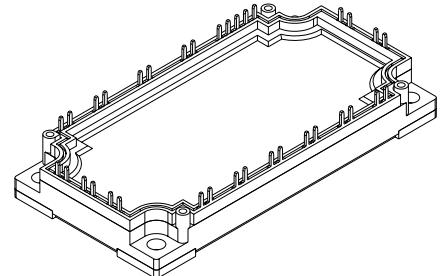
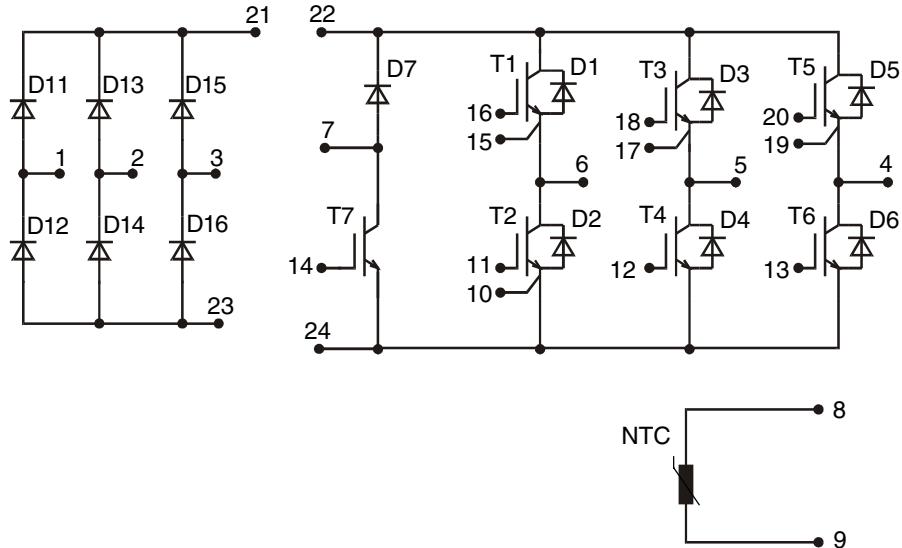


Converter - Brake - Inverter Module (CBI3)



| Three Phase Rectifier | Brake Chopper | Three Phase Inverter |
|----------------------------|-------------------------------|-------------------------------|
| $V_{RRM} = 1600 \text{ V}$ | $V_{CES} = 1200 \text{ V}$ | $V_{CES} = 1200 \text{ V}$ |
| $I_{FAVM} = 42 \text{ A}$ | $I_{C25} = 35 \text{ A}$ | $I_{C25} = 50 \text{ A}$ |
| $I_{FSM} = 300 \text{ A}$ | $V_{CE(sat)} = 2.3 \text{ V}$ | $V_{CE(sat)} = 2.5 \text{ V}$ |

Input Rectifier D11 - D16

| Symbol | Conditions | Maximum Ratings | | |
|------------|--|-----------------|--|---|
| V_{RRM} | | 1600 | | V |
| I_{FAV} | $T_c = 80^\circ\text{C}$; sine 180° | 30 | | A |
| I_{DAVM} | $T_c = 80^\circ\text{C}$; rectangular; $d = 1/3$; bridge | 80 | | A |
| I_{FSM} | $T_{VJ} = 25^\circ\text{C}$; $t = 10 \text{ ms}$; sine 50 Hz | 300 | | A |
| P_{tot} | $T_c = 25^\circ\text{C}$ | 100 | | W |

Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

Features

- High level of integration - only one power semiconductor module required for the whole drive
- NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

| Symbol | Conditions | Characteristic Values | | |
|------------|--|---|------|---------|
| | | ($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified) | | |
| | | min. | typ. | max. |
| V_F | $I_F = 35 \text{ A}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | | 1.2 | 1.4 V |
| | | | 1.2 | V |
| I_R | $V_R = V_{RRM}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | | 0.02 | mA |
| | | | 0.4 | mA |
| R_{thJC} | (per diode) | | | 1.3 K/W |

Output Inverter T1 - T6

| Symbol | Conditions | Maximum Ratings | | |
|-----------------------------------|---|---|---------------|---|
| V_{CES} | $T_{VJ} = 25^\circ\text{C}$ to 150°C | 1200 | | V |
| V_{GES} | Continuous | ± 20 | | V |
| I_{C25} | $T_C = 25^\circ\text{C}$ | 50 | | A |
| I_{C80} | $T_C = 80^\circ\text{C}$ | 35 | | A |
| RBSOA | $V_{GE} = \pm 15 \text{ V}$; $R_G = 47 \Omega$; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$ | $I_{CM} = 50$ $V_{CEK} \leq V_{CES}$ | | A |
| t_{sc} (SCSOA) | $V_{CE} = V_{CES}$; $V_{GE} = \pm 15 \text{ V}$; $R_G = 47 \Omega$; $T_{VJ} = 125^\circ\text{C}$ non-repetitive | 10 | μs | |
| P_{tot} | $T_C = 25^\circ\text{C}$ | 225 | | W |

| Symbol | Conditions | Characteristic Values | | |
|--|---|--|-------------|----------------------------------|
| | | $(T_{VJ} = 25^\circ\text{C}, \text{unless otherwise specified})$ | min. | typ. |
| $V_{CE(sat)}$ | $I_C = 35 \text{ A}$; $V_{GE} = 15 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | 2.5 2.9 | 3.1 | V |
| $V_{GE(th)}$ | $I_C = 1 \text{ mA}$; $V_{GE} = V_{CE}$ | 4.5 | 6.5 | V |
| I_{CES} | $V_{CE} = V_{CES}$; $V_{GE} = 0 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | 1.0 | 1.1 | mA |
| I_{GES} | $V_{CE} = 0 \text{ V}$; $V_{GE} = \pm 20 \text{ V}$ | | 200 | nA |
| $t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off} | $\left. \begin{array}{l} \text{Inductive load, } T_{VJ} = 125^\circ\text{C} \\ V_{CE} = 600 \text{ V}; I_C = 35 \text{ A} \\ V_{GE} = \pm 15 \text{ V}; R_G = 47 \Omega \end{array} \right\}$ | 100 70 500 70 5.3 3.9 | | ns ns ns ns mJ mJ |
| C_{ies} | | 1.65 | | nF |
| Q_{Gon} | | 120 | | nC |
| R_{thJC} | | | 0.55 | K/W |

Output Inverter D1 - D6

| Symbol | Conditions | Maximum Ratings | | |
|---------------|--------------------------|------------------------|--|---|
| I_{F25} | $T_C = 25^\circ\text{C}$ | 50 | | A |
| I_{F80} | $T_C = 80^\circ\text{C}$ | 35 | | A |

| Symbol | Conditions | Characteristic Values | | |
|---------------|--|------------------------------|-------------|-------------|
| | | min. | typ. | max. |
| V_F | $I_F = 35 \text{ A}$; $V_{GE} = 0 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | 2.4 1.8 | 2.8 | V |
| t_{rr} | $\left. \begin{array}{l} I_F = 30 \text{ A}; di_F/dt = -500 \text{ A}/\mu\text{s} \\ V_R = 600 \text{ V}; V_{GE} = 0 \text{ V} \end{array} \right\}$ | 27 150 | | A ns |
| R_{thJC} | | | 1.19 | K/W |

Brake Chopper T7

| Symbol | Conditions | Maximum Ratings | | |
|-----------------------------------|---|---|---------|---|
| V_{CES} | $T_{VJ} = 25^\circ C$ to $150^\circ C$ | 1200 | | V |
| V_{GES} | Continuous | ± 20 | | V |
| I_{C25} | $T_C = 25^\circ C$ | 35 | | A |
| I_{C80} | $T_C = 80^\circ C$ | 25 | | A |
| RBSOA | $V_{GE} = \pm 15 V$; $R_G = 82 \Omega$; $T_{VJ} = 125^\circ C$ Clamped inductive load; $L = 100 \mu H$ | $I_{CM} = 35$ $V_{CEK} \leq V_{CES}$ | | A |
| t_{sc} (SCSOA) | $V_{CE} = V_{CES}$; $V_{GE} = \pm 15 V$; $R_G = 82 \Omega$; $T_{VJ} = 125^\circ C$ non-repetitive | 10 | μs | |
| P_{tot} | $T_C = 25^\circ C$ | 180 | | W |

| Symbol | Conditions | Characteristic Values | | |
|--|--|---|-------------|----------------------------------|
| | | ($T_{VJ} = 25^\circ C$, unless otherwise specified) | | |
| | | min. | typ. | max. |
| $V_{CE(sat)}$ | $I_C = 20 A$; $V_{GE} = 15 V$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | 2.3 2.6 | 3.0 V | V |
| $V_{GE(th)}$ | $I_C = 0.6 mA$; $V_{GE} = V_{CE}$ | 4.5 | | 6.5 V |
| I_{CES} | $V_{CE} = V_{CES}$; $V_{GE} = 0 V$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | | 0.8 0.8 | mA mA |
| I_{GES} | $V_{CE} = 0 V$; $V_{GE} = \pm 20 V$ | | 200 | nA |
| $t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off} | Inductive load, $T_{VJ} = 125^\circ C$ $V_{CE} = 600 V$; $I_C = 20 A$ $V_{GE} = \pm 15 V$; $R_G = 82 \Omega$ | 100 75 500 70 3.1 2.4 | | ns ns ns ns mJ mJ |
| C_{ies} Q_{Gon} | | 1 70 | | nF nC |
| R_{thJC} | | | 0.7 | K/W |

Brake Chopper D7

| Symbol | Conditions | Maximum Ratings | | |
|----------------------|---|------------------------------|-------------|-------------|
| V_{RRM} | $T_{VJ} = 25^\circ C$ to $150^\circ C$ | 1200 | | V |
| I_{F25} | $T_C = 25^\circ C$ | 16 | | A |
| I_{F80} | $T_C = 80^\circ C$ | 11 | | A |
| Symbol | Conditions | Characteristic Values | | |
| | | min. | typ. | max. |
| V_F | $I_F = 20 A$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | 3.2 2.5 | 3.6 V | V |
| I_R | $V_R = V_{RRM}$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | 0.07 | 0.06 mA | mA |
| I_{RM} t_{rr} | $I_F = 10 A$; $dI_F/dt = -400 A/\mu s$; $T_{VJ} = 125^\circ C$ $V_R = 600 V$ | 13 110 | | A ns |
| R_{thJC} | | | 3.2 | K/W |

Temperature Sensor NTC

| Symbol | Conditions | Characteristic Values | | |
|-------------------------|------------------------|-----------------------|-------------|----------------------|
| | | min. | typ. | max. |
| R_{25} $B_{25/50}$ | $T = 25^\circ\text{C}$ | 4.75 | 5.0 3375 | 5.25 k Ω K |

Module

| Symbol | Conditions | Maximum Ratings | | |
|------------|--|-----------------|------------------|--|
| T_{VJ} | | -40...+150 | $^\circ\text{C}$ | |
| T_{JM} | | 150 | $^\circ\text{C}$ | |
| T_{stg} | | -40...+125 | $^\circ\text{C}$ | |
| V_{ISOL} | $I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$ | 2500 | V~ | |
| M_d | Mounting torque (M5) | 3 - 6 | Nm | |

| Symbol | Conditions | Characteristic Values | | |
|----------------|------------------------------|-----------------------|------|------------|
| | | min. | typ. | max. |
| $R_{pin-chip}$ | | | 5 | m Ω |
| d_s | Creepage distance on surface | 6 | | mm |
| d_A | Strike distance in air | 6 | | mm |
| R_{thCH} | with heatsink compound | 0.01 | | K/W |
| Weight | | 300 | | g |

Dimensions in mm (1 mm = 0.0394")

