TSH80-TSH81-TSH82

Wide Band, Rail-to-Rail Operational Amplifier with Standby Function

- **4.5V, 12V** operating conditions
- 3dB-bandwidth: 100MHz
- Slew-rate: **100V/μs**
- Output current: up to **55mA**
- Input single supply voltage
- Output rail-to-rail
- Specified for 150Ω load
- Low distortion, THD: **0.1%**
- SOT23-5, TSSOP and SO packages

L
SOT23-5
(Plastic Micro package)

D
SO-8
(Plastic Micro package)

P
TSSOP8
(Plastic Micro package)

Description

The TSH8x series offers single and dual operational amplifiers featuring high video performances with large bandwidth, low distortion and excellent supply voltage rejection. These amplifiers feature also large output voltage swing and high output current capability to drive standard 150Ω loads.

Running at single or dual supply voltage from 4.5V to 12V, these amplifiers are tested at 5V(±2.5V) and 10V(±5V) supplies.

The TSH81 also features a standby mode, which allows the operational amplifier to be put into a standby mode with low power consumption and high output impedance.The function allows power saving or signals switching/multiplexing for high speed applications and video applications.
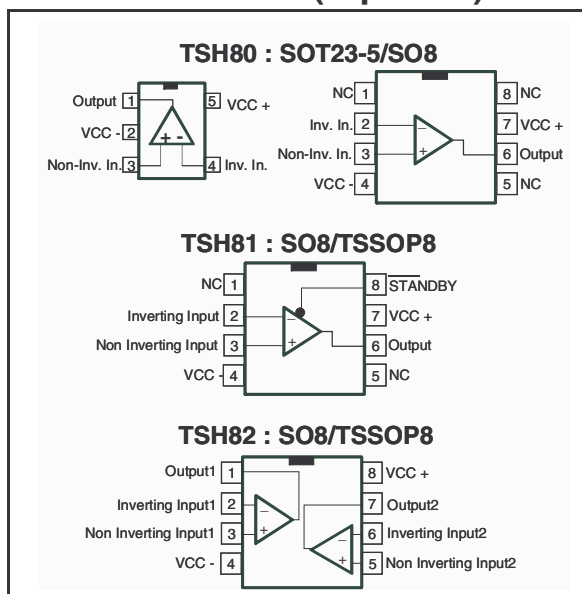
For board space and weight saving, TSH8x series is proposed in SOT23-5, TSSOP8 and SO-8 packages.

Application

- Video buffers
- A/D converters driver
- Hi-Fi applications
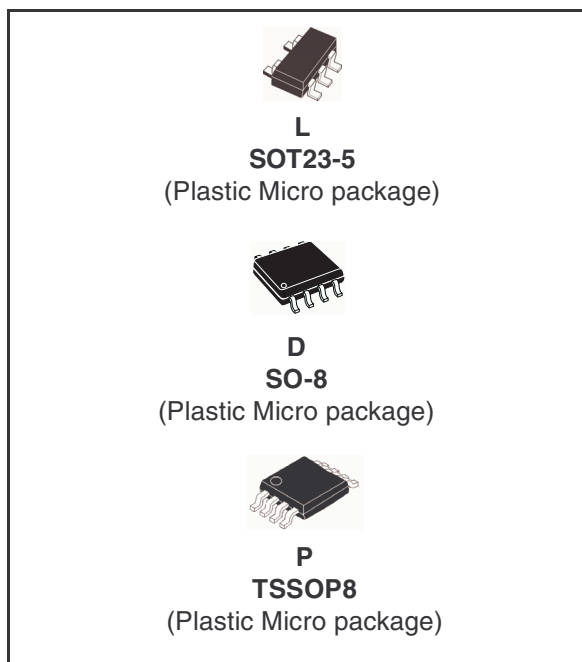
Pin Connections (top view)

TSH80 : SOT23-5/SO8

TSH81 : SO8/TSSOP8

TSH82 : SO8/TSSOP8

Order Codes

Type	Temperature Range	Package	Packaging	Marking
TSH80ILT	-40°C to +85°C	SOT23-5	Tape & Reel	K303
TSH80IYLT		SOT23-5 (automotive grade level)		K310
TSH80ID/DT		SO-8	Tube or Tape & Reel	TSH80I
TSH80IYD/IYDT	-40°C to +125°C	SO-8 (automotive grade level)		SH80IY
TSH81ID/DT	-40°C to +85°C	SO-8		TSH81I
TSH81IPT		TSSOP8	Tape & Reel	SH81I
TSH82ID/DT		SO-8	Tube or Tape & Reel	TSH82I
TSH82IPT		TSSOP8	Tape & Reel	SH82I
TSH82IYD/ITDT	-40°C to +125°C	SO-8 (automotive grade level)	Tube or Tape & Reel	SH82IY

1   Absolute Maximum Ratings

Table 1.   **Key parameters and their absolute maximum ratings**

Symbol	Parameter	Value	Unit
V_{CC}	Supply Voltage [1]	14	V
V_{id}	Differential Input Voltage [2]	±2	V
V_i	Input Voltage [3]	±6	V
T_{oper}	Operating Free Air Temperature Range	-40 to +85	°C
T_{stg}	Storage Temperature	-65 to +150	°C
T_j	Maximum Junction Temperature	150	°C
R_{thjc}	Thermal resistance junction to case [4] SOT23-5 SO8 TSSOPO8	80 28 37	°C/W
R_{thja}	Thermal resistance junction to ambient area SOT23-5 SO8 TSSOPO8	250 157 130	°C/W
ESD	Human Body Model	2	kV

1. All voltage values, except differential voltage are with respect to network ground terminal

2. Differential voltages are non-inverting input terminal with respect to the inverting terminal

3. The magnitude of input and output must never exceed V_{CC} +0.3V

4. Short-circuits can cause excessive heating

Table 2.   **Operating conditions**

Symbol	Parameter	Value	Unit
V_{CC}	Supply Voltage	4.5 to 12	V
V_{IC}	Common Mode Input Voltage Range	V_{CC}^- to (V_{CC}^+ -1.1)	V
Standby		(V_{CC}^-) to (V_{CC}^+)	V

2 Electrical Characteristics

Table 3. V_{CC}^+ = +5V, V_{CC}^- = GND, V_{ic} = 2.5V, T_{amb} = 25°C (unless otherwise specified)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
$|V_{io}|$	Input Offset Voltage	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$		1.1	10 12	mV
ΔV_{io}	Input Offset Voltage Drift vs. Temperature	$T_{min.}$ < T_{amb} < $T_{max.}$		3		µV/°C
I_{io}	Input Offset Current	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$		0.1	3.5 5	µA
I_{ib}	Input Bias Current	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$		6	15 20	µA
C_{in}	Input Capacitance			0.3		pF
I_{CC}	Supply Current per Operator	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$		8.2	10.5 11.5	mA
CMR	Common Mode Rejection Ratio ($\delta Vic/\delta Vio$)	+0.1<Vic<3.9V & Vout=2.5V T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$	72 70	97		dB
SVR	Supply Voltage Rejection Ratio ($\delta Vcc/\delta Vio$)	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$	68 65	75		dB
PSR	Power Supply Rejection Ratio ($\delta Vcc/\delta Vout$)	Positive & Negative Rail		75		dB
A_{vd}	Large Signal Voltage Gain	R_L=150Ω to 1.5V V_{out}=1V to 4V T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$	75 70	84		dB
I_o	Output Short Circuit Current Source	T_{amb}=25°C V_{id}=+1, V_{out} to 1.5V V_{id}=-1, V_{out} to 1.5V |Source| Sink $T_{min.}$ < T_{amb} < $T_{max.}$ V_{id}=+1, V_{out} to 1.5V V_{id}=-1, V_{out} to 1.5V |Source| Sink	35 33 28 28	55 55		mA

Table 3. V_{CC}^+ = +5V, V_{CC}^- = GND, V_{ic} = 2.5V, T_{amb} = 25°C (unless otherwise specified)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
V_{oh}	High Level Output Voltage	T_{amb}=25°C R_L = 150Ω to GND R_L = 600Ω to GND R_L = 2kΩ to GND R_L = 10kΩ to GND R_L = 150Ω to 2.5V R_L = 600Ω to 2.5V R_L = 2kΩ to 2.5V R_L = 10kΩ to 2.5V $T_{min.} < T_{amb} < T_{max.}$ R_L = 150Ω to GND R_L = 150Ω to 2.5V	4.2 4.5 4.1 4.4	4.36 4.85 4.90 4.93 4.66 4.90 4.92 4.93		V
V_{ol}	Low Level Output Voltage	T_{amb}=25°C R_L = 150Ω to GND R_L = 600Ω to GND R_L = 2kΩ to GND R_L = 10kΩ to GND R_L = 150Ω to 2.5V R_L = 600Ω to 2.5V R_L = 2kΩ to 2.5V R_L = 10kΩ to 2.5V $T_{min.} < T_{amb} < T_{max.}$ R_L = 150Ω to GND R_L = 150Ω to 2.5V		48 54 55 56 220 105 76 61	150 400 200 450	mV
GBP	Gain Bandwidth Product	F=10MHz A_{VCL}=+11 A_{VCL}=-10		65 55		MHz
Bw	Bandwidth @-3dB	A_{VCL}=+1 R_L=150Ω to 2.5V		87		MHz
SR	Slew Rate	A_{VCL}=+2 R_L=150Ω // C_L to 2.5V C_L = 5pF C_L = 30pF	60	104 105		V/µs
φm	Phase Margin	R_L=150Ω // 30pF to 2.5V		40		°
en	Equivalent Input Noise Voltage	F=100kHz		11		nV/√Hz
THD	Total Harmonic Distortion	A_{VCL}=+2, F=4MHz R_L=150Ω // 30pF to 2.5V V_{out}=1Vpp V_{out}=2Vpp		-61 -54		dB

Table 3. V_{CC}^+ = +5V, V_{CC}^- = GND, V_{ic} = 2.5V, T_{amb} = 25°C (unless otherwise specified)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
IM2	Second order inter modulation product	A_{VCL}=+2, V_{out}=2Vpp R_L=150Ω to 2.5V Fin1=180kHz, Fin2=280kHz spurious measurement @100kHz		-76		dBc
IM3	Third order inter modulation product	A_{VCL}=+2, V_{out}=2Vpp R_L=150Ω to 2.5V Fin1=180kHz, Fin2=280KHz spurious measurement @400kHz		-68		dBc
ΔG	Differential gain	A_{VCL}=+2, R_L=150Ω to 2.5V F=4.5MHz, V_{out}=2Vpp		0.5		%
Df	Differential phase	A_{VCL}=+2, R_L=150Ω to 2.5V F=4.5MHz, V_{out}=2Vpp		0.5		$^\circ$
Gf	Gain Flatness	F=DC to 6MHz, A_{VCL}=+2		0.2		dB
Vo1/Vo2	Channel Separation	F=1MHz to 10MHz		65		dB

Table 4. V_{CC}^+ = +5V, V_{CC}^- = -5V, V_{ic} = GND, T_{amb} = 25°C (unless otherwise specified)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
$|V_{io}|$	Input Offset Voltage	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$		0.8	10 12	mV
ΔV_{io}	Input Offset Voltage Drift vs. Temperature	$T_{min.}$ < T_{amb} < $T_{max.}$		2		µV/°C
I_{io}	Input Offset Current	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$		0.1	3.5 5	µA
I_{ib}	Input Bias Current	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$		6	15 20	µA
C_{in}	Input Capacitance			0.7		pF
I_{CC}	Supply Current per Operator	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$		9.8	12.3 13.4	mA
CMR	Common Mode Rejection Ratio (δVic/δVio)	-4.9 < Vic < 3.9V & Vout=GND T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$	81 72	106		dB
SVR	Supply Voltage Rejection Ratio (δVCC/δVio)	T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$	71 65	77		dB

Table 4. $V_{CC}{}^+$ = +5V, $V_{CC}{}^-$ = -5V, V_{ic} = GND, T_{amb} = 25°C (unless otherwise specified)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
PSR	Power Supply Rejection Ratio (δVCC/δVout)	Positive & Negative Rail		75		dB
A_{vd}	Large Signal Voltage Gain	R_L=150Ω to GND V_{out}=-4 to +4 T_{amb} = 25°C $T_{min.}$ < T_{amb} < $T_{max.}$	75 70	86		dB
I_o	Output Short Circuit Current Source	T_{amb}=25°C V_{id}=+1, V_{out} to 1.5V V_{id}=-1, V_{out} to 1.5V |Source| Sink $T_{min.}$ < T_{amb} < $T_{max.}$ V_{id}=+1, V_{out} to 1.5V V_{id}=-1, V_{out} to 1.5V |Source| Sink	35 30 28 28	55 55		mA
V_{oh}	High Level Output Voltage	T_{amb}=25°C R_L = 150Ω to GND R_L = 600Ω to GND R_L = 2kΩ to GND R_L = 10kΩ to GND $T_{min.}$ < T_{amb} < $T_{max.}$ R_L = 150Ω to GND	4.2 4.1	4.36 4.85 4.9 4.93		V
V_{ol}	Low Level Output Voltage	T_{amb}=25°C R_L = 150Ω to GND R_L = 600Ω to GND R_L = 2kΩ to GND R_L = 10kΩ to GND $T_{min.}$ < T_{amb} < $T_{max.}$ R_L = 150Ω to GND		-4.63 -4.86 -4.9 -4.93	-4.4 -4.3	mV
GBP	Gain Bandwidth Product	F=10MHz A_{VCL}=+11 A_{VCL}=-10		65 55		MHz
Bw	Bandwidth @-3dB	A_{VCL}=+1 R_L=150Ω // 30pF to GND		100		MHz
SR	Slew Rate	A_{VCL}=+2 R_L=150Ω // C_L to GND C_L = 5pF C_L = 30pF	68	117 118		V/μs
ϕm	Phase Margin	R_L=150Ω to gnd		40		$^\circ$

Table 4. V_{CC}^{+} = +5V, V_{CC}^{-} = -5V, V_{ic} = GND, T_{amb} = 25°C (unless otherwise specified)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
en	Equivalent Input Noise Voltage	F=100kHz		11		nV/√Hz
THD	Total Harmonic Distortion	A_{VCL}=+2, F=4MHz R_L=150Ω // 30pF to gnd V_{out}=1Vpp V_{out}=2Vpp		-61 -54		dB
IM2	Second order inter modulation product	A_{VCL}=+2, V_{out}=2Vpp R_L=150Ω to gnd Fin1=180kHz, Fin2=280KHz spurious measurement @100kHz		-76		dBc
IM3	Third order inter modulation product	A_{VCL}=+2, V_{out}=2Vpp R_L=150Ω to gnd Fin1=180kHz, Fin2=280KHz spurious measurement @400kHz		-68		dBc
ΔG	Differential gain	A_{VCL}=+2, R_L=150Ω to gnd F=4.5MHz, V_{out}=2Vpp		0.5		%
Df	Differential phase	A_{VCL}=+2, R_L=150Ω to gnd F=4.5MHz, V_{out}=2Vpp		0.5		°
Gf	Gain Flatness	F=DC to 6MHz, A_{VCL}=+2		0.2		dB
Vo1/Vo2	Channel Separation	F=1MHz to 10MHz		65		dB

Table 5.   Standby mode

V_{CC}^+, V_{CC}^-, T_{amb} = 25°C (unless otherwise specified)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
VI_{ow}	Standby Low Level		V_{CC}^-		(V_{CC}^- +0.8)	V
V_{high}	Standby High Level		(V_{CC}^- +2)		(V_{CC}^+)	V
$I_{CC\ SBY}$	Current Consumption per Operator when STANDBY is Active	pin 8 (TSH81) to V_{CC}^-		20	55	µA
Z_{out}	Output Impedance (Rout// Cout)	R_{out} C_{out}		10 17		MΩ pF
T_{on}	Time from Standby Mode to Active Mode			2		µs
T_{off}	Time from Active Mode to Standby Mode	Down to $I_{CC\ SBY}$ = 10µA		10		µs

TSH81 STANDBY CONTROL pin 8 ($\overline{SBY}$)	**OPERATOR STATUS**
V_{low}	Standby
V_{high}	Active

Figure 1. Closed loop gain & phase vs. frequency

Gain=+2, Vcc= ±2.5V, R_L=150Ω, T_{amb} = 25°C
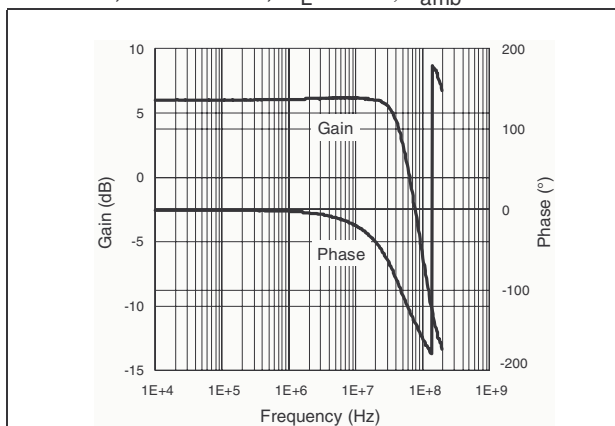

Figure 2. Overshoot function of output capacitance

Gain=+2, Vcc= ±2.5V, T_{amb} = 25°C
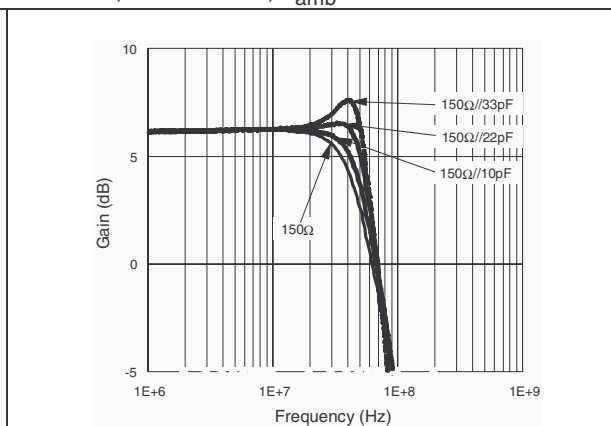
Figure 3. Closed loop gain & phase vs. frequency

Gain=-10, Vcc= ±2.5V, R_L=150Ω, T_{amb} = 25°C
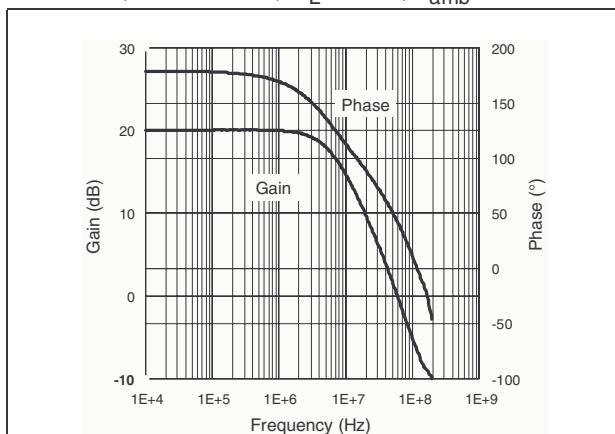
Figure 4. Closed loop gain & phase vs. frequency

Gain=+11, Vcc= ±2.5V, R_L=150Ω, T_{amb} = 25°C
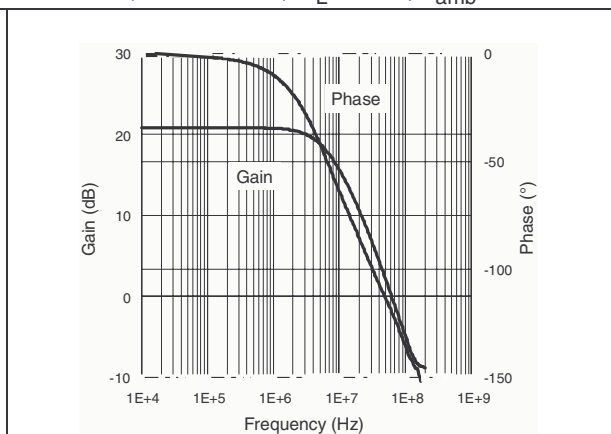
Figure 5. Large signal measurement - positive slew rate

Gain=2,Vcc=±2.5V,Z^L=150Ω//5.6pF,Vin=400mVpk
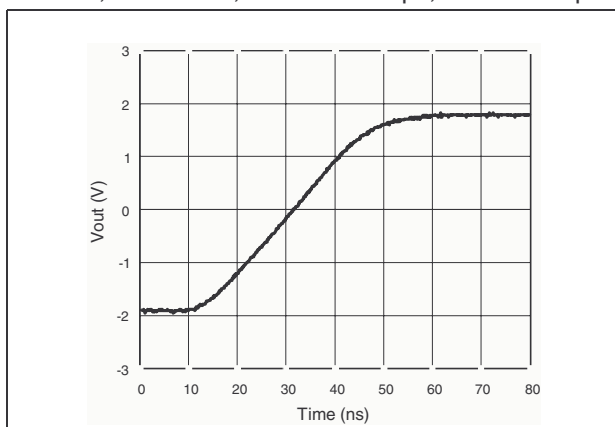
Figure 6. Large signal measurement - negative slew rate

Gain=2,Vcc=±2.5V,Z_L=150Ω//5.6pF,Vin=400mVpk
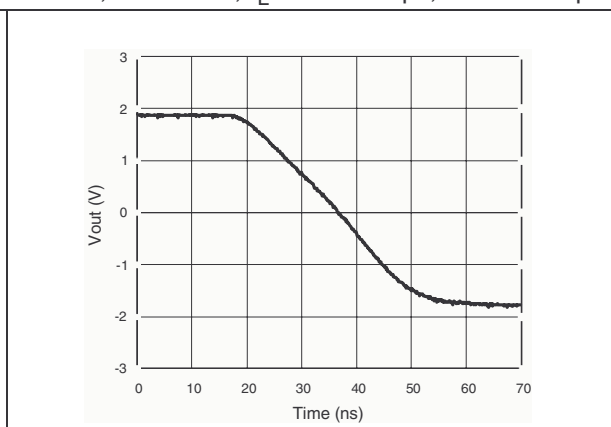
Figure 7.   Small signal measurement - rise time
Gain=2,Vcc=±2.5V,Zl=150Ω,Vin=400mVpk
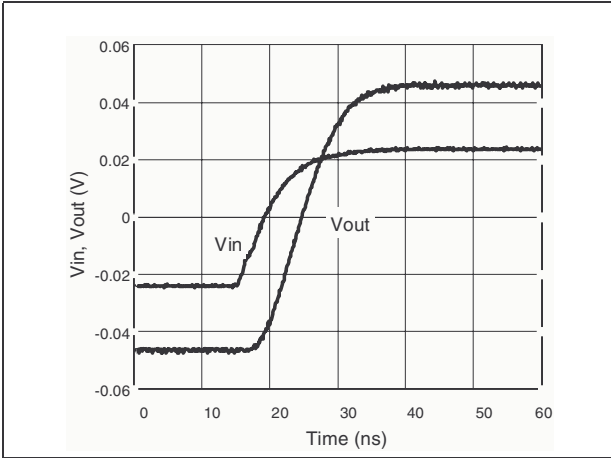
Figure 8.   Small signal measurement - fall time
Gain=2,Vcc=±2.5V,Zl=150Ω,Vin=400mVpk
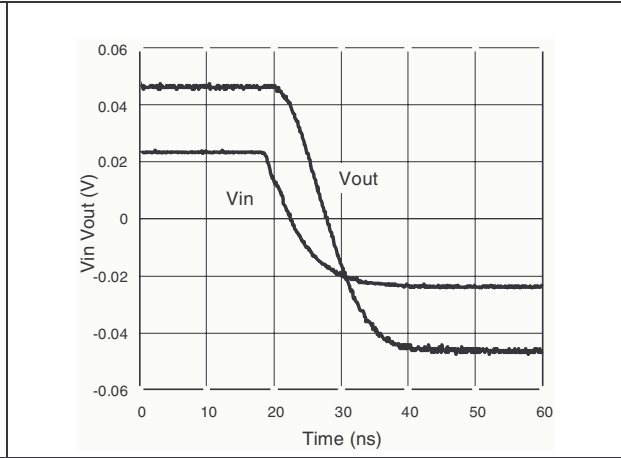
Figure 9.   Channel separation (Xtalk) vs. frequency
Measurement configuration: Xtalk=20log(V0/V1)
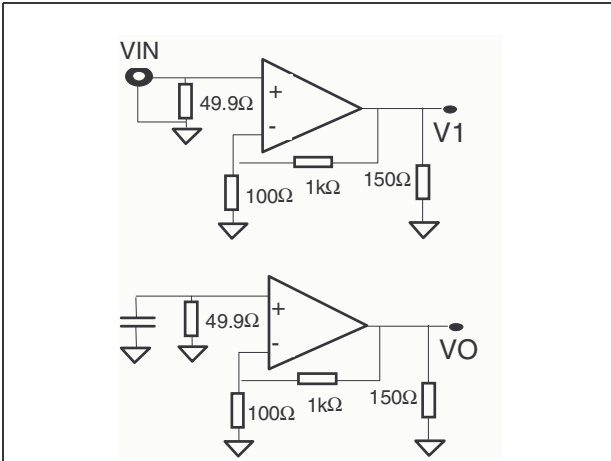
Figure 10.   Channel separation (Xtalk) vs. frequency
Gain=+11, Vcc=±2.5V, ZL=150Ω//27pF
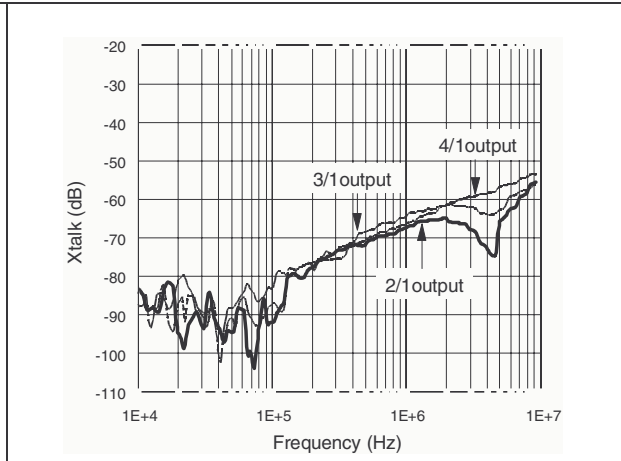
Figure 11.   Equivalent noise voltage
Gain=100, Vcc=±2.5V, No load
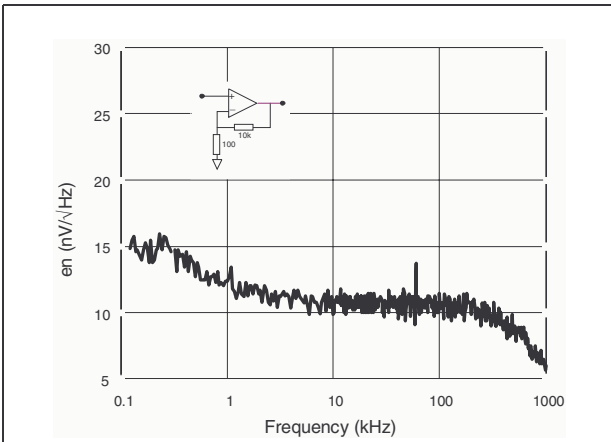
Figure 12.   Maximum output swing
Gain=11, Vcc=±2.5V, RL=150Ω
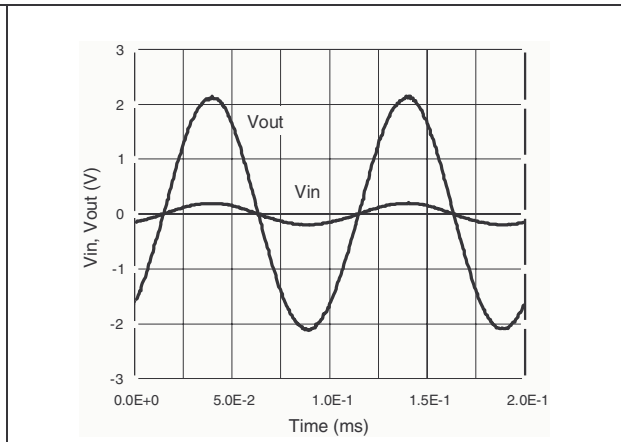
3   Inter Modulation Products

The IFR2026 synthesizer generates a two tones signal (F1=180kHz, F2=280kHz); each tone having the same amplitude level.

The HP3585 spectrum analyzer measures the inter modulation products function of the output voltage. The generator and the spectrum analyzer are phase locked for precision considerations.

Figure 13. Standby mode - Ton, Toff
Vcc= ±2.5V, Open Loop
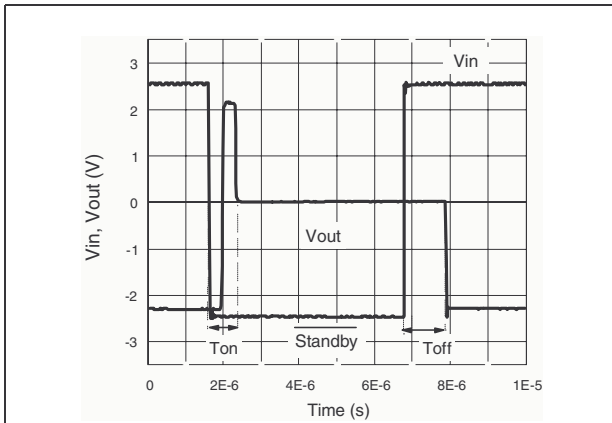
Figure 14. Group delay
Gain=2, Vcc= ±2.5V, ZL=150Ω//27pF, T_{amb} = 25°C
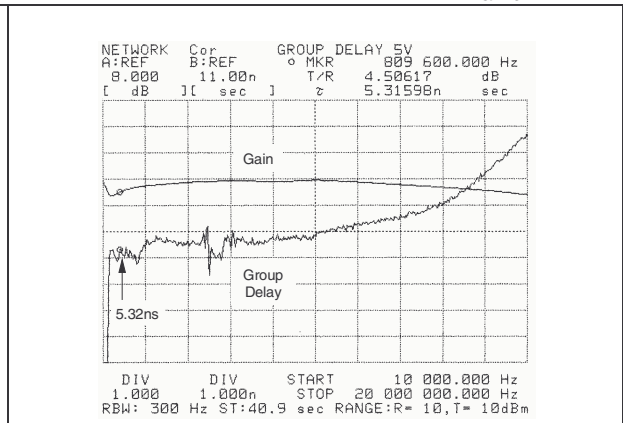
Figure 15. Third order inter modulation
Gain=2, Vcc= ±2.5V, ZL=150Ω//27pF, T_{amb} = 25°C
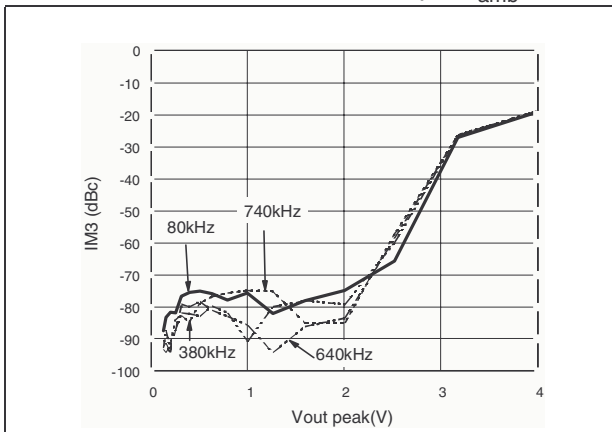
Figure 16. Closed loop gain & phase vs. frequency

Gain=+2, Vcc= ±5V, R_L=150Ω, T_{amb} = 25°C
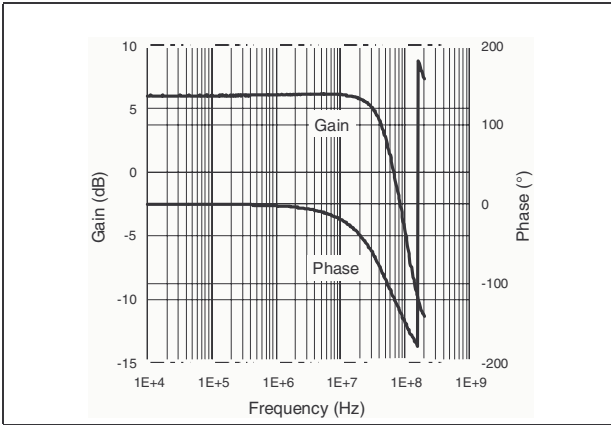
Figure 17. Overshoot function of output capacitance

Gain=+2, Vcc= ±5V, T_{amb} = 25°C
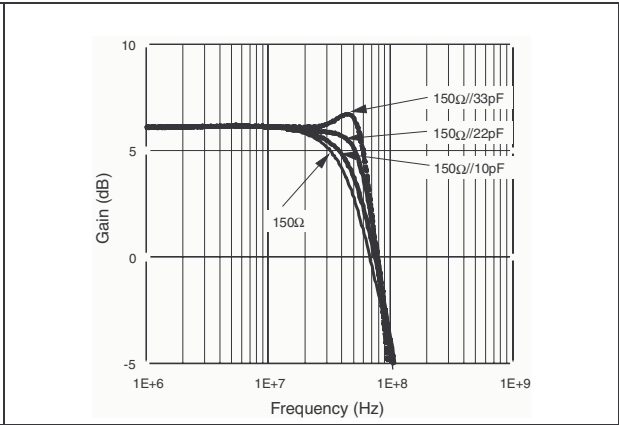
Figure 18. Closed loop gain & phase vs. frequency

Gain=-10, Vcc= ±5V, R_L=150Ω, T_{amb} = 25°C
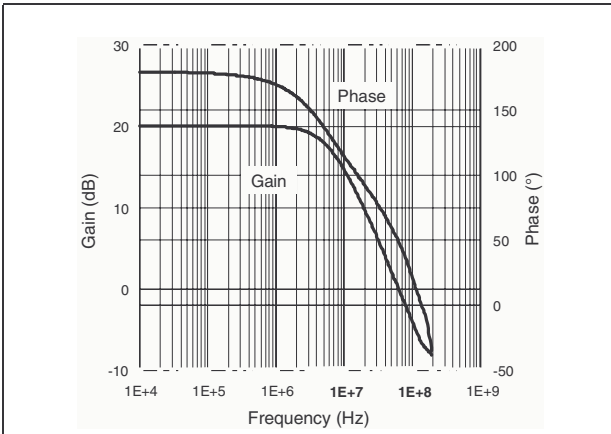
Figure 19. Closed loop gain & phase vs. frequency

Gain=+11, Vcc= ±5V, R_L=150Ω, T_{amb} = 25°C
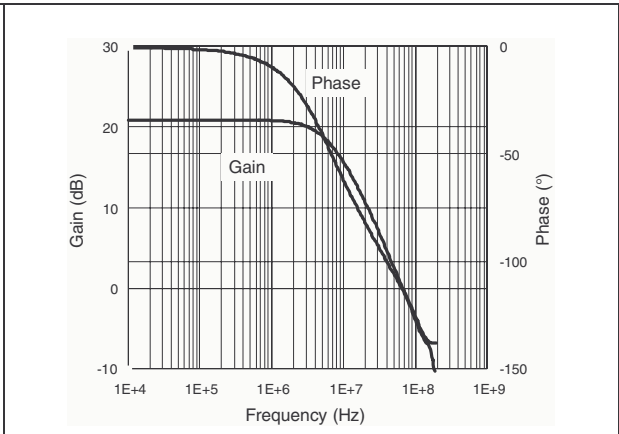
Figure 20. Large signal measurement - positive slew rate

Gain=2,Vcc=±5V,Z_L=150Ω//5.6pF,Vin=400mVpk
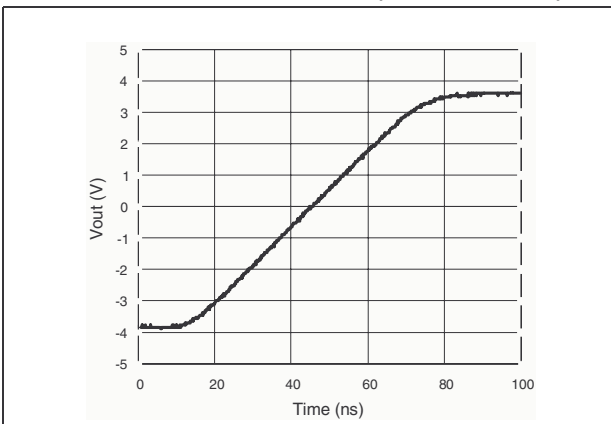
Figure 21. Large signal measurement - negative slew rate
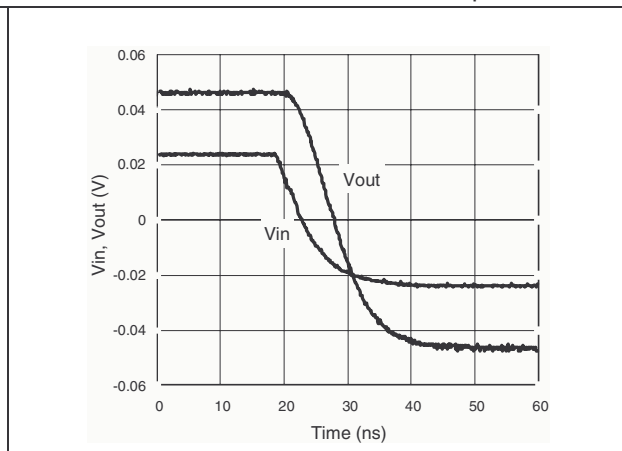
Gain=2,Vcc=±5V,Z_L=150Ω//5.6pF,Vin=400mVpk
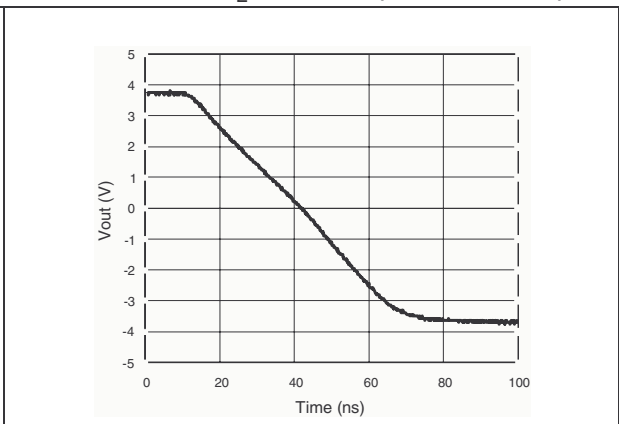
Figure 22. Small signal measurement - rise time
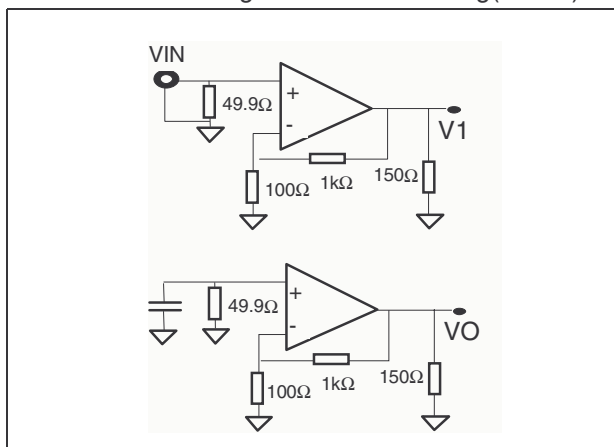
Gain=2,Vcc=±5V,Zl=150Ω,Vin=400mVpk
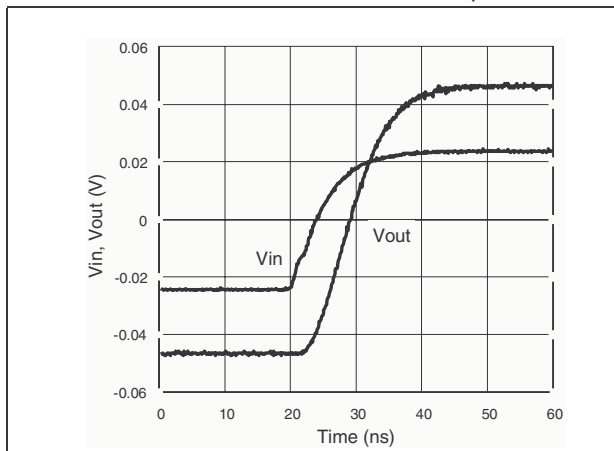
Figure 23. Small signal measurement - fall time
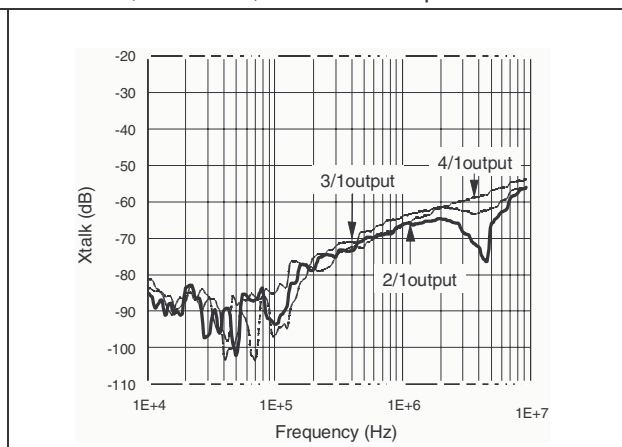
Gain=2,Vcc=±5V,Zl=150Ω,Vin=400mVpk

Figure 24. Channel separation (Xtalk) vs. frequency

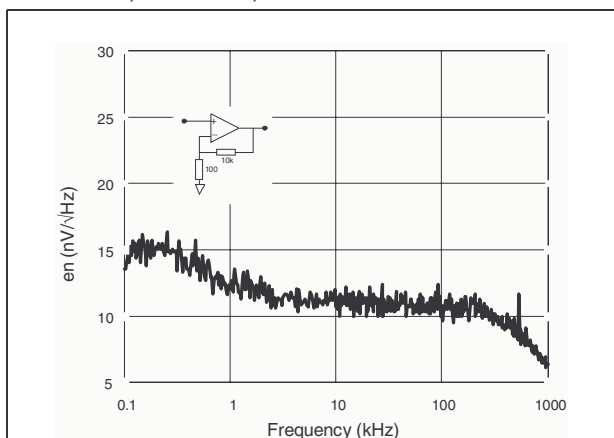Measurement configuration: Xtalk=20log(V0/V1)

Figure 25. Channel separation (Xtalk) vs. frequency

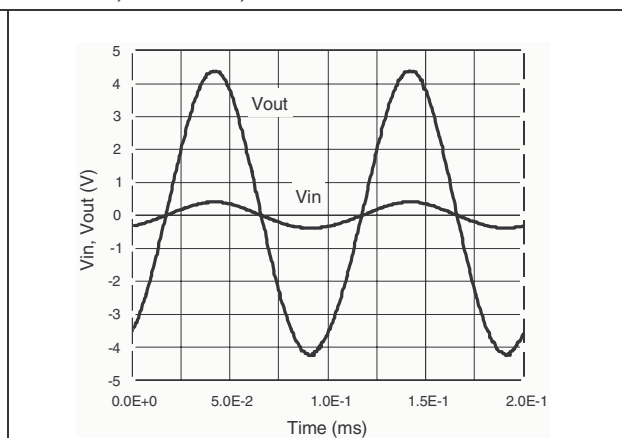Gain=+11, Vcc=±5V, ZL=150Ω//27pF

Figure 26. Equivalent noise voltage

Gain=100, Vcc=±5V, No load

Figure 27. Maximum output swing

Gain=11, Vcc=±5V, RL=150Ω

The IFR2026 synthesizer generates a two tones signal (F1=180kHz, F2=280kHz); each tone having the same amplitude level.

The HP3585 spectrum analyzer measures the inter modulation products function of the output voltage. The generator and the spectrum analyzer are phase locked for precision considerations.
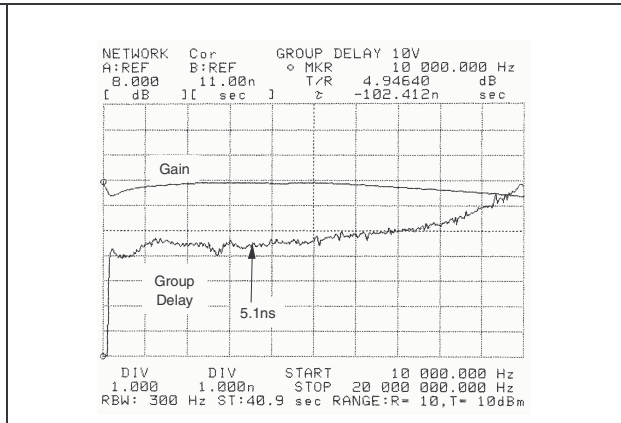
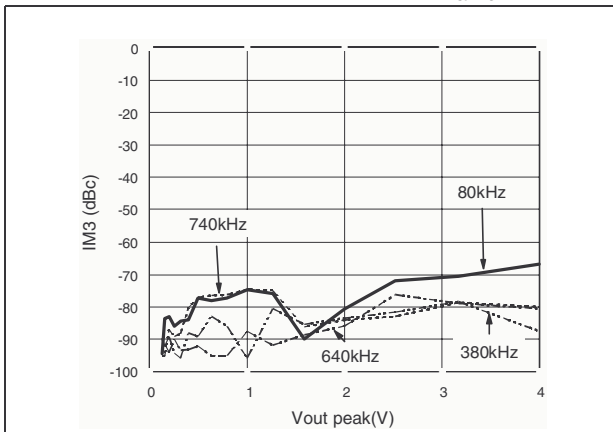**Figure 28. Standby mode - Ton, Toff**
Vcc= ±5V, Open Loop
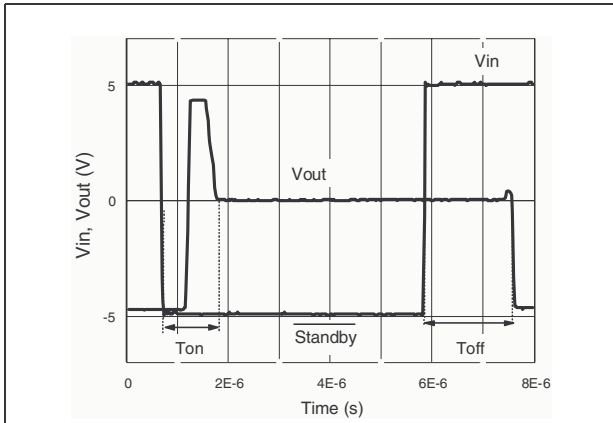
Figure 29. Group delay
Gain=2, Vcc= ±5V, ZL=150Ω//27pF, T_{amb} = 25°C

Figure 30. Third order inter modulation
Gain=2, Vcc= ±5V, ZL=150Ω//27pF, T_{amb} = 25°C

4 Testing Conditions

4.1 Layout precautions:

To use the TSH8X circuits in the best manner at high frequencies, some precautions have to be taken for power supplies:

● First of all, the implementation of a proper ground plane in both sides of the PCB is mandatory for high speed circuit applications to provide low inductance and low resistance common return.

● Power supply bypass capacitors (4.7uF and ceramic 100pF) should be placed as close as possible to the IC pins in order to improve high frequency bypassing and reduce harmonic distortion. The power supply capacitors must be incorporated for both the negative and the positive pins.

● Proper termination of all inputs and outputs must be in accordance with output termination resistors; then the amplifier load will be only resistive and the stability of the amplifier will be improved.

All leads must be wide and as short as possible especially for op amp inputs and outputs in order to decrease parasitic capacitance and inductance.

● For lower gain application, attention should be paid not to use large feedback resistance (>1kΩ) to reduce time constant with parasitic capacitances.

● Choose component sizes as small as possible (SMD).

● Finally, on output, the load capacitance must be negligible to maintain good stability. You can put a serial resistance the closest to the output pin to minimize its influence.

Figure 31. CCIR330 video line
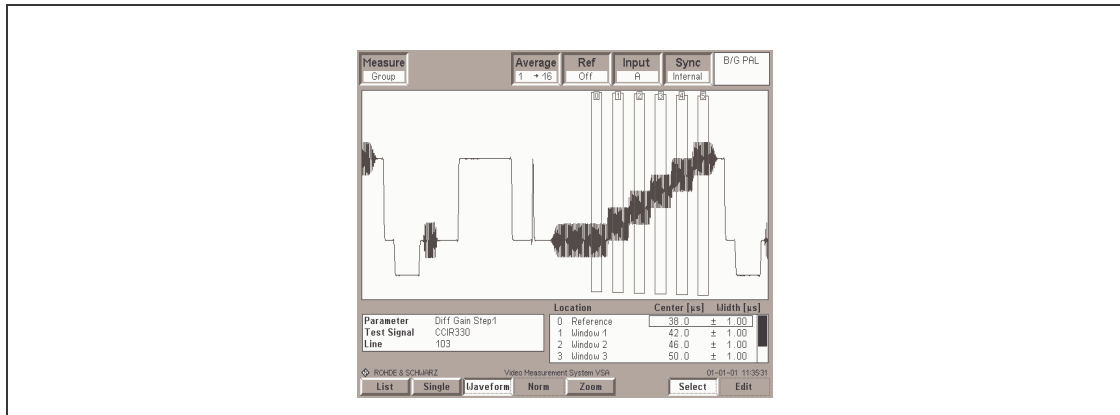
4.2 Maximum input level:

The input level must not exceed the following values:

● Negative peak: must be greater than -Vcc+400mV.

● Positive peak value: must be lower than +Vcc-400mV.

The electrical characteristics show the influence of the load on this parameter.

4.3   Video capabilities:

To characterize the differential phase and differential gain a CCIR330 video line is used.

The video line contains 5 (flat) levels of luma on which is superimposed chroma signal. (the first level contains no luma). The luma gives various amplitudes which define the saturation of the signal. The chrominance gives various phases which define the color of the signal.

Differential phase (respectively differential gain) distortion is present if a signal chrominance phase (gain) is affected by luminance level. They represent the ability to uniformly process the high frequency information at all luminance levels.

When differential gain is present, color saturation is not correctly reproduced.

The input generator is the Rhode & Schwarz CCVS. The output measurement is done by the Rhode and Schwarz VSA.

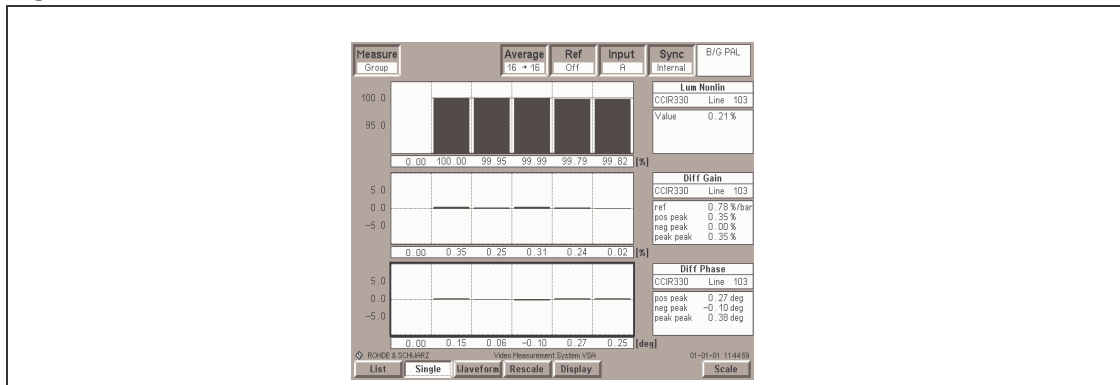**Figure 32.   Measurement on Rhode and Schwarz VSA**

Table 6.   Video results

Parameter	Value (Vcc=±2.5V)	Value (Vcc=±5V)	Unit
Lum NL	0.1	0.3	%
Lum NL Step 1	100	100	%
Lum NL Step 2	100	99.9	%
Lum NL Step 3	99.9	99.8	%
Lum NL Step 4	99.9	99.9	%
Lum NL Step 5	99.9	99.7	%
Diff Gain pos	0	0	%
Diff Gain neg	-0.7	-0.6	%
Diff Gain pp	0.7	0.6	%
Diff Gain Step1	-0.5	-0.3	%
Diff Gain Step2	-0.7	-0.6	%
Diff Gain Step3	-0.3	-0.5	%
Diff Gain Step4	-0.1	-0.3	%
Diff Gain Step5	-0.4	-0.5	%
Diff Phase pos	0	0.1	deg
Diff Phase neg	-0.2	-0.4	deg
Diff Phase pp	0.2	0.5	deg
Diff Phase Step1	-0.2	-0.4	deg
Diff Phase Step2	-0.1	-0.4	deg
Diff Phase Step3	-0.1	-0.3	deg
Diff Phase Step4	0	0.1	deg
Diff Phase Step5	-0.2	-0.1	deg

5 Precautions on Asymmetrical Supply Operation

The TSH8X can be used either with a dual or a single supply. If a single supply is used, the inputs are biased to the mid-supply voltage (+Vcc/2). This bias network must be carefully designed, in order to reject any noise present on the supply rail.

As the bias current is 15uA, you must carefully choose the resistance R1 not to introduce an offset mismatch at the amplifier inputs.
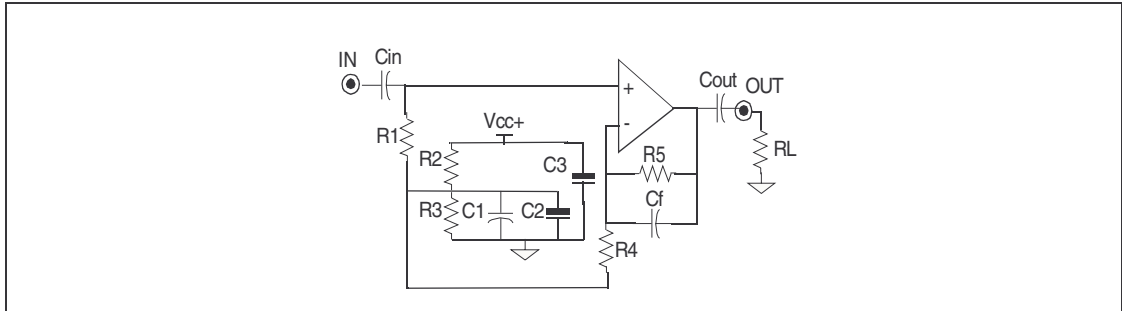

R1=10kΩ will be convenient. C1, C2, C3 are bypass capacitors from perturbation on Vcc as well as for the input and output signals. We choose C1=100nF and C2=C3=100uF.

R2, R3 are such that the current through them must be superior to 100 times the bias current. So, we take R2=R3=4.7kΩ.

Cin, as Cout are chosen to filter the DC signal by the low pass filters (R1,Cin) and (Rout, Cout). By taking R1=10kΩ, RL=150Ω, and Cin=2uF, Cout=220uF we provide a cutoff frequency below 10Hz.

Figure 33. Use of the TSH8x in gain = -1 configuration
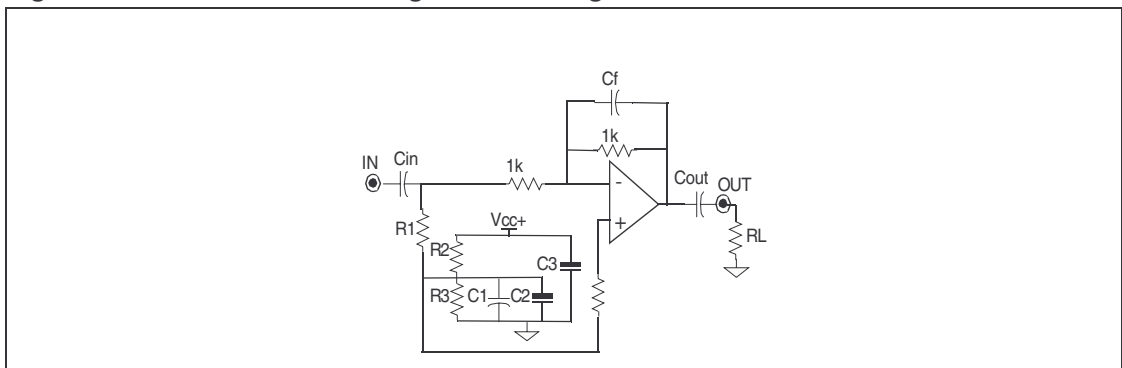
Some precautions have to be added, specially for low power supply application.

A feedback capacitance Cf should be added for better stability.

The table summarizes the impact of the capacitance Cf on the phase margin of the circuit.

Table 7.   **Capacitance Cf on the phase margin of the circuit**

Parameter	Cf (pF)	Vcc=±1.5V	Vcc=±2.5V	Vcc=±5V	Unit
Phase Margin	0	28	43	56	deg
f-3dB		40	39.3	38.3	MHz
Phase Margin	5.6	30	43	56	deg
f-3dB		40	39.3	38.3	MHz
Phase Margin	22	37	52	67	deg
f-3dB		37	34	32	MHz
Phase Margin	33	48	65	78	deg
f-3dB		33.7	30.7	27.6	MHz

Figure 34. Example of a video application
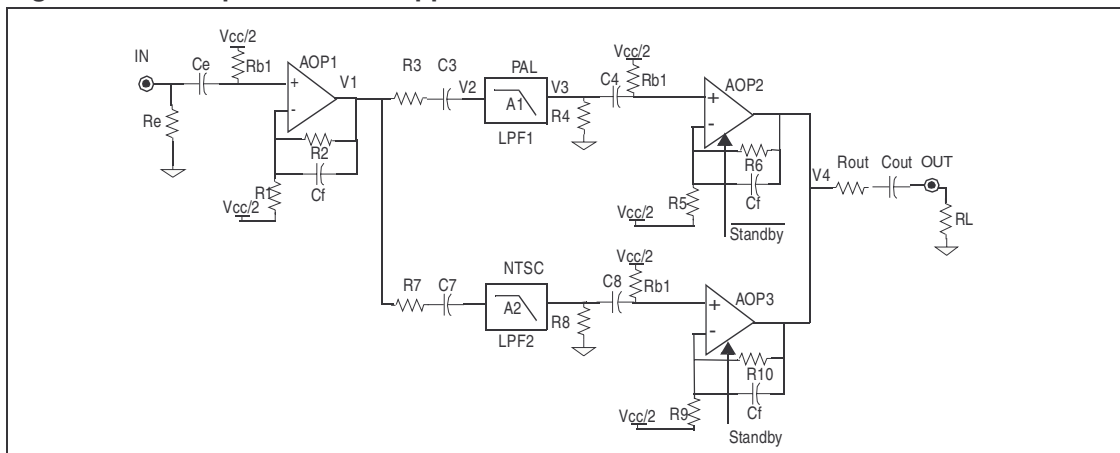
This example shows a possible application of the TSH8X circuit. Here, you can multiplex the channels for the different standard PAL, NTSC as you filter for the different bands; the video signal can be filtered with two different cutoff frequencies, corresponding to a PAL encoded signal (LPF1) or a NTSC signal (LPF2).

You can multiplex input signals, as the outputs are in high impedance state in standby mode. This enables you, to use a PAL filter as the Standby mode is active and to use the NTSC filter otherwise.

The video application requires 1Vpeak at input and output.

Calculation of components:

A decoupling capacitor is provided to cutoff the frequencies below 10Hz according I bias. Hence Ce=10uF, with Rb1=10kΩ. At the output, Cout=220uF.

The AOP1 is in 6dB configuration for the adaptation bridge. R1=R2=1kΩ,V1=2Vpk, V2=1Vpk

For the PAL communication, we need a low pass filtering. The load resistance R4 is function of the output resistance of the filter.V3=V2/A1 where A1 is the attenuation factor of the filter LPF1.

To compensate the filter insertion loss, we add an additional factor to the gain of the 2nd amplifier AOP2.

For example, for an attenuation of 3dB, we choose R5=300Ω and R6=1kΩ. We have V4=2Vpk and Vout=1Vpk.

The calculation of the parameters R7, C7, R8, C8, R9, R10 will be exactly the same

6 Package Mechanical Data

In order to meet environmental requirements, ST offers these devices in ECOPACK® packages. These packages have a Lead-free second level interconnect. The category of second level interconnect is marked on the package and on the inner box label, in compliance with JEDEC Standard JESD97. The maximum ratings related to soldering conditions are also marked on the inner box label. ECOPACK is an ST trademark. ECOPACK specifications are available at: www.st.com.

6.1 SO-8 Package

	SO-8 MECHANICAL DATA					
DIM.	**mm.**			**inch**		
	MIN.	**TYP**	**MAX.**	**MIN.**	**TYP.**	**MAX.**
A	1.35		1.75	0.053		0.069
A1	0.10		0.25	0.04		0.010
A2	1.10		1.65	0.043		0.065
B	0.33		0.51	0.013		0.020
C	0.19		0.25	0.007		0.010
D	4.80		5.00	0.189		0.197
E	3.80		4.00	0.150		0.157
e		1.27			0.050	
H	5.80		6.20	0.228		0.244
h	0.25		0.50	0.010		0.020
L	0.40		1.27	0.016		0.050
k	8° (max.)					
ddd			0.1			0.04
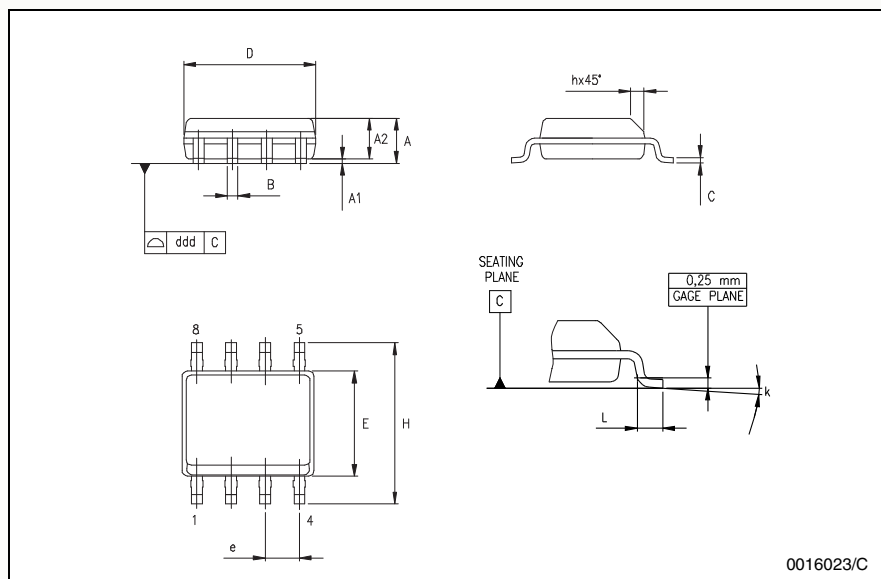
0016023/C

6.2 TSSOP8 Package

TSSOP8 MECHANICAL DATA						
DIM.	**mm.**			**inch**		
	MIN.	**TYP**	**MAX.**	**MIN.**	**TYP.**	**MAX.**
A			1.2			0.047
A1	0.05		0.15	0.002		0.006
A2	0.80	1.00	1.05	0.031	0.039	0.041
b	0.19		0.30	0.007		0.012
c	0.09		0.20	0.004		0.008
D	2.90	3.00	3.10	0.114	0.118	0.122
E	6.20	6.40	6.60	0.244	0.252	0.260
E1	4.30	4.40	4.50	0.169	0.173	0.177
e		0.65			0.0256	
K	0˚		8˚	0˚		8˚
L	0.45	0.60	0.75	0.018	0.024	0.030
L1		1			0.039	

0079397/D
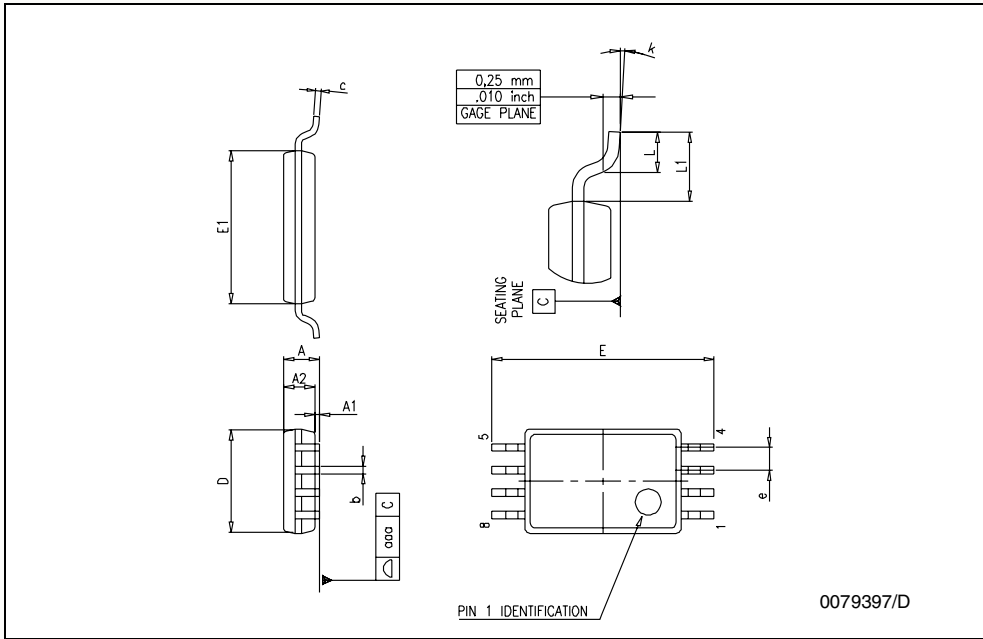
6.3 SOT23-5 Package

SOT23-5L MECHANICAL DATA						
DIM.	**mm.**			**mils**		
	MIN.	**TYP**	**MAX.**	**MIN.**	**TYP.**	**MAX.**
A	0.90		1.45	35.4		57.1
A1	0.00		0.15	0.0		5.9
A2	0.90		1.30	35.4		51.2
b	0.35		0.50	13.7		19.7
C	0.09		0.20	3.5		7.8
D	2.80		3.00	110.2		118.1
E	2.60		3.00	102.3		118.1
E1	1.50		1.75	59.0		68.8
e		0.95			37.4	
e1		1.9			74.8	
L	0.35		0.55	13.7		21.6
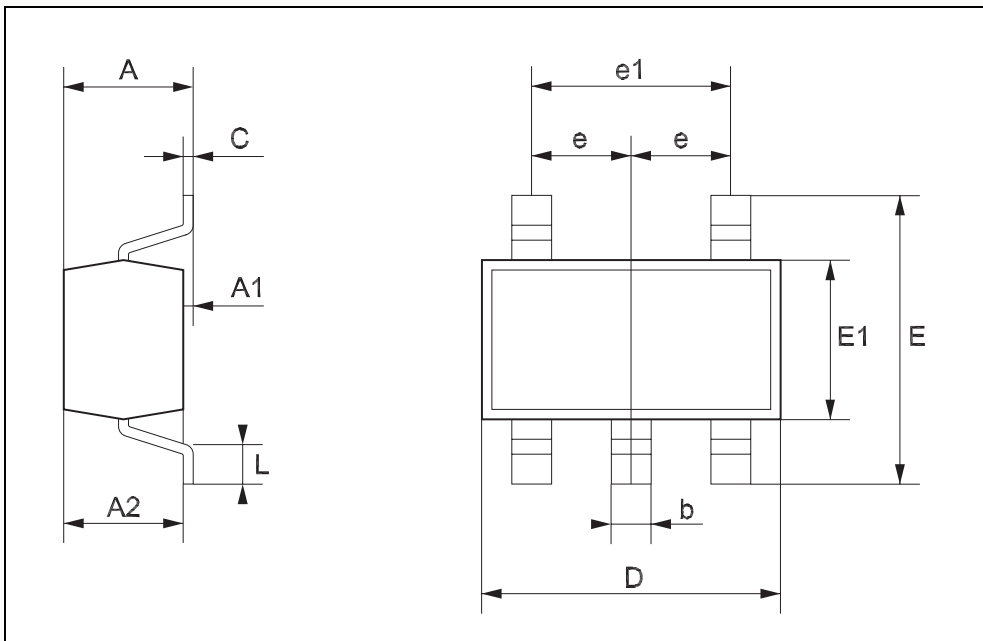
7 Revision History

Date	Revision	Changes
Feb. 2003	1	First Release
Aug. 2005	2	PPAP references inserted in the datasheet see *Table : Order Codes on page 2*.