## Legacy Device: Motorola MC145583

The ML145583 is a CMOS transceiver composed of three drivers and five receivers that fulfills the electrical specifications of EIA-232-E, EIA-562, and CCITT V. 28 while operating from a single +3.3 or +5.0 V power supply. This transceiver is a high-performance, low-power consumption device that is equipped with a standby function.
A voltage tripler and inverter converts the +3.3 V to $\pm 8.8 \mathrm{~V}$, or a voltage doubler and inverter converts the +5.0 V to $\pm 8.8 \mathrm{~V}$. This is accomplished through an on-chip 40 kHz oscillator and five inexpensive external capacitors.

## FEATURES

## Drivers:

- $\pm 5$ V Minimum Output Swing at 3.3 or 5.0 V Power Supply
- $300 \Omega$ Power-Off Impedance
- Output Current Limiting
- Three-State Outputs During Standby Mode


## Receivers:

- $\pm 25 \mathrm{~V}$ Input Range
- 3 to $7 \mathrm{k} \Omega$ Input Impedance
- 0.8 V Hysteresis for Enhanced Noise Immunity
- Three-State Outputs During Standby Mode


## Ring Monitor Circuit:

- Invert the Input Level on Rx1 to Logic Output Level on RIMON at Standby Mode


FUNCTION DIAGRAM

CHARGE PUMPS


RECEIVER


DRIVER


MAXIMUM RATINGS (Voltage polarities referenced to GND)

| Rating | Symbol | Value | Unit |
| :--- | :---: | :---: | :---: |
| DC Supply Voltage | $\mathrm{V}_{\mathrm{CC}}$ | -0.5 to +6.0 | V |
| Input VoltageRx1 - Rx5 Inputs <br> DI1 - DI3 Inputs | $\mathrm{V}_{\mathrm{IR}}$ | $\mathrm{V}_{\mathrm{SS}}-15$ to $\mathrm{V}_{\mathrm{DD}}+15$ <br> -0.5 to $\mathrm{V}_{\mathrm{CC}}+0.5$ | V |
| DC Current per Pin | I | $\pm 100$ | mA |
| Power Dissipation | $\mathrm{P}_{\mathrm{D}}$ | 1 | W |
| Operating Temperature Range | $\mathrm{T}_{\mathrm{A}}$ | -40 to +85 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $\mathrm{T}_{\text {stg }}$ | -85 to +150 | ${ }^{\circ} \mathrm{C}$ |

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation, it is recommended that the voltage at the DI and DO pins be constrained to the range $\mathrm{GND} \leq \mathrm{V}_{\mathrm{DI}} \leq \mathrm{V}_{\mathrm{CC}}$ and $\mathrm{GND} \leq \mathrm{V}_{\mathrm{DO}}$ $\leq \mathrm{V}_{\mathrm{CC}}$. Also, the voltage at the Rx pin should be constrained to $\left(\mathrm{V}_{\mathrm{SS}}-15 \mathrm{~V}\right) \leq \mathrm{V}_{\mathrm{Rx} 1}-\mathrm{Rx} 5$ $\leq\left(\mathrm{V}_{\mathrm{DD}}+15 \mathrm{~V}\right)$, and Tx should be constrained to $\mathrm{V}_{\mathrm{SS}} \leq \mathrm{V}_{\mathrm{Tx} 1}-\mathrm{Tx} 3 \leq \mathrm{V}_{\mathrm{DD}}$.

Unused inputs must always be tied to an appropriate logic voltage level (e.g., GND or $\mathrm{V}_{\mathrm{CC}}$ for DI , and GND for Rx).

## RECOMMENDED OPERATING LIMITS

| Parameter | Symbol | Min | Typ | Max | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Power Supply | $\mathrm{V}_{\mathrm{CC}}$ | 3.0 | 3.3 | 3.6 | V |
|  | $\mathrm{~V}_{\mathrm{CC}}{ }^{*}$ | 4.5 | 5.0 | 5.5 |  |
| Operating Temperature Range | $\mathrm{T}_{\mathrm{A}}$ | -40 | - | 85 | ${ }^{\circ} \mathrm{C}$ |

* Capacitors C 1 and C 2 are replaced by a $1 \mu \mathrm{~F}$ capacitor at $\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V}$.

DC ELECTRICAL CHARACTERISTICS (Voltage polarities referenced to GND = $0 \mathrm{~V} ; \mathrm{C} 1-\mathrm{C} 5=1 \mu \mathrm{~F} ; \mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ )

\begin{tabular}{|c|c|c|c|c|c|}
\hline Parameter \& Symbol \& Min \& Typ \& Max \& Unit <br>
\hline DC Power Supply \& $\mathrm{V}_{\text {CC }}$ \& 3.0 \& 3.3 \& 3.6 \& V <br>
\hline Quiescent Supply Current (Output Unloaded, Input Low) \& ICC \& - \& 2.8 \& 6.0 \& mA <br>
\hline Quiescent Supply Current (Standby Mode; STB = 1, Output Unloaded) \& ${ }^{\text {ICC(STB) }}$ \& - \& < 5 \& 10 \& $\mu \mathrm{A}$ <br>
\hline Control Signal Input Voltage (STB) \& $$
\begin{aligned}
& \mathrm{V}_{\mathrm{IL}} \\
& \mathrm{~V}_{\mathrm{IH}}
\end{aligned}
$$ \& $$
\frac{-}{v_{\mathrm{Cc}}-0.5}
$$ \& \& \& V <br>
\hline Control Signal Input Current (STB) \& $$
\begin{aligned}
& \mathrm{I}_{\mathrm{IL}} \\
& \mathrm{I}_{\mathrm{IH}}
\end{aligned}
$$ \& - \& \& $$
\begin{aligned}
& \hline 10 \\
& 10
\end{aligned}
$$ \& $\mu \mathrm{A}$ <br>
\hline  \& VD

$\mathrm{V}_{\text {SS }}$ \& \[
$$
\begin{aligned}
& 8.5 \\
& 7.5 \\
& \hline-
\end{aligned}
$$

\] \& \[

$$
\begin{gathered}
8.8 \\
7.9 \\
\hline-8.8 \\
-7.8
\end{gathered}
$$

\] \& \[

$$
\begin{aligned}
& -8.5 \\
& -7.0
\end{aligned}
$$
\] \& V <br>

\hline
\end{tabular}

## RECEIVER ELECTRICAL SPECIFICATIONS

(Voltage polarities referenced to $\mathrm{GND}=0 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V} \pm 10 \% ; \mathrm{C} 1-\mathrm{C} 5=1 \mu \mathrm{~F} ; \mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ )

| Parameter |  | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input Turn-On Threshold (VDO1 - DO5 = $\mathrm{V}_{\text {OL }}$; Rx1 - Rx5) | $\begin{aligned} & \hline 3.3 \mathrm{~V} \\ & 5.0 \mathrm{~V} \end{aligned}$ | $\mathrm{V}_{\text {on }}$ | $\begin{aligned} & 1.35 \\ & 2.00 \end{aligned}$ | $\begin{aligned} & \hline 1.8 \\ & 2.5 \end{aligned}$ | $\begin{aligned} & 2.35 \\ & 3.10 \end{aligned}$ | V |
| Input Turn-Off Threshold ( $\left.\mathrm{V}_{\mathrm{DO} 1-\mathrm{DO5}}=\mathrm{V}_{\mathrm{OH}} ; \mathrm{Rx} 1-\mathrm{Rx} 5\right)$ | $\begin{aligned} & 3.3 \mathrm{~V} \\ & 5.0 \mathrm{~V} \end{aligned}$ | $\mathrm{V}_{\text {off }}$ | $\begin{aligned} & 0.75 \\ & 1.20 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.5 \end{aligned}$ | $\begin{aligned} & 1.25 \\ & 1.80 \end{aligned}$ | V |
| Input Resistance |  | $\mathrm{R}_{\text {in }}$ | 3 | 5.4 | 7 | $\mathrm{k} \Omega$ |
| High-Level Output Voltage (DO1 - DO5) $\mathrm{V}_{\mathrm{Rx} 1}-\mathrm{Rx} 5=-3$ to -25 V | $\begin{aligned} & \mathrm{I}_{\text {out }}=-20 \mu \mathrm{~A} \\ & \mathrm{I}_{\text {out }}=-1 \mathrm{~mA} \end{aligned}$ | $\mathrm{V}_{\mathrm{OH}}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{CC}}-0.1 \\ & \mathrm{~V}_{\mathrm{CC}}-0.6 \end{aligned}$ | 2.7 |  | V |
| Low-Level Output Voltage (DO1 - DO5) $V_{R x 1}-R \times 5=+3 \text { to }+25 V$ | $\begin{array}{r} \mathrm{I}_{\text {out }}=+20 \mu \mathrm{~A} \\ \mathrm{I}_{\text {out }}=+1.6 \mathrm{~mA} \end{array}$ | V OL |  | $\begin{gathered} 0.01 \\ 0.5 \end{gathered}$ | $\begin{aligned} & \hline 0.1 \\ & 0.7 \end{aligned}$ | V |
| Ring Monitor Circuit (Input Threshold) |  | $\mathrm{V}_{\text {TH }}$ | - | 1.1 | - | V |
| High-Level Output Voltage (RIMON) | $\begin{aligned} & \mathrm{I}_{\text {out }}=-20 \mu \mathrm{~A} \\ & \mathrm{I}_{\text {out }}=-1 \mathrm{~mA} \end{aligned}$ | $\mathrm{V}_{\mathrm{OH}}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{CC}}-0.1 \\ & \mathrm{~V}_{\mathrm{CC}}-0.6 \end{aligned}$ | $\overline{2.7}$ | - | V |
| Low-Level Output Voltage (RIMON) | $\begin{array}{r} \mathrm{I}_{\text {out }}=+20 \mu \mathrm{~A} \\ \mathrm{I}_{\text {out }}=+1.6 \mathrm{~mA} \end{array}$ | V OL | - | $\begin{gathered} 0.01 \\ 0.5 \end{gathered}$ | $\begin{aligned} & 0.1 \\ & 0.7 \end{aligned}$ | V |

## DRIVER ELECTRICAL SPECIFICATIONS

(Voltage polarities referenced to GND $=0 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}$ or $+5.0 \mathrm{~V} \pm 10 \%$; $\mathrm{C} 1-\mathrm{C} 5=1 \mu \mathrm{~F} ; \mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ )

| Parameter | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Digital Input Voltage <br> Logic Low <br> Logic High | $\begin{aligned} & \mathrm{V}_{\mathrm{IL}} \\ & \mathrm{~V}_{\mathrm{IH}} \end{aligned}$ |  |  |  | V |
| Digital Input Current DI1 - DI3 <br> $V_{\text {DI }}=$ GND  <br> $V_{D I}=V_{C C}$  <br> Digital Input Current <br> DI1 - DI3 $0$ $\mathrm{V}_{\mathrm{DI}}=\mathrm{V}_{\mathrm{CC}}$ | $\begin{aligned} & \mathrm{I}_{\mathrm{IL}} \\ & \mathrm{I}_{\mathrm{IH}} \end{aligned}$ |  |  | $\pm \overline{1.0}$ | $\mu \mathrm{A}$ |
| Output High Voltage <br> Load on All Tx1 - Tx3, RL=3k』; CP = 2500 pF, $\mathrm{V}_{\mathrm{DI} 11}-\mathrm{DI} 3=$ Logic Low No Load | $\mathrm{V}_{\mathrm{OH}}$ | $\begin{aligned} & 5.0 \\ & 8.5 \end{aligned}$ | $\begin{aligned} & 7.0 \\ & 8.8 \end{aligned}$ | - | V |
| Output Low Voltage Load on All Tx1 - Tx3, RL=3 k $; \mathrm{C}_{\mathrm{P}}=2500 \mathrm{pF}, \mathrm{V}_{\mathrm{DI} 11}-\mathrm{DI} 3=$ Logic High No Load | V OL |  | $\begin{aligned} & -7.0 \\ & -8.8 \end{aligned}$ | $\begin{aligned} & -5.0 \\ & -8.5 \end{aligned}$ | V |
| Ripple (Refer to $\mathrm{V}_{\text {DD }}-\mathrm{V}_{\text {SS }}$ Value) ${ }^{* * *}$ | $\mathrm{V}_{\text {RF }}$ | - | - | $\pm 5 \%$ |  |
| Off Source Impedance ${ }^{\text {Tx1 - Tx3 }}$ | $\mathrm{Z}_{\text {off }}$ | 300 | - | - | $\Omega$ |
| Output Short Circuit Current ( $\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}$ or 5.5 V ) <br> Tx1 - Tx3 Shorted to GND* <br> Tx1 - Tx3 Shorted to $\pm 15 \mathrm{~V}^{* *}$ | ISC | - | - | $\begin{gathered} \pm 60 \\ \pm 100 \\ \hline \end{gathered}$ | mA |

*Specification is for one Tx output to be shorted at a time. Should all three driver outputs be shorted simultaneously, device power dissipation limits could be exceeded.
** This condition could exceed package limitations.
${ }^{* * *}$ Ripple $V_{\text {RF }}$ would not exceed $\pm 5 \%$ of ( $V_{D D}-V_{S S}$ ).
SWITCHING CHARACTERISTICS ( $\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}$ or $\left.+5 \mathrm{~V}, \pm 10 \% ; \mathrm{C} 1-\mathrm{C} 5=1 \mu \mathrm{~F} ; \mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$

| Parameter |  | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Drivers |  |  |  |  |  |  |
| $\begin{aligned} & \text { Propagation Delay Time } \\ & \text { Low-to-High } \\ & \quad\left(R_{L}=3 \mathrm{k} \Omega, C_{L}=50 \mathrm{pF} \text { or } 2500 \mathrm{pF}\right) \end{aligned}$ | Tx1-Tx3 | ${ }^{\text {t }}$ DPLH | - | 0.5 | 1 | $\mu \mathrm{s}$ |
| $\begin{aligned} & \text { High-to-Low } \\ & \qquad\left(R_{L}=3 \mathrm{k} \Omega, C_{L}=50 \mathrm{pF} \text { or } 2500 \mathrm{pF}\right) \end{aligned}$ |  | ${ }^{\text {t }}$ DPHL | - | 0.5 | 1 |  |
| Output Slew Rate (Source R=300 $\Omega$ ) Loading: $R_{L}=3-7 \mathrm{k} \Omega ; \mathrm{C}_{\mathrm{L}}=2500 \mathrm{pF}$ | Tx1-Tx3 | SR | $\pm 4$ | - | $\pm 30$ | V/us |
| Output Disable Time* |  | tDAZ | - | 4 | 10 | $\mu \mathrm{s}$ |
| Output Enable Time* |  | tDZA | - | 25 | 50 | ms |

## Receivers

| Propagation Delay Time Low-to-High | DO1 - DO5 | $t_{\text {RPLH }}$ | - | - | 1 | $\mu \mathrm{s}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| High-to-Low |  | $\mathrm{t}_{\mathrm{RPHL}}$ | - | - | 1 |  |
| Output Rise Time | DO1 - DO5 | $\mathrm{t}_{\mathrm{r}}$ | - | 120 | 200 | ns |
| Output Fall Time | DO1 - DO5 | $\mathrm{t}_{\mathrm{f}}$ | - | 40 | 100 | ns |
| Output Disable Time* |  | traz | - | 4 | 10 | $\mu \mathrm{s}$ |
| Output Enable Time* |  | trZA | - | 25 | 50 | ms |

* Including the charge pump setup time.


## TRUTH TABLES

Drivers

| DI | STB | Tx |
| :---: | :---: | :---: |
| $X$ | $H$ | $Z^{*}$ |
| $H$ | L | L |
| L | L | H |

${ }^{*} \mathrm{~V}_{\mathrm{SS}} \leq \mathrm{V}_{\mathrm{Tx}} \leq \mathrm{V}_{\mathrm{DD}} \quad \mathrm{X}=$ Don't Care

## Receivers

| Rx STB DO <br> X H $\mathrm{Z}^{*}$ <br> H L L <br> L L H |
| :--- |
| * GND $\leq \mathrm{V}_{\mathrm{DO}} \leq \mathrm{V}_{\mathrm{CC}}$ |

## PIN DESCRIPTIONS

## VCC

Digital Power Supply (Pin 27)
This digital supply pin is connected to the logic power supply. This pin should have a not less than $0.33 \mu \mathrm{~F}$ capacitor GND.

## GND

## Ground (Pin 2)

Ground return pin is typically connected to the signal ground pin of the EIA-232-E connector (Pin 7) as well as to the logic power supply ground.

## VDD

## Positive Power Supply (Pin 23)

This is the positive output of the on-chip voltage tripler and the positive power supply input of the driver/receiver sections of the device. This pin requires an external storage capacitor to filter the $50 \%$ duty cycle voltage generated by the charge pump.

## VSS

## Negative Power Supply (Pin 5)

This is the negative output of the on-chip voltage tripler/inverter and the negative power supply input of the driver/ receiver sections of the device. This pin requires an external storage capacitor to filter the $50 \%$ duty cycle voltage generated by the charge pump.

## RIMON

## Ring Monitor Circuit (Pin 4)

The Ring Monitor Circuit will convert the input level on Rx1 pin at standby mode and output on the RIMON pin.

## STB

## Standby Mode (Pin 6)

The device enters the standby mode while this pin is connected to
the logic high level. During the standby mode, driver and receiver output pins become high-impedance state. In this condition, supply current ICC is below $5 \mu \mathrm{~A}$ (typ).

C5+, C5-, C2+, C2-, C1+, C1-
Voltage Tripler and Inverter (Pins 1, 3, 28, 26, 25, 24)
These are the connections to the internal voltage tripler and inverter, which generate the VDD and VSS voltages.

## Rx1, Rx2, Rx3, Rx4, Rx5 <br> Receive Data Inputs (Pins 7, 8, 9, 11, 13)

These are the EIA-232-E receive signal inputs. A voltage between +3 and +25 V is decoded as a space, and causes the corresponding DO pin to swing to GND $(0 \mathrm{~V})$. A voltage between -3 and -25 V is decoded as a mark, and causes the DO pin to swing up to $\mathrm{V}_{\mathrm{CC}}$.

## D01, DO2, D03, DO4, DO5

Data Outputs (Pins 22, 21, 20, 18, 16)
These are the receiver digital output pins, which swing from $\mathrm{VCC}_{\mathrm{C}}$ to GND. Output level of these pins is high impedance while in standby mode.

## DI1, DI2, DI3

Data Inputs (Pins 19, 17, 15)
These are the high impedance digital input pins to the drivers. Input voltage levels on these pins must be betweenVCC and GND.

## Tx1, Tx2, Tx3 <br> Transmit Data Output (Pins 10, 12, 14)

These are the EIA-232-E transmit signal output pins, which swing toward VDD and VSS. A logic 1 at a DI input causes the corresponding Tx output to swing toward VSS. The actual levels and slew rate achieved will depend on the output loading (RL/CL). The minimum output impedance is $300 \Omega$ when turned off.

## SWITCHING CHARACTERISTICS



## DRIVER



RECEIVER


RECEIVER


## ESD PROTECTION

ESD protection on IC devices that have their pins accessible to the outside world is essential. High static voltages applied to the pins when someone touches them either directly or indirectly can cause damage to gate oxides and transistor junctions by coupling a portion of the energy from the I/O pin to the power supply buses of the IC. This coupling will usually occur
through the internal ESD protection diodes which are designed to do just that. The key to protecting the IC is to shunt as much of the energy to ground as possible before it enters the IC. Figure 1 shows a technique which will clamp the ESD voltage at approximately $\pm 15 \mathrm{~V}$ using the MMBZ15VDLT1. Any residual voltage which appears on the supply pins is shunted to ground through the capacitors C1and C2.


Figure 1. ESD Protection Scheme

## OUTLINE DIMENSIONS

SOIC 28W = -7P
(ML145583-7P)
SOG PACKAGE
CASE 751F-04


NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER
3. DIMENSION A AND B DO NOT INCLUDE MOLD

PROTRUSION
4. MAXIMUM MOLD PROTRUSION 0.15 MAXIMUM MOLD
(0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 (0.005) TOTAL IN EXCESS OF D DIMENSION AT MAXIMUM MATERIAL CONDITION.

| DIM | MILLIMETERS |  | INCHES |  |
| :---: | :---: | :---: | :---: | :---: |
|  | MIN | MAX | MIN | MAX |
| A | 17.80 | 18.05 | 0.701 | 0.711 |
| B | 7.40 | 7.60 | 0.292 | 0.299 |
| C | 2.35 | 2.65 | 0.093 | 0.104 |
| D | 0.35 | 0.49 | 0.014 | 0.019 |
| F | 0.41 | 0.90 | 0.016 | 0.035 |
| G | 1.27 | SC | 0.050 |  |
| J | 0.23 | 0.32 | 0.009 | 0.013 |
| K | 0.13 | 0.29 | 0.005 | 0.011 |
| M | $0^{\circ}$ | $8^{\circ}$ | $0^{\circ}$ | $8^{\circ}$ |
| P | 10.05 | 10.55 | 0.395 | 0.415 |
| R | 0.25 | 0.75 | 0.010 | 0.029 |

Lansdale Semiconductor reserves the right to make changes without further notice to any products herein to improve reliability, function or design. Lansdale does not assume any liability arising out of the application or use of any product or circuit described herein; neither does it convey any license under its patent rights nor the rights of others. "Typical" parameters which may be provided in Lansdale data sheets and/or specifications can vary in different applications, and actual performance may vary over time. All operating parameters, including "Typicals" must be validated for each customer application by the customer's technical experts. Lansdale Semiconductor is a registered trademark of Lansdale Semiconductor, Inc.

