

Initial Release

High Speed Quad MOSFET Driver

Features

- □ 6ns rise and fall time with 1000pF load
- □ 2A peak output source/sink current
- 1.2V to 5V input CMOS compatible
- □ 5V to 12V total supply voltage
- Smart Logic threshold
- Low jitter design
- Four matched channels
- Outputs can swing below ground
- Output is high impedence when disabled
- □ Low inductance package
- □ High-performance thermally-enhanced

Applications

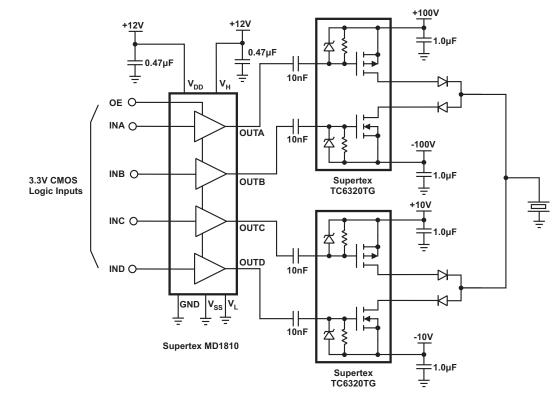
- Medical ultrasound imaging
- Piezoelectric transducer drivers
- Nondestructive evaluation
- PIN diode driver
- CCD Clock driver/buffer
- □ High speed level translator

General Description

The Supertex MD1810 is a high-speed quad MOSFET driver. It is designed to drive high voltage P-and N-channel MOSFETs for medical ultrasound imaging applications. The MD1810 can also be used for ultrasound metal flaw detection, nondestructive evaluation test, piezoelectric transducer drive, clock drive, and PIN diode drive.

The MD1810 has four inputs which individually control four outputs. It also has an output enable (OE) pin. When OE is low, all of the outputs will be in a high impedance state regardless of their logic input control. When OE is high, the MD1810 sets the threshold logic transition to $(V_{OE}+V_{GND})/2$. This ensures the transition to always be at half the amplitude of the logic input signal. This allows the device to have inherent propagation delay matching regardless of the logic input amplitude.

The output stage of the MD1810 has separate power connections enabling the output signal L and H levels to be chosen independently from the V_{DD} and V_{SS} supply voltages. As an example, the input logic levels may be 0 and 1.8 volts, the control logic may be powered by +5 and -5 volts, and the output L and H levels may be varied anywhere over the range of -5 to +5 volts. The output stage is capable of peak currents of up to ±2 amps, depending on the supply voltages used and load capacitance present.



Typical Application Circuit

Ordering Information

DEVICE	Package Option
DEVICE	16-Lead 4x4x0.9 QFN
MD1810	MD1810K6-G
θ _{JA}	45°C/W (1oz. 4-layer 3x4inch PCB)

-G indicates package is RoHS compliant ('Green')

Absolute Maximum Ratings*

$-0.5V \text{ to } +13.5V$ $V_{L}-0.5V \text{ to } V_{DD}+0.5V$ $V_{SS}-0.5V \text{ to } V_{H}+0.5V$ $-7V \text{ to } +0.5V$
V_{ss} -0.5V to V_{H} +0.5V
-7V to +0.5V
V_{ss} -0.5V to V_{ss} +7V
+125°C
-65°C to 150°C
235°C
2.2W

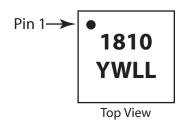
*Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied. Continuous operation of the device at the absolute rating level may affect device reliability. All voltages are referenced to device ground.



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Product Marking Information				
1 ^{s⊤} Line	Device Number	1810		
2 ND Line	Year, Week Code, Lot Number	YWLL		

Example: 5A88 means Lot #88 of first or second week in 2005



DC Electrical Characteristics ($V_{H} = V_{DD} = 12V$, $V_{L} = V_{SS} = GND = 0V$, $V_{OE} = 3.3V$, $T_{J} = 25^{\circ}C$)

Sym.	Parameter	Min.	Тур.	Max.	Units	Conditions
V _{DD} -V _{SS}	Logic supply voltage	4.5		13	V	
V _{ss}	Low side supply voltage	-5.5		0	V	
V _H	Output high supply voltage	V _{ss} +2		V _{DD}	V	
VL	Output low supply voltage	V _{ss}		V _{DD} -2	V	
I _{DDQ}	V _{DD} quiescent current		0.8		mA	No input transitions, OE = 1
I _{HQ}	V _H quiescent current			10	μA	No input transitions, OE – 1
I _{DD}	V _{DD} average current		7.0		mA	One channel on at 5.0Mhz, No load
I _H	V _H average current		18		mA	One channel on at 5.00012, No load
V _{IH}	Input logic voltage high	V _{OE} -0.3		5	V	
V _{IL}	Input logic voltage low	0		0.3	V	For logic inputs INA, INB, INC, and IND
I _{IH}	Input logic current high			1.0	μA	
I _{IL}	Input logic current low			1.0	μA	
V _{IH}	OE Input logic voltage high	1.2		5	V	
V	OE Input logic voltage low	0		0.3	V	For logic input OE
R _{IN}	Input logic impedance to GND	12	20	30	KΩ	
C _{IN}	Logic input capacitance		5	10	pF	

Outputs $(V_{H} = V_{DD} = 12V, V_{L} = V_{SS} = GND = 0V, V_{OE} = 3.3V, T_{J} = 25^{\circ}C)$

Sym.	Parameter	Min.	Тур.	Max.	Units	Conditions
R _{SINK}	Output sink resistance			12.5	Ω	I _{SINK} = 50mA
R _{SOURCE}	Output source resistance			12.5	Ω	I _{SOURCE} = 50mA
I _{sink}	Peak output sink current		2.0		A	
I _{SOURCE}	Peak output source current		2.0		A	

MD1810

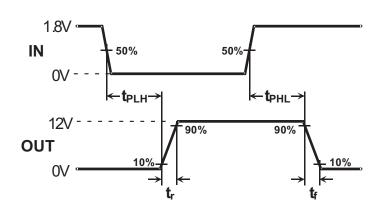
AC Electrical Characteristics $(V_{H} = V_{DD} = 12V, V_{L} = V_{SS} = GND = 0V, V_{OE} = 3.3V, T_{J} = 25^{\circ}C)$

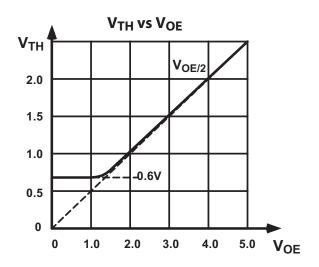
Sym.	Parameter	Min.	Тур.	Max.	Units	Conditions
t _{irf}	Input or OE rise & fall time			10	ns	Logic input edge speed requirement
t _{PLH}	Propagation delay when output is from low to high		7		ns	
t _{PHL}	Propagation delay when output is from high to low		7		ns	C _{LOAD} = 1000pF, see timing diagram
t _{POE}	Propagation delay OE to output		9		ns	Input signal rise/fall time 2ns
t _r	Output rise time		6		ns	
t _r	Output fall time		6		ns	
l t _r - t _f l	Rise and fall time matching		1.0		ns	
l t _{PLH} -t _{PHL} l	Propagation low to high and high to low matching		1.0		ns	for each channel
Δt_{dm}	Propagation delay matching		±2.0		ns	Device to device delay match

Logic Truth Table

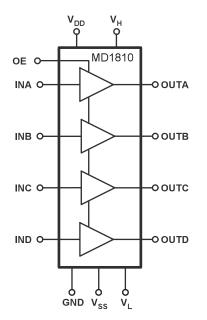
Logic	Qutnut	
OE	IN	Output
Н	L	VL
Н	Н	V _H
L	Х	High Z

Timing Diagram and V_{TH} / V_{OE} Curve

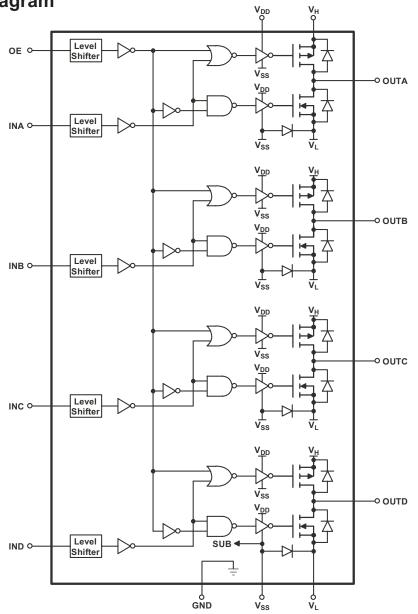




Simplified Block Diagram

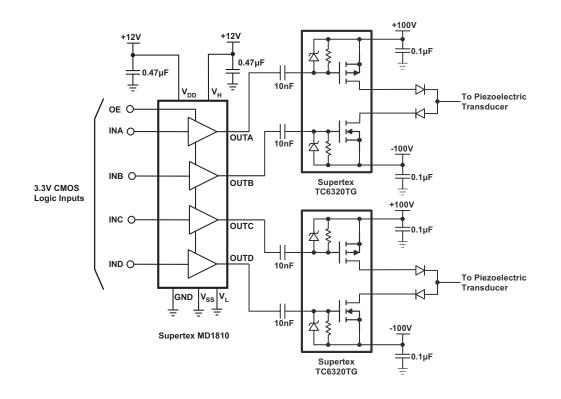


Detailed Block Diagram

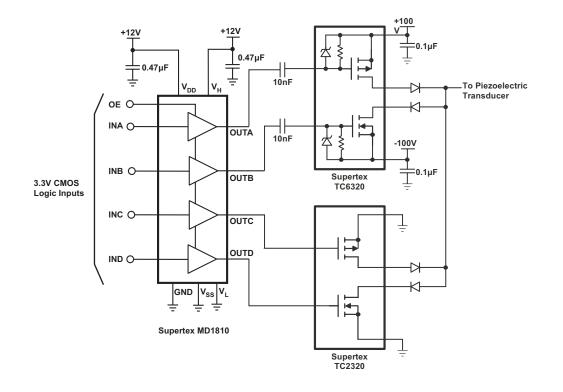


Typical Applications

2-Channel +100V to -100V Pulser



Single Channel ±100V to 0V Pulser



Application Information

For proper operation of the MD1810, low inductance bypass capacitors should be used on the various supply pins. The GND pin should be connected to the logic ground. The INA, INB INC, IND, and OE pins should be connected to a logic source with a swing of GND to $V_{_{\rm LL}},$ where $V_{_{\rm LL}}$ is 1.2 to 5.0 volts. Good trace practices should be followed corresponding to the desired operating speed. The internal circuitry of the MD1810 is capable of operating up to 100MHz, with the primary speed limitation being the loading effects of the load capacitance. Because of this speed and the high transient currents that result with capacitive loads, the bypass capacitors should be as close to the chip pins as possible. Unless the load specifically requires bipolar drive, the V_{ss} , and V_{μ} pins should have low inductance feed-through connections directly to a ground plane. If these voltages are not zero, then they need bypass capacitors in a manner similar to the positive power supplies. The power connection $V_{_{\rm DD}}$ should have a ceramic bypass capacitor to the ground plane with short leads and decoupling components to prevent resonance in the power leads.

The voltages of V_H and V_L decide the output signal levels. These two pins can draw fast transient currents of up to 2A, so they should be provided with an appropriate bypass capacitor located

next to the chip pins. A ceramic capacitor of up to 1.0μ F may be appropriate, with a series ferrite bead to prevent resonance in the power supply lead coming to the capacitor. Pay particular attention to minimizing trace lengths, current loop area and using sufficient trace width to reduce inductance. Surface mount components are highly recommended. Since the output impedance of this driver is very low, in some cases it may be desirable to add a small series resistance in series with the output signal to obtain better waveform transitions at the load terminals. This will of course reduce the output voltage slew rate at the terminals of a capacitive load.

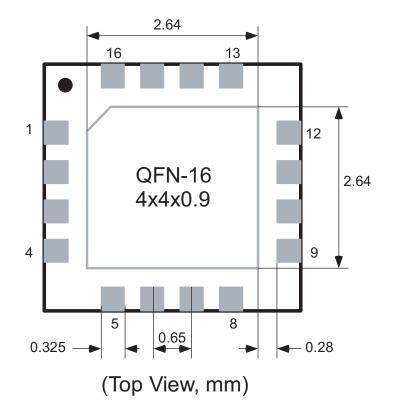
Pay particular attention that parasitic couplings are minimized from the output to the input signal terminals. The parasitic feedback may cause oscillations or spurious waveform shapes on the edges of signal transitions. Since the input operates with signals down to 1.2V even small coupled voltages may cause problems. Use of a solid ground plane and good power and signal layout practices will prevent this problem. Be careful that a circulating ground return current from a capacitive load cannot react with common inductance to cause noise voltages in the input logic circuitry.

Pin Description

V _{DD}	High side supply voltage.
V _{SS}	Low side supply voltage. V _{ss} is also connected to the IC substrate. It is required to connect to the most negative potential of voltage supplies and powered-up first.
V _H	Supply voltage for P-channel output stage.
VL	Supply voltage for N-channel output stage.
GND	Logic input ground reference.
OE	Output enable logic input. When OE is high, $(V_{OE}+V_{GND})/2$ sets the threshold transition between logic level high and low. When OE is low, all outputs are at high impedance. Keep OE low until IC powered up.
INA, INB,INC, IND	Logic input. Input logic high will cause the output to swing to V_{H} . Input logic low will cause the output to swing to V_{L} . Keep all logic inputs low until IC powered up.
OUTA, OUTB, OUTC, OUTD	Output drivers
Substrate	The IC substrate is internally connected to the thermal pad. Thermal Pad and $\rm V_{ss}$ must be connected externally.

Pin Configuration

Pin #	Function
1	INB
2	VL
3	GND
4	VL
5	INC
6	IND
7	V _{ss}
8	OUTD
9	OUTC
10	V _H
11	V _H
12	OUTB
13	OUTA
14	V _{DD}
15	INA
16	OE
Note	Thermal Pad, and Pin #7 (V _{ss}), must be connected externally



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