## Features

- Fast Read Access Time 90 ns
- Dual Voltage Range Operation
  - Unregulated Battery Power Supply Range, 2.7V to 3.6V or Standard 5V  $\pm\,10\%$  Supply Range
- Pin Compatible with JEDEC Standard AT27C1024
- Low Power CMOS Operation
  - 20  $\mu A$  Max (Less than 1  $\mu A$  Typical) Standby for  $V_{CC}$  = 3.6V
  - 36 mW Max Active at 5 MHz for V  $_{\rm CC}$  = 3.6V
- JEDEC Standard Surface Mount Packages
  - 44-lead PLCC
  - 40-lead VSOP
- High Reliability CMOS Technology
  - 2,000V ESD Protection
  - 200 mA Latchup Immunity
- Rapid Programming Algorithm 100 µs/Word (Typical)
- CMOS and TTL Compatible Inputs and Outputs – JEDEC Standard for LVTTL and LVBO
- Integrated Product Identification Code
- Industrial Temperature Range

## 1. Description

The AT27BV1024 is a high-performance, low-power, low-voltage 1,048,576-bit onetime programmable read-only memory (OTP EPROM) organized as 64K by 16 bits. It requires only one supply in the range of 2.7V to 3.6V in normal read mode operation. The by-16 organization makes this part ideal for portable and handheld 16- and 32-bit microprocessor based systems using either regulated or unregulated battery power.

Atmel's innovative design techniques provide fast speeds that rival 5V parts while keeping the low power consumption of a 3V supply. At  $V_{CC}$  = 2.7V, any word can be accessed in less than 120 ns. With a typical power dissipation of only 18 mW at 5 MHz and  $V_{CC}$  = 3V, the AT27BV1024 consumes less than one fifth the power of a standard 5V EPROM.

Standby mode supply current is typically less than 1  $\mu$ A at 3V. The AT27BV1024 simplifies system design and stretches battery lifetime even further by eliminating the need for power supply regulation.

The AT27BV1024 is available in industry standard JEDEC-approved one-time programmable (OTP) plastic PLCC and VSOP packages. All devices feature two-line control ( $\overline{CE}$ ,  $\overline{OE}$ ) to give designers the flexibility to prevent bus contention.

The AT27BV1024 operating with V<sub>CC</sub> at 3.0V produces TTL level outputs that are compatible with standard TTL logic devices operating at V<sub>CC</sub> = 5.0V. At V<sub>CC</sub> = 2.7V, the part is compatible with JEDEC approved low voltage battery operation (LVBO) interface specifications. The device is also capable of standard 5-volt operation making it ideally suited for dual supply range systems or card products that are pluggable in both 3-volt and 5-volt hosts.

Atmel's AT27BV1024 has additional features to ensure high quality and efficient production use. The Rapid Programming Algorithm reduces the time required to program the part and guarantees reliable programming. Programming time is typically only 100  $\mu$ s/word. The Integrated Product Identification Code electronically identifies





1-Megabit (64K x 16) Unregulated Battery-Voltage High-Speed OTP EPROM

# AT27BV1024



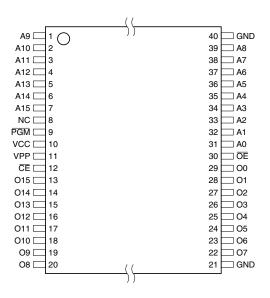
the device and manufacturer. This feature is used by industry-standard programming equipment to select the proper programming algorithms and voltages. The AT27BV1024 programs exactly the same way as a standard 5V AT27C1024 and uses the same programming equipment.

#### 2. Pin Configurations

Pin Name	Function
A0 - A15	Addresses
O0 - O15	Outputs
CE	Chip Enable
ŌĒ	Output Enable
PGM	Program Strobe
NC	No Connect

Note: Both GND pins must be connected.

#### 2.1 40-lead VSOP (Type 1) Top View



#### 2.2 44-lead PLCC Top View

		013	014	015	Ы	VPP	Я	VCC	PGM	Ŋ	A15	A14	
	~												1
012 🗆	-	9	ß	4	С	N	5	4	43	42	4	4 39	□ A13
	<i>'</i>						0						
011 🗆	8											38	🗆 A12
O10 🗆	9											37	🗆 A11
O9 🗆	10	)										36	🗆 A10
O8 🗆	11	1										35	🗆 A9
GND 🗆	12	2										34	GND
NC 🗆	13	3										33	D NC
07 🗆	14	1										32	🗆 A8
O6 🗆	15	5										31	🗆 A7
O5 🗆	16											30	🗆 A6
04 🗆	17	<sup>7</sup> ∞	~	~	_	~	~	+		6		8 <sup>29</sup>	🗆 A5
		₽	÷	20	21	22	23	24	25	26	27	ŝ	
											Ш		
		ő	0	6	8	ВО	S	Ao	A	A2	ЪЗ	A4	

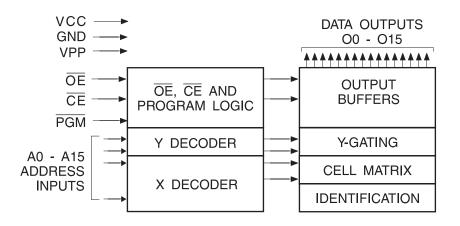
Note: PLCC Package Pins 1 and 23 are Don't Connect.

# <sup>2</sup> AT27BV1024

#### 3. System Considerations

Switching between active and standby conditions via the Chip Enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device non-conformance. At a minimum, a 0.1  $\mu$ F high frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the V<sub>CC</sub> and Ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a 4.7  $\mu$ F bulk electrolytic capacitor should be utilized, again connected between the V<sub>CC</sub> and Ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.

#### 4. Block Diagram



#### 5. Absolute Maximum Ratings\*

Temperature Under Bias	55° C to +125° C
Storage Temperature	65° C to +150° C
Voltage on Any Pin with Respect to Ground	2.0V to +7.0V <sup>(1)</sup>
Voltage on A9 with Respect to Ground	2.0V to +14.0V <sup>(1)</sup>
V <sub>PP</sub> Supply Voltage with Respect to Ground	2.0V to +14.0V <sup>(1)</sup>

\*NOTICE: Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability

Note: 1. Minimum voltage is -0.6V DC which may undershoot to -2.0V for pulses of less than 20 ns. Maximum output pin voltage is  $V_{CC}$  + 0.75V DC which may overshoot to +7.0V for pulses of less than 20 ns.





### 6. Operating Modes

Mode \ Pin	CE	ŌE	PGM	Ai	V <sub>PP</sub>	V <sub>cc</sub>	Outputs
Read <sup>(2)</sup>	V <sub>IL</sub>	V <sub>IL</sub>	X <sup>(1)</sup>	Ai	Х	V <sub>CC</sub>	D <sub>OUT</sub>
Output Disable <sup>(2)</sup>	Х	V <sub>IH</sub>	Х	х	Х	V <sub>CC</sub>	High Z
Standby <sup>(2)</sup>	V <sub>IH</sub>	Х	Х	х	X <sup>(5)</sup>	V <sub>CC</sub>	High Z
Rapid Program <sup>(3)</sup>	V <sub>IL</sub>	V <sub>IH</sub>	V <sub>IL</sub>	Ai	V <sub>PP</sub>	V <sub>CC</sub>	D <sub>IN</sub>
PGM Verify <sup>(3)</sup>	V <sub>IL</sub>	V <sub>IL</sub>	V <sub>IH</sub>	Ai	V <sub>PP</sub>	V <sub>CC</sub>	D <sub>OUT</sub>
PGM Inhibit <sup>(3)</sup>	V <sub>IH</sub>	Х	Х	х	V <sub>PP</sub>	V <sub>CC</sub>	High Z
Product Identification <sup>(3)(5)</sup>	V <sub>IL</sub>	V <sub>IL</sub>	х	$A9 = V_{H}^{(4)}$ $A0 = V_{IH} \text{ or } V_{IL}$ $A1 - A15 = V_{IL}$	V <sub>cc</sub>	V <sub>cc</sub>	Identification Code

Notes: 1. X can be  $V_{IL}$  or  $V_{IH}$ .

2. Read, output disable, and standby modes require, 2.7V  $\leq$ V<sub>CC</sub>  $\leq$ 3.6V, or 4.5V  $\leq$ V<sub>CC</sub>  $\leq$ 5.5V.

3. Refer to Programming Characteristics. Programming modes require  $V_{CC} = 6.5V$ .

4.  $V_{H} = 12.0 \pm 0.5 V.$ 

 Two identifier words may be selected. All Ai inputs are held low (V<sub>IL</sub>), except A9 which is set to V<sub>H</sub> and A0 which is toggled low (V<sub>IL</sub>) to select the Manufacturer's Identification word and high (V<sub>IH</sub>) to select the Device Code word.

## 7. DC and AC Operating Conditions for Read Operation

	AT27BV1024-90
Industrial Operating Temperature (Case)	-40° C - 85° C
M. Dewer Supply	2.7V to 3.6V
V <sub>CC</sub> Power Supply	5V ±10%

# 4 AT27BV1024

## 8. DC and Operating Characteristics for Read Operation

Symbol	Parameter	Condition	Min	Max	Units
$V_{\rm CC} = 2.7$	V to 3.6V	· · · · · · · · · · · · · · · · · · ·			
ILI	Input Load Current	$V_{IN} = 0V$ to $V_{CC}$		±1	μA
I <sub>LO</sub>	Output Leakage Current	$V_{OUT} = 0V$ to $V_{CC}$		±5	μA
I <sub>PP1</sub> <sup>(2)</sup>	V <sub>PP</sub> <sup>(1)</sup> Read/Standby Current	V <sub>PP</sub> = V <sub>CC</sub>		10	μA
	) ( (1) Otomolhus Osumont	$I_{SB1}$ (CMOS), $\overline{CE} = V_{CC} \pm 0.3V$		20	μA
I <sub>SB</sub>	V <sub>CC</sub> <sup>(1)</sup> Standby Current	$I_{SB2}$ (TTL), $\overline{CE} = 2.0$ to $V_{CC} + 0.5V$		100	μA
I <sub>cc</sub>	V <sub>CC</sub> Active Current	f = 5 MHz, $I_{OUT}$ = 0 mA, $\overline{CE}$ = $V_{IL}$ , $V_{CC}$ = 3.6V		8	mA
		V <sub>CC</sub> = 3.0 to 3.6V	-0.6	0.8	V
V <sub>IL</sub>	Input Low Voltage	V <sub>CC</sub> = 2.7 to 3.6V	-0.6	0.2 x V <sub>CC</sub>	V
	land the Matterna	V <sub>CC</sub> = 3.0 to 3.6V	2.0	V <sub>CC</sub> + 0.5	V
V <sub>IH</sub>	Input High Voltage	V <sub>CC</sub> = 2.7 to 3.6V	$0.7  ext{ v}_{\text{cc}}$	V <sub>CC</sub> + 0.5	V
		I <sub>OL</sub> = 2.0 mA		0.4	V
V <sub>OL</sub>	OL Output Low Voltage	I <sub>OL</sub> = 100 μA		0.2	V
	I <sub>OL</sub> = 20 μA		0.1	V	
		I <sub>OH</sub> = -2.0 mA	2.4		V
V <sub>OH</sub>	Output High Voltage	I <sub>OH</sub> = -100 μA	V <sub>CC</sub> - 0.2		V
		I <sub>OH</sub> = -20 μA	V <sub>CC</sub> - 0.1		V
V <sub>cc</sub> = 4.5	V to 5.5V				
ILI	Input Load Current	$V_{IN} = 0V$ to $V_{CC}$		±1	μA
I <sub>LO</sub>	Output Leakage Current	$V_{OUT} = 0V$ to $V_{CC}$		±5	μA
I <sub>PP1</sub> <sup>(2)</sup>	V <sub>PP</sub> <sup>(1)</sup> Read/Standby Current	V <sub>PP</sub> = V <sub>CC</sub>		10	μA
	) ( (1) Otomolhus Osument	$I_{SB1}$ (CMOS), $\overline{CE} = V_{CC} \pm 0.3V$		100	μA
I <sub>SB</sub>	V <sub>CC</sub> <sup>(1)</sup> Standby Current	$I_{SB2}$ (TTL), $\overline{CE}$ = 2.0 to $V_{CC}$ + 0.5V		1	mA
I <sub>CC</sub>	V <sub>CC</sub> Active Current	$f = 5 \text{ MHz}, I_{OUT} = 0 \text{ mA}, \overline{CE} = V_{IL}$		30	mA
V <sub>IL</sub>	Input Low Voltage		-0.6	0.8	V
V <sub>IH</sub>	Input High Voltage		2.0	V <sub>CC</sub> + 0.5	V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 2.1 mA		0.4	V
V <sub>OH</sub>	Output High Voltage	I <sub>OH</sub> = -400 μA	2.4		V

Notes: 1.  $V_{CC}$  must be applied simultaneously with or before  $V_{PP}$  and removed simultaneously with or after  $V_{PP}$ 

2. V<sub>PP</sub> may be connected directly to V<sub>CC</sub>, except during programming. The supply current would then be the sum of I<sub>CC</sub> and I<sub>PP</sub>



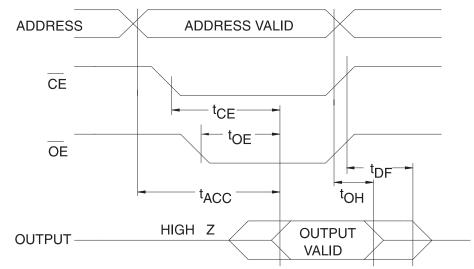


### 9. AC Characteristics for Read Operation

 $V_{CC}$  = 2.7V to 3.6V and 4.5V to 5.5V

			AT27B	AT27BV1024-90	
Symbol	Parameter	Condition	Min	Max	Unit
t <sub>ACC</sub> <sup>(3)</sup>	Address to Output Delay	$\overline{CE} = \overline{OE} \\ = V_{IL}$		90	ns
t <sub>CE</sub> <sup>(2)</sup>	CE to Output Delay	$\overline{OE} = V_{IL}$		90	ns
t <sub>OE</sub> <sup>(2)(3)</sup>	OE to Output Delay	$\overline{CE} = V_{IL}$		30	ns
t <sub>DF</sub> <sup>(4)(5)</sup>	$\overline{OE}$ or $\overline{CE}$ High to Output Float, Whichever Occurred First			30	ns
t <sub>он</sub>	Output Hold from Address, $\overline{CE}$ or $\overline{OE}$ , Whichever Occurred First		0		ns

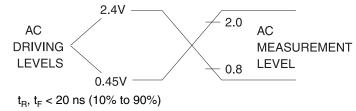
# **10. AC Waveforms for Read Operation**<sup>(1)</sup>



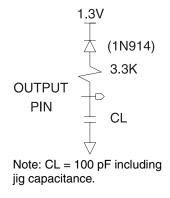
- Notes: 1. Timing measurement references are 0.8V and 2.0V. Input AC drive levels are 0.45V and 2.4V, unless otherwise specified.
  - 2.  $\overline{OE}$  may be delayed up to t<sub>CE</sub> t<sub>OE</sub> after the falling edge of  $\overline{CE}$  without impact on t<sub>CE</sub>.
  - 3.  $\overline{\text{OE}}$  may be delayed up to  $t_{ACC}$   $t_{OE}$  after the address is valid without impact on  $t_{ACC}$ .
  - 4. This parameter is only sampled and is not 100% tested.
  - 5. Output float is defined as the point when data is no longer driven.
  - 6. When reading a AT27BV1024, a 0.1  $\mu$ F capacitor is required across V<sub>CC</sub> and ground to suppress spurious voltage transients.

AT27BV1024





### 12. Output Test Load



### 13. Pin Capacitance

 $f = 1 \text{ MHz } T = 25^{\circ}C^{(1)}$ 

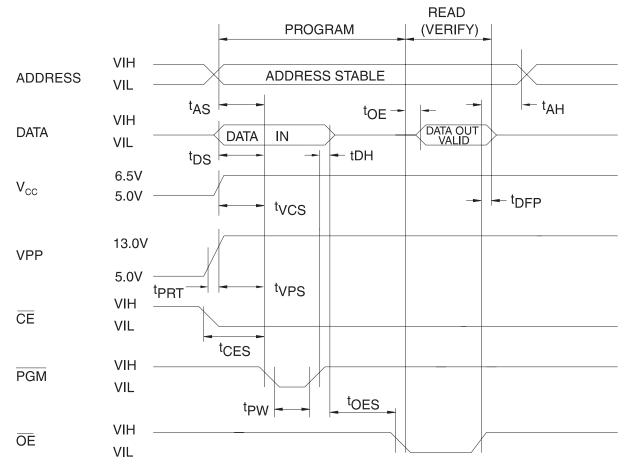
Symbol	Тур	Мах	Units	Conditions
C <sub>IN</sub>	4	10	pF	$V_{IN} = 0V$
C <sub>OUT</sub>	8	12	pF	$V_{OUT} = 0V$

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not 100% tested.





## 14. Programming Waveforms<sup>(1)</sup>



- Notes: 1. The Input Timing Reference is 0.8V for  $V_{IL}$  and 2.0V for  $V_{IH}$ .
  - 2.  $t_{OE}$  and  $t_{DFP}$  are characteristics of the device but must be accommodated by the programmer.
  - 3. When programming the AT27BV1024 a 0.1  $\mu$ F capacitor is required across V<sub>PP</sub> and ground to suppress spurious voltage transients.

## **15. DC Programming Characteristics**

 $T_{A} = 25 \pm 5^{\circ}\,C, \, V_{CC} = 6.5 \pm 0.25 V, \, V_{PP} = 13.0 \pm 0.25 V$ 

			Li	Limits			
Symbol	Parameter	Test Conditions	Min	Мах	Units		
ILI	Input Load Current	$V_{IN} = V_{IL}, V_{IH}$		±10	μA		
V <sub>IL</sub>	Input Low Level		-0.6	0.8	V		
V <sub>IH</sub>	Input High Level		2.0	V <sub>CC</sub> + 0.1	V		
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 2.1 mA		0.4	V		
V <sub>OH</sub>	Output High Voltage	I <sub>OH</sub> = -400 μA	2.4		V		
I <sub>CC2</sub>	V <sub>CC</sub> Supply Current (Program and Verify)			50	mA		
I <sub>PP2</sub>	V <sub>PP</sub> Supply Current	$\overline{CE} = \overline{PGM} = V_{IL}$		30	mA		
V <sub>ID</sub>	A9 Product Identification Voltage		11.5	12.5	V		

## **16. AC Programming Characteristics**

 $T_{A} = 25 \pm 5^{\circ} \, C, \, V_{CC} = 6.5 \pm 0.25 V, \, V_{PP} = 13.0 \pm 0.25 V$ 

			Lin	nits	
Symbol	Parameter	Test Conditions <sup>(1)</sup>	Min	Max	Units
t <sub>AS</sub>	Address Setup Time		2		μs
t <sub>CES</sub>	CE Setup Time		2		μs
t <sub>OES</sub>	OE Setup Time	Input Rise and Fall Times: (10% to 90%) 20 ns	2		μs
t <sub>DS</sub>	Data Setup Time		2		μs
t <sub>AH</sub>	Address Hold Time	Input Pulse Levels:	0		μs
t <sub>DH</sub>	Data Hold Time	0.45V to 2.4V	2		μs
t <sub>DFP</sub>	OE High to Output Float Delay <sup>(2)</sup>	Input Timing Reference Level:	0	130	ns
t <sub>VPS</sub>	V <sub>PP</sub> Setup Time	0.8V to 2.0V	2		μs
t <sub>VCS</sub>	V <sub>CC</sub> Setup Time		2		μs
t <sub>PW</sub>	PGM Program Pulse Width <sup>(3)</sup>	Output Timing Reference Level: 0.8V to 2.0V	95	105	μs
t <sub>OE</sub>	Data Valid from OE			150	ns
t <sub>PRT</sub>	V <sub>PP</sub> Pulse Rise Time During Programming		50		ns

Notes: 1.  $V_{CC}$  must be applied simultaneously or before  $V_{PP}$  and removed simultaneously or after  $V_{PP}$ 

 This parameter is only sampled and is not 100% tested. Output Float is defined as the point where data is no longer driven – see timing diagram.

3. Program Pulse width tolerance is 100  $\mu sec \pm 5\%.$ 

# 17. Atmel's AT27BV1024 Integrated Product Identification Code<sup>(1)</sup>

		Pins							Hex		
Codes	A0	015-08	07	<b>O</b> 6	<b>O</b> 5	04	O3	02	01	00	Data
Manufacturer	0	0	0	0	0	1	1	1	1	0	001E
Device Type	1	0	1	1	1	1	0	0	0	1	00F1

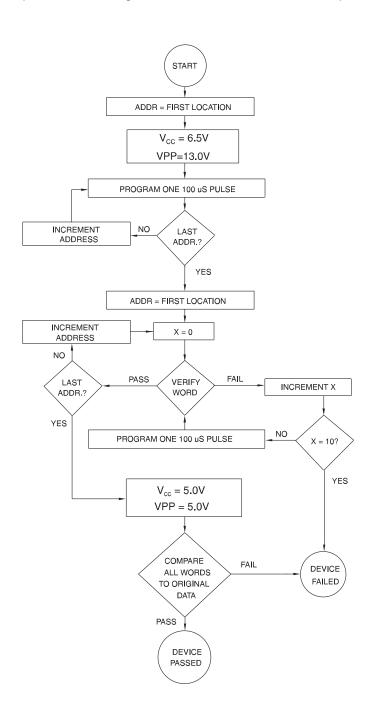
Note: 1. The AT27BV1024 has the same Product Identification Code as the AT27C1024. Both are programming compatible.





#### 18. Rapid Programming Algorithm

A 100  $\mu$ s PGM pulse width is used to program. The address is set to the first location. V<sub>CC</sub> is raised to 6.5V and V<sub>PP</sub> is raised to 13.0V. Each address is first programmed with one 100  $\mu$ s PGM pulse without verification. Then a verification/reprogramming loop is executed for each address. In the event a word fails to pass verification, up to 10 successive 100  $\mu$ s pulses are applied with a verification after each pulse. If the word fails to verify after 10 pulses have been applied, the part is considered failed. After the word verifies properly, the next address is selected until all have been checked. V<sub>PP</sub> is then lowered to 5.0V and V<sub>CC</sub> to 5.0V. All words are read again and compared with the original data to determine if the device passes or fails.



# 19. Ordering Information

#### 19.1 Standard Package

t <sub>ACC</sub>	I <sub>cc</sub> (	mA)								
(ns)	Active Standby		Ordering Code	Package	Operation Range					
90	8	0.02	AT27BV1024-90JI	44J	Industrial					
			AT27BV1024-90VI	40V <sup>(1)</sup>	(-40° C to 85° C)					
Note:										

19.2 Green Package (Pb/Halide-free)

t <sub>ACC</sub> (ns)	I <sub>CC</sub> (mA)				
	Active	Standby	Ordering Code	Package	<b>Operation Range</b>
90	8	0.02	AT27BV1024-90JU	44J	Industrial (-40° C to 85° C)
120	8	0.02	AT27BV1024-12JU	44J	Industrial (-40° C to 85° C)

Note: 1. The 40-lead VSOP package is not recommended for new designs.

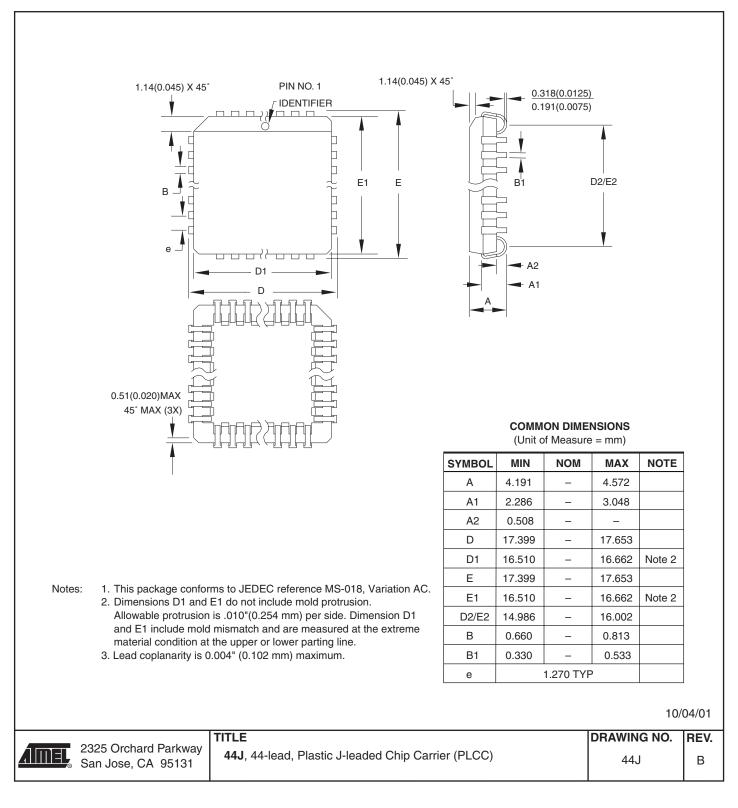
Package Type				
44J	44-lead, Plastic J-leaded Chip Carrier (PLCC)			
40V	40-lead, Plastic Thin Small Outline Package (VSOP)			



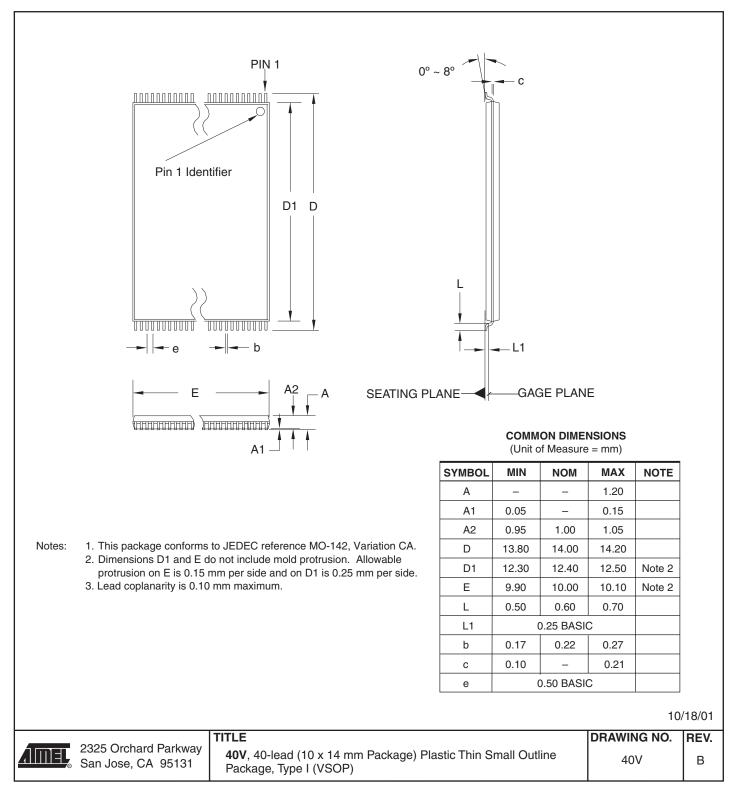


### 20. Packaging Information

## 21. 44J – PLCC



#### 22. 40V – VSOP







#### Headquarters

*Atmel Corporation* 2325 Orchard Parkway San Jose, CA 95131 USA Tel: 1(408) 441-0311 Fax: 1(408) 487-2600

#### International

Atmel Asia Room 1219 Chinachem Golden Plaza 77 Mody Road Tsimshatsui East Kowloon Hong Kong Tel: (852) 2721-9778 Fax: (852) 2722-1369 Atmel Europe Le Krebs 8, Rue Jean-Pierre Timbaud BP 309 78054 Saint-Quentin-en-Yvelines Cedex France Tel: (33) 1-30-60-70-00 Fax: (33) 1-30-60-71-11

#### Atmel Japan

9F, Tonetsu Shinkawa Bldg. 1-24-8 Shinkawa Chuo-ku, Tokyo 104-0033 Japan Tel: (81) 3-3523-3551 Fax: (81) 3-3523-7581

#### **Product Contact**

Web Site www.atmel.com Technical Support eprom@atmel.com Sales Contact www.atmel.com/contacts

Literature Requests www.atmel.com/literature

Disclaimer: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. EXCEPT AS SET FORTH IN ATMEL'S TERMS AND CONDI-TIONS OF SALE LOCATED ON ATMEL'S WEB SITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDEN-TAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS OF PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and product descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel's products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.

© 2007 Atmel Corporation. All rights reserved. Atmel<sup>®</sup>, logo and combinations thereof, and others are registered trademarks or trademarks of Atmel Corporation or its subsidiaries. Other terms and product names may be trademarks of others.