



TO-92



Pin Definition:

- 1. Cathode
- 2. Anode
- 3. Reference

**SOT-23** 

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Reference

3. Anode

### **General Description**

TS1431 series integrated circuits are three-terminal programmable shunt regulator diodes. These monolithic IC voltage references operate as a low temperature coefficient zener which is programmable from Vref to 36 volts with two external resistors. These devices exhibit a wide operating current range of 1.0 to 100mA with a typical dynamic impedance of  $0.22\Omega$ . The characteristics of these references make them excellent replacements for zener diodes in many applications such as digital voltmeters, power supplies, and op amp circuitry. The 2.5V reference makes it convenient to obtain a stable reference from 5.0V logic supplies, and since The TS1431 series operates as a shunt regulator, it can be used as either a positive or negative stage reference.

#### **Features**

 Precision Reference Voltage TS1431 – 2.495V±2% TS1431A – 2.495V±1%

TS1431B - 2.495V±1%

- Equivalent Full Range Temp. Coefficient: 50ppm/ °C
- Programmable Output Voltage up to 36V
- Fast Turn-On Response
- Sink Current Capability of 1~100mA
- Low Dynamic Output Impedance: 0.2Ω
- Low Output Noise

### **Application**

- Voltage Monitor
- Delay Timmer
- Constant –Current Source/Sink
- High-Current Shunt Regulator
- Crow Bar
- Over-Voltage / Under-Voltage Protection

### Ordering Information

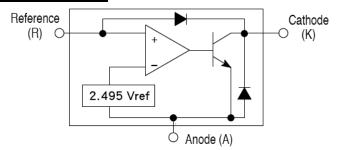
Part No.	Package	Packing
TS1431 <u>x</u> CT B0	TO-92	1Kpcs / Bulk
TS1431 <u>x</u> CT A3	TO-92	2Kpcs / Ammo
TS1431 <u>x</u> CX RF	SOT-23	3Kpcs / 7" Reel
TS1431 <u>x</u> CT B0G	TO-92	1Kpcs / Bulk
TS1431 <u>x</u> CT A3G	TO-92	2Kpcs / Ammo
TS1431xCX RFG	SOT-23	3Kpcs / 7" Reel

Note: "G" denote for Green Product

Where xx denotes voltage tolerance

Blank: ±2%, A: ±1%, B: ±0.5%

### **Block Diagram**



**Absolute Maximum Rating** (Ta = 25°C unless otherwise noted)

Parameter		Symbol	Limit	Unit
Cathode Voltage		Vka	36	V
Continuous Cathode Current Range		lk	1 ~ +100	mA
Reference Input Current Range		Iref	-0.05 ~ +10	mA
Power Dissipation	TO-92 SOT-23	Pd	0.625 0.30	W
Junction Temperature		Tj	+150	°C
Operating Temperature Range		Toper	0 ~ +70	°C
Storage Temperature Range		Tstg	-65 ~ <b>+</b> 150	°C









**Recommend Operating Condition** 

Parameter	Symbol	Limit	Unit
Cathode Voltage (Note 1)	$V_{KA}$	Ref ~ 36	V
Continuous Cathode Current Range	I <sub>K</sub>	1 ~ 100	mA

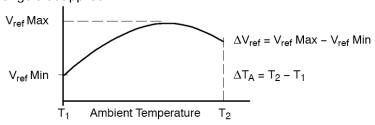
**Recommend Operating Condition** 

Parameter		Symbol	Test Conditions	Min	Тур	Max	Unit
	TS1431		\\ -\\   -10mm \( \( \( \( \) \)   (\( \) \)	2.450		2.550	
Reference voltage	TS1431A	$V_{REF}$	$V_{KA} = V_{REF}$ , $I_K = 10$ mA (Figure 1) Ta=25°C	2.475	2.495	2.525	V
	TS1431B		1a-25 C	2.487		2.513	
Deviation of reference voltage	ce input	$\DeltaV_{REF}$	$V_{KA} = V_{REF}$ , $I_K = 10$ mA (Figure 1) Ta= full range		3	17	mV
Radio of change in \	/ref to	$\Delta V_{REF} / \Delta V_{KA}$	$I_{KA}$ =10mA, $V_{KA}$ = 10V to $V_{REF}$		-1.4	-2.7	m\//\/
change in cathode V	oltage/	ΔV <sub>REF</sub> /ΔV <sub>KA</sub>	V <sub>KA</sub> = 36V to 10V (Figure 2)		-1.0	-2.0	mV/V
Reference Input current		I <sub>REF</sub>	R1=10KΩ, R2= $\infty$ , I <sub>KA</sub> =10mA Ta= full range (Figure 2)		0.7	4.0	uA
Deviation of reference current, over temp.	ce input	$\Delta I_{REF}$	R1=10K $\Omega$ , R2= $\infty$ , I <sub>KA</sub> =10mA Ta= full range (Figure 2)		0.4	1.2	uA
Off-state Cathode Current		I <sub>KA</sub> (off)	V <sub>REF</sub> =0V (Figure 3), V <sub>KA</sub> =36V		-	1.0	uA
Dynamic Output Impedance		Z <sub>KA</sub>	f<1KHz, $V_{KA} = V_{REF}$ $I_{KA} = 1$ mA to 100mA (Figure 1)		0.22	0.5	Ω
Minimum operating cathode current		I <sub>KA</sub> (min)	V <sub>KA</sub> = V <sub>REF</sub> (Figure 1)		0.4	0.6	mA
			1 61 1 1166 1 4				

<sup>\*</sup> The deviation parameters  $\Delta V_{REF}$  and  $\Delta I_{REF}$  are defined as difference between the maximum value and minimum value obtained over the full operating ambient temperature range that applied.

\* The average temperature coefficient of the reference input voltage,  $\alpha V_{REF}$  is defined as:

$$\alpha V_{ref} \, \left( \frac{ppm}{^{\circ}C} \right) = \frac{\left( \frac{(\Delta V_{ref})}{V_{ref} \, \left( T_{A} = 25^{\circ}C \right)} \times 10^{6} \right)}{\Delta T_{A}}$$



Where: **T2-T1** = full temperature change.

 $\alpha V_{REF}$  can be positive or negative depending on whether the slope is positive or negative.

Example: Maximum V<sub>REF</sub>=2.496V at 30°C, minimum V<sub>REF</sub> =2.492V at 0°C, V<sub>REF</sub> =2.495V at 25°C, ΔT=70°C

$$\alpha V_{REF}$$
 | = [4mV / 2495mV] \* 10<sup>6</sup> / 70°C  $\approx$  23ppm/°C

Because minimum  $V_{\text{REF}}$  occurs at the lower temperature, the coefficient is positive.

\* The dynamic impedance ZKA is defined as:

$$|Z_{K\Delta}| = \Delta V_{K\Delta} / \Delta I_{K\Delta}$$

\* When the device operating with two external resistors, R1 and R2, (refer to Figure 2) the total dynamic impedance of the circuit is given by:

$$|Z_{KA}| = \Delta v / \Delta i | \approx Z_{KA} | * (1 + R1 / R2)$$





#### **Test Circuits**

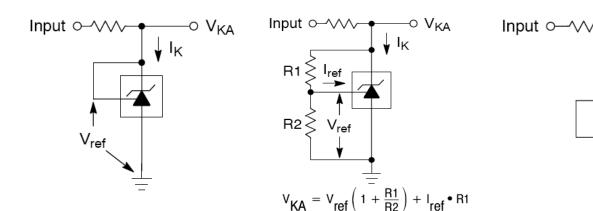


Figure 1:  $V_{KA} = V_{REF}$ 

Figure 2:  $V_{KA} > V_{REF}$ 

Figure 3: Off-State Current

### Additional Information – Stability

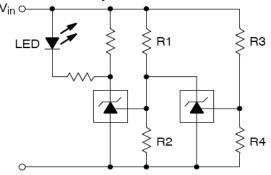
When The TS1431/1431A/1431B is used as a shunt regulator, there are two options for selection of  $C_L$ , are recommended for optional stability:

- A) No load capacitance across the device, decouple at the load.
- B) Large capacitance across the device, optional decoupling at the load.

The reason for this is that TS1431/1431A/1431B exhibits instability with capacitances in the range of 10nF to 1uF (approx.) at light cathode current up to 3mA (typ). The device is less stable the lower the cathode voltage has been set for. Therefore while the device will be perfectly stable operating at a cathode current of 10mA (approx.) with a 0.1uF capacitor across it, it will oscillate transiently during start up as the cathode current passes through the instability region. Select a very low capacitance, or alternatively a high capacitance (10uF) will avoid this issue altogether. Since the user will probably wish to have local decoupling at the load anyway, the most cost effective method is to use no capacitance at all directly across the device. PCB trace/via resistance and inductance prevent the local load decoupling from causing the oscillation during the transient start up phase.

Note: if the TS1431/1431A/1431B is located right at the load, so the load decoupling capacitor is directly across it, then this capacitor will have to be  $\leq 1$ nF or  $\geq 10$ uF.

### Applications Examples



L.E.D. indicator is 'ON' when V<sub>in</sub> is between the upper and lower limits,

Lower limit = 
$$\left(1 + \frac{R1}{R2}\right) V_{ref}$$

Upper limit = 
$$\left(1 + \frac{R3}{R4}\right) V_{ref}$$

Figure 4: Voltage Monitor

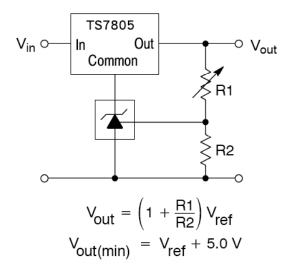


Figure 5: Output Control for Three Terminal Fixed Regulator





### **Applications Examples (Continue)**

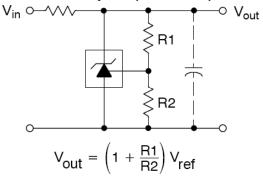


Figure 6: Shunt Regulator

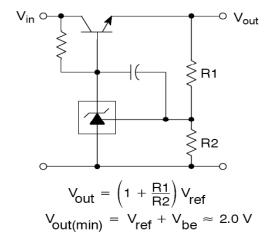


Figure 8: Series Pass Regulator

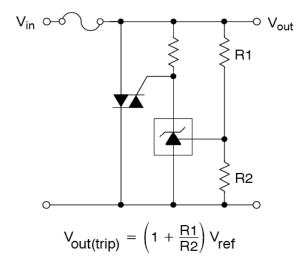


Figure 10: TRIAC Crowbar

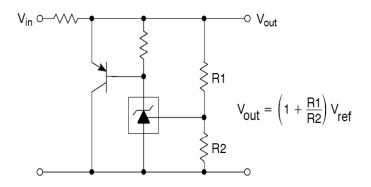
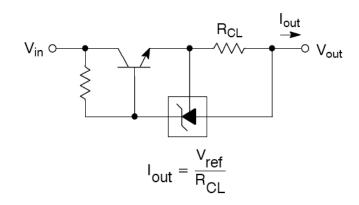


Figure 7: High Current Shunt Regulator



**Figure 9: Constant Current Source** 

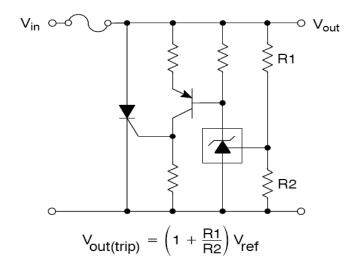
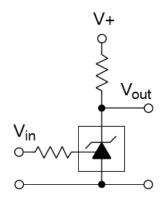


Figure 11: SCR Crowbar





### **Applications Examples (Continue)**



Vin	Vout	
<vref< td=""><td colspan="2">V+</td></vref<>	V+	
>Vref	≈0.74V	

Figure 12: Single-Supply Comparator with Temperature-Compensated Threshold

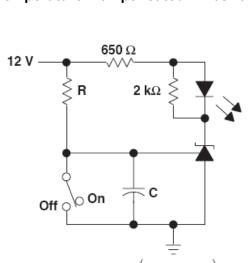


Figure 14: Delay Timer

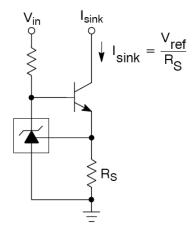


Figure 13: Constant Current Sink





### **Typical Performance Characteristics**

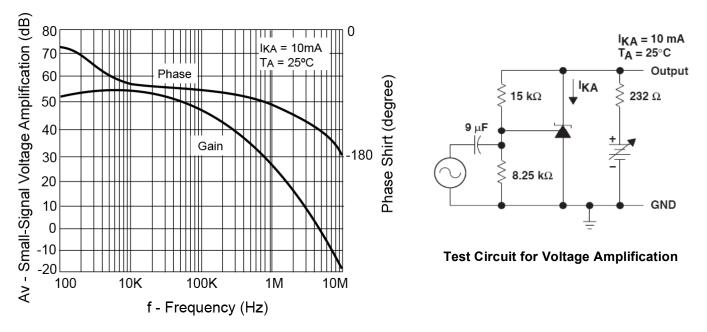


Figure 14: Small-Signal Voltage Gain and Phase Shirt vs. Frequency

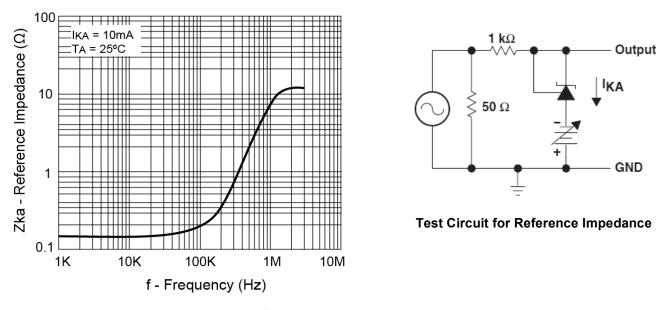
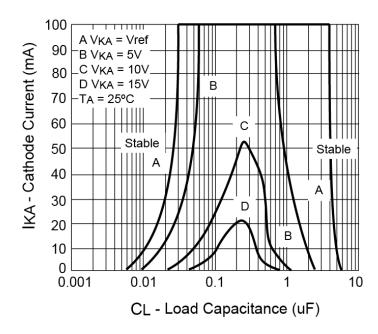


Figure 15: Reference Impedance vs. Frequency

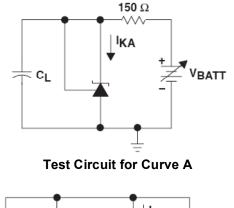


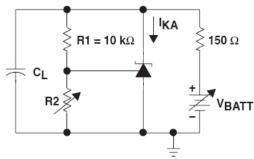


### **Typical Performance Characteristics (Continue)**



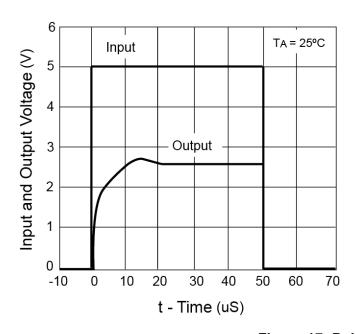
The areas under the curves represent conditions that may cause the device to oscillate. For curves B, C, and D, R2 and V+ were adjusted to establish the initial VKA and IKA conditions with CL=0. VBATT and CL then were adjusted to determine the ranges of stability.

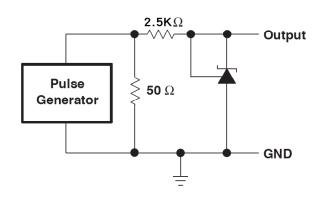




Test Circuit for Curve B, C and D

Figure 16: Stability Boundary Condition





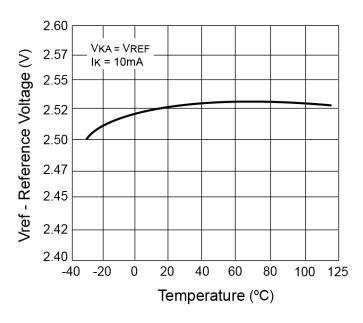
Test Circuit for Pulse Response, lk=1mA

Figure 17: Pulse Response





### **Electrical Characteristics**



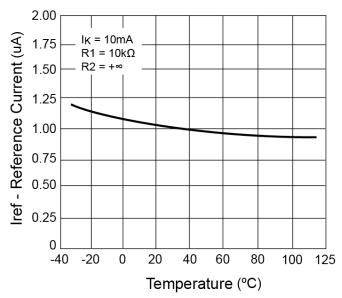


Figure 18: Reference Voltage vs. Temperature

Figure 19: Reference Current vs. Temperature

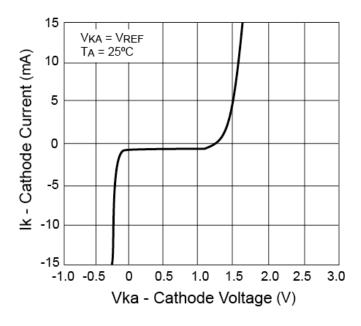
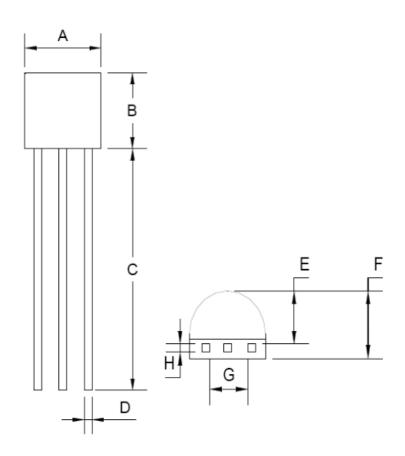


Figure 20: Cathode Current vs. Cathode Voltage



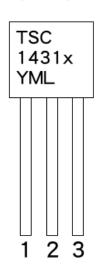


# **TO-92 Mechanical Drawing**



	TO-92 DIMENSION				
DIM MILLIMETE		ETERS	INCHES		
DIM	MIN	MAX	MIN	MAX	
Α	4.30	4.70	0.169	0.185	
В	4.30	4.70	0.169	0.185	
С	14.30(typ)		0.563(typ)		
D	0.43	0.49	0.017	0.019	
Е	2.19	2.81	0.086	0.111	
F	3.30	3.70	0.130	0.146	
G	2.42	2.66	0.095	0.105	
Н	0.37	0.43	0.015	0.017	

### **Marking Diagram**



X = Tolerance Code

 $(A = \pm 1\%, B = \pm 0.5\%, Blank = \pm 2\%,)$ 

Y = Year Code

M = Month Code

(A=Jan, B=Feb, C=Mar, D=Apl, E=May, F=Jun, G=Jul, H=Aug, I=Sep,

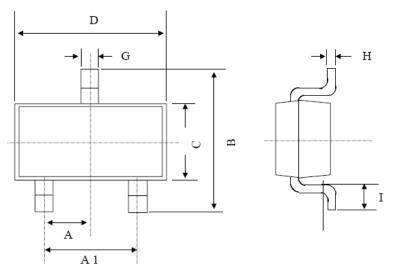
J=Oct, K=Nov, L=Dec)

**L** = Lot Code

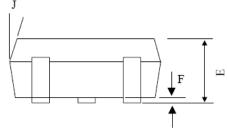




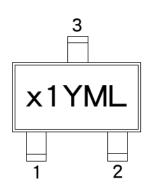
# **SOT-23 Mechanical Drawing**



SOT-23 DIMENSION						
DIM	MILLIM	MILLIMETERS		INCHES		
DIIVI	MIN	MAX	MIN	MAX.		
Α	0.95	BSC	0.037	0.037 BSC		
A1	1.9 I	BSC	0.074	0.074 BSC		
В	2.60	3.00	0.102	0.118		
С	1.40	1.70	0.055	0.067		
D	2.80	3.10	0.110	0.122		
Е	1.00	1.30	0.039	0.051		
F	0.00	0.10	0.000	0.004		
G	0.35	0.50	0.014	0.020		
Н	0.10	0.20	0.004	0.008		
I	0.30	0.60	0.012	0.024		
J	5°	10°	5°	10°		



### **Marking Diagram**



1 = Device Code

X = Tolerance Code

$$(A = \pm 1\%, B = \pm 0.5\%, C = \pm 2\%,)$$

Y = Year Code

M = Month Code

(A=Jan, B=Feb, C=Mar, D=Apl, E=May, F=Jun, G=Jul, H=Aug, I=Sep, J=Oct, K=Nov, L=Dec)

L = Lot Code



# TS1431

### Adjustable Precision Shunt Regulator

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