

FEDL9208-01<u>Issue Date: Feb.</u> 23, 2004

ML9208-xx

5 × 7 Dot Character × 16-Digit Display Controller/Driver with Character RAM

GENERAL DESCRIPTION

The ML9208-xx is a dot matrix vacuum fluorescent display tube controller driver IC which displays characters, numerics and symbols.

Dot matrix vacuum fluorescent display tube drive signals are generated by serial data sent from a micro-controller. A display system is easily realized by internal ROM and RAM for character display.

FEATURES

• Logic power supply and vacuum fluorescent display tube drive power supply (V_{DD})

: $3.3 \text{ V} \pm 10\% \text{ or } 5.0 \text{ V} \pm 10\%$

• Fluorescent display tube drive power supply (V_{FL}) : V_{DD} –20 V to V_{DD} –42 V

• VFD driver output current

(VFD driver output can be connected directly to the fluorescent display tube. No pull-down resistor is required.)

 $\begin{array}{lll} \mbox{- Segment driver (SEG1 to SEG35)} & : -6 \mbox{ mA} & (V_{FL} = V_{DD} - 42 \mbox{ V}) \\ \mbox{- Segment driver (AD1 and AD2)} & : -15 \mbox{ mA} & (V_{FL} = V_{DD} - 42 \mbox{ V}) \\ \mbox{- Grid driver (COM1 to COM16)} & : -30 \mbox{ mA} & (V_{FL} = V_{DD} - 42 \mbox{ V}) \\ \end{array}$

• General output port output current

- Output driver (P1 and P2) $\pm 1 \text{ mA } (V_{DD} = 3.3 \text{ V} \pm 10\%)$ $\pm 2 \text{ mA } (V_{DD} = 5.0 \text{ V} \pm 10\%)$

• Content of display

- CGROM 5×7 dots : 248 types (character data) - CGRAM 5×7 dots : 8 types (character data)

- ADRAM 16 (display digit) × 2 bits (symbol data)

- DCRAM 16 (display digit) × 8 bits (register for character data display)

- General output port 2 bits (static operation)

• Display control function

Display digit : 9 to 16 digitsDisplay duty (contrast adjustment) : 8 stages

- All lights ON/OFFs

• 3 interfaces with microcontroller : DA, \overline{CS} , \overline{CP} (4 interfaces when \overline{RESET} is added)

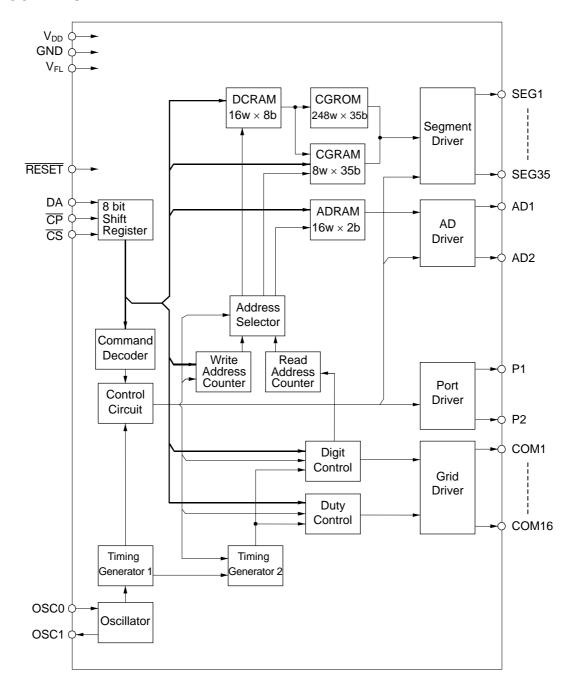
• 1-byte instruction execution (excluding data write to RAM)

• Built-in oscillation circuit (external R and C)

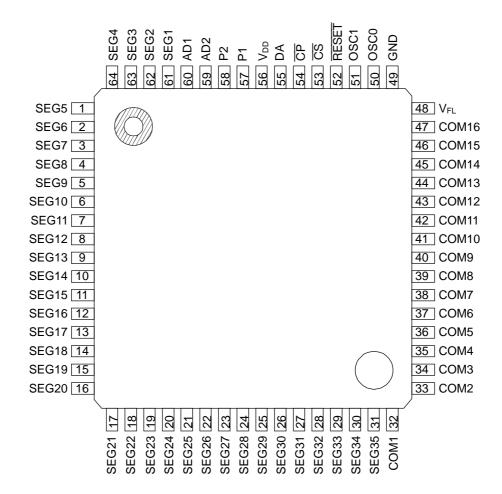
• Package options:

64-pin plastic QFP (QFP64-P-1414-0.80-BK) (ML9208-xxGA) 64-pin plastic SSOP (SSOP64-P-525-0.80-K) (ML9208-xxMB)

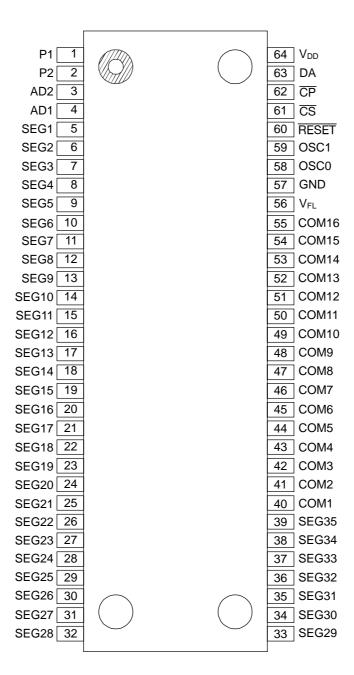
BLOCK DIAGRAM



PIN CONFIGURATION (TOP VIEW)



64-Pin Plastic QFP



64-Pin Plastic SSOP

PIN DESCRIPTION

P	in									
QFP	SSOP	Symbol	Type	Connects to	Description					
1 to 31, 61 to 64	5 to 39	SEG1 to 35	0	Fluorescent tube anode electrode	Fluorescent display tube anode electrode drive output. Directly connected to fluorescent display tube and a pull-down resistor is not necessary. I _{OH} > -6 mA					
32 to 47	40 to 55	COM1 to 16	0	Fluorescent tube grid electrode	Fluorescent display tube grid electrode drive output. Directly connected to fluorescent display tube and a pull-down resistor is not necessary. I _{OH} > -30 mA					
59, 60	3, 4	AD1, AD2	0	Fluorescent tube anode electrode	Fluorescent display tube anode electrode drive output. Directly connected to fluorescent display tube and a pull-down resistor is not necessary. $I_{OH} > -15 \text{ mA}$					
57, 58	1, 2	P1, P2	0	LED drive control pins	General port output. Output of these pins in static operation, so these pins can drive the LED.					
56	64	V_{DD}			V _{DD} -GND are power supplies for internal logic.					
49	57	GND	_	Power supply	V_{DD} - V_{FL} are power supplies for driving fluorescent tubes.					
48	56	V_{FL}			Apply V _{FL} after V _{DD} is applied.					
55	63	DA	- 1	Microcontroller	Serial data input (positive logic). Input from LSB.					
					Shift clock input.					
54	62	СP	I	Microcontroller	Serial data is shifted on the rising edge of $\overline{\sf CP}$.					
53	61	CS	ı	Microcontroller	Chip select input.					
	01	65	'	Microcontroller	Serial data transfer is disabled when $\overline{\text{CS}}$ pin is "H" level.					
52	60	RESET	ı	Microcontroller or C ₂ , R ₂	Reset input. "Low" initializes all the functions. Initial status is as follows. • Address of each RAM ···· address "00"H • Data of each RAM ···· Content is undefined • Display digit ···· 16 digits • Contrast adjustment ··· 8/16 • All lights ON or OFF ··· OFF mode • All outputs ··· "Low" level RESET (Circuit when R and C are connected externally) See Application Circuit.					
50	58	OSC0	I		External RC pin for RC oscillation. Connect R and C externally. The RC time constant depends on the V_{DD} voltage used. Set the target oscillation frequency to 2 MHz.					
51	59	OSC1	0	C ₁ , R ₁	$\begin{array}{c c} \hline OSC0 \\ \hline \hline OSC1 \\ \hline \end{array} \begin{array}{c} R_1 \\ \hline \end{array} \begin{array}{c} C_1 \\ \hline \end{array} \begin{array}{c} \text{(RC oscillation circuit)} \\ \hline \end{array}$					

ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Condition		Rating	Unit	
Supply Voltage (1)	V_{DD}	_	_		V	
Supply Voltage (2)	V_{FL}	_		-45 to V _{DD} +0.3	V	
Input Voltage	V_{IN}	_		-0.3 to V _{DD} +0.3	V	
Dower Dissipation	D	Ta ≥ 25°C	QFP	541	mW	
Power Dissipation	P _D	1a ≥ 25 C	SSOP	590		
Storage Temperature	T _{STG}	_		-55 to 150	°C	
	I _{O1}	COM1 to 16	-40 to 0.0	mA		
Output Current	I _{O2}	AD1, AD2	AD1, AD2		mA	
Output Current	I _{O3}	SEG1 to 35	SEG1 to 35		mA	
	I _{O4}	P1, P2		-4.0 to 4.0	mA	

RECOMMENDED OPERATING CONDITIONS-1

When the power supply voltage is 5 V (typ.)

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit
Supply Voltage (1)	V_{DD}	_	4.5	5.0	5.5	V
Supply Voltage (2)	V_{FL}	_	-36.5	_	-20	٧
High Level Input Voltage	V _{IH}	All input pins excluding OSC0 pin	$0.7~V_{DD}$	_	_	V
Low Level Input Voltage	V_{IL}	All input pins excluding OSC0 pin	_	_	$0.3\ V_{DD}$	V
CP Frequency	f _C	_	_	_	2.0	MHz
Oscillation Frequency	fosc	$R_1 = 3.3 \text{ k}\Omega, C_1 = 39 \text{ pF}$	1.5	2.0	2.5	MHz
Frame Frequency	f _{FR}	DIGIT = 1 to 16, $R_1 = 3.3 \text{ k}\Omega$, $C_1 = 39 \text{ pF}$	183	244	305	Hz
Operating Temperature	T _{op}	_	-40	_	85	°C

RECOMMENDED OPERATING CONDITIONS-2

When the power supply voltage is 3.3 V (typ.)

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit
Supply Voltage (1)	V_{DD}	_	3.0	3.3	3.6	V
Supply Voltage (2)	V_{FL}		-38.4	_	-20	V
High Level Input Voltage	V_{IH}	All input pins excluding OSC0 pin	$0.8\ V_{DD}$	_	_	V
Low Level Input Voltage	V_{IL}	All input pins excluding OSC0 pin	_	_	$0.2\ V_{DD}$	V
CP Frequency	f _C	_	_	_	2.0	MHz
Oscillation Frequency	fosc	$R_1 = 3.3 \text{ k}\Omega, C_1 = 39 \text{ pF}$	1.5	2.0	2.5	MHz
Frame Frequency	f _{FR}	DIGIT = 1 to 16, $R_1 = 3.3 \text{ k}\Omega$, $C_1 = 39 \text{ pF}$	183	244	305	Hz
Operating Temperature	T _{op}	_	-40	_	85	°C

ELECTRICAL CHARACTERISTICS

DC Characteristics-1

(V_{DD} = 5.0 V ±10%, V_{FL} = V_{DD} -42 V, Ta = -40 to +85°C, unless otherwise specified)

(VDD = 3.0 V ±1070, VFL = VDD = 42 V, Ta = -40 to +03 G, driless otherwise specified)									
Parameter	Symbol	Applied pin		Condition	Min.	Max.	Unit		
High Level Input Voltage	V _{IH}	CS, CP, DA, RESET		_	0.7 V _{DD}		V		
Low Level Input Voltage	V _{IL}	CS, CP, DA, RESET	_		_	0.3 V _{DD}	V		
High Level Input Current	I _{IH}	CS, CP, DA, RESET	$V_{IH} = V_{DD}$		-1.0	1.0	μΑ		
Low Level Input Current	I _{IL}	CS, CP, DA, RESET	V _{IL} = 0.0 V		-1.0	1.0	μΑ		
	V _{OH1}	COM1 to 16	$I_{OH1} = -30 \text{ mA}$		V _{DD} -1.5	_	V		
High Level Output Voltage	V _{OH2}	AD1, AD2	I,	$_{OH2} = -15 \text{ mA}$	V _{DD} -1.5	_	V		
riigir Level Output voltage	V_{OH3}	SEG1 to 35	$I_{OH3} = -6 \text{ mA}$		V _{DD} -1.5	_	V		
	V _{OH4}	P1, P2		$I_{OH4} = -2 \text{ mA}$		$I_{OH4} = -2 \text{ mA}$		_	V
Low Level Output Voltage	V _{OL1}	COM1 to 16 AD1, AD2 SEG1 to 35		_	_	V _{FL} +1.0	V		
	V_{OL2}	P1, P2		$I_{OL1} = 2 \text{ mA}$	_	1.0	V		
	I _{DD1}		fosc =	Duty = 15/16 Digit = 1 to 16 All output lights ON	_	4	mA		
Current Consumption	I _{DD2}	V_{DD}	2 MHz, no load	Duty = 8/16 Digit = 1 to 9 All output lights OFF	_	3	mA		

DC Characteristics-2

(V_{DD} = 3.3 V \pm 10%, V_{FL} = V_{DD} -42 V, Ta = -40 to +85°C, unless otherwise specified)

Parameter	Symbol	Applied pin		Condition	Min.	Max.	Unit		
High Level Input Voltage	V _{IH}	CS, CP, DA, RESET		_	0.8 V _{DD}	_	V		
Low Level Input Voltage	V _{IL}	CS, CP, DA, RESET			_	0.2 V _{DD}	V		
High Level Input Current	I _{IH}	$\overline{\text{CS}}, \overline{\text{CP}},$ DA, $\overline{\text{RESET}}$	$V_{IH} = V_{DD}$		-1.0	1.0	μΑ		
Low Level Input Current	I _{IL}	$\overline{\text{CS}}, \overline{\text{CP}},$ DA, $\overline{\text{RESET}}$	V _{IL} = 0.0 V		-1.0	1.0	μΑ		
	V _{OH1}	COM1 to 16	$I_{OH1} = -30 \text{ mA}$		$I_{OH1} = -30 \text{ mA}$ V_{DD}		V _{DD} -1.5	_	V
High Lavel Output Valtage	V_{OH2}	AD1, AD2	$I_{OH2} = -15 \text{ mA}$		V _{DD} -1.5	_	V		
High Level Output Voltage	V _{OH3}	SEG1 to 35		$I_{OH3} = -6 \text{ mA}$		_	V		
	V_{OH4}	P1, P2		$I_{OH4} = -1 \text{ mA}$		_	V		
Low Level Output Voltage	V _{OL1}	COM1 to 16 AD1, AD2 SEG1 to 35	_		_	V _{FL} +1.0	٧		
	V_{OL2}	P1, P2		$I_{OL1} = 1 \text{ mA}$	_	1.0	V		
-	I _{DD1}	.,	F _{osc} =	Duty = 15/16 Digit = 1 to 16 All output lights ON	_	3	mA		
Current Consumption	I _{DD2}	V_{DD}	2 MHz, no load	Duty = 8/16 Digit = 1 to 9 All output lights OFF	_	2	mA		

AC Characteristics-1

(V_{DD} = 5.0 V \pm 10%, V_{FL} = V_{DD} -42 V, Ta = -40 to +85°C, unless otherwise specified)

(100 - 0.0 1 - 1070) 12 1, 14 - 10 to 100 0; amos other med openious							
Parameter	Symbol	Condition	on	Min.	Max.	Unit	
CP Frequency	f _C	_		_	2.0	MHz	
CP Pulse Width	t _{CW}	_	250	_	ns		
DA Setup Time	t _{DS}	_	_			ns	
DA Hold Time	t _{DH}	_		250	_	ns	
CS Setup Time	t _{CSS}	_		250	_	ns	
CS Hold Time	t _{CSH}	$R_1 = 3.3 \text{ k}\Omega, C_2$	ı = 47 pF	16	_	μS	
CS Wait Time	t _{CSW}	_	— 25		_	ns	
Data Processing Time	t _{DOFF}	$R_1 = 3.3 \text{ k}\Omega, C_2$	8	_	μS		
RESET Pulse Width	t _{WRES}	When RESET signa microcontroller etc	250	_	ns		
RESET Time	t _{RSON}	When RESET signa microcontroller etc	•	250		ns	
		$R_2 = 1.0 \text{ k}\Omega, C_2$	= 0.1 μF		200	μS	
DA Wait Time	t _{RSOFF}	_		250	_	ns	
All Output Slow Poto	t _R	C - 100 pF	t _R = 20 to 80%	_	2.0	μS	
All Output Slew Rate	t _F	$C_1 = 100 \text{ pF}$	t _F = 80 to 20%		2.0	μS	
V _{DD} Rise Time	t _{PRZ}	When mounted	in the unit	_	100	μS	
V _{DD} Off Time	t _{POF}	When mounted in the	5.0	_	ms		

AC Characteristics-2

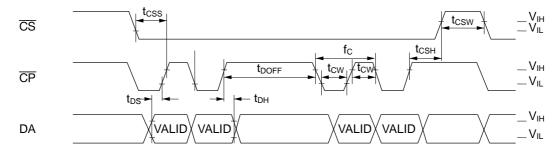
(V_{DD} = 3.3 V \pm 10%, V_{FL} = V_{DD} -42 V, Ta = -40 to +85°C, unless otherwise specified)

(VDD = 0.0 V ±1070, VFL = VDD 12 V, Ta = 10 to 100 C, amode canor mod openinea)							
Parameter	Symbol	Condition	on	Min.	Max.	Unit	
CP Frequency	f _C	_		_	2.0	MHz	
CP Pulse Width	t _{CW}	_	250	_	ns		
DA Setup Time	t _{DS}	_	250	_	ns		
DA Hold Time	t _{DH}	_		250	_	ns	
CS Setup Time	t _{CSS}	_		250	_	ns	
CS Hold Time	t _{CSH}	$R_1 = 3.3 \text{ k}\Omega, C_1$	₁ = 39 pF	16	_	μS	
CS Wait Time	t _{CSW}	_	250	_	ns		
Data Processing Time	t _{DOFF}	$R_1 = 3.3 \text{ k}\Omega, C_1$	8	_	μS		
RESET Pulse Width	t _{WRES}	When RESET signa microcontroller etc	250	_	ns		
RESET Time	t _{RSON}	When RESET signa microcontroller etc	•	250	_	ns	
		$R_2 = 1.0 \text{ k}\Omega, C_2$	e = 0.1 μF		200	μS	
DA Wait Time	t _{RSOFF}	_		250	_	ns	
All Output Claus Data	t _R	C 400 = F	t _R = 20 to 80%	_	2.0	μS	
All Output Slew Rate	t _F	$C_1 = 100 \text{ pF}$	t _F = 80 to 20%	_	2.0	μS	
V _{DD} Rise Time	t _{PRZ}	When mounted in the unit			100	μS	
V _{DD} Off Time	t _{POF}	When mounted in the	5.0	_	ms		

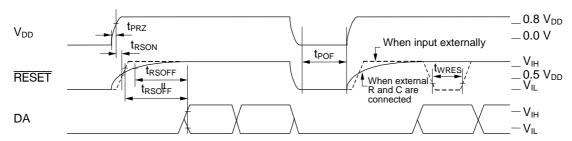
TIMING DIAGRAM

Symbol	$V_{DD} = 3.3 \text{ V} \pm 10\%$	$V_{DD} = 5.0 \text{ V} \pm 10\%$				
V _{IH}	0.8 V _{DD}	0.7 V _{DD}				
V _{IL}	0.2 V _{DD}	0.3 V _{DD}				

• Data Timing



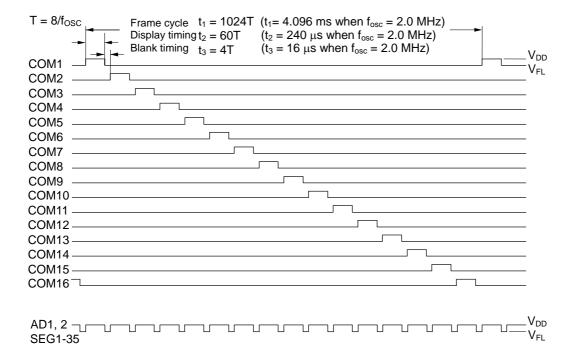
• Reset Timing



• Output Timing



• Digit Output Timing (for 16-digit display, at a duty of 15/16)



FUNCTIONAL DESCRIPTION

Commands List

	Command	LSB			1st	byte			MSB	LSB			2nd	byte			MSB	
		В0	В1	B2	ВЗ	В4	B5	В6	В7	В0	В1	B2	ВЗ	B4	B5	B6	В7	
1	DCRAM data write	X0	X1	X2	Х3	1	0	0	0	C0	C1	C2	СЗ	C4	C5	C6	C7	
										C0	C5	C10	C15	C20	C25	C30	*	2nd byte
										C1	C6	C11	C16	C21	C26	C31	*	3rd byte
2	CGRAM data write	X0	X1	X2	*	0	1	0	0 0	C2	C7	C12	C17	C22	C27	C32	*	4th byte
										СЗ	C8	C13	C18	C23	C28	C33	*	5th byte
										C4	6 9	C14	C19	C24	C29	C34	*	6th byte
3	ADRAM data write	X0	X1	X2	Х3	1	1	0	0	C0	C1	*	*	*	*	*	*	
4	General output port set	P1	P2	*	*	0	0	1	0	*.		n't c						
5	Display duty set	D0	D1	D2	*	1	0	1	0									ch RAM
6	Number of digits set	K0	K1	K2	*	0	1	1	0	 Character code specification for each RAM 					ioi eacii			
7	All lights ON/OFF	L	Н	*	*	1	1	1	0	-								
	Test mode									specification								
		•	•	•						· Dn	· Die	nlav	dut	v sp	ےcifi	ratio	n	

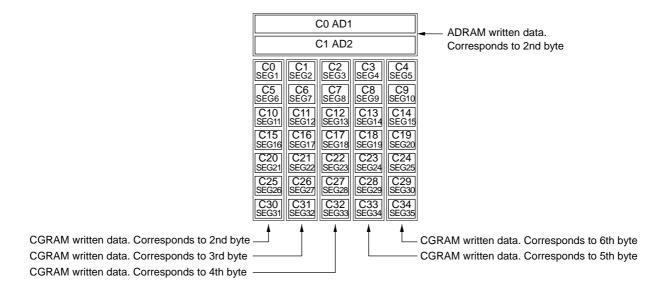
Dn: Display duty specification
Kn: Number of digits specification
H: All lights ON instruction
L: All lights OFF instruction

When data is written to RAM (DCRAM, CGRAM, ADRAM) continuously, addresses are internally incremented automatically.

Therefore it is not necessary to specify the 1st byte to write RAM data for the 2nd and later bytes.

Note: The test mode is used for inspection before shipment. It is not a user function.

Positional Relationship Between SEGn and ADn (one digit)



Data Transfer Method and Command Write Method

Display control command and data are written by an 8-bit serial transfer.

Write timing is shown in the figure below.

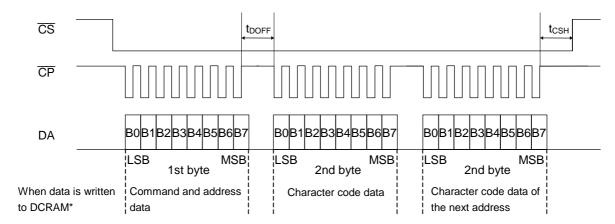
Setting the \overline{CS} pin to "Low" level enables a data transfer.

Data is 8 bits and is sequentially input into the DA pin from LSB (LSB first).

As shown in the figure below, data is read by the shift register at the rising edge of the shift clock, which is input into the \overline{CP} pin. If 8-bit data is input, internal load signals are automatically generated and data is written to each register and RAM.

Therefore it is not necessary to input load signals from the outside.

Setting the \overline{CS} pin to "High" disables data transfer. Data input from the point when the \overline{CS} pin changes from "High" to "Low" is recognized in 8-bit units.



^{*} When data is written to RAM (DCRAM, ADRAM, CGRAM) continuously, addresses are internally incremented automatically.

Therefore it is not necessary to specify the 1st byte to write RAM data for the 2nd and later bytes.

Reset Function

Reset is executed when the \overline{RESET} pin is set to "L", (when turning power on, for example) and initializes all functions.

Initial status is as follows.

- Address of each RAM address "00"H
- Data of each RAM All contents are undefined
- General output port All general output ports go "Low"
- Display digit ····· 16 digits
- Contrast adjustment ····· 8/16
- All display lights ON or OFF OFF mode
- Segment output All segment outputs go "Low"
- AD output ······ All AD outputs go "Low"

Please set again according to "Setting Flowchart" after reset.

Description of Commands and Functions

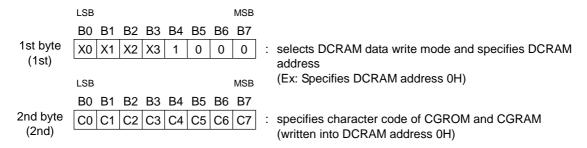
 DCRAM data write (Specifies the address of DCRAM and writes the character code of CGROM and CGRAM.)

DCRAM (Data Control RAM) has a 4-bit address to store character code of CGROM and CGRAM.

The character code specified by DCRAM is converted to a 5×7 dot matrix character pattern via CGROM or CGRAM.

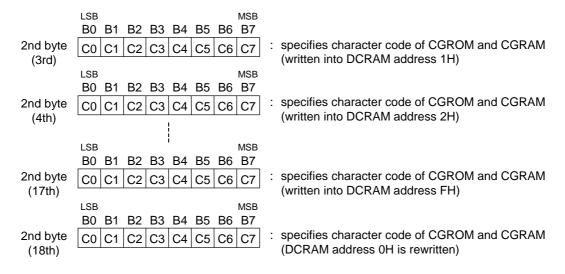
(The DCRAM can store 16 characters.)

[Command format]



To specify the character code of CGROM and CGRAM continuously to the next address, specify only character code as follows.

The addresses of DCRAM are automatically incremented. Specification of an address is unnecessary.



X0 (LSB) to X3 (MSB): DCRAM addresses (4 bits: 16 characters)

C0 (LSB) to C7 (MSB): Character code of CGROM and CGRAM (8 bits: 256 characters)

[COM positions and set DCRAM addresses]

HEX	X0	X1	X2	ХЗ	COM
	Χ0	٨١	^2	۸٥	position
0	0	0	0	0	COM1
1	1	0	0	0	COM2
2	0	1	0	0	COM3
3	1	1	1	0	COM4
4	0	0	1	0	COM5
5	1	0	1	0	COM6
6	0	1	1	0	COM7
7	1	1	1	0	COM8
8	0	0	0	1	COM9
9	1	0	0	1	COM10
Α	0	1	0	1	COM11
В	1	1	0	1	COM12
С	0	0	1	1	COM13
D	1	0	1	1	COM14
Е	0	1	1	1	COM15
F	1	1	1	1	COM16

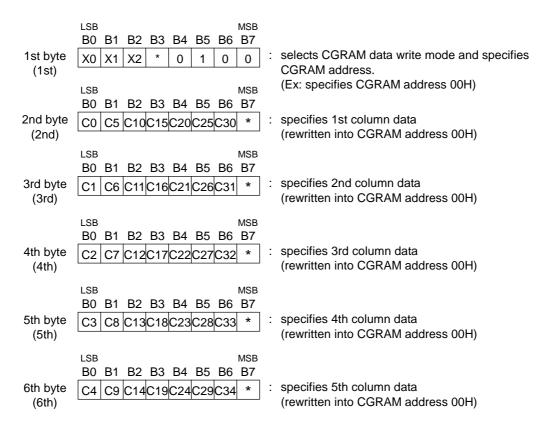
2. CGRAM data write

(Specifies the addresses of CGRAM and writes character pattern data.)

CGRAM (Character Generator RAM) has a 3-bit address to store 5×7 dot matrix character patterns. A character pattern stored in CGRAM can be displayed by specifying the character code (address) by DCRAM.

The address of CGRAM is assigned to 00H to 07H. (All the other addresses are the CGROM addresses.) (The CGRAM can store 8 types of character patterns.)

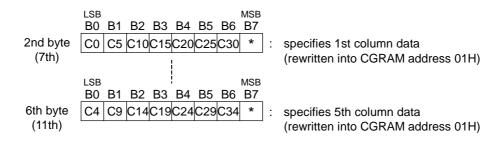
[Command format]



To specify character pattern data continuously to the next address, specify only character pattern data as follows.

The addresses of CGRAM are automatically incremented. Specification of an address is therefore unnecessary.

The 2nd to 6th byte (character pattern data) are regarded as one data item, so 250 ns is sufficient for t_{DOFF} time between bytes.



X0 (LSB) to X2 (MSB) : CGRAM addresses (3 bits: 8 characters)

C0 (LSB) to C34 (MSB) : Character pattern data (35 bits: 35 outputs per digit)

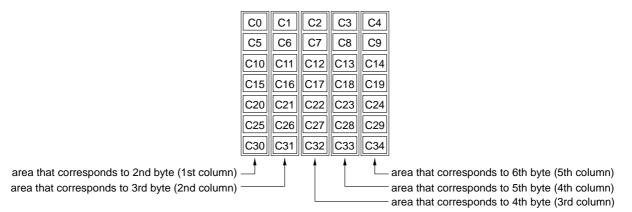
* : Don't care

[CGROM addresses and set CGRAM addresses]

Refer to ROMCODE table

HEX	X0	X1	X2	CGROM address
00	0	0	0	RAM00(00000000B)
01	1	0	0	RAM01(00000001B)
02	0	1	0	RAM02(00000010B)
03	1	1	0	RAM03(00000011B)
04	0	0	1	RAM04(00000100B)
05	1	0	1	RAM05(00000101B)
06	0	1	1	RAM06(00000110B)
07	1	1	1	RAM07(00000111B)

Positional relationship between the output area of CGROM and that of CGRAM



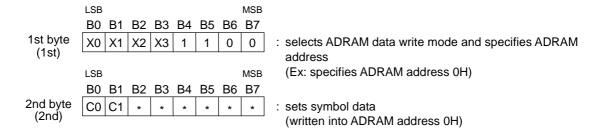
Note: CGROM (Character Generator ROM) has an 8-bit address to generate 5×7 dot matrix character patterns. CGRAM can store 248 types of character patterns.

3. ADRAM data write

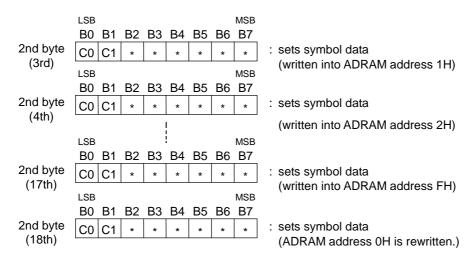
(specifies address of ADRAM and writes symbol data)

ADRAM (Additional Data RAM) has a 2-bit address to store symbol data. Symbol data specified by ADRAM is directly output without CGROM and CGRAM. (The ADRAM can store 2 types of symbol patterns for each digit.) The terminal to which the contents of ADRAM are output can be used as a cursor.

[Command format]



To specify symbol data continuously to the next address, specify only symbol data as follows. The address of ADRAM is automatically incremented. Specification of addresses is therefore unnecessary.



X0 (LSB) to X3 (MSB): ADRAM addresses (4 bits: 16 characters)
C0 (LSB) to C1 (MSB): Symbol data (2 bits: 2-symbol data per digit)
*: Don't care

[COM positions and ADRAM addresses]

HEX	X0	X1	X2	Х3	COM position
0	0	0	0	0	COM1
1	1	0	0	0	COM2
2	0	1	0	0	COM3
3	1	1	1	0	COM4
4	0	0	1	0	COM5
5	1	0	1	0	COM6
6	0	1	1	0	COM7
7	1	1	1	0	COM8
8	0	0	0	1	COM9
9	1	0	0	1	COM10
Α	0	1	0	1	COM11
В	1	1	0	1	COM12
С	0	0	1	1	COM13
D	1	0	1	1	COM14
Е	0	1	1	1	COM15
F	1	1	1	1	COM16

4. General output port set

(specifies the general output port status)

The general output port is an output for 2-bit static operation.

It is used to control other I/O devices and turn on LED. (static operation)

When at the "High" level, this output becomes the V_{DD} voltage, and when at the "Low" level, it becomes the ground potential. Therefore, the fluorescent display tube cannot be driven.

[Command format]

P1, P2: general output port

* : don't care

[Set data and set state of general output port]

P1	P2	Display state of general output port
0	0	Sets P1 and P2 to low
1	0	Sets P1 to high and P2 to low
0	1	Sets P1 to low and P2 to high
1	1	Sets P1 and P2 to high

← (The state when power is applied or when RESET is input.)

5. Display duty set

(writes display duty value to duty cycle register)

Display duty adjusts contrast in 8 stages using 3-bit data.

When power is turned on or when the \overline{RESET} signal is input, the duty cycle register value is "0". Always execute this instruction before turning the display on, then set a desired duty value.

[Command format]

D0 (LSB) to D2 (MSB) $\,$: display duty data (3 bits: 8 stages)

* : don't care

[Relation between setup data and controlled COM duty]

HEX	D0	D1	D2	COM duty	
0	0	0	0	8/16	
1	1	0	0	9/16	
2	0	1	0	10/16	
3	1	1	0	11/16	
4	0	0	1	12/16	
5	1	0	1	13/16	
6	0	1	1	14/16	
7	1	1	1	15/16	

← (The state when power is turned on or when RESET signal is input.)

6. Number of digits set

(writes the number of display digits to the display digit register)

The number of digits set can display 9 to 16 digits using 3-bit data.

When power is turned on or when a \overline{RESET} signal is input, the number of digit register value is "0". Always execute this instruction to change the number of digits before turning the dispaly on.

[Command format]

 LSB
 MSB

 B0
 B1
 B2
 B3
 B4
 B5
 B6
 B7

 1st byte
 K0
 K1
 K2
 *
 0
 1
 1
 0

: selects the number of digit set mode and specifies the number of digit value

K0 (LSB) to K2 (MSB) : number of digit data (3 bits: 8 digits)

*: don't care

[Relation between setup data and controlled COM]

HEX	K0	K1	K2	Number of digits of COM
0	0	0	0	COM1 to 16
1	1	0	0	COM1 to 9
2	0	1	0	COM1 to 10
3	1	1	0	COM1 to 11
4	0	0	1	COM1 to 12
5	1	0	1	COM1 to 13
6	0	1	1	COM1 to 14
7	1	1	1	COM1 to 15

← (The state when power is turned on or when RESET signal is input.)

7. All display lights ON/OFF set (turns all dispaly lights ON or OFF)

All display lights ON is used primarily for display testing.

All display lights OFF is primarily used for display blink and to prevent malfunction when power is turned on. This command cannot control the general output port.

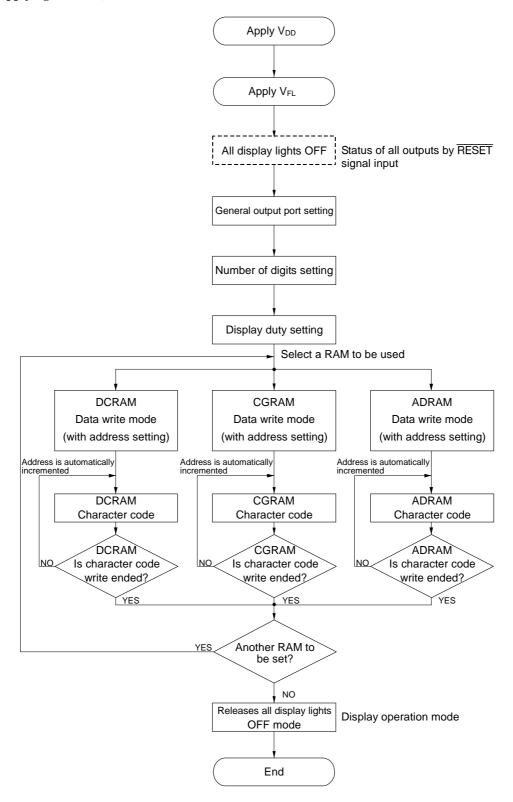
[Command format]

L: sets all lights OFF H: sets all lights ON *: Don't care

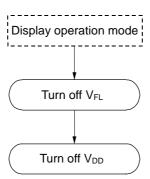
[Set data and display state of SEG and AD]

	L	Н	Display state of SEG and AD	<u> </u>
_	0	0	Normal display	
	1	0	Sets all outputs to Low	\leftarrow (The state when power is applied or when $\overline{\text{RESET}}$ is input.)
_	0	1	Sets all outputs to High	
_	1	1	Sets all outputs to High	← (All lights ON mode has priority.)

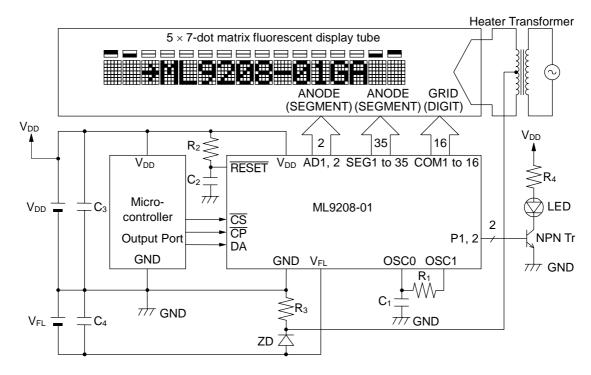
Setting Flowchart (Power applying included)



Power-off Flowchart



APPLICATION CIRCUIT

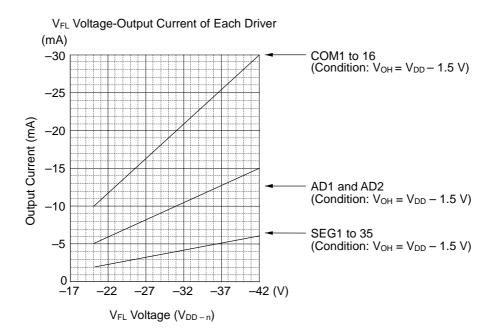


Notes: 1. The V_{DD} value depends on the power supply voltage of the microcontroller used. Adjust the values of the constants R_1 , R_2 , R_4 , C_1 , and C_2 to the power supply voltage used.

2. The V_{FL} value depends on the fluorescent display tube used. Adjust the values of the constants R_3 and ZD to the power supply voltage used.

Reference data

The figure below shows the relationship between the V_{FL} voltage and the output current of each driver. Take care that the total power consumption to be used does not exceed the power dissipation.



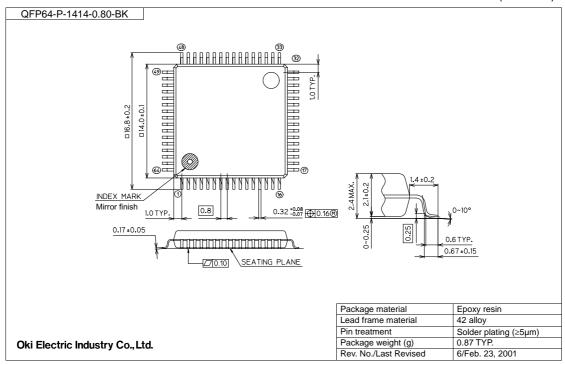
ML9208-01 ROM CODE

 * ROM CODE_A is the character set for SEGA1 to SEGA35. $^{\star}00000000b(00h)$ to 00001111b(0Fh) are the CGRAM_A addresses.

∖ MSB																
LSB	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111
0000	RAM0															
0001	RAM1			· ::::												
0010	RAM2			:::: :::::					::: :::						::::: :::::	
0011	RAM3															
0100	RAM4															
0101	RAM5															
0110	RAM6															
0111	RAM7			:::::::												
1000																
1001																
1010										:::::: :: ::						
1011												!!!!!				
1100	₩															
1101			:::::	*****											• • • • •	
1110																
1111											ш					

PACKAGE DIMENSIONS

(Unit: mm)



Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact Oki's responsible sales person for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

(Unit: mm) SSOP64-P-525-0.80-K 26.0 ± 0.2 10.7 ± 0.2 14.1± 0.3 INDEX MARK 0.8 0.37 *0.08 -0.07 0.16 M 0.6 TYP. 0.7 ± 0.15 0.78 TYP. -[Z] 0.10] SEATING PLANE Package material Epoxy resin 42 alloy Lead frame material Solder plating (≥5µm) 1.34 TYP. Pin treatment Package weight (g)
Rev. No./Last Revised Oki Electric Industry Co., Ltd. 3/Dec. 5, 1996

Notes for Mounting the Surface Mount Type Package

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REVISION HISTORY

Document		Pa	ge			
No.	Date	Previous Edition	Current Edition	Description		
FEDL9208-02	Feb. 23, 2004	-	ı	Final edition 1		

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