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## NTE1729 Integrated Circuit Pulse Width Modulator (PWM) Control Circuit

### **Description:**

The NTE1729 is an inverter control unit in a 16-Lead DIP type package which provides all the control circuitry for PWM type switching regulators. Included in this device is the voltage reference, dual error amplifiers, oscillator, pulse width modulator, pulse steering flip flop, dual alternating output switches, and dead time control.

### **Features:**

- Complete PWM Power Control Circuit
- Adjustable Dead Time: 0 to 100%
- No Double Pulsing of Same Output during Load Transient Condition
- Dual Error Amplifiers have Wide Common Mode Input Voltage Capability:  $-0.3V$  to  $V_{CC} - 2V$
- Circuit Architecture Provides Easy Synchronization
- Uncommitted Outputs for 250mA Sink or Source
- With Miss-Operation Prevention Circuit for Low Level Supply Voltage

### **Absolute Maximum Ratings:** ( $T_A = +25^{\circ}C$ unless otherwise specified)

Supply Voltage, $V_{CC}$ .....	41V
Error Amplifier Input Voltage, $V_{ICM}$ .....	$V_{CC} + 0.3V$
Output Voltage, $V_{CER}$ .....	41V
Total Power Dissipation ( $T_A = +25^{\circ}C$ ), $P_T$ .....	1000mW
Operating Temperature Range, $T_{opr}$ .....	$-20^{\circ}$ to $+85^{\circ}C$
Storage Temperature Range, $T_{stg}$ .....	$-65^{\circ}$ to $+150^{\circ}C$

### **Recommended Operating Conditions:**

Parameter	Symbol	Min	Typ	Max	Unit
Supply Voltage	$V_{CC}$	7	–	40	V
Output Voltage	$V_{CER}$	-0.3	–	40	V
Output Current	$I_C$	–	–	200	mA
Error Amplifier Sink Current	$I_{OAMP}$	–	–	-0.3	mA
Timing Capacitor	$C_T$	0.47	–	10000	nF
Timing Resistance	$R_T$	1.8	–	500	k $\Omega$
Oscillation Frequency	$f_{osc}$	1	–	300	kHz
Operating Temperature	$T_{opt}$	-20	–	+70	$^{\circ}C$

**Electrical Characteristics:** ( $V_{CC} = +15V$ ,  $f = 10kHz$ ,  $-20^{\circ} \leq T_A \leq +70^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit	
<b>Reference Section</b>							
Output Voltage	$V_{ref}$	$I_{ref} = 1mA$ , $T_A = +25^{\circ}C$	4.75	5.0	5.25	V	
Line Regulation	$REG_{IN}$	$7V \leq V_{CC} \leq 40V$ , $I_{ref} = 1mA$ , $T_A = +25^{\circ}C$	–	8	25	mV	
Load Regulation	$REG_L$	$1mA \leq I_{ref} \leq 10mA$ , $T_A = +25^{\circ}C$	–	1	15	mV	
Temperature Coefficient	$V_{ref}$	$-20^{\circ} \leq T_A \leq +85^{\circ}C$ , $I_{ref} = 1mA$	–	0.01	0.03	%/ $^{\circ}C$	
Short-Circuit Output Current	$I_{short}$	$V_{ref} = 0$ , $T_A = +25^{\circ}C$ , Note 2	–	50	–	mA	
<b>Oscillator Section</b>							
Frequency	$f_{OSC}$	$C_T = 0.01\mu F$ , $R_T = 12k\Omega$ , $T_A = +25^{\circ}C$	–	10	–	kHz	
Standard Deviation of Frequency		$7V \leq V_{CC} \leq 40V$ , $C_T$ , $R_T$ , Const., $T_A = +25^{\circ}C$ , Note 1	–	10	–	%	
Frequency Change with Temperature		$0^{\circ} \leq T_A \leq +70^{\circ}C$ , $C_T = 0.01\mu F$ , $R_T = 12k\Omega$	–	1	2	%	
Frequency Change with Voltage		$7V \leq V_{CC} \leq 40V$ , $C_T = 0.01\mu F$ , $R_T = 12k\Omega$ , $T_A = +25^{\circ}C$	–	–	1	%	
<b>Dead-Time Control Section</b>							
Input Bias Current		$0 \leq V_I \leq 5.25V$	–	–2	–10	$\mu A$	
Maximum Duty Cycle (Each Output)		$V_I = 0$	45	49	–	%	
Input Threshold Voltage	$V_{th}$	Zero Duty Cycle	–	3.0	3.3	V	
		Maximum Duty Cycle	0	–	–	V	
<b>Error Amplifier Section</b>							
Input Offset Voltage	$V_{IO}$	$V_{OAMP} = 2.5V$	–	2	10	mV	
Input Offset Current	$I_{IO}$	$V_{OAMP} = 2.5V$	–	25	250	nA	
Input Bias Current		$V_{OAMP} = 2.5V$	–	0.2	1.0	mA	
Common Mode Input Voltage	Low	$V_{ICM}$	$7V \leq V_{CC} \leq 40V$	–0.3	–	–	V
	High			$V_{CC}^{-2}$	–	–	V
Open-Loop Voltage Amplification	$A_V$	$V_{OAMP} = 0.5V$ to $3.5V$ , $T_A = +25^{\circ}C$	60	80	–	dB	
Unity Gain Bandwidth		$T_A = +25^{\circ}C$	500	830	–	kHz	
Common Mode Rejection Ratio	CMRR	$V_{CC} = 40V$ , $T_A = +25^{\circ}C$	65	80	–	dB	
Output Sink Current		$V_{OAMP} = 0.7V$	0.3	0.7	–	mA	
Output Source Current		$V_{OAMP} = 3.5V$	–2	–10	–	mA	
<b>PWM Section</b>							
Input Threshold Voltage		Zero Duty Cycle	–	4.0	4.5	V	
Input Sink Current		$V_{(Pin3)} = 0.7V$	0.3	0.7	–	mA	
<b>Output Section</b>							
Collector Cutoff Current	$I_{CER}$	$V_{CE} = 40V$ , $V_{CC} = 40V$	–	2	100	$\mu A$	
Emitter Cutoff Current		$V_{CC} = V_C = 40V$	–	–	–100	$\mu A$	
Collector Saturation Voltage	$V_{CE(sat)}$	$I_C = 200mA$ , $V_E = 0$ , Common Emitter	0	0.95	1.3	V	
	$V_{CE(on)}$	$I_E = 200mA$ , $V_C = 15V$ , Emitter Follower	–	1.6	2.5	V	

**Electrical Characteristics (Cont'd):** ( $V_{CC} = +15V$ ,  $f = 10kHz$ ,  $-20^{\circ} \leq T_A \leq +70^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
<b>Output Section (Cont'd)</b>						
Output Voltage Rise Time	Common Emitter	$V_{CC} = 15V$ , $R_L = 150\Omega$ , $I_O = 100mA$ , $T_A = +25^{\circ}C$	–	100	200	ns
	Emitter Follower		–	100	200	ns
Output Voltage Fall Time	Common Emitter		–	70	200	ns
	Emitter Follower		–	70	200	ns
<b>Total Device</b>						
Standby Current	$I_{CC(S.B.)}$	$V_{CC} = 15V$ , all other inputs and outputs open	–	8.0	12.5	mA
Bias Current	$I_{CC(B.I.)}$	$V_{(Pin4)} = 2V$	–	10	–	mA

Note 1. Standard deviation is a measure of the statistical distribution about the mean as derived from the formula:

$$\alpha = \sqrt{\frac{\sum_{n=1}^N (X_n - \bar{X})^2}{N - 1}}$$

Calculation expression of frequency is as follows:

$$f_{osc} = \frac{1}{0.817 R_T \bullet C_T + 1.42 \bullet 10^{-6}} \text{ (Hz)} \quad [R_T] = \Omega, [C_T] = F$$

Note 2. Maximum duration of short-circuit condition is 1sec (non-repetitive).



