

# Ultrafast SiGe Voltage Comparators

# ADCMP580/ADCMP581/ADCMP582

#### **FEATURES**

180 ps propagation delay
25 ps overdrive and slew rate dispersion
8 GHz equivalent input rise time bandwidth
100 ps minimum pulse width
37 ps typical output rise/fall
10 ps deterministic jitter (DJ)
200 fs random jitter (RJ)
-2 V to +3 V input range with +5 V/-5 V supplies
On-chip terminations at both input pins
Resistor-programmable hysteresis
Differential latch control
Power supply rejection > 70 dB

#### **APPLICATIONS**

Automatic test equipment (ATE)
High speed instrumentation
Pulse spectroscopy
Medical imaging and diagnostics
High speed line receivers
Threshold detection
Peak and zero-crossing detectors
High speed trigger circuitry
Clock and data signal restoration

#### **FUNCTIONAL BLOCK DIAGRAM**

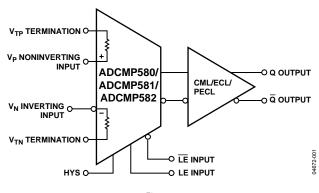


Figure 1.

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#### **GENERAL DESCRIPTION**

The ADCMP580/ADCMP581/ADCMP582 are ultrafast voltage comparators fabricated on Analog Devices' proprietary XFCB3 Silicon Germanium (SiGe) bipolar process. The ADCMP580 features CML output drivers; the ADCMP581 features reduced swing ECL (negative ECL) output drivers; and the ADCMP582 features reduced swing PECL (positive ECL) output drivers.

All three comparators offer 180 ps propagation delay and 100 ps minimum pulse width for 10 Gbps operation with 200 fs random jitter (RJ). Overdrive and slew rate dispersion are typically less than 15 ps.

The  $\pm 5$  V power supplies enable a wide -2 V to +3 V input range with logic levels referenced to the CML/NECL/PECL outputs. The inputs have 50  $\Omega$  on-chip termination resistors with the optional capability to be left open (on an individual pin basis) for applications requiring high impedance input.

The CML output stage is designed to directly drive 400 mV into 50  $\Omega$  transmission lines terminated to ground. The NECL output stages are designed to directly drive 400 mV into 50  $\Omega$  terminated to -2 V. The PECL output stages are designed to directly drive 400 mV into 50  $\Omega$  terminated to  $V_{\rm CCO}-2$  V. High speed latch and programmable hysteresis are also provided. The differential latch input controls are also 50  $\Omega$  terminated to an independent  $V_{\rm TT}$  pin to interface to either CML or ECL or to PECL logic.

The ADCMP580/ADCMP581/ADCMP582 are available in a 16-lead LFCSP package.

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#### **REVISION HISTORY**

7/05—Revision 0: Initial Version

### **SPECIFICATIONS**

 $V_{\text{CCI}}$  = +5.0 V;  $V_{\text{EE}}$  = -5.0 V;  $V_{\text{CCO}}$  = +3.3 V;  $T_{\text{A}}$  = 25°C, unless otherwise noted.

Table 1.

Parameter	Symbol	Condition	Min	Тур	Max	Unit
DC INPUT CHARACTERISTICS						
Input Voltage Range	$V_P, V_N$		-2.0		+3.0	V
Input Differential Range			-2.0		+2.0	V
Input Offset Voltage	Vos		-10.0	±4	+10.0	mV
Offset Voltage Tempco	$\Delta V_{OS}/d_T$			10		μV/°C
Input Bias Current	I <sub>P</sub> , I <sub>N</sub>	Open termination		15	30.0	μA
Input Bias Current Tempco	$\Delta I_B/d_T$			50		nA/°C
Input Offset Current				2	±5.0	μΑ
Input Resistance				47 to 53		Ω
Input Resistance, Differential Mode		Open termination		50		kΩ
Input Resistance, Common Mode		Open termination		500		kΩ
Active Gain	Av			48		dB
Common-Mode Rejection	CMRR	$V_{CM} = -2.0 \text{ V to } +3.0 \text{ V}$		60		dB
Hysteresis		R <sub>HYS</sub> = ∞		1		mV
LATCH ENABLE CHARACTERISTICS						
Latch Enable Input Impedance	Z <sub>IN</sub>	Each pin, V <sub>TT</sub> at ac ground		47 to 53		Ω
Latch to Output Delay	t <sub>PLOH</sub> , t <sub>PLOL</sub>	$V_{OD} = 200 \text{ mV}$		175		ps
Latch Minimum Pulse Width	t <sub>PL</sub>	$V_{OD} = 200 \text{ mV}$		100		ps
ADCMP580 (CML)						
Latch Enable Input Range			-0.8		0	V
Latch Enable Input Differential			0.2	0.4	0.5	V
Latch Setup Time	ts	V <sub>OD</sub> = 200 mV		95		ps
Latch Hold Time	t <sub>H</sub>	$V_{OD} = 200 \text{ mV}$		-90		ps
ADCMP581 (NECL)						
Latch Enable Input Range			-1.8		+0.8	V
Latch Enable Input Differential			0.2	0.4	0.5	V
Latch Setup Time	t <sub>s</sub>	V <sub>OD</sub> = 200 mV		70		ps
Latch Hold Time	t <sub>H</sub>	$V_{OD} = 200 \text{ mV}$		-65		ps
ADCMP582 (PECL)						'
Latch Enable Input Range			V <sub>cco</sub> – 1.8		$V_{\text{CCO}} - 0.8$	V
Latch Enable Input Differential			0.2	0.4	0.5	V
Latch Setup Time	<b>t</b> s	V <sub>OD</sub> = 200 mV		30		ps
Latch Hold Time	tн	V <sub>OD</sub> = 200 mV		-25		ps
DC OUTPUT CHARACTERISTICS						-
ADCMP580 (CML)						
Output Impedance	Z <sub>OUT</sub>			50		Ω
Output Voltage High Level	V <sub>OH</sub>	50 Ω to GND	-0.10	0	0.03	V
Output Voltage Low Level	V <sub>OL</sub>	50 Ω to GND	-0.50	-0.40	-0.35	V
Output Voltage Differential		50 Ω to GND	340	395	450	mV
ADCMP581 (NECL)						
Output Voltage High Level	V <sub>OH</sub>	50 Ω to -2 V, T <sub>A</sub> = 125°C	-0.99	-0.87	-0.75	V
Output Voltage High Level	V <sub>OH</sub>	50 Ω to $-2$ V, $T_A = 25$ °C	-1.06	-0.94	-0.82	V
Output Voltage High Level	V <sub>OH</sub>	50 Ω to -2 V, T <sub>A</sub> = -55°C	-1.11	-0.99	-0.87	V
Output Voltage Low Level	V <sub>OL</sub>	50 Ω to -2 V, T <sub>A</sub> = 125°C	-1.43	-1.26	-1.13	V
Output Voltage Low Level	V <sub>OL</sub>	$50 \Omega$ to $-2 V$ , $T_A = 25$ °C	-1.50	-1.33	-1.20	V
Output Voltage Low Level	Vol	$50 \Omega$ to $-2 V$ , $T_A = -55$ °C	-1.55	-1.38	-1.25	V
Output Voltage Differential		50 Ω to -2.0 V	340	395	450	mV

VOH VOH VOH VOL VOL VOL	$ \begin{array}{l} Vcco = 3.3 \ V \\ 50 \ \Omega \ to \ Vcco - 2 \ V, T_A = 125 ^{\circ} C \\ 50 \ \Omega \ to \ Vcco - 2 \ V, T_A = 25 ^{\circ} C \\ 50 \ \Omega \ to \ Vcco - 2 \ V, T_A = -55 ^{\circ} C \\ 50 \ \Omega \ to \ Vcco - 2 \ V, T_A = 25 ^{\circ} C \\ 50 \ \Omega \ to \ Vcco - 2 \ V, T_A = -55 ^{\circ} C \\ 50 \ \Omega \ to \ Vcco - 2 \ V, T_A = -55 ^{\circ} C \\ 50 \ \Omega \ to \ Vcco - 2 \ V, T_A = -55 ^{\circ} C \\ \end{array} $	Vcco - 0.99 Vcco - 1.06 Vcco - 1.11 Vcco - 1.43 Vcco - 1.50 Vcco - 1.55	Vcco - 0.87 Vcco - 0.94 Vcco - 0.99 Vcco - 1.26 Vcco - 1.33	Vcco - 0.75 Vcco - 0.82 Vcco - 0.87 Vcco - 1.13	V V
Voh Voh Vol Vol	$50 \Omega \text{ to V}_{CCO} - 2 \text{ V, T}_{A} = 25^{\circ}\text{C}$ $50 \Omega \text{ to V}_{CCO} - 2 \text{ V, T}_{A} = -55^{\circ}\text{C}$ $50 \Omega \text{ to V}_{CCO} - 2 \text{ V, T}_{A} = 125^{\circ}\text{C}$ $50 \Omega \text{ to V}_{CCO} - 2 \text{ V, T}_{A} = 25^{\circ}\text{C}$ $50 \Omega \text{ to V}_{CCO} - 2 \text{ V, T}_{A} = -55^{\circ}\text{C}$	Vcco - 1.06 Vcco - 1.11 Vcco - 1.43 Vcco - 1.50	V <sub>CCO</sub> - 0.94 V <sub>CCO</sub> - 0.99 V <sub>CCO</sub> - 1.26	$V_{CCO} - 0.82$ $V_{CCO} - 0.87$	V
V <sub>OL</sub> V <sub>OL</sub> V <sub>OL</sub>	$\begin{array}{l} 50 \ \Omega \ to \ V_{CCO} - 2 \ V, T_A = -55 ^{\circ} C \\ 50 \ \Omega \ to \ V_{CCO} - 2 \ V, T_A = 125 ^{\circ} C \\ 50 \ \Omega \ to \ V_{CCO} - 2 \ V, T_A = 25 ^{\circ} C \\ 50 \ \Omega \ to \ V_{CCO} - 2 \ V, T_A = -55 ^{\circ} C \end{array}$	V <sub>CCO</sub> - 1.11 V <sub>CCO</sub> - 1.43 V <sub>CCO</sub> - 1.50	V <sub>CCO</sub> – 0.99 V <sub>CCO</sub> – 1.26	$V_{\text{CCO}} - 0.87$	
V <sub>OL</sub> V <sub>OL</sub> V <sub>OL</sub>	$\begin{array}{l} 50 \ \Omega \ to \ V_{CCO} - 2 \ V, T_A = -55 ^{\circ} C \\ 50 \ \Omega \ to \ V_{CCO} - 2 \ V, T_A = 125 ^{\circ} C \\ 50 \ \Omega \ to \ V_{CCO} - 2 \ V, T_A = 25 ^{\circ} C \\ 50 \ \Omega \ to \ V_{CCO} - 2 \ V, T_A = -55 ^{\circ} C \end{array}$	V <sub>CCO</sub> – 1.43 V <sub>CCO</sub> – 1.50	V <sub>CCO</sub> – 1.26		V
V <sub>OL</sub>	50 Ω to $V_{CCO}$ – 2 V, $T_A$ = 25°C 50 Ω to $V_{CCO}$ – 2 V, $T_A$ = -55°C	V <sub>cco</sub> – 1.50		Vcco - 1 13	
V <sub>OL</sub>	50 Ω to $V_{CCO}$ – 2 V, $T_A$ = 25°C 50 Ω to $V_{CCO}$ – 2 V, $T_A$ = -55°C		Vcco – 1.33		V
V <sub>OL</sub>	$50 \Omega$ to $V_{CCO} - 2 V$ , $T_A = -55$ °C			V <sub>CCO</sub> – 1.20	V
			V <sub>CCO</sub> – 1.35	V <sub>CCO</sub> – 1.25	V
ton		340	395	450	mV
† <sub>BD</sub>					
LPIJ	V <sub>OD</sub> = 500 mV		180		ps
					ps/°C
_ , , , , , ,	V <sub>OD</sub> = 500 mV, 5 V/ns		10		ps
	50 mV < V <sub>OD</sub> < 1.0 V		10		ps
	10 mV < V <sub>OD</sub> < 200m V		15		ps
	2 V/ns to 10 V/ns		15		ps
	100 ps to 5 ns		15		ps
	•		10		ps
					ps/V
$BW_{FO}$					GHz
	$t_R = t_F = 25 \text{ ps}, 20/80$				
	>50% output swing		12.5		Gbps
DJ	V <sub>OD</sub> = 500 mV, 5 V/ns PRBS <sup>31</sup> – 1 NRZ, 5 Gbps		15		ps
DJ	V <sub>OD</sub> = 200 mV, 5 V/ns PRBS <sup>31</sup> – 1 NRZ, 10 Gbps		25		ps
RJ	V <sub>OD</sub> = 200 mV, 5 V/ns, 1.25 GHz		0.2		ps
$PW_{MIN}$	$\Delta t_{PD} < 5 \text{ ps}$		100		ps
$PW_{MIN}$	$\Delta t_{PD} < 10 \text{ ps}$		80		ps
$t_{R_r}$ $t_{F}$	20/80		37		ps
$V_{CCI}$		+4.5	+5.0	+5.5	V
$V_{\text{EE}}$		-5.5	-5.0	-4.5	V
I <sub>VCCI</sub>	$V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to GND}$		6	8	mA
I <sub>VEE</sub>	$V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to GND}$	-50	-40	-34	mA
			230		mW
Ivccı	$V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } -2 \text{ V}$		6	8	mA
		-35			mA
	•				mW
. 5					
Vcco		+25	+3.3	+50	٧
	$V_{ccl} = +5.0 \text{ V}. 50 \text{ O to } V_{cco} - 2 \text{ V}$				mA
					mA
	· ·	_35			mA
					mW
				330	dB
					dВ
					dB dB
	DJ  RJ  PW <sub>MIN</sub> PW <sub>MIN</sub> t <sub>R</sub> , t <sub>F</sub> V <sub>CCI</sub> V <sub>EE</sub>	$V_{OD} = 500 \text{ mV}, 5 \text{ V/ns}$ $50 \text{ mV} < V_{OD} < 1.0 \text{ V}$ $10 \text{ mV} < V_{OD} < 200 \text{ mV}$ $2 \text{ V/ns to } 10 \text{ V/ns}$ $100 \text{ ps to } 5 \text{ ns}$ $1.0 \text{ V/ns}, 15 \text{ MHz}, V_{CM} = 0.0 \text{ V}$ $V_{OD} = 0.2 \text{ V}, -2 \text{ V} < V_{CM} < 3 \text{ V}$ $0.0 \text{ V to } 400 \text{ mV input}$ $t_R = t_F = 25 \text{ ps, } 20/80$ $>50\% \text{ output swing}$ $DJ \qquad V_{OD} = 500 \text{ mV}, 5 \text{ V/ns}$ $PRBS^{31} - 1 \text{ NRZ}, 5 \text{ Gbps}$ $DJ \qquad V_{OD} = 200 \text{ mV}, 5 \text{ V/ns}$ $PRBS^{31} - 1 \text{ NRZ}, 10 \text{ Gbps}$ $RJ \qquad V_{OD} = 200 \text{ mV}, 5 \text{ V/ns, } 1.25 \text{ GHz}$ $PW_{MIN} \qquad \Delta t_{PD} < 5 \text{ ps}$ $PW_{MIN} \qquad \Delta t_{PD} < 10 \text{ ps}$ $t_R, t_F \qquad 20/80$ $V_{CCI} \qquad V_{EE} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to GND}$ $P_D \qquad 50 \Omega \text{ to GND}$ $I_{VCCI} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } -2 \text{ V}$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to } -2 \text{ V}$ $V_{CCO} \qquad I_{VCCI} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} -2 \text{ V}$ $V_{CCO} \qquad I_{VCCI} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} -2 \text{ V}$ $V_{CCO} \qquad I_{VCCI} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} -2 \text{ V}$ $V_{CCO} \qquad I_{VCCI} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} -2 \text{ V}$ $V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} -2 \text{ V}$ $V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} -2 \text{ V}$ $P_D \qquad 50 \Omega \text{ to } V_{CCO} -2 \text{ V}$ $P_D \qquad 50 \Omega \text{ to } V_{CCO} -2 \text{ V}$ $V_{CCI} = 5.0 \text{ V} + 5\%$ $PSR_{VCCI} \qquad V_{CCI} = 5.0 \text{ V} + 5\%$	$V_{OD} = 500 \text{ mV}, 5 \text{ V/ns}$ $50 \text{ mV} < V_{OD} < 1.0 \text{ V}$ $10 \text{ mV} < V_{OD} < 200 \text{ mV}$ $2 \text{ V/ns to } 10 \text{ V/ns}$ $100 \text{ ps to } 5 \text{ ns}$ $1.0 \text{ V/ns}, 15 \text{ MHz}, V_{CM} = 0.0 \text{ V}$ $V_{OD} = 0.2 \text{ V}, -2 \text{ V} < V_{CM} < 3 \text{ V}$ $0.0 \text{ V to } 400 \text{ mV} \text{ input}$ $t_R = t_F = 25 \text{ ps}, 20/80$ $> 50\% \text{ output swing}$ $DJ \qquad V_{OD} = 500 \text{ mV}, 5 \text{ V/ns}$ $PRBS^{31} - 1 \text{ NRZ}, 5 \text{ Gbps}$ $DJ \qquad V_{OD} = 200 \text{ mV}, 5 \text{ V/ns}$ $PRBS^{31} - 1 \text{ NRZ}, 10 \text{ Gbps}$ $RJ \qquad V_{OD} = 200 \text{ mV}, 5 \text{ V/ns}, 1.25 \text{ GHz}$ $PW_{MIN} \qquad \Delta t_{PD} < 5 \text{ ps}$ $PW_{MIN} \qquad \Delta t_{PD} < 5 \text{ ps}$ $PW_{MIN} \qquad \Delta t_{PD} < 10 \text{ ps}$ $t_R, t_F \qquad 20/80$ $V_{CCI} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to GND}$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to GND}$ $I_{VCCI} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to GND}$ $I_{VCCI} \qquad V_{CEI} = +5.0 \text{ V}, 50 \Omega \text{ to } -2 \text{ V}$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to } -2 \text{ V}$ $V_{DE} \qquad V_{CCO} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{CCO} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{CCO} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{CCO} \qquad V_{CCI} = +5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{CE} \qquad V_{CEI} = -5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V}, 50 \Omega \text{ to } V_{CCO} - 2 \text{ V}$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V} + 5\%$ $V_{EE} \qquad V_{EE} = -5.0 \text{ V} + 5\%$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

<sup>&</sup>lt;sup>1</sup> Equivalent input bandwidth assumes a simple first-order input response and is calculated with the following formula:  $BW_{EQ} = 0.22/(tr_{COMP}^2 - tr_{N}^2)$ , where  $tr_{N}$  is the 20/80 transition time of a quasi-Gaussian input edge applied to the comparator input and  $tr_{COMP}$  is the effective transition time digitized by the comparator.

### **TIMING INFORMATION**

Figure 2 shows the ADCMP580/ADCMP581/ADCMP582 compare and latch timing relationships. Table 2 provides the definitions of the terms shown in the figure.

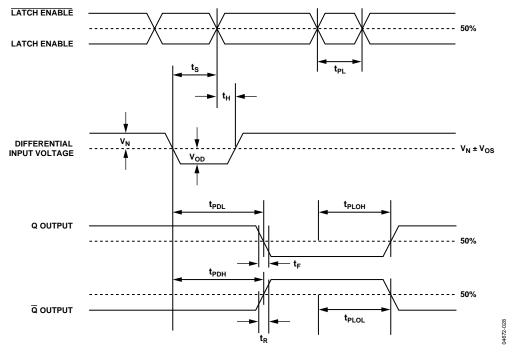


Figure 2. Comparator Timing Diagram

**Table 2. Timing Descriptions** 

Symbol	Timing	Description
<b>t</b> PDH	Input to Output High Delay	Propagation delay measured from the time the input signal crosses the reference (± the input offset voltage) to the 50% point of an output low-to-high transition.
t <sub>PDL</sub>	Input to Output Low Delay	Propagation delay measured from the time the input signal crosses the reference (± the input offset voltage) to the 50% point of an output high-to-low transition.
<b>t</b> <sub>PLOH</sub>	Latch Enable to Output High Delay	Propagation delay measured from the 50% point of the latch enable signal low-to-high transition to the 50% point of an output low-to-high transition.
<b>t</b> <sub>PLOL</sub>	Latch Enable to Output Low Delay	Propagation delay measured from the 50% point of the latch enable signal low-to-high transition to the 50% point of an output high-to-low transition.
tн	Minimum Hold Time	Minimum time after the negative transition of the latch enable signal that the input signal must remain unchanged to be acquired and held at the outputs.
<b>t</b> <sub>PL</sub>	Minimum Latch Enable Pulse Width	Minimum time that the latch enable signal must be high to acquire an input signal change.
<b>t</b> s	Minimum Setup Time	Minimum time before the negative transition of the latch enable signal that an input signal change must be present to be acquired and held at the outputs.
t <sub>R</sub>	Output Rise Time	Amount of time required to transition from a low to a high output as measured at the 20% and 80% points.
t <sub>F</sub>	Output Fall Time	Amount of time required to transition from a high to a low output as measured at the 20% and 80% points.
$V_N$	Normal Input Voltage	Difference between the input voltages $V_P$ and $V_N$ for output true.
$V_{\text{OD}}$	Voltage Overdrive	Difference between the input voltages $V_P$ and $V_N$ for output false.

### **ABSOLUTE MAXIMUM RATINGS**

Table 3.

Rating
-0.5 V to +6.0 V
-6.0 V to +0.5 V
-0.5 V to +6.0 V
−3.0 V to +4.0 V
-2 V to +2 V
−2.5 V to +5.5 V
−5.5 V to +0.5 V
1 mA
–25 mA
−40 mA
–40 mA
−40°C to +125°C
125°C
−65°C to +150°C

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### THERMAL CONSIDERATIONS

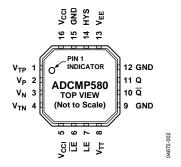
The ADCMP580/ADCMP581/ADCMP582 LFCSP 16-lead package option has a  $\theta_{JA}$  (junction-to-ambient thermal resistance) of 70°C/W in still air.

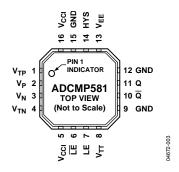
#### **ESD CAUTION**

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



# PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS





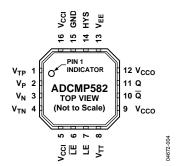


Figure 3. ADCMP580 Pin Configuration

Figure 4. ADCMP581 Pin Configuration

Figure 5. ADCMP582 Pin Configuration

**Table 4. Pin Function Descriptions** 

Pin No.	Mnemonic	Description
1	V <sub>TP</sub>	Termination Resistor Return Pin for VP Input.
2	V <sub>P</sub>	Noninverting Analog Input.
3	V <sub>N</sub>	Inverting Analog Input.
4	V <sub>TN</sub>	Termination Resistor Return Pin for V <sub>N</sub> Input.
5, 16	Vccı	Positive Supply Voltage.
6	ĪĒ	Latch Enable Input Pin, Inverting Side. In compare mode ( $\overline{\text{LE}} = \text{low}$ ), the output tracks changes at the input of the comparator. In latch mode ( $\overline{\text{LE}} = \text{high}$ ), the output reflects the input state just prior to the comparator being placed into latch mode. $\overline{\text{LE}}$ must be driven in complement with LE.
7	LE	Latch Enable Input Pin, Noninverting Side. In compare mode (LE = high), the output tracks changes at the input of the comparator. In latch mode (LE = low), the output reflects the input state just prior to the comparator being placed into latch mode. LE must be driven in complement with LE.
8	V <sub>TT</sub>	Termination Return Pin for the LE/LE Input Pins.
		For the ADCMP580 (CML output stage), this pin should be connected to the GND ground.
		For the ADCMP581 (ECL output stage), this pin should be connected to the –2 V termination potential.
		For the ADCMP582 (PECL output stage), this pin should be connected to the $V_{CCO}$ – 2 V termination potential.
9, 12	GND/Vcco	Digital Ground Pin/Positive Logic Power Supply Terminal.
		For the ADCMP580/ADCMP581, this pin should be connected to the GND pin.
		For the ADCMP582, this pin should be connected to the positive logic power V <sub>CCO</sub> supply.
10	Q	Inverting Output. $\overline{Q}$ is logic low if the analog voltage at the noninverting input, $V_P$ , is greater than the analog voltage at the inverting input, $V_N$ , provided that the comparator is in compare mode. See the $LE/\overline{LE}$ descriptions (Pin 6 to Pin 7) for more information.
11	Q	Noninverting Output. Q is logic high if the analog voltage at the noninverting input, $V_P$ , is greater than the <u>analog</u> voltage at the inverting input, $V_N$ , provided that the comparator is in compare mode. See the <u>LE/LE</u> descriptions (Pin 6 to Pin 7) for more information.
13	V <sub>EE</sub>	Negative Power Supply.
14	HYS	Hysteresis Control. Leave this pin disconnected for zero hysteresis. Connect this pin to the VEE supply with a suitably sized resistor to add the desired amount of hysteresis. Refer to Figure 9 for proper sizing of the HYS hysteresis control resistor.
15	GND	Analog Ground.
Heat Sink Paddle	N/C	The metallic back surface of the package is not electrically connected to any part of the circuit. It can be left floating for optimal electrical isolation between the package handle and the substrate of the die. It can also be soldered to the application board if improved thermal and/or mechanical stability is desired.

### TYPICAL PERFORMANCE CHARACTERISTICS

 $V_{\text{CCI}}$  = +5.0 V,  $V_{\text{EE}}$  = -5.0 V,  $V_{\text{CCO}}$  = +3.3 V,  $T_{\text{A}}$  = 25°C, unless otherwise noted.

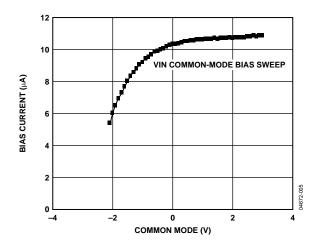


Figure 6. Bias Current vs. Common-Mode Voltage

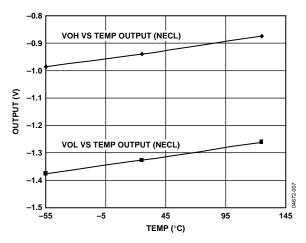


Figure 7. ADCMP581 Output Voltage vs. Temperature

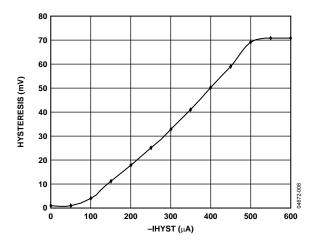


Figure 8. Hysteresis vs. –IHYST

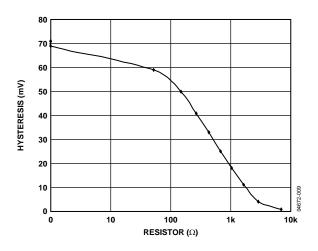


Figure 9. Hysteresis vs. R<sub>HYS</sub> Control Resistor

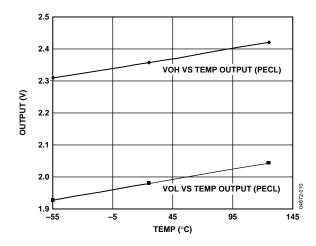


Figure 10. ADCMP582 Output Voltage vs. Temperature

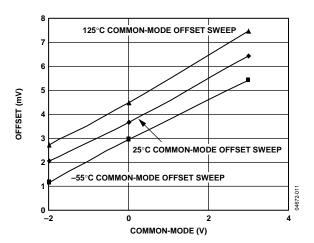


Figure 11. A Typical VOS vs. Common- Mode Voltage

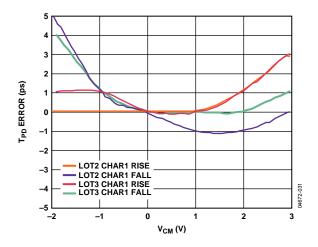


Figure 12. ADCMP580 Prop Delay vs. Common-Mode Voltage

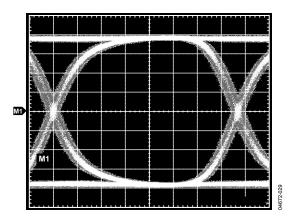


Figure 13. ADCMP580 Eye Diagram at 7.5 Gbps

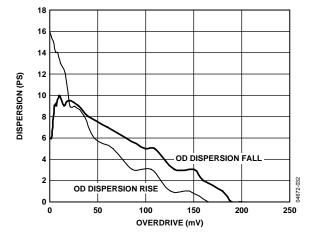


Figure 14. Dispersion vs. Overdrive

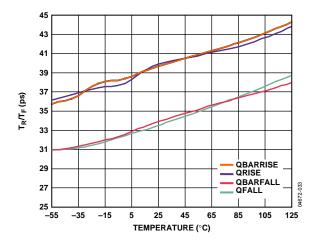


Figure 15. ADCMP581  $T_R/T_F$  vs. Temperature

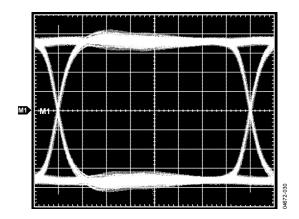


Figure 16. ADCMP582 Eye Diagram at 2.5 Gbps

### TYPICAL APPLICATION CIRCUITS

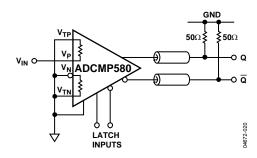


Figure 17. Zero-Crossing Detector with CML Outputs

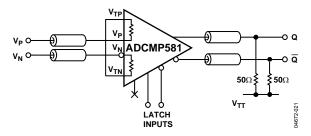


Figure 18. LVDS to a 50  $\Omega$  Back-Terminated (RS) ECL Receiver

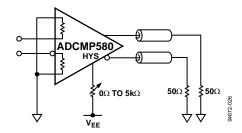


Figure 19. Adding Hysteresis Using the HYS Control

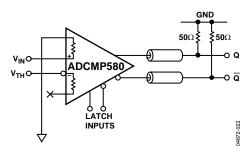


Figure 20. Comparator with -2 to +3 V Input Range

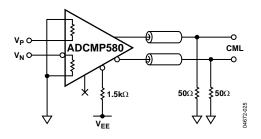


Figure 21. Disabling the Latch Feature on the ADCMP580

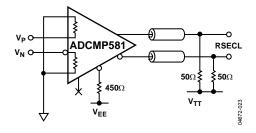


Figure 22. Disabling the Latch Feature on the ADCMP581

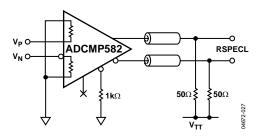


Figure 23. Disabling the Latch Feature on the ADCMP582

#### APPLICATION INFORMATION

#### POWER/GROUND LAYOUT AND BYPASSING

The ADCMP58x family of comparators is designed for very high speed applications. Consequently, high speed design techniques must be used to achieve the specified performance. It is critically important to use low impedance supply planes, particularly for the negative supply ( $V_{\rm EE}$ ), the output supply plane ( $V_{\rm CCO}$ ), and the ground plane (GND). Individual supply planes are recommended as part of a multilayer board. Providing the lowest inductance return path for the switching currents ensures the best possible performance in the target application.

It is also important to adequately bypass the input and output supplies. A 1  $\mu F$  electrolytic bypass capacitor should be placed within several inches of each power supply pin to ground. In addition, multiple high quality 0.1  $\mu F$  bypass capacitors should be placed as close as possible to each of the  $V_{\rm EE}, V_{\rm CCI}$ , and  $V_{\rm CCO}$  supply pins and should be connected to the GND plane with redundant vias. High frequency bypass capacitors should be carefully selected for minimum inductance and ESR. Parasitic layout inductance should be strictly avoided to maximize the effectiveness of the bypass at high frequencies.

#### **ADCMP58x FAMILY OF OUTPUT STAGES**

Specified propagation delay dispersion performance is achieved by using proper transmission line terminations. The outputs of the ADCMP580 family comparators are designed to directly drive 400 mV into 50  $\Omega$  cable or microstrip/stripline transmission lines terminated with 50  $\Omega$  referenced to the proper return. The CML output stage is shown in the simplified schematic diagram in Figure 24. Each output is back-terminated with 50  $\Omega$  for best transmission line matching. The outputs of the ADCMP581/ADCMP582 are illustrated in Figure 25; they should be terminated to -2 V for ECL outputs of ADCMP581 and V<sub>CCO</sub> - 2 V for PECL outputs of ADCMP582. As an alternative, Thevenin equivalent termination networks may also be used. If these high speed signals must be routed more than a centimeter, then either microstrip or stripline techniques are required to ensure proper transition times and to prevent excessive output ringing and pulse width-dependent propagation delay dispersion.

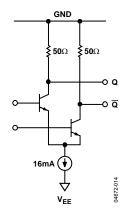


Figure 24. Simplified Schematic Diagram of the ADCMP580 CML Output Stage

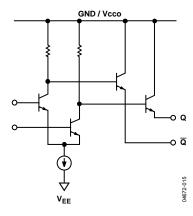


Figure 25. Simplified Schematic Diagram of the ADCMP581/ADCMP582 ECL/PECL Output Stage

#### **USING/DISABLING THE LATCH FEATURE**

The latch inputs (LE/ $\overline{\text{LE}}$ ) are active low for latch mode and are internally terminated with 50  $\Omega$  resistors to the V<sub>TT</sub> pin. When using the ADCMP580, V<sub>TT</sub> should be connected to ground. When using the ADCMP581, V<sub>TT</sub> should be connected to -2 V. When using the ADCMP582, V<sub>TT</sub> should be connected externally to V<sub>CCO</sub> -2 V, preferably with its own low inductance plane.

When using the ADCMP580/ADCMP582, the latch function can be disabled by connecting the  $\overline{LE}$  pin to  $V_{EE}$  with an external pull-down resistor and leaving the LE pin disconnected. To prevent excessive power dissipation, the resistor should be 1.5 k $\Omega$  for the ADCMP580 and 1 k $\Omega$  for the ADCMP582. When using the ADCMP581 comparators, the latch can be disabled by connecting the LE pin to GND with an external 450  $\Omega$  resistor and leaving the  $\overline{LE}$  pin disconnected. The idea is to create an approximate 0.5 V offset using the internal resistor as half of the voltage divider. The  $V_{TT}$  pin should be connected as recommended.

#### **OPTIMIZING HIGH SPEED PERFORMANCE**

As with any high speed comparator, proper design and layout techniques are essential to obtaining the specified performance. Stray capacitance, inductance, inductive power, and ground impedances or other layout issues can severely limit performance and can cause oscillation. Discontinuities along input and output transmission lines can also severely limit the specified pulse width dispersion performance.

For applications in a 50  $\Omega$  environment, input and output matching have a significant impact on data-dependent (or deterministic) jitter (DJ) and pulse width dispersion performance. The ADCMP58x family of comparators provides internal 50  $\Omega$  termination resistors for both  $V_P$  and  $V_N$  inputs. The return side for each termination is pinned out separately with the  $V_{TP}$  and  $V_{TN}$  pins, respectively. If a 50  $\Omega$  termination is desired at one or both of the  $V_P/V_N$  inputs, the  $V_{TP}$  and  $V_{TN}$ pins can be connected (or disconnected) to (from) the desired termination potential as appropriate. The termination potential should be carefully bypassed using ceramic capacitors as discussed previously to prevent undesired aberrations on the input signal due to parasitic inductance in the termination return path. If a 50  $\Omega$  termination is not desired, either one or both of the V<sub>TP</sub>/V<sub>TN</sub> termination pins can be left disconnected. In this case, the open pins should be left floating with no external pull downs or bypassing capacitors.

For applications that require high speed operation but do not have on-chip 50  $\Omega$  termination resistors, some reflections should be expected, because the comparator inputs can no longer provide matched impedance to the input trace leading up to the device. It then becomes important to back-match the drive source impedance to the input transmission path leading to the input to minimize multiple reflections. For applications in which the comparator is less than 1 cm from the driving signal source, the source impedance should be minimized. High source impedance in combination with parasitic input capacitance of the comparator could cause undesirable degradation in bandwidth at the input, thus degrading the overall response. It is therefore recommended that the drive source impedance should be no more than 50  $\Omega$  for best high speed performance.

# COMPARATOR PROPAGATION DELAY DISPERSION

The ADCMP58x family of comparators has been specifically designed to reduce propagation delay dispersion over a wide input overdrive range of 5 mV to 500 mV. Propagation delay dispersion is a change in propagation delays, which results from a change in the degree of overdrive or slew rate (how far or fast the input signal exceeds the switching threshold). The overall result is a higher degree of timing accuracy.

Propagation delay dispersion is a specification that becomes important in critical timing applications, such as data communication, automatic test and measurement, instrumentation, and event-driven applications, such as pulse spectroscopy, nuclear instrumentation, and medical imaging. Dispersion is defined as the variation in the overall propagation delay as the input overdrive conditions are changed (see Figure 26 and Figure 27). For the ADCMP58x family of comparators, dispersion is typically <25 ps, as the overdrive varies from 5 mV to 500 mV, and the input slew rate varies from 1 V/ns to 10 V/ns. This specification applies for both positive and negative signals, because the ADCMP58x family of comparators has almost equal delays for positive- and negative-going inputs.

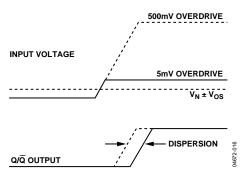


Figure 26. Propagation Delay—Overdrive Dispersion

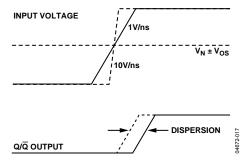


Figure 27. Propagation Delay—Slew Rate Dispersion

#### **COMPARATOR HYSTERESIS**

Adding hysteresis to a comparator is often desirable in a noisy environment or when the differential inputs are very small or slow moving. The transfer function for a comparator with hysteresis is shown in Figure 28. If the input voltage approaches the threshold from the negative direction, the comparator switches from a low to a high when the input crosses  $+V_{\rm H}/2$ . The new switching threshold becomes  $-V_{\rm H}/2$ . The comparator remains in the high state until the threshold  $-V_{\rm H}/2$  is crossed from the positive direction. In this manner, noise centered on 0 V input does not cause the comparator to switch states unless it exceeds the region bounded by  $\pm V_{\rm H}/2$ .

The customary technique for introducing hysteresis into a comparator uses positive feedback from the output back to the input. A limitation of this approach is that the amount of hysteresis varies with the output logic levels, resulting in hysteresis that is not symmetric about the threshold. The external feedback network can also introduce significant parasitics that reduce high speed performance and can even reduce overall stability in some cases.

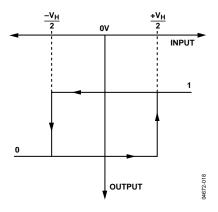


Figure 28. Comparator Hysteresis Transfer Function

The ADCMP58x family of comparators offers a programmable hysteresis feature that can significantly improve the accuracy and stability of the desired hysteresis. By connecting an external pull-down resistor from the HYS pin to  $V_{\text{EE}}$ , a variable amount of hysteresis can be applied. Leaving the HYS pin disconnected disables the feature, and hysteresis is then less than 1 mV, as specified. The maximum range of hysteresis that can be applied by using this method is approximately  $\pm 25$  mV.

Figure 29 illustrates the amount of applied hysteresis as a function of external resistor value. The advantage of applying hysteresis in this manner is improved accuracy, stability, and reduced component count. An external bypass capacitor is not required on the HYS pin and it would likely degrade the jitter performance of the device.

The hysteresis pin may also be driven by a current source. It is biased approximately 400 mV above  $V_{EE}$  and has an internal series resistance of approximately 600  $\Omega$ .

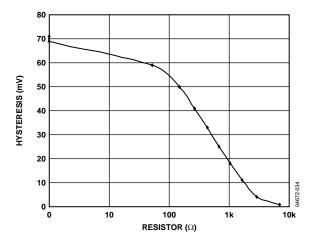


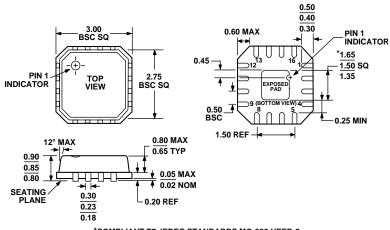
Figure 29. Comparator Hysteresis vs. R<sub>HYS</sub> Control Resistor

#### MINIMUM INPUT SLEW RATE REQUIREMENT

As with many high speed comparators, a minimum slew rate requirement must be met to ensure that the device does not oscillate as the input signal crosses the threshold. This oscillation is due in part to the high input bandwidth of the comparator and the feedback parasitics inherent in the package. A minimum slew rate of 50 V/ $\mu$ s should ensure clean output transitions from the ADCMP58x family of comparators.

The slew rate may be too slow for other reasons. The extremely high bandwidth of these devices means that broadband noise can be a significant factor when input slew rates are low. There is  $120~\mu V$  of thermal noise generated over the comparator's bandwidth by the two  $50~\Omega$  terminations at room temperature. With a slew rate of only  $50~V/\mu s$ , the inputs will be inside this noise band for over 2~ps, rendering the comparator's jitter performance of 200~fs irrelevant. Raising the slew rate of the input signal and/or reducing the bandwidth over which that resistance is seen at the input can greatly reduce jitter. We do not characterize the devices this way, but simply bypassing a reference input close to the package can reduce jitter 30% in low slew rate applications.

### **OUTLINE DIMENSIONS**



\*COMPLIANT TO JEDEC STANDARDS MO-220-VEED-2 EXCEPT FOR EXPOSED PAD DIMENSION.

Figure 30. 16-Lead Lead Frame Chip Scale Package [LFCSP\_VQ] (CP-16-3) Dimensions shown in millimeters

#### **ORDERING GUIDE**

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Model	Temperature Range	Package Description	Package Option	Branding
ADCMP580BCP-WP	-40°C to +125°C	16-LEAD LFCSP-VQ	CP-16-3	GO7
ADCMP580BCP-R2	-40°C to +125°C	16-LEAD LFCSP-VQ	CP-16-3	GO7
ADCMP580BCP-RL7	-40°C to +125°C	16-LEAD LFCSP-VQ	CP-16-3	GO7
ADCMP581BCP-WP	-40°C to +125°C	16-LEAD LFCSP-VQ	CP-16-3	GO9
ADCMP581BCP-R2	-40°C to +125°C	16-LEAD LFCSP-VQ	CP-16-3	GO9
ADCMP581BCP-RL7	-40°C to +125°C	16-LEAD LFCSP-VQ	CP-16-3	GO9
ADCMP582BCP-WP	-40°C to +125°C	16-LEAD LFCSP-VQ	CP-16-3	GOB
ADCMP582BCP-R2	-40°C to +125°C	16-LEAD LFCSP-VQ	CP-16-3	GOB
ADCMP582BCP-RL7	-40°C to +125°C	16-LEAD LFCSP-VQ	CP-16-3	GOB
EVAL-ADCMP580BCP		Evaluation Board		
EVAL-ADCMP581BCP		Evaluation Board		
EVAL-ADCMP582BCP		Evaluation Board		

# **NOTES**

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**Preliminary Technical Data** 

# **NOTES**