# $\pm 15 k V$ ESD-Protected, Isolated RS-485/RS-422 Data Interfaces 


#### Abstract

General Description The MAX1480EA/MAX1480EC/MAX1490EA/MAX1490EB are complete, electrically isolated, RS-485/RS-422 data communications interface solutions in a hybrid microcircuit. The RS-485/RS-422 I/O pins are protected against $\pm 15 \mathrm{kV}$ electrostatic discharge (ESD) shocks, without latchup. Transceivers, optocouplers, and a transformer provide a complete interface in a standard DIP package A single +5 V supply on the logic side powers both sides of the interface.

The MAX1480EC/MAX1490EB feature reduced-slew-rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables, allowing error-free data transmission at data rates up to 160 kbps . The MAX1480EA/MAX1490EA driver slew rate is not limited, allowing transmission rates up to 2.5 Mbps . The MAX1480EA/MAX1480EC are designed for half-duplex communication, while the MAX1490EA/MAX1490EB feature full-duplex communication.

Drivers are short-circuit current limited and protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a highimpedance state. The receiver input has a fail-safe feature that guarantees a known output ( $\overline{\mathrm{RO}}$ low for the MAX1480EA/MAX1480EC, RO high for the MAX1490EA/ MAX1490EB) if the input is open circuit. The MAX1480EA/MAX1480EC/MAX1490EA/MAX1490EB withstand $1260 V_{\text {RMS }}$ ( 1 min ) or $1520 V_{\mathrm{RMS}}$ (1s). Their isolated outputs meet all RS-485/RS-422 specifications. The MAX1480EA/MAX1480EC are available in a 28 -pin DIP package, and the MAX1490EA/MAX1490EB are available in a 24 -pin DIP package.


## Applications

Isolated RS-485/RS-422 Data Interface
Transceivers for EMI-Sensitive Applications
Industrial-Control Local Area Networks
Automatic Test Equipment
HVAC/Building Control Networks Telecom

Features

- Isolated Data Interface, Guaranteed to 1260VRMS (1min)
- $\pm 15 k V$ ESD Protection on I/O Pins
- Slew-Rate Limited for Errorless Data Transmission (MAX1480EC/MAX1490EB)
- High-Speed, Isolated, 2.5Mbps RS-485/RS-422 Interface (MAX1480EA/MAX1490EA)
- Full-Duplex Data Communication (MAX1490EA/MAX1490EB)
- Single +5V Supply
- Current Limiting and Thermal Shutdown for Driver Overload Protection
- Standard 0.6in DIP Packages

28-Pin DIP (MAX1480EA/MAX1480EC)
24-Pin DIP (MAX1490EA/MAX1490EB)
Ordering Information

| PART $^{\dagger}$ | TEMP. RANGE | PIN-PACKAGE |
| :---: | ---: | :--- |
| MAX1480EACPI | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 28 Wide Plastic DIP |
| MAX1480EAEPI | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 28 Wide Plastic DIP* |

Ordering Information continued at end of data sheet.
$\dagger$ Data rate for $A$ parts is up to 2.5 Mbps . Data rate for $C$ parts is up to 250kbps.
*See Reliability section at end of data sheet.
Pin Configurations


Pin Configurations continued at end of data sheet.

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## ABSOLUTE MAXIMUM RATINGS

With Respect to GND_
Supply Voltage (VCC_)
-0.3V to +6 V
Control Input Voltage (SD, FS)..............-0.3V to (VCC_ +0.3 V )
Receiver Output Voltage (RO, RO).......-0.3V to ( $\mathrm{VCC}_{\mathrm{C}}+0.3 \mathrm{~V}$ )
Output Switch Voltage (D1, D2)......................................+12V
With Respect to ISO COM_
Control Input Voltage (ISO DE_) ....-0.3V to (ISO VCC_ +0.3 V )
Driver Input Voltage (ISO DI_) .......-0.3V to (ISO Vcc_ + 0.3V)
Receiver Output Voltage (ISO RO_) ..-0.3V to (ISO Vcc_ +0.3 V )
Driver Output Voltage (A, B, Y, Z) ...................... 8 V to +12.5 V
Receiver Input Voltage (A, B)............................. 8 V to +12.5 V


Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS

( $\mathrm{VCC}_{-}=+5 \mathrm{~V} \pm 10 \%, \mathrm{~V}_{F S}=\mathrm{V}_{C C}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{V}_{C C}=+5 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$. ) (Notes 1, 2)


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## ELECTRICAL CHARACTERISTICS (continued)

$\left(V_{C C-}=+5 \mathrm{~V} \pm 10 \%, \mathrm{~V}_{\text {FS }}=\mathrm{V}_{C_{C}}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}\right.$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{V}_{C C_{-}}=+5 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Notes 1, 2)

| PARAMETER | SYMBOL | CONDITIONS |  |  | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Change in Magnitude of Driver Output Voltage for Complementary Output States | $\Delta \mathrm{V}_{\mathrm{OD}}$ | $\mathrm{R}=27 \Omega$ or $50 \Omega$, Figure 4 |  | Differential |  |  | 0.3 | V |
|  |  |  |  | Common mode |  |  | 0.3 |  |
| Driver Common-Mode Output | Voc | $\mathrm{R}=27 \Omega$ or $50 \Omega$, Figure 4 |  |  |  |  | 4 | V |
| Input Current (A, B) | ISO IN | $\begin{aligned} & \mathrm{DE}^{\prime}=0 \\ & \mathrm{VCC}_{-}=0 \text { or }+5.5 \mathrm{~V} \end{aligned}$ | V IN $=+12 \mathrm{~V}$ | MAX1490EA/ MAX1490EB |  |  | 1.0 | mA |
|  |  |  |  | MAX1480EA/ MAX1480EC |  |  | 0.25 |  |
|  |  |  | V IN $=-7 \mathrm{~V}$ | $\begin{aligned} & \text { MAX1490EA/ } \\ & \text { MAX1490EB } \end{aligned}$ |  |  | 0.8 |  |
|  |  |  |  | MAX1480EA/ <br> MAX1480EC |  |  | 0.2 |  |
| Receiver Input Resistance | RIN | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {CM }} \leq+12 \mathrm{~V}$ |  | (MAX1480E_) | 48 |  |  | k $\Omega$ |
|  |  |  |  | (MAX1490E_) | 12 |  |  |  |
| Receiver Differential Threshold | $\mathrm{V}_{\text {TH }}$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {CM }} \leq+12 \mathrm{~V}$ |  |  | -0.2 |  | 0.2 | V |
| Receiver Input Hysteresis | $\Delta \mathrm{V}_{\text {TH }}$ | $V_{C M}=0$ |  |  |  | 70 |  | mV |
| Receiver Output Low Voltage | VOL | Using resistor values listed in Tables 1 and 2 |  |  |  |  | 0.4 | V |
| Receiver Output High Current | IOH | Vout $=5.5 \mathrm{~V}$ |  |  |  |  | 250 | $\mu \mathrm{A}$ |
| Driver Short-Circuit Current | ISO IOSD | $-7 \mathrm{~V} \leq \mathrm{VO} \leq 12 \mathrm{~V}$ (Note 5) |  |  |  | 100 |  | mA |
| ESD Protection | ISO IOSD | $\mathrm{A}, \mathrm{B}, \mathrm{Y}$, and Z pins, tested using Human Body Model, Figures 1 and 2 |  |  |  | $\pm 15$ |  | kV |

## SWITCHING CHARACTERISTICS—MAX1480EA/MAX1490EA

$\left(\mathrm{V}_{C C_{-}}=+5 \mathrm{~V} \pm 10 \%, \mathrm{~V}_{\text {FS }}=\mathrm{V}_{C C_{-}}, \mathrm{T}_{A}=\mathrm{T}_{\text {MIN }}\right.$ to $T_{\text {MAX }}$, unless otherwise noted. Typical values are at $\mathrm{V}_{C C_{-}}=+5 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Input to Output Propagation Delay | tpLH | Figures 5 and 7, RDIFF $=54 \Omega$, $C_{L 1}=C_{L 2}=100 \mathrm{pF}$ |  | 90 | 275 | ns |
|  | tpHL |  |  | 60 | 275 |  |
| Driver Output Skew | tSKEW | Figures 5 and 7, RDIFF $=54 \Omega, \mathrm{CL1}=\mathrm{CL2}=100 \mathrm{pF}$ |  | 30 | 100 | ns |
| Driver Rise or Fall Time | tR, tF | Figures 5 and 7, RDIFF $=54 \Omega, \mathrm{CL1}=\mathrm{CL2}=100 \mathrm{pF}$ |  | 15 | 50 | ns |
| Driver Enable to Output High (MAX1480EA Only) | tz ${ }^{\text {l }}$ | Figures 6 and 8, CL = 100pF, S2 closed |  | 1.0 | 1.8 | $\mu \mathrm{S}$ |
| Driver Enable to Output Low (MAX1480EA Only) | tzL | Figures 6 and 8, CL $=100 \mathrm{pF}$, S1 closed |  | 1.0 | 1.8 | $\mu \mathrm{s}$ |
| Driver Disable Time from Low (MAX1480EA Only) | tLZ | Figures 6 and 8, $C_{L}=15 p F$, S1 closed |  | 0.5 | 1.8 | $\mu \mathrm{S}$ |
| Driver Disable Time from High (MAX1480EA Only) | thz | Figures 6 and 8, CL $=15 \mathrm{pF}$, S 2 closed |  | 0.5 | 1.8 | $\mu \mathrm{S}$ |
| Receiver Input to Output Propagation Delay | tPLH | Figures 5 and 10, $\mathrm{RDIFF}=54 \Omega, \mathrm{CL}_{\text {L }}=\mathrm{CLL}^{2}=100 \mathrm{pF}$ |  | 120 | 225 | ns |
|  | tphL |  |  | 90 | 225 |  |

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## SWITCHING CHARACTERISTICS—MAX1480EA/MAX1490EA (continued)

$\left(\mathrm{V}_{C C_{-}}=+5 \mathrm{~V} \pm 10 \%, \mathrm{~V}_{\text {FS }}=\mathrm{V}_{\text {CC_ }}, \mathrm{T}_{A}=\mathrm{T}_{\text {MIN }}\right.$ to $T_{\text {MAX }}$, unless otherwise noted. Typical values are at $\mathrm{V}_{C C}=+5 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :--- | :---: | :--- | :---: | :---: | :---: | :---: |
| ItpLH - tphLI Differential <br> Receiver Skew | tSKD | Figures 5 and 10, RDIFF $=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$ |  | 30 | 150 | ns |
| Maximum Data Rate | fMAX | tSKEW, tSKD, tPHL $\leq 25 \%$ of data period | 2.5 |  | Mbps |  |
| Time to Shutdown | tSHDN |  | 100 | $\mu \mathrm{~s}$ |  |  |
| Shutdown to Driver Output High | tZH(SHDN) | Figures 6 and 9, $C_{L}=100 \mathrm{pF}$, S2 closed | 3 | 15 | $\mu \mathrm{~s}$ |  |
| Shutdown to Driver Output Low | tZH(SHDN) | Figures 6 and 9, $\mathrm{CL}=100 \mathrm{pF}$, S1 closed | 3 | 15 | $\mu \mathrm{~s}$ |  |

## SWITCHING CHARACTERISTICS—MAX1480EC/MAX1490EB

$\left(\mathrm{V}_{C C_{-}}=+5 \mathrm{~V} \pm 10 \%, \mathrm{~V}_{\text {FS }}=\mathrm{V}_{C C_{-}}, \mathrm{T}_{A}=\mathrm{T}_{\text {MIN }}\right.$ to $\mathrm{T}_{\text {MAX }}$, unless otherwise noted. Typical values are at $\mathrm{V}_{C C}=+5 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Input to Output Propagation Delay | tPLH | Figures 5 and 7, RDIFF $=54 \Omega, C_{L 1}=$ CL2 $=100 \mathrm{pF}$ |  | 1.4 | 3.0 | $\mu \mathrm{s}$ |
|  | tPHL | Figures 5 and 7, RDIFF $=54 \Omega, \mathrm{CL}_{\text {L1 }}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$ |  | 1.1 | 3.0 |  |
| Driver Output Skew | tSKEW | Figures 5 and 7, RDIFF $=54 \Omega, \mathrm{CL}_{\text {L1 }}=\mathrm{CL}_{\text {L2 }}=100 \mathrm{pF}$ |  | 300 | 1200 | ns |
| Driver Rise or Fall Time | tR, tF | Figures 5 and 7, RDIFF $=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$ |  | 1.0 | 2.0 | $\mu \mathrm{s}$ |
| Driver Enable to Output High (MAX1480EC Only) | tZH | Figures 6 and 8, CL = 100pF, S2 closed |  | 1.4 | 4.5 | $\mu \mathrm{s}$ |
| Driver Enable to Output Low (MAX1480EC Only) | tzL | Figures 6 and 8, CL = 100pF, S1 closed |  | 1.4 | 4.5 | $\mu \mathrm{s}$ |
| Driver Disable Time from Low (MAX1480EC Only) | tız | Figures 6 and 8, CL $=15 \mathrm{pF}$, S1 closed |  | 2.0 | 4.5 | $\mu \mathrm{s}$ |
| Driver Disable Time from High (MAX1480EC Only) | thz | Figures 6 and 8, CL $=15 \mathrm{pF}$, S2 closed |  | 1.7 | 4.5 | $\mu \mathrm{s}$ |
| Receiver Input to Output Propagation Delay | tPLH | Figures 5 and 10, RDIFF $=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$ |  | 0.9 | 3.0 | $\mu \mathrm{s}$ |
|  | tPHL |  |  | 1.1 | 3.0 |  |
| ItPLH - tphl I Differential Receiver Skew | tSKD | Figures 5 and 10, RDIFF $=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$ | 200 |  |  | ns |
| Maximum Data Rate | $f_{\text {max }}$ | tSKEW, tSKD $\leq 25 \%$ of data period | 160 |  |  | kbps |
| Time to Shutdown | tSHDN |  |  | 100 |  | $\mu \mathrm{s}$ |
| Shutdown to Driver Output High | tZH(SHDN) | Figures 6 and 9, CL = 100pF, S2 closed |  | 3 | 15 | $\mu \mathrm{s}$ |
| Shutdown to Driver Output Low | tZL(SHDN) | Figures 6 and 9, CL = 100pF, S1 closed |  | 3 | 15 | $\mu \mathrm{s}$ |

Note 1: All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to logicside ground (GND_), unless otherwise specified.
Note 2: For DE' and DI' pin descriptions, see Detailed Block Diagram and Typical Application Circuit (Figure 1 for MAX1480EA/ MAX1480EC, Figure 2 for MAX1490EA/MAX1490EB).
Note 3: Shutdown supply current is the current at $\mathrm{V}_{\mathrm{CC}} 1$ and $\mathrm{V}_{\mathrm{CC}}$ when shutdown is enabled.
Note 4: Limit guaranteed by applying $1520 V_{\text {RMS }}$ for 1 s . Test voltage is applied between all pins on one side of the package to all pins on the other side of the package, e.g., between pins 1-14 and pins 15-28 on the 28-pin package.
Note 5: Applies to peak current (see Typical Operating Characteristics). Although the MAX1480EA/MAX1480EC and MAX1490EA/MAX1490EB provide electrical isolation between logic ground and signal paths, they do not provide isolation between external shields and the signal paths (see Isolated Common Connection section).

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Typical Operating Characteristics
$\left(\mathrm{V}_{C C}-=+5 \mathrm{~V}, \mathrm{~V}_{\text {FS }}=\mathrm{V}_{C C}\right.$ _, Figures 1 and $2, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted. $)$


RECEIVER OUTPUT LOW VOLTAGE vs. TEMPERATURE


DRIVER OUTPUT CURRENT


OUTPUT CURRENT vs RECEIVER OUTPUT HIGH VOLTAGE


OUTPUT CURRENT vs. DRIVER OUTPUT LOW VOLTAGE


DRIVER DIFFERENTIAL OUTPUT VOLTAGE
vs. TEMPERATURE


RECEIVER OUTPUT HIGH VOLTAGE
vs. TEMPERATURE


OUTPUT CURRENT vs. DRIVER OUTPUT HIGH VOLTAGE


SHUTDOWN CURRENT
vs. TEMPERATURE


## $\pm 15 k V$ ESD-Protected, Isolated RS-485/RS-422 Data Interfaces



Typical Operating Characteristics (continued)
$\left({\mathrm{V} C C_{-}}=+5 \mathrm{~V}, \mathrm{~V}_{\text {FS }}=\mathrm{V}_{C C_{-}}\right.$, Figures 1 and $2, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted. $)$


MAX1490EB



20ns/div

MAX1480EA/MAX1490EA RECEIVER tpLH


## 土15kV ESD-Protected, Isolated RS-485/RS-422 Data Interfaces

$\left(\mathrm{V}_{C C_{-}}=+5 \mathrm{~V}, \mathrm{~V}_{\mathrm{FS}}=\mathrm{V}_{C C_{-}}, \mathrm{V}_{\mathrm{DI}}{ }^{\prime}=0, \mathrm{DE}^{\prime}\right.$ toggled 0 to 5 V at 5 kHz , Figures 1 and $2, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted. $)$


MAX1480EC
DRIVER ENABLE TIME


MAX1480EC/MAX1490EB RECEIVER tPLH


MAX1480EC
DRIVER DISABLE TIME


MAX1480EA/MAX1490EA
POWER-UP DELAY TO DRIVER OUTPUTS VALID

$V_{D I^{\prime}}=0$
$V_{S D}=5 \mathrm{~V}$ TO 0 AT 1kHz

## 土15kV ESD-Protected, Isolated RS-485/RS-422 Data Interfaces

Pin Description

| PIN |  | NAME | FUNCTION |
| :---: | :---: | :---: | :---: |
| MAX1480EA/ MAX1480EC | MAX1490EA/ MAX1490EB |  |  |
| 1, 2, 8, 10 | 1, 2, 8, 10 | $\mathrm{V}_{\text {CC1 }}-\mathrm{V}_{\text {CC4 }}$ | Logic-Side (Nonisolated Side) +5V Supply Voltages |
| 3, 4 | 3, 4 | D1, D2 | Internal Connections. Leave these pins unconnected. |
| 5 | 5 | GND1 | Logic-Side Ground. Connect to GND2 (pin 12). |
| 6 | 6 | FS | Frequency Select Input. If FS = VCC_ or is open, switch frequency is high; if FS = GND, switch frequency is low. For optimal performance and minimal supply current, connect FS to VCC_ or leave unconnected. |
| 7 | 7 | SD | Shutdown Input. Ground for normal operation. When high, the power oscillator is disabled. |
| 9 | 9 | DI | Driver Input. With DE' high (MAX1480EA/MAX1480EC only), a low on DI' forces output A low and output B high. Similarly, a high on DI' forces output A high and output B low. Drives internal LED cathode through a resistor (see Table 1 for MAX1480EA/MAX1480EC, Table 2 for MAX1490EA/MAX1490EB). |
| 11 | - | DE | Driver-Enable Input. The driver outputs, A and B , are enabled by bringing $\mathrm{DE}{ }^{\prime}$ high. The driver outputs are high impedance when DE' is low. If the driver outputs are enabled, the device functions as a line driver. While the driver outputs are high impedance, the device functions as a line receiver. Drives internal LED cathode through a resistor (Table 1). |
| - | 11 | RO | Receiver Output. If $A>B$ by $200 \mathrm{mV}, \mathrm{RO}$ is high; if $A<B$ by $200 \mathrm{mV}, R O$ is low. Open collector; must have pullup to $\mathrm{V}_{\mathrm{CC}}$ (Table 2). |
| 12 | 12 | GND2 | Logic-Side Ground. Connect to GND1 (pin 5). |
| 13 | - | $\overline{\mathrm{RO}}$ | Receiver Output. If $A>B$ by $200 \mathrm{mV}, \overline{\mathrm{RO}}$ is low; if $A<B$ by $200 \mathrm{mV}, \overline{\mathrm{RO}}$ is high. Open collector; must have pullup to $\mathrm{V}_{\mathrm{CC}}$ (Table 1). |
| 14 | - | VCC5 | Logic-Side (Nonisolated Side) +5V Supply Voltage |
| 15 | 13 | ISO RO LED | Isolated Receiver Output LED. Internal LED anode in MAX1480EA/MAX1480EC and LED cathode in MAX1490EA/MAX1490EB. Connect to ISO RO DRV through a resistor (Table 1 for MAX1480EA/MAX1480EC; Table 2 for MAX1490EA/MAX1490EB). |
| 16 | - | ISO COM2 | Isolated Common. Connect to ISO COM1 (pin 20). |
| 17 | - | ISO DE DRV | Isolated Driver-Enable Drive. The driver outputs, A and B, are enabled by bringing $D E^{\prime}$ high. The driver outputs are high impedance when DE' is low. If the driver outputs are enabled, the device functions as a line driver. While the driver outputs are high impedance, the device functions as a line receiver. Open-collector output; must have pullup to ISO VCC_ and be connected to ISO DE IN for normal operation (Table 1). |
| 18 | 14 | ISO VCC2 | Isolated Supply Voltage. Connect to ISO VCC1 (pin 26 for MAX1480EA/ MAX1480EC, or pin 22 for MAX1490EA/MAX1490EB). |
| 19 | 15 | ISO DI DRV | Isolated Driver-Input Drive. With DE' high (MAX1480EA/MAX1480EC only), a low on DI' forces output A low and output B high. Similarly, a high on DI' forces output A high and output B low. Connect to ISO DI IN (on the MAX1480EA/MAX1480EC only) for normal operation. Open-collector output; connect a pullup resistor to ISO VCC_ (Table 1 for MAX1480EA/MAX1480EC, Table 2 for MAX1490EA/MAX1490EB). |
| 20 | 16 | ISO COM1 | Isolated Common. For MAX1480EA/MAX1480EC, connect to ISO COM2 (pin 16) (Figures 1 and 2). |

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Pin Description（continued）

| PIN |  | FUNCTION |  |
| :---: | :---: | :---: | :--- |
| MAX1480EA／ <br> MAX1480EC | MAX1490EA／ <br> MAX1490EB |  |  |
| - | 17 | Y | Noninverting Driver Output |
| - | 18 | $Z$ | Inverting Driver Output |
| - | 19 | $B$ | Inverting Receiver Input |
| - | 20 | A | Noninverting Receiver Input |
| 21 | - | ISO DE IN | Isolated Driver－Enable Input．Connect to ISO DE DRV for normal operation． |
| 22 | - | ISO DI IN | Isolated Driver Input．Connect to ISO DI DRV for normal operation． |
| 23 | - | A | Noninverting Driver Output and Noninverting Receiver Input |
| 24 | 21 | ISO RO DRV | Isolated Receiver－Output Drive．Connect to ISO RO LED through a resistor（see <br> Table 1 for MAX1480EA／MAX1480EC，Table 2 for MAX1490EA／MAX1490EB）． |
| 25 | - | B | Inverting Driver Output and Inverting Receiver Input |
| 26 | 22 | ISO VCC1 | Isolated Supply Voltage Source |
| 27,28 | 23,24 | AC2，AC1 | Internal Connections．Leave these pins unconnected． |

Note：For DE＇and DI＇pin descriptions，see Detailed Block Diagram and Typical Application Circuit（Figure 1 for MAX1480EA／ MAX1480EC，Figure 2 for MAX1490EA／MAX1490EB）．

## Detailed Description

The MAX1480EA／MAX1480EC／MAX1490EA／MAX1490EB are complete，electrically isolated，RS－485／RS－422 data－ communications interface solutions．Transceivers，opto－ couplers，a power driver，and a transformer in one standard 28 －pin DIP package（ 24 －pin package for the MAX1490EA／MAX1490EB）provide a complete inter－ face．Signals and power are internally transported across the isolation barrier（Figures 1，2）．Power is transferred from the logic side（nonisolated side）to the isolated side of the barrier through a center－tapped transformer．Signals cross the barrier through high－ speed optocouplers．A single +5 V supply on the logic side powers both sides of the interface．The MAX1480EA／MAX1480EC offer half－duplex communica－ tions while the MAX1490EA／MAX1490EB feature full－ duplex communication．The functional input／output relationships are shown in Tables 3 through 6.
The MAX1480EC／MAX1490EB feature reduced－slew－rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables，allowing error－free transmission at data rates up to 160 kbps ．The MAX1480EA／MAX1490EA driver slew rate is not limited， allowing transmission rates up to 2.5 Mbps ．
The MAX1480EC／MAX1490EB shutdown feature reduces supply current to as low as $0.2 \mu \mathrm{~A}$ by using the SD pin（see Low－Power Shutdown Mode section）．

Drivers are short－circuit current limited and are protect－ ed against excessive power dissipation by thermal shutdown circuitry that puts the driver outputs into a high－impedance state．The receiver input has a fail－safe feature that guarantees a logic－high RO（logic－low $\overline{\mathrm{RO}}$ ） output if the input is open circuit．
On the MAX1480EA／MAX1480EC，the driver outputs are enabled by bringing DE＇high．Driver－enable time is typi－ cally $1.0 \mu \mathrm{~s}$ ．Allow time for the devices to be enabled before sending data（see Typical Operating Characteristics）．When enabled，driver outputs function as line drivers．Driver outputs are high impedance when DE＇is low．When outputs are high impedance，they func－ tion as line receivers．
The MAX1480EA／MAX1480EC／MAX1490EA／MAX1490EB withstand $1260 V_{\text {RMS }}$（ 1 min ）or $1520 V_{\text {RMS }}$（1s）．The logic inputs can be driven from TTL／CMOS logic with a series resistor，and the received data output can directly drive TTL or CMOS－logic families with only a resistive pullup．

## Low－Power Shutdown Mode

The SD pin shuts down the oscillator on the internal power driver．With the primary side in shutdown，no power is transferred across the isolation barrier．The DI and DE optocouplers，however，still consume current if the drive signals on the nonsolated side are low．Therefore，leave DI＇and DE＇high or floating when in shutdown mode． Under these conditions，the MAX1480EC／MAX1490EB supply current is reduced to as low as $0.2 \mu \mathrm{~A}$ ．

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Figure 1. MAX1480EA/MAX1480EC Detailed Block Diagram and Application Circuit
Table 1. Pullup and LED Drive Resistors for Figure 1

| PART | R1 $\boldsymbol{\Omega} \mathbf{)}$ | R2 $(\boldsymbol{\Omega})$ | R3 $(\boldsymbol{\Omega})$ | R4 $(\boldsymbol{\Omega})$ | R5 $(\boldsymbol{\Omega})$ | R6 $(\boldsymbol{\Omega})$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MAX1480EA | 200 | 200 | 1000 | 4300 | 1000 | 200 |
| MAX1480EC | 200 | 200 | 3000 | 3000 | 3000 | 200 |

The high-speed optocouplers on the MAX1480EA/ MAX1480EC/MAX1490EA consume an additional 10mA through VCC5 (VCC4 for the MAX1490EA). Therefore, to completely shut down these devices, use an external Pchannel MOSFET as shown in Figure 3. In normal operation, SD is low, turning the MOSFET on and thereby providing power to all the VCC pins. When SD is pulled high, the power oscillator is disabled and the switch is turned off, disconnecting power from the DI and DE opto-
couplers. In normal operating mode, the switch carries only the optocoupler currents, so an on-resistance of several ohms does not significantly degrade efficiency.

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Figure 2．MAX1490EA／MAX1490EB Detailed Block Diagram and Typical Application Circuit
Table 2．Pullup and LED Drive Resistors for Figure 2

| PART | R1 $\boldsymbol{\Omega} \boldsymbol{)}$ | R2 $(\boldsymbol{\Omega})$ | R3 $(\boldsymbol{\Omega})$ | R4（ $\boldsymbol{\Omega})$ |
| :---: | :---: | :---: | :---: | :---: |
| MAX1490EA | 200 | 1000 | 330 | 1000 |
| MAX1490EB | 200 | 3000 | 330 | 3000 |

## MAX1480EC／MAX1490EB： Reduced EMI and Reflections

The MAX1480EC／MAX1490EB are slew－rate－limited， minimizing EMI and reducing reflections caused by improperly terminated cables．Figure 11 shows both the driver output waveform of a MAX1480EA／ MAX1490EA transmitting a 150 kHz signal and the Fourier analysis of that waveform．High－frequency har－ monics with large amplitudes are evident．Figure 12 shows the same information for the slew－rate－limited

MAX1480EC／MAX1490EB transmitting the same signal． The high－frequency harmonics have much lower ampli－ tudes，and therefore the potential for EMI is significantly reduced．

Driver Output Protection
There are two mechanisms to prevent excessive output current and power dissipation caused by faults or by bus contention．A foldback current limit on the output stage provides immediate protection against short cir－

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Figure 3. MAX1480EA Low-Power Shutdown Mode


Figure 4. Driver DC Test Load


Figure 5. Driver/Receiver Timing Test Circuit

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Figure 6. Driver Timing Test Load
Switching Waveforms


Figure 7. Driver Propagation Delays and Transition Times


Figure 9. Times to/from Shutdown


Figure 8. Driver Enable and Disable Times


Figure 10. Receiver Propagation Delays

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cuits over the entire common－mode range（see Typical Operating Characteristics）．In addition，a thermal shut－ down circuit forces the driver outputs into a high－im pedance state if the die temperature rises excessively．

## Propagation Delay Skew

Propagation delay skew is the difference between the low－to－high and high－to－low propagation delay．Small driver／receiver skew times help reduce EMI and reflec－ tions by maintaining balanced differential signals．


Figure 11．Driver Output Waveform and FFT Plot of MAX1480EA／MAX1490EA Transmitting a 150kHz Signal


Figure 12．Driver Output Waveform and FFT Plot of MAX1480EC／MAX1490EB Transmitting a 150kHz Signal

Function Tables
Half－Duplex Devices （MAX1480EA／MAX1480EC）

Table 3．Transmitting

| INPUTS $^{\star}$ |  | OUTPUTS |  |
| :---: | :---: | :---: | :---: |
| $\mathbf{D E}^{\boldsymbol{*}}$ | $\mathbf{D I}^{\boldsymbol{*}}$ | $\mathbf{B}$ | $\mathbf{A}$ |
| 1 | 1 | 0 | 1 |
| 1 | 0 | 1 | 0 |
| 0 | $X$ | High－Z | High－Z |

$X=$ Don＇t care；High－Z＝High impedance

Table 4．Receiving

| INPUTS $^{\boldsymbol{*}}$ |  | OUTPUT <br> （RO） |
| :---: | :---: | :---: |
| DE＇$^{\boldsymbol{\prime}}$ | $\mathbf{V}_{\mathbf{A}}-\mathbf{V}_{\mathbf{B}}$ |  |
| 0 | $\geq+0.2 \mathrm{~V}$ | 0 |
| 0 | $\leq-0.2 \mathrm{~V}$ | 1 |
| 0 | Open | 0 |

Full－Duplex Devices （MAX1490EA／MAX1490EB）

Table 5．Transmitting

| INPUT $^{*}$ <br> （DI＇） | OUTPUTS |  |
| :---: | :---: | :---: |
|  | $\mathbf{Z}$ | $\mathbf{Y}$ |
| 1 | 0 | 1 |
| 0 | 1 | 0 |

＊For DE＇and DI＇pin descriptions，see Detailed Block Diagram and Typical Application Circuit（Figure 1 for MAX1480EA／ MAX1480EC，Figure 2 for MAX1490EA／MAX1490EB）．

Table 6．Receiving

| INPUT <br> $\left(\mathbf{V}_{\mathbf{A}}-\mathbf{V}_{\mathbf{B}}\right)$ | OUTPUT <br> $(\mathbf{R O})$ |
| :---: | :---: |
| $\geq+0.2 \mathrm{~V}$ | 1 |
| $\leq-0.2 \mathrm{~V}$ | 0 |
| Open | 1 |

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## Applications Information

These E versions of the MAX1480EA/MAX1480EC/ 1490EA/MAX1490EB provide extra protection against ESD. The rugged MAX1480EA/MAX1480EC/MAX1490EA/ MAX1490EB are intended for harsh environments where high-speed communication is important. These devices eliminate the need for transient suppressor diodes or the use of discrete protection components. The standard (non-E) MAX1480A/MAX1480C/MAX1490A/MAX1490B are recommended for applications where cost is critical.

## 士15kV ESD Protection

As with all Maxim devices, ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver outputs and receiver inputs have extra protection against static electricity. Maxim's engineers developed state-of-the-art structures to protect these pins against ESD of $\pm 15 \mathrm{kV}$ without damage. The ESD structures withstand high ESD in all states: normal operation, shutdown, and powered down. After an ESD event, Maxim's MAX1480EA/MAX1480EC/MAX1490EA/ MAX1490EB keep working without latchup. An isolation capacitor of 270 pF 4 kV should be placed between ISO COM and logic ground for optional performance against an ESD pulse with respect to logic ground.
ESD protection can be tested in various ways; the transmitter outputs and receiver inputs of this product family are characterized for protection to $\pm 15 \mathrm{kV}$ using the Human Body Model.

ESD Test Conditions
The $\pm 15 \mathrm{kV}$ ESD test specifications apply only to the A, B, Y , and Z I/O pins. The test surge may be referenced to either the ISO COM or to the nonisolated GND (Figures 1 and 2).


Figure 13. Human Body ESD Test Model

## Human Body Model

Figure 13 shows the Human Body Model, and Figure 14 shows the current waveform it generates when discharged into low impedance. This model consists of a 100 pF capacitor charged to the ESD voltage of interest, which is then discharged into the test device through a $1.5 \mathrm{k} \Omega$ resistor.

## Machine Model

The Machine Model for ESD tests all pins using a 200pF storage capacitor and zero discharge resistance. Its objective is to simulate the stress caused by contact that occurs with handling and assembly during manufacturing. All pins require this protection during manufactur-ing-not just inputs and outputs. Therefore, after PC board assembly, the Machine Model is less relevant to I/O ports.
The MAX1480EA/MAX1480EC are designed for bidirectional data communications on multipoint bus-transmission lines. The MAX1490EA/MAX1490EB are designed for full-duplex bidirectional communications that are primarily point-to-point. Figures 15 and 16 show half-duplex and full-duplex typical network application circuits, respectively. To minimize reflections, terminate the line at both ends with its characteristic impedance, and keep stub lengths off the main line as short as possible. The slew-rate-limited MAX1480EC/MAX1490EB are more tolerant of imperfect termination and stubs off the main line.

## Layout Considerations

The MAX1480EA/MAX1480EC/MAX1490EA/MAX1490EB pinouts enable optimal PC board layout by minimizing interconnect lengths and crossovers:

- For maximum isolation, the "isolation barrier" should not be breached except by the MAX1480EA/


Figure 14. Human Body Current Waveform

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Figure 15. Typical Half-Duplex RS-485/RS-422 Network

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Figure 16. Typical Full-Duplex RS-485/RS-422 Network

MAX1480EC/MAX1490EA/MAX1490EB. Connections and components from one side should not be located near those of the other side.

- A shield trace connected to the ground on each side of the barrier can help intercept capacitive currents that might otherwise couple into the signal path. In a double-sided or multilayer board, these shield traces should be present on all conductor layers.
- Try to maximize the width of the isolation barrier wherever possible; a clear space of at least 0.25 inches between ground and isolated common is suggested.


## Pullup and LED Drive Resistors

The MAX1480EA/MAX1480EC/MAX1490EA/MAX1490EB are specified and characterized using the resistor values shown in Tables 1 and 2. Altering the recommended values can degrade performance.
DI and DE are intended to be driven through a series current-limiting resistor. Directly grounding these pins destroys the device.
The DI and DE (MAX1480EA/MAX1480EC only) inputs are the cathodes of LEDs whose anodes are connected to the supply. These points are best driven by a CMOSlogic gate with a series resistor to limit the current. The
resistor values shown in Tables 1 and 2 are recommended when the 74 HC 86 gate or equivalent is used. These values may need to be adjusted if a driving gate with dissimilar series resistance is used.
All pullup resistors are based on optocoupler specifications in order to optimize the devices' data-transfer rates.

Isolated Common Connection
The isolated common may be completely floating with respect to the logic ground and the effective network ground. The receiver input resistors cause the isolated common voltage to go to the mean voltage of the receiver inputs. If using shielded cable, connect the isolated common to the shield through a $100 \Omega$ resistor. In the case of the MAX1490EA/MAX1490EB, each shield should have its own $100 \Omega$ resistor (Figures 1, 2, 15, and 16).

## Double-Isolated RS-485 Repeater

The RS-422/RS-485 standard is specified for cable lengths up to 4000 feet. When approaching or exceeding the specified maximum cable length, a ground-potential difference of several tens of volts can easily develop. This difference can be either DC, AC, at power-line frequency, or any imaginable noise or impulse waveform. It is typically very low impedance so that if a connection between the two grounds is attempted, very large cur-

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rents may flow. These currents are by their nature unstable and unpredictable. In addition, they may cause noise to be injected into sensitive instrumentation and, in severe cases, might actually cause physical damage to such equipment.
Figure 17 shows a half-duplex (2-wire), bidirectional, party-line repeater system that prevents interference and/or damage from ground-potential differences. Two MAX1480EA/MAX1480EC isolated RS-485 transceivers are used to isolate each of the network segments from the electrical environment of the repeater. The MAX1480EA/MAX1480EC also regenerate bus signals that may have been degraded by line attenuation or dispersion.
In the idle state, both transmitters are disabled, while all receivers in the system are enabled. If any device on the system has information for any other device, it starts sending its data onto the bus. Each data transmission on the bus retriggers the one-shot, keeping the sending transmitter enabled until there are no more transmissions. All receivers receive all data; if this is undesirable, the protocol must allow for an address field so receivers can ignore data not directed to them.
Each node must refrain from transmitting when data already exists on the bus, and must resend data that is
corrupted by the collisions that inevitably occur with a party-line system. With the repeater of Figure 17, there might be transmitters up to 8000 feet apart. That represents more than $8 \mu \mathrm{~s}$ (assuming $1 \mathrm{~ns} /$ foot of delay) in which two nodes could be transmitting simultaneously.
The circuit in Figure 17 can be used either directly as shown, with the slew-rate-limited MAX1480EC, for data transfer rates up to 160kbps, or with the MAX1480EA for data rates up to 2.5 Mbps (see Table 1 for pullup and LED resistor values when using the MAX1480EA). If dualport isolation is not needed, one of the MAX1480EC devices can be replaced by a MAX487E for 250kbps applications.

## Reliability

These products contain transformers, optocouplers, and capacitors, in addition to several monolithic ICs and diodes. As such, the reliability expectations more closely represent those of discrete optocouplers rather than the more robust characteristics of monolithic silicon ICs. The reliability testing programs for these multicomponent devices may be viewed on the Maxim website (www.maxim-ic.com) under Technical Support, Technical Reference, Multichip Products.


Figure 17. Double-Isolated RS-485 Repeater

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## Ordering Information（continued）

| PART $^{\dagger}$ | TEMP．RANGE | PIN－PACKAGE |
| :--- | ---: | :--- |
| MAX1480ECCPI | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 28 Wide Plastic DIP |
| MAX1480ECEPI | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 28 Wide Plastic DIP |
| MAX1490EACPG | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 24 Wide Plastic DIP |
| MAX1490EAEPG | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 24 Wide Plastic DIP |
| MAX1490EBCPG | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | 24 Wide Plastic DIP |
| MAX1490EBEPG | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 24 Wide Plastic DIP |

$\dagger$ Data rate for A parts is up to 2500 kbps ．Data rate for $C$ parts is up to 250kbps．

Pin Configurations（continued）


This device is constructed using a unique set of packaging techniques that impose a limit on the thermal profile the device can be exposed to during board－level solder attach and rework．Maxim recommends the use of the solder profiles rec－ ommended in the industry－standard specification，JEDEC 020A，paragraph 7．6，Table 3 for IR／VPR and Convection Reflow processes．Preheating，per this standard，is required． Hand or wave soldering is not recommended．

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