## MICROMONITOR CHIP

#### DESCRIPTION

The IN1232 MicroMonitor Chip monitors three vital conditions for a microprocessor: power supply, software execution, and external override. First, a precision temperature—compensated reference and comparator cir-

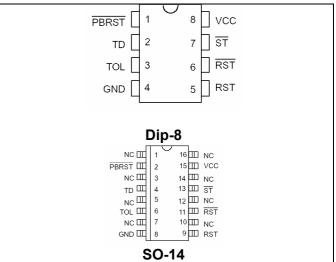
cuit monitors the status of  $V_{CC}$ . When an out–of–tolerance condition occurs, an internal power fail signal is generated which forces reset to the active state. When  $V_{CC}$  returns to an in–tolerance condition, the reset signals are kept in the active state for a minimum of 250 ms to allow the power supply and processor to stabilize.

The second function the IN1232 performs is pushbutton reset control. The IN1232 debounces the pushbutton input and guarantees an active reset pulse width of 250 ms minimum. The third function is a watchdog timer. The IN1232 has an internal timer that forces the reset signals to the active state if the strobe input is not driven low prior to time—out. The watchdog timer function can be set to operate on time—out settings of approximately 150 ms, 600 ms, and 1.2 seconds.

#### **FEATURES**

components

□ Halts and restarts an out–of–control microprocessor
□ Holds microprocessor in check during power transients
□ Automatically restarts microprocessor after power failure
□ Monitors pushbutton for external override
□ Accurate 5% or 10% microprocessor power supply monitoring
□ Eliminates the need for discrete



#### SO-14 PIN DESCRIPTION

PBRST	Pushbutton Reset Input
TD	Time Delay Set
TOL	Selects 5% or 10% V <sub>CC</sub> Detect
GND	Ground
RST	Reset Output (Active High)
RST	Reset Output (Active Low, open
	drain)
ST	Strobe Input
<sup>∨</sup> CC	+5 Volt Power
NC	No Connections

## **ABSOLUTE MAXIMUM RATINGS\***

PARAMETER

Supply Voltage

Voltage on V <sub>CC</sub> Pin Relative to Ground	–0.5V to +7.0V
Voltage on I/O Relative to Ground	$-0.5V$ to $V_{CC} + 0.5V$
Operating Temperature	0°C to 70°C
Operating Temperature (Industrial	–40°C to +85°C
Version)	
Storage Temperature	–55°C to +125°C
Soldering Temperature	260°C for 10 seconds

SYMBOL MIN

4.5

TYP

5.0

MAX

5.5

## RECOMMENDED DC OPERATING CONDITIONS

 $V_{CC}$ 

(0°0	C to	70°C
rs	TON	ES

UNITS

ST and PBRST Input High	V <sub>IH</sub>	2.0		V <sub>CC</sub> +0.3	V	1
Level						
ST and PBRST Input Low	$V_{IL}$	-0.3		+0.8	V	1
Level						
DC ELECTRICAL CHARA	<b>DC ELECTRICAL CHARACTERISTICS</b> $(0 \square C \text{ to } 70 \square^{C; V}CC = 4.5 \text{ to } 5.5)$					
PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Input Leakage	I <sub>IL</sub>	-1.0		+1.0	μΑ	3
Output Current @ 2.4V	I <sub>OH</sub>	-8	<b>–10</b>		mA	5
Output Current @ 0.4V	I <sub>OL</sub>	8	10		mA	
Low Level @ RST	$V_{OL}$			0.4	V	1
Output Voltage @ –500 μA	$V_{OH}$	V <sub>CC</sub> -0.5V	V <sub>CC</sub> -0.1V	'	V	1,7
Operating Current	I <sub>cc</sub>		0.5	2.0	mA	2
V <sub>CC</sub> Trip Point (TOL = GND)	$V_{CCTP}$	4.50	4.62	4.74	V	1
$V_{CC}$ Trip Point (TOL = $V_{CC}$ )	$V_{CCTP}$	4.25	4.37	4.49	V	1
CAPACITANCE						$(t_A = 25^{\circ}C)$
PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Input Capacitance	C <sub>IN</sub>			5	pF	
Output Capacitance	$C_{OUT}$			7	pF	
AC ELECTRICAL CHARAC	TERISTICS	(0°C to 70	oC;	5V + 10%)	)	
PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
PBRST = V <sub>IL</sub>	t <sub>PB</sub>	20			ms	
RESET Active Time	t <sub>RST</sub>	250	610	1000	ms	
ST Pulse Width	t <sub>ST</sub>	20			ns	6, 8
V <sub>CC</sub> Fail Detect to RST and RST	t <sub>RPD</sub>		100	175	μS	
V <sub>CC</sub> Slew Rate 4.75V to 4.25V	t <sub>F</sub>	300			μS	
V <sub>CC</sub> Detect to RST and RST Transition	t <sub>RPU</sub>	250	610	1000	ms	4
V <sub>CC</sub> Slew Rate 4.25V to 4.75V	t <sub>R</sub>	0	5		μS	
PBRST Stable Low to RST	t <sub>PDLY</sub>			20	ms	

# and RST NOTES:

- 1. All voltages referenced to ground.
- 2. Measured with outputs open.
- 3. PBRST is internally pulled up to  $V_{CC}$  with an internal impedance of 10K typical.
- 4.  $t_R = 5 \mu s$ .



<sup>\*</sup> This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

- 5. RST is an open drain output.
- 6. Must not exceed t<sub>TD</sub> minimum. See Table 1.
- 7. RST remains within 0.5V of  $V_{CC}$  on power–down until  $V_{CC}$  drops below 2.0V. RST remains within 0.5V of GND on power–down until  $V_{CC}$  drops below 2.0V.
- 8. Watchdog can not be disabled. It must be strobed to avoid resets.

#### **OPERATION - POWER MONITOR**

The IN1232 detects out–of–tolerance power supply conditions and warns a processor–based system of impending power failure. When  $V_{\rm CC}$  falls below a preset level as defined by TOL (Pin 3), the  $V_{\rm CC}$  comparator outputs the signals RST (Pin 5) and RST (Pin 6). When TOL is connected to ground, the RST and RST signals become active as  $V_{\rm CC}$  falls below 4.75 volts. When TOL is connected to  $V_{\rm CC}$ , the RST and RST signals become active as  $V_{\rm CC}$  falls below 4.5 volts. The RST and RST are excellent control signals for a microprocessor, as processing is stopped at the last possible moments of valid  $V_{\rm CC}$ . On power–up, RST and RST are kept active for a minimum of 250 ms to allow the power supply and processor to stabilize.

#### **OPERATION - PUSHBUTTON RESET**

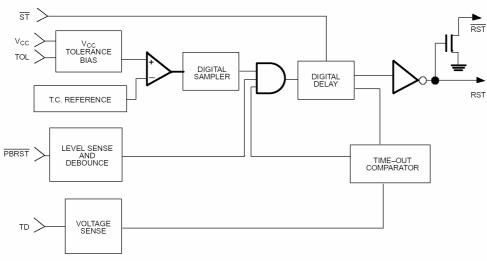
The IN1232 provides an input pin for direct connection to a pushbutton (Figure 2). The pushbutton reset input requires an active low signal. Internally, this input is de-bounced and timed such that RST and RST signals of at least 250 ms minimum are generated. The 250 ms delay starts as the pushbutton reset input is released from low level.

#### **OPERATION – WATCHDOG TIMER**

A watchdog timer function forces RST and RST signals to the active state when the ST input is not stimulated for a predetermined time period. The time period is set by the TD input to be typically 150 ms with TD connected to ground, 600 ms with TD left unconnected, and 1.2 sec-

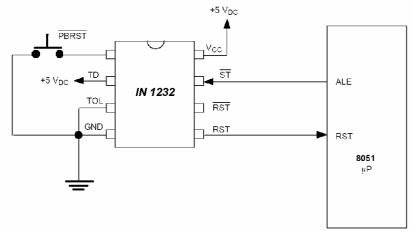
onds with TD connected to  $V_{\rm CC}$ . The watchdog timer starts timing out from the set time period as soon as RST and RST are inactive. If a high–to–low transition occurs on the ST input pin prior to time–out, the watchdog timer is reset and begins to time–out again. If the watchdog timer is allowed to time-out, then the RST and RST signals are driven to the active state for 250 ms minimum. The ST input can be derived from microprocessor address signals, data signals, and/or control signals. When the microprocessor is functioning normally, these signals would, as a matter of routine, cause the watchdog to be reset prior to time–out. To guarantee that the watchdog timer does not time–out, a high–to–low transition must occur at or less than the minimum shown in Table 1. A typical circuit example is shown in Figure 3.

#### MICROMONITOR BLOCK DIAGRAM

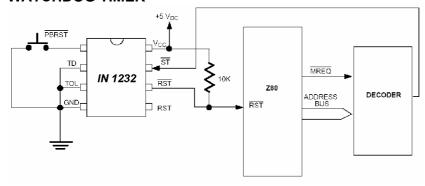




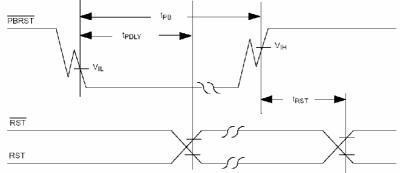
## **PUSHBUTTON RESET**



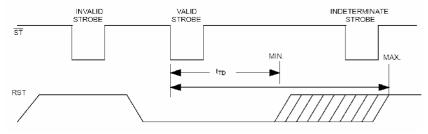
#### **WATCHDOG TIMER**



### TIMING DIAGRAM: PUSHBUTTON RESET



## **TIMING DIAGRAM: STROBE INPUT**

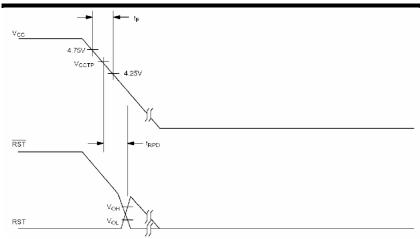


## **WATCHDOG TIMEOUTS**

TD PIN TIME-OUT

	MIN	TYP	MAX
GND	62.5 ms	150 ms	250 ms
Float	250 ms	600 ms	1000 ms
VCC	500 ms	1200 ms	2000 ms

**TIMING DIAGRAM: POWER DOWN** 



## TIMING DIAGRAM: POWER UP

