# **Switching Voltage Regulators**

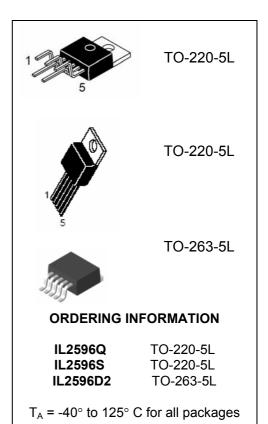
IL2596-xx

#### **Features**

- 3.3V, 5V, 12V, and adjustable output versions
- Adjustable version output voltage range, 1.2V to 37V ± 4% max over line and load conditions
- Guaranteed 3A output load current
- Input voltage range up to 40V
- Requires only 4 external components
- Excellent line and load regulation specifications
- 150kHz fixed frequency internal oscillator
- TTL shutdown capability
- Low power standby mode, I<sub>O</sub> typically 100μA
- Thermal shutdown and current limit protection

#### **Functions**

- Simple high-efficiency step-down regulator
- · On-card switching regulators
- Positive to negative converter



## **Description**

The IL2596 series of regulators are monolithic integrated circuits that provide all the active functions for a step-down switching regulator, capable of driving a 3A load with excellent line and load regulation. These devices are available in fixed output voltages of 3.3V, 5V, 12V and an adjustable output version.

Requiring a minimum number of external components, these regulators are simple to use.

The IL2596 series operates at a switching frequency of 150kHz. Available in standard 5-lead TO-220

Other features include a guaranteed ± 4% tolerance on output voltage under specified input voltage and output load conditions, and ± 15% on the oscillator frequency. External shutdown is included, featuring typically 100µA standby current. Self protection features include a two stage frequency reducing current limit for output switch and an over temperature shutdown for complete protection under fault conditions. The over temperature shutdown level is about 145°C with 5°C hysteresis.

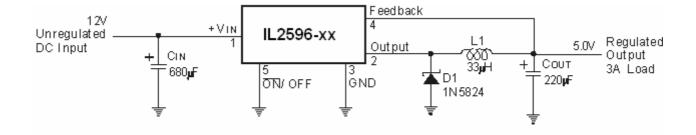


# **Absolute Maximum Rating**

 $(T_A = 25^{\circ}C)$ 

Characteristic	Symbol	Value	Unit
Maximum Input Supply Voltage	Vı	45	V
ON/OFF Pin Input Voltage	V <sub>IN</sub>	-0.3 ≤ V ≤ +25	V
Feedback Pin Voltage		-0.3 ≤ V ≤ +25	V
Output Voltage to Ground	Vo	-1	V
Power Dissipation	P <sub>D</sub>	Internally limited	W
Storage Temperature Range	$T_{stg}$	-65 to +150	°C
Operating Temperature Range	TJ	$40 \le T_J \le +125$	°C
Operating Supply Voltage	V <sub>IN</sub>	4.5 to 40	V

# **Typical Aplication (Fixed Output Voltage Versions)**





### **Electrical Characteristics**

Unless otherwise specified,  $T_J$  = 25 °C  $V_{IN}$  = 12V for the 3.3V, 5V, and Adjustable version and  $V_{IN}$  = 24V for the 12V version.  $I_{LOAD}$  = 500mA.

$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Characteristic	Symbol	Test Condition		Min	Тур	Max	Unit
D.2A ≤ ILCAD ≤ 3A   D.   D.   D.	Output Voltage	V <sub>OUT</sub>	IL2596-3		3.168	3.3	3.432	
Efficiency   IL2596-3   IL2596-3   IL2596-5   IL2596-5   IL2596-12   V <sub>IN</sub> = 25V, I <sub>LOAD</sub> = 3A   80   90   112596-12   V <sub>IN</sub> = 25V, I <sub>LOAD</sub> = 3A   73   90   112596-A   V <sub>OUT</sub> = 3V, I <sub>LOAD</sub> = 3A   73   90   112596-A   V <sub>OUT</sub> = 3V, I <sub>LOAD</sub> = 3A   73   90   112596-A   V <sub>OUT</sub> = 3V, I <sub>LOAD</sub> = 3A   73   90   90   112596-A   V <sub>OUT</sub> = 3V, I <sub>LOAD</sub> = 3A   73   90   90   90   90   90   90   90   9			IL2596-5		4.8	5.0	5.2	V
Hardward			IL2596–12		11.52	12.0	12.48	
$ \begin{array}{ c c c c c c c c } \hline & IL2596-12 & V_{IN} = 25V, I_{LOAD} = 3A & 90 \\ \hline & IL2596-A & V_{OUT} = 3V, I_{LOAD} = 3A & 73 & 8 \\ \hline & IL2596-A & V_{OUT} = 3V, I_{LOAD} = 3A & 73 & 8 \\ \hline & IL2596-A & 4.5V \leq V_{IN} \leq 40V, \\ 0.2A \leq I_{LOAD} \leq 3A \\ V_{OUT} programmed for \\ 3V & & & & & & & & & & & & & & & & & & $	Efficiency		IL2596-3	I <sub>LOAD</sub> = 3A		73		
$ \begin{array}{ c c c c c c c c c } \hline & IL2596-A & V_{OUT} = 3V, I_{LOAD} = 3A & 73 & \% \\ \hline Feedback Voltage & V_{FB} & IL2596-A & 4.5V \leq V_{IN} \leq 40V, \\ 0.2A \leq I_{LOAD} \leq 3A \\ V_{OUT} programmed for \\ 3V & & & & & & & & & & & & & & & & & & $		η	IL2596-5	I <sub>LOAD</sub> = 3A		80		%
$ \begin{array}{ c c c c c c c c } \hline Feedback Voltage & V_{FB} & IL2596-A & 4.5V \le V_{IN} \le 40V, \\ 0.2A \le I_{LOAD} \le 3A \\ V_{OUT} \ programmed for \\ 3V & & & & & & & & & & & & & & & & & & $			IL2596-12	$V_{IN}$ = 25V, $I_{LOAD}$ = 3A		90		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			IL2596-A	$V_{OUT} = 3V$ , $I_{LOAD} = 3A$		73		%
Current         fo         Interpretation (Note 1,2)         Interpretation (Note 2)         Interpretation (Note 2)         Interpretation (Note 1,2)         Int	Feedback Voltage	V <sub>FB</sub>	IL2596-A	$0.2A \le I_{LOAD} \le 3A$ $V_{OUT}$ programmed for	1.193	1.230	1.267	V
Saturation Voltage   V <sub>SAT</sub>   I <sub>OUT</sub> = 3A   (Note 1,2)   100   % (Note 2)   100   % (Note 3)   0   (Note 1,2)   (Note 3)   0   (Note 1,2)   (Note 1,2)   0   (Note 1,2)   0   (Note 1,2)   (Note 1,2)   0   (Note 1,3)   0   (Note 1,3)   0   (Note 3)   5   10   mA   (Note 1,3)   0   (Note 3)   5   10   mA   (Note 1,3)   0   (Note 3)   5   10   mA   (Note 1,3)   0   (Note 3)   (Note 3)   0   (Note 3)   (Note 3)		I <sub>D</sub>	IL2596-A; V <sub>F</sub>	<sub>EB</sub> = 1.3V		15	50	nA
Max Duty Cycle (ON)   DC (Note 2)   100   %	Oscillator Frequency	f <sub>O</sub>			110	150	173	kHz
Max Duty Cycle (ON)         DC (Note 2)         (Note 2)         100         %           Max Duty Cycle (OFF)         (Note 3)         0         0            Current Limit $I_{CL}$ Peak Current (Note 1,2)         3.4         4.5         6.0         A           Output Leakage Current $I_{L}$ (Note 1,3)         Output = 0V (Note 1,3)         2         30         mA           Quiescent Current $I_{Q}$ (Note 3)         5         10         mA           Standby Quiescent Current $I_{STBY}$ ON/OFF pin = 5V (OFF), $V_{IN}$ = 40V         100         200         μA           ON/OFF Pin Logic Input $V_{IH}$ Low (Regulator ON)         2.0         1.3         0.6         V           ON/OFF Pin Input $V_{IL}$ High (Regulator OFF)         5         15         μA	Saturation Voltage	V <sub>SAT</sub>				1.16	1.4	V
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		DC				100		%
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			(Note 3)			0		
Output Leakage Current $I_L$ Output = 0V (Note 1,3)50μAQuiescent Current $I_Q$ Output = -1V, $V_{IN}$ = 40V230mAQuiescent Current $I_Q$ (Note 3)510mAStandby Quiescent Current $I_{STBY}$ ON/OFF pin = 5V (OFF), $V_{IN}$ = 40V100200μAON/OFF Pin Logic Input Threshold Voltage $V_{IL}$ Low (Regulator ON)2.01.30.6VON/OFF Pin Input $V_{IL}$ High (Regulator OFF)515μA	Current Limit	I <sub>CL</sub>		t	3.4	4.5	6.0	Α
Quiescent Current $I_Q$ (Note 3)510mAStandby Quiescent Current $I_{STBY}$ ON/OFF pin = 5V (OFF), $V_{IN}$ = 40V100200 $\mu A$ ON/OFF Pin Logic Input $V_{IH}$ Low (Regulator ON)2.01.30.6VThreshold Voltage $V_{IL}$ High (Regulator OFF)515 $\mu A$		IL	Output = 0V				50	μА
Standby Quiescent Current $I_{STBY}$ ON/OFF pin = 5V (OFF), $V_{IN}$ = 40V $100$ 200 $\mu$ A ON/OFF Pin Logic Input Threshold Voltage $V_{IL}$ High (Regulator OFF) $V_{LOGIC}$ = 2.5V (regulator OFF) $V_{LOGIC}$ $V_{LOGIC}$ $V_{LOGIC}$ $V_{IL}$			Output = -1V	', V <sub>IN</sub> = 40V		2	30	mA
Current	Quiescent Current	IQ				5	10	mA
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		I <sub>STBY</sub>	ON/OFF pin = 5V (OFF), V <sub>IN</sub> = 40V			100	200	μА
Threshold Voltage $V_{IL}$ High (Regulator OFF) $I_{H}$ $V_{LOGIC}$ = 2.5V (regulator OFF) $I_{LOGIC}$ 5 15 $I_{LOGIC}$ $I_{L$		V <sub>IH</sub>	Low (Regulator ON)		2.0	1.3	0.6	V
		V <sub>IL</sub>	High (Regulator OFF)					
	ON/OFF Pin Input	I <sub>H</sub>	,			5	15	μА
	Current	ΙL				0.02	5	1

Note 1: No elements connected to output pin.

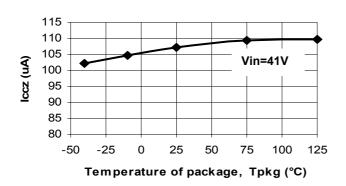
Note 3: Feedback pin removed from output and connected to 12V for the 3.3V, 5V, and the A version, and 15V for the 12V version. To force the output transistor switch OFF.



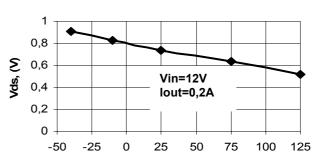
Note 2: Feedback pin removed from output and connected to 0V to force the output transistor switch ON.

# **Typical Perfomance Characteristics**

#### Iccz vs Tpkg (TO-220)

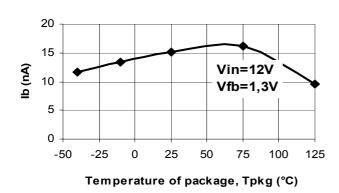


## Vds vs Tpkg (TO-220)

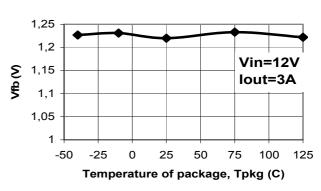


Temperature of package, Tpkg (°C)

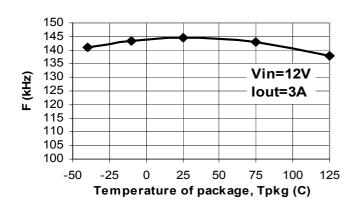
## Ib (on 4 pin) vs Tpkg (TO-220)



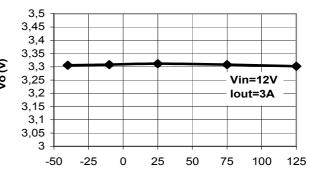
IL2596-adj Vfb vs Tpkg (TO-220)



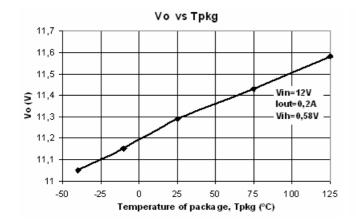
## Frequency F vs Tpkg (TO-220)

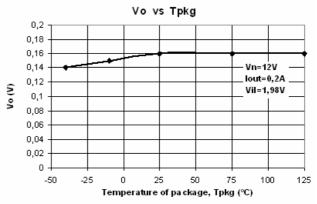


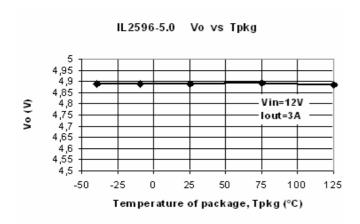
IL2596-3.3 Vo vs Tpkg

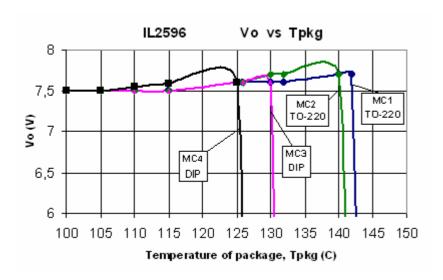


Temperature of package, Tpkg (°C)

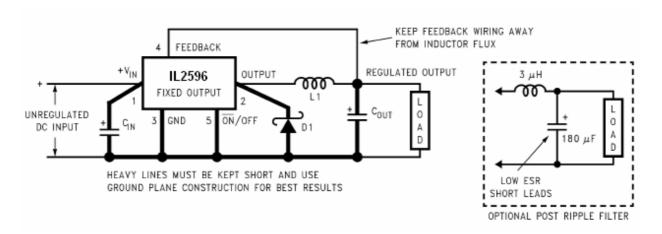






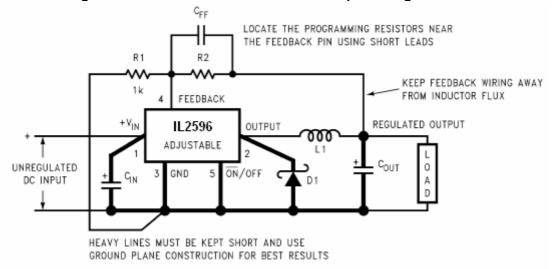


#### **Test Circuits**



CIN —470 µF, 50V, Aluminum Electrolytic Nichicon "PL Series" COUT —220 µF, 25V Aluminum Electrolytic, Nichicon "PL Series" D1 —5A, 40V Schottky Rectifier, 1N5825 L1 —68 µH, L38

Figure 1. Standard Test Circuit for Fixed Output Voltage Versions



$$V_{OUT} = V_{REF} \left( 1 + \frac{R_2}{R_1} \right)$$

where  $V_{REF} = 1.23V$ 

$$R_2 = R_1 \left( \frac{v_{OUT}}{v_{REF}} - 1 \right)$$

Select R1 to be approximately 1 kW, use a 1% resistor for best stability.  $C_{\text{IN}}$  —470  $\mu\text{F}$ , 50V, Aluminum Electrolytic Nichicon "PL Series"  $C_{\text{OUT}}$  —220  $\mu\text{F}$ , 35V Aluminum Electrolytic, Nichicon "PL Series"  $D_1$  —5A, 40V Schottky Rectifier, 1N5825  $L_1$  —68  $\mu\text{H}$ , L38  $R_1$  —1 kW, 1%

$$C_{FF} = \frac{1}{31\times 10^3\times R_2}$$

Figure 2. Standard Test Circuit for Adjustable Output Voltage Versions



## **Application Information** IL2596 5.0 $0.1 \, \mu F$ ON/OFF GND 680 µF R2 47k

Figure 3. Delayed Startup

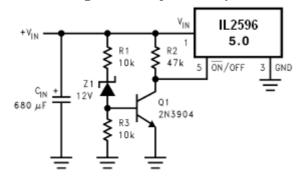


Figure 4. Undervoltage Lockout for Buck Regulator

#### **DELAYED STARTUP**

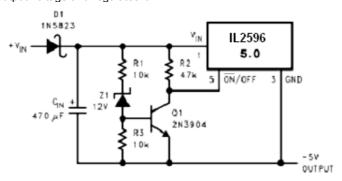
The circuit in Figure 3 uses the the ON /OFF pin to provide a time delay between the time the input voltage is applied and the time the output voltage comes up (only the circuitry pertaining to the delayed start up is shown). As the input voltage rises, the charging of capacitor C1 pulls the ON /OFF pin high, keeping the regulator off. Once the input voltage reaches its final value and the capacitor stops charging, and resistor R2 pulls the ON /OFF pin low, thus allowing the circuit to start switching. Resistor R<sub>1</sub> is included to limit the maximum voltage applied to the ON /OFF pin (maximum of 25V), reduces power supply noise sensitivity, and also limits the capacitor, C1, discharge current. When high input ripple voltage exists, avoid long delay time, because this ripple can be coupled into the ON /OFF pin and cause problems. This delayed startup feature is useful in situations where the input power source is limited in the amount of current it can deliver. It allows the input voltage to rise to a higher voltage before the regulator starts operating. Buck regulators require less input current at higher input voltages.

#### **UNDERVOLTAGE LOCKOUT**

Some applications require the regulator to remain off until the input voltage reaches a predetermined voltage. An undervoltage lockout feature applied to a buck regulator is shown in Figure 4, while Figure 5 and 6 applies the same feature to an inverting circuit. The circuit in Figure 5 features a constant threshold voltage for turn on and turn off (zener voltage plus approximately one volt). If hysteresis is needed, the circuit in Figure 6 has a turn ON voltage which is different than the turn OFF voltage. The amount of hysteresis is approximately equal to the value of the output voltage. If zener voltages greater than 25V are used, an additional 47 kΩ resistor is needed from the ON /OFF pin to the ground pin to stay within the 25V maximum limit of the ON /OFF pin.

#### **INVERTING REGULATOR**

The circuit in Figure 7 converts a positive input voltage to a negative output voltage with a common ground. The circuit operates by bootstrapping the regulator's ground pin to the negative output voltage, then grounding the feedback pin, the regulator senses the inverted output voltage and regulates it.



This circuit has an ON/OFF threshold of approximately 13V.

Figure 5. Undervoltage Lockout for Inverting Regulator

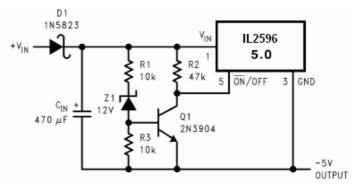


This example uses the IL2596-5.0 to generate a -5V output, but other output voltages are possible by selecting other output voltage versions, including the adjustable version. Since this regulator topology can produce an output voltage that is either greater than or less than the input voltage, the maximum output current greatly depends on both the input and output voltage. The curve shown in Figure 8 provides a guide as to the amount of output load current possible for the different input and output voltage conditions.

The maximum voltage appearing across the regulator is the absolute sum of the input and output voltage, and this must be limited to a maximum of 40V. For example, when converting +20V to −12V, the regulator would see 32V between the input pin and ground pin. The IL2596 has a maximum input voltage spec of 40V.

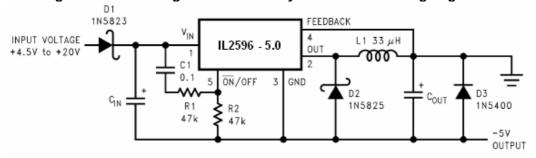
Additional diodes are required in this regulator configuration. Diode D1 is used to isolate input voltage ripple or noise from coupling through the C<sub>IN</sub> capacitor to the output, under light or no load conditions. Also, this diode isolation changes the topology to closley resemble a buck configuration thus providing good closed loop stability. A Schottky diode is recommended for low input voltages, (because of its lower voltage drop) but for higher input voltages, a fast recovery diode could be used.

Without diode D3, when the input voltage is first applied, the charging current of C<sub>IN</sub> can pull the output positive by several volts for a short period of time. Adding D3 prevents the output from going positive by more than a diode voltage.



This circuit has hysteresis Regulator starts switching at VIN = 13V Regulator stops switching at VIN = 8V

Figure 6. Undervoltage Lockout with Hysteresis for Inverting Regulator



CIN —68  $\mu$ F/25V Tant. Sprague 595D 470  $\mu$ F/50V Elec. Panasonic HFQ COUT —47  $\mu$ F/20V Tant. Sprague 595D 220  $\mu$ F/25V Elec. Panasonic HFQ

Figure 7. Inverting -5V Regulator with Delayed Startup

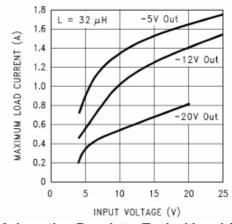


Figure 8. Inverting Regulator Typical Load Current



Because of differences in the operation of the inverting regulator, the standard design procedure is not used to select the inductor value. In the majority of designs, a 33 µH, 3.5A inductor is the best choice. Capacitor selection can also be narrowed down to just a few values. Using the values shown in Figure 7will provide good results in the majority of inverting designs

This type of inverting regulator can require relatively large amounts of input current when starting up, even with light loads. Input currents as high as the IL2596 current limit (approx 4.5A) are needed for at least 2 ms or more, until the output reaches its nominal output voltage. The actual time depends on the output voltage and the size of the output capacitor. Input power sources that are current limited or sources that can not deliver these currents without getting loaded down, may not work correctly. Because of the relatively high startup currents required by the inverting topology, the delayed startup feature (C1, R1 and R<sub>2</sub>) shown in Figure 7 is recommended. By delaying the regulator startup, the input capacitor is allowed to charge up to a higher voltage before the switcher begins operating. A portion of the high input current needed for startup is now supplied by the input capacitor (CIN). For severe start up conditions, the input capacitor can be made much larger than normal.

#### **INVERTING REGULATOR SHUTDOWN METHODS**

To use the ON /OFF pin in a standard buck configuration is simple, pull it below 1.3V (@25°C, referenced to ground) to turn regulator ON, pull it above 1.3V to shut the regulator OFF. With the inverting configuration, some level shifting is required, because the ground pin of the regulator is no longer at ground, but is now setting at the negative output voltage level. Two different shutdown methods for inverting regulators are shown in Figure 9and 10.

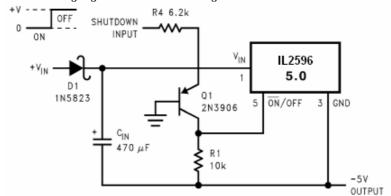


Figure 9. Inverting Regulator Ground Referenced Shutdown

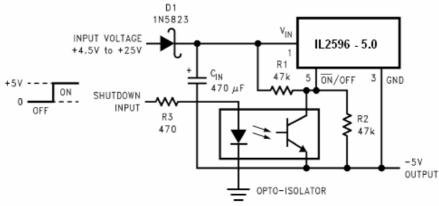
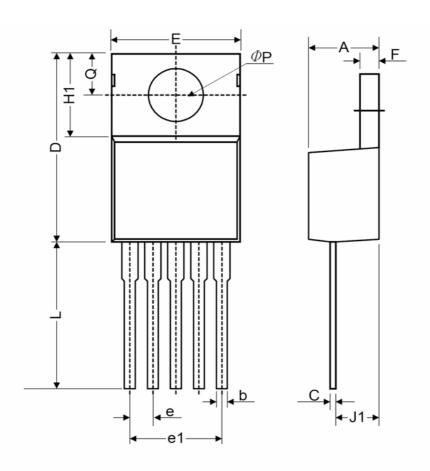


Figure 10. Inverting Regulator Ground Referenced Shutdown using Opto Device

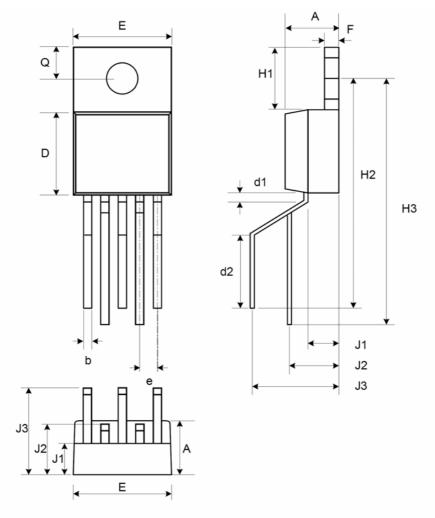


TO-220-5L



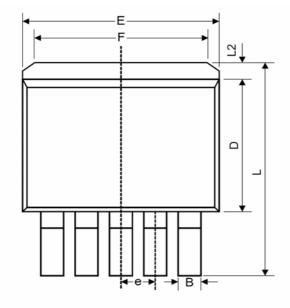
Symbol	Dimensions In Millimeters			Dimensions In Inches		
Symbol	Min.	Nom.	Max.	Min.	Nom.	Max.
Α	4.07	4.45	4.82	0.160	0.175	0.190
b	0.76	0.89	1.02	0.030	0.035	0.040
С	0.36	0.50	0.64	0.014	0.020	0.025
D	14.22	14.86	15.50	0.560	0.585	0.610
Е	9.78	10.16	10.54	0.385	0.400	0.415
е	1.57	1.71	1.85	0.062	0.067	0.073
e1	6.68	6.81	6.93	0.263	0.268	0.273
F	1.14	1.27	1.40	0.045	0.050	0.055
H1	5.46	6.16	6.86	0.215	0.243	0.270
J1	2.29	2.74	3.18	0.090	0.108	0.125
L	13.21	13.97	14.73	0.520	0.550	0.580
Øp	3.68	3.81	3.94	0.145	0.150	0.155
Q	2.54	2.73	2.92	0.100	0.107	0.115

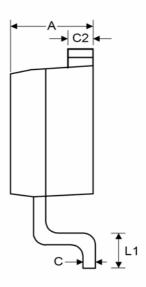
TO-220-5L (Bent Staggered)

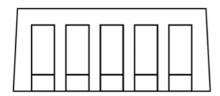


Symbol	Dimensions In Millimeters			Dimensions In Inches			
Symbol	Min.	Nom.	Max.	Min.	Nom.	Max.	
Α	4.4	4.6	4.7	0.175	0.180	0.185	
b	0.7	0.8	0.9	0.027	0.032	0.037	
D	8.4	8.7	8.9	0.330	0.340	0.350	
d1		1.0			0.039		
d2		6.3			0.248		
E	9.91	10.16	10.41	0.390	0.400	0.410	
е	1.6	1.7	1.8	0.062	0.067	0.072	
F	1.2	1.25	1.3	0.048	0.050	0.052	
H1	6.4				0.250		
H2	20.8	21.6	22.4	0.820	0.850	0.880	
H3	23.9	24.7	25.5	0.942	0.972	1.002	
J1	2.7 0.105						
J2	3.7	4.5	5.3	0.147	0.177	0.207	
J3		8.4			0.331		
Q	2.5	2.8	3.0	0.100	0.110	0.120	

TO-263-5L







Symbol	Dimensions In Millimeters			Dimensions In Inches		
	Min.	Nom.	Max.	Min.	Nom.	Max.
Α	4.07	4.46	4.85	0.160	0.176	0.191
В	0.66	0.84	1.02	0.026	0.033	0.040
С	0.36	0.50	0.64	0.014	0.020	0.025
C2	1.14	1.27	1.40	0.045	0.050	0.055
D	8.65	9.15	9.65	0.341	0.360	0.380
Е	9.78	10.16	10.54	0.385	0.400	0.415
е	1.57	1.71	1.85	0.062	0.068	0.073
F	6.60	6.86	7.11	0.260	0.270	0.280
L	14.61	15.24	15.88	0.575	0.600	0.625
L1	2.29	2.54	2.79	0.090	0.100	0.110
L2	-	-	2.92	-	-	0.115