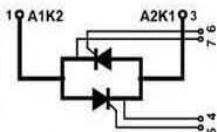


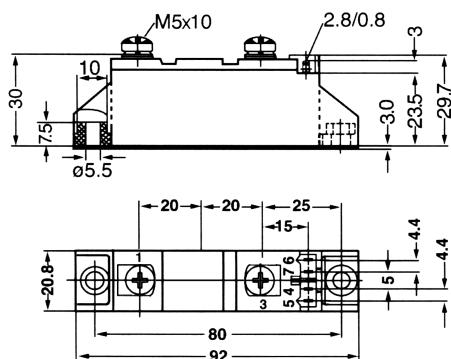
SSAC27

Solid State AC Controller(Anti-Parallel Thyristor-Thyristor Modules)



Type	V_{RSM} V	V_{RRM} V
	V_{DSM}	V_{DRM}
SSAC27GK08	900	800
SSAC27GK12	1300	1200
SSAC27GK14	1500	1400
SSAC27GK16	1700	1600
SSAC27GK18	1900	1800

Dimensions in mm (1mm=0.0394")



Symbol	Test Conditions	Maximum Ratings	Unit
I_{TRMS} , I_{FRMS} I_{TAVM} , I_{FAVM}	$T_{VJ}=T_{VJM}$ $T_c=85^\circ C$; 180° sine	50 27	A
I_{TSM} , I_{FSM}	$T_{VJ}=45^\circ C$ $V_R=0$	520 560	A
	$T_{VJ}=T_{VJM}$ $V_R=0$	460 500	
$\int i^2 dt$	$T_{VJ}=45^\circ C$ $V_R=0$	1350 1300	$A^2 s$
	$T_{VJ}=T_{VJM}$ $V_R=0$	1050 1030	
$(di/dt)_{cr}$	$T_{VJ}=T_{VJM}$ $f=50Hz$, $t_p=200\mu s$ $V_D=2/3V_{DRM}$ $I_G=0.45A$	150	A/us
	non repetitive, $I_T=I_{TAVM}$ $dIG/dt=0.45A/\mu s$	500	
$(dv/dt)_{cr}$	$T_{VJ}=T_{VJM}$; $V_{DR}=2/3V_{DRM}$ $R_{GK}=\infty$; method 1 (linear voltage rise)	1000	V/us
P_{GM}	$T_{VJ}=T_{VJM}$ $I_T=I_{TAVM}$	10 5	W
P_{GAV}		0.5	W
V_{RGM}		10	V
T_{VJ} T_{VJM} T_{stg}		-40...+125 125 -40...+125	°C
V_{ISOL}	50/60Hz, RMS $I_{ISOL}\leq 1mA$	3000 3600	V~
M_d	Mounting torque (M5) Terminal connection torque (M5)	2.5-4.0/22-35 2.5-4.0/22-35	Nm/lb.in.
Weight	Typical including screws	90	g

SSAC27

Solid State AC Controller(Anti-Parallel Thyristor-Thyristor Modules)

Symbol	Test Conditions	Characteristic Values	Unit
I_{RRM}, I_{DRM}	$T_{VJ}=T_{VJM}; V_R=V_{RRM}; V_D=V_{DRM}$	3	mA
V_T, V_F	$I_T, I_F=80A; T_{VJ}=25^\circ C$	1.64	V
V_{TO}	For power-loss calculations only ($T_{VJ}=125^\circ C$)	0.85	V
r_T		11	$m\Omega$
V_{GT}	$V_D=6V; T_{VJ}=25^\circ C$ $T_{VJ}=-40^\circ C$	1.5 1.6	V
I_{GT}	$V_D=6V; T_{VJ}=25^\circ C$ $T_{VJ}=-40^\circ C$	100 200	mA
V_{GD}	$T_{VJ}=T_{VJM}; V_D=2/3V_{DRM}$	0.2	V
I_{GD}		10	mA
I_L	$T_{VJ}=25^\circ C; t_p=10\mu s; V_D=6V$ $I_G=0.45A; dI/dt=0.45A/\mu s$	450	mA
I_H	$T_{VJ}=25^\circ C; V_D=6V; R_{GK}=\infty$	200	mA
t_{gd}	$T_{VJ}=25^\circ C; V_D=1/2V_{DRM}$ $I_G=0.45A; dI/dt=0.45A/\mu s$	2	us
t_q	$T_{VJ}=T_{VJM}; I_T=20A; t_p=200\mu s; -dI/dt=10A/\mu s$ $V_R=100V; dv/dt=20V/\mu s; V_D=2/3V_{DRM}$	typ. 150	us
Q_s	$T_{VJ}=T_{VJM}; I_T, I_F=25A; -dI/dt=0.64A/\mu s$	50	uC
I_{RM}		6	A
R_{thJC}	per thyristor/diode; DC current per module	0.88 0.44	K/W
R_{thJK}	per thyristor/diode; DC current per module	1.08 0.54	K/W
ds	Creeping distance on surface	12.7	mm
da	Strike distance through air	9.6	mm
a	Maximum allowable acceleration	50	m/s^2

FEATURES

- * International standard package
- * Copper Base Plate with Inter-DCB
- * Planar passivated chips
- * Isolation voltage 3600 V~

APPLICATIONS

- * DC motor control
- * Softstart AC motor controller
- * Light, heat and temperature control

ADVANTAGES

- * Space and weight savings
- * Simple mounting with two screws
- * Improved temperature and power cycling
- * Reduced protection circuits



SSAC27

Solid State AC Controller(Anti-Parallel Thyristor-Thyristor Modules)

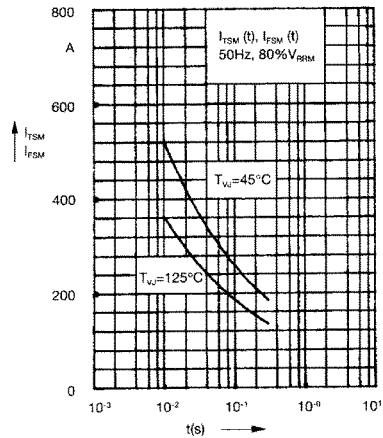


Fig. 1 Surge overload current
 I_{TSM}, I_{FSM} : Crest value, t : duration

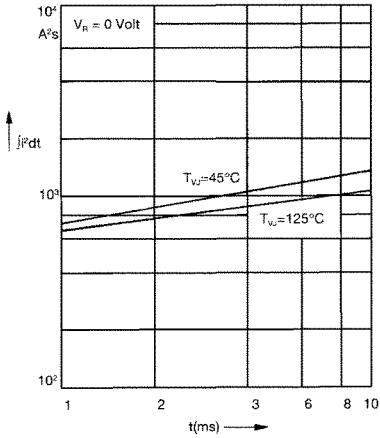


Fig. 2 $\int i^2 dt$ versus time (1-10 ms)

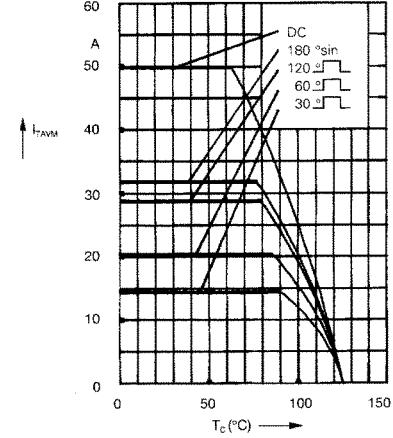


Fig. 2a Maximum forward current
at case temperature

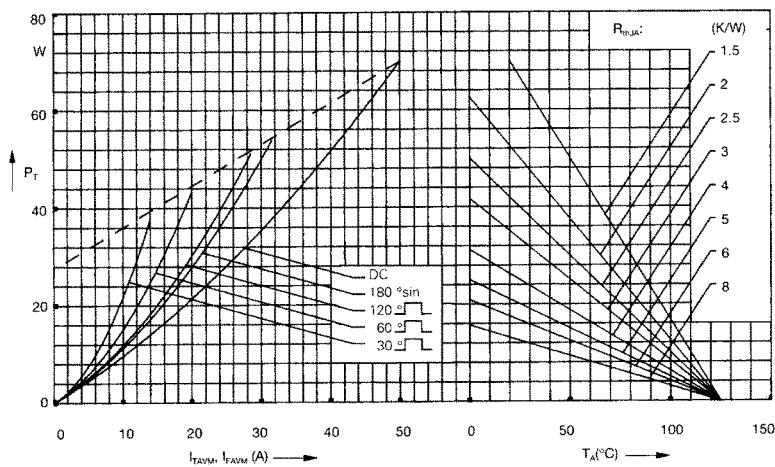


Fig. 3 Power dissipation versus on-state current and ambient temperature
(per thyristor or diode)

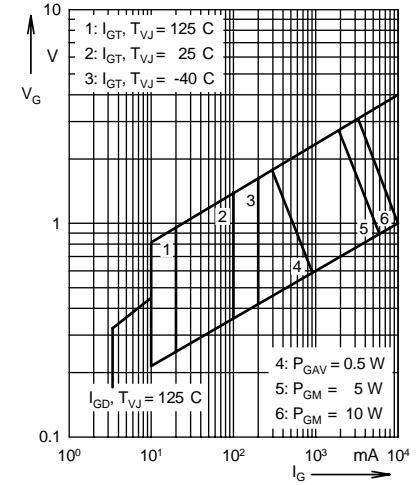


Fig. 4 Gate trigger characteristics

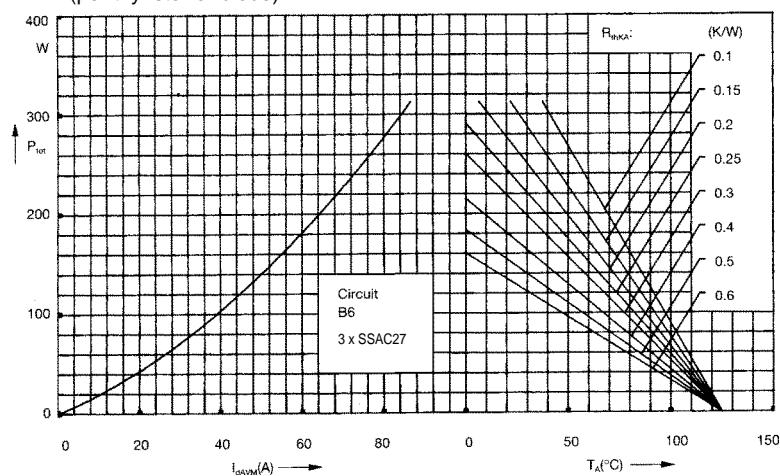


Fig. 5 Three phase rectifier bridge: Power dissipation versus direct output current
and ambient temperature

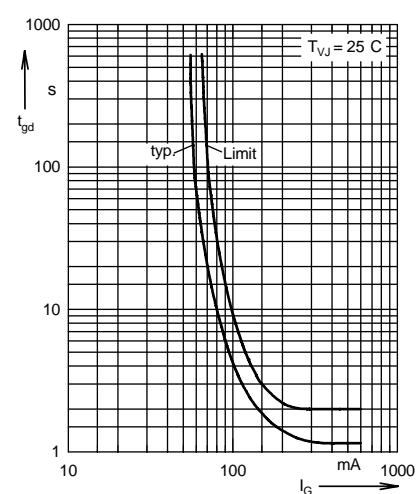


Fig. 6 Gate trigger delay time

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Solid State AC Controller(Anti-Parallel Thyristor-Thyristor Modules)

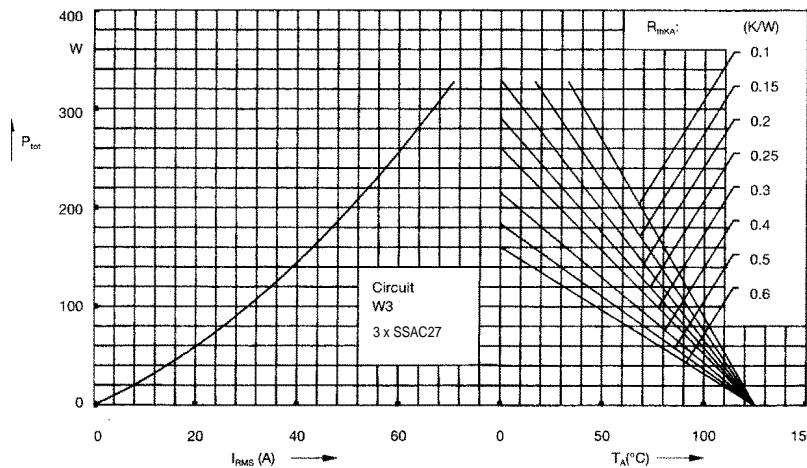


Fig. 7 Three phase AC-controller:
Power dissipation versus RMS
output current and ambient
temperature

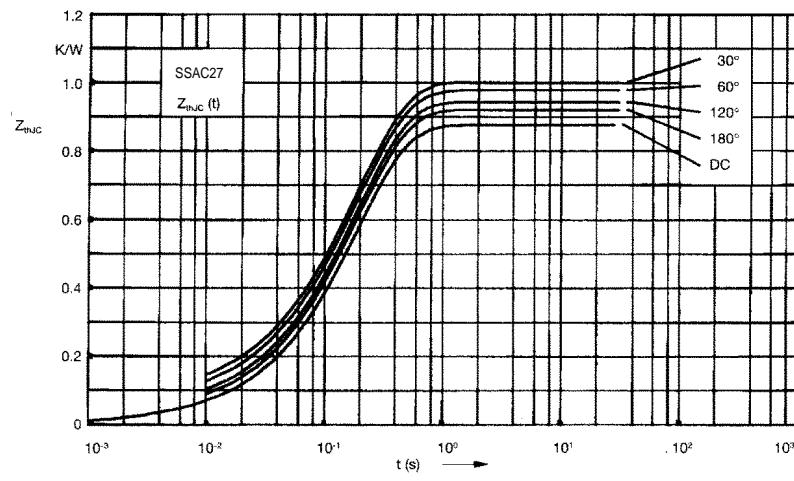


Fig. 8 Transient thermal impedance
junction to case (per thyristor or
diode)

R_{thJC} for various conduction angles d:

d	R_{thJC} (K/W)
DC	0.88
180°	0.92
120°	0.95
60°	0.98
30°	1.01

Constants for Z_{thJC} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.019	0.0031
2	0.029	0.0216
3	0.832	0.191

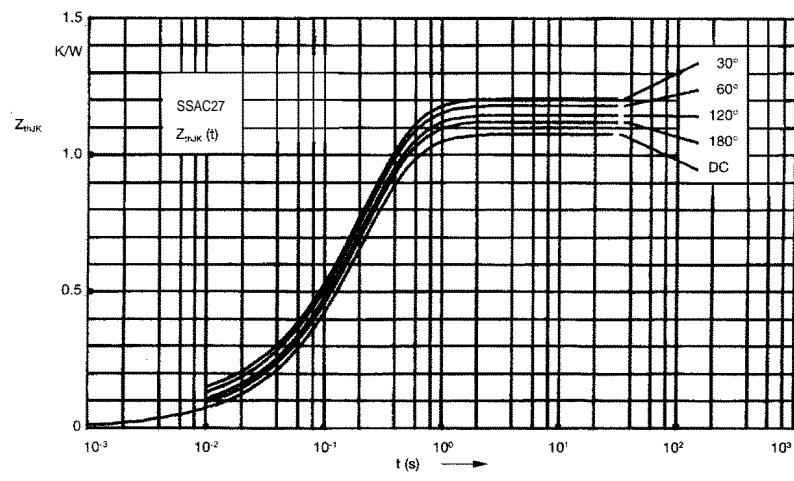


Fig. 9 Transient thermal impedance
junction to heatsink (per thyristor or
diode)

R_{thJK} for various conduction angles d:

d	R_{thJK} (K/W)
DC	1.08
180°	1.12
120°	1.15
60°	1.18
30°	1.21

Constants for Z_{thJK} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.019	0.0031
2	0.029	0.0216
3	0.832	0.191
4	0.2	0.45