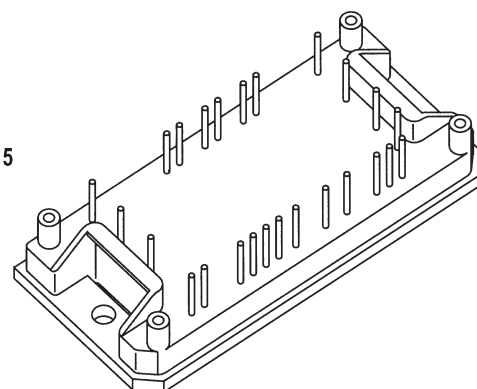
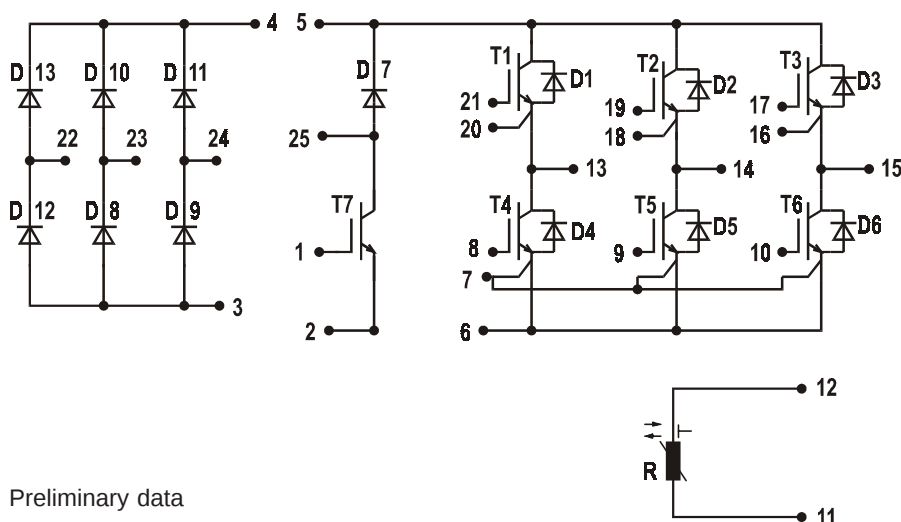


Converter - Brake - Inverter Module (CBI1)



Preliminary data

Rectifier	Brake	Inverter
$V_{RRM} = 1600V$	$V_{CES} = 1200 V$	$V_{CES} = 1200 V$
$I_{FAVM} = 11 A$	$I_{C25} = 3.6 A$	$I_{C25} = 3.6 A$
$I_{FSM} = 250 A$	$V_{CE(sat)} = 2.8 V$	$V_{CE(sat)} = 2.8 V$

Input Rectifier Bridge D8 - D13

Symbol	Conditions	Maximum Ratings	
V_{RRM}		1600	V
I_F	$T_{VJ} = 25^{\circ}C$	36	A
I_{FAVM}	$T_{VJ} = 150^{\circ}C$; $T_K = 70^{\circ}C$	11	A
I_{FSM}	$T_{VJ} = 45^{\circ}C$; $t = 10 \text{ ms sine } 50 \text{ Hz}$	250	A
i^2t	$T_{VJ} = 125^{\circ}C$	310	A ² s
T_{VJ}		+150	$^{\circ}C$

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^{\circ}C$, unless otherwise specified)		
		min.	typ.	max.
I_R	$V_{RRM} = 1200 V$; $T_{VJ} = 25^{\circ}C$ $T_{VJ} = 125^{\circ}C$			10 μA 3 mA
V_F	$I_F = 36 A$		1.15	1.4 V
R_{thJC}	per die		1.4	$^{\circ}C/W$

Features

- NPT IGBT technology
Square RBSOA, no latchup
- Free wheeling diodes with Hiperfast and soft recovery behaviour
- Isolation voltage 2500 V~
- Built in temperature sense
- High level of integration:
one module for complete drive system
- **Direct Copper Bonded** Al_2O_3 ceramic base plate

Applications

- AC motor control
- AC servo and robot drives

Advantages

- No need of external isolation
- Easy to mount with two screws
- Package designed for wave soldering
- High temperature and power cycling capability

IXYS reserves the right to change limits, test conditions and dimensions.

Output Inverter T1 - T6, D1 - D6

Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$	1200	V
V_{CGR}	$T_{VJ} = 25^{\circ}\text{C}; R_{GE} = 20\text{k}\Omega$	1200	V
V_{GE}	$T_{VJ} = 25^{\circ}\text{C}$	± 20	V
I_C	$T_C = 25^{\circ}\text{C}$	3.6	A
	$T_C = 90^{\circ}\text{C}$	2.4	A
I_{CM}	$t_p = 1\text{ ms} = 1\% \text{ duty cycle};$ $T_C = 25^{\circ}\text{C}$ $T_C = 110^{\circ}\text{C}$	7.2	A
		4.8	A
t_{SC}	$V_{CE} = 600\text{ V}; T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	μs
P_{tot}	$T_C = 25^{\circ}\text{C}$	45	W
T_{VJ}	Free-Wheeling Diode	+150	$^{\circ}\text{C}$
T_{VJ}	IGBT	+150	$^{\circ}\text{C}$

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified)		
		min.	typ.	max.
I_{CES}	$V_{GE} = 0\text{ V}; V_{CE} = 1000\text{ V}$		1	25 μA
I_{GES}	$V_{CE} = 0\text{ V}; V_{GE} = 25\text{ V}$		0.1	100 nA
$V_{GE(th)}$	$V_{GE} = V_{CE}; I_C = 0.1\text{ mA}$	4.5	5.5	6.5 V
$V_{(BR)CES}$	$V_{GE} = 0\text{ V}; I_C = 10\text{ mA}; T_{VJ} = -40^{\circ}\text{C}$	1200		V
V_{CEsat}	$V_{GE} = 15\text{ V}; I_C = 1.5\text{ A};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$		2.8	3.3 V
			4	4.5 V
t_f	$\left. \begin{array}{l} \text{Inductive load, } T_{VJ} = 125^{\circ}\text{C} \\ V_{CC} = 600\text{ V}; I_C = 1.5\text{ A} \\ R_G = 100\ \Omega; V_{GE} = \pm 15\text{ V} \end{array} \right\}$		100	ns
t_r			58	ns
$t_{d(on)}$			80	ns
$t_{d(off)}$			290	ns
E_{off}			0.12	mJ
E_{on}			0.34	mJ
C_{iss}	$\left. \begin{array}{l} V_{GE} = 0\text{ V} \\ V_{CE} = 25\text{ V} \\ f = 1\text{ MHz} \end{array} \right\}$		225	pF
C_{oss}			25	pF
C_{rss}			13	pF
g_{fs}	$V_{CE} = 20\text{ V}; I_C = 1.5\text{ A}$		0.6	S
Q_g	$V_{CC} = 800\text{ V}; I_C = 1\text{ A pulse}; V_{GE} = 15\text{ V}$		24.1	nC
V_F	$I_F = 4\text{ A}; V_{GE} = 0\text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 100^{\circ}\text{C}$		2.3	3 V
			2	V
t_{rr}	$I_F = 4\text{ A}; V_{GE} = 0\text{ V}; T_{VJ} = 100^{\circ}\text{C}$ $V_R = -300\text{ V}; di_F/dt = -800\text{ A}/\mu\text{s}$		55	ns
Q_r	$I_F = 4\text{ A}; V_{GE} = 0\text{ V}; T_{VJ} = 100^{\circ}\text{C}$ $V_R = -300\text{ V}; di_F/dt = -800\text{ A}/\mu\text{s}$		0.8	μC
I_r				250 μA
R_{thJC}	IGBT	(per die)	2.3	$^{\circ}\text{C}/\text{W}$
	Diode	(per die)	2.25	$^{\circ}\text{C}/\text{W}$

Brake Chopper T7, D7

Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$	1200	V
V_{CGR}	$T_{VJ} = 25^{\circ}\text{C}; R_{GE} = 20\text{k}\Omega$	1200	V
V_{GE}	$T_{VJ} = 25^{\circ}\text{C}$	± 20	V
I_C	$T_C = 25^{\circ}\text{C}$	3.6	A
	$T_C = 90^{\circ}\text{C}$	2.4	A
I_{CM}	$t_p = 1\text{ ms} = 1\% \text{ duty cycle};$ $T_C = 25^{\circ}\text{C}$ $T_C = 110^{\circ}\text{C}$	7.2	A
		4.8	A
t_{SC}	$V_{CE} = 600\text{ V}; T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	μs
P_{tot}	$T_C = 25^{\circ}\text{C}$	45	W
T_{VJ}	Free-Wheeling Diode	+150	$^{\circ}\text{C}$
T_{VJ}	IGBT	+150	$^{\circ}\text{C}$

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified)		
		min.	typ.	max.
I_{CES}	$V_{GE} = 0\text{ V}; V_{CE} = 1000\text{ V}$		1	25 μA
I_{GES}	$V_{CE} = 0\text{ V}; V_{GE} = 25\text{ V}$		0.1	100 nA
$V_{GE(th)}$	$V_{GE} = V_{CE}; I_C = 0.1\text{ mA}$	4.5	5.5	6.5 V
$V_{(BR)CES}$	$V_{GE} = 0\text{ V}; I_C = 10\text{ mA}; T_{VJ} = -40^{\circ}\text{C}$	1200		V
V_{CEsat}	$V_{GE} = 15\text{ V}; I_C = 1.5\text{ A};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$		2.8	3.3 V
			4	4.5 V
t_f	$\left. \begin{array}{l} \text{Inductive load, } T_{VJ} = 125^{\circ}\text{C} \\ V_{CC} = 600\text{ V}; I_C = 1.5\text{ A} \\ R_G = 100\ \Omega; V_{GE} = \pm 15\text{ V} \end{array} \right\}$		100	ns
t_r			58	ns
$t_{d(on)}$			80	ns
$t_{d(off)}$			290	ns
E_{off}			0.12	mJ
E_{on}			0.34	mJ
C_{iss}	$\left. \begin{array}{l} V_{GE} = 0\text{ V} \\ V_{CE} = 25\text{ V} \\ f = 1\text{ MHz} \end{array} \right\}$		225	pF
C_{oss}			25	pF
C_{rss}			13	pF
g_{fs}	$V_{CE} = 20\text{ V}; I_C = 1.5\text{ A}$		0.6	S
Q_g	$V_{CC} = 800\text{ V}; I_C = 1\text{ A pulse}; V_{GE} = 15\text{ V}$		24.1	nC
V_F	$I_F = 4\text{ A}; V_{GE} = 0\text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 100^{\circ}\text{C}$		2.3	3 V
			2	V
t_{rr}	$I_F = 4\text{ A}; V_{GE} = 0\text{ V}; T_{VJ} = 100^{\circ}\text{C}$ $V_R = -300\text{ V}; di_F/dt = -800\text{ A}/\mu\text{s}$		55	ns
Q_r	$I_F = 4\text{ A}; V_{GE} = 0\text{ V}; T_{VJ} = 100^{\circ}\text{C}$ $V_R = -300\text{ V}; di_F/dt = -800\text{ A}/\mu\text{s}$		0.8	μC
I_r			250	μA
R_{thJC}	IGBT	(per die)	2.3	$^{\circ}\text{C}/\text{W}$
	Diode	(per die)	2.25	$^{\circ}\text{C}/\text{W}$

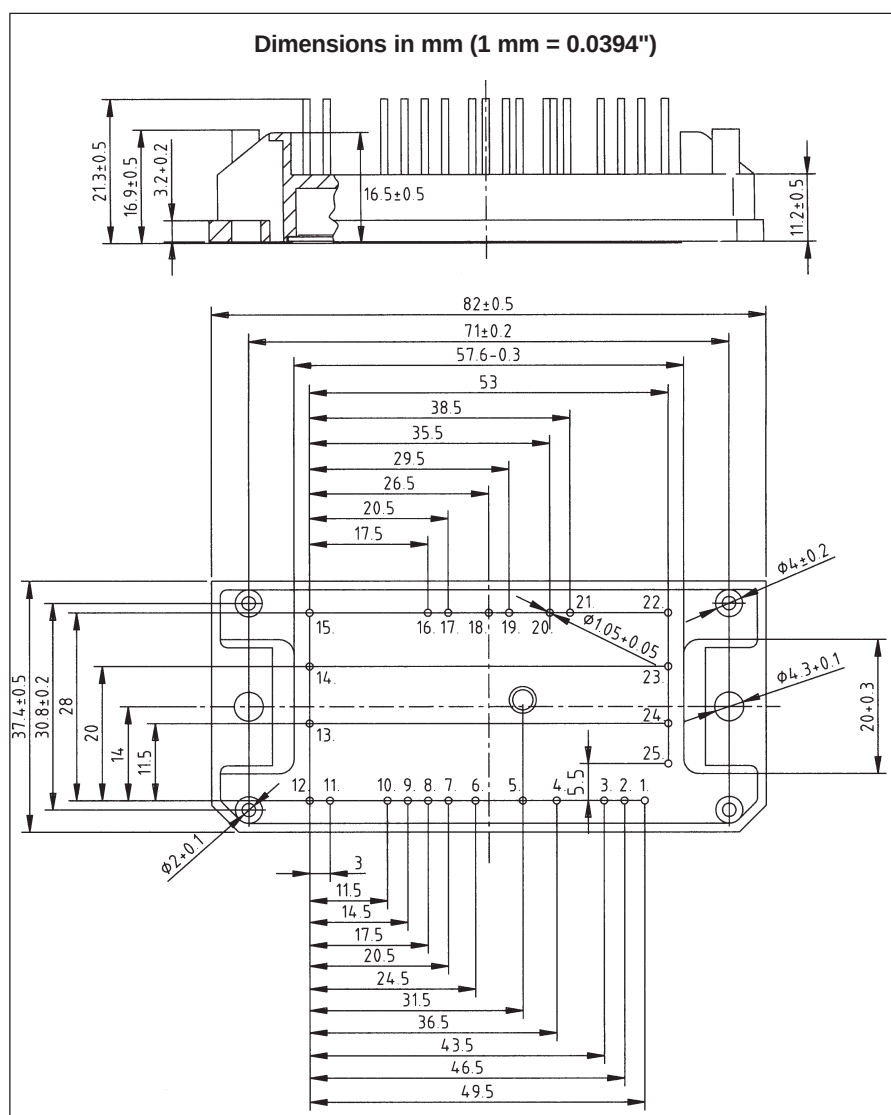
Module

Symbol	Conditions	Maximum Ratings	
T_{stg}		-40...+125	°C
V_{ISOL}	$I_{ISOL} \leq 1 \text{ mA}$; 50/60 Hz; $t = 1 \text{ min}$	2500	V~
M_d	Mounting torque (M4)	2.0 - 2.2 18 - 20	Nm lb.in.
d_s	Creepage distance on surface	12.7	mm
d_A	Strike distance in air	12.7	mm
Weight	typ.	42	g

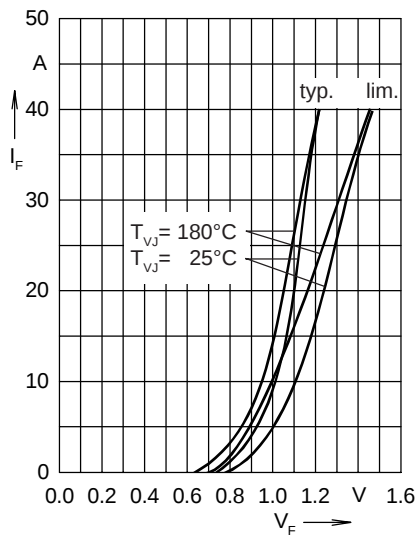
Temperature Sensor R

Symbol	Conditions	Maximum Ratings	
R	$T_{amb} = 20^\circ\text{C}$	4.7	k Ω

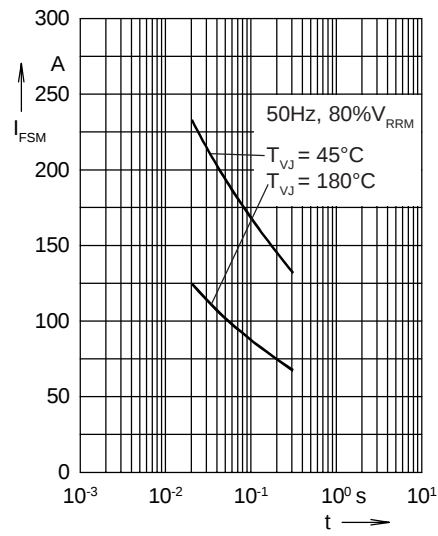
For additional data see C620/4.7k 5% S+M NTC thermistor catalog



Input Rectifier Bridge D8 - D13

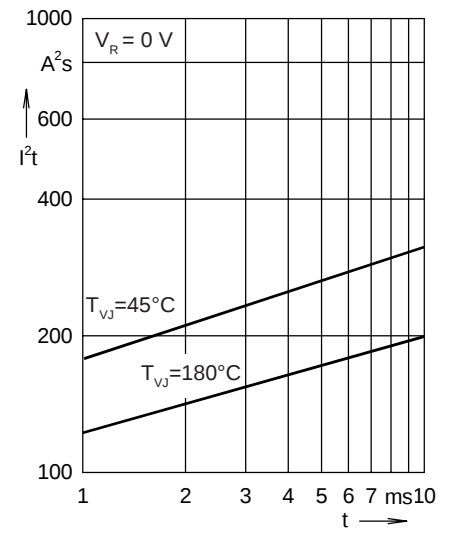


Forward characteristics

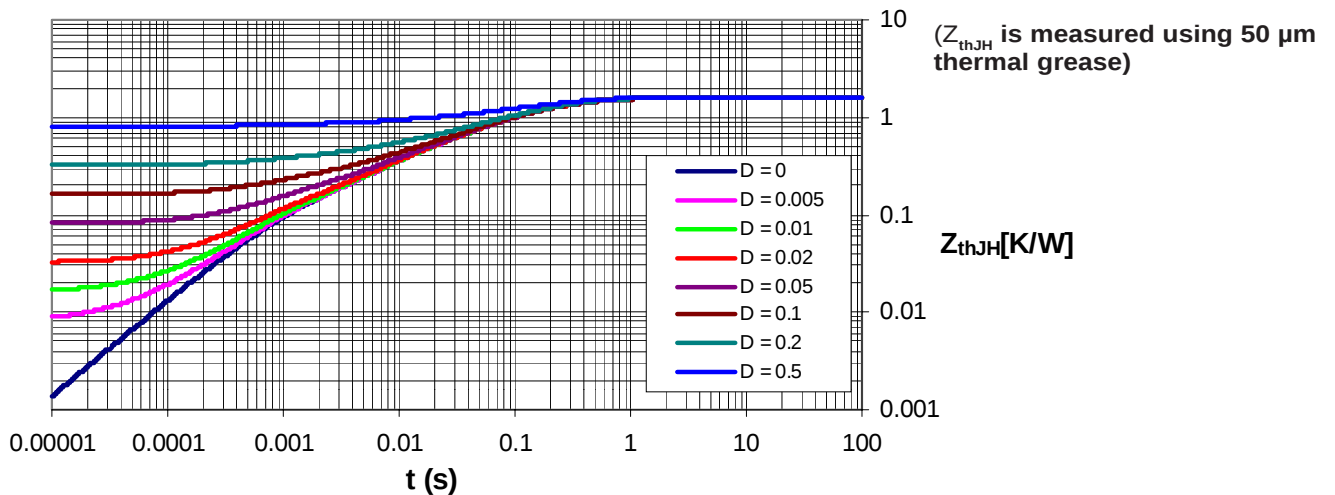


Surge overload current

I_{FSM} : crest value, t : duration



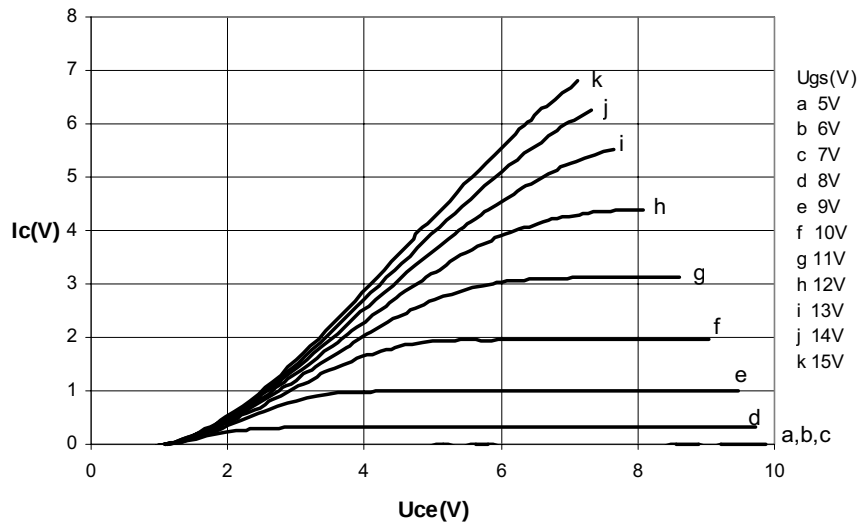
I^2t versus time (1-10 ms)



Transient thermal resistance junction to heatsink

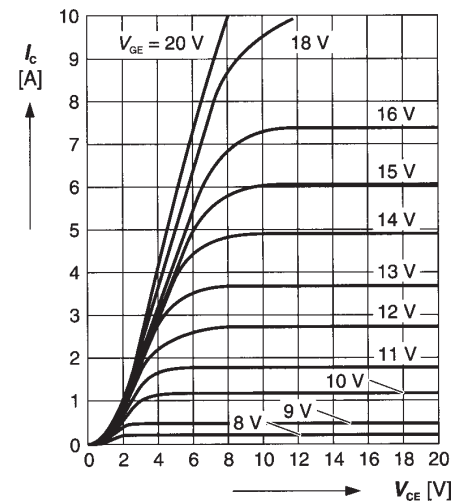
Output Inverter T1 - T6

Typ. output characteristics 25°C



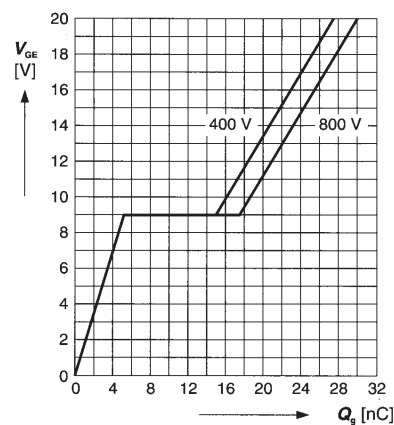
Typ. output characteristics

$I_c = f(V_{ce})$
parameter: $t_p = 80 \mu s$; $T_j = 125^\circ C$



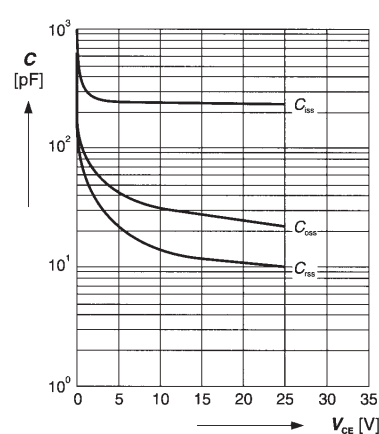
Typ. gate charge

$V_{GE} = f(Q_g)$
parameter: $I_{C \text{ puls}} = 1 A$

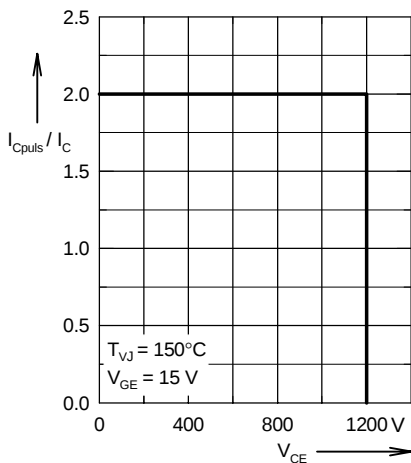


Typ. capacitances

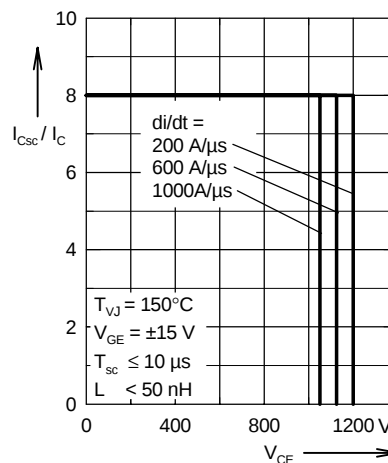
$C = f(V_{ce})$
parameter: $V_{GE} = 0 V$; $f = 1 MHz$



Reverse biased safe operating area

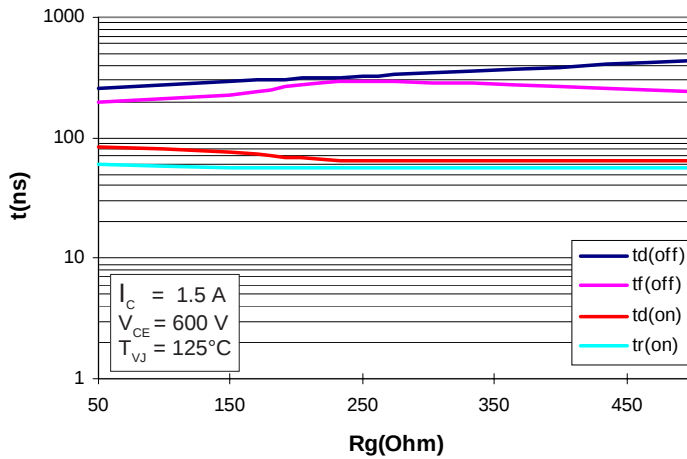


Short circuit safe operating area

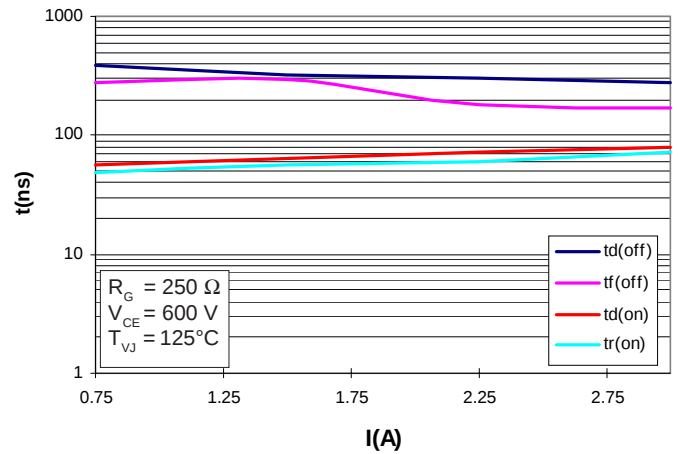


Output Inverter T1 - T6

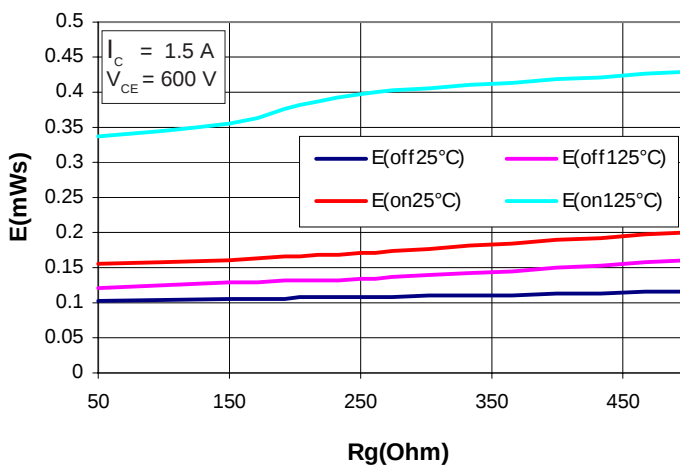
Typ. switching times



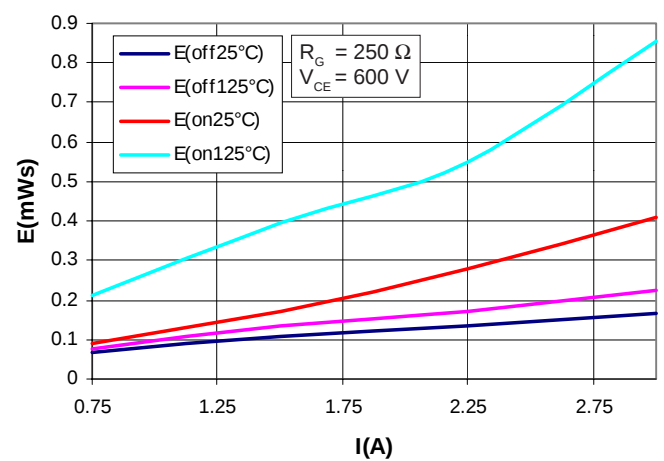
Typ. switching times



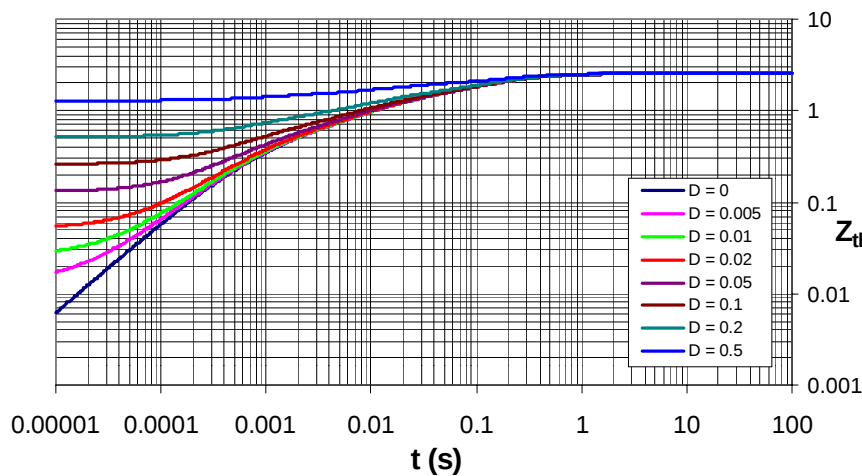
Typ. switching losses



Typ. switching losses



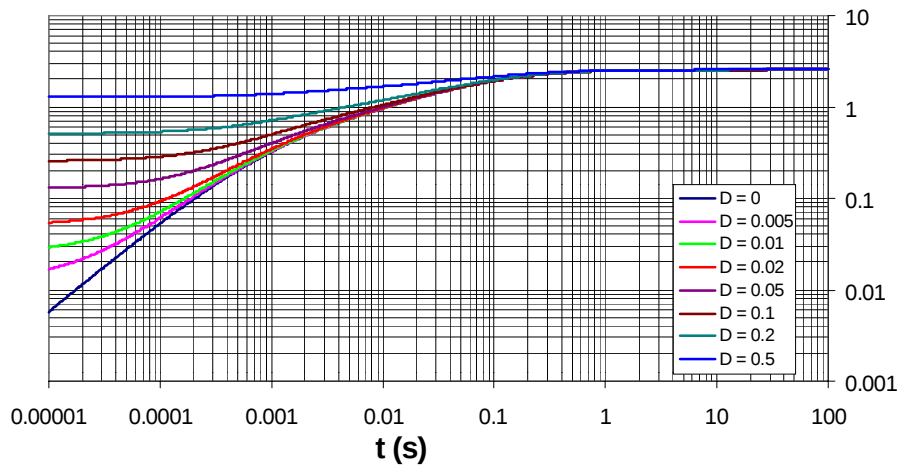
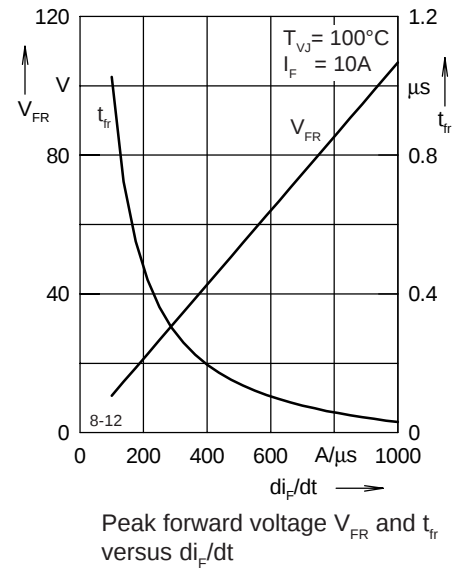
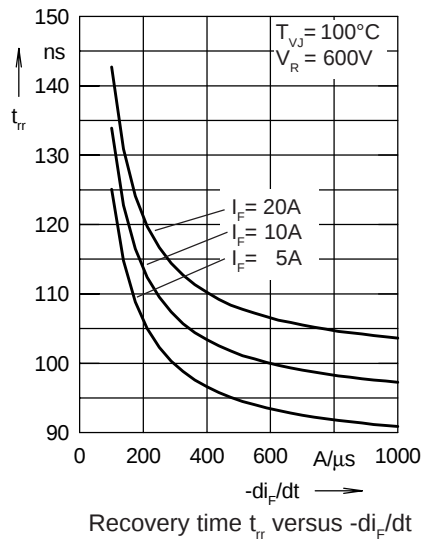
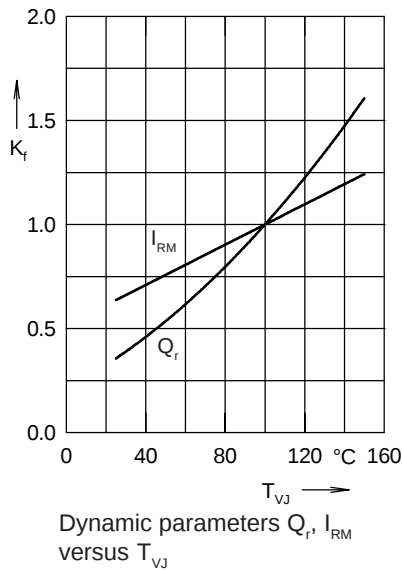
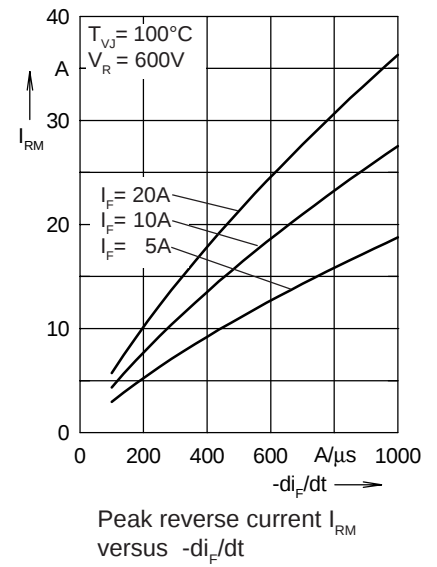
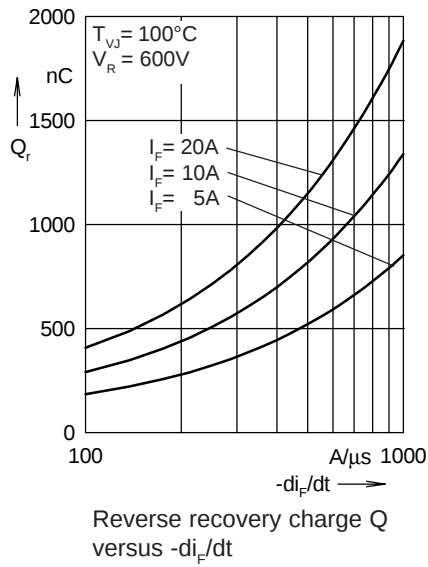
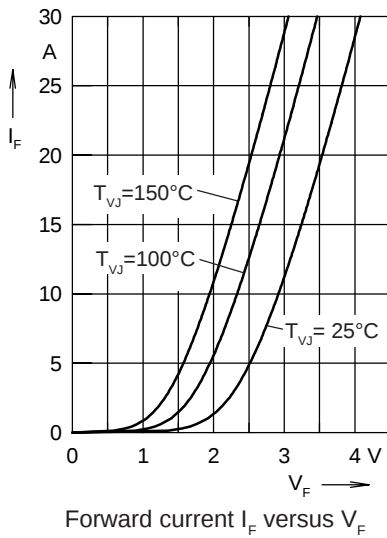
Transient thermal resistance junction to heatsink



(Z_{thJH} is measured using 50 μm thermal grease)

IGBT
 Z_{thJH} [K/W]

Output Inverter D1 - D6



(Z_{thJH} is measured using 50 μm thermal grease)

FRED
 Z_{thJH} [K/W]

Transient thermal resistance junction to heatsink