

## **KSZ8001L/S**

# 1.8V, 3.3V 10/100BASE-T/TX/FX Physical Layer Transceiver

Data Sheet Rev. 1.04

#### **General Description**

The KSZ8001 is a 10BASE-T/100BASE-TX/100BASE-FX Physical Layer Transceiver, operating the core at 1.8 volts to meet low voltage and low power requirements. The solution provides MII/RMII/SMII interfaces to transmit and receive data. A unique mixed-signal design extends signaling distance while reducing power consumption.

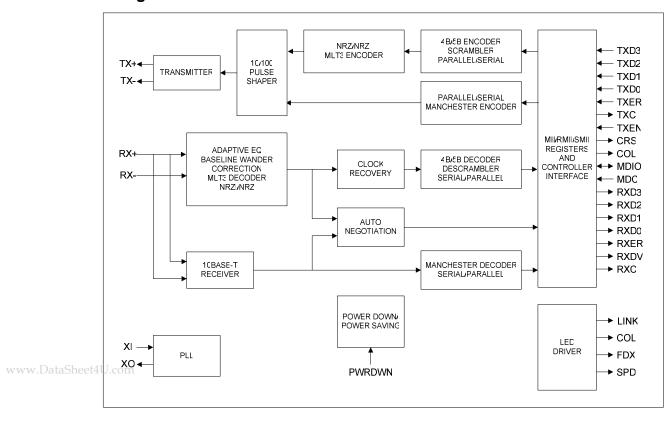
HP Auto MDI/MDI-X provides the most robust solution for eliminating the need to differentiate between crossover and straight-through cables.

Featuring LinkMD cable diagnostics, which allows detection of common cabling plant problems such as open and short circuits, the KSZ8001 represents a new level of features and performance and is an ideal choice of physical layer transceiver for 100BASE-TX/10BASE-T/100BASE-FX applications.

#### **Features**

- Single chip 100BASE-TX/100BASE-FX/10BASE-T physical layer solution
- 1.8V CMOS design, power consumption 250 mW
- Robust (130m+) operation over standard cables
- Supports Media Independent Interface (MII), Reduced MII (RMII), and Serial MII (SMII)
- LinkMD feature to determine cable length and diagnose faulty cables up 200 m with +/- 2 m accuracy
- Supports HP MDI/MDI-X auto crossover
- Supports power down mode and power saving mode
- MDC/MDIO to 12.5 MHz for rapid configuration
- Fully compliant to IEEE 802.3u standard
- Supports auto-negotiation and manual selection for 10/100Mbps speed and full / half-duplex mode

#### **Functional Diagram**



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### **Features (continued)**

- Configurable through MII serial management port or via external control pins
- Programmable LED outputs for link, activity, full/half duplex, collision and speed
- On-chip built-in analog front end filtering for both 100BASE-TX and 10BASE-T
- Supports back-to-back, 100BASE-FX to 100BASE-TX for media converter applications
- Single 3.3V power supply with built-in 1.8V regulator ('L' parts)
- 48 Pin LQFP, 48 Pin SSOP

#### **Ordering Information**

Part Number	Integrated LDO	Temperature Range	Package	Lead Finish
KS8001L	Yes	0°-70°C	48-LQFP	Standard
KS8001S	No	0°-70°C	48-SSOP	Standard
KSZ8001L	Yes	0°-70°C	48-LQFP	Lead-free
KSZ8001LI	Yes	-40°-85°C	48-LQFP	Lead-free
KSZ8001S	No	0°-70°C	48-SSOP	Lead-free
KSZ8001SI	No	-40°–85°C	48-SSOP	Lead-free

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# **Revision History**

Revision	Date	Summary of Changes
PRELIMINARY	25 Mar 2004	Preliminary data
0.8	9 Aug 2004	Updated pin 38 (VDDRCV) definition to 3.3V
		Corrected pin configuration diagrams to reflect NC on pins 42 and 43
		Updated crystal tolerance to +/- 50 ppm
0.81	17 Sep 2004	• Updated series resistance for crystal specification to 40 $\Omega$
0.82	25 Jan 2005	LinkMD distance coefficient changed to 0.39
		Interrupt register status bits set to RO/SC
		Recommended reset circuit added
		RMII timing added
1.00	31 Mar 2005	Added lead-free part numbers
1.01	16 May 2005	Changed REXT value to 6.65 KΩ
		Removed preliminary status
		Added KSZ8001S to ordering information
1.02	30 Jan 2006	Updated part ordering information
		Corrected recommended reset circuits to match corresponding description
		Added Micrel disclaimer to last page
		Corrected crystal/oscillator PPM in Reference Clock Connection Diagrams
		Added current consumption for KSZ8001L
		Correct RXC clock pulse width timing in 100BASE-TX MII Receive Timing Diagram
		Added description for Auto MDI/MDI-X mode in register 1f.15
		Updated description for MDI/MDI-X select in register 1f.14
		Corrected Auto-Negotiation Complete bit, register 1f.7, to read only
		Added "Circuit Design Reference for Power Supply" section
		Updated Pin Description for the following pins: MDIO, VDDIO, VDDC, RX+, RX-, TX+, TX-, XI, XO
1.03	7 March 2006	Removed 48 Pin QFN (targeted) package option
		Renamed KS8001 to KSZ8001 throughout datasheet
		Added mechanical info for SSOP package
		Updated package thermal resistance
1.04	25 June 2009	Update ordering information.

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# **Pin Description**

Pin Number	Pin Name	Type (Note 1)	Pin Function
1	MDIO	I/O	MII Management (MIIM) Interface: Data I/O
			This pin requires an external 4.7K pull-up resistor.
2	MDC	1	MII Management (MIIM) Interface: Clock Input
			This pin is synchronous to the MDIO data line.
3	RXD3/	lpd/O	MII Mode: Receive Data Output[3] <sup>2</sup> /
	PHYAD1		Configuration Mode: The pull-up/pull-down value is latched as PHYADDR[1]
			during reset. See "Strapping Options" section for details.
4	RXD2/	lpd/O	MII Mode: MII Receive Data Output[2] <sup>2</sup> /
	PHYAD2		Configuration Mode: The pull-up/pull-down value is latched as PHYADDR[2] during reset. See "Strapping Options" section for details.
5	RXD1/	lpd/O	MII Mode: Receive Data Output[1] <sup>2</sup> /
	RXD[1]/		RMII Mode: Receive Data Output[1] <sup>3</sup> /
	PHYAD3		Configuration Mode: The pull-up/pull-down value is latched as PHYADDR[3]
			during reset. See "Strapping Options" section for details.
6	RXD0/	lpd/O	MII Mode: Receive Data Output[0] <sup>2</sup> /
	RXD[0]/		RMII Mode: Receive Data Output[0] <sup>3</sup> /
	RX		SMII Mode: Receive Data and Control <sup>4</sup> /
	PHYAD4		Configuration Mode: The pull-up/pull-down value is latched as PHYADDR[4]
7	VDDIO	Pwr	during reset. See "Strapping Options" section for details.  3.3V digital VDD
8	GND	Gnd	Ground
9	RXDV/	Ipd/O	MII Mode: Receive Data Valid Output /
9	CRSDV/	ipu/O	RMII Mode: Carrier Sense/Receive Data Valid /
	PCS_LPBK		Configuration Mode: The pull-up/pull-down value is latched as pcs_lpbk
			during reset. See "Strapping Options" section for details.
10	RXC/	lpd/O	MII Receive Clock Output
	SMII_SELE		Operating at:
	CT		25 MHz = 100 Mbps
			2.5 MHz = 10 Mbps
			Configuration Mode: The pull-up/pull-down value is latched as SMII during reset. See "Strapping Options" section for details.
11	RXER/	lpd/O	MII Mode: Receive Error Output /
	RX_ER/		RMII Mode: Receive Error /
	ISO		Configuration Mode: The pull-up/pull-down value is latched as ISOLATE during reset. See "Strapping Options" section for details.
12	GND	Gnd	Ground
13	VDDC	Pwr	1.8V digital core VDD
			VDD output : KSZ8001L / KSZ8001SL
			VDD input : KSZ8001S
			(See "Circuit Design Reference for Power Supply" section for details)
14	TXER	lpd	MII Transmit Error Input
15	TXC/	I/O	MII Mode: MII Transmit Clock Output /
	REFCLK/		RMII Mode: 50 MHz Reference Clock Input /
w.DataSheet4U.co	CLOCK		SMII Mode: 125 MHz Synchronization Clock Input
16	TXEN	lpd	MII Transmit Enable Input

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Pin Number	Pin Name	Type (Note 1)	Pin Function				
17	TXD0/	lpd	MII Mode: Trans	smit Data Input[0] /			
	TXD[0]/			nsmit Data Input[0] /			
	TX		SMII Mode: Transmit Data and Control				
18	TXD1/	lpd	MII Mode: Transmit Data Input[1] /				
	TXD[1]/		RMII Mode: Transmit Data Input[1] /				
19	SYNC TXD2	Ind	SMII Mode: SYN				
20	TXD3	lpd lpd	MII Transmit Dat MII Transmit Dat				
21	COL/	Ipd/O	MII Collision Det				
21	RMII_SELE	ipu/C	Configuration Mo	•	vn value is latched as RMII select		
22	CRS/	lpd/O	MII Carrier Sens				
	RMII_BTB		Configuration Mo	ode: The pull-up/pull-dov t when RMII mode is se	vn value is latched as RMII Loop- lected. See "Strapping Options		
23	GND	Gnd	Ground				
24	VDDIO	Pwr	3.3V digital VDD				
25	INT#/ PHYAD0	Ipu/O	Management Interface (MII) Interrupt Out.  Configuration Mode: Latched as PHYAD[0] during power up / reset. See "Strapping Options" section for details.				
26	LED0/ TEST	lpu/O		own enable test mode and only used oin is also programmable via register			
			LED mode = 00				
			Link/Act	Pin State	LED Definition		
			No Link	Н	Off		
			Link	L	On		
			Activity	-	Toggle		
			LED mode = 01		1		
			Link	Pin State	LED Definition		
			No Link	Н	Off		
			Link	L	On		
			LED mode = 10		011		
			10Mbps Link	Pin State	LED Definition		
			No Link	H	Off		
			Link	1	On		
27	LED1 / SPD100/ noFEF	lpu/O	Programmable L Configuration Mo / reset. See "Stra	ED Output 1 ode: Latched as SPEED	(Register 0, bit 13) during power up for details. Active Low. The LED1		
			LED mode = 00				
v.DataSheet4U.co	m		Speed	Pin State	LED Definition		
			10BT	H	Off		
			100BT	L	On		

Pin Number	Pin Name	Type (Note 1)	Pin Function			
			LED mode = 01			
			Speed	Pin State	LED Definition	
			10BT	Н	Off	
			100BT	L	On	
			LED mode = 10			
			100Mbps Link	Pin State	LED Definition	
			No Link	Н	Off	
			Link	L	On	
28	LED2/ DUPLEX	lpu/O	/ reset. See "Str	ode: Latched as DUPLE	X (register 0h, bit 8) during power up for details. Active Low. The LED2	
			LED mode = 00			
			Duplex	Pin State	LED Definition	
			Half	Н	Off	
			Full	L	On	
			LED mode = 01			
			Full Duplex/Col	Pin State	LED Definition	
			Half	Н	Off	
			Full	L	On	
			Collision	-	Toggle	
			LED mode = 10			
			Duplex	Pin State	LED Definition	
			Half	Н	Off	
			Full	L	On	
29	LED3/ NWAYEN	Ipu/O	up / reset. See " LED3 pin is also	ode: Latched as ANEG_I	EN (register 0h, bit 12) during power ion for details. Active Low. The ter 1eh.	
			LED mode = 00	T	1	
			Collision	Pin State	LED Definition	
			No Collision	H	Off	
			Collision	L	On	
			LED mode = 01	T =	1	
			Activity	Pin State	LED Definition	
			Activity	-	Toggle	
			LED mode = 10	Dia Otata	LED Definition	
			Activity	Pin State	LED Definition	
w DataSheet4LL 30	PD#	Inu	Activity	input (active low)	Toggle	
30	FD#	lpu	1 (high) = Norma 0 (low) = Power	al operation		

Pin Number	Pin Name	Type (Note 1)	Pin Function
31	VDDRX	Pwr	1.8V analog VDD
			(See "Circuit Design Reference for Power Supply" section for details)
32	RX-	I/O	Physical receive or transmit '-' differential signal
33	RX+	I/O	Physical receive or transmit '+' differential signal
34	FXSD/	Ipd/O	Fiber Mode Enable / Signal Detect in Fiber Mode
	FXEN		If FXEN=0, FX mode is disable. The default is "0".
	21.15	ļ .	(See "100BASE-FX Mode" section for details)
35	GND	Gnd	Ground
36	GND	Gnd	Ground
37	REXT	I	Connect a 6.65KΩ external resistor from this pin to ground
38	VDDRCV	Pwr	3.3V analog VDD
			(See "Circuit Design Reference for Power Supply" section for details)
39	GND	Gnd	Ground
40	TX-	I/O	Physical transmit or receive '-' differential signal
41	TX+	I/O	Physical transmit or receive '+' differential signal
42	NC		No Connect
43	NC		No Connect
44	GND	Gnd	Ground
45	XO	0	25MHz crystal/oscillator clock connections
46	XI	I	Pins (XI, XO) connect to a crystal. If an oscillator is used, XI connects to a 3.3V tolerant oscillator and XO is a no connect.
			Clock is +/- 50ppm for both crystal and oscillator.
47	VDDPLL	Pwr	1.8V analog PLL VDD
			(See "Circuit Design Reference for Power Supply" section for details)
48	RST#	lpu	Chip Reset
			Active low, minimum of 50 us pulse is required

Note 1:

Pwr = power supply; Ipu/O = input w/ internal pull up during
Gnd = ground; reset, output pin otherwise;
I = input; Ipd/O = input w/ internal pull down during
O = output; reset, output pin otherwise;

 $I/O = bi\text{-directional} \\ Ipu = input w/ internal pull up; \\ PU = strap pull up; \\ PU = strap pull up;$ 

Ipd = input w/ internal pull down;

#### Note 2:

MII Rx Mode: The RXD[3..0] bits are synchronous with RXCLK. When RXDV is asserted, RXD [3..0] presents valid data to MAC through the MII. RXD [3..0] is invalid when RXDV is de-asserted.

#### Note 3:

RMII Rx Mode: The RXD[1..0] bits are synchronous with REF\_CLK. For each clock period in which CRS\_DV is asserted, two bits of recovered data are sent from the PHY.

#### Note 4:

SMII Rx Mode: Receive data and control information are sent in 10 bit segments. In 100MBit mode, each segment represents a new byte of data. In 10MBit mode, each segment is repeated ten times; therefore, every ten segments represents a new byte of data. The MAC can sample any one of every 10 segments in 10MBit mode.

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#### Note 5:

MII Tx Mode: The TXD[3..0] bits are synchronous with TXCLK. When TXEN is asserted, TXD [3..0] presents valid data from the MAC through the MII. TXD [3..0] has no effect when TXEN is de-asserted.

#### Note 6:

RMII Tx Mode: The TXD[1..0] bits are synchronous with REF\_CLK. For each clock period in which TX\_EN is asserted, two bits of recovered data are recovered by the PHY.

#### Note 7:

SMII Tx Mode: Transmit data and control information are received in 10 bit segments. In 100MBit mode, each segment represents a new byte of data. In 10MBit mode, each segment is repeated ten times; therefore, every ten segments represents a new byte of data. The PHY can sample any one of every 10 segments in 10MBit mode.

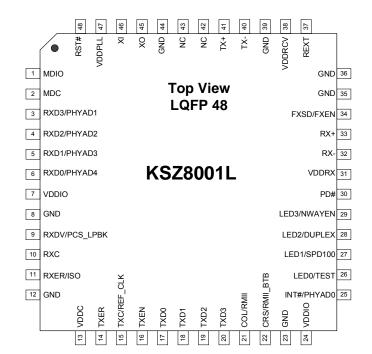
## **Strapping Options**

Pin Number	Pin Name	Type (Note 2)	Description
6, 5, 4,	PHYAD[4:1] /	Ipd/O	PHY Address latched at power-up / reset.
3	RXD[0:3]		The default PHY address is 00001.
25	PHYAD0 / INT#	lpu/O	
9	PCS_LPBK / RXDV	lpd/O	Enables PCS_LPBK mode at power-up / reset. PD (default) = Disable, PU = Enable
10	SMII_SELECT / RXC	lpd/O	Enables SMII mode at power-up / reset. PD (default) = Disable, PU = Enable
11	ISO / RXER	Ipd/O	Enables ISOLATE mode at power-up /reset. PD (default) = Disable, PU = Enable
21	RMII_SELECT / COL	lpd/O	Enables RMII mode at power-up / reset. PD (default) = Disable, PU = Enable
22	RMII_BTB/ CRS	lpd/O	Enable RMII_BTB mode at power-up / reset. PD (default) = Disable, PU = Enable
27	SPD100 / No FEF / LED1	lpu/O	Latched into Register 0h bit 13 during power-up / reset.  PD = 10Mb/s, PU (default) = 100Mb/s.  If SPD100 is asserted during power-up / reset, this pin also latched as the Speed Support in register 4h. (If FXEN is pulled up, the latched value 0 means no Far _End _Fault.)
28	DUPLEX/ LED2	lpu/O	Latched into Register 0h bit 8 during power-up / reset. PD = Half Duplex, PU (default) = Full duplex. If Duplex is pulled up during reset, this pin also latched as the Duplex support in register 4h.
29	NWAYEN/ LED3	lpu/O	Nway (auto-=Negotiation) Enable Latched into Register 0h bit 12 during power-up / reset. PD = Disable Auto-Negotiation, PU (default) = Enable Auto- Negotiation
30 vw. DataSbeet411.com	PD#	lpu	Power Down Enable PU (default) = Normal operation, PD = Power down mode

**Note:** Strap-in is latched during power up or reset. In some systems, the MAC RXD pins may drive high at all times causing the PHY strap-in to be latched high during power up or system reset. In this case, it is recommended to use a strong pull down to GND via 1kohm resistor on RXDV, RXC, and RXER pins. Otherwise, the PHY may stay in Isolate or loop back modes.

## **Pin Configuration**





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## **Functional Description**

#### **100BASE-TX Transmit**

The 100BASE-TX transmit function performs parallel-to-serial conversion, NRZ to NRZI conversion, MLT-3 encoding and transmission. The circuitry starts with a parallel-to-serial conversion, which converts the 25 MHz, 4-bit nibbles into a 125 MHz serial bit stream. The incoming data is clocked in at the positive edge of the TXC signal. The serialized data is further converted from NRZ to NRZI format, and then transmitted in MLT3 current output. The output current is set by an external 1% 6.65 K $\Omega$  resistor for the 1:1 transformer ratio. It has typical rise/fall times of 4 ns and complies with the ANSI TP-PMD standard regarding amplitude balance, overshoot and timing jitter. The wave-shaped 10BASE-T output driver is also incorporated into the 100BASE-TX driver.

#### 100BASE-TX Receive

The 100BASE-TX receive function performs adaptive equalization, DC restoration, MLT-3 to NRZI conversion, data and clock recovery, NRZI to NRZ conversion, and serial-to-parallel conversion. The receiving side starts with the equalization filter to compensate for inter-symbol interference (ISI) over the twisted pair cable. Since the amplitude loss and phase distortion are a function of the length of the cable, the equalizer has to adjust its characteristic to optimize performance. In this design, the variable equalizer will make an initial estimation based upon comparisons of incoming signal strength against some known cable characteristics, then tunes itself for optimization. This is an ongoing process and can self adjust against environmental changes such as temperature variations.

The equalized signal then goes through a DC restoration and data conversion block. The DC restoration circuit is used to compensate for the effects of base line wander and to improve the dynamic range. The differential data conversion circuit converts the MLT3 format back to NRZI. The slicing threshold is also adaptive.

The clock recovery circuit extracts the 125 MHz clock from the edges of the NRZI signal. This recovered clock is then used to convert the NRZI signal into the NRZ format. Finally, the NRZ serial data is converted to 4-bit parallel 4B nibbles. A synchronized 25 MHz RXC is generated so that the 4B nibbles is clocked out at the negative edge of RCK25 and is valid for the receiver at the positive edge. When no valid data is present, the clock recovery circuit is locked to the 25 MHz reference clock and both TXC and RXC clocks continue to run.

#### PLL Clock Synthesizer

The KSZ8001 generates 125 MHz, 25 MHz and 20 MHz clocks for system timing. An internal crystal oscillator circuit provides the reference clock for the synthesizer.

#### Scrambler/De-scrambler (100BASE-TX only)

The purpose of the scrambler is to spread the power spectrum of the signal in order to reduce EMI and baseline wander.

#### **10BASE-T Transmit**

When TXEN (transmit enable) goes high, data encoding and transmission will begin. The KSZ8001 will continue to encode and transmit data as long as TXEN remains high. The data transmission will end when TXEN goes low. The last transition occurs at the boundary of the bit cell if the last bit is zero, or at the center of the bit cell if the last bit is one. The output driver is incorporated into the 100BASE- driver to allow transmission with the same magnetic. They are internally wave-shaped and pre-emphasized into outputs with a typical 2.5 V amplitude. The harmonic contents are at least 27 dB below the fundamental when driven by an all-ones Manchester-encoded signal.

#### **10BASE-T Receive**

On the receive side, input buffer and level detecting squelch circuits are employed. A differential input receiver circuit and a PLL performs the decoding function. The Manchester-encoded data stream is separated into clock signal and NRZ data. A squelch circuit rejects signals with levels less than 300 mV or with short pulse widths in order to prevent noises at the RX+ or RX- input from falsely trigger the decoder. When the input exceeds the squelch limit, the PLL locks onto the incoming signal and the KSZ8001 decodes a data frame. This activates the carrier sense (CRS) ad RXDV signals and makes the receive data (RXD) available. The wreceive clock is maintained active during idle periods in between data reception.

#### SQE and Jabber Function (10BASE-T only)

In 10BASE-T operation, a short pulse will be put out on the COL pin after each packet is transmitted. This is required as a test of the 10BASE-T transmit/receive path and is called SQE test. The 10BASE-T transmitter will be disabled and COL will go high if TXEN is High for more than 20 ms (Jabbering). If TXEN then goes low for more than 250 ms, the 10BASE-T transmitter will be re-enabled and COL will go Low.

#### **Auto-Negotiation**

The KSZ8001 performs auto-negotiation by hardware strapping option (pin 29) or software (Register 0.12). It will automatically choose its mode of operation by advertising its abilities and comparing them with those received from its link partner whenever auto-negotiation is enabled. It can also be configured to advertise 100BASE-TX or 10BASE-T in either full- or half-duplex mode. Autonegotiation is disabled in FX mode.

During auto-negotiation, the contents of Register 4, coded in Fast Link Pulse (FLP), will be sent to its link partner under the conditions of power-on, link-loss or re-start. At the same time, the KSZ8001 will monitor incoming data to determine its mode of operation. Parallel detection circuit will be enabled as soon as either 10BASE-T NLP (Normal Link Pulse) or 100BASE-TX idle is detected. The operation mode is configured based on the following priority:

Priority 1: 100BASE-TX, full-duplex

Priority 2: 100BASE-TX, half-duplex

Priority 3: 10BASE-T, full-duplex

Priority 4: 10BASE-T, half-duplex

When the KSZ8001 receives a burst of FLP from its link partner with 3 identical link code words (ignoring acknowledge bit), it will store these code words in Register 5 and wait for the next 3 identical code words. Once the KSZ8001 detects the second code words, it then configures itself according to the above-mentioned priority. In addition, the KSZ8001 also checks for 100BASE-TX idle or 10BASE-T NLP symbols. If either is detected, the KSZ8001 automatically configures to match the detected operating speed.

## **MII Management Interface**

The KSZ8001 supports the IEEE 802.3 MII Management Interface, also known as the Management Data Input / Output (MDIO) Interface. This interface allows upper-layer devices to monitor and control the state of the KSZ8001. The MDIO interface consists of the following:

- A physical connection including a data line (MDIO), a clock line (MDC) and an optional interrupt line (INTRPT)
- A specific protocol that runs across the above-mentioned physical connection and it also allows one controller to communicate with multiple KSZ8001 devices. Each KSZ8001 is assigned an MII address between 0 and 31 by the PHYAD inputs.
- An internal addressable set of fourteen 16-bit MDIO registers. Register [0:6] are required and their functions are specified by the IEEE 802.3 specifications. Additional registers are provided for expanded functionality.

The INTPRT pin functions as a management data interrupt in the MII. An active Low or High in this pin indicates a status change on the KSZ8001 based upon 1fh.9 level control. Register bits at 1bh[15:8] are the interrupt enable bits. Register bits at 1bh[7:0] are the interrupt condition bits. This interrupt is cleared by reading Register 1bh.

#### **MII Data Interface**

The data interface consists of separate channels for transmitting data from a 10/100 802.3 compliant Media Access Controller (MAC) to the KSZ8001, and for receiving data from the line. Normal data transmission is implemented in 4B Nibble Mode (4-bit wide nibbles).

**Transmit Clock (TXC)**: The transmit clock is normally generated by the KSZ8001 from an external 25MHz reference source at the X1 input. The transmit data and control signals must always be synchronized to the TXC by the MAC. The KSZ8001 normally samples these signals on the rising edge of the TXC.

**Receive Clock (RXC)**: For 100BASE-TX links, the receive clock is continuously recovered from the line. If the link goes down, and auto-negotiation is disabled, the receive clock then operates off the master input clock (X1 or TXC). For 10BASE-T links, the receive clock is recovered from the line while carrier is active, and operates from the master input clock when the line is idle. The KSZ8001 synchronizes the receive data and control signals on the falling edge of RXC in order to stabilize the signals at the rising edge of the clock with 10ns setup and hold times.

**Transmit Enable**: The MAC must assert TXEN at the same time as the first nibble of the preamble, and de-assert TXEN after the last bit of the packet.

**Receive Data Valid:** The KSZ8001 asserts RXDV when it receives a valid packet. Line operating speed and MII mode will determine timing changes in the following way:

- For 100BASE-TX link with the MII in 4B mode, RXDV is asserted from the first nibble of the preamble to the last nibble of the data packet.
- For 10BASE-T links, the entire preamble is truncated. RXDV is asserted with the first nibble of the SFD " 5D" and remains asserted until the end of the packet.

**Error Signals**: Whenever the KSZ8001 receives an error symbol from the network, it asserts RXER and drives "1110" (4B) on the RXD pins. When the MAC asserts TXER, the KSZ8001 will drive "H" symbols (a Transmit Error define in the IEEE 802.3 4B/5B code group) out on the line to force signaling errors.

**Carrier Sense (CRS)**: For 100TX links, a start-of-stream delimiter, or /J/K symbol pair causes assertion of Carrier Sense (CRS). An end-of-stream delimiter, or /T/R symbol pair causes de-assertion of CRS. The PMA layer will also de-assert CRS if IDLE symbols are received without /T/R, yet in this case RXER will be asserted for one clock cycle when CRS is de-asserted. For 10T links, CRS assertion is based on reception of valid preamble, and de-assertion on reception of an end-of-frame (EOF) marker.

**Collision**: Whenever the line state is half-duplex and the transmitter and receiver are active at the same time, then the KSZ8001 asserts its collision signal, which is asynchronous to any clock.

## RMII (Reduced MII) Data Interface

RMII interface specifies a low pin count (Reduced) Media Independent Interface (RMII) intended for use between Ethernet PHYs and Switch or Repeater ASICs. It is fully compliant with IEEE 802.3u [2].

This interface has the following characteristics:

- It is capable of supporting 10Mb/s and 100Mb/s data rates
- A single clock reference is sourced from the MAC to PHY (or from an external source)
- It provides independent 2 bit wide (di-bit) transmit and receive data paths
- It uses TTL signal levels, compatible with common digital CMOS ASIC processes

#### **RMII Signal Definition**

	Direction	Direction	
Signal Name	(with respect to the PHY)	(with respect to the MAC)	Use
REF_CLK	Input	Input or Output	Synchronous clock reference for receive, transmit and control interface
CRS_DV	Output	Input	Carrier Sense/Receive Data Valid
RXD[1:0]	Output	Input	Receive Data
TX_EN	Input	Output	Transit Enable
TXD[1:0]	Input	Output	Transit Data
WRXDERSheet4U.com	Output	Input (Not Required)	Receive Error

**Note:** Unused MII signals, TXD[3:2], TXER need to be tied to GND when RMII is used

#### Reference Clock (REF CLK)

REF\_CLK is a continuous 50 MHz clock that provides the timing reference for CRS\_DV, RXD[1:0], TX\_EN, TXD[1:0], and RX\_ER. REF\_CLK is sourced by the MAC or an external source. Switch implementations may choose to provide REF\_CLK as an input or an output depending on whether they provide a REF\_CLK output or rely on an external clock distribution device. Each PHY device shall have an input corresponding to this clock but may use a single clock input for multiple PHYs implemented on a single IC.

#### Carrier Sense/Receive Data Valid (CRS\_DV)

CRS\_DV is asserted asynchronously on detection of carrier due to the criteria relevant to the operating mode. That is, in 10BASE-T mode, when squelch is passed or in 100BASE-X mode when 2 non-contiguous zeroes in 10 bits are detected carrier is said to be detected.

Loss of carrier shall result in the de-assertion of CRS\_DV synchronous to REF\_CLK. So long as carrier criteria are being met, CRS\_DV shall remain asserted continuously from the first recovered di-bit of the frame through the final recovered di-bit and shall be negated prior to the first REF\_CLK that follows the final di-bit.

The data on RXD[1:0] is considered valid once CRS\_DV is asserted. However, since the assertion of CRS\_DV is asynchronous relative to REF\_CLK, the data on RXD[1:0] shall be "00" until proper receive signal decoding takes place (see definition of RXD[1:0] behavior).

#### Receive Data [1:0] (RXD[1:0])

RXD[1:0] shall transition synchronously to REF\_CLK. For each clock period in which CRS\_DV is asserted, RXD[1:0] transfers two bits of recovered data from the PHY. In some cases (e.g. before data recovery or during error conditions) a pre-determined value for RXD[1:0] is transferred instead of recovered data. RXD[1:0] shall be "00" to indicate idle when CRS\_DV is de-asserted. Values of RXD[1:0] other than "00" when CRS\_DV is de-asserted are reserved for out-of-band signaling (to be defined). Values other than "00" on RXD[1:0] while CRS\_DV is de-asserted shall be ignored by the MAC/repeater. Upon assertion of CRS\_DV, the PHY shall ensure that RXD[1:0]=00 until proper receive decoding takes place.

#### Transmit Enable (TX\_EN)

Transmit Enable TX\_EN indicates that the MAC is presenting di-bits on TXD[1:0] on the RMII for trans-mission. TX\_EN shall be asserted synchronously with the first nibble of the preamble and shall remain asserted while all di-bits to be transmitted are presented to the RMII. TX\_EN shall be negated prior to the first REF\_CLK following the final di-bit of a frame. TX\_EN shall transition synchronously with respect to REF\_CLK.

#### Transmit Data [1:0] (TXD[1:0])

Transmit Data TXD[1:0] shall transition synchronously with respect to REF\_CLK. When TX\_EN is asserted, TXD[1:0] are accepted for transmission by the PHY. TXD[1:0] shall be "00" to indicate idle when TX\_EN is de-asserted. Values of TXD[1:0] other than "00" when TX\_EN is de-asserted are reserved for out-of-band signaling (to be defined). Values other than "00" on TXD[1:0] while TX\_EN is disserted shall be ignored by the PHY.

#### Collision Detection

Since the definition of CRS\_DV and TX\_EN both contain an accurate indication of the start of frame, the MAC can reliably regenerate the COL signal of the MII by Ending TX\_EN and CRS\_DV.

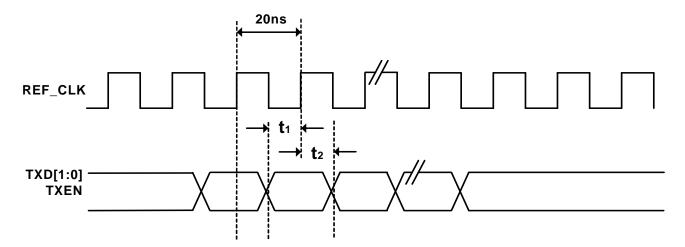
During the IPG time following the successful transmission of a frame, the COL signal is asserted by some transceivers as a self-test. The Signal Quality Error (SQE) function will not be supported by the reduced MII due to the lack of the COL signal. Historically, SQE was present to indicate that a transceiver located physically remote from the MAC was functioning. Since the reduced MII only supports chip-to-chip connections on a PCB, SQE functionality is not required.

#### RX ER

The PHY shall provide RX\_ER as an output according to the rules specified in IEEE 802.3u [2] (see Clause 24, Figure 24-11 - Receive State Diagram). RX\_ER shall be asserted for one or more REF\_CLK periods to indicate that an error (e.g. a coding error or any error that a PHY is capable of detecting, and that may otherwise be undetectable by the MAC sublayer) was detected somewhere in the frame presently being transferred from the PHY. RX\_ER shall transition synchronously with respect to REF\_CLK. While CRS\_DV is de-asserted, RX\_ER shall have no effect on the MAC.

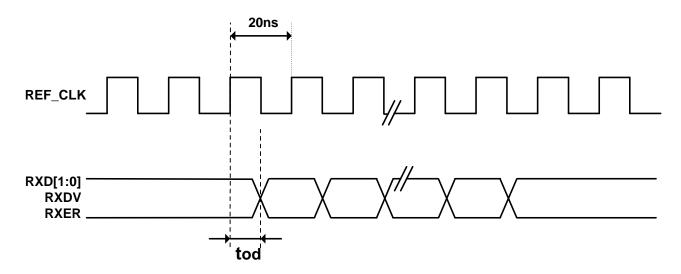
#### **RMII AC Characteristics**

## **RMII Transmit Timing**



Parameter	Min	Тур	Max	Unit
REF_CLK Frequency		50		MHz
TXD[1:0], TX_EN, Data Setup to REF_CLK rising edge	4			ns
TXD[1:0], TX_EN, Data hold from REF_CLK rising edge	2			ns

## **RMII Receive Timing**



WV	Parameter et4U.com	Min	Тур	Max	Unit
	REF_CLK Frequency		50		MHz
	RXD[1:0], CRS_DV, RX_ER Output delay from REF_CLK rising edge	2.8		10	ns

## **SMII Signal Definition**

SMII is composed of two signals per port, a global synchronization signal, and a global 125MHz reference clock. All signals are synchronous to the clock. All SMII I/F uses a common 125MHz reference clock and SYNC signals that are synchronous to the reference clock. There are two signals in SMII from MAC-to-PHY for each port (TXD and TxSYNC), and one signal per port from PHY-to-MAC (RXD).

The Serial Media Independent Interface (SMII) is designed to satisfy the following requirements:

- Convey complete MII information between a 10/100 PHY and MAC with two pins per port.
- Allow a multi-port MAC/PHY communication with one system clock.
- Operate in both half and full duplex.
- Per packet switching between 10Mbit and 100Mbit data rates.
- Allow direct MAC-to-MAC communication.

#### **SMII Signals**

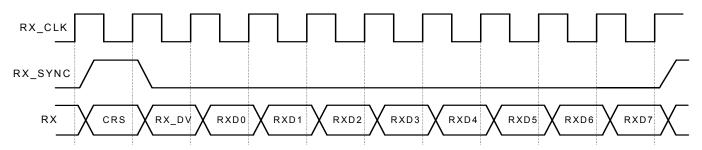
Signal Name	From	То	Use
RX	PHY	MAC	Receive Data and Control
TX	MAC	PHY	Transmit Data and Control
SYNC	MAC	PHY	Synchronization
Clock	System	MAC&PHY	Synchronization

#### **Receive Path**

Receive data and control information are signaled in ten bit segments. In 100Mbit mode, each segment represents a new byte of data. In 10Mbit mode, each segment is repeated ten times; therefore, every ten segments represent a new byte of data. The MAC can simply any one of every 10 segment ion 10Mbit mode.

Segment boundaries are delimited by SYNC. The MAC continuously generates a pulse on SYNC every 10 clocks.

#### **Receive Sequence Diagram**



RX contains all of the information found on the receive path of the standard MII.

Bits	Purpose
CRS	Carrier Sense – identical to MII, except that it is not an asynchronous signal
RX_DV	Receive Data Valid – identical to MII
RXD7-0	Encoded Data, see the RXD0-7 Encoding table

RX - Bit Description

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RXD7-0 are used to convey packet data, RX\_ER, and PHY status. The MAC can infer the meaning of RXD on a segment-by-basis by encoding the two control bits.

CRS	RX_DV	RXD0	RXD1	RXD2	RXD3	RXD4	RXD5	RXD6	RXD7
X	0	RX_ER from previous frame	Speed 0=10Mbit 1=100Mbit	Duplex 0=Half 1=Full	Link 0=Down 1=Up	Jabber 0=OK 1=Error	Upper Nibble 0=invalid 1=valid	False Carrier Detected	1
Χ	1	One Data Byte (Two MII Data Nibble)							

TXD7 - 0 Encoding

Inter-frame status bit RXD5 conveys the validity of the upper nibble of the byte of the previous frame. Inter-frame status bit RXD0 indicates whether or not the PHY detected an error somewhere on the previous frame. Both of these bits should be valid in the segment immediately following a frame, and should stay valid until the first data segment of the next frame begins. When asserted, inter-frame status bit RXD6 indicates that the PHY has detected a false carrier event.

In order to send receive data to the MAC synchronous to the reference clock, the PHY must pass the data through an elasticity FIFO to handle any difference between the reference clock rate and the clock at the packet source. The Ethernet specification calls for packet data to be referenced to a clock with a frequency tolerance of 100ppm (0.01%); however, it is not uncommon to encounter Ethernet stations with clocks that have frequency errors up to 0.1%. Therefore, the elasticity FIFO should be at least 27 bits \* long, filling to the halfway point before beginning valid data transfer via RX. RX\_ER should be asserted if, during the reception of a frame, this FIFO overflows or underflows.

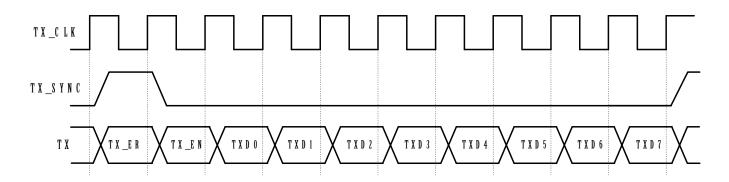
Only RXD and RX\_DV should be passed through the elasticity FIFO. CRS should not be passed through the elasticity FIFO. Instead, CRS should be asserted for the time the 'wire' is busy receiving a frame.

#### **Transmit Path**

Transmit data and control information are signaled in ten bit segments, just like the receive path. In 100Mbit mode, each segment represents anew byte of data. In 10Mbit mode each segment is repeated ten times; therefore, every ten segments represents a new byte of data. The PHY can sample any one of every 10 segments in 10Mbit mode.

Segment boundaries are delimited by SYNC. The MAC continuously generates a pulse on SYNC every 10 clocks.

#### Transmit Sequence Diagram



	Bits	Purpose
	TX_EN	Transmit Enable – identical to MII
www	DIX FRet4U.com	Transmit Error – identical to MII
	TXD7-0	Encoded Data – see TXD7-0 Encoding Table

TX- Bit Description

As far as the PHY is concerned, TXD7-0 are used to convey only packet data. To allow for a direct MAC-to-MAC connection, the MAC uses TXD7-0 to signal 'status' in between frames.

TX_ER	TX_EN	TXD0	TXD1	TXD2	TXD3	TXD4	TXD7-5
х	0	Use to force an error in a direct MAC to MAC connection	1 100MBit	1 Full Duplex	1 Link Up	0 No Jabber	1
Х	1	One Data Byte (Two MII Data Nibbles)					

TXD7 - 0 Encoding

#### **Collision Detection**

Collisions occur when CRS and TX\_EN are simultaneously asserted. For this to work, the PHY must ensure that CRS is not affected by its transmit path.

## **DC Specification**

Parameter	Symbol	Min	Max	Units
Input High Voltage	Vih	2.0		Volts
Input Low Voltage	Vil		0.8	Volts
Input High Current	lih	-10	10	uA
Input Low Current	lil	-10	10	uA

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# **Timing Specification**

Parameter	Min	Max	Units
Input Setup	1.5		ns
Input Hold	1		ns
Output Delay	1.5	5	ns

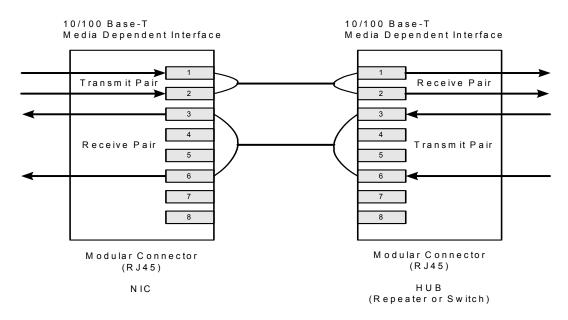
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## **HP Auto Crossover (Auto MDI/MDI-X)**

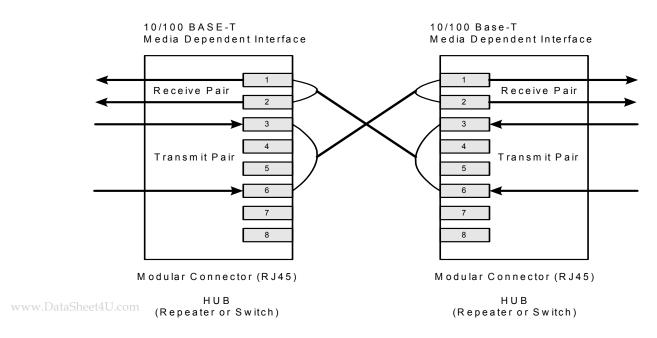
Automatic MDI/MDI-X configuration is intended to eliminate the need for crossover cables between similar devices. The assignment of pin-outs for a 10/100 BASE-T crossover function cable is shown below.

This feature can eliminate the confusion in real applications by allowing both straight cable and crossover cables. This feature is controlled by register 1f:13, see "Register 1fh" section for details.

#### Straight Through Cable



#### Crossover Cable



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#### Auto MDI/MDI-X Cross-Over Transformer Connection

KSZ8001 features HP Auto MDI/MDI-X crossover and requires symmetric transformers that support Auto MDI/MDI-X. See "Selection of Isolation Transformer" for a list of transformers that support Auto MDI/MDI-X.

## **Power Management**

The KSZ8001 offers the following modes for power management:

 Power Down Mode: This mode can be achieved by writing to Register 0.11 or pulling pin 30 PD# Low. In the power down state, the KS8061 disables all internal functions and drives output pins to logic zero, except for the MII serial management interface.

Power Saving Mode: writing to register 1fh.10 can disable this mode. The KSZ8001 will then turn off everything except for
the Energy Detect and PLL circuits when the cable is not installed. In other words, the KSZ8001 will shutdown most of the
internal circuits to save power if there is no link. Power Saving mode will be in this most effective state when AutoNegotiation Mode is enabled.

#### 100BASE-FX Mode

100BASE-FX mode is activated when FXSD/FXEN is higher than 0.6V (This pin has a default pull down). Under this mode, the autonegotiation and auto-MDIX features are disabled.

In fiber operation FXSD pin should connect to the SD (signal detect) output of the fiber module. The internal threshold of FXSD is around  $\frac{2}{3}$  Vdd +/- 50 mV (2.2V +/- 0.05V at 3.3V). Above this level, it is considered Fiber signal detected, and the operation is summarized in the following table:

FXSD/FXEN	Condition	
Less than 0.6V	100TX mode	
Less than 2.15V,	FX mode	
but greater than 0.6V	No signal detected	
	FEF generated	
Greater than 2.25V	FX mode	
	Signal detected	

To ensure proper operation, the swing of fiber module SD should cover the threshold variation. A resistive voltage divider is recommended to adjust the SD voltage range.

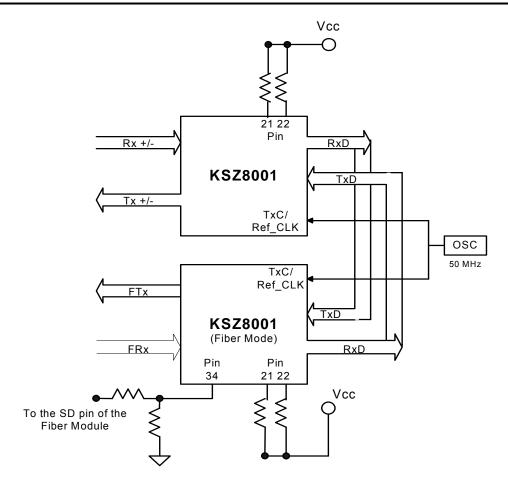
FEF (Far End Fault), repetition of a special pattern, which consists of 84-ones and 1-zero, is generated under "FX mode with no signal detected". The purpose of FEF is to notify the sender of a faulty link. When receiving a FEF, the LINK will go down to indicate a fault, even with fiber signal detected. The transmitter is not affected by receiving a FEF and still sends out its normal transmit pattern from MAC. FEF can be disabled by strapping pin27 low, please refer to "Strapping Options" section.

## **Media Converter Operation**

The KSZ8001 is capable of performing media conversion with 2 parts in a back-to-back RMII mode as indicated in the diagram. Both parts are in RMII mode and with RMII\_BTB asserted (pin21 & 22 strapped high). One part is operating at TX mode and the other in FX mode. Both parts can share a common 50MHz oscillator.

Under this operation, auto-Negotiation on the TX side will prohibit 10BASE-T link up. Additional options can be implemented under this operation. Disable the transmitter and set it at tri-state by controlling the high TXD2 pin. In order to do this, RXD2 and TXD2 pins need to be connected via an inverter. When TXD2 pin is high in both the copper and fiber operation, it disables transmit. Meanwhile, the RXD2 pin on the copper side serves as the energy detect and can indicate if a line signal is detected. TXD3 should be tied low and RXD3 let float. Please contact your local Micrel FAE for a Media Converter reference design.

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## **LinkMD Cable Diagnostics**

The KSZ8001 utilizes time domain reflectometry (TDR) to analyze the cabling plant for common cabling problems such as open circuits, short circuits and impedance mismatches. LinkMD works by sending a pulse of known amplitude and duration down the MDI and MDIX pairs and analyzing the shape of the reflected signal. Timing the duration gives an indication of the distance to the cabling fault with maximum distance of 200 m and accuracy of +/- 2 m. Cable diagnostics are only valid for copper connections and do not support fiber optic operation.

LinkMD is used by accessing register 1dh, the LinkMD Control/Status register in conjunction with register 1fh, the 100BASE-TX PHY Controller register. To use LinkMD, HP Auto-MDIX is disabled by writing a '1' to 1f:13 to enable manual control over which pair is used to transmit the LinkMD pulse. The self-clearing Cable diagnostic test enable bit, 1d.15 is set to '1' to start the test on this pair. When 1d.15 returns to '0', the test is complete. The test result is returned in 1d.14:13 and the distance is returned in 1d.8:0. The cable diagnostic test results are as follows:

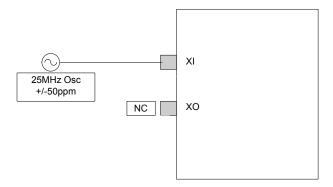
- 00 = Valid test, normal condition
- 01 = Valid test, open circuit in cable
- 10 = Valid test, short circuit in cable
- 11 = Invalid test, LinkMD failed

The '11' case, Invalid test, occurs when it is not possible for the KSZ8001 to shut down the link partner. In this case, the test is not run, since it would not be possible for the KSZ8001 to determine if the detected signal is a reflection of the signal generated or a signal from another source.

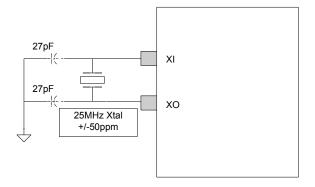
Cable length can be determined by multiplying the contents of 1d.8:0 by 0.39. This constant may be calibrated for different cabling conditions, including cables with a velocity of propagation that varies significantly from the norm.

## **Reference Clock Connection Options**

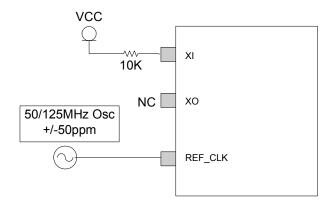
KSZ8001 is capable of performing three different kinds of clock speed options for connecting the external reference clock depends upon the different interface of using MII/RMII/SMII. The figures below illustrate the recommended connection for using the different interface options. Please see the selection of reference crystal table for specifications.



## 25MHz Oscillator Reference Clock Connection Diagram



## 25MHz Crystal Reference Clock Connection Diagram



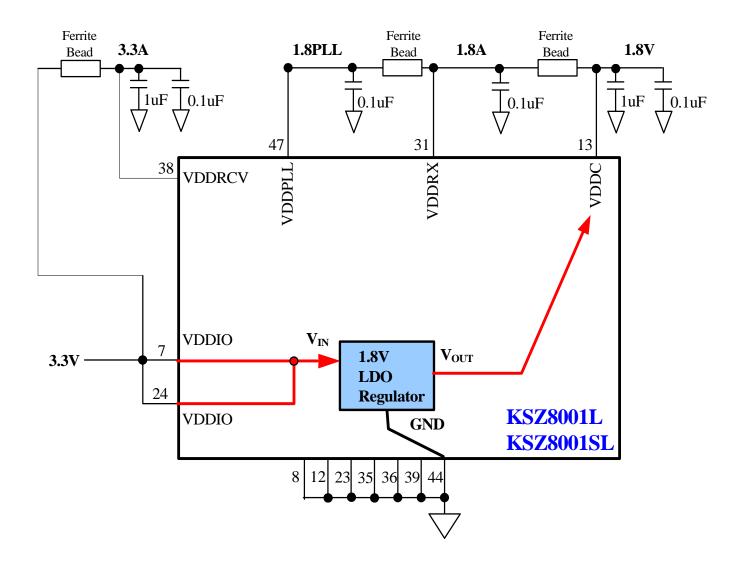
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50/125 MHz Oscillator Reference Clock Connection for RMII/SMII Mode Diagram

24

# **Circuit Design Reference for Power Supply**

The following diagram shows the power connections for the single 3.3V supply KSZ8001L and KSZ8001SL devices.



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# Register Map

Register No.	Description
0h	Basic Control Register
1h	Basic Status Register
2h	PHY Identifier I
3h	PHY Identifier II
4h	Auto-Negotiation Advertisement Register
5h	Auto-Negotiation Link Partner Ability Register
6h	Auto-Negotiation Expansion Register
7h	Auto-Negotiation Next Page Register
8h	Link Partner Next Page Ability
9h-14h	Reserved
15h	RXER Counter Register
16h – 1ah	Reserved
1bh	Interrupt Control/Status Register
1ch	Reserved
1dh	LinkMD Control/Status Register
1eh	PHY Control Register
1fh	100BASE-TX PHY Control Register

Address	Name	Description	Mode	Default
Register 0	h – Basic Con	trol		
0.15	Reset	1 = software reset. Bit is self-clearing	RW/	0
			SC	
0.14	Loop-back	1 = loop-back mode	RW	0
		0 = normal operation		
0.13	Speed Select	1 = 100Mb/s	RW	Set by SPD100
	(LSB)	0 = 10Mb/s		
		Ignored if Auto-Negotiation is enabled		
		(0.12 = 1)		
0.12	Auto-	1 = enable auto-negotiation process (override	RW	Set by NWAYEN
	Negotiation	0.13 and 0.8)		
	Enable	0 = disable auto-negotiation process		
0.11	Power Down	1 = power down mode	RW	0
		0 = normal operation		
0.10	Isolate	1 = electrical isolation of PHY from MII and TX+/TX-	RW	Set by ISO
		0 = normal operation		
0.9	Restart Auto-	1 = restart auto-negotiation process	RW/	0
	Negotiation	0 = normal operation. Bit is self-clearing	SC	
0.8	Duplex Mode	1 = full duplex	RW	Set by DUPLEX
		0 = half duplex		
0.7	Collision Test	1 = enable COL test	RW	0
		0 = disable COL test		
0.6:1	Reserved		RO	0
0.0	Disable	0 = enable transmitter	RW	0
w.DataSheet4U	⊲Transmitter	1 = disable transmitter		

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Address	Name	Description	Mode	Default
Register 1h	n – Basic Statı	ıs		•
1.15	100BASE-T4	1 = T4 capable	RO	0
1.10	100DAGE-14	0 = not T4 capable		
1.14	100BASE-TX	1 = capable of 100BASE-X full duplex	RO	1
	Full Duplex	0 = not capable of 100BASE-X full duplex	'	1
1.13	100BASE-TX	1 = capable of 100BASE-X half duplex	RO	1
	Half Duplex	0 = not capable of 100BASE-X half duplex		
1.12	10BASE-T Full	1 = 10Mbps with full duplex	RO	1
	Duplex	0 = no 10Mbps with full duplex capability		
1.11	10BASE-T Half	1 = 10Mbps with half duplex	RO	1
	Duplex	0 = no 10Mbps with half duplex capability		
1.10:7	Reserved		RO	0
1.6	No Preamble	1 = preamble suppression	RO	1
		0 = normal preamble		
1.5	Auto-	1 = auto-negotiation process completed	RO	0
	Negotiation Complete	0 = auto-negotiation process not completed		
1.4	Remote Fault	1 = remote fault	RO/	0
1.4	Remote Fault	0 = no remote fault	LH	0
1.3	Auto-	1 = capable to perform auto-negotiation	RO	1
1.0	Negotiation	0 = unable to perform auto-negotiation	110	'
	Ability	andsie to perform date negetiation		
1.2	Link Status	1 = link is up	RO/	0
		0 = link is down	LL	
1.1	Jabber Detect	1 = jabber detected	RO/	0
		0 = jabber not detected. Default is Low	LH	
1.0	Extended Capability	1 = supports extended capabilities registers	RO	1
Register 2h	n – PHY Identi	fier 1		
2.15:0	PHY ID	Assigned to the 3 <sup>rd</sup> through 18 <sup>th</sup> bits of the	RO	0022h
	Number	Organizationally Unique Identifier (OUI).		
		Kendin Communication's OUI is 0010A1 (hex)		
Register 3h	n – PHY Identi	fier 2		
3.15:10	PHY ID	Assigned to the 19 <sup>th</sup> through 24 <sup>th</sup> bits of the	RO	000101
000	Number	Organizationally Unique Identifier (OUI).		
		Kendin Communication's OUI is 0010A1 (hex)		
3.9:4	Model Number	Six bit manufacturer's model number	RO	100001
3.3:0	Revision Number	Four bit manufacturer's model number	RO	1010
Register 4h		tiation Advertisement		
4.15	Next Page	1 = next page capable	RW	0
		0 = no next page capability.		_
4.14	Reserved		RO	0
Δ 13	Remote Fault	1 = remote fault supported	RW	0
w.DataSheet4U	com	0 = no remote fault		
4.12 : 11	Reserved		RO	0
	l	1	1	1

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Name	Description	Mode	Default
Pause	1 = pause function supported	RW	0
	0 = no pause function		
100BASE-T4	1 = T4 capable	RO	0
	0 = no T4 capability		
100BASE-TX	1 = TX with full duplex	RW	Set by SPD100 & DUPLEX
Full Duplex	0 = no TX full duplex capability		
100BASE-TX	1 = TX capable	RW	Set by SPD100
	0 = no TX capability		
10BASE-T Full	1 = 10Mbps with full duplex	RW	Set by
Duplex	0 = no 10Mbps full duplex capability		DUPLEX
10BASE-T	1 = 10Mbps capable	RW	1
	0 = no 10Mbps capability		
Selector Field	[00001] = IEEE 802.3	RW	00001
5h — Auto-Nego	tiation Link Partner Ability		
	·		
Next Page	1 - 1	RU	0
A -1			
Acknowledge	· ·	RO	0
D t. E. II	-		
Remote Fault		RO	0
B	U = no remote fault		
Reserved		RO	0
Pause	5.10 5 .11	RO	0
	No PAUSE		
	1		
	Asymmetric PAUSE (link partner)		
	Symmetric PAUSE		
	1		
	Symmetric & Asymmetric PAUSE (local		
	device)		
100 BASE-T4	1 = T4 capable	RO	0
	0 = no T4 capability		
100BASE-TX	1 = TX with full duplex	RO	0
Full Duplex	0 = no TX full duplex capability		
100BASE-TX	1 = TX capable	RO	0
	0 = no TX capability		
10BASE-T Full	1 = 10Mbps with full duplex	RO	0
Duplex	0 = no 10Mbps full duplex capability		
10BASE-T	1 = 10Mbps capable	RO	0
	0 = no 10Mbps capability		
Selector Field	[00001] = IEEE 802.3	RO	00001
_ 6h – Auto-Nego	tiation Expansion	l	<u> </u>
T T			
Reserved		RO	0
	Pause  100BASE-T4  100BASE-TX Full Duplex  100BASE-T Full Duplex  10BASE-T  Selector Field  5h - Auto-Nego  Next Page  Acknowledge  Remote Fault  Reserved  Pause  100BASE-T4  100BASE-TX Full Duplex  100BASE-TX Full Duplex  100BASE-TX Selector Field  Duplex  100BASE-TX Full Duplex  100BASE-TX Selector Field	Pause 1 = pause function supported 0 = no pause function  100BASE-T4 1 = T4 capable 0 = no T4 capability  100BASE-TX 1 = TX with full duplex Full Duplex 0 = no TX full duplex capability  100BASE-TX 1 = TX capable 0 = no TX capability  100BASE-TX 1 = TX capable 0 = no TX capability  100BASE-T Full 1 = 10Mbps with full duplex capability  100BASE-T 1 = 10Mbps capable 0 = no 10Mbps capability  Selector Field [00001] = IEEE 802.3  Sh — Auto-Negotiation Link Partner Ability  Next Page 1 = next page capable 0 = no next page capability  Acknowledge 1 = ink code word received from partner 0 = link code word not yet received  Remote Fault 1 = remote fault detected 0 = no remote fault  Reserved  Pause 5.10 5.11 0 No PAUSE 1 Asymmetric PAUSE (link partner) 0 Symmetric PAUSE (link partner) 0 Symmetric & Asymmetric PAUSE (local device) 1 = TX capable 0 = no T4 capability  100BASE-T4 1 = T4 capable 0 = no T4 capability  100BASE-TX 1 = TX with full duplex capability  100BASE-TX 1 = TX capable 0 = no TX capability  100BASE-TF ull 1 = 10Mbps with full duplex capability  10BASE-T 1 = 10Mbps with full duplex capability  10BASE-T 1 = 10Mbps capable 0 = no 10Mbps capability	Pause 1 = pause function supported 0 = no pause function  100BASE-T4 1 = T4 capable 0 = no T4 capability  100BASE-TX

Address	Name	Description	Mode	Default
6.4	Parallel	1 = fault detected by parallel detection	RO/	0
	Detection Fault	0 = no fault detected by parallel detection.	LH	
6.3	Link Partner	1 = link partner has next page capability	RO	0
	Next Page	0 = link partner does not have next page		
	Able	capability		
6.2	Next Page	1 = local device has next page capability	RO	1
	Able	0 = local device does not have next page		
		capability		
6.1	Page Received	1 = new page received	RO/	0
		0 = new page not yet received	LH	
6.0	Link Partner	1 = link partner has auto-negotiation capability	RO	0
	Auto-	0 = link partner does not have auto-negotiation		
	Negotiation Able	capability		
Register		tiation Next Page	1	
7 15	Novt Dago	1 - additional poyt page(a) will follow	DW	Ιο.
7.15	Next Page	1 = additional next page(s) will follow	RW	0
7.4.4	Deserved	0 = last page	DO	
7.14	Reserved		RO	0
7.13	Message Page	1 = message page	RW	1
7.13	iviessage Fage	0 = unformatted page	IXVV	1
7.12	A aknowladge?	. Ŭ	RW	0
7.12	Acknowledge2	1 = will comply with message 0 = cannot comply with message	KVV	0
7.11	Togglo	1 = previous value of the transmitted link code	RO	0
7.11	Toggle	word equaled logic One	RU	0
		0 = logic Zero		
7.10:0	Message Field	11-bit wide field to encode 2048 messages	RW	001
	ccage : .c.a	The six mass note to ensure the increases		
Register	8h – Link Partne	er Next Page Ability		
8.15	Next Page	1 = additional Next Page(s) will follow	RO	0
	l tom : ago	0 = last page		
8.14	Acknowledge	1 = successful receipt of link word	RO	0
0	riomougo	0 = no successful receipt of link word	1.0	
8.13	Message Page	1 = Message Page	RO	0
0.10	Wessage Fage	0 = Unformatted Page	110	
8.12	Acknowledge2	1 = able to act on the information	RO	0
0.12	Acknowledgez	0 = not able to act on the information	NO	0
		0 - not able to act on the information		
8.11	Toggle	1 = previous value of transmitted Link Code	RO	0
0.11	Toggic	Word equal	1.0	Ĭ
		to logic zero		
		0 = previous value of transmitted Link Code		
		Word equal to logic one		
8.10:0	Message Field		RO	0
Register	 15h ⊟ RXER Co	⊔ unter		
			T = -	T
15.15:0	RXER Counter	RX Error counter for the RX_ER in each	RO	0000
		package		

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Address	Name	Description	Mode	Default
Register 1	oh – Interrupt	Control/Status Register		
1b.15	Jabber	1=Enable Jabber Interrupt	RW	0
10.15	Interrupt	0=Disable Jabber Interrupt	KVV	0
	Enable	0-Disable Jabbel Interrupt		
1b.14	Receive Error	1=Enable Receive Error Interrupt	RW	0
	Interrupt Enable	0=Disable Receive Error Interrupt		
1b.13	Page Received	1=Enable Page Received Interrupt	RW	0
	Interrupt Enable	0=Disable Page Received Interrupt		
1b.12	Parallel Detect	1= Enable Parallel Detect Fault Interrupt	RW	0
	Fault Interrupt Enable	0= Disable Parallel Detect Fault Interrupt		
1b.11	Link Partner	1= Enable Link Partner Acknowledge Interrupt	RW	0
	Acknowledge Interrupt Enable	0= Disable Link Partner Acknowledge Interrupt		
1b.10	Link Down	1= Enable Link Down Interrupt	RW	0
	Interrupt Enable	0= Disable Link Down Interrupt		
1b.9	Remote Fault	1= Enable Remote Fault Interrupt	RW	0
	Interrupt Enable	0= Disable Remote Fault Interrupt		
1b.8	Link Up	1= Enable Link Up Interrupt	RW	0
	Interrupt Enable	0= Disable Link Up Interrupt		
1b.7	Jabber	1= Jabber Interrupt Occurred	RO/	0
	Interrupt	0= Jabber Interrupt Does Not Occurred	SC	
1b.6	Receive Error	1= Receive Error Occurred	RO/	0
	Interrupt	0= Receive Error Does Not Occurred	SC	
1b.5	Page Receive	1= Page Receive Occurred	RO/	0
41. 4	Interrupt	0= Page Receive Does Not Occurred	SC	<u> </u>
1b.4	Parallel Detect Fault Interrupt	1= Parallel Detect Fault Occurred	RO/	0
45.0		0= Parallel Detect Fault Does Not Occurred	SC BC/	
1b.3	Link Partner Acknowledge	1= Link Partner Acknowledge Occurred 0= Link Partner Acknowledge Does Not	RO/ SC	0
	Interrupt	Occurred	30	
1b.2	Link Down	1= Link Down Occurred	RO/	0
	Interrupt	0= Link Down Does Not Occurred	SC	
1b.1	Remote Fault	1= Remote Fault Occurred	RO/	0
	Interrupt	0= Remote Fault Does Not Occurred	SC	
1b.0	Link Up	1= Link Up Interrupt Occurred	RO/	0
	Interrupt	0= Link Up Interrupt Does Not Occurred	SC	
Register 1	dh – LinkMD C	ontrol/Status Register		
1d.15	Cable	0 = Indicates cable diagnostic test has	RW/	0
	diagnostic test enable	completed and the status information is valid for read.	sc	
w.DataSheet4U	l.com	1 = the cable diagnostic test is activated. This bit is self-clearing.		

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Address	Name	Description	Mode	Default
1d.14:13	Cable	[00] = normal condition	RO	0
	diagnostic test	[01] = open condition has been detected in		
	result	cable		
		[10] = short condition has been detected in		
		cable		
		[11] = cable diagnostic test failed		
1d.12:9	Reserved			
1d.8:0	Cable fault	Distance to fault, approximately	RO	0
	counter	0.39m*cabfaultcnt value		
Register 1	1eh – PHY Con	trol		
1e:15:14	LED mode	[00] =	RW	0
		LED3 <- collision		
		LED2 <- full duplex		
		LED1 <- speed		
		LED0 <- link/activity		
		[01] =		
		LED3 <- activity		
		LED2 <- full duplex/collision		
		LED1 <- speed		
		LED1 <- speed LED0 <- link		
		LEDU <- IIIIK		
		1403		
		[10] =		
		LED3 <- activity		
		LED2 <- full duplex		
		LED1 <- 100Mbps link		
		LED0 <- 10Mbps link		
		[11] = reserved		
1e.13	Polarity	0 = Polarity is not reversed	RO	
		1 = Polarity is reversed		
1e.12	Far end fault	0 = Far end fault detected	RO	
10.12	detect	1 = Far end fault not detected	110	
1e.11	MDIX/MDI	0 = MDIX	RO	
10.11	state	1 = MDI	110	
1e:10:8	Reserved			
1e:7	Remote	0: normal mode	RW	0
	loopback	1: remote (analog) loop back is enable	,	
1e:6:0	Reserved			
Register 1	 	-TX PHY Controller		
			DIA	
1f:15	HP_MDIX	0: Micrel Auto MDI/MDI-X mode	RW	1
- D-4-Cl14	T.T.	1: HP Auto MDI/MDI-X mode	1	

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Address	Name	Description	Mode	Default
1f:14	MDI/MDI-X Select	When Auto MDI/MDI-X is disabled,	RW	0
		0 = Transmit on TX+/- (pins 41,40)		
		Receive on RX+/- (pins 33,32)		
		1 = Transmit on RX+/- (pins 33,32)		
		Receive on TX+/- (pins 41,40)		
1f:13	Pairswap	1 = disable MDI/MDIX	RW	0
	disable	0 = enable MDI/MDIX		
1f.12	Energy detect	1 = presence of signal on RX+/- analog wire pair	RO	0
		0 = no signal detected on RX+/-		
1f.11	Force link	1 = force link pass	RW	0
		0 = normal link operation		
		This bit bypasses the control logic and allow transmitter to send pattern even if there is no link.		
1f.10	Power Saving	1 = enable power saving	RW	1
		0 = disable		
1f.9	Interrupt Level	1 = interrupt pin active high	RW	0
		0 = active low		
1f.8	Enable Jabber	1 = enable jabber counter	RW	1
		0 = disable		
1f.7	Auto-	1 = auto-negotiation complete	RO	0
	Negotiation	0 = not complete		
	Complete	This bit has the same definition as register 1.5.		
1f.6	Enable Pause	1 = flow control capable	RO	0
	(Flow-Control Result)	0 = no flow control		
1f.5	PHY Isolate	1 = PHY in isolate mode	RO	0
		0 = not isolated		
1f.4:2	Operation	[000] = still in auto-negotiation	RO	0
	Mode	[001] = 10BASE-T half duplex		
	Indication	[010] = 100BASE-TX half duplex		
		[011] = default		
		[101] = 10BASE-T full duplex		
		[110] = 100BASE-TX full duplex		
		[111] = PHY/MII isolate		
1f.1	Enable SQE	1 = enable SQE test	RW	0
	test	0 = disable		
1f.0	Disable Data	1 = disable scrambler	RW	0
	Scrambling	0 = enable		

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# Absolute Maximum Rating (Note 1)

Storage Temperature (T <sub>S</sub> )	55°C to +150°C
Supply Referenced to GND	0.5V to +4.0
All pins	0.5V to +4.0

Important: Please read the Notes at the end of the Electrical Characteristics.

# Operating Range (Note 2)

Supply Voltage
$(V_{DDPLL},V_{DDRX},V_{DDC})1.8V\pm5\%$
$(V_{DDRCV,}V_{DDIO})3.3V\pm5\%$
Ambient Temperature Commercial (TAC)0°C to
+70°C
Ambient Temperature Industrial $(T_{AI})$ 40°C to
+85°C

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# Package Thermal Resistance $(\theta_{JA})^{(Note 3)}$

Thermal Resistance	$\theta_{JA}$	θ <sub>JA</sub>	θυα	θυς
Airflow Velocity (m/s)	0	1	2	0
KSZ8001L / KSZ8001LI	83.56	77.08	72.36	35.90
KSZ8001SL / KSZ8001SLI	75.19	68.20	66.43	42.65
KSZ8001S	42.43	36.19	34.24	6.75

# **Electrical Characteristics** (Note4)

Symbol	Parameter	Condition	Min	Тур	Max	Unit
Total Supply Current (Note 5)						
KSZ80011	•	on is for the single 3.3V supply KSZ800 VDDPLL) that are provided by the KSZ	•		•	ply

- Transformer consumes an additional 45mA @ 3.3V for 100BASE-TX and 70mA @ 3.3V for 10BASE-T.

$I_{DD1}$	100BASE-TX	Chip only, no transformer		52		mA
$I_{DD2}$	10BASE-T	Chip only, no transformer		32		mA
$I_{DD3}$	Power Saving Mode	Ethernet cable disconnected		35		mA
I <sub>DD4</sub>	SW Power Down Mode	Register (software) power down		5		mA
I <sub>DD5</sub>	Power down pin (PD#)	Chip (hardware) power down		3		mA
TTL Inpu	ts					
V <sub>IH</sub>	Input High Voltage		2.0			V
V <sub>IL</sub>	Input Low Voltage				0.8	V
I <sub>IN</sub>	Input Current	$V_{IN} = GND - V_{DD}$		-10	10	μΑ
TTL Out	outs					
V <sub>OH</sub>	Output High Voltage	I <sub>OH</sub> = -4mA	2.4			V
V <sub>OL</sub>	Output Low Voltage				0.4	V
l l <sub>OZ</sub> l	Output Tri-State Leakage				10	μА
100BASE	-TX Transmit (measured diff	erentially after 1:1 transformer)				
Vo	Peak Differential Ouput Voltage	$50Ω$ from each output to $V_{DD}$	0.95		1.05	V
$V_{IMB}$	Output Voltage Imbalance	$50Ω$ from each output to $V_{DD}$			2	%
$t_{r,} t_{t}$	Rise/Fall Time		3		5	ns
	Rise/Fall Time Imbalance		0		0.5	ns
	Duty Cycle Distortion				±0.25	ns
	Overshoot				5	%
w. <b>Vse</b> tShee	Refernce Voltage of ISET			0.75		V
	Propagation Delay			45	60	Ns
	Jitter			0.7	1.4	ns <sub>(pk-pk)</sub>

$V_{P}$	Peak Differential Ouput Voltage	$50\Omega$ from each output to $V_{\text{DD}}$	2.2		2.8	V
$V_{IMB}$	Output Voltage Imbalance	$50Ω$ from each output to $V_{DD}$			±3.5	ns
t <sub>r,</sub> t <sub>t</sub>	Rise/Fall Time			25		ns
Clock O	utputs					
X1, X2	Crystal Oscillator			25		MHz
RXC <sub>100</sub>	Receive Clock, 100TX			25		MHz
RXC <sub>10</sub>	Receive Clock, 10T			2.5		MHz
	Receive Clock Jitter			3.0		ns <sub>(pk-pk)</sub>
TXC <sub>100</sub>	Transmit Clock, 100TX			25		MHz
TXC <sub>10</sub>	Transmit Clock, 10T			2.5		MHz
	Transmit Clock Jitter			1.8		ns <sub>(pk-pk)</sub>

Note 1: Exceeding the absolute rating(s) may cause permanent damage to the device. Operating at maximum conditions for extended periods may affect device reliability.

Note 2: This device is not guaranteed to operate beyond its specified operating rating. Unused inputs must always be tied to an appropriate logic voltage level (Ground to  $V_{DD}$ ).

Note 3: No HS (heat spreader) in package.

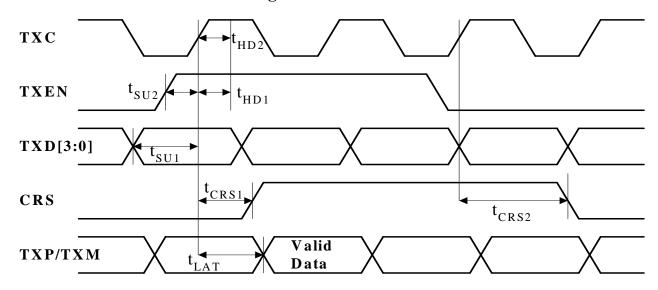
Note 4: Specification for packaged product only.

Note 5: 100% data transmission in full-duplex mode and minimum IPG with 130-meter cable.

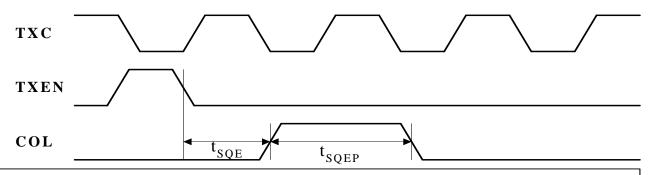
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# **Timing Diagrams**

## 10BaseT MII Transmit Timing



## **SQE** Timing

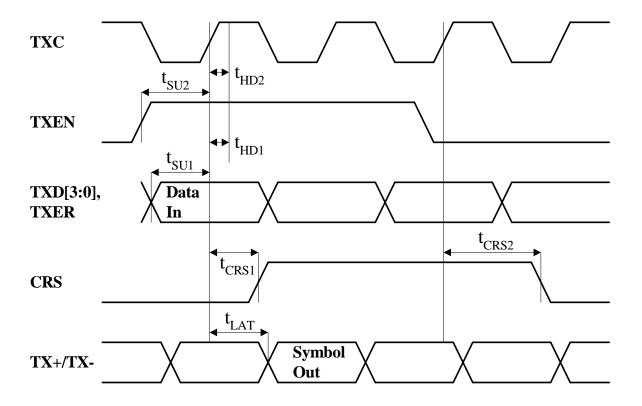


		min.	typ.	max.
SU1	TXD[3:0] Setup to TXC High	10ns		
SU2	TXEN Setup to TXC High	10ns		
HD1	TXD[3:0] Hold after TXC High	Ons		
ID1	TXEN Hold after TXC High	Ons		
RS1	TXEN High to CRS asserted latency		4BT	
RS2	TXEN Low to CRS de-asserted latency		8BT	
AT	TXEN High to TXP/TXM output (TX latency)		4BT	
QE	COL (SQE) Delay after TXEN de-asserted		2.5us	
QEP QEP	COL (SQE) Pulse Duration		1.0us	

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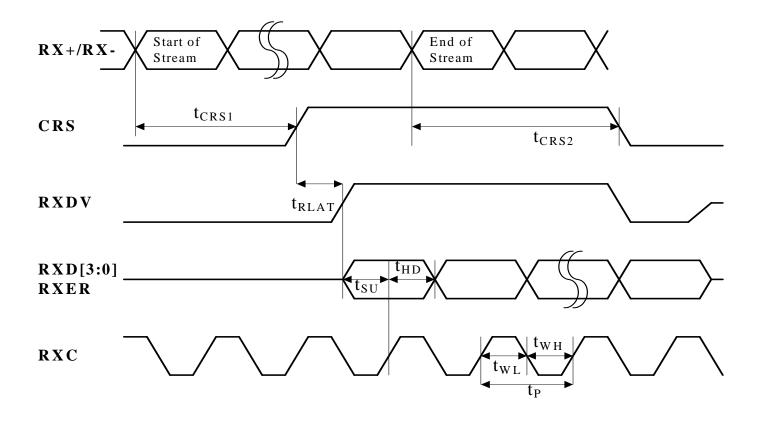
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# 100BaseTX MII Transmit Timing



		min.	typ.	max.
t <sub>HD1</sub> t <sub>HD2</sub> t <sub>HD3</sub> t <sub>CRSJ</sub> t <sub>CRSS</sub>	TXD[3:0] Setup to TXC High  TX_ER Setup to TXC High  TXD[3:0] Hold after TXC High  TXER Hold after TXC High  TXEN Hold after TXC High  TXEN High to CRS asserted latency  TXEN Low to CRS de-asserted latency  TXEN High to TX+/TX- output (TX latency)	10ns 10ns Ons Ons Ons	4BT 4BT 7BT	

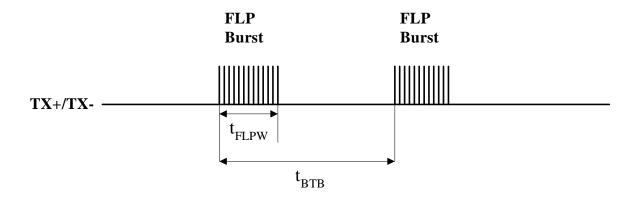
# 100BaseTX MII Receive Timing

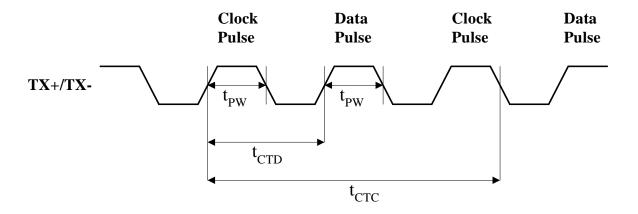


		min.	typ.	max.
t <sub>P</sub>	RXC period		40ns	
$t_{WL}$	RXC pulse width		20ns	
$t_{WH}$	RXC pulse width		20ns	
$t_{SU}$	RXD[3:0], RXER, RXDV setup to rising edge of RXC		20ns	
$t_{ m HD}$	RXD[3:0], RXER, RXDV hold from rising edge of RXC		20ns	
$t_{RLAT}$	CRS to RXD latency, 4B or 5B aligned	1 B T	2BT	3 B T
$t_{CRS1}$	"Start of Stream" to CRS asserted		140ns	
$t_{CRS2}$	"End of Stream" to CRS de-asserted		170ns	

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# **Auto Negotiation / Fast Link Pulse Timing**

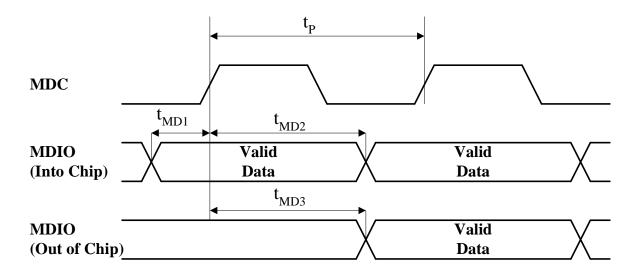




		min.	typ.	max.
$t_{\rm BTB} \\ t_{\rm FLPW} \\ t_{\rm PW} \\ t_{\rm CTD} \\ t_{\rm CTC}$	FLP burst to FLP burst FLP burst width Clock/Data pulse width Clock pulse to data pulse Clock pulse to clock pulse	8ms	16ms 2ms 100ns 69us 136us	24ms
CIC	Number of Clock/Data pulses per burst	17		33

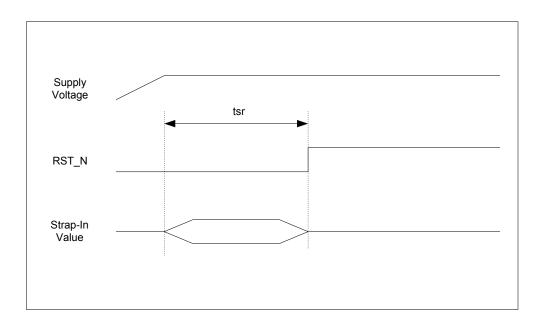
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# **Serial Management Interface Timing**



		min.	typ.	max.
$\begin{bmatrix} t_{\mathrm{p}} \\ t_{\mathrm{MD1}} \\ t_{\mathrm{MD2}} \\ t_{\mathrm{MD3}} \end{bmatrix}$	MDC period MDIO Setup to MDC (MDIO as input) MDIO Hold after MDC (MDIO as input) MDC to MDIO Valid (MDIO as output)	10ns 10ns	400 ns 222ns	
D . C				

## **Reset Timing Diagram**

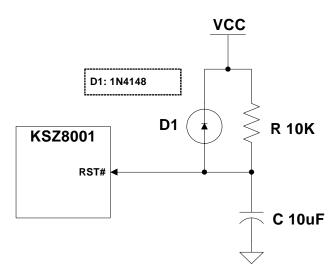


## **Reset Timing Parameters**

Parameter	Description		Max	Units
t <sub>sr</sub>	Stable supply voltages to reset high	50		us

## **Reset Circuit Diagram**

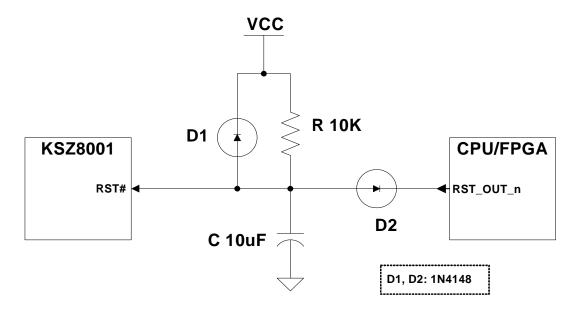
Micrel recommends the following discrete reset circuit when powering up the KSZ8001 device.



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**Recommended Reset Circuit** 

For the application where the reset circuit signal comes from another device (e.g., CPU, FPGA, etc), the following reset circuit is recommended.



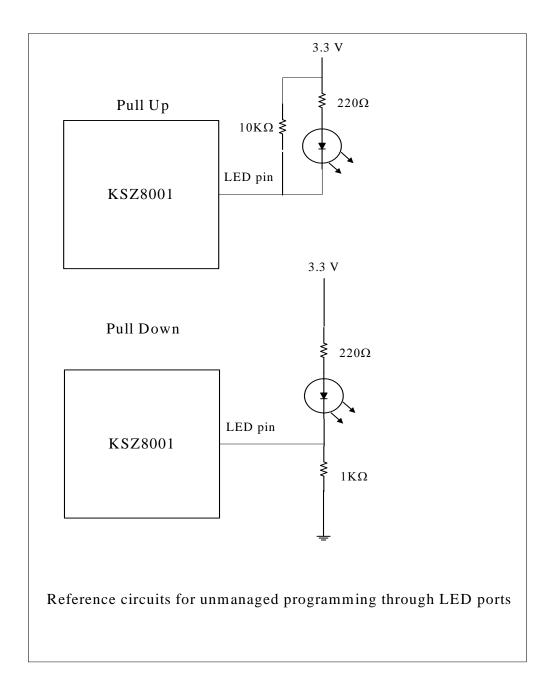
## Recommended Circuit for Interfacing with CPU/FPGA Reset

At power-on-reset, R, C, and D1 provide the necessary ramp rise time to reset the Micrel device. The reset out from CPU/FPGA provides warm reset after power up. It is also recommend to power up VDD core voltage earlier than VDDIO voltage. At worst case, the both VDD core and VDDIO voltages should come up at the same time.

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## **Reference Circuit for Strapping Option Configuration**

The following figure shows the reference circuits for external pull-up and pull-down on the LED strapping pins.



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### **Selection of Isolation Transformer**

A 1:1 isolation transformer is required at the line interface. An isolation transformer with integrated common-mode choke is recommended for exceeding FCC requirements. The following table gives recommended transformer characteristics.

#### **Transformer Selection Criteria**

Parameter	Value	Test Condition
Turns Ratio	1 CT : 1 CT	
Open-Circuit Inductance (min.)	350 uH	100 mV, 100 kHz, 8 mA
Leakage Inductance (max.)	0.4 uH	1 MHz (min.)
Inter-Winding Capacitance (max.)	12 pF	
D.C. Resistance (max.)	0.9 Ohms	
Insertion Loss (max.)	1.0 dB	0-65 MHz
HIPOT (min.)	1500 Vrms	

#### **Magnetic Vendor Selection Lists**

Single Port						
Magnetic manufacturer	Part number	AUTO MDIX	Number of port			
Pulse	H1102	Yes	1			
Bel Fuse	S558-5999-U7	Yes	1			
Bel Fuse	SI-46001	Yes	1			
Bel Fuse	SI-50170	Yes	1			
YCL	PT163020	Yes	1			
Transpower	HB726	Yes	1			
Delta	LF8505	Yes	1			
LanKom	LF-H41S	Yes	1			

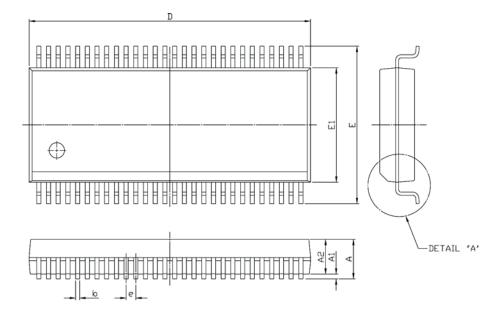
## **Selection of Reference Crystal**

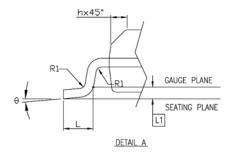
An oscillator or crystal with the following typical characteristics is recommended.

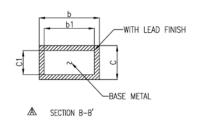
Charateristics	Value	Units
Frequency	25.00000	MHz
Frequency Tolerance(max)	± 50	ppm
Load Capacitance (max)	20	pF
Series Resistance	40	Ω

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# **Package Information**





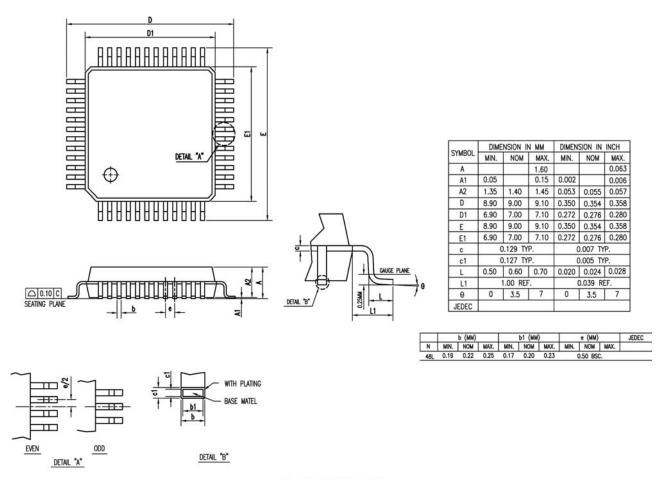


SYMBOL	DIMENSION IN MM			DIMENSION IN INCH		
SIMBUL	MIN.	NOM	MAX.	MIN.	NOM	MAX.
Α	2.413	2.591	2.794	0.095	0.102	0.110
A1	0.203	0.305	0.406	0.008	0.012	0.016
b	0.203		0.343	0.008		0.014
Ь1	0.203	0.254	0.305	0.008	0.010	0.012
С	0.127		0.254	0.005		0.010
c1	0.127		0.216	0.005		0.009
Ε	10.058	10.312	10.566	0.396	0.406	0.416
E1	7.391	7.493	7.595	0.291	0.295	0.299
е	0.6	35 BAS	IC	0.025 BASIC		
h	0.381		0.635	0.015		0.025
L	0.508		1.016	0.020		0.040
L1	0.254 BASIC		0.	010 BAS	SIC	
R1						
θ	0		5	0		5

		D (MM)	JEDEC	
N	MIN.	NOM	MAX.	
48	15.748	15.875	16.002	MO-118AA
56	18.288	18.415	18.542	MO-118AB

48-Pin SSOP (SM)

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48-Pin LQFP (LQ)

#### MICREL, INC. 1849 FORTUNE DRIVE SAN JOSE, CA 95131 USA

TEL: +1 (408) 944-0800 FAX: +1 (408) 944-0970 WEB: http://www.micrel.com

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