5k\Omega$ resistor. It is important to match the parallel resistance on each sense resistor to maintain high CMR. The TCR mismatch between the two external resistors will effect gain error drift and CMR drift

There are two methods for nulling the RCV420 output offset voltage. The first method applies to applications using the internal 10V reference for level shifting. For these applica-

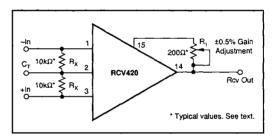


FIGURE 2. Optional Gain Adjustment.

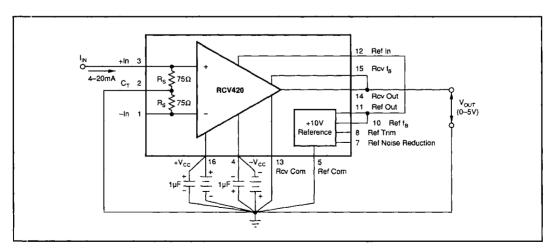


FIGURE 1. Basic Power Supply and Signal Connections.

tions, the voltage reference output trim procedure can be used to null offset errors at the output of the RCV420. The voltage reference trim circuit is discussed under "Voltage Reference."

When the voltage reference is not used for level shifting or when large offset adjustments are required, the circuit in Figure 3 can be used for offset adjustment. A low impedance on the Rcv Com pin is required to maintain high CMR.

ZERO ADJUSTMENT

Level shifting the RCV420 output voltage can be achieved using either the Ref In pin or the Rcv Com pin. The disadvanage of using the Ref In pin is that there is an 8:1 voltage attenuation from this pin to the output of the RCV420. Thus, use the Rcv Com pin for large offsets, because the voltage on this pin is seen directly at the output. Figure 4 shows the circuit used to level-shift the output of the RCV420 using the

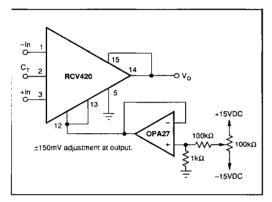


FIGURE 3. Optional Output Offset Nulling Using External Amplifier.

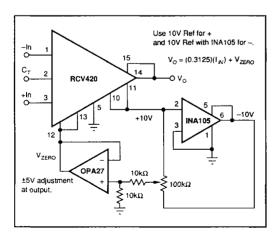


FIGURE 4. Optional Zero Adjust Circuit.

Rev Com pin. It is important to use a low-output impedance amplifier to maintain high CMR. With this method of zero adjustment, the Ref In pin must be connected to the Rev Com pin.

MAINTAINING COMMON-MODE REJECTION

Two factors are important in maintaining high CMR: (1) resistor matching and tracking (the internal resistor network does this) and (2) source impedance. CMR depends on the accurate matching of several resistor ratios. The high accuracies needed to maintain the specified CMR and CMR temperature coefficient are difficult and expensive to reliably achieve with discrete components. Any resistance imbalance introduced by external circuitry directly affects CMR. These imbalances can occur by: mismatching sense resistors when gain is decreased, adding resistance in the feedback path when gain is increased, and adding series resistance on the Rcv Com pin.

The two sense resistors are laser-trimmed to typically match within 0.01%; therefore, when adding parallel resistance to decrease gain, take care to match the parallel resistance on each sense resistor. To maintain high CMR when increasing the gain of the RCV420, keep the series resistance added to the feedback network as small as possible. Whether the Rcv Com pin is grounded or connected to a voltage reference for level shifting, keep the series resistance on this pin as low as possible. For example, a resistance of 20Ω on this pin degrades CMR from 86dB to approximately 80dB. For applications requiring better than 86dB CMR, the circuit shown in Figure 5 can be used to adjust CMR.

PROTECTING THE SENSE RESISTOR

The 75Ω sense resistors are designed for a maximum continuous current of 40mA, but can withstand as much as 250mA for up to 0.1s (see absolute maximum ratings). There are several ways to protect the sense resistor from overcur-

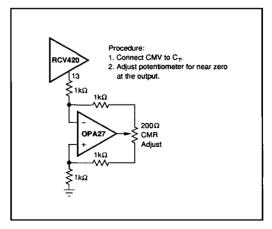


FIGURE 5. Optional Circuit for Externally Trimming CMR.

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rent conditions exceeding these specifications. Refer to Figure 6. The simplest and least expensive method is a resistor as shown in Figure 6a. The value of the resistor is determined from the expression

$$R_x = V_{cc}/40\text{mA} - 75\Omega$$

and the full scale voltage drop is

$$V_{RX} = 20 \text{mA} \times R_{x}$$

for a system operating off of a 32V supply $R_x = 725\Omega$ and $V_{RX} = 14.5V$. In applications that cannot tolerate such a large voltage drop, use circuits 6b or 6c. In circuit 6b a power JFET and source resistor are used as a current limit. The 200Ω potentiometer, R_{XY} is adjusted to provide a current limit of approximately 30mA. This circuit introduces a 1-4V drop at full scale. If only a very small series voltage drop at full scale can be tolerated, then a 0.032A series 217 fast-acting fuse should be used, as shown in Figure 6c.

RESISTOR NOISE IN THE RCV420

The output voltage noise of the RCV420 is dominated by the thermal noise generated in the resistor network. Figure 7 shows the model for calculating resistor noise in the RCV420. The expression for resistor noise is:

$$e_s(rms) = \sqrt{2\pi KTRB}$$

where: $K = Boltzman's constant (J/^{\circ}K)$

T = Absolute temperature (°K)

 $R = Resistance (\Omega)$

B = Bandwidth (Hz)

At room temperature, this noise becomes:

$$e_N = 1.3 \times 10^{-10} \sqrt{R}$$
 (V/ \sqrt{Hz})

The four noise sources in Figure 7 are:

$$e_{N1} = 1.3 \times 10^{-10} \sqrt{R_1}$$

 $e_{N2} = 1.3 \times 10^{-10} \sqrt{R_5}$

$$e_{N3} = 1.3 \times 10^{-10} \sqrt{R_3}$$

 $\epsilon_{N4} = 1.3 \times 10^{-10} \sqrt{R_6}$

Referred to output,

$$\epsilon_{NO1} = e_{N1}(A_D)$$

$$\epsilon_{NO2} = e_{N2} (A_D)$$

$$\epsilon_{NO3} = \epsilon_{N3} (R_J/R_3)$$

$$\epsilon_{NO4} = e_{N4} [(R_5 + R_6)/R_5] (A_D)$$

where $A_{\rm D}$ is the differential voltage gain of amplifier. Adding as the root of the sums squared:

$$e_{NO} = \sqrt{(e_{NO1}^2 + e_{NO2}^2 + e_{NO3}^2 + e_{NO4}^2)}$$

e_{NO} at a 150kHz bandwidth

- = 0.35 mVrms
- = 2.1mVp-p with a crest factor of 6 (statistically includes 99.7% of all noise peak occurrences).

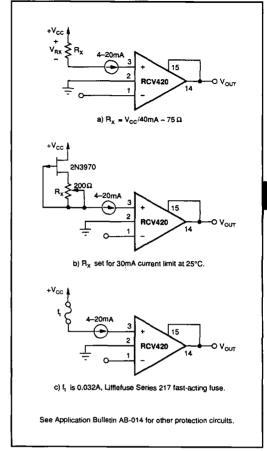


FIGURE 6. Protecting the Sense Resistors with a) Resistor, b)
JFET, c) Fuse.

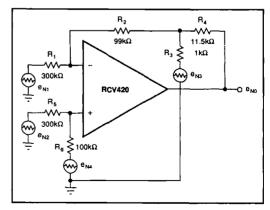


FIGURE 7. Resistor Noise Model.

VOLTAGE REFERENCE

The RCV420 contains a precision 10V reference. Figure 8 shows the circuit for output voltage adjustment. Trimming the output will change the voltage drift by approximately

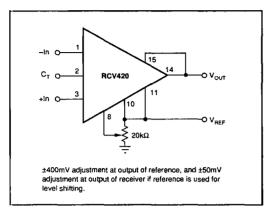


FIGURE 8. Optional Voltage Reference External Trim Circuit.

0.007ppm/°C per mV of trimmed voltage. Any mismatch in TCR between the two sides of the potentiometer will also affect drift, but the effect is divided by approximately 5. The trim range of the voltage reference using this method is typically ±400mV. The voltage reference trim can be used to trim offset errors at the output of the RCV420. There is an 8:1 voltage attenuation from Ref In to RCV Out, and thus the trim range at the output of the receiver is typically ±50mV. The highfrequency noise (to 1MHz) of the voltage reference is typically 1mVp-p. When the voltage reference is used for level shifting, its noise contribution at the output of the receiver is typically 125µVp-p due to the 8:1 attenuation from Ref In to RCV Out. The reference noise can be reduced by connecting an external capacitor between the Noise Reduction pin and ground. For example, a 0.1µF capacitor reduces the high-frequency noise to about 200µVp-p at the output of the reference and about 25μVp-p at the output of the receiver.

APPLICATIONS

The RCV420 is ideally suited for applications requiring precise current-to-voltage conversion and high CMR. The following figures show several typical application circuits.

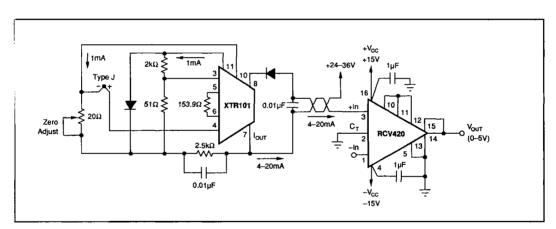


FIGURE 9, RCV420 Used in Conjunction with XTR101 to Form a Complete Solution for 4-20mA Loop.

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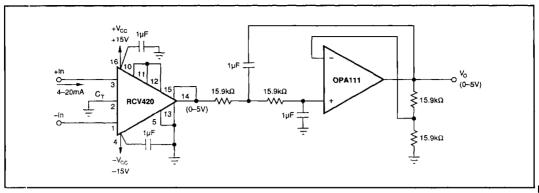


FIGURE 10. 4–20mA to 0-10V Conversion With Second-Order Active Low-Pass Filtering ($f_{-Lor} = 10$ Hz).

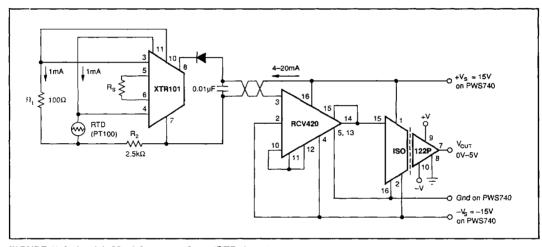
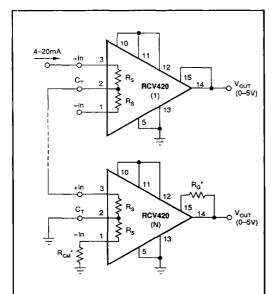


FIGURE 11. Isolated 4-20mA Instrument Loop (RTD shown).



 $^{\circ}R_{_{CM}}$ and $R_{_{O}}$ are used to provide a first order correction of CMR and Gain Error, respectively. Table 1 gives typical resistor values for $R_{_{CM}}$ and $R_{_{G}}$ when as many as three RCV420s are stacked. Table 2 gives typical CMR and Gain Error with no correction. Further improvement in CMR and Gain Error can be achieved using a $500 k\Omega$ potentiometer for $R_{_{CM}}$ and a 100Ω potentiometer for $R_{_{G}}$.

RCV420	R _{cm} (kΩ)	$R_{G}(\Omega)$
1	∞	0
2	200	7
3	67	23

TABLE 1. Typical Values for $R_{\rm CM}$ and $R_{\rm G}$.

RCV420	CMR (dB)	GAIN ERROR %
1	94	0.025
2	68	0.075
3	62	0.200

TABLE 2. Typical CMR and Gain Error Without Correction.

FIGURE 12, Series 4-20mA Receivers.

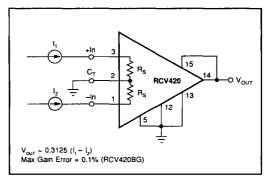


FIGURE 13. Differential Current-to-Voltage Converter.

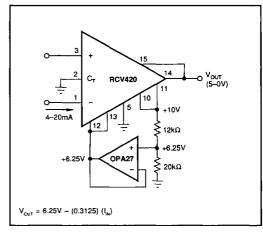


FIGURE 14. 4-20mA to 5-0V Conversion.

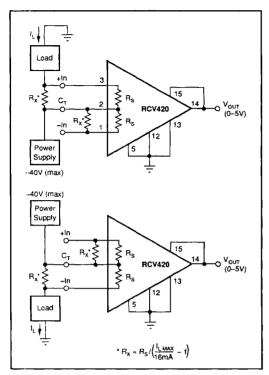


FIGURE 15. Power Supply Current Monitor Circuit.

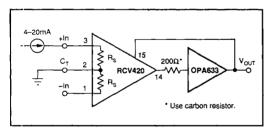


FIGURE 16. 4–20mA Receiver with Output Current Boosted to ±100mA.

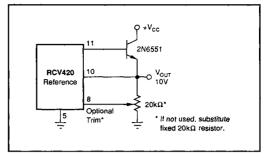


FIGURE 17. 10V with Output Current Boosted to 100mA max.

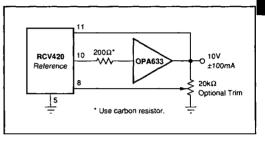


FIGURE 18. 10V with Output to Source/Sink 100mA.

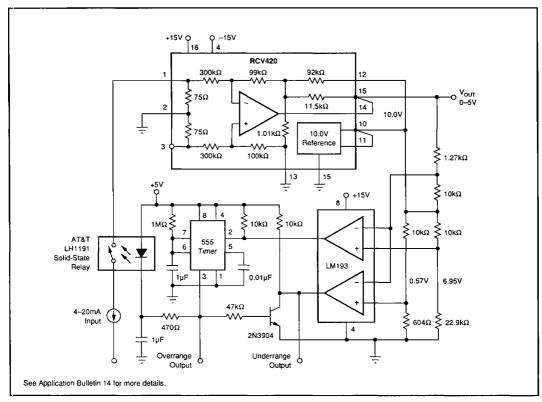


FIGURE 19. 4-20mA Current Loop Receiver with Open Line and Overrange Detection Logic Outputs.