

# ST6040/41

# 8 BIT HCMOS MCUS WITH A/D CONVERTER & LCD DRIVER

#### PRELIMINARY DATA

8-BIT ARCHITECTURE

STATIC HCMOS OPERATION

3.0 TO 6.0 V SUPPLY OPERATING RANGE

3.25US TCYCLE (with 4 MHz clock)

RUN, WAIT & STOP MODES

■ USER ROM: ■ RESERVED ROM: 3876 BYTES 220 BYTES

DATA ROM :DATA RAM :

64 BYTES 64 BYTES

■ 44-PIN PLASTIC PLCC PACKAGE (ST6040)

 48-PIN PLASTIC DUAL IN LINE PACKAGE (ST6041)

■ 15 PUSH-PULL BIDIRECTIONAL IN-PUTS/OUTPUTS WITH 5mA DRIVING CAPA-BILITY (ST6040)

■ 16 PUSH-PULL BIDIRECTIONAL IN-PUTS/OUTPUTS WITH 5mA DRIVING CAPA-BILITY (ST6041)

■ TWO 8-BIT COUNTER WITH A 7-BIT PRO-GRAMMABLE PRESCALER (Timer)

 DIGITAL SOFTWARE ACTIVATED WATCH-DOG/TIMER (DSWD)

 8-BIT A/D CONVERTER WITH 3 ANALOG IN-PUTS

 18 LINES LCD DRIVER WITH 2:1 MULTIPLEX-ING (36 segments driving, ST6040)

 20 LINES LCD DRIVER WITH 2:1 MULTIPLEX-ING (40 segments driving, ST6041)

 ONE EXTERNAL RISING EDGE SENSITIVE IN-TERRUPT INPUT (ST6040)

 ONE EXTERNAL FALLING EDGE SENSITIVE INTERRUPT INPUT (ST6041)

ON-CHIP CLOCK OSCILLATOR

POWER-ON RESET

BYTE EFFICIENT INSTRUCTION SET

BIT TEST AND JUMP INSTRUCTIONS

 WAIT, STOP AND BIT MANIPULATION IN-STRUCTIONS

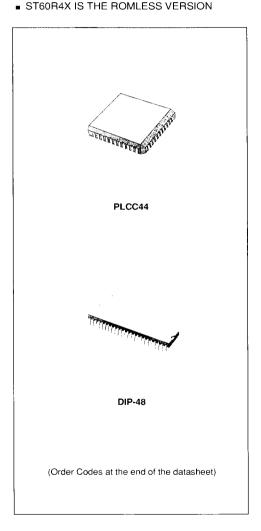
■ TRUE LIFO 4 LEVEL STACK

9 POWERFUL ADDRESSING MODES

■ THE ACCUMULATOR, THE X, Y, V & W REGISTERS, THE PORT AND PERIPHERALS DATA/CONTROL REGISTERS ARE ADDRESSED IN THE DATA SPACE AS RAM LOCATIONS

■ THE DEVELOPMENT TOOL OF THE ST604X MICROCONTROLLERS CONSISTS OF THE EMS6-HW/B4X EMULATION AND DEVELOP-

MENT SYSTEM CONNECTED VIA A STAND-ARD RS232 SERIAL LINE TO AN MS-DOS PC



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Figure 1: ST6040 Pin Configuration.

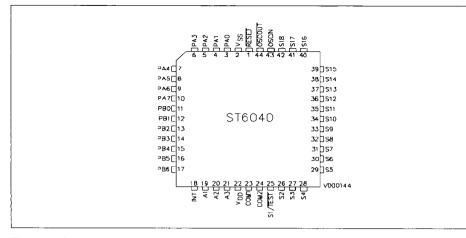
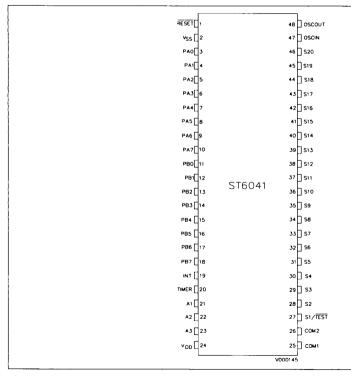


Figure 2: ST6041 Pin Configuration.



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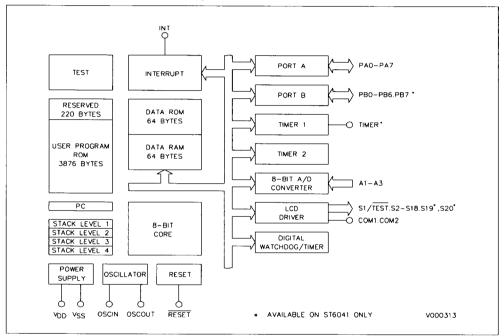
SGS-THOMSON MICROELECTRONICS

#### GENERAL DESCRIPTION

The ST6040 and ST6041 microcontrollers are powerful members of the 8-bit HCMOS ST60XX family, a series of devices oriented to low-medium complexity applications. All ST60XX members are based on a building block approach: to a common core is associated a combination of on-chip peripherals (macrocells) available from a standard library to form around the core all the existing and future ST6 devices. These peripherals are designed with the same core technology giving full compatibility,

short design and testing time. The macrocells of the ST6040/ST6041 are: two Timers each including an 8-bit counter with a 7-bit software programmable prescaler (Timer), the 8-bit A/D Converter with 3 analog inputs, the liquid crystal display driver (LCD) with 18x2 (ST6040) and 20x2 (ST6041) lines (36/40 segments), the software activated digital watchdog/timer (DSWD). Thanks to these peripherals the ST6040/ST6041 are well suited to consumer, automotive and industrial controls applications.

Figure 3: ST6040 and ST6041 Block Diagram.



#### PIN DESCRIPTION

 $V_{DD}$  and  $V_{SS}$ . Power is supplied to the MCU using these two pins.  $V_{DD}$  is power and  $V_{SS}$  is the ground connection.

**OSCIN**, **OSCOUT**. These pins are internally connected with the on-chip oscillator circuit. A crystal quartz or a ceramic resonator has to be connected between these two pins in order to allow a right operating of the MCU. The OSCIN pin is the input pin, the OSCOUT pin is the output pin.

**RESET.** The active low RESET pin is used to restart the microcontroller at the beginning of its program.

**INT.** The INT pin provides the capability for asynchronous applying an external interrupt to the MCU. This pin is rising edge sensitive on ST6040 and falling edge sensitive on ST6041.

**PA0-PA7.** These 8 lines are organized as one I/O port (A). Each line may be configured as either an input or an output under software control of the data direction register. Port A has a push-pull output configuration with 5mA drive capability and schmitt trigger inputs.

**PB0-PB6,PB7 (\*).** These 8 lines are organized as one I/O port (B). Each line may be configured as either an input or an output under software control of the data direction register. Port B has a push-pull

output configuration with 5mA drive capability and schmitt trigger inputs. (\*) PB7 is available only on ST6041.

**TIMER** (\*). This is the Timer 1 I/O pin. In input mode it is connected to the prescaler and acts as external timer clock (DOUT=TOUT=0) or as control gate for the internal timer clock (DOUT=1,TOUT=0). In the output mode the timer pin outputs the data bit when a time out occurs. (\*) This pin is available only on ST6041.

**A1-A3.** These pins are the analog inputs for the onchip 8-bit A/D converter. The user can select by software which analog channel has to be converted.

**COM1, COM2.** These two pins are the LCD peripheral common outputs. They are the outputs of the on-chip backplane voltage generator which is used for multiplexing the 18/20 LCD lines allowing 36/40 segments driving.

S1/TEST. This pin is the LCD driver segment 1 output but also enables the factory test mode if tied low when Reset is active. The test mode is used to place the MCU into special operating mode.

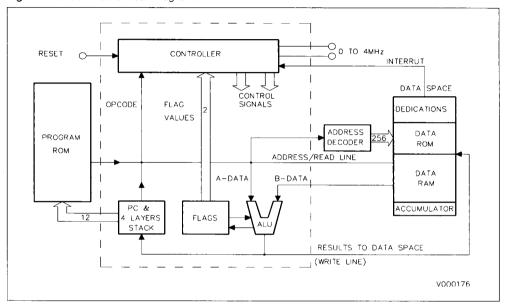
S2-S18,S19(\*),S20(\*). These pins are the LCD driver segments outputs 2 to 20. (\*) S19 and S20 are available only on ST6041.

#### ST60XX CORE

The Core of the ST60XX Family is implemented independently from the I/O or memory configuration. Consequently, it can be treated as an independent central processor communicating with I/O and memory via internal addresses, data, and control buses. The in-core communications are arranged

Figure 4: ST60XX Core Block Diagram.

as shown in the following block diagram figure; the controller being externally linked to both the reset and the oscillator while the core is linked to the dedicated on-chip macrocells peripherals via the serial data bus and indirectly for interrupt purposes, through the control registers.



#### INPUT/OUTPUT PORT

The ST6040 and ST6041 microcontrollers have respectively 15 and 16 Input/Output lines that can be individually programmed either in the input mode or the output mode. The lines are organized in two ports (port A,B). The ports occupies four registers in the data space there being two registers, the DATA registers (DRA, DRB), used to read the logic level values of the lines programmed in the input mode

or to write the logic value of the signal to be output on the lines configured in the output mode, and two DATA DIRECTION registers (DDRA, DDRB), that allow the selection of the direction of each pin (input or output). In input mode the data register remains unchanged as the logic value at port pins is read directly into the shift register of the port macrocell.

#### **TIMERS**

The ST6040 and ST6041 offer two on-chip Timer peripherals each consisting of an 8-bit counter with a 7-bit programmable prescaler, thus giving a maximum count of 2<sup>15</sup>, and a control logic that allows configuring the peripheral in three operating modes. Timer 1 of ST6041 has the external TIMER pin available for the user. The content of the 8-bit counter can be read/written in the Timer/Counter register

TCR that can be addressed in the data space as RAM location at the 13H (timer 1) and 16H (timer 2) addresses. The state of the 7-bit prescaler can be read in the PSC register at the 12H (timer 1) and 15H (timer 2) addresses. The control logic device can be managed thanks to the TSCR register (14H timer 1 and 17H timer2 addresses).

### SOFTWARE ACTIVATED DIGITAL WATCHDOG/TIMER

The software activated digital watchdog/timer consists of a down counter that can be used to provide a controlled recovery from a software upset or as a simple 7-bit timer for general purpose counting. The watchdog/timer is using one data space register (DSWDR location 18H). The watchdog register is set to FEH after reset and the watchdog function is disabled. If the user is using the cell as a watchdog

the watchdog time can be programmed using the 6 MSBits in the Watchdog/timer register; if the user selects the timer option there are 7 available counter bits. This is because when the cell is used as watchdog function bit 1 of the register is used for managing the watchdog. The check time can be set differently for different routines within the general program.

#### 8-BIT A/D CONVERTER

The ST6040 and ST6041 A/D converter is an 8-bit analog to digital converter with 3 analog inputs offering 8-bit resolution with  $\pm$  1/2 bit of linearity and a conversion time of 150uS (clock frequency of 4MHz).

The ST6040 and ST6041 A/D peripheral converts by a process of successive approximations using a clock frequency from 100 to 500Khz. The clock is derived from the oscillator with a division factor of twelve.

#### LIQUID CRYSTAL DISPLAY DRIVER LCD

The Liquid Crystal Display Driver macrocell is based on an eight segment driver which can be multiplexed by the use of two backplanes. The ST6040 and

ST6041 LCD allows two-lines multiplexed operation of 18 and 20 segments pair allowing direct driving of 36/40 segments.

#### **DEVELOPMENT SUPPORT & EMULATION SYSTEM**

The ST60XX development system offers powerful in-circuit emulator and easy-to-use sets (dedicated boards) of modular hardware and software tools to shorten the total system development time of the final application. The ST60XX emulator offers emulation power with plug-in flexibility in the selection of

emulation hardware modules for the dedicated macrocells. The emulator can be interfaced with a standard RS232 serial link to industry standard MS-DOS personal computers. The ST60R4X romless version is also available to provide flexibility in prototypes or pre-production.

#### ABSOLUTE MAXIMUM RATINGS

This product contains devices to protect the inputs against damage due to high static voltages, however it is advised to take normal precaution to avoid application of any voltage higher than maximum rated voltages. For proper operation it is recom-

mended that  $V_1$  and  $V_0$  must be higher than  $V_{SS}$  and smaller than  $V_{DD}$ . Reliability is enhanced if unused inputs are connected to an appropriated logic voltage level ( $V_{DD}$  or  $V_{SS}$ ).

Symbol	Parameter	Value	Unit
$V_{DD}$	Supply Voltage	- 0.3 to 7.0	V
V <sub>1</sub>	Input Voltage	$V_{SS} - 0.3 \text{ to } V_{DD} + 0.3$	V
Vo	Output Voltage	$V_{SS} - 0.3 \text{ to } V_{DD} + 0.3$	V
lo	Current Drain per Pin Excluding V <sub>DD</sub> & V <sub>SS</sub>	± 10	mA
$IV_{DD}$	Total Current into V <sub>DD</sub> (source)	50	mA
IVss	Total Current out of V <sub>SS</sub> (sink)	50	mA
PD	Power Dissipation	30	mW
ESD	ESD Susceptibility	2000 <sup>(1)</sup>	V
T <sub>stg</sub>	Storage Temperature	- 65 to 150	∘c

Notes: 1. MIL 883B Mode, 100pF through 1.5KΩ.

# RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
TA	Operating Temperature	6 Version 7 Version	- 40 - 40		85 110	°C °C
$V_{DD}$	Operating Supply Voltage		3		6	V
fosc	Oscillator Frequency	$V_{DD} = 4.5 - 6.0V$	0		4	MHz
fosc	Oscillator Frequency	V <sub>DD</sub> = 3.5V	0		1	MHz
fosc	Oscillator Frequency	V <sub>DD</sub> = 3.0V	0		0.5	MHz
AV <sub>DD</sub> AV <sub>SS</sub>	Analog Supply Voltage		Vss		V <sub>DD</sub>	٧

Note: On ST6040/ST6041 AV<sub>DD</sub> and AV<sub>SS</sub> are internally connected to digital  $V_{SS}$  and  $V_{DD}$ .

#### THERMAL CHARACTERISTICS

R <sub>th(J-A)</sub>	Thermal Resistance P-DIP	Max.	65	°C/W
	PLCC		85	!



Stresses above those listed as "absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

#### POWER CONSIDERATIONS

The average chip-junction temperature, Tj, in Celsius can be obtained from :

 $Tj = TA + PD \times RthJA$ 

where: TA = Ambient Temperature,

RthJA = Package thermal resistance (junction-to-ambient.

PD = Pint + Pport.

Pint =  $I_{DD} \times V_{DD}$  (chip internal power),

Pport = Port power dissipation (determined by the user).

For most applications, Pport < Pint and the former can be neglected. Pport may become significant if

the device is configured to drive darlington bases or sink LED loads. An approximate relationship between PD and TJ (if Pport is neglected) is:

PD = K (TJ + 273).

Solving previous equations gives:

 $K = PD \times (TA + 273) + RthJA \times PD^2$ 

where K is constant pertaining to the particular part. K can be determined from the equation by measuring PD for a know TA. Using this value of K the values of PD and TJ can be obtained by solving first equations iteratively for any value of TA.

#### DC ELECTRICAL CHARACTERISTICS

 $T_A = -40$  to 85°C unless otherwise specified.

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V <sub>P</sub>	Positive Threshold	All I/O Lines $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$	1.8 2.8 3.6	2.0 3.2 4.0	2.2 3.8 4.4	V
V <sub>N</sub>	Negative Threshold	All I/O Lines $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$	1.1 1.6 2.0	1.3 2.0 2.4	1.5 2.4 2.8	٧
V <sub>H</sub>	Hysteresis Voltage	All I/O Lines $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$	0.6 0.9 1.1	0.8 1.2 1.6	0.9 1.4 1.8	٧
V <sub>IL</sub>	Input Low Level Voltage	RESET PIN $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$			0.90 1.35 1.65	٧
V <sub>IL</sub>	Input Low Level Voltage	INT PIN $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$			0.90 1.35 1.65	٧
V <sub>IH</sub>	Input High Level Voltage	RESET PIN $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$	2.10 3.15 3.85			٧
V <sub>IH</sub>	Input High Level Voltage	INT PIN $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$	2.10 3.15 3.85			V
V <sub>OL</sub>	Low Level Output Voltage	All I/O Lines $I_O < 1\mu A$ $V_{DD} = 3.0V$ $V_{DD} = 5.5V$			0.1 0.1	٧
V <sub>OL</sub>	Low Level Output Voltage	All I/O Lines $I_{OL} < 5mA$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$			0.8 0.8	V
V <sub>OH</sub>	High Level Output Voltage	All I/O Lines I <sub>O</sub> < $1\mu$ A $V_{DD} = 3.0V$ $V_{DD} = 5.5V$	2.9 5.4			٧
V <sub>OH</sub>	High Level Output Voltage	All I/O Lines $I_{OH} = -5mA$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$	3.0 4.0			V

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SGS-THOMSON MICROELECTRONICS

# DC ELECTRICAL CHARACTERISTICS (continued)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
t <sub>IL</sub> , t <sub>IH</sub>	Input Leakage Current	All Digital Inputs Vin = V <sub>DD</sub> or V <sub>SS</sub>				μА
		$V_{DD} = 3.0V$ $V_{DD} = 5.5V$		0.1 0.1	1.0 1.0	
$I_{\rm IL},I_{\rm IH}$	Input Leakage Current	All A/D Conv. Inputs Vin = V <sub>DD</sub> or V <sub>SS</sub>				μА
		$V_{DD} = 3.0V$ $V_{DD} = 5.5V$		0.1 0.1	1.0 1.0	
Von	Trigger Level ON Voltage	RESET $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$			1.0 1.5 1.7	٧
V <sub>OFF</sub>	Trigger Level ON Voltage	RESET $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$	2.0 3.0 3.8			٧
I <sub>DD</sub>	Supply Current RUN Mode	$ Load = 0mA $ $F_{osc} = 0.5MHz$ $V_{DD} = 3.0V$ $F_{osc} = 4MHz$ $V_{DD} = 5.5V$			3.5 5.0	mA mA
I <sub>DD</sub>	Supply Current WAIT Mode	ILoad = 0mA Fosc = 0.5MHz			5.0	IIIA
		$V_{DD} = 3.0V$ $F_{osc} = 4MHz$ $V_{DD} = 5.5V$			1.7 2.5	mA
IDD	Supply Current STOP Mode	Note ILoad = 0mA			2.5	mA
.00	The state of the s	$V_{DD} = 3.0V$ $V_{DD} = 5.5V$			20 30	μA μA

# AC ELECTRICAL CHARACTERISTICS

 $T_A = -40$  to  $85^{\circ}$ C unless otherwise specified.

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
fosc	Oscillator Frequency	Crystal or External Clock $V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$	DC DC DC		0.5 4 4	
tsu	Oscillator Start-up Time	$V_{DD} = 3.0V$ $V_{DD} = 4.5V$ $V_{DD} = 5.5V$			15 10 10	mS
CIN	Input Capacitance	All Inputs Pins	-		10	pF
Соит	Output Capacitance	All Output Pins			15	pF



# A/D ELECTRICAL CHARACTERISTICS

 $T_A = -40$  to 85°C unless otherwise specified.

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
Res	Resolution		8	8	8	Bit
Lin	Non Linearity	Max Deviation from the Best Straight Line			± 1/2	LSB
Qe	Quantization Error	Uncertainly due to converter resolution.			± 1/2	LSB
ZO	Zero Offset Error	V <sub>I</sub> = AV <sub>SS</sub>			1	LSB
FSO	Full Scale Error	$V_1 = AV_{DD}$			1	LSB
tc	Conversion Time	fosc = 4MHz <sup>(1)</sup>		150		μs
VAN	Conversion Range		AVSS		AVDD	V
ZIR	Zero Input Reading	Conversion result when $V_1 = AV_{SS}$ .	00			Hex
FSR	Full Scale Reading	Conversion result when $V_1 = AV_{DD}$ .			FF	Hex
AV <sub>SS</sub> AV <sub>DD</sub>	Analog Reference	(2)	Vss		V <sub>DD</sub>	V
AC <sub>IN</sub>	Analog Input Capacitance				5	pF
ASI	Analog Source Impedance				30	ΚΩ
SSI	Analog Refer. Supply Imped.				2	ΚΩ

Notes: 1. With oscillator frequencies less than 1.2MHz, the A/D converter accuracy is decreased.

2. In ST6040/ST6041 Devices Analog V<sub>SS</sub> and V<sub>DD</sub> are internally connected to digital V<sub>SS</sub> and V<sub>DD</sub>.

#### TIMER CHARACTERISTICS

 $T_A = -40$  to 85°C unless otherwise specified.

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
Res	Resolution		1 fo . 12			s
f <sub>IN</sub>	Input Frequency at TIMER Pin	V <sub>DD</sub> = 3.0V V <sub>DD</sub> = 4.5V		1/4 fosc		MHz

Note: Timer pin is available only on ST6041 timer 1.

# LCD DRIVER CHARACTERISTICS

 $T_A = -40$  to 85°C unless otherwise specified.

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
fBP	Backplane Frequency	Fosc = 4MHz V <sub>DD</sub> = 4.5V	80	80	80	Hz
vos	DC Offset Voltage	$V_{\rm DD} = 3.0 \text{V } V_{\rm DD} = 4.5 \text{V}$			50	Μv
V <sub>OL</sub>	Low Level Output Voltage	V <sub>DD</sub> = 4.5V		0.5		V
V <sub>OH</sub>	High Level Output Voltage	V <sub>DD</sub> = 4.5V		0.5		V

# ORDERING INFORMATION

The following chapter deals with the procedure for transfer the Program/Data ROM codes to SGS-THOMSON

Communication of the ROM codes. To communicate the contents of Program/Data ROM memories to SGS-THOMSON, the customer has to send two 2764 EPROM that must be programmed as follows: 0000H-007FH Reserved (Should be filled with FFH) 0080H-0F9FH User program

0FA0H-0FFBH Reserved (Should be filled with FFH)

0FFCH Interrupt vector LOW byte
0FFDH Interrupt vector HIGH byte
0FFEH Reset vector LOW byte
0FFFH Reset vector HIGH byte

The Data ROM codes (64 Bytes) of the microcontroller must be placed in the EPROM from:

1140H-117FH

All unused bytes must be set to FFH. For shipment to SGS-THOMSON the EPROMs should be placed in a conductive IC carrier and packaged carefully.

Listing Generation & Verification. When SGS-THOMSON receives the EPROMs, they are compared and a computer listing is generated from them. This listing refers exactly to the mask that will be used to produce the microcontroller. Then the listing is returned to the customer that must thoroughly check, complete, sign and return it to SGS-THOMSON. SGS-THOMSON will also program one 2764 EPROM from the data file corresponding to the listing to help the customer in its verification. The signed listing constitutes a part of the contractual agreement for the creation of the customer mask. SGS-THOMSON sales organization will provide detailed information on contractual points.

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310040/41			
ST6040 Part Numb	er		
0.00.0		040C6/XX	
Device			Customer ROM Code
Package			Temperature Range
· uonugo			3
Device : ST6040			
Package : C : 44 PLC	С		
Temperature range :	– 40°C to 85°C 6 - 40°C to 110°C 7		
Marking: it is by defa tached option		pe (part number). If a spe	ecial marking is required see a
ST6041 Part Numb	er		
		041B6/XX	
Device		]    [	Customer ROM Code
Package			Temperature Range
Device : ST6041			
Package : B : 48 Plas	tic Dual-in-line		
Temperature range :	– 40°C to 85°C 6 - 40°C to 110°C 7		
		oe (part number). If a spe	ecial marking is required see
tached opti	n list.		
	ST604X MICROCOL	NTROLLER OPTION LIS	ST
Customer			
Address			
Contact		,	
Phone No	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		
Reference			
Device	[] (d)		
Package	[] (p)		
Temperature Range	[] (t)		
For marking two lines	with 10 characters maximur	n are possible	
Special Marking [] (y	n) Line 1 "" (M) Line 2 "" (M)		
[d] $1 = ST6040, 2 = S$	T6041		
[p] B=Plastic Dual in			
(t) $6 = -40 \text{ to } 85^{\circ}\text{C}$			
$7 = -40 \text{ to } 110^{\circ}\text{C}$			
(M) Letters, digits, '.',	'-', '/' and spaces only		
Signature			
Date			
12/12			
12/12	<b> \$77</b> \$	GS-THOMSON	

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