## STMicroelectronics Solutions for ADSL Line Interfaces



This paper describes STMicroelectronics ADSL analog line interface solutions.
After a short overview of the ADSL application environment, this article focuses on the implementation of line drivers. Magnetic circuits such as hybrid or line transformer circuits will not be described in detail.

## The ADSL concept

Asymmetric Digital Subscriber Line (ADSL) is a modem technology, which converts existing twisted-pair telephone lines into access paths for multimedia and high speed data communications.

An ADSL modem is connected to a twisted-pair telephone line, creating three information channels: a high-speed downstream channel (up to 1.1 MHz and 2.2 MHz for ADSL2+) depending on the implementation of the ADSL architecture, a medium-speed upstream channel (up to 135 kHz or 230 kHz ) and a POTS (Plain Old Telephone Service), split off from the modem by filters.
Figure 1: Typical spectral representation of a DMT ADSL signal (subscriber side)


ADSL allows the wide-band access necessary to transmit media such as movies, television, remote CDROMs via LANs and the Internet into individual workplaces and homes.

## The line interface - ADSL remote terminal (RT)

Figure 2 shows a typical analog line interface used for ADSL. The upstream and downstream signals are separated from the telephone line by using an hybrid circuit and a line transformer. On this note, emphasis will be placed on the emission path.
Figure 2: Typical ADSL Line Interface


## The emission path

The features of the TS613 and TS612 drivers are shown in Table 1 below.
Table 1: Features of drivers

|  |  | $\begin{aligned} & \text { GBP } \\ & (\mathrm{MHz}) \end{aligned}$ | $\begin{gathered} \text { BW } \\ \text { Gain=4 } \\ \text { MHz) } \end{gathered}$ | $\begin{gathered} \text { SR } \\ (V / \mu s) \end{gathered}$ | lout typ. (mA) | Noise $(\mathrm{nV} / \sqrt{\mathrm{Hz}})$ | Icc per op. (mA) | $\begin{gathered} \mathrm{HD} 2 / \mathrm{HD}^{1}{ }^{1} \\ (\mathrm{dBc}) \end{gathered}$ | Vout diff. <br> (Vpp min) | Packages |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TS613 | VFA | 130 | 34 | 40 | 320 | 3 | 11 | 74/79 | 18 | SO8 SO8 Exposed Pad |
| TS612 | VFA | 130 | 34 | 40 | 320 | 3 | 14 | 74/79 | 18 | SO20 Batwing |

1) Single ended $4 \mathrm{Vpp} / 100 \mathrm{kHz}$ on $25 \Omega / / 15 \mathrm{pF}$

In order to shrink the line interface size, the TS613 comes in the classic SO8 plastic package as well as the SO8 ExposedPAD plastic package, capable of dissipating 1.7 W at room temperature. While this circuit does not feature a power-down function, it does have the advantage of featuring a standard pinout.

Figure 3: Thermal considerations: power dissipation of the drivers vs. room temperature


The TS612 comes in SO20 plastic batwing package which increases its power dissipation capability to 2.7 W at room temperature. It features a power-down or stand-by function in order to minimize the consumption when the modem is not in communication.

## Power Supply

Remote ADSL modem terminals must be designed to be easily connected to a PC. For such applications, the driver should use a +12 V single power supply, which is available via standard PCI connectors. Note that the TS613 and TS612 can also be powered by a dual power supply at $+/-6 \mathrm{~V}$.

Figure 4 shows a single +12 V supply circuit with the TS613 as a remote terminal transmitter in differential mode. Note that one could also use the TS612 in exactly the same schema.
Figure 4: Implementation of the TS613 as a differential line driver with a +12V single supply


The driver is biased with a mid-supply (nominally +6 V ) in order to maintain the DC component of the signal at +6 V . This allows a maximum dynamic range between 0 and +12 V . Several options are possible in order to provide this bias supply-such as for example, a virtual ground using an operational amplifier, or, the cheapest solution, a two-resistor divider. A high resistance value is required to limit the current consumption. On the other hand, the current must be high enough to bias the inverting input of the driver. If we consider the positive input's bias current ( $15 \mu \mathrm{~A}$ max) as $1 \%$ of the current through the resistance divider ( 1.5 mA ), two $3.9 \mathrm{k} \Omega$ resistors are sufficient to keep a stable mid-supply .

The input provides two high-pass filters with a break frequency of about 1.6 kHz which is necessary to remove the DC component of the input signal. To avoid DC current flowing into the primary side of the transformer, an output capacitor is used. The $1 \mu \mathrm{~F}$ capacitance provides a path for low frequencies, the 10 nF capacitance provides a path for high end of the spectrum.

## Filtering

As the hybrid circuit cannot perfectly separate the upstream signal and the downstream signal, any distortion from the upstream signal could affect the downstream signal. For the upstream path, a lowpass filter becomes absolutely necessary in order to cut off the higher frequencies from the DAC analog output and the driver distortions. In this simple non-inverting amplification configuration, it is easy to implement a Sallen-Key low-pass filter by using the TS613 or TS612.

Figure 5: Transmission path filtering


A first solution is to use a LC cell before the driver to provide the low-pass filtering. Nevertheless, as shown in Figure 6, using 2nd order active filtering is a good solution especially as regards cost and space-saving considerations.
Figure 6: TS613 line driver with 2nd order active filtering


In the configuration shown in Figure 6, we assume $\mathrm{R} 4=\mathrm{R} 6, \mathrm{R} 5=\mathrm{R} 7, \mathrm{C} 1=\mathrm{C} 3$ and $\mathrm{C} 2=\mathrm{C} 4$.

The resistances R1, R2 and R3 allow us to calculate the gain of the structure as follows:

$$
\text { Gain }=1+\frac{2 R 2}{R 1}=1+\frac{2 R 3}{R 1}
$$

The damping factor can be derived from these resistances and the capacitances $\mathrm{C} 1, \mathrm{C} 2, \mathrm{C} 3$ and C 4 :

$$
\zeta=\frac{2 C 1-\alpha C 2}{2 \sqrt{C 1 C 2}}=\frac{2 C 3-\alpha C 4}{2 \sqrt{C 3 C 4}}
$$

with:

$$
\alpha=\frac{2 R 2}{R 1}=\frac{2 R 3}{R 1}
$$

The higher the gain, the more sensitive the damping factor is. When the gain is higher than 1 it is preferable to use very stable resistance and capacitance values.

The value of the gain does not affect the cut-off frequency, $f_{c}$, which is derived as follows:

$$
f c=\frac{1}{2 \pi \sqrt{R 4 R 5 C 1 C 2}}=\frac{1}{2 \pi \sqrt{R 6 R 7 C 3 C 4}}
$$

Moreover this expression shows that it is possible to shift the cut-off frequency by simply changing the values of the resistances R4, R5 or R6, R7 - with neither a change of capacitance nor of the damping factor.

The following table shows a calculations of components for a cut-off frequency around 130 kHz for the ADSL over POTS and 270 kHz for the ADSL over ISDN. The final, accurate settings are made by compromising between the attenuation of the highest frequencies of the upstream signal and the impact of the distortion on the downstream signal. This is best done directly in the application. Nevertheless we can start with the following initial values:

| R1 <br> ( $\Omega$ ) | $\begin{aligned} & \text { R2 } \\ & \text { R3 } \\ & (\Omega) \end{aligned}$ | $\begin{aligned} & \text { R4 } \\ & \text { R6 } \\ & (\Omega) \end{aligned}$ | $\begin{aligned} & \text { R5 } \\ & \text { R7 } \\ & (\Omega) \end{aligned}$ | $\begin{gathered} \mathrm{C} 1 \\ \mathrm{C} 3 \\ (\mathrm{nF}) \end{gathered}$ | $\begin{gathered} \mathrm{C} 2 \\ \mathrm{C} 4 \\ (\mathrm{nF}) \end{gathered}$ | Gain <br> (dB) | $\begin{gathered} \mathrm{fc} \\ (\mathrm{kHz}) \end{gathered}$ | $\zeta$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 180 | 536 | 261 | 261 | 10 | 2.2 | 16.8 | 130 | 0.73 |
| 180 | 536 | 127 | 127 | 10 | 2.2 | 16.8 | 270 | 0.73 |

## Transformation ratio

In differential mode, the TS613 and TS612 are able to deliver a typical amplitude signal of 18 V peak to peak.

The dynamic line impedance is $100 \Omega$. The typical value of the amplitude signal required on the line is up to 12.4 V peak to peak. By using a $1: 2$ transformer ratio the reflected impedance back to the primary will be a quarter ( $25 \Omega$ ) and therefore the amplitude of the signal required with this impedance will be halved ( 6.2 V peak to peak). Assuming a $25 \Omega$ series resistance ( $12.5 \Omega$ for both outputs) is necessary for impedance matching, the output signal amplitude required is 12.4 V peak to peak. This value is acceptable for both TS613 and TS612. In this case, the load impedance is $25 \Omega$ for each driver in single ended.

Increasing the line level by using an active impedance matching
With passive matching, the output signal amplitude of the driver must be twice the amplitude on the load. To go beyond this limitation an active matching impedance can be used. With this technique it is possible to maintain good impedance matching with an amplitude on the load higher than half of the output driver amplitude. This concept is shown in Figure 7 for a differential line.
Figure 7: TS613 as a differential line driver with an active impedance matching


## Component calculation

Let us consider the equivalent circuit for a single-ended configuration, as shown in Figure 8.
Figure 8: Single ended equivalent circuit


For unloaded system, we can assume that currents through R1, R2 and R3 are respectively:

$$
\frac{2 V i}{R 1}, \frac{\left(V i-V o^{\circ}\right)}{R 2} \text { and } \frac{(V i+V o)}{R 3}
$$

As $V o^{\circ}$ equals V o without loading, the gain in this case becomes:

$$
G=\frac{V o(\text { noload })}{V i}=\frac{1+\frac{2 R 2}{R 1}+\frac{R 2}{R 3}}{1-\frac{R 2}{R 3}}
$$

The gain for the loaded system will be:

Equation 1

$$
G L=\frac{V o(\text { withload })}{V i}=\frac{1}{2} \frac{1+\frac{2 R 2}{R 1}+\frac{R 2}{R 3}}{1-\frac{R 2}{R 3}}
$$

As shown in Figure 9, this system is an ideal generator, with a synthesized impedance equal to the internal impedance of the system. Therefore, the output voltage becomes:

Equation 2

$$
V o=(\text { ViG })-(\text { Rolout })
$$

with Ro the synthesized impedance and lout the output current. On the other hand Vo can be expressed as:

Equation 3

$$
V o=\frac{V i\left(1+\frac{2 R 2}{R 1}+\frac{R 2}{R 3}\right)}{1-\frac{R 2}{R 3}}-\frac{R s 1 \text { lout }}{1-\frac{R 2}{R 3}}
$$

Figure 9: Equivalent schematic, where Ro is the synthesized impedance


By identifying of both Equation 2 and Equation 3, the synthesized impedance is, with Rs1=Rs2=Rs:

Equation 4

$$
R o=\frac{R s}{1-\frac{R 2}{R 3}}
$$

Unlike the level of $\mathrm{Vo}^{\circ}$ required for passive impedance, $\mathrm{V} 0^{\circ}$ will be smaller than 2 Vo in this case. Let us write $\mathrm{Vo}^{\circ}=\mathrm{kVo}$ with k the matching factor varying between 1 and 2 . Assuming that the current through R3 is negligible, the resistance divider becomes:

$$
R o=\frac{k V o R L}{R L+2 R s 1}
$$

After choosing the k factor, Rs will equal to $1 / 2 R L(k-1)$.

A good impedance matching assumes:
Equation 5

$$
R o=\frac{1}{2} R L
$$

From Equation 3 and Equation 5 we derive:
Equation 6

$$
\frac{R 2}{R 3}=1-\frac{2 R s}{R L}
$$

By fixing an arbitrary value for R2 in Equation 6, we arrive at:

$$
R 3=\frac{R 2}{1-\frac{2 R s}{R L}}
$$

Finally, the values of R2 and R3 allow us to extract R1 from Equation 1 so that:
Equation 7

$$
R 1=\frac{2 R 2}{2\left(1-\frac{R 2}{R 3}\right) G_{L}-1-\frac{R 2}{R 3}}
$$

with $G_{L}$ the required gain.

| $G_{L}$ (gain for the loaded system) | $G_{L}$ is fixed for the application requirements <br> $G_{L}=$ Vo/Vi $=0.5(1+2 R 2 / R 1+\mathrm{R} 2 / \mathrm{R} 3) /(1-\mathrm{R} 2 / \mathrm{R} 3)$ |
| :---: | :--- |
| R1 | $2 \mathrm{R} 2 /\left[2(1-\mathrm{R} 2 / \mathrm{R} 3) \mathrm{G}_{\mathrm{L}}-1-\mathrm{R} 2 / \mathrm{R} 3\right]$ |
| R2 (=R4) | Arbitrarily fixed |
| R3 (=R5) | $\mathrm{R} 2 /(1-\mathrm{Rs} / 0.5 \mathrm{RL})$ |
| Rs | $0.5 \mathrm{RL}(\mathrm{k}-1)$ |

## Capabilities

The table below shows the calculated components for different values of k for a differential load of $25 \Omega$. In all cases, $\mathrm{R} 2=1000 \Omega$ and the gain=16dB. The last column displays the maximum amplitude level on the line regarding the TS613 maximum output capabilities ( $18 \mathrm{Vp}-\mathrm{p}$ diff.) and a $1: 2$ line transformer ratio.

| Active matching |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{k}$ | R1 <br> $(\Omega)$ | R3 <br> $(\Omega)$ | Rs <br> $(\Omega)$ | TS613 Output Level to get <br> 12.4Vpp on the line with a <br> turn ratio of 2. <br> (Vp-p diff) | Maximum Line Level <br> (Vp-p diff) |
| 1.3 | 953 | 1400 | $3.75(3.9 / / 100)$ | 8.06 | 27.5 |
| 1.4 | 590 | 1620 | $5(10 / / 10)$ | 8.68 | 25.7 |
| 1.5 | 422 | 2000 | $6.36(6.8 / / 100)$ | 9.35 | 25.3 |
| 1.6 | 316 | 2490 | $7.57(8.2 / / 100)$ | 9.95 | 23.7 |
| 1.7 | 261 | 3300 | $8.71(10 / / 68)$ | 10.52 | 22.3 |
| Passive matching |  |  |  |  | 12.4 |

## Measurement of power consumption in application

Conditions:

- Passive impedance matching
- Transformer turns ratio: 2
- Maximum level required on the line: $12.4 \mathrm{~V} p \mathrm{p}$
- Maximum output level of the driver: 12.4 Vpp
- Crest factor: 5.3 (Vp/Vrms)
- Power Supply: 12V

Power consumption of the driver during emission on 900 and 4550 meter twisted pair telephone lines:

- TS613: 360mW
- TS612: 450mW

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