# 74AUP1Z04

# Low-power X-tal driver with enable and internal resistor Rev. 02 — 3 July 2008 Product data

**Product data sheet** 

#### 1. **General description**

The 74AUP1Z04 combines the functions of the 74AUP1GU04 and 74AUP1G04 with enable circuitry and an internal bias resistor to provide a device optimized for use in crystal oscillator applications.

When not in use the EN input can be driven HIGH, pulling up the X1 input and putting the device in a low power disable mode. Schmitt trigger action at the  $\overline{\text{EN}}$  input makes the circuit tolerant to slower input rise and fall times across the entire V<sub>CC</sub> range from 0.8 V to 3.6 V.

This device is fully specified for partial power-down applications using I<sub>OFF</sub> at output Y. The I<sub>OFF</sub> circuitry disables the output Y, preventing the damaging backflow current through the device when it is powered down.

The integration of the two devices into the 74AUP1Z04 produces the benefits of a compact footprint, lower power dissipation and stable operation over a wide range of frequency and temperature.

#### **Features** 2.

- Wide supply voltage range from 0.8 V to 3.6 V
- High noise immunity
- ESD protection:
  - HBM JESD22-A114E Class 3A exceeds 5000 V
  - MM JESD22-A115-A exceeds 200 V
  - CDM JESD22-C101C exceeds 1000 V
- Latch-up performance exceeds 100 mA per JESD 78 Class II
- Inputs accept voltages up to 3.6 V
- Low noise overshoot and undershoot < 10 % of V<sub>CC</sub>
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation at output Y
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C



## Low-power X-tal driver with enable and internal resistor

## 3. Ordering information

Table 1. Ordering information

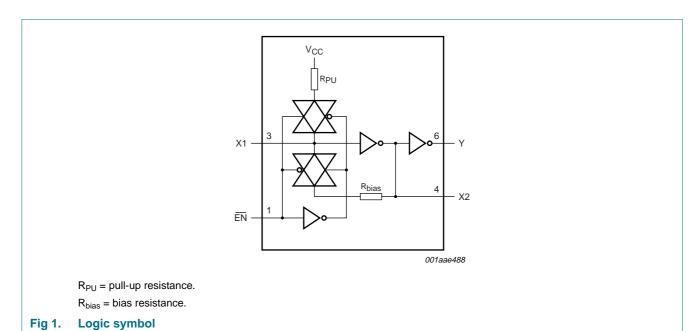
Type number	Package						
	Temperature range	Name	Description	Version			
74AUP1Z04GW	–40 °C to +125 °C	SC-88	plastic surface-mounted package; 6 leads	SOT363			
74AUP1Z04GM	–40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 $\times$ 1.45 $\times$ 0.5 mm	SOT886			
74AUP1Z04GF	–40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 $\times$ 1 $\times$ 0.5 mm	SOT891			

## 4. Marking

#### Table 2. Marking

Type number	Marking code
74AUP1Z04GW	a4
74AUP1Z04GM	a4
74AUP1Z04GF	a4

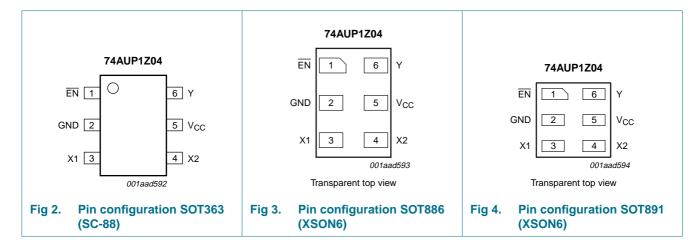
## 5. Functional diagram



Low-power X-tal driver with enable and internal resistor

## 6. Pinning information

#### 6.1 Pinning



#### 6.2 Pin description

Table 3. Pin description

Symbol	Pin	Description
EN	1	enable input (active LOW)
GND	2	ground (0 V)
X1	3	data input
X2	4	data output
V <sub>CC</sub>	5	supply voltage
Υ	6	data output

## 7. Functional description

Table 4. Function table[1]

Input X1		Output		
EN	X1	X2	Υ	
L	L	Н	L	
L	Н	L	Н	
Н	L	Н	L	
Н	Н	L	Н	

<sup>[1]</sup> H = HIGH voltage level; L = LOW voltage level.

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#### Low-power X-tal driver with enable and internal resistor

## 8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC}$	supply voltage		-0.5	+4.6	V
$I_{IK}$	input clamping current	V <sub>I</sub> < 0 V	-50	-	mA
$V_{I}$	input voltage		<u>[1]</u> –0.5	+4.6	V
$I_{OK}$	output clamping current	$V_O > V_{CC}$ or $V_O < 0 V$	-	±50	mA
$V_{O}$	output voltage		<u>[1]</u> –0.5	$V_{CC} + 0.5$	V
I <sub>O</sub>	output current	$V_O = 0 V \text{ to } V_{CC}$	-	±20	mA
$I_{CC}$	supply current		-	50	mA
$I_{GND}$	ground current		-50	-	mA
$T_{stg}$	storage temperature		-65	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$	[2] -	250	mW

<sup>[1]</sup> The minimum input and output voltage ratings may be exceeded if the input and output current ratings are observed.

## 9. Recommended operating conditions

Table 6. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC}$	supply voltage		8.0	3.6	V
$V_{I}$	input voltage		0	3.6	V
$V_{O}$	output voltage		0	$V_{CC}$	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	200	ns/V

<sup>[2]</sup> For SC-88 packages: above 87.5 °C the value of P<sub>tot</sub> derates linearly with 4.0 mW/K. For XSON6 packages: above 45 °C the value of P<sub>tot</sub> derates linearly with 2.4 mW/K.

## Low-power X-tal driver with enable and internal resistor

## 10. Static characteristics

Table 7. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
T <sub>amb</sub> = 2	5 °C					
$V_{IH}$	HIGH-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	$0.75 \times V_{\text{CC}}$	-	-	V
		EN input				
		$V_{CC} = 0.8 \text{ V}$	$0.70 \times V_{CC}$	-	-	V
		$V_{CC} = 0.9 \text{ V to } 1.95 \text{ V}$	$0.65 \times V_{CC}$	-	-	V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	1.6	-	-	V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	2.0	-	-	V
V <sub>IL</sub>	LOW-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	$0.25 \times V_{CC}$	٧
		EN input				
		$V_{CC} = 0.8 \text{ V}$	-	-	$0.30 \times V_{CC}$	٧
		V <sub>CC</sub> = 0.9 V to 1.95 V	-	-	$0.35 \times V_{CC}$	V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	-	-	0.7	٧
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	-	-	0.9	٧
V <sub>OH</sub>	HIGH-level output voltage	Y output; V <sub>I</sub> at X1 input = V <sub>IH</sub> or V <sub>IL</sub>				
		$I_{O} = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	V <sub>CC</sub> - 0.1	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.11	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.32	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	2.05	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.9	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.72	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.6	-	-	V
		X2 output; $V_I = GND$ or $V_{CC}$				
		$I_{O} = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	V <sub>CC</sub> - 0.1	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.11	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.32	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	2.05	-	-	٧
		$I_O = -3.1 \text{ mA}$ ; $V_{CC} = 2.3 \text{ V}$	1.9	-	-	V
		$I_O = -2.7 \text{ mA}$ ; $V_{CC} = 3.0 \text{ V}$	2.72	-	-	V
		$I_O = -4.0 \text{ mA}$ ; $V_{CC} = 3.0 \text{ V}$	2.6	-	-	V

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>OL</sub>	LOW-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	0.1	V
		$I_{O} = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.3 \times V_{CC}$	V
		$I_{O} = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.31	V
		$I_{O} = 1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	-	-	0.31	V
		$I_{O} = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.31	V
		$I_{O} = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.44	V
		$I_{O} = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.31	V
		$I_{O} = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.44	V
		X2 output; $V_I = GND$ or $V_{CC}$				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	0.1	V
		$I_{O} = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.3 \times V_{CC}$	V
		$I_{O} = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.31	V
		$I_{O} = 1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	-	-	0.31	V
		$I_{O} = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.31	V
		$I_{O} = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.44	V
		$I_{O} = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.31	V
		$I_{O} = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.44	V
I <sub>I</sub>	input leakage current	X1 input				
		$V_I = \overline{EN} = V_{CC}$ ; $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.1	μΑ
		EN input				
		$V_I = GND \text{ to } 3.6 \text{ V};$ $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.1	μΑ
pu	pull-up current	X1 input; $\overline{EN} = V_{CC}$				
		$V_{I} = GND; V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	15	μΑ
OFF	power-off leakage current	$V_I$ or $V_O = 0$ V to 3.6 V; $V_{CC} = 0$ V	<u>[1]</u> _	-	±0.2	μΑ
Noff	additional power-off leakage current	$V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC} = 0$ V to 0.2 V	[1] -	-	±0.2	μΑ
CC	supply current	$V_I$ = GND or $V_{CC}$ ; $I_O$ = 0 A; $\overline{EN}$ = GND; $V_{CC}$ = 0.8 V to 3.6 V	-	-	75	μΑ
VICC	additional supply current	EN input				
		$V_{I} = V_{CC} - 0.6 \text{ V}; I_{O} = 0 \text{ A};$ $V_{CC} = 3.3 \text{ V}$	-	-	40	μΑ
ì	input capacitance	X1 input				
		$V_{CC} = 0 \text{ V to } 3.6 \text{ V};$ $V_{I} = \text{GND or } V_{CC}$	-	1.3	-	pF
		EN input				
		$V_{CC} = 0 \text{ V to } 3.6 \text{ V};$ $V_{I} = \text{GND or } V_{CC}$	-	0.8	-	pF

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Co	output capacitance	X2 output				
		$V_O = GND; V_{CC} = 0 V$	-	1.5	-	pF
		Y output				
		$V_O = GND; V_{CC} = 0 V$	-	1.7	-	pF
9 <sub>fs</sub>	forward transconductance	see Figure 10 and Figure 11				
		$V_{CC} = 0.8 \text{ V}$	-	-	-	mA/V
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	0.2	-	9.9	mA/V
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	3.9	-	17.7	mA/V
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	7.9	-	24.3	mA/V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	18	-	30.7	mA/V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	20.5	-	32.4	mA/V
R <sub>bias</sub>	bias resistance	$\overline{EN}$ = GND; f <sub>i</sub> = 0 Hz; V <sub>I</sub> = 0 V or V <sub>CC</sub> ; see <u>Figure 5</u> ; for frequency behavior see <u>Figure 6</u>	1.08	1.62	3.08	ΜΩ
T <sub>amb</sub> = -	40 °C to +85 °C					
$V_{IH}$	HIGH-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		EN input				
		$V_{CC} = 0.8 \text{ V}$	$0.70 \times V_{CC}$	-	-	V
		$V_{CC} = 0.9 \text{ V to } 1.95 \text{ V}$	$0.65 \times V_{CC}$	-	-	V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	1.6	-	-	V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	2.0	-	-	V
$V_{IL}$	LOW-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	$0.25 \times V_{CC}$	V
		EN input				
		$V_{CC} = 0.8 \text{ V}$	-	-	$0.30 \times V_{CC}$	V
		$V_{CC} = 0.9 \text{ V to } 1.95 \text{ V}$	-	-	$0.35 \times V_{CC}$	V
		$V_{CC}$ = 2.3 V to 2.7 V	-	-	0.7	V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	-	-	0.9	V

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Uni
V <sub>OH</sub>	HIGH-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				
		$I_{O} = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	$V_{CC} - 0.1$	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.7 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.03	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.30	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.97	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.85	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.67	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.55	-	-	V
		$V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				
		$I_O = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	V <sub>CC</sub> - 0.1	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.7 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.03	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.30	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.97	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.85	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.67	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.55	-	-	V
OL	LOW-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				
		$I_O = 20 \ \mu A; \ V_{CC} = 0.8 \ V \ to \ 3.6 \ V$	-	-	0.1	V
		$I_O = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.3 \times V_{CC}$	V
		$I_O = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.37	V
		$I_O = 1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	-	-	0.35	V
		$I_O = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.33	V
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.45	V
		$I_O = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.33	V
		$I_O = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.45	V
		X2 output; $V_I = GND$ or $V_{CC}$				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	0.1	V
		$I_O = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.3 \times V_{CC}$	V
		$I_O = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.37	V
		$I_{O} = 1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	-	-	0.35	V
		$I_{O} = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.33	٧
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.45	V
		$I_{O} = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.33	V
		$I_O = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.45	V

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
l <sub>l</sub>	input leakage current	X1 input				
		$V_I = \overline{EN} = V_{CC}$ ; $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.5	μΑ
		EN input				
		$V_I = GND \text{ to } 3.6 \text{ V};$ $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.5	μΑ
l <sub>pu</sub>	pull-up current	X1 input; $\overline{EN} = V_{CC}$				
		$V_I = GND$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	-	-	15	μΑ
l <sub>OFF</sub>	power-off leakage current	$V_I$ or $V_O = 0$ V to 3.6 V; $V_{CC} = 0$ V	<u>[1]</u> _	-	±0.5	μΑ
$\Delta I_{OFF}$	additional power-off leakage current	$V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC} = 0$ V to 0.2 V	<u>[1]</u> _	-	±0.6	μΑ
I <sub>CC</sub>	supply current	$V_1$ = GND or $V_{CC}$ ; $I_0$ = 0 A; $\overline{EN}$ = GND; $V_{CC}$ = 0.8 V to 3.6 V	-	-	75	μΑ
$\Delta I_{CC}$	additional supply current	EN input				
		$V_{I} = V_{CC} - 0.6 \text{ V}; I_{O} = 0 \text{ A};$ $V_{CC} = 3.3 \text{ V}$	-	-	50	μΑ
<b>9</b> fs	forward transconductance	see Figure 10 and Figure 11				
		V <sub>CC</sub> = 0.8 V	-	-	-	mA/V
		V <sub>CC</sub> = 1.1 V to 1.3 V	-	-	10.8	mA/V
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	1.8	-	21.2	mA/V
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	7.5	-	29.9	mA/V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	15.0	-	38.0	mA/V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	17.8	-	39.2	mA/V
R <sub>bias</sub>	bias resistance	$\overline{EN}$ = GND; f <sub>i</sub> = 0 Hz; V <sub>I</sub> = 0 V or V <sub>CC</sub> ; see <u>Figure 5</u> ; for frequency behavior see <u>Figure 6</u>	1.07	-	3.11	ΜΩ
T <sub>amb</sub> = -	40 °C to +125 °C					
$V_{IH}$	HIGH-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		EN input				
		V <sub>CC</sub> = 0.8 V	$0.75 \times V_{CC}$	-	-	V
		$V_{CC} = 0.9 \text{ V to } 1.95 \text{ V}$	$0.70 \times V_{CC}$	-	-	V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	1.6	-	-	V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	2.0	-	-	V
V <sub>IL</sub>	LOW-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	$0.25 \times V_{CC}$	V
		EN input				
		V <sub>CC</sub> = 0.8 V	-	-	$0.25 \times V_{CC}$	V
		V <sub>CC</sub> = 0.9 V to 1.95 V	-	-	$0.30 \times V_{CC}$	V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	-	-	0.7	V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	-	-	0.9	V

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

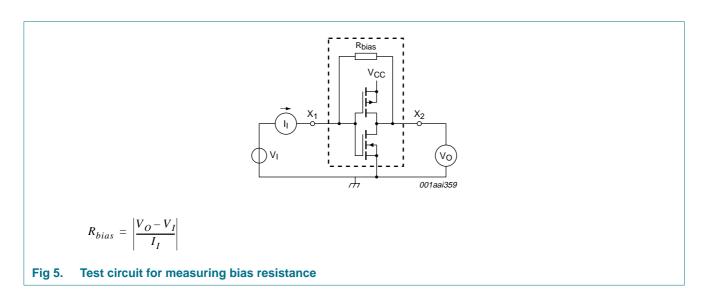
Symbol	Parameter	Conditions	Min	Тур	Max	Uni
/ <sub>OH</sub>	HIGH-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				V
		$I_{O} = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	V <sub>CC</sub> - 0.11	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.6 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	0.93	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.17	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.77	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.67	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.40	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.30	-	-	V
		X2 output; $V_I = GND$ or $V_{CC}$				V
		$I_O = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	V <sub>CC</sub> – 0.11	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.6 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	0.93	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.17	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.77	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.67	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.40	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.30	-	-	V
OL	LOW-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				
		$I_{O}$ = 20 $\mu$ A; $V_{CC}$ = 0.8 V to 3.6 V	-	-	0.11	V
		$I_O = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.33 \times V_{CC}$	V
		$I_O = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.41	٧
		$I_O = 1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	-	-	0.39	٧
		$I_O = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.36	V
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.50	V
		$I_O = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.36	V
		$I_O = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.50	V
		X2 output; $V_I = GND$ or $V_{CC}$				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	0.11	V
		I <sub>O</sub> = 1.1 mA; V <sub>CC</sub> = 1.1 V	-	-	$0.33 \times V_{CC}$	V
		$I_O = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.41	V
		$I_O = 1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	-	-	0.39	V
		$I_O = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.36	V
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.50	V
		I <sub>O</sub> = 2.7 mA; V <sub>CC</sub> = 3.0 V	-	-	0.36	V
		$I_O = 4.0 \text{ mA}$ ; $V_{CC} = 3.0 \text{ V}$	-	-	0.50	V

## Low-power X-tal driver with enable and internal resistor

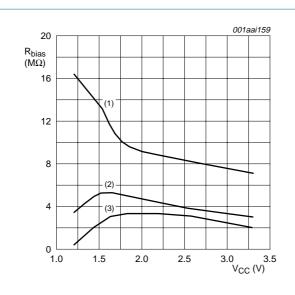
**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
l <sub>l</sub>	input leakage current	X1 input				
		$V_I = \overline{EN} = V_{CC}$ ; $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.75	μΑ
		EN input				
		$V_I = GND \text{ to } 3.6 \text{ V};$ $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.75	μΑ
I <sub>pu</sub>	pull-up current	X1 input; $\overline{EN} = V_{CC}$				
		$V_I = GND$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	-	-	15	μΑ
l <sub>OFF</sub>	power-off leakage current	$V_I$ or $V_O = 0$ V to 3.6 V; $V_{CC} = 0$ V	[1]	-	±0.75	μΑ
$\Delta I_{OFF}$	additional power-off leakage current	$V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC} = 0$ V to 0.2 V	[1] _	-	±0.75	μΑ
I <sub>CC</sub>	supply current	$V_I$ = GND or $V_{CC}$ ; $I_O$ = 0 A; $\overline{EN}$ = GND; $V_{CC}$ = 0.8 V to 3.6 V	-	-	75	μΑ
$\Delta I_{CC}$	additional supply current	EN input				
		$V_I = V_{CC} - 0.6 \text{ V}; I_O = 0 \text{ A};$ $V_{CC} = 3.3 \text{ V}$	-	-	75	μΑ
g <sub>fs</sub>	forward transconductance	see Figure 10 and Figure 11				
		$V_{CC} = 0.8 \text{ V}$	-	-	-	mA/V
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	-	-	10.8	mA/V
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	1.8	-	21.2	mA/V
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	6.9	-	29.9	mA/V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	13.4	-	38.0	mA/V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	15.8	-	39.2	mA/V
R <sub>bias</sub>	bias resistance	$\overline{\text{EN}}$ = GND; f <sub>i</sub> = 0 Hz; V <sub>I</sub> = 0 V or V <sub>CC</sub> ; see Figure 5; for frequency behavior see Figure 6	1.07	-	3.11	ΜΩ

#### [1] Only for output Y and input $\overline{EN}$ .



#### Low-power X-tal driver with enable and internal resistor



- (1)  $f_i = 30 \text{ kHz}.$
- (2)  $f_i = 1 \text{ MHz}.$
- (3)  $f_i = 10 \text{ MHz}.$

Fig 6. Typical bias resistance versus supply voltage

## 11. Dynamic characteristics

Table 8. Dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 9.

Symbol	Parameter	Conditions		T <sub>amb</sub> =25 °C		$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$			Unit	
				Min			Max (125 °C)			
$C_L = 5 pl$	=									
t <sub>pd</sub>	propagation delay	X1 to X2; see Figure 7	[2]							
		$V_{CC} = 0.8 \text{ V}$		-	12.8	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$		1.2	3.0	3.9	1.2	3.9	3.9	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$		1.0	2.2	2.6	1.0	2.7	2.7	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$		8.0	1.9	2.3	8.0	2.4	2.5	ns
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$		0.7	1.6	1.9	0.7	2.0	2.0	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$		0.7	1.4	1.6	0.7	1.7	1.7	ns
		X1 to Y; see Figure 8	[2]							
		$V_{CC} = 0.8 \text{ V}$		-	39.2	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$		2.5	8.0	10.7	2.3	10.8	10.9	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$		2.2	5.5	6.6	2.0	7.0	7.0	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$		1.8	4.4	5.5	1.7	5.9	6.0	ns
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$		1.5	3.5	4.1	1.4	4.4	4.5	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$		1.5	3.1	3.5	1.4	3.8	3.8	ns

**Table 8. Dynamic characteristics** ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 9.

Symbol	Parameter	Conditions		T <sub>amb</sub> =25 °C			$T_{amb}$ = -40 °C to +125 °C			
			Min Typ[1] Max		Max	Min	Max (85 °C)	Max (125 °C)		
C <sub>L</sub> = 10	pF			•		•				
t <sub>pd</sub>	propagation delay	X1 to X2; see Figure 7								
		$V_{CC} = 0.8 \text{ V}$	-	20.9	-	-	-	-	ns	
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	1.4	4.1	5.4	1.3	5.6	5.6	ns	
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	1.3	2.9	3.6	1.2	3.8	3.8	ns	
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	1.2	2.5	3.0	1.1	3.2	3.2	ns	
		$V_{CC}$ = 2.3 V to 2.7 V	0.9	2.0	2.4	8.0	2.5	2.5	ns	
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	0.9	1.8	2.1	8.0	2.3	2.3	ns	
		X1 to Y; see Figure 8								
		$V_{CC} = 0.8 V$	-	46.6	-	-	-	-	ns	
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	2.7	9.2	12.4	2.5	12.7	12.7	ns	
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	2.5	6.3	7.8	2.2	8.2	8.2	ns	
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	2.3	5.0	6.2	2.2	6.7	6.7	ns	
		$V_{CC}$ = 2.3 V to 2.7 V	1.8	4.0	4.7	1.7	5.0	5.1	ns	
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	1.9	3.6	4.2	1.8	4.5	4.5	ns	
C <sub>L</sub> = 15	pF									
$t_{pd}$	propagation delay	X1 to X2; see Figure 7								
		$V_{CC} = 0.8 \text{ V}$	-	28.9	-	-	-	-	ns	
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	1.7	5.2	7.1	1.6	7.2	7.3	ns	
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	1.6	3.6	4.4	1.6	4.7	4.8	ns	
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	1.3	3.0	3.7	1.3	3.9	4.0	ns	
		$V_{CC}$ = 2.3 V to 2.7 V	1.0	2.4	2.9	1.0	3.1	3.1	ns	
		$V_{CC}$ = 3.0 V to 3.6 V	1.1	2.2	2.5	1.0	2.7	2.7	ns	
		X1 to Y; see Figure 8 [2]								
		$V_{CC} = 0.8 \text{ V}$	-	53.9	-	-	-	-	ns	
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	3.1	10.4	14.2	2.8	14.6	14.7	ns	
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	2.9	7.0	8.5	2.7	9.2	9.3	ns	
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	2.5	5.6	6.9	2.3	7.4	7.5	ns	
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	2.1	4.5	5.4	2.0	5.7	5.7	ns	
		$V_{CC}$ = 3.0 V to 3.6 V	2.3	4.1	4.7	2.1	5.1	5.1	ns	

#### Low-power X-tal driver with enable and internal resistor

 Table 8.
 Dynamic characteristics ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 9.

Symbol	Parameter	Conditions		T,	<sub>amb</sub> =25 °	°C	$T_{amb}$ = -40 °C to +125 °C			Unit
				Min Typ[1] Max		Max	Min	Max (85 °C)	Max (125 °C)	
$C_L = 30  \mu$	οF									
$t_{pd}$	propagation delay	X1 to X2; see Figure 7	[2]							
		$V_{CC} = 0.8 V$		-	52.8	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$		2.4	8.5	11.8	2.3	12.2	12.4	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$		2.2	5.6	6.8	2.0	7.5	7.6	ns
		$V_{CC}$ = 1.65 V to 1.95 V		2.0	4.5	5.6	1.9	6.2	6.2	ns
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$		1.5	3.7	4.2	1.4	4.6	4.6	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$		1.7	3.3	3.7	1.6	4.0	4.2	ns
		X1 to Y; see Figure 8	[2]							
		$V_{CC} = 0.8 \text{ V}$		-	77.6	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$		3.7	13.8	19.2	3.3	19.8	20.1	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$		3.4	9.2	11.2	3.1	12.2	12.3	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$		3.4	7.4	8.8	3.1	9.7	9.7	ns
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$		2.6	5.9	6.7	2.4	7.4	7.4	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$		3.2	5.4	6.2	2.9	6.7	6.9	ns
C <sub>L</sub> = 5 pl	F, 10 pF, 15 pF and	30 pF								
$C_{PD}$	power dissipation capacitance	$f_i = 1 \text{ MHz}; \overline{EN} = GND;$ $V_I = GND \text{ to } V_{CC}$	[3][4][5]							
		$V_{CC} = 0.8 \text{ V}$		-	6.8	-	-	-	-	pF
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$		-	12.0	-	-	-	-	pF
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$		-	18.2	-	-	-	-	pF
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$		-	19.2	-	-	-	-	pF
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$		-	21.9	-	-	-	-	pF
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$		-	24.9	-	-	-	-	pF

- [1] All typical values are measured at nominal  $V_{\mbox{\scriptsize CC}}$ .
- [2]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .
- [3] All specified values are the average typical values over all stated loads.
- [4]  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu W$ ).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o) \text{ where:}$ 

 $f_i$  = input frequency in MHz;

f<sub>o</sub> = output frequency in MHz;

C<sub>L</sub> = output load capacitance in pF;

 $V_{CC}$  = supply voltage in V;

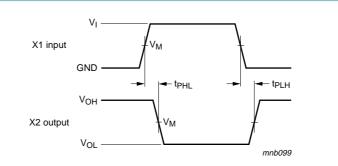
N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_o)$  = sum of the outputs.

[5] Feedback current is included in the C<sub>PD</sub>.

#### Low-power X-tal driver with enable and internal resistor

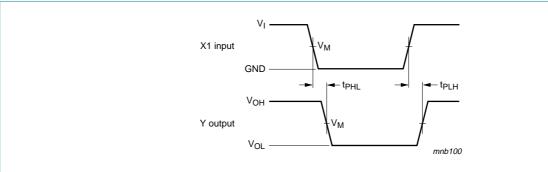
#### 12. Waveforms



Measurement points are given in Table 9.

Logic levels:  $V_{\text{OL}}$  and  $V_{\text{OH}}$  are typical output voltage drop that occur with the output load.

Fig 7. The input (X1) to output (X2) propagation delays



Measurement points are given in Table 9.

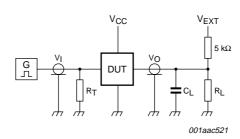
Logic levels:  $V_{\text{OL}}$  and  $V_{\text{OH}}$  are typical output voltage drop that occur with the output load.

Fig 8. The input (X1) to output (Y) propagation delays

Table 9. Measurement points

Supply voltage	Output	Input		
V <sub>CC</sub>	V <sub>M</sub>	V <sub>M</sub>	VI	$t_r = t_f$
0.8 V to 3.6 V	$0.5 \times V_{\text{CC}}$	$0.5 \times V_{\text{CC}}$	V <sub>CC</sub>	≤ 3.0 ns

#### Low-power X-tal driver with enable and internal resistor



Test data is given in Table 10.

Definitions for test circuit:

R<sub>L</sub> = Load resistance.

C<sub>L</sub> = Load capacitance including jig and probe capacitance.

 $R_T$  = Termination resistance should be equal to the output impedance  $Z_o$  of the pulse generator.

 $V_{\text{EXT}}$  = External voltage for measuring switching times.

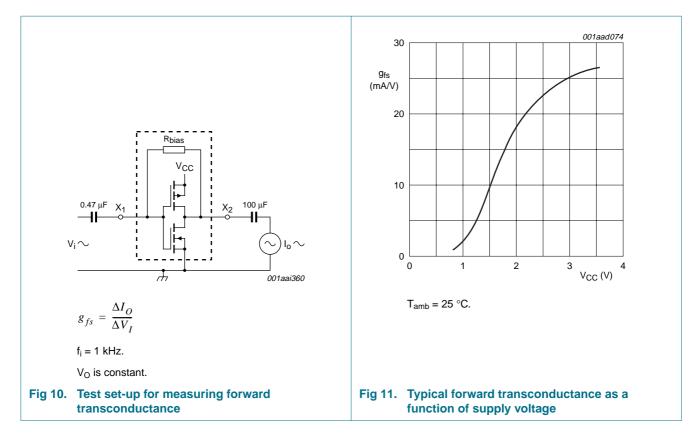
Fig 9. Load circuitry for switching times

#### Table 10. Test data

Supply voltage	Load	V <sub>EXT</sub>			
V <sub>CC</sub>	CL	R <sub>L</sub> [1]	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub>
0.8 V to 3.6 V	5 pF, 10 pF, 15 pF and 30 pF	5 k $\!\Omega$ or 1 M $\!\Omega$	open	GND	$2 \times V_{CC}$

[1] For measuring enable and disable times  $R_L$  = 5  $k\Omega$ , for measuring propagation delays, setup and hold times and pulse width  $R_L$  = 1  $M\Omega$ .

#### Low-power X-tal driver with enable and internal resistor



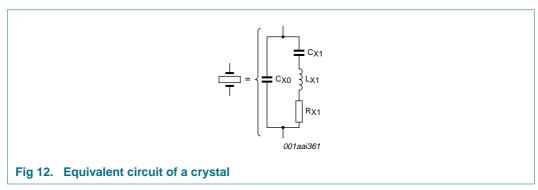
## 13. Application information

Crystal controlled oscillator circuits are widely used in clock pulse generators because of their excellent frequency stability and wide operating frequency range. The use of the 74AUP1Z04 provides the additional advantages of low power dissipation, stable operation over a wide range of frequency and temperature and a very small footprint. This application information describes crystal characteristics, design and testing of crystal oscillator circuits based on the 74AUP1Z04.

#### 13.1 Crystal characteristics

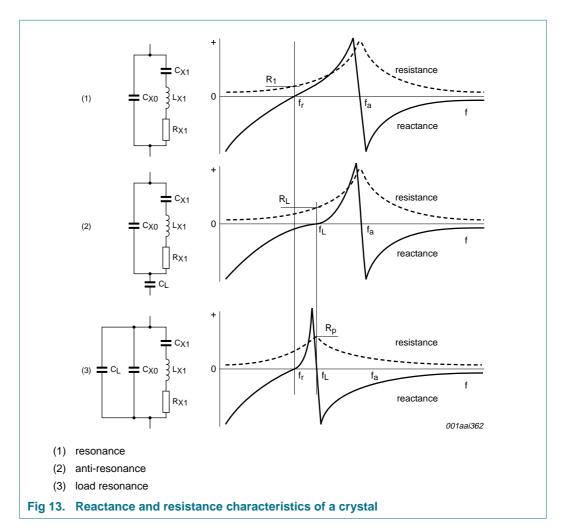
Figure 12 is the equivalent circuit of a quartz crystal.

The reactive and resistive component of the impedance of the crystal alone and the crystal with a series and a parallel capacitance is shown in Figure 13.



74AUP1Z04\_2 © NXP B.V. 2008. All rights reserved.

#### Low-power X-tal driver with enable and internal resistor



#### 13.1.1 **Design**

Figure 14 shows the recommended way to connect a crystal to the 74AUP1Z04. This circuit is basically a Pierce oscillator circuit in which the crystal is operating at its fundamental frequency and is tuned by the parallel load capacitance of  $C_1$  and  $C_2$ .  $C_1$  and  $C_2$  are in series with the crystal. They should be approximately equal.  $R_1$  is the drive-limiting resistor and is set to approximately the same value as the reactance of  $C_1$  at the crystal frequency ( $R_1 = X_{C1}$ ). This will result in an input to the crystal of 50 % of the rail-to-rail output of X2. This keeps the drive level into the crystal within drive specifications (the designer should verify this). Overdriving the crystal can cause damage.

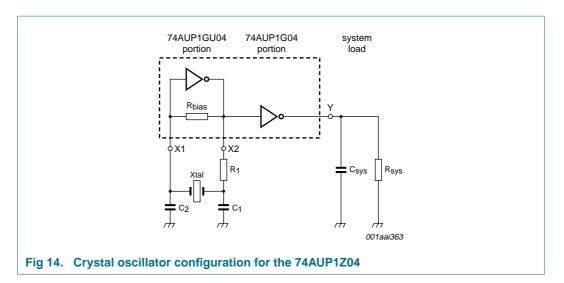
The internal bias resistor provides negative feedback and sets a bias point of the inverter near mid-supply, operating the 74AUP1GU04 portion in the high gain linear region.

To calculate the values of C<sub>1</sub> and C<sub>2</sub>, the designer can use the formula:

$$C_L = \frac{C_1 \times C_2}{C_1 + C_2} + C_s$$

 $C_L$  is the load capacitance as specified by the crystal manufacturer,  $C_s$  is the stray capacitance of the circuit (for the 74AUP1Z04 this is equal to an input capacitance of 1.5 pF).

#### Low-power X-tal driver with enable and internal resistor



#### **13.1.2 Testing**

After the calculations are performed for a particular crystal, the oscillator circuit should be tested. The following simple checks will verify the prototype design of a crystal controlled oscillator circuit. Perform them after laying out the board:

- Test the oscillator over worst-case conditions (lowest supply voltage, worst-case crystal and highest operating temperature). Adding series and parallel resistors can simulate a worst-case crystal.
- Insure that the circuit does not oscillate without the crystal.
- Check the frequency stability over a supply range greater than that which is likely to occur during normal operation.
- Check that the start-up time is within system requirements.

As the 74AUP1Z04 isolates the system loading, once the design is optimized, the single layout may work in multiple applications for any given crystal.

#### Low-power X-tal driver with enable and internal resistor

## 14. Package outline

#### Plastic surface-mounted package; 6 leads

**SOT363** 

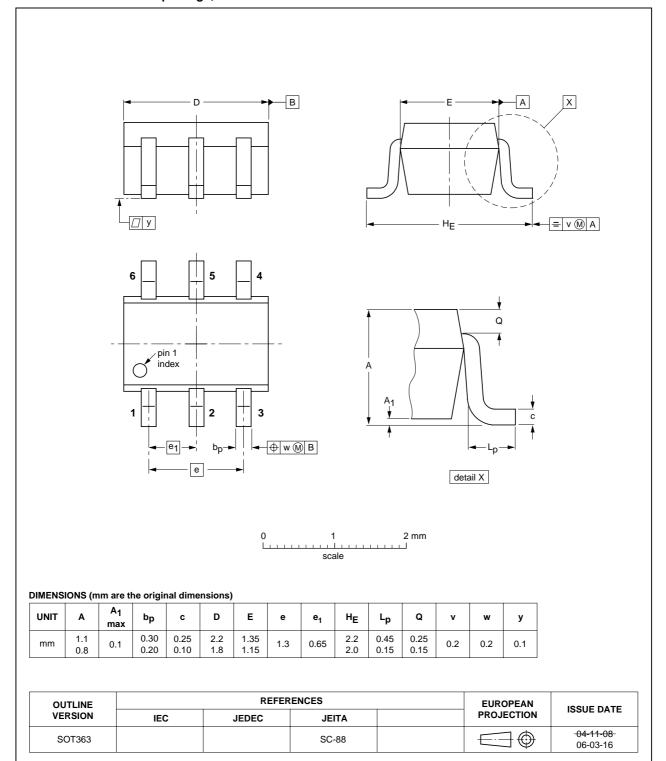


Fig 15. Package outline SOT363 (SC-88)

Low-power X-tal driver with enable and internal resistor

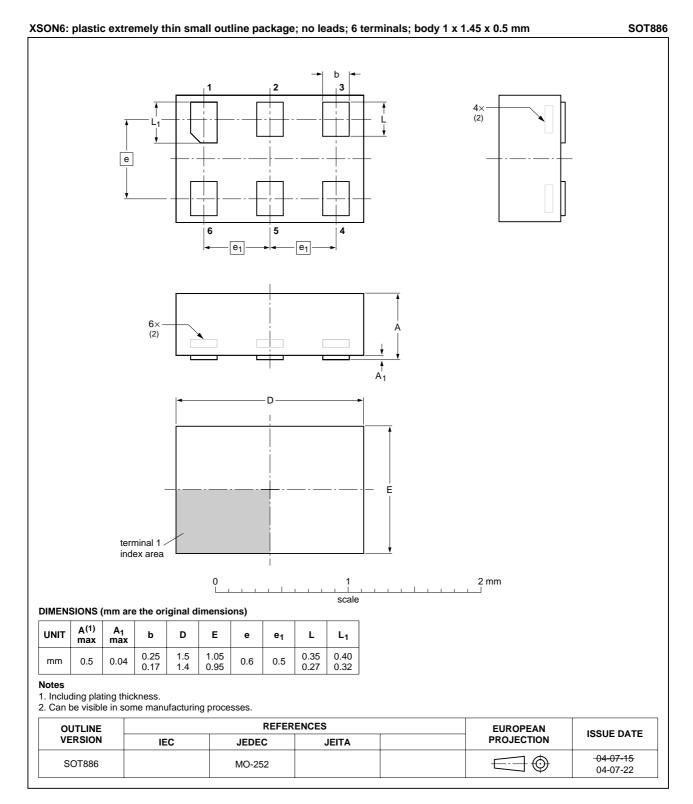


Fig 16. Package outline SOT886 (XSON6)

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Low-power X-tal driver with enable and internal resistor

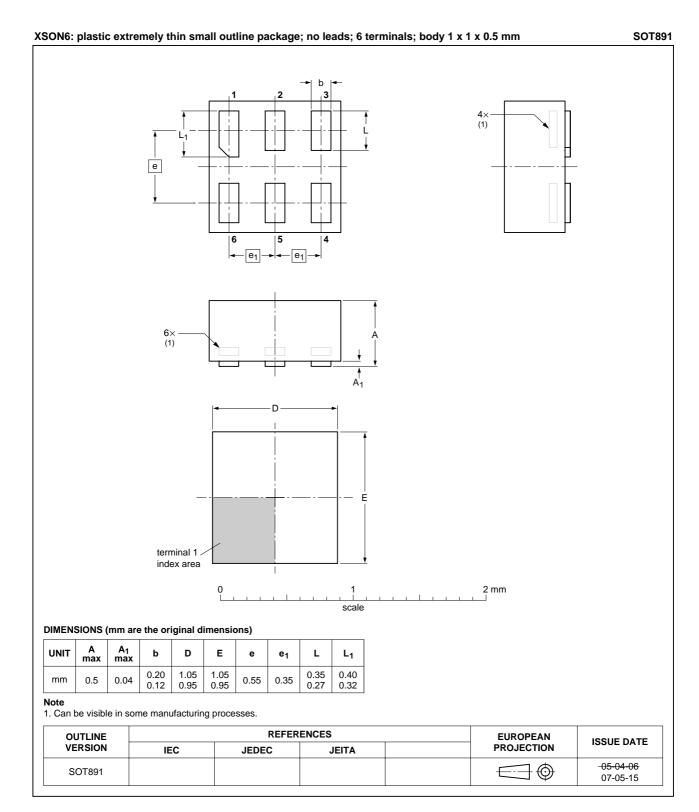


Fig 17. Package outline SOT891 (XSON6)

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## Low-power X-tal driver with enable and internal resistor

## 15. Abbreviations

#### Table 11. Abbreviations

Acronym	Description
CDM	Charged Device Model
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
MM	Machine Model

## 16. Revision history

#### Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes					
74AUP1Z04_2	20080703	Product data sheet	-	74AUP1Z04_1					
Modifications:	<ul> <li>Section 2 "</li> </ul>	Features":							
	Removed:	Removed: Low static power consumption; I <sub>CC</sub> 0.9 μA maximum.							
	Section 10 "Static characteristics":								
	Removed: Feedback current (I <sub>fbck</sub> ).								
	Changed: Maximum supply current (I <sub>CC</sub> ).								
	Added: forward transconductance and bias resistance.								
	Section 11 "Dynamic characteristics":								
	Changed: <sup>-</sup>	Typical power dissipation cap	pacitance.						
74AUP1Z04_1	20061212	Product data sheet	-	-					

#### Low-power X-tal driver with enable and internal resistor

## 17. Legal information

#### 17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <a href="http://www.nxp.com">http://www.nxp.com</a>.

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#### Low-power X-tal driver with enable and internal resistor

#### 19. Contents

1	General description
2	Features
3	Ordering information 2
4	Marking 2
5	Functional diagram 2
6	Pinning information 3
6.1	Pinning
6.2	Pin description
7	Functional description 3
8	Limiting values 4
9	Recommended operating conditions 4
10	Static characteristics 5
11	Dynamic characteristics
12	Waveforms
13	Application information
13.1	Crystal characteristics 17
13.1.1	Design
13.1.2	Testing
14	Package outline
15	Abbreviations
16	Revision history
17	Legal information
17.1	Data sheet status 24
17.2	Definitions
17.3	Disclaimers
17.4	Trademarks24
18	Contact information 24
19	Contents

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