32Mb LW R-R HSTL High Speed Synchronous SRAM (1Mb x 36)

**Preliminary** 

## **Description**

The CXK77K36R320GB is a high speed CMOS synchronous static RAM with common I/O pins, organized as 1,048,576 words by 36 bits. This synchronous SRAM integrates input registers, high speed RAM, output registers, and a one-deep write buffer onto a single monolithic IC. Register - Register (R-R) read operations and Late Write (LW) write operations are supported, providing a high-performance user interface.

All address and control input signals except  $\overline{G}$  (Output Enable) and ZZ (Sleep Mode) are registered on the rising edge of the K differential input clock.

During read operations, output data is driven valid from the rising edge of K, one full clock cycle after the address is registered.

During write operations, input data is registered on the rising edge of K, one full clock cycle after the address is registered.

Sleep (power down) capability is provided via the ZZ input signal.

Output drivers are series terminated, and output impedance is programmable via the ZQ input pin. By connecting an external control resistor RQ between ZQ and  $V_{SS}$ , the impedance of the output drivers can be precisely controlled.

333 MHz operation is obtained from a single 2.5V power supply. JTAG boundary scan interface is provided using a subset of IEEE standard 1149.1 protocol.

#### **Features**

•	3 Speed Bins	Cycle Time / Access Time
	-3	3.0ns / 1.6ns
	-33	3.3ns / 1.6ns
	-4	4.0ns / 2.0ns

• Single 2.5V power supply ( $V_{DD}$ ): 2.5V  $\pm$  5%

 ${f Note}$ : 1.8V  ${f V}_{DD}$  is also supported. Please contact Sony Memory Marketing Department for further information.

• Dedicated output supply voltage ( $V_{DDO}$ ): 1.5V  $\pm$  0.1V

Note: 1.8V V<sub>DDO</sub> is also supported. Please contact Sony Memory Marketing Department for further information.

- HSTL-compatible I/O interface with dedicated input reference voltage (V<sub>RFF</sub>): 0.75V typical
- Register Register (R-R) read protocol
- Late Write (LW) write protocol
- Full read/write coherency
- Byte Write capability
- Differential input clocks  $(K/\overline{K})$
- Asynchronous output enable (<del>G</del>)
- Sleep (power down) mode via dedicated mode pin (ZZ)
- Programmable output driver impedance
- JTAG boundary scan (subset of IEEE standard 1149.1)
- 119 pin (7x17), 1.27mm pitch, 14mm x 22mm Ball Grid Array (BGA) package

# 1Mb x 36 Pin Assignment (Top View)

	1	2	3	4	5	6	7
A	V <sub>DDQ</sub>	SA	SA	NC	SA	SA	$V_{\mathrm{DDQ}}$
В	NC	SA	SA	SA (32M)	SA	SA	NC
C	NC	SA	SA	$V_{\mathrm{DD}}$	SA	SA	NC
D	DQc	DQc	V <sub>SS</sub>	ZQ	V <sub>SS</sub>	DQb	DQb
E	DQc	DQc	$V_{SS}$	SS	$V_{SS}$	DQb	DQb
F	V <sub>DDQ</sub>	DQc	$V_{SS}$	$\overline{G}$	$V_{SS}$	DQb	$V_{\mathrm{DDQ}}$
G	DQc	DQc	SBWc	NC	SBWb	DQb	DQb
Н	DQc	DQc	$V_{SS}$	NC	$V_{SS}$	DQb	DQb
J	V <sub>DDQ</sub>	$V_{DD}$	$V_{REF}$	$V_{DD}$	$V_{REF}$	$V_{DD}$	$V_{\mathrm{DDQ}}$
K	DQd	DQd	$V_{SS}$	K	$V_{SS}$	DQa	DQa
L	DQd	DQd	SBWd	K	SBWa	DQa	DQa
M	V <sub>DDQ</sub>	DQd	$V_{SS}$	SW	$V_{SS}$	DQa	$V_{\mathrm{DDQ}}$
N	DQd	DQd	$V_{SS}$	SA	$V_{SS}$	DQa	DQa
P	DQd	DQd	$V_{SS}$	SA	$V_{SS}$	DQa	DQa
R	NC	SA	M1 <sup>(1)</sup>	$V_{DD}$	M2 <sup>(2)</sup>	SA	NC
T	NC	NC (x18)	SA	SA (x36)	SA	NC (x18)	ZZ
U	V <sub>DDQ</sub>	TMS	TDI	TCK	TDO	RSVD (3)	V <sub>DDQ</sub>

#### **Notes**:

- 1. Pad Location 3R is defined as an M1 mode pin in LW SRAMs. However, it must be tied "low" in this device.
- 2. Pad Location 5R is defined as an M2 mode pin in LW SRAMs. However, it must be tied "high" in this device.
- 3. Pad Location 6U must be left unconnected. It is used by Sony for internal test purposes.

# **Pin Description**

Symbol	Type	Description
SA	Input	Synchronous Address Inputs - Registered on the rising edge of K.
DQa, DQb DQc, DQd	I/O	Synchronous Data Inputs / Outputs - Registered on the rising edge of K during write operations.  Driven from the rising edge of K during read operations.  DQa - indicates Data Byte a  DQb - indicates Data Byte b  DQc - indicates Data Byte c  DQd - indicates Data Byte d
$K, \overline{K}$	Input	Differential Input Clocks
SS	Input	
SW	Input	
SBWa, SBWb SBWc, SBWd	Input	
G	Input	Asynchronous Output Enable Input - Deasserted (high) disables the data output drivers.
ZZ	Input	Asynchronous Sleep Mode Input - Asserted (high) forces the device into low-power mode.
M1, M2	Input	Read Operation Protocol Select - These mode pins must be tied "low" and "high" respectively to select Register - Register read operations.
ZQ	Input	Output Driver Impedance Control Resistor Input - This pin must be connected to V <sub>SS</sub> through an external resistor RQ to program data output driver impedance. See the Programmable Output Driver Impedance section for further information.
V <sub>DD</sub>		2.5V Core Power Supply - Core supply voltage.
V <sub>DDQ</sub>		Output Power Supply - Output buffer supply voltage.
V <sub>REF</sub>		Input Reference Voltage - Input buffer threshold voltage.
V <sub>SS</sub>		Ground
TCK	Input	JTAG Clock
TMS	Input	JTAG Mode Select - Weakly pulled "high" internally.
TDI	Input	JTAG Data In - Weakly pulled "high" internally.
TDO	Output	JTAG Data Out
RSVD		Reserved - This pin is reserved for Sony test purposes. It must be left unconnected.
NC		No Connect - These pins are true no-connects, i.e. there is no internal chip connection to these pins. They can be left unconnected or tied directly to $V_{DD}$ , $V_{DDQ}$ , or $V_{SS}$ .

### •Clock Truth Table

K	ZZ	$\overline{SS}$ $(t_n)$	$\overline{SW}$ $(t_n)$	$\overline{SBW}x$ $(t_n)$	G	Operation	DQ (t <sub>n</sub> )	DQ (t <sub>n+1</sub> )
X	1	X	X	X	X	Sleep (Power Down) Mode	Hi - Z	Hi - Z
1	0	1	X	X	X	Deselect	***	Hi - Z
$\uparrow$	0	0	1	X	1	Read	Hi - Z	Hi - Z
$\uparrow$	0	0	1	X	0	Read	***	Q(t <sub>n</sub> )
1	0	0	0	0	X	Write All Bytes	***	D(t <sub>n</sub> )
$\uparrow$	0	0	0	X	X	Write Bytes With $\overline{SBW}x = 0$	***	D(t <sub>n</sub> )
$\uparrow$	0	0	0	1	X	Abort Write	***	Hi - Z

#### **Notes:**

- 1. "1" = input "high"; "0" = input "low"; "X" = input "don't care".
- 2. "\*\*\*" indicates that the input requirement or output state is determined by the previous operation.
- 3. DQs are tri-stated in response to Write and Deselect commands, one cycle after the command is sampled.

## •Sleep (Power Down) Mode

Sleep (power down) mode is provided through the asynchronous input signal ZZ. When ZZ is asserted (high), the output drivers are disabled and the SRAM begins to draw standby current. Contents of the memory array are preserved. An enable time ( $t_{ZZE}$ ) must be met before the SRAM is guaranteed to be in sleep mode, and a recovery time ( $t_{ZZR}$ ) must be met before the SRAM can resume normal operation.

## •Programmable Impedance Output Drivers

These devices have programmable impedance output drivers. The output impedance is controlled by an external resistor RQ connected between the SRAM's ZQ pin and  $V_{SS}$ , and is equal to one-fifth the value of this resistor, nominally. See the DC Electrical Characteristics section for further information.

#### **Output Driver Impedance Power-Up Requirements**

Output driver impedance will reach the programmed value within 8192 cycles after power-up. Consequently, it is recommended that Read operations not be initiated until after the initial 8192 cycles have elapsed.

#### **Output Driver Impedance Updates**

Output driver impedance is updated during Write and Deselect operations when the output driver is disabled.

# Power-Up Sequence

For reliability purposes, Sony recommends that power supplies power up in the following sequence:  $V_{SS}$ ,  $V_{DD}$ ,  $V_{DDQ}$ ,  $V_{REF}$ , and Inputs.  $V_{DDQ}$  should never exceed  $V_{DD}$ . If this power supply sequence cannot be met, a large bypass diode may be required between  $V_{DD}$  and  $V_{DDQ}$ . Please contact Sony Memory Application Department for further information.

# •Absolute Maximum Ratings

Parameter	Symbol	Rating	Units
Supply Voltage	$V_{DD}$	-0.5 to +3.2	V
Output Supply Voltage	V <sub>DDQ</sub>	-0.5 to +2.3	V
Input Voltage (Address, Control, Data, Clock)	V <sub>IN</sub>	-0.5 to V <sub>DDQ</sub> + 0.5 (2.3V max)	V
Input Voltage (M1, M2)	V <sub>MIN</sub>	$-0.5 \text{ to V}_{DD} + 0.5 (3.2 \text{V max})$	V
Input Voltage (TCK, TMS, TDI)	V <sub>TIN</sub>	-0.5 to +3.8V	V
Operating Temperature	T <sub>A</sub>	0 to 85	°C
Junction Temperature	$T_{J}$	0 to 110	°C
Storage Temperature	T <sub>STG</sub>	-55 to 150	°C

**Notes**: Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions other than those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

# •BGA Package Thermal Characteristics

Parameter	Symbol	Rating	Units
Junction to Case Temperature	$\Theta_{ m JC}$	3.6	°C/W

# •I/O Capacitance

$$(T_A = 25^{\circ}C, f = 1 \text{ MHz})$$

Parameter		Symbol Test conditions		Min	Max	Units
	Address	$C_{IN}$	$V_{IN} = 0V$		4.0	pF
Input Capacitance	Control	$C_{IN}$	$V_{IN} = 0V$		4.0	pF
	Clock	C <sub>KIN</sub>	$V_{KIN} = 0V$		4.5	pF
Output Capacitance	Data	$C_{OUT}$	$V_{OUT} = 0V$		5.0	pF

Note: These parameters are sampled and are not 100% tested.

# **•**DC Recommended Operating Conditions

 $(V_{SS} = 0V, T_A = 0 \text{ to } 85^{\circ}C)$ 

Parameter	Symbol	Min	Тур	Max	Units	Notes
Supply Voltage	$V_{DD}$	2.37	2.5	2.63	V	1
Output Supply Voltage	V <sub>DDQ</sub>	1.4	1.5	1.6	V	2
Input Reference Voltage	V <sub>REF</sub>	V <sub>DDQ</sub> /2 - 0.1	V <sub>DDQ</sub> /2	$V_{DDQ}/2 + 0.1$	V	3
Input High Voltage (Address, Control, Data)	V <sub>IH</sub>	V <sub>REF</sub> + 0.1		$V_{DDQ} + 0.3$	V	4
Input Low Voltage (Address, Control, Data)	$V_{\rm IL}$	-0.3		V <sub>REF</sub> - 0.1	V	5
Input High Voltage (M1, M2)	$V_{MIH}$	$V_{REF} + 0.3$		$V_{DD} + 0.3$	V	
Input Low Voltage (M1, M2)	$V_{ m MIL}$	-0.3		V <sub>REF</sub> - 0.3	V	
Clock Input Signal Voltage	V <sub>KIN</sub>	-0.3		$V_{DDQ} + 0.3$	V	
Clock Input Differential Voltage	V <sub>DIF</sub>	0.2		$V_{\rm DDQ} + 0.6$	V	
Clock Input Common Mode Voltage	$V_{CM}$	V <sub>DDQ</sub> /2 - 0.1	$V_{\rm DDQ}/2$	$V_{DDQ}/2 + 0.1$	V	

<sup>1.</sup>  $V_{DD}$  = 1.8V  $\pm$  0.1V is also supported. Please contact Sony Memory Marketing Department for further information.

<sup>2.</sup>  $V_{DDO}$  = 1.8V  $\pm$  0.1V is also supported. Please contact Sony Memory Marketing Department for further information.

<sup>3.</sup> The peak-to-peak AC component superimposed on  $V_{\mbox{\scriptsize REF}}$  may not exceed 5% of the DC component.

<sup>4.</sup>  $V_{IH}$  (max)  $AC = V_{DDQ} + 0.75V$  for pulse widths less than one-quarter of the cycle time ( $t_{CYC}/4$ ).

<sup>5.</sup>  $V_{IL}$  (min) AC = -0.75V for pulse widths less than one-quarter of the cycle time ( $t_{CYC}$ /4).

# •DC Electrical Characteristics

$$(V_{DD} = 2.5V \pm 5\%, V_{SS} = 0V, T_A = 0 \text{ to } 85^{\circ}\text{C})$$

Parameter	Symbol	Test Conditions	Min	Тур	Max	Units	Notes
Input Leakage Current (Address, Control, Clock)	$I_{LI}$	$V_{IN} = V_{SS}$ to $V_{DDQ}$	-5		5	uA	
Input Leakage Current (M1, M2)	I <sub>MLI</sub>	$V_{MIN} = V_{SS}$ to $V_{DD}$	-5		5	uA	
Output Leakage Current	$I_{LO}$	$\begin{aligned} &V_{OUT} = V_{SS} \text{ to } V_{DDQ} \\ &\overline{G} = V_{IH} \end{aligned}$	-5		5	uA	
Average Power Supply Operating Current	$I_{\mathrm{DD-3}} \\ I_{\mathrm{DD-33}} \\ I_{\mathrm{DD-4}}$	$I_{OUT} = 0 \text{ mA}$ $\overline{SS} = V_{IL}, ZZ = V_{IL}$		 	650 600 540	mA	
Power Supply Standby Current	$I_{SB}$	$I_{OUT} = 0 \text{ mA}$ $ZZ = V_{IH}$			180	mA	1
Output High Voltage	V <sub>OH</sub>	$I_{OH} = -6.0 \text{ mA}$ $RQ = 250\Omega$	V <sub>DDQ</sub> - 0.4			V	
Output Low Voltage	V <sub>OL</sub>	$I_{OL} = 6.0 \text{ mA}$ $RQ = 250\Omega$			0.4	V	
		$V_{OH}$ , $V_{OL} = V_{DDQ}/2$ $RQ < 150\Omega$			35 (30*1.15)	Ω	2
Output Driver Impedance	R <sub>OUT</sub>	$V_{OH}$ , $V_{OL} = V_{DDQ}/2$ $150\Omega \le RQ \le 300\Omega$	(RQ/5)* 0.85	RQ/5	(RQ/5)* 1.15	Ω	
		$V_{OH}$ , $V_{OL} = V_{DDQ}/2$ $RQ > 300\Omega$	51 (60*0.85)			Ω	3

<sup>1.</sup> This parameter is guaranteed at  $T_A = 0$  to  $55^{\circ}$ C.

<sup>2.</sup> For maximum output drive (i.e. minimum impedance), the ZQ pin can be tied directly to  $V_{SS}$ .

<sup>3.</sup> For minimum output drive (i.e. maximum impedance), the ZQ pin can be left unconnected or tied to  $V_{DDO}$ .

# •AC Electrical Characteristics

$$(V_{DD} = 2.5V \pm 5\%, V_{SS} = 0V, T_A = 0 \text{ to } 85^{\circ}\text{C})$$

Parameter	Symbol	-	3	-3	33	-	4	Units	Notes
rarameter	Symbol	Min	Max	Min	Max	Min	Max	Units	Notes
Input Cycle Time	t <sub>KHKH</sub>	3.0		3.3		4.0		ns	
Input Clock High Pulse Width	t <sub>KHKL</sub>	1.2		1.3		1.5		ns	
Input Clock Low Pulse Width	t <sub>KLKH</sub>	1.2		1.3		1.5		ns	
Address Input Setup Time	t <sub>AVKH</sub>	0.3		0.3		0.3		ns	1
Address Input Hold Time	t <sub>KHAX</sub>	0.5		0.6		0.7		ns	
Write Enable Input Setup Time	t <sub>WVKH</sub>	0.3		0.3		0.3		ns	1
Write Enable Input Hold Time	t <sub>KHWX</sub>	0.5		0.6		0.7		ns	
Sync Select Input Setup Time	t <sub>SVKH</sub>	0.3		0.3		0.3		ns	1
Sync Select Input Hold Time	t <sub>KHSX</sub>	0.5		0.6		0.7		ns	
Data Input Setup Time	t <sub>DVKH</sub>	0.3		0.3		0.3		ns	1
Data Input Hold Time	t <sub>KHDX</sub>	0.5		0.6		0.7		ns	
Input Clock High to Output Data Valid	t <sub>KHQV</sub>		1.6		1.6		2.0	ns	
Input Clock High to Output Data Hold	t <sub>KHQX</sub>	0.65		0.65		0.65		ns	2
Input Clock High to Output Data Low-Z	t <sub>KHQX1</sub>	0.65		0.65		0.65		ns	2,3
Input Clock High to Output Data High-Z	t <sub>KHQZ</sub>	0.65	1.8	0.65	1.8	0.65	2.2	ns	2,3
Output Enable Low to Output Data Valid	t <sub>GLQV</sub>		2.5		2.5	-	2.5	ns	
Output Enable Low to Output Data Low-Z	t <sub>GLQX</sub>	0.3		0.3		0.3		ns	2,3
Output Enable High to Output Data High-Z	t <sub>GHQZ</sub>		2.5		2.5		2.5	ns	2,3
Sleep Mode Enable Time	t <sub>ZZE</sub>		15		15		15	ns	2
Sleep Mode Recovery Time	t <sub>ZZR</sub>	20		20		20		ns	2

<sup>1.</sup> These parameters are measured from  $V_{REF}\pm 200 \text{mV}$  to the clock mid-point.

<sup>2.</sup> These parameters are guaranteed by design through extensive corner-lot characterization.

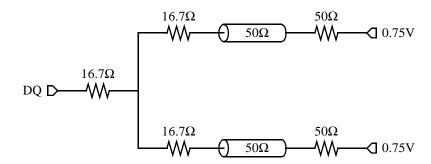
<sup>3.</sup> These parameters are measured at  $\pm\,50\text{mV}$  from steady state voltage.

# •AC Test Conditions

$$(V_{DD}$$
 = 2.5V  $\pm$  5%,  $V_{DDQ}$  = 1.5V  $\pm$  0.1V,  $T_A$  = 0 to 85°C)

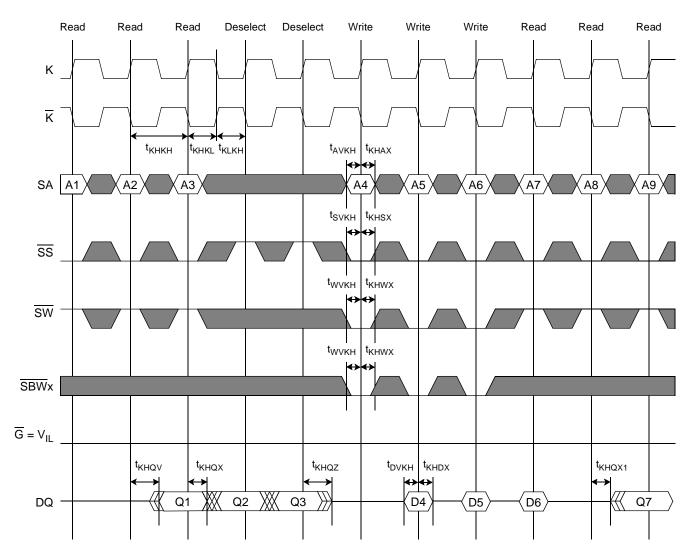
Item	Symbol	Conditions	Units	Notes
Input Reference Voltage	V <sub>REF</sub>	0.75	V	
Input High Level	V <sub>IH</sub>	1.25	V	
Input Low Level	V <sub>IL</sub>	0.25	V	
Input Rise & Fall Time		2.0	V/ns	
Input Reference Level		0.75	V	
Clock Input High Voltage	V <sub>KIH</sub>	1.25	V	$V_{\rm DIF} = 1.0V$
Clock Input Low Voltage	V <sub>KIL</sub>	0.25	V	$V_{\rm DIF} = 1.0 V$
Clock Input Common Mode Voltage	$V_{CM}$	0.75	V	
Clock Input Rise & Fall Time		2.0	V/ns	
Clock Input Reference Level		K/K cross	V	
Output Reference Level		0.75	V	
Output Load Conditions		$RQ = 250\Omega$		See Figure 1 below

Figure 1: AC Test Output Load



# $\label{eq:Read-Write-Read} \begin{array}{c} \textbf{Read-Write-Read Timing Diagram} \\ \textbf{Synchronously Controlled via SS and Deselect Operations } (\overline{G} = Low) \end{array}$

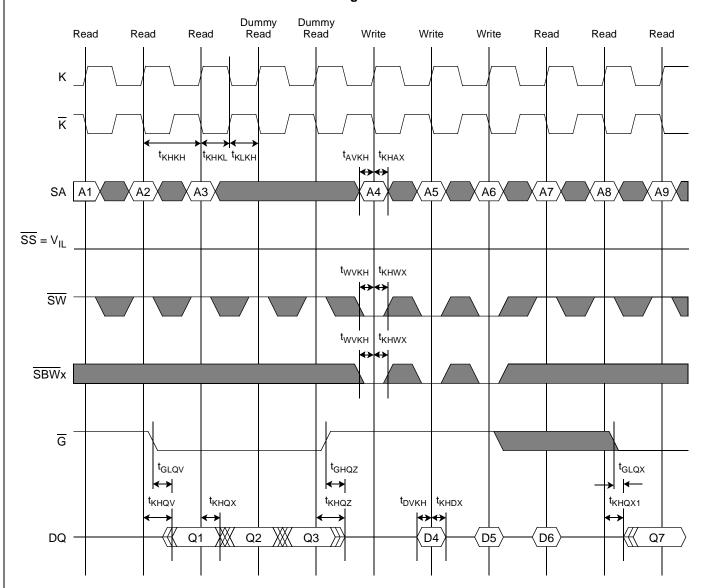
Figure 2



**Note**: In the diagram above, two Deselect operations are inserted between Read and Write operations to control the data bus transition from output to input. This depiction is for clarity purposes only. It is NOT a requirement. Depending on the application, one Deselect operation may be sufficient.

# 

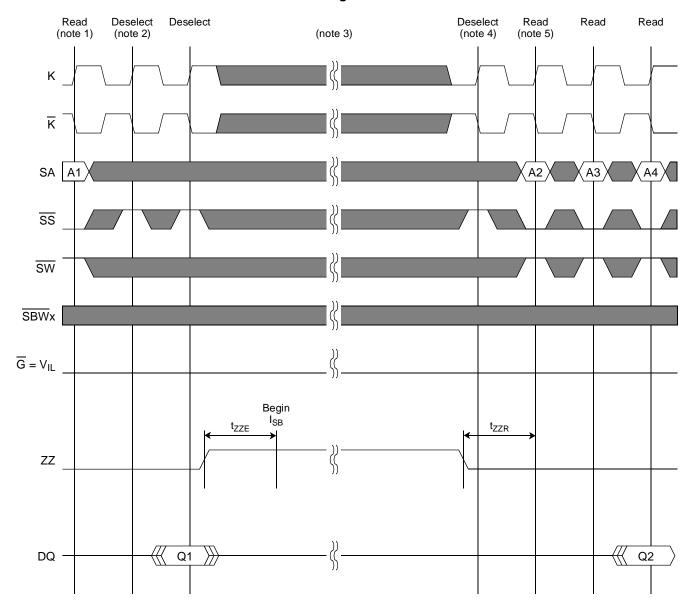
Figure 3



**Note**: In the diagram above, two Dummy Read operations are inserted between Read and Write operations to control the data bus transition from output to input. This depiction is for clarity purposes only. It is NOT a requirement. Depending on the application, one Dummy Read operation may be sufficient.

# Sleep (Power-Down) Mode Timing Diagram

#### Figure 4



#### Notes:

- 1: This can be any operation. The depiction of a Read operation here is provided only as an example.
- 2: Before ZZ is asserted, at least two (2) Deselect operations must be initiated after the last Read or Write operation is initiated, in order to ensure the successful completion of the last Read or Write operation.
- 3: While ZZ is asserted, all of the SRAM's address, control, data, and clock inputs are ignored.
- 4: After ZZ is deasserted, Deselect operations must be initiated until the specified recovery time (t<sub>ZZR</sub>) has been met. Read and Write operations may NOT be initiated during this time.
- 5: This can be any operation. The depiction of a Read operation here is provided only as an example.

## •Test Mode Description

These devices provide a JTAG Test Access Port (TAP) and Boundary Scan interface using a limited set of IEEE std. 1149.1 functions. This test mode is intended to provide a mechanism for testing the interconnect between master (processor, controller, etc.), SRAMs, other components, and the printed circuit board.

In conformance with a subset of IEEE std. 1149.1, these devices contain a TAP Controller and four TAP Registers. The TAP Registers consist of one Instruction Register and three Data Registers (ID, Bypass, and Boundary Scan Registers).

The TAP consists of the following four signals:

TCK: Test Clock Induces (clocks) TAP Controller state transitions.

TMS: Test Mode Select Inputs commands to the TAP Controller. Sampled on the rising edge of TCK.
 TDI: Test Data In Inputs data serially to the TAP Registers. Sampled on the rising edge of TCK.
 TDO: Test Data Out Outputs data serially from the TAP Registers. Driven from the falling edge of TCK.

## **Disabling the TAP**

When JTAG is not used, TCK should be tied "low" to prevent clocking the SRAM. TMS and TDI should either be tied "high" through a pull-up resistor or left unconnected. TDO should be left unconnected.

**Note**: Operation of the TAP does not interfere with normal SRAM operation except when the SAMPLE-Z instruction is selected. Consequently, TCK, TMS, and TDI can be controlled any number of ways without adversely affecting the functionality of the device.

# JTAG DC Recommended Operating Conditions

$$(V_{DD} = 2.5V \pm 5\%, V_{SS} = 0V, T_A = 0 \text{ to } 85^{\circ}C)$$

Parameter	Symbol	Test Conditions	Min	Max	Units
JTAG Input High Voltage	$V_{TIH}$		1.4	3.6	V
JTAG Input Low Voltage	V <sub>TIL</sub>		-0.3	0.8	V
JTAG Output High Voltage (CMOS)	$V_{TOH}$	$I_{TOH} = -100uA$	V <sub>DD</sub> - 0.1		V
JTAG Output Low Voltage (CMOS)	$V_{TOL}$	$I_{TOL} = 100uA$		0.1	V
JTAG Output High Voltage (TTL)	V <sub>TOH</sub>	$I_{TOH} = -8.0 \text{mA}$	V <sub>DD</sub> - 0.4		V
JTAG Output Low Voltage (TTL)	V <sub>TOL</sub>	$I_{TOL} = 8.0 \text{mA}$		0.4	V
JTAG Input Leakage Current	$I_{TLI}$	$V_{TIN} = V_{SS}$ to 3.3V	-10	10	uA

## **JTAG AC Test Conditions**

$$(V_{DD} = 2.5V \pm 5\%, V_{SS} = 0V, T_A = 0 \text{ to } 85^{\circ}C)$$

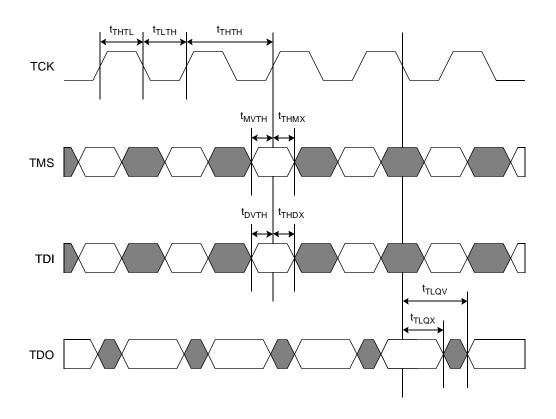
Parameter	Symbol	Conditions	Units	Notes
JTAG Input High Level	$V_{TIH}$	2.5	V	
JTAG Input Low Level	V <sub>TIL</sub>	0.0	V	
JTAG Input Rise & Fall Time		1.0	V/ns	
JTAG Input Reference Level		1.25	V	
JTAG Output Reference Level		1.25	V	
JTAG Output Load Condition				See Fig.1 (page 9)

# JTAG AC Electrical Characteristics

Parameter	Symbol	Min	Max	Unit
TCK Cycle Time	t <sub>THTH</sub>	50		ns
TCK High Pulse Width	t <sub>THTL</sub>	20		ns
TCK Low Pulse Width	t <sub>TLTH</sub>	20		ns
TMS Setup Time	t <sub>MVTH</sub>	5		ns
TMS Hold Time	t <sub>THMX</sub>	5		ns
TDI Setup Time	t <sub>DVTH</sub>	5		ns
TDI Hold Time	t <sub>THDX</sub>	5		ns
Capture Setup Time (Address, Control, Data, Clock)	t <sub>CS</sub>	5		ns
Capture Hold Time (Address, Control, Data, Clock)	t <sub>CH</sub>	5		ns
TCK Low to TDO Valid	t <sub>TLQV</sub>		10	ns
TCK Low to TDO Hold	t <sub>TLQX</sub>	0		ns

# **JTAG Timing Diagram**

Figure 5



## **TAP Controller**

The TAP Controller is a 16-state state machine that controls access to the various TAP Registers and executes the operations associated with each TAP Instruction. State transitions are controlled by TMS and occur on the rising edge of TCK.

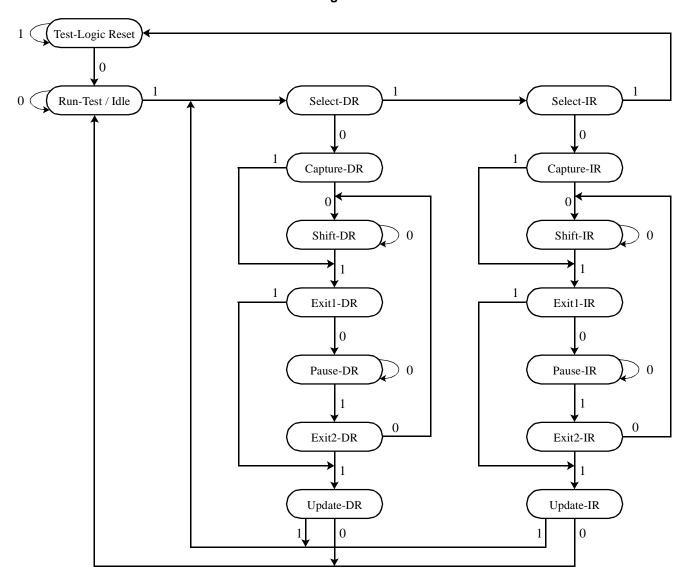
The TAP Controller enters the "Test-Logic Reset" state in one of two ways:

- 1. At power up.
- 2. When a logic "1" is applied to TMS for at least 5 consecutive rising edges of TCK.

The TDI input receiver is sampled only when the TAP Controller is in either the "Shift-IR" state or the "Shift-DR" state. The TDO output driver is active only when the TAP Controller is in either the "Shift-IR" state or the "Shift-DR" state.

## **TAP Controller State Diagram**

Figure 6



## **TAP Registers**

TAP Registers are serial shift registers that capture serial input data (from TDI) on the rising edge of TCK, and drive serial output data (to TDO) from the falling edge of TCK. They are divided into two groups: "Instruction Registers" (IR), which are manipulated via the "IR" states in the TAP Controller, and "Data Registers" (DR), which are manipulated via the "DR" states in the TAP Controller.

#### **Instruction Register (IR - 3 Bits)**

The Instruction Register stores the various TAP Instructions supported by these devices. It is loaded with the IDCODE instruction at power-up, and when the TAP Controller is in the "Test-Logic Reset" and "Capture-IR" states. It is inserted between TDI and TDO when the TAP Controller is in the "Shift-IR" state, at which time it can be loaded with a new instruction. However, newly loaded instructions are not executed until the TAP Controller has reached the "Update-IR" state.

The Instruction Register is 3 bits wide, and is encoded as follows:

Code (2:0)	Instruction	Description
000	BYPASS	See code "111".
001	IDCODE	Loads a predefined device- and manufacturer-specific identification code into the ID Register when the TAP Controller is in the "Capture-DR" state, and inserts the ID Register between TDI and TDO when the TAP Controller is in the "Shift-DR" state.  See the ID Register description for more information.
010	SAMPLE-Z	Loads the individual logic states of all signals composing the SRAM's I/O ring into the Boundary Scan Register when the TAP Controller is in the "Capture-DR" state, and inserts the Boundary Scan Register between TDI and TDO when the TAP Controller is in the "Shift-DR" state.
		Also disables the SRAM's data output drivers.
		See the Boundary Scan Register description for more information.
011	PRIVATE	Do not use. Reserved for manufacturer use only.
100	SAMPLE	Loads the individual logic states of all signals composing the SRAM's I/O ring into the Boundary Scan Register when the TAP Controller is in the "Capture-DR" state, and inserts the Boundary Scan Register between TDI and TDO when the TAP Controller is in the "Shift-DR" state.  See the Boundary Scan Register description for more information.
101	PRIVATE	Do not use. Reserved for manufacturer use only.
110	PRIVATE	Do not use. Reserved for manufacturer use only.
111	BYPASS	Loads a logic "0" into the Bypass Register when the TAP Controller is in the "Capture-DR" state, and inserts the Bypass Register between TDI and TDO when the TAP Controller is in the "Shift-DR" state.  See the Bypass Register description for more information.

Bit 0 is the LSB and Bit 2 is the MSB. When the Instruction Register is selected, TDI serially shifts data into the MSB, and the LSB serially shifts data out through TDO.

#### Bypass Register (DR - 1 Bit)

The Bypass Register is one bit wide, and provides the minimum length serial path between TDI and TDO. It is loaded with a logic "0" when the BYPASS instruction has been loaded in the Instruction Register and the TAP Controller is in the "Capture-DR" state. It is inserted between TDI and TDO when the BYPASS instruction has been loaded into the Instruction Register and the TAP Controller is in the "Shift-DR" state.

#### ID Register (DR - 32 Bits)

The ID Register is loaded with a predetermined device- and manufacturer-specific identification code when the IDCODE instruction has been loaded into the Instruction Register and the TAP Controller is in the "Capture-DR" state. It is inserted between TDI and TDO when the IDCODE instruction has been loaded into the Instruction Register and the TAP Controller is in the "Shift-DR" state.

The ID Register is 32 bits wide, and contains the following information:

Device	Revision Number (31:28)	Part Number (27:12)	Sony ID (11:1)	Start Bit (0)
1Mb x 36	xxxx	0000 0000 0111 0011	0000 1110 001	1

Bit 0 is the LSB and Bit 31 is the MSB. When the ID Register is selected, TDI serially shifts data into the MSB, and the LSB serially shifts data out through TDO.

#### **Boundary Scan Registers (DR - 70 Bits)**

The Boundary Scan Register is equal in length to the number of active signal connections to the SRAM (excluding the TAP pins) plus a number of place holder locations reserved for functional and/or density upgrades. It is loaded with the individual logic states of all signals composing the SRAM's I/O ring when the SAMPLE or SAMPLE-Z instruction has been loaded into the Instruction Register and the TAP Controller is in the "Capture-DR" state. It is inserted between TDI and TDO when the SAMPLE or SAMPLE-Z instruction has been loaded into the Instruction Register and the TAP Controller is in the "Shift-DR" state.

The Boundary Scan Register contains the following bits:

1Mb x 36					
DQ	36				
SA	20				
$K, \overline{K}$	2				
$\overline{SS}$ , $\overline{SW}$ , $\overline{SBW}$ x	6				
G, ZZ	2				
ZQ, M1, M2	3				
Place Holder	1				

**Note**: K and  $\overline{K}$  are connected to a differential input receiver that generates a single-ended input clock signal to the device. Therefore, in order to capture deterministic values for these signals in the Boundary Scan Register, they must be at opposite logic levels when sampled.

**Note**: When an external resistor RQ is connected between the ZQ pin and  $V_{SS}$ , the value of the ZQ signal captured in the Boundary Scan Register is non-deterministic.

**Note**: Place Holders are required for some NC pins to allow for future density and/or functional upgrades. They are connected to  $V_{SS}$  internally, regardless of pin connection externally.

## **Boundary Scan Register Bit Order Assignments**

The table below depicts the order in which the bits are arranged in the Boundary Scan Register. Bit 1 is the LSB and bit 70 is the MSB. When the Boundary Scan Register is selected, TDI serially shifts data into the MSB, and the LSB serially shifts data out through TDO.

1Mb x 36						
Bit	Signal	Pad	Bit	Signal	Pad	
1	M2	5R	36	SA	3B	
2	SA	4P	37	SA	2B	
3	SA	4T	38	SA	3A	
4	SA	6R	39	SA	3C	
5	SA	5T	40	SA	2C	
6	ZZ	7T	41	SA	2A	
7	DQa	6P	42	DQc	2D	
8	DQa	7P	43	DQc	1D	
9	DQa	6N	44	DQc	2E	
10	DQa	7N	45	DQc	1E	
11	DQa	6M	46	DQc	2F	
12	DQa	6L	47	DQc	2G	
13	DQa	7L	48	DQc	1G	
14	DQa	6K	49	DQc	2H	
15	DQa	7K	50	DQc	1H	
16	SBWa	5L	51	SBWc	3G	
17	K	4L	52	ZQ	4D	
18	K	4K	53	SS	4E	
19	G	4F	54	SA	4B	
20	<del>SBW</del> b	5G	55	NC <sup>(1)</sup>	4H	
21	DQb	7H	56	SW	4M	
22	DQb	6H	57	<del>SBW</del> d	3L	
22	DQb	7G	58	DQd	1K	
24	DQb	6G	59	DQd	2K	
25	DQb	6F	60	DQd	1L	
26	DQb	7E	61	DQd	2L	
27	DQb	6E	62	DQd	2M	
28	DQb	7D	63	DQd	1N	
29	DQb	6D	64	DQd	2N	
30	SA	6A	65	DQd	1P	
31	SA	6C	66	DQd	2P	
32	SA	5C	67	SA	3T	
33	SA	5A	68	SA	2R	
34	SA	6B	69	SA	4N	
35	SA	5B	70	M1	3R	

Note 1: NC pin at pad location 4H is connected to V<sub>SS</sub> internally, regardless of pin connection externally.

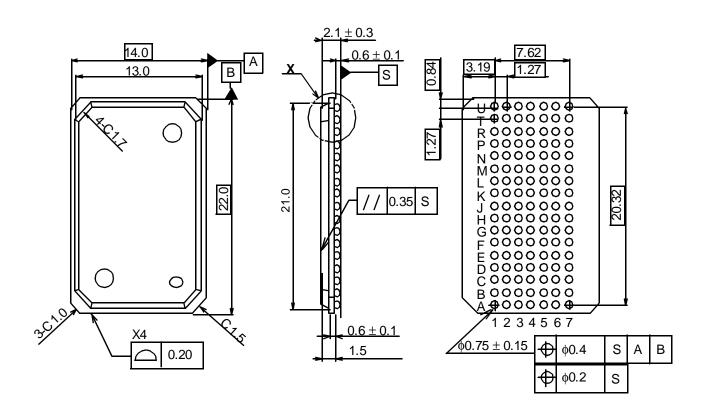
# •Ordering Information\_

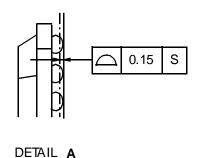
Part Number	$V_{\mathrm{DD}}$	I/O Type	Size	Speed (Cycle Time / Access Time)
CXK77K36R320GB-3	2.5V	HSTL	1Mb x 36	3.0ns / 1.6ns
CXK77K36R320GB-33	2.5V	HSTL	1Mb x 36	3.3ns / 1.6ns
CXK77K36R320GB-4	2.5V	HSTL	1Mb x 36	4.0ns / 2.0ns

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32Mb LW R-R, rev 0.6 19 / 22 March 16, 2004

# 119 Pin BGA Package Dimensions





SONY CODE	BGA-119P-021
EIAJ CODE	BGA119-P-1422
JEDEC CODE	

## PACKAGE STRUCTURE

PACKAGE MATERIAL	EPOXY RESIN
BORAD TREATMENT	COPPER-CLAD LAMINATE
LEAD MATERIAL	SOLDER
PACKAGE MASS	1.1g

This product utilizes lead (Pb) as one of the elements composing the package solder ball. The quantity of lead (Pb) per package is approxmiately 70.81mg (1.7mg per ball \* 119 balls \* 35%). Lead (Pb) has been shown to be hazardous to the environment, and therefore may be subject to regulations within each country.

# •Revision History

Rev. #	Rev. Date	Description of Modification			
rev 0.0	11/30/01	Initial Version			
rev 0.1	03/22/02	1. Modified BGA Package Thermal Characteristics section (p. 6).  Θ <sub>JC</sub> 2. Modified DC Recommended Operating Conditions section (p. 7).  V <sub>DDQ</sub> (max) V <sub>REF</sub> , V <sub>CM</sub> (max) Added note 1 regarding 2.5V V <sub>DD</sub> support. Added note 2 regarding 1.8V V <sub>DDQ</sub> support.  3. Modified DC Electrical Characteristics section (p. 8).  R <sub>OUT</sub> RQ/5 ± 10% (GBD) to RQ/5 ± 4. Modified AC Electrical Characteristics section (p. 9). Removed "-25" bin. Added "-33" bin.  -3 t <sub>KHQV</sub> t <sub>KHQZ</sub> , t <sub>GLQV</sub> , t <sub>GHQZ</sub> 5. Removed 1.8V V <sub>DDQ</sub> AC Test Conditions. 6. Modified JTAG DC Recommended Operating Conditions section (p. 14 V <sub>TIH</sub> (min) V <sub>TIL</sub> (max) 7. Modified JTAG Instruction Register definition (p. 17).	1.7ns to 1.5ns 1.9ns to 1.7ns		
rev 0.2	04/02/02		1.6V to $V_{DD}$ to $V_{DDQ}/2 - 0.1V$ to $V_{DDQ}/2 + 0.1V$		
rev 0.3	06/24/02	1. Modified AC Electrical Characteristics section (p. 9).  -3, -33  t <sub>AVKH</sub> , t <sub>WVKH</sub> , t <sub>SVKH</sub> , t <sub>DVKH</sub> -3, -33  t <sub>KHAX</sub> , t <sub>KHWX</sub> , t <sub>KHSX</sub> , t <sub>KHDX</sub> 2. Modified JTAG DC Recommended Operating Conditions section (p. 15  V <sub>TIH</sub> (min)  V <sub>TIL</sub> (max)  3. Modified JTAG AC Electrical Characteristics section (p.16).  TCK Cycle Time  TCK High / Low Pulse Widths  TMS/TDI Input Setup & Hold Times  TDO Output Valid Time  Added Capture Setup & Hold Times	0.5ns to 0.3ns 0.5ns to 0.3ns 0.5ns to 0.3ns 1.4V to 1.2V 0.8V to 0.6V 100ns to 50ns 40ns to 20ns 10ns to 5ns 20ns to 10ns 5ns		
rev 0.4	02/05/03	Removed all x18 information (created separate x18 data sheet).     Changed V <sub>DD</sub> from 1.8V nominal to 2.5V nominal, throughout docume 3. Modified Absolute Maximum Ratings (p. 5).     V <sub>DD</sub> (max)     Modified DC Recommended Operating Conditions section (p. 6).     V <sub>DD</sub> (min)     V <sub>DD</sub> (max)     V <sub>DD</sub> (max)	2.5V to 3.2V 1.7V to 2.37V 1.9V to 2.63V V <sub>DD</sub> to 1.6V		

Rev. #	Rev. Date	Description of Modification	
rev 0.4	02/05/03	Modified DC Electrical Characteristics section (p. 7).     I <sub>MLI</sub> , I <sub>LO</sub> (min/max)     Added preliminary I <sub>DD</sub> and I <sub>SB</sub> specifications.     Modified AC Electrical Characteristics section (p. 8).	$\pm 10$ uA to $\pm 5$ uA
		All Bins t <sub>KHQX</sub> , t <sub>KHQX1</sub> , t <sub>KHQZ</sub> (min)	0.5ns to 0.7ns
		-3 t <sub>KHAX</sub> , t <sub>KHWX</sub> , t <sub>KHSX</sub> , t <sub>KHDX</sub>	0.3ns to 0.5ns
		-33 t <sub>KHAX</sub> , t <sub>KHXX</sub> , t <sub>KHSX</sub> , t <sub>KHDX</sub>	0.3ns to 0.6ns
		tKHQV	1.7ns to 1.6ns
		t <sub>KHQZ</sub> , t <sub>GLQV</sub> , t <sub>GHQZ</sub> ,	1.9ns to 1.8ns
		-4 t <sub>KHAX</sub> , t <sub>KHWX</sub> , t <sub>KHSX</sub> , t <sub>KHDX</sub> 7. Removed 1.8V V <sub>DDO</sub> AC Test Conditions.	0.3ns to 0.7ns
		8. Modified JTAG DC Recommended Operating Conditions section	on (p. 13).
		V <sub>TIH</sub> (min)	1.2V to 1.4V
		V <sub>TIH</sub> (max)	$V_{DD} + 0.3V$ to 3.6V
		V <sub>TIL</sub> (max)	0.6V to 0.8V
		<ul><li>9. Removed 1.8V JTAG AC Test Conditions.</li><li>10. Added 2.5V JTAG AC Test Conditions (p.13).</li></ul>	
rev 0.5	07/08/03	1. Modified AC Electrical Characteristics section (p. 8).	
		-3 t <sub>GLQV</sub> , t <sub>GHQZ</sub>	1.7ns to 2.5ns
		-33 t <sub>GLQV</sub> , t <sub>GHQZ</sub>	1.8ns to 2.5ns
		-4 t <sub>GLQV</sub> , t <sub>GHQZ</sub>	2.2ns to 2.5ns
		2. Modified JTAG ID Register definition (p. 17).	044
		Changed Part Number code from T.B.D. to 0000 0000 0111 0	011.
rev 0.6	03/16/04	1. Modified I/O Capacitance section (p. 5).	
		$C_{IN}$	3.5pF to 4.0pF
		C <sub>KIN</sub>	3.5pF to 4.5pF
		$C_{OUT}$	4.5pF to 5.0pF
		2. Modified AC Electrical Characteristics section (p. 8).	
		All Bins $t_{KHQX}, t_{KHQX1}, t_{KHQZ}$ (min)	0.7ns to 0.65ns
		-3 t <sub>KHQV</sub>	1.5ns to 1.6ns
		t <sub>KHQZ</sub>	1.7ns to 1.8ns
		3. Added note to Package Dimensions section regarding lead conto	ent in solder balls (p. 20).