

## Description

The AUK 60C32/P 60C52/P is a high-performance micro controller fabricated with AUK high-density CMOS technology. The AUK CMOS technology combines the high speed and density characteristics of MOS with the low power attributes of CMOS.

The 60C52 contains a 8Kx8 ROM, a 256x8 RAM, 32 I/O lines, three 16bit counter/timers, a six source two-priority level nested interrupt structure, a serial I/O port for either multi-processor communication, I/O expansion or full duplex UART, and on-chip oscillator and clock circuits.

In addition, the device has two software selectable modes of power reduction idle mode and power-down mode. The idle mode freezes the CPU while allowing the RAM, timers, serial port, and interrupt system to continue functioning.

The power-down mode saves the RAM contents but freezes the oscillator, causing all other chip function to be inoperative.

## Features

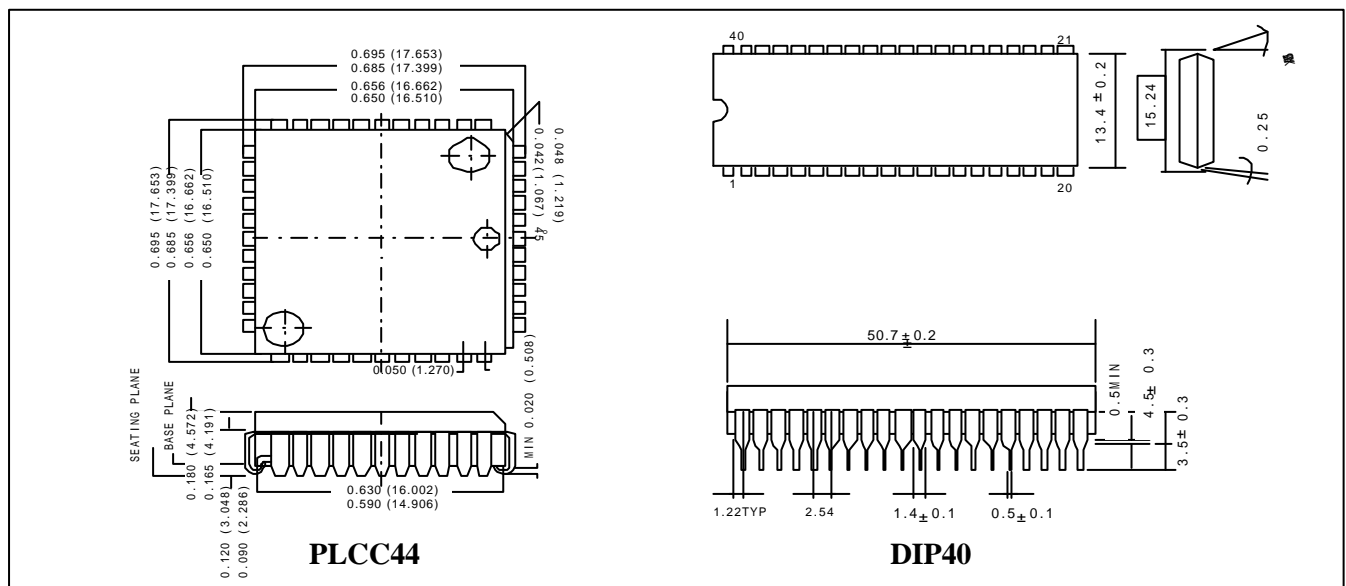
- 8-bit CPU optimized for control applications.
- Pin-to-pin compatible with intel's 80C52/80C32.
- 256 Bytes of on-chip data RAM.
- 60C52 low power CPU only.
- 32 programmable I/O lines.
- Three 16bit timer/counters.
- TTL and CMOS compatible logic levels
- 64K external program memory space and data memory space.
- MCS-51 fully compatible instruction set
- ONCE™ (ON-circuit emulation) mode
- Power control modes
  - Idle mode
  - Power down mode
- 6 interrupt source

## Ordering Information

Type NO.	Marking	Package Code	Type NO.	Marking	Package Code
SD60C32	SD60C32	PLCC44	SD60C32P	SD60C32	DIP40
SD60C52	SD60C52	PLCC44	SD60C52P	SD60C52	DIP40

## Outline Dimensions

unit : mm

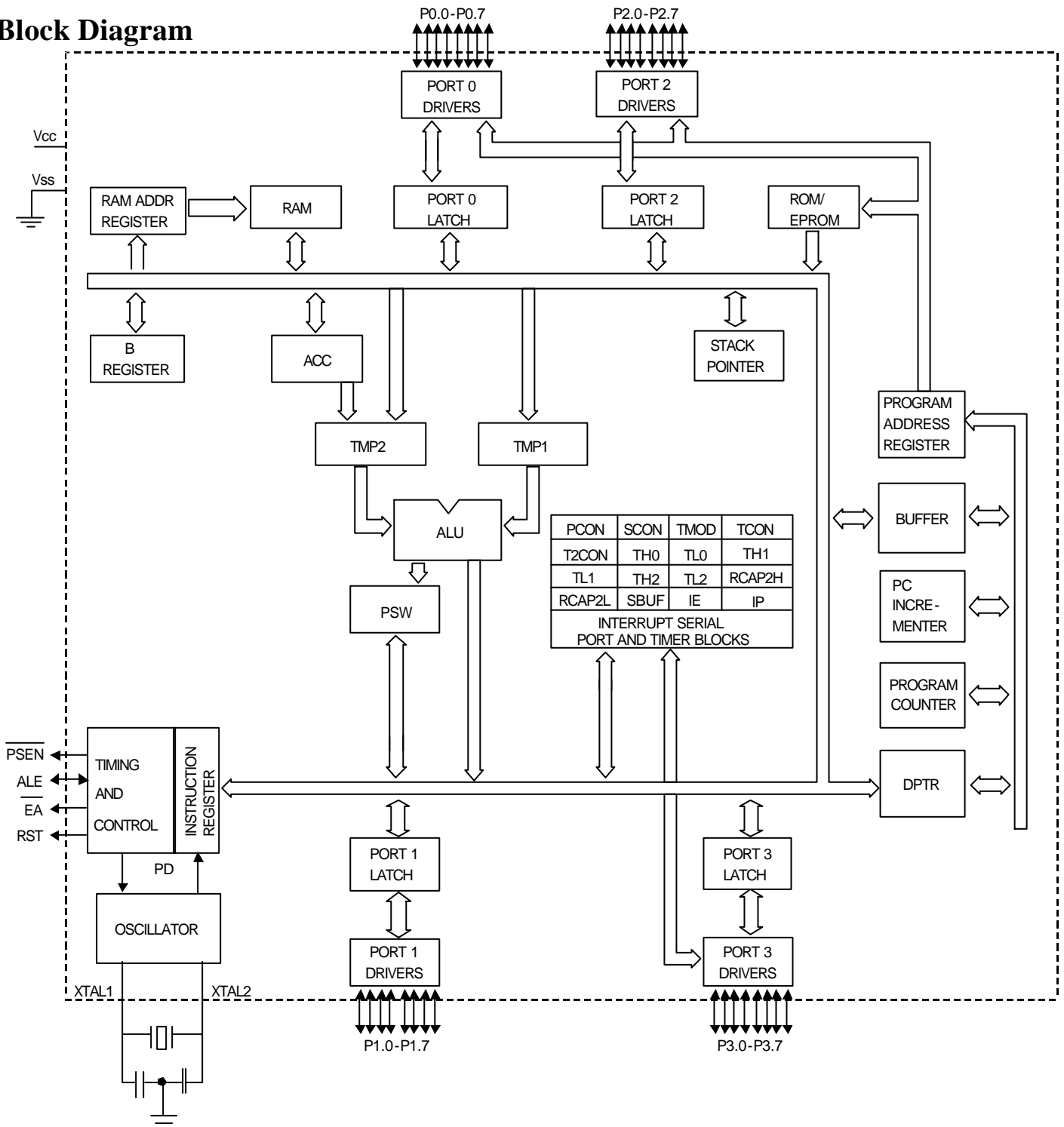


# SD60C32/P SD60C52/P

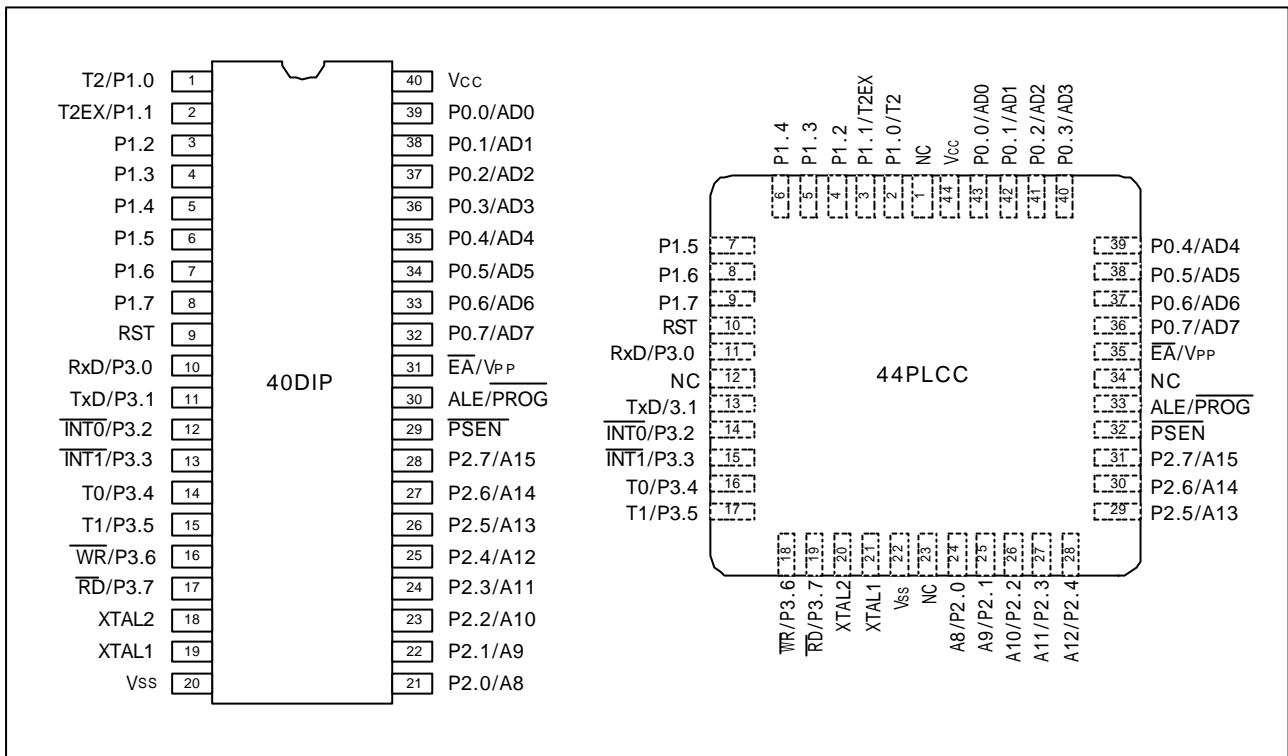
## Absolute Maximum Ratings

Characteristic	Rating	Unit
Ambient temperature under bias	0 ~ +70	
Storage temperature	- 65 ~ + 150	
Voltage on any pin to $V_{SS}$	- 0.5 ~ $V_{CC} + 0.5$	V
Maximum $I_{OL}$ per I/O pin	15	mA
Power dissipation	1.5	W

## Block Diagram



## Pin Configuration



## Pin Description

**V<sub>CC</sub>** : PIN 40 (DIP40), PIN 44 (PLCC44)

Supply voltage during normal, Idle and power down operations.

**V<sub>SS</sub>** : PIN 20 (DIP40), PIN 22 (PLCC44)

Circuit ground.

**Port 0** : PIN 32~39 (DIP40), PIN 36~43 (PLCC44)

Port 0 is an 8bit open drain bi-directional I/O port. As an output port each pin can sink several LS TTL inputs. Port 0 pins that have 1's written to them float, and in that state can be used as high impedance inputs.

Port 0 is also the multiplexed low-order address and data bus during accesses to external program and data memory.

In this application it uses strong internal pullups when emitting 1's and source and sink several LS TTL inputs. Port 0 outputs the code bytes during program verification on the 60C52 external pullups resistors are required during program verification.

**Port 1** : PIN 1~8 (DIP40), PIN 2~9 (PLCC44)

Port 1 output buffers can drive LSI TTL inputs.

Port 1 is an 8bit bi-directional I/O port with internal pullups.

Port 1 pins that have 1's written to them are pulled high by the internal pullups, and in that state can be used as inputs. As inputs, Port 1 pins that are externally being pulled low will source current because of the internal pullups

**Pin Description (Continued)**

In addition, Port 1 serves the functions of the following special features of the 60C52.

Port Pin	Alternate Function
P1.0	T2(External Count Input to Timer / Counter 2)
P1.1	T2EX(Timer / Counter 2 Capture/Reload Trigger and Direction Control)

Port 1 receives the low-order address bytes during ROM verification.

**Port 2 : PIN 21~28 (40DIP), PIN 24~31 (44PLCC)**

Port 2 is an 8-bit bi-directional I/O port with internal pullups. The port 2 output buffers can drive LS TTL inputs.

Port 2 pins that have 1's written to them are pulled high by the internal pullups, and in that state can be used as input.

As inputs, port 2 pins that are externally being pulled low will source current because of the internal pullups.

Port 2 emits the high-order address byte during fetches from external Program Memory and during accesses to external data memory that use 16-bit addresses (MOVX @ DPTR).

In this application it uses strong internal pullups when emitting 1s. During accesses to external data memory that use 8 bit addresses (MOVX @ Ri), port 2 emits the contents of the P2 special function register

**Port 3 : PIN 10~17 (DIP40), PIN 13~19 (PLCC44)**

Port 3 is an 8bit bi-directional I/O port with internal pullups. The port 3 output buffers can drive LS TTL input. Port 3 pins that have 1's written to them are pulled high by the internal pullups, and in that state can be used as inputs. As inputs, Port 3 pins that are externally being pulled low will source current because of the pullups.

Port 3 also serves the function of various special feature of the MCS-51 Family, as listed below :

Port PIN	PIN NO.	Alternate Function
P3.0	10	RxD (Serial input port)
P3.1	11	TxD (Serial output port)
P3.2	12	$\overline{\text{INT0}}$ (External interrupt 0)
P3.3	13	$\overline{\text{INT1}}$ (External interrupt 1)
P3.4	14	T0 (Timer 0 external input)
P3.5	15	T1 (Timer 1 external input)
P3.6	16	$\overline{\text{WR}}$ (External data memory write strobe)
P3.7	17	$\overline{\text{RD}}$ (External data memory read strobe)

# SD60C32/P SD60C52/P

RST: PIN 9 (DIP40), PIN 10 (PLCC44)

Reset input. A high on this pin for two machine cycles while the oscillator is running resets the device. An internal pulldown resistor permits a power-on reset with only a capacitor connected to  $V_{CC}$ .

ALE: PIN 30 (DIP40), PIN 33 (PLCC44)

Address latch enable output pulse for latching the low byte of the address during accesses to external memory.

In normal operation ALE is emitted at a constant rate of 1/6 the oscillator frequency, and may be used for external timing or clocking purposes.

Note : However, that one ALE pulse is skipped during each access to external data memory.

This pin is also the program pulse input PROG during EPROM programming.

$\overline{\text{PSEN}}$  : PIN 29 (DIP40), PIN 32 (PLCC44)

Program store enable is the read strobe to external program memory. When the 60C52 is executing code from external program memory,  $\overline{\text{PSEN}}$  is activated twice each machine cycle, except that two  $\overline{\text{PSEN}}$  activations are skipped during each access to external data memory.  $\overline{\text{PSEN}}$  is not activated during fetches from internal program memory.

$\overline{\text{EA}}$ : PIN 31 (DIP40), PIN 35 (PLCC44)

External access enable.  $\overline{\text{EA}}$  must be strapped to  $V_{SS}$  in order to enable the device to fetch code from external program memory locations starting at 0000H up to FFFFH. If  $\overline{\text{EA}}$  is strapped to  $V_{CC}$  the device executes from internal program memory unless the program counter contains an address greater than 0FFFH.

XTAL1: PIN 19 (DIP40), PIN 21 (PLCC44)

Input to the Inverting oscillator amplifier and input to the internal clock generator circuits.

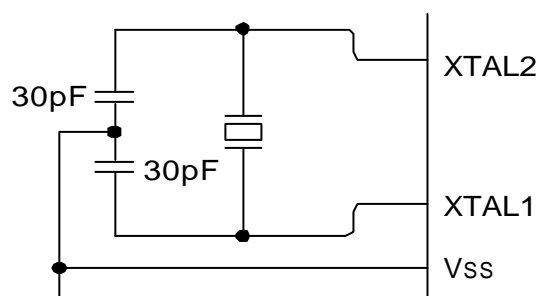
XTAL2: PIN 18 (DIP40), PIN 20 (PLCC44)

Output from the inverting oscillator amplifier

0 Crystal Oscillator

NC: PIN1, 12, 23, 34 (PLCC44)

Non connection pins.



**Idle Mode**

In the Idle mode, the CPU puts itself to sleep while all the on chip peripherals stay active. The instruction that invokes the Idle mode is the last instruction executed in the normal operating mode before Idle mode is activated.

The content of the on-chip RAM and all the special function registers remain intact during this mode. The Idle mode can be terminated either by any enabled interrupt, at which time the process is picked up at the interrupt service routine and continued, or by a hardware reset which starts the processor the same as a power on reset.

**Power Down Mode**

In the power down mode the oscillator is stopped, and the instruction that invokes power down is the last instruction executed. The on-chip RAM and special function register retain their values until the power down mode is terminated.

The only exit from power down is a hardware reset. Reset redefines the SFRs but does not change the on-chip RAM. The reset should not be activated before  $V_{CC}$  is restored to its normal operating level and must be held active long enough to allow the oscillator to restart and stabilize.

The control bits for the reduced power modes are in the special function register PCON.

Table. Status of the external pins during Idle and power down modes.

<b>Mode</b>	<b>Program Memory</b>	<b>ALE</b>	<b>PSEN</b>	<b>PORT 0</b>	<b>PORT 1</b>	<b>PORT 2</b>	<b>PORT 3</b>
Idle	Internal	1	1	Data	Data	Data	Data
Idle	External	1	1	Float	Data	Address	Data
Power Down	Internal	0	0	Data	Data	Data	Data
Power Down	External	0	0	Float	Data	Data	Data

# SD60C32/P SD60C52/P

## Electrical Characteristics (DC)

( $T_a = 0 \sim 70$  or  $-40 \sim 85$ ,  $V_{CC} = 5V \pm 20\%$ ,  $V_{SS} = 0V$ )

SYMBOL	PARAMETER	TEST CONDITIONS	LIMITS			UNIT
			MIN	TYP.	MAX	
$V_{IL}$	Input low voltage, except $\overline{EA}$		-0.5		$0.2V_{CC} - 0.1$	V
$V_{IL1}$	Input low voltage to $\overline{EA}$		0		$0.2V_{CC} - 0.3$	V
$V_{IH}$	Input high voltage, except XTAL1, RST		$0.2V_{CC} + 0.9$		$V_{CC} + 0.5$	V
$V_{IH1}$	Input high voltage to XTAL1, RST		$0.7 V_{CC}$		$V_{CC} + 0.5$	V
$V_{OL}$	Output low voltage to ports 1,2,3	$I_{OL} = 1.6mA$			0.45	V
$V_{OL1}$	Output low voltage to ports 0, ALE, PSEN	$I_{OL} = 3.2mA$			0.45	V
$V_{OH}$	Output high voltage to ports 1,2,3,ALE,PSEN	$I_{OH} = -60\mu A$ $I_{OH} = -30\mu A$ $I_{OH} = -10\mu A$	$V_{CC} - 0.3$ $V_{CC} - 0.7$ $V_{CC} - 1.5$			V
$V_{OH1}$	Output high voltage (port 0 in external bus mode)	$I_{OH} = -200\mu A$ $I_{OH} = -3.2mA$ $I_{OH} = -7.0mA$	$V_{CC} - 0.3$ $V_{CC} - 0.7$ $V_{CC} - 1.5$			V
$I_{IL}$	Logical 0 input current to ports 1,2,3	$V_{IN} = 0.45V$		-10	-50	$\mu A$
$I_{TL}$	Logical 1 to 0 transition current to ports 1,2,3	$V_{IN} = 2V$		-265	-650	$\mu A$
$I_{LI}$	Input leakage current to port 0, $\overline{EA}$	$0 < V_{IN} < V_{CC}$		0.02	$\pm 10$	$\mu A$
$I_{CC}$	Power supply current Active mode @ 12MHz Idle mode @ 12MHz Power-down mode			15 5 5	30 7.5 75	mA mA $\mu A$
$R_{RST}$	Internal reset pull-down resistor		40	100	225	kohm
$C_{10}$	Pin capacitance			10		pF

# SD60C32/P SD60C52/P

## Electrical Characteristics (AC)

( $T_a = 0 \sim 70$  or  $-40 \sim 85$ ,  $V_{CC} = 5V \pm 20\%$ ,  $V_{SS} = 0V$ )

SYMBOL	FIGURE	PARAMETER	12MHz CLOCK		VARIABLE CLOCK		UNIT
			MIN	MAX	MIN	MAX	
$1/t_{CLCL}$		Oscillator frequency : Speed Versions 60C32/60C52			3.5	16	MHz
$t_{LHLL}$	1	ALE pulse width	127		$2t_{CLCL}-40$		ns
$t_{AVLL}$	1	Address valid to ALE low	43		$t_{CLCL}-40$		ns
$t_{LLAX}$	1	Address hold after ALE low	53		$t_{CLCL}-30$		ns
$t_{LLIV}$	1	ALE low to valid instruction in		234		$4t_{CLCL}-100$	ns
$t_{LLPL}$	1	ALE low to PSEN low	53		$t_{CLCL}-30$		ns
$t_{PLPH}$	1	PSEN pulse with	205		$3t_{CLCL}-45$		ns
$t_{PLIV}$	1	PSEN low to valid instruction in		145		$3t_{CLCL}-105$	ns
$t_{PXIX}$	1	Input instruction hold after PSEN	0		0		ns
$t_{PXIZ}$	1	Input instruction float after PSEN		59		$t_{CLCL}-25$	ns
$t_{AVIV}$	1	Address to valid instruction in		312		$5t_{CLCL}-105$	ns
$t_{PLAZ}$	1	PSEN low to address float		10		10	ns
Data Memory							
$t_{RLRH}$	2, 3	RD pulse width	400		$6t_{CLCL}-100$		ns
$t_{WLWH}$	2, 3	WR pulse width	400		$6t_{CLCL}-100$		ns
$t_{RLDV}$	2, 3	RD low to valid data in		252		$5t_{CLCL}-165$	ns
$t_{RHDX}$	2, 3	Data hold after RD	0		0		ns
$t_{RHDZ}$	2, 3	Data float after RD		107		$2t_{CLCL}-70$	ns
$t_{LLDV}$	2, 3	ALE low to valid data in		517		$8t_{CLCL}-150$	ns
$t_{AVDV}$	2, 3	Address to valid data in		585		$9t_{CLCL}-165$	ns
$t_{LLWL}$	2, 3	ALE low to RD or WR low	200	300	$3t_{CLCL}-50$	$3t_{CLCL}+50$	ns
$t_{AVWL}$	2, 3	Address valid to WR low or RD low	203		$4t_{CLCL}-130$		ns
$t_{QVWX}$	2, 3	Data valid to WR transition	33		$t_{CLCL}-50$		ns
$t_{WHOX}$	2, 3	Data hold after WR	33		$t_{CLCL}-50$		ns
$t_{QVWH}$	2, 3	Data valid to WR High	433		$7t_{CLCL}-150$		ns
$t_{RLAZ}$	2, 3	RD low to address float		0		0	ns
$t_{WHLH}$	2, 3	RD or WR high to ALE high	43	123	$t_{CLCL}-40$	$t_{CLCL}-40$	ns
External Clock							
$t_{CHCX}$	4	High time	20		20		ns
$t_{CLCX}$	4	Low time	20		20		ns
$t_{CLCH}$	4	Rise time		20		20	ns
$t_{CHCL}$	4	Fall time		20		20	ns



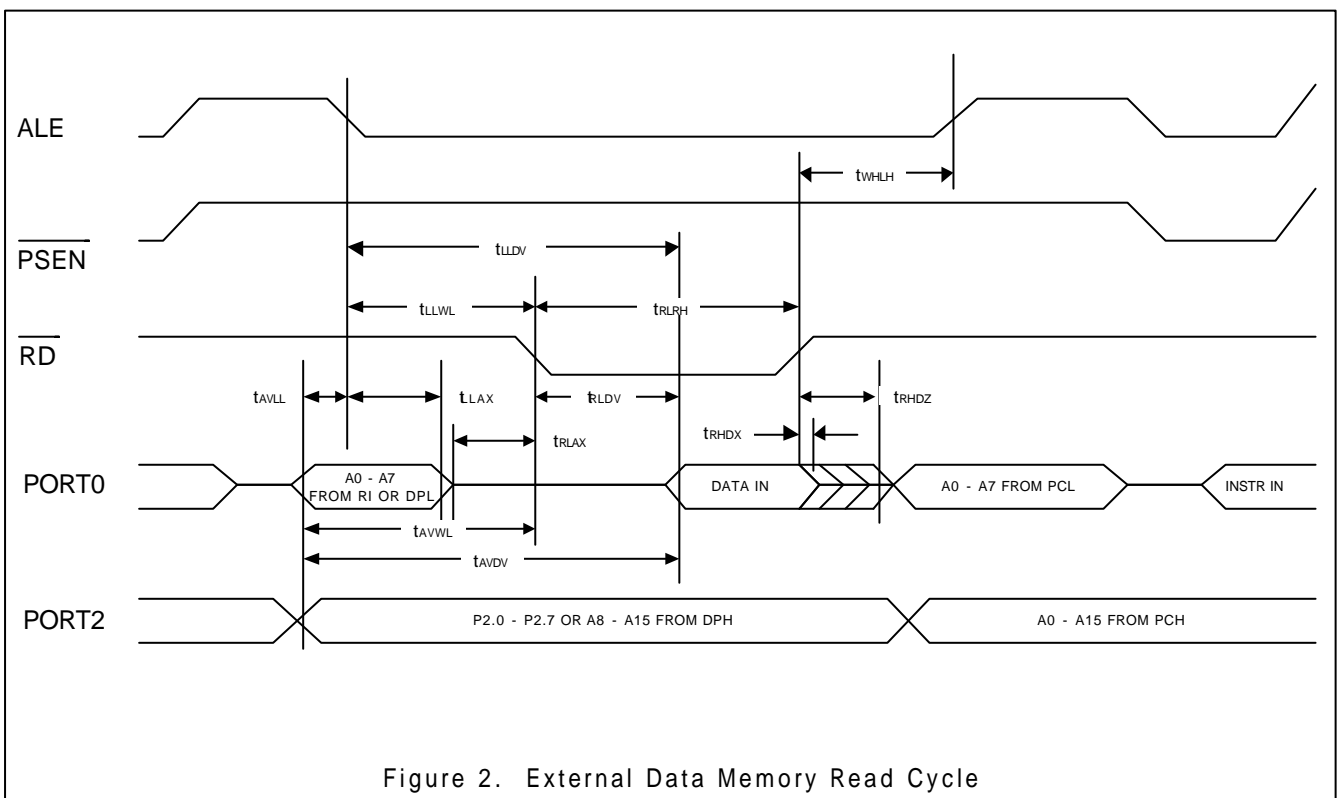
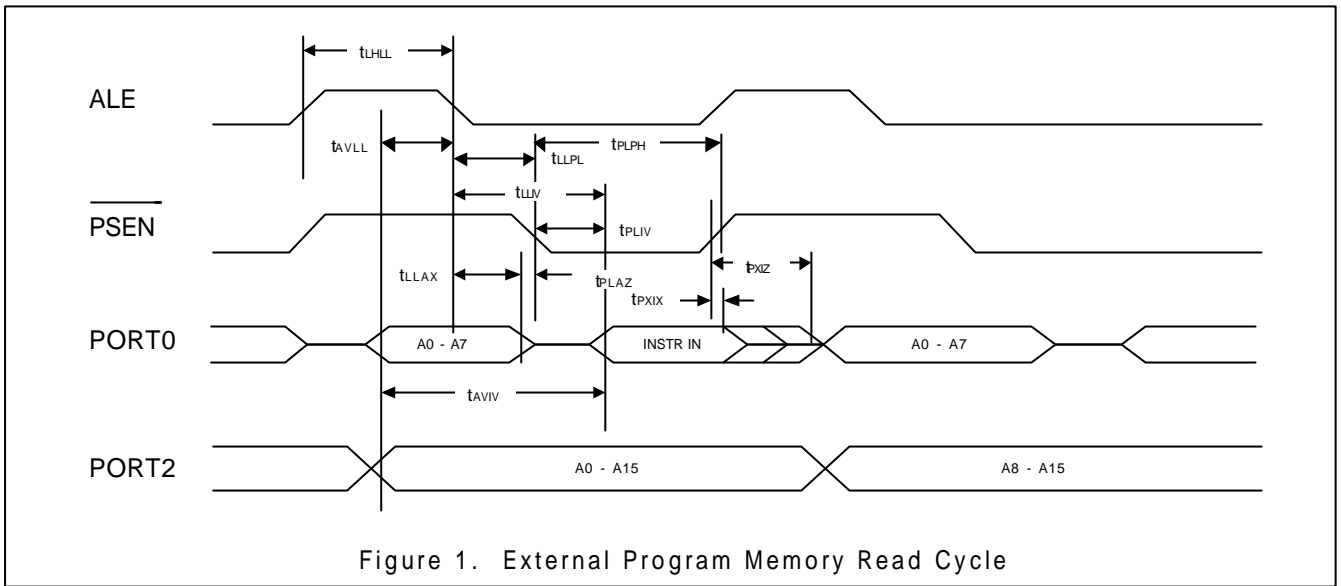
# SD60C32/P SD60C52/P

## Electrical Characteristics (Continued)

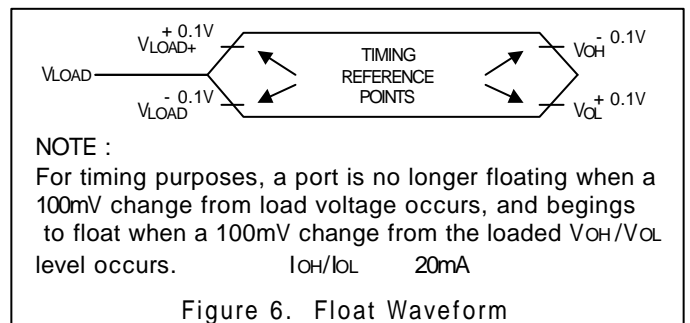
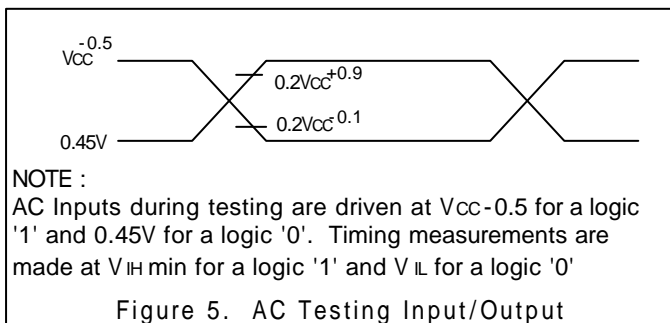
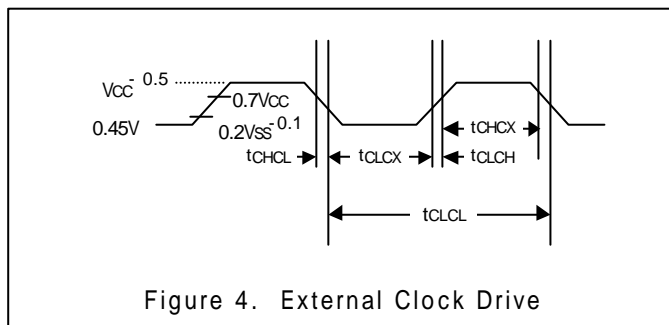
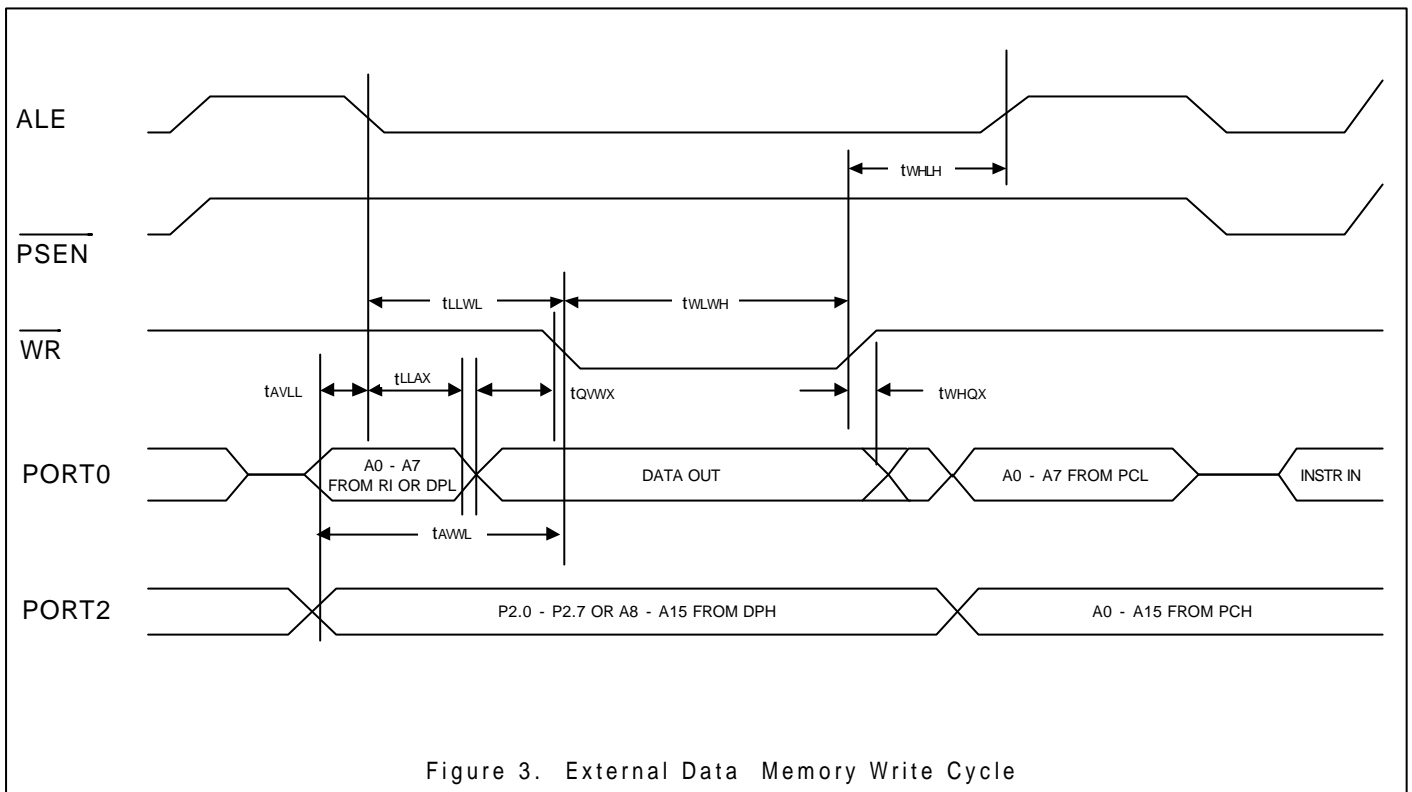
( $T_a = 0 \sim 70$  or  $-40 \sim 85$ ,  $V_{CC} = 5V \pm 20\%$ ,  $V_{SS} = 0V$ )

SYMBOL	FIGURE	PARAMETER	16MHz CLOCK		VARIABLE CLOCK		UNIT
			MIN	MAX	MIN	MAX	
$1/t_{CLCL}$		Oscillator frequency : Speed Versions 60C52/60C32			3.5	16	MHz
$t_{LHLL}$	1	ALE pulse width	85		$2t_{CLCL}-40$		ns
$t_{AVLL}$	1	Address valid to ALE low	23		$t_{CLCL}-40$		ns
$t_{LLAX}$	1	Address hold after ALE low	33		$t_{CLCL}-30$		ns
$t_{LLIV}$	1	ALE low to valid instruction in		150		$4t_{CLCL}-100$	ns
$t_{LLPL}$	1	ALE low to PSEN low	23		$t_{CLCL}-40$		ns
$t_{PLPH}$	1	PSEN pulse with	143		$3t_{CLCL}-45$		ns
$t_{PLIV}$	1	PSEN low to valid instruction in		83		$3t_{CLCL}-105$	ns
$t_{PXIX}$	1	Input instruction hold after PSEN	0		0		ns
$t_{PXIZ}$	1	Input instruction float after PSEN		38		$t_{CLCL}-25$	ns
$t_{AVTV}$	1	Address to valid instruction in		208		$5t_{CLCL}-105$	ns
$t_{PLAZ}$	1	PSEN low to address float		10		10	ns
Data Memory							
$t_{RLRH}$	2, 3	RD pulse width	275		$6t_{CLCL}-100$		ns
$t_{WLWH}$	2, 3	WR pulse width	275		$6t_{CLCL}-100$		ns
$t_{RLDV}$	2, 3	RD low to valid data in		148		$5t_{CLCL}-165$	ns
$t_{RHDZ}$	2, 3	Data hold after RD	0		0		ns
$t_{RHDZ}$	2, 3	Data float after RD		55		$2t_{CLCL}-70$	ns
$t_{LLDV}$	2, 3	ALE low to valid data in		350		$8t_{CLCL}-150$	ns
$t_{AVDV}$	2, 3	Address to valid data in		398		$9t_{CLCL}-165$	ns
$t_{LLWL}$	2, 3	ALE low to RD or WR low	138	238	$3t_{CLCL}-50$	$3t_{CLCL}+50$	ns
$t_{AVWL}$	2, 3	Address valid to WR low or RD low	120		$4t_{CLCL}-130$		ns
$t_{ZVWX}$	2, 3	Data valid to WR transition	13		$t_{CLCL}-50$		ns
$t_{WHOX}$	2, 3	Data hold after WR	13		$t_{CLCL}-50$		ns
$t_{QVWH}$	2, 3	Data valid to WR High	288		$7t_{CLCL}-150$		ns
$t_{RLAZ}$	2, 3	RD low to address float		0		0	ns
$t_{WHLH}$	2, 3	RD or WR high to ALE high	23	103	$t_{CLCL}-40$	$t_{CLCL}+40$	ns
External Clock							
$t_{CHCX}$	4	High time	20		20		ns
$t_{CLCX}$	4	Low time	20		20		ns
$t_{CLCH}$	4	Rise time		20		20	ns
$t_{CHCL}$	4	Fall time		20		20	ns

## Timing Diagram



## Timing Diagram (Continued)



## Timing Diagram (Continued)

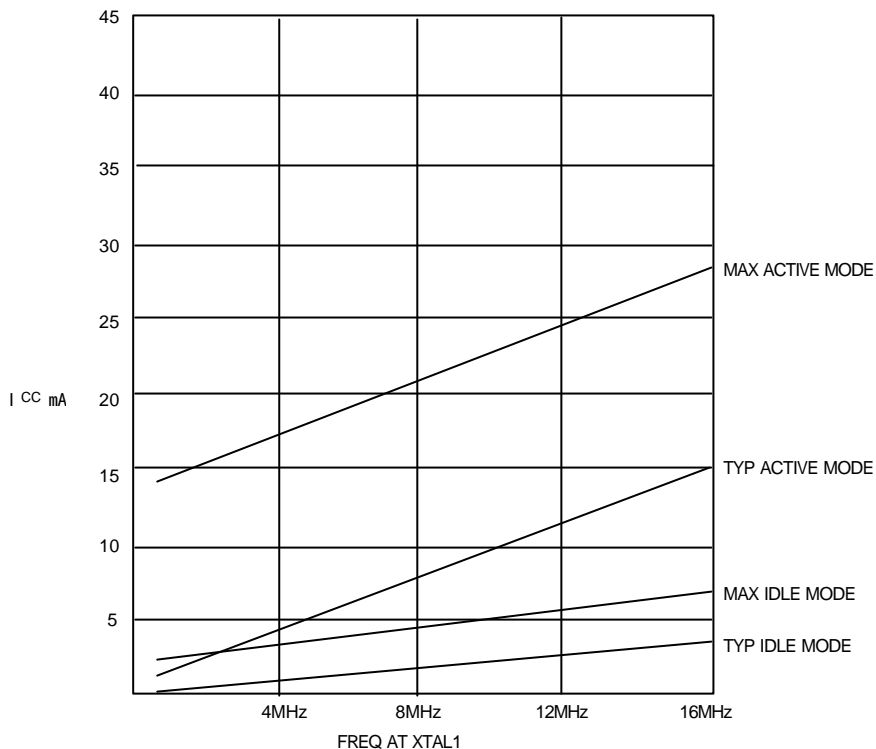
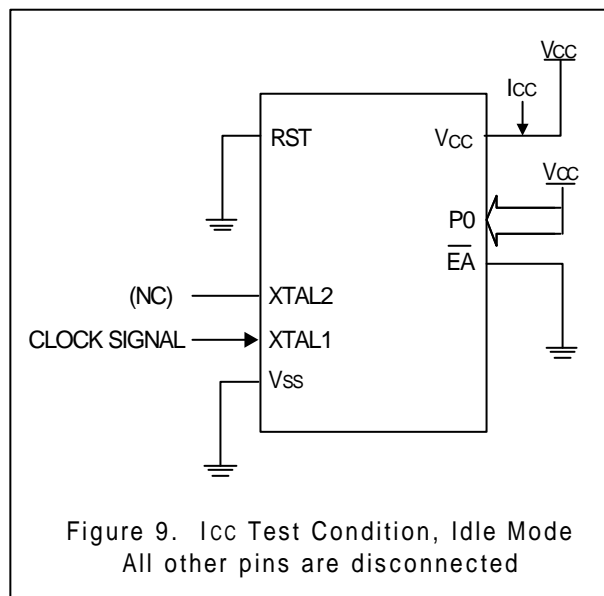
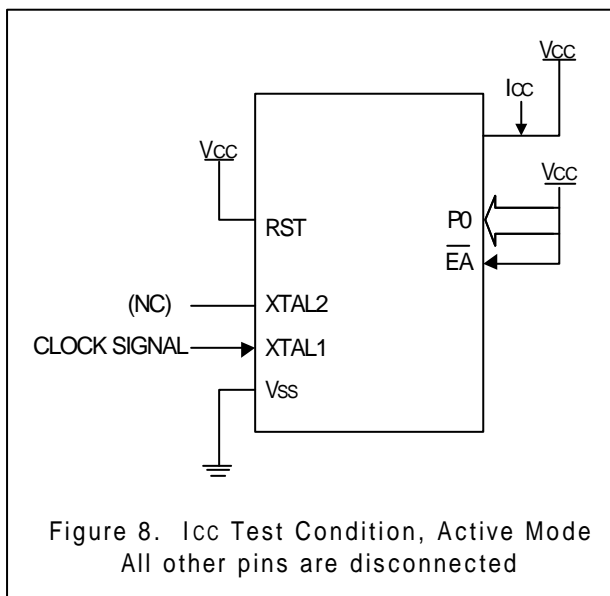


Figure 7.  $I_{CC}$  vs. FREQ  
Valid only within frequency specifications of the device under test



Timing Diagram (Continued)

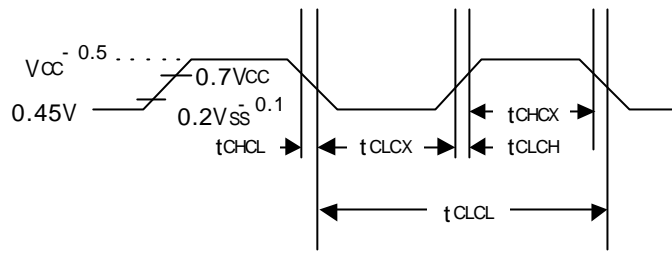


Figure 10. Clock Signal Waveform for  $I_{CC}$  Tests in Active and Idle Modes  
 $t_{CLCH} = t_{CHCL} = 5ns$

