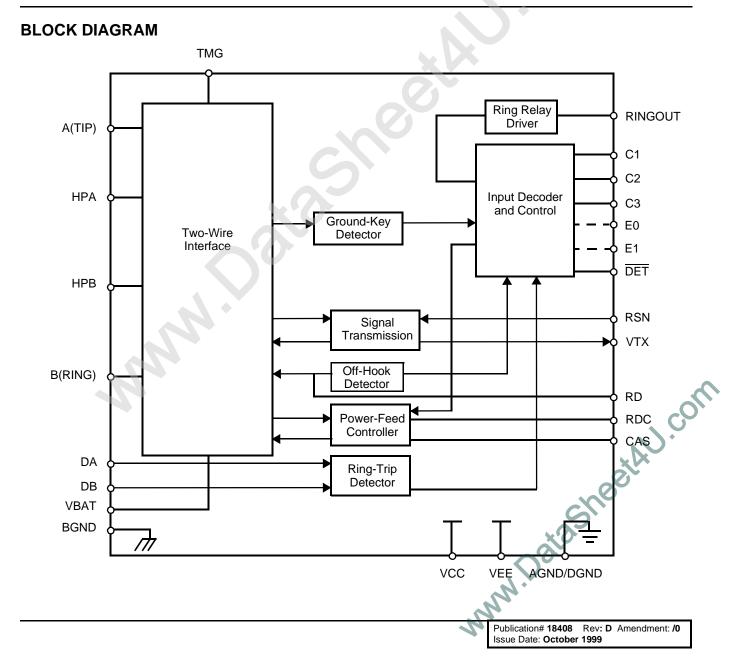
## Am7945 Subscriber Line Interface Circuit

### DISTINCTIVE CHARACTERISTICS

- Programmable constant-current feed
- Current gain = 200
- Programmable loop-detect threshold
- Low power Standby state
- Ground-key detector
- Tip Open state for ground-start lines
- -19 V to -56.5 V battery operation

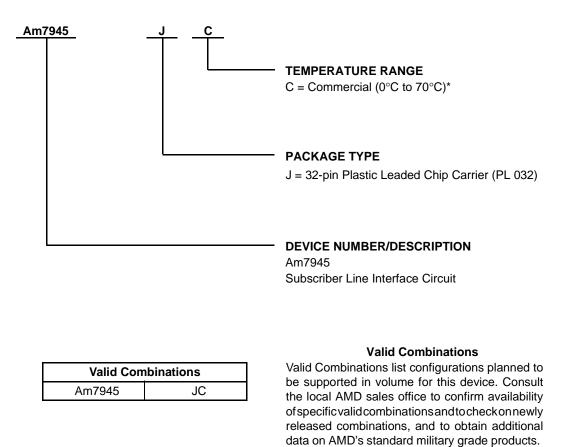
- On-chip Thermal Management (TMG) feature
- Two-wire impedance set by single external impedance
- On-hook transmission
- On-chip ring relay driver and relay snubber circuit
- Ideal for low cost PABX and key telephone systems



#### **ORDERING INFORMATION**

#### **Standard Products**

AMD standard products are available in several packages and operating ranges. The order number (Valid Combination) is formed by a combination of the elements below.

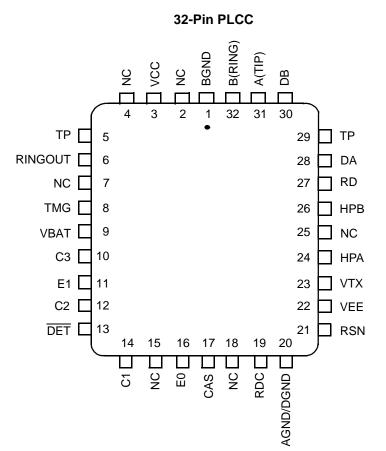


## Note:

\* Functionality of the device from  $0^{\circ}$ C to +70°C is guaranteed by production testing. Performance from -40°C to +85°C is guaranteed by characterization and periodic sampling of production units.

## CONNECTION DIAGRAM

#### **Top View**



#### Notes:

- 1. Pin 1 is marked for orientation.
- 2. TP is a thermal conduction pin tied to substrate.
- 3. NC = No Connect

#### **PIN DESCRIPTIONS**

Pin Names	Туре	Description
AGND/DGND	Gnd	Analog and digital ground
A(TIP)	Output	Output of A(TIP) power amplifier
BGND	Gnd	Battery (power) ground
B(RING)	Output	Output of B(RING) power amplifier
C3–C1	Input	Decoder. TTL compatible. C3 is MSB and C1 is LSB.
CAS	Capacitor	Anti-saturation pin for capacitor to filter reference voltage when operating in anti-saturation region.
DA	Input	Ring-Trip Negative. Negative input to ring-trip comparator.
DB	Input	Ring-Trip Positive. Positive input to ring-trip comparator.
DET	Output	Switchhook Detector. When enabled, a logic Low indicates the selected detector is tripped. The detect condition is selected by the logic inputs (C3–C1, E0, E1). The output is open-collector with a built-in 15 k $\Omega$ pull-up resistor.
E0	Input	Ground-Key Enable. A logic High enables DET. A logic Low disables DET (PLCC only).
E1	Input	Ground-Key Enable. E1 = Low connects the ground-key or ring-trip detector to $\overline{\text{DET}}$ . E1 = High connects the off-hook or ring-trip detector to $\overline{\text{DET}}$ (PLCC only).
HPA	Capacitor	High-Pass Filter Capacitor. A(TIP) side of high-pass filter capacitor.
НРВ	Capacitor	High-Pass Filter Capacitor. B(RING) side of high-pass filter capacitor.
RD	Resistor	Detect Resistor. Threshold modification and filter point for the off-hook detector.
RDC	Resistor	DC Feed Resistor. Connection point for the DC feed current programming network. The other end of the network connects to the receiver summing node (RSN). $V_{RDC}$ is negative for normal polarity and positive for reverse polarity.
RINGOUT	Output	Ring Relay Driver. Open-collector driver with emitter internally connected to BGND.
RSN	Input	Receive Summing Node. The metallic current (both AC and DC) between A(TIP) and B(RING) is equal to 200 times the current into this pin. Networks that program receive gain, two-wire impedance, and feed resistance all connect to this node.
TMG	—	Thermal Management. Connect an external resistor between this pin and the VBAT pin to reduce on-chip power dissipation in the normal polarity, Active state only. See Table 2.
TP	Thermal	Thermal pin. Connection for heat dissipation. Internally connected to substrate (QBAT). Leave as open circuit or connected to QBAT. In both cases, the TP pins can connect to an area of copper on the board to enhance heat dissipation.
VBAT	Battery	Battery supply
VCC	Power	+5 V power supply
VEE	Power	–5 V power supply
VTX	Output	Transmit Audio. This output is a unity gain version of the A(TIP) and B(RING) metallic voltage. VTX also sources the two-wire input impedance programming network.

#### **ABSOLUTE MAXIMUM RATINGS**

Storage temperature55°C to +150°C
With respect to AGND/DGND:
V <sub>CC</sub> –0.4 V to +7.0 V
$V_{EE}.$
V <sub>BAT</sub>
Continuous +0.4 V to -70 V 10 ms
BGND+3 V to –3 V
A(TIP) or B(RING) with respect to BGND:
Continuous
10 ms (f = 0.1 Hz)
$1 \text{ ms} (f = 0.1 \text{ Hz}) \dots -80 \text{ V to +8 V}$
10 µs (f = 0.1 Hz)100 V to +12 V
Current from A(TIP) or B(RING) ±150 mA
Current from TMG 100 mA
Voltage on RINGOUT:
During transient BGND to +10 V
During steady stateBGND to +7 V
Current through relay drivers 60 mA
DA and DB inputs
Voltage on ring-trip inputs V <sub>BAT</sub> to 0 V Current into ring-trip inputs ±10 mA
C3–C1, E0, E1 to AGND/DGND0.4 V to V <sub>CC</sub> + 0.4 V
Maximum power dissipation, $T_A = 85^{\circ}C$ No heat sink (See note):
In 32-pin PLCC package 1.4 W
Thermal data $\dots \dots \theta_{JA}$
In 32-pin PLCC package
Note: Thermal limiting circuitry on chip will shut down the cir-

**Note:** Thermal limiting circuitry on chip will shut down the circuit at a junction temperature of about 165°C. The device should never be exposed to this temperature. Operation above 145°C junction temperature may degrade device reliability. See the SLIC Packaging Considerations for more information.

Stresses above those listed under Absolute Maximum Ratings may cause permanent device failure. Functionality at or above these limits is not implied. Exposure to Absolute Maximum Ratings for extended periods may affect device reliability.

#### **OPERATING RANGES**

#### Commercial (C) Devices

Ambient temperature 0°C to +70°C*
$V_{CC},\ldots\ldots$ .4.75 V to 5.25 V
$V_{EE}$
$V_{\text{BAT}}$
AGND/DGND
BGND with respect to AGND/DGND
Load resistance on VTX to GND $\ldots \ldots 10 \text{ k}\Omega$ min

The Operating Ranges define those limits over which the functionality of the device is guaranteed by production testing.

\* Functionality of the device from  $0^{\circ}$ C to  $+70^{\circ}$ C is guaranteed by production testing. Performance from  $-40^{\circ}$ C to  $+85^{\circ}$ C is guaranteed by characterization and periodic sampling of production units.

#### **ELECTRICAL CHARACTERISTICS**

The Am7945 device is tested under the following conditions unless otherwise noted: BAT = -48 V,  $V_{CC}$  = +5 V,  $V_{EE}$  = -5 V,  $R_L$  = 900  $\Omega$ . The device is not tested in Polarity Reversal state.

Description	Test Conditions (See Note 1)	Min	Тур	Max	Unit	Note
Analog output (V <sub>TX</sub> ) impedance			3		Ω	
Analog output (V <sub>TX</sub> ) offset	0°C to +70°C -40°C to +85°C	-37 -40		+37 +40	mV	4
Analog (RSN) input impedance	300 Hz to 3.4 kHz		1	20	Ω	4
Longitudinal impedance at A or B				35	Ω	
Overload level	4-wire and 2-wire, Active state	-2.5		+2.5	Vpk	2a
	On hook, $R_{LAC} = 900 \Omega$ , Active or OHT state	0.95			Vrms	2b
Transmission Performance	- <b>·</b>	•			•	
2-wire return loss (See Test Circuit D)	200 to 3.4 kHz	26			dB	4, 8
Longitudinal Balance (2-Wire and	4-Wire, See Test Circuit C); R <sub>L</sub> = 740 $\Omega$ a	t BAT = 4	48 V			
Longitudinal to metallic L-T, L-4 normal polarity	200 Hz to 1 kHz 0°C to +70°C -40°C to +85°C	52 50				4
	1 kHz to 3.4 kHz 0°C to +70°C -40°C to +85°C	52 50			dB	4
Longitudinal signal generation 4-L	300 Hz to 800 Hz, normal polarity	40				
Longitudinal current per pin	Active state and OHT state	20	27		mArms	
Insertion Loss (2- to 4-Wire and 4-	to 2-Wire, See Test Circuits A and B) BA	AT = −48	V, R <sub>L</sub> = 9	Ω 00		
Gain accuracy	0 dBm, 1 kHz 0°C to +70°C -40°C to +85°C	-0.15 -0.20		+0.15 +0.20		4
Gain accuracy, OHT state	-10 dBm, On hook, $R_{LAC}$ = 900 $\Omega$	-1.0		+1.0		4
Variation with frequency	300 to 3.4 kHz, relative to 1 kHz 0°C to +70°C -40°C to +85°C	-0.10 -0.15		+0.10 +0.15	dB	4
Gain tracking	+7 dBm to –55 dBm, reference 0 dBm 0°C to +70°C –40°C to +85°C	-0.10 -0.15		+0.10 +0.15		4 4
Balance Return Signal (4- to 4-Wire	e, See Test Circuit B) BAT = –48 V, R <sub>L</sub> = <sup>g</sup>	900 Ω				
Gain accuracy	0 dBm, 1 kHz 0°C to +70°C -40°C to +85°C	-0.15 -0.20		+0.15 +0.20		3 4
Variation with frequency	requency 300 to 3.4 kHz, relative to 1 kHz 0°C to +70°C -40°C to +85°C			+0.10 +0.15	dB	3 4
Gain tracking	+3 dBm to –55 dBm, reference 0 dBm 0°C to +70°C –40°C to +85°C	-0.10 -0.15		+0.10 +0.15		3, 4 4
Group delay	f = 1 kHz			4	μs	4, 8
Total Harmonic Distortion (2- to 4-	Wire or 4- to 2-Wire, See Test Circuits A	and B) E	BAT = -4	8 V, R <sub>L</sub> =	900 Ω	
Harmonic distortion 300 Hz to 3.4 kHz	2-wire level = 0 dBm 2-wire level = +7 dBm		64 55	-50 -40	dB	

## ELECTRICAL CHARACTERISTICS (continued)

Description	Test Conditions (See Note 1)	Min	Тур	Max	Unit	Note
Idle Channel Noise (2-Wire and 4-V	Vire)					
C-message weighted	2-wire, 0°C to +70°C -40°C to +85°C		+7 +10 +7 +12			
	4-wire, 0°C to +70°C -40°C to +85°C		+7 +7	+10 +12	dBrnc	4
Psophometric weighted	2-wire, 0°C to +70°C -40°C to +85°C		-83 -83	-78	dBmp	4
	4-wire, 0°C to +70°C -40°C to +85°C		-83 -83	-75	abinp	4
Line Characteristics, Active State (	See Figure 1)					
Short loops, Active state	$BAT = -48 \text{ V}, \text{ R}_{LDC} = 600 \ \Omega$	24.7		29.3		
Long loops, Active state	BAT = $-48$ V, R <sub>LDC</sub> = 1.9 k $\Omega$	17.5				
OHT state	$BAT = -48 \text{ V}, \text{ R}_{LDC} = 600 \ \Omega$	15.5		20.5	1	
Standby state	$I_{L} = \frac{ V_{BAT}  - 3 V}{R_{L} + 1800}$ $T_{A} = 25^{\circ}C$	0.71 <sub>L</sub>	ΙL	1.3I <sub>L</sub>	mA	
	$R_L = 600 \Omega$ , BAT = -48 V T <sub>A</sub> = 70°C	15.0	17.4			
Loop current	Tip Open state, $R_L = 0 \Omega$			100		
	Disconnect state, $R_L = 0 \Omega$			100	μA	
	Tip Open state, Bwire to GND	21	30	44		
	Tip Open state, Bwire = BAT + 6 V	20	30	45	mA	
I <sub>L</sub> LIM (I <sub>TIP</sub> + I <sub>RING</sub> )	Tip and ring shorted to GND		100	130		
Ground-start signaling (tip voltage)	Active state, $R_{TIP}$ to -48 V = 7.0 k $\Omega$ $R_{RING}$ to GND = 100 k $\Omega$	-7.5	-5.0		v	
Open circuit voltage	Active and OHT state, BAT = $-48$ V	40.5	42.0			
Power Dissipation, BAT = -48 V			-			
On hook, Open Circuit state			25	100		
On hook, OHT state			120	210		
On hook, Active state	$R_{TMG}$ = Open $R_{TMG}$ = 1700 $\Omega$		160 195	230 280	mW	
On hook, Standby state			35	100		
Off hook, OHT state	$R_{L}$ = 300 $\Omega$ , $R_{TMG}$ = $\infty$ , $BAT$ = -48 V		735	1100		
Off hook, Active state	$ \begin{array}{l} R_{L} = 300 \ \Omega, \ R_{TMG} = \infty, \ BAT = -48 \ V \\ R_{L} = 300 \ \Omega, \ R_{TMG} = \infty \end{array} $		1.25 0.57	1.60 0.85	W	
Off hook, Standby state	$R_{L} = 600 \ \Omega, T_{A} = 25^{\circ}C$		0.68	1.0		

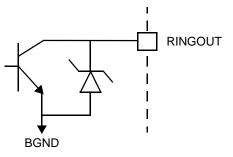
## ELECTRICAL CHARACTERISTICS (continued)

Description	Test Conditions (See Note 1)	Min	Тур	Max	Unit	Note
Supply Currents, BAT = -48 V						
V <sub>CC</sub> , On-hook supply current	Open Circuit state OHT state Standby state Active state		1.7 4.9 2.2 6.3	2.5 7.5 3.0 8.5		
V <sub>EE</sub> , On-hook supply current	Open Circuit state OHT state Standby state Active state		0.7 2.0 0.77 2.1	2.0 3.5 2.0 5.0	mA	
V <sub>BAT</sub> , On-hook supply current	Open Circuit state OHT state Standby state Active state		0.18 1.9 0.45 4.2	1.0 4.7 1.5 5.7		
Power-Supply Rejection Ratio (V <sub>R</sub>	IPPLE = 50 mVrms), Active Normal State	9				
V <sub>CC</sub>	50 Hz to 3.4 kHz	30	40			
V <sub>EE</sub>	50 Hz to 3.4 kHz	28	35		dB	5
V <sub>BAT</sub>	50 Hz to 3.4 kHz	28	50			
Effective internal resistance	CAS pin to GND	85	170	255	kΩ	
RFI rejection	100 kHz to 30 MHz (See Figure E)			1.0	mVrms	4
Off-Hook Detector		·				
Current threshold	$I_{DET} = \frac{375}{R_D}$	-12		+12	%	
Ground-Key Detector Thresholds	Active State, BAT = -48 V				•	
Ground-key resistance threshold	B(RING) to GND	2.0	5.0	10.0	kΩ	
Ground-key current threshold	B(RING) to GND		9		mA	
Ring-Trip Detector Input		·				
Bias current		-0.5	-0.05		μA	
Offset voltage	Source resistance = 2 M $\Omega$	-50	0	+50	mV	6
Logic Inputs (C3–C1, E0, E1)		·				
Input High voltage		2.0			v	
Input Low voltage				0.8	V	
Input High current	All inputs except C3 and E1	-75		40		
	Input C3	-75		200	μA	
	Input E1	-75		45	1	
Input Low current		-0.4			mA	
Logic Output (DET)	-				·	
Output Low voltage	I <sub>OUT</sub> = 0.8 mA			0.4	V	
Output High voltage	I <sub>OUT</sub> = -0.1 mA	2.4			V	

### ELECTRICAL CHARACTERISTICS (continued)

Description	Test Conditions (See Note 1)	Min	Тур	Max	Unit	Note
Relay Driver Output (RINGOUT)						
On voltage	35 mA sink		+0.25	+0.4	V	
Off leakage	V <sub>OH</sub> = +5 V			100	μA	
Zener breakover	100 µA	6	7.2			
Zener On voltage	30 mA		10		V	

#### **RELAY DRIVER SCHEMATIC**

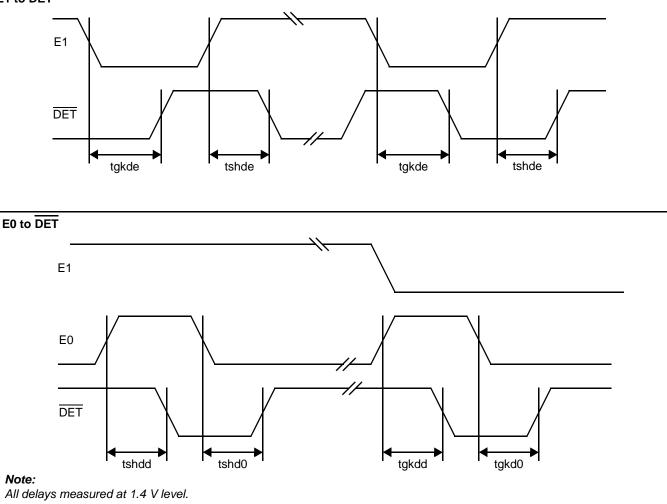


## SWITCHING CHARACTERISTICS (32-Pin PLCC only)

Symbol	Parameter	Test Conditions	Temperature Ranges	Min	Тур	Мах	Unit	Note
	E1 Low to $\overline{\text{DET}}$ High (E0 = 1)		0°C to +70°C −40°C to +85°C			3.8 4.0		
tgkde	E1 Low to $\overline{\text{DET}}$ Low (E0 = 1)	Ground-Key Detect state R <sub>L</sub> open, R <sub>G</sub> connected	0°C to +70°C −40°C to +85°C			1.1 1.6		
tgkdd	E0 High to $\overline{\text{DET}}$ Low (E1 = 0)	(See Figure H)	0°C to +70°C -40°C to +85°C			1.1 1.6		
tgkd0	E0 Low to $\overline{\text{DET}}$ High (E1 = 0)		0°C to +70°C -40°C to +85°C			3.8 4.0		4
	E1 High to $\overline{\text{DET}}$ Low (E0 = 1)		0°C to +70°C -40°C to +85°C			1.2 1.7	μs	4
tshde	E1 High to $\overline{\text{DET}}$ High (E0 = 1)	Switchhook Detect state $R_L = 600 \Omega$ , $R_G$ open	0°C to +70°C −40°C to +85°C			3.8 4.0		
tshdd	E0 High to $\overline{\text{DET}}$ Low (E1 = 1)	(See Figure G)	0°C to +70°C -40°C to +85°C			1.1 1.6		
tshd0	E0 Low to $\overline{\text{DET}}$ High (E1 = 1)		0°C to +70°C –40°C to +85°C			3.8 4.0		

#### SWITCHING WAVEFORMS

#### E1 to DET



#### Notes:

- 1. Unless otherwise noted, test conditions are  $V_{CC} = +5 \text{ V}$ ,  $V_{EE} = -5 \text{ V}$ ,  $C_{HP} = 0.33 \text{ }\mu\text{F}$ ,  $R_{DC1} = R_{DC2} = 9.26 \text{ }\text{k}\Omega$ ,  $C_{DC} = 0.33 \text{ }\mu\text{F}$ ,  $R_D = 35.4 \text{ }\text{k}\Omega$ ,  $C_{CAS} = 0.33 \text{ }\mu\text{F}$ , no fuse resistors, BAT = -48 V,  $R_L = 900 \Omega$ , and  $R_{TMG} = 1700 \Omega$ .
- a. Overload level is defined when THD = 1%.
  b. Overload level is defined when THD = 1.5%
- 3. Balance return signal is the signal generated at  $V_{TX}$  by  $V_{RX}$ . This specification assumes the two-wire AC load impedance matches the programmed impedance.
- 4. Not tested in production. This parameter is guaranteed by characterization or correlation to other tests.
- 5. This parameter is tested at 1 kHz with a termination impedance of 900  $\Omega$  and an  $R_L$  of 600  $\Omega$  in production. Performance at other frequencies is guaranteed by characterization.
- 6. Tested with 0  $\Omega$  source impedance. 2 M $\!\Omega$  is specified for system design only.



 Group delay can be considerably reduced by using a Z<sub>T</sub> network such as that shown in Note 7 above. The network reduces the group delay to less than 2 μs. The effect of group delay on the linecard performance may be compensated for by using the QSLAC<sup>TM</sup> or DSLAC<sup>TM</sup> device.

						DET OI	ıtput
State	Э	C3	C2	C1	2-Wire Status	E1 = 1	E1 = 0
0		0	0	0	Open Circuit	Ring trip	Ring trip
1		0	0	1	Ringing	Ring trip	Ring trip
2		0	1	0	Active	Loop detector	Ground key
3		0	1	1	On-Hook TX (OHT)	Loop detector	Ground key
4		1	0	0	Tip Open	Loop detector	Ground key
5		1	0	1	Standby	Loop detector	Ground key
6		1	1	0	Reserved		
7		1	1	1	Reserved		

Table 1. SLIC Decoding

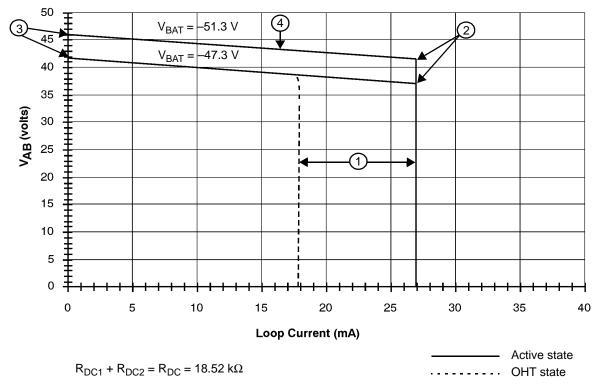
Note:

E0 High enables  $\overline{\text{DET}}$ .

Table 2.	User-Programmable Components
----------	------------------------------

$Z_{\rm T} = 200(Z_{\rm 2WIN} - 2R_{\rm F})$	$Z_{\rm T}$ is connected between the VTX and RSN pins. The fuse resistors are $R_{\rm F}$ and $Z_{2WIN}$ is the desired 2-wire AC input impedance. When computing $Z_{\rm T}$ , the internal current amplifier pole and any external stray capacitance between VTX and RSN must be taken into account.
$Z_{RX} = \frac{Z_L}{G_{42L}} \bullet \frac{200 \bullet Z_T}{Z_T + 200(Z_L + 2 \bullet R_F)}$	$Z_{RX}$ is connected from $V_{RX}$ to $R_{SN}.\ Z_{T}$ is defined above, and $G_{42L}$ is the desired receive gain.
$R_{DC1} + R_{DC2} = \frac{500}{I_{LOOP}}$	$R_{DC1},R_{DC2},\text{and}C_{DC}$ form the network connected to the RDC pin. $R_{DC1}$ and $R_{DC2}$ are approximately equal. $I_{LOOP}$ is the desired loop current in the constant-current region.
$C_{DC} = 1.5 \text{ ms} \bullet \frac{R_{DC1} + R_{DC2}}{R_{DC1} \bullet R_{DC2}}$	
$R_{\rm D} = \frac{375}{I_{\rm T}},  C_{\rm D} = \frac{0.5 \text{ ms}}{R_{\rm D}}$	$R_D$ and $C_D$ form the network connected from RD to –5 V and $I_T$ is the threshold current between on hook and off hook.
$I_{OHT} = \frac{500 \text{ V} \bullet 0.66}{R_{DC1} + R_{DC2}}$	OHT loop current (constant-current region).
$C_{CAS} = \frac{1}{3.4 \bullet 10^5 \pi f_c}$	$C_{\mbox{CAS}}$ is the regulator filter capacitor and $f_{\mbox{c}}$ is the desired filter cutoff frequency.
Thermal Management Equations (Normal Active and Tip C	open States)
$R_{TMG} \ge \frac{ V_{BAT}  - 6 V}{I_{LOOP}}$	$R_{TMG}$ is connected from $T_{MG}$ to $V_{BAT}$ and is used to limit power dissipation within the SLIC in Normal Active and Tip Open states only.
$P_{RTMG} = \frac{ V_{BAT}  - 6 V - (I_{L} \bullet R_{L})^{2}}{R_{TMG}}$	Power dissipated in the $T_{MG}$ resistor, $R_{TMG},$ during Active and Tip Open states.
$P_{SLIC} =  V_{BAT}  \bullet I_L - (P_{RTMG} - R_L(I_L)^2) + 0.12 W$	Power dissipated in the SLIC while in Active and Tip Open states.

#### DC FEED CHARACTERISTICS



#### Notes:

1. Constant-current region:

Active state:

OHT state:

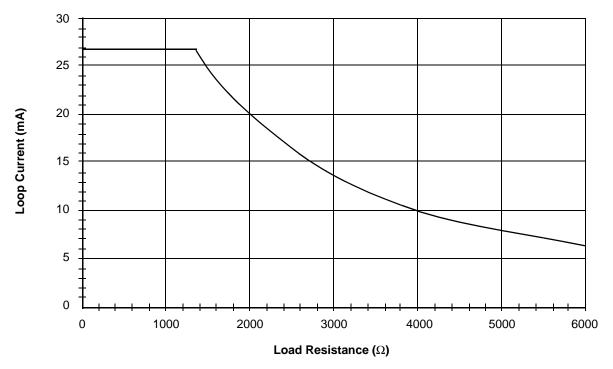
$$I_{\rm L} = \frac{2}{3} \bullet \frac{500}{R_{\rm DC}}$$

 $I_{L} = \frac{500}{R_{DC}}$ 

- 2. Anti-sat (battery tracking) turn-on:  $V_{AB} = 1.017 |V_{BAT}| 10.7$
- 3. Open circuit voltage:  $V_{AB} = 1.017 |V_{BAT}| 6.3$
- 4. Anti-sat (battery tracking) region:  $V_{AB} = 1.017 |V_{BAT}| 6.3 I_L \frac{R_{DC}}{120}$

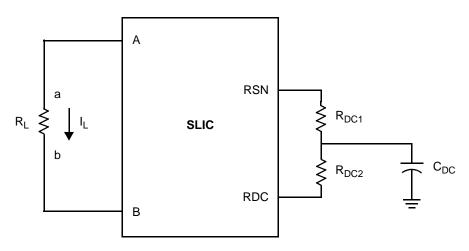
a. V<sub>A</sub>–V<sub>B</sub> (V<sub>AB</sub>) Voltage vs. Loop Current (Typical)

#### **DC FEED CHARACTERISTICS (continued)**



$$\begin{split} R_{DC1} + R_{DC2} &= R_{DC} = 18.52 \text{ k}\Omega \\ V_{BAT} &= -47.3 \text{ V} \end{split}$$

b. Loop Current vs. Load Resistance (Typical)

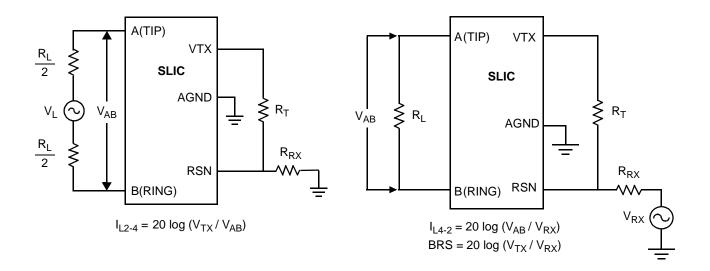


Feed current programmed by  $R_{DC1}$  and  $R_{DC2}$ 

c. Feed Programming

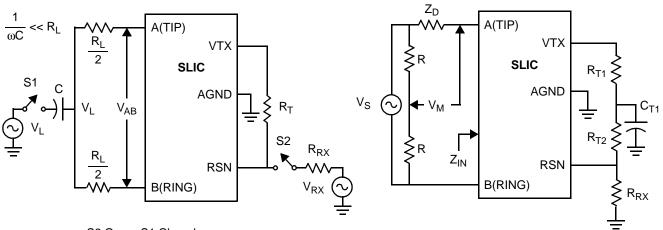
Figure 1. DC Feed Characteristics

#### TEST CIRCUITS



A. Two- to Four-Wire Insertion Loss

B. Four- to Two-Wire Insertion Loss and Balance Return Signal



S2 Open, S1 Closed L-T Long. Bal. = 20 log (V\_{AB} / V\_L) L-4 Long. Bal. = 20 log (V\_{TX} / V\_L)

S2 Closed, S1 Open 4-L Long. Sig. Gen. = 20 log (V\_L / V\_RX)

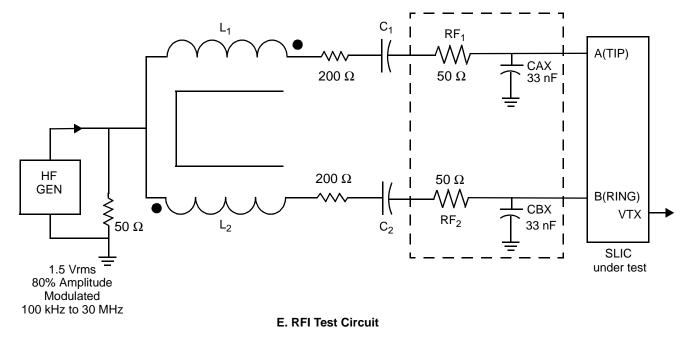
C. Longitudinal Balance

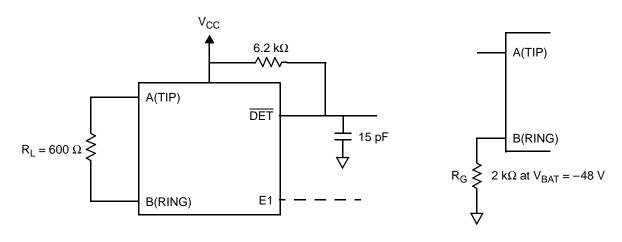
Note:  $Z_D$  is the desired impedance (e.g., the characteristic impedance of the line).

 $R_{L} = -20 \log (2 V_{M} / V_{S})$ 

#### D. Two-Wire Return Loss Test Circuit

#### **TEST CIRCUITS (continued)**

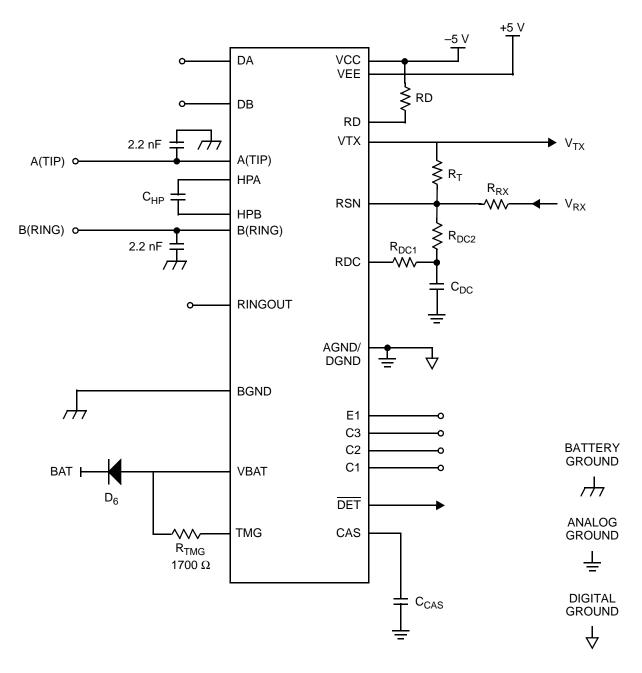




F. Loop-Detector Switching

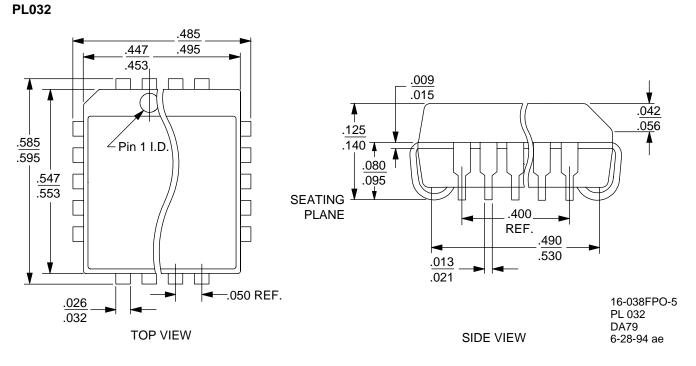
G. Ground-Key Switching

#### **TEST CIRCUITS (continued)**



H. Am7945 Test Circuit

## PHYSICAL DIMENSION



#### **REVISION SUMMARY**

#### Revision A to B

• Minor changes were made to the data sheet style and format to conform to AMD standards.

#### **Revision B to Revision C**

• In the Pin Description table, inserted/changed TP pin description to: "Thermal pin. Connection for heat dissipation. Internally connected to substrate (QBAT). Leave as open circuit or connected to QBAT. In both cases, the TP pins can connect to an area of copper on the board to enhance heat dissipation."

#### **Revision C to Revision D**

- Deleted information on the Ceramic DIP and Plastic DIP packages.
- The PL032 package was added to the new Physical Dimension section.
- Updated the Pin Description table to correct inconsistencies.

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