# SPIDER - TLE7235E

8 Channel High-Side and Low-Side Relay Switch with Limp Home Mode

# Automotive Power



Never stop thinking



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# SPI Driver for Enhanced Relay Control

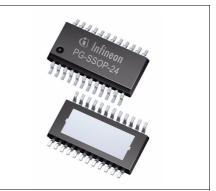
**TLE7235E** 



### 1 Overview

#### Features

- 8 bit SPI for diagnostics and control, providing daisy chain capability
- Very wide range for digital supply voltage
- Two configurable input pins offer complete flexibility for PWM operation
- Stable behavior at under voltage
- Green Product (RoHS compliant)
- AEC Qualified



PG-SSOP-24-4

#### Description

The TLE7235E is an eight channel high-side and low-side power switch in PG-SSOP-24-4 package providing embedded protective functions. It is especially designed for standard relays and LEDs in automotive applications.

The output stages incorporate two low-side, four high-side and two auto configuring high-side or low-side switches.

A serial peripheral interface (SPI) is utilized for control and diagnosis of the device and the load. For direct control, there are two input pins available.

The TLE7235E provides a micro controller fail-safe function which is activated via a high signal at the limp home input pin. There is a power supply integrated in the device to ensure this functionality even without digital supply voltage.

The power transistors are built by N-channel power MOSFETs. The device is monolithically integrated in Smart Power Technology.

Туре	Package	Marking
TLE7235E	PG-SSOP-24-4	TLE7235E



#### Overview

#### Table 1 Product Summary

Operating range power supply voltage	V <sub>bb</sub>	5.5 28 V
Digital supply voltage	V <sub>DD</sub>	3.0 5.5 V
Typical On-State resistance at 25 °C	R <sub>DS(ON)</sub>	
high-side: 2 channels (Relay)		0.9 Ω
high-side: 2 channels (Generic, LED)		1.6 Ω
auto configuring: 2 channels (Relay, Supplies)		0.9 Ω
low-side: 2 channels (Relay)		0.9 Ω
Nominal load current (all channels active)	I <sub>L(nom, min)</sub>	
Relay		350 mA
LED, Generic		175 mA
Over load switch off threshold	$I_{\rm DS(OVL,\ min)}$	500 mA
Output leakage current per channel at 25 °C	I <sub>DS(OFF, max)</sub>	1 μΑ
Drain to source clamping voltage	V <sub>DS(CL, min)</sub>	41 V
Source to ground clamping voltage	V <sub>bb(CL, max)</sub>	-16 V
SPI clock frequency	$f_{\rm SCLK(max)}$	5 MHz

#### **Protective Functions**

- Over load and short circuit protection
- Thermal shutdown
- Electrostatic discharge protection (ESD)

#### **Diagnostic Functions**

- Latched diagnostic information via SPI
- · Open load detection in OFF-state
- Over load detection in ON-state
- Over temperature

#### Limp Home / Fail-Safe Functions

- Limp home activation via pin LHI
- Limp home configuration via input pins

#### Applications

- Especially designed for driving relays and LEDs in automotive applications
- All types of resistive and inductive loads
- Suitable to switch 5 V power supply lines by auto configuring channels

### TLE7235E



#### **Detailed Description**

The TLE7235E is an eight channel high-side and low-side relay switch providing embedded protective functions. The output stages incorporate two low-side switches (0.9  $\Omega$  per channel), four high-side switches (two channels with 0.9  $\Omega$  and two channels with 1.6  $\Omega$ ) and two auto-configuring high-side or low-side switches (0.9  $\Omega$  per channel). The auto-configuring switches can be utilized in high-side or low-side configuration just by connecting the load accordingly. They are also suitable to switch a 5 V supply line in high-side configuration. Protective and diagnostic functions adjust automatically to the chosen configuration.

The 8 bit serial peripheral interface (SPI) is utilized for control and diagnosis of the device and the loads. The SPI interface provides daisy chain capability in order to assemble multiple devices in one SPI chain by using the same number of micro-controller pins.

Furthermore, the TLE7235E is equipped with two input pins that can be individually routed to the output control of each channel thus offering complete flexibility in design and PCB-layout. The input multiplexer is controlled via SPI.

In limp home mode (fail-safe mode), the input pins are directly routed to the configurable output channels 4 and 5. The limp home mode operates independently of digital power supply and is activated via pin LHI.

The device provides full diagnosis of the load via open load, over load and short circuit detection. SPI diagnosis flags indicate latched fault conditions that may have occurred.

Each output stage is protected against short circuit. In case of over load, the affected channel switches off. There are temperature sensors available for each channel to protect the device against over temperature.

The device protects itself with a build in reverse polarity protection which prohibits intrinsic current flow through the logic during reverse polarity. However the output stages still incorporate a reverse diode where current can flow through during reverse polarity.

The power transistors are built by N-channel power MOSFETs. The inputs are ground referenced CMOS compatible. The device is monolithically integrated in Smart Power Technology.



**Block Diagram** 

# 2 Block Diagram

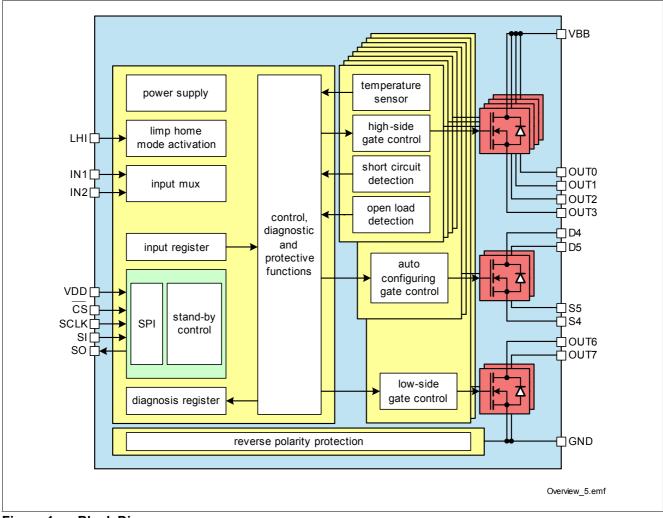


Figure 1 Block Diagram



**Block Diagram** 

### 2.1 Terms

Figure 2 shows all terms used in this data sheet.

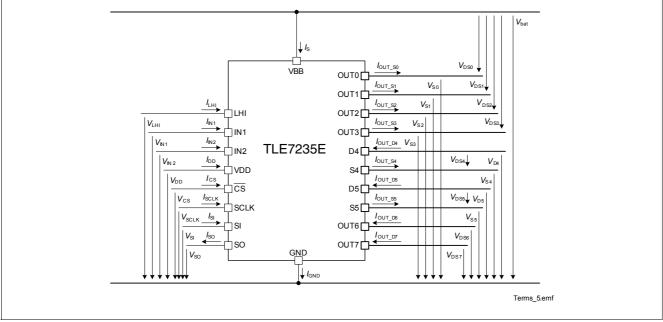


Figure 2 Terms

In all tables of the electrical characteristics is valid:

Channel related symbols without channel number are valid for each channel separately (e.g.  $V_{\text{DS}}$  specification is valid for  $V_{\text{DS0}} \dots V_{\text{DS7}}$ ). In order to make the description of output currents easier, the load current  $I_{\text{Out}}$  is equivalent to the drain current  $I_{\text{OUT}}$  in low-side configuration and the source current  $I_{\text{OUT}}$  in high-side configuration.

All SPI register bits are marked as follows: ADDR. PARAMETER (e.g. ICR01.INX1). In SPI register description, the values in bold letters (e.g. 0) are default values.



#### **Pin Configuration**

# **3** Pin Configuration

### 3.1 Pin Assignment

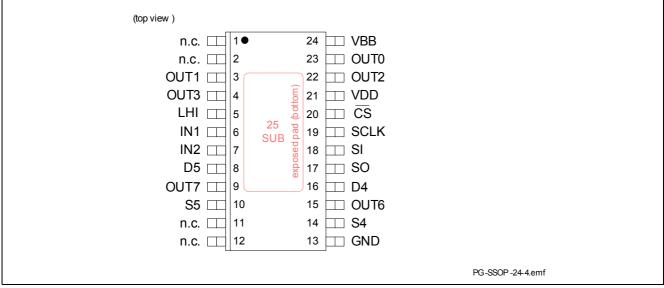


Figure 3 Pin Configuration PG-SSOP24-4

### 3.2 Pin Definitions and Functions

Pin	Symbol	I/O	Function
Power S	Supply	Į	
21	VDD	-	Digital power supply
24	VBB	-	Power supply
13	GND	-	Digital, analog and power ground
25	SUB	-	Substrate pins for thermal connection.
			To enable reverse polarity protection these pins must be floating
Power S	Stages		
23	OUT0	0	Source of high side power transistor channel 0
3	OUT1	0	Source of high side power transistor channel 1
22	OUT2	0	Source of high side power transistor channel 2
4	OUT3	0	Source of high side power transistor channel 3
16	D4	0	Drain of auto configuring power transistor 4
14	S4	0	Source of auto configuring power transistor 4
8	D5	0	Drain of auto configuring power transistor 5
10	S5	0	Source of auto configuring power transistor 5
15	OUT6	0	Drain of low side power transistor channel 6
9	OUT7	0	Drain of low side power transistor channel 7
Inputs	I	L.	·
5	LHI	I	Limp home activation input pin (pull down)
6	IN1	I	Input multiplexer input 1 pin (pull down)



### **TLE7235E**

### **Pin Configuration**

Pin	Symbol	I/O	Function	
7	IN2	I	Input multiplexer input 2 pin (pull down)	
SPI		1		
20	CS	I	SPI Chip select (pull up)	
19	SCLK	I	Serial clock	
18	SI	I	Serial data in	
17	SO	0	Serial data out	
Others		1		
1,2,11,12	n.c.	I	not connected	



# 4 Electrical Characteristics

### 4.1 Absolute Maximum Ratings <sup>1)</sup>

Stresses above the ones listed here may affect device reliability or may cause permanent damage to the device. The values below are not considering combinations of different maximum conditions at one time

 $T_j$  = -40 °C to +150 °C; all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

	lute Maximum Ratings <sup>1)</sup>					<b>T</b> ( <b>0</b> ) ""
Pos.	Parameter	Symbol		it Values	Unit	Test Conditions
			min.	max.		
	Supply					
4.1.1	Power supply voltage	$V_{\rm bb}$	-16	40	V	-16V max. 2 minutes
4.1.2	Digital supply voltage	$V_{DD}$	-0.3	5.5	V	-
4.1.3	Power supply voltage for full short circuit protection (single pulse) $(T_i = -40 \text{ °C} \dots 150 \text{ °C})$	V <sub>bat(SC)</sub>	0	28	V	_
Power	Stages	I.				
4.1.4	Load current	IL			А	-
	channel 0, 1, 4, 5, 6, 7		-0.5	0.5		
	channel 2, 3		-0.25	0.25		
4.1.5	Voltage at power transistor	V <sub>DS</sub>	_	41	V	-
4.1.6	Power transistor's source voltage	$V_{Out\_S}$	-16	_	V	-
4.1.7	Power transistor's drain voltage	V <sub>Out_D</sub>	-	41	V	-
4.1.8	Max. energy dissipation one channel single pulse for ch. 0, 1, 4, 5, 6, 7	E <sub>AS</sub>		05	mJ	2)
			_	65		T <sub>j(0)</sub> = 105 °C I <sub>D(0)</sub> = 0.35 A
			-	50		T <sub>j(0)</sub> = 150 °C I <sub>D(0)</sub> = 0.250 A
4.1.9	Maximum energy dissipation one channel repetitive pulses for ch. 0, 1, 4, 5, 6, 7	E <sub>AR</sub>			mJ	2)
	1 · 10 <sup>4</sup> cycles		-	18		T <sub>j(0)</sub> = 105 °C I <sub>D(0)</sub> = 0.250 A
	1 · 10 <sup>6</sup> cycles		-	13		$T_{j(0)}$ = 105 °C $I_{D(0)}$ = 0.220 A
4.1.10	Max. energy dissipation one channel single pulse for ch. 2,3	E <sub>AS</sub>			mJ	2)
			-	50		$T_{\rm j(0)}$ = 105 °C $I_{\rm D(0)}$ = 0.250 A
			-	30		<i>T</i> <sub>j(0)</sub> = 150 °C <i>I</i> <sub>D(0)</sub> = 0.250 A

<sup>1)</sup> not subject to production test



#### **Electrical Characteristics**

 $T_j$  = -40 °C to +150 °C; all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Abso Pos.	Parameter	Symbol	Lim	it Values	Unit	Test Conditions
			min.         max.           mJ         2)			
4.1.11	Maximum energy dissipation one channel repetitive pulses for ch. 2,3	E <sub>AR</sub>			mJ	2)
	1 · 10 <sup>4</sup> cycles		-	12		T <sub>j(0)</sub> = 105 °C I <sub>D(0)</sub> = 0.180 A
	1 · 10 <sup>6</sup> cycles		-	11		$T_{j(0)}$ = 105 °C $I_{D(0)}$ = 0.180 A
Logic	Pins					
4.1.12	Voltage at input pins	$V_{\rm IN}$	-0.3	V <sub>DD</sub> + 0.3	V	3)
4.1.13	Voltage at LHI pin	$V_{LHI}$	-0.3	5.5	V	-
4.1.14	Voltage at chip select pin	V <sub>CS</sub>	-0.3	V <sub>DD</sub> + 0.3	V	3)
4.1.15	Voltage at serial clock pin	V <sub>SCLK</sub>	-0.3	V <sub>DD</sub> + 0.3	V	3)
4.1.16	Voltage at serial input pin	V <sub>SI</sub>	-0.3	V <sub>DD</sub> + 0.3	V	3)
4.1.17	Voltage at serial output pin	V <sub>SO</sub>	-0.3	V <sub>DD</sub> + 0.3	V	3)
Tempe	eratures					
4.1.18	Junction Temperature	Tj	-40	150	°C	-
4.1.19	Storage Temperature	$T_{\rm stg}$	-55	150	°C	-
ESD S	usceptibility		· ·			· ·
4.1.20	ESD susceptibility on all pins	$V_{ESD}$	-2	2	kV	HBM <sup>4)</sup>
1) not	subject to production test		4	+		

1) not subject to production test

2) Pulse shape represents inductive switch off:  $I_L(t) = I_L(0) * (1 - t / t_{pulse}); 0 < t < t_{pulse}$ 

3)  $V_{\rm DD}$  + 0.3 V < 5.5 V

4) ESD susceptibility, HBM according to EIA/JESD 22-A114

### 4.2 Functional Range

Pos.	Parameter	Symbol	Liı	mit Values	Unit	Conditions	
			Min.	Max.			
4.2.1	Supply Voltage Range for Nominal Operation	$V_{\rm bb(nom)}$	9	16	V	-	
4.2.2	upper Supply Voltage Range for Extended Operation	$V_{\rm bb(ext),up}$	16	28	V	Parameter Deviations possible	
4.2.3	lower Supply Voltage Range for Extended Operation	$V_{\rm bb(ext),low}$	5.5	9	V	Parameter Deviations possible	
4.2.4	Junction Temperature	Tj	-40	150	°C	-	

Note: Within the functional range the IC operates as described in the circuit description. The electrical characteristics are specified within the conditions given in the related electrical characteristics table.



#### **Electrical Characteristics**

### 4.3 Thermal Resistance

Note: This thermal data was generated in accordance with JEDEC JESD51 standards. For more information, go to www.jedec.org.

Therm	Thermal Resistance <sup>1)</sup>								
Pos.	Parameter	Symbol		Limit Val	ues	Unit	Conditions		
			Min.	Тур.	Max.				
4.3.1	Junction to Case, bottom	$R_{\mathrm{thJC,back}}$	-	_	4	K/W	2)		
4.3.2	Junction to Case, top	$R_{\mathrm{thJC,top}}$	-	_	35	K/W	2)		
4.3.3	Junction to Pin (6,7,18 or 19)	R <sub>thJPin</sub>	-	-	12	K/W	2)		
4.3.4	Junction to Ambient (1s0p, min. footprint)	$R_{\mathrm{thJA,min}}$	-	95	-	K/W	3)		
4.3.5	Junction to Ambient (1s0p+300mm <sup>2</sup> Cu)	R <sub>thJA,300</sub>	-	50	-	K/W	4)		
4.3.6	Junction to Ambient (1s0p+600mm <sup>2</sup> Cu)	R <sub>thJA,600</sub>	-	40	-	K/W	5)		
4.3.7	Junction to Ambient (2s2p)	R <sub>thJA,2s2p</sub>	-	31	-	K/W	6)		

1) Not subject to production test

2) Specified  $R_{\text{thJSP}}$  value is simulated at natural convection on a cold plate setup (all pins are fixed to ambient temperature).  $T_a = 85 \,^{\circ}\text{C}$ . Ch1 to Ch8 are dissipating 1 W power (0.125 W each).

 Specified R<sub>thJA</sub> value is according to Jedec JESD51-2,-3 at natural convection on FR4 1s0p board; The product (Chip+Package) was simulated on a 76.2 x 114.3 x 1.5 mm board with minimal footprint copper area and 70 μm thickness. T<sub>a</sub> = 85 °C, Ch1 to Ch8 are dissipating 1 W power (0.125 W each).

4) Specified  $R_{\text{thJA}}$  value is according to Jedec JESD51-2,-3 at natural convection on FR4 1s0p board; The product (Chip+Package) was simulated on a 76.2 x 114.3 x 1.5 mm board with additional heatspreading copper area of 300mm<sup>2</sup> and 70  $\mu$ m thickness.  $T_a$  = 85 °C, Ch1 to Ch8 are dissipating 1 W power (0.125 W each).

5) Specified  $R_{\text{thJA}}$  value is according to Jedec JESD51-2,-3 at natural convection on FR4 1s0p board; The product (Chip+Package) was simulated on a 76.2 x 114.3 x 1.5 mm board with additional heatspreading copper area of 600mm<sup>2</sup> and 70  $\mu$ m thickness.  $T_a$  = 85 °C, Ch1 to Ch8 are dissipating 1 W power (0.125 W each).

6) Specified R<sub>thJA</sub> value is according to Jedec JESD51-2,-7 at natural convection on FR4 2s2p board; The product (Chip+Package) was simulated on a 76.2 x 114.3 x 1.5 mm board with 2 inner copper layers (2 x 70 μm Cu, 2 x 35 μm Cu). T<sub>a</sub> = 85 °C, Ch1 to Ch8 are dissipating 1 W power (0.125 W each).



#### **Power Supply**

### 5 **Power Supply**

The TLE7235E is supplied by two supply voltages  $V_{bb}$  and  $V_{DD}$ . The  $V_{bb}$  supply line is connected to a battery feed and used by the power switches and by an integrated power supply for the register banks. There is an under voltage reset function implemented for the  $V_{bb}$  power supply. After start-up of the power supply, all SPI registers are reset to their default values and the device is in sleep mode (standby). The SPI command CMD.WAKE = 1 is switching the device to operation mode (ON), while a command CMD.STB = 1 send the device to sleep mode (standby) again.

The  $V_{\text{DD}}$  supply line is used by the SPI shift register related circuitry and for driving the SO line. As a result, the daisy chain function is available as soon as  $V_{\text{DD}}$  is provided in the specified range independent of  $V_{\text{bb}}$ . A capacitor between pins  $V_{\text{DD}}$  and GND is recommended (especially in case of EMI).

### 5.1 Operation Modes

There is a limp home functionality implemented in the TLE7235E, which is activated via pin LHI. Please refer to **Section 5.2** for details.

The device provides a sleep mode (stand by) to minimize current consumption, which also resets the register banks. It is entered and left by dedicated SPI commands . The sleep mode current is minimized only when limp home is inactive. After limp home, the device enters sleep mode automatically.

The following table shows the operation modes depending on  $V_{\rm bb}$ ,  $V_{\rm DD}$  and the limp home input signal LHI.

0 V	0 V	0 V	12 V	12 V	12 V	12 V
0 V	5 V	5 V	0 V	0 V	5 V	5 V
Х	0 V	5 V	0 V	5 V	0 V	5 V
-	-	-	1	1	1	1
-	-	-	-	1	-	1
-	1	1	-	-	1	1
reset	reset	reset	1	reset	1	reset
-	-	-	1	-	1	-
	0 V X - - - - reset	0 V 5 V X 0 V   - ✓ reset reset	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

### 5.2 Limp Home Mode

The TLE7235E offers the capability of driving dedicated channels during fail-safe operation of the system. This limp home mode is activated by a high signal at pin LHI. In limp home mode, the SPI registers are reset and the input pins are directly routed to the auto configuring channels (channel 4 and 5). As a result, the limp home operation can be chosen for high-side and low-side driven loads.

Due to the integrated power supply, limp home operation is independent of digital power supply  $V_{\text{DD}}$ . In case of stand-by, a high signal at pin LHI will wake up the device. After limp home operation, the device enters sleep mode in any case.

### 5.3 Reset

There are several reset trigger implemented in the device. A reset switches off all channels and sets the registers to default values. After any kind of reset, the transmission error flag (TER) is set.

#### Under Voltage Reset:

During this device condition a read on SPI always delivers the Standard Diagnostic Frame with a TER flag. This under voltage reset is released when all the supply voltages levels are above under voltage threshold.



#### **Power Supply**

**Reset Command:** There is a reset command available to reset all register bits of the register bank and the diagnosis registers. As soon as CMD.RST = 1, a reset is triggered.

**Limp Home Mode:** In limp home mode, the SPI write-registers are reset. The SPI interface is operating normally, so the limp home bit LHI as well as the diagnosis flags can be read, but no command is accepted until the device leaves the Limp home operation.



**Power Supply** 

### 5.4 Electrical Characteristics

Unless otherwise specified:

 $V_{\rm DD}$  = 3.0 V to 5.5V,  $V_{\rm BAT}$  = 9.0 V to 16V,  $T_{\rm i}$  = -40 °C to +150 °C

Pos.	Parameter	Symbol	Li	mit Va	lues	Unit	<b>Test Conditions</b>	
			min.	typ.	max.	1		
Powe	r Supply $V_{\rm bb}$			-+		•	•	
5.4.1	Supply voltage for full operation	$V_{\rm bb}$	9	-	28	V		
5.4.2	Under voltage reset threshold voltage	$V_{\rm bb(UV)}$	-	-	5.5	V		
5.4.3	Operating current	Is	-	-	15	mA	V <sub>bb</sub> = 16 V	
			-	-	12	mA	<sup>1)</sup> $V_{\rm bb}$ = 16 V all diagnosis off	
5.4.4	Sleep mode current with disconnected loads (stand by)	$I_{\rm S(Sleep)}$			10	μA	$V_{bb} = 16 V$ $V_{LHI} = 0 V$ $AWK = 0$ $T = 25 co(1)$	
			_	-		_	$T_{\rm j} = 25  ^{\circ}{\rm C}^{1)}$	
			_	-	13	_	$T_{\rm j}$ = 85 °C <sup>1</sup> )	
			-	-	20		<i>T</i> <sub>j</sub> = 150 °C	
-	I Power Supply V <sub>DD</sub>	T/	0.0			14	1	
.4.5	0	V <sub>DD</sub>	3.0	-	5.5	V		
4.6	Under voltage reset threshold voltage	V <sub>DD(PO)</sub>	-	-	3.0	V		
5.4.7	Logic supply current	I <sub>DD</sub>	-	_	0.2	mA	$f_{\text{SCLK}} = 0 \text{ Hz}$ $V_{\text{CS}} = 0 \text{ V}$ AWK= 1 $V_{\text{CS}} = 0 \text{ V}$	
5.4.8	Logic supply sleep mode current	$I_{\rm DD(Sleep)}$				μA	$V_{\rm CS} = V_{\rm DD}$ AWK = 0	
			-	-	20		<i>T</i> <sub>j</sub> = 25 °C <sup>1)</sup>	
			-	-	20		$T_{\rm j}$ = 85 °C <sup>1)</sup>	
			-	-	40		<i>T</i> <sub>j</sub> = 150 °C	
imin	gs							
5.4.9	Sleep mode wake-up time	t <sub>wu(Sleep)</sub>	-	-	200	μs	1)	
5.4.10	$V_{\rm bb}$ under voltage reset delay time	t <sub>bb(UVR)</sub>		-	1	μs	1)	
	<b>T</b> T 1 1 1 1 1					1 -	1)	

5.4.11 $V_{DD}$  under voltage reset delay time $t_{DD(UVR)}$ 1)Not subject to production test, specified by design.

Note: Characteristics show the deviation of parameter at the given supply voltage and junction temperature. Typical values show the typical parameters expected at  $V_{bb}$  = 13.5 V,  $V_{DD}$  = 5.0 V,  $T_j$  = 25 °C.

\_

1)

μs

1



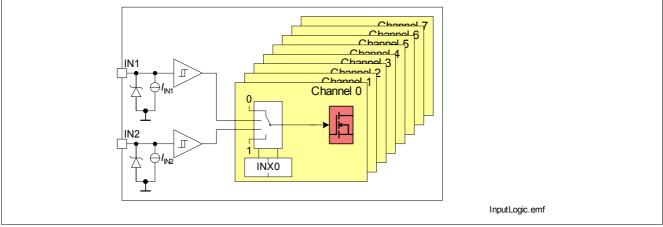
The TLE7235E is an eight channel high-side and low-side relay switch. The power stages are built by N-channel vertical power MOSFET transistors. The gates of the high-side switches are controlled by charge pumps.

### 6.1 Input Circuit

There are two input pins available at TLE7235E, which can be configured to be used for control of the output stages. The INXn parameter of the input configuration register provide following possibilities:

- channel is switched off
- channel is switched according to signal level at input pin IN1
- channel is switched according to signal level at input pin IN2
- channel is switched on

Figure 4 shows the input circuit of TLE7235E.



#### Figure 4 Input Multiplexer

The current sink to ground ensures that the channels switch off in case of open input pin. The zener diode protects the input circuit against ESD pulses.

### 6.2 Channels 4 and 5

The TLE7235E provides two auto-configuring high-side or low-side switches (channels 4 and 5). They adjust the diagnostic and protective functions according their potentials at drain and source automatically.

In high-side configuration, the load is connected between ground and source of the power transistors (S4 or S5). The drain of the power transistors (D4 and D5) can be connected to any potential between GND-pin potential and VBB-pin potential. When the drain is connected to VBB, the channel behave like the other high side channels. The drain can also be connected to a 5 V power supply and the source pin will be utilized as switched 5 V supply line.

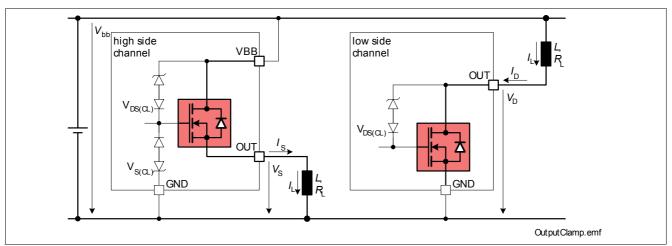
In low-side configuration, the source of the power transistors are to be connected to GND.

The configuration can be chosen for each of these channels individually, so it is feasible to connect one channel in low-side and the other in high-side configuration.



### 6.3 Inductive Output Clamp

When switching off inductive loads with low-side switches, the potential at pin OUT rises to  $V_{\text{DS(CL)}}$  potential, because the inductance intends to continue driving the current. For the high-side channels, the potential at pin OUT drops below ground potential to  $V_{\text{S(CL)}}$ . The voltage clamping is necessary to prevent destruction of the device, see **Figure 5** for details. Nevertheless, the maximum allowed load inductance is limited by the max. clamping energy  $E_{\text{AR}}$  see electrical characteristics "E<sub>AR</sub>" on Page 10.





#### **Maximum Load Inductance**

During demagnetization of inductive loads, energy has to be dissipated in the TLE7235E. This energy can be calculated with following equations:

$$E = V_{\rm D(CL)} \cdot \left[ \frac{V_{\rm bb} - V_{\rm D(CL)}}{R_{\rm L}} \cdot \ln \left( 1 - \frac{R_{\rm L} \cdot I_{\rm L}}{V_{\rm bb} - V_{\rm D(CL)}} \right) + I_{\rm L} \right] \cdot \frac{L}{R_{\rm L}} \qquad \text{Low-side}$$
(1)

$$E = (V_{bb} - V_{S(CL)}) \cdot \left[\frac{V_{S(CL)}}{R_L} \cdot \ln\left(1 - \frac{R_L \cdot I_L}{V_{S(CL)}}\right) + I_L\right] \cdot \frac{L}{R_L}$$
 High-side (2)

These equations simplify under the assumption of  $R_{\rm L}$  = 0:

$$E = \frac{1}{2}LI_{L}^{2} \cdot \left(1 - \frac{V_{bb}}{V_{bb} - V_{D(CL)}}\right) \qquad \text{Low-side} \qquad (3)$$
$$E = \frac{1}{2}LI_{L}^{2} \cdot \left(1 - \frac{V_{bb}}{V_{S(CL)}}\right) \qquad \text{High-side} \qquad (4)$$

The maximum energy, which is converted into heat, is limited by the thermal design of the component.



### 6.4 Timing Diagrams

The power transistors are switched on and off with a dedicated slope via the INX bits of the serial peripheral interface (SPI). The switching times  $t_{ON}$  and  $t_{OFF}$  are designed equally.

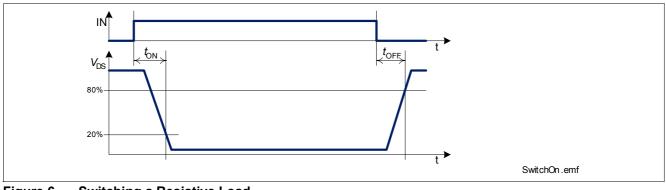


Figure 6 Switching a Resistive Load

In input mode, a high signal at the input pin is equivalent to a SPI ON command and a low signal to SPI OFF command respectively. Please refer to **Section 9.3** for details on SPI protocol.



### 6.5 Electrical Characteristics

Unless otherwise specified:  $V_{\text{DD}}$  = 3.0 V to 5.5V,  $V_{\text{BAT}}$  = 9.0 V to 16V,  $T_{\text{j}}$  = -40 °C to +150 °C typical values:  $V_{\text{DD}}$  = 5.0 V,  $V_{\text{BAT}}$  = 13.5 V,  $T_{\text{j}}$  = 25 °C

Pos.	Parameter	Symbol	Li	mit Val	ues	Unit	<b>Test Conditions</b>
			min.	typ.	max.		
Outp	ut Characteristics	-				*	•
6.5.1	On-State resistance	$R_{\rm DS(ON)}$				Ω	
	channel 0, 1, 4, 5, 6, 7		-				<i>I</i> <sub>L</sub> = 220 mA
				0.9	-	_	<i>T</i> <sub>j</sub> = 25 °C
			-	1.4	1.9		<i>T</i> <sub>j</sub> = 150 °C
	channel 2, 3		-				$I_{\rm L} = 110  {\rm mA}$
				1.6	-	_	$T_{\rm j}$ = 25 °C
			-	2.6	3.9		<i>T</i> <sub>j</sub> = 150 °C
6.5.2	Nominal load current	I <sub>Out(nom)</sub>				mA	all channels on $T = 100 \circ C$
							$T_{a} = 100 \text{ °C}$ $T_{j,max} = 150 \text{ °C}$
							based on $R_{\text{thja}}$
	channel 0, 1, 4, 5, 6, 7		350	500	_		1)
	channel 2, 3		175	250	_	-	1)
6.5.3	Output leakage current in sleep mode	$I_{\text{Out(Sleep)}}$				μA	V <sub>DS</sub> = 13.5 V
			-	-	1		$T_{\rm j} = 25 \ ^{\circ}{\rm C}^{1)}$
			-	-	2		$T_{\rm j}$ = 85 °C <sup>1)</sup>
			-	-	5		<i>T</i> <sub>j</sub> = 150 °C
6.5.4	Output clamping voltage	$V_{\rm OUT\_S(CL)}$	-	-	-16	V	-
		$V_{\text{OUT_DS(CL)}}$	41	-	-	V	-
Input	Characteristics						
6.5.5	L level of pin IN & LHI	$V_{\rm IN(L)}$	0	-	0.6	V	-
6.5.6	H level of pin IN & LHI	V <sub>IN(H)</sub>	1.8	-	5.5	V	-
6.5.7	Input voltage hysteresis at pin IN	$\Delta V_{\mathrm{IN}}$	-	0.1	-	V	1)
6.5.8	L-input pull-down current through pin IN	$I_{\rm IN(L)}$	1.5	-	_	μA	$V_{\rm IN}$ = 0.6 V <sup>1)</sup>
6.5.9	H-input pull-down current through pin IN	I <sub>IN(H)</sub>	10	40	80	μA	$V_{\rm IN}$ = 5 V
Timin	gs			·			
6.5.10	Turn-on time	t <sub>ON</sub>				μs	$V_{\rm bb}$ = 13.5 V
	$V_{\rm DS}$ = 20% $V_{\rm bat}$						resistive load
	channel 0, 1,4,5		-	-	100		I <sub>DS</sub> = 250 mA
	channel 2, 3		-	-	100		I <sub>DS</sub> = 120 mA
	channel 6,7		-	-	100		I <sub>DS</sub> = 250 mA
6.5.11		t <sub>OFF</sub>				μs	$V_{\rm bb}$ = 13.5 V
	$V_{\rm DS} = 80\% V_{\rm bb}$						resistive load
	channel 0, 1, 4, 5		-	-	100	_	<i>I</i> <sub>DS</sub> = 250 mA
	channel 2, 3 (HS)		-	-	100		<i>I</i> <sub>DS</sub> = 120 mA
	channel 6, 7 (LS) t subject to production test, specified by design		-	-	100		I <sub>DS</sub> = 250 mA

1) Not subject to production test, specified by design.



### 6.6 Command Description

#### Input Configuration Registers

ICR01	000 <sub>B</sub>				
3	2	1	0		
	INX1	IN	K0		
	rw	rv	V		
ICR23	001 <sub>B</sub>				
3	2	1	0		
	INX3	IN	(2		
	rw	rv	V		
ICR45	010 <sub>B</sub>				
3	2	1	0		
	INX5	INX4			
	rw	rv	V		
ICR67	011 <sub>B</sub>				
3	2	1	0		
	INX7	IN	<b>K</b> 6		
	rw	rv	V		

Field	Bits	Туре	Description
INXn	[3:2], [1:0]	rw	Input Multiplexer Configuration Channel n
n = 7 to 0			00 Channel n is switched off
			01 Channel n is switched by input 1
			10 Channel n is switched by input 2
			11 Channel n is switched on



# 7 Protection Functions

The device provides embedded protective functions. Integrated protection functions are designed to prevent IC destruction under fault conditions described in this data sheet. Fault conditions are considered as "outside" normal operating range. Protection functions are not designed for continuous repetitive operation.

### 7.1 Over Load Protection

The TLE7235E is protected in case of over load or short circuit of the load. After time  $t_{OFF(OVL)}$ , the over loaded channel n switches off and the according diagnosis flag Dn is set. The channel can be switched on after clearing the protection latch by command CMD.CPL = 1. The CPL command clears itself with the next valid SPI communication frame. Please refer to Figure 7 for details.

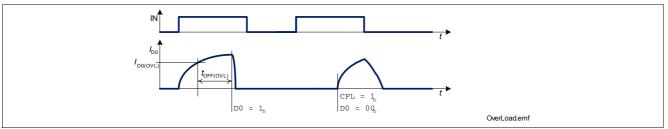


Figure 7 Shut Down at Over Load

### 7.2 Over Temperature Protection

A temperature sensor for each channel causes an overheated channel to switch off to prevent destruction. The according diagnosis flag is set. This flag is also set in OFF state, if the regarding channel temperature is too high. The channel can be only switched on after clearing the protection latch by SPI command CMD. CPL = 1. The CPL command clears itself with the next valid SPI communication frame. Please refer to "Diagnostic Features" on Page 23 for information on diagnosis features.

### 7.3 ESD protection

There is a designed in protection against ESD disturbances up to the specified limit by using the defined model. Please see electrical characteristics **"ESD susceptibility on all pins" on Page 11** 

### 7.4 Reverse Polarity Protection

There is a reverse polarity protection implemented in the TLE7235E. This protection has to be divided into two parts. First the protection of the control circuits and second in the protection of the power transistors.

The control circuits are reverse polarity protected by protective measures in the ground connection. In case of reverse polarity, there is no current flow through the control circuits. The digital pins need serial resistors if the connected input stages are not floating to ground.

The power transistors contain intrinsic body diodes that cause power dissipation. The reverse current through these intrinsic body diodes has to be limited by the connected loads. The over temperature and over load protection are not active during reverse polarity.

### 7.5 Loss of $V_{\rm bb}$

In case of loss of  $V_{bb}$  connection in on-state, all inductances of the loads have to be demagnetized through the ground connection or through an additional path from  $V_{bb}$  to ground. Then for example, a diode (see D2 in **Figure 14 "Application Diagram" on Page 35**) can be placed.



#### **Protection Functions**

### 7.6 Electrical Characteristics

Unless otherwise specified:

 $V_{\rm DD}$  = 3.0 V to 5.5V,  $V_{\rm BAT}$  = 9.0 V to 16V,  $T_{\rm j}$  = -40 °C to +150 °C typical values:  $V_{\rm DD}$  = 5.0 V,  $V_{\rm BAT}$  = 13.5 V,  $T_{\rm j}$  = 25 °C

Pos.	Parameter	Symbol	L	imit Val	ues	Unit	<b>Test Conditions</b>
			min.	min. typ.			
Over	Load Protection				1	L.	1
7.6.1	Over load detection current at channel 0,1,4,5,6,7	I <sub>Out(OVL)</sub>	0.5		1.0	A	
7.6.2	Over load detection current at channel 2,3	I <sub>Out(OVL)</sub>	0.22		0.5	А	
7.6.3	Over load shut-down delay time	t <sub>OFF(OVL)</sub>			60	μs	
Over	Temperature Protection						
7.6.4	Thermal shut down temperature	$T_{j(SC)}$	150	170 <sup>1)</sup>		°C	
1) No	t subject to production test, specified by design			1	1	1	



The SPI of TLE7235E provides diagnosis information about the device and about the load. The diagnosis information of the protective functions of channel n is latched in the diagnosis flags Dn. It is cleared by the SPI command CMD.CPL = 1. The CPL command clears itself with the next valid SPI communication frame. The open load diagnosis of channel n is latched in the diagnosis flag OLn. This flag is cleared by reading the according diagnosis register.

Following table shows possible failure modes and the according protective and diagnostic action.

Failure Mode	Comment
Open Load	Diagnosis, when channel n is switched on: none Diagnosis, when channel n is switched off: according to voltage level at the output pin, flag OLn is set after time $t_{d(OL)}$ . A diagnosis current can be enabled by SPI command DCCR.DCENn = 1.
Over Temperature	When over temperature occurs, the according diagnosis flag Dn is set. If the affected channel n was active it is switched off. The diagnosis flags are latched until they have been cleared by SPI command CMD.CPL = 1.
Over Load (Short Circuit)	When over load is detected at channel n, the affected channel is switched off after time $t_{OFF(OVL)}$ and the dedicated diagnosis flag Dn is set.The diagnosis flags are latched until they have been cleared by SPI command CMD.CPL = 1.



### 8.1 Electrical Characteristics

Unless otherwise specified:

 $V_{\rm DD}$  = 3.0 V to 5.5V,  $V_{\rm BAT}$  = 9.0 V to 16V,  $T_{\rm j}$  = -40 °C to +150 °C typical values:  $V_{\rm BAT}$  = 13.5 V,  $V_{\rm DD}$  = 5.0 V,  $T_{\rm j}$  = 25 °C

Pos.	Parameter	Symbol	Li	mit Va	lues	Uni	<b>Test Conditions</b>	
			min.	typ.	typ. max.			
OFF S	tate Diagnosis							
8.1.1	Open load diagnosis delay time	t <sub>d(OL)</sub>	100	-	250	μs	-	
High S	Side Channels 0,1,2,3							
8.1.2	Open load detection threshold voltage for Channel 0,1,2,3	V <sub>D(OL03)</sub>	2.3	-	3.9	V	1)	
8.1.3	Output diagnosis current channel 0,1,2,3	I <sub>L(DC03)</sub>	50	-	300	μA	measured at $V_{\rm D(OL)}$ threshold	
Config	gurable Channels 4,5							
8.1.4	Open load detection threshold voltage for Channel 4,5 in all configurations	V <sub>D(OL4,5)</sub>	1	-	2.2	V	1)	
8.1.5	Output diagnosis current channel 4,5 in high side configuration	I <sub>L(DCHS)</sub>	80	-	300	μA	measured at $V_{\rm D(OL)}$ threshold	
8.1.6	Output diagnosis current channel 4,5 in low side configuration	I <sub>L(DCLS)</sub>	20	-	100	μA	measured at $V_{\rm D(OL)}$ threshold	
Low si	ide Channels 6,7							
8.1.7	Open load detection threshold voltage for Channel 6,7	V <sub>D(OL6,7)</sub>		-	2.2	V	1)	
8.1.8	Output diagnosis current channel 6,7	$I_{L(DC6,7)}$	50	-	100	μA	measured at VOL threshold	
ON Sta	ate Diagnosis (see also Protection in Ch	apter 7)	1					
8.1.9	Over load detection current at channel 0,1,4,5,6,7	$I_{\rm L(OVL)}$	0.5	-	1.0	A	-	
8.1.10	Over load detection current at channel 2,3	$I_{\rm L(OVL)}$	0.22	-	0.5	A	-	
8.1.11	Over load detection delay time at channel 0,1,4,5,6,7	t <sub>OFF(OVL)</sub>	-	-	60	μs	-	

1) Open load detection voltages are referenced to ground



### 8.2 Command Description

**Diagnosis Registers** (read only, register bank RB = 1)

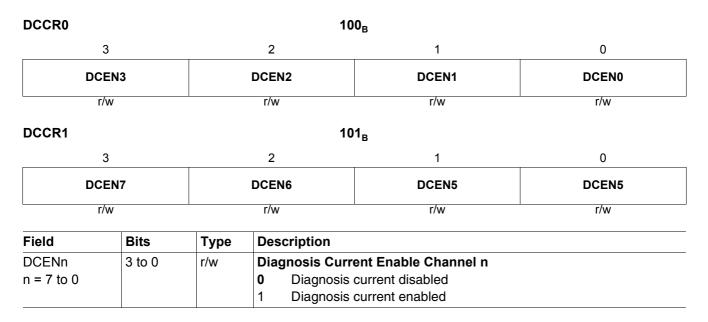
DR01			0	0 <sub>B</sub>			
	3		2	1	0		
о	L1		D1	OL0	D0		
	r		r	r	r		
DR23			0	1 <sub>B</sub>			
	3		2	1	0		
о	L3		D3	OL2	D2		
	r		r	r	r		
DR45			1	0 <sub>B</sub>			
	3		2	1	0		
о	L5		D5	OL4	D4		
	r		r	r	r		
DR67			1	1 <sub>B</sub>			
	3		2	1	0		
o	L7		D7	OL6	D6		
	r		r	r	r		
Field	Bits	Туре	Description				
Dn n = 7 to 0	2, 0	r	<ul> <li>Diagnostic Feedback of Channel n</li> <li>normal operation</li> <li>over load or over temperature switch off occurred</li> </ul>				
OLn n = 7 to 0	3, 1	r	<ul> <li>Open Load Detection of Channel n</li> <li>normal operation</li> <li>Open load at OFF-state occurred</li> </ul>				
CMD Command Re	egister		1 Open loa				

3	2	1	0
Wake	STB	RST	CPL
r/w	r/w	r/w	r/w

Field	Bits	Туре	Description
CPL	0	r/w	please refer to Section 7 for description
RST	1	r/w	please refer to Section 5.3 for description
STB	2	r/w	please refer to Section 5 for description
Wake	3	r/w	please refer to Section 5 for description



#### **Diagnosis Current Configuration Register**

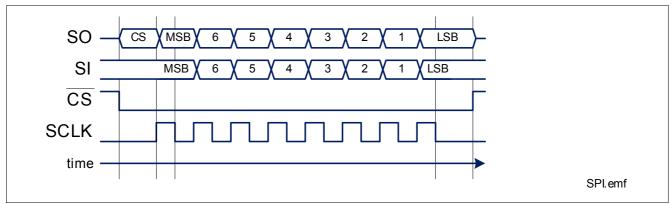




# 9 Serial Peripheral Interface (SPI)

The diagnosis and control interface is based on a serial peripheral interface (SPI).

The SPI is a full duplex synchronous serial slave interface, which uses four lines: SO, SI, SCLK and  $\overline{CS}$ . Data is transferred by the lines SI and SO at the data rate given by SCLK. The falling edge of  $\overline{CS}$  indicates the beginning of a data access. Data is sampled in on line SI at the falling edge of SCLK and shifted out on line SO at the rising edge of SCLK. Each access must be terminated by a rising edge of  $\overline{CS}$ . A modulo 8 counter ensures that data is taken only, when a multiple of 8 bit has been transferred. The interface provides daisy chain capability.



#### Figure 8 Serial Peripheral Interface

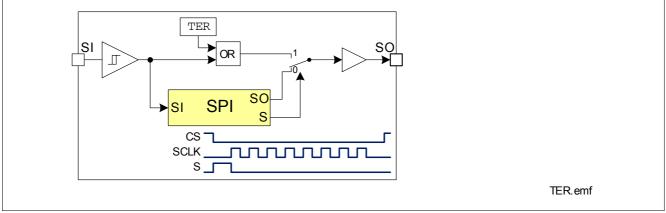
The SPI protocol is described in **Section 9.3**. It is reset to the default values after reset.

### 9.1 SPI Signal Description

**CS** - Chip Select: The system micro controller selects the TLE7235E by means of the  $\overline{CS}$  pin. Whenever the pin is in low state, data transfer can take place. When  $\overline{CS}$  is in high state, any signals at the SCLK and SI pins are ignored and SO is forced into a high impedance state.

### CS High to Low transition:

- The diagnosis information is transferred into the shift register.
- SO changes from high impedance state to high or low state depending on the logic OR combination between the transmission error flag (TER) and the signal level at pin SI. As a result, even in daisy chain configuration, a high signal indicates a faulty transmission. For details, please refer to **Figure 9**. This information stays available to the first rising edge of SCLK.







### CS Low to High transition:

- Command decoding is only done, when after the falling edge of CS exactly a multiple (1, 2, 3, ...) of eight SCLK signals have been detected. In case of faulty transmission, the transmission error flag (TER) is set and the command is ignored.
- Data from shift register is transferred into the input matrix register.

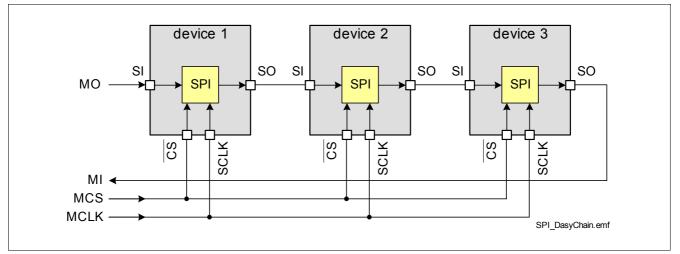
**SCLK** - **Serial Clock:** This input pin clocks the internal shift register. The serial input (SI) transfers data into the shift register on the falling edge of SCLK while the serial output (SO) shifts diagnostic information out on the rising edge of the serial clock. It is essential that the SCLK pin is in low state whenever chip select  $\overline{CS}$  makes any transition.

**SI - Serial Input:** Serial input data bits are shifted in at this pin, the most significant bit first. SI information is read on the falling edge of SCLK. The 8 bit input data consist of two parts (control and data). Please refer to **Section 9.3** for further information.

**SO Serial Output:** Data is shifted out serially at this pin, the most significant bit first. SO is in high impedance state until the  $\overline{CS}$  pin goes to low state. New data will appear at the SO pin following the rising edge of SCLK. Please refer to Section 9.3 for further information.

### 9.2 Daisy Chain Capability

The SPI of TLE7235E provides daisy chain capability. In this configuration several devices are activated by the same  $\overline{CS}$  signal  $\overline{MCS}$ . The SI line of one device is connected with the SO line of another device (see Figure 10), which builds a chain. The ends of the chain are connected with the output and input of the master device, MO and MI respectively. The master device provides the master clock MCLK, which is connected to the SCLK line of each device in the chain.





In the SPI block of each device, there is one shift register where one bit from SI line is shifted in each SCLK. The bit shifted out can be seen at SO. After 8 SCLK cycles, the data transfer for one device has been finished. In single chip configuration, the  $\overline{CS}$  line must go high to make the device accept the transferred data. In daisy chain configuration the data shifted out at device #1 has been shifted in to device #2. When using three devices in daisy chain, three times 8 bits have to be shifted through the devices. After that, the  $\overline{MCS}$  line must go high (see Figure 11).



MI – SO device 3	SO device 2	SO device 1	<u> </u>
MO—SI device 3	SI device 2	SI device 1	
MCS			
MCLK			
time			►
		SPI_DasyCl	hain2.

Figure 11 Data Transfer in Daisy Chain Configuration

#### 9.3 **SPI Protocol**

The control and diagnosis function of the TLE7235E is based on two register banks which are accessed via following SPI protocol. The control register bank contains eight registers (with 4 bit each) addressed by a 3 bit pointer. The diagnosis register bank contains four registers (with 4 bit each) addressed by a 2 bit pointer. An additional indication bit is available to differentiate between standard diagnosis information and data read from a register bank.

#### **Control and Diagnosis Mode**

CS <sup>1)</sup>	7	6	5	4	3	2	1	0
Write Registe	er Commar	nd		11				
	1		ADDR			DA	TA	
Read Regist	er Commai	nd						
	0		ADDR		х	x	0	RB
Read Standa	rd Diagnos	sis				1	1	1
	0	Х	х	х	Х	Х	1	х
Standard Dia	ignosis			· · · · · ·				Ľ
TER	0	0	AWK	LH	D67	D45	D23	D01
Second Fran	ne of Read	Command						
TER	0	1	ADDR (D	)iagnosis)		DA	TA	
TER	1	ADDR (Control)				DA	TA	
	Write Registe Read Registe Read Standa Standard Dia TER Second Fran TER	Write Register Comman 1 Read Register Comman 0 Read Standard Diagnos 0 Standard Diagnosis TER 0 Second Frame of Read TER 0	Write Register Command    I Read Register Command	Write Register Command         1       ADDR         Read Register Command         0       ADDR         Read Standard Diagnosis         0       x         Standard Diagnosis         TER       0       0         Second Frame of Read Command         TER       0       1         ADDR         Read Standard Diagnosis         0       1         ADDR	Write Register Command       1       ADDR         Read Register Command       0       ADDR         0       ADDR       Read Standard Diagnosis         0       x       x       x         Standard Diagnosis       0       AWK       LH         Standard Diagnosis       0       AWK       LH         Standard Diagnosis       0       1       ADDR (Diagnosis)	Write Register Command       1       ADDR         Read Register Command       0       ADDR       x         0       ADDR       x         Read Standard Diagnosis       0       x       x         0       x       x       x         Standard Diagnosis       0       AWK       LH       D67         Standard Diagnosis       0       1       ADDR (Diagnosis)       0	Write Register Command       ADDR       DA         Read Register Command       0       ADDR       X       X         Read Standard Diagnosis       0       X       X       X       X         Q       X       X       X       X       X         Standard Diagnosis       0       X       X       X       X         TER       0       0       AWK       LH       D67       D45         Second Frame of Read Command       TER       0       1       ADDR (Diagnosis)       DA	Write Register CommandImage: Image: Ima

This bit is valid between CS hi -> lo and first SCLK lo -> hi transition.

Note: Reading a register needs two SPI frames. In the first frame the RD command is sent. In the second frame, the output at SPI signal SO will contain the requested information. Any command can be executed in the second frame.



Field	Bits	Туре	Description			
TER			Transmission Error			
			<ul> <li>Previous transmission was successful (modulo 8 clocks received)</li> </ul>			
			1 Previous transmission failed or first transmission after reset			
RB	0		Register Bank			
			0 CONTR Control Register Bank			
			1 DIAG Diagnosis Register Bank (read only)			
ADDR	6:4		Address			
			Pointer to register for read and write command			
DATA	3:0		Data			
			Data written to or read from register selected by address ADDR			

#### **Standard Diagnosis:**

Field	Bits	Туре	Description	
AWK	5		Awake, Device active	
LH	4		Limp home mode active	
Dxy	3, 2, 1, 0		Failure mode alert of channel x and y	

### 9.4 Register Overview

#### Control Register Bank

Name	Addr	3	2	1	0	default <sup>1)</sup>	type
ICR01	000 <sub>B</sub>	INX1		IN	X0	0 <sub>H</sub>	r/w
ICR23	001 <sub>B</sub>	INX3		IN	X2	0 <sub>H</sub>	r/w
ICR45	010 <sub>B</sub>	IN	IX5	INX4		0 <sub>H</sub>	r/w
ICR67	011 <sub>B</sub>	INX7		IN	X6	0 <sub>H</sub>	r/w
DCCR0	100 <sub>B</sub>	DCEN3	DCEN2	DCEN1 DCEN0		0 <sub>H</sub>	r/w
DCCR1	101 <sub>B</sub>	DCEN7	DCEN6	DCEN5 DCEN4		0 <sub>H</sub>	r/w
CMD	110 <sub>B</sub>	WAKE	STB	RST CPL <sup>2)</sup>		0 <sub>H</sub>	W
unused	111 <sub>B</sub>	_	_	_	_	0 <sub>H</sub>	_

1) The default values are set after  $V_{\rm bb}$  power-on, STB-command and RST-command

All command bits are cleared at the end of transmission, respectively after execution

2) CPL bit needs a valid next SPI communication frame to be cleared



### Diagnosis Register Bank (read only)

Name	Addr	3	2	1	0
DR01	000 <sub>B</sub>	OL1	D1	OL0	D0
DR23	001 <sub>B</sub>	OL3	D3	OL2	D2
DR45	010 <sub>B</sub>	OL5	D5	OL4	D4
DR67	011 <sub>B</sub>	OL7	D7	OL6	D6

### 9.5 Timing Diagrams

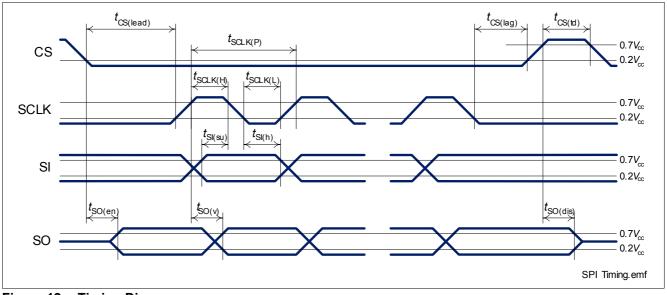


Figure 12 Timing Diagram



### 9.6 Electrical Characteristics

Unless otherwise specified:  $V_{\text{DD}}$  = 3.0 V to 5.5V,  $V_{\text{BAT}}$  = 9.0 V to 16V,  $T_{\text{j}}$  = -40 °C to +150 °C typical values:  $V_{\text{DD}}$  = 5.0 V,  $V_{\text{BAT}}$  = 13.5 V,  $T_{\text{j}}$  = 25 °C

Pos.	Parameter	Symbol	Limit Values			Unit	Test Conditions
			min.	typ.	max.		
Input	Characteristics (CS, SCLK, SI)	ł	-+	-	+		
9.6.1	L level of pin		0	_	0.2*V <sub>DD</sub>	V	-
	CS	$V_{\rm CS(L)}$					
	SCLK	$V_{\rm SCLK(L)}$					
	SI	$V_{SI(L)}$					
9.6.2	·		$0.5^*V_{\rm DD}$	-	$V_{DD}$	V	-
	CS	V <sub>CS(H)</sub>					
	SCLK	V <sub>SCLK(H)</sub>					
	SI	V <sub>SI(H)</sub>	-	40	0.0		V ON
9.6.3	L-input pull-up current through $\overline{CS}$	I <sub>CS(L)</sub>	5	40	90	μA	$V_{\rm CS} = 0 V$
0.0.4	11 in the line of the sector 1	T	0.5			•	$V_{\rm DD} = 5 \text{ V}$
9.6.4	H-input pull-up current through CS	$I_{\rm CS(H)}$	2.5	-	-	μA	V = 5 M
							$V_{\rm DD} = 5 V$ $V_{\rm DD} = 0.5*V$
9.6.5	Lipput pull down ourront through pin	I	1.5			^	$V_{\rm CS} = 0.5^* V_{\rm DD}$
9.0.5	L-input pull-down current through pin SCLK		1.5	-	-	μA	$V_{\rm DD} = 5 \rm V$
	SI	I <sub>SI(L)</sub>					$V_{\text{SCLK}} = V_{\text{SI}} = 0.2*V_{\text{DI}}$
9.6.6		I <sub>SCLK(H)</sub>				μA	1)
0.0.0	SCLK	$I_{SI(H)}$	10	40	80	μπ	V <sub>DD</sub> = 5 ∨
	SI	- SI(H)					$V_{\text{SCLK}} = V_{\text{SI}} = V_{\text{DD}}$
Outpu	ut Characteristics (SO)						JOLIX OF DD
9.6.7	L level output voltage	V <sub>SO(L)</sub>	0	-	0.4	V	I <sub>SO</sub> = +2 mA
9.6.8	H level output voltage	V <sub>SO(H)</sub>	V <sub>DD</sub> -	_	V <sub>DD</sub>		$I_{\rm SO}$ = -1.5 mA
		30(1)	0.4 V		00		30
9.6.9	Output tristate leakage current	$I_{\rm SO(OFF)}$	-10	-	10	μA	$V_{\rm CS} = V_{\rm DD}$
Timin	igs	()		1		1	
9.6.10	Serial clock frequency	$f_{\rm SCLK}$	0	-	5	MHz	-
9.6.11	Serial clock period	t <sub>SCLK(P)</sub>	200	-	_	ns	-
9.6.12	Serial clock high time	t <sub>SCLK(H)</sub>	50	-	-	ns	1)
9.6.13	Serial clock low time	t <sub>SCLK(L)</sub>	50	_	-	ns	1)
9.6.14	Enable lead time (falling $\overline{CS}$ to rising SCLK)	$t_{\rm CS(lead)}$	250	-	-	ns	1)
9.6.15	,	<i>t</i>	250	_		ns	1)
	CS)	t <sub>CS(lag)</sub>	200			115	
9.6.16		t <sub>CS(td)</sub>	250	-	-	ns	1)
	falling CS)						
9.6.17	Data setup time (required time SI to	t <sub>SI(su)</sub>	20	-	-	ns	1)
	falling SCLK)						
9.6.18	Data hold time (falling SCLK to SI)	t <sub>SI(h)</sub>	20	_	_	ns	1)



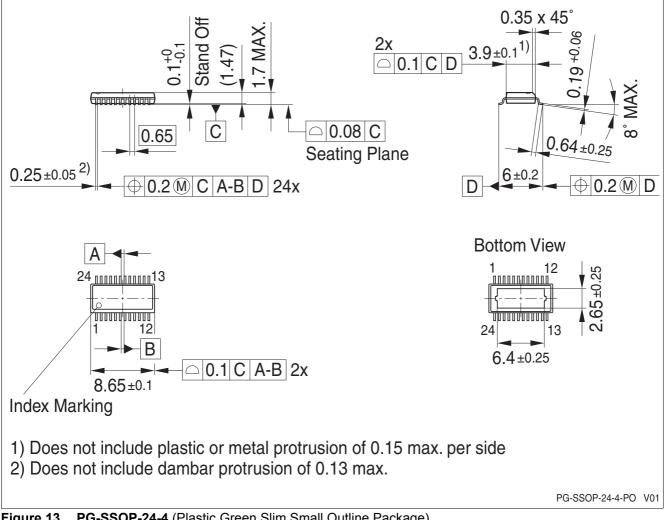
Unless otherwise specified:  $V_{\text{DD}}$  = 3.0 V to 5.5V,  $V_{\text{BAT}}$  = 9.0 V to 16V,  $T_{\text{j}}$  = -40 °C to +150 °C typical values:  $V_{\text{DD}}$  = 5.0 V,  $V_{\text{BAT}}$  = 13.5 V,  $T_{\text{j}}$  = 25 °C

Pos.	Parameter	Symbol	Limit Values			Unit	<b>Test Conditions</b>
			min.	typ.	max.		
9.6.19	Output enable time (falling $\overline{CS}$ to SO valid)	t <sub>SO(en)</sub>	-	-	200	ns	$C_{\rm L}$ = 20 pF <sup>1)</sup>
9.6.20	Output disable time (rising $\overline{CS}$ to SO tri-state)	t <sub>SO(dis)</sub>	-	-	200	ns	$C_{\rm L}$ = 20 pF <sup>1)</sup>
9.6.21	Output data valid time with capacitive load	t <sub>SO(v)</sub>	-	-	100	ns	C <sub>L</sub> = 20 pF <sup>1)</sup>

1) Not subject to production test, specified by design.



#### **Package Outlines** 10



PG-SSOP-24-4 (Plastic Green Slim Small Outline Package) Figure 13

### Green Product (RoHS compliant)

To meet the world-wide customer requirements for environmentally friendly products and to be compliant with government regulations the device is available as a green product. Green products are RoHS-Compliant (i.e Pbfree finish on leads and suitable for Pb-free soldering according to IPC/JEDEC J-STD-020).

For further information on alternative packages, please visit our website: http://www.infineon.com/packages.

Dimensions in mm

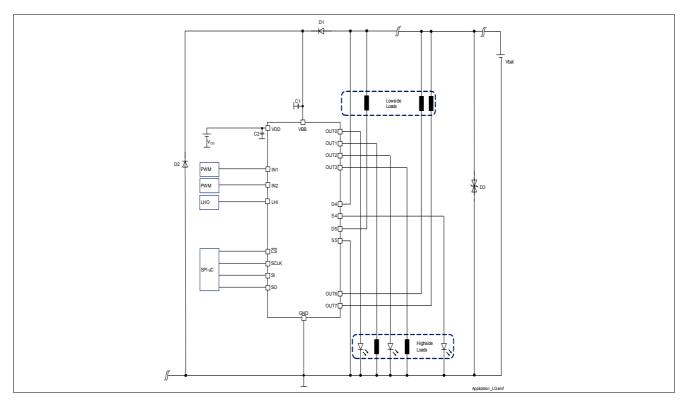


#### **Application Information**

# 11 Application Information

Note: The following information is given as a hint for the implementation of the device only and shall not be regarded as a description or warranty of a certain functionality, condition or quality of the device.

Figure 14 shows a simplified application circuit. Vdd need to be externally reverse polarity protected.



#### Figure 14 Application Diagram

Note: This is a very simplified example of an application circuit. The function must be verified in the real application.

The circuit above shows a example of using this device in a automotive target application.

D1,C1 are used for blocking negative disturbances from Battery supply.

D2 is optional for loss of battery if no other circuit on this battery feed can limit the voltage to the negative max. rating of the device (-16 V) .

D3 is limiting the battery voltage below the maximum rated positive voltage of the VBB pin (40 V).

C2 is for EMC and to stabilize the digital driver, recommended value is 47nF.

There are no resistors to the  $\mu$ C needed due to the internal reverse polarity protection.

For further information you may contact http://www.infineon.com/



#### **Revision History**

# 12 Revision History

Revision	Date	Changes
Rev. 1.0	2008-10-30	released Datasheet

Edition 2008-10-30

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