## Data Sheet

## Distinctive Characteristics

## Architectural Advantages

- Single 1.8 volt read, program and erase ( 1.65 to 1.95 volt)
- Manufactured on $0.11 \mu \mathrm{~m}$ process technology
- Simultaneous Read/Write operation
- Data can be continuously read from one bank while executing erase/program functions in other bank
- Zero latency between read and write operations
- Four bank architecture: WS128J: 16Mb/48Mb/48Mb/ $16 \mathrm{Mb}, \mathrm{WS} 064 \mathrm{~J}: 8 \mathrm{Mb} / 24 \mathrm{Mb} / 24 \mathrm{Mb} / 8 \mathrm{Mb}$
■ Programable Burst Interface
- 2 Modes of Burst Read Operation
- Linear Burst: 8, 16, and 32 words with wrap-around
- Continuous Sequential Burst
- Secured Silicon Sector region
- 128 words accessible through a command sequence, 64 words for the Factory Secured Silicon Sector and 64words for the Customer Secured Silicon Sector.
- Sector Architecture

4 Kword x 16 boot sectors, eight at the top of the address range, and eight at the bottom of the address range

- WS128J: 4 Kword X 16, 32 Kword $\times 254$ sectors

Bank A : 4 Kword x 8, 32 Kword x 31 sectors
Bank B : 32 Kword x 96 sectors
Bank C: 32 Kword x 96 sectors
Bank D : 4 Kword x 8, 32 Kword $\times 31$ sectors

- WS064J: 4 Kword $\times 16,32$ Kword $\times 126$ sectors.

Bank A : 4 Kword x 8, 32 Kword x 15 sectors
Bank B: 32 Kword $x 48$ sectors
Bank C: 32 Kword $x 48$ sectors
Bank D : 4 Kword x 8, 32 Kword x 15 sectors

■ WS128J : 84-ball ( $8 \mathrm{~mm} \times 11.6 \mathrm{~mm}$ ) FBGA package, WS064J : 80-ball ( $7 \mathrm{~mm} \times 9 \mathrm{~mm}$ ) FBGA package
■ Cyclling Endurance : 1,000,000 cycles per sector typical
■ Data retention : 20-years typical

## Performance Characteristics

■ Read access times at $\mathbf{8 0 / 6 6} \mathbf{~ M H z}$

- Synchronous latency of $71 / 56 \mathrm{~ns}$ (at 30 pF )
- Asynchronous random access times of $55 / 55 \mathrm{~ns}$ (at 30 pF )
- Power dissipation (typical values, $\mathrm{C}_{\mathrm{L}}=\mathbf{3 0} \mathbf{~ p F}$ )
- Burst Mode Read: $18 \mathrm{~mA} @ 80 \mathrm{Mhz}$
- Simultaneous Operation: 60 mA @ 80Mhz
- Program/Erase: 15 mA
- Standby mode: $0.2 \mu \mathrm{~A}$


## Hardware Features

- Handshaking feature available
- Provides host system with minimum possible latency by monitoring RDY
- Hardware reset input (RESET\#)
- Hardware method to reset the device for reading array data
- WP\# input
- Write protect (WP\#) function allows protection of four outermost boot sectors, regardless of sector protect status
- Persistent Sector Protection
- A command sector protection method to lock combinations of individual sectors and sector groups to prevent program or erase operations within that sector
- Sectors can be locked and unlocked in-system at $\mathrm{V}_{\mathrm{CC}}$ level
- Password Sector Protection
- A sophisticated sector protection method to lock combinations of individual sectors and sector groups to prevent program or erase operations within that sector using a user-defined 64-bit password
- ACC input: Acceleration function reduces programming time; all sectors locked when ACC = $V_{\text {IL }}$
- CMOS compatible inputs, CMOS compatible outputs
- Low $V_{\text {cc }}$ write inhibit


## Software Features

- Supports Common Flash Memory Interface (CFI)
- Software command set compatible with JEDEC 42.4 standards
- Backwards compatible with Am29BDS, Am29BDD, Am29BL, and MBM29BS families
- Data\# Polling and toggle bits
- Provides a software method of detecting program and erase operation completion
- Erase Suspend/Resume
- Suspends an erase operation to read data from, or program data to, a sector that is not being erased, then resumes the erase operation


## - Unlock Bypass Program command

- Reduces overall programming time when issuing multiple program command sequences


## General Description

The S29WS128J/064J/S29WS064J is a $128 / 64$ Mbit, 1.8 Volt-only, simultaneous Read/Write, Burst Mode Flash memory device, organized as $8,388,608 / 4,194,304$ words of 16 bits each. This device uses a single $\mathrm{V}_{\mathrm{CC}}$ of 1.65 to 1.95 V to read, program, and erase the memory array. A 12.0volt $\mathrm{V}_{\mathrm{HH}}$ on ACC may be used for faster program performance if desired. The device can also be programmed in standard EPROM programmers.

At 80 MHz , the device provides a burst access of 9.1 ns at 30 pF with a latency of 46 ns at 30 pF . At 66 MHz , the device provides a burst access of 11.2 ns at 30 pF with a latency of 56 ns at 30 pF . The device operates within the wireless temperature range of $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, and is offered in Various FBGA packages

The Simultaneous Read/Write architecture provides simultaneous operation by dividing the memory space into four banks. The device can improve overall system performance by allowing a host system to program or erase in one bank, then immediately and simultaneously read from another bank, with zero latency. This releases the system from waiting for the completion of program or erase operations.

The device is divided as shown in the following table:

| Bank | Quantity |  | Size |
| :---: | :---: | :---: | :---: |
|  | $\mathbf{1 2 8 M b}$ | $\mathbf{6 4} \mathbf{~ M b}$ |  |
| A | 8 | 8 | 32 Kwords |
|  | 31 | 15 | 32 Kwords |
| B | 96 | 48 | 32 Kwords |
| C | 96 | 48 | 32 Kwords |
| D | 31 | 15 | 4 Kwords |
|  | 8 | 8 |  |

The device uses Chip Enable (CE\#), Write Enable (WE\#), Address Valid (AVD\#) and Output Enable (OE\#) to control asynchronous read and write operations. For burst operations, the device additionally requires Ready (RDY), and Clock (CLK). This implementation allows easy interface with minimal glue logic to a wide range of microprocessors/microcontrollers for high performance read operations.

The burst read mode feature gives system designers flexibility in the interface to the device. The user can preset the burst length and wrap through the same memory space, or read the flash array in continuous mode.

The clock polarity feature provides system designers a choice of active clock edges, either rising or falling. The active clock edge initiates burst accesses and determines when data will be output.

The device is entirely command set compatible with the JEDEC 42.4 single-power-supply Flash standard. Commands are written to the command register using standard microprocessor write timing. Register contents serve as inputs to an internal state-machine that controls the erase and programming circuitry. Write cycles also internally latch addresses and data needed for the programming and erase operations. Reading data out of the device is similar to reading from other Flash or EPROM devices.

The Erase Suspend/Erase Resume feature enables the user to put erase or program on hold for any period of time to read data from, or program data to, any sector that is not selected for erasure. True background erase can thus be achieved. If a read is needed from the Secured Silicon Sector area (One Time Program area) after an erase suspend, then the user must use the proper command sequence to enter and exit this region. Program suspend is also offered.

The hardware RESET\# pin terminates any operation in progress and resets the internal state machine to reading array data. The RESET\# pin may be tied to the system reset circuitry. A system reset would thus also reset the device, enabling the system microprocessor to read boot-up firmware from the Flash memory device.

The host system can detect whether a program or erase operation is complete by using the device status bit DQ7 (Data\# Polling) and DQ6/DQ2 (toggle bits). After a program or erase cycle has been completed, the device automatically returns to reading array data.
The sector erase architecture allows memory sectors to be erased and reprogrammed without affecting the data contents of other sectors. The device is fully erased when shipped from the factory.

Hardware data protection measures include a low $\mathrm{V}_{\mathrm{CC}}$ detector that automatically inhibits write operations during power transitions. The device also offers two types of data protection at the sector level. When at $\mathrm{V}_{\mathrm{IL}}$, WP\# locks the four outermost boot sectors.
The device offers two power-saving features. When addresses have been stable for a specified amount of time, the device enters the automatic sleep mode. The system can also place the device into the standby mode. Power consumption is greatly reduced in both modes.
Spansion ${ }^{\text {TM }}$ Flash memory products combine years of Flash memory manufacturing experience to produce the highest levels of quality, reliability and cost effectiveness. The device electrically erases all bits within a sector simultaneously via Fowler-Nordheim tunnelling. The data is programmed using hot electron injection.

## Table of Contents

Notice On Data Sheet Designations ..... ii
Advance Information ..... ii
Preliminary ..... ii
Combination ..... ii
Full Production (No Designation on Document) ..... ii
Product Selector Guide ..... 6
Block Diagram ..... 6
Block Diagram of Simultaneous Operation Circuit 7Connection Diagram 8
Special Handling Instructions for FBGA Package .....  8
Connection Diagram ..... 9
Input/Output Descriptions ..... 10
Logic Symbol ..... II
Ordering Information ..... 12
128 Mb Products based on 110 nm Floating Gate Technology .....  13
64 Mb Products based on 110 nm Floating Gate Technology .....  13
Device Bus Operations .....  14
Table 1. Device Bus Operations ..... 14
Requirements for Asynchronous ReadOperation (Non-Burst) ..... 14
Requirements for Synchronous (Burst) Read Operation ..... 14
8-, 16-, and 32-Word Linear Burst with Wrap Around ..... 15
Table 2. Burst Address Groups ..... 15
Configuration Register ..... 16
Handshaking ..... 16
Simultaneous Read/Write Operations with Zero Latency ..... 16
Writing Commands/Command Sequences ..... 16
Accelerated Program Operation .....  17
Autoselect Mode .....  .17
Table 3. Autoselect Codes (High Voltage Method) ..... 18
Sector/Sector Block Protection and Unprotection .....  18
Table 4. S29WS128J/064J Boot Sector/Sector Block Addresses forProtection/Unprotection18
Table 5. S29WS064J Boot Sector/Sector Block Addresses for Protection/Unprotection ..... 21
Advanced Sector Protection/Unprotection ..... 23
Figure 1. Advanced Sector Protection/Unprotection. ..... 23
Lock Register ..... 24
Table 6. Lock Register ..... 24
Persistent Protection Bits ..... 24
Figure 2. PPB Program/Erase Algorithm ..... 26
Dynamic Protection Bits ..... 26
Persistent Protection Bit Lock Bit .....  27
Password Protection Method .....  27
Figure 3. Lock Register Program Algorithm ..... 28
Advanced Sector Protection Software Examples ..... 29
Table 7. Sector Protection Schemes ..... 29
Hardware Data Protection Methods ..... 29
WP\# Method ..... 29
ACC Method ..... 29
Low $\mathrm{V}_{\mathrm{CC}}$ Write Inhibit ..... 29
Write Pulse "Glitch Protection" ..... 30
Power-Up Write Inhibit ..... 30
Common Flash Memory Interface (CFI) ..... 30
Table 8. CFI Query Identification String ..... 30
Table 9. System Interface String ..... 31
Table 10. Device Geometry Definition ..... 31
Table 11. Primary Vendor-Specific Extended Query ..... 32
Table 12. WS128J Sector Address Table ..... 33
Table 13. WS064J Sector Address Table ..... 41
Command Definitions ..... 46
Reading Array Data ..... 46
Set Configuration Register Command Sequence ..... 47
Figure 4. Synchronous/Asynchronous State Diagram ..... 48
Read Mode Setting ..... 48
Programmable Wait State Configuration ..... 48
Table 14. Programmable Wait State Settings ..... 49
Standard wait-state Handshaking Option ..... 49
Table 15. Wait States for Standard wait-state Handshaking ..... 49
Read Mode Configuration ..... 50
Table 16. Read Mode Settings ..... 50
Burst Active Clock Edge Configuration .....  50
RDY Configuration ..... 50
Configuration Register ..... 50
Table 17. Configuration Register ..... 51
Reset Command .....  51
Autoselect Command Sequence ..... 51
Enter Secured Silicon Sector/Exit Secured Silicon Sector Command Se- quence ..... 52
Program Command Sequence .....  53
Unlock Bypass Command Sequence .....  .53
Figure 5. Program Operation ..... 54
Chip Erase Command Sequence .....  54
Sector Erase Command Sequence ..... 55
Erase Suspend/Erase Resume Commands ..... 55
Figure 6. Erase Operation ..... 56
Password Program Command ..... 57
Password Verify Command ..... 57
Password Protection Mode Locking Bit Program Command ..... 57
Persistent Sector Protection Mode Locking Bit Program Command 57
Secured Silicon Sector Protection Bit Program Command ..... 58
PPB Lock Bit Set Command ..... 58
DPB Write/Erase/Status Command ..... 58
Password Unlock Command ..... 58
PPB Program Command .....  59
All PPB Erase Command ..... 59
PPB Status Command ..... 59
PPB Lock Bit Status Command ..... 59
Command Definitions ..... 60
Table 18. Command Definitions ..... 60
Write Operation Status ..... 62
DQ7: Data\# Polling ..... 62
Figure 7. Data\# Polling Algorithm ..... 63
RDY: Ready ..... 63
DQ6: Toggle Bit I ..... 64
Figure 8. Toggle Bit Algorithm ..... 65
DQ2: Toggle Bit II .....  .65
Table 19. DQ6 and DQ2 Indications ..... 66
Reading Toggle Bits DQ6/DQ2 ..... 66
DQ5: Exceeded Timing Limits .....  .66
DQ3: Sector Erase Timer ..... 67
Table 20. Write Operation Status ..... 67
Absolute Maximum Ratings ..... 68
Figure 9. Maximum Negative Overshoot Waveform. ..... 68
Figure 10. Maximum Positive Overshoot Waveform ..... 68
Operating Ranges ..... 69
Commercial (C) Devices ..... 69
Wireless (W) Devices .....  69
Supply Voltages ..... 69
DC Characteristics ..... 70
Test Conditions ..... 71
Figure 11. Test Setup ..... 71
Table 21. Test Specifications ..... 71
Key to Switching Waveforms ..... 71
Switching Waveforms ..... 71
Figure 12. Input Waveforms and Measurement Levels ..... 71
AC Characteristics ..... 72
$V_{\text {cc }}$ Power-up .....  72
Figure 13. $\mathrm{V}_{\mathrm{CC}}$ Power-up Diagram ..... 72
CLK Characterization .....  .72
Figure 14. CLK Characterization ..... 72
Synchronous/Burst Read .....  73
Figure 15. CLK Synchronous Burst Mode Read (rising active CLK).74
Figure 16. CLK Synchronous Burst Mode Read (Falling Active Clock)75
Figure 17. Synchronous Burst Mode Read ..... 75
Figure 18. 8-word Linear Burst with Wrap Around ..... 76
Figure 19. Linear Burst with RDY Set One Cycle Before Data... ..... 76
Asynchronous Mode Read .....  77
Figure 20. Asynchronous Mode Read with Latched Addresses. ..... 77
Figure 21. Asynchronous Mode Read ..... 78
Hardware Reset (RESET\#) ..... 78
Figure 22. Reset Timings ..... 79
Erase/Program Operations ..... 80
Figure 23. Asynchronous Program Operation Timings: AVD\# Latched Addresses ..... 81
Figure 24. Asynchronous Program Operation Timings: WE\# Latched
Addresses .....  82
Figure 25. Synchronous Program Operation Timings: WE\# Latched
Addresses ..... 83
Figure 26. Synchronous Program Operation Timings: CLK LatchedAddresses84
Figure 27. Chip/Sector Erase Command Sequence ..... 85
Figure 28. Accelerated Unlock Bypass Programming Timing. ... ..... 86
Figure 29. Data\# Polling Timings (During Embedded Algorithm) 86
Figure 30. Toggle Bit Timings (During Embedded Algorithm) ... 87
Figure 31. Synchronous Data Poling Timings/Toggle Bit Timings 87Figure 32. DQ2 vs. DQ688
Temporary Sector Unprotect ..... 88
Figure 33. Temporary Sector Unprotect Timing Diagram ..... 88
Figure 34. Sector/Sector Block Protect and Unprotect Timing Diagram ..... 89
Figure 35. Latency with Boundary Crossing ..... 89
Figure 36. Latency with Boundary Crossing into Program/Erase Bank
Figure 37. Example of Wait States Insertion90
Figure 38. Back-to-Back Read/Write Cycle Timings1
Erase and Programming Performance ..... 93
Physical Dimensions ..... 94
VBH084-84-ball Fine-Pitch Ball Grid Array (FBGA) 8xll. 6 mm MCPCompatible Package (I28Mb)94
VBR080-80-ball Fine-Pitch Ball Grid Array (FBGA) $7 \times 9 \mathrm{~mm}$ (64Mb)95
Revision Summary ..... 96
Revision A0 (July 22, 2004) ..... 96
Revision Al (October 6, 2004) ..... 96
Revision A2 (December 10, 2004) ..... 96
Revision A3 (February 19, 2005) ..... 96
Revision A4 (June 24, 2005) ..... 96
Revision A5 (March 31, 2006) ..... 96
Revision A6 (April 28, 2006) ..... 97

## Product Selector Guide

| Synchronous/Burst |  |  | Asynchronous |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Speed Option | 66 MHz | $\mathbf{8 0} \mathrm{MHz}$ <br> (Note) | Speed Option | 66 MHz | 80 MHz <br> (Note) |
| Max Latency, ns ( $\mathrm{t}_{\text {IACC }}$ ) | 56 | 71 | Max Access Time, ns ( $\mathrm{t}_{\text {ACC }}$ ) | 55 | 55 |
| Max Burst Access Time, ns ( $\mathrm{t}_{\mathrm{BACC}}$ ) | 11.2 | 9.1 | Max CE\# Access, ns ( $\mathrm{t}_{\text {CE }}$ ) | 55 | 55 |
| Max OE\# Access, ns ( $\mathrm{t}_{\mathrm{OE}}$ ) | 11.2 | 9.1 | Max OE\# Access, ns ( $\mathrm{t}_{\mathrm{OE}}$ ) | 11.2 | 9.1 |

Note: 80 MHz option is available for S29WS064J only.

## Block Diagram



## Block Diagram of Simultaneous Operation Circuit



Note: Amax: WS064J (A21), WS128J (A22)

## Connection Diagram

S29WS064J
80-ball Fine-Pitch Ball Grid Array
(Top View, Balls Facing Down)


## Special Handling Instructions for FBGA Package

Special handling is required for Flash Memory products in FBGA packages.
Flash memory devices in FBGA packages may be damaged if exposed to ultrasonic cleaning methods. The package and/or data integrity may be compromised if the package body is exposed to temperatures above $150^{\circ} \mathrm{C}$ for prolonged periods of time.

## Connection Diagram

S29WS128J-MCP Compatible 84-ball Fine-Pitch Ball Grid Array
(Top View, Balls Facing Down)


## Input/Output Descriptions

| Amax-A0 | = | Address inputs |
| :---: | :---: | :---: |
| DQ15-DQ0 | = | Data input/output |
| CE\# | = | Chip Enable input. Asynchronous relative to CLK for the Burst mode. |
| OE\# | = | Output Enable input. Asynchronous relative to CLK for the Burst mode. |
| WE\# | = | Write Enable input. |
| $\mathrm{V}_{\mathrm{CC}}$ | = | Device Power Supply $(1.65-1.95 \mathrm{~V}) .$ |
| $\mathrm{V}_{\text {SS }}$ | = | Ground |
| NC | = | No Connect; not connected internally |
| RDY | = | Ready output; |
|  |  | In Synchronous Mode, indicates the status of the Burst read. |
|  |  | Low $=$ data not valid at expected time. High = data valid. |
|  |  | In Asynchronous Mode, indicates the status of the internal program and erase function. |
|  |  | Low = program/erase in progress. |
|  |  | High Impedance = program/erase completed. |
| CLK | = | CLK is not required in asynchronous mode. In burst mode, after the initial word is output, subsequent active edges of CLK increment the internal address counter. |
| AVD\# | = | Address Valid input. Indicates to device that the valid address is present on the address inputs (Amax-A0). |
|  |  | Low = for asynchronous mode, indicates valid address; for burst mode, causes starting address to be latched. |
|  |  | High = device ignores address inputs |
| RESET\# | $=$ | Hardware reset input. Low = device resets and returns to reading array data |
| WP\# | $=$ | Hardware write protect input. At $\mathrm{V}_{\mathrm{IL}}$, disables program and erase functions in the four outermost sectors. Should be at $\mathrm{V}_{\mathrm{IH}}$ for all other conditions. |
| ACC | $=$ | At $\mathrm{V}_{\mathrm{HH}}$, accelerates programming; automatically places device in unlock bypass mode. At $\mathrm{V}_{\mathrm{IL}}$, locks all sectors. Should be at $\mathrm{V}_{\mathrm{IH}}$ for all other conditions. |

## Note:

1. $A m a x=$ A22 (WS128J), A21 (WS064J).

## Logic Symbol


*Max = 22 for the WS128J and 21 for the WS064J.

## Ordering Information

The order number (Valid Combination) is formed by the following:


128 Mb Products based on 110 nm Floating Gate Technology

| Valid Combinations for FBGA Packages | Package Marking | Temperature | Burst Speed | Boot Protect | Package Material Set | Package Type |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| S29WS128JOPBAW00 | WS128JOPBAW00 | $\left(-25-+85^{\circ} \mathrm{C}\right)$ | 66 MHz | Dual | Lead (Pb)Free Compliant Package | 84 - ball <br> $8 \mathrm{~mm} \times 11.6 \mathrm{~mm}$ <br> MCP Compatible |
| S29WS128JOPBAW01 | WS128J0PBAW01 |  |  | None |  |  |
| S29WS128JOPBAW10 | WS128JOPBAW10 |  |  | Dual |  |  |
| S29WS128JOPBAW11 | WS128JOPBAW11 |  |  | None |  |  |
| S29WS128JOPBAI10 | WS128JOPBAI10 | $\left(-40-+85{ }^{\circ} \mathrm{C}\right)$ |  | Dual |  |  |
| S29WS128JOPBAI11 | WS128JOPBAI11 |  |  | None |  |  |
| S29WS128JOPBFW00 | WS128J0PBFW00 | $\left(-25-+85{ }^{\circ} \mathrm{C}\right)$ |  | Dual | Standard <br> Lead (Pb)- <br> Free Package |  |
| S29WS128JOPBFW01 | WS128JOPBFW01 |  |  | None |  |  |
| S29WS128JOPBFW10 | WS128JOPBFW10 |  |  | Dual |  |  |
| S29WS128JOPBFW11 | WS128J0PBFW11 |  |  | None |  |  |
| S29WS128JOPBFI10 | WS128JOPBFI10 | $\left(-40-+85{ }^{\circ} \mathrm{C}\right)$ |  | Dual |  |  |
| S29WS128JOPBFI11 | WS128J0PBFI11 |  |  | None |  |  |

64 Mb Products based on 110 nm Floating Gate Technology

| Valid Combinations for <br> FBGA Packages | Package Marking | Temperature | Burst <br> Speed | Boot <br> Protect | Package <br> Material Set | Package Type |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

## Valid Combinations

Valid Combination configuration planned to be supported for this device.

## Notes:

1.80 MHz operation has a different $\mathrm{Vcc}(+1.70 \mathrm{~V}$ to 1.95 V$)$.

## Device Bus Operations

This section describes the requirements and use of the device bus operations, which are initiated through the internal command register. The command register itself does not occupy any addressable memory location. The register is composed of latches that store the commands, along with the address and data information needed to execute the command. The contents of the register serve as inputs to the internal state machine. The state machine outputs dictate the function of the device. Table 1 lists the device bus operations, the inputs and control levels they require, and the resulting output. The following subsections describe each of these operations in further detail.

Table I. Device Bus Operations

| Operation | CE\# | OE\# | WE\# | A22-0 | DQ15-0 | RESET\# | $\begin{gathered} \text { CLK } \\ \text { (See Note) } \end{gathered}$ | AVD\# |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Asynchronous Read - Addresses Latched | L | L | H | Addr In | I/O | H | X | 7 |
| Asynchronous Read - Addresses Steady State | L | L | H | Addr In | I/O | H | X | L |
| Asynchronous Write | L | H | L | Addr In | I/O | H | X | L |
| Synchronous Write | L | H | L | Addr In | I/O | H | 75 | 75 |
| Standby (CE\#) | H | X | X | HIGH Z | HIGH Z | H | X | X |
| Hardware Reset | X | X | X | HIGH Z | HIGH Z | L | X | X |
| Burst Read Operations |  |  |  |  |  |  |  |  |
| Load Starting Burst Address | L | X | H | Addr In | X | H | 5 | $\square$ |
| Advance Burst to next address with appropriate Data presented on the Data Bus | L | L | H | HIGH Z | Burst Data Out | H | $\uparrow$ | H |
| Terminate current Burst read cycle | H | X | H | HIGH Z | HIGH Z | H | $\Psi$ | X |
| Terminate current Burst read cycle via RESET\# | X | X | H | HIGH Z | HIGH Z | L | X | X |
| Terminate current Burst read cycle and start new Burst read cycle | L | X | H | HIGH Z | I/O | H | $\Psi$ | $\square$ |

Legend: $L=$ Logic $0, H=$ Logic 1, $X=$ Don't Care
Note: Default active edge of CLK is the rising edge.

## Requirements for Asynchronous ReadOperation (Non-Burst)

To read data from the memory array, the system must first assert a valid address on Amax-A0(A22-A0 for WS128J and A21-A0 for WS064J), while driving AVD\# and CE\# to $\mathrm{V}_{\mathrm{IL}}$. WE\# should remain at $\mathrm{V}_{\mathrm{IH}}$. The rising edge of AVD\# latches the address. The data will appear on DQ15-DQ0. Since the memory array is divided into four banks, each bank remains enabled for read access until the command register contents are altered.
Address access time ( $\mathrm{t}_{\mathrm{ACC}}$ ) is equal to the delay from stable addresses to valid output data. The chip enable access time ( $\mathrm{t}_{\mathrm{CE}}$ ) is the delay from the stable addresses and stable CE\# to valid data at the outputs. The output enable access time ( $\mathrm{t}_{\mathrm{OE}}$ ) is the delay from the falling edge of OE\# to valid data at the output.

The internal state machine is set for reading array data in asynchronous mode upon device power-up, or after a hardware reset. This ensures that no spurious alteration of the memory content occurs during the power transition.

## Requirements for Synchronous (Burst) Read Operation

The device is capable of continuous sequential burst operation and linear burst operation of a preset length. When the device first powers up, it is enabled for asynchronous read operation.

Prior to entering burst mode, the system should determine how many wait states are desired for the initial word ( $\mathrm{t}_{\mathrm{IACC}}$ ) of each burst access, what mode of burst operation is desired, which edge of the clock will be the active clock edge, and how the RDY signal will transition with valid data. The system would then write the configuration register command sequence. See "Set Configuration Register Command Sequence" section on page 47 and "Command Definitions" section on page 46 for further details.

Once the system has written the "Set Configuration Register" command sequence, the device is enabled for synchronous reads only.
The initial word is output $\mathrm{t}_{\text {IACC }}$ after the active edge of the first CLK cycle. Subsequent words are output $t_{\text {BACC }}$ after the active edge of each successive clock cycle, which automatically increments the internal address counter. Note that the device has a fixed internal address boundary that occurs every 64 words, starting at address 00003Fh.

During the time the device is outputting data at this fixed internal address boundary (address $00003 \mathrm{Fh}, 00007 \mathrm{Fh}, 0000 \mathrm{BFh}$, etc.), a two cycle latency (WS128J/064J model numbers 00 and 01) or a three cycle latency (WS128J model numbers 10 and 11) occurs before data appears for the next address (address 000040h, 000080h, 0000C0h, etc.).
Additionally, when the device is read from an odd address, one wait state is inserted when the address pointer crosses the first boundary that occurs every 16 words. For instance, if the device is read from $000011 \mathrm{~h}, 000013 \mathrm{~h}, \ldots, 00001 \mathrm{Fh}$ (odd), one wait state is inserted before the data of 000020h is output. This wait is inserted only at the boundary of the first 16 words. Then, if the device is read from the odd address within the last 16 words of 64 word boundary (address $000031 \mathrm{~h}, 000033 \mathrm{~h}, \ldots, 00003 \mathrm{Fh}$ ), a three-cycle latency occurs before data appears for the next address (address 000040h). During the boundary crossing condition, the system must assert an additional wait state for WS128J model numbers 10 and 11.

The RDY output indicates this condition to the system by pulsing deactive (low). See Figure 35, "Latency with Boundary Crossing," on page 89.

The device will continue to output sequential burst data, wrapping around to address 000000h after it reaches the highest addressable memory location, until the system drives CE\# high, RESET\# low, or AVD\# low in conjunction with a new address. See Table 1, "Device Bus Operations," on page 14.

If the host system crosses the bank boundary while reading in burst mode, and the device is not programming or erasing, a two-cycle latency will occur as described above in the subsequent bank. If the host system crosses the bank boundary while the device is programming or erasing, the device will provide read status information. The clock will be ignored. After the host has completed status reads, or the device has completed the program or erase operation, the host can restart a burst operation using a new address and AVD\# pulse.

## 8-, 16-, and 32-Word Linear Burst with Wrap Around

The remaining three burst read modes are of the linear wrap around design, in which a fixed number of words are read from consecutive addresses. In each of these modes, the burst addresses read are determined by the group within which the starting address falls. The groups are sized according to the number of words read in a single burst sequence for a given mode (see Table 2.)

Table 2. Burst Address Groups

| Mode | Group Size | Group Address Ranges |
| :---: | :---: | :--- |
| 8 -word | 8 words | $0-7 h, 8-F h, 10-17 h, \ldots$ |
| 16 -word | 16 words | $0-$ Fh, 10-1Fh, 20-2Fh,... |
| 32 -word | 32 words | $00-1 F h, 20-3 F h, 40-5 F h, \ldots$ |


#### Abstract

As an example: if the starting address in the 8 -word mode is 39 h , the address range to be read would be $38-3 \mathrm{Fh}$, and the burst sequence would be $39-3 \mathrm{~A}-3 \mathrm{~B}-3 \mathrm{C}-3 \mathrm{D}-3 \mathrm{E}-3 \mathrm{~F}-38 \mathrm{~h}-\mathrm{etc}$. The burst sequence begins with the starting address written to the device, but wraps back to the first address in the selected group. In a similar fashion, the 16 -word and 32 -word Linear Wrap modes begin their burst sequence on the starting address written to the device, and then wrap back to the first address in the selected address group. Note that in these three burst read modes the address pointer does not cross the boundary that occurs every 128 or 64 words; thus, no wait states are inserted (except during the initial access).


The RDY pin indicates when data is valid on the bus.

## Configuration Register

The device uses a configuration register to set the various burst parameters: number of wait states, burst read mode, active clock edge, RDY configuration, and synchronous mode active.

## Handshaking

The device is equipped with a handshaking feature that allows the host system to simply monitor the RDY signal from the device to determine when the initial word of burst data is ready to be read. The host system should use the programmable wait state configuration to set the number of wait states for optimal burst mode operation. The initial word of burst data is indicated by the active edge of RDY after OE\# goes low.

For optimal burst mode performance, the host system must set the appropriate number of wait states in the flash device depending on clock frequency. See "Set Configuration Register Command Sequence" section on page 47 for more information.

## Simultaneous Read/Write Operations with Zero Latency

This device is capable of reading data from one bank of memory while programming or erasing in another bank of memory. An erase operation may also be suspended to read from or program to another location within the same bank (except the sector being erased). Figure 38, "Back-toBack Read/Write Cycle Timings," on page 92 shows how read and write cycles may be initiated for simultaneous operation with zero latency. Refer to the DC Characteristics table for read-whileprogram and read-while-erase current specifications.

## Writing Commands/Command Sequences

The device has the capability of performing an asynchronous or synchronous write operation. While the device is configured in Asynchronous read mode, it is able to perform Asynchronous write operations only. CLK is ignored in the Asynchronous programming mode. When in the Synchronous read mode configuration, the device is able to perform both Asynchronous and Synchronous write operations. CLK and WE\# address latch is supported in the Synchronous programming mode. During a synchronous write operation, to write a command or command sequence (which includes programming data to the device and erasing sectors of memory), the system must drive AVD\# and CE\# to $\mathrm{V}_{\mathrm{IL}}$, and $\mathrm{OE} \#$ to $\mathrm{V}_{\mathrm{IH}}$ when providing an address to the device, and drive WE\# and CE\# to $\mathrm{V}_{\mathrm{IL}}$, and $\mathrm{OE} \#$ to $\mathrm{V}_{\mathrm{IH}}$. when writing commands or data. During an asynchronous write operation, the system must drive CE\# and WE\# to $\mathrm{V}_{\mathrm{IL}}$ and $\mathrm{OE} \#$ to $\mathrm{V}_{\mathrm{IH}}$ when providing an address, command, and data. Addresses are latched on the last falling edge of WE\# or CE\#, while data is latched on the 1st rising edge of WE\# or CE\#. The asynchronous and synchronous programing operation is independent of the Set Device Read Mode bit in the Configuration Register (see Table 17, "Configuration Register," on page 51).
The device features an Unlock Bypass mode to facilitate faster programming. Once the device enters the Unlock Bypass mode, only two write cycles are required to program a word, instead of four.

An erase operation can erase one sector, multiple sectors, or the entire device. Table 12, "WS128J Sector Address Table," on page 33 and Table 13, "WS064J Sector Address Table," on page 41 indicate the address space that each sector occupies. The device address space is divided into four banks. A "bank address" is the address bits required to uniquely select a bank. Similarly, a "sector address" is the address bits required to uniquely select a sector.
$I_{C C 2}$ in the "DC Characteristics" section on page 70 represents the active current specification for the write mode. The AC Characteristics section contains timing specification tables and timing diagrams for write operations.

## Accelerated Program Operation

The device offers accelerated program operations through the ACC function. ACC is primarily intended to allow faster manufacturing throughput at the factory.

If the system asserts $\mathrm{V}_{\mathrm{HH}}$ on this input, the device automatically enters the aforementioned Unlock Bypass mode and uses the higher voltage on the input to reduce the time required for program operations. The system would use a two-cycle program command sequence as required by the Unlock Bypass mode. Removing $\mathrm{V}_{\mathrm{HH}}$ from the ACC input returns the device to normal operation. Note that sectors must be unlocked prior to raising ACC to $\mathrm{V}_{\mathrm{HH}}$. Note that the ACC pin must not be at $V_{H H}$ for operations other than accelerated programming, or device damage may result. In addition, the ACC pin must not be left floating or unconnected; inconsistent behavior of the device may result.
When at $\mathrm{V}_{\mathrm{IL}}$, ACC locks all sectors. ACC should be at $\mathrm{V}_{\mathrm{IH}}$ for all other conditions.

## Autoselect Mode

The autoselect mode provides manufacturer and device identification, and sector protection verification, through identifier codes output from the internal register (which is separate from the memory array) on DQ15-DQ0. This mode is primarily intended for programming equipment to automatically match a device to be programmed with its corresponding programming algorithm. However, the autoselect codes can also be accessed in-system through the command register.
When using programming equipment, the autoselect mode requires $\mathrm{V}_{\text {ID }}$ on address pin A9. Address pins must be as shown in Table 3, "Autoselect Codes (High Voltage Method)," on page 18. In addition, when verifying sector protection, the sector address must appear on the appropriate highest order address bits (see Table , "," on page 18 and Table , "," on page 21). Table 3 shows the remaining address bits that are don't care. When all necessary bits have been set as required, the programming equipment may then read the corresponding identifier code on DQ15DQ0. However, the autoselect codes can also be accessed in-system through the command register, for instances when the device is erased or programmed in a system without access to high voltage on the A9 pin. The command sequence is illustrated in Table 18, "Command Definitions," on page 60. Note that if a Bank Address (BA) on address bits A22, A21, and A20 for the WS128J (A21:A19 for the WS064J) is asserted during the third write cycle of the autoselect command, the host system can read autoselect data that bank and then immediately read array data from the other bank, without exiting the autoselect mode.

To access the autoselect codes in-system, the host system can issue the autoselect command via the command register, as shown in Table 18, "Command Definitions," on page 60. This method does not require $\mathrm{V}_{\mathrm{ID}}$. Autoselect mode may only be entered and used when in the asynchronous read mode. Refer to the "Autoselect Command Sequence" section on page 51 for more information.

Table 3. Autoselect Codes (High Voltage Method)

|  | Description | CE\# | OE\# | WE\# | RESET\# | $\begin{gathered} \text { Amax } \\ \text { to } \\ \text { A12 } \end{gathered}$ | $\begin{gathered} \text { A11 } \\ \text { to } \\ \text { A10 } \end{gathered}$ | A9 | A8 | A7 | A6 | $\begin{aligned} & \text { A5 } \\ & \text { to } \\ & \text { A4 } \end{aligned}$ | A3 | A2 | A1 | A0 | $\begin{aligned} & \text { DQ15 } \\ & \text { to DQ0 } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Manufacturer ID: Spansion |  | L | L | H | H | X | X | $V_{\text {ID }}$ | X | X | L | X | L | L | L | L | 0001h |
| $\begin{aligned} & \text { O- } \\ & \text { O} \\ & \stackrel{\mathrm{O}}{\mathrm{O}} \end{aligned}$ | Read Cycle 1 | L | L | H | H | X | X | $\mathrm{V}_{\text {ID }}$ | X | L | L | L | L | L | L | H | 227Eh |
|  | Read Cycle 2 |  |  |  |  |  |  |  |  |  |  |  | H | H | H | L | $\begin{aligned} & \text { 2218h (WS128J) } \\ & \text { 221Eh (WS064) } \end{aligned}$ |
|  | Read Cycle 3 |  |  |  |  |  |  |  |  |  |  |  | H | H | H | H | $\begin{aligned} & \text { 2200h (WS128J) } \\ & \text { 2201h (WS064) } \end{aligned}$ |
| Sector Protection Verification |  | L | L | H | H | SA | X | $V_{\text {ID }}$ | X | L | L | L | L | L | H | L | 0001h (protected), 0000h (unprotected) |
| Indicator Bits |  | L | L | H | H | X | X | $\mathrm{V}_{\text {ID }}$ | X | X | L | X | L | L | H | H | $\text { DQ15 - DQ8 = } 0$ <br> DQ7 - Factory Lock Bit <br> 1 = Locked, $0=$ Not Locked <br> DQ6 -Customer Lock Bit <br> 1 = Locked, $0=$ Not Locked <br> DQ5 = Handshake Bit <br> 1 = Reserved, $0=$ Standard Handshake DQ4 \& DQ3 - Boot Code DQ2 - DQ0 = 001 |
| Har <br> Pro | ware Sector Group ction | L | L | H | H | SA | X | $V_{\text {ID }}$ | X | X | X | L | L | L | H | L | 0001h (protected), 0000h (unprotected) |

Legend: $L=$ Logic Low $=V_{I L}, H=$ Logic High $=V_{I H}, B A=$ Bank Address, $S A=$ Sector Address, $X=$ Don't care.
Notes:

1. The autoselect codes may also be accessed in-system via command sequences.
2. PPB Protection Status is shown on the data bus

## Sector/Sector Block Protection and Unprotection

The hardware sector protection feature disables both programming and erase operations in any sector. The hardware sector unprotection feature re-enables both program and erase operations in previously protected sectors. Sector protection/unprotection can be implemented via two methods.
(Note: For the following discussion, the term "sector" applies to both sectors and sector blocks. A sector block consists of two or more adjacent sectors that are protected or unprotected at the same time (see Table , "," on page 18 and Table , "," on page 21).)

Table 4. S29WSI28J/064J Boot Sector/Sector Block Addresses for Protection/Unprotection (Sheet I of 3)

| Sector | A22-A12 | Sector/ <br> Sector Block Size |
| :---: | :---: | :---: |
| SA0 | 00000000000 | 4 Kwords |
| SA1 | 00000000001 | 4 Kwords |
| SA2 | 00000000010 | 4 Kwords |
| SA3 | 00000000011 | 4 Kwords |
| SA4 | 00000000100 | 4 Kwords |
| SA5 | 00000000101 | 4 Kwords |
| SA6 | 00000000110 | 4 Kwords |
| SA7 | 00000000111 | 4 Kwords |
| SA9 | $00000001 X X X$, | 32 Kwords |
| SA10 | $00000010 X X X$, | 32 Kwords |
|  | $00000011 X X X$, | 32 Kwords |

Table 4. S29WSI28J/064J Boot Sector/Sector Block Addresses for Protection/Unprotection (Sheet 2 of 3)

| Sector | A22-A12 | Sector/ Sector Block Size |
| :---: | :---: | :---: |
| SA11-SA14 | 000001XXXXX | 128 (4×32) Kwords |
| SA15-SA18 | 000010XXXXX | 128 (4×32) Kwords |
| SA19-SA22 | 000011XXXXX | 128 (4×32) Kwords |
| SA23-SA26 | 000100XXXXX | 128 (4x32) Kwords |
| SA27-SA30 | 000101XXXXX | 128 (4x32) Kwords |
| SA31-SA34 | 000110XXXXX | 128 (4×32) Kwords |
| SA35-SA38 | 000111XXXXX | 128 (4×32) Kwords |
| SA39-SA42 | 001000XXXXX | 128 (4x32) Kwords |
| SA43-SA46 | 001001XXXXX | 128 (4×32) Kwords |
| SA47-SA50 | 001010XXXXX | 128 (4×32) Kwords |
| SA51-SA54 | 001011XXXXX | 128 (4×32) Kwords |
| SA55-SA58 | 001100XXXXX | 128 (4×32) Kwords |
| SA59-SA62 | 001101XXXXX | 128 (4×32) Kwords |
| SA63-SA66 | 001110XXXXX | 128 (4×32) Kwords |
| SA67-SA70 | 001111XXXXX | 128 (4×32) Kwords |
| SA71-SA74 | 010000XXXXX | 128 (4x32) Kwords |
| SA75-SA78 | 010001XXXXX | 128 (4x32) Kwords |
| SA79-SA82 | 010010XXXXX | 128 (4×32) Kwords |
| SA83-SA86 | 010011XXXXX | 128 (4×32) Kwords |
| SA87-SA90 | 010100XXXXX | 128 (4×32) Kwords |
| SA91-SA94 | 010101XXXXX | 128 (4×32) Kwords |
| SA95-SA98 | 010110XXXXX | 128 (4×32) Kwords |
| SA99-SA102 | 010111XXXXX | 128 (4x32) Kwords |
| SA103-SA106 | 011000XXXXX | 128 (4×32) Kwords |
| SA107-SA110 | 011001XXXXX | 128 (4×32) Kwords |
| SA111-SA114 | 011010XXXXX | 128 (4×32) Kwords |
| SA115-SA118 | 011011XXXXX | 128 (4×32) Kwords |
| SA119-SA122 | 011100XXXXX | 128 (4×32) Kwords |
| SA123-SA126 | 011101XXXXX | 128 (4×32) Kwords |
| SA127-SA130 | 011110XXXXX | 128 (4x32) Kwords |
| SA131-SA134 | 011111XXXXX | 128 (4×32) Kwords |
| SA135-SA138 | 100000XXXXX | 128 (4×32) Kwords |
| SA139-SA142 | 100001XXXXX | 128 (4×32) Kwords |
| SA143-SA146 | 100010XXXXX | 128 (4×32) Kwords |
| SA147-SA150 | 100011XXXXX | 128 (4×32) Kwords |
| SA151-SA154 | 100100XXXXX | 128 (4x32) Kwords |
| SA155-SA158 | 100101XXXXX | 128 (4×32) Kwords |
| SA159-SA162 | 100110XXXXX | 128 (4×32) Kwords |
| SA163-SA166 | 100111XXXXX | 128 (4x32) Kwords |

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Table 4. S29WSI28J/064J Boot Sector/Sector Block Addresses for Protection/Unprotection (Sheet $\mathbf{3}$ of 3)

| Sector | A22-A12 | Sector/ <br> Sector Block Size |
| :---: | :---: | :---: |
| SA167-SA170 | 101000XXXXX | 128 (4×32) Kwords |
| SA171-SA174 | 101001XXXXX | 128 (4×32) Kwords |
| SA175-SA178 | 101010XXXXX | 128 (4×32) Kwords |
| SA179-SA182 | 101011XXXXX | 128 (4×32) Kwords |
| SA183-SA186 | 101100XXXXX | 128 (4×32) Kwords |
| SA187-SA190 | 101101XXXXX | 128 (4x32) Kwords |
| SA191-SA194 | 101110XXXXX | 128 (4x32) Kwords |
| SA195-SA198 | 101111XXXXX | 128 (4×32) Kwords |
| SA199-SA202 | 110000XXXXX | 128 (4×32) Kwords |
| SA203-SA206 | 110001XXXXX | 128 (4×32) Kwords |
| SA207-SA210 | 110010XXXXX | 128 (4×32) Kwords |
| SA211-SA214 | 110011XXXXX | 128 (4x32) Kwords |
| SA215-SA218 | 110100XXXXX | 128 (4x32) Kwords |
| SA219-SA222 | 110101XXXXX | 128 (4×32) Kwords |
| SA223-SA226 | 110110XXXXX | 128 (4×32) Kwords |
| SA227-SA230 | 110111XXXXX | 128 (4x32) Kwords |
| SA231-SA234 | 111000XXXXX | 128 (4×32) Kwords |
| SA235-SA238 | 111001XXXXX | 128 (4×32) Kwords |
| SA239-SA242 | 111010XXXXX | 128 (4×32) Kwords |
| SA243-SA246 | 111011XXXXX | 128 (4×32) Kwords |
| SA247-SA250 | 111100XXXXX | 128 (4x32) Kwords |
| SA251-SA254 | 111101XXXXX | 128 (4x32) Kwords |
| SA255-SA258 | 111110XXXXX | 128 (4x32) Kwords |
| SA259 | 11111100XXX | 32 Kwords |
| SA260 | 11111101XXX | 32 Kwords |
| SA261 | 11111110XXX | 32 Kwords |
| SA262 | 11111111000 | 4 Kwords |
| SA263 | 11111111001 | 4 Kwords |
| SA264 | 11111111010 | 4 Kwords |
| SA265 | 11111111011 | 4 Kwords |
| SA266 | 11111111100 | 4 Kwords |
| SA267 | 11111111101 | 4 Kwords |
| SA268 | 11111111110 | 4 Kwords |
| SA269 | 11111111111 | 4 Kwords |

Table 5. S29WS064J Boot Sector/Sector Block Addresses for Protection/Unprotection (Sheet I of 2)

| Sector | A21-A12 | Sector/ Sector Block Size |
| :---: | :---: | :---: |
| SAO | 0000000000 | 4 Kwords |
| SA1 | 0000000001 | 4 Kwords |
| SA2 | 0000000010 | 4 Kwords |
| SA3 | 0000000011 | 4 Kwords |
| SA4 | 0000000100 | 4 Kwords |
| SA5 | 0000000101 | 4 Kwords |
| SA6 | 0000000110 | 4 Kwords |
| SA7 | 0000000111 | 4 Kwords |
| SA8 | 0000001XXX | 32 Kwords |
| SA9 | 0000010XXX | 32 Kwords |
| SA10 | 0000011XXX | 32 Kwords |
| SA11-SA14 | 00001XXXXX | 128 (4x32) Kwords |
| SA15-SA18 | 00010XXXXX | 128 (4×32) Kwords |
| SA19-SA22 | 00011XXXXX | 128 (4x32) Kwords |
| SA23-SA26 | 00100XXXXX | 128 (4×32) Kwords |
| SA27-SA30 | 00101XXXXX | 128 (4×32) Kwords |
| SA31-SA34 | 00110XXXXX | 128 (4x32) Kwords |
| SA35-SA38 | 00111XXXXX | 128 (4×32) Kwords |
| SA39-SA42 | 01000XXXXX | 128 (4×32) Kwords |
| SA43-SA46 | 01001XXXXX | 128 (4×32) Kwords |
| SA47-SA50 | 01010XXXXX | 128 (4×32) Kwords |
| SA51-SA54 | 01011XXXXX | 128 (4x32) Kwords |
| SA55-SA58 | 01100XXXXX | 128 (4×32) Kwords |
| SA59-SA62 | 01101XXXXX | 128 (4×32) Kwords |
| SA63-SA66 | 01110XXXXX | 128 (4×32) Kwords |
| SA67-SA70 | 01111XXXXX | 128 (4×32) Kwords |
| SA71-SA74 | 10000XXXXX | 128 (4x32) Kwords |
| SA75-SA78 | 10001XXXXX | 128 (4×32) Kwords |
| SA79-SA82 | 10010XXXXX | 128 (4×32) Kwords |
| SA83-SA86 | 10011XXXXX | 128 (4×32) Kwords |
| SA87-SA90 | 10100XXXXX | 128 (4×32) Kwords |
| SA91-SA94 | 10101XXXXX | 128 (4×32) Kwords |
| SA95-SA98 | 10110XXXXX | 128 (4×32) Kwords |
| SA99-SA102 | 10111XXXXX | 128 (4×32) Kwords |
| SA103-SA106 | 11000XXXXX | 128 (4×32) Kwords |
| SA107-SA110 | 11001XXXXX | 128 (4×32) Kwords |
| SA111-SA114 | 11010XXXXX | 128 (4x32) Kwords |
| SA115-SA118 | 11011XXXXX | 128 (4×32) Kwords |
| SA119-SA122 | 11100XXXXX | 128 (4x32) Kwords |

Table 5. S29WS064J Boot Sector/Sector Block Addresses for Protection/Unprotection (Sheet 2 of 2)

| Sector | A21-A12 | Sector/ <br> Sector Block Size |
| :---: | :---: | :---: |
| SA123-SA126 | $11101 X X X X X$ | $128(4 \times 32) \mathrm{Kwords}$ |
| SA127-SA130 | $11110 X X X X X$ | $128(4 \times 32) \mathrm{Kwords}$ |
| SA131 | $1111100 X X X$ | 32 Kwords |
| SA132 | $1111101 X X X$ | 32 Kwords |
| SA133 | $1111110 X X X$ | 32 Kwords |
| SA134 | 1111111000 | 4 Kwords |
| SA135 | 1111111001 | 4 Kwords |
| SA137 | 1111111010 | 4 Kwords |
| SA139 | 1111111011 | 4 Kwords |
| SA140 | 1111111100 | 4 Kwords |
| SA141 | 1111111101 | 4 Kwords |
|  | 111111110 | 4 Kwords |

## Advanced Sector Protection/Unprotection

The Advanced Sector Protection/Unprotection feature disables or enables programming or erase operations in any or all sectors and can be implemented through software and/or hardware methods, which are independent of each other. This section describes the various methods of protecting data stored in the memory array. An overview of these methods in shown in Figure 1.


Figure I. Advanced Sector Protection/Unprotection

## Lock Register

As shipped from the factory, all devices default to the persistent mode when power is applied, and all sectors are unprotected, unless otherwise chosen through the DYB ordering option. The device programmer or host system must then choose which sector protection method to use. Programming (setting to " 0 ") any one of the following two one-time programmable, non-volatile bits locks the part permanently in that mode:

■ Lock Register Persistent Protection Mode Lock Bit (DQ1)
■ Lock Register Password Protection Mode Lock Bit (DQ2)
Table 6. Lock Register

| Device | DQ15-05 | DQ4 | DQ3 | DQ2 | DQI | DQ0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| S29WS256N | 1 | 1 | 1 | Password Protection Mode Lock Bit | Persistent Protection Mode Lock Bit | Customer SecSi Sector Protection Bit |
| $\begin{aligned} & \text { S29WS128N/ } \\ & \text { S29WS064N } \end{aligned}$ | Undefined | DYB Lock Boot Bit 0 = sectors power up protected 1 = sectors power up unprotected | PPB One-Time Programmable Bit $0=$ All PPB erase command disabled 1 = All PPB Erase command enabled | Password Protection Mode Lock Bit | Persistent Protection Mode Lock Bit | SecSi Sector Protection Bit |

## Notes

1. If the password mode is chosen, the password must be programmed before setting the corresponding lock register bit.
2. After the Lock Register Bits Command Set Entry command sequence is written, reads and writes for Bank 0 are disabled, while reads from other banks are allowed until exiting this mode.
3. If both lock bits are selected to be programmed (to zeros) at the same time, the operation aborts.
4. Once the Password Mode Lock Bit is programmed, the Persistent Mode Lock Bit is permanently disabled, and no changes to the protection scheme are allowed. Similarly, if the Persistent Mode Lock Bit is programmed, the Password Mode is permanently disabled.

After selecting a sector protection method, each sector can operate in any of the following three states:

1. Constantly locked. The selected sectors are protected and can not be reprogrammed unless PPB lock bit is cleared via a password, hardware reset, or power cycle.
2. Dynamically locked. The selected sectors are protected and can be altered via software commands.
3. Unlocked. The sectors are unprotected and can be erased and/or programmed.

These states are controlled by the bit types described in Sections -.

## Persistent Protection Bits

The Persistent Protection Bits are unique and nonvolatile for each sector and have the same endurances as the Flash memory. Preprogramming and verification prior to erasure are handled by the device, and therefore do not require system monitoring.

## Notes

1. Each PPB is individually programmed and all are erased in parallel.
2. While programming PPB for a sector, array data can be read from any other bank, except Bank 0 (used for Data\# Polling) and the bank in which sector PPB is being programmed.
3. Entry command disables reads and writes for the bank selected.
4. Reads within that bank return the PPB status for that sector
5. Reads from other banks are allowed while writes are not allowed.
6. All Reads must be performed using the Asynchronous mode.
7. The specific sector address (A23-A14 WS256N, A22-A14 WS128N, A21-A14 WS064N) are written at the same time as the program command.
8. If the PPB Lock Bit is set, the PPB Program or erase command does not execute and timesout without programming or erasing the PPB.
9. There are no means for individually erasing a specific PPB and no specific sector address is required for this operation.
10.Exit command must be issued after the execution which resets the device to read mode and re-enables reads and writes for Bank 0
11.The programming state of the PPB for a given sector can be verified by writing a PPB Status Read Command to the device as described by the flow chart shown in Figure 2.


Figure 2. PPB Program/Erase Algorithm

## Dynamic Protection Bits

Dynamic Protection Bits are volatile and unique for each sector and can be individually modified. DYBs only control the protection scheme for unprotected sectors that have their PPBs cleared (erased to "1"). By issuing the DYB Set or Clear command sequences, the DYBs are set (programmed to " 0 ") or cleared (erased to " 1 "), thus placing each sector in the protected or unprotected state respectively. This feature allows software to easily protect sectors against inadvertent changes yet does not prevent the easy removal of protection when changes are needed.

## Notes

1. The DYBs can be set (programmed to " 0 ") or cleared (erased to " 1 ") as often as needed. When the parts are first shipped, the PPBs are cleared (erased to " 1 ") and upon power up or reset, the DYBs can be set or cleared depending upon the ordering option chosen.
2. If the option to clear the DYBs after power up is chosen, (erased to "1"), then the sectorsmay be modified depending upon the PPB state of that sector (see Table 7).
3. The sectors would be in the protected state If the option to set the DYBs after power up is chosen (programmed to " 0 ").
4. It is possible to have sectors that are persistently locked with sectors that are left in the dynamic state.
5. The DYB Set or Clear commands for the dynamic sectors signify protected or unprotected state of the sectors respectively. However, if there is a need to change the status of the persistently locked sectors, a few more steps are required. First, the PPB Lock Bit must be cleared by either putting the device through a power-cycle, or hardware reset. The PPBs can then be changed to reflect the desired settings. Setting the PPB Lock Bit once again locks the PPBs, and the device operates normally again.
6. To achieve the best protection, it is recommended to execute the PPB Lock Bit Set command early in the boot code and protect the boot code by holding WP\# $=\mathrm{V}_{\mathrm{IL}}$. Note that the PPB and DYB bits have the same function when $A C C=V_{H H}$ as they do when $A C C=V_{I H}$.

## Persistent Protection Bit Lock Bit

The Persistent Protection Bit Lock Bit is a global volatile bit for all sectors. When set (programmed to " 0 "), it locks all PPBs and when cleared (programmed to " 1 "), allows the PPBs to be changed. There is only one PPB Lock Bit per device.

## Notes

1. No software command sequence unlocks this bit unless the device is in the password protection mode; only a hardware reset or a power-up clears this bit.
2. The PPB Lock Bit must be set (programmed to "0") only after all PPBs are configured to the desired settings.

## Password Protection Method

The Password Protection Method allows an even higher level of security than the Persistent Sector Protection Mode by requiring a 64 bit password for unlocking the device PPB Lock Bit. In addition to this password requirement, after power up and reset, the PPB Lock Bit is set " 0 " to maintain the password mode of operation. Successful execution of the Password Unlock command by entering the entire password clears the PPB Lock Bit, allowing for sector PPBs modifications.

## Notes

1. There is no special addressing order required for programming the password. Once the Password is written and verified, the Password Mode Locking Bit must be set in order to prevent access.
2. The Password Program Command is only capable of programming "0"s. Programming a " 1 " after a cell is programmed as a " 0 " results in a time-out with the cell as a " 0 ".
3. The password is all " 1 "s when shipped from the factory.
4. All 64-bit password combinations are valid as a password.
5. There is no means to verify what the password is after it is set.
6. The Password Mode Lock Bit, once set, prevents reading the 64-bit password on the data bus and further password programming.
7. The Password Mode Lock Bit is not erasable.
8. The lower two address bits (A1-A0) are valid during the Password Read, Password Program, and Password Unlock.
9. The exact password must be entered in order for the unlocking function to occur.
10.The Password Unlock command cannot be issued any faster than $1 \mu \mathrm{~s}$ at a time to prevent a hacker from running through all the 64-bit combinations in an attempt to correctly match a password.
11.Approximately $1 \mu \mathrm{~s}$ is required for unlocking the device after the valid 64-bit password is given to the device.
10. Password verification is only allowed during the password programming operation.
13.All further commands to the password region are disabled and all operations are ignored.
14.If the password is lost after setting the Password Mode Lock Bit, there is no way to clear the PPB Lock Bit.
11. Entry command sequence must be issued prior to any of any operation and it disables reads and writes for Bank 0 . Reads and writes for other banks excluding Bank 0 are allowed.
16.If the user attempts to program or erase a protected sector, the device ignores the command and returns to read mode.
17.A program or erase command to a protected sector enables status polling and returns to read mode without having modified the contents of the protected sector.
18.The programming of the DYB, PPB, and PPB Lock for a given sector can be verified by writing individual status read commands DYB Status, PPB Status, and PPB Lock Status to the device.


Figure 3. Lock Register Program Algorithm

## Advanced Sector Protection Software Examples

Table 7. Sector Protection Schemes

| Unique Device PPB Lock Bit$\begin{aligned} & 0=\text { locked } \\ & 1=\text { unlocked } \end{aligned}$ |  | Sector PPB $0=$ protected I = unprotected | $\begin{gathered} \text { Sector DYB } \\ \mathbf{0 = \text { protected }} \\ \mathrm{I}=\text { unprotected } \end{gathered}$ | Sector Protection Status |
| :---: | :---: | :---: | :---: | :---: |
| Any Sector | 0 | 0 | x | Protected through PPB |
| Any Sector | 0 | 0 | X | Protected through PPB |
| Any Sector | 0 | 1 | 1 | Unprotected |
| Any Sector | 0 | 1 | 0 | Protected through DYB |
| Any Sector | 1 | 0 | X | Protected through PPB |
| Any Sector | 1 | 0 | x | Protected through PPB |
| Any Sector | 1 | 1 | 0 | Protected through DYB |
| Any Sector | 1 | 1 | 1 | Unprotected |

Table 7 contains all possible combinations of the DYB, PPB, and PPB Lock Bit relating to the status of the sector. In summary, if the PPB Lock Bit is locked (set to " 0 "), no changes to the PPBs are allowed. The PPB Lock Bit can only be unlocked (reset to "1") through a hardware reset or power cycle. See also Figure 1 for an overview of the Advanced Sector Protection feature.

## Hardware Data Protection Methods

The device offers two main types of data protection at the sector level via hardware control:
■ When WP\# is at $V_{I L}$, the four outermost sectors are locked (device specific).

- When ACC is at $V_{I L}$, all sectors are locked.

There are additional methods by which intended or accidental erasure of any sectors can be prevented via hardware means. The following subsections describes these methods:

## WP\# Method

The Write Protect feature provides a hardware method of protecting the four outermost sectors. This function is provided by the WP\# pin and overrides the previously discussed Sector Protection/Unprotection method.
If the system asserts $V_{\text {IL }}$ on the WP\# pin, the device disables program and erase functions in the "outermost" boot sectors. The outermost boot sectors are the sectors containing both the lower and upper set of sectors in a dual-boot-configured device.

If the system asserts $\mathrm{V}_{\mathrm{IH}}$ on the WP\# pin, the device reverts to whether the boot sectors were last set to be protected or unprotected. That is, sector protection or unprotection for these sectors depends on whether they were last protected or unprotected.
Note that the WP\# pin must not be left floating or unconnected as inconsistent behavior of the device may result.
The WP\# pin must be held stable during a command sequence execution

## ACC Method

This method is similar to above, except it protects all sectors. Once ACC input is set to $\mathrm{V}_{\mathrm{IL}}$, all program and erase functions are disabled and hence all sectors are protected.

## Low $\mathbf{V}_{\text {cc }}$ Write Inhibit

When $\mathrm{V}_{\mathrm{CC}}$ is less than $\mathrm{V}_{\mathrm{LKO}}$, the device does not accept any write cycles. This protects data during $\mathrm{V}_{\mathrm{CC}}$ power-up and power-down.

The command register and all internal program/erase circuits are disabled, and the device resets to reading array data. Subsequent writes are ignored until $\mathrm{V}_{\mathrm{CC}}$ is greater than $\mathrm{V}_{\mathrm{LKO}}$. The system must provide the proper signals to the control inputs to prevent unintentional writes when $\mathrm{V}_{\mathrm{CC}}$ is greater than $\mathrm{V}_{\text {LKO }}$.

## Write Pulse "Glitch Protection"

Noise pulses of less than 3 ns (typical) on OE\#, CE\# or WE\# do not initiate a write cycle.

## Power-Up Write Inhibit

If WE\# = CE\# = RESET\# = $\mathrm{V}_{\mathrm{IL}}$ and $\mathrm{OE} \#=\mathrm{V}_{\mathrm{IH}}$ during power up, the device does not accept commands on the rising edge of WE\#. The internal state machine is automatically reset to the read mode on power-up.

## Common Flash Memory Interface (CFI)

The Common Flash Interface (CFI) specification outlines device and host system software interrogation handshake, which allows specific vendor-specified software algorithms to be used for entire families of devices. Software support can then be device-independent, JEDEC ID-independent, and forward- and backward-compatible for the specified flash device families. Flash vendors can standardize their existing interfaces for long-term compatibility.

This device enters the CFI Query mode when the system writes the CFI Query command, 98 h , to address 55 h any time the device is ready to read array data. The system can read CFI information at the addresses given in Tables $8-11$. To terminate reading CFI data, the system must write the reset command.

The system can also write the CFI query command when the device is in the autoselect mode. The device enters the CFI query mode, and the system can read CFI data at the addresses given in Tables 8-11. The system must write the reset command to return the device to the autoselect mode.

Table 8. CFI Query Identification String

| Addresses | Data | Description |
| :---: | :---: | :---: |
| $\begin{aligned} & \hline 10 h \\ & 11 \mathrm{~h} \\ & 12 \mathrm{~h} \end{aligned}$ | 0051h 0052h 0059h | Query Unique ASCII string "QRY" |
| $\begin{aligned} & 13 h \\ & 14 h \end{aligned}$ | $\begin{aligned} & \text { 0002h } \\ & \text { 0000h } \end{aligned}$ | Primary OEM Command Set |
| $\begin{aligned} & 15 h \\ & 16 h \end{aligned}$ | $\begin{aligned} & \text { 0040h } \\ & 0000 \mathrm{~h} \end{aligned}$ | Address for Primary Extended Table |
| $\begin{aligned} & 17 \mathrm{~h} \\ & 18 \mathrm{~h} \end{aligned}$ | $\begin{aligned} & \text { 0000h } \\ & 0000 \mathrm{~h} \end{aligned}$ | Alternate OEM Command Set (00h = none exists) |
| $\begin{aligned} & 19 \mathrm{~h} \\ & 1 \mathrm{Ah} \end{aligned}$ | $\begin{aligned} & \text { 0000h } \\ & 0000 \mathrm{~h} \end{aligned}$ | Address for Alternate OEM Extended Table (00h = none exists) |

Table 9. System Interface String

| Addresses | Data | Description |
| :---: | :---: | :---: |
| 1Bh | 0017h | $V_{\text {CC }}$ Min. (write/erase) <br> D7-D4: volt, D3-D0: 100 millivolt |
| 1Ch | 0019h | $V_{\text {CC }}$ Max. (write/erase) <br> D7-D4: volt, D3-D0: 100 millivolt |
| 1Dh | 0000h | $\mathrm{V}_{\mathrm{PP}}$ Min. voltage ( $00 \mathrm{~h}=$ no $\mathrm{V}_{\text {PP }}$ pin present) |
| 1Eh | 0000h | $\mathrm{V}_{\text {PP }}$ Max. voltage ( $00 \mathrm{~h}=$ no $\mathrm{V}_{\text {PP }}$ pin present) |
| 1Fh | 0003h | Typical timeout per single byte/word write $2^{N} \mu \mathrm{~s}$ |
| 20h | 0000h | Typical timeout for Min. size buffer write $2^{N} \mu \mathrm{~s}$ ( $00 \mathrm{~h}=$ not supported) |
| 21h | 0009h | Typical timeout per individual block erase $2^{\mathrm{N}} \mathrm{ms}$ |
| 22h | 0000h | Typical timeout for full chip erase $2^{\mathrm{N}} \mathrm{ms}$ ( $00 \mathrm{~h}=$ not supported) |
| 23h | 0004h | Max. timeout for byte/word write $2^{N}$ times typical |
| 24h | 0000h | Max. timeout for buffer write $2^{N}$ times typical |
| 25h | 0004h | Max. timeout per individual block erase $2^{N}$ times typical |
| 26h | 0000h | Max. timeout for full chip erase $2^{N}$ times typical ( $00 \mathrm{~h}=$ not supported) |

Table 10. Device Geometry Definition

| Addresses | Data | Description |
| :---: | :---: | :---: |
| 27h | 0018h (WS128J) <br> 0017h (WS064J) | Device Size $=2^{N}$ byte |
| $\begin{aligned} & 28 \mathrm{~h} \\ & 29 \mathrm{~h} \end{aligned}$ | $\begin{aligned} & \text { 0001h } \\ & \text { 0000h } \end{aligned}$ | Flash Device Interface description (refer to CFI publication 100) |
| $\begin{aligned} & 2 \mathrm{Ah} \\ & 2 \mathrm{Bh} \end{aligned}$ | $\begin{aligned} & \text { 0000h } \\ & \text { 0000h } \end{aligned}$ | Max. number of bytes in multi-byte write $=2^{N}$ (00h = not supported) |
| 2Ch | 0003h | Number of Erase Block Regions within device |
| $\begin{aligned} & \text { 2Dh } \\ & \text { 2Eh } \\ & \text { 2Fh } \\ & 30 \mathrm{~h} \end{aligned}$ | $\begin{aligned} & \text { 0007h } \\ & 0000 \mathrm{~h} \\ & 0020 \mathrm{~h} \\ & 0000 \mathrm{~h} \end{aligned}$ | Erase Block Region 1 Information (refer to the CFI specification or CFI publication 100) |
| 31h | 00FDh (WS128J) 007Dh (WS064J) |  |
| $\begin{aligned} & 32 h \\ & 33 h \\ & 34 h \end{aligned}$ | $\begin{aligned} & \text { 0000h } \\ & \text { 0000h } \\ & 0001 \mathrm{~h} \end{aligned}$ | Erase Block Region 2 Information |
| $\begin{aligned} & 35 \mathrm{~h} \\ & 36 \mathrm{~h} \\ & 37 \mathrm{~h} \\ & 38 \mathrm{~h} \end{aligned}$ | $\begin{aligned} & \text { 0007h } \\ & 0000 \mathrm{~h} \\ & 0020 \mathrm{~h} \\ & 0000 \mathrm{~h} \end{aligned}$ | Erase Block Region 3 Information |
| $\begin{aligned} & 39 \mathrm{~h} \\ & \text { 3Ah } \\ & \text { 3Bh } \\ & \text { 3Ch } \end{aligned}$ | 0000h 0000h 0000h 0000h | Erase Block Region 4 Information |

Table II. Primary Vendor-Specific Extended Query

| Addresses | Data | Description |
| :---: | :---: | :---: |
| $\begin{aligned} & 40 h \\ & 41 \mathrm{~h} \\ & 42 \mathrm{~h} \end{aligned}$ | $\begin{aligned} & \text { 0050h } \\ & 0052 \mathrm{~h} \\ & 0049 \mathrm{~h} \end{aligned}$ | Query-unique ASCII string "PRI" |
| 43h | 0031h | Major version number, ASCII |
| 44h | 0033h | Minor version number, ASCII |
| 45h | 000Ch | Address Sensitive Unlock (Bits 1-0) <br> $0=$ Required, $1=$ Not Required <br> Silicon Technology (Bits 5-2) $0011=0.13 \mu \mathrm{~m}$ |
| 46h | 0002h | Erase Suspend $0=$ Not Supported, $1=$ To Read Only, $2=$ To Read \& Write |
| 47h | 0001h | Sector Protect <br> $0=$ Not Supported, $\mathrm{X}=$ Number of sectors in per group |
| 48h | 0001h | Sector Temporary Unprotect $00=$ Not Supported, $01=$ Supported |
| 49h | 0007h | Sector Protect/Unprotect scheme 07 = Advanced Sector Protection |
| 4Ah | 00E7h (WS128J) 0077h (WS064J) | Simultaneous Operation <br> Number of Sectors in all banks except boot block |
| 4Bh | 0001h | Burst Mode Type $00=$ Not Supported, 01 = Supported |
| 4Ch | 0000h | Page Mode Type $00=$ Not Supported, $01=4$ Word Page, $02=8$ Word Page, $04=16$ Word Page |
| 4Dh | 00B5h | ACC (Acceleration) Supply Minimum <br> 00h = Not Supported, D7-D4: Volt, D3-D0: 100 mV |
| 4Eh | 00C5h | ACC (Acceleration) Supply Maximum <br> 00h = Not Supported, D7-D4: Volt, D3-D0: 100 mV |
| 4Fh | 0001h | Top/Bottom Boot Sector Flag <br> 01h = Dual Boot Device, 02h = Bottom Boot Device, 03h = Top Boot Device |
| 50h | 0000h | Program Suspend. 00h = not supported |
| 57h | 0004h | Bank Organization: $\mathrm{X}=$ Number of banks |
| 58h | $\begin{aligned} & \text { 0027h (WS128J) } \\ & \text { 0017h (WS064J) } \end{aligned}$ | Bank A Region Information. $\mathrm{X}=$ Number of sectors in bank |
| 59h | 0060h (WS128J) 0030h (WS064J) | Bank B Region Information. $\mathrm{X}=$ Number of sectors in bank |
| 5Ah | 0060h (WS128J) 0030h (WS064J) | Bank C Region Information. $\mathrm{X}=$ Number of sectors in bank |
| 5Bh | 0027h (WS128J) 0017h (WS064J) | Bank D Region Information. $\mathrm{X}=$ Number of sectors in bank |

Table 12. WSI28J Sector Address Table (Sheet I of 8)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank D | SA0 | 4 Kwords | 000000h-000FFFh |
|  | SA1 | 4 Kwords | 001000h-001FFFh |
|  | SA2 | 4 Kwords | 002000h-002FFFh |
|  | SA3 | 4 Kwords | 003000h-003FFFh |
|  | SA4 | 4 Kwords | 004000h-004FFFh |
|  | SA5 | 4 Kwords | 005000h-005FFFh |
|  | SA6 | 4 Kwords | 006000h-006FFFh |
|  | SA7 | 4 Kwords | 007000h-007FFFh |
|  | SA8 | 32 Kwords | 008000h-00FFFFh |
|  | SA9 | 32 Kwords | 010000h-017FFFh |
|  | SA10 | 32 Kwords | 018000h-01FFFFh |
|  | SA11 | 32 Kwords | 020000h-027FFFh |
|  | SA12 | 32 Kwords | 028000h-02FFFFh |
|  | SA13 | 32 Kwords | 030000h-037FFFh |
|  | SA14 | 32 Kwords | 038000h-03FFFFh |
|  | SA15 | 32 Kwords | 040000h-047FFFh |
|  | SA16 | 32 Kwords | 048000h-04FFFFh |
|  | SA17 | 32 Kwords | 050000h-057FFFh |
|  | SA18 | 32 Kwords | 058000h-05FFFFh |
|  | SA19 | 32 Kwords | 060000h-067FFFh |
|  | SA20 | 32 Kwords | 068000h-06FFFFh |
|  | SA21 | 32 Kwords | 070000h-077FFFh |
|  | SA22 | 32 Kwords | 078000h-07FFFFh |
|  | SA23 | 32 Kwords | 080000h-087FFFh |
|  | SA24 | 32 Kwords | 088000h-08FFFFh |
|  | SA25 | 32 Kwords | 090000h-097FFFh |
|  | SA26 | 32 Kwords | 098000h-09FFFFh |
|  | SA27 | 32 Kwords | 0A0000h-0A7FFFh |
|  | SA28 | 32 Kwords | 0A8000h-0AFFFFh |
|  | SA29 | 32 Kwords | 0B0000h-0B7FFFh |
|  | SA30 | 32 Kwords | 0B8000h-0BFFFFh |
|  | SA31 | 32 Kwords | 0C0000h-0C7FFFh |
|  | SA32 | 32 Kwords | 0C8000h-0CFFFFh |
|  | SA33 | 32 Kwords | 0D0000h-0D7FFFh |
|  | SA34 | 32 Kwords | 0D8000h-0DFFFFh |
|  | SA35 | 32 Kwords | 0E0000h-0E7FFFh |
|  | SA36 | 32 Kwords | 0E8000h-0EFFFFh |
|  | SA37 | 32 Kwords | 0F0000h-0F7FFFh |
|  | SA38 | 32 Kwords | 0F8000h-0FFFFFh |

Data Shet

Table I2. WSI28J Sector Address Table (Sheet 2 of 8)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank C | SA39 | 32 Kwords | 100000h-107FFFh |
|  | SA40 | 32 Kwords | 108000h-10FFFFh |
|  | SA41 | 32 Kwords | 110000h-117FFFh |
|  | SA42 | 32 Kwords | 118000h-11FFFFh |
|  | SA43 | 32 Kwords | 120000h-127FFFh |
|  | SA44 | 32 Kwords | 128000h-12FFFFh |
|  | SA45 | 32 Kwords | 130000h-137FFFh |
|  | SA46 | 32 Kwords | 138000h-13FFFFh |
|  | SA47 | 32 Kwords | 140000h-147FFFh |
|  | SA48 | 32 Kwords | 148000h-14FFFFh |
|  | SA49 | 32 Kwords | 150000h-157FFFh |
|  | SA50 | 32 Kwords | 158000h-15FFFFh |
|  | SA51 | 32 Kwords | 160000h-167FFFh |
|  | SA52 | 32 Kwords | 168000h-16FFFFh |
|  | SA53 | 32 Kwords | 170000h-177FFFh |
|  | SA54 | 32 Kwords | 178000h-17FFFFh |
|  | SA55 | 32 Kwords | 180000h-187FFFh |
|  | SA56 | 32 Kwords | 188000h-18FFFFh |
|  | SA57 | 32 Kwords | 190000h-197FFFh |
|  | SA58 | 32 Kwords | 198000h-19FFFFh |
|  | SA59 | 32 Kwords | 1A0000h-1A7FFFh |
|  | SA60 | 32 Kwords | 1A8000h-1AFFFFh |
|  | SA61 | 32 Kwords | 1B0000h-1B7FFFh |
|  | SA62 | 32 Kwords | 1B8000h-1BFFFFh |
|  | SA63 | 32 Kwords | 1C0000h-1C7FFFh |
|  | SA64 | 32 Kwords | 1C8000h-1CFFFFh |
|  | SA65 | 32 Kwords | 1D0000h-1D7FFFh |
|  | SA66 | 32 Kwords | 1D8000h-1DFFFFh |
|  | SA67 | 32 Kwords | 1E0000h-1E7FFFh |
|  | SA68 | 32 Kwords | 1E8000h-1EFFFFh |
|  | SA69 | 32 Kwords | 1F0000h-1F7FFFh |
|  | SA70 | 32 Kwords | 1F8000h-1FFFFFh |

Table I2. WSI28J Sector Address Table (Sheet 3 of 8)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank C | SA71 | 32 Kwords | 200000h-207FFFh |
|  | SA72 | 32 Kwords | 208000h-20FFFFh |
|  | SA73 | 32 Kwords | 210000h-217FFFh |
|  | SA74 | 32 Kwords | 218000h-21FFFFh |
|  | SA75 | 32 Kwords | 220000h-227FFFh |
|  | SA76 | 32 Kwords | 228000h-22FFFFh |
|  | SA77 | 32 Kwords | 230000h-237FFFh |
|  | SA78 | 32 Kwords | 238000h-23FFFFh |
|  | SA79 | 32 Kwords | 240000h-247FFFh |
|  | SA80 | 32 Kwords | 248000h-24FFFFh |
|  | SA81 | 32 Kwords | 250000h-257FFFh |
|  | SA82 | 32 Kwords | 258000h-25FFFFh |
|  | SA83 | 32 Kwords | 260000h-267FFFh |
|  | SA84 | 32 Kwords | 268000h-26FFFFh |
|  | SA85 | 32 Kwords | 270000h-277FFFh |
|  | SA86 | 32 Kwords | 278000h-27FFFFh |
|  | SA87 | 32 Kwords | 280000h-287FFFh |
|  | SA88 | 32 Kwords | 288000h-28FFFFh |
|  | SA89 | 32 Kwords | 290000h-297FFFh |
|  | SA90 | 32 Kwords | 298000h-29FFFFh |
|  | SA91 | 32 Kwords | 2A0000h-2A7FFFh |
|  | SA92 | 32 Kwords | 2A8000h-2AFFFFh |
|  | SA93 | 32 Kwords | 2B0000h-2B7FFFh |
|  | SA94 | 32 Kwords | 2B8000h-2BFFFFh |
|  | SA95 | 32 Kwords | 2C0000h-2C7FFFh |
|  | SA96 | 32 Kwords | 2C8000h-2CFFFFh |
|  | SA97 | 32 Kwords | 2D0000h-2D7FFFh |
|  | SA98 | 32 Kwords | 2D8000h-2DFFFFh |
|  | SA99 | 32 Kwords | 2E0000h-2E7FFFh |
|  | SA100 | 32 Kwords | 2E8000h-2EFFFFh |
|  | SA101 | 32 Kwords | 2F0000h-2F7FFFh |
|  | SA102 | 32 Kwords | 2F8000h-2FFFFFh |

Data Shet

Table 12. WSI28J Sector Address Table (Sheet 4 of 8)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank C | SA103 | 32 Kwords | 300000h-307FFFh |
|  | SA104 | 32 Kwords | 308000h-30FFFFh |
|  | SA105 | 32 Kwords | 310000h-317FFFh |
|  | SA106 | 32 Kwords | 318000h-31FFFFh |
|  | SA107 | 32 Kwords | 320000h-327FFFh |
|  | SA108 | 32 Kwords | 328000h-32FFFFh |
|  | SA109 | 32 Kwords | 330000h-337FFFh |
|  | SA110 | 32 Kwords | 338000h-33FFFFh |
|  | SA111 | 32 Kwords | 340000h-347FFFh |
|  | SA112 | 32 Kwords | 348000h-34FFFFh |
|  | SA113 | 32 Kwords | 350000h-357FFFh |
|  | SA114 | 32 Kwords | 358000h-35FFFFh |
|  | SA115 | 32 Kwords | 360000h-367FFFh |
|  | SA116 | 32 Kwords | 368000h-36FFFFh |
|  | SA117 | 32 Kwords | 370000h-377FFFh |
|  | SA118 | 32 Kwords | 378000h-37FFFFh |
|  | SA119 | 32 Kwords | 380000h-387FFFh |
|  | SA120 | 32 Kwords | 388000h-38FFFFh |
|  | SA121 | 32 Kwords | 390000h-397FFFh |
|  | SA122 | 32 Kwords | 398000h-39FFFFh |
|  | SA123 | 32 Kwords | 3A0000h-3A7FFFh |
|  | SA124 | 32 Kwords | 3A8000h-3AFFFFh |
|  | SA125 | 32 Kwords | 3B0000h-3B7FFFh |
|  | SA126 | 32 Kwords | 3B8000h-3BFFFFh |
|  | SA127 | 32 Kwords | 3C0000h-3C7FFFh |
|  | SA128 | 32 Kwords | 3C8000h-3CFFFFh |
|  | SA129 | 32 Kwords | 3D0000h-3D7FFFh |
|  | SA130 | 32 Kwords | 3D8000h-3DFFFFh |
|  | SA131 | 32 Kwords | 3E0000h-3E7FFFh |
|  | SA132 | 32 Kwords | 3E8000h-3EFFFFh |
|  | SA133 | 32 Kwords | 3F0000h-3F7FFFh |
|  | SA134 | 32 Kwords | 3F8000h-3FFFFFh |

Table I2. WSI28J Sector Address Table (Sheet 5 of 8)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank B | SA135 | 32 Kwords | 400000h-407FFFh |
|  | SA136 | 32 Kwords | 408000h-40FFFFh |
|  | SA137 | 32 Kwords | 410000h-417FFFh |
|  | SA138 | 32 Kwords | 418000h-41FFFFh |
|  | SA139 | 32 Kwords | 420000h-427FFFh |
|  | SA140 | 32 Kwords | 428000h-42FFFFh |
|  | SA141 | 32 Kwords | 430000h-437FFFh |
|  | SA142 | 32 Kwords | 438000h-43FFFFh |
|  | SA143 | 32 Kwords | 440000h-447FFFh |
|  | SA144 | 32 Kwords | 448000h-44FFFFh |
|  | SA145 | 32 Kwords | 450000h-457FFFh |
|  | SA146 | 32 Kwords | 458000h-45FFFFh |
|  | SA147 | 32 Kwords | 460000h-467FFFh |
|  | SA148 | 32 Kwords | 468000h-46FFFFh |
|  | SA149 | 32 Kwords | 470000h-477FFFh |
|  | SA150 | 32 Kwords | 478000h-47FFFFh |
|  | SA151 | 32 Kwords | 480000h-487FFFh |
|  | SA152 | 32 Kwords | 488000h-48FFFFh |
|  | SA153 | 32 Kwords | 490000h-497FFFh |
|  | SA154 | 32 Kwords | 498000h-49FFFFh |
|  | SA155 | 32 Kwords | 4A0000h-4A7FFFh |
|  | SA156 | 32 Kwords | 4A8000h-4AFFFFh |
|  | SA157 | 32 Kwords | 4B0000h-4B7FFFh |
|  | SA158 | 32 Kwords | 4B8000h-4BFFFFh |
|  | SA159 | 32 Kwords | 4C0000h-4C7FFFh |
|  | SA160 | 32 Kwords | 4C8000h-4CFFFFh |
|  | SA161 | 32 Kwords | 4D0000h-4D7FFFh |
|  | SA162 | 32 Kwords | 4D8000h-4DFFFFh |
|  | SA163 | 32 Kwords | 4E0000h-4E7FFFh |
|  | SA164 | 32 Kwords | 4E8000h-4EFFFFh |
|  | SA165 | 32 Kwords | 4F0000h-4F7FFFh |
|  | SA166 | 32 Kwords | 4F8000h-4FFFFFh |

Data Shet

Table I2. WSI28J Sector Address Table (Sheet 6 of 8)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank B | SA167 | 32 Kwords | 500000h-507FFFh |
|  | SA168 | 32 Kwords | 508000h-50FFFFh |
|  | SA169 | 32 Kwords | 510000h-517FFFh |
|  | SA170 | 32 Kwords | 518000h-51FFFFh |
|  | SA171 | 32 Kwords | 520000h-527FFFh |
|  | SA172 | 32 Kwords | 528000h-52FFFFh |
|  | SA173 | 32 Kwords | 530000h-537FFFh |
|  | SA174 | 32 Kwords | 538000h-53FFFFh |
|  | SA175 | 32 Kwords | 540000h-547FFFh |
|  | SA176 | 32 Kwords | 548000h-54FFFFh |
|  | SA177 | 32 Kwords | 550000h-557FFFh |
|  | SA178 | 32 Kwords | 558000h-55FFFFh |
|  | SA179 | 32 Kwords | 560000h-567FFFh |
|  | SA180 | 32 Kwords | 568000h-56FFFFh |
|  | SA181 | 32 Kwords | 570000h-577FFFh |
|  | SA182 | 32 Kwords | 578000h-57FFFFh |
|  | SA183 | 32 Kwords | 580000h-587FFFh |
|  | SA184 | 32 Kwords | 588000h-58FFFFh |
|  | SA185 | 32 Kwords | 590000h-597FFFh |
|  | SA186 | 32 Kwords | 598000h-59FFFFh |
|  | SA187 | 32 Kwords | 5A0000h-5A7FFFh |
|  | SA188 | 32 Kwords | 5A8000h-5AFFFFh |
|  | SA189 | 32 Kwords | 5B0000h-5B7FFFh |
|  | SA190 | 32 Kwords | 5B8000h-5BFFFFh |
|  | SA191 | 32 Kwords | 5C0000h-5C7FFFh |
|  | SA192 | 32 Kwords | 5C8000h-5CFFFFh |
|  | SA193 | 32 Kwords | 5D0000h-5D7FFFh |
|  | SA194 | 32 Kwords | 5D8000h-5DFFFFh |
|  | SA195 | 32 Kwords | 5E0000h-5E7FFFh |
|  | SA196 | 32 Kwords | 5E8000h-5EFFFFh |
|  | SA197 | 32 Kwords | 5F0000h-5F7FFFh |
|  | SA198 | 32 Kwords | 5F8000h-5FFFFFh |

Table I2. WSI28J Sector Address Table (Sheet 7 of 8)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank B | SA199 | 32 Kwords | 600000h-607FFFh |
|  | SA200 | 32 Kwords | 608000h-60FFFFh |
|  | SA201 | 32 Kwords | 610000h-617FFFh |
|  | SA202 | 32 Kwords | 618000h-61FFFFh |
|  | SA203 | 32 Kwords | 620000h-627FFFh |
|  | SA204 | 32 Kwords | 628000h-62FFFFh |
|  | SA205 | 32 Kwords | 630000h-637FFFh |
|  | SA206 | 32 Kwords | 638000h-63FFFFh |
|  | SA207 | 32 Kwords | 640000h-647FFFh |
|  | SA208 | 32 Kwords | 648000h-64FFFFh |
|  | SA209 | 32 Kwords | 650000h-657FFFh |
|  | SA210 | 32 Kwords | 658000h-65FFFFh |
|  | SA211 | 32 Kwords | 660000h-667FFFh |
|  | SA212 | 32 Kwords | 668000h-66FFFFh |
|  | SA213 | 32 Kwords | 670000h-677FFFh |
|  | SA214 | 32 Kwords | 678000h-67FFFFh |
|  | SA215 | 32 Kwords | 680000h-687FFFh |
|  | SA216 | 32 Kwords | 688000h-68FFFFh |
|  | SA217 | 32 Kwords | 690000h-697FFFh |
|  | SA218 | 32 Kwords | 698000h-69FFFFh |
|  | SA219 | 32 Kwords | 6A0000h-6A7FFFh |
|  | SA220 | 32 Kwords | 6A8000h-6AFFFFh |
|  | SA221 | 32 Kwords | 6B0000h-6B7FFFh |
|  | SA222 | 32 Kwords | 6B8000h-6BFFFFh |
|  | SA223 | 32 Kwords | 6C0000h-6C7FFFh |
|  | SA224 | 32 Kwords | 6C8000h-6CFFFFh |
|  | SA225 | 32 Kwords | 6D0000h-6D7FFFh |
|  | SA226 | 32 Kwords | 6D8000h-6DFFFFh |
|  | SA227 | 32 Kwords | 6E0000h-6E7FFFh |
|  | SA228 | 32 Kwords | 6E8000h-6EFFFFh |
|  | SA229 | 32 Kwords | 6F0000h-6F7FFFh |
|  | SA230 | 32 Kwords | 6F8000h-6FFFFFh |

Table I2. WSI28J Sector Address Table (Sheet 8 of 8 )

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank A | SA231 | 32 Kwords | 700000h-707FFFh |
|  | SA232 | 32 Kwords | 708000h-70FFFFh |
|  | SA233 | 32 Kwords | 710000h-717FFFh |
|  | SA234 | 32 Kwords | 718000h-71FFFFh |
|  | SA235 | 32 Kwords | 720000h-727FFFh |
|  | SA236 | 32 Kwords | 728000h-72FFFFh |
|  | SA237 | 32 Kwords | 730000h-737FFFh |
|  | SA238 | 32 Kwords | 738000h-73FFFFh |
|  | SA239 | 32 Kwords | 740000h-747FFFh |
|  | SA240 | 32 Kwords | 748000h-74FFFFh |
|  | SA241 | 32 Kwords | 750000h-757FFFh |
|  | SA242 | 32 Kwords | 758000h-75FFFFh |
|  | SA243 | 32 Kwords | 760000h-767FFFh |
|  | SA244 | 32 Kwords | 768000h-76FFFFh |
|  | SA245 | 32 Kwords | 770000h-777FFFh |
|  | SA246 | 32 Kwords | 778000h-77FFFFh |
|  | SA247 | 32 Kwords | 780000h-787FFFh |
|  | SA248 | 32 Kwords | 788000h-78FFFFh |
|  | SA249 | 32 Kwords | 790000h-797FFFh |
|  | SA250 | 32 Kwords | 798000h-79FFFFh |
|  | SA251 | 32 Kwords | 7A0000h-7A7FFFh |
|  | SA252 | 32 Kwords | 7A8000h-7AFFFFh |
|  | SA253 | 32 Kwords | 7B0000h-7B7FFFh |
|  | SA254 | 32 Kwords | 7B8000h-7BFFFFh |
|  | SA255 | 32 Kwords | 7C0000h-7C7FFFh |
|  | SA256 | 32 Kwords | 7C8000h-7CFFFFh |
|  | SA257 | 32 Kwords | 7D0000h-7D7FFFh |
|  | SA258 | 32 Kwords | 7D8000h-7DFFFFh |
|  | SA259 | 32 Kwords | 7E0000h-7E7FFFh |
|  | SA260 | 32 Kwords | 7E8000h-7EFFFFh |
|  | SA261 | 32 Kwords | 7F0000h-7F7FFFh |
|  | SA262 | 4 Kwords | 7F8000h-7F8FFFh |
|  | SA263 | 4 Kwords | 7F9000h-7F9FFFh |
|  | SA264 | 4 Kwords | 7FA000h-7FAFFFh |
|  | SA265 | 4 Kwords | 7FB000h-7FBFFFh |
|  | SA266 | 4 Kwords | 7FC000h-7FCFFFh |
|  | SA267 | 4 Kwords | 7FD000h-7FDFFFh |
|  | SA268 | 4 Kwords | 7FE000h-7FEFFFh |
|  | SA269 | 4 Kwords | 7FF000h-7FFFFFh |

Table I3. WS064J Sector Address Table (Sheet I of 6)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank D | SA0 | 4 Kwords | 000000h-000FFFh |
|  | SA1 | 4 Kwords | 001000h-001FFFh |
|  | SA2 | 4 Kwords | 002000h-002FFFh |
|  | SA3 | 4 Kwords | 003000h-003FFFh |
|  | SA4 | 4 Kwords | 004000h-004FFFh |
|  | SA5 | 4 Kwords | 005000h-005FFFh |
|  | SA6 | 4 Kwords | 006000h-006FFFh |
|  | SA7 | 4 Kwords | 007000h-007FFFh |
|  | SA8 | 32 Kwords | 008000h-00FFFFh |
|  | SA9 | 32 Kwords | 010000h-017FFFh |
|  | SA10 | 32 Kwords | 018000h-01FFFFh |
|  | SA11 | 32 Kwords | 020000h-027FFFh |
|  | SA12 | 32 Kwords | 028000h-02FFFFh |
|  | SA13 | 32 Kwords | 030000h-037FFFh |
|  | SA14 | 32 Kwords | 038000h-03FFFFh |
|  | SA15 | 32 Kwords | 040000h-047FFFh |
|  | SA16 | 32 Kwords | 048000h-04FFFFh |
|  | SA17 | 32 Kwords | 050000h-057FFFh |
|  | SA18 | 32 Kwords | 058000h-05FFFFh |
|  | SA19 | 32 Kwords | 060000h-067FFFh |
|  | SA20 | 32 Kwords | 068000h-06FFFFh |
|  | SA21 | 32 Kwords | 070000h-077FFFh |
|  | SA22 | 32 Kwords | 078000h-07FFFFh |

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Table 13. WS064J Sector Address Table (Sheet 2 of 6)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank C | SA23 | 32 Kwords | 080000h-087FFFh |
|  | SA24 | 32 Kwords | 088000h-08FFFFh |
|  | SA25 | 32 Kwords | 090000h-097FFFh |
|  | SA26 | 32 Kwords | 098000h-09FFFFh |
|  | SA27 | 32 Kwords | 0A0000h-0A7FFFh |
|  | SA28 | 32 Kwords | 0A8000h-0AFFFFh |
|  | SA29 | 32 Kwords | 0B0000h-0B7FFFh |
|  | SA30 | 32 Kwords | 0B8000h-0BFFFFh |
|  | SA31 | 32 Kwords | 0C0000h-0C7FFFh |
|  | SA32 | 32 Kwords | 0C8000h-0CFFFFh |
|  | SA33 | 32 Kwords | 0D0000h-0D7FFFh |
|  | SA34 | 32 Kwords | 0D8000h-0DFFFFh |
|  | SA35 | 32 Kwords | 0E0000h-0E7FFFh |
|  | SA36 | 32 Kwords | OE8000h-0EFFFFh |
|  | SA37 | 32 Kwords | 0F0000h-0F7FFFh |
|  | SA38 | 32 Kwords | 0F8000h-0FFFFFh |
|  | SA39 | 32 Kwords | 100000h-107FFFh |
|  | SA40 | 32 Kwords | 108000h-10FFFFh |
|  | SA41 | 32 Kwords | 110000h-117FFFh |
|  | SA42 | 32 Kwords | 118000h-11FFFFh |
|  | SA43 | 32 Kwords | 120000h-127FFFh |
|  | SA44 | 32 Kwords | 128000h-12FFFFh |
|  | SA45 | 32 Kwords | 130000h-137FFFh |
|  | SA46 | 32 Kwords | 138000h-13FFFFh |

Table 13. WS064J Sector Address Table (Sheet 3 of 6)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank C | SA47 | 32 Kwords | 140000h-147FFFh |
|  | SA48 | 32 Kwords | 148000h-14FFFFh |
|  | SA49 | 32 Kwords | 150000h-157FFFh |
|  | SA50 | 32 Kwords | 158000h-15FFFFh |
|  | SA51 | 32 Kwords | 160000h-167FFFh |
|  | SA52 | 32 Kwords | 168000h-16FFFFh |
|  | SA53 | 32 Kwords | 170000h-177FFFh |
|  | SA54 | 32 Kwords | 178000h-17FFFFh |
|  | SA55 | 32 Kwords | 180000h-187FFFh |
|  | SA56 | 32 Kwords | 188000h-18FFFFh |
|  | SA57 | 32 Kwords | 190000h-197FFFh |
|  | SA58 | 32 Kwords | 198000h-19FFFFh |
|  | SA59 | 32 Kwords | 1A0000h-1A7FFFh |
|  | SA60 | 32 Kwords | 1A8000h-1AFFFFh |
|  | SA61 | 32 Kwords | 1B0000h-1B7FFFh |
|  | SA62 | 32 Kwords | 1B8000h-1BFFFFh |
|  | SA63 | 32 Kwords | 1C0000h-1C7FFFh |
|  | SA64 | 32 Kwords | 1C8000h-1CFFFFh |
|  | SA65 | 32 Kwords | 1D0000h-1D7FFFh |
|  | SA66 | 32 Kwords | 1D8000h-1DFFFFh |
|  | SA67 | 32 Kwords | 1E0000h-1E7FFFh |
|  | SA68 | 32 Kwords | 1E8000h-1EFFFFh |
|  | SA69 | 32 Kwords | 1F0000h-1F7FFFh |
|  | SA70 | 32 Kwords | 1F8000h-1FFFFFh |

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Table I3. WS064J Sector Address Table (Sheet 4 of 6)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank B | SA71 | 32 Kwords | 200000h-207FFFh |
|  | SA72 | 32 Kwords | 208000h-20FFFFh |
|  | SA73 | 32 Kwords | 210000h-217FFFh |
|  | SA74 | 32 Kwords | 218000h-21FFFFh |
|  | SA75 | 32 Kwords | 220000h-227FFFh |
|  | SA76 | 32 Kwords | 228000h-22FFFFh |
|  | SA77 | 32 Kwords | 230000h-237FFFh |
|  | SA78 | 32 Kwords | 238000h-23FFFFh |
|  | SA79 | 32 Kwords | 240000h-247FFFh |
|  | SA80 | 32 Kwords | 248000h-24FFFFh |
|  | SA81 | 32 Kwords | 250000h-257FFFh |
|  | SA82 | 32 Kwords | 258000h-25FFFFh |
|  | SA83 | 32 Kwords | 260000h-267FFFh |
|  | SA84 | 32 Kwords | 268000h-26FFFFh |
|  | SA85 | 32 Kwords | 270000h-277FFFh |
|  | SA86 | 32 Kwords | 278000h-27FFFFh |
|  | SA87 | 32 Kwords | 280000h-287FFFh |
|  | SA88 | 32 Kwords | 288000h-28FFFFh |
|  | SA89 | 32 Kwords | 290000h-297FFFh |
|  | SA90 | 32 Kwords | 298000h-29FFFFh |
|  | SA91 | 32 Kwords | 2A0000h-2A7FFFh |
|  | SA92 | 32 Kwords | 2A8000h-2AFFFFh |
|  | SA93 | 32 Kwords | 2B0000h-2B7FFFh |
|  | SA94 | 32 Kwords | 2B8000h-2BFFFFh |

Table I3. WS064J Sector Address Table (Sheet 5 of 6)

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank B | SA95 | 32 Kwords | 2C0000h-2C7FFFh |
|  | SA96 | 32 Kwords | 2C8000h-2CFFFFh |
|  | SA97 | 32 Kwords | 2D0000h-2D7FFFh |
|  | SA98 | 32 Kwords | 2D8000h-2DFFFFh |
|  | SA99 | 32 Kwords | 2E0000h-2E7FFFh |
|  | SA100 | 32 Kwords | 2E8000h-2EFFFFh |
|  | SA101 | 32 Kwords | 2F0000h-2F7FFFh |
|  | SA102 | 32 Kwords | 2F8000h-2FFFFFh |
|  | SA103 | 32 Kwords | 300000h-307FFFh |
|  | SA104 | 32 Kwords | 308000h-30FFFFh |
|  | SA105 | 32 Kwords | 310000h-317FFFh |
|  | SA106 | 32 Kwords | 318000h-31FFFFh |
|  | SA107 | 32 Kwords | 320000h-327FFFh |
|  | SA108 | 32 Kwords | 328000h-32FFFFh |
|  | SA109 | 32 Kwords | 330000h-337FFFh |
|  | SA110 | 32 Kwords | 338000h-33FFFFh |
|  | SA111 | 32 Kwords | 340000h-347FFFh |
|  | SA112 | 32 Kwords | 348000h-34FFFFh |
|  | SA113 | 32 Kwords | 350000h-357FFFh |
|  | SA114 | 32 Kwords | 358000h-35FFFFh |
|  | SA115 | 32 Kwords | 360000h-367FFFh |
|  | SA116 | 32 Kwords | 368000h-36FFFFh |
|  | SA117 | 32 Kwords | 370000h-377FFFh |
|  | SA118 | 32 Kwords | 378000h-37FFFFh |

Table I3. WS064J Sector Address Table (Sheet 6 of 6 )

| Bank | Sector | Sector Size | (x16) Address Range |
| :---: | :---: | :---: | :---: |
| Bank A | SA119 | 32 Kwords | 380000h-387FFFh |
|  | SA120 | 32 Kwords | 388000h-38FFFFh |
|  | SA121 | 32 Kwords | 390000h-397FFFh |
|  | SA122 | 32 Kwords | 398000h-39FFFFh |
|  | SA123 | 32 Kwords | 3A0000h-3A7FFFh |
|  | SA124 | 32 Kwords | 3A8000h-3AFFFFh |
|  | SA125 | 32 Kwords | 3B0000h-3B7FFFh |
|  | SA126 | 32 Kwords | 3B8000h-3BFFFFh |
|  | SA127 | 32 Kwords | 3C0000h-3C7FFFh |
|  | SA128 | 32 Kwords | 3C8000h-3CFFFFh |
|  | SA129 | 32 Kwords | 3D0000h-3D7FFFh |
|  | SA130 | 32 Kwords | 3D8000h-3DFFFFh |
|  | SA131 | 32 Kwords | 3E0000h-3E7FFFh |
|  | SA132 | 32 Kwords | 3E8000h-3EFFFFh |
|  | SA133 | 32 Kwords | 3F0000h-3F7FFFh |
|  | SA134 | 4 Kwords | 3F8000h-3F8FFFh |
|  | SA135 | 4 Kwords | 3F9000h-3F9FFFh |
|  | SA136 | 4 Kwords | 3FA000h-3FAFFFh |
|  | SA137 | 4 Kwords | 3FB000h-3FBFFFh |
|  | SA138 | 4 Kwords | 3FC000h-3FCFFFh |
|  | SA139 | 4 Kwords | 3FD000h-3FDFFFh |
|  | SA140 | 4 Kwords | 3FE000h-3FEFFFh |
|  | SA141 | 4 Kwords | 3FF000h-3FFFFFh |

## Command Definitions

Writing specific address and data commands or sequences into the command register initiates device operations. Table 18, "Command Definitions," on page 60 defines the valid register command sequences. Writing incorrect address and data values or writing them in the improper sequence may place the device in an unknown state. The system must write the reset command to return the device to reading array data. Refer to the AC Characteristics section for timing diagrams.

## Reading Array Data

The device is automatically set to reading array data after device power-up. No commands are required to retrieve data in asynchronous mode. Each bank is ready to read array data after completing an Embedded Program or Embedded Erase algorithm.
After the device accepts an Erase Suspend command, the corresponding bank enters the erase-suspend-read mode, after which the system can read data from any non-erase-suspended sector within the same bank. After completing a programming operation in the Erase Suspend mode, the system may once again read array data from any non-erase-suspended sector within the same bank. See the "Erase Suspend/Erase Resume Commands" section on page 55 for more information.

The system must issue the reset command to return a bank to the read (or erase-suspend-read) mode if DQ5 goes high during an active program or erase operation, or if the bank is in the autoselect mode. See the "Reset Command" section on page 51 for more information.

See also "Requirements for Asynchronous ReadOperation (Non-Burst)" section on page 14 and "Requirements for Synchronous (Burst) Read Operation" section on page 14 for more information. The Asynchronous Read and Synchronous/Burst Read tables provide the read parameters, and Figure 15, "CLK Synchronous Burst Mode Read (rising active CLK)," on page 74, Figure 17, "Synchronous Burst Mode Read," on page 75, and Figure 20, "Asynchronous Mode Read with Latched Addresses," on page 77 show the timings.

## Set Configuration Register Command Sequence

The device uses a configuration register to set the various burst parameters: number of wait states, burst read mode, active clock edge, RDY configuration, and synchronous mode active. The configuration register must be set before the device will enter burst mode.
The configuration register is loaded with a three-cycle command sequence. The first two cycles are standard unlock sequences. On the third cycle, the data should be COh, address bits A11-A0 should be 555h, and address bits A19-A12 set the code to be latched. The device will power up or after a hardware reset with the default setting, which is in asynchronous mode. The register must be set before the device can enter synchronous mode. The configuration register can not be changed during device operations (program, erase, or sector lock).


Figure 4. Synchronous/Asynchronous State Diagram

## Read Mode Setting

On power-up or hardware reset, the device is set to be in asynchronous read mode. This setting allows the system to enable or disable burst mode during system operations. Address A19 determines this setting: "1" for asynchronous mode, " 0 " for synchronous mode.

## Programmable Wait State Configuration

The programmable wait state feature informs the device of the number of clock cycles that must elapse after AVD\# is driven active before data will be available. This value is determined by the input frequency of the device. Address bits A14-A12 determine the setting (see Table 14, "Programmable Wait State Settings," on page 49).

The wait state command sequence instructs the device to set a particular number of clock cycles for the initial access in burst mode. The number of wait states that should be programmed into the device is directly related to the clock frequency.

Table 14. Programmable Wait State Settings

| AI4 | Al3 | Al2 | Total Initial Access Cycles |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 2 |
| 0 | 0 | 1 | 3 |
| 0 | 1 | 0 | 4 |
| 0 | 1 | 1 | 5 |
| 1 | 0 | 0 | 6 |
| 1 | 0 | 1 | 7 (default) |
| 1 | 1 | 0 | Reserved |
| 1 | 1 | Reserved |  |

## Notes:

1. Upon power-up or hardware reset, the default setting is seven wait states.
2. RDY will default to being active with data when the Wait State Setting is set to a total initial access cycle of 2.

It is recommended that the wait state command sequence be written, even if the default wait state value is desired, to ensure the device is set as expected. A hardware reset will set the wait state to the default setting.

## Standard wait-state Handshaking Option

The host system must set the appropriate number of wait states in the flash device depending upon the clock frequency. The host system should set address bits A14-A12 to 010 for a clock frequency of $66 / 80 \mathrm{MHz}$ for the system/device to execute at maximum speed.

Table 15 describes the recommended number of clock cycles (wait states) for various conditions.
Table 15. Wait States for Standard wait-state Handshaking

| Burst Mode | Typical No. of Clock Cycles after AVD\# Low |  |
| :--- | :---: | :---: |
|  | $\mathbf{6 6 ~ M H z}$ | $\mathbf{8 0} \mathbf{~ M H z}$ |
| 8-Word or 16-Word or Continuous | 4 | 6 or $\mathbf{7}$ |
| 32-Word | 5 | 7 |

## Notes:

1. In the 8-, 16- and 32 -word burst read modes, the address pointer does not cross 64-word boundaries (addresses which are multiples of 3Fh).
2. For WS128J model numbers 10 and 11, an additional clock cycle is required for boundary crossings while in Continuous read mode.

The host system must set the appropriate number of wait states in the flash device depending upon the clock frequency. Note that the host system must set again the number of wait state when the host system change the clock frequency. For example, the host system must set from 6 or 7 wait state to less than 5 wait states when the host system change the clock frequency from 80 MHz to less than 80 MHz . The autoselect function allows the host system to determine whether the flash device is enabled for handshaking. See the "Autoselect Command Sequence" section on page 51 for more information.

## Read Mode Configuration

The device supports four different read modes: continuous mode, and 8, 16, and 32 word linear wrap around modes. A continuous sequence begins at the starting address and advances the address pointer until the burst operation is complete. If the highest address in the device is reached during the continuous burst read mode, the address pointer wraps around to the lowest address.
For example, an eight-word linear read with wrap around begins on the starting address written to the device and then advances to the next 8 word boundary. The address pointer then returns to the 1 st word after the previous eight word boundary, wrapping through the starting location. The sixteen- and thirty-two linear wrap around modes operate in a fashion similar to the eightword mode.

Table 16 shows the address bits and settings for the four read modes.
Table 16. Read Mode Settings

| Burst Modes | Address Bits |  |
| :--- | :---: | :---: |
|  | Al6 | Al5 |
| Continuous | 0 | 0 |
| 8-word linear wrap around | 0 | 1 |
| 16-word linear wrap around | 1 | 0 |
| 32-word linear wrap around | 1 | 1 |

Note: Upon power-up or hardware reset the default setting is continuous.

## Burst Active Clock Edge Configuration

By default, the device will deliver data on the rising edge of the clock after the initial synchronous access time. Subsequent outputs will also be on the following rising edges, barring any delays. The device can be set so that the falling clock edge is active for all synchronous accesses. Address bit A17 determines this setting; "1" for rising active, " 0 " for falling active.

## RDY Configuration

By default, the device is set so that the RDY pin will output $\mathrm{V}_{\mathrm{OH}}$ whenever there is valid data on the outputs. The device can be set so that RDY goes active one data cycle before active data. Address bit A18 determines this setting; "1" for RDY active with data, " 0 " for RDY active one clock cycle before valid data. Only the combination of wait state 2 and RDY active one clock cycle before data is not supported. In asynchronous mode, RDY is an open-drain output.

## Configuration Register

Table 17 shows the address bits that determine the configuration register settings for various device functions.

Table 17. Configuration Register

| Address Bit | Function | Settings (Binary) |
| :---: | :---: | :---: |
| A19 | Set Device Read Mode | $0=$ Synchronous Read (Burst Mode) Enabled 1 = Asynchronous Mode (default) |
| A18 | RDY | $0=$ RDY active one clock cycle before data 1 = RDY active with data (default) |
| A17 | Clock | $0=$ Burst starts and data is output on the falling edge of CLK <br> 1 = Burst starts and data is output on the rising edge of CLK (default) |
| A16 |  | Synchronous Mode |
| A15 | Read Mode | $00=$ Continuous (default) <br> $01=8$-word linear with wrap around <br> $10=16$-word linear with wrap around <br> 11 = 32-word linear with wrap around |
| A14 |  | 000 = Data is valid on the 2nd active CLK edge after AVD\# transition to $\mathrm{V}_{\text {IH }}$ |
| A13 |  | 001 = Data is valid on the 3rd active CLK edge after AVD\# transition to $\mathrm{V}_{\mathrm{IH}}$ <br> $010=$ Data is valid on the 4th active CLK edge after AVD\# transition to $\mathrm{V}_{\mathrm{IH}}$ |
| A12 | Programmable Wait State | 011 = Data is valid on the 5th active CLK edge after AVD\# transition to $\mathrm{V}_{\mathrm{IH}}$ <br> $100=$ Data is valid on the 6th active CLK edge after AVD\# transition to $\mathrm{V}_{\mathrm{IH}}$ <br> 101 = Data is valid on the 7th active CLK edge after AVD\# transition to $\mathrm{V}_{\mathrm{IH}}$ (default) <br> 110 = Reserved <br> 111 = Reserved |

Note: Device is in the default state upon power-up or hardware reset.

## Reset Command

Writing the reset command resets the banks to the read or erase-suspend-read mode. Address bits are don't cares for this command.

The reset command may be written between the sequence cycles in an erase command sequence before erasing begins. This resets the bank to which the system was writing to the read mode. Once erasure begins, however, the device ignores reset commands until the operation is complete.
The reset command may be written between the sequence cycles in a program command sequence before programming begins (prior to the third cycle). This resets the bank to which the system was writing to the read mode. If the program command sequence is written to a bank that is in the Erase Suspend mode, writing the reset command returns that bank to the erase-sus-pend-read mode. Once programming begins, however, the device ignores reset commands until the operation is complete.
The reset command may be written between the sequence cycles in an autoselect command sequence. Once in the autoselect mode, the reset command must be written to return to the read mode. If a bank entered the autoselect mode while in the Erase Suspend mode, writing the reset command returns that bank to the erase-suspend-read mode.

If DQ5 goes high during a program or erase operation, writing the reset command returns the banks to the read mode (or erase-suspend-read mode if that bank was in Erase Suspend).

## Autoselect Command Sequence

The autoselect command sequence allows the host system to access the manufacturer and device codes, and determine whether or not a sector is protected. Table 18, "Command Definitions," on page 60 shows the address and data requirements. The autoselect command sequence may be
written to an address within a bank that is either in the read or erase-suspend-read mode. The autoselect command may not be written while the device is actively programming or erasing in the other bank.

The autoselect command sequence is initiated by first writing two unlock cycles. This is followed by a third write cycle that contains the bank address and the autoselect command. The bank then enters the autoselect mode. No subsequent data will be made available if the autoselect data is read in synchronous mode. The system may read at any address within the same bank any number of times without initiating another autoselect command sequence. Read commands to other banks will return data from the array. The following table describes the address requirements for the various autoselect functions, and the resulting data. BA represents the bank address, and SA represents the sector address. The device ID is read in three cycles.

| Description | Address | Read Data |
| :---: | :---: | :---: |
| Manufacturer ID | (BA) + 00h | 0001h |
| Device ID, Word 1 | $(B A)+01 \mathrm{~h}$ | 227Eh |
| Device ID, Word 2 | $(B A)+0 E h$ | $\begin{aligned} & \text { 2218h (WS128J) } \\ & \text { 221Eh (WS064J) } \end{aligned}$ |
| Device ID, Word 3 | $(B A)+0 F h$ | $\begin{aligned} & \text { 2200h (WS128J) } \\ & \text { 2201h (WS064J) } \end{aligned}$ |
| Sector Protection Verification | $(S A)+02 h$ | 0001 (locked), 0000 (unlocked) |
| Indicator Bits | $(B A)+03 \mathrm{~h}$ | $\text { DQ15 - DQ8 = } 0$ <br> DQ7 - Factory Lock Bit 1 = Locked, $0=$ Not Locked DQ6 -Customer Lock Bit 1 = Locked, $0=$ Not Locked DQ5 - Handshake Bit 1 = Reserved, 0 = Standard Handshake DQ4 \& DQ3 - Boot Code 00 = Dual Boot Sector, 01 = Top Boot Sector, 10 = Bottom Boot Sector DQ2 - DQ0 = 001 |

The system must write the reset command to return to the read mode (or erase-suspend-read mode if the bank was previously in Erase Suspend).

## Enter Secured Silicon Sector/Exit Secured Silicon Sector Command Sequence

The Secured Silicon Sector region provides a secured data area containing a random, eight word electronic serial number (ESN). The system can access the Secured Silicon Sector region by issuing the three-cycle Enter Secured Silicon Sector command sequence. The device continues to access the Secured Silicon Sector region until the system issues the four-cycle Exit Secured Silicon Sector command sequence. The Exit Secured Silicon Sector command sequence returns the device to normal operation. The Secured Silicon Sector is not accessible when the device is executing an Embedded Program or embedded Erase algorithm. Table 18, "Command Definitions," on page 60 shows the address and data requirements for both command sequences.

The following commands are not allowed when the Secured Silicon is accessible.

- CFI

■ Unlock Bypass Entry
■ Unlock Bypass Program
■ Unlock Bypass Reset
■ Erase Suspend/Resume

- Chip Erase


## Program Command Sequence

Programming is a four-bus-cycle operation. The program command sequence is initiated by writing two unlock write cycles, followed by the program set-up command. The program address and data are written next, which in turn initiate the Embedded Program algorithm. The system is not required to provide further controls or timings. The device automatically provides internally generated program pulses and verifies the programmed cell margin. Table 18, "Command Definitions," on page 60 shows the address and data requirements for the program command sequence.

When the Embedded Program algorithm is complete, that bank then returns to the read mode and addresses are no longer latched. The system can determine the status of the program operation by monitoring DQ7 or DQ6/DQ2. Refer to the "Write Operation Status" section on page 62 for information on these status bits.

Any commands written to the device during the Embedded Program Algorithm are ignored. Note that a hardware reset immediately terminates the program operation. The program command sequence should be reinitiated once that bank has returned to the read mode, to ensure data integrity.
Programming is allowed in any sequence and across sector boundaries. A bit cannot be programmed from "0" back to a "1." Attempting to do so may cause that bank to set DQ5 = 1, or cause the DQ7 and DQ6 status bit to indicate the operation was successful. However, a succeeding read will show that the data is still "0." Only erase operations can convert a "0" to a "1."

## Unlock Bypass Command Sequence

The unlock bypass feature allows the system to primarily program to a array faster than using the standard program command sequence. The unlock bypass command sequence is initiated by first writing two unlock cycles. This is followed by a third write cycle containing the unlock bypass command, 20h. The device then enters the unlock bypass mode. A two-cycle unlock bypass program command sequence is all that is required to program in this mode. The first cycle in this sequence contains the unlock bypass program command, AOh; the second cycle contains the program address and data. Additional data is programmed in the same manner. This mode dispenses with the initial two unlock cycles required in the standard program command sequence, resulting in faster total programming time. The host system may also initiate the chip erase and sector erase sequences in the unlock bypass mode. The erase command sequences are four cycles in length instead of six cycles. Table 18, "Command Definitions," on page 60 shows the requirements for the unlock bypass command sequences.

During the unlock bypass mode, only the Read, Unlock Bypass Program, Unlock Bypass Sector Erase, Unlock Bypass Chip Erase, and Unlock Bypass Reset commands are valid. To exit the unlock bypass mode, the system must issue the two-cycle unlock bypass reset command sequence. The first cycle must contain the bank address and the data 90 h . The second cycle need only contain the data 00 h . The array then returns to the read mode.

The device offers accelerated program operations through the ACC input. When the system asserts $\mathrm{V}_{\mathrm{HH}}$ on this input, the device automatically enters the Unlock Bypass mode. The system may then write the two-cycle Unlock Bypass program command sequence. The device uses the higher voltage on the ACC input to accelerate the operation.

Figure 5, "Program Operation," on page 54 illustrates the algorithm for the program operation. Refer to the Erase/Program Operations table in the AC Characteristics section for parameters, and Figure 23, "Asynchronous Program Operation Timings: AVD\# Latched Addresses," on page 81 and Figure 25, "Synchronous Program Operation Timings: WE\# Latched Addresses," on page 83 for timing diagrams.


Note: See Table 18 for program command sequence.
Figure 5. Program Operation

## Chip Erase Command Sequence

Chip erase is a six bus cycle operation. The chip erase command sequence is initiated by writing two unlock cycles, followed by a set-up command. Two additional unlock write cycles are then followed by the chip erase command, which in turn invokes the Embedded Erase algorithm. The device does not require the system to preprogram prior to erase. The Embedded Erase algorithm automatically preprograms and verifies the entire memory for an all zero data pattern prior to electrical erase. The system is not required to provide any controls or timings during these operations. Table 18, "Command Definitions," on page 60 shows the address and data requirements for the chip erase command sequence.

When the Embedded Erase algorithm is complete, that bank returns to the read mode and addresses are no longer latched. The system can determine the status of the erase operation by using DQ7 or DQ6/DQ2. Refer to the "Write Operation Status" section on page 62 for information on these status bits.

Any commands written during the chip erase operation are ignored. However, note that a hardware reset immediately terminates the erase operation. If that occurs, the chip erase command sequence should be reinitiated once that bank has returned to reading array data, to ensure data integrity.

The host system may also initiate the chip erase command sequence while the device is in the unlock bypass mode. The command sequence is two cycles cycles in length instead of six cycles. See Table 18, "Command Definitions," on page 60 for details on the unlock bypass command sequences.

Figure 6, "Erase Operation," on page 56 illustrates the algorithm for the erase operation. Refer to the Erase/Program Operations table in the AC Characteristics section for parameters and timing diagrams.

## Sector Erase Command Sequence

Sector erase is a six bus cycle operation. The sector erase command sequence is initiated by writing two unlock cycles, followed by a set-up command. Two additional unlock cycles are written, and are then followed by the address of the sector to be erased, and the sector erase command. Table 18, "Command Definitions," on page 60 shows the address and data requirements for the sector erase command sequence.

The device does not require the system to preprogram prior to erase. The Embedded Erase algorithm automatically programs and verifies the entire memory for an all zero data pattern prior to electrical erase. The system is not required to provide any controls or timings during these operations.
After the command sequence is written, a sector erase time-out of no less than $50 \mu \mathrm{~s}$ occurs. During the time-out period, additional sector addresses and sector erase commands may be written. Loading the sector erase buffer may be done in any sequence, and the number of sectors may be from one sector to all sectors. The time between these additional cycles must be less than $50 \mu \mathrm{~s}$, otherwise erasure may begin. Any sector erase address and command following the exceeded time-out may or may not be accepted. It is recommended that processor interrupts be disabled during this time to ensure all commands are accepted. The interrupts can be re-enabled after the last Sector Erase command is written. If any command other than 30h, BOh, FOh is input during the time-out period, the normal operation will not be guaranteed.
The system can monitor DQ3 to determine if the sector erase timer has timed out (See "DQ3: Sector Erase Timer" section on page 67.) The time-out begins from the rising edge of the final WE\# pulse in the command sequence.
When the Embedded Erase algorithm is complete, the bank returns to reading array data and addresses are no longer latched. Note that while the Embedded Erase operation is in progress, the system can read data from the non-erasing bank. The system can determine the status of the erase operation by reading DQ7 or DQ6/DQ2 in the erasing bank. Refer to the "Write Operation Status" section on page 62 for information on these status bits.
Once the sector erase operation has begun, only the Erase Suspend command is valid. All other commands are ignored. However, note that a hardware reset immediately terminates the erase operation. If that occurs, the sector erase command sequence should be reinitiated once that bank has returned to reading array data, to ensure data integrity.

The host system may also initiate the sector erase command sequence while the device is in the unlock bypass mode. The command sequence is four cycles cycles in length instead of six cycles.
Figure 6, "Erase Operation," on page 56 illustrates the algorithm for the erase operation. Refer to the Erase/Program Operations table in the AC Characteristics on page 72 for parameters and timing diagrams.

## Erase Suspend/Erase Resume Commands

The Erase Suspend command, B0h, allows the system to interrupt a sector erase operation and then read data from, or program data to, any sector not selected for erasure. The bank address is required when writing this command. This command is valid only during the sector erase op-
eration, including the minimum $50 \mu$ s time-out period during the sector erase command sequence. The Erase Suspend command is ignored if written during the chip erase operation or Embedded Program algorithm.

When the Erase Suspend command is written during the sector erase operation, the device requires a maximum of $35 \mu$ s to suspend the erase operation. However, when the Erase Suspend command is written during the sector erase time-out, the device immediately terminates the time-out period and suspends the erase operation.

After the erase operation has been suspended, the bank enters the erase-suspend-read mode. The system can read data from or program data to any sector not selected for erasure. (The device "erase suspends" all sectors selected for erasure.) Reading at any address within erasesuspended sectors produces status information on DQ7-DQ0. The system can use DQ7, or DQ6 and DQ2 together, to determine if a sector is actively erasing or is erase-suspended. Refer to the Figure, "Write Operation Status," on page 62 for information on these status bits.

After an erase-suspended program operation is complete, the bank returns to the erase-suspendread mode. The system can determine the status of the program operation using the DQ7 or DQ6 status bits, just as in the standard program operation. Refer to the "Write Operation Status" section on page 62 for more information.

In the erase-suspend-read mode, the system can also issue the autoselect command sequence. Refer to the "Autoselect Mode" section on page 17 and "Autoselect Command Sequence" section on page 51 for details.
To resume the sector erase operation, the system must write the Erase Resume command. The bank address of the erase-suspended bank is required when writing this command. Further writes of the Resume command are ignored. Another Erase Suspend command can be written after the chip has resumed erasing.


## Notes:

1. See Table 18 for erase command sequence.
2. See the section on DQ3 for information on the sector erase timer

Figure 6. Erase Operation

## Password Program Command

The Password Program Command permits programming the password that is used as part of the hardware protection scheme. The actual password is 64-bits long. 4 Password Program commands are required to program the password. The user must enter the unlock cycle, password program command (38h) and the program address/data for each portion of the password when programming. There are no provisions for entering the 2 -cycle unlock cycle, the password program command, and all the password data. There is no special addressing order required for programming the password. Also, when the password is undergoing programming, Simultaneous Operation is disabled. Read operations to any memory location will return the programming status except DQ7. Once programming is complete, the user must issue a Read/Reset command to the device to normal operation. Once the Password is written and verified, the Password Mode Locking Bit must be set in order to prevent verification. The Password Program Command is only capable of programming " 0 "s. Programming a " 1 " after a cell is programmed as a " 0 " results in a timeout by the Embedded Program Algorithm ${ }^{T M}$ with the cell remaining as a " 0 ". The password is all F's when shipped from the factory. All 64-bit password combinations are valid as a password.

## Password Verify Command

The Password Verify Command is used to verify the Password. The Password is verifiable only when the Password Mode Locking Bit is not programmed. If the Password Mode Locking Bit is programmed and the user attempts to verify the Password, the device will always drive all F's onto the DQ data bus.

Also, the device will not operate in Simultaneous Operation when the Password Verify command is executed. Only the password is returned regardless of the bank address. The lower two address bits (A1-A0) are valid during the Password Verify. Writing the Secured Silicon Exit command returns the device back to normal operation.

## Password Protection Mode Locking Bit Program Command

The Password Protection Mode Locking Bit Program Command programs the Password Protection Mode Locking Bit, which prevents further verifies or updates to the password. Once programmed, the Password Protection Mode Locking Bit cannot be erased and the Persistent Protection Mode Locking Bit program circuitry is disabled, thereby forcing the device to remain in the Password Protection Mode. After issuing "PL/68h" at the fourth bus cycle, the device requires a time out period of approximately $150 \mu$ s for programming the Password Protection Mode Locking Bit. Then by writing "PL/48h" at the fifth bus cycle, the device outputs verify data at DQO. If DQ0 $=1$, then the Password Protection Mode Locking Bit is programmed. If not, the system must repeat this program sequence from the fourth cycle of "PL/68h". Exiting the Password Protection Mode Locking Bit Program command is accomplished by writing the Secured Silicon Sector Exit command or Read/Reset command.

## Persistent Sector Protection Mode Locking Bit Program Command

The Persistent Sector Protection Mode Locking Bit Program Command programs the Persistent Sector Protection Mode Locking Bit, which prevents the Password Mode Locking Bit from ever being programmed. By disabling the program circuitry of the Password Mode Locking Bit, the device is forced to remain in the Persistent Sector Protection mode of operation, once this bit is set. After issuing "SL/68h" at the fourth bus cycle, the device requires a time out period of approximately $150 \mu \mathrm{~s}$ for programming the Persistent Protect ion Mode Locking Bit. Then by writ ing "SMPL/48h" at the fifth bus cycle, the device outputs verify data at DQ0. If DQ0 $=1$, then the Persistent Protection Mode Locking Bit is programmed. If not, the system must repeat this program sequence from the fourth cycle of "PL/68h". Exiting the Persistent Protection Mode Locking Bit Program command is accomplished by writing the Secured Silicon Sector Exit command or Read/Reset command.

## Secured Silicon Sector Protection Bit Program Command

To protect the Secured Silicon Sector, write the Secured Silicon Sector Protect command sequence while in the Secured Silicon Sector mode. After issuing "OW/48h" at the fourth bus cycle, the device requires a time out period of approximately $150 \mu$ s to protect the Secured Silicon Sector. Then, by writing "OPBP/48" at the fifth bus cycle, the device outputs verify data at DQ0. If DQ0 $=1$, then the Secured Silicon Sector is protected. If not, then the system must repeat this program sequence from the fourth cycle of "OPBP/48h". Exiting the Secured Silicon Sector Protection Mode Locking Bit Program command is accomplished by writing the Secured Silicon Sector Exit command or Read/Reset command.

## PPB Lock Bit Set Command

The PPB Lock Bit Set command is used to set the PPB Lock bit if it is cleared either at reset or if the Password Unlock command was successfully executed. There is no PPB Lock Bit Clear command. Once the PPB Lock Bit is set, it cannot be cleared unless the device is taken through a power-on clear or the Password Unlock command is executed. Upon setting the PPB Lock Bit, the PPBs are latched. If the Password Mode Locking Bit is set, the PPB Lock Bit status is reflected as set, even after a power-on reset cycle. Exiting the PPB Lock Bit Set command is accomplished by writing the Secured Silicon Exit command, only while in the Persistent Sector Protection Mode.

## DPB Write/Erase/Status Command

The DPB Write command is used to set or clear a DPB for a given sector. The high order address bits (Amax-A11) are issued at the same time as the code 01 h or 00h on DQ7-DQ0. All other DQ data bus pins are ignored during the data write cycle. The DPBs are modifiable at any time, regardless of the state of the PPB or PPB Lock Bit. If the PPB is set, the sector is protected regardless of the value of the DPB. If the PPB is cleared, setting the DPB to a 1 protects the sector from programs or erases. Since this is a volatile bit, removing power or resetting the device will clear the DPBs. The programming of the DPB for a given sector can be verified by writing a DPB Status command to the device. Exiting the DPB Write/Erase command is accomplished by writing the Read/Reset command. Exiting the DPB Status command is accomplished by writting the Secured Silicon Sector Exit command

## Password Unlock Command

The Password Unlock command is used to clear the PPB Lock Bit so that the PPBs can be unlocked for modification, thereby allowing the PPBs to become accessible for modification. The exact password must be entered in order for the unlocking function to occur. This command cannot be issued any faster than $2 \mu \mathrm{~s}$ at a time to prevent a hacker from running through the all 64-bit combinations in an attempt to correctly match a password. If the command is issued before the $2 \mu \mathrm{~s}$ execution window for each portion of the unlock, the command will be ignored.
The Password Unlock function is accomplished by writing Password Unlock command and data to the device to perform the clearing of the PPB Lock Bit. The password is 64 bits long, so the user must write the Password Unlock command 4 times. A1 and A0 are used for matching. Writing the Password Unlock command is not address order specific. The lower address A1-A0=00, the next Password Unlock command is to $A 1-A 0=01$, then to $A 1-A 0=10$, and finally to $A 1-A 0=11$.
Once the Password Unlock command is entered for all four words, the RDY pin goes LOW indicating that the device is busy. Also, reading the Bank $D$ results in the DQ6 pin toggling, indicating that the Password Unlock function is in progress. Reading the other bank returns actual array data. Approximately $1 \mu \mathrm{~s}$ is required for each portion of the unlock. Once the first portion of the password unlock completes (RDY is not driven and DQ6 does not toggle when read), the Password Unlock command is issued again, only this time with the next part of the password. Four Password Unlock commands are required to successfully clear the PPB Lock Bit. As with the first Password Unlock command, the RDY signal goes LOW and reading the device results in the DQ6 pin toggling on successive read operations until complete. It is the responsibility of the microprocessor to keep
track of the number of Password Unlock commands, the order, and when to read the PPB Lock bit to confirm successful password unlock. In order to relock the device into the Password Mode, the PPB Lock Bit Set command can be re-issued. Exiting the Password Unlock command is accomplished by writing the Secured Silicon Sector Exit command.

## PPB Program Command

The PPB Program command is used to program, or set, a given PPB. Each PPB is individually programmed (but is bulk erased with the other PPBs). The specific sector address (Amax-A12) are written at the same time as the program command 60 h with A6 $=0$. If the PPB Lock Bit is set and the corresponding PPB is set for the sector, the PPB Program command will not execute and the command will time-out without programming the PPB.
After programming a PPB, two additional cycles are needed to determine whether the PPB has been programmed with margin. After 4th cycle, the device requires approximately $150 \mu \mathrm{~s}$ time out period for programming the PPB. And then after 5th cycle, the device outputs verify data at DQ0.

The PPB Program command does not follow the Embedded Program algorithm. Writing the Secured Silicon Sector Exit command or Read/Reset command return the device back to normal operation.

## All PPB Erase Command

The All PPB Erase command is used to erase all PPBs in bulk. There is no means for individually erasing a specific PPB. Unlike the PPB program, no specific sector address is required. However, when the PPB erase command is written (60h) and A6 $=1$, all Sector PPBs are erased in parallel. If the PPB Lock Bit is set the ALL PPB Erase command will not execute and the command will timeout without erasing the PPBs.

After erasing the PPBs, two additional cycles are needed to determine whether the PPB has been erased with margin. After 4th cycle, the device requires approximately 1.5 ms time out period for erasing the PPB. And then after 5th cycle, the device outputs verify data at DQ0.
It is the responsibility of the user to preprogram all PPBs prior to issuing the All PPB Erase command. If the user attempts to erase a cleared PPB, over-erasure may occur making it difficult to program the PPB at a later time. Also note that the total number of PPB program/erase cycles is limited to 100 cycles. Cycling the PPBs beyond 100 cycles is not guaranteed. Writing the Secured Silicon Sector Exit command or Read/Reset command return the device back to normal operation.

## PPB Status Command

The programming of the PPB for a given sector can be verified by writing a PPB status verify command to the device. Writing the Secured Silicon Sector Exit command or Read/Reset command return the device back to normal operation.

## PPB Lock Bit Status Command

The programming of the PPB Lock Bit for a given sector can be verified by writing a PPB Lock Bit status verify command to the device. Writing the Secured Silicon Sector Exit command or Read/ Reset command return the device back to normal operation.

## Command Definitions

Table 18. Command Definitions

| Command Sequence (Note I) |  |  | Bus Cycles (Notes I-6) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | First | Second |  | Third |  | Fourth |  | Fifth |  | Sixth |  | Seventh |  |
|  |  | Addr | Data | Addr | Data | Addr | Data | Addr | Data | Addr | Data | Addr | Data | Addr | Data |
| Asynchronous Read (Note 7) |  |  | 1 | RA | RD |  |  |  |  |  |  |  |  |  |  |  |  |
| Reset (Note 8) |  |  | 1 | XXX | F0 |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Manufacturer ID | 4 | 555 | AA | 2AA | 55 | (BA) | 90 | $\begin{aligned} & \text { (BA) } \\ & \text { X00 } \end{aligned}$ | 0001 |  |  |  |  |  |  |
|  | Device ID (Note 10) | 6 | 555 | AA | 2AA | 55 | $\begin{gathered} \text { (BA) } \\ 555 \end{gathered}$ | 90 | $\begin{aligned} & \text { (BA) } \\ & \text { X01 } \end{aligned}$ | 227E | $\underset{O E}{(\mathrm{BA}) \mathrm{X}}$ | (Note 10) | $\begin{aligned} & \text { (BA) } \\ & \text { XOF } \end{aligned}$ | $\begin{aligned} & \text { (Not } \\ & \text { e } 10 \text { ) } \end{aligned}$ |  |  |
|  | Sector Lock Verify (Note 11) | 4 | 555 | AA | 2AA | 55 | $\begin{aligned} & (\mathrm{SA}) \\ & 555 \end{aligned}$ | 90 | $\begin{aligned} & \text { (SA) } \\ & \text { X02 } \end{aligned}$ | $\begin{gathered} 0000 / \\ 0001 \end{gathered}$ |  |  |  |  |  |  |
|  | Indicator Bits | 4 | 555 | AA | 2AA | 55 | $\begin{gathered} (\mathrm{BA}) \\ 555 \end{gathered}$ | 90 | $\begin{aligned} & \text { (BA) } \\ & \text { X03 } \end{aligned}$ | (Note 12) |  |  |  |  |  |  |
| Program |  | 4 | 555 | AA | 2AA | 55 | 555 | A0 | PA | Data |  |  |  |  |  |  |
| Chip Erase |  | 6 | 555 | AA | 2AA | 55 | 555 | 80 | 555 | AA | 2AA | 55 | 555 | 10 |  |  |
| Sector Erase |  | 6 | 555 | AA | 2AA | 55 | 555 | 80 | 555 | AA | 2AA | 55 | SA | 30 |  |  |
| Erase Suspend (Note 15) |  | 1 | BA | B0 |  |  |  |  |  |  |  |  |  |  |  |  |
| Erase Resume (Note 16) |  | 1 | BA | 30 |  |  |  |  |  |  |  |  |  |  |  |  |
| Set Configuration Register (Note 17) |  | 3 | 555 | AA | 2AA | 55 | $\begin{gathered} \text { (CR) } \\ 555 \end{gathered}$ | C0 |  |  |  |  |  |  |  |  |
| CFI Query (Note 18) |  | 1 | 55 | 98 |  |  |  |  |  |  |  |  |  |  |  |  |
| Unlock <br> Bypass <br> Mode | Unlock Bypass Entry | 3 | 555 | AA | 2AA | 55 | 555 | 20 |  |  |  |  |  |  |  |  |
|  | Unlock Bypass Program (Notes 13, 14) | 2 | XX | A0 | PA | PD |  |  |  |  |  |  |  |  |  |  |
|  | Unlock Bypass Sector Erase (Notes $13,14)$ | 2 | XX | 80 | SA | 30 |  |  |  |  |  |  |  |  |  |  |
|  | Unlock Bypass Erase (Notes 13, 14) | 2 | XX | 80 | XXX | 10 |  |  |  |  |  |  |  |  |  |  |
|  | Unlock Bypass Reset (Notes 13, 14) | 2 | XX | 90 | XXX | 00 |  |  |  |  |  |  |  |  |  |  |
| Sector Protection Command Definitions |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Secured <br> Silicon <br> Sector | Secured Silicon Sector Entry | 3 | 555 | AA | 2AA | 55 | 555 | 88 |  |  |  |  |  |  |  |  |
|  | Secured Silicon Sector Exit | 4 | 555 | AA | 2AA | 55 | 555 | 90 | XX | 00 |  |  |  |  |  |  |
|  | Secured Silicon Protection Bit Program (Notes 19, 21) | 6 | 555 | AA | 2AA | 55 | 555 | 60 | OW | 68 | OW | 48 | OW | $\begin{aligned} & \text { RD } \\ & (0) \end{aligned}$ |  |  |
| Password Protection | Password Program (Notes 23) | 4 | 555 | AA | 2AA | 55 | 555 | 38 | XX0 | PD0 |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  | XX1 | PD1 |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  | XX2 | PD2 |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  | XX3 | PD3 |  |  |  |  |  |  |
|  | Password Verify | 4 | 555 | AA | 2AA | 55 | 555 | C8 | XX0 | PD0 |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  | XX1 | PD1 |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  | XX2 | PD2 |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  | XX3 | PD3 |  |  |  |  |  |  |
|  | Password Unlock (Note 23) | 7 | 555 | AA | 2AA | 55 | 555 | 28 | XX0 | PDO | XX1 | PD1 | XX2 | PD2 | XX3 | PD3 |


| Command Sequence (Note I) |  | $\begin{aligned} & \stackrel{0}{\nu} \\ & \stackrel{\partial}{0} \\ & \hline \end{aligned}$ | Bus Cycles (Notes 1-6) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | First | Second |  | Third |  | Fourth |  | Fifth |  | Sixth |  | Seventh |  |
|  |  | Addr | Data | Addr | Data | Addr | Data | Addr | Data | Addr | Data | Addr | Data | Addr | Data |
| PPB Commands | PPB Program (Notes 21) |  | 6 | 555 | AA | 2AA | 55 | 555 | 60 | $\begin{gathered} \text { SBA } \\ +W P \end{gathered}$ | 68 | $\begin{gathered} \text { SBA } \\ + \text { WP } \end{gathered}$ | 48 | XX | $\begin{aligned} & \text { RD } \\ & \text { (0) } \end{aligned}$ |  |  |
|  | All PPB Erase (Notes $22,24)$ |  | 6 | 555 | AA | 2AA | 55 | 555 | 60 | WPE | 60 | $\begin{aligned} & \text { SBA } \\ & \text { WPE } \end{aligned}$ | 40 | XX | $\begin{aligned} & \text { RD } \\ & \text { (0) } \end{aligned}$ |  |  |
|  | PPB Status (Note 25) | 4 | 555 | AA | 2AA | 55 | $\begin{aligned} & \text { SBA } \\ & 555 \end{aligned}$ | 90 | $\begin{aligned} & \text { SBA } \\ & +W P \end{aligned}$ | $\begin{aligned} & \text { RD } \\ & \text { (0) } \end{aligned}$ |  |  |  |  |  |  |
| PPB LockBit | PPB Lock Bit Set | 3 | 555 | AA | 2AA | 55 | 555 | 78 |  |  |  |  |  |  |  |  |
|  | PPB Lock Bit Status | 4 | 555 | AA | 2AA | 55 | $\begin{gathered} \hline \text { (BA) } \\ 555 \end{gathered}$ | 58 | BA | $\begin{aligned} & \hline \text { RD } \\ & (1) \end{aligned}$ |  |  |  |  |  |  |
| DPB | DPB Write | 4 | 555 | AA | 2AA | 55 | 555 | 48 | SA | X1 |  |  |  |  |  |  |
|  | DPB Erase | 4 | 555 | AA | 2AA | 55 | 555 | 48 | SA | X0 |  |  |  |  |  |  |
|  | DPB Status | 4 | 555 | AA | 2AA | 55 | $\begin{aligned} & \hline \text { (BA) } \\ & 555 \end{aligned}$ | 58 | SA | $\begin{aligned} & \text { RD } \\ & (0) \end{aligned}$ |  |  |  |  |  |  |
| Password Protection Mode Locking Bit Program (Notes 21) |  | 6 | 555 | AA | 2AA | 55 | 555 | 60 | PL | 68 | PL | 48 | PL | $\begin{aligned} & \text { RD } \\ & (0) \end{aligned}$ |  |  |
| Persistent Pr Locking Bit | Protection Mode Program (Notes 21) | 6 | 555 | AA | 2AA | 55 | 555 | 60 | SL | 68 | SL | 48 | SL | $\begin{aligned} & \hline \text { RD } \\ & (0) \\ & \hline \end{aligned}$ |  |  |

## Legend:

X $=$ Don't care
$R A=$ Address of the memory location to be read.
$R D=$ Data read from location $R A$ during read operation.
$P A=$ Address of the memory location to be programmed. Addresses latch on the rising edge of the AVD\# pulse or active edge of CLK which ever comes first.
$P D=$ Data to be programmed at location PA. Data latches on the rising edge of WE\# or CE\# pulse, whichever happens first.
$S A=$ Address of the sector to be verified (in autoselect mode) or erased. Address bits Amax-A12 uniquely select any sector.
BA = Address of the bank (WS128J: A22, A21, A20, WS064J: A21, A20, A19) that is being switched to autoselect mode, is in bypass mode, or is being erased.
SLA = Address of the sector to be locked. Set sector address (SA) and either A6 = 1 for unlocked or A6 = 0 for locked.
SBA $=$ sector address block to be protected.
$C R=$ Configuration Register address bits A19-A12.
OW = Address ( $A 7-A O$ ) is (00011010).
PD3-PDO = Password Data. PD3-PDO present four 16 bit combinations that represent the 64-bit Password
PWA = Password Address. Address bits A1 and AO are used to select each 16-bit portion of the 64-bit entity.
PWD = Password Data.
$P L=$ Address $(A 7-A O)$ is (00001010)
$R D(0)=D Q O$ protection indicator bit. If protected, $D Q O=1$, if unprotected, $D Q O=0$.
$R D(1)=D Q 1$ protection indicator bit. If protected, $D Q 1=1$, if unprotected, $D Q 1=0$.
$S L=$ Address (A7-AO) is (00010010)
WD = Write Data. See "Configuration Register" definition for specific write data
$W P=$ Address (A7-AO) is (00000010)
$W P E=\operatorname{address}(A 7-A O)$ is (01000010)

## Notes:

1. See Table 1 for description of bus operations.
2. All values are in hexadecimal.
3. Except for the following, all bus cycles are write cycle: read cycle, fourth through sixth cycles of the Autoselect commands, fourth cycle of the configuration register verify and password verify commands, and any cycle reading at $R D(0)$ and $R D(1)$.
4. Data bits $D Q 15-D Q 8$ are don't care in command sequences, except for $R D, P D, W D, P W D$, and PD3-PDO.
5. Unless otherwise noted, address bits Amax-A12 are don't cares.
6. Writing incorrect address and data values or writing them in the improper sequence may place the device in an unknown state. The system must write the reset command to return the device to reading array data.
7. No unlock or command cycles required when bank is reading array data.
8. The Reset command is required to return to reading array data (or to the erase-suspend-read mode if previously in Erase Suspend) when a bank is in the autoselect mode, or if DQ5 goes high (while the bank is providing status information) or performing sector lock/unlock.
9. The fourth cycle of the autoselect command sequence is a read cycle. The system must provide the bank address. See the Autoselect Command Sequence section for more information.
10. (BA)XOFh = 2200h (WS128J), (BA)X0Eh $=2218 h(W S 128 \mathrm{~J}),(B A) X 0 F h=221 E h(W S 064 J),(B A) X 0 E h ~=2201 h(W S 064 J)$
11. The data is 0000 h for an unlocked sector and 0001 h for a locked sector
12. DQ15-DQ8 = 0, DQ7 - Factory Lock Bit (1 = Locked, $0=$ Not Locked), DQ6 -Customer Lock Bit (1 = Locked, $0=$ Not Locked), DQ5 = Handshake Bit ( $1=$ Reserved, $0=$ Standard Handshake)8, DQ4 \& DQ3 - Boot Code $(00=$ Dual Boot Sector, $01=$ Top Boot Sector, $10=$ Bottom Boot Sector, $11=$ No Boot Sector), $D Q 2-D Q 0=001$
13. The Unlock Bypass command sequence is required prior to this command sequence.
[^0]
## Write Operation Status

The device provides several bits to determine the status of a program or erase operation: DQ2, DQ3, DQ5, DQ6, and DQ7. Table 20, "Write Operation Status," on page 67 and the following subsections describe the function of these bits. DQ7 and DQ6 each offers a method for determining whether a program or erase operation is complete or in progress.

## DQ7: Data\# Polling

The Data\# Polling bit, DQ7, indicates to the host system whether an Embedded Program or Erase algorithm is in progress or completed, or whether a bank is in Erase Suspend. Data\# Polling is valid after the rising edge of the final WE\# pulse in the command sequence.

During the Embedded Program algorithm, the device outputs on DQ7 the complement of the datum programmed to DQ7. This DQ7 status also applies to programming during Erase Suspend. When the Embedded Program algorithm is complete, the device outputs the datum programmed to DQ7. The system must provide the program address to read valid status information on DQ7. If a program address falls within a protected sector, Data\# Polling on DQ7 is active for approximately $1 \mu \mathrm{~s}$, then that bank returns to the read mode.

During the Embedded Erase algorithm, Data\# Polling produces a "0" on DQ7. When the Embedded Erase algorithm is complete, or if the bank enters the Erase Suspend mode, Data\# Polling produces a "1" on DQ7. The system must provide an address within any of the sectors selected for erasure to read valid status information on DQ7.

After an erase command sequence is written, if all sectors selected for erasing are protected, Data\# Polling on DQ7 is active for approximately $100 \mu \mathrm{~s}$, then the bank returns to the read mode. If not all selected sectors are protected, the Embedded Erase algorithm erases the unprotected sectors, and ignores the selected sectors that are protected. However, if the system reads DQ7 at an address within a protected sector, the status may not be valid.

Just prior to the completion of an Embedded Program or Erase operation, DQ7 may change asynchronously with DQ6-DQ0 while Output Enable (OE\#) is asserted low. That is, the device may change from providing status information to valid data on DQ7. Depending on when the system samples the DQ7 output, it may read the status or valid data. Even if the device has completed the program or erase operation and DQ7 has valid data, the data outputs on DQ6-DQ0 may be still invalid. Valid data on DQ7-D00 will appear on successive read cycles.

Table 20, "Write Operation Status," on page 67 shows the outputs for Data\# Polling on DQ7. Figure 7, "Data\# Polling Algorithm," on page 63 shows the Data\# Polling algorithm. Figure 29, "Data\# Polling Timings (During Embedded Algorithm)," on page 86 in the AC Characteristics section shows the Data\# Polling timing diagram.


## Notes:

1. $\quad V A=$ Valid address for programming. During a sector erase operation, a valid address is any sector address within the sector being erased. During chip erase, a valid address is any non-protected sector address.
2. DQ7 should be rechecked even if DQ5 = "1" because DQ7 may change simultaneously with DQ5.

Figure 7. Data\# Polling Algorithm

## RDY: Ready

The RDY is a dedicated output that, when the device is configured in the Synchronous mode, indicates (when at logic low) the system should wait 1 clock cycle before expecting the next word of data. The RDY pin is only controlled by CE\#. Using the RDY Configuration Command Sequence, RDY can be set so that a logic low indicates the system should wait 2 clock cycles before expecting valid data.
The following conditions cause the RDY output to be low: during the initial access (in burst mode), and after the boundary that occurs every 64 words beginning with the 64th address, 3Fh.
When the device is configured in Asynchronous Mode, the RDY is an open-drain output pin which indicates whether an Embedded Algorithm is in progress or completed. The RDY status is valid after the rising edge of the final WE\# pulse in the command sequence.

If the output is low (Busy), the device is actively erasing or programming. (This includes programming in the Erase Suspend mode.) If the output is in high impedance (Ready), the device is in the read mode, the standby mode, or in the erase-suspend-read mode. Table 20, "Write Operation Status," on page 67 shows the outputs for RDY.

## DQ6: Toggle Bit I

Toggle Bit I on DQ6 indicates whether an Embedded Program or Erase algorithm is in progress or complete, or whether the device has entered the Erase Suspend mode. Toggle Bit I may be read at any address in the same bank, and is valid after the rising edge of the final WE\# pulse in the command sequence (prior to the program or erase operation), and during the sector erase timeout.

During an Embedded Program or Erase algorithm operation, successive read cycles to any address cause DQ6 to toggle. When the operation is complete, DQ6 stops toggling.

After an erase command sequence is written, if all sectors selected for erasing are protected, DQ6 toggles for approximately $100 \mu \mathrm{~s}$, then returns to reading array data. If not all selected sectors are protected, the Embedded Erase algorithm erases the unprotected sectors, and ignores the selected sectors that are protected.

The system can use DQ6 and DQ2 together to determine whether a sector is actively erasing or is erase-suspended. When the device is actively erasing (that is, the Embedded Erase algorithm is in progress), DQ6 toggles. When the device enters the Erase Suspend mode, DQ6 stops toggling. However, the system must also use DQ2 to determine which sectors are erasing or erasesuspended. Alternatively, the system can use DQ7 (see the subsection on DQ7: Data\# Polling).

If a program address falls within a protected sector, DQ6 toggles for approximately 1 ms after the program command sequence is written, then returns to reading array data.

DQ6 also toggles during the erase-suspend-program mode, and stops toggling once the Embedded Program algorithm is complete.
See the following for additional information: Figure 8, "Toggle Bit Algorithm," on page 65, DQ6: Toggle Bit I on page 64, Figure 30, "Toggle Bit Timings (During Embedded Algorithm)," on page 87 (toggle bit timing diagram), and Table 19, "DQ6 and DQ2 Indications," on page 66.

Toggle Bit I on DQ6 requires either OE\# or CE\# to be deasserteed and reasserted to show the change in state.


Note: The system should recheck the toggle bit even if DQ5 = "1" because the toggle bit may stop toggling as DQ5 changes to "1." See the subsections on DQ6 and DQ2 for more information.

Figure 8. Toggle Bit Algorithm

## DQ2: Toggle Bit II

The "Toggle Bit II" on DQ2, when used with DQ6, indicates whether a particular sector is actively erasing (that is, the Embedded Erase algorithm is in progress), or whether that sector is erasesuspended. Toggle Bit II is valid after the rising edge of the final WE\# pulse in the command sequence.

DQ2 toggles when the system reads at addresses within those sectors that have been selected for erasure. But DQ2 cannot distinguish whether the sector is actively erasing or is erase-suspended. DQ6, by comparison, indicates whether the device is actively erasing, or is in Erase

Suspend, but cannot distinguish which sectors are selected for erasure. Thus, both status bits are required for sector and mode information. Refer to Table 19, "DQ6 and DQ2 Indications," on page 66 to compare outputs for DQ2 and DQ6.

See the following for additional information: Figure 8, "Toggle Bit Algorithm," on page 65, See DQ6: Toggle Bit I on page 64, Figure 30, "Toggle Bit Timings (During Embedded Algorithm)," on page 87, and Table 19, "DQ6 and DQ2 Indications," on page 66.

Table 19. DQ6 and DQ2 Indications

| If device is | and the system reads | then DQ6 | and DQ2 |
| :---: | :---: | :---: | :---: |
| programming, | at any address, | toggles, | does not toggle. |
| actively erasing, | at an address within a sector <br> selected for erasure, | toggles, | also toggles. |
|  | at an address within sectors not <br> selected for erasure, | toggles, | does not toggle. |
|  | does not toggle, | toggles. |  |
| at address within sectors not <br> selected for erasure, | returns array data, | returns array data. The system can read <br> from any sector not selected for erasure. |  |

## Reading Toggle Bits DQ6/DQ2

Refer to Figure 8, "Toggle Bit Algorithm," on page 65 for the following discussion. Whenever the system initially begins reading toggle bit status, it must read DQ7-DQ0 at least twice in a row to determine whether a toggle bit is toggling. Typically, the system would note and store the value of the toggle bit after the first read. After the second read, the system would compare the new value of the toggle bit with the first. If the toggle bit is not toggling, the device has completed the program or erase operation. The system can read array data on DQ7-DQ0 on the following read cycle.
However, if after the initial two read cycles, the system determines that the toggle bit is still toggling, the system also should note whether the value of DQ5 is high (see the section on DQ5). If it is, the system should then determine again whether the toggle bit is toggling, since the toggle bit may have stopped toggling just as DQ5 went high. If the toggle bit is no longer toggling, the device has successfully completed the program or erase operation. If it is still toggling, the device did not completed the operation successfully, and the system must write the reset command to return to reading array data.

The remaining scenario is that the system initially determines that the toggle bit is toggling and DQ5 has not gone high. The system may continue to monitor the toggle bit and DQ5 through successive read cycles, determining the status as described in the previous paragraph. Alternatively, it may choose to perform other system tasks. In this case, the system must start at the beginning of the algorithm when it returns to determine the status of the operation (Figure 8, "Toggle Bit Algorithm," on page 65).

## DQ5: Exceeded Timing Limits

DQ5 indicates whether the program or erase time has exceeded a specified internal pulse count limit. Under these conditions DQ5 produces a " 1 ," indicating that the program or erase cycle was not successfully completed.

The device may output a " 1 " on DQ5 if the system tries to program a " 1 " to a location that was previously programmed to " 0 ." Only an erase operation can change a " 0 " back to a " 1 ." Under this condition, the device halts the operation, and when the timing limit has been exceeded, DQ5 produces a "1."

Under both these conditions, the system must write the reset command to return to the read mode (or to the erase-suspend-read mode if a bank was previously in the erase-suspend-program mode).

## DQ3: Sector Erase Timer

After writing a sector erase command sequence, the system may read DQ3 to determine whether or not erasure has begun. (The sector erase timer does not apply to the chip erase command.) If additional sectors are selected for erasure, the entire time-out also applies after each additional sector erase command. When the time-out period is complete, DQ3 switches from a " 0 " to a " 1 ." If the time between additional sector erase commands from the system can be assumed to be less than $50 \mu \mathrm{~s}$, the system need not monitor DQ3. See also Sector Erase Command Sequence on page 55 .

After the sector erase command is written, the system should read the status of DQ7 (Data\# Polling) or DQ6 (Toggle Bit I) to ensure that the device has accepted the command sequence, and then read DQ3. If DQ3 is "1," the Embedded Erase algorithm has begun; all further commands (except Erase Suspend) are ignored until the erase operation is complete. If DQ3 is " 0, " the device will accept additional sector erase commands. To ensure the command has been accepted, the system software should check the status of DQ3 prior to and following each subsequent sector erase command. If DQ3 is high on the second status check, the last command might not have been accepted.
Table 20 shows the status of DQ3 relative to the other status bits.
Table 20. Write Operation Status

| Status |  |  | $\begin{aligned} & \text { DQ7 } \\ & \text { (Note 2) } \end{aligned}$ | DQ6 | $\begin{aligned} & \text { DQ5 } \\ & \text { (Note I) } \end{aligned}$ | DQ3 | $\begin{gathered} \text { DQ2 } \\ \text { (Note 2) } \end{gathered}$ | RDY (Note 5) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Standard Mode | Embedded Program Algorithm |  | DQ7\# | Toggle | 0 | N/A | No toggle (Note 6) | 0 |
|  | Embedded Erase Algorithm |  | 0 | Toggle | 0 | 1 | Toggle | 0 |
| Erase Suspend Mode | Erase-Suspend- <br> Read (Note 4) | Erase <br> Suspended Sector | 1 | No toggle (Note 6) | 0 | N/A | Toggle | High Impedance |
|  |  | Non-Erase Suspended Sector | Data | Data | Data | Data | Data | High Impedance |
|  | Erase-Suspend-Program |  | DQ7\# | Toggle | 0 | N/A | N/A | 0 |

## Notes:

1. DQ5 switches to '1' when an Embedded Program or Embedded Erase operation has exceeded the maximum timing limits. Refer to the section on DQ5 for more information.
2. $D Q 7$ and $D Q 2$ require a valid address when reading status information. Refer to the appropriate subsection for further details.
3. When reading write operation status bits, the system must always provide the bank address where the Embedded Algorithm is in progress. The device outputs array data if the system addresses a non-busy bank.
4. The system may read either asynchronously or synchronously (burst) while in erase suspend.
5. The RDY pin acts a dedicated output to indicate the status of an embedded erase or program operation is in progress. This is available in the Asynchronous mode only.
6. When the device is set to Asynchronous mode, these status flags should be read by CE\# toggle.

## Absolute Maximum Ratings

Storage Temperature, Plastic Packages . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Ambient Temperature with Power Applied . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . $-65^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$
Voltage with Respect to Ground:
All Inputs and I/Os except as noted below (Note 1). . . . . . . . . . . . . . . . . . . . . . . - 0.5 V to $\mathrm{V}_{\mathrm{CC}}+0.5 \mathrm{~V}$
VCC (Note 1). . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 0.5 V to +2.5 V
A9, RESET\#, ACC (Note 1). . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 0.5 V to +12.5 V
Output Short Circuit Current (Note 3) . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 100 mA

## Notes:

1. Minimum $D C$ voltage on input or $I / O s$ is -0.5 V . During voltage transitions, inputs or I/Os may undershoot $V_{S S}$ to -2.0 V for periods of up to 20 ns. See Figure 9. Maximum DC voltage on input or I/Os is $V_{C C}+0.5 \mathrm{~V}$. During voltage transitions outputs may overshoot to $V_{C C}+2.0$ V for periods up to 20 ns. See Figure 10.
2. No more than one output may be shorted to ground at a time. Duration of the short circuit should not be greater than one second.
3. Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational sections of this data sheet is not implied. Exposure of the device to absolute maximum rating conditions for extended periods may affect device reliability.


Figure 9. Maximum Negative Overshoot Waveform


Figure 10. Maximum Positive Overshoot Waveform

## Operating Ranges

## Wireless (W) Devices

Ambient Temperature ( $\mathrm{T}_{\mathrm{A}}$ ) . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$

## Industrial (I) Devices

Ambient Temperature ( $\mathrm{T}_{\mathrm{A}}$ ) . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$

## Supply Voltages

V ${ }_{\text {CC }}$ Supply Voltages . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 1.65 V to 1.95 V ( 66 MHz )
Note: Operating ranges define those limits between which the functionality of the device is guaranteed.

## DC Characteristics

CMOS Compatible

| Parameter | Description | Test Conditions Notes: I |  | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{\mathrm{LI}}$ | Input Load Current | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{SS}}$ to $\mathrm{V}_{\mathrm{CC}}, \mathrm{V}_{\mathrm{CC}}=\mathrm{V}_{\mathrm{CC}}$ max |  |  |  | $\pm 1$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {LO }}$ | Output Leakage Current | $\mathrm{V}_{\text {OUT }}=\mathrm{V}_{\text {SS }}$ to $\mathrm{V}_{\mathrm{CC}}, \mathrm{V}_{\mathrm{CC}}=\mathrm{V}_{\mathrm{CC}} \mathrm{max}$ |  |  |  | $\pm 1$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {CCB }}$ | $\mathrm{V}_{\mathrm{CC}}$ Active burst Read Current | $\begin{aligned} & \mathrm{CE} \#=\mathrm{V}_{\mathrm{IL}}, \mathrm{OE} \#=\mathrm{V}_{\mathrm{IH}}, \\ & \mathrm{WE} \#=\mathrm{V}_{\mathrm{IH}}, \text { burst } \\ & \text { length }=8 \end{aligned}$ | 66 MHz |  | 15 | 30 | mA |
|  |  |  | 80 MHz |  | 18 | 36 | mA |
|  |  | $\begin{aligned} & \mathrm{CE} \#=\mathrm{V}_{\mathrm{IL}}, \mathrm{OE} \#=\mathrm{V}_{\mathrm{IH}}, \\ & \mathrm{WE} \#=\mathrm{V}_{\mathrm{IH}}, \text { burst } \\ & \text { length }=16 \end{aligned}$ | 66 MHz |  | 15 | 30 | mA |
|  |  |  | 80 MHz |  | 18 | 36 | mA |
|  |  | $\begin{aligned} & \mathrm{CE} \#=\mathrm{V}_{\mathrm{IL}}, \mathrm{OE} \#=\mathrm{V}_{\mathrm{IH}}, \\ & \mathrm{WE} \#=\mathrm{V}_{\mathrm{IH}} \text {, burst } \\ & \text { length = Continuous } \end{aligned}$ | 66 MHz |  | 15 | 30 | mA |
|  |  |  | 80 MHz |  | 18 | 36 | mA |
| $\mathrm{I}_{\text {IO1 }}$ | V CC Non-active Output | $\mathrm{OE} \#=\mathrm{V}_{\text {IH }}$ |  |  | 0.2 | 10 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\mathrm{CC1}}$ | $\mathrm{V}_{\mathrm{CC}}$ Active Asynchronous Read Current (Note 2) | $\begin{aligned} & \mathrm{CE} \mathrm{\#}=\mathrm{V}_{\mathrm{IL},} \mathrm{OE} \#=\mathrm{V}_{\mathrm{IH}}, \\ & \mathrm{WE} \#=\mathrm{V}_{\mathrm{IH}} \end{aligned}$ | 10 MHz |  | 20 | 30 | mA |
|  |  |  | 5 MHz |  | 12 | 16 | mA |
|  |  |  | 1 MHz |  | 3.5 | 5 | mA |
| $\mathrm{I}_{\mathrm{CC} 2}$ | $\mathrm{V}_{\text {CC }}$ Active Write Current (Note 3) | $C E \#=\mathrm{V}_{\mathrm{IL}}, \mathrm{OE} \#=\mathrm{V}_{\mathrm{IH}}, \mathrm{ACC}=\mathrm{V}_{\mathrm{IH}}$ |  |  | 15 | 40 | mA |
| $\mathrm{I}_{\mathrm{CC} 3}$ | $\mathrm{V}_{\text {CC }}$ Standby Current (Note 4) | $C E \#=$ RESET\# $=\mathrm{V}_{\text {CC }} \pm 0.2 \mathrm{~V}$ |  |  | 0.2 | 50 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\mathrm{CC} 4}$ | $\mathrm{V}_{\text {CC }}$ Reset Current | RESET\# $=\mathrm{V}_{\text {IL, }}$, $\mathrm{CLK}=\mathrm{V}_{\mathrm{IL}}$ |  |  | 0.2 | 50 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\mathrm{CC} 5}$ | $\mathrm{V}_{\mathrm{CC}}$ Active Current (Read While Write) | $C E \#=V_{I L}, \mathrm{OE} \#=\mathrm{V}_{\mathrm{IH}}$ | 66 MHz |  | 22 | 54 | mA |
|  |  |  | 80 MHz |  | 25 | 60 | mA |
| $\mathrm{I}_{\mathrm{CC6}}$ | $\mathrm{V}_{\text {CC }}$ Sleep Current | $\mathrm{CE} \#=\mathrm{V}_{\mathrm{IL}} \mathrm{OE} \#=\mathrm{V}_{\mathrm{IH}}$ |  |  | 0.2 | 50 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {ACC }}$ | Accelerated Program Current (Note 5) | $\begin{aligned} & \mathrm{CE} \#=\mathrm{V}_{\mathrm{IL}}, O E \#=\mathrm{V}_{\mathrm{IH}}, \\ & \mathrm{~V}_{\mathrm{ACC}}=12.0 \pm 0.5 \mathrm{~V} \end{aligned}$ | $V_{\text {ACC }}$ |  | 7 | 15 | mA |
|  |  |  | $\mathrm{V}_{\mathrm{CC}}$ |  | 5 | 10 | mA |
| $\mathrm{V}_{\text {IL }}$ | Input Low Voltage |  |  | -0.5 |  | 0.4 | V |
| $\mathrm{V}_{\mathrm{IH}}$ | Input High Voltage |  |  | $\mathrm{V}_{\text {CC }}-0.4$ |  | $\mathrm{V}_{\mathrm{CC}}+0.4$ |  |
| $\mathrm{V}_{\mathrm{OL}}$ | Output Low Voltage | $\mathrm{I}_{\mathrm{OL}}=100 \mu \mathrm{~A}, \mathrm{~V}_{\mathrm{CC}}=\mathrm{V}_{\mathrm{CC} \text { min }}=\mathrm{V}_{\mathrm{IO}}$ |  |  |  | 0.1 | V |
| $\mathrm{V}_{\mathrm{OH}}$ | Output High Voltage | $\mathrm{I}_{\mathrm{OH}}=-100 \mu \mathrm{~A}, \mathrm{~V}_{\mathrm{CC}}=\mathrm{V}_{\mathrm{CC} \text { min }}$ |  | $\mathrm{V}_{\mathrm{CC}}-0.1$ |  |  | V |
| $V_{\text {ID }}$ | Voltage for Autoselect and Temporary Sector Unprotect | $\mathrm{V}_{\mathrm{CC}}=1.8 \mathrm{~V}$ |  | 11.5 |  | 12.5 | V |
| $\mathrm{V}_{\mathrm{HH}}$ | Voltage for Accelerated Program |  |  | 11.5 |  | 12.5 | V |
| $\mathrm{V}_{\text {LKO }}$ | Low $\mathrm{V}_{\text {cc }}$ Lock-out Voltage |  |  | 1.0 |  | 1.4 | V |

## Notes:

1. Maximum $I_{C C}$ specifications are tested with $V_{C C}=V_{C C}$ max.
2. The $I_{C C}$ current listed is typically less than $2 \mathrm{~mA} / \mathrm{MHz}$, with $O E \#$ at $V_{I H}$.
3. I ${ }_{C C}$ active while Embedded Erase or Embedded Program is in progress.
4. Device enters automatic sleep mode when addresses are stable for $t_{A C C}+60$ ns. Typical sleep mode current is equal to $I_{C C 3}$.
5. Total current during accelerated programming is the sum of $V_{A C C}$ and $V_{C C}$ currents.
6. 80 MHz applies only to the WS064J.

## Test Conditions



Figure II. Test Setup
Table 2I. Test Specifications

| Test Condition | All Speed Options | Unit |
| :--- | :---: | :---: |
| Output Load Capacitance, $\mathrm{C}_{\mathrm{L}}$ <br> (including jig capacitance) | 30 | pF |
| Input Rise and Fall Times | $2.5-3$ | ns |
| Input Pulse Levels | $0.0-\mathrm{V}_{\mathrm{CC}}$ | V |
| Input timing measurement reference levels | $\mathrm{V}_{\mathrm{CC}} / 2$ | V |
| Output timing measurement reference levels | $\mathrm{V}_{\mathrm{CC}} / 2$ | V |

## Key to Switching Waveforms

| Waveform | Inputs | Outputs |
| :---: | :---: | :---: |
|  | Steady |  |
| $\square \square$ | Changing from H to L |  |
|  | Changing from L to H |  |
| $X X X X$ | Don't Care, Any Change Permitted | Changing, State Unknown |
|  | Does Not Apply | Center Line is High Impedance State (High Z) |

## Switching Waveforms



Figure I2. Input Waveforms and Measurement Levels

## AC Characteristics

$V_{c c}$ Power-up

| Parameter | Description | Test Setup | Speed | Unit |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\mathrm{VCS}}$ | $\mathrm{V}_{\mathrm{CC}}$ Setup Time | Min | 50 | $\mu \mathrm{~s}$ |
| $\mathrm{t}_{\mathrm{RSTH}}$ | RESET\# Low Hold Time | Min | 50 | $\mu \mathrm{~s}$ |

## Notes:

1. $V_{C C}$ ramp rate is $>1 \mathrm{~V} / 100 \mu \mathrm{~s}$
2. $V_{C C}$ ramp rate $<1 \mathrm{~V} / 100 \mu \mathrm{~s}$, a Hardware Reset will be required.


Figure 13. Vcc Power-up Diagram

## CLK Characterization

| Parameter | Description |  | 66 MHz | $\begin{gathered} 80 \mathrm{MHz} \\ \text { (WaitState=6,7) } \end{gathered}$ | $80 \mathrm{MHz}$ <br> (WaitState less than 5) | Unit | Condition |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{f}_{\text {CLK }}$ | CLK Frequency | Max | 66.0 | 80.0 | 66.0 | MHz |  |
|  |  | Min | 15.2 | 66.0 | 18.2 | MHz | continuous burst, CLK duty 50\% +/10\% |
|  |  | Min | 32.0 | - | 32.0 | KHz | $\begin{array}{\|c\|} \hline \text { 8/16/32-word } \\ \text { burst, } \\ \text { CLK duty } 50 \%+/- \\ 10 \% \end{array}$ |
| $\mathrm{t}_{\text {CLKH }}$ | CLK high time | Min | 39.6 | - | 33.0 | ns | continuous burst |
|  |  | Min | 7 | 5 | 5 | ns | $\begin{aligned} & 8 / 16 / 32 \text {-word } \\ & \text { burst } \end{aligned}$ |
| $\mathrm{t}_{\text {CLKL }}$ | CLK Low Time | Min | 7.0 | 5.0 | 5.0 | ns |  |
| $\mathrm{t}_{\mathrm{CR}}$ | CLK Rise Time | Max | 3 | 2.5 | 2.5 | ns |  |
| $\mathrm{t}_{\mathrm{CF}}$ | CLK Fall Time |  |  |  |  |  |  |

Note: 80 MHz applies only to the WS064J.


Note: For WS128J (model numbers 10 and 11), and additional clock cycle is required during boundary crossing while in continuous read mode.

Figure 14. CLK Characterization

## Synchronous/Burst Read

| Parameter |  | Description |  | 66 MHz | $\begin{gathered} 80 \mathrm{MHz} \\ \text { (WS064J only) } \end{gathered}$ | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| JEDEC | Standard |  |  |  |  |  |
|  | $\mathrm{t}_{\text {IACC }}$ | Latency (Standard wait-state Handshake mode) for 8-Word and and Continuous 16-Word Burst | Max | 56 | 71 | ns |
|  | $\mathrm{t}_{\text {IACC }}$ | Latency (Standard wait-state Handshake mode) for 32-Word Burst | Max | 71 | 84 | ns |
|  | $\mathrm{t}_{\text {BACC }}$ | Burst Access Time Valid Clock to Output Delay | Max | 11.2 | 9.1 | ns |
|  | $\mathrm{t}_{\text {ACS }}$ | Address Setup Time to CLK (Note 1) | Min |  | 4 | ns |
|  | $\mathrm{t}_{\mathrm{ACH}}$ | Address Hold Time from CLK (Note 1) | Min |  | 5.5 | ns |
|  | $\mathrm{t}_{\mathrm{BDH}}$ | Data Hold Time from Next Clock Cycle | Min |  | 2 | ns |
|  | $\mathrm{t}_{\mathrm{CR}}$ | Chip Enable to RDY Valid | Max | 11.2 | 9.1 | ns |
|  | $\mathrm{t}_{\text {OE }}$ | Output Enable to Output Valid | Max | 11.2 | 9.1 | ns |
|  | $\mathrm{t}_{\text {CEZ }}$ | Chip Enable to High Z | Max |  | 8 | ns |
|  | $\mathrm{t}_{\text {OEZ }}$ | Output Enable to High Z | Max |  | 8 | ns |
|  | $\mathrm{t}_{\text {CES }}$ | CE\# Setup Time to CLK | Min |  | 4 | ns |
|  | $\mathrm{t}_{\text {RDYS }}$ | RDY Setup Time to CLK | Min |  | 4 | ns |
|  | $t_{\text {RACC }}$ | Ready Access Time from CLK | Max | 11.2 | 9.1 | ns |
|  | $\mathrm{t}_{\text {AAS }}$ | Address Setup Time to AVD\# (Note 1) | Min |  | 4 | ns |
|  | $\mathrm{t}_{\text {AAH }}$ | Address Hold Time to AVD\# (Note 1) | Min |  | 5.5 | ns |
|  | $\mathrm{t}_{\text {CAS }}$ | CE\# Setup Time to AVD\# | Min |  | 0 | ns |
|  | $\mathrm{t}_{\mathrm{AVC}}$ | AVD\# Low to CLK | Min |  | 4 | ns |
|  | $\mathrm{t}_{\text {AVD }}$ | AVD\# Pulse | Min |  | 10 | ns |
|  | $\mathrm{t}_{\text {ACC }}$ | Access Time | Max | 55 | 55 | ns |
|  | $\mathrm{t}_{\text {CKA }}$ | CLK to access resume | Max | 11.2 | 9.1 | ns |
|  | $\mathrm{t}_{\text {CKZ }}$ | CLK to High Z | Max |  | 8 | ns |
|  | $\mathrm{t}_{\text {OES }}$ | Output Enable Setup Time | Min |  | 4 | ns |

## Notes:

1. Addresses are latched on the first of either the active edge of CLK or the rising edge of AVD\#.


## Notes:

1. Figure shows total number of wait states set to seven cycles. The total number of wait states can be programmed from two cycles to seven cycles.
2. If any burst address occurs at a 64 -word boundary, two additional clock cycle when wait state is set to less than 5 or three additional clock cycle when wait state is set to $6 \& 7$ are inserted, and is indicated by RDY.
3. The device is in synchronous mode.

Figure 15. CLK Synchronous Burst Mode Read (rising active CLK)


## Notes:

1. Figure shows total number of wait states set to four cycles. The total number of wait states can be programmed from two cycles to seven cycles. Clock is set for active falling edge.
2. If any burst address occurs at a 64-word boundary, two additional clock cycle when wait state is set to less than 5 or three additional clock cycle when wait state is set to 6 \& 7 are inserted, clock cycle are inserted, and is indicated by RDY.
3. The device is in synchronous mode.

Figure 16. CLK Synchronous Burst Mode Read (Falling Active Clock)


## Notes:

1. Figure shows total number of wait states set to seven cycles. The total number of wait states can be programmed from two cycles to seven cycles. Clock is set for active rising edge.
2. If any burst address occurs at a 64-word boundary, two additional clock cycle are inserted, and is indicated by RDY.
3. The device is in synchronous mode.

Figure 17. Synchronous Burst Mode Read


## Notes:

1. Figure shows total number of wait states set to seven cycles. The total number of wait states can be programmed from two cycles to seven cycles. Clock is set for active rising edge.
2. If any burst address occurs at a 64-word boundary, two additional clock cycle are inserted, and is indicated by RDY.
3. The device is in synchronous mode with wrap around.
4. D0-D7 in data waveform indicates the order the data within a given 8-word address range, from lowest to highest. Starting address in figure is the 4th address in range (AC)

Figure 18. 8-word Linear Burst with Wrap Around


## Notes:

1. Figure assumes 6 wait states for initial access and synchronous read.
2. The Set Configuration Register command sequence has been written with $A 18=0$; device will output RDY one cycle before valid data.

Figure 19. Linear Burst with RDY Set One Cycle Before Data

## Asynchronous Mode Read

| Parameter |  | Description |  |  | 66 MHz | $\begin{gathered} 80 \mathrm{MHz} \\ \text { (WS064J only) } \end{gathered}$ | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| JEDEC | Standard |  |  |  |  |  |  |
|  | $\mathrm{t}_{\text {CE }}$ | Access Time from CE\# Low |  | Max | 55 | 55 | ns |
|  | $\mathrm{t}_{\text {ACC }}$ | Asynchronous Access Time |  | Max | 55 | 55 | ns |
|  | $\mathrm{t}_{\text {AVDP }}$ | AVD\# Low Time |  | Min | 10 |  | ns |
|  | $\mathrm{t}_{\text {AAVDS }}$ | Address Setup Time to Rising Edge of AVD |  | Min | 4 |  | ns |
|  | $\mathrm{t}_{\text {AAVDH }}$ | Address Hold Time from Rising Edge of AVD |  | Min | 5.5 |  | ns |
|  | toe | Output Enable to Output Valid |  | Max | 11.2 | 9.1 | ns |
|  | $\mathrm{t}_{\text {OEH }}$ | Output Enable Hold Time | Read | Min | 0 |  | ns |
|  |  |  | Toggle and Data\# Polling | Min | 8 |  | ns |
|  | $\mathrm{t}_{\text {OEZ }}$ | Output Enable to High Z |  | Max |  | 8 | ns |
|  | $\mathrm{t}_{\text {CAS }}$ | CE\# Setup Time to AVD\# |  | Min |  | 0 | ns |



Note: $R A=$ Read Address, $R D=$ Read Data.
Figure 20. Asynchronous Mode Read with Latched Addresses


Note: $R A=$ Read Address, $R D=$ Read Data.
Figure 21. Asynchronous Mode Read
Hardware Reset (RESET\#)

| Parameter |  | Description |  | All Speed Options | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| JEDEC | Std |  |  |  |  |
|  | $t_{\text {Ready }}$ | RESET\# Pin Low (During Embedded Algorithms) to Read Mode (See Note) | Max | 35 | $\mu \mathrm{s}$ |
|  | $t_{\text {Ready }}$ | RESET\# Pin Low (NOT During Embedded Algorithms) to Read Mode (See Note) | Max | 500 | ns |
|  | $\mathrm{t}_{\mathrm{RP}}$ | RESET\# Pulse Width | Min | 500 | ns |
|  | $\mathrm{t}_{\mathrm{RH}}$ | Reset High Time Before Read (See Note) | Min | 200 | ns |
|  | $t_{\text {RPD }}$ | RESET\# Low to Standby Mode | Min | 20 | $\mu \mathrm{s}$ |

Note: Not 100\% tested.


Reset Timings NOT during Embedded Algorithms


Reset Timings during Embedded Algorithms


Figure 22. Reset Timings

Erase/Program Operations

| Parameter |  | Description |  |  | 66 MHz | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| JEDEC | Standard |  |  |  |  |  |
| $\mathrm{t}_{\text {AVAV }}$ | $\mathrm{t}_{\text {WC }}$ | Write Cycle Time (Note 1) |  | Min | 45 | ns |
| $\mathrm{t}_{\text {AVWL }}$ | $\mathrm{t}_{\text {AS }}$ | Address Setup Time (Notes 2, 3) | Synchronous | Min | 4 | ns |
|  |  |  | Asynchronous |  | 0 |  |
| ${ }^{\text {W WLAX }}$ | $\mathrm{t}_{\text {AH }}$ | Address Hold Time (Notes 2, 3) | Synchronous | Min | 5.5 | ns |
|  |  |  | Asynchronous |  | 20 |  |
|  | $\mathrm{t}_{\text {AVDP }}$ | AVD\# Low Time |  | Min | 10 | ns |
| $t_{\text {DVWH }}$ | $\mathrm{t}_{\mathrm{DS}}$ | Data Setup Time |  | Min | 20 | ns |
| $\mathrm{t}_{\text {WHDX }}$ | $t_{\text {DH }}$ | Data Hold Time |  | Min | 0 | ns |
| $\mathrm{t}_{\text {GHWL }}$ | $\mathrm{t}_{\text {GHWL }}$ | Read Recovery Time Before Write |  | Min | 0 | ns |
|  | $\mathrm{t}_{\text {CAS }}$ | CE\# Setup Time to AVD\# |  | Min | 0 | ns |
| $t_{\text {WHEH }}$ | $\mathrm{t}_{\mathrm{CH}}$ | CE\# Hold Time |  | Min | 0 | ns |
| $t_{\text {WLWH }}$ | $t_{\text {WP }}$ | Write Pulse Width |  | Min | 20 | ns |
| $\mathrm{t}_{\text {WHWL }}$ | $t_{\text {WPH }}$ | Write Pulse Width High |  | Min | 20 | ns |
|  | $\mathrm{t}_{\text {SR/W }}$ | Latency Between Read and Write Operations |  | Min | 0 | ns |
| $\mathrm{t}_{\text {WHWH1 }}$ | $\mathrm{t}_{\text {WHWH1 }}$ | Programming Operation (Note 4 |  | Typ | <7 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {WHWH1 }}$ | $\mathrm{t}_{\text {WHWH1 }}$ | Accelerated Programming Opera | tion (Note 4) | Typ | <4 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {WHWH2 }}$ | $\mathrm{t}_{\text {WHWH2 }}$ | Sector Erase Operation (Notes 4, 5) |  | Typ | $<0.2$ | sec |
|  |  | Chip Erase Operation (Notes 4, 5) |  |  | $<104$ |  |
|  | $\mathrm{t}_{\text {VID }}$ | $\mathrm{V}_{\text {ACC }}$ Rise and Fall Time |  | Min | 500 | ns |
|  | $\mathrm{t}_{\text {VIDS }}$ | $\mathrm{V}_{\text {ACC }}$ Setup Time (During Accelerated Programming) |  | Min | 1 | $\mu \mathrm{s}$ |
|  | tvCS | $\mathrm{V}_{\text {CC }}$ Setup Time |  | Min | 50 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {ELWL }}$ | $\mathrm{t}_{\mathrm{CS}}$ | CE\# Setup Time to WE\# |  | Min | 0 | ns |
|  | $\mathrm{t}_{\text {AVSW }}$ | AVD\# Setup Time to WE\# |  | Min | 4 | ns |
|  | $\mathrm{t}_{\text {AVHW }}$ | AVD\# Hold Time to WE\# |  | Min | 4 | ns |
|  | $\mathrm{t}_{\text {AVHC }}$ | AVD\# Hold Time to CLK |  | Min | 4 | ns |
|  | $\mathrm{t}_{\mathrm{csw}}$ | Clock Setup Time to WE\# |  | Min | 5 | ns |

## Notes:

1. Not $100 \%$ tested.
2. Asynchronous mode allows both Asynchronous and Synchronous program operation. Synchronous mode allows both Asynchronous and Synchronous program operation.
3. In asynchronous program operation timing, addresses are latched on the falling edge of WE\# or rising edge of AVD\#. In synchronous program operation timing, addresses are latched on the first of either the rising edge of AVD\# or the active edge of CLK.
4. See the Erase and Programming Performance section for more information.
5. Does not include the preprogramming time.


## Notes:

1. $P A=$ Program Address, $P D=$ Program Data, $V A=$ Valid Address for reading status bits.
2. "In progress" and "complete" refer to status of program operation.
3. A22-A12 are don't care during command sequence unlock cycles.
4. $C L K$ can be either $V_{I L}$ or $V_{I H}$.
5. The Asynchronous programming operation is independent of the Set Device Read Mode bit in the Configuration Register.

Figure 23. Asynchronous Program Operation Timings: AVD\# Latched Addresses


## Notes:

1. $P A=$ Program Address, $P D=$ Program Data, $V A=$ Valid Address for reading status bits.
2. "In progress" and "complete" refer to status of program operation.
3. A22-A12 are don't care during command sequence unlock cycles.
4. $C L K$ can be either $V_{I L}$ or $V_{I H}$.
5. The Asynchronous programming operation is independent of the Set Device Read Mode bit in the Configuration Register.

Figure 24. Asynchronous Program Operation Timings: WE\# Latched Addresses


## Notes:

1. $P A=$ Program Address, $P D=$ Program Data, $V A=$ Valid Address for reading status bits.
2. "In progress" and "complete" refer to status of program operation.
3. A22-A12 are don't care during command sequence unlock cycles.
4. Addresses are latched on the first of either the rising edge of AVD\# or the active edge of CLK.
5. Either CE\# or AVD\# is required to go from low to high in between programming command sequences.
6. The Synchronous programming operation is dependent of the Set Device Read Mode bit in the Configuration Register. The Configuration Register must be set to the Synchronous Read Mode.

Figure 25. Synchronous Program Operation Timings: WE\# Latched Addresses


## Notes:

1. $P A=$ Program Address, $P D=$ Program Data, $V A=$ Valid Address for reading status bits.
2. "In progress" and "complete" refer to status of program operation.
3. A22-A12 are don't care during command sequence unlock cycles.
4. Addresses are latched on the first of either the rising edge of AVD\# or the active edge of CLK.
5. Either CE\# or AVD\# is required to go from low to high in between programming command sequences.
6. The Synchronous programming operation is dependent of the Set Device Read Mode bit in the Configuration Register. The Configuration Register must be set to the Synchronous Read Mode.

Figure 26. Synchronous Program Operation Timings: CLK Latched Addresses


## Notes:

1. $S A$ is the sector address for Sector Erase.
2. Address bits A22-A12 are don't cares during unlock cycles in the command sequence.

Figure 27. Chip/Sector Erase Command Sequence


Note: Use setup and hold times from conventional program operation.
Figure 28. Accelerated Unlock Bypass Programming Timing


## Notes:

1. Status reads in figure are shown as asynchronous.
2. $V A=$ Valid Address. Two read cycles are required to determine status. When the Embedded Algorithm operation is complete, and Data\# Polling will output true data.
3. While in Asynchronous mode, RDY will be low while the device is in embedded erase or programming mode.

Figure 29. Data\# Polling Timings (During Embedded Algorithm)


## Notes:

1. Status reads in figure are shown as asynchronous.
2. $V A=$ Valid Address. Two read cycles are required to determine status. When the Embedded Algorithm operation is complete, the toggle bits will stop toggling.
3. While in Asynchronous mode, RDY will be low while the device is in embedded erase or programming mode.

Figure 30. Toggle Bit Timings (During Embedded Algorithm)


## Notes:

1. The timings are similar to synchronous read timings.
2. $V A=$ Valid Address. Two read cycles are required to determine status. When the Embedded Algorithm operation is complete, the toggle bits will stop toggling.
3. RDY is active with data ( $A 18=0$ in the Configuration Register). When $A 18=1$ in the Configuration Register, RDY is active one clock cycle before data.

Figure 31. Synchronous Data Polling Timings/Toggle Bit Timings


Note: DQ2 toggles only when read at an address within an erase-suspended sector. The system may use OE\# or CE\# to toggle DQ2 and DQ6.

Figure 32. DQ2 vs. DQ6

## Temporary Sector Unprotect

| Parameter |  |  |  |  |  |
| :---: | :---: | :--- | :---: | :---: | :---: |
| JEDEC | Std | Description | All Speed Options | Unit |  |
|  | $\mathrm{t}_{\text {VIDR }}$ | V ID Rise and Fall Time (See Note) | Min | 500 | ns |
|  | $\mathrm{t}_{\mathrm{VHH}}$ | V $_{\text {HH }}$ Rise and Fall Time (See Note) | Min | 250 | ns |
|  | $\mathrm{t}_{\text {RSP }}$ | RESET\# Setup Time for Temporary Sector <br> Unprotect | Min | 4 | $\mu \mathrm{~s}$ |
|  | $\mathrm{t}_{\text {RRB }}$ | RESET\# Hold Time from RDY High for <br> Temporary Sector Unprotect | Min | 4 | $\mu \mathrm{~s}$ |

Note: Not 100\% tested.


Figure 33. Temporary Sector Unprotect Timing Diagram


Note: For sector protect, $A 6=0, A 1=1, A 0=0$. For sector unprotect, $A 6=1, A 1=1, A 0=0$.
Figure 34. Sector/Sector Block Protect and Unprotect Timing Diagram


## Notes:

1. RDY active with data ( $A 18=0$ in the Configuration Register).
2. RDY active one clock cycle before data ( $A 18=1$ in the Configuration Register).
3. Cxx indicates the clock that triggers Dxx on the outputs; for example, C60 triggers D60. Figure shows the device not crossing a bank in the process of performing an erase or program.
4. If the starting address latched in is either 3Eh or 3Fh (or some 64 multiple of either), there is no additional 2 cycle latency at the boundary crossing.

Figure 35. Latency with Boundary Crossing

Address boundary occurs every 64 words, beginning at address $00003 F h:(00007 \mathrm{Fh}, 0000 \mathrm{BFh}$, etc.) Address 000000 h is also a boundary crossing.


## Notes:

1. RDY active with data (A18 $=0$ in the Configuration Register).
2. RDY active one clock cycle before data (A18 = 1 in the Configuration Register).
3. Cxx indicates the clock that triggers Dxx on the outputs; for example, C60 triggers D60. Figure shows the device crossing a bank in the process of performing an erase or program.

Figure 36. Latency with Boundary Crossing into Program/Erase Bank


Wait State Decoding Addresses:
A14, A13, A12 = " 111 " $\Rightarrow$ Reserved
A14, A13, A12 = " 110 " $\Rightarrow$ Reserved
A14, A13, A12 = " $101 " \Rightarrow 5$ programmed, 7 total
A14, A13, A12 = " 100 " $\Rightarrow 4$ programmed, 6 total
A14, A13, A12 = " 011 " $\Rightarrow 3$ programmed, 5 total
A14, A13, A12 = "010" $\Rightarrow 2$ programmed, 4 total
A14, A13, A12 = " $001 " \Rightarrow 1$ programmed, 3 total
A14, A13, A12 = " 000 " $\Rightarrow 0$ programmed, 2 total
Note: Figure assumes address DO is not at an address boundary, active clock edge is rising, and wait state is set to "101".
Figure 37. Example of Wait States Insertion


Note: Breakpoints in waveforms indicate that system may alternately read array data from the "non-busy bank" while checking the status of the program or erase operation in the "busy" bank. The system should read status twice to ensure valid information.

Figure 38. Back-to-Back Read/Write Cycle Timings

## Erase and Programming Performance

| Parameter |  | Typ (Note I) | Max (Note 2) | Unit | Comments |
| :--- | :--- | :---: | :---: | :---: | :---: |
| Sector Erase Time | 32 Kword | $<0.4$ | $<2$ | s | Excludes 00h programming |
|  | 4 Kword | $<0.2$ | $<2$ |  |  |

## Notes:

1. Typical program and erase times assume the following conditions: $25^{\circ} \mathrm{C}, 1.8 \mathrm{~V} \mathrm{~V}_{\mathrm{CC}}, 100 \mathrm{~K}$ cycles. Additionally, programming typicals assumes a checkerboard pattern.
2. Under worst case conditions of $90^{\circ} \mathrm{C}, V_{C C}=1.65 \mathrm{~V}, 1,000,000$ cycles
3. The typical chip programming time is considerably less than the maximum chip programming time listed.
4. In the pre-programming step of the Embedded Erase algorithm, all words are programmed to 00h before erasure.
5. System-level overhead is the time required to execute the two- or four-bus-cycle sequence for the program command. See Table 18, "Command Definitions," on page 60 for further information on command definitions.
6. The device has a minimum erase and program cycle endurance of 100,000 cycles.

## Physical Dimensions

## VBH084 - 84-ball Fine-Pitch Ball Grid Array (FBGA) 8xll. 6 mm MCP Compatible Package (I28Mb)



| PACKAGE | VBH 084 |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| JEDEC | N/A |  |  |  |
|  | $\begin{gathered} 11.60 \mathrm{~mm} \times 8.00 \mathrm{~mm} \text { NOM } \\ \text { PACKAGE } \end{gathered}$ |  |  |  |
| SYMBOL | MIN | NOM | MAX | NOTE |
| A | --- | --- | 1.00 | OVERALL THICKNESS |
| A1 | 0.18 | --- | --- | BALL HEIGHT |
| A2 | 0.62 | --- | 0.76 | BODY THICKNESS |
| D | 11.60 BSC. |  |  | BODY SIZE |
| E | 8.00 BSC. |  |  | BODY SIZE |
| D1 | 8.80 BSC. |  |  | BALL FOOTPRINT |
| E1 | 7.20 BSC. |  |  | BALL FOOTPRINT |
| MD | 12 |  |  | ROW MATRIX SIZE D DIRECTION |
| ME | 10 |  |  | ROW MATRIX SIZE E DIRECTION |
| N | 84 |  |  | TOTAL BALL COUNT |
| ¢b | 0.33 | --- | 0.43 | BALL DIAMETER |
| e | 0.80 BSC. |  |  | BALL PITCH |
| SD / SE | 0.40 BSC. |  |  | SOLDER BALL PLACEMENT |
|  | $\begin{aligned} & \text { (A2-A9, B10-L10, } \\ & \text { M2-M9, B1-L1) } \end{aligned}$ |  |  | DEPOPULATED SOLDER BALLS |

NOTES:

1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.
2. ALL DIMENSIONS ARE IN MILLIMETERS.
3. BALL POSITION DESIGNATION PER JESD 95-1, SPP-010 (EXCEPT AS NOTED).
4. e REPRESENTS THE SOLDER BALL GRID PITCH.
5. SYMBOL "MD" IS THE BALL ROW MATRIX SIZE IN THE "D" DIRECTION.
SYMBOL "ME" IS THE BALL COLUMN MATRIX SIZE IN THE "E" DIRECTION.
N IS THE TOTAL NUMBER OF SOLDER BALLS.
6 DIMENSION "b" IS MEASURED AT THE MAXIMUM BALL DIAMETER IN A PLANE PARALLEL TO DATUM C.
7 SD AND SE ARE MEASURED WITH RESPECT TO DATUMS A AND B AND DEFINE THE POSITION OF THE CENTER SOLDER BALL IN THE OUTER ROW.
WHEN THERE IS AN ODD NUMBER OF SOLDER BALLS IN THE OUTER ROW PARALLEL TO THE D OR E DIMENSION, RESPECTIVELY, SD OR SE $=0.000$.
WHEN THERE IS AN EVEN NUMBER OF SOLDER BALLS IN THE OUTER ROW, SD OR SE = e/2
6. NOT USED.
7. "+" INDICATES THE THEORETICAL CENTER OF DEPOPULATED BALLS.
8. A1 CORNER TO BE IDENTIFIED BY CHAMFER, LASER OR INK MARK, METALLIZED MARK INDENTATION OR OTHER MEANS.

Note: BSC is an ANSI standard for Basic Space Centering

## VBR080 - 80-ball Fine-Pitch Ball Grid Array (FBGA) $7 \times 9 \mathrm{~mm}$ (64Mb)



| PACKAGE | VBR 080 |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| JEDEC | N/A |  |  |  |
|  | $9.00 \mathrm{~mm} \times 7.00 \mathrm{~mm}$ NOM PACKAGE |  |  |  |
| SYMBOL | MIN | NOM | MAX | NOTE |
| A | --- | --- | 1.00 | OVERALL THICKNESS |
| A1 | 0.17 | --- | --- | BALL HEIGHT |
| A2 | 0.62 | --- | 0.73 | BODY THICKNESS |
| D | 9.00 BSC . |  |  | BODY SIZE |
| E | 7.00 BSC. |  |  | BODY SIZE |
| D1 | 7.20 BSC. |  |  | BALL FOOTPRINT |
| E1 | 5.60 BSC . |  |  | BALL FOOTPRINT |
| MD | 10 |  |  | ROW MATRIX SIZE D DIRECTION |
| ME | 8 |  |  | ROW MATRIX SIZE E DIRECTION |
| N | 80 |  |  | TOTAL BALL COUNT |
| ¢b | 0.35 | --- | 0.45 | BALL DIAMETER |
| e | 0.80 BSC . |  |  | BALL PITCH |
| SD / SE | 0.40 BSC . |  |  | SOLDER BALL PLACEMENT |
|  | NONE |  |  | DEPOPULATED SOLDER BALLS |

NOTES:

1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.
2. ALL DIMENSIONS ARE IN MILLIMETERS.
3. BALL POSITION DESIGNATION PER JESD 95-1, SPP-010 (EXCEPT AS NOTED).
4. e REPRESENTS THE SOLDER BALL GRID PITCH.
5. SYMBOL "MD" IS THE BALL ROW MATRIX SIZE IN THE "D" DIRECTION.
SYMBOL "ME" IS THE BALL COLUMN MATRIX SIZE IN THE "E" DIRECTION.
N IS THE TOTAL NUMBER OF SOLDER BALLS.
6 DIMENSION "b" IS MEASURED AT THE MAXIMUM BALL DIAMETER IN A PLANE PARALLEL TO DATUM C.
4 SD AND SE ARE MEASURED WITH RESPECT TO DATUMS A AND B AND DEFINE THE POSITION OF THE CENTER SOLDER BALL IN THE OUTER ROW.

WHEN THERE IS AN ODD NUMBER OF SOLDER BALLS IN THE OUTER ROW PARALLEL TO THE D OR E DIMENSION, RESPECTIVELY, SD OR SE $=0.000$.
WHEN THERE IS AN EVEN NUMBER OF SOLDER BALLS IN THE OUTER ROW, SD OR SE $=\mathrm{e} / 2$
8. NOT USED.
9. "+" INDICATES THE THEORETICAL CENTER OF DEPOPULATED BALLS.
10 A1 CORNER TO BE IDENTIFIED BY CHAMFER, LASER OR INK MARK, METALLIZED MARK INDENTATION OR OTHER MEANS.

Note: BSC is an ANSI standard for Basic Space Centering

## Revision Summary

## Revision A0 (July 22, 2004)

Initial release.

## Revision Al (October 6, 2004)

Add 'BF' parts on Valid Combination table.

## Revision A2 (December 10, 2004)

Remove all in terms of 104 MHz speed bin.
Change statement of command during time-out period of sector erase.
Change exit command statement about password program command
Change exit command statement about password protection mode locking bit program command Change exit command statement about persistentsector protection mode locking bit program command

Change exit command statement about Secured Silicon sector protection bit program command Change exit command statement about PPB program command
Change exit command statement about All PPB erase command
Change exit command statement about PPB/PPB lock bit status command
Change PPB command table.
Remove note 19 in command table.
Change waveform about boundary crossing.
Remove DC spec output disable status in synchronous read mode.
Change the word from SMPL to PL, from OPBP to OW
Change the statement PPB Lock Bit Set Command.
Delete $\mathrm{V}_{\mathrm{IO}}$ pin
Added description at "RDY Configuration" in page56
Modified $\mathrm{t}_{\mathrm{AH}}$ in Asynchronous mode to 20ns in page89

## Revision A3 (February 19, 2005)

Change "Secsi" to "Secured Silicon"
Add migration statement.
Modify "Sync Latency", "Asyn Access time" @80MHz
Update "Product Selector Guide" on tACC, tCE, tIACC@80MHz
Modify Table 15( "Wait States for Standard Wait-state Handshaking")
Change "Supply Voltage" to "1.70V to 1.95 V for 80 MHz parts
Modify "CLK Characterization" table

## Revision A4 (June 24, 2005)

Added information for "Revision 1" for boundary crossing while in Continuous read mode Removed all references to WS128J 80 MHz and WS064J Industrial grades

## Revision A5 (March 3I, 2006)

Updated the Valid Combinations table for the 128 Mb device

## Revision A6 (May II, 2006)

Add new OPNs, supporting Industrial temperature

## Colophon

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[^0]:    14. The Unlock Bypass Reset command is required to return to reading array data.
    15. The system may read and program in non-erasing sectors, or enter the autoselect mode, when in the Erase Suspend mode. The Erase Suspend command is valid only during a sector erase operation, and requires the bank address.
    16. The Erase Resume command is valid only during the Erase Suspend mode, and requires the bank address.
    17. See "Set Configuration Register Command Sequence" for details.
    18. Command is valid when device is ready to read array data or when device is in autoselect mode.
    19. Regardless of CLK and AVD\# interaction or Control Register bit 15 setting, command mode verifies are always asynchronous read operations.
    20. ACC must be at $V_{H H}$ during the entire operation of this command
    21. The fourth cycle programs the addressed locking bit. The fifth and sixth cycles are used to validate whether the bit has been fully programmed. If DQ0 (in the sixth cycle) reads 0 , the program command must be issued and verified again.
    22. The fourth cycle erases all PPBs. The fifth and sixth cycles are used to validate whether the bits have been fully erased. If DQO (in the sixth cycle) reads 1, the erase command must be issued and verified again.
    23. The entire four bus-cycle sequence must be entered for each portion of the password.
    24. Before issuing the erase command, all PPBs should be programmed in order to prevent over-erasure of PPBs.
    25. In the fourth cycle, 01h indicates PPB set; OOh indicates PPB not set.
