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#### **FEATURES**

- Halts and restarts an out-of-control microprocessor
- Holds microprocessor in check during power transients
- Automatically restarts microprocessor after power failure
- Monitors pushbutton for external override
- Accurate 10% or 20% microprocessor power monitoring
- Eliminates need for discrete components
- 20% tolerance for use with 3.0-volt systems
- Pin-compatible with the DS1232
- Low cost 8-pin DIP, 8-pin SOIC, and space saving μ-SOP packages available
- Industrial temperature range of -40°C to +85°C

#### **PIN ASSIGNMENT**

PBRST	1		8	Ъ	$V_{\text{CC}}$
TD	2	2	7	þ	ST
TOL	[] З		6		RST
GND	4		5	þ	RST
	832 8 Mech				,
		1 (	7		
PBRST	Щ	1	<sup>8</sup>	Π	V <sub>cc</sub>
PBRST TD		1 C	8 7		V <sub>cc</sub> ST
PBRST TD TOL		1 2 3	Ĩ		
PBRST TD TOL GND			7		ST

PBRST []1	8 Vcc
TD [] 2	7 🛛 ST
TOL 🛛 3	6 RST
GND 4	5 🛛 RST

DS1832µ 8-Pin µ-SOP (118-mil) See Mech. Drawings Section

#### **PIN DESCRIPTION**

PBRST	- Pushbutton Reset Input
TD	- Time Delay Set
TOL	- Selects 10% or 20% V <sub>CC</sub> Detect
GND	- Ground
RST	- Active High Reset Output
RST	- Active Low Reset Output
$\overline{ST}$	- Strobe Input
V <sub>CC</sub>	- Power Supply

#### DESCRIPTION

The DS1832 3.3-Volt MicroMonitor monitors three vital conditions for a microprocessor: power supply, software execution, and external override. First, a precision temperature-compensated reference and comparator circuit monitor the status of  $V_{CC}$ . When an out-of-tolerance condition occurs, an internal power-fail signal is generated which forces the resets to an active state. When  $V_{CC}$  returns to an in-tolerance condition, the reset signals are kept in the active state for a minimum of 250 ms to allow the power supply and processor to stabilize.

The second function the DS1832 performs is pushbutton reset control. The DS1832 debounces the pushbutton input and guarantees an active reset pulse width of 250 ms minimum. The third function is a watchdog timer. The DS1832 has an internal timer that forces the reset signals to the active state if the strobe input is not driven low prior to timeout. The watchdog timer function can be set to operate on timeout settings of approximately 150 ms, 600 ms, or 1.2 seconds.

#### **OPERATION - POWER MONITOR**

The DS1832 detects out-of-tolerance power supply conditions and warns a processor-based system of impending power failure. When  $V_{CC}$  falls below a preset level as defined by TOL, the  $V_{CC}$  comparator outputs the signals RST and  $\overline{RST}$ . When TOL is connected to ground, the RST and  $\overline{RST}$  signals become active as  $V_{CC}$  falls below 2.98 volts. When TOL is connected to  $V_{CC}$ , the RST and  $\overline{RST}$  signals become active as  $V_{CC}$  falls below 2.64 volts. The RST and  $\overline{RST}$  are excellent control signals for a microprocessor, as processing is stopped at the last possible moments of valid  $V_{CC}$ . On power-up, RST and  $\overline{RST}$  are kept active for a minimum of 250 ms to allow the power supply and processor to stabilize.

### **OPERATION - PUSHBUTTON RESET**

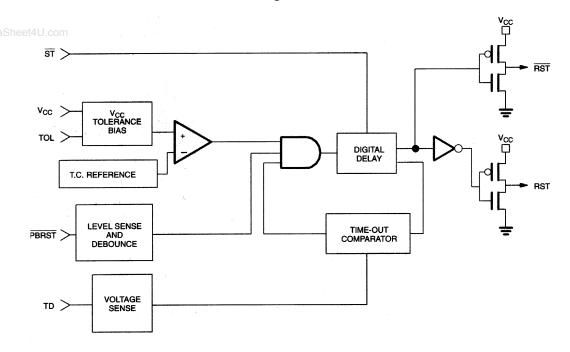
The DS1832 provides an input pin for direct connection to a pushbutton reset (see Figure 2). The pushbutton reset input requires an active low signal. Internally, this input is debounced and timed such that RST and  $\overline{\text{RST}}$  signals of at least 250 ms minimum are generated. The 250 ms delay commences as the pushbutton reset input is released from the low level.

### **OPERATION - WATCHDOG TIMER**

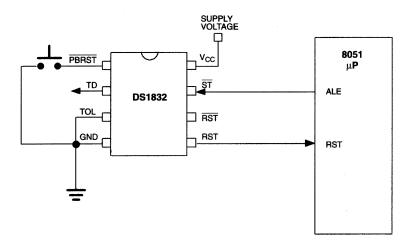
The watchdog timer function forces RST and  $\overline{\text{RST}}$  signals active when the  $\overline{\text{ST}}$  input is not clocked within the predetermined time period. The timeout period is determined by the condition of the TD pin. If TD is connected to ground the minimum watchdog timeout would be 62.5 ms, TD floating would yield a minimum timeout of 250 ms, and TD connected to V<sub>CC</sub> would provide a timeout of 500 ms minimum. Timeout of the watchdog starts when RST and  $\overline{\text{RST}}$  become inactive. If a high-to-low transition occurs on the  $\overline{\text{ST}}$  input pin prior to timeout, the watchdog timer is reset and begins to timeout again. If the watchdog timer is allowed to timeout, then the RST and  $\overline{\text{RST}}$  signals are driven active for a minimum of 250 ms. The  $\overline{\text{ST}}$  input can be derived from many microprocessor outputs. The most typical signals used are the microprocessor address signals, data signals or control signals. When the microprocessor functions normally, these signals would, as a matter of routine, cause the watchdog to be reset prior to timeout. To guarantee that the watchdog timer does not timeout, a high-to-low transition must occur at or less than the minimum times shown in Table 1. A typical circuit example is shown in Figure 4.

The DS1832 watchdog function cannot be disabled. The watchdog strobe input must be strobed to avoid a watchdog timeout and reset.

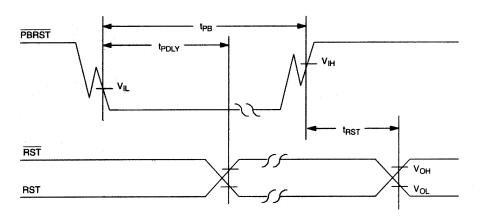
# MICROMONITOR BLOCK DIAGRAM Figure 1



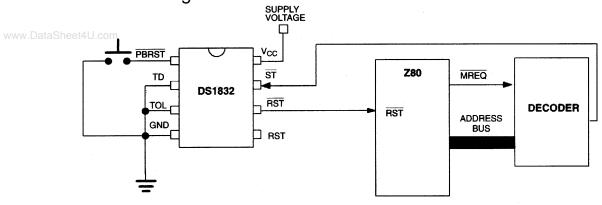
#### **PUSHBUTTON RESET** Figure 2



## TIMING DIAGRAM: PUSHBUTTON RESET Figure 3



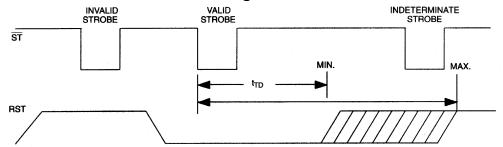
## WATCHDOG TIMER Figure 4



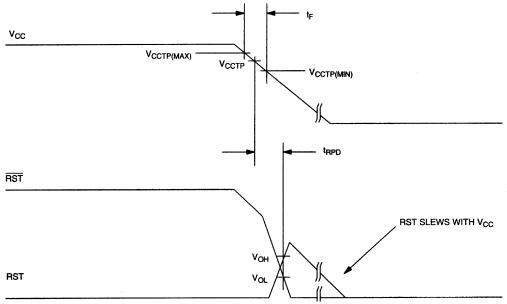
### WATCHDOG TIMEOUTS Table 1

	TIMEOUT				
TD	MIN	ТҮР	MAX		
GND	62.5 ms	150 ms	250 ms		
Float	250 ms	600 ms	1000 ms		
V <sub>CC</sub>	500 ms	1200 ms	2000 ms		

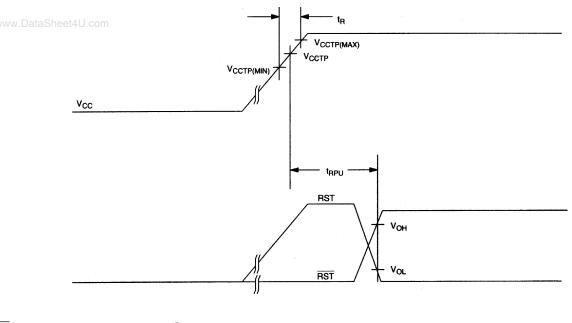
## TIMING DIAGRAM: STROBE INPUT Figure 5



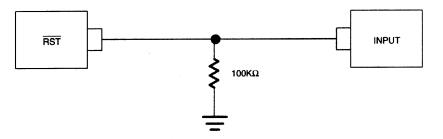
## TIMING DIAGRAM: POWER DOWN Figure 6



## TIMING DIAGRAM: POWER-UP Figure 7



### **RST VALID TO 0 VOLTS V**<sub>cc</sub> Figure 8



### **OUTPUT VALID CONDITIONS**

The RST output uses a push-pull output which can maintain a valid output down to 0.8 volts  $V_{CC}$ . To sink current below 0.8 volts a resistor can be connected from  $\overline{RST}$  to Ground (see Figure 8). This arrangement will maintain a valid value on  $\overline{RST}$  during both power-up and power-down but will draw current when  $\overline{RST}$  is in the high state. A value of about 100 k $\Omega$  should be adequate in most situations. The output with a resistor pull-down can maintain a valid reset down to  $V_{CC}$  equal to 0 volts.

### **ABSOLUTE MAXIMUM RATINGS\***

Voltage on any Pin Relative to Ground Voltage on I/O Relative to Ground Operating Temperature Storage Temperature Soldering Temperature  $\begin{array}{l} -0.5V \ to \ +7.0V \\ -0.5V \ to \ V_{CC} \ +0.5V \\ -40^{\circ}C \ to \ +85^{\circ}C \\ -55^{\circ}C \ to \ +125^{\circ}C \\ 260^{\circ}C \ for \ 10 \ seconds \end{array}$ 

\* This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

RECOMMENDED DC OPERATING CONDITIONS					(-40°C to +85°C)			
PARAMETER	SYMBOL	MIN	ТҮР	MAX	UNITS	NOTES		
Supply Voltage	V <sub>CC</sub>	1.0		5.5	V	1		
ST and PBRST Input High Level	V <sub>IH</sub>	2.0		V <sub>CC</sub> +0.3	V	1, 3		
		$V_{CC}$				1, 4		
		-0.4						
ST and PBRST Input Low Level	V <sub>IL</sub>	-0.3		0.5	V	1		

#### DC ELECTRICAL CHARACTERISTICS

(-40°C to +85°C; V<sub>cc</sub>=1.2V to 5.5V)

PARAMETER	SYMBOL	MIN	ТҮР	MAX	UNITS	NOTES	
V <sub>CC</sub> Trip Point (TOL = GND)	V <sub>CCTP</sub>	2.80	2.88	2.97	V	1	
$V_{CC}$ Trip Point (TOL = $V_{CC}$ )	V <sub>CCTP</sub>	2.47	2.55	2.64	V	1	
Input Leakage	I <sub>IL</sub>	-1.0		+1.0	μA	2	
Output Current @ 2.4V	I <sub>OH</sub>		350		μΑ	3	
Output Current @ 0.4V	I <sub>OL</sub>	10			mA	3	
Output Voltage @ -500 uA	V <sub>OH</sub>	V <sub>CC</sub>	V <sub>CC</sub>		V	4	
		-0.3V	-0.1V				
Operating Current	I <sub>CC</sub>			35	μA	5	

#### CAPACITANCE

(t<sub>A</sub>=25°C)

CAFACITANCE				(LA	(=25  C)	
PARAMETER	SYMBOL	MIN	ТҮР	MAX	UNITS	NOTES
Input Capacitance	C <sub>IN</sub>			5	pF	
Output Capacitance	C <sub>OUT</sub>			7	pF	

AC ELECTRICAL CHARACTERISTICS			(-40°C to +85°C; V <sub>cc</sub> =1.2V to 5.5V)				
PARAMETER	SYMBOL	MIN	ТҮР	MAX	UNITS	NOTES	
$\frac{-WWW.D}{PBRST} = V_{IL}$	t <sub>PB</sub>	20			ms		
RESET Active Time	t <sub>RST</sub>	250	610	1000	ms		
ST Pulse Width	t <sub>ST</sub>	20			ns	6, 7	
$V_{CC}$ Detect to RST and $\overline{RST}$	t <sub>RPD</sub>		5	8	μs	8	
V <sub>CC</sub> Slew Rate	t <sub>F</sub>	20			μs		
$V_{CC}$ Detect to RST and $\overline{RST}$	t <sub>RPU</sub>	250	610	1000	ms	9	
V <sub>CC</sub> Slew Rate	t <sub>R</sub>	0			ns		
$\overrightarrow{\text{PBRST}} \text{ Stable Low to } \overrightarrow{\text{RST}} \text{ and } \overrightarrow{\text{RST}}$	t <sub>PDLY</sub>			20	ms		

#### NOTES:

- 1. All voltages referenced to ground.
- 2.  $\overline{PBRST}$  is internally pulled up to V<sub>CC</sub> with an internal impedance of 40 k $\Omega$  typical.
- 3. Measured with  $V_{CC} \ge 2.7V$ .
- 4. Measured with  $V_{CC} < 2.7 V$ .
- 5. Measured with outputs open,  $V_{CC} \le 3.6$  volts, and all inputs at  $V_{CC}$  or Ground.
- 6. Must not exceed  $t_{TD}$  minimum.
- 7. The Watchdog cannot be disabled it must be strobed to avoid resets.
- 8. Noise immunity Pulses  $< 2 \ \mu s$  at V<sub>CCTP</sub> minimum will not cause a reset.
- 9.  $t_R = 5 \ \mu s$ .

#### **MARKING INFORMATION:**

8-pin DIP - "DS1832" 8-pin SOIC - "DS1832" 8-pin - μ-SOP - "1832"