



50MHz to 1000MHz High-Linearity, Serial/ Parallel-Controlled Analog/Digital VGA

MAX2065

General Description

The MAX2065 high-linearity, analog/digital variable-gain amplifier (VGA) is designed to operate in the 50MHz to 1000MHz frequency range with two independent attenuators (see the *Typical Application Circuit*). The digital attenuator is controlled as a slave peripheral using either the SPI™-compatible interface or a parallel bus with 31dB total adjustment range in 1dB steps. An added feature allows “rapid-fire” gain selection between each of four steps, preprogrammed by the user through the SPI-compatible interface. The 2-pin control allows the user to quickly access any one of four customized attenuation states without reprogramming the SPI bus. The analog attenuator is controlled using an external voltage or through the SPI-compatible interface using an on-chip 8-bit DAC.

Because each of the three stages has its own RF input and RF output, this component can be configured to either optimize NF (amplifier configured first), OIP3 (amplifier last), or a compromise of NF and OIP3. The device's performance features include 22dB amplifier gain (amplifier only), 6.5dB NF at maximum gain (includes attenuator insertion losses), and a high OIP3 level of +42dBm. Each of these features makes the MAX2065 an ideal VGA for numerous receiver and transmitter applications.

In addition, the MAX2065 operates from a single +5V supply with full performance, or a single +3.3V supply with slightly reduced performance, and has an adjustable bias to trade current consumption for linearity performance. This device is available in a compact 40-pin thin QFN package (6mm x 6mm) with an exposed pad. Electrical performance is guaranteed over the extended temperature range ($T_C = -40^\circ\text{C}$ to $+85^\circ\text{C}$).

Applications

IF and RF Gain Stages
 Temperature Compensation Circuits
 Cellular Band WCDMA and cdma2000® Base Stations
 GSM 850/GSM 900 EDGE Base Stations
 WiMAX and LTE Base Stations and Customer Premise Equipment
 Fixed Broadband Wireless Access
 Wireless Local Loop
 Military Systems
 Video-on-Demand (VOD) and DOCSIS®-Compliant EDGE QAM Modulation
 Cable Modem Termination Systems (CMTS)

SPI is a trademark of Motorola, Inc.



Features

- ◆ 50MHz to 1000MHz RF Frequency Range
- ◆ Pin-Compatible Family Includes:
 MAX2066 (Digital VGA)
 MAX2067 (Analog VGA)
- ◆ +19.4dB (Typ) Maximum Gain
- ◆ 0.5dB Gain Flatness Over 100MHz Bandwidth
- ◆ 62dB Gain Range (31dB Analog + 31dB Digital)
- ◆ Built-in DAC for Analog Attenuation Control
- ◆ Supports Four “Rapid-Fire” Preprogrammed Attenuator States
 Quickly Access Any One of Four Customized Attenuation States Without Reprogramming the SPI Bus
 Ideal for Fast-Attack, High-Level Blocker Protection Prevents ADC Overdrive Condition
- ◆ Excellent Linearity (Configured with Amplifier Last)
 +42dBm OIP3
 +63dBm OIP2
 +19dBm Output 1dB Compression Point
 -67dBc HD2
 -83dBc HD3
- ◆ 6.5dB Typical Noise Figure (NF)
- ◆ Fast, 25ns Digital Switching
- ◆ Very Low Digital VGA Amplitude Overshoot/Undershoot
- ◆ Single +5V Supply (Optional +3.3V Operation)
- ◆ External Current-Setting Resistors Provide Option for Operating Device in Reduced-Power/Reduced-Performance Mode

Ordering Information

| PART | TEMP RANGE | PIN-PACKAGE | PKG CODE |
|--------------|----------------|-----------------|----------|
| MAX2065ETL+ | -40°C to +85°C | 40 Thin QFN-EP* | T4066-3 |
| MAX2065ETL+T | -40°C to +85°C | 40 Thin QFN-EP* | T4066-3 |

+Denotes a lead-free package.

*EP = Exposed pad.

T = Tape and reel.

Pin Configuration appears at end of data sheet.

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ABSOLUTE MAXIMUM RATINGS

| | | | |
|-----------------------------------------------------------------|------------------------|-----------------------------------------------------------------------|---------------------------------|
| VCC_ to GND | -0.3V to +5.5V | RF Input Power (ATTEN1_IN, ATTEN1_OUT, ATTEN2_IN, ATTEN2_OUT)..... | +20dBm |
| VDD_LOGIC, DATA, CS, CLK, SER/PAR, VDAC_EN, VREF_SELECT..... | -0.3V to (VCC_ + 0.3V) | RF Input Power (AMP_IN)..... | +18dBm |
| STATE_A, STATE_B, D0-D4 | -0.3V to (VCC_ + 0.3V) | Continuous Power Dissipation (Note 1) | 6.5W |
| AMP_IN, AMP_OUT, VREF_IN, ANALOG_VCTRL | -0.3V to (VCC_ + 0.3V) | θ_{JA} (Notes 2, 3)..... | +38°C/W |
| ATTEN1_IN, ATTEN1_OUT, ATTEN2_IN, ATTEN2_OUT..... | -1.2V to + 1.2V | θ_{JC} (Note 3) | +10°C/W |
| RSET to GND..... | -0.3V to + 1.2V | Operating Temperature Range (Note 4)..... | T _C = -40°C to +85°C |
| | | Maximum Junction Temperature | +150°C |
| | | Storage Temperature..... | -65°C to +150°C |
| | | Lead Temperature (soldering, 10s) | +300°C |

Note 1: Based on junction temperature $T_J = T_C + (\theta_{JC} \times V_{CC} \times I_{CC})$. This formula can be used when the temperature of the exposed pad is known while the device is soldered down to a printed-circuit board (PCB). See the *Applications Information* section for details. The junction temperature must not exceed +150°C.

Note 2: Junction temperature $T_J = T_A + (\theta_{JA} \times V_{CC} \times I_{CC})$. This formula can be used when the ambient temperature of the PCB is known. The junction temperature must not exceed +150°C.

Note 3: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a 4-layer board. For detailed information on package thermal considerations, refer to www.maxim-ic.com/thermal-tutorial.

Note 4: T_C is the temperature on the exposed pad of the package. T_A is the ambient temperature of the device and PCB.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

+3.3V SUPPLY DC ELECTRICAL CHARACTERISTICS

(Typical Application Circuit, high-current (HC) mode, V_{CC} = +3.0V to +3.6V, T_C = -40°C to +85°C. Typical values are at V_{CC} = +3.3V and T_C = +25°C, unless otherwise noted.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------------------------------------------------------------------------|-----------------|------------|-----|-----|-----|-------|
| Supply Voltage | V _{CC} | | 3.0 | 3.3 | 3.6 | V |
| Supply Current | I _{CC} | | | 60 | 80 | mA |
| LOGIC INPUTS (DATA, CS, CLK, VDAC_EN, VREF_SELECT, SER/PAR, STATE_A, STATE_B, D0-D4) | | | | | | |
| Input High Voltage | V _{IH} | | | 2 | | V |
| Input Low Voltage | V _{IL} | | | 0.8 | | V |

+5V SUPPLY DC ELECTRICAL CHARACTERISTICS

(Typical Application Circuit, V_{CC} = +4.75V to +5.25V, T_C = -40°C to +85°C. Typical values are at V_{CC} = +5V and T_C = +25°C, unless otherwise noted.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------------------------------------------------------------------------|-----------------|------------------------|------|-----|------|-------|
| Supply Voltage | V _{CC} | | 4.75 | 5 | 5.25 | V |
| Supply Current | I _{CC} | Low-current (LC) mode | | 73 | 93 | mA |
| | | High-current (HC) mode | | 124 | 146 | |
| LOGIC INPUTS (DATA, CS, CLK, VDAC_EN, VREF_SELECT, SER/PAR, STATE_A, STATE_B, D0-D4) | | | | | | |
| Input High Voltage | V _{IH} | | 3 | | | V |
| Input Low Voltage | V _{IL} | | | | 0.8 | V |
| Input Current Logic-High | I _{IH} | | -1 | | +1 | μA |
| Input Current Logic-Low | I _{IL} | | -1 | | +1 | μA |

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+3.3V SUPPLY AC ELECTRICAL CHARACTERISTICS

(Typical Application Circuit, $V_{CC} = +3.0V$ to $+3.6V$, $T_C = -40^{\circ}C$ to $+85^{\circ}C$. Typical values are at $V_{CC} = +3.3V$, HC mode with attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^{\circ}C$, unless otherwise noted.) (Note 5)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------------|----------|----------------------------------------------|-----|------|------|-------|
| RF Frequency Range | f_{RF} | (Notes 6, 7) | 50 | | 1000 | MHz |
| Small Signal Gain | G | | | 18.8 | | dB |
| Output Third-Order Intercept Point | OIP3 | $P_{OUT} = 0dBm/$ tone, maximum gain setting | | 37.5 | | dBm |
| Noise Figure | NF | Maximum gain setting | | 6.7 | | dB |
| Total Attenuation Range | | Analog and digital combined | | 61.5 | | dB |

+5V SUPPLY AC ELECTRICAL CHARACTERISTICS

(Typical Application Circuit, $V_{CC} = +4.75$ to $+5.25V$, HC mode with each attenuator set for maximum gain, $50MHz \leq f_{RF} \leq 1000MHz$, $T_C = -40^{\circ}C$ to $+85^{\circ}C$. Typical values are at $V_{CC} = +5.0V$, HC mode, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^{\circ}C$, unless otherwise noted.) (Note 5)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------------|----------|---------------------------------------------------------|--------|--------|------|-----------------|
| RF Frequency Range | f_{RF} | (Notes 6, 7) | 50 | | 1000 | MHz |
| Small Signal Gain | G | 200MHz | | 19.4 | | dB |
| | | 350MHz, $T_C = +25^{\circ}C$ | 17.5 | 18.7 | 19.7 | |
| | | 450MHz | | 18.2 | | |
| | | 750MHz | | 16.4 | | |
| | | 900MHz | | 15.6 | | |
| Gain Variation vs. Temperature | | | | -0.006 | | dB/ $^{\circ}C$ |
| Gain Flatness vs. Frequency | | Any 100MHz frequency band from 50MHz to 500MHz | | 0.5 | | dB |
| Noise Figure | NF | 200MHz | | 6.5 | | dB |
| | | 350MHz, $T_C = +25^{\circ}C$ (Note 7) | | 6.8 | 8 | |
| | | 450MHz | | 7 | | |
| | | 750MHz | | 7.8 | | |
| | | 900MHz | | 8.2 | | |
| Total Attenuation Range | | Analog and digital combined | | 61.5 | | dB |
| Output Second-Order Intercept Point | OIP2 | $P_{OUT} = 0dBm/$ tone, $\Delta f = 1MHz$, $f_1 + f_2$ | | 63 | | dBm |
| Output Third-Order Intercept Point | OIP3 | $P_{OUT} = 0dBm/$ tone, HC mode, $\Delta f = 1MHz$ | 200MHz | | 42 | dBm |
| | | | 350MHz | | 40 | |
| | | | 450MHz | | 39 | |
| | | | 750MHz | | 36 | |
| | | | 900MHz | | 35 | |
| | | $P_{OUT} = 0dBm/$ tone, LC mode, $\Delta f = 1MHz$ | 200MHz | | 40 | |
| | | | 350MHz | | 38 | |
| | | | 450MHz | | 37 | |
| | | | 750MHz | | 35 | |
| | | | 900MHz | | 33 | |

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+5V SUPPLY AC ELECTRICAL CHARACTERISTICS (continued)

(Typical Application Circuit, $V_{CC} = +4.75$ to $+5.25V$, HC mode with each attenuator set for maximum gain, $50MHz \leq f_{RF} \leq 1000MHz$, $T_C = -40^\circ C$ to $+85^\circ C$. Typical values are at $V_{CC} = +5.0V$, HC mode, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, unless otherwise noted.) (Note 5)

| PARAMETER | SYMBOL | CONDITIONS | | MIN | TYP | MAX | UNITS |
|------------------------------------|-----------|---------------------------------------------------------------------------------------------|-------------|------|-------|------|---------|
| Output -1dB Compression Point | P_{1dB} | 350MHz, $T_C = +25^\circ C$ (Note 8) | | 17 | 18.7 | | dBm |
| Second Harmonic | | $P_{OUT} = +3dBm$, $f_{RF} = 200MHz$, $T_C = +25^\circ C$ (Note 7) | | -60 | -67 | | dBc |
| Third Harmonic | | $P_{OUT} = +3dBm$, $f_{RF} = 200MHz$, $T_C = +25^\circ C$ (Note 7) | | -71 | -83 | | dBc |
| Input Return Loss | | 50 Ω source, maximum gain setting | | | 18 | | dB |
| Output Return Loss | | 50 Ω load, maximum gain setting | | | 18 | | dB |
| DIGITAL ATTENUATOR | | | | | | | |
| Insertion Loss | | | | | 2.5 | | dB |
| Input Second-Order Intercept Point | IIP2 | $P_{RF1} = 0dBm$, $P_{RF2} = 0dBm$, $\Delta f = 1MHz$, $f_1 + f_2$ | | | 52 | | dBm |
| Input Third-Order Intercept Point | IIP3 | $P_{RF1} = 0dBm$, $P_{RF2} = 0dBm$, $\Delta f = 1MHz$ | | | 41 | | dBm |
| Attenuation Range | | | | | 31.2 | | dB |
| Step Size | | | | | 1 | | dB |
| Relative Step Accuracy | | | | | 0.2 | | dB |
| Absolute Step Accuracy | | | | | 0.45 | | dB |
| Insertion Phase Step | | $f_{RF} = 170MHz$ | 0dB to 16dB | | 4.8 | | Degrees |
| | | | 24dB | | 8 | | |
| | | | 31dB | | 10.8 | | |
| Amplitude Overshoot/Undershoot | | Between any two states | ET = 15ns | | 1.0 | | dB |
| | | | ET = 40ns | | 0.05 | | |
| Switching Speed | | RF settled to within $\pm 0.1dB$ | 31dB to 0dB | | 25 | | ns |
| | | | 0dB to 31dB | | 21 | | |
| Input Return Loss | | 50 Ω source | | | 19 | | dB |
| Output Return Loss | | 50 Ω load | | | 19 | | dB |
| ANALOG ATTENUATOR | | | | | | | |
| Insertion Loss | | | | | 1.2 | | dB |
| Input Second-Order Intercept Point | IIP2 | $P_{RF1} = 0dBm$, $P_{RF2} = 0dBm$, maximum gain setting, $\Delta f = 1MHz$, $f_1 + f_2$ | | | 70 | | dBm |
| Input Third-Order Intercept Point | IIP3 | $P_{RF1} = 0dBm$, $P_{RF2} = 0dBm$, maximum gain setting, $\Delta f = 1MHz$ | | | 36 | | dBm |
| Attenuation Range | | Analog control input | | | 31.1 | | dB |
| Gain Control Slope | | Analog control input | | | -12.5 | | dB/V |
| Maximum Gain Control Slope | | Over analog control input range | | | -35 | | dB/V |
| Insertion Phase Change | | Over analog control input range | | | 18 | | Degrees |
| Group Delay | | Maximum gain setting | | | 0.98 | | ns |
| Group Delay vs. Control Voltage | | Over analog control input range | | | -0.25 | | ns |
| Analog Control Input Range | | | | 0.25 | | 2.75 | V |

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+5V SUPPLY AC ELECTRICAL CHARACTERISTICS (continued)

(Typical Application Circuit, $V_{CC} = +4.75$ to $+5.25V$, HC mode with each attenuator set for maximum gain, $50MHz \leq f_{RF} \leq 1000MHz$, $T_C = -40^\circ C$ to $+85^\circ C$. Typical values are at $V_{CC} = +5.0V$, HC mode, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, unless otherwise noted.) (Note 5)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------------------|------------------|---------------------|------|-----|------|------------|
| Analog Control Input Impedance | | | | 80 | | k Ω |
| Input Return Loss | | 50 Ω source | | 22 | | dB |
| Output Return Loss | | 50 Ω load | | 22 | | dB |
| D/A CONVERTER | | | | | | |
| Number of Bits | | | | 8 | | Bits |
| Output Voltage | | DAC code = 00000000 | | | 0.25 | V |
| | | DAC code = 11111111 | 2.75 | | | |
| SERIAL PERIPHERAL INTERFACE (SPI) | | | | | | |
| Maximum Clock Speed | f _{CLK} | | | 20 | | MHz |
| Data-to-Clock Setup Time | t _{CS} | | | 2 | | ns |
| Data-to-Clock Hold Time | t _{CH} | | | 2.5 | | ns |
| Clock-to- \overline{CS} Setup Time | t _{ES} | | | 3 | | ns |
| \overline{CS} Positive Pulse Width | t _{EW} | | | 7 | | ns |
| \overline{CS} Setup Time | t _{EWS} | | | 3.5 | | ns |
| Clock Pulse Width | t _{CW} | | | 5 | | ns |

Note 5: All limits include external component losses. Output measurements are performed at RF output port of the *Typical Application Circuit*.

Note 6: Operating outside this range is possible, but with degraded performance of some parameters.

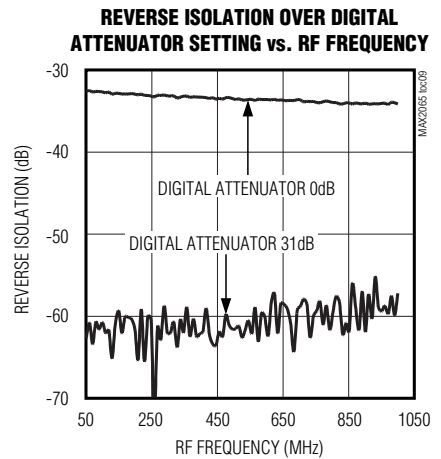
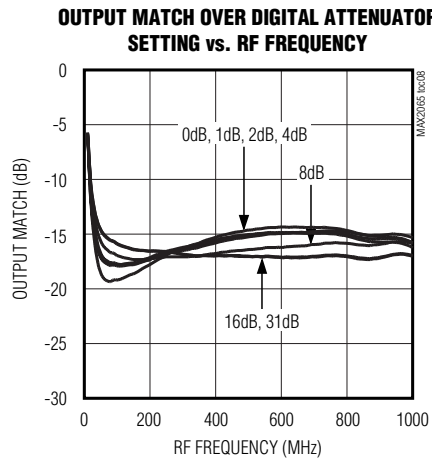
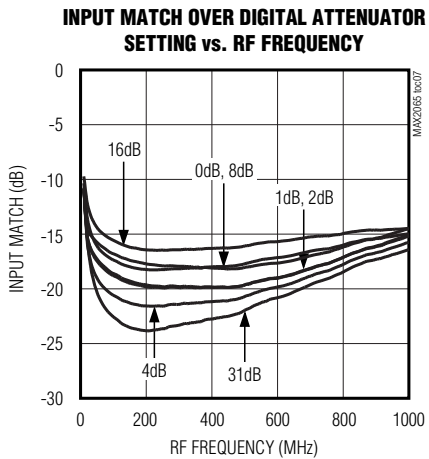
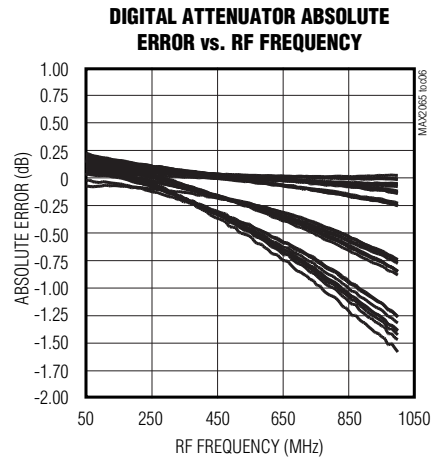
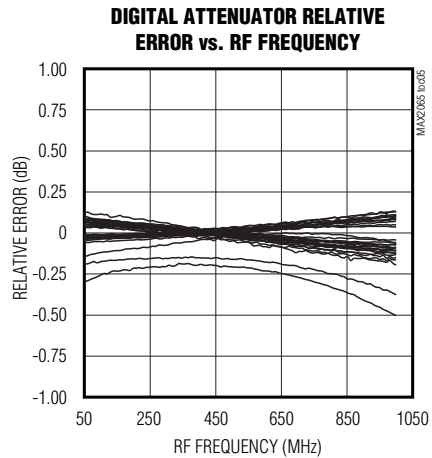
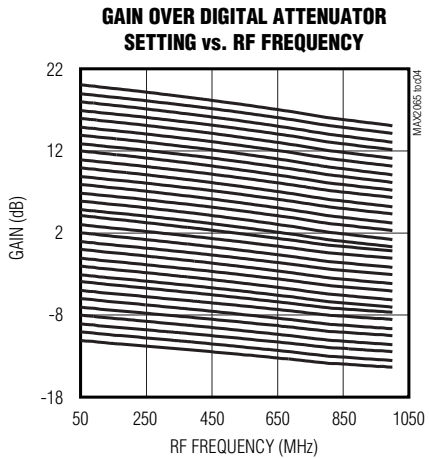
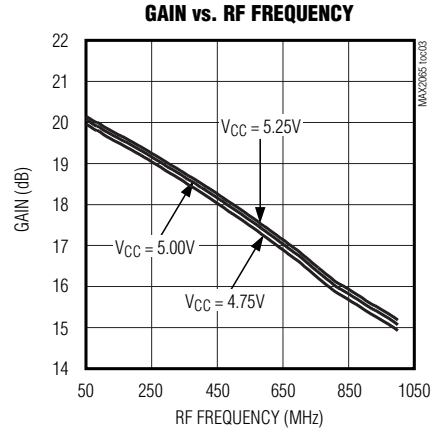
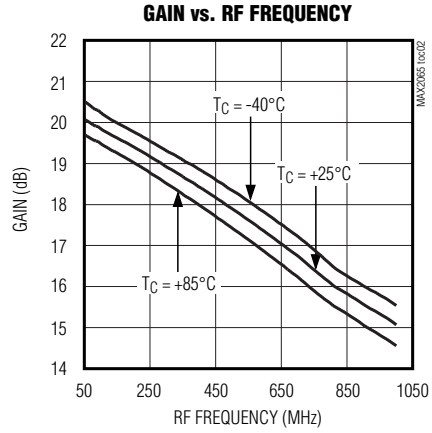
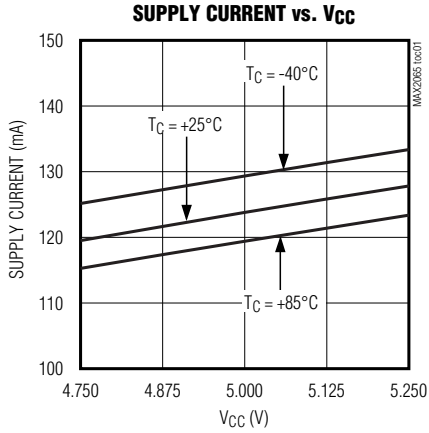
Note 7: Guaranteed by design and characterization.

Note 8: It is advisable not to operate continuously the VGA RF input above +15dBm.

50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

Typical Operating Characteristics

($V_{CC} = +5.0V$, HC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal DAC reference used, unless otherwise noted.)

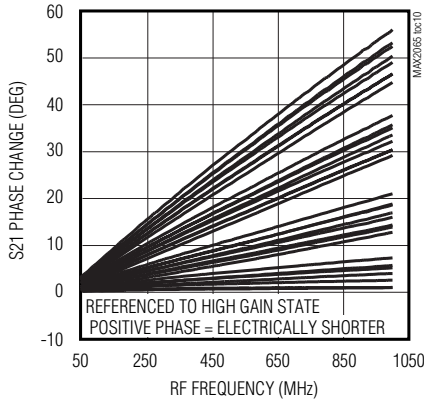


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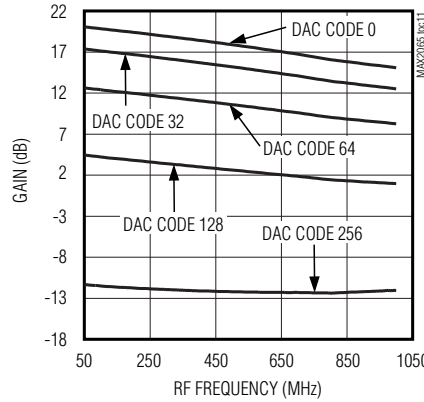
Typical Operating Characteristics (continued)

($V_{CC} = +5.0V$, HC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal DAC reference used, unless otherwise noted.)

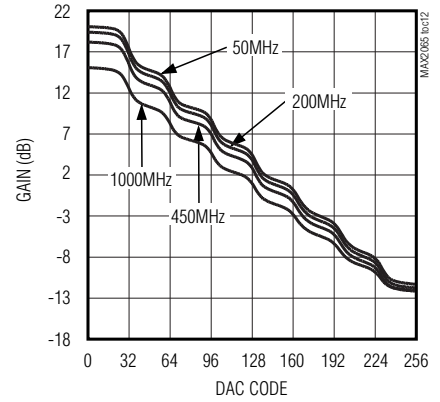
S21 PHASE CHANGE OVER DIGITAL ATTENUATOR SETTING vs. RF FREQUENCY



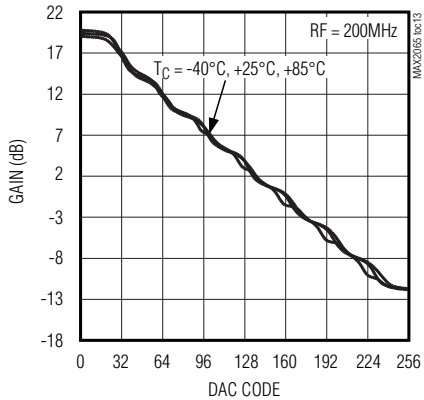
GAIN OVER ANALOG ATTENUATOR SETTING vs. RF FREQUENCY



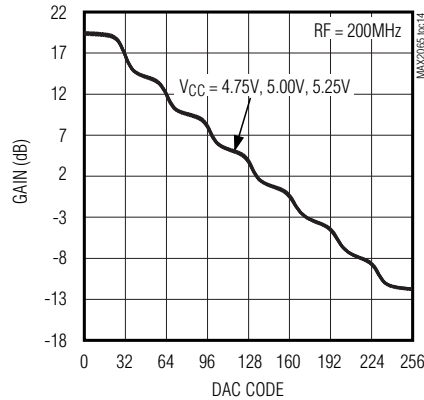
GAIN vs. ANALOG ATTENUATOR SETTING



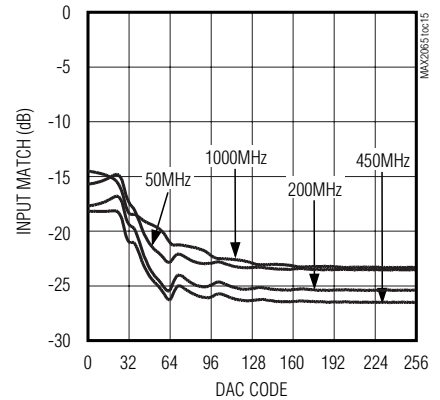
GAIN vs. ANALOG ATTENUATOR SETTING



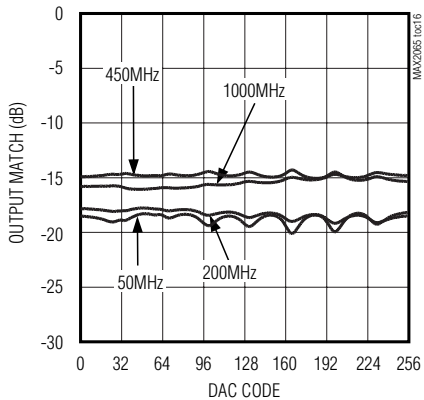
GAIN vs. ANALOG ATTENUATOR SETTING



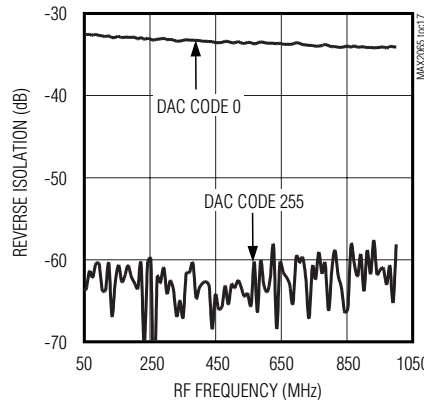
INPUT MATCH vs. ANALOG ATTENUATOR SETTING



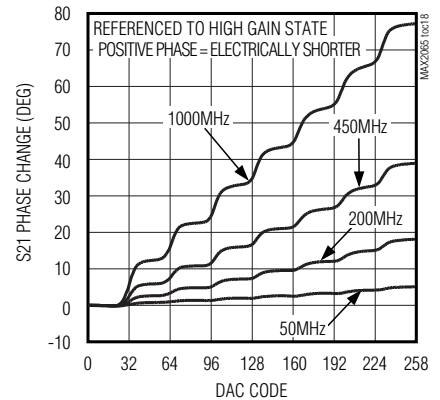
OUTPUT MATCH vs. ANALOG ATTENUATOR SETTING



REVERSE ISOLATION OVER ANALOG ATTENUATOR SETTING vs. RF FREQUENCY



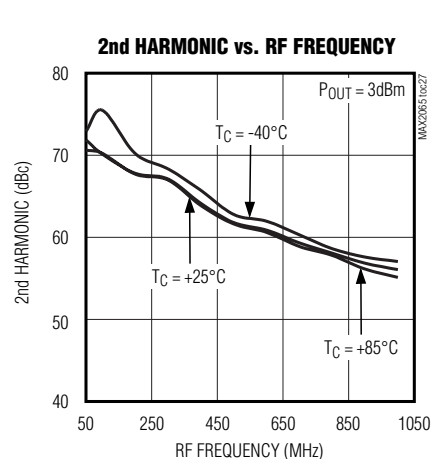
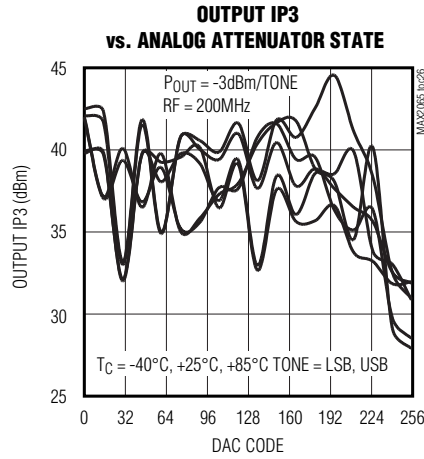
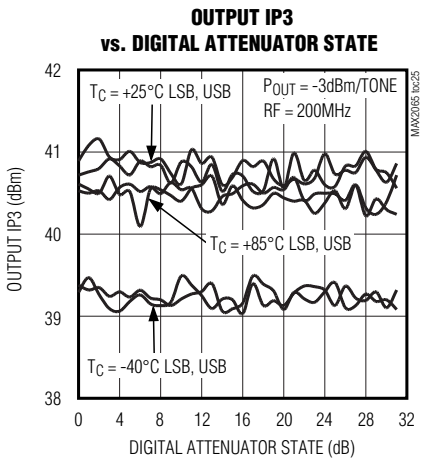
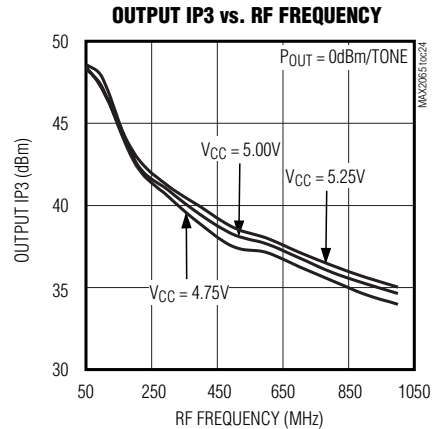
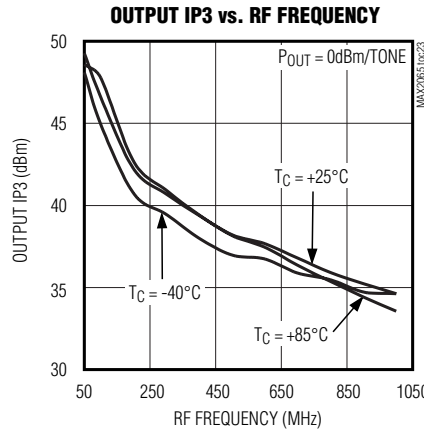
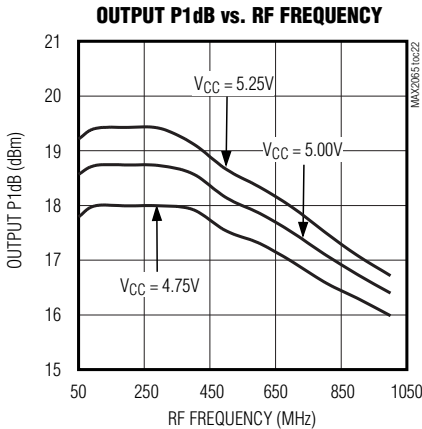
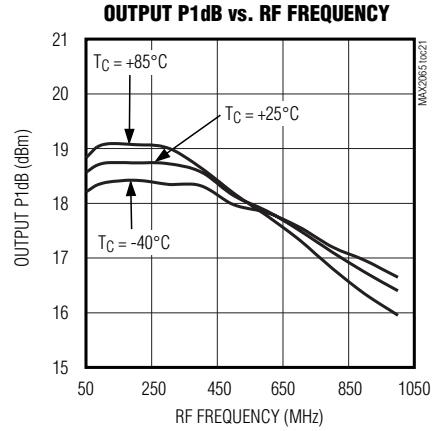
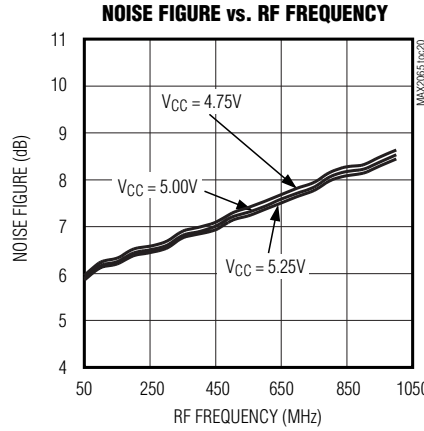
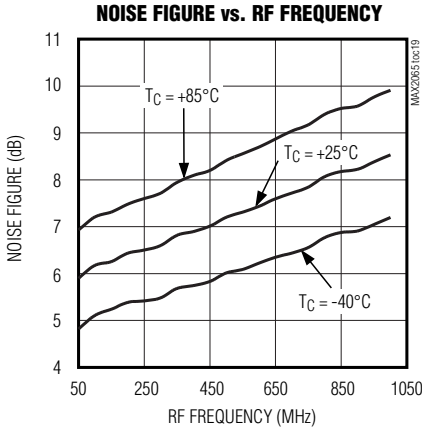
S21 PHASE CHANGE vs. ANALOG ATTENUATOR SETTING



50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

Typical Operating Characteristics (continued)

($V_{CC} = +5.0V$, HC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal DAC reference used, unless otherwise noted.)

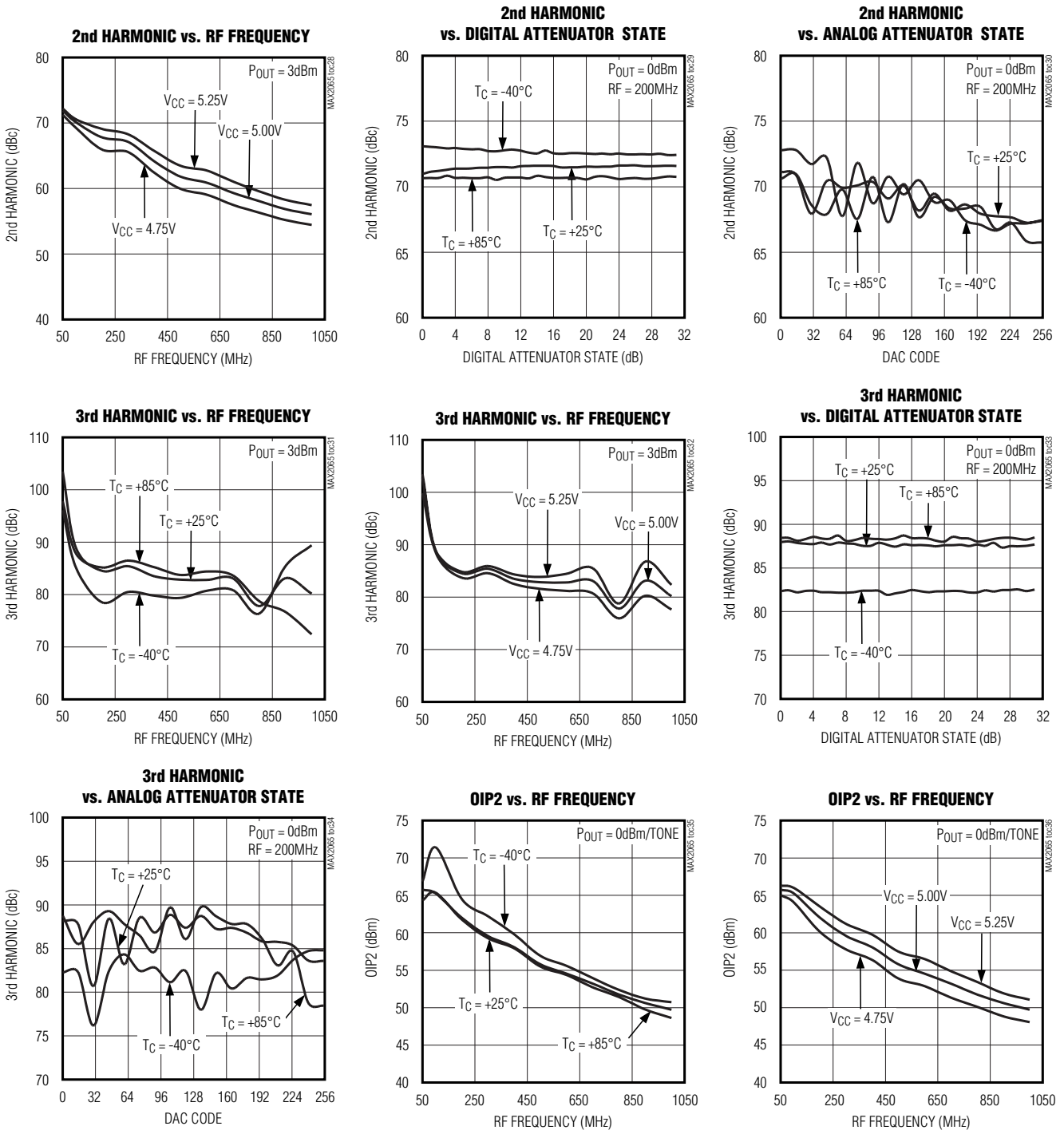


50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

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Typical Operating Characteristics (continued)

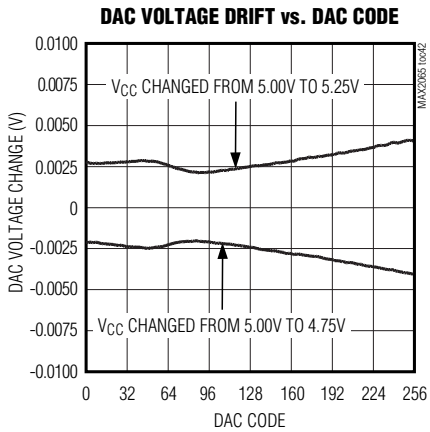
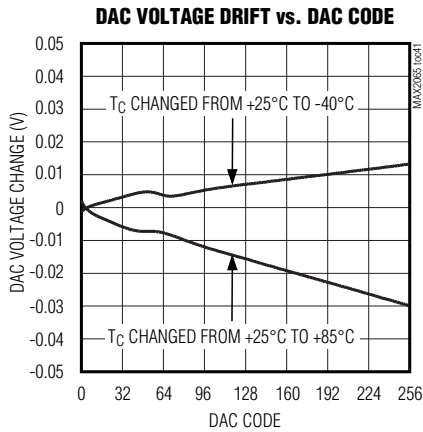
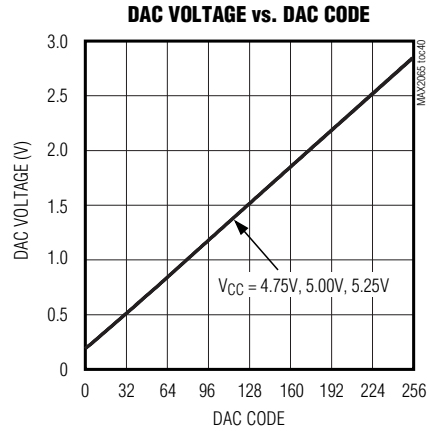
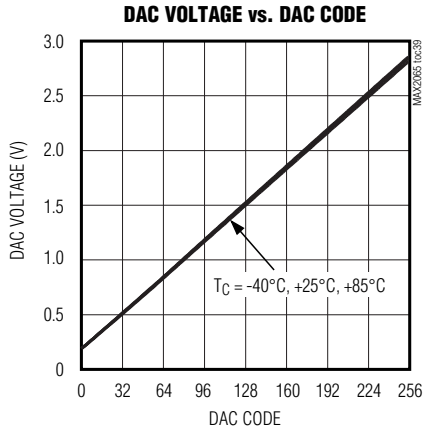
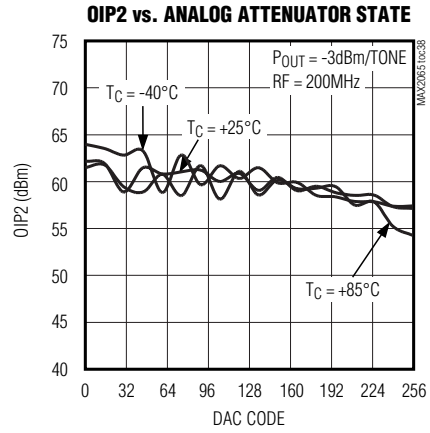
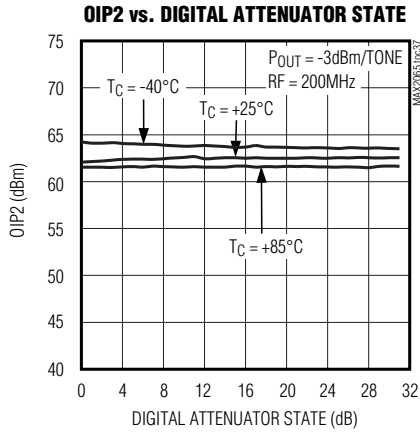
($V_{CC} = +5.0V$, HC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal DAC reference used, unless otherwise noted.)



50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

Typical Operating Characteristics (continued)

($V_{CC} = +5.0V$, HC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal DAC reference used, unless otherwise noted.)

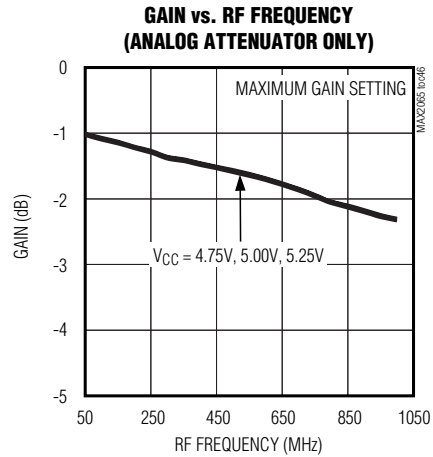
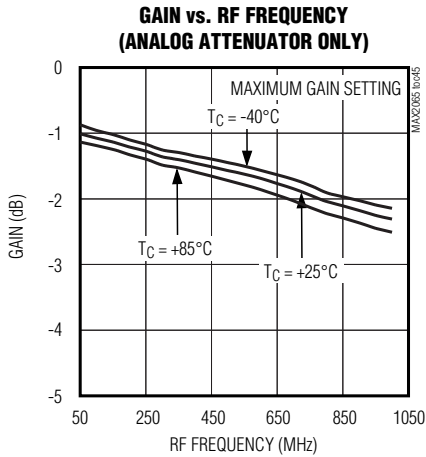
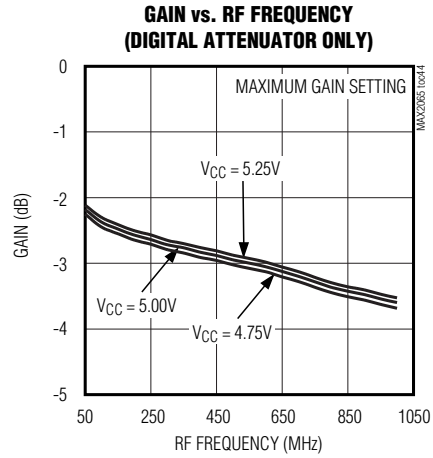
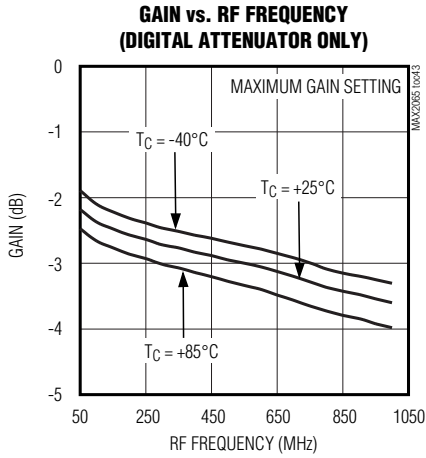


50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

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Typical Operating Characteristics (continued)

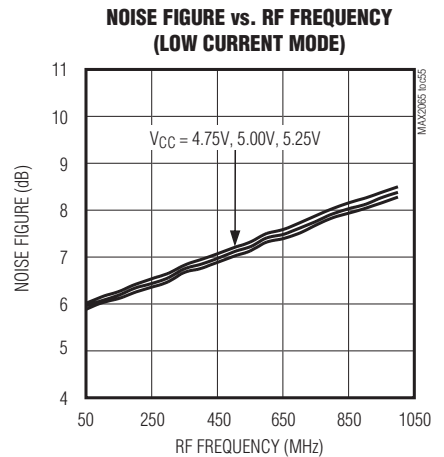
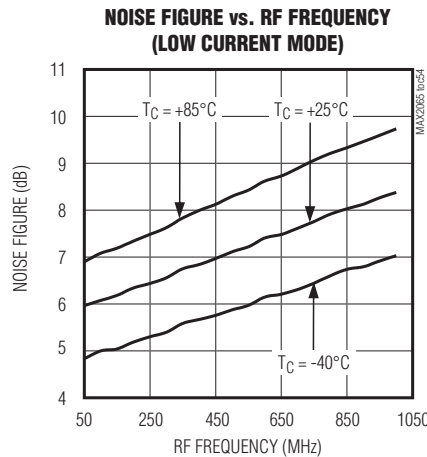
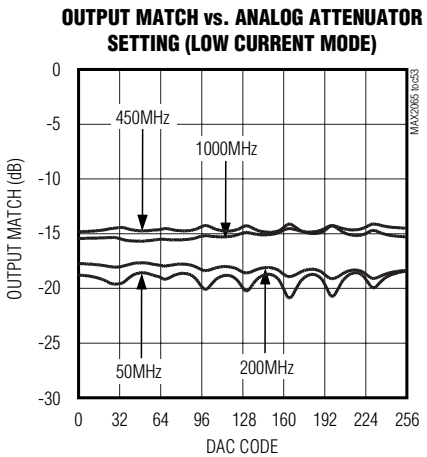
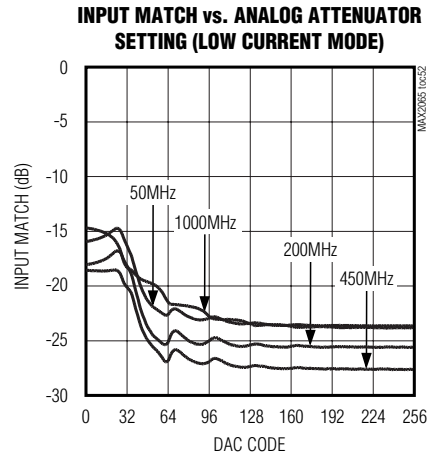
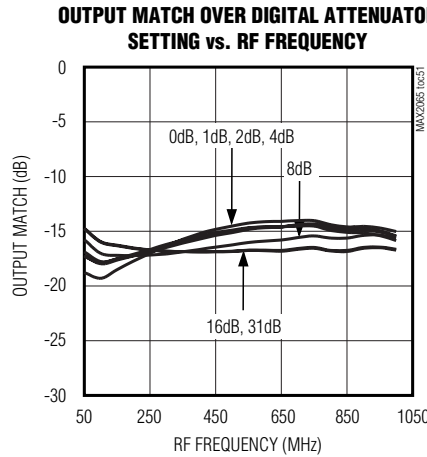
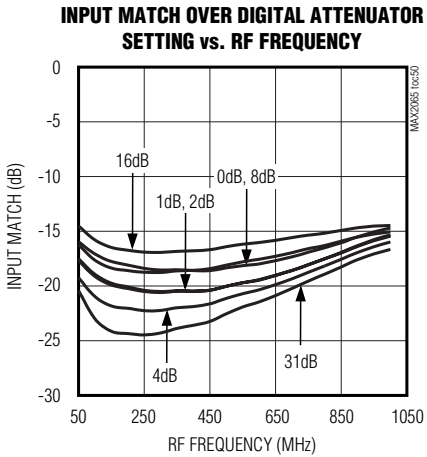
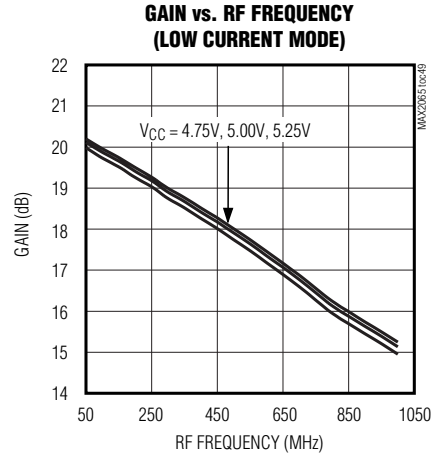
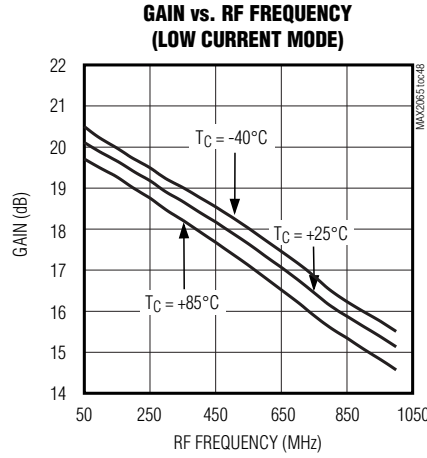
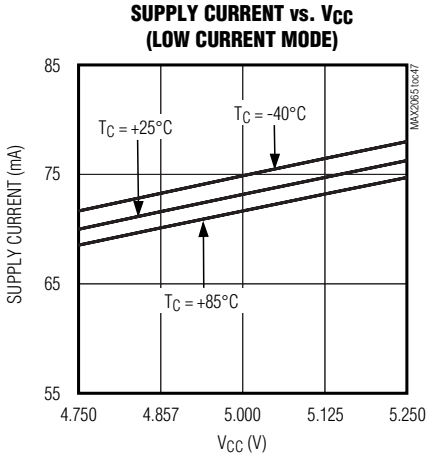
($V_{CC} = +5.0V$, attenuator only, maximum gain, $P_{IN} = -20dBm$ and $T_C = +25^\circ C$, unless otherwise noted.)



50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

Typical Operating Characteristics (continued)

($V_{CC} = +5.0V$, LC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal reference used, unless otherwise noted.)

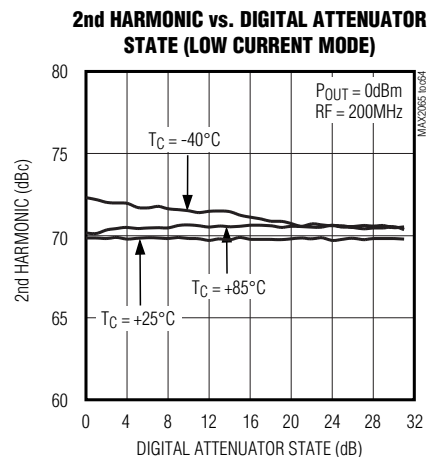
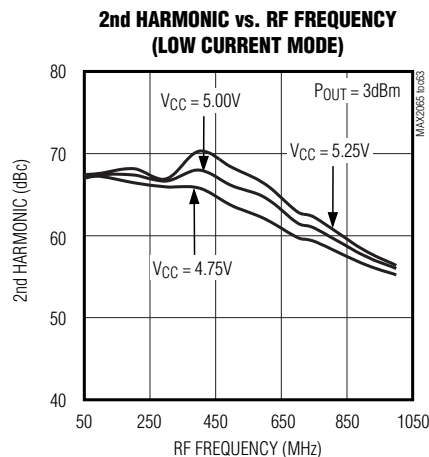
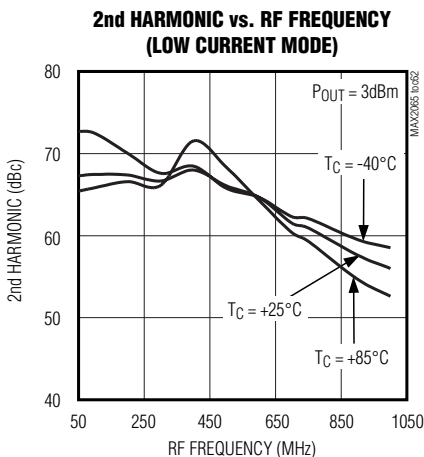
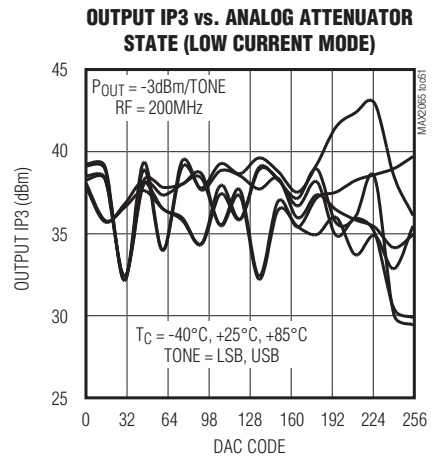
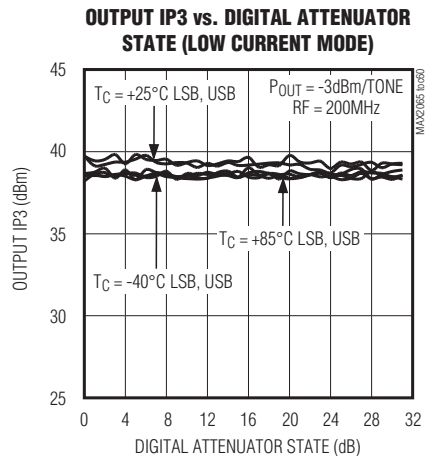
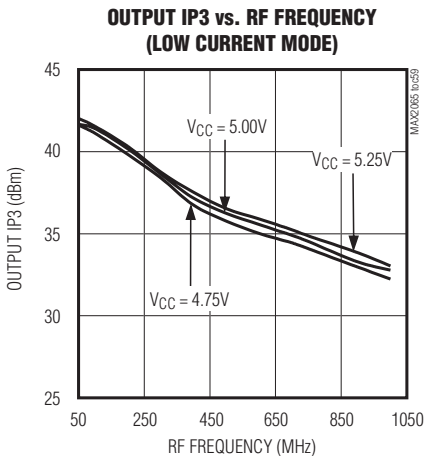
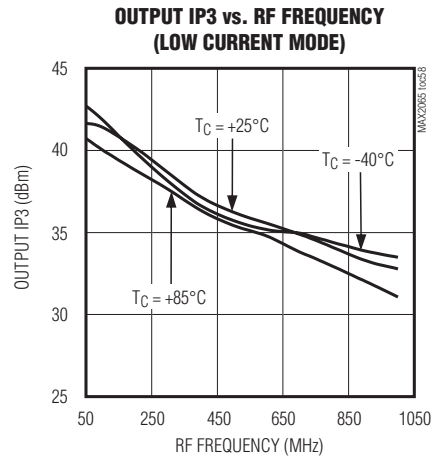
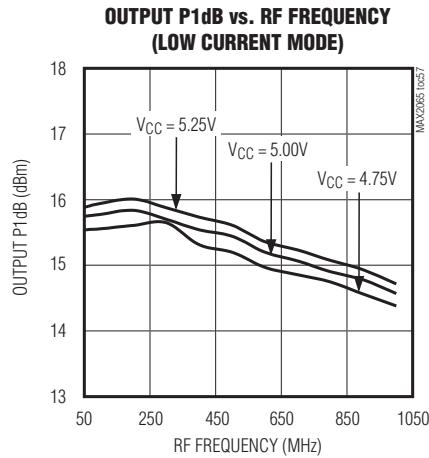
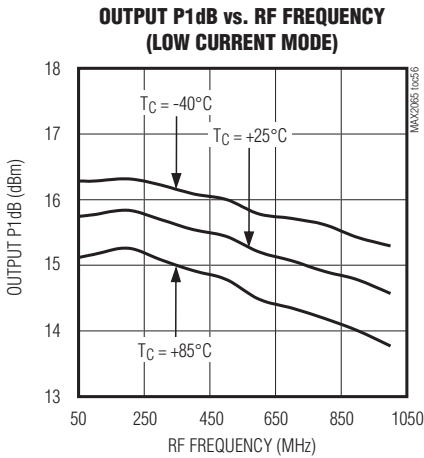


50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

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Typical Operating Characteristics (continued)

($V_{CC} = +5.0V$, LC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal reference used, unless otherwise noted.)

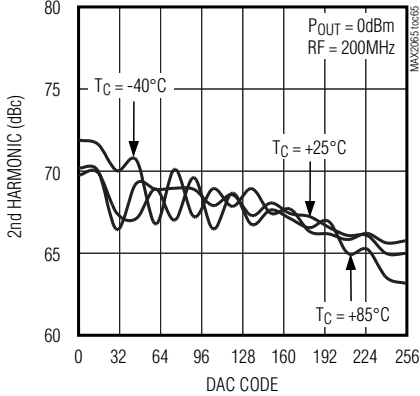


50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

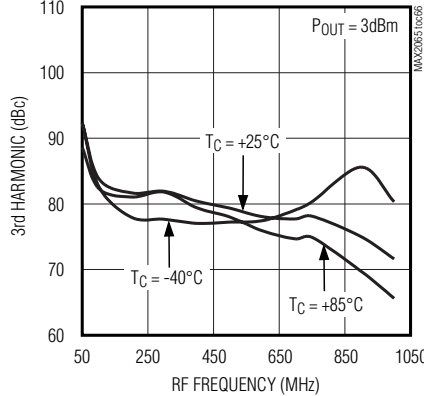
Typical Operating Characteristics (continued)

($V_{CC} = +5.0V$, LC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal reference used, unless otherwise noted.)

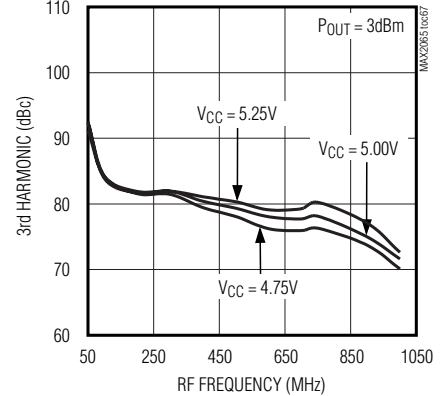
2nd HARMONIC vs. ANALOG ATTENUATOR STATE (LOW CURRENT MODE)



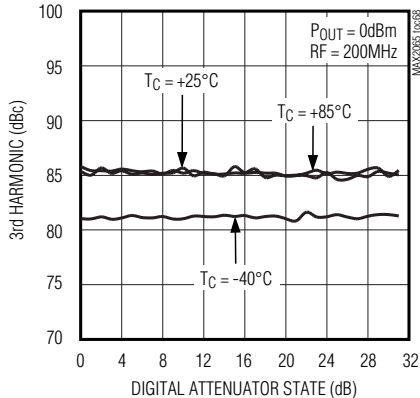
3rd HARMONIC vs. RF FREQUENCY (LOW CURRENT MODE)



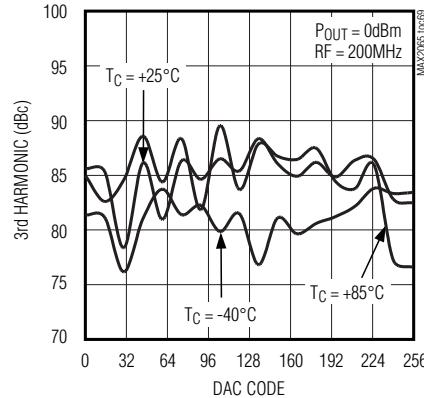
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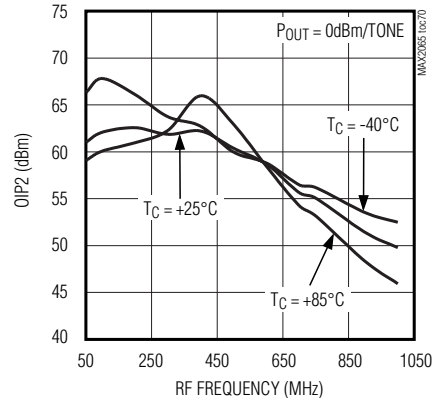
3rd HARMONIC vs. DIGITAL ATTENUATOR STATE (LOW CURRENT MODE)



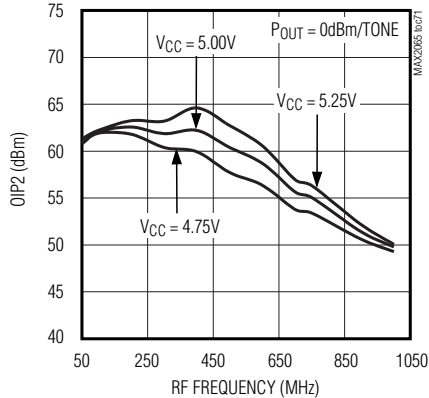
3rd HARMONIC vs. ANALOG ATTENUATOR STATE (LOW CURRENT MODE)



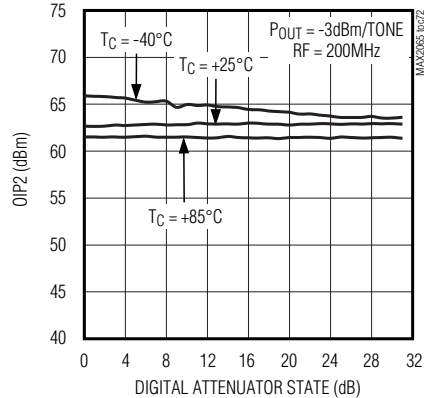
OIP2 vs. RF FREQUENCY (LOW CURRENT MODE)



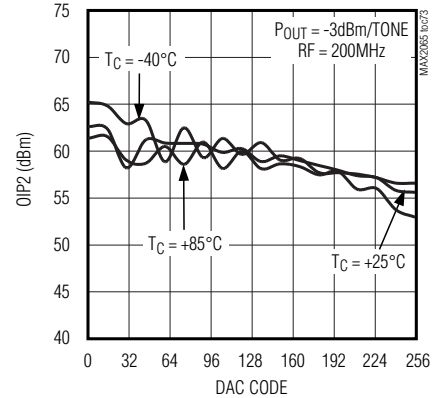
OIP2 vs. RF FREQUENCY (LOW CURRENT MODE)



OIP2 vs. DIGITAL ATTENUATOR STATE (LOW CURRENT MODE)



OIP2 vs. ANALOG ATTENUATOR STATE (LOW CURRENT MODE)

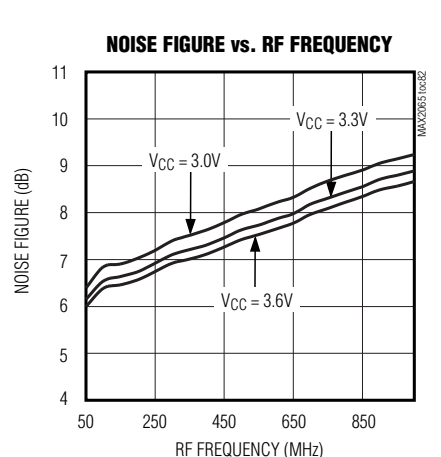
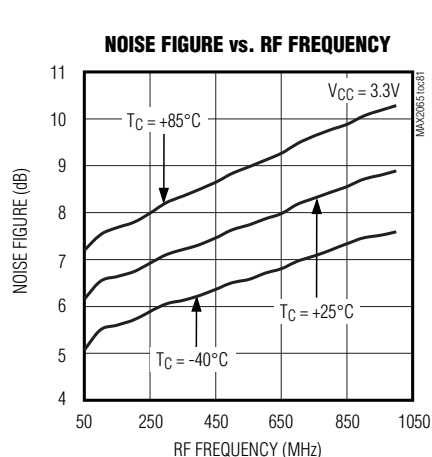
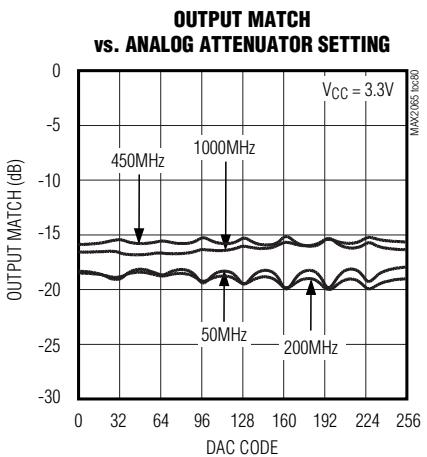
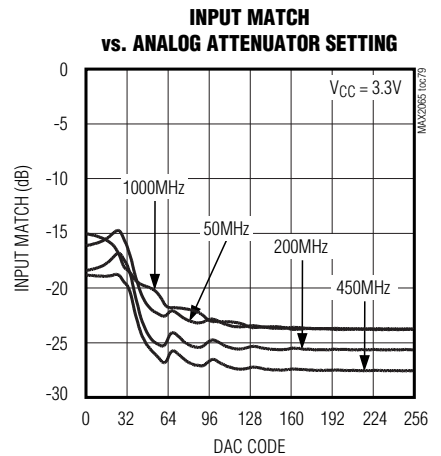
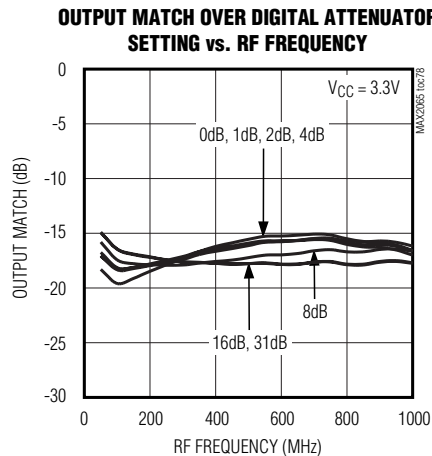
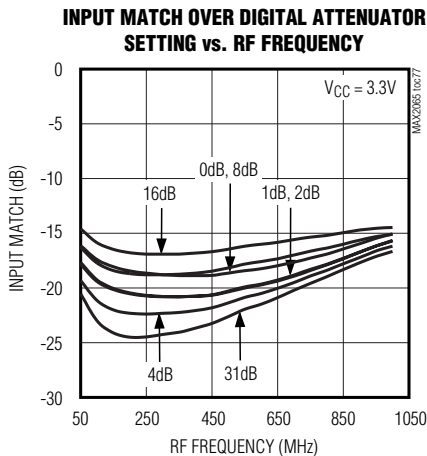
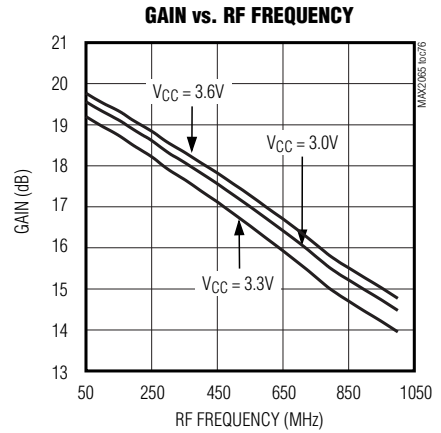
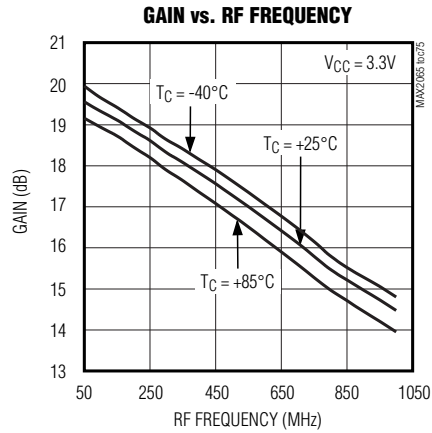
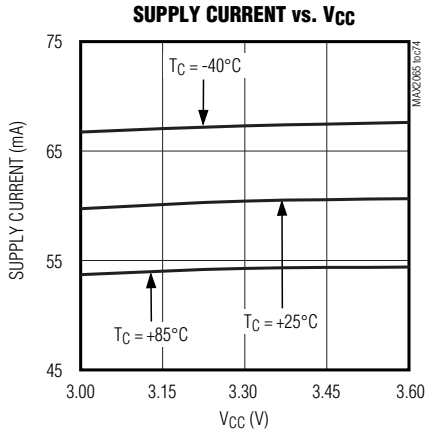


50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

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Typical Operating Characteristics (continued)

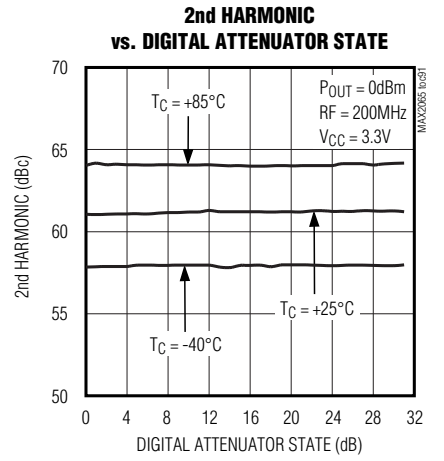
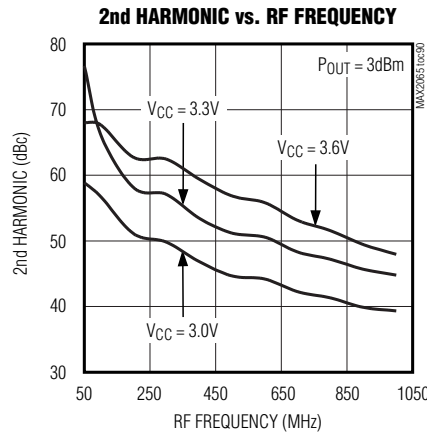
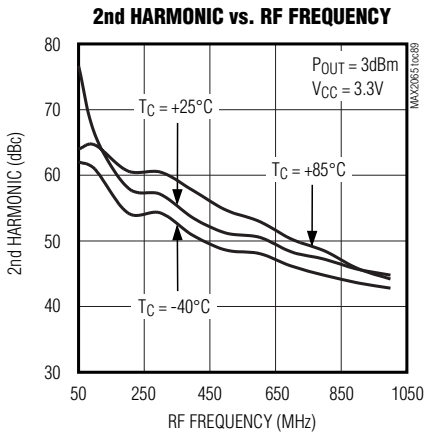
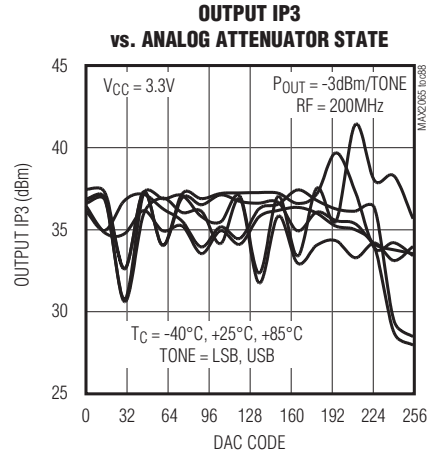
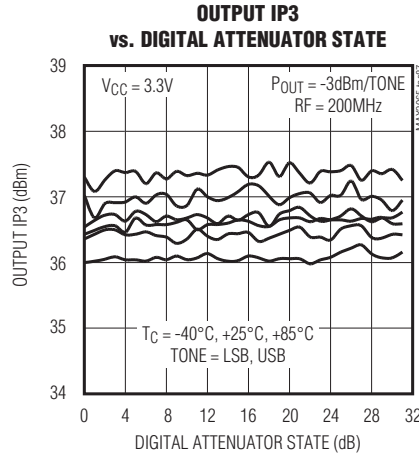
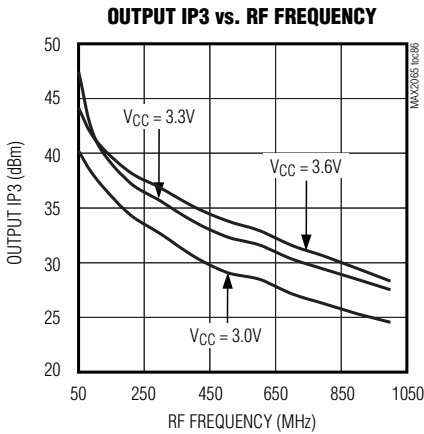
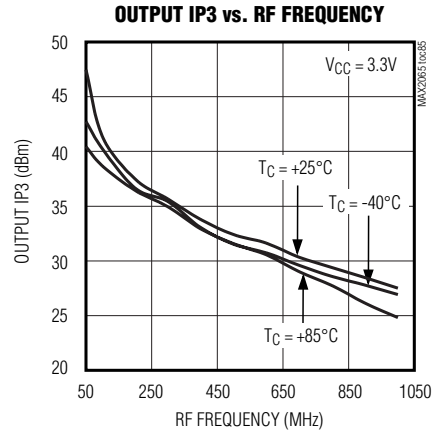
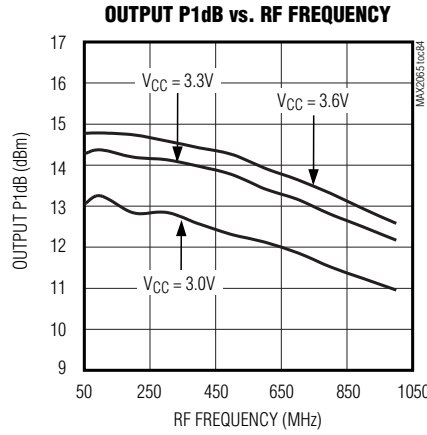
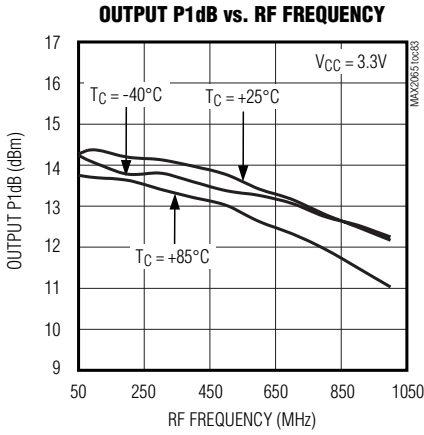
($V_{CC} = +3.3V$, HC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal DAC reference used, unless otherwise noted.)



50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

Typical Operating Characteristics (continued)

($V_{CC} = +3.3V$, HC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal DAC reference used, unless otherwise noted.)

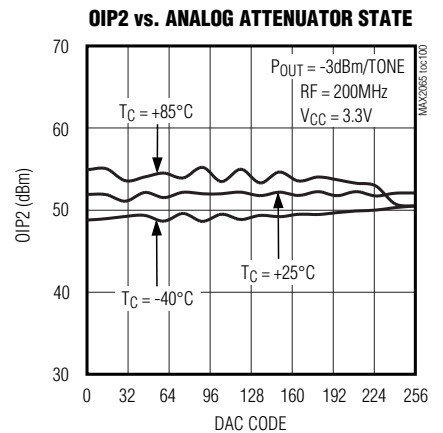
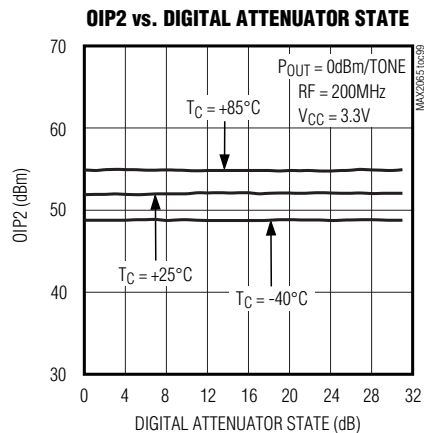
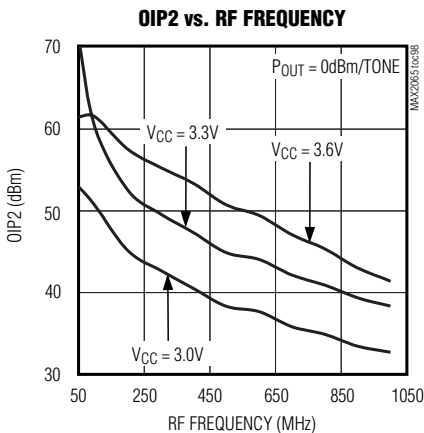
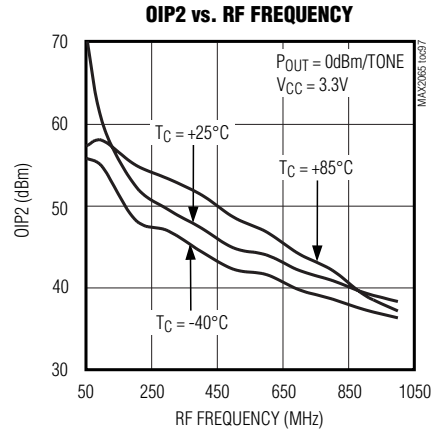
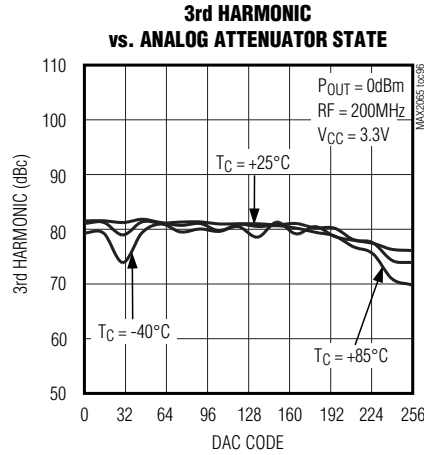
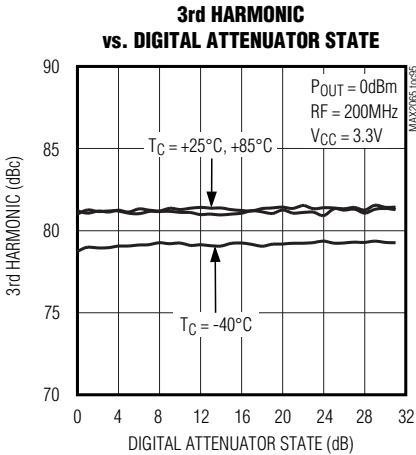
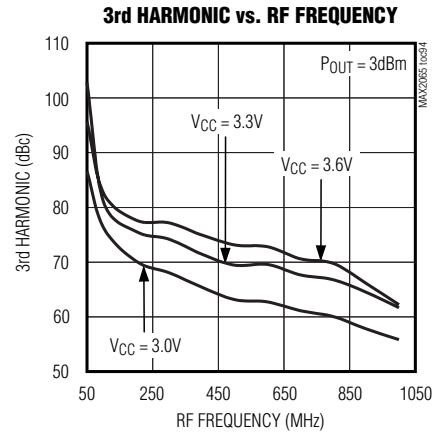
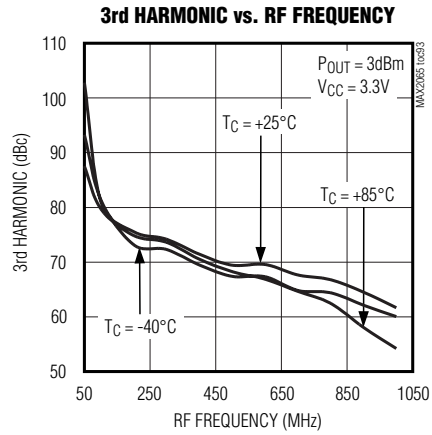
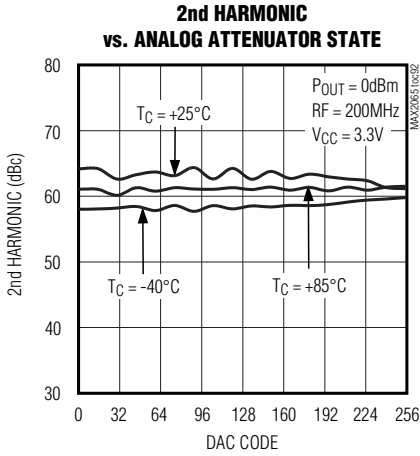


50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

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Typical Operating Characteristics (continued)

($V_{CC} = +3.3V$, HC mode, both attenuators set for maximum gain, $P_{IN} = -20dBm$, $f_{RF} = 200MHz$, and $T_C = +25^\circ C$, internal DAC reference used, unless otherwise noted.)



50MHz to 1000MHz High-Linearity, Serial/ Parallel-Controlled Analog/Digital VGA

Pin Description

| PIN | NAME | DESCRIPTION | | | | | | | | | | | | | | | |
|-------------------------------------------|-----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------|---------|--------------------|-----------|-----------|-----------------------|-----------|-----------|-----------------------|-----------|-----------|-----------------------|-----------|-----------|-----------------------|
| 1, 16, 19, 22, 24–28, 30, 31, 33–36 | GND | Ground | | | | | | | | | | | | | | | |
| 2 | VREF_SELECT | DAC Reference Voltage Selection Logic Input. Logic 1 = internal DAC reference voltage, Logic 0 = external DAC reference voltage. Logic input disabled (don't care) when VDAC_EN = Logic 0. | | | | | | | | | | | | | | | |
| 3 | VDAC_EN | DAC Enable/Disable Logic Input. Logic 0 = disable DAC circuit, Logic 1 = enable DAC circuit. | | | | | | | | | | | | | | | |
| 4 | DATA | SPI Data Digital Input | | | | | | | | | | | | | | | |
| 5 | CLK | SPI Clock Digital Input | | | | | | | | | | | | | | | |
| 6 | \overline{CS} | SPI Chip-Select Digital Input | | | | | | | | | | | | | | | |
| 7 | VDD_LOGIC | Digital Logic Supply Input | | | | | | | | | | | | | | | |
| 8 | SER/PAR | Digital Attenuator SPI or Parallel Control Selection Logic Input. Logic 0 = parallel control, Logic 1 = serial control. | | | | | | | | | | | | | | | |
| 9 | STATE_A | Digital Attenuator Preprogrammed Attenuation State Logic Input | | | | | | | | | | | | | | | |
| 10 | STATE_B | <table border="1"> <thead> <tr> <th>State A</th> <th>State B</th> <th>Digital Attenuator</th> </tr> </thead> <tbody> <tr> <td>Logic = 0</td> <td>Logic = 0</td> <td>Preprogrammed State 1</td> </tr> <tr> <td>Logic = 1</td> <td>Logic = 0</td> <td>Preprogrammed State 2</td> </tr> <tr> <td>Logic = 0</td> <td>Logic = 1</td> <td>Preprogrammed State 3</td> </tr> <tr> <td>Logic = 1</td> <td>Logic = 1</td> <td>Preprogrammed State 4</td> </tr> </tbody> </table> | State A | State B | Digital Attenuator | Logic = 0 | Logic = 0 | Preprogrammed State 1 | Logic = 1 | Logic = 0 | Preprogrammed State 2 | Logic = 0 | Logic = 1 | Preprogrammed State 3 | Logic = 1 | Logic = 1 | Preprogrammed State 4 |
| State A | State B | Digital Attenuator | | | | | | | | | | | | | | | |
| Logic = 0 | Logic = 0 | Preprogrammed State 1 | | | | | | | | | | | | | | | |
| Logic = 1 | Logic = 0 | Preprogrammed State 2 | | | | | | | | | | | | | | | |
| Logic = 0 | Logic = 1 | Preprogrammed State 3 | | | | | | | | | | | | | | | |
| Logic = 1 | Logic = 1 | Preprogrammed State 4 | | | | | | | | | | | | | | | |
| 11 | D4 | 16dB Attenuator Logic Input. Logic 0 = disable, Logic 1 = enable. | | | | | | | | | | | | | | | |
| 12 | D3 | 8dB Attenuator Logic Input. Logic 0 = disable, Logic 1 = enable. | | | | | | | | | | | | | | | |
| 13 | D2 | 4dB Attenuator Logic Input. Logic 0 = disable, Logic 1 = enable. | | | | | | | | | | | | | | | |
| 14 | D1 | 2dB Attenuator Logic Input. Logic 0 = disable, Logic 1 = enable. | | | | | | | | | | | | | | | |
| 15 | D0 | 1dB Attenuator Logic Input. Logic 0 = disable, Logic 1 = enable. | | | | | | | | | | | | | | | |
| 17 | AMP_OUT | Driver Amplifier Output (50 Ω) | | | | | | | | | | | | | | | |
| 18 | RSET | Driver Amplifier Bias-Setting. See the <i>External Bias</i> section. | | | | | | | | | | | | | | | |
| 20 | AMP_IN | Driver Amplifier Input (50 Ω) | | | | | | | | | | | | | | | |
| 21 | VCC_AMP | Driver Amplifier Supply Voltage Input | | | | | | | | | | | | | | | |
| 23 | ATTEN2_OUT | 5-Bit Digital Attenuator Output (50 Ω) | | | | | | | | | | | | | | | |
| 29 | ATTEN2_IN | 5-Bit Digital Attenuator Input (50 Ω) | | | | | | | | | | | | | | | |
| 32 | ATTEN1_OUT | Analog Attenuator Output (50 Ω) | | | | | | | | | | | | | | | |
| 37 | ATTEN1_IN | Analog Attenuator Input (50 Ω) | | | | | | | | | | | | | | | |
| 38 | VCC_ANALOG | Analog Bias and Control Supply Voltage Input | | | | | | | | | | | | | | | |
| 39 | ANALOG_VCTRL | Analog Attenuator Voltage Control Input | | | | | | | | | | | | | | | |
| 40 | VREF_IN | External DAC Voltage Reference Input | | | | | | | | | | | | | | | |
| — | EP | Exposed Pad. Internally connected to GND. Connect EP to GND for proper RF performance and enhanced thermal dissipation. | | | | | | | | | | | | | | | |

50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

Detailed Description

The MAX2065 high-linearity analog/digital variable-gain amplifier is a general-purpose, high-performance amplifier designed to interface with 50Ω systems operating in the 50MHz to 1000MHz frequency range.

The MAX2065 integrates one digital attenuator and one analog attenuator to provide 62dB of total gain control, as well as a driver amplifier optimized to provide high gain, high IP3, low noise figure, and low power consumption. For applications that do not require high linearity, the bias current of the amplifier can be adjusted by an external resistor to further reduce power consumption.

The digital attenuator is controlled as a slave peripheral using either the SPI-compatible interface or a parallel bus with 31dB total adjustment range in 1dB steps. An added feature allows “rapid-fire” gain selection between each of the four unique steps (preprogrammed by the user through the SPI-compatible interface). The 2-pin control allows the user to quickly access any one of four customized attenuation states without reprogramming the SPI bus. The analog attenuator is controlled using an external voltage or through the SPI-compatible interface using an on-chip DAC. Because each of the three stages has its own external RF input and RF output, this component can be configured to either optimize NF (amplifier configured first), OIP3 (amplifier last), or a compromise of NF and OIP3. The device’s performance features include 22dB stand-alone amplifier gain (amplifier only), 6.5dB NF at maximum gain (includes attenuator insertion loss for both attenuators), and a high OIP3 level of +42dBm. Each of these features makes the MAX2065 an ideal VGA for numerous receiver and transmitter applications.

In addition, the MAX2065 operates from a single +5V supply, or a single +3.3V supply with slightly reduced performance, and has adjustable bias to trade current consumption for linearity performance.

Analog and 5-Bit Digital Attenuator Control

The MAX2065 integrates one analog attenuator and one 5-bit digital attenuator to achieve a high level of dynamic range. The analog attenuator has a 31dB range and is controlled using an external voltage or through the 3-wire serial peripheral interface (SPI) using an on-chip 8-bit DAC. The digital attenuator has a 31dB control range, a 1dB step size, and is programmed through the 3-wire SPI. See the *Applications Information* section and Table 1 for attenuator programming details. The attenuators can be used for both static and dynamic power control.

Driver Amplifier

The MAX2065 includes a high-performance driver with a fixed gain of 22dB. The driver amplifier circuit is optimized for high linearity for the 50MHz to 1000MHz frequency range.

Applications Information

SPI Interface and Attenuator Settings

The digital attenuator is programmed through the 3-wire SPI/MICROWIRE™-compatible serial interface using 5-bit words. Twenty-eight bits of data are shifted in MSB first and is framed by \overline{CS} . When \overline{CS} is low, the clock is active and data is shifted on the rising edge of the clock. When \overline{CS} transitions high, the data is latched and the attenuator setting changes (Figure 1). See Table 2 for details on the SPI data format.

Table 1. Control Logic

| VDAC_EN | SER/PAR | VREF_SELECT | ANALOG ATTENUATOR | DIGITAL ATTENUATOR | D/A CONVERTER |
|---------|---------|-------------|----------------------------------------|---------------------|-----------------------------------------------|
| 0 | 0 | X | Controlled by external control voltage | Parallel controlled | Disabled |
| 1 | 0 | 1 | Controlled by on-chip DAC | Parallel controlled | Enabled (DAC uses on-chip voltage reference) |
| 0 | 1 | X | Controlled by external control voltage | SPI controlled | Disabled |
| 1 | 1 | 0 | Controlled by on-chip DAC | SPI controlled | Enabled (DAC uses external voltage reference) |

X = Don't care.

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50MHz to 1000MHz High-Linearity, Serial/Parallel-Controlled Analog/Digital VGA

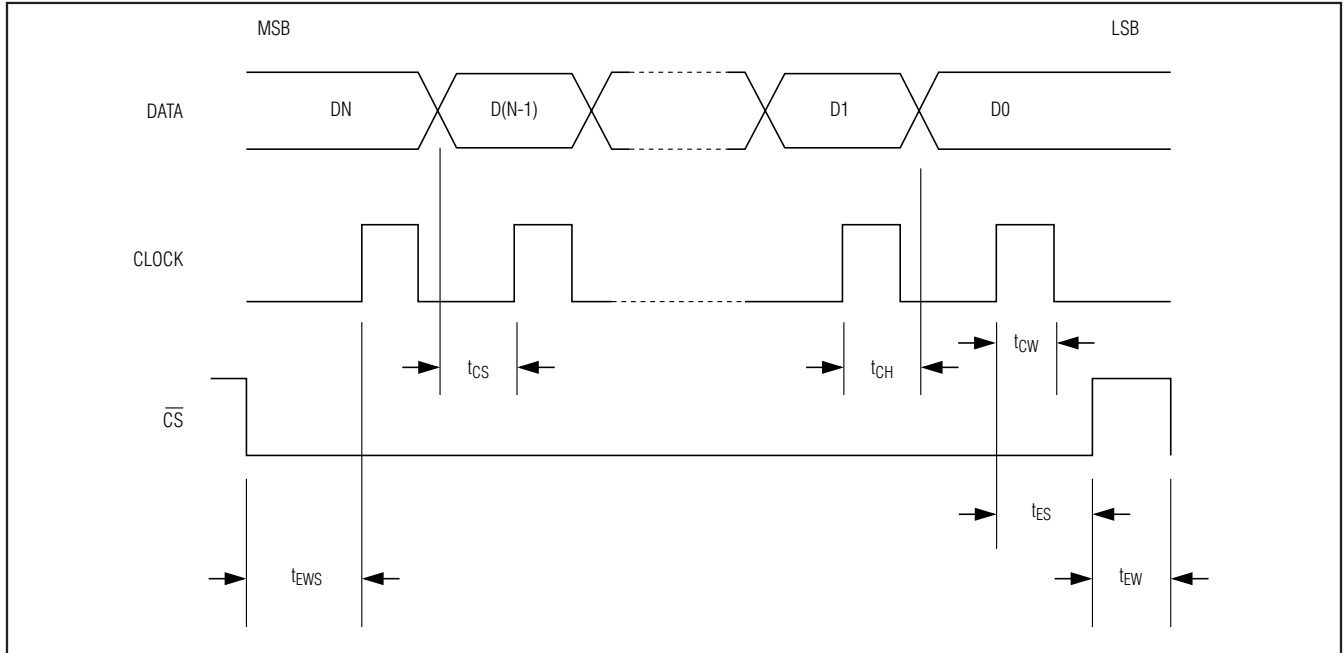


Figure 1. MAX2065 SPI Timing Diagram

Table 2. SPI Data Format

| FUNCTION | BIT | DESCRIPTION |
|----------------------------|-----------|----------------------------------------------------------------------------------------------------------------|
| Digital Attenuator State 4 | D27 (MSB) | 16dB step (MSB of the 5-bit word used to program the digital attenuator state 4) |
| | D26 | 8dB step |
| | D25 | 4dB step |
| | D24 | 2dB step |
| | D23 | 1dB step (LSB) |
| Digital Attenuator State 3 | D22 | 5-bit word used to program the digital attenuator state 3 (see the description for digital attenuator state 4) |
| | D21 | |
| | D20 | |
| | D19 | |
| | D18 | |
| Digital Attenuator State 2 | D17 | 5-bit word used to program the digital attenuator state 2 (see the description for digital attenuator state 4) |
| | D16 | |
| | D15 | |
| | D14 | |
| | D13 | |
| Digital Attenuator State 1 | D12 | 5-bit word used to program the digital attenuator state 1 (see the description for digital attenuator state 4) |
| | D11 | |
| | D10 | |
| | D9 | |
| | D8 | |

50MHz to 1000MHz High-Linearity, Serial/ Parallel-Controlled Analog/Digital VGA

Table 2. SPI Data Format (continued)

| FUNCTION | BIT | DESCRIPTION |
|-------------|----------|------------------------------------------------------------------|
| On-Chip DAC | D7 | Bit 7 (MSB) of on-chip DAC used to program the analog attenuator |
| | D6 | Bit 6 of DAC |
| | D5 | Bit 5 of DAC |
| | D4 | Bit 4 of DAC |
| | D3 | Bit 3 of DAC |
| | D2 | Bit 2 of DAC |
| | D1 | Bit 1 of DAC |
| | D0 (LSB) | Bit 0 (LSB) of the on-chip DAC |

Attenuator and DAC Operation

The analog attenuator is controlled by an external control voltage applied at ANALOG_VCTRL (pin 39) or by the on-chip 8-bit DAC, while the digital attenuator is controlled through the SPI-compatible interface or parallel bus. The DAC enable/disable logic-input pin (VDAC_EN), digital attenuator SPI or parallel control selection logic-input pin (SER/PAR), and the DAC reference voltage selection logic-input pin (VREF_SELECT) determine how the attenuators are controlled. The on-chip DAC can also be enabled or disabled. When the DAC is enabled, either the on-chip voltage reference or the external voltage reference can be selected. See Table 1 for the attenuator and DAC operation truth table.

Digital Attenuator Settings Using the Parallel Control Bus

To capitalize on its fast 25ns switching capability, the MAX2065 offers a supplemental 5-bit parallel control interface. The digital logic attenuator-control pins (D0–D4) enable the attenuator stages (Table 3).

Direct access to this 5-bit bus enables the user to avoid any programming delays associated with the SPI

interface. One of the limitations of any SPI bus is the speed at which commands can be clocked into each peripheral device. By offering direct access to the 5-bit parallel interface, the user can quickly shift between digital attenuator states needed for critical “fast-attack” automatic gain control (AGC) applications.

“Rapid-Fire” Preprogrammed Attenuation States

The MAX2065 has an added feature that provides “rapid fire” gain selection between four preprogrammed attenuation steps. As with the supplemental 5-bit bus mentioned above, this “rapid fire” gain selection allows the user to quickly access any one of four customized digital attenuation states without incurring the delays associated with reprogramming the device through the SPI bus.

The switching speed is comparable to that achieved using the supplemental 5-bit parallel bus. However, by employing this specific feature, the digital attenuator I/O is further reduced by a factor of either 5 or 2.5 (5 control bits vs. 1 or 2, respectively) depending on the number of states desired.

Table 3. Digital Attenuator Settings (Parallel Control)

| INPUT | LOGIC = 0 (OR GROUND) | LOGIC = 1 |
|-------|------------------------------------------------------------|------------------------|
| D0 | Disable 1dB attenuator, or when SPI is default programmer | Enable 1dB attenuator |
| D1 | Disable 2dB attenuator, or when SPI is default programmer | Enable 2dB attenuator |
| D2 | Disable 4dB attenuator, or when SPI is default programmer | Enable 4dB attenuator |
| D3 | Disable 8dB attenuator, or when SPI is default programmer | Enable 8dB attenuator |
| D4 | Disable 16dB attenuator, or when SPI is default programmer | Enable 16dB attenuator |

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The user can employ the STATE_A and STATE_B logic-input pins to apply each step as required (Table 4). Toggling just the STATE_A pin (one control bit) yields two preprogrammed attenuation states; toggling both the STATE_A and STATE_B pins together (two control bits) yield four preprogrammed attenuation states.

As an example, assume that the AGC application requires a static attenuation adjustment to trim out gain inconsistencies within a receiver lineup. The same AGC circuit can also be called upon to dynamically attenuate an unwanted blocker signal that could de-sense the receiver and lead to an ADC overdrive condition. In this example, the MAX2065 would be preprogrammed (through the SPI bus) with two customized attenuation states—one to address the static gain trim adjustment, the second to counter the unwanted blocker condition.

Table 4. Preprogrammed Attenuation State Settings

| STATE_A | STATE_B | DIGITAL ATTENUATOR |
|---------|---------|-----------------------------------|
| 0 | 0 | Preprogrammed attenuation state 1 |
| 1 | 0 | Preprogrammed attenuation state 2 |
| 0 | 1 | Preprogrammed attenuation state 3 |
| 1 | 1 | Preprogrammed attenuation state 4 |

Toggling just the STATE_A control bit enables the user to switch quickly between the static and dynamic attenuation settings with only one I/O pin.

If desired, the user can also program two additional attenuation states by using the STATE_B control bit as a second I/O pin. These two additional attenuation settings are useful for software-defined radio applications where multiple static gain settings may be needed to account for different frequencies of operation, or where multiple dynamic attenuation settings are needed to account for different blocker levels (as defined by multiple wireless standards).

Cascaded OIP3 Considerations

Due to both attenuator's finite IP3 performance, the cascaded OIP3 degrades when both attenuators are set at higher attenuation states.

External Bias

Bias currents for the driver amplifier are set and optimized through external resistors. Resistors R1 and R1A connected to RSET (pin 18) set the bias current for the amplifier. The external biasing resistor values can be increased for reduced current operation at the expense of performance.

Table 5. Typical Application Circuit Component Values (HC Mode)

| DESIGNATION | VALUE | SIZE | VENDOR | DESCRIPTION |
|---------------------------------------------------|--------------|--------------------------------|---------------------------------|-----------------------|
| C1, C2, C7, C11 | 10nF | 0402 | Murata Mfg. Co., Ltd. | X7R |
| C3, C4, C6, C8, C9, C10 | 1000pF | 0402 | Murata Mfg. Co., Ltd. | C0G ceramic capacitor |
| C12, C13 | 150pF | 0402 | Murata Mfg. Co., Ltd. | C0G ceramic capacitor |
| L1 | 470nH | 1008 | Coilcraft, Inc. | 1008CS-471XJLC |
| R1, R1A | 10 Ω | 0402 | Panasonic Corp. | 1% |
| R2 (+3.3V applications only) | 1k Ω | 0402 | Panasonic Corp. | 1% |
| R3 (+3.3V applications only) | 2k Ω | 0402 | Panasonic Corp. | 1% |
| R4 (+5V applications and using internal DAC only) | 47k Ω | 0402 | Panasonic Corp. | 1% |
| U1 | — | 40-pin thin QFN-EP (6mm x 6mm) | Maxim Integrated Products, Inc. | MAX2065ETL+ |

50MHz to 1000MHz High-Linearity, Serial/ Parallel-Controlled Analog/Digital VGA

Table 6. Typical Application Circuit Component Values (LC Mode)

| DESIGNATION | VALUE | SIZE | VENDOR | DESCRIPTION |
|---------------------------------------------------|--------|--------------------------------|---------------------------------|-----------------------|
| C1, C2, C7, C11 | 10nF | 0402 | Murata Mfg. Co., Ltd. | X7R |
| C3, C4, C6, C8, C9, C10 | 1000pF | 0402 | Murata Mfg. Co., Ltd. | C0G ceramic capacitor |
| C12, C13 | 150pF | 0402 | Murata Mfg. Co., Ltd. | C0G ceramic capacitor |
| L1 | 470nH | 1008 | Coilcraft, Inc. | 1008CS-471XJLC |
| R1 | 24Ω | 0402 | Vishay | 1% |
| R1A | 0.01μF | 0402 | Murata Mfg. Co., Ltd. | X7R |
| R2 (+3.3V applications only) | 1kΩ | 0402 | Panasonic Corp. | 1% |
| R3 (+3.3V applications only) | 2kΩ | 0402 | Panasonic Corp. | 1% |
| R4 (+5V applications and using internal DAC only) | 47kΩ | 0402 | Panasonic Corp. | 1% |
| U1 | — | 40-pin thin QFN-EP (6mm x 6mm) | Maxim Integrated Products, Inc. | MAX2065ETL+ |

+5V and +3.3V Supply Voltage

The MAX2065 features an optional +3.3V supply voltage operation with slightly reduced linearity performance.

Layout Considerations

The pin configuration of the MAX2065 has been optimized to facilitate a very compact physical layout of the device and its associated discrete components.

The exposed paddle (EP) of the MAX2065's 40-pin thin QFN-EP package provides a low thermal-resistance path to the die. It is important that the PCB on which the MAX2065 is mounted be designed to conduct heat from the EP. In addition, provide the EP with a low-inductance path to electrical ground. The EP **must** be soldered to a ground plane on the PCB, either directly or through an array of plated via holes.

Amplitude Overshoot Reduction

To reduce amplitude overshoot during digital attenuator state change, connect a bandpass filter (parallel LC type) from ATTEN2_OUT (pin 23) to ground. L = 18nH and C = 47pF are recommended for 169MHz operation (Figure 2). Contact the factory for recommended components for other operating frequencies.

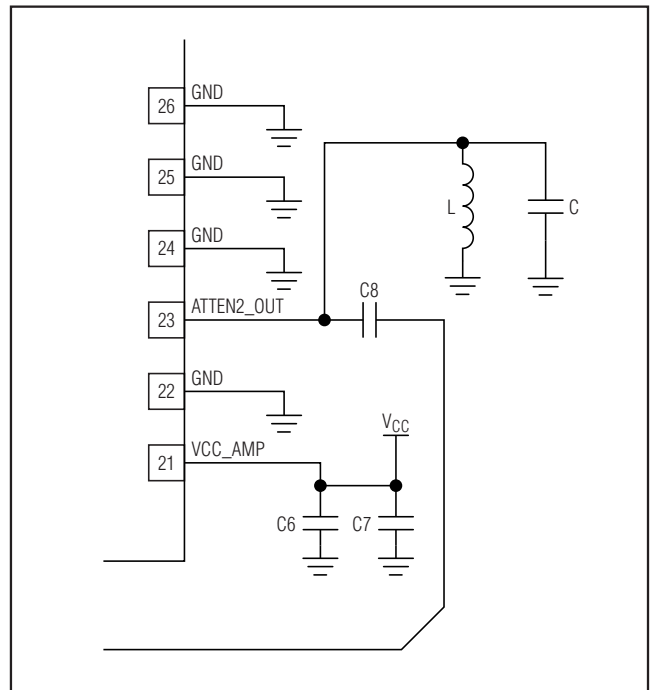
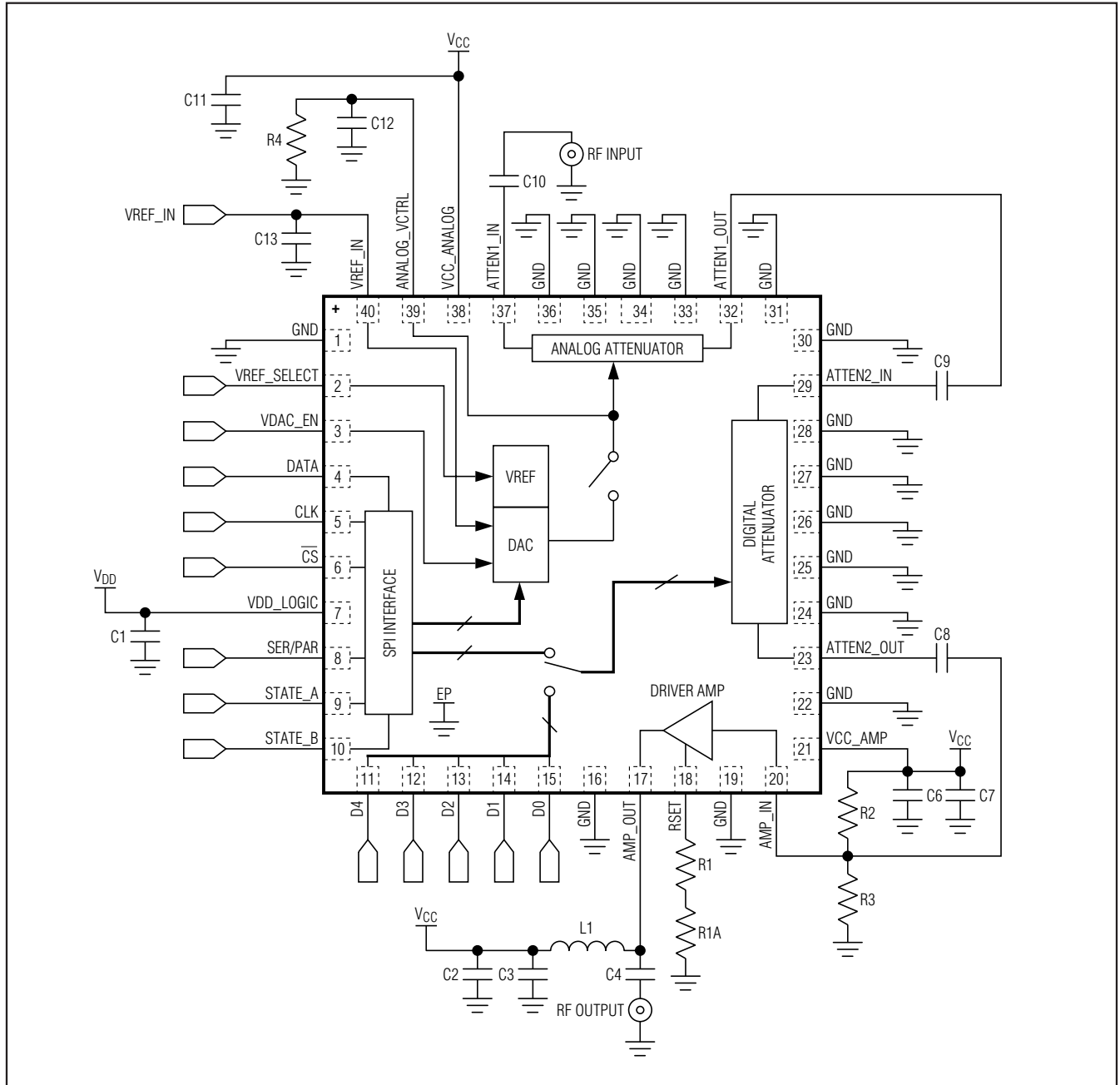


Figure 2. Bandpass Filter to Reduce Amplitude Overshoot

50MHz to 1000MHz High-Linearity, Serial/ Parallel-Controlled Analog/Digital VGA

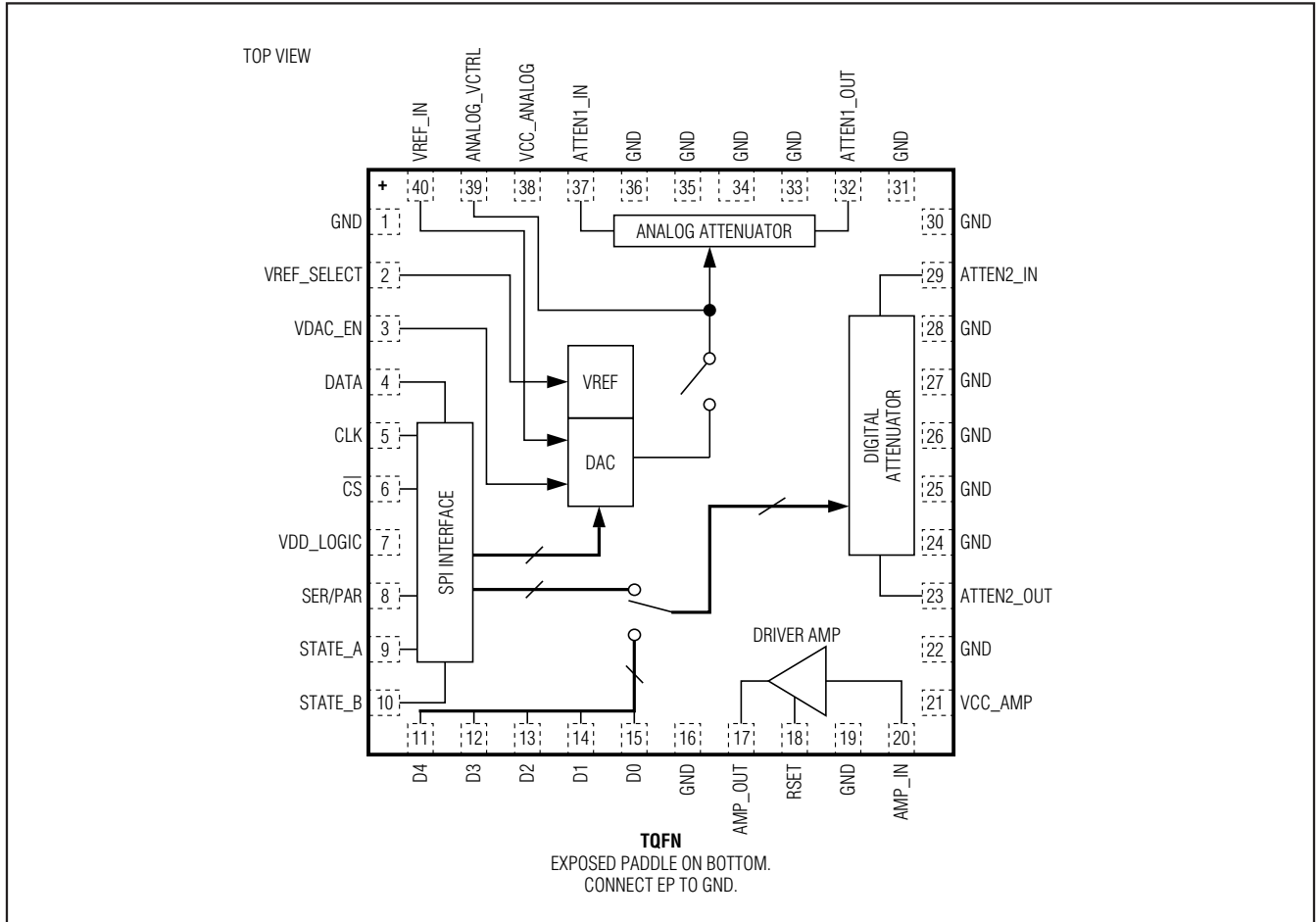
Typical Application Circuit



50MHz to 1000MHz High-Linearity, Serial/ Parallel-Controlled Analog/Digital VGA

Pin Configuration/Functional Block Diagram

MAX2065



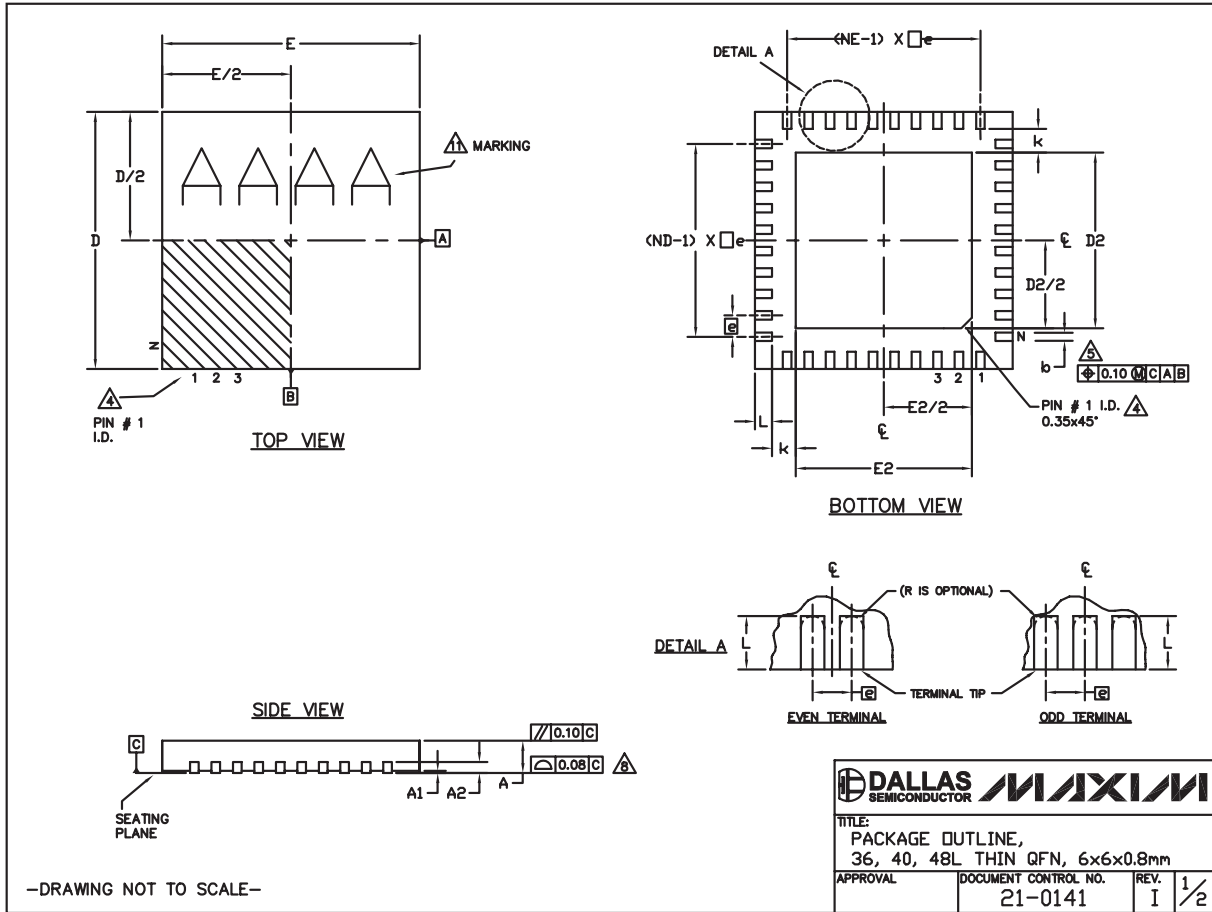
Chip Information

PROCESS: SiGe BiCMOS

50MHz to 1000MHz High-Linearity, Serial/ Parallel-Controlled Analog/Digital VGA

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)



50MHz to 1000MHz High-Linearity, Serial/ Parallel-Controlled Analog/Digital VGA

MAX2065

Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)


| COMMON DIMENSIONS | | | | | | | | | |
|-------------------|-----------|------|------|-----------|------|------|-----------|------|------|
| PKG. SYMBOL | 36L 6x6 | | | 40L 6x6 | | | 48L 6x6 | | |
| | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. |
| A | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 |
| A1 | 0 | 0.02 | 0.05 | 0 | 0.02 | 0.05 | 0 | - | 0.05 |
| A2 | 0.20 REF. | | | 0.20 REF. | | | 0.20 REF. | | |
| b | 0.20 | 0.25 | 0.30 | 0.20 | 0.25 | 0.30 | 0.15 | 0.20 | 0.25 |
| D | 5.90 | 6.00 | 6.10 | 5.90 | 6.00 | 6.10 | 5.90 | 6.00 | 6.10 |
| E | 5.90 | 6.00 | 6.10 | 5.90 | 6.00 | 6.10 | 5.90 | 6.00 | 6.10 |
| e | 0.50 BSC. | | | 0.50 BSC. | | | 0.40 BSC. | | |
| k | 0.25 | - | - | 0.25 | - | - | 0.25 | - | - |
| L | 0.35 | 0.50 | 0.65 | 0.30 | 0.40 | 0.50 | 0.30 | 0.40 | 0.50 |
| N | 36 | | | 40 | | | 48 | | |
| ND | 9 | | | 10 | | | 12 | | |
| NE | 9 | | | 10 | | | 12 | | |
| JEDEC | WJJD-1 | | | WJJD-2 | | | - | | |

| EXPOSED PAD VARIATIONS | | | | | | |
|------------------------|------|------|------|------|------|------|
| PKG. CODES | D2 | | | E2 | | |
| | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. |
| T3666-2 | 3.60 | 3.70 | 3.80 | 3.60 | 3.70 | 3.80 |
| T3666-3 | 3.60 | 3.70 | 3.80 | 3.60 | 3.70 | 3.80 |
| T3666N-1 | 3.60 | 3.70 | 3.80 | 3.60 | 3.70 | 3.80 |
| T3666MN-1 | 3.60 | 3.70 | 3.80 | 3.60 | 3.70 | 3.80 |
| T4066-2 | 4.00 | 4.10 | 4.20 | 4.00 | 4.10 | 4.20 |
| T4066-3 | 4.00 | 4.10 | 4.20 | 4.00 | 4.10 | 4.20 |
| T4066-5 | 4.00 | 4.10 | 4.20 | 4.00 | 4.10 | 4.20 |
| T4866-1 | 4.40 | 4.50 | 4.60 | 4.40 | 4.50 | 4.60 |
| T4866N-1 | 4.40 | 4.50 | 4.60 | 4.40 | 4.50 | 4.60 |
| T4866-2 | 4.40 | 4.50 | 4.60 | 4.40 | 4.50 | 4.60 |

NOTES:

- DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994.
- ALL DIMENSIONS ARE IN MILLIMETERS. ANGLES ARE IN DEGREES.
- N IS THE TOTAL NUMBER OF TERMINALS.
- THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JESD 95-1 SPP-012. DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 IDENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE.
- DIMENSION *b* APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25mm AND 0.30mm FROM TERMINAL TIP.
- ND AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.
- DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.
- COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
- DRAWING CONFORMS TO JEDEC MQ220, EXCEPT FOR 0.4mm LEAD PITCH PACKAGE T4866-1.
- WARPAGE SHALL NOT EXCEED 0.10mm.
- MARKING IS FOR PACKAGE ORIENTATION REFERENCE ONLY.
- NUMBER OF LEADS SHOWN FOR REFERENCE ONLY.
- ALL DIMENSIONS APPLY TO BOTH LEADED (-) AND PbFREE (+) PKG. CODES.

-DRAWING NOT TO SCALE-

| | |
|---------------------------------------------------------------------------------------|---------------------------------|
|  | |
| TITLE: PACKAGE OUTLINE, 36, 40, 48L THIN QFN, 6x6x0.8mm | |
| APPROVAL | DOCUMENT CONTROL NO. 21-0141 |
| REV. I | 2/2 |

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